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### **Understanding Embedded - FPGAs (Field Programmable Gate Array)**

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

### **Applications of Embedded - FPGAs**

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

#### **Details**

Product Status	Active
Number of LABs/CLBs	360
Number of Logic Elements/Cells	2880
Total RAM Bits	40960
Number of I/O	291
Number of Gates	116000
Voltage - Supply	3V ~ 3.6V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 70°C (TA)
Package / Case	484-BBGA
Supplier Device Package	484-FBGA (23x23)
Purchase URL	<a href="https://www.e-xfl.com/pro/item?MUrl=&amp;PartUrl=epf10k50vfc484-3">https://www.e-xfl.com/pro/item?MUrl=&amp;PartUrl=epf10k50vfc484-3</a>

**Table 2. FLEX 10K Device Features**

Feature	EPF10K70	EPF10K100 EPF10K100A	EPF10K130V	EPF10K250A
Typical gates (logic and RAM) (1)	70,000	100,000	130,000	250,000
Maximum system gates	118,000	158,000	211,000	310,000
LEs	3,744	4,992	6,656	12,160
LABs	468	624	832	1,520
EABs	9	12	16	20
Total RAM bits	18,432	24,576	32,768	40,960
Maximum user I/O pins	358	406	470	470

**Note to tables:**

(1) The embedded IEEE Std. 1149.1 JTAG circuitry adds up to 31,250 gates in addition to the listed typical or maximum system gates.

**...and More Features**

- Devices are fabricated on advanced processes and operate with a 3.3-V or 5.0-V supply voltage (see [Table 3](#))
- In-circuit reconfigurability (ICR) via external configuration device, intelligent controller, or JTAG port
- ClockLock™ and ClockBoost™ options for reduced clock delay/skew and clock multiplication
- Built-in low-skew clock distribution trees
- 100% functional testing of all devices; test vectors or scan chains are not required

**Table 3. Supply Voltages for FLEX 10K & FLEX 10KA Devices**

5.0-V Devices	3.3-V Devices
EPF10K10	EPF10K10A
EPF10K20	EPF10K30A
EPF10K30	EPF10K50V
EPF10K40	EPF10K100A
EPF10K50	EPF10K130V
EPF10K70	EPF10K250A
EPF10K100	

**Notes to tables:**

- (1) FLEX 10K and FLEX 10KA device package types include plastic J-lead chip carrier (PLCC), thin quad flat pack (TQFP), plastic quad flat pack (PQFP), power quad flat pack (RQFP), ball-grid array (BGA), pin-grid array (PGA), and FineLine BGA™ packages.
- (2) This option is supported with a 256-pin FineLine BGA package. By using SameFrame pin migration, all FineLine BGA packages are pin compatible. For example, a board can be designed to support both 256-pin and 484-pin FineLine BGA packages. The Altera software automatically avoids conflicting pins when future migration is set.

## General Description

Altera’s FLEX 10K devices are the industry’s first embedded PLDs. Based on reconfigurable CMOS SRAM elements, the Flexible Logic Element MatriX (FLEX) architecture incorporates all features necessary to implement common gate array megafunctions. With up to 250,000 gates, the FLEX 10K family provides the density, speed, and features to integrate entire systems, including multiple 32-bit buses, into a single device.

FLEX 10K devices are reconfigurable, which allows 100% testing prior to shipment. As a result, the designer is not required to generate test vectors for fault coverage purposes. Additionally, the designer does not need to manage inventories of different ASIC designs; FLEX 10K devices can be configured on the board for the specific functionality required.

Table 6 shows FLEX 10K performance for some common designs. All performance values were obtained with Synopsys DesignWare or LPM functions. No special design technique was required to implement the applications; the designer simply inferred or instantiated a function in a Verilog HDL, VHDL, Altera Hardware Description Language (AHDL), or schematic design file.

**Table 6. FLEX 10K & FLEX 10KA Performance**

Application	Resources Used		Performance				Units
	LEs	EABs	-1 Speed Grade	-2 Speed Grade	-3 Speed Grade	-4 Speed Grade	
16-bit loadable counter (1)	16	0	204	166	125	95	MHz
16-bit accumulator (1)	16	0	204	166	125	95	MHz
16-to-1 multiplexer (2)	10	0	4.2	5.8	6.0	7.0	ns
256 × 8 RAM read cycle speed (3)	0	1	172	145	108	84	MHz
256 × 8 RAM write cycle speed (3)	0	1	106	89	68	63	MHz

**Notes:**

- (1) The speed grade of this application is limited because of clock high and low specifications.
- (2) This application uses combinatorial inputs and outputs.
- (3) This application uses registered inputs and outputs.

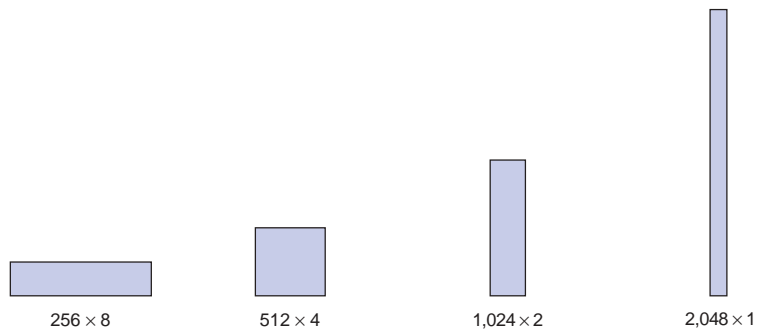
Logic functions are implemented by programming the EAB with a read-only pattern during configuration, creating a large LUT. With LUTs, combinatorial functions are implemented by looking up the results, rather than by computing them. This implementation of combinatorial functions can be faster than using algorithms implemented in general logic, a performance advantage that is further enhanced by the fast access times of EABs. The large capacity of EABs enables designers to implement complex functions in one logic level without the routing delays associated with linked LEs or field-programmable gate array (FPGA) RAM blocks. For example, a single EAB can implement a  $4 \times 4$  multiplier with eight inputs and eight outputs. Parameterized functions such as LPM functions can automatically take advantage of the EAB.

The EAB provides advantages over FPGAs, which implement on-board RAM as arrays of small, distributed RAM blocks. These FPGA RAM blocks contain delays that are less predictable as the size of the RAM increases. In addition, FPGA RAM blocks are prone to routing problems because small blocks of RAM must be connected together to make larger blocks. In contrast, EABs can be used to implement large, dedicated blocks of RAM that eliminate these timing and routing concerns.

EABs can be used to implement synchronous RAM, which is easier to use than asynchronous RAM. A circuit using asynchronous RAM must generate the RAM write enable ( $\overline{WE}$ ) signal, while ensuring that its data and address signals meet setup and hold time specifications relative to the  $\overline{WE}$  signal. In contrast, the EAB's synchronous RAM generates its own  $\overline{WE}$  signal and is self-timed with respect to the global clock. A circuit using the EAB's self-timed RAM need only meet the setup and hold time specifications of the global clock.

When used as RAM, each EAB can be configured in any of the following sizes:  $256 \times 8$ ,  $512 \times 4$ ,  $1,024 \times 2$ , or  $2,048 \times 1$ . See [Figure 2](#).

**Figure 2. EAB Memory Configurations**



### Normal Mode

The normal mode is suitable for general logic applications and wide decoding functions that can take advantage of a cascade chain. In normal mode, four data inputs from the LAB local interconnect and the carry-in are inputs to a four-input LUT. The Compiler automatically selects the carry-in or the DATA3 signal as one of the inputs to the LUT. The LUT output can be combined with the cascade-in signal to form a cascade chain through the cascade-out signal. Either the register or the LUT can be used to drive both the local interconnect and the FastTrack Interconnect at the same time.

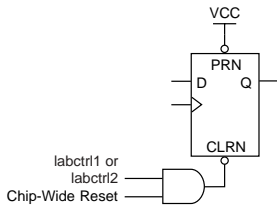
The LUT and the register in the LE can be used independently; this feature is known as register packing. To support register packing, the LE has two outputs; one drives the local interconnect and the other drives the FastTrack Interconnect. The DATA4 signal can drive the register directly, allowing the LUT to compute a function that is independent of the registered signal; a three-input function can be computed in the LUT, and a fourth independent signal can be registered. Alternatively, a four-input function can be generated, and one of the inputs to this function can be used to drive the register. The register in a packed LE can still use the clock enable, clear, and preset signals in the LE. In a packed LE, the register can drive the FastTrack Interconnect while the LUT drives the local interconnect, or vice versa.

### Arithmetic Mode

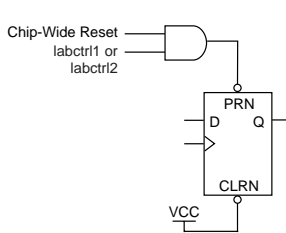
The arithmetic mode offers 2 three-input LUTs that are ideal for implementing adders, accumulators, and comparators. One LUT computes a three-input function, and the other generates a carry output. As shown in [Figure 9](#) on page 19, the first LUT uses the carry-in signal and two data inputs from the LAB local interconnect to generate a combinatorial or registered output. For example, in an adder, this output is the sum of three signals: a, b, and carry-in. The second LUT uses the same three signals to generate a carry-out signal, thereby creating a carry chain. The arithmetic mode also supports simultaneous use of the cascade chain.

Figure 10. LE Clear & Preset Modes

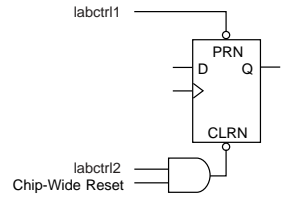
**Asynchronous Clear**



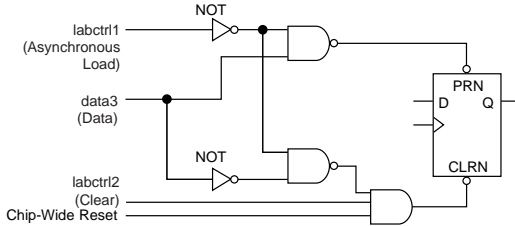
**Asynchronous Preset**



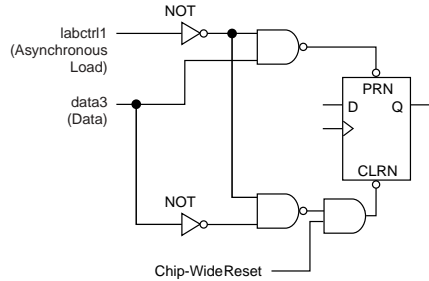
**Asynchronous Clear & Preset**



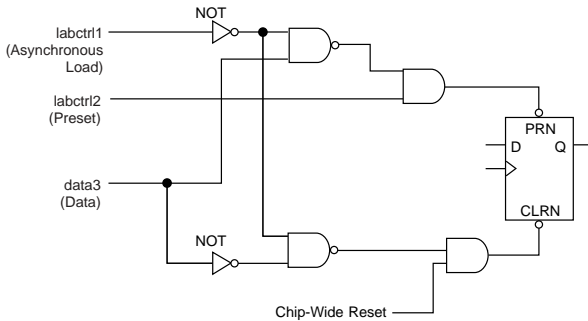
**Asynchronous Load with Clear**



**Asynchronous Load without Clear or Preset**



**Asynchronous Load with Preset**



**Asynchronous Clear**

The flipflop can be cleared by either LABCTRL1 or LABCTRL2. In this mode, the preset signal is tied to  $V_{CC}$  to deactivate it.

## Slew-Rate Control

The output buffer in each IOE has an adjustable output slew rate that can be configured for low-noise or high-speed performance. A slower slew rate reduces system noise and adds a maximum delay of approximately 2.9 ns. The fast slew rate should be used for speed-critical outputs in systems that are adequately protected against noise. Designers can specify the slew rate on a pin-by-pin basis during design entry or assign a default slew rate to all pins on a device-wide basis. The slow slew rate setting affects only the falling edge of the output.

## Open-Drain Output Option

FLEX 10K devices provide an optional open-drain (electrically equivalent to an open-collector) output for each I/O pin. This open-drain output enables the device to provide system-level control signals (e.g., interrupt and write enable signals) that can be asserted by any of several devices. It can also provide an additional wired-OR plane. Additionally, the Altera software can convert tri-state buffers with grounded data inputs to open-drain pins automatically.

Open-drain output pins on FLEX 10K devices (with a pull-up resistor to the 5.0-V supply) can drive 5.0-V CMOS input pins that require a  $V_{IH}$  of 3.5 V. When the open-drain pin is active, it will drive low. When the pin is inactive, the trace will be pulled up to 5.0 V by the resistor. The open-drain pin will only drive low or tri-state; it will never drive high. The rise time is dependent on the value of the pull-up resistor and load impedance. The  $I_{OL}$  current specification should be considered when selecting a pull-up resistor.

Output pins on 5.0-V FLEX 10K devices with  $V_{CCIO} = 3.3$  V or 5.0 V (with a pull-up resistor to the 5.0-V supply) can also drive 5.0-V CMOS input pins. In this case, the pull-up transistor will turn off when the pin voltage exceeds 3.3 V. Therefore, the pin does not have to be open-drain.

## MultiVolt I/O Interface

The FLEX 10K device architecture supports the MultiVolt I/O interface feature, which allows FLEX 10K devices to interface with systems of differing supply voltages. These devices have one set of  $V_{CC}$  pins for internal operation and input buffers ( $V_{CCINT}$ ) and another set for I/O output drivers ( $V_{CCIO}$ ).

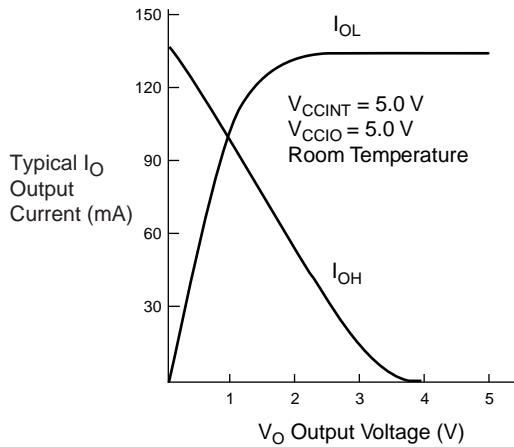
**Notes to tables:**

- (1) See the *Operating Requirements for Altera Devices Data Sheet*.
- (2) Minimum DC input voltage is  $-0.5\text{ V}$ . During transitions, the inputs may undershoot to  $-2.0\text{ V}$  for input currents less than  $100\text{ mA}$  and periods shorter than  $20\text{ ns}$ .
- (3) Numbers in parentheses are for industrial-temperature-range devices.
- (4) Maximum  $V_{CC}$  rise time is  $100\text{ ms}$ .  $V_{CC}$  must rise monotonically.
- (5) Typical values are for  $T_A = 25^\circ\text{ C}$  and  $V_{CC} = 5.0\text{ V}$ .
- (6) These values are specified under the Recommended Operation Condition shown in [Table 18](#) on page 45.
- (7) The  $I_{OH}$  parameter refers to high-level TTL or CMOS output current.
- (8) The  $I_{OL}$  parameter refers to low-level TTL or CMOS output current. This parameter applies to open-drain pins as well as output pins.
- (9) This value is specified for normal device operation. The value may vary during power-up.
- (10) Capacitance is sample-tested only.

Figure 20 shows the typical output drive characteristics of FLEX 10K devices with  $5.0\text{-V}$  and  $3.3\text{-V}$   $V_{CCIO}$ . The output driver is compliant with the  $5.0\text{-V}$  *PCI Local Bus Specification, Revision 2.2* (for  $5.0\text{-V}$   $V_{CCIO}$ ).

**Figure 20. Output Drive Characteristics of FLEX 10K Devices**

**5.0-V**



**3.3-V**

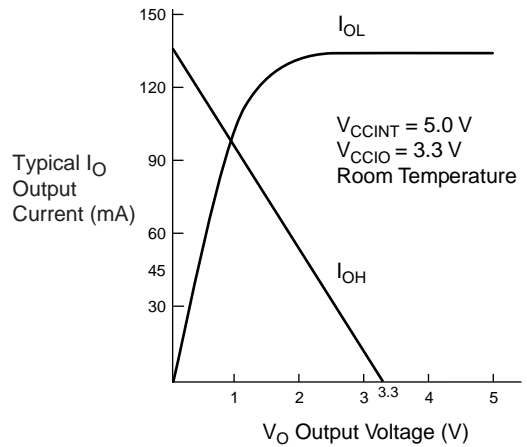




Figure 26. FLEX 10K Device IOE Timing Model

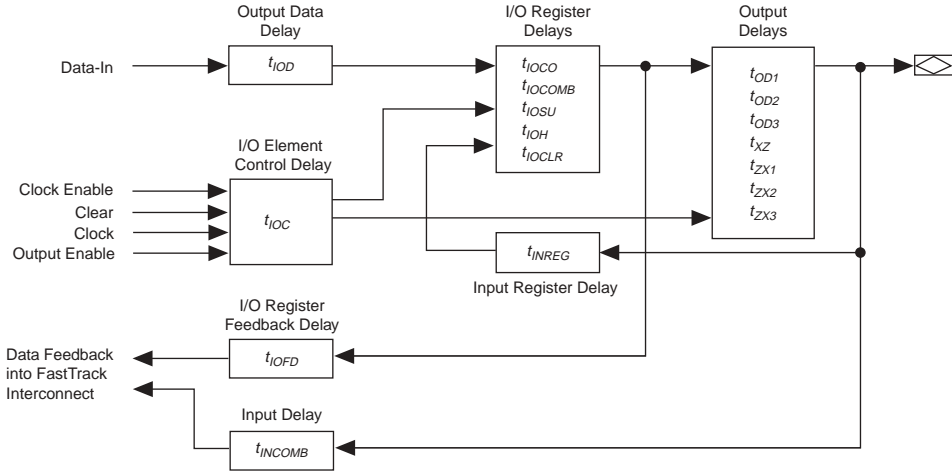


Figure 27. FLEX 10K Device EAB Timing Model

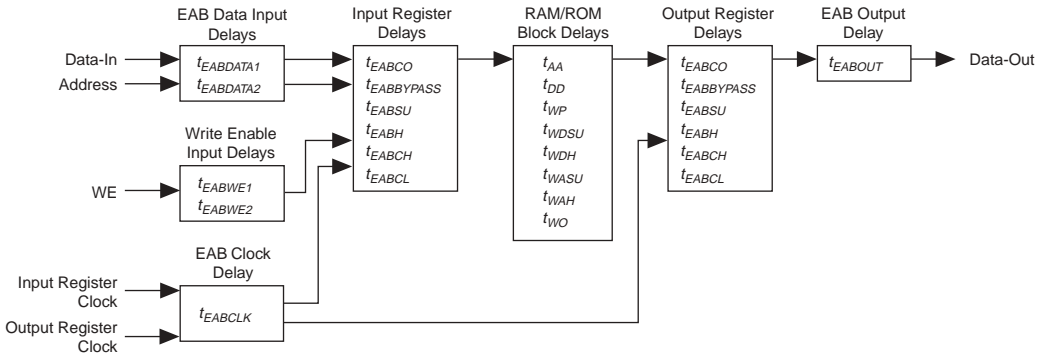
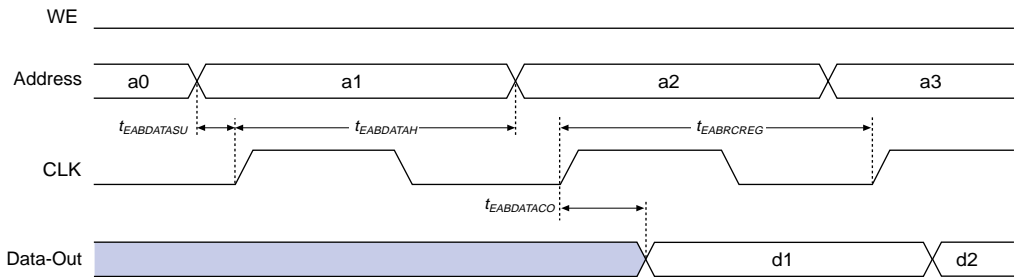


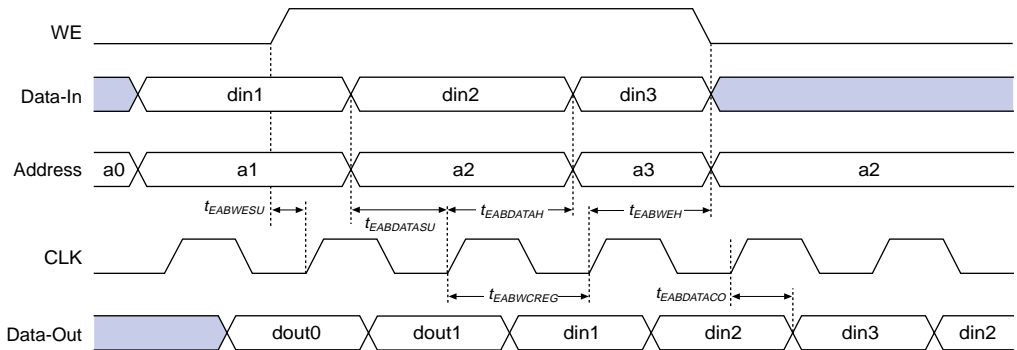
Figure 28 shows the timing model for bidirectional I/O pin timing.

Figure 30. EAB Synchronous Timing Waveforms

**EAB Synchronous Read**



**EAB Synchronous Write (EAB Output Registers Used)**



**Table 41. EPF10K10 & EPF10K20 Device EAB Internal Microparameters** *Note (1)*

Symbol	-3 Speed Grade		-4 Speed Grade		Unit
	Min	Max	Min	Max	
$t_{EABDATA1}$		1.5		1.9	ns
$t_{EABDATA2}$		4.8		6.0	ns
$t_{EABWE1}$		1.0		1.2	ns
$t_{EABWE2}$		5.0		6.2	ns
$t_{EABCLK}$		1.0		2.2	ns
$t_{EABCO}$		0.5		0.6	ns
$t_{EABBYPASS}$		1.5		1.9	ns
$t_{EABSU}$	1.5		1.8		ns
$t_{EABH}$	2.0		2.5		ns
$t_{AA}$		8.7		10.7	ns
$t_{WP}$	5.8		7.2		ns
$t_{WDSU}$	1.6		2.0		ns
$t_{WDH}$	0.3		0.4		ns
$t_{WASU}$	0.5		0.6		ns
$t_{WAH}$	1.0		1.2		ns
$t_{WO}$		5.0		6.2	ns
$t_{DD}$		5.0		6.2	ns
$t_{EABOUT}$		0.5		0.6	ns
$t_{EABCH}$	4.0		4.0		ns
$t_{EABCL}$	5.8		7.2		ns

Tables 48 through 56 show EPF10K30, EPF10K40, and EPF10K50 device internal and external timing parameters.

**Table 48. EPF10K30, EPF10K40 & EPF10K50 Device LE Timing Microparameters** *Note (1)*

Symbol	-3 Speed Grade		-4 Speed Grade		Unit
	Min	Max	Min	Max	
$t_{LUT}$		1.3		1.8	ns
$t_{CLUT}$		0.6		0.6	ns
$t_{RLUT}$		1.5		2.0	ns
$t_{PACKED}$		0.5		0.8	ns
$t_{EN}$		0.9		1.5	ns
$t_{CICO}$		0.2		0.4	ns
$t_{CGEN}$		0.9		1.4	ns
$t_{CGENR}$		0.9		1.4	ns
$t_{CASC}$		1.0		1.2	ns
$t_C$		1.3		1.6	ns
$t_{CO}$		0.9		1.2	ns
$t_{COMB}$		0.6		0.6	ns
$t_{SU}$	1.4		1.4		ns
$t_H$	0.9		1.3		ns
$t_{PRE}$		0.9		1.2	ns
$t_{CLR}$		0.9		1.2	ns
$t_{CH}$	4.0		4.0		ns
$t_{CL}$	4.0		4.0		ns

**Table 49. EPF10K30, EPF10K40 & EPF10K50 Device IOE Timing Microparameters** *Note (1)*

Symbol	-3 Speed Grade		-4 Speed Grade		Unit
	Min	Max	Min	Max	
$t_{IOD}$		0.4		0.6	ns
$t_{IOC}$		0.5		0.9	ns
$t_{IOCO}$		0.4		0.5	ns
$t_{IOCOMB}$		0.0		0.0	ns
$t_{IOSU}$	3.1		3.5		ns
$t_{IOH}$	1.0		1.9		ns
$t_{IOCLR}$		1.0		1.2	ns
$t_{OD1}$		3.3		3.6	ns
$t_{OD2}$		5.6		6.5	ns
$t_{OD3}$		7.0		8.3	ns
$t_{XZ}$		5.2		5.5	ns
$t_{ZX1}$		5.2		5.5	ns
$t_{ZX2}$		7.5		8.4	ns
$t_{ZX3}$		8.9		10.2	ns
$t_{INREG}$		7.7		10.0	ns
$t_{IOFD}$		3.3		4.0	ns
$t_{INCOMB}$		3.3		4.0	ns

**Table 51. EPF10K30, EPF10K40 & EPF10K50 Device EAB Internal Timing Macroparameters***Note (1)*

Symbol	-3 Speed Grade		-4 Speed Grade		Unit
	Min	Max	Min	Max	
$t_{EABAA}$		13.7		17.0	ns
$t_{EABRCCOMB}$	13.7		17.0		ns
$t_{EABRCREG}$	9.7		11.9		ns
$t_{EABWP}$	5.8		7.2		ns
$t_{EABWCCOMB}$	7.3		9.0		ns
$t_{EABWCREG}$	13.0		16.0		ns
$t_{EABDD}$		10.0		12.5	ns
$t_{EABDATACO}$		2.0		3.4	ns
$t_{EABDATASU}$	5.3		5.6		ns
$t_{EABDATAH}$	0.0		0.0		ns
$t_{EABWESU}$	5.5		5.8		ns
$t_{EABWEH}$	0.0		0.0		ns
$t_{EABWDSU}$	5.5		5.8		ns
$t_{EABWDH}$	0.0		0.0		ns
$t_{EABWASU}$	2.1		2.7		ns
$t_{EABWAH}$	0.0		0.0		ns
$t_{EABWO}$		9.5		11.8	ns

**Table 58. EPF10K70 Device IOE Timing Microparameters** *Note (1)*

Symbol	-2 Speed Grade		-3 Speed Grade		-4 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{IOD}$		0.0		0.0		0.0	ns
$t_{IOC}$		0.4		0.5		0.7	ns
$t_{IOCO}$		0.4		0.4		0.9	ns
$t_{IOCOMB}$		0.0		0.0		0.0	ns
$t_{IOSU}$	4.5		5.0		6.2		ns
$t_{IOH}$	0.4		0.5		0.7		ns
$t_{IOCLR}$		0.6		0.7		1.6	ns
$t_{OD1}$		3.6		4.0		5.0	ns
$t_{OD2}$		5.6		6.3		7.3	ns
$t_{OD3}$		6.9		7.7		8.7	ns
$t_{XZ}$		5.5		6.2		6.8	ns
$t_{ZX1}$		5.5		6.2		6.8	ns
$t_{ZX2}$		7.5		8.5		9.1	ns
$t_{ZX3}$		8.8		9.9		10.5	ns
$t_{INREG}$		8.0		9.0		10.2	ns
$t_{IOFD}$		7.2		8.1		10.3	ns
$t_{INCOMB}$		7.2		8.1		10.3	ns

**Table 74. EPF10K50V Device EAB Internal Timing Macroparameters** *Note (1)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		-4 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
$t_{EABAA}$		9.5		13.6		16.5		20.8	ns
$t_{EABRCCOMB}$	9.5		13.6		16.5		20.8		ns
$t_{EABRCREG}$	6.1		8.8		10.8		13.4		ns
$t_{EABWP}$	6.0		4.9		6.0		7.4		ns
$t_{EABWCCOMB}$	6.2		6.1		7.5		9.2		ns
$t_{EABWCREG}$	12.0		11.6		14.2		17.4		ns
$t_{EABDD}$		6.8		9.7		11.8		14.9	ns
$t_{EABDATACO}$		1.0		1.4		1.8		2.2	ns
$t_{EABDATASU}$	5.3		4.6		5.6		6.9		ns
$t_{EABDATAH}$	0.0		0.0		0.0		0.0		ns
$t_{EABWESU}$	4.4		4.8		5.8		7.2		ns
$t_{EABWEH}$	0.0		0.0		0.0		0.0		ns
$t_{EABWDSU}$	1.8		1.1		1.4		2.1		ns
$t_{EABWDH}$	0.0		0.0		0.0		0.0		ns
$t_{EABWASU}$	4.5		4.6		5.6		7.4		ns
$t_{EABWAH}$	0.0		0.0		0.0		0.0		ns
$t_{EABWO}$		5.1		9.4		11.4		14.0	ns



**Table 81. EPF10K130V Device EAB Internal Timing Macroparameters** *Note (1)*

Symbol	-2 Speed Grade		-3 Speed Grade		-4 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{EABAA}$		11.2		14.2		14.2	ns
$t_{EABRCCOMB}$	11.1		14.2		14.2		ns
$t_{EABRCREG}$	8.5		10.8		10.8		ns
$t_{EABWP}$	3.7		4.7		4.7		ns
$t_{EABWCCOMB}$	7.6		9.7		9.7		ns
$t_{EABWCREG}$	14.0		17.8		17.8		ns
$t_{EABDD}$		11.1		14.2		14.2	ns
$t_{EABDATACO}$		3.6		4.6		4.6	ns
$t_{EABDATASU}$	4.4		5.6		5.6		ns
$t_{EABDATAH}$	0.0		0.0		0.0		ns
$t_{EABWESU}$	4.4		5.6		5.6		ns
$t_{EABWEH}$	0.0		0.0		0.0		ns
$t_{EABWDSU}$	4.6		5.9		5.9		ns
$t_{EABWDH}$	0.0		0.0		0.0		ns
$t_{EABWASU}$	3.9		5.0		5.0		ns
$t_{EABWAH}$	0.0		0.0		0.0		ns
$t_{EABWO}$		11.1		14.2		14.2	ns

Notes to tables:

- (1) All timing parameters are described in Tables 32 through 38 in this data sheet.
- (2) Using an LE to register the signal may provide a lower setup time.
- (3) This parameter is specified by characterization.

Tables 85 through 91 show EPF10K10A device internal and external timing parameters.

**Table 85. EPF10K10A Device LE Timing Microparameters** *Note (1)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{LUT}$		0.9		1.2		1.6	ns
$t_{CLUT}$		1.2		1.4		1.9	ns
$t_{RLUT}$		1.9		2.3		3.0	ns
$t_{PACKED}$		0.6		0.7		0.9	ns
$t_{EN}$		0.5		0.6		0.8	ns
$t_{CICO}$		0.2		0.3		0.4	ns
$t_{CGEN}$		0.7		0.9		1.1	ns
$t_{CGENR}$		0.7		0.9		1.1	ns
$t_{CASC}$		1.0		1.2		1.7	ns
$t_C$		1.2		1.4		1.9	ns
$t_{CO}$		0.5		0.6		0.8	ns
$t_{COMB}$		0.5		0.6		0.8	ns
$t_{SU}$	1.1		1.3		1.7		ns
$t_H$	0.6		0.7		0.9		ns
$t_{PRE}$		0.5		0.6		0.9	ns
$t_{CLR}$		0.5		0.6		0.9	ns
$t_{CH}$	3.0		3.5		4.0		ns
$t_{CL}$	3.0		3.5		4.0		ns

**Table 86. EPF10K10A Device IOE Timing Microparameters** *Note (1) (Part 1 of 2)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
		1.3		1.5		2.0	ns
$t_{IOC}$		0.2		0.3		0.3	ns
$t_{IOCO}$		0.2		0.3		0.4	ns
$t_{IOCOMB}$		0.6		0.7		0.9	ns
$t_{IOSU}$	0.8		1.0		1.3		ns

**Table 87. EPF10K10A Device EAB Internal Microparameters** *Note (1)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{EABDATA1}$		3.3		3.9		5.2	ns
$t_{EABDATA2}$		1.0		1.3		1.7	ns
$t_{EABWE1}$		2.6		3.1		4.1	ns
$t_{EABWE2}$		2.7		3.2		4.3	ns
$t_{EABCLK}$		0.0		0.0		0.0	ns
$t_{EABCO}$		1.2		1.4		1.8	ns
$t_{EABBYPASS}$		0.1		0.2		0.2	ns
$t_{EABSU}$	1.4		1.7		2.2		ns
$t_{EABH}$	0.1		0.1		0.1		ns
$t_{AA}$		4.5		5.4		7.3	ns
$t_{WP}$	2.0		2.4		3.2		ns
$t_{WDSU}$	0.7		0.8		1.1		ns
$t_{WDH}$	0.5		0.6		0.7		ns
$t_{WASU}$	0.6		0.7		0.9		ns
$t_{WAH}$	0.9		1.1		1.5		ns
$t_{WO}$		3.3		3.9		5.2	ns
$t_{DD}$		3.3		3.9		5.2	ns
$t_{EABOUT}$		0.1		0.1		0.2	ns
$t_{EABCH}$	3.0		3.5		4.0		ns
$t_{EABCL}$	3.03		3.5		4.0		ns

Notes to tables:

- (1) All timing parameters are described in Tables 32 through 38 in this data sheet.
- (2) Using an LE to register the signal may provide a lower setup time.
- (3) This parameter is specified by characterization.

Tables 92 through 98 show EPF10K30A device internal and external timing parameters.

**Table 92. EPF10K30A Device LE Timing Microparameters** *Note (1)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{LUT}$		0.8		1.1		1.5	ns
$t_{CLUT}$		0.6		0.7		1.0	ns
$t_{RLUT}$		1.2		1.5		2.0	ns
$t_{PACKED}$		0.6		0.6		1.0	ns
$t_{EN}$		1.3		1.5		2.0	ns
$t_{CICO}$		0.2		0.3		0.4	ns
$t_{CGEN}$		0.8		1.0		1.3	ns
$t_{CGENR}$		0.6		0.8		1.0	ns
$t_{CASC}$		0.9		1.1		1.4	ns
$t_C$		1.1		1.3		1.7	ns
$t_{CO}$		0.4		0.6		0.7	ns
$t_{COMB}$		0.6		0.7		0.9	ns
$t_{SU}$	0.9		0.9		1.4		ns
$t_H$	1.1		1.3		1.7		ns
$t_{PRE}$		0.5		0.6		0.8	ns
$t_{CLR}$		0.5		0.6		0.8	ns
$t_{CH}$	3.0		3.5		4.0		ns
$t_{CL}$	3.0		3.5		4.0		ns

**Table 93. EPF10K30A Device IOE Timing Microparameters** *Note (1) (Part 1 of 2)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{IOD}$		2.2		2.6		3.4	ns
$t_{IOC}$		0.3		0.3		0.5	ns
$t_{IOCO}$		0.2		0.2		0.3	ns
$t_{IOCOMB}$		0.5		0.6		0.8	ns
$t_{IOSU}$	1.4		1.7		2.2		ns

**Table 101. EPF10K100A Device EAB Internal Microparameters** *Note (1)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{EABDATA1}$		1.8		2.1		2.4	ns
$t_{EABDATA2}$		3.2		3.7		4.4	ns
$t_{EABWE1}$		0.8		0.9		1.1	ns
$t_{EABWE2}$		2.3		2.7		3.1	ns
$t_{EABCLK}$		0.8		0.9		1.1	ns
$t_{EABCO}$		1.0		1.1		1.4	ns
$t_{EABBYPASS}$		0.3		0.3		0.4	ns
$t_{EABSU}$	1.3		1.5		1.8		ns
$t_{EABH}$	0.4		0.5		0.5		ns
$t_{AA}$		4.1		4.8		5.6	ns
$t_{WP}$	3.2		3.7		4.4		ns
$t_{WDSU}$	2.4		2.8		3.3		ns
$t_{WDH}$	0.2		0.2		0.3		ns
$t_{WASU}$	0.2		0.2		0.3		ns
$t_{WAH}$	0.0		0.0		0.0		ns
$t_{WO}$		3.4		3.9		4.6	ns
$t_{DD}$		3.4		3.9		4.6	ns
$t_{EABOUT}$		0.3		0.3		0.4	ns
$t_{EABCH}$	2.5		3.5		4.0		ns
$t_{EABCL}$	3.2		3.7		4.4		ns