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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Not For New Designs
Core Processor	ARM® Cortex®-M3
Core Size	32-Bit Single-Core
Speed	32MHz
Connectivity	EBI/EMI, I <sup>2</sup> C, IrDA, SmartCard, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, LCD, POR, PWM, WDT
Number of I/O	56
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	4K x 8
Voltage - Supply (Vcc/Vdd)	1.85V ~ 3.8V
Data Converters	A/D 8x12b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	64-QFN (9x9)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/silicon-labs/efm32tg840f32-qfn64t">https://www.e-xfl.com/product-detail/silicon-labs/efm32tg840f32-qfn64t</a>

# 1 Ordering Information

Table 1.1 (p. 2) shows the available EFM32TG840 devices.

**Table 1.1. Ordering Information**

Ordering Code	Flash (kB)	RAM (kB)	Max Speed (MHz)	Supply Voltage (V)	Temperature (°C)	Package
EFM32TG840F8-QFN64	8	2	32	1.98 - 3.8	-40 - 85	QFN64
EFM32TG840F16-QFN64	16	4	32	1.98 - 3.8	-40 - 85	QFN64
EFM32TG840F32-QFN64	32	4	32	1.98 - 3.8	-40 - 85	QFN64

Visit **[www.silabs.com](http://www.silabs.com)** for information on global distributors and representatives.

### 2.1.19 Voltage Comparator (VCMP)

The Voltage Supply Comparator is used to monitor the supply voltage from software. An interrupt can be generated when the supply falls below or rises above a programmable threshold. Response time and thereby also the current consumption can be configured by altering the current supply to the comparator.

### 2.1.20 Analog to Digital Converter (ADC)

The ADC is a Successive Approximation Register (SAR) architecture, with a resolution of up to 12 bits at up to one million samples per second. The integrated input mux can select inputs from 8 external pins and 6 internal signals.

### 2.1.21 Digital to Analog Converter (DAC)

The Digital to Analog Converter (DAC) can convert a digital value to an analog output voltage. The DAC is fully differential rail-to-rail, with 12-bit resolution. It has two single ended output buffers which can be combined into one differential output. The DAC may be used for a number of different applications such as sensor interfaces or sound output.

### 2.1.22 Operational Amplifier (OPAMP)

The EFM32TG840 features 3 Operational Amplifiers. The Operational Amplifier is a versatile general purpose amplifier with rail-to-rail differential input and rail-to-rail single ended output. The input can be set to pin, DAC or OPAMP, whereas the output can be pin, OPAMP or ADC. The current is programmable and the OPAMP has various internal configurations such as unity gain, programmable gain using internal resistors etc.

### 2.1.23 Low Energy Sensor Interface (LESENSE)

The Low Energy Sensor Interface (LESENSE<sup>™</sup>), is a highly configurable sensor interface with support for up to 8 individually configurable sensors. By controlling the analog comparators and DAC, LESENSE is capable of supporting a wide range of sensors and measurement schemes, and can for instance measure LC sensors, resistive sensors and capacitive sensors. LESENSE also includes a programmable FSM which enables simple processing of measurement results without CPU intervention. LESENSE is available in energy mode EM2, in addition to EM0 and EM1, making it ideal for sensor monitoring in applications with a strict energy budget.

### 2.1.24 Advanced Encryption Standard Accelerator (AES)

The AES accelerator performs AES encryption and decryption with 128-bit or 256-bit keys. Encrypting or decrypting one 128-bit data block takes 52 HFCORECLK cycles with 128-bit keys and 75 HFCORECLK cycles with 256-bit keys. The AES module is an AHB slave which enables efficient access to the data and key registers. All write accesses to the AES module must be 32-bit operations, i.e. 8- or 16-bit operations are not supported.

### 2.1.25 General Purpose Input/Output (GPIO)

In the EFM32TG840, there are 56 General Purpose Input/Output (GPIO) pins, which are divided into ports with up to 16 pins each. These pins can individually be configured as either an output or input. More advanced configurations like open-drain, filtering and drive strength can also be configured individually for the pins. The GPIO pins can also be overridden by peripheral pin connections, like Timer PWM outputs or USART communication, which can be routed to several locations on the device. The GPIO supports up to 16 asynchronous external pin interrupts, which enables interrupts from any pin on the device. Also, the input value of a pin can be routed through the Peripheral Reflex System to other peripherals.

## 2.1.26 Liquid Crystal Display Driver (LCD)

The LCD driver is capable of driving a segmented LCD display with up to 8x20 segments. A voltage boost function enables it to provide the LCD display with higher voltage than the supply voltage for the device. In addition, an animation feature can run custom animations on the LCD display without any CPU intervention. The LCD driver can also remain active even in Energy Mode 2 and provides a Frame Counter interrupt that can wake-up the device on a regular basis for updating data.

## 2.2 Configuration Summary

The features of the EFM32TG840 is a subset of the feature set described in the EFM32TG Reference Manual. Table 2.1 (p. 7) describes device specific implementation of the features.

**Table 2.1. Configuration Summary**

Module	Configuration	Pin Connections
Cortex-M3	Full configuration	NA
DBG	Full configuration	DBG_SWCLK, DBG_SWDIO, DBG_SWO
MSC	Full configuration	NA
DMA	Full configuration	NA
RMU	Full configuration	NA
EMU	Full configuration	NA
CMU	Full configuration	CMU_OUT0, CMU_OUT1
WDOG	Full configuration	NA
PRS	Full configuration	NA
I2C0	Full configuration	I2C0_SDA, I2C0_SCL
USART0	Full configuration with IrDA	US0_TX, US0_RX, US0_CLK, US0_CS
USART1	Full configuration with I2S	US1_TX, US1_RX, US1_CLK, US1_CS
LEUART0	Full configuration	LEU0_TX, LEU0_RX
TIMER0	Full configuration	TIM0_CC[2:0]
TIMER1	Full configuration	TIM1_CC[2:0]
RTC	Full configuration	NA
LETIMER0	Full configuration	LET0_O[1:0]
PCNT0	Full configuration, 16-bit count register	PCNT0_S[1:0]
ACMP0	Full configuration	ACMP0_CH[7:4], ACMP0_O
ACMP1	Full configuration	ACMP1_CH[7:4], ACMP1_O
VCMP	Full configuration	NA
ADC0	Full configuration	ADC0_CH[7:0]
DAC0	Full configuration	DAC0_OUT[1:0], DAC0_OUTxALT
OPAMP	Full configuration	Outputs: OPAMP_OUTx, OPAMP_OUTxALT, Inputs: OPAMP_Px, OPAMP_Nx
AES	Full configuration	NA

## 3 Electrical Characteristics

### 3.1 Test Conditions

#### 3.1.1 Typical Values

The typical data are based on  $T_{AMB}=25^{\circ}\text{C}$  and  $V_{DD}=3.0\text{ V}$ , as defined in Table 3.2 (p. 9), by simulation and/or technology characterisation unless otherwise specified.

#### 3.1.2 Minimum and Maximum Values

The minimum and maximum values represent the worst conditions of ambient temperature, supply voltage and frequencies, as defined in Table 3.2 (p. 9), by simulation and/or technology characterisation unless otherwise specified.

### 3.2 Absolute Maximum Ratings

The absolute maximum ratings are stress ratings, and functional operation under such conditions are not guaranteed. Stress beyond the limits specified in Table 3.1 (p. 9) may affect the device reliability or cause permanent damage to the device. Functional operating conditions are given in Table 3.2 (p. 9).

**Table 3.1. Absolute Maximum Ratings**

Symbol	Parameter	Condition	Min	Typ	Max	Unit
$T_{STG}$	Storage temperature range		-40		150 <sup>1</sup>	$^{\circ}\text{C}$
$T_S$	Maximum soldering temperature	Latest IPC/JEDEC J-STD-020 Standard			260	$^{\circ}\text{C}$
$V_{DDMAX}$	External main supply voltage		0		3.8	V
$V_{IOPIN}$	Voltage on any I/O pin		-0.3		$V_{DD}+0.3$	V

<sup>1</sup>Based on programmed devices tested for 10000 hours at  $150^{\circ}\text{C}$ . Storage temperature affects retention of preprogrammed calibration values stored in flash. Please refer to the Flash section in the Electrical Characteristics for information on flash data retention for different temperatures.

### 3.3 General Operating Conditions

#### 3.3.1 General Operating Conditions

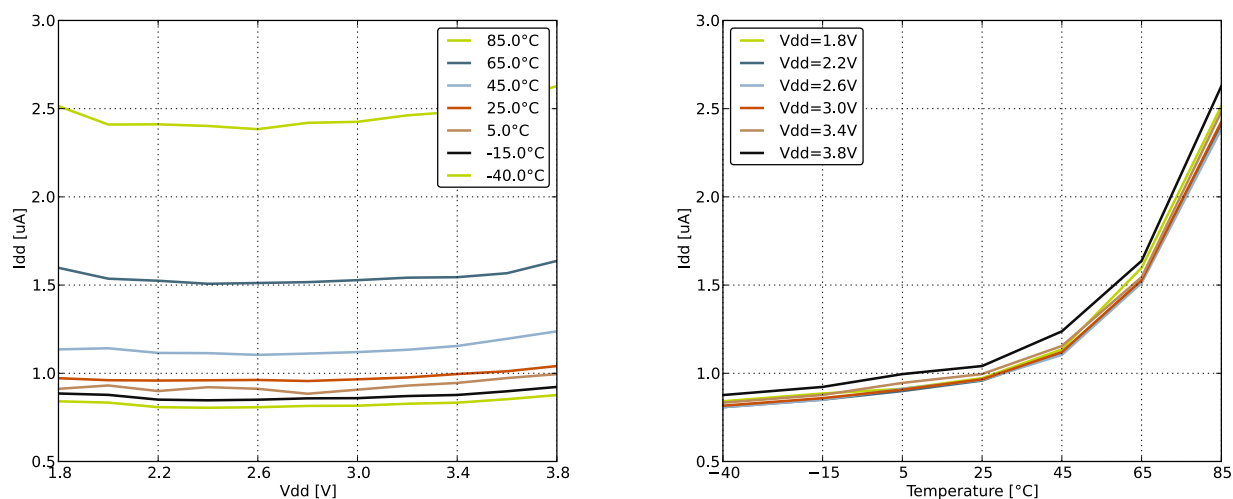
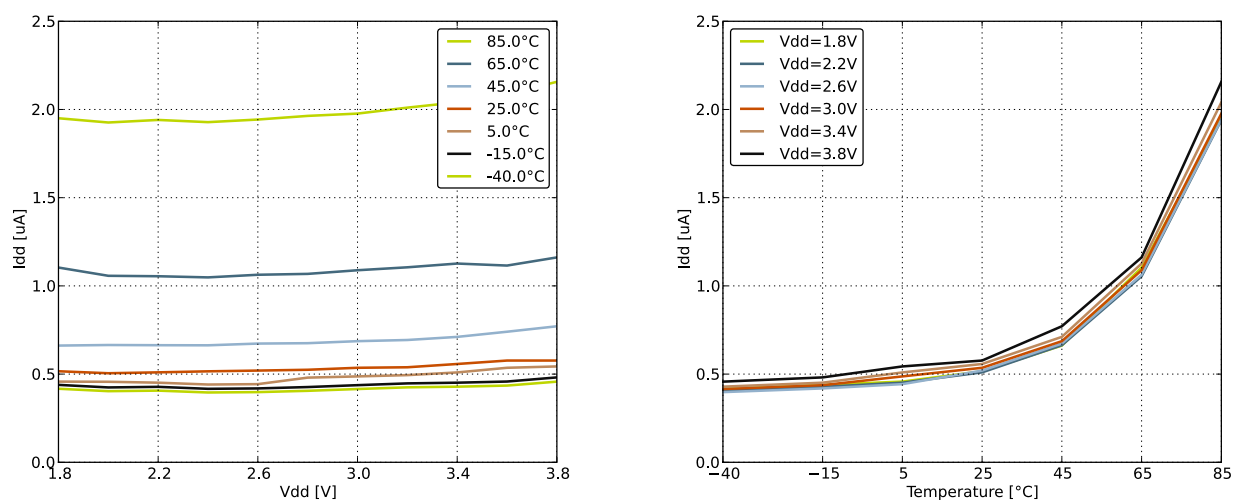
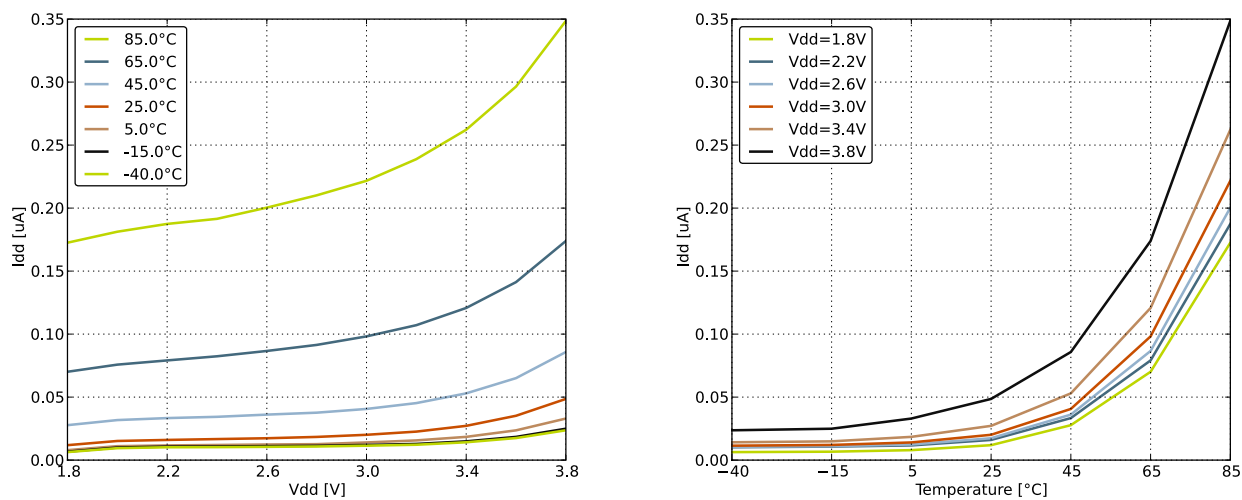
**Table 3.2. General Operating Conditions**

Symbol	Parameter	Min	Typ	Max	Unit
$T_{AMB}$	Ambient temperature range	-40		85	$^{\circ}\text{C}$
$V_{DDOP}$	Operating supply voltage	1.98		3.8	V
$f_{APB}$	Internal APB clock frequency			32	MHz
$f_{AHB}$	Internal AHB clock frequency			32	MHz

## 3.4 Current Consumption

**Table 3.3. Current Consumption**

Symbol	Parameter	Condition	Min	Typ	Max	Unit
I <sub>EM0</sub>	EM0 current. No prescaling. Running prime number calculation code from Flash. (Production test condition = 14 MHz)	32 MHz HFXO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		157		μA/ MHz
		28 MHz HFRCO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		150	170	μA/ MHz
		21 MHz HFRCO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		153	172	μA/ MHz
		14 MHz HFRCO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		155	175	μA/ MHz
		11 MHz HFRCO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		157	178	μA/ MHz
		6.6 MHz HFRCO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		162	183	μA/ MHz
		1.2 MHz HFRCO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		200	240	μA/ MHz
I <sub>EM1</sub>	EM1 current (Production test condition = 14 MHz)	32 MHz HFXO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		53		μA/ MHz
		28 MHz HFRCO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		51	57	μA/ MHz
		21 MHz HFRCO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		55	59	μA/ MHz
		14 MHz HFRCO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		56	61	μA/ MHz
		11 MHz HFRCO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		58	63	μA/ MHz
		6.6 MHz HFRCO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		63	68	μA/ MHz
		1.2 MHz HFRCO. all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		100	122	μA/ MHz
I <sub>EM2</sub>	EM2 current	EM2 current with RTC prescaled to 1 Hz, 32.768 kHz LFRCO, V <sub>DD</sub> = 3.0 V, T <sub>AMB</sub> =25°C		1.0	1.2	μA
		EM2 current with RTC prescaled to 1 Hz, 32.768 kHz LFRCO, V <sub>DD</sub> = 3.0 V, T <sub>AMB</sub> =85°C		2.4	5.0	μA
I <sub>EM3</sub>	EM3 current	V <sub>DD</sub> = 3.0 V, T <sub>AMB</sub> =25°C		0.59	1.0	μA
		V <sub>DD</sub> = 3.0 V, T <sub>AMB</sub> =85°C		2.0	4.5	μA
I <sub>EM4</sub>	EM4 current	V <sub>DD</sub> = 3.0 V, T <sub>AMB</sub> =25°C		0.02	0.055	μA
		V <sub>DD</sub> = 3.0 V, T <sub>AMB</sub> =85°C		0.25	0.70	μA

**Figure 3.1. EM2 current consumption. RTC prescaled to 1kHz, 32.768 kHz LFRCO.****Figure 3.2. EM3 current consumption.****Figure 3.3. EM4 current consumption.**

## 3.7 Flash

**Table 3.6. Flash**

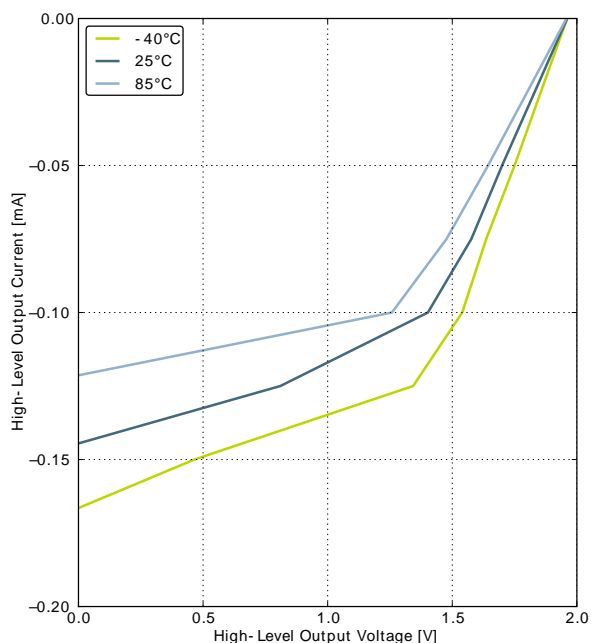
Symbol	Parameter	Condition	Min	Typ	Max	Unit
EC <sub>FLASH</sub>	Flash erase cycles before failure		20000			cycles
RET <sub>FLASH</sub>	Flash data retention	T <sub>AMB</sub> <150°C	10000			h
		T <sub>AMB</sub> <85°C	10			years
		T <sub>AMB</sub> <70°C	20			years
t <sub>W_PROG</sub>	Word (32-bit) programming time		20			µs
t <sub>P_ERASE</sub>	Page erase time		20	20.4	20.8	ms
t <sub>D_ERASE</sub>	Device erase time		40	40.8	41.6	ms
I <sub>ERASE</sub>	Erase current				7 <sup>1</sup>	mA
I <sub>WRITE</sub>	Write current				7 <sup>1</sup>	mA
V <sub>FLASH</sub>	Supply voltage during flash erase and write		1.98		3.8	V

<sup>1</sup> Measured at 25°C

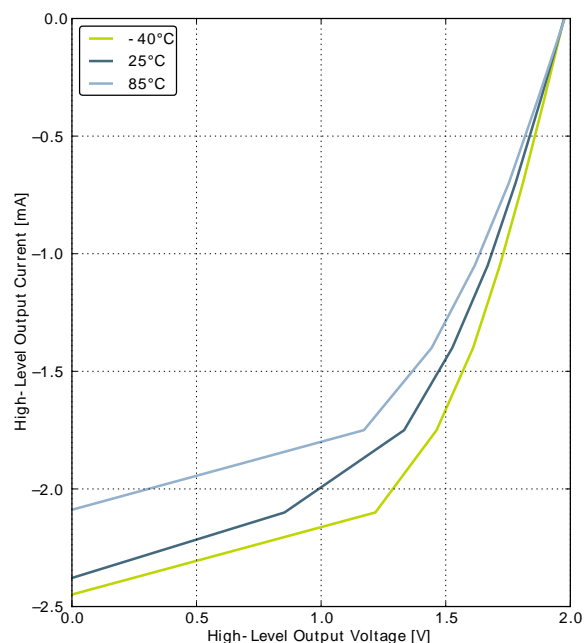
## 3.8 General Purpose Input Output

**Table 3.7. GPIO**

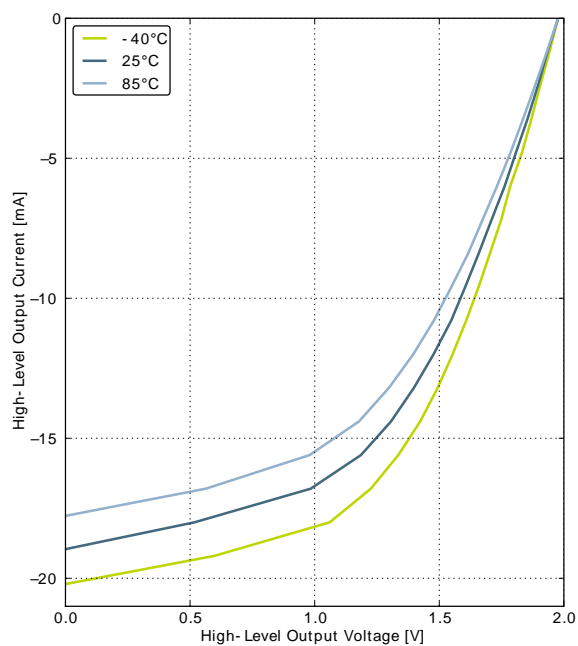
Symbol	Parameter	Condition	Min	Typ	Max	Unit
V <sub>IOIL</sub>	Input low voltage				0.30V <sub>DD</sub>	V
V <sub>IOIH</sub>	Input high voltage		0.70V <sub>DD</sub>			V
V <sub>IOOH</sub>	Output high voltage (Production test condition = 3.0V, DRIVEMODE = STANDARD)	Sourcing 0.1 mA, V <sub>DD</sub> =1.98 V, GPIO_Px_CTRL DRIVEMODE = LOWEST		0.80V <sub>DD</sub>		V
		Sourcing 0.1 mA, V <sub>DD</sub> =3.0 V, GPIO_Px_CTRL DRIVEMODE = LOWEST		0.90V <sub>DD</sub>		V
		Sourcing 1 mA, V <sub>DD</sub> =1.98 V, GPIO_Px_CTRL DRIVEMODE = LOW		0.85V <sub>DD</sub>		V
		Sourcing 1 mA, V <sub>DD</sub> =3.0 V, GPIO_Px_CTRL DRIVEMODE = LOW		0.90V <sub>DD</sub>		V
		Sourcing 6 mA, V <sub>DD</sub> =1.98 V, GPIO_Px_CTRL DRIVEMODE = STANDARD	0.75V <sub>DD</sub>			V
		Sourcing 6 mA, V <sub>DD</sub> =3.0 V, GPIO_Px_CTRL DRIVEMODE = STANDARD	0.85V <sub>DD</sub>			V
		Sourcing 20 mA, V <sub>DD</sub> =1.98 V, GPIO_Px_CTRL DRIVEMODE = HIGH	0.60V <sub>DD</sub>			V

**Figure 3.5. Typical High-Level Output Current, 2V Supply Voltage**

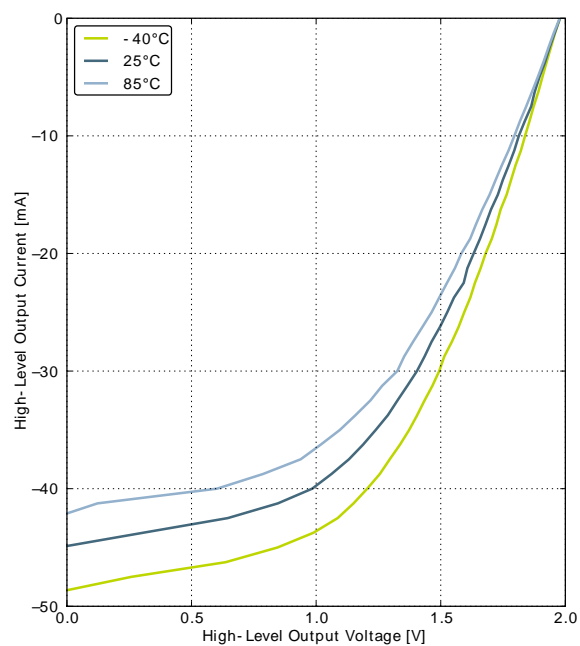
GPIO\_Px\_CTRL DRIVEMODE = LOWEST



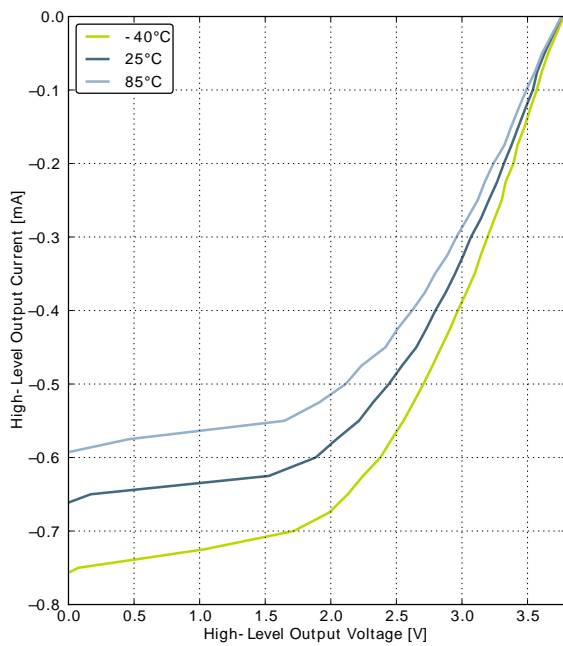
GPIO\_Px\_CTRL DRIVEMODE = LOW



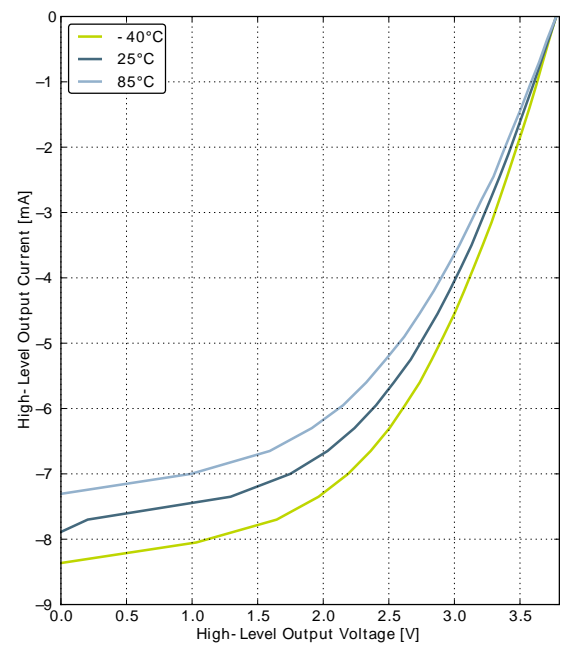
GPIO\_Px\_CTRL DRIVEMODE = STANDARD



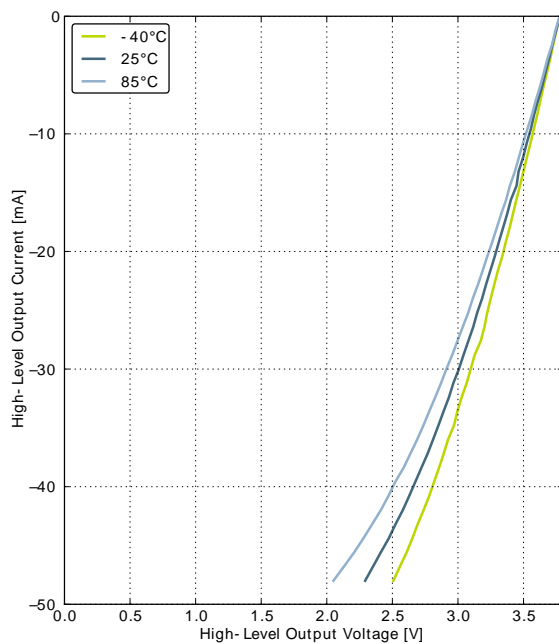
GPIO\_Px\_CTRL DRIVEMODE = HIGH

**Figure 3.9. Typical High-Level Output Current, 3.8V Supply Voltage**

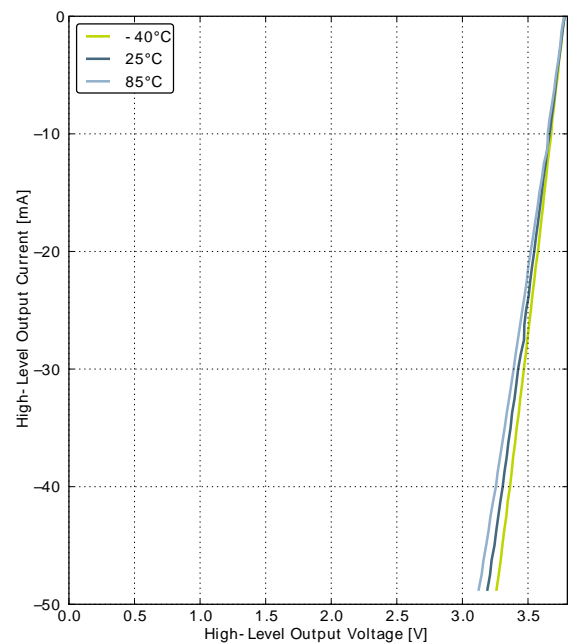
GPIO\_Px\_CTRL DRIVEMODE = LOWEST



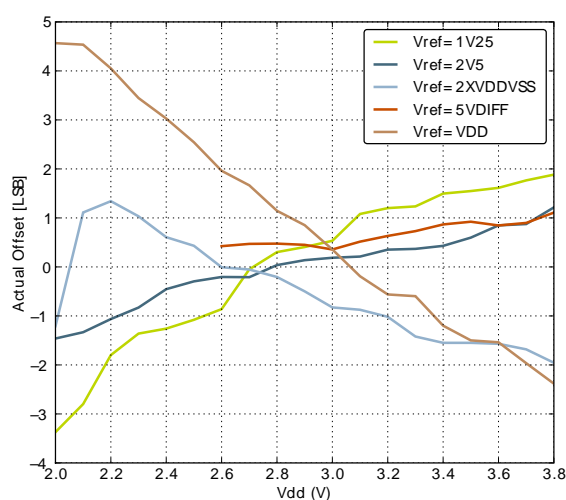
GPIO\_Px\_CTRL DRIVEMODE = LOW



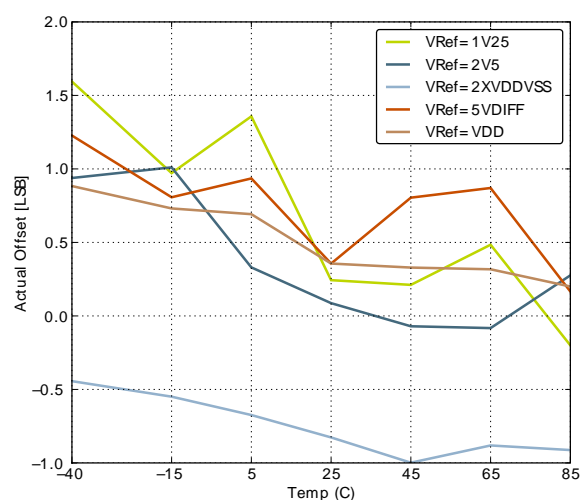
GPIO\_Px\_CTRL DRIVEMODE = STANDARD



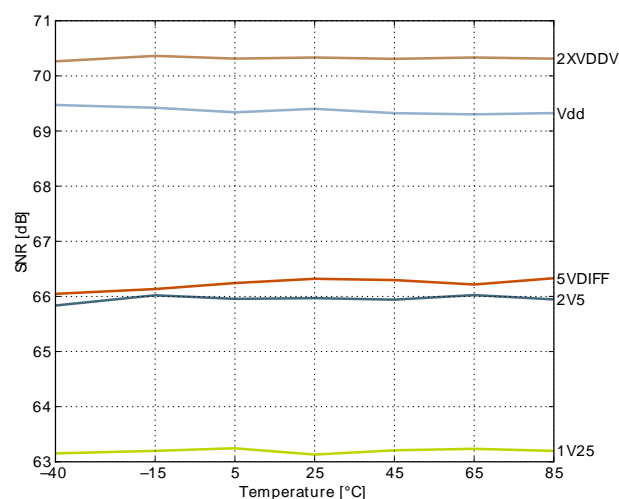
GPIO\_Px\_CTRL DRIVEMODE = HIGH

**Figure 3.22. ADC Absolute Offset, Common Mode =  $V_{DD}/2$** 

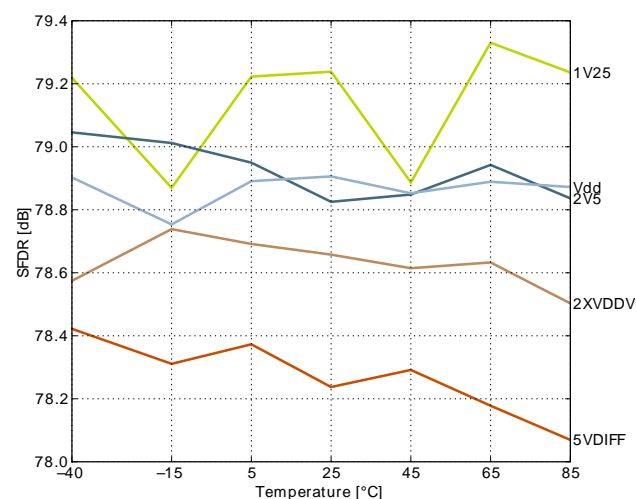
Offset vs Supply Voltage, Temp = 25°C



Offset vs Temperature, Vdd = 3V

**Figure 3.23. ADC Dynamic Performance vs Temperature for all ADC References, Vdd = 3V**

Signal to Noise Ratio (SNR)

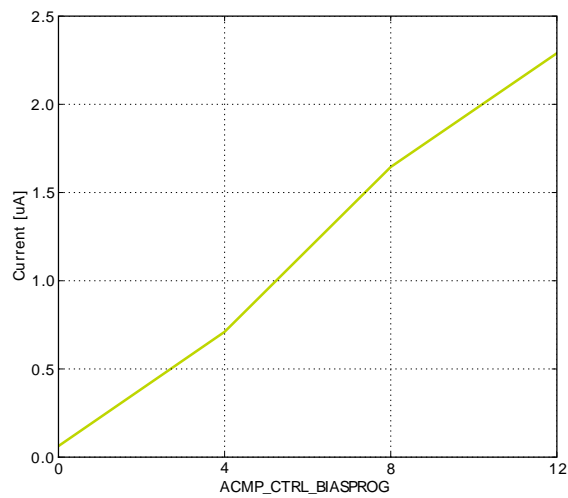
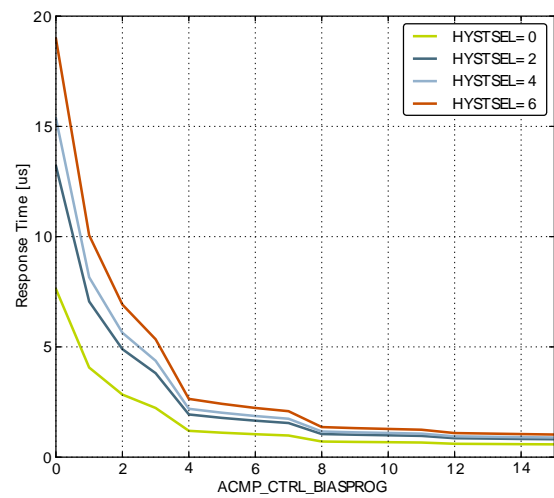
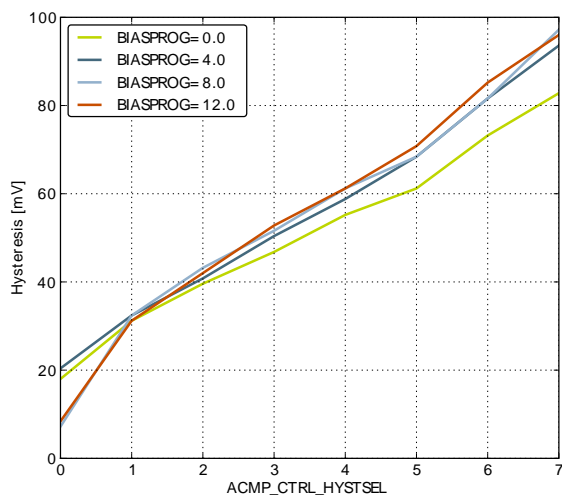


Spurious-Free Dynamic Range (SFDR)

## 3.11 Digital Analog Converter (DAC)

**Table 3.15. DAC**

Symbol	Parameter	Condition	Min	Typ	Max	Unit
$V_{DACOUT}$	Output voltage range	VDD voltage reference, single ended	0		$V_{DD}$	V
		VDD voltage reference, differential	$-V_{DD}$		$V_{DD}$	V
$V_{DACCM}$	Output common mode voltage range		0		$V_{DD}$	V
$I_{DAC}$	Active current including references for 2 channels	500 kSamples/s, 12bit		400	650	$\mu A$
		100 kSamples/s, 12 bit		200	250	$\mu A$
		1 kSamples/s 12 bit NORMAL		17	25	$\mu A$

**Figure 3.29. ACMP Characteristics,  $V_{dd} = 3V$ , Temp = 25°C, FULLBIAS = 0, HALFBIAS = 1****Current consumption, HYSTSEL = 4****Response time ,  $V_{cm} = 1.25V$ , CP+ to CP- = 100mV****Hysteresis**

## 4 Pinout and Package

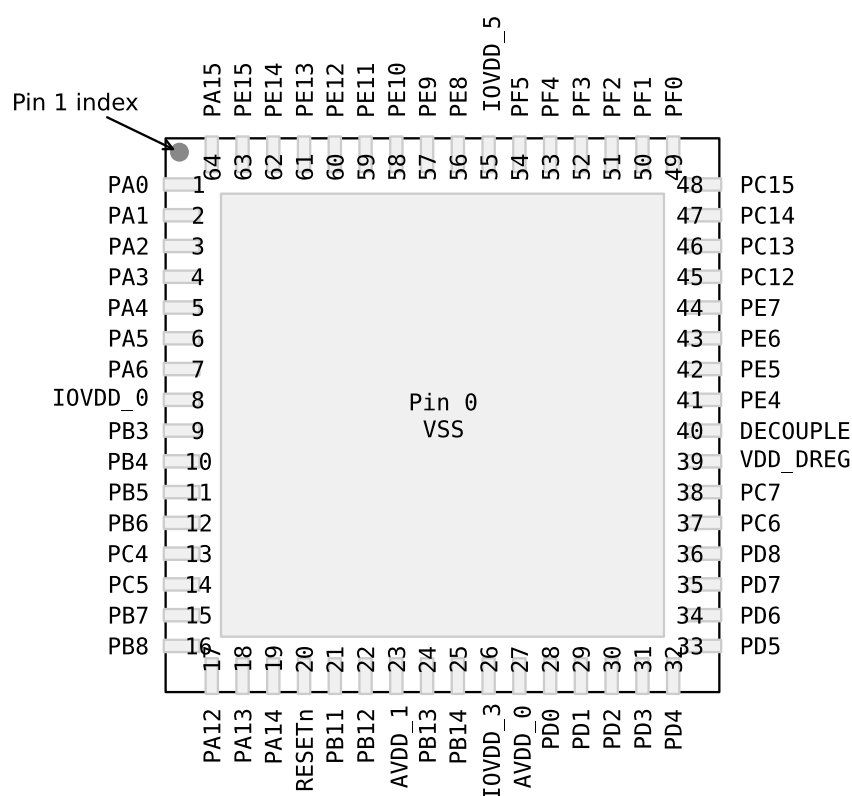
### Note

Please refer to the application note "AN0002 EFM32 Hardware Design Considerations" for guidelines on designing Printed Circuit Boards (PCB's) for the EFM32TG840.

### 4.1 Pinout

The *EFM32TG840* pinout is shown in Figure 4.1 (p. 46) and Table 4.1 (p. 46). Alternate locations are denoted by "#" followed by the location number (Multiple locations on the same pin are split with "/"). Alternate locations can be configured in the LOCATION bitfield in the \*\_ROUTE register in the module in question.

**Figure 4.1. EFM32TG840 Pinout (top view, not to scale)**



**Table 4.1. Device Pinout**

QFN64 Pin# and Name		Pin Alternate Functionality / Description			
Pin #	Pin Name	Analog	Timers	Communication	Other
0	VSS	Ground.			
1	PA0	LCD_SEG13	TIM0_CC0 #0/1/4	LEU0_RX #4 I2C0_SDA #0	PRS_CH0 #0 GPIO_EM4WU0
2	PA1	LCD_SEG14	TIM0_CC1 #0/1	I2C0_SCL #0	CMU_CLK1 #0 PRS_CH1 #0

Alternate	LOCATION							
Functionality	0	1	2	3	4	5	6	Description
								If AVDD is used directly as the LCD supply voltage, this pin may be left unconnected or used as a GPIO.
LCD_COM0	PE4							LCD driver common line number 0.
LCD_COM1	PE5							LCD driver common line number 1.
LCD_COM2	PE6							LCD driver common line number 2.
LCD_COM3	PE7							LCD driver common line number 3.
LCD_SEG0	PF2							LCD segment line 0. Segments 0, 1, 2 and 3 are controlled by SEGEN0.
LCD_SEG1	PF3							LCD segment line 1. Segments 0, 1, 2 and 3 are controlled by SEGEN0.
LCD_SEG2	PF4							LCD segment line 2. Segments 0, 1, 2 and 3 are controlled by SEGEN0.
LCD_SEG3	PF5							LCD segment line 3. Segments 0, 1, 2 and 3 are controlled by SEGEN0.
LCD_SEG4	PE8							LCD segment line 4. Segments 4, 5, 6 and 7 are controlled by SEGEN1.
LCD_SEG5	PE9							LCD segment line 5. Segments 4, 5, 6 and 7 are controlled by SEGEN1.
LCD_SEG6	PE10							LCD segment line 6. Segments 4, 5, 6 and 7 are controlled by SEGEN1.
LCD_SEG7	PE11							LCD segment line 7. Segments 4, 5, 6 and 7 are controlled by SEGEN1.
LCD_SEG8	PE12							LCD segment line 8. Segments 8, 9, 10 and 11 are controlled by SEGEN2.
LCD_SEG9	PE13							LCD segment line 9. Segments 8, 9, 10 and 11 are controlled by SEGEN2.
LCD_SEG10	PE14							LCD segment line 10. Segments 8, 9, 10 and 11 are controlled by SEGEN2.
LCD_SEG11	PE15							LCD segment line 11. Segments 8, 9, 10 and 11 are controlled by SEGEN2.
LCD_SEG12	PA15							LCD segment line 12. Segments 12, 13, 14 and 15 are controlled by SEGEN3.
LCD_SEG13	PA0							LCD segment line 13. Segments 12, 13, 14 and 15 are controlled by SEGEN3.
LCD_SEG14	PA1							LCD segment line 14. Segments 12, 13, 14 and 15 are controlled by SEGEN3.
LCD_SEG15	PA2							LCD segment line 15. Segments 12, 13, 14 and 15 are controlled by SEGEN3.
LCD_SEG16	PA3							LCD segment line 16. Segments 16, 17, 18 and 19 are controlled by SEGEN4.
LCD_SEG17	PA4							LCD segment line 17. Segments 16, 17, 18 and 19 are controlled by SEGEN4.
LCD_SEG18	PA5							LCD segment line 18. Segments 16, 17, 18 and 19 are controlled by SEGEN4.
LCD_SEG19	PA6							LCD segment line 19. Segments 16, 17, 18 and 19 are controlled by SEGEN4.
LCD_SEG20/ LCD_COM4	PB3							LCD segment line 20. Segments 20, 21, 22 and 23 are controlled by SEGEN5. This pin may also be used as LCD COM line 4
LCD_SEG21/ LCD_COM5	PB4							LCD segment line 21. Segments 20, 21, 22 and 23 are controlled by SEGEN5. This pin may also be used as LCD COM line 5
LCD_SEG22/ LCD_COM6	PB5							LCD segment line 22. Segments 20, 21, 22 and 23 are controlled by SEGEN5. This pin may also be used as LCD COM line 6

Alternate	LOCATION							
Functionality	0	1	2	3	4	5	6	Description
US0_TX	PE10	PE7		PE13	PB7			USART0 Asynchronous Transmit. Also used as receive input in half duplex communication. USART0 Synchronous mode Master Output / Slave Input (MOSI).
US1_CLK	PB7	PD2	PF0					USART1 clock input / output.
US1_CS	PB8	PD3	PF1					USART1 chip select input / output.
US1_RX		PD1	PD6					USART1 Asynchronous Receive. USART1 Synchronous mode Master Input / Slave Output (MISO).
US1_TX		PD0	PD7					USART1 Asynchronous Transmit. Also used as receive input in half duplex communication. USART1 Synchronous mode Master Output / Slave Input (MOSI).

## 4.3 GPIO Pinout Overview

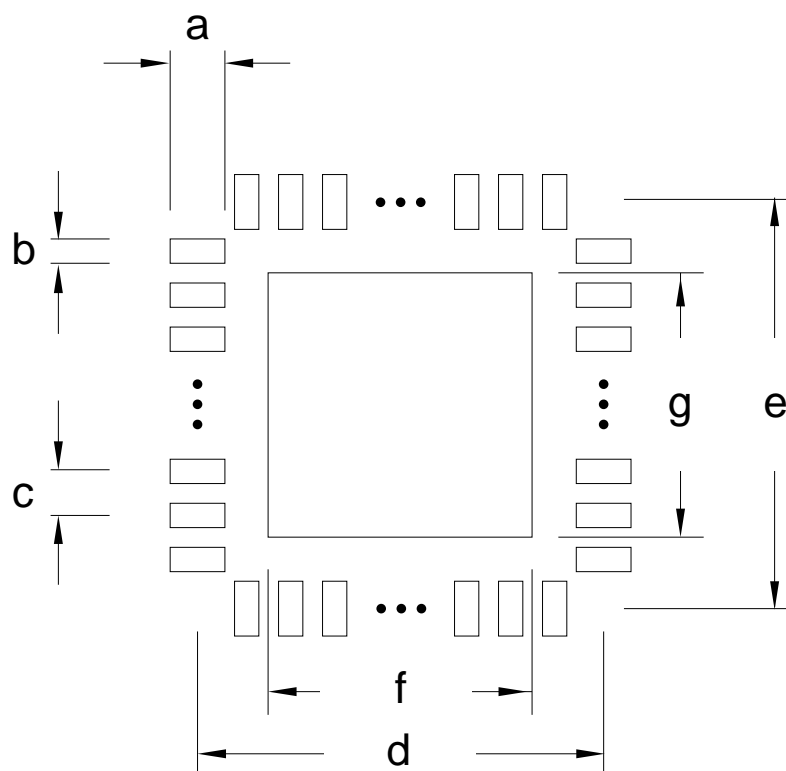
The specific GPIO pins available in *EFM32TG840* is shown in Table 4.3 (p. 53). Each GPIO port is organized as 16-bit ports indicated by letters A through F, and the individual pin on this port is indicated by a number from 15 down to 0.

**Table 4.3. GPIO Pinout**

Port	Pin 15	Pin 14	Pin 13	Pin 12	Pin 11	Pin 10	Pin 9	Pin 8	Pin 7	Pin 6	Pin 5	Pin 4	Pin 3	Pin 2	Pin 1	Pin 0
Port A	PA15	PA14	PA13	PA12	-	-	-	-	-	PA6	PA5	PA4	PA3	PA2	PA1	PA0
Port B	-	PB14	PB13	PB12	PB11	-	-	PB8	PB7	PB6	PB5	PB4	PB3	-	-	-
Port C	PC15	PC14	PC13	PC12	-	-	-	-	PC7	PC6	PC5	PC4	-	-	-	-
Port D	-	-	-	-	-	-	-	PD8	PD7	PD6	PD5	PD4	PD3	PD2	PD1	PD0
Port E	PE15	PE14	PE13	PE12	PE11	PE10	PE9	PE8	PE7	PE6	PE5	PE4	-	-	-	-
Port F	-	-	-	-	-	-	-	-	-	-	PF5	PF4	PF3	PF2	PF1	PF0

## 4.4 Opamp Pinout Overview

The specific opamp terminals available in *EFM32TG840* is shown in Figure 4.2 (p. 54) .

**Figure 5.2. QFN64 PCB Solder Mask****Table 5.2. QFN64 PCB Solder Mask Dimensions (Dimensions in mm)**

Symbol	Dim. (mm)	Symbol	Dim. (mm)
a	0.97	e	8.90
b	0.42	f	7.32
c	0.50	g	7.32
d	8.90	-	-

## 7 Revision History

### 7.1 Revision 1.40

March 6th, 2015

Updated Block Diagram.

Updated Energy Modes current consumption.

Updated Power Management section.

Updated LFRCO and HFRCO sections.

Added AUXHFRCO to block diagram and Electrical Characteristics.

Corrected unit to kHz on LFRCO plots y-axis.

Updated ADC section and added clarification on conditions for  $INL_{ADC}$  and  $DNL_{ADC}$  parameters.

Updated DAC section and added clarification on conditions for  $INL_{DAC}$  and  $DNL_{DAC}$  parameters.

Updated OPAMP section.

Updated ACMP section and the response time graph.

Updated VCMP section.

Updated Digital Peripherals section.

### 7.2 Revision 1.30

July 2nd, 2014

Corrected single power supply voltage minimum value from 1.85V to 1.98V.

Updated current consumption.

Updated transition between energy modes.

Updated power management data.

Updated GPIO data.

Updated LFXO, HFXO, HFRCO and ULFRCO data.

Updated LFRCO and HFRCO plots.

Updated ACMP data.

### 7.3 Revision 1.21

November 21st, 2013

Updated figures.

Updated errata-link.

Updated chip marking.

Added link to Environmental and Quality information.

Re-added missing DAC-data.

## 7.4 Revision 1.20

September 30th, 2013

Added I2C characterization data.

Corrected the DAC and OPAMP2 pin sharing information in the Alternate Functionality Pinout section.

Corrected GPIO operating voltage from 1.8 V to 1.85 V.

Corrected the ADC gain and offset measurement reference voltage from 2.25 to 2.5V.

Corrected the ADC resolution from 12, 10 and 6 bit to 12, 8 and 6 bit.

Document changed status from "Preliminary".

Updated Environmental information.

Updated trademark, disclaimer and contact information.

Other minor corrections.

## 7.5 Revision 1.10

June 28th, 2013

Updated power requirements in the Power Management section.

Removed minimum load capacitance figure and table. Added reference to application note.

Other minor corrections.

## 7.6 Revision 1.00

September 11th, 2012

Updated the HFRCO 1 MHz band typical value to 1.2 MHz.

Updated the HFRCO 7 MHz band typical value to 6.6 MHz.

Added GPIO\_EM4WU3, GPIO\_EM4WU4 and GPIO\_EM4WU5 pins and removed GPIO\_EM4WU1 in the Alternate functionality overview table.

Other minor corrections.

## 7.7 Revision 0.96

May 4th, 2012

Corrected PCB footprint figures and tables.

## 7.8 Revision 0.95

February 27th, 2012

Corrected operating voltage from 1.8 V to 1.85 V.

## A Disclaimer and Trademarks

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