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Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

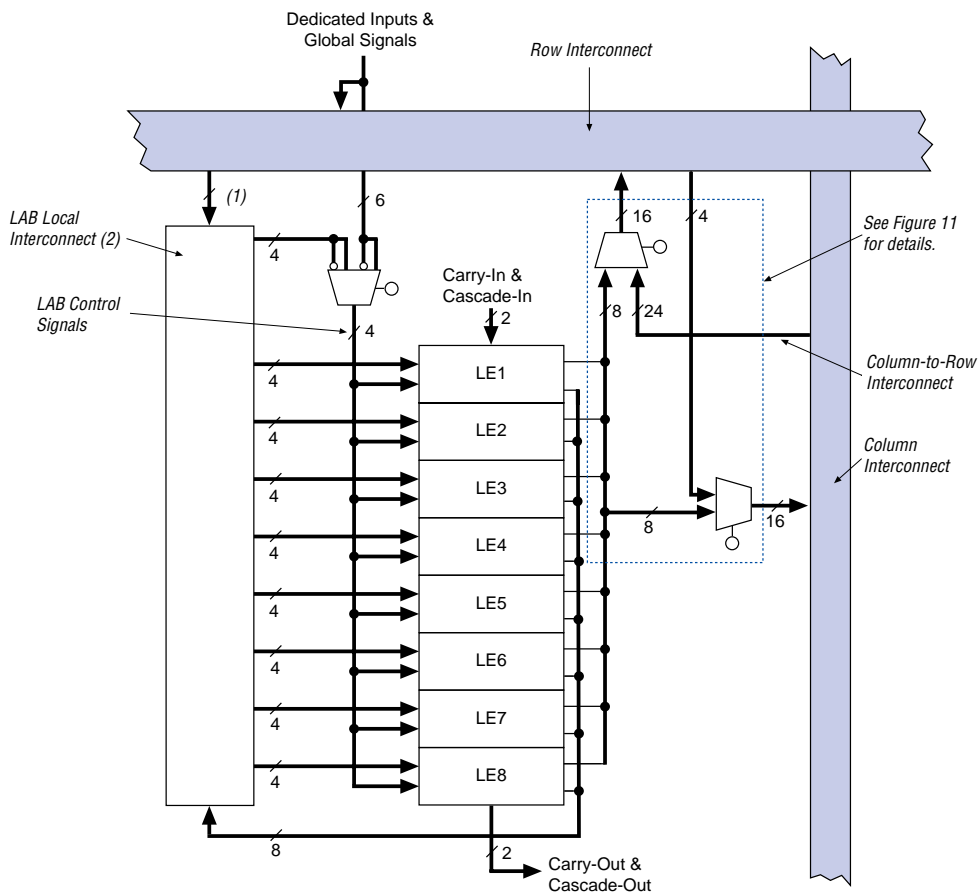
Details

| | |
|--------------------------------|---|
| Product Status | Obsolete |
| Number of LABs/CLBs | 216 |
| Number of Logic Elements/Cells | 1728 |
| Total RAM Bits | 12288 |
| Number of I/O | 147 |
| Number of Gates | 69000 |
| Voltage - Supply | 3V ~ 3.6V |
| Mounting Type | Surface Mount |
| Operating Temperature | -40°C ~ 85°C (TA) |
| Package / Case | 208-BFQFP |
| Supplier Device Package | 208-PQFP (28x28) |
| Purchase URL | https://www.e-xfl.com/product-detail/intel/epf10k30aqi208-3n |

Logic Array Block

Each LAB consists of eight LEs, their associated carry and cascade chains, LAB control signals, and the LAB local interconnect. The LAB provides the coarse-grained structure to the FLEX 10K architecture, facilitating efficient routing with optimum device utilization and high performance. See [Figure 5](#).

Figure 5. FLEX 10K LAB



Notes:

- (1) EPF10K10, EPF10K10A, EPF10K20, EPF10K30, EPF10K30A, EPF10K40, EPF10K50, and EPF10K50V devices have 22 inputs to the LAB local interconnect channel from the row; EPF10K70, EPF10K100, EPF10K100A, EPF10K130V, and EPF10K250A devices have 26.
- (2) EPF10K10, EPF10K10A, EPF10K20, EPF10K30, EPF10K30A, EPF10K40, EPF10K50, and EPF10K50V devices have 30 LAB local interconnect channels; EPF10K70, EPF10K100, EPF10K100A, EPF10K130V, and EPF10K250A devices have 34 LABs.

Each LAB provides four control signals with programmable inversion that can be used in all eight LEs. Two of these signals can be used as clocks; the other two can be used for clear/preset control. The LAB clocks can be driven by the dedicated clock input pins, global signals, I/O signals, or internal signals via the LAB local interconnect. The LAB preset and clear control signals can be driven by the global signals, I/O signals, or internal signals via the LAB local interconnect. The global control signals are typically used for global clock, clear, or preset signals because they provide asynchronous control with very low skew across the device. If logic is required on a control signal, it can be generated in one or more LEs in any LAB and driven into the local interconnect of the target LAB. In addition, the global control signals can be generated from LE outputs.

Logic Element

The LE, the smallest unit of logic in the FLEX 10K architecture, has a compact size that provides efficient logic utilization. Each LE contains a four-input LUT, which is a function generator that can quickly compute any function of four variables. In addition, each LE contains a programmable flipflop with a synchronous enable, a carry chain, and a cascade chain. Each LE drives both the local and the FastTrack Interconnect. See [Figure 6](#).

Figure 6. FLEX 10K Logic Element

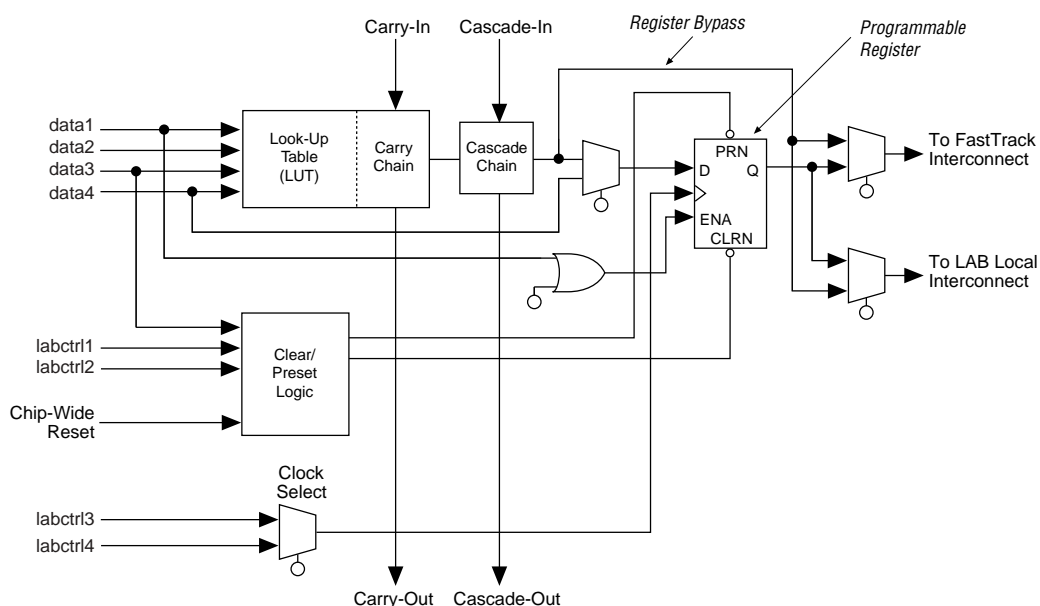


Figure 7 shows how an n -bit full adder can be implemented in $n + 1$ LEs with the carry chain. One portion of the LUT generates the sum of two bits using the input signals and the carry-in signal; the sum is routed to the output of the LE. The register can either be bypassed for simple adders or be used for an accumulator function. The carry chain logic generates the carry-out signal, which is routed directly to the carry-in signal of the next higher-order bit. The final carry-out signal is routed to an LE, where it can be used as a general-purpose signal.

Figure 7. Carry Chain Operation (n -bit Full Adder)

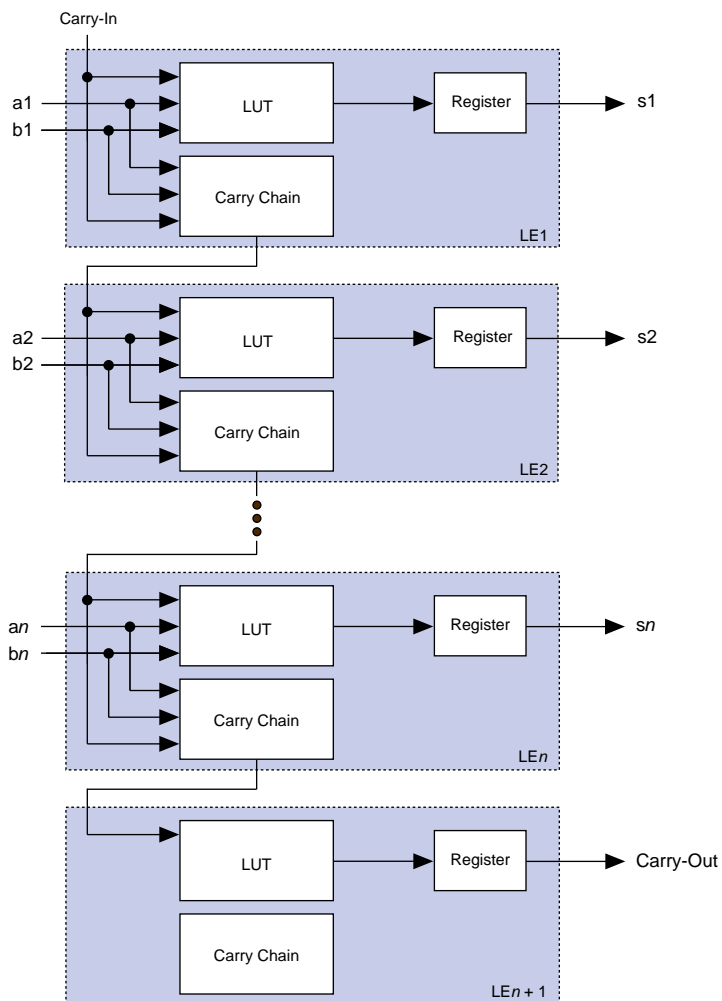


Figure 15. FLEX 10K Column-to-IOE Connections

The values for m and n are provided in Table 11.

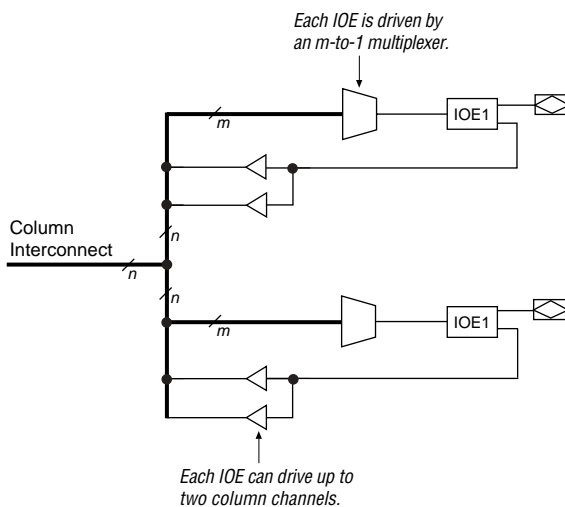


Table 11 lists the FLEX 10K column-to-IOE interconnect resources.

| Table 11. FLEX 10K Column-to-IOE Interconnect Resources | | |
|--|---|--|
| Device | Channels per Column (n) | Column Channel per Pin (m) |
| EPF10K10 EPF10K10A | 24 | 16 |
| EPF10K20 | 24 | 16 |
| EPF10K30 EPF10K30A | 24 | 16 |
| EPF10K40 | 24 | 16 |
| EPF10K50 EPF10K50V | 24 | 16 |
| EPF10K70 | 24 | 16 |
| EPF10K100 EPF10K100A | 24 | 16 |
| EPF10K130V | 32 | 24 |
| EPF10K250A | 40 | 32 |

ClockLock & ClockBoost Features

To support high-speed designs, selected FLEX 10K devices offer optional ClockLock and ClockBoost circuitry containing a phase-locked loop (PLL) that is used to increase design speed and reduce resource usage. The ClockLock circuitry uses a synchronizing PLL that reduces the clock delay and skew within a device. This reduction minimizes clock-to-output and setup times while maintaining zero hold times. The ClockBoost circuitry, which provides a clock multiplier, allows the designer to enhance device area efficiency by sharing resources within the device. The ClockBoost feature allows the designer to distribute a low-speed clock and multiply that clock on-device. Combined, the ClockLock and ClockBoost features provide significant improvements in system performance and bandwidth.

The ClockLock and ClockBoost features in FLEX 10K devices are enabled through the Altera software. External devices are not required to use these features. The output of the ClockLock and ClockBoost circuits is not available at any of the device pins.

The ClockLock and ClockBoost circuitry locks onto the rising edge of the incoming clock. The circuit output can only drive the clock inputs of registers; the generated clock cannot be gated or inverted.

The dedicated clock pin (GCLK1) supplies the clock to the ClockLock and ClockBoost circuitry. When the dedicated clock pin is driving the ClockLock or ClockBoost circuitry, it cannot drive elsewhere in the device.

In designs that require both a multiplied and non-multiplied clock, the clock trace on the board can be connected to GCLK1. With the Altera software, GCLK1 can feed both the ClockLock and ClockBoost circuitry in the FLEX 10K device. However, when both circuits are used, the other clock pin (GCLK0) cannot be used. [Figure 17](#) shows a block diagram of how to enable both the ClockLock and ClockBoost circuits in the Altera software. The example shown is a schematic, but a similar approach applies for designs created in AHDL, VHDL, and Verilog HDL. When the ClockLock and ClockBoost circuits are used simultaneously, the input frequency parameter must be the same for both circuits. In [Figure 17](#), the input frequency must meet the requirements specified when the ClockBoost multiplication factor is two.

Figure 18 shows the timing requirements for the JTAG signals.

Figure 18. JTAG Waveforms

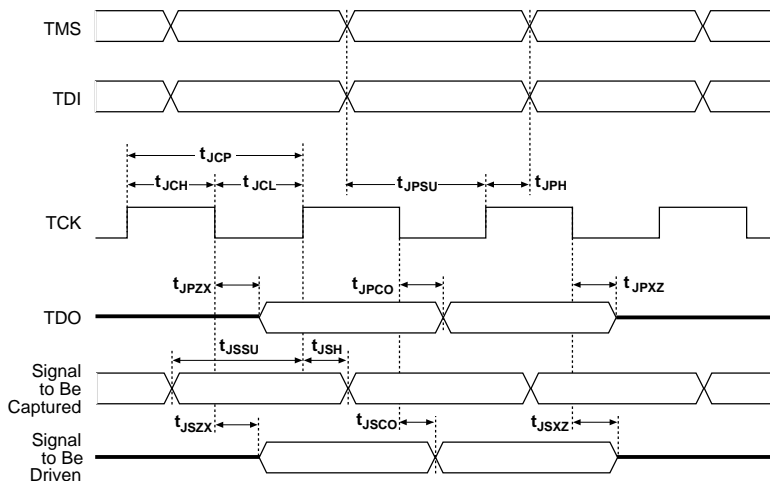


Table 16 shows the timing parameters and values for FLEX 10K devices.

Table 16. JTAG Timing Parameters & Values

| Symbol | Parameter | Min | Max | Unit |
|------------|--|-----|-----|------|
| t_{JCP} | TCK clock period | 100 | | ns |
| t_{JCH} | TCK clock high time | 50 | | ns |
| t_{JCL} | TCK clock low time | 50 | | ns |
| t_{JPSU} | JTAG port setup time | 20 | | ns |
| t_{JPH} | JTAG port hold time | 45 | | ns |
| t_{JPCO} | JTAG port clock to output | | 25 | ns |
| t_{JPZX} | JTAG port high impedance to valid output | | 25 | ns |
| t_{JPXZ} | JTAG port valid output to high impedance | | 25 | ns |
| t_{JSSU} | Capture register setup time | 20 | | ns |
| t_{JSH} | Capture register hold time | 45 | | ns |
| t_{JSCO} | Update register clock to output | | 35 | ns |
| t_{JSZX} | Update register high-impedance to valid output | | 35 | ns |
| t_{JSXZ} | Update register valid output to high impedance | | 35 | ns |

Table 18. FLEX 10K 5.0-V Device Recommended Operating Conditions

| Symbol | Parameter | Conditions | Min | Max | Unit |
|-------------|---|--------------------|-------------|-------------------|------|
| V_{CCINT} | Supply voltage for internal logic and input buffers | (3), (4) | 4.75 (4.50) | 5.25 (5.50) | V |
| V_{CCIO} | Supply voltage for output buffers, 5.0-V operation | (3), (4) | 4.75 (4.50) | 5.25 (5.50) | V |
| | Supply voltage for output buffers, 3.3-V operation | (3), (4) | 3.00 (3.00) | 3.60 (3.60) | V |
| V_I | Input voltage | | −0.5 | $V_{CCINT} + 0.5$ | V |
| V_O | Output voltage | | 0 | V_{CCIO} | V |
| T_A | Ambient temperature | For commercial use | 0 | 70 | ° C |
| | | For industrial use | −40 | 85 | ° C |
| T_J | Operating temperature | For commercial use | 0 | 85 | ° C |
| | | For industrial use | −40 | 100 | ° C |
| t_R | Input rise time | | | 40 | ns |
| t_F | Input fall time | | | 40 | ns |

Table 27. FLEX 10KA 3.3-V Device Recommended Operating Conditions

| Symbol | Parameter | Conditions | Min | Max | Unit |
|-------------|---|--------------------|-------------|-------------|------|
| V_{CCINT} | Supply voltage for internal logic and input buffers | (3), (4) | 3.00 (3.00) | 3.60 (3.60) | V |
| V_{CCIO} | Supply voltage for output buffers, 3.3-V operation | (3), (4) | 3.00 (3.00) | 3.60 (3.60) | V |
| | Supply voltage for output buffers, 2.5-V operation | (3), (4) | 2.30 (2.30) | 2.70 (2.70) | V |
| V_I | Input voltage | (5) | −0.5 | 5.75 | V |
| V_O | Output voltage | | 0 | V_{CCIO} | V |
| T_A | Ambient temperature | For commercial use | 0 | 70 | ° C |
| | | For industrial use | −40 | 85 | ° C |
| T_J | Operating temperature | For commercial use | 0 | 85 | ° C |
| | | For industrial use | −40 | 100 | ° C |
| t_R | Input rise time | | | 40 | ns |
| t_F | Input fall time | | | 40 | ns |

Figure 22 shows the typical output drive characteristics of EPF10K10A, EPF10K30A, EPF10K100A, and EPF10K250A devices with 3.3-V and 2.5-V V_{CCIO} . The output driver is compliant with the 3.3-V *PCI Local Bus Specification, Revision 2.2* (with 3.3-V V_{CCIO}). Moreover, device analysis shows that the EPF10K10A, EPF10K30A, and EPF 10K100A devices can drive a 5.0-V PCI bus with eight or fewer loads.

Figure 22. Output Drive Characteristics for EPF10K10A, EPF10K30A & EPF10K100A Devices

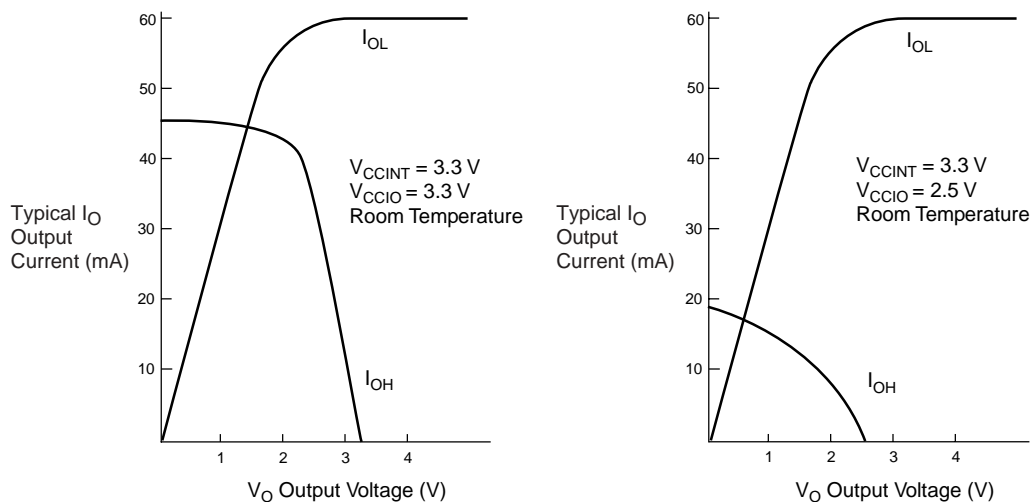
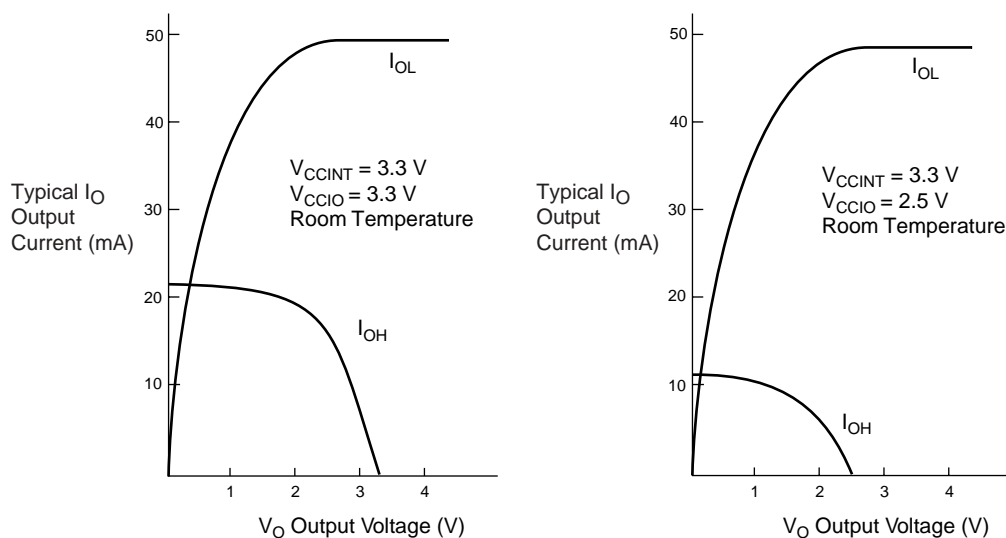


Figure 23 shows the typical output drive characteristics of the EPF10K250A device with 3.3-V and 2.5-V V_{CCIO} .

Figure 23. Output Drive Characteristics for EPF10K250A Device

Timing Model

The continuous, high-performance FastTrack Interconnect routing resources ensure predictable performance and accurate simulation and timing analysis. This predictable performance contrasts with that of FPGAs, which use a segmented connection scheme and therefore have unpredictable performance.

Device performance can be estimated by following the signal path from a source, through the interconnect, to the destination. For example, the registered performance between two LEs on the same row can be calculated by adding the following parameters:

- LE register clock-to-output delay (t_{CO})
- Interconnect delay ($t_{S\text{AMEROW}}$)
- LE look-up table delay (t_{LUT})
- LE register setup time (t_{SU})

The routing delay depends on the placement of the source and destination LEs. A more complex registered path may involve multiple combinatorial LEs between the source and destination LEs.

Table 45. EPF10K10 & EPF10K20 Device External Timing Parameters *Note (1)*

| Symbol | -3 Speed Grade | | -4 Speed Grade | | Unit |
|----------------------------|----------------|------|----------------|------|------|
| | Min | Max | Min | Max | |
| t_{DDR} | | 16.1 | | 20.0 | ns |
| t_{INSU} (2), (3) | 5.5 | | 6.0 | | ns |
| t_{INH} (3) | 0.0 | | 0.0 | | ns |
| t_{OUTCO} (3) | 2.0 | 6.7 | 2.0 | 8.4 | ns |

Table 46. EPF10K10 Device External Bidirectional Timing Parameters *Note (1)*

| Symbol | -3 Speed Grade | | -4 Speed Grade | | Unit |
|-------------------------|----------------|------|----------------|------|------|
| | Min | Max | Min | Max | |
| $t_{\text{INSUBIDIR}}$ | 4.5 | | 5.6 | | ns |
| t_{INHBIDIR} | 0.0 | | 0.0 | | ns |
| $t_{\text{OUTCOBIDIR}}$ | 2.0 | 6.7 | 2.0 | 8.4 | ns |
| t_{XZBIDIR} | | 10.5 | | 13.4 | ns |
| t_{ZXBIDIR} | | 10.5 | | 13.4 | ns |

Table 47. EPF10K20 Device External Bidirectional Timing Parameters *Note (1)*

| Symbol | -3 Speed Grade | | -4 Speed Grade | | Unit |
|-------------------------|----------------|------|----------------|------|------|
| | Min | Max | Min | Max | |
| $t_{\text{INSUBIDIR}}$ | 4.6 | | 5.7 | | ns |
| t_{INHBIDIR} | 0.0 | | 0.0 | | ns |
| $t_{\text{OUTCOBIDIR}}$ | 2.0 | 6.7 | 2.0 | 8.4 | ns |
| t_{XZBIDIR} | | 10.5 | | 13.4 | ns |
| t_{ZXBIDIR} | | 10.5 | | 13.4 | ns |

Notes to tables:

- (1) All timing parameters are described in Tables 32 through 38 in this data sheet.
- (2) Using an LE to register the signal may provide a lower setup time.
- (3) This parameter is specified by characterization.

Table 51. EPF10K30, EPF10K40 & EPF10K50 Device EAB Internal Timing Macroparameters*Note (1)*

| Symbol | -3 Speed Grade | | -4 Speed Grade | | Unit |
|-----------------|----------------|------|----------------|------|------|
| | Min | Max | Min | Max | |
| t_{EABAA} | | 13.7 | | 17.0 | ns |
| $t_{EABRCCOMB}$ | 13.7 | | 17.0 | | ns |
| $t_{EABRCREG}$ | 9.7 | | 11.9 | | ns |
| t_{EABWP} | 5.8 | | 7.2 | | ns |
| $t_{EABWCCOMB}$ | 7.3 | | 9.0 | | ns |
| $t_{EABWCREG}$ | 13.0 | | 16.0 | | ns |
| t_{EABDD} | | 10.0 | | 12.5 | ns |
| $t_{EABDATACO}$ | | 2.0 | | 3.4 | ns |
| $t_{EABDATASU}$ | 5.3 | | 5.6 | | ns |
| $t_{EABDATAH}$ | 0.0 | | 0.0 | | ns |
| $t_{EABWESU}$ | 5.5 | | 5.8 | | ns |
| t_{EABWEH} | 0.0 | | 0.0 | | ns |
| $t_{EABWDSU}$ | 5.5 | | 5.8 | | ns |
| t_{EABWDH} | 0.0 | | 0.0 | | ns |
| $t_{EABWASU}$ | 2.1 | | 2.7 | | ns |
| t_{EABWAH} | 0.0 | | 0.0 | | ns |
| t_{EABWO} | | 9.5 | | 11.8 | ns |

Table 52. EPF10K30 Device Interconnect Timing Microparameters *Note (1)*

| Symbol | -3 Speed Grade | | -4 Speed Grade | | Unit |
|------------------|----------------|-----|----------------|------|------|
| | Min | Max | Min | Max | |
| $t_{DIN2IOE}$ | | 6.9 | | 8.7 | ns |
| t_{DIN2LE} | | 3.6 | | 4.8 | ns |
| $t_{DIN2DATA}$ | | 5.5 | | 7.2 | ns |
| $t_{DCLK2IOE}$ | | 4.6 | | 6.2 | ns |
| $t_{DCLK2LE}$ | | 3.6 | | 4.8 | ns |
| $t_{SAMELAB}$ | | 0.3 | | 0.3 | ns |
| $t_{SAMEROW}$ | | 3.3 | | 3.7 | ns |
| $t_{SAMECOLUMN}$ | | 2.5 | | 2.7 | ns |
| $t_{DIFFROW}$ | | 5.8 | | 6.4 | ns |
| $t_{TROWROWS}$ | | 9.1 | | 10.1 | ns |
| $t_{LEPERIPH}$ | | 6.2 | | 7.1 | ns |
| $t_{LABCARRY}$ | | 0.4 | | 0.6 | ns |
| $t_{LABCASC}$ | | 2.4 | | 3.0 | ns |

Table 53. EPF10K40 Device Interconnect Timing Microparameters *Note (1)*

| Symbol | -3 Speed Grade | | -4 Speed Grade | | Unit |
|------------------|----------------|-----|----------------|------|------|
| | Min | Max | Min | Max | |
| $t_{DIN2IOE}$ | | 7.6 | | 9.4 | ns |
| t_{DIN2LE} | | 3.6 | | 4.8 | ns |
| $t_{DIN2DATA}$ | | 5.5 | | 7.2 | ns |
| $t_{DCLK2IOE}$ | | 4.6 | | 6.2 | ns |
| $t_{DCLK2LE}$ | | 3.6 | | 4.8 | ns |
| $t_{SAMELAB}$ | | 0.3 | | 0.3 | ns |
| $t_{SAMEROW}$ | | 3.3 | | 3.7 | ns |
| $t_{SAMECOLUMN}$ | | 3.1 | | 3.2 | ns |
| $t_{DIFFROW}$ | | 6.4 | | 6.4 | ns |
| $t_{TROWROWS}$ | | 9.7 | | 10.6 | ns |
| $t_{LEPERIPH}$ | | 6.4 | | 7.1 | ns |
| $t_{LABCARRY}$ | | 0.4 | | 0.6 | ns |
| $t_{LABCASC}$ | | 2.4 | | 3.0 | ns |

Table 54. EPF10K50 Device Interconnect Timing Microparameters *Note (1)*

| Symbol | -3 Speed Grade | | -4 Speed Grade | | Unit |
|------------------|----------------|------|----------------|------|------|
| | Min | Max | Min | Max | |
| $t_{DIN2IOE}$ | | 8.4 | | 10.2 | ns |
| t_{DIN2LE} | | 3.6 | | 4.8 | ns |
| $t_{DIN2DATA}$ | | 5.5 | | 7.2 | ns |
| $t_{DCLK2IOE}$ | | 4.6 | | 6.2 | ns |
| $t_{DCLK2LE}$ | | 3.6 | | 4.8 | ns |
| $t_{SAMELAB}$ | | 0.3 | | 0.3 | ns |
| $t_{SAMEROW}$ | | 3.3 | | 3.7 | ns |
| $t_{SAMECOLUMN}$ | | 3.9 | | 4.1 | ns |
| $t_{DIFFROW}$ | | 7.2 | | 7.8 | ns |
| $t_{TWOROWS}$ | | 10.5 | | 11.5 | ns |
| $t_{LEPERIPH}$ | | 7.5 | | 8.2 | ns |
| $t_{LABCARRY}$ | | 0.4 | | 0.6 | ns |
| $t_{LABCASC}$ | | 2.4 | | 3.0 | ns |

Table 55. EPF10K30, EPF10K40 & EPF10K50 Device External Timing Parameters *Note (1)*

| Symbol | -3 Speed Grade | | -4 Speed Grade | | Unit |
|---------------------|----------------|------|----------------|------|------|
| | Min | Max | Min | Max | |
| t_{DRR} | | 17.2 | | 21.1 | ns |
| t_{INSU} (2), (3) | 5.7 | | 6.4 | | ns |
| t_{INH} (3) | 0.0 | | 0.0 | | ns |
| t_{OUTCO} (3) | 2.0 | 8.8 | 2.0 | 11.2 | ns |

Table 56. EPF10K30, EPF10K40 & EPF10K50 Device External Bidirectional Timing Parameters *Note (1)*

| Symbol | -3 Speed Grade | | -4 Speed Grade | | Unit |
|------------------|----------------|------|----------------|------|------|
| | Min | Max | Min | Max | |
| $t_{INSUBIDIR}$ | 4.1 | | 4.6 | | ns |
| $t_{INHBIDIR}$ | 0.0 | | 0.0 | | ns |
| $t_{OUTCOBIDIR}$ | 2.0 | 8.8 | 2.0 | 11.2 | ns |
| $t_{XZBIDIR}$ | | 12.3 | | 15.0 | ns |
| $t_{ZXBIDIR}$ | | 12.3 | | 15.0 | ns |

Notes to tables:

- (1) All timing parameters are described in Tables 32 through 38 in this data sheet.
- (2) Using an LE to register the signal may provide a lower setup time.
- (3) This parameter is specified by characterization.

Tables 57 through 63 show EPF10K70 device internal and external timing parameters.

Table 57. EPF10K70 Device LE Timing Microparameters *Note (1)*

| Symbol | -2 Speed Grade | | -3 Speed Grade | | -4 Speed Grade | | Unit |
|--------------|----------------|-----|----------------|-----|----------------|-----|------|
| | Min | Max | Min | Max | Min | Max | |
| t_{LUT} | | 1.3 | | 1.5 | | 2.0 | ns |
| t_{CLUT} | | 0.4 | | 0.4 | | 0.5 | ns |
| t_{RLUT} | | 1.5 | | 1.6 | | 2.0 | ns |
| t_{PACKED} | | 0.8 | | 0.9 | | 1.3 | ns |
| t_{EN} | | 0.8 | | 0.9 | | 1.2 | ns |
| t_{CICO} | | 0.2 | | 0.2 | | 0.3 | ns |
| t_{CGEN} | | 1.0 | | 1.1 | | 1.4 | ns |
| t_{CGENR} | | 1.1 | | 1.2 | | 1.5 | ns |
| t_{CASC} | | 1.0 | | 1.1 | | 1.3 | ns |
| t_C | | 0.7 | | 0.8 | | 1.0 | ns |
| t_{CO} | | 0.9 | | 1.0 | | 1.4 | ns |
| t_{COMB} | | 0.4 | | 0.5 | | 0.7 | ns |
| t_{SU} | 1.9 | | 2.1 | | 2.6 | | ns |
| t_H | 2.1 | | 2.3 | | 3.1 | | ns |
| t_{PRE} | | 0.9 | | 1.0 | | 1.4 | ns |
| t_{CLR} | | 0.9 | | 1.0 | | 1.4 | ns |
| t_{CH} | 4.0 | | 4.0 | | 4.0 | | ns |
| t_{CL} | 4.0 | | 4.0 | | 4.0 | | ns |

Table 58. EPF10K70 Device IOE Timing Microparameters *Note (1)*

| Symbol | -2 Speed Grade | | -3 Speed Grade | | -4 Speed Grade | | Unit |
|--------------|----------------|-----|----------------|-----|----------------|------|------|
| | Min | Max | Min | Max | Min | Max | |
| t_{IOD} | | 0.0 | | 0.0 | | 0.0 | ns |
| t_{IOC} | | 0.4 | | 0.5 | | 0.7 | ns |
| t_{IOCO} | | 0.4 | | 0.4 | | 0.9 | ns |
| t_{IOCOMB} | | 0.0 | | 0.0 | | 0.0 | ns |
| t_{IOSU} | 4.5 | | 5.0 | | 6.2 | | ns |
| t_{IOH} | 0.4 | | 0.5 | | 0.7 | | ns |
| t_{IOCLR} | | 0.6 | | 0.7 | | 1.6 | ns |
| t_{OD1} | | 3.6 | | 4.0 | | 5.0 | ns |
| t_{OD2} | | 5.6 | | 6.3 | | 7.3 | ns |
| t_{OD3} | | 6.9 | | 7.7 | | 8.7 | ns |
| t_{XZ} | | 5.5 | | 6.2 | | 6.8 | ns |
| t_{ZX1} | | 5.5 | | 6.2 | | 6.8 | ns |
| t_{ZX2} | | 7.5 | | 8.5 | | 9.1 | ns |
| t_{ZX3} | | 8.8 | | 9.9 | | 10.5 | ns |
| t_{INREG} | | 8.0 | | 9.0 | | 10.2 | ns |
| t_{IOFD} | | 7.2 | | 8.1 | | 10.3 | ns |
| t_{INCOMB} | | 7.2 | | 8.1 | | 10.3 | ns |

Table 79. EPF10K130V Device IOE Timing Microparameters *Note (1)*

| Symbol | -2 Speed Grade | | -3 Speed Grade | | -4 Speed Grade | | Unit |
|--------------|----------------|-----|----------------|------|----------------|------|------|
| | Min | Max | Min | Max | Min | Max | |
| t_{IOD} | | 1.3 | | 1.6 | | 2.0 | ns |
| t_{IOC} | | 0.4 | | 0.5 | | 0.7 | ns |
| t_{IOCO} | | 0.3 | | 0.4 | | 0.5 | ns |
| t_{IOCOMB} | | 0.0 | | 0.0 | | 0.0 | ns |
| t_{IOSU} | 2.6 | | 3.3 | | 3.8 | | ns |
| t_{IOH} | 0.0 | | 0.0 | | 0.0 | | ns |
| t_{IOCLR} | | 1.7 | | 2.2 | | 2.7 | ns |
| t_{OD1} | | 3.5 | | 4.4 | | 5.0 | ns |
| t_{OD2} | | — | | — | | — | ns |
| t_{OD3} | | 8.2 | | 8.1 | | 9.7 | ns |
| t_{XZ} | | 4.9 | | 6.3 | | 7.4 | ns |
| t_{ZX1} | | 4.9 | | 6.3 | | 7.4 | ns |
| t_{ZX2} | | — | | — | | — | ns |
| t_{ZX3} | | 9.6 | | 10.0 | | 12.1 | ns |
| t_{INREG} | | 7.9 | | 10.0 | | 12.6 | ns |
| t_{IOFD} | | 6.2 | | 7.9 | | 9.9 | ns |
| t_{INCOMB} | | 6.2 | | 7.9 | | 9.9 | ns |

Notes to tables:

- (1) All timing parameters are described in Tables 32 through 38 in this data sheet.
- (2) Using an LE to register the signal may provide a lower setup time.
- (3) This parameter is specified by characterization.

Tables 92 through 98 show EPF10K30A device internal and external timing parameters.

Table 92. EPF10K30A Device LE Timing Microparameters *Note (1)*

| Symbol | -1 Speed Grade | | -2 Speed Grade | | -3 Speed Grade | | Unit |
|--------------|----------------|-----|----------------|-----|----------------|-----|------|
| | Min | Max | Min | Max | Min | Max | |
| t_{LUT} | | 0.8 | | 1.1 | | 1.5 | ns |
| t_{CLUT} | | 0.6 | | 0.7 | | 1.0 | ns |
| t_{RLUT} | | 1.2 | | 1.5 | | 2.0 | ns |
| t_{PACKED} | | 0.6 | | 0.6 | | 1.0 | ns |
| t_{EN} | | 1.3 | | 1.5 | | 2.0 | ns |
| t_{CICO} | | 0.2 | | 0.3 | | 0.4 | ns |
| t_{CGEN} | | 0.8 | | 1.0 | | 1.3 | ns |
| t_{CGENR} | | 0.6 | | 0.8 | | 1.0 | ns |
| t_{CASC} | | 0.9 | | 1.1 | | 1.4 | ns |
| t_C | | 1.1 | | 1.3 | | 1.7 | ns |
| t_{CO} | | 0.4 | | 0.6 | | 0.7 | ns |
| t_{COMB} | | 0.6 | | 0.7 | | 0.9 | ns |
| t_{SU} | 0.9 | | 0.9 | | 1.4 | | ns |
| t_H | 1.1 | | 1.3 | | 1.7 | | ns |
| t_{PRE} | | 0.5 | | 0.6 | | 0.8 | ns |
| t_{CLR} | | 0.5 | | 0.6 | | 0.8 | ns |
| t_{CH} | 3.0 | | 3.5 | | 4.0 | | ns |
| t_{CL} | 3.0 | | 3.5 | | 4.0 | | ns |

Table 93. EPF10K30A Device IOE Timing Microparameters *Note (1) (Part 1 of 2)*

| Symbol | -1 Speed Grade | | -2 Speed Grade | | -3 Speed Grade | | Unit |
|--------------|----------------|-----|----------------|-----|----------------|-----|------|
| | Min | Max | Min | Max | Min | Max | |
| t_{IOD} | | 2.2 | | 2.6 | | 3.4 | ns |
| t_{IOC} | | 0.3 | | 0.3 | | 0.5 | ns |
| t_{IOCO} | | 0.2 | | 0.2 | | 0.3 | ns |
| t_{IOCOMB} | | 0.5 | | 0.6 | | 0.8 | ns |
| t_{IOSU} | 1.4 | | 1.7 | | 2.2 | | ns |

Table 102. EPF10K100A Device EAB Internal Timing Macroparameters *Note (1)*

| Symbol | -1 Speed Grade | | -2 Speed Grade | | -3 Speed Grade | | Unit |
|------------------|----------------|-----|----------------|-----|----------------|-----|------|
| | Min | Max | Min | Max | Min | Max | |
| t_{EABAA} | | 6.8 | | 7.8 | | 9.2 | ns |
| $t_{EABRCCOMB}$ | 6.8 | | 7.8 | | 9.2 | | ns |
| $t_{EABRCREG}$ | 5.4 | | 6.2 | | 7.4 | | ns |
| t_{EABWP} | 3.2 | | 3.7 | | 4.4 | | ns |
| $t_{EABWCCOMB}$ | 3.4 | | 3.9 | | 4.7 | | ns |
| $t_{EABWCREG}$ | 9.4 | | 10.8 | | 12.8 | | ns |
| t_{EABDD} | | 6.1 | | 6.9 | | 8.2 | ns |
| $t_{EABDATA CO}$ | | 2.1 | | 2.3 | | 2.9 | ns |
| $t_{EABDATASU}$ | 3.7 | | 4.3 | | 5.1 | | ns |
| $t_{EABDATAH}$ | 0.0 | | 0.0 | | 0.0 | | ns |
| $t_{EABWESU}$ | 2.8 | | 3.3 | | 3.8 | | ns |
| t_{EABWEH} | 0.0 | | 0.0 | | 0.0 | | ns |
| $t_{EABWDSU}$ | 3.4 | | 4.0 | | 4.6 | | ns |
| t_{EABWDH} | 0.0 | | 0.0 | | 0.0 | | ns |
| $t_{EABWASU}$ | 1.9 | | 2.3 | | 2.6 | | ns |
| t_{EABWAH} | 0.0 | | 0.0 | | 0.0 | | ns |
| t_{EABWO} | | 5.1 | | 5.7 | | 6.9 | ns |

Notes to tables:

- (1) All timing parameters are described in Tables 32 through 38 in this data sheet.
- (2) Using an LE to register the signal may provide a lower setup time.
- (3) This parameter is specified by characterization.

Tables 106 through 112 show EPF10K250A device internal and external timing parameters.

| Table 106. EPF10K250A Device LE Timing Microparameters <i>Note (1)</i> | | | | | | | |
|--|----------------|-----|----------------|-----|----------------|-----|------|
| Symbol | -1 Speed Grade | | -2 Speed Grade | | -3 Speed Grade | | Unit |
| | Min | Max | Min | Max | Min | Max | |
| t_{LUT} | | 0.9 | | 1.0 | | 1.4 | ns |
| t_{CLUT} | | 1.2 | | 1.3 | | 1.6 | ns |
| t_{RLUT} | | 2.0 | | 2.3 | | 2.7 | ns |
| t_{PACKED} | | 0.4 | | 0.4 | | 0.5 | ns |
| t_{EN} | | 1.4 | | 1.6 | | 1.9 | ns |
| t_{CICO} | | 0.2 | | 0.3 | | 0.3 | ns |
| t_{CGEN} | | 0.4 | | 0.6 | | 0.6 | ns |
| t_{CGENR} | | 0.8 | | 1.0 | | 1.1 | ns |
| t_{CASC} | | 0.7 | | 0.8 | | 1.0 | ns |
| t_C | | 1.2 | | 1.3 | | 1.6 | ns |
| t_{CO} | | 0.6 | | 0.7 | | 0.9 | ns |
| t_{COMB} | | 0.5 | | 0.6 | | 0.7 | ns |
| t_{SU} | 1.2 | | 1.4 | | 1.7 | | ns |
| t_H | 1.2 | | 1.3 | | 1.6 | | ns |
| t_{PRE} | | 0.7 | | 0.8 | | 0.9 | ns |
| t_{CLR} | | 0.7 | | 0.8 | | 0.9 | ns |
| t_{CH} | 2.5 | | 3.0 | | 3.5 | | ns |
| t_{CL} | 2.5 | | 3.0 | | 3.5 | | ns |