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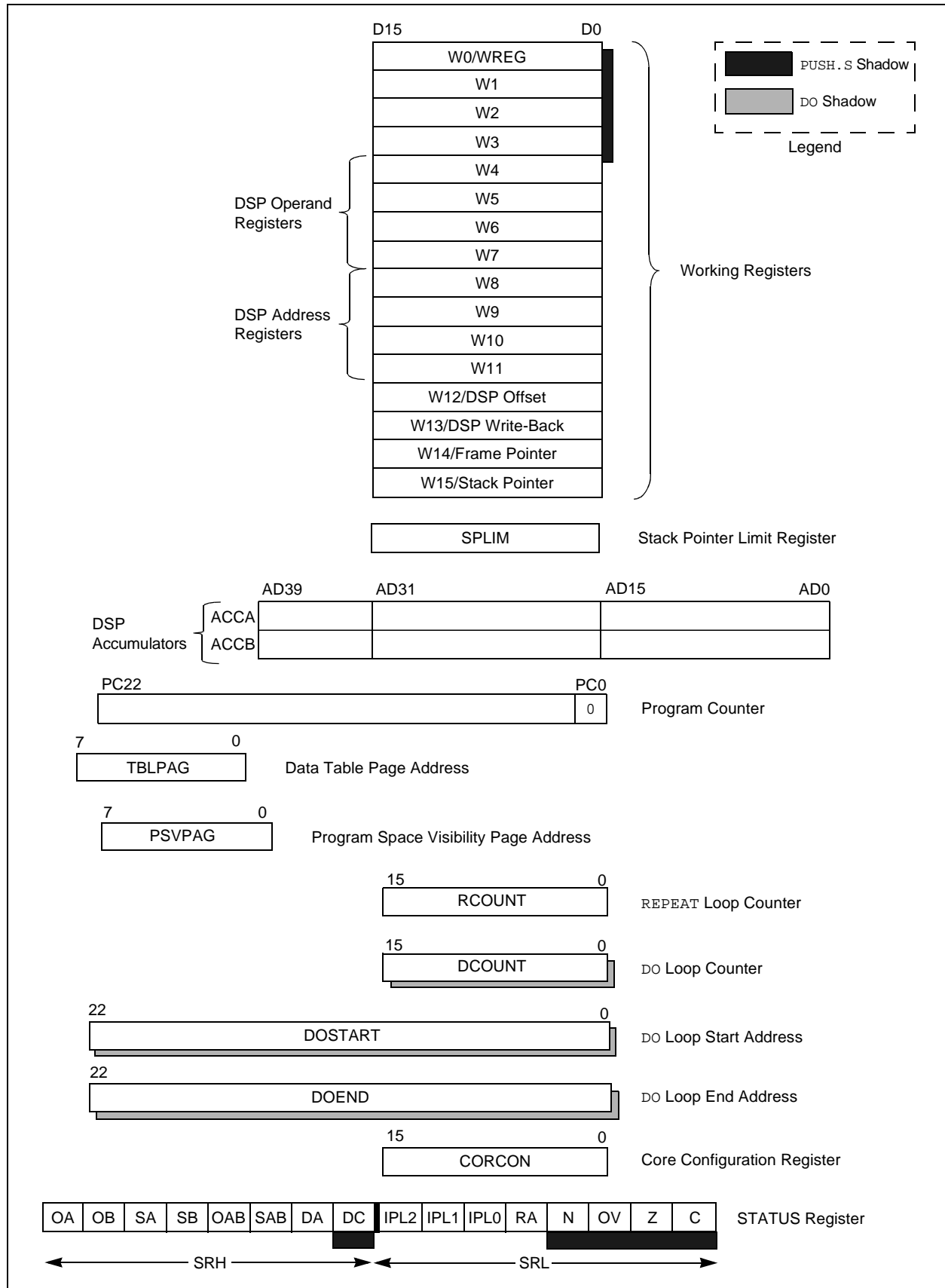
"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	40 MIPs
Connectivity	CANbus, I <sup>2</sup> C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, QEI, POR, PWM, WDT
Number of I/O	58
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	9K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 16x10b; D/A 1x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	64-VQFN (9x9)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/dspic33fj64gs606-i-mr">https://www.e-xfl.com/product-detail/microchip-technology/dspic33fj64gs606-i-mr</a>

FIGURE 3-2: PROGRAMMER'S MODEL



**FIGURE 4-4: DATA MEMORY MAP FOR DEVICES WITH 8-KBYTE RAM**

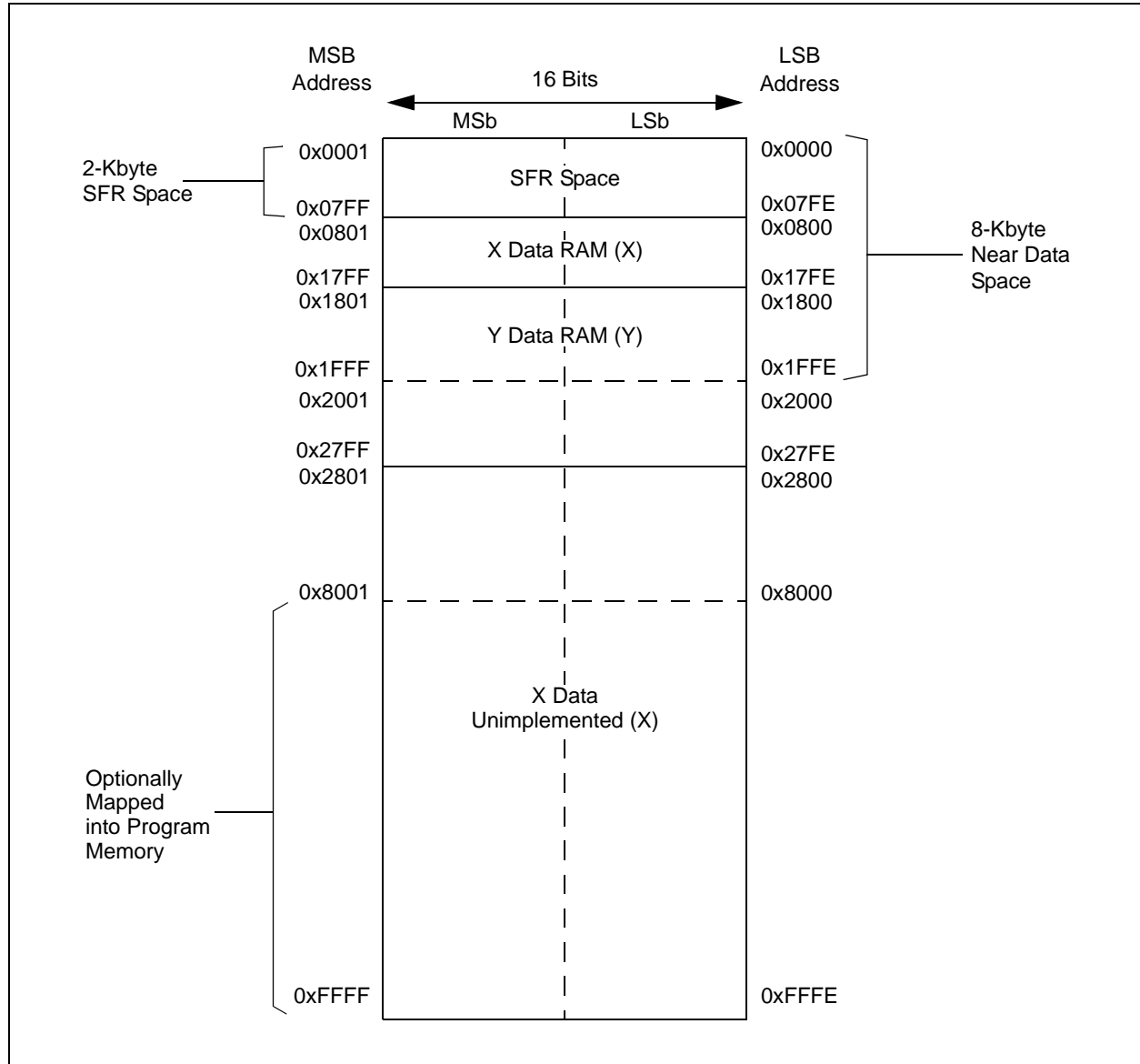
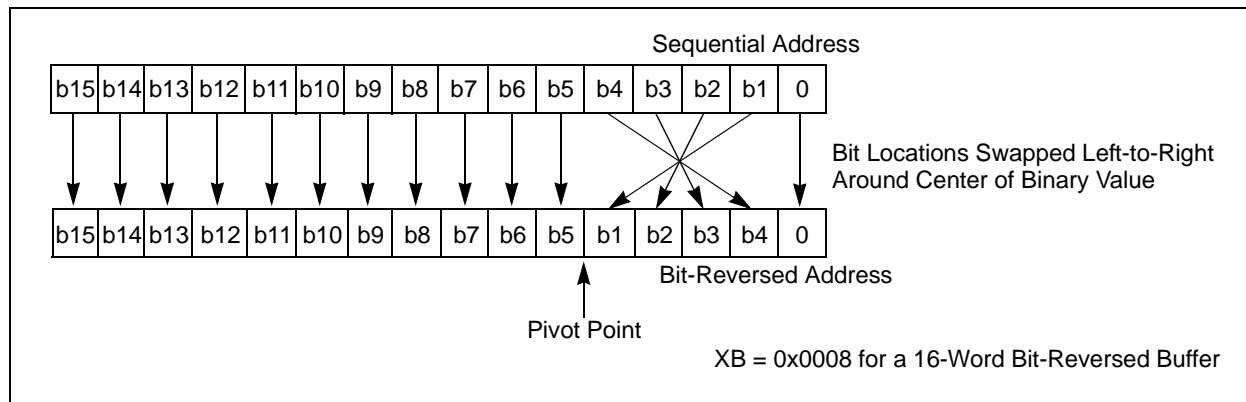


TABLE 4-32: HIGH-SPEED 10-BIT ADC REGISTER MAP FOR dsPIC33FJ32GS610 AND dsPIC33FJ64GS610 DEVICES ONLY (CONTINUED)

File Name	SFR Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
ADCBUF22	036C	ADC Data Buffer 22																xxxx
ADCBUF23	036E	ADC Data Buffer 23																xxxx
ADCBUF24	0370	ADC Data Buffer 24																xxxx
ADCBUF25	0372	ADC Data Buffer 25																xxxx

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**FIGURE 4-8: BIT-REVERSED ADDRESS EXAMPLE****TABLE 4-67: BIT-REVERSED ADDRESS SEQUENCE (16-ENTRY)**

Normal Address					Bit-Reversed Address				
A3	A2	A1	A0	Decimal	A3	A2	A1	A0	Decimal
0	0	0	0	0	0	0	0	0	0
0	0	0	1	1	1	0	0	0	8
0	0	1	0	2	0	1	0	0	4
0	0	1	1	3	1	1	0	0	12
0	1	0	0	4	0	0	1	0	2
0	1	0	1	5	1	0	1	0	10
0	1	1	0	6	0	1	1	0	6
0	1	1	1	7	1	1	1	0	14
1	0	0	0	8	0	0	0	1	1
1	0	0	1	9	1	0	0	1	9
1	0	1	0	10	0	1	0	1	5
1	0	1	1	11	1	1	0	1	13
1	1	0	0	12	0	0	1	1	3
1	1	0	1	13	1	0	1	1	11
1	1	1	0	14	0	1	1	1	7
1	1	1	1	15	1	1	1	1	15

## REGISTER 7-33: IPC14: INTERRUPT PRIORITY CONTROL REGISTER 14

U-0	U-0	U-0	U-0	U-0	R/W-1	R/W-0	R/W-0
—	—	—	—	—	QE11IP2	QE11IP1	QE11IP0
bit 15							bit 8

U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0
—	PSEMIP2	PSEMIP1	PSEMIP0	—	—	—	—
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-11 **Unimplemented:** Read as '0'

bit 10-8 **QE11IP<2:0>:** QE11 Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **PSEMIP<2:0>:** PWM Special Event Match Interrupt Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 3-0 **Unimplemented:** Read as '0'

**REGISTER 7-38: IPC21: INTERRUPT PRIORITY CONTROL REGISTER 21**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0
—	ADCP12IP2	ADCP12IP1	ADCP12IP0	—	—	—	—
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-7 **Unimplemented:** Read as '0'

bit 6-4 **ADCP12IP<2:0>:** ADC Pair 12 Conversion Done Interrupt 1 Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

- 
- 
- 

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 3-0 **Unimplemented:** Read as '0'

## 7.4 Interrupt Setup Procedures

### 7.4.1 INITIALIZATION

Complete the following steps to configure an interrupt source at initialization:

1. Set the NSTDIS bit (INTCON1<15>) if nested interrupts are not desired.
2. Select the user-assigned priority level for the interrupt source by writing the control bits in the appropriate IPCx register. The priority level will depend on the specific application and type of interrupt source. If multiple priority levels are not desired, the IPCx register control bits for all enabled interrupt sources can be programmed to the same non-zero value.

**Note:** At a device Reset, the IPCx registers are initialized such that all user interrupt sources are assigned to Priority Level 4.

3. Clear the interrupt flag status bit associated with the peripheral in the associated IFSx register.
4. Enable the interrupt source by setting the interrupt enable control bit associated with the source in the appropriate IECx register.

### 7.4.2 INTERRUPT SERVICE ROUTINE

The method used to declare an ISR and initialize the IVT with the correct vector address depends on the programming language (C or assembler) and the language development toolsuite used to develop the application.

In general, the user application must clear the interrupt flag in the appropriate IFSx register for the source of interrupt that the ISR handles. Otherwise, program will re-enter the ISR immediately after exiting the routine. If the ISR is coded in assembly language, it must be terminated using a RETFIE instruction to unstack the saved PC value, SRL value and old CPU priority level.

### 7.4.3 TRAP SERVICE ROUTINE

A Trap Service Routine (TSR) is coded like an ISR, except that the appropriate trap status flag in the INTCON1 register must be cleared to avoid re-entry into the TSR.

### 7.4.4 INTERRUPT DISABLE

The following steps outline the procedure to disable all user interrupts:

1. Push the current SR value onto the software stack using the PUSH instruction.
2. Force the CPU to Priority Level 7 by inclusive ORing the value, E0h, with SRL.

To enable user interrupts, the POP instruction can be used to restore the previous SR value.

**Note:** Only user interrupts with a priority level of 7 or lower can be disabled. Trap sources (Level 8-Level 15) cannot be disabled.

The DISI instruction provides a convenient way to disable interrupts of Priority Levels 1-6 for a fixed period of time. Level 7 interrupt sources are not disabled by the DISI instruction.



**REGISTER 8-4: DMAxSTB: DMA CHANNEL x RAM START ADDRESS OFFSET REGISTER B**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
STB<15:8>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
STB<7:0>							
bit 7				bit 0			

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
-n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 15-0                      **STB<15:0>**: Secondary DMA RAM Start Address bits (source or destination)

**REGISTER 8-5: DMAxPAD: DMA CHANNEL x PERIPHERAL ADDRESS REGISTER<sup>(1)</sup>**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PAD<15:8> <sup>(2)</sup>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PAD<7:0> <sup>(2)</sup>							
bit 7				bit 0			

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
-n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 15-0                      **PAD<15:0>**: Peripheral Address Register bits<sup>(2)</sup>

**Note 1:** If the channel is enabled (i.e., active), writes to this register may result in unpredictable behavior of the DMA channel and should be avoided.

**2:** See Table 8-1 for a complete list of peripheral addresses.

**REGISTER 8-9: DSADR: MOST RECENT DMA RAM ADDRESS REGISTER**

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
DSADR<15:8>							
bit 15				bit 8			

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
DSADR<7:0>							
bit 7				bit 0			

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0      **DSADR<15:0>**: Most Recent DMA RAM Address Accessed by DMA Controller bits

## REGISTER 10-1: PMD1: PERIPHERAL MODULE DISABLE CONTROL REGISTER 1

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0
T5MD	T4MD	T3MD	T2MD	T1MD	QE11MD	PWMMD <sup>(1)</sup>	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0
I2C1MD	U2MD	U1MD	SPI2MD	SPI1MD	—	C1MD	ADCMD
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

- bit 15      **T5MD:** Timer5 Module Disable bit  
                  1 = Timer5 module is disabled  
                  0 = Timer5 module is enabled
- bit 14      **T4MD:** Timer4 Module Disable bit  
                  1 = Timer4 module is disabled  
                  0 = Timer4 module is enabled
- bit 13      **T3MD:** Timer3 Module Disable bit  
                  1 = Timer3 module is disabled  
                  0 = Timer3 module is enabled
- bit 12      **T2MD:** Timer2 Module Disable bit  
                  1 = Timer2 module is disabled  
                  0 = Timer2 module is enabled
- bit 11      **T1MD:** Timer1 Module Disable bit  
                  1 = Timer1 module is disabled  
                  0 = Timer1 module is enabled
- bit 10      **QE11MD:** QE11 Module Disable bit  
                  1 = QE11 module is disabled  
                  0 = QE11 module is enabled
- bit 9      **PWMMD:** PWM Module Disable bit<sup>(1)</sup>  
                  1 = PWM module is disabled  
                  0 = PWM module is enabled
- bit 8      **Unimplemented:** Read as '0'
- bit 7      **I2C1MD:** I2C1 Module Disable bit  
                  1 = I2C1 module is disabled  
                  0 = I2C1 module is enabled
- bit 6      **U2MD:** UART2 Module Disable bit  
                  1 = UART2 module is disabled  
                  0 = UART2 module is enabled
- bit 5      **U1MD:** UART1 Module Disable bit  
                  1 = UART1 module is disabled  
                  0 = UART1 module is enabled
- bit 4      **SPI2MD:** SPI2 Module Disable bit  
                  1 = SPI2 module is disabled  
                  0 = SPI2 module is enabled

**Note 1:** Once the PWM module is re-enabled (PWMMD is set to '1' and then set to '0'), all PWM registers must be re-initialized.

## 12.0 TIMER1

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ32GS406/606/608/610 and dsPIC33FJ64GS406/606/608/610 families of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “Timers” (DS70205) in the “dsPIC33/PIC24 Family Reference Manual”, which is available from the Microchip web site (www.microchip.com). The information in this data sheet supersedes the information in the FRM.

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The Timer1 module is a 16-bit timer, which can serve as a time counter for the Real-Time Clock (RTC), or operate as a free-running interval timer/counter.

The Timer1 module has the following unique features over other timers:

- Can be operated from the low-power 32.767 kHz crystal oscillator available on the device.
- Can be operated in Asynchronous Counter mode from an external clock source.
- The external clock input (T1CK) can optionally be synchronized to the internal device clock and the clock synchronization is performed after the prescaler.

The unique features of Timer1 allow it to be used for Real-Time Clock (RTC) applications. A block diagram of Timer1 is shown in Figure 12-1.

The Timer1 module can operate in one of the following modes:

- Timer mode
- Gated Timer mode
- Synchronous Counter mode
- Asynchronous Counter mode

In Timer and Gated Timer modes, the input clock is derived from the internal instruction cycle clock (FCY). In Synchronous and Asynchronous Counter modes, the input clock is derived from the external clock input at the T1CK pin.

The Timer modes are determined by the following bits:

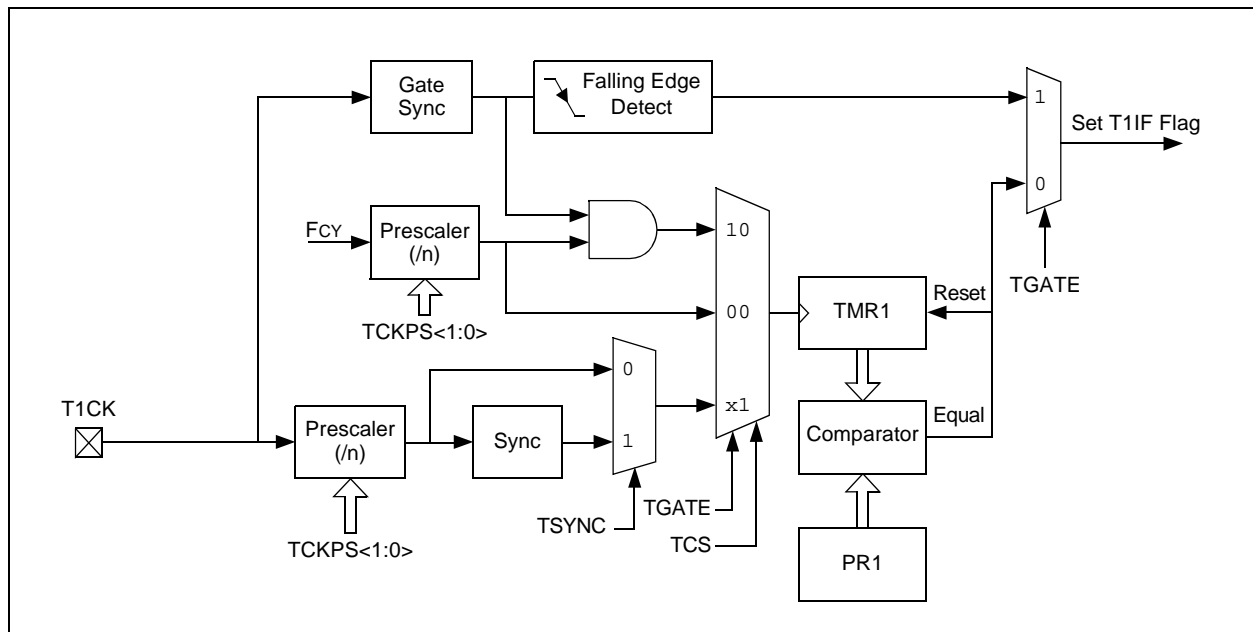
- Timer Clock Source Control bit: TCS (T1CON<1>)
- Timer Synchronization Control bit: TSYNC (T1CON<2>)
- Timer Gate Control bit: TGATE (T1CON<6>)

The timer control bit settings for different operating modes are given in the Table 12-1.

**TABLE 12-1: TIMER MODE SETTINGS**

Mode	TCS	TGATE	TSYNC
Timer	0	0	x
Gated Timer	0	1	x
Synchronous Counter	1	x	1
Asynchronous Counter	1	x	0

**FIGURE 12-1: 16-BIT TIMER1 MODULE BLOCK DIAGRAM**



NOTES:

## dsPIC33FJ32GS406/606/608/610 and dsPIC33FJ64GS406/606/608/610

### REGISTER 21-16: CxRXFnSID: ECANx ACCEPTANCE FILTER n STANDARD IDENTIFIER REGISTER (n = 0-15)

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
SID10	SID9	SID8	SID7	SID6	SID5	SID4	SID3
bit 15						bit 8	

R/W-x	R/W-x	R/W-x	U-0	R/W-x	U-0	R/W-x	R/W-x
SID2	SID1	SID0	—	EXIDE	—	EID17	EID16
bit 7						bit 0	

#### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-5

**SID<10:0>:** Standard Identifier bits

1 = Message address bit, SIDx, must be '1' to match filter

0 = Message address bit, SIDx, must be '0' to match filter

bit 4

**Unimplemented:** Read as '0'

bit 3

**EXIDE:** Extended Identifier Enable bit

If MIDE = 1, then:

1 = Matches only messages with Extended Identifier addresses

0 = Matches only messages with Standard Identifier addresses

If MIDE = 0, then:

Ignores EXIDE bit.

bit 2

**Unimplemented:** Read as '0'

bit 1-0

**EID<17:16>:** Extended Identifier bits

1 = Message address bit, EIDx, must be '1' to match filter

0 = Message address bit, EIDx, must be '0' to match filter

## BUFFER 21-5: ECANx MESSAGE BUFFER WORD 4

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
Byte 3							
bit 15				bit 8			

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
Byte 2							
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-8 **Byte 3<15:8>**: ECANx Message Byte 3

bit 7-0 **Byte 2<7:0>**: ECANx Message Byte 2

## BUFFER 21-6: ECANx MESSAGE BUFFER WORD 5

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
Byte 5							
bit 15				bit 8			

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
Byte 4							
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-8 **Byte 5<15:8>**: ECANx Message Byte 5

bit 7-0 **Byte 4<7:0>**: ECANx Message Byte 4

## REGISTER 22-8: ADCPC2: ADC CONVERT PAIR CONTROL REGISTER 2

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
IRQEN5	PEND5	SWTRG5	TRGSRC54	TRGSRC53	TRGSRC52	TRGSRC51	TRGSRC50
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
IRQEN4	PEND4	SWTRG4	TRGSRC44	TRGSRC43	TRGSRC42	TRGSRC41	TRGSRC40
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **IRQEN5:** Interrupt Request Enable 5 bit  
1 = Enables IRQ generation when requested conversion of Channels AN11 and AN10 is completed  
0 = IRQ is not generated
- bit 14      **PEND5:** Pending Conversion Status 5 bit  
1 = Conversion of Channels AN11 and AN10 is pending; set when selected trigger is asserted  
0 = Conversion is complete
- bit 13      **SWTRG5:** Software Trigger 5 bit  
1 = Starts conversion of AN11 and AN10 (if selected by the TRGSRCx<4:0> bits)<sup>(1)</sup>  
This bit is automatically cleared by hardware when the PEND5 bit is set.  
0 = Conversion has not started

**Note 1:** The trigger source must be set as an individual software trigger prior to setting this bit to '1'. If other conversions are in progress, the conversion is performed when the conversion resources are available.



## 23.0 HIGH-SPEED ANALOG COMPARATOR

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ32GS406/606/608/610 and dsPIC33FJ64GS406/606/608/610 families of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**High-Speed Analog Comparator**” (DS70296) in the “dsPIC33/PIC24 Family Reference Manual”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)). The information in this data sheet supersedes the information in the FRM.

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The dsPIC33F Switch Mode Power Supply (SMPS) comparator module monitors current and/or voltage transients that may be too fast for the CPU and ADC to capture.

### 23.1 Features Overview

The SMPS comparator module offers the following major features:

- 16 Selectable Comparator Inputs
- Up to Four Analog Comparators

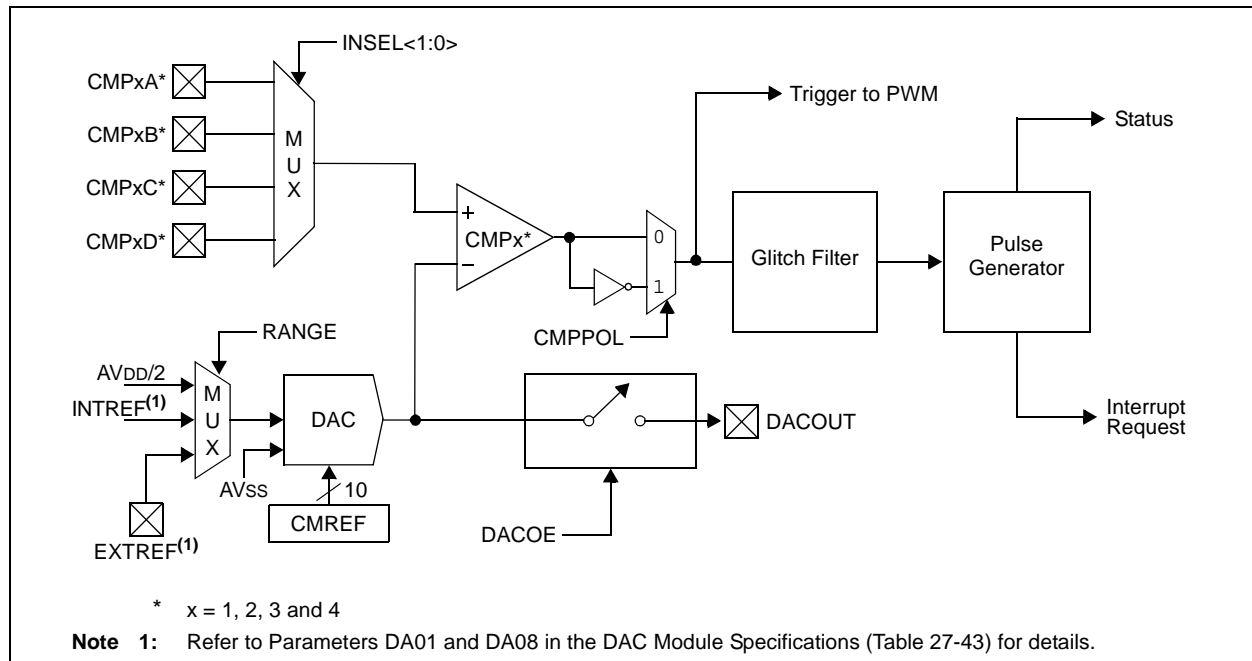
- 10-Bit DAC for each Analog Comparator
- Programmable Output Polarity
- Interrupt Generation Capability
- DACOUT Pin to provide DAC Output
- DAC has Three Ranges of Operation:
  - $AV_{DD}/2$
  - Internal Reference (INTREF)
  - External Reference (EXTREF)
- ADC Sample-and-Convert Trigger Capability
- Disable Capability reduces Power Consumption
- Functional Support for PWM module:
  - PWM duty cycle control
  - PWM period control
  - PWM Fault detect

### 23.2 Module Description

Figure 23-1 shows a functional block diagram of one analog comparator from the SMPS comparator module. The analog comparator provides high-speed operation with a typical delay of 20 ns. The comparator has a typical offset voltage of  $\pm 5$  mV. The negative input of the comparator is always connected to the DAC circuit. The positive input of the comparator is connected to an analog multiplexer that selects the desired source pin.

The analog comparator input pins are typically shared with pins used by the Analog-to-Digital Converter (ADC) module. Both the comparator and the ADC can use the same pins at the same time. This capability enables a user to measure an input voltage with the ADC and detect voltage transients with the comparator.

**FIGURE 23-1: HIGH-SPEED ANALOG COMPARATOR x MODULE BLOCK DIAGRAM**



**TABLE 27-36: SPIx SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 1, SMP = 0) TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ <sup>(2)</sup>	Max	Units	Conditions
SP70	TscP	Maximum SCKx Input Frequency	—	—	15	MHz	See <b>Note 3</b>
SP72	TscF	SCKx Input Fall Time	—	—	—	ns	See Parameter DO32 and <b>Note 4</b>
SP73	TscR	SCKx Input Rise Time	—	—	—	ns	See Parameter DO31 and <b>Note 4</b>
SP30	TdoF	SDOx Data Output Fall Time	—	—	—	ns	See Parameter DO32 and <b>Note 4</b>
SP31	TdoR	SDOx Data Output Rise Time	—	—	—	ns	See Parameter DO31 and <b>Note 4</b>
SP35	Tsch2doV, TscL2doV	SDOx Data Output Valid after SCKx Edge	—	6	20	ns	
SP36	TdoV2scH, TdoV2scL	SDOx Data Output Setup to First SCKx Edge	30	—	—	ns	
SP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCKx Edge	30	—	—	ns	
SP41	Tsch2diL, TscL2diL	Hold Time of SDIx Data Input to SCKx Edge	30	—	—	ns	
SP50	TssL2scH, TssL2scL	$\overline{SSx} \downarrow$ to SCKx $\uparrow$ or SCKx Input	120	—	—	ns	
SP51	TssH2doZ	$\overline{SSx} \uparrow$ to SDOx Output High-Impedance	10	—	50	ns	See <b>Note 4</b>
SP52	Tsch2ssH TscL2ssH	$\overline{SSx}$ after SCKx Edge	1.5 TCY + 40	—	—	ns	See <b>Note 4</b>

**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**2:** Data in "Typ" column is at 3.3V, +25°C unless otherwise stated.

**3:** The minimum clock period for SCKx is 66.7 ns. Therefore, the SCKx clock, generated by the master, must not violate this specification.

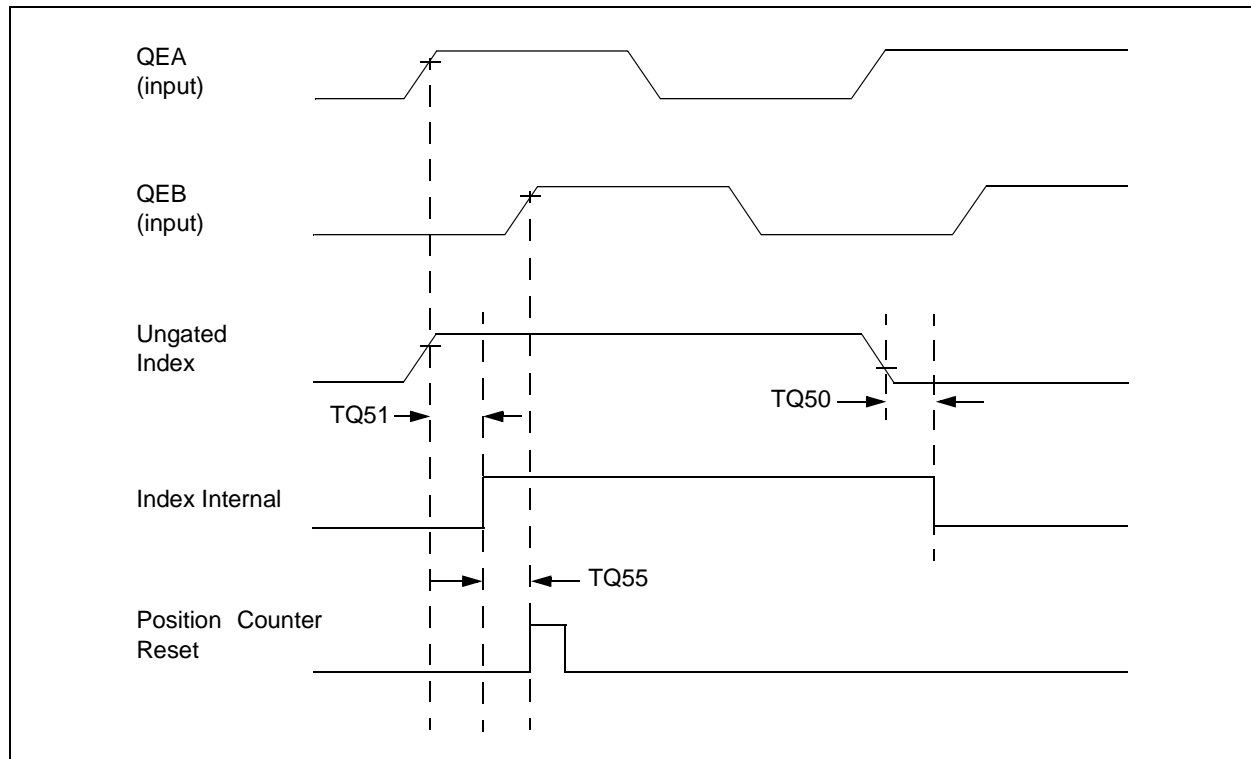
**4:** Assumes 50 pF load on all SPIx pins.

**TABLE 27-45: QUADRATURE DECODER TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended			
Param No.	Symbol	Characteristic <sup>(1)</sup>	Typ <sup>(2)</sup>	Max	Units	Conditions
TQ30	TQuL	Quadrature Input Low Time	6 TcY	—	ns	
TQ31	TQuH	Quadrature Input High Time	6 TcY	—	ns	
TQ35	TQuIN	Quadrature Input Period	12 TcY	—	ns	
TQ36	TQuP	Quadrature Phase Period	3 TcY	—	ns	
TQ40	TQuFL	Filter Time to Recognize Low, with Digital Filter	3 * N * TcY	—	ns	N = 1, 2, 4, 16, 32, 64, 128 and 256 ( <b>Note 3</b> )
TQ41	TQuFH	Filter Time to Recognize High, with Digital Filter	3 * N * TcY	—	ns	N = 1, 2, 4, 16, 32, 64, 128 and 256 ( <b>Note 3</b> )

- Note 1:** These parameters are characterized but not tested in manufacturing.  
**Note 2:** Data in “Typ” column is at 3.3V, +25°C unless otherwise stated.  
**Note 3:** N = Index Channel Digital Filter Clock Divide Select bits. Refer to “**Quadrature Encoder Interface (QEI)**” (DS70208) in the “*dsPIC33/PIC24 Family Reference Manual*”.

**FIGURE 27-25: QEI MODULE INDEX PULSE TIMING CHARACTERISTICS**



**Revision D (January 2012)**

This revision includes minor typographical and formatting changes throughout the data sheet text.

All occurrences of PGCn and PGDn (where n = 1, 2, or 3) were updated to: PGECn and PGEDn throughout the document.

All other changes are referenced by their respective section in Table B-3.

**TABLE B-3: MAJOR SECTION UPDATES**

Section Name	Update Description
<b>“16-Bit Digital Signal Controllers with High-Speed PWM, ADC and Comparators”</b>	Added 50 MIPS to Operating Range.  Changed the Oscillator frequency range in System Management.  Added the <b>“Referenced Sources”</b> section.
<b>Section 1.0 “Device Overview”</b>	Updated the block diagram of the core and peripheral modules (see Figure 1-1).
<b>Section 2.0 “Guidelines for Getting Started with 16-Bit Digital Signal Controllers”</b>	Updated the Recommended Minimum Connection diagram (see Figure 2-1).  Updated the VCAP pin capacitor specification in <b>Section 2.3 “Capacitor on Internal Voltage Regulator (VCAP)”</b> .
<b>Section 4.0 “Memory Organization”</b>	Removed IPC20 and updated IFS5, IFS7, IEC5, IEC7, and IPC29 in the Interrupt Controller Register Map for dsPIC33FJ64GS606 devices (see Table 4-6).  Removed IPC20 and IPC21 and updated IFS5, IFS7, IEC5, IEC7, and IPC29 in the Interrupt Controller Register Map for dsPIC33FJ32GS406 and dsPIC33FJ64GS406 devices (see Table 4-7).  Removed IPC20 and updated IFS5, IFS7, IEC5, IEC7, and IPC29 in the Interrupt Controller Register Map for dsPIC33FJ32GS606 devices (see Table 4-10).  Added High-Speed 10-bit ADC Register Map for dsPIC33FJ32GS406 and dsPIC33FJ64GS406 devices (see Table 4-35).  Updated ODCG in PORTG Register Map for dsPIC33FJ32GS610 and dsPIC33FJ64GS610 devices (see Table 4-54).  Updated ODCG in PORTG Register Map for dsPIC33FJ32GS608 and dsPIC33FJ64GS608 devices (see Table 4-55).  Updated ODCG in PORTG Register Map for dsPIC33FJ32GS406/606 and dsPIC33FJ64GS406/606 devices (see Table 4-56).
<b>Section 9.0 “Oscillator Configuration”</b>	Changed the High-Speed Crystal (HS) frequency range in <b>Section 9.1.1 “System Clock sources”</b> .  Updated the device operating speed to up to 50 MHz in <b>Section 9.1.2 “System Clock Selection”</b> .  Updated <b>Section 9.1.3 “PLL Configuration”</b> to reflect the new operating range/speed of 50 MIPS/50 MHz.  Updated <b>Section 9.2 “Auxiliary Clock Generation”</b> .

## INDEX

### A

AC Characteristics .....	382
10-Bit, High-Speed ADC .....	410
Internal FRC Accuracy .....	385
Internal LPRC Accuracy .....	385
Load Conditions .....	382
Temperature and Voltage Specifications .....	382
Arithmetic Logic Unit (ALU) .....	39
Assembler .....	
MPASM Assembler .....	366

### B

Barrel Shifter .....	43
Bit-Reversed Addressing .....	102
Example .....	103
Implementation .....	102
Sequence Table (16-Entry) .....	103
Block Diagrams .....	
16-Bit Timer1 Module .....	217
AC-to-DC Power Supply with PFC and 3 Outputs .....	32
ADC Module with 1 SAR for dsPIC33FJ32GS406, dsPIC33FJ64GS406 Devices .....	315
ADC Module with 2 SARs for dsPIC33FJ32GS606, dsPIC33FJ64GS606 Devices .....	316
ADC Module with 2 SARs for dsPIC33FJ32GS608, dsPIC33FJ64GS608 Devices .....	317
ADC Module with 2 SARs for dsPIC33FJ32GS610, dsPIC33FJ64GS610 Devices .....	318
Boost Converter Implementation .....	27
Conceptual High-Speed PWMx .....	233
Connections for On-Chip Voltage Regulator .....	353
Digital PFC .....	27
DMA Top Level Architecture Using Dedicated Transaction Bus .....	180
DSP Engine .....	40
dsPIC33FJ32GS406/606/608/610 and dsPIC33FJ64GS406/606/608/610 .....	18
dsPIC33FJ32GS406/606/608/610 and dsPIC33FJ64GS406/606/608/610 CPU Core .....	34
ECANx Module .....	286
High-Speed Analog Comparator x Module .....	345
High-Speed PWMx Architecture .....	232
I2Cx Module .....	272
Input Capture x .....	225
Interleaved PFC .....	30
MCLR Pin Connections .....	24
Minimum Connections .....	24
Multi-Phase Synchronous Buck Converter .....	28
Off-Line Ups .....	29
Oscillator Circuit Placement .....	25
Oscillator System .....	190
Output Compare x Module .....	227
Phase-Shifted Full-Bridge Converter .....	31
PLL .....	192
Quadrature Encoder Interface x .....	261
Reset System .....	116
Shared Port Structure .....	214
Simplified UARTx Module .....	279
Single-Phase Synchronous Buck Converter .....	28
SPIx Module .....	265
Timer2/3/4/5 (32-Bit) .....	221

Type B Timer .....	219
Type C Timer .....	219
Watchdog Timer (WDT) .....	354
Brown-out Reset (BOR) .....	120, 349, 353

### C

C Compilers .....	
MPLAB XC Compilers .....	366
Clock Generation .....	
Auxiliary .....	193
Reference .....	193
Clock Switching .....	201
Enabling .....	201
Sequence .....	201
Code Examples .....	
Erasing a Program Memory Page .....	113
Initiating a Programming Sequence .....	114
Loading Write Buffers .....	114
Port Write/Read .....	215
PWRSAV Instruction Syntax .....	203
Code Protection .....	349, 356
CodeGuard Security .....	349, 356
Configuration Bits .....	349
Description .....	350
Configuration Register Map .....	349
Configuring Analog Port Pins .....	215
CPU .....	
Control Registers .....	36
Data Addressing Overview .....	33
DSP Engine Overview .....	33
Special MCU Features .....	34
CPU Clocking System .....	191
PLL Configuration .....	192
Selection .....	191
Sources .....	191
Customer Change Notification Service .....	455
Customer Notification Service .....	455
Customer Support .....	455

### D

Data Accumulators and Adder/Subtractor .....	41
Data Space Write Saturation .....	43
Overflow and Saturation .....	41
Round Logic .....	42
Write-Back .....	42
Data Address Space .....	47
Alignment .....	47
Memory Map for 4-Kbyte RAM Devices .....	48
Memory Map for 8-Kbyte RAM Devices .....	49
Memory Map for 9-Kbyte RAM Devices .....	50
Near Data Space .....	47
SFR Space .....	47
Software Stack .....	99
Width .....	47
DC and AC Characteristics .....	
Graphs and Tables .....	423
DC Characteristics .....	
Brown-out Reset (BOR) .....	380
Doze Current (IDOE) .....	376
I/O Pin Input Specifications .....	377
I/O Pin Output Specifications .....	379