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### Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

### Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

#### Details

Product Status	Obsolete
Number of LABs/CLBs	144
Number of Logic Elements/Cells	1152
Total RAM Bits	12288
Number of I/O	102
Number of Gates	63000
Voltage - Supply	4.5V ~ 5.5V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 85°C (TA)
Package / Case	144-LQFP
Supplier Device Package	144-TQFP (20x20)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/intel/epf10k20ti144-4">https://www.e-xfl.com/product-detail/intel/epf10k20ti144-4</a>

The logic array consists of logic array blocks (LABs). Each LAB contains eight LEs and a local interconnect. An LE consists of a 4-input look-up table (LUT), a programmable flipflop, and dedicated signal paths for carry and cascade functions. The eight LEs can be used to create medium-sized blocks of logic—8-bit counters, address decoders, or state machines—or combined across LABs to create larger logic blocks. Each LAB represents about 96 usable gates of logic.

Signal interconnections within FLEX 10K devices and to and from device pins are provided by the FastTrack Interconnect, a series of fast, continuous row and column channels that run the entire length and width of the device.

Each I/O pin is fed by an I/O element (IOE) located at the end of each row and column of the FastTrack Interconnect. Each IOE contains a bidirectional I/O buffer and a flipflop that can be used as either an output or input register to feed input, output, or bidirectional signals. When used with a dedicated clock pin, these registers provide exceptional performance. As inputs, they provide setup times as low as 1.6 ns and hold times of 0 ns; as outputs, these registers provide clock-to-output times as low as 5.3 ns. IOEs provide a variety of features, such as JTAG BST support, slew-rate control, tri-state buffers, and open-drain outputs.

**Figure 1** shows a block diagram of the FLEX 10K architecture. Each group of LEs is combined into an LAB; LABs are arranged into rows and columns. Each row also contains a single EAB. The LABs and EABs are interconnected by the FastTrack Interconnect. IOEs are located at the end of each row and column of the FastTrack Interconnect.

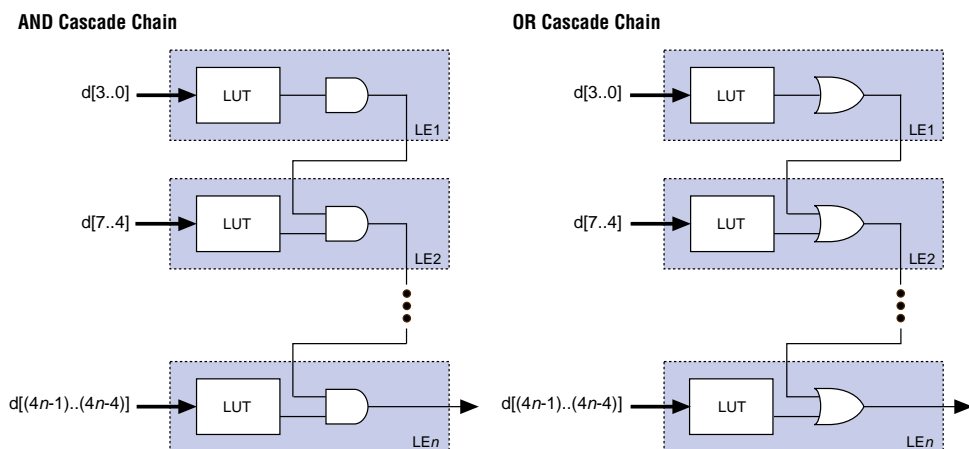
### Cascade Chain

With the cascade chain, the FLEX 10K architecture can implement functions that have a very wide fan-in. Adjacent LUTs can be used to compute portions of the function in parallel; the cascade chain serially connects the intermediate values. The cascade chain can use a logical AND or logical OR (via De Morgan's inversion) to connect the outputs of adjacent LEs. Each additional LE provides four more inputs to the effective width of a function, with a delay as low as 0.7 ns per LE. Cascade chain logic can be created automatically by the Compiler during design processing, or manually by the designer during design entry.

Cascade chains longer than eight bits are implemented automatically by linking several LABs together. For easier routing, a long cascade chain skips every other LAB in a row. A cascade chain longer than one LAB skips either from even-numbered LAB to even-numbered LAB, or from odd-numbered LAB to odd-numbered LAB (e.g., the last LE of the first LAB in a row cascades to the first LE of the third LAB). The cascade chain does not cross the center of the row (e.g., in the EPF10K50 device, the cascade chain stops at the eighteenth LAB and a new one begins at the nineteenth LAB). This break is due to the EAB's placement in the middle of the row.

Figure 8 shows how the cascade function can connect adjacent LEs to form functions with a wide fan-in. These examples show functions of  $4n$  variables implemented with  $n$  LEs. The LE delay is as low as 1.6 ns; the cascade chain delay is as low as 0.7 ns. With the cascade chain, 3.7 ns is needed to decode a 16-bit address.

**Figure 8. Cascade Chain Operation**



For improved routing, the row interconnect is comprised of a combination of full-length and half-length channels. The full-length channels connect to all LABs in a row; the half-length channels connect to the LABs in half of the row. The EAB can be driven by the half-length channels in the left half of the row and by the full-length channels. The EAB drives out to the full-length channels. In addition to providing a predictable, row-wide interconnect, this architecture provides increased routing resources. Two neighboring LABs can be connected using a half-row channel, thereby saving the other half of the channel for the other half of the row.

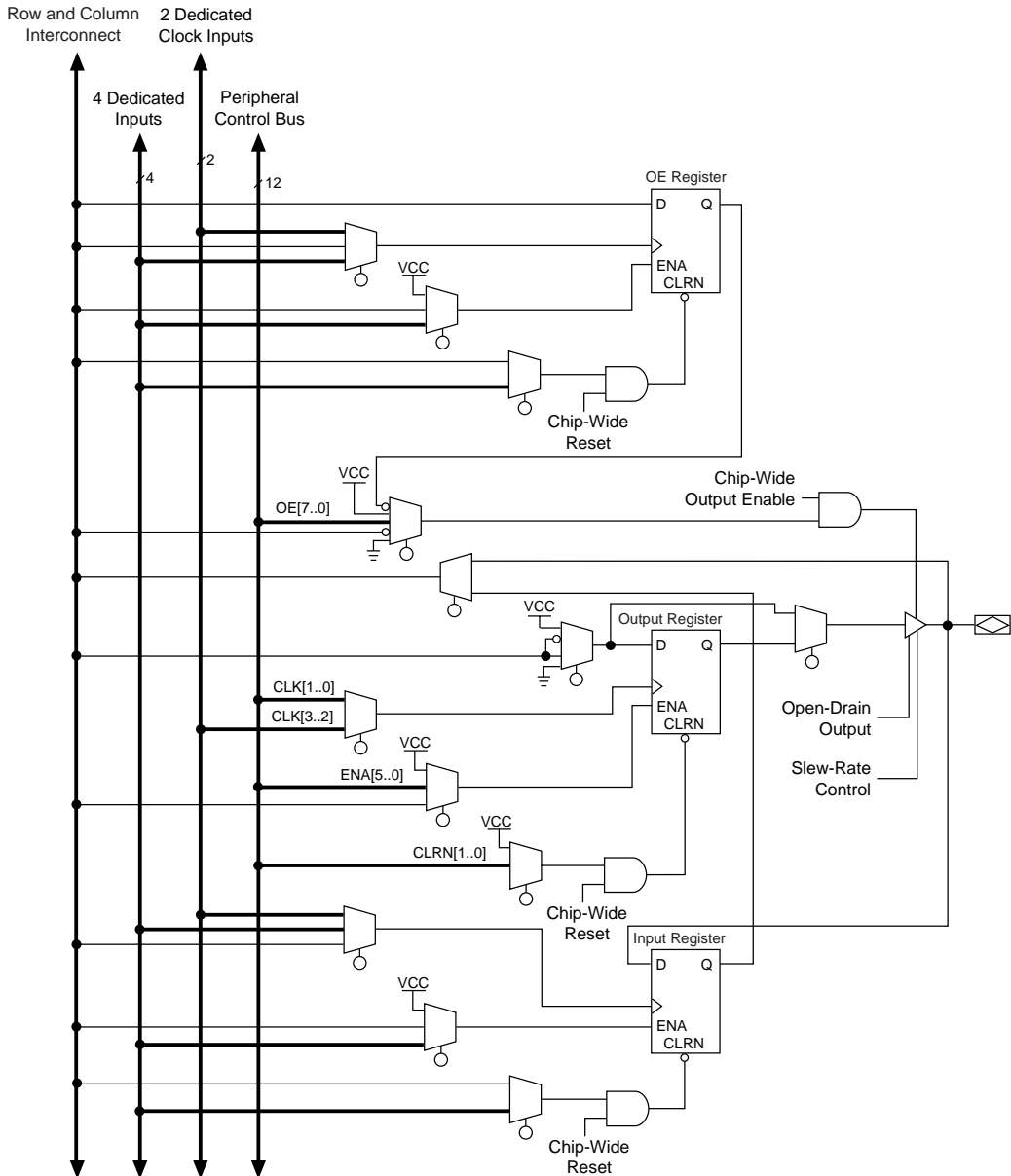
**Table 7** summarizes the FastTrack Interconnect resources available in each FLEX 10K device.

<b>Table 7. FLEX 10K FastTrack Interconnect Resources</b>				
<b>Device</b>	<b>Rows</b>	<b>Channels per Row</b>	<b>Columns</b>	<b>Channels per Column</b>
EPF10K10 EPF10K10A	3	144	24	24
EPF10K20	6	144	24	24
EPF10K30 EPF10K30A	6	216	36	24
EPF10K40	8	216	36	24
EPF10K50 EPF10K50V	10	216	36	24
EPF10K70	9	312	52	24
EPF10K100 EPF10K100A	12	312	52	24
EPF10K130V	16	312	52	32
EPF10K250A	20	456	76	40

In addition to general-purpose I/O pins, FLEX 10K devices have six dedicated input pins that provide low-skew signal distribution across the device. These six inputs can be used for global clock, clear, preset, and peripheral output enable and clock enable control signals. These signals are available as control signals for all LABs and IOEs in the device.

The dedicated inputs can also be used as general-purpose data inputs because they can feed the local interconnect of each LAB in the device. However, the use of dedicated inputs as data inputs can introduce additional delay into the control signal network.

Figure 13. Bidirectional I/O Registers



Each IOE selects the clock, clear, clock enable, and output enable controls from a network of I/O control signals called the peripheral control bus. The peripheral control bus uses high-speed drivers to minimize signal skew across devices; it provides up to 12 peripheral control signals that can be allocated as follows:

- Up to eight output enable signals
- Up to six clock enable signals
- Up to two clock signals
- Up to two clear signals

If more than six clock enable or eight output enable signals are required, each IOE on the device can be controlled by clock enable and output enable signals driven by specific LEs. In addition to the two clock signals available on the peripheral control bus, each IOE can use one of two dedicated clock pins. Each peripheral control signal can be driven by any of the dedicated input pins or the first LE of each LAB in a particular row. In addition, an LE in a different row can drive a column interconnect, which causes a row interconnect to drive the peripheral control signal. The chip-wide reset signal will reset all IOE registers, overriding any other control signals.

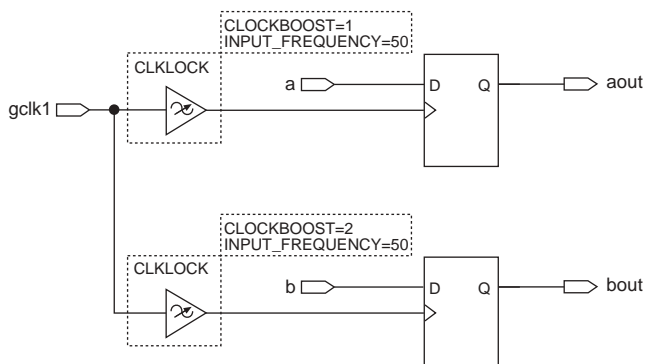
Tables 8 and 9 list the sources for each peripheral control signal, and the rows that can drive global signals. These tables also show how the output enable, clock enable, clock, and clear signals share 12 peripheral control signals.

Table 10 lists the FLEX 10K row-to-IOE interconnect resources.

<b>Table 10. FLEX 10K Row-to-IOE Interconnect Resources</b>		
<b>Device</b>	<b>Channels per Row (<i>n</i>)</b>	<b>Row Channels per Pin (<i>m</i>)</b>
EPF10K10 EPF10K10A	144	18
EPF10K20	144	18
EPF10K30 EPF10K30A	216	27
EPF10K40	216	27
EPF10K50 EPF10K50V	216	27
EPF10K70	312	39
EPF10K100 EPF10K100A	312	39
EPF10K130V	312	39
EPF10K250A	456	57

#### *Column-to-IOE Connections*

When an IOE is used as an input, it can drive up to two separate column channels. When an IOE is used as an output, the signal is driven by a multiplexer that selects a signal from the column channels. Two IOEs connect to each side of the column channels. Each IOE can be driven by column channels via a multiplexer. The set of column channels that each IOE can access is different for each IOE. See Figure 15.

**Figure 17. Enabling ClockLock & ClockBoost in the Same Design**

To use both the ClockLock and ClockBoost circuits in the same design, designers must use Revision C EPF10K100GC503-3DX devices and MAX+PLUS II software versions 7.2 or higher. The die revision is indicated by the third digit of the nine-digit code on the top side of the device.

## Output Configuration

This section discusses the peripheral component interconnect (PCI) pull-up clamping diode option, slew-rate control, open-drain output option, MultiVolt I/O interface, and power sequencing for FLEX 10K devices. The PCI pull-up clamping diode, slew-rate control, and open-drain output options are controlled pin-by-pin via Altera logic options. The MultiVolt I/O interface is controlled by connecting  $V_{CCIO}$  to a different voltage than  $V_{CCINT}$ . Its effect can be simulated in the Altera software via the **Global Project Device Options** dialog box (Assign menu).

### PCI Clamping Diodes

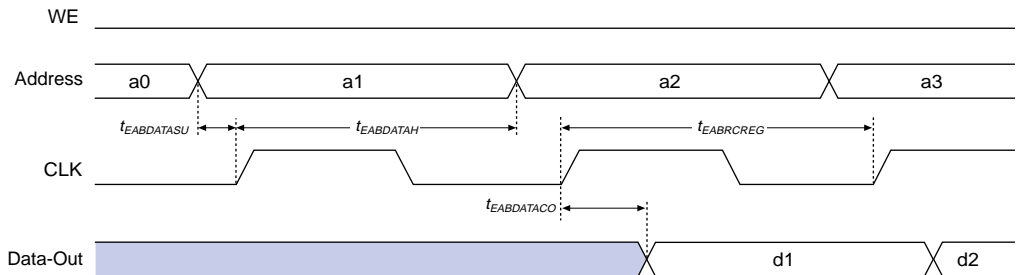
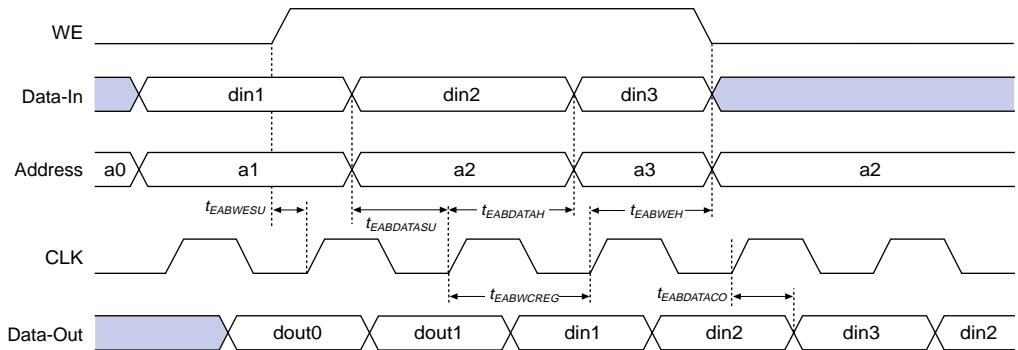
The EPF10K10A and EPF10K30A devices have a pull-up clamping diode on every I/O, dedicated input, and dedicated clock pin. PCI clamping diodes clamp the transient overshoot caused by reflected waves to the  $V_{CCIO}$  value and are required for 3.3-V PCI compliance. Clamping diodes can also be used to limit overshoot in other systems.

Clamping diodes are controlled on a pin-by-pin basis via a logic option in the Altera software. When  $V_{CCIO}$  is 3.3 V, a pin that has the clamping diode turned on can be driven by a 2.5-V or 3.3-V signal, but not a 5.0-V signal. When  $V_{CCIO}$  is 2.5 V, a pin that has the clamping diode turned on can be driven by a 2.5-V signal, but not a 3.3-V or 5.0-V signal. However, a clamping diode can be turned on for a subset of pins, which allows devices to bridge between a 3.3-V PCI bus and a 5.0-V device.



**Table 18. FLEX 10K 5.0-V Device Recommended Operating Conditions**

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CCINT}$	Supply voltage for internal logic and input buffers	(3), (4)	4.75 (4.50)	5.25 (5.50)	V
$V_{CCIO}$	Supply voltage for output buffers, 5.0-V operation	(3), (4)	4.75 (4.50)	5.25 (5.50)	V
	Supply voltage for output buffers, 3.3-V operation	(3), (4)	3.00 (3.00)	3.60 (3.60)	V
$V_I$	Input voltage		−0.5	$V_{CCINT} + 0.5$	V
$V_O$	Output voltage		0	$V_{CCIO}$	V
$T_A$	Ambient temperature	For commercial use	0	70	° C
		For industrial use	−40	85	° C
$T_J$	Operating temperature	For commercial use	0	85	° C
		For industrial use	−40	100	° C
$t_R$	Input rise time			40	ns
$t_F$	Input fall time			40	ns

**Figure 30. EAB Synchronous Timing Waveforms****EAB Synchronous Read****EAB Synchronous Write (EAB Output Registers Used)**

**Table 41. EPF10K10 & EPF10K20 Device EAB Internal Microparameters** *Note (1)*

Symbol	-3 Speed Grade		-4 Speed Grade		Unit
	Min	Max	Min	Max	
$t_{EABDATA1}$		1.5		1.9	ns
$t_{EABDATA2}$		4.8		6.0	ns
$t_{EABWE1}$		1.0		1.2	ns
$t_{EABWE2}$		5.0		6.2	ns
$t_{EABCLK}$		1.0		2.2	ns
$t_{EABCO}$		0.5		0.6	ns
$t_{EABYPASS}$		1.5		1.9	ns
$t_{EABSU}$	1.5		1.8		ns
$t_{EABH}$	2.0		2.5		ns
$t_{AA}$		8.7		10.7	ns
$t_{WP}$	5.8		7.2		ns
$t_{WDSU}$	1.6		2.0		ns
$t_{WDH}$	0.3		0.4		ns
$t_{WASU}$	0.5		0.6		ns
$t_{WAH}$	1.0		1.2		ns
$t_{WO}$		5.0		6.2	ns
$t_{DD}$		5.0		6.2	ns
$t_{EABOUT}$		0.5		0.6	ns
$t_{EABCH}$	4.0		4.0		ns
$t_{EABCL}$	5.8		7.2		ns

**Table 43. EPF10K10 Device Interconnect Timing Microparameters** *Note (1)*

Symbol	-3 Speed Grade		-4 Speed Grade		Unit
	Min	Max	Min	Max	
$t_{DIN2IOE}$		4.8		6.2	ns
$t_{DIN2LE}$		2.6		3.8	ns
$t_{DIN2DATA}$		4.3		5.2	ns
$t_{DCLK2IOE}$		3.4		4.0	ns
$t_{DCLK2LE}$		2.6		3.8	ns
$t_{SAMELAB}$		0.6		0.6	ns
$t_{SAMEROW}$		3.6		3.8	ns
$t_{SAMECOLUMN}$		0.9		1.1	ns
$t_{DIFFROW}$		4.5		4.9	ns
$t_{TWOROWS}$		8.1		8.7	ns
$t_{LEPERIPH}$		3.3		3.9	ns
$t_{LABCARRY}$		0.5		0.8	ns
$t_{LABCASC}$		2.7		3.0	ns

**Table 44. EPF10K20 Device Interconnect Timing Microparameters** *Note (1)*

Symbol	-3 Speed Grade		-4 Speed Grade		Unit
	Min	Max	Min	Max	
$t_{DIN2IOE}$		5.2		6.6	ns
$t_{DIN2LE}$		2.6		3.8	ns
$t_{DIN2DATA}$		4.3		5.2	ns
$t_{DCLK2IOE}$		4.3		4.0	ns
$t_{DCLK2LE}$		2.6		3.8	ns
$t_{SAMELAB}$		0.6		0.6	ns
$t_{SAMEROW}$		3.7		3.9	ns
$t_{SAMECOLUMN}$		1.4		1.6	ns
$t_{DIFFROW}$		5.1		5.5	ns
$t_{TWOROWS}$		8.8		9.4	ns
$t_{LEPERIPH}$		4.7		5.6	ns
$t_{LABCARRY}$		0.5		0.8	ns
$t_{LABCASC}$		2.7		3.0	ns

**Table 59. EPF10K70 Device EAB Internal Microparameters** *Note (1)*

Symbol	-2 Speed Grade		-3 Speed Grade		-4 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{EABDATA1}$		1.3		1.5		1.9	ns
$t_{EABDATA2}$		4.3		4.8		6.0	ns
$t_{EABWE1}$		0.9		1.0		1.2	ns
$t_{EABWE2}$		4.5		5.0		6.2	ns
$t_{EABCLK}$		0.9		1.0		2.2	ns
$t_{EABCO}$		0.4		0.5		0.6	ns
$t_{EABYPASS}$		1.3		1.5		1.9	ns
$t_{EABSU}$	1.3		1.5		1.8		ns
$t_{EABH}$	1.8		2.0		2.5		ns
$t_{AA}$		7.8		8.7		10.7	ns
$t_{WP}$	5.2		5.8		7.2		ns
$t_{WDSU}$	1.4		1.6		2.0		ns
$t_{WDH}$	0.3		0.3		0.4		ns
$t_{WASU}$	0.4		0.5		0.6		ns
$t_{WAH}$	0.9		1.0		1.2		ns
$t_{WO}$		4.5		5.0		6.2	ns
$t_{DD}$		4.5		5.0		6.2	ns
$t_{EABOUT}$		0.4		0.5		0.6	ns
$t_{EABCH}$	4.0		4.0		4.0		ns
$t_{EABCL}$	5.2		5.8		7.2		ns

**Table 68. EPF10K100 Device Interconnect Timing Microparameters** *Note (1)*

Symbol	-3DX Speed Grade		-3 Speed Grade		-4 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{DIN2IOE}$		10.3		10.3		12.2	ns
$t_{DIN2LE}$		4.8		4.8		6.0	ns
$t_{DIN2DATA}$		7.3		7.3		11.0	ns
$t_{DCLK2IOE}$ without ClockLock or ClockBoost circuitry		6.2		6.2		7.7	ns
$t_{DCLK2IOE}$ with ClockLock or ClockBoost circuitry		2.3		–		–	ns
$t_{DCLK2LE}$ without ClockLock or ClockBoost circuitry		4.8		4.8		6.0	ns
$t_{DCLK2LE}$ with ClockLock or ClockBoost circuitry		2.3		–		–	ns
$t_{SAMELAB}$		0.4		0.4		0.5	ns
$t_{SAMEROW}$		4.9		4.9		5.5	ns
$t_{SAMECOLUMN}$		5.1		5.1		5.4	ns
$t_{DIFFROW}$		10.0		10.0		10.9	ns
$t_{TWOROWS}$		14.9		14.9		16.4	ns
$t_{LEPERIPH}$		6.9		6.9		8.1	ns
$t_{LABCARRY}$		0.9		0.9		1.1	ns
$t_{LABCASC}$		3.0		3.0		3.2	ns

**Table 74. EPF10K50V Device EAB Internal Timing Macroparameters** *Note (1)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		-4 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
$t_{EABAA}$		9.5		13.6		16.5		20.8	ns
$t_{EABRCCOMB}$	9.5		13.6		16.5		20.8		ns
$t_{EABRCREG}$	6.1		8.8		10.8		13.4		ns
$t_{EABWP}$	6.0		4.9		6.0		7.4		ns
$t_{EABWCCOMB}$	6.2		6.1		7.5		9.2		ns
$t_{EABWCREG}$	12.0		11.6		14.2		17.4		ns
$t_{EABDD}$		6.8		9.7		11.8		14.9	ns
$t_{EABDATACO}$		1.0		1.4		1.8		2.2	ns
$t_{EABDATASU}$	5.3		4.6		5.6		6.9		ns
$t_{EABDATAH}$	0.0		0.0		0.0		0.0		ns
$t_{EABWESU}$	4.4		4.8		5.8		7.2		ns
$t_{EABWEH}$	0.0		0.0		0.0		0.0		ns
$t_{EABWDSU}$	1.8		1.1		1.4		2.1		ns
$t_{EABWDH}$	0.0		0.0		0.0		0.0		ns
$t_{EABWASU}$	4.5		4.6		5.6		7.4		ns
$t_{EABWAH}$	0.0		0.0		0.0		0.0		ns
$t_{EABWO}$		5.1		9.4		11.4		14.0	ns

**Table 86. EPF10K10A Device IOE Timing Microparameters** *Note (1) (Part 2 of 2)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{IOH}$	0.8		1.0		1.3		ns
$t_{IOCLR}$		1.2		1.4		1.9	ns
$t_{OD1}$		1.2		1.4		1.9	ns
$t_{OD2}$		2.9		3.5		4.7	ns
$t_{OD3}$		6.6		7.8		10.5	ns
$t_{XZ}$		1.2		1.4		1.9	ns
$t_{ZX1}$		1.2		1.4		1.9	ns
$t_{ZX2}$		2.9		3.5		4.7	ns
$t_{ZX3}$		6.6		7.8		10.5	ns
$t_{INREG}$		5.2		6.3		8.4	ns
$t_{IOFD}$		3.1		3.8		5.0	ns
$t_{INCOMB}$		3.1		3.8		5.0	ns



**Table 89. EPF10K10A Device Interconnect Timing Microparameters** *Note (1)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{DIN2IOE}$		4.2		5.0		6.5	ns
$t_{DIN2LE}$		2.2		2.6		3.4	ns
$t_{DIN2DATA}$		4.3		5.2		7.1	ns
$t_{DCLK2IOE}$		4.2		4.9		6.6	ns
$t_{DCLK2LE}$		2.2		2.6		3.4	ns
$t_{SAMELAB}$		0.1		0.1		0.2	ns
$t_{SAMEROW}$		2.2		2.4		2.9	ns
$t_{SAMECOLUMN}$		0.8		1.0		1.4	ns
$t_{DIFFROW}$		3.0		3.4		4.3	ns
$t_{TWOROWS}$		5.2		5.8		7.2	ns
$t_{LEPERIPH}$		1.8		2.2		2.8	ns
$t_{LABCARRY}$		0.5		0.5		0.7	ns
$t_{LABCASC}$		0.9		1.0		1.5	ns

**Table 90. EPF10K10A External Reference Timing Parameters** *Note (1)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{DRR}$		10.0		12.0		16.0	ns
$t_{INSU}$ (2), (3)	1.6		2.1		2.8		ns
$t_{INH}$ (3)	0.0		0.0		0.0		ns
$t_{OUTCO}$ (3)	2.0	5.8	2.0	6.9	2.0	9.2	ns

**Table 91. EPF10K10A Device External Bidirectional Timing Parameters** *Note (1)*

Symbol	-2 Speed Grade		-3 Speed Grade		-4 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{INSUBIDIR}$	2.4		3.3		4.5		ns
$t_{INHBIDIR}$	0.0		0.0		0.0		ns
$t_{OUTCOBIDIR}$	2.0	5.8	2.0	6.9	2.0	9.2	ns
$t_{XZBIDIR}$		6.3		7.5		9.9	ns
$t_{ZXBIDIR}$		6.3		7.5		9.9	ns

**Notes to tables:**

- (1) All timing parameters are described in Tables 32 through 38 in this data sheet.
- (2) Using an LE to register the signal may provide a lower setup time.
- (3) This parameter is specified by characterization.

Tables 99 through 105 show EPF10K100A device internal and external timing parameters.

**Table 99. EPF10K100A Device LE Timing Microparameters** *Note (1)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{LUT}$		1.0		1.2		1.4	ns
$t_{CLUT}$		0.8		0.9		1.1	ns
$t_{RLUT}$		1.4		1.6		1.9	ns
$t_{PACKED}$		0.4		0.5		0.5	ns
$t_{EN}$		0.6		0.7		0.8	ns
$t_{CICO}$		0.2		0.2		0.3	ns
$t_{CGEN}$		0.4		0.4		0.6	ns
$t_{CGENR}$		0.6		0.7		0.8	ns
$t_{CASC}$		0.7		0.9		1.0	ns
$t_C$		0.9		1.0		1.2	ns
$t_{CO}$		0.2		0.3		0.3	ns
$t_{COMB}$		0.6		0.7		0.8	ns
$t_{SU}$	0.8		1.0		1.2		ns
$t_H$	0.3		0.5		0.5		ns
$t_{PRE}$		0.3		0.3		0.4	ns
$t_{CLR}$		0.3		0.3		0.4	ns
$t_{CH}$	2.5		3.5		4.0		ns
$t_{CL}$	2.5		3.5		4.0		ns

**Table 110. EPF10K250A Device Interconnect Timing Microparameters** *Note (1)*

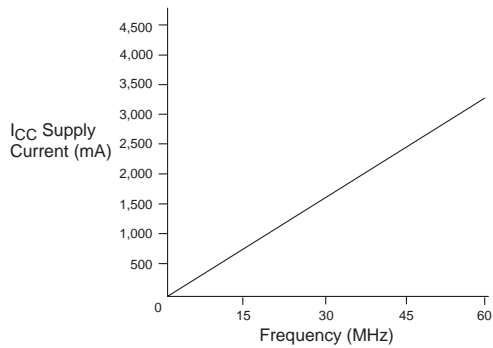
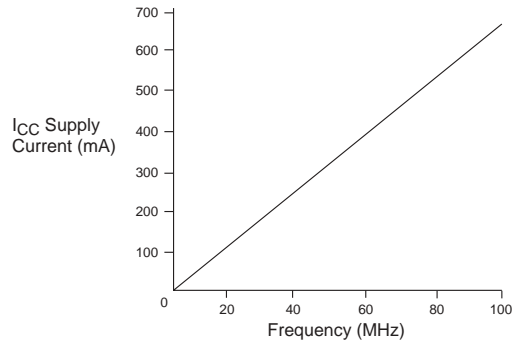
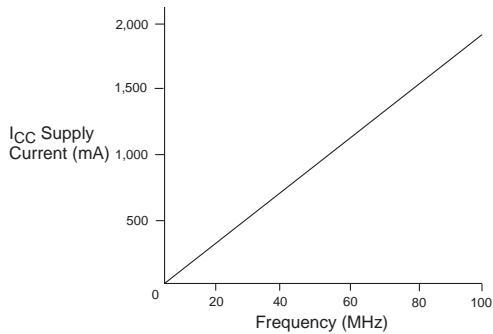
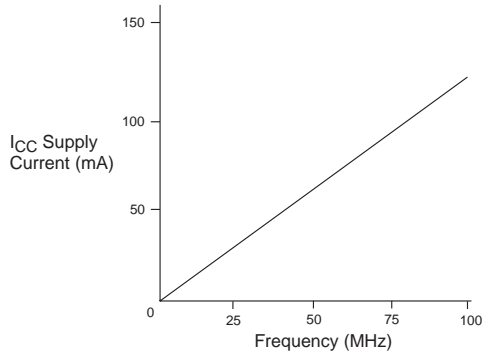
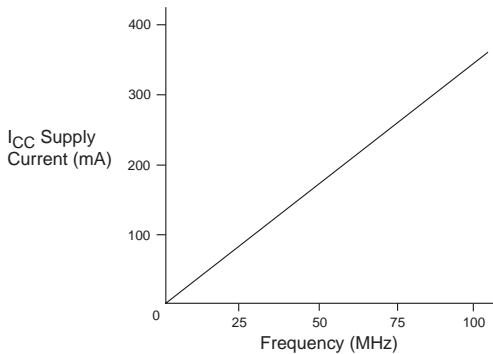
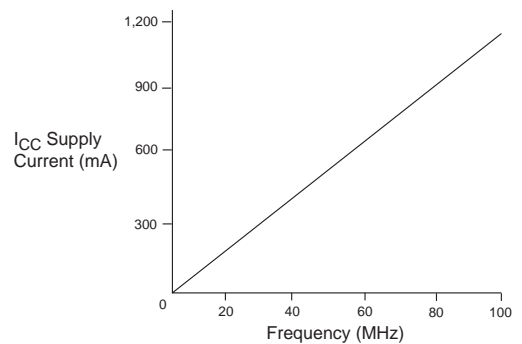
Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{DIN2IOE}$		7.8		8.5		9.4	ns
$t_{DIN2LE}$		2.7		3.1		3.5	ns
$t_{DIN2DATA}$		1.6		1.6		1.7	ns
$t_{DCLK2IOE}$		3.6		4.0		4.6	ns
$t_{DCLK2LE}$		2.7		3.1		3.5	ns
$t_{SAMELAB}$		0.2		0.3		0.3	ns
$t_{SAMEROW}$		6.7		7.3		8.2	ns
$t_{SAMECOLUMN}$		2.5		2.7		3.0	ns
$t_{DIFFROW}$		9.2		10.0		11.2	ns
$t_{TWOROWS}$		15.9		17.3		19.4	ns
$t_{LEPERIPH}$		7.5		8.1		8.9	ns
$t_{LABCARRY}$		0.3		0.4		0.5	ns
$t_{LABCASC}$		0.4		0.4		0.5	ns

**Table 111. EPF10K250A Device External Reference Timing Parameters** *Note (1)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{DRR}$		15.0		17.0		20.0	ns
$t_{INSU}$ (2), (3)	6.9		8.0		9.4		ns
$t_{INH}$ (3)	0.0		0.0		0.0		ns
$t_{OUTCO}$ (3)	2.0	8.0	2.0	8.9	2.0	10.4	ns

**Table 112. EPF10K250A Device External Bidirectional Timing Parameters** *Note (1)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{INSUBIDIR}$	9.3		10.6		12.7		ns
$t_{INHBIDIR}$	0.0		0.0		0.0		ns
$t_{OUTCOBIDIR}$	2.0	8.0	2.0	8.9	2.0	10.4	ns
$t_{XZBIDIR}$		10.8		12.2		14.2	ns
$t_{ZXBIDIR}$		10.8		12.2		14.2	ns

**Figure 32.  $I_{CCACTIVE}$  vs. Operating Frequency (Part 2 of 3)****EPF10K100****EPF10K50V****EPF10K130V****EPF10K10A****EPF10K30A****EPF10K100A**

Multiple FLEX 10K devices can be configured in any of the five configuration schemes by connecting the configuration enable (nCE) and configuration enable output (nCEO) pins on each device.

**Table 116. Data Sources for Configuration**

Configuration Scheme	Data Source
Configuration device	EPC1, EPC2, EPC16, or EPC1441 configuration device
Passive serial (PS)	BitBlaster, MasterBlaster, or ByteBlasterMV download cable, or serial data source
Passive parallel asynchronous (PPA)	Parallel data source
Passive parallel synchronous (PPS)	Parallel data source
JTAG	BitBlaster, MasterBlaster, or ByteBlasterMV download cable, or microprocessor with Jam STAPL file or Jam Byte-Code file

## Device Pin-Outs

See the Altera web site (<http://www.altera.com>) or the Altera Digital Library for pin-out information.

## Revision History

The information contained in the *FLEX 10K Embedded Programmable Logic Device Family Data Sheet* version 4.2 supersedes information published in previous versions.

### Version 4.2 Changes

The following change was made to version 4.2 of the *FLEX 10K Embedded Programmable Logic Device Family Data Sheet*: updated [Figure 13](#).

### Version 4.1 Changes

The following changes were made to version 4.1 of the *FLEX 10K Embedded Programmable Logic Device Family Data Sheet*.

- Updated General Description section
- Updated I/O Element section
- Updated SameFrame Pin-Outs section
- Updated Figure 16
- Updated Tables 13 and 116
- Added Note 9 to Table 19
- Added Note 10 to Table 24
- Added Note 10 to Table 28