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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

| Details | |
|----------------------------|---|
| Product Status | Active |
| Core Processor | PIC |
| Core Size | 16-Bit |
| Speed | 32MHz |
| Connectivity | I ² C, IrDA, SPI, UART/USART |
| Peripherals | Brown-out Detect/Reset, POR, PWM, WDT |
| Number of I/O | 24 |
| Program Memory Size | 16KB (5.5K x 24) |
| Program Memory Type | FLASH |
| EEPROM Size | 512 x 8 |
| RAM Size | 1.5K x 8 |
| Voltage - Supply (Vcc/Vdd) | 1.8V ~ 3.6V |
| Data Converters | A/D 9x10b |
| Oscillator Type | Internal |
| Operating Temperature | -40°C ~ 85°C (TA) |
| Mounting Type | Through Hole |
| Package / Case | 28-DIP (0.300", 7.62mm) |
| Supplier Device Package | 28-SPDIP |
| Purchase URL | https://www.e-xfl.com/product-detail/microchip-technology/pic24f16ka102-i-sp |

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3.2 CPU Control Registers

REGISTER 3-1: SR: ALU STATUS REGISTER

| | | | | | | | |
|--------|-----|-----|-----|-----|-----|-----|------------|
| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | R/W-0, HSC |
| — | — | — | — | — | — | — | DC |
| bit 15 | | | | | | | bit 8 |

| | | | | | | | |
|---------------------------|---------------------------|---------------------------|----------|------------|------------|------------|------------|
| R/W-0, HSC ⁽¹⁾ | R/W-0, HSC ⁽¹⁾ | R/W-0, HSC ⁽¹⁾ | R-0, HSC | R/W-0, HSC | R/W-0, HSC | R/W-0, HSC | R/W-0, HSC |
| IPL2 ⁽²⁾ | IPL1 ⁽²⁾ | IPL0 ⁽²⁾ | RA | N | OV | Z | C |
| bit 7 | | | | | | | bit 0 |

| | |
|-------------------|---------------------------------------|
| Legend: | HSC = Hardware Settable/Clearable bit |
| R = Readable bit | W = Writable bit |
| -n = Value at POR | '1' = Bit is set |
| | U = Unimplemented bit, read as '0' |
| | '0' = Bit is cleared |
| | x = Bit is unknown |

- bit 15-9 **Unimplemented:** Read as '0'
- bit 8 **DC:** ALU Half Carry/Borrow bit
 1 = A carry-out from the 4th low-order bit (for byte-sized data) or 8th low-order bit (for word-sized data) of the result occurred
 0 = No carry-out from the 4th or 8th low-order bit of the result has occurred
- bit 7-5 **IPL<2:0>:** CPU Interrupt Priority Level Status bits^(1,2)
 111 = CPU interrupt priority level is 7 (15); user interrupts disabled
 110 = CPU interrupt priority level is 6 (14)
 101 = CPU Interrupt priority level is 5 (13)
 100 = CPU interrupt priority level is 4 (12)
 011 = CPU interrupt priority level is 3 (11)
 010 = CPU interrupt priority level is 2 (10)
 001 = CPU interrupt priority level is 1 (9)
 000 = CPU interrupt priority level is 0 (8)
- bit 4 **RA:** REPEAT Loop Active bit
 1 = REPEAT loop in progress
 0 = REPEAT loop not in progress
- bit 3 **N:** ALU Negative bit
 1 = Result was negative
 0 = Result was non-negative (zero or positive)
- bit 2 **OV:** ALU Overflow bit
 1 = Overflow occurred for signed (2's complement) arithmetic in this arithmetic operation
 0 = No overflow has occurred
- bit 1 **Z:** ALU Zero bit
 1 = An operation, which effects the Z bit, has set it at some time in the past
 0 = The most recent operation, which effects the Z bit, has cleared it (i.e., a non-zero result)
- bit 0 **C:** ALU Carry/Borrow bit
 1 = A carry-out from the Most Significant bit (MSb) of the result occurred
 0 = No carry-out from the Most Significant bit (MSb) of the result occurred

- Note 1:** The IPL Status bits are read-only when NSTDIS (INTCON1<15>) = 1.
- Note 2:** The IPL Status bits are concatenated with the IPL3 bit (CORCON<3>) to form the CPU Interrupt Priority Level (IPL). The value in parentheses indicates the IPL when IPL3 = 1.

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3.3.2 DIVIDER

The divide block supports 32-bit/16-bit and 16-bit/16-bit signed and unsigned integer divide operations with the following data sizes:

1. 32-bit signed/16-bit signed divide
2. 32-bit unsigned/16-bit unsigned divide
3. 16-bit signed/16-bit signed divide
4. 16-bit unsigned/16-bit unsigned divide

The quotient for all divide instructions ends up in W0 and the remainder in W1. Sixteen-bit signed and unsigned DIV instructions can specify any W register for both the 16-bit divisor (Wn), and any W register (aligned) pair (W(m + 1):Wm) for the 32-bit dividend. The divide algorithm takes one cycle per bit of divisor, so both 32-bit/16-bit and 16-bit/16-bit instructions take the same number of cycles to execute.

3.3.3 MULTI-BIT SHIFT SUPPORT

The PIC24F ALU supports both single bit and single-cycle, multi-bit arithmetic and logic shifts. Multi-bit shifts are implemented using a shifter block, capable of performing up to a 15-bit arithmetic right shift, or up to a 15-bit left shift, in a single cycle. All multi-bit shift instructions only support Register Direct Addressing for both the operand source and result destination.

A full summary of instructions that use the shift operation is provided below in Table 3-2.

TABLE 3-2: INSTRUCTIONS THAT USE THE SINGLE AND MULTI-BIT SHIFT OPERATION

| Instruction | Description |
|-------------|---|
| ASR | Arithmetic shift right source register by one or more bits. |
| SL | Shift left source register by one or more bits. |
| LSR | Logical shift right source register by one or more bits. |

TABLE 4-9: I²C™ REGISTER MAP

| File Name | Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets | |
|-----------|------|---------|--------|---------|--------|--------|--------|-----------------------|-----------------------------------|------------------------|-------|-------|-------|-------|-------|-------|-------|------------|------|
| I2C1RCV | 0200 | — | — | — | — | — | — | — | — | I2C1 Receive Register | | | | | | | | | 0000 |
| I2C1TRN | 0202 | — | — | — | — | — | — | — | — | I2C1 Transmit Register | | | | | | | | | 00FF |
| I2C1BRG | 0204 | — | — | — | — | — | — | — | I2C1 Baud Rate Generator Register | | | | | | | | | | 0000 |
| I2C1CON | 0206 | I2CEN | — | I2CSIDL | SCLREL | IPMIEN | A10M | DISSLW | SMEN | GCEN | STREN | ACKDT | ACKEN | RCEN | PEN | RSEN | SEN | 1000 | |
| I2C1STAT | 0208 | ACKSTAT | TRSTAT | — | — | — | BCL | GCSTAT | ADD10 | IWCOL | I2COV | D/Ā | P | S | R/W | RBF | TBF | 0000 | |
| I2C1ADD | 020A | — | — | — | — | — | — | I2C1 Address Register | | | | | | | | | | 0000 | |
| I2C1MSK | 020C | — | — | — | — | — | — | AMSK9 | AMSK8 | AMSK7 | AMSK6 | AMSK5 | AMSK4 | AMSK3 | AMSK2 | AMSK1 | AMSK0 | 0000 | |

Legend: — = unimplemented, read as '0'. Reset values are shown in h.5adecimal.

TABLE 4-10: UART REGISTER MAP

| File Name | Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|-----------|------|--|--------|----------|--------|--------|--------|-------|-------------------------|----------|----------|-------|-------|-------|--------|--------|-------|------------|
| U1MODE | 0220 | UARTEN | — | USIDL | IREN | RTSMD | — | UEN1 | UEN0 | WAKE | LPBACK | ABAUD | RXINV | BRGH | PDSEL1 | PDSEL0 | STSEL | 0000 |
| U1STA | 0222 | UTXISEL1 | UTXINV | UTXISEL0 | — | UTXBRK | UTXEN | UTXBF | TRMT | URXISEL1 | URXISEL0 | ADDEN | RIDLE | PERR | FERR | OERR | URXDA | 0110 |
| U1TXREG | 0224 | — | — | — | — | — | — | — | UART1 Transmit Register | | | | | | | | | 0000 |
| U1RXREG | 0226 | — | — | — | — | — | — | — | UART1 Receive Register | | | | | | | | | 0000 |
| U1BRG | 0228 | Baud Rate Generator Prescaler Register | | | | | | | | | | | | | | | | 0000 |
| U2MODE | 0230 | UARTEN | — | USIDL | IREN | RTSMD | — | UEN1 | UEN0 | WAKE | LPBACK | ABAUD | RXINV | BRGH | PDSEL1 | PDSEL0 | STSEL | 0000 |
| U2STA | 0232 | UTXISEL1 | UTXINV | UTXISEL0 | — | UTXBRK | UTXEN | UTXBF | TRMT | URXISEL1 | URXISEL0 | ADDEN | RIDLE | PERR | FERR | OERR | URXDA | 0110 |
| U2TXREG | 0234 | — | — | — | — | — | — | — | UART2 Transmit Register | | | | | | | | | 0000 |
| U2RXREG | 0236 | — | — | — | — | — | — | — | UART2 Receive Register | | | | | | | | | 0000 |
| U2BRG | 0238 | Baud Rate Generator Prescaler | | | | | | | | | | | | | | | | 0000 |

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-11: SPI REGISTER MAP

| File Name | Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|-----------|------|------------------------------|--------|---------|--------|--------|---------|---------|---------|-------|--------|--------|-------|-------|-------|--------|--------|------------|
| SPI1STAT | 0240 | SPIEN | — | SPISIDL | — | — | SPIBEC2 | SPIBEC1 | SPIBEC0 | SRMPT | SPIROV | SRXMPT | ISEL2 | ISEL1 | ISEL0 | SPITBF | SPIRBF | 0000 |
| SPI1CON1 | 0242 | — | — | — | DISSCK | DISSDO | MODE16 | SMP | CKE | SSEN | CKP | MSTEN | SPRE2 | SPRE1 | SPRE0 | PPRE1 | PPRE0 | 0000 |
| SPI1CON2 | 0244 | FRMEN | SPIFSD | SPIFPOL | — | — | — | — | — | — | — | — | — | — | — | SPIFE | SPIBEN | 0000 |
| SPI1BUF | 0248 | SPI1 Transmit/Receive Buffer | | | | | | | | | | | | | | | | 0000 |

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

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REGISTER 8-22: IPC18: INTERRUPT PRIORITY CONTROL REGISTER 18

| | | | | | | | |
|--------|-----|-----|-----|-----|-----|-----|-------|
| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
| — | — | — | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| | | | | | | | |
|-------|-----|-----|-----|-----|---------|---------|---------|
| U-0 | U-0 | U-0 | U-0 | U-0 | R/W-1 | R/W-0 | R/W-0 |
| — | — | — | — | — | HLVDIP2 | HLVDIP1 | HLVDIP0 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-3 **Unimplemented:** Read as '0'
 bit 2-0 **HLVDIP<2:0>:** High/Low-Voltage Detect Interrupt Priority bits
 111 = Interrupt is Priority 7 (highest priority interrupt)
 •
 •
 •
 001 = Interrupt is Priority 1
 000 = Interrupt source is disabled

REGISTER 8-23: IPC19: INTERRUPT PRIORITY CONTROL REGISTER 19

| | | | | | | | |
|--------|-----|-----|-----|-----|-----|-----|-------|
| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
| — | — | — | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| | | | | | | | |
|-------|---------|---------|---------|-----|-----|-----|-------|
| U-0 | R/W-1 | R/W-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 |
| — | CTMUIP2 | CTMUIP1 | CTMUIP0 | — | — | — | — |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-7 **Unimplemented:** Read as '0'
 bit 6-4 **CTMUIP<2:0>:** CTMU Interrupt Priority bits
 111 = Interrupt is Priority 7 (highest priority interrupt)
 •
 •
 •
 001 = Interrupt is Priority 1
 000 = Interrupt source is disabled
 bit 3-0 **Unimplemented:** Read as '0'

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9.1 CPU Clocking Scheme

The system clock source can be provided by one of four sources:

- Primary Oscillator (POSC) on the OSC1 and OSCO pins
- Secondary Oscillator (SOSC) on the SOSCI and SOSCO pins

The PIC24F16KA102 family devices consist of two types of secondary oscillator:

- High-Power Secondary Oscillator
- Low-Power Secondary Oscillator

These can be selected by using the SOSSEL (FOSC<5>) bit.

- Fast Internal RC (FRC) Oscillator
 - 8 MHz FRC Oscillator
 - 500 kHz Lower Power FRC Oscillator
- Low-Power Internal RC (LPRC) Oscillator

The primary oscillator and 8 MHz FRC sources have the option of using the internal 4x PLL. The frequency of the FRC clock source can optionally be reduced by the programmable clock divider. The selected clock source generates the processor and peripheral clock sources.

The processor clock source is divided by two to produce the internal instruction cycle clock, F_{cy}. In this document, the instruction cycle clock is also denoted by Fosc/2. The internal instruction cycle clock, Fosc/2, can be provided on the OSCO I/O pin for some operating modes of the primary oscillator.

9.2 Initial Configuration on POR

The oscillator source (and operating mode) that is used at a device Power-on Reset (POR) event is selected using Configuration bit settings. The Oscillator Configuration bit settings are located in the Configuration registers in the program memory (refer to **Section 26.1 “Configuration Bits”** for further details). The Primary Oscillator Configuration bits, POSCMD<1:0> (FOSC<1:0>), and the Initial Oscillator Select Configuration bits, FNOSEC<2:0> (FOSCSEL<2:0>), select the oscillator source that is used at a POR. The FRC Primary Oscillator with Postscaler (FRCDIV) is the default (unprogrammed) selection. The secondary oscillator, or one of the internal oscillators, may be chosen by programming these bit locations. The EC mode frequency range Configuration bits, POSCFREQ<1:0> (FOSC<4:3>), optimize power consumption when running in EC mode. The default configuration is “frequency range is greater than 8 MHz”.

The Configuration bits allow users to choose between the various clock modes, shown in Table 9-1.

9.2.1 CLOCK SWITCHING MODE CONFIGURATION BITS

The FCKSM Configuration bits (FOSC<7:6>) are used jointly to configure device clock switching and the FSCM. Clock switching is enabled only when FCKSM1 is programmed ('0'). The FSCM is enabled only when FCKSM<1:0> are both programmed ('00').

TABLE 9-1: CONFIGURATION BIT VALUES FOR CLOCK SELECTION

| Oscillator Mode | Oscillator Source | POSCMD<1:0> | FNOSEC<2:0> | Note |
|---|-------------------|-------------|-------------|-------------|
| 8 MHz FRC Oscillator with Postscaler (FRCDIV) | Internal | 11 | 111 | 1, 2 |
| 500 MHz FRC Oscillator with Postscaler (LPFRCDIV) | Internal | 11 | 110 | 1 |
| Low-Power RC Oscillator (LPRC) | Internal | 11 | 101 | 1 |
| Secondary (Timer1) Oscillator (SOSC) | Secondary | 00 | 100 | 1 |
| Primary Oscillator (HS) with PLL Module (HSPLL) | Primary | 10 | 011 | |
| Primary Oscillator (EC) with PLL Module (ECPLL) | Primary | 00 | 011 | |
| Primary Oscillator (HS) | Primary | 10 | 010 | |
| Primary Oscillator (XT) | Primary | 01 | 010 | |
| Primary Oscillator (EC) | Primary | 00 | 010 | |
| 8 MHz FRC Oscillator with PLL Module (FRCPLL) | Internal | 11 | 001 | 1 |
| 8 MHz FRC Oscillator (FRC) | Internal | 11 | 000 | 1 |

Note 1: OSCO pin function is determined by the OSCIOFNC Configuration bit.

2: This is the default oscillator mode for an unprogrammed (erased) device.

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REGISTER 9-4: REFOCON: REFERENCE OSCILLATOR CONTROL REGISTER

| | | | | | | | |
|--------|-----|--------|-------|--------|--------|--------|--------|
| R/W-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
| ROEN | — | ROSSLP | ROSEL | RODIV3 | RODIV2 | RODIV1 | RODIV0 |
| bit 15 | | | | | | | bit 8 |

| | | | | | | | |
|-------|-----|-----|-----|-----|-----|-----|-------|
| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
| — | — | — | — | — | — | — | — |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

- bit 15 **ROEN:** Reference Oscillator Output Enable bit
 1 = Reference oscillator is enabled on REFO pin
 0 = Reference oscillator is disabled
- bit 14 **Unimplemented:** Read as '0'
- bit 13 **ROSSLP:** Reference Oscillator Output Stop in Sleep bit
 1 = Reference oscillator continues to run in Sleep
 0 = Reference oscillator is disabled in Sleep
- bit 12 **ROSEL:** Reference Oscillator Source Select bit
 1 = Primary oscillator is used as the base clock⁽¹⁾
 0 = System clock is used as the base clock; base clock reflects any clock switching of the device
- bit 11-8 **RODIV<3:0>:** Reference Oscillator Divisor Select bits
 1111 = Base clock value divided by 32,768
 1110 = Base clock value divided by 16,384
 1101 = Base clock value divided by 8,192
 1100 = Base clock value divided by 4,096
 1011 = Base clock value divided by 2,048
 1010 = Base clock value divided by 1,024
 1001 = Base clock value divided by 512
 1000 = Base clock value divided by 256
 0111 = Base clock value divided by 128
 0110 = Base clock value divided by 64
 0101 = Base clock value divided by 32
 0100 = Base clock value divided by 16
 0011 = Base clock value divided by 8
 0010 = Base clock value divided by 4
 0001 = Base clock value divided by 2
 0000 = Base clock value
- bit 7-0 **Unimplemented:** Read as '0'

Note 1: The crystal oscillator must be enabled using the FOSC<2:0> bits; the crystal maintains the operation in Sleep mode.

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REGISTER 10-2: DSWAKE: DEEP SLEEP WAKE-UP SOURCE REGISTER⁽¹⁾

| | | | | | | | |
|--------|-----|-----|-----|-----|-----|-----|-----------|
| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | R/W-0, HS |
| — | — | — | — | — | — | — | DSINT0 |
| bit 15 | | | | | | | bit 8 |

| | | | | | | | |
|-----------|-----|-----|-----------|-----------|-----------|-----|------------------------|
| R/W-0, HS | U-0 | U-0 | R/W-0, HS | R/W-0, HS | R/W-0, HS | U-0 | R/W-0, HS |
| DSFLT | — | — | DSWDT | DSRTCC | DSMCLR | — | DSPOR ^(2,3) |
| bit 7 | | | | | | | bit 0 |

| | | | |
|-------------------|----------------------------|------------------------------------|--------------------|
| Legend: | HS = Hardware Settable bit | | |
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

- bit 15-9 **Unimplemented:** Read as '0'
- bit 8 **DSINT0:** Interrupt-on-Change bit
 1 = Interrupt-on-change was asserted during Deep Sleep
 0 = Interrupt-on-change was not asserted during Deep Sleep
- bit 7 **DSFLT:** Deep Sleep Fault Detected bit
 1 = A Fault occurred during Deep Sleep, and some Deep Sleep configuration settings may have been corrupted
 0 = No Fault was detected during Deep Sleep
- bit 6-5 **Unimplemented:** Read as '0'
- bit 4 **DSWDT:** Deep Sleep Watchdog Timer Time-out bit
 1 = The Deep Sleep Watchdog Timer timed out during Deep Sleep
 0 = The Deep Sleep Watchdog Timer did not time out during Deep Sleep
- bit 3 **DSRTCC:** Real-Time Clock and Calendar Alarm bit
 1 = The Real-Time Clock and Calendar triggered an alarm during Deep Sleep
 0 = The Real-Time Clock and Calendar did not trigger an alarm during Deep Sleep
- bit 2 **DSMCLR:** $\overline{\text{MCLR}}$ Event bit
 1 = The $\overline{\text{MCLR}}$ pin was active and was asserted during Deep Sleep
 0 = The $\overline{\text{MCLR}}$ pin was not active, or was active, but not asserted during Deep Sleep
- bit 1 **Unimplemented:** Read as '0'
- bit 0 **DSPOR:** Power-on Reset Event bit^(2,3)
 1 = The V_{DD} supply POR circuit was active and a POR event was detected
 0 = The V_{DD} supply POR circuit was not active, or was active but did not detect a POR event

- Note 1:** All register bits are cleared when the DSCON<DSEN> bit is set.
- Note 2:** All register bits are reset only in the case of a POR event outside Deep Sleep mode, except bit, DSPOR, which does not reset on a POR event that is caused due to a Deep Sleep exit.
- Note 3:** Unlike the other bits in this register, this bit can be set outside of Deep Sleep.

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REGISTER 10-3: PMD1: PERIPHERAL MODULE DISABLE REGISTER 1

| | | | | | | | |
|--------|-----|-------|-------|-------|-----|-------|-----|
| U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | U-0 | U-0 | U-0 |
| — | — | T3MD | T2MD | T1MD | — | — | — |
| bit 15 | | | | | | bit 8 | |

| | | | | | | | |
|--------|-------|-------|-----|--------|-----|-------|--------|
| R/W-0 | R/W-0 | R/W-0 | U-0 | R/W-0 | U-0 | U-0 | R/W-0 |
| I2C1MD | U2MD | U1MD | — | SPI1MD | — | — | ADC1MD |
| bit 7 | | | | | | bit 0 | |

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

- bit 15-14 **Unimplemented:** Read as '0'
- bit 13 **T3MD:** Timer3 Module Disable bit
 1 = Timer3 module is disabled. All Timer3 registers are held in Reset and are not writable.
 0 = Timer3 module is enabled
- bit 12 **T2MD:** Timer2 Module Disable bit
 1 = Timer2 module is disabled. All Timer2 registers are held in Reset and are not writable.
 0 = Timer2 module is enabled
- bit 11 **T1MD:** Timer1 Module Disable bit
 1 = Timer1 module is disabled. All Timer1 registers are held in Reset and are not writable.
 0 = Timer1 module is enabled
- bit 10-8 **Unimplemented:** Read as '0'
- bit 7 **I2C1MD:** I2C1 Module Disable bit
 1 = I2C1 module is disabled. All I2C1 registers are held in Reset and are not writable.
 0 = I2C1 module is enabled
- bit 6 **U2MD:** UART2 Module Disable bit
 1 = UART2 module is disabled. All UART2 registers are held in Reset and are not writable.
 0 = UART2 module is enabled
- bit 5 **U1MD:** UART1 Module Disable bit
 1 = UART1 module is disabled. All UART1 registers are held in Reset and are not writable.
 0 = UART1 module is enabled
- bit 4 **Unimplemented:** Read as '0'
- bit 3 **SPI1MD:** SPI1 Module Disable bit
 1 = SPI1 module is disabled. All SPI1 registers are held in Reset and are not writable.
 0 = SPI1 module is enabled
- bit 2-1 **Unimplemented:** Read as '0'
- bit 0 **ADC1MD:** A/D Module Disable bit
 1 = A/D module is disabled. All A/D registers are held in Reset and are not writable.
 0 = A/D module is enabled

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REGISTER 10-6: PMD4: PERIPHERAL MODULE DISABLE REGISTER 4

| | | | | | | | |
|--------|-----|-----|-----|-----|-----|-------|-----|
| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
| — | — | — | — | — | — | — | — |
| bit 15 | | | | | | bit 8 | |

| | | | | | | | |
|-------|-----|-----|-------|--------|--------|--------|-----|
| U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | U-0 |
| — | — | — | EEMD | REFOMD | CTMUMD | HLVDMD | — |
| bit 7 | | | | | | bit 0 | |

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-5 **Unimplemented:** Read as '0'

bit 4 **EEMD:** EEPROM Memory Module Disable bit

- 1 = Disable EEPROM memory Flash panel, minimizing current consumption
- 0 = EEPROM memory is disabled

bit 3 **REFOMD:** Reference Oscillator Module Disable bit

- 1 = Reference oscillator module is disabled. All Reference Oscillator registers are held in Reset and are not writable
- 0 = Reference Oscillator module is enabled

bit 2 **CTMUMD:** CTMU Module Disable bit

- 1 = CTMU module is disabled. All CTMU registers are held in Reset and are not writable.
- 0 = CTMU module is enabled

bit 1 **HLVDMD:** HLVD Module Disable bit

- 1 = HLVD module is disabled. All HLVD registers are held in Reset and are not writable.
- 0 = HLVD module is enabled

bit 0 **Unimplemented:** Read as '0'

PIC24F16KA102 FAMILY

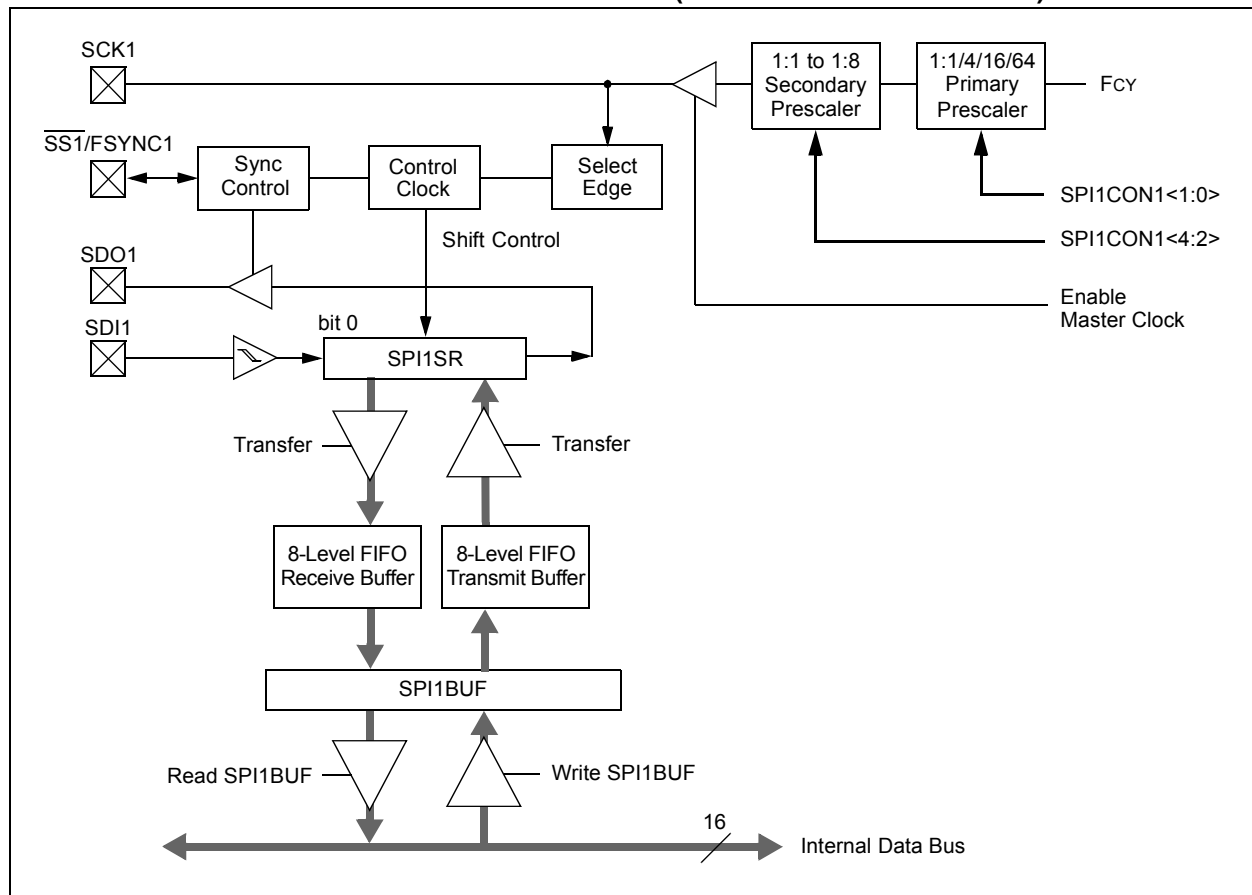
To set up the SPI module for the Enhanced Buffer Master (EBM) mode of operation:

- If using interrupts:
 - Clear the respective SPI1IF bit in the IFS0 register.
 - Set the respective SPI1IE bit in the IEC0 register.
 - Write the respective SPI1IPx bits in the IPC2 register.
- Write the desired settings to the SPI1CON1 and SPI1CON2 registers with the MSTEN bit (SPI1CON1<5>) = 1.
- Clear the SPIROV bit (SPI1STAT<6>).
- Select Enhanced Buffer mode by setting the SPIBEN bit (SPI1CON2<0>).
- Enable SPI operation by setting the SPIEN bit (SPI1STAT<15>).
- Write the data to be transmitted to the SPI1BUF register. Transmission (and reception) will start as soon as data is written to the SPI1BUF register.

To set up the SPI module for the Enhanced Buffer Slave mode of operation:

- Clear the SPI1BUF register.
- If using interrupts:
 - Clear the respective SPI1IF bit in the IFS0 register.
 - Set the respective SPI1IE bit in the IEC0 register.
 - Write the respective SPI1IPx bits in the IPC2 register to set the interrupt priority.
- Write the desired settings to the SPI1CON1 and SPI1CON2 registers with the MSTEN bit (SPI1CON1<5>) = 0.
- Clear the SMP bit.
- If the CKE bit is set, then the SSEN bit must be set, thus enabling the SS1 pin.
- Clear the SPIROV bit (SPI1STAT<6>).
- Select Enhanced Buffer mode by setting the SPIBEN bit (SPI1CON2<0>).
- Enable SPI operation by setting the SPIEN bit (SPI1STAT<15>).

FIGURE 16-2: SPI1 MODULE BLOCK DIAGRAM (ENHANCED BUFFER MODE)



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REGISTER 17-3: I2C1MSK: I2C1 SLAVE MODE ADDRESS MASK REGISTER

| | | | | | | | |
|--------|-----|-----|-----|-----|-----|-------|-------|
| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | R/W-0 | R/W-0 |
| — | — | — | — | — | — | AMSK9 | AMSK8 |
| bit 15 | | | | | | bit 8 | |

| | | | | | | | |
|-------|-------|-------|-------|-------|-------|-------|-------|
| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
| AMSK7 | AMSK6 | AMSK5 | AMSK4 | AMSK3 | AMSK2 | AMSK1 | AMSK0 |
| bit 7 | | | | | | bit 0 | |

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-10 **Unimplemented:** Read as '0'

bit 9-0 **AMSK<9:0>:** Mask for Address Bit x Select bits

1 = Enable masking for bit x of incoming message address; bit match is not required in this position
 0 = Disable masking for bit x; bit match is required in this position

REGISTER 17-4: PADCFG1: PAD CONFIGURATION CONTROL REGISTER

| | | | | | | | |
|--------|-----|-----|-----|-----|-----|-------|-----|
| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
| — | — | — | — | — | — | — | — |
| bit 15 | | | | | | bit 8 | |

| | | | | | | | |
|-------|-----|-----|----------|--------------------------|----------------------------|----------------------------|-----|
| U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | U-0 |
| — | — | — | SMBUSDEL | OC1TRIS ^(2,3) | RTSECSEL1 ^(1,3) | RTSECSEL0 ^(1,3) | — |
| bit 7 | | | | | | bit 0 | |

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-5 **Unimplemented:** Read as '0'

bit 4 **SMBUSDEL:** SMBus SDA Input Delay Select bit

1 = The I²C module is configured for a longer SMBus input delay (nominal 300 ns delay)
 0 = The I²C module is configured for a legacy input delay (nominal 150 ns delay)

bit 0 **Unimplemented:** Read as '0'

Note 1: To enable the actual RTCC output, the RTCOE (RCFGCAL<10>) bit needs to be set.

Note 2: To enable the actual OC1 output, the OCPWM1 module has to be enabled.

Note 3: Bits<3:1> are described in related chapters.

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REGISTER 19-6: WKDYHR: WEEKDAY AND HOURS VALUE REGISTER⁽¹⁾

| | | | | | | | |
|--------|-----|-----|-----|-----|-------|-------|-------|
| U-0 | U-0 | U-0 | U-0 | U-0 | R/W-x | R/W-x | R/W-x |
| — | — | — | — | — | WDAY2 | WDAY1 | WDAY0 |
| bit 15 | | | | | | bit 8 | |

| | | | | | | | |
|-------|-----|--------|--------|--------|--------|--------|--------|
| U-0 | U-0 | R/W-x | R/W-x | R/W-x | R/W-x | R/W-x | R/W-x |
| — | — | HRTEN1 | HRTEN0 | HRONE3 | HRONE2 | HRONE1 | HRONE0 |
| bit 7 | | | | | | bit 0 | |

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

- bit 15-11 **Unimplemented:** Read as '0'
- bit 10-8 **WDAY<2:0>:** Binary Coded Decimal Value of Weekday Digit bits
Contains a value from 0 to 6.
- bit 7-6 **Unimplemented:** Read as '0'
- bit 5-4 **HRTEN<1:0>:** Binary Coded Decimal Value of Hour's Tens Digit bits
Contains a value from 0 to 2.
- bit 3-0 **HRONE<3:0>:** Binary Coded Decimal Value of Hour's Ones Digit bits
Contains a value from 0 to 9.

Note 1: A write to this register is only allowed when RTCWREN = 1.

REGISTER 19-7: MINSEC: MINUTES AND SECONDS VALUE REGISTER

| | | | | | | | |
|--------|---------|---------|---------|---------|---------|---------|---------|
| U-0 | R/W-x | R/W-x | R/W-x | R/W-x | R/W-x | R/W-x | R/W-x |
| — | MINTEN2 | MINTEN1 | MINTEN0 | MINONE3 | MINONE2 | MINONE1 | MINONE0 |
| bit 15 | | | | | | bit 8 | |

| | | | | | | | |
|-------|---------|---------|---------|---------|---------|---------|---------|
| U-0 | R/W-x | R/W-x | R/W-x | R/W-x | R/W-x | R/W-x | R/W-x |
| — | SECTEN2 | SECTEN1 | SECTEN0 | SECONE3 | SECONE2 | SECONE1 | SECONE0 |
| bit 7 | | | | | | bit 0 | |

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

- bit 15 **Unimplemented:** Read as '0'
- bit 14-12 **MINTEN<2:0>:** Binary Coded Decimal Value of Minute's Tens Digit bits
Contains a value from 0 to 5.
- bit 11-8 **MINONE<3:0>:** Binary Coded Decimal Value of Minute's Ones Digit bits
Contains a value from 0 to 9.
- bit 7 **Unimplemented:** Read as '0'
- bit 6-4 **SECTEN<2:0>:** Binary Coded Decimal Value of Second's Tens Digit bits
Contains a value from 0 to 5.
- bit 3-0 **SECONE<3:0>:** Binary Coded Decimal Value of Second's Ones Digit bits
Contains a value from 0 to 9.

22.0 10-BIT HIGH-SPEED A/D CONVERTER

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information on the 10-Bit High-Speed A/D Converter, refer to the “PIC24F Family Reference Manual”, Section 17. “10-Bit A/D Converter” (DS39705).

The 10-bit A/D Converter has the following key features:

- Successive Approximation (SAR) conversion
- Conversion speeds of up to 500 ksp/s
- Nine analog input pins
- External voltage reference input pins
- Internal band gap reference inputs
- Automatic Channel Scan mode
- Selectable conversion trigger source
- 16-word conversion result buffer
- Selectable Buffer Fill modes
- Four result alignment options
- Operation During CPU Sleep and Idle modes

On all PIC24F16KA102 family devices, the 10-bit A/D Converter has nine analog input pins, designated AN0 through AN5 and AN10 through AN12. In addition, there are two analog input pins for external voltage reference connections (VREF+ and VREF-). These voltage reference inputs may be shared with other analog input pins.

A block diagram of the A/D Converter is displayed in Figure 22-1.

To perform an A/D conversion:

1. Configure the A/D module:
 - a) Configure port pins as analog inputs and/or select band gap reference inputs (AD1PCFG<15:13>, AD1PCFG<9:6>).
 - b) Select voltage reference source to match expected range on analog inputs (AD1CON2<15:13>).
 - c) Select the analog conversion clock to match the desired data rate with the processor clock (AD1CON3<7:0>).
 - d) Select the appropriate sample/conversion sequence (AD1CON1<7:5> and AD1CON3<12:8>).
 - e) Select how conversion results are presented in the buffer (AD1CON1<9:8>).
 - f) Select interrupt rate (AD1CON2<5:2>).
 - g) Turn on A/D module (AD1CON1<15>).
2. Configure A/D interrupt (if required):
 - a) Clear the AD1IF bit.
 - b) Select A/D interrupt priority.

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REGISTER 26-4: FOSC: OSCILLATOR CONFIGURATION REGISTER

| R/P-1 | R/P-1 | R/P-1 | R/P-1 | R/P-1 | R/P-1 | R/P-1 | R/P-1 |
|--------|--------|---------|-----------|-----------|----------|---------|---------|
| FCKSM1 | FCKSM0 | SOSCSEL | POSCFREQ1 | POSCFREQ0 | OSCIOFNC | POSCMD1 | POSCMD0 |
| bit 7 | | | | | | | bit 0 |

Legend:

| | | |
|-------------------|----------------------|------------------------------------|
| R = Readable bit | P = Programmable bit | U = Unimplemented bit, read as '0' |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared |
| | | x = Bit is unknown |

- bit 7-6 **FCKSM<1:0>**: Clock Switching and Monitor Selection Configuration bits
 1x = Clock switching is disabled, Fail-Safe Clock Monitor is disabled
 01 = Clock switching is enabled, Fail-Safe Clock Monitor is disabled
 00 = Clock switching is enabled, Fail-Safe Clock Monitor is enabled
- bit 5 **SOSCSEL**: Secondary Oscillator Select bit
 1 = Secondary oscillator is configured for high-power operation
 0 = Secondary oscillator is configured for low-power operation
- bit 4-3 **POSCFREQ<1:0>**: Primary Oscillator Frequency Range Configuration bits
 11 = Primary oscillator/external clock input frequency is greater than 8 MHz
 10 = Primary oscillator/external clock input frequency is between 100 kHz and 8 MHz
 01 = Primary oscillator/external clock input frequency is less than 100 kHz
 00 = Reserved; do not use
- bit 2 **OSCIOFNC**: CLKO Enable Configuration bit
 1 = CLKO output signal active on the OSCO pin; primary oscillator must be disabled or configured for the External Clock mode (EC) for the CLKO to be active (POSCMD<1:0> = 11 or 00)
 0 = CLKO output is disabled
- bit 1-0 **POSCMD<1:0>**: Primary Oscillator Configuration bits
 11 = Primary Oscillator mode is disabled
 10 = HS Oscillator mode is selected
 01 = XT Oscillator mode is selected
 00 = External Clock mode is selected

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27.0 DEVELOPMENT SUPPORT

The PIC[®] microcontrollers and dsPIC[®] digital signal controllers are supported with a full range of software and hardware development tools:

- Integrated Development Environment
 - MPLAB[®] IDE Software
- Compilers/Assemblers/Linkers
 - MPLAB C Compiler for Various Device Families
 - HI-TECH C[®] for Various Device Families
 - MPASM[™] Assembler
 - MPLINK[™] Object Linker/
MPLIB[™] Object Librarian
 - MPLAB Assembler/Linker/Librarian for Various Device Families
- Simulators
 - MPLAB SIM Software Simulator
- Emulators
 - MPLAB REAL ICE[™] In-Circuit Emulator
- In-Circuit Debuggers
 - MPLAB ICD 3
 - PICKit[™] 3 Debug Express
- Device Programmers
 - PICKit[™] 2 Programmer
 - MPLAB PM3 Device Programmer
- Low-Cost Demonstration/Development Boards, Evaluation Kits, and Starter Kits

27.1 MPLAB Integrated Development Environment Software

The MPLAB IDE software brings an ease of software development previously unseen in the 8/16/32-bit microcontroller market. The MPLAB IDE is a Windows[®] operating system-based application that contains:

- A single graphical interface to all debugging tools
 - Simulator
 - Programmer (sold separately)
 - In-Circuit Emulator (sold separately)
 - In-Circuit Debugger (sold separately)
- A full-featured editor with color-coded context
- A multiple project manager
- Customizable data windows with direct edit of contents
- High-level source code debugging
- Mouse over variable inspection
- Drag and drop variables from source to watch windows
- Extensive on-line help
- Integration of select third party tools, such as IAR C Compilers

The MPLAB IDE allows you to:

- Edit your source files (either C or assembly)
- One-touch compile or assemble, and download to emulator and simulator tools (automatically updates all project information)
- Debug using:
 - Source files (C or assembly)
 - Mixed C and assembly
 - Machine code

MPLAB IDE supports multiple debugging tools in a single development paradigm, from the cost-effective simulators, through low-cost in-circuit debuggers, to full-featured emulators. This eliminates the learning curve when upgrading to tools with increased flexibility and power.

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TABLE 29-7: DC CHARACTERISTICS: IDLE CURRENT (IDLE)

| DC CHARACTERISTICS | | | Standard Operating Conditions: 1.8V to 3.6V (unless otherwise stated) | | | |
|---|------------------------|------|---|------------|------|-------------------------------|
| | | | Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended | | | |
| Param No. | Typical ⁽¹⁾ | Max | Units | Conditions | | |
| Idle Current (IDLE): Core Off, Clock on Base Current, PMD Bits are Set⁽²⁾ | | | | | | |
| DC40 | 48 | 100 | μA | -40°C | 1.8V | 0.5 MIPS, Fosc = 1 MHz |
| DC40a | | 100 | | +25°C | | |
| DC40b | | 100 | | +60°C | | |
| DC40c | | 100 | | +85°C | | |
| DC40d | | 100 | | +125°C | | |
| DC40e | 106 | 215 | μA | -40°C | 3.3V | |
| DC40f | | 215 | | +25°C | | |
| DC40g | | 215 | | +60°C | | |
| DC40h | | 215 | | +85°C | | |
| DC40i | | 450 | | +125°C | | |
| DC42 | 94 | 200 | μA | -40°C | 1.8V | 1 MIPS, Fosc = 2 MHz |
| DC42a | | 200 | | +25°C | | |
| DC42b | | 200 | | +60°C | | |
| DC42c | | 200 | | +85°C | | |
| DC42d | | 300 | | +125°C | | |
| DC42e | 160 | 395 | μA | -40°C | 3.3V | |
| DC42f | | 395 | | +25°C | | |
| DC42g | | 395 | | +60°C | | |
| DC42h | | 395 | | +85°C | | |
| DC42i | | 600 | | +125°C | | |
| DC43 | 3.1 | 6.0 | mA | -40°C | 3.3V | 16 MIPS, Fosc = 32 MHz |
| DC43a | | 6.0 | | +25°C | | |
| DC43b | | 6.0 | | +60°C | | |
| DC43c | | 6.0 | | +85°C | | |
| DC43d | | 6.0 | | +125°C | | |
| DC44 | 0.56 | 0.74 | mA | -40°C | 1.8V | FRC (4 MIPS), Fosc = 8 MHz |
| DC44a | | 0.74 | | +25°C | | |
| DC44b | | 0.74 | | +60°C | | |
| DC44c | | 0.74 | | +85°C | | |
| DC44d | | 0.74 | | +125°C | | |
| DC44e | 0.95 | 1.50 | mA | -40°C | 3.3V | |
| DC44f | | 1.50 | | +25°C | | |
| DC44g | | 1.50 | | +60°C | | |
| DC44h | | 1.50 | | +85°C | | |
| DC44i | | 1.50 | | +125°C | | |

Note 1: Data in "Typical" column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

2: Operating Parameters:

- Core is off
- EC mode with the clock input driven with a square wave rail-to-rail
- I/Os are configured as outputs, driven low
- MCLR – VDD
- WDT FSCM are disabled
- SRAM, program and data memory are active
- All PMD bits are set except for the modules being measured

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TABLE 29-26: COMPARATOR TIMINGS

| Param No. | Symbol | Characteristic | Min | Typ | Max | Units | Comments |
|-----------|--------|---|-----|-----|-----|-------|----------|
| 300 | TRESP | Response Time ^{*(1)} | — | 150 | 400 | ns | |
| 301 | TMC2OV | Comparator Mode Change to Output Valid* | — | — | 10 | μs | |

* Parameters are characterized but not tested.

Note 1: Response time is measured with one comparator input at $(V_{DD} - 1.5)/2$, while the other input transitions from V_{SS} to V_{DD} .

TABLE 29-27: COMPARATOR VOLTAGE REFERENCE SETTLING TIME SPECIFICATIONS

| Param No. | Symbol | Characteristic | Min | Typ | Max | Units | Comments |
|-----------|--------|------------------------------|-----|-----|-----|-------|----------|
| VR310 | TSET | Settling Time ⁽¹⁾ | — | — | 10 | μs | |

Note 1: Settling time is measured while $CVRR = 1$ and $CVR<3:0>$ bits transition from '0000' to '1111'.

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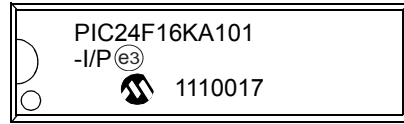
30.0 PACKAGING INFORMATION

30.1 Package Marking Information

20-Lead PDIP



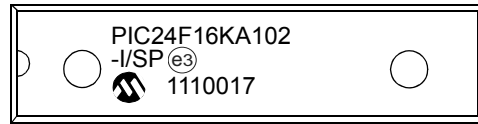
Example



28-Lead SPDIP



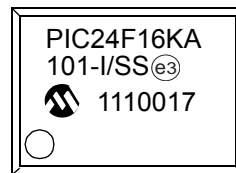
Example



20-Lead SSOP



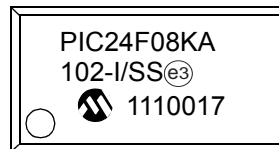
Example



28-Lead SSOP



Example



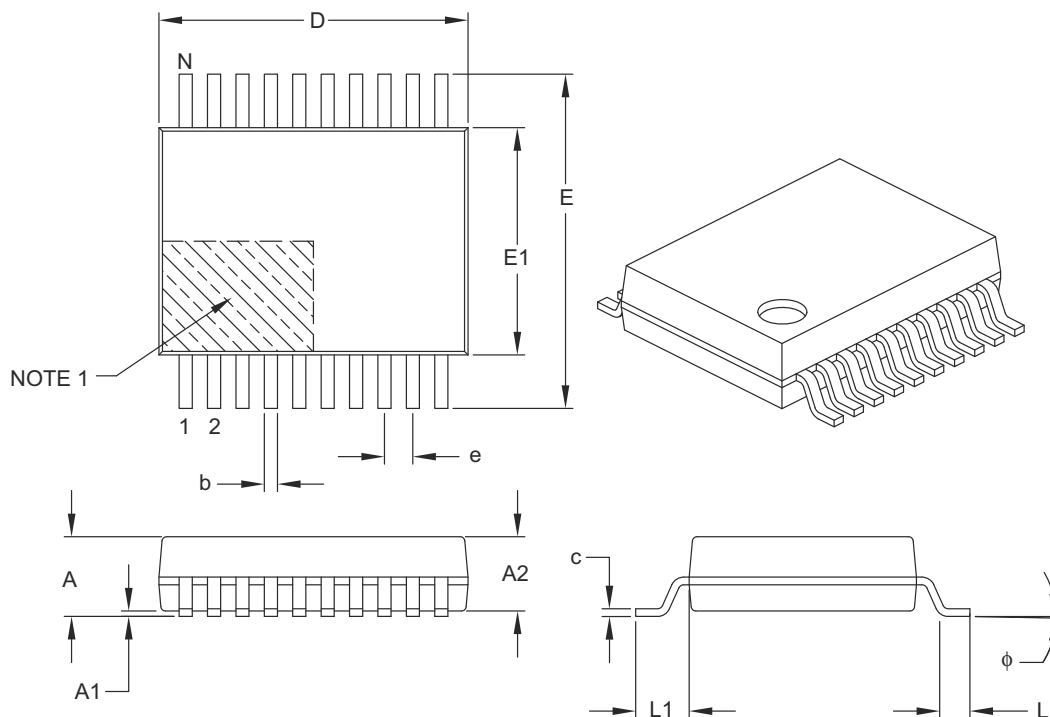
Legend: XX...X Product-specific information
 Y Year code (last digit of calendar year)
 YY Year code (last 2 digits of calendar year)
 WW Week code (week of January 1 is week '01')
 NNN Alphanumeric traceability code
 (e3) Pb-free JEDEC designator for Matte Tin (Sn)
 * This package is Pb-free. The Pb-free JEDEC designator (e3) can be found on the outer packaging for this package.

Note: In the event the full Microchip part number cannot be marked on one line, it will be carried over to the next line, thus limiting the number of available characters for customer-specific information.

PIC24F16KA102 FAMILY

20-Lead Plastic Shrink Small Outline (SS) – 5.30 mm Body [SSOP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



| Dimension Limits | Units | MILLIMETERS | | |
|--------------------------|--------|-------------|------|------|
| | | MIN | NOM | MAX |
| Number of Pins | N | 20 | | |
| Pitch | e | 0.65 BSC | | |
| Overall Height | A | – | – | 2.00 |
| Molded Package Thickness | A2 | 1.65 | 1.75 | 1.85 |
| Standoff | A1 | 0.05 | – | – |
| Overall Width | E | 7.40 | 7.80 | 8.20 |
| Molded Package Width | E1 | 5.00 | 5.30 | 5.60 |
| Overall Length | D | 6.90 | 7.20 | 7.50 |
| Foot Length | L | 0.55 | 0.75 | 0.95 |
| Footprint | L1 | 1.25 REF | | |
| Lead Thickness | c | 0.09 | – | 0.25 |
| Foot Angle | ϕ | 0° | 4° | 8° |
| Lead Width | b | 0.22 | – | 0.38 |

Notes:

- Pin 1 visual index feature may vary, but must be located within the hatched area.
- Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.20 mm per side.
- Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

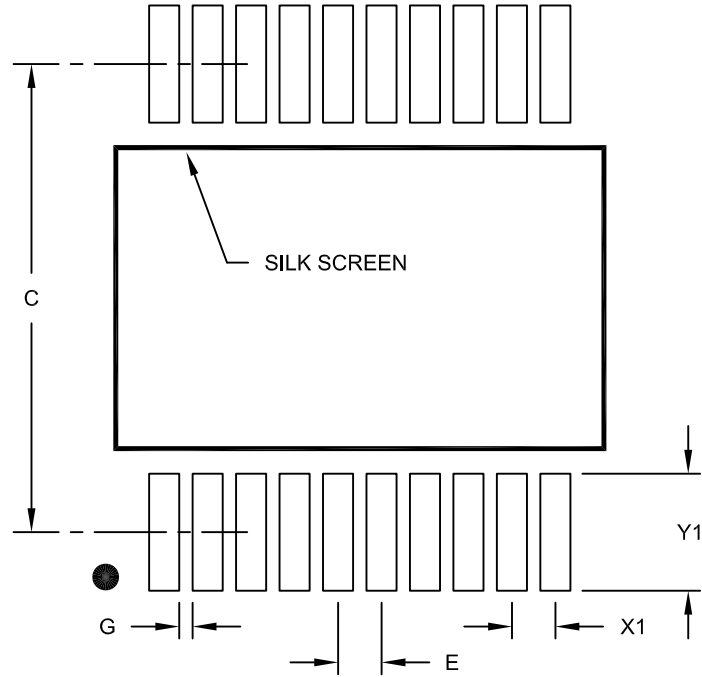
REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-072B

PIC24F16KA102 FAMILY

20-Lead Plastic Shrink Small Outline (SS) - 5.30 mm Body [SSOP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

| Dimension Limits | Units | MILLIMETERS | | |
|--------------------------|-------|-------------|------|------|
| | | MIN | NOM | MAX |
| Contact Pitch | E | 0.65 BSC | | |
| Contact Pad Spacing | C | | 7.20 | |
| Contact Pad Width (X20) | X1 | | | 0.45 |
| Contact Pad Length (X20) | Y1 | | | 1.75 |
| Distance Between Pads | G | 0.20 | | |

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2072A