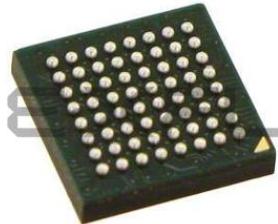


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**What is "Embedded - Microcontrollers"?**



"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

**Applications of "Embedded - Microcontrollers"**

**Details**

Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	50MHz
Connectivity	I²C, IrDA, SPI, UART/USART, USB, USB OTG
Peripherals	DMA, I²S, LVD, POR, PWM, WDT
Number of I/O	40
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	2K x 8
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	1.71V ~ 3.6V
Data Converters	A/D 13x16b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LFBGA
Supplier Device Package	64-MAPBGA (5x5)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/nxp-semiconductors/mk20dx64vmp5">https://www.e-xfl.com/product-detail/nxp-semiconductors/mk20dx64vmp5</a>

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## Terminology and guidelines

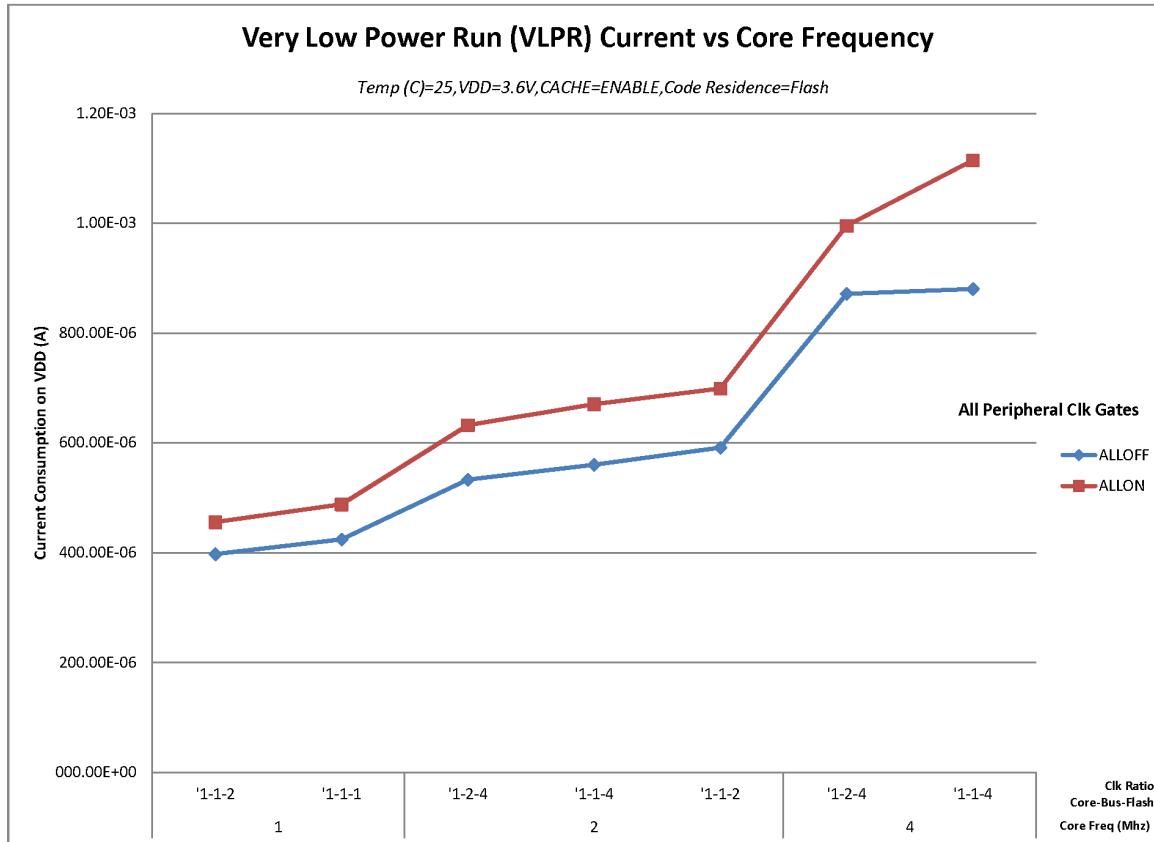
Field	Description	Values
FFF	Program flash memory size	<ul style="list-style-type: none"> <li>• 32 = 32 KB</li> <li>• 64 = 64 KB</li> <li>• 128 = 128 KB</li> <li>• 256 = 256 KB</li> <li>• 512 = 512 KB</li> <li>• 1M0 = 1 MB</li> </ul>
R	Silicon revision	<ul style="list-style-type: none"> <li>• Z = Initial</li> <li>• (Blank) = Main</li> <li>• A = Revision after main</li> </ul>
T	Temperature range (°C)	<ul style="list-style-type: none"> <li>• V = -40 to 105</li> <li>• C = -40 to 85</li> </ul>
PP	Package identifier	<ul style="list-style-type: none"> <li>• FM = 32 QFN (5 mm x 5 mm)</li> <li>• FT = 48 QFN (7 mm x 7 mm)</li> <li>• LF = 48 LQFP (7 mm x 7 mm)</li> <li>• LH = 64 LQFP (10 mm x 10 mm)</li> <li>• MP = 64 MAPBGA (5 mm x 5 mm)</li> <li>• LK = 80 LQFP (12 mm x 12 mm)</li> <li>• MB = 81 MAPBGA (8 mm x 8 mm)</li> <li>• LL = 100 LQFP (14 mm x 14 mm)</li> <li>• ML = 104 MAPBGA (8 mm x 8 mm)</li> <li>• MC = 121 MAPBGA (8 mm x 8 mm)</li> <li>• LQ = 144 LQFP (20 mm x 20 mm)</li> <li>• MD = 144 MAPBGA (13 mm x 13 mm)</li> <li>• MJ = 256 MAPBGA (17 mm x 17 mm)</li> </ul>
CC	Maximum CPU frequency (MHz)	<ul style="list-style-type: none"> <li>• 5 = 50 MHz</li> <li>• 7 = 72 MHz</li> <li>• 10 = 100 MHz</li> <li>• 12 = 120 MHz</li> <li>• 15 = 150 MHz</li> </ul>
N	Packaging type	<ul style="list-style-type: none"> <li>• R = Tape and reel</li> <li>• (Blank) = Trays</li> </ul>

## 2.4 Example

This is an example part number:

MK20DN32VLH5

## 3 Terminology and guidelines



**Figure 3. VLPR mode supply current vs. core frequency**

### 5.2.6 EMC radiated emissions operating behaviors

**Table 7. EMC radiated emissions operating behaviors for 64LQFP**

Symbol	Description	Frequency band (MHz)	Typ.	Unit	Notes
V <sub>RE1</sub>	Radiated emissions voltage, band 1	0.15–50	19	dB $\mu$ V	<a href="#">1</a> , <a href="#">2</a>
V <sub>RE2</sub>	Radiated emissions voltage, band 2	50–150	21	dB $\mu$ V	
V <sub>RE3</sub>	Radiated emissions voltage, band 3	150–500	19	dB $\mu$ V	
V <sub>RE4</sub>	Radiated emissions voltage, band 4	500–1000	11	dB $\mu$ V	
V <sub>RE_IEC</sub>	IEC level	0.15–1000	L	—	<a href="#">2</a> , <a href="#">3</a>

- Determined according to IEC Standard 61967-1, *Integrated Circuits - Measurement of Electromagnetic Emissions, 150 kHz to 1 GHz Part 1: General Conditions and Definitions* and IEC Standard 61967-2, *Integrated Circuits - Measurement of Electromagnetic Emissions, 150 kHz to 1 GHz Part 2: Measurement of Radiated Emissions—TEM Cell and Wideband TEM Cell Method*. Measurements were made while the microcontroller was running basic application code. The reported

## 6.1.1 JTAG electricals

Table 12. JTAG voltage range electricals

Symbol	Description	Min.	Max.	Unit
	Operating voltage	2.7	5.5	V
J1	TCLK frequency of operation	—	10	MHz
	• JTAG	—	5	
J2	TCLK cycle period	1/J1	—	ns
J3	TCLK clock pulse width	100	—	ns
	• JTAG	200	—	ns
	• CJTAG			ns
J4	TCLK rise and fall times	—	1	ns
J5	TMS input data setup time to TCLK rise	53	—	ns
	• JTAG	112	—	
J6	TDI input data setup time to TCLK rise	8	—	ns
J7	TMS input data hold time after TCLK rise	3.4	—	ns
	• JTAG	3.4	—	
J8	TDI input data hold time after TCLK rise	3.4	—	ns
J9	TCLK low to TMS data valid	—	48	ns
	• JTAG	—	85	
J10	TCLK low to TDO data valid	—	48	ns
J11	Output data hold/invalid time after clock edge <sup>1</sup>	—	3	ns

1. They are common for JTAG and CJTAG. Input transition = 1 ns and Output load = 50pf

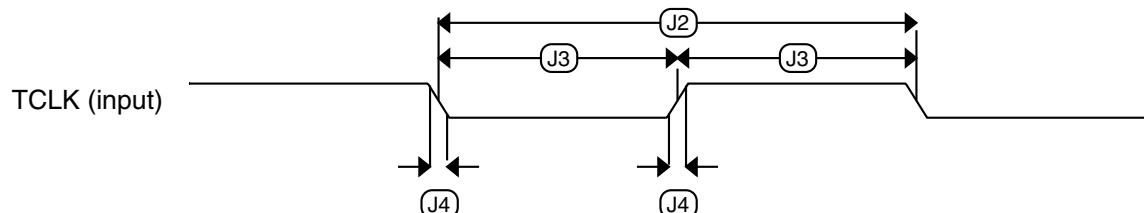
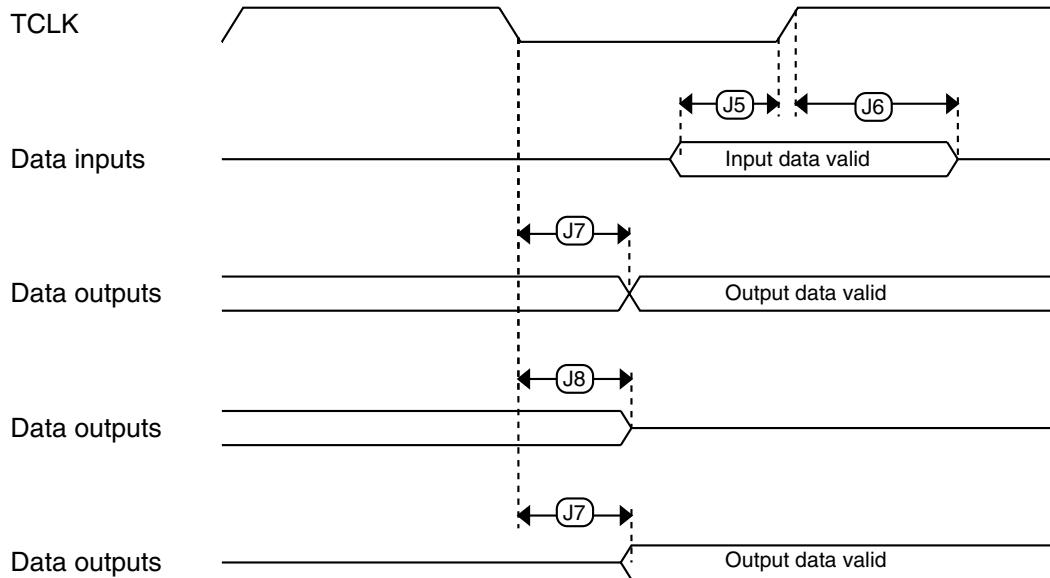
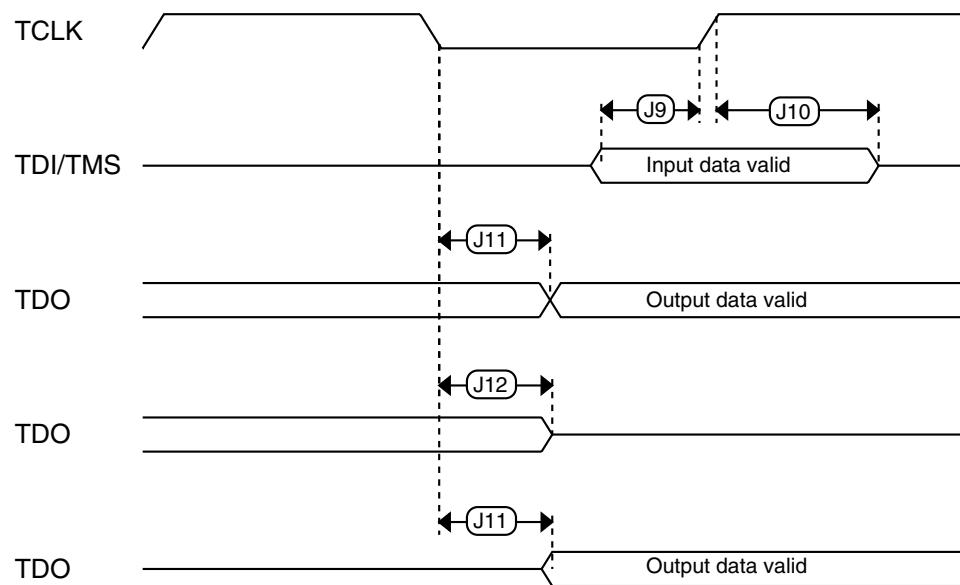


Figure 4. Test clock input timing



**Figure 5. Boundary scan (JTAG) timing**



**Figure 6. Test Access Port timing**

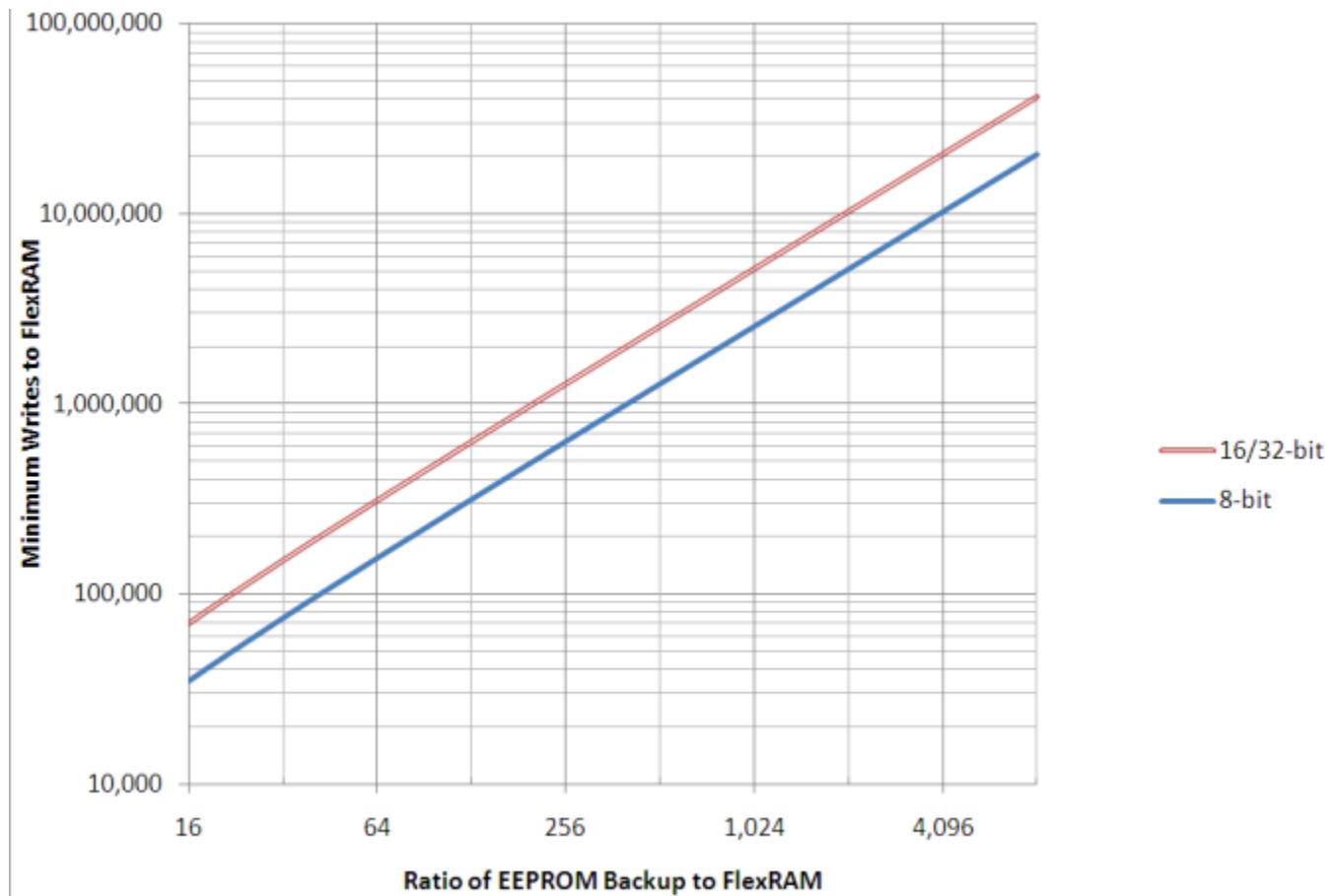
**Table 13. MCG specifications (continued)**

Symbol	Description		Min.	Typ.	Max.	Unit	Notes
$f_{\text{fll\_ref}}$	FLL reference frequency range		31.25	—	39.0625	kHz	
$f_{\text{dco}}$	DCO output frequency range	Low range (DRS=00) $640 \times f_{\text{fll\_ref}}$	20	20.97	25	MHz	2, 3
		Mid range (DRS=01) $1280 \times f_{\text{fll\_ref}}$	40	41.94	50	MHz	
		Mid-high range (DRS=10) $1920 \times f_{\text{fll\_ref}}$	60	62.91	75	MHz	
		High range (DRS=11) $2560 \times f_{\text{fll\_ref}}$	80	83.89	100	MHz	
$f_{\text{dco\_t\_DMX3}_2}$	DCO output frequency	Low range (DRS=00) $732 \times f_{\text{fll\_ref}}$	—	23.99	—	MHz	4, 5
		Mid range (DRS=01) $1464 \times f_{\text{fll\_ref}}$	—	47.97	—	MHz	
		Mid-high range (DRS=10) $2197 \times f_{\text{fll\_ref}}$	—	71.99	—	MHz	
		High range (DRS=11) $2929 \times f_{\text{fll\_ref}}$	—	95.98	—	MHz	
$J_{\text{cyc\_fll}}$	FLL period jitter		—	180	—	ps	
	• $f_{\text{VCO}} = 48 \text{ MHz}$		—	150	—	ps	
$t_{\text{fll\_acquire}}$	FLL target frequency acquisition time		—	—	1	ms	6
PLL							
$f_{\text{vco}}$	VCO operating frequency		48.0	—	100	MHz	
$I_{\text{pll}}$	PLL operating current • PLL @ 96 MHz ( $f_{\text{osc\_hi\_1}} = 8 \text{ MHz}$ , $f_{\text{pll\_ref}} = 2 \text{ MHz}$ , VDIV multiplier = 48)		—	1060	—	$\mu\text{A}$	7
$I_{\text{pll}}$	PLL operating current • PLL @ 48 MHz ( $f_{\text{osc\_hi\_1}} = 8 \text{ MHz}$ , $f_{\text{pll\_ref}} = 2 \text{ MHz}$ , VDIV multiplier = 24)		—	600	—	$\mu\text{A}$	7
$f_{\text{pll\_ref}}$	PLL reference frequency range		2.0	—	4.0	MHz	
$J_{\text{cyc\_pll}}$	PLL period jitter (RMS)		—	120	—	ps	8
	• $f_{\text{vco}} = 48 \text{ MHz}$		—	50	—	ps	

Table continues on the next page...

## Peripheral operating requirements and behaviors

- EEPROM — allocated FlexNVM based on DEPART; entered with the Program Partition command
- EESIZE — allocated FlexRAM based on DEPART; entered with the Program Partition command
- Write\_efficiency —
  - 0.25 for 8-bit writes to FlexRAM
  - 0.50 for 16-bit or 32-bit writes to FlexRAM
- $n_{nvmcycd}$  — data flash cycling endurance (the following graph assumes 10,000 cycles)



**Figure 8. EEPROM backup writes to FlexRAM**

## 6.4.2 EzPort Switching Specifications

**Table 22. EzPort switching specifications**

Num	Description	Min.	Max.	Unit
	Operating voltage	1.71	3.6	V

*Table continues on the next page...*

**Table 24. 16-bit ADC characteristics ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SSA}$ ) (continued)**

Symbol	Description	Conditions <sup>1</sup>	Min.	Typ. <sup>2</sup>	Max.	Unit	Notes
$f_{ADACK}$	ADC asynchronous clock source	<ul style="list-style-type: none"> <li>• ADLPC=1, ADHSC=0</li> <li>• ADLPC=1, ADHSC=1</li> <li>• ADLPC=0, ADHSC=0</li> <li>• ADLPC=0, ADHSC=1</li> </ul>	1.2 3.0 2.4 4.4	2.4 4.0 5.2 6.2	3.9 7.3 6.1 9.5	MHz MHz MHz MHz	$t_{ADACK} = 1/f_{ADACK}$
	Sample Time	See Reference Manual chapter for sample times					
TUE	Total unadjusted error	<ul style="list-style-type: none"> <li>• 12 bit modes</li> <li>• &lt;12 bit modes</li> </ul>	— —	$\pm 4$ $\pm 1.4$	$\pm 6.8$ $\pm 2.1$	LSB <sup>4</sup>	<sup>5</sup>
DNL	Differential non-linearity	<ul style="list-style-type: none"> <li>• 12 bit modes</li> <li>• &lt;12 bit modes</li> </ul>	— —	$\pm 0.7$ $\pm 0.2$	-1.1 to +1.9 -0.3 to 0.5	LSB <sup>4</sup>	<sup>5</sup>
INL	Integral non-linearity	<ul style="list-style-type: none"> <li>• 12 bit modes</li> <li>• &lt;12 bit modes</li> </ul>	— —	$\pm 1.0$ $\pm 0.5$	-2.7 to +1.9 -0.7 to +0.5	LSB <sup>4</sup>	<sup>5</sup>
$E_{FS}$	Full-scale error	<ul style="list-style-type: none"> <li>• 12 bit modes</li> <li>• &lt;12 bit modes</li> </ul>	— —	-4 -1.4	-5.4 -1.8	LSB <sup>4</sup>	$V_{ADIN} = V_{DDA}$ <sup>5</sup>
$E_Q$	Quantization error	<ul style="list-style-type: none"> <li>• 16 bit modes</li> <li>• ≤13 bit modes</li> </ul>	— —	-1 to 0 —	— $\pm 0.5$	LSB <sup>4</sup>	
ENOB	Effective number of bits	16 bit differential mode <ul style="list-style-type: none"> <li>• Avg=32</li> <li>• Avg=4</li> </ul> 16 bit single-ended mode <ul style="list-style-type: none"> <li>• Avg=32</li> <li>• Avg=4</li> </ul>	12.8 11.9 12.2 11.4	14.5 13.8 13.9 13.1	— — — —	bits bits bits bits	<sup>6</sup>
SINAD	Signal-to-noise plus distortion	See ENOB	$6.02 \times ENOB + 1.76$			dB	
THD	Total harmonic distortion	16 bit differential mode <ul style="list-style-type: none"> <li>• Avg=32</li> </ul> 16 bit single-ended mode <ul style="list-style-type: none"> <li>• Avg=32</li> </ul>	— —	-94 -85	— —	dB dB	<sup>7</sup>

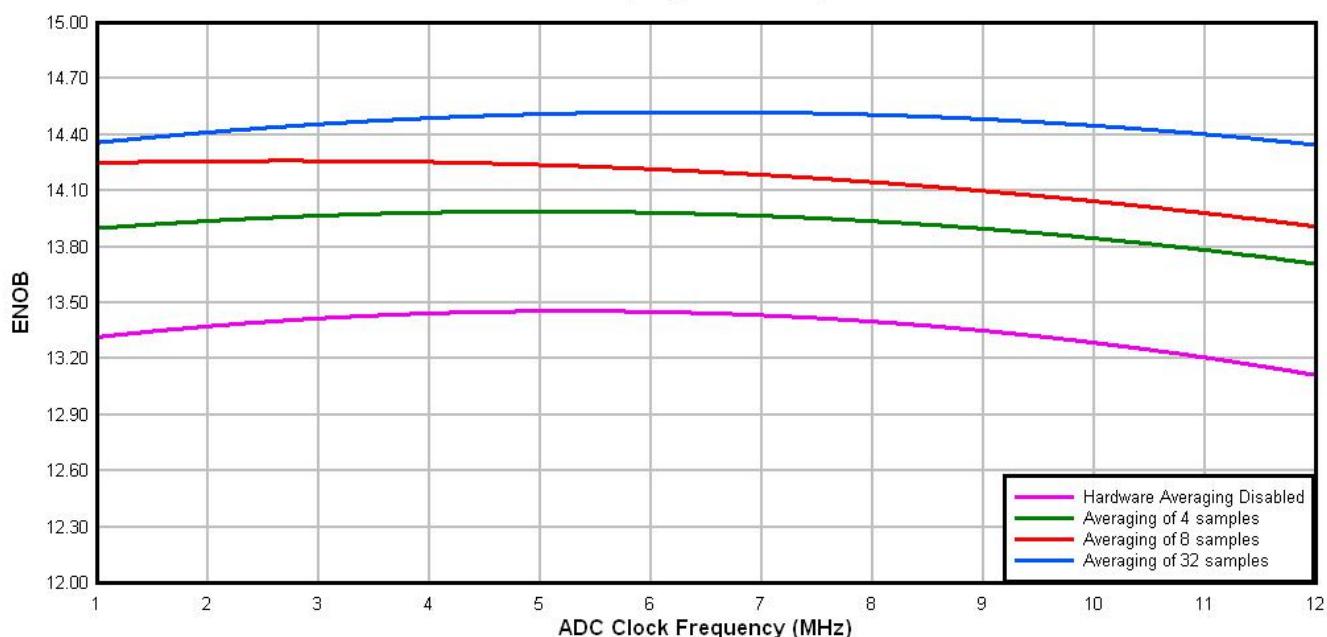
Table continues on the next page...

**Table 24. 16-bit ADC characteristics ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SSA}$ ) (continued)**

Symbol	Description	Conditions <sup>1</sup>	Min.	Typ. <sup>2</sup>	Max.	Unit	Notes
SFDR	Spurious free dynamic range	16 bit differential mode • Avg=32  16 bit single-ended mode • Avg=32	82	95	—	dB	<sup>7</sup>
$E_{IL}$	Input leakage error			$I_{in} \times R_{AS}$		mV	$I_{in}$ = leakage current (refer to the MCU's voltage and current operating ratings)
	Temp sensor slope	-40°C to 105°C	—	1.715	—	mV/°C	
$V_{TEMP25}$	Temp sensor voltage	25°C	—	719	—	mV	

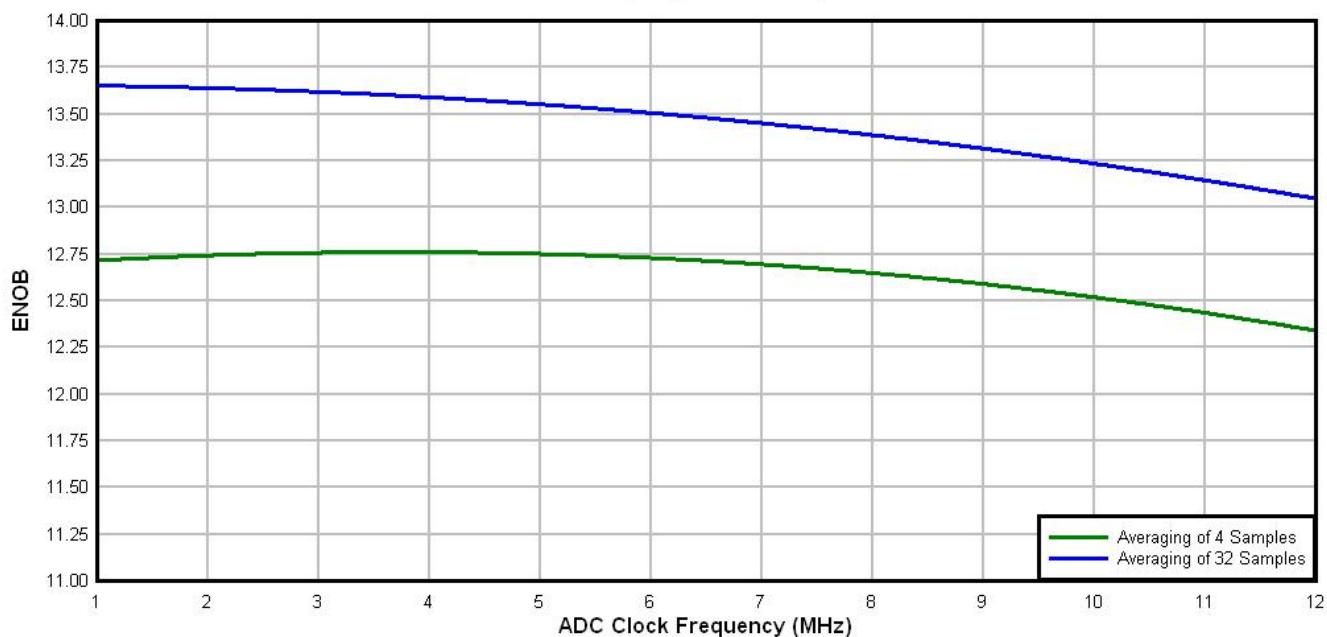
1. All accuracy numbers assume the ADC is calibrated with  $V_{REFH} = V_{DDA}$
2. Typical values assume  $V_{DDA} = 3.0$  V, Temp = 25°C,  $f_{ADCK} = 2.0$  MHz unless otherwise stated. Typical values are for reference only and are not tested in production.
3. The ADC supply current depends on the ADC conversion clock speed, conversion rate and the ADLPC bit (low power). For lowest power operation the ADLPC bit should be set, the HSC bit should be clear with 1MHz ADC conversion clock speed.
4.  $1 \text{ LSB} = (V_{REFH} - V_{REFL})/2^N$
5. ADC conversion clock <16MHz, Max hardware averaging (AVGE = %1, AVGS = %11)
6. Input data is 100 Hz sine wave. ADC conversion clock <12MHz.
7. Input data is 1 kHz sine wave. ADC conversion clock <12MHz.

**Typical ADC 16-bit Differential ENOB vs ADC Clock  
100Hz, 90% FS Sine Input**



**Figure 11. Typical ENOB vs. ADC\_CLK for 16-bit differential mode**

**Typical ADC 16-bit Single-Ended ENOB vs ADC Clock  
100Hz, 90% FS Sine Input**



**Figure 12. Typical ENOB vs. ADC\_CLK for 16-bit single-ended mode**

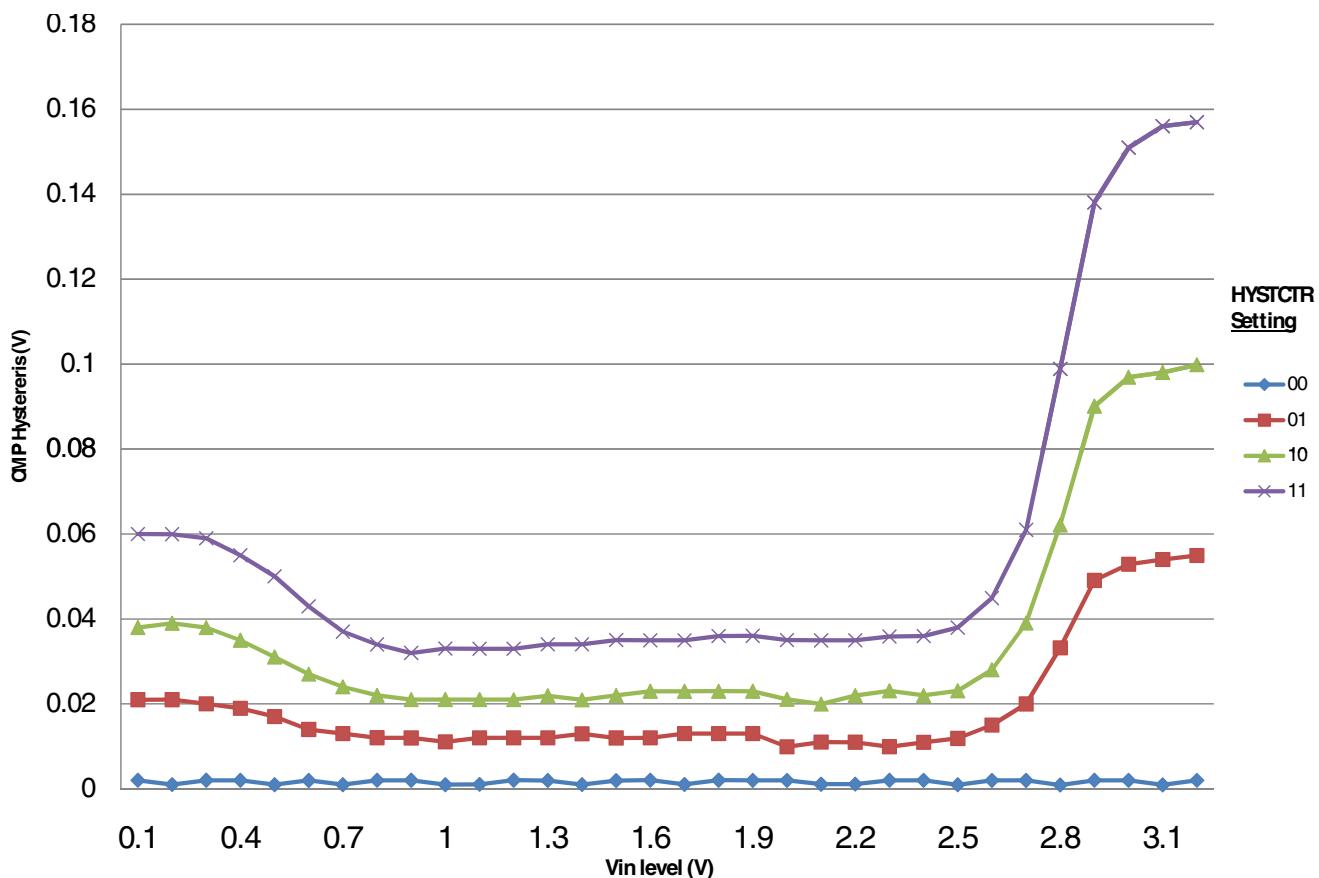


Figure 14. Typical hysteresis vs. Vin level (VDD=3.3V, PMODE=1)

### 6.6.3 Voltage reference electrical specifications

Table 26. VREF full-range operating requirements

Symbol	Description	Min.	Max.	Unit	Notes
V <sub>DDA</sub>	Supply voltage	1.71	3.6	V	
T <sub>A</sub>	Temperature	-40	105	°C	
C <sub>L</sub>	Output load capacitance	100		nF	1, 2

1. C<sub>L</sub> must be connected to VREF\_OUT if the VREF\_OUT functionality is being used for either an internal or external reference.
2. The load capacitance should not exceed +/-25% of the nominal specified C<sub>L</sub> value over the operating temperature range of the device.

Table 27. VREF full-range operating behaviors

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
V <sub>out</sub>	Voltage reference output with factory trim at nominal V <sub>DDA</sub> and temperature=25C	1.1915	1.195	1.1977	V	

Table continues on the next page...

**Table 31. USB VREG electrical specifications  
(continued)**

Symbol	Description	Min.	Typ. <sup>1</sup>	Max.	Unit	Notes
C <sub>OUT</sub>	External output capacitor	1.76	2.2	8.16	μF	
ESR	External output capacitor equivalent series resistance	1	—	100	mΩ	
I <sub>LIM</sub>	Short circuit current	—	290	—	mA	

1. Typical values assume VREGIN = 5.0 V, Temp = 25 °C unless otherwise stated.  
 2. Operating in pass-through mode: regulator output voltage equal to the input voltage minus a drop proportional to I<sub>Load</sub>.

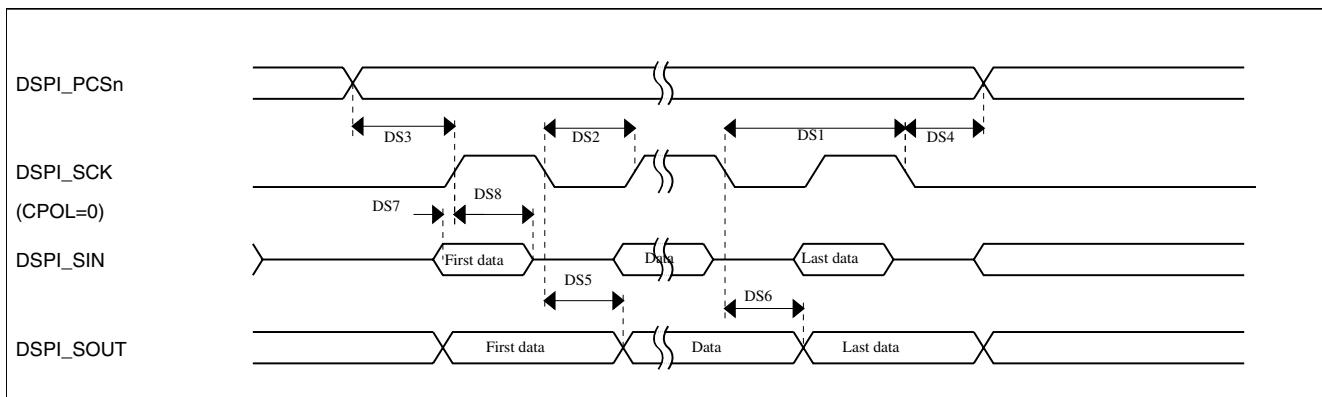
## 6.8.4 DSPI switching specifications (limited voltage range)

The DMA Serial Peripheral Interface (DSPI) provides a synchronous serial bus with master and slave operations. Many of the transfer attributes are programmable. The tables below provide DSPI timing characteristics for classic SPI timing modes. Refer to the DSPI chapter of the Reference Manual for information on the modified transfer formats used for communicating with slower peripheral devices.

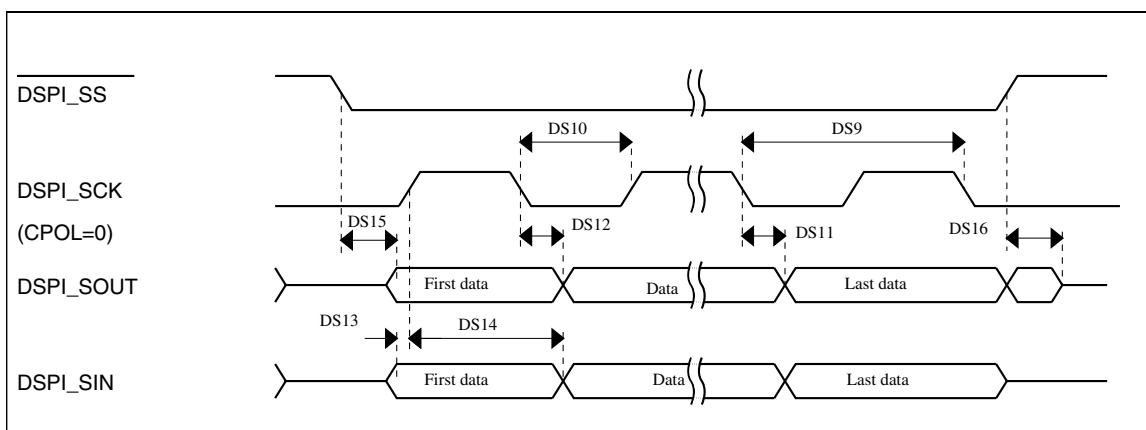
**Table 32. Master mode DSPI timing (limited voltage range)**

Num	Description	Min.	Max.	Unit	Notes
	Operating voltage	2.7	3.6	V	
	Frequency of operation	—	25	MHz	
DS1	DSPI_SCK output cycle time	2 x t <sub>BUS</sub>	—	ns	
DS2	DSPI_SCK output high/low time	(t <sub>SCK</sub> /2) – 2	(t <sub>SCK</sub> /2) + 2	ns	
DS3	DSPI_PCS <sub>n</sub> valid to DSPI_SCK delay	(t <sub>BUS</sub> x 2) – 2	—	ns	<sup>1</sup>
DS4	DSPI_SCK to DSPI_PCS <sub>n</sub> invalid delay	(t <sub>BUS</sub> x 2) – 2	—	ns	<sup>2</sup>
DS5	DSPI_SCK to DSPI_SOUT valid	—	8	ns	
DS6	DSPI_SCK to DSPI_SOUT invalid	0	—	ns	
DS7	DSPI_SIN to DSPI_SCK input setup	14	—	ns	
DS8	DSPI_SCK to DSPI_SIN input hold	0	—	ns	

1. The delay is programmable in SPIx\_CTARn[PSSCK] and SPIx\_CTARn[CSSCK].  
 2. The delay is programmable in SPIx\_CTARn[PASC] and SPIx\_CTARn[ASC].

**Figure 15. DSPI classic SPI timing — master mode****Table 33. Slave mode DSPI timing (limited voltage range)**

Num	Description	Min.	Max.	Unit
	Operating voltage	2.7	3.6	V
	Frequency of operation		12.5	MHz
DS9	DSPI_SCK input cycle time	$4 \times t_{BUS}$	—	ns
DS10	DSPI_SCK input high/low time	$(t_{SCK}/2) - 2$	$(t_{SCK}/2) + 2$	ns
DS11	DSPI_SCK to DSPI_SOUT valid	—	20	ns
DS12	DSPI_SCK to DSPI_SOUT invalid	0	—	ns
DS13	DSPI_SIN to DSPI_SCK input setup	2	—	ns
DS14	DSPI_SCK to DSPI_SIN input hold	7	—	ns
DS15	DSPI_SS active to DSPI_SOUT driven	—	14	ns
DS16	DSPI_SS inactive to DSPI_SOUT not driven	—	14	ns

**Figure 16. DSPI classic SPI timing — slave mode**

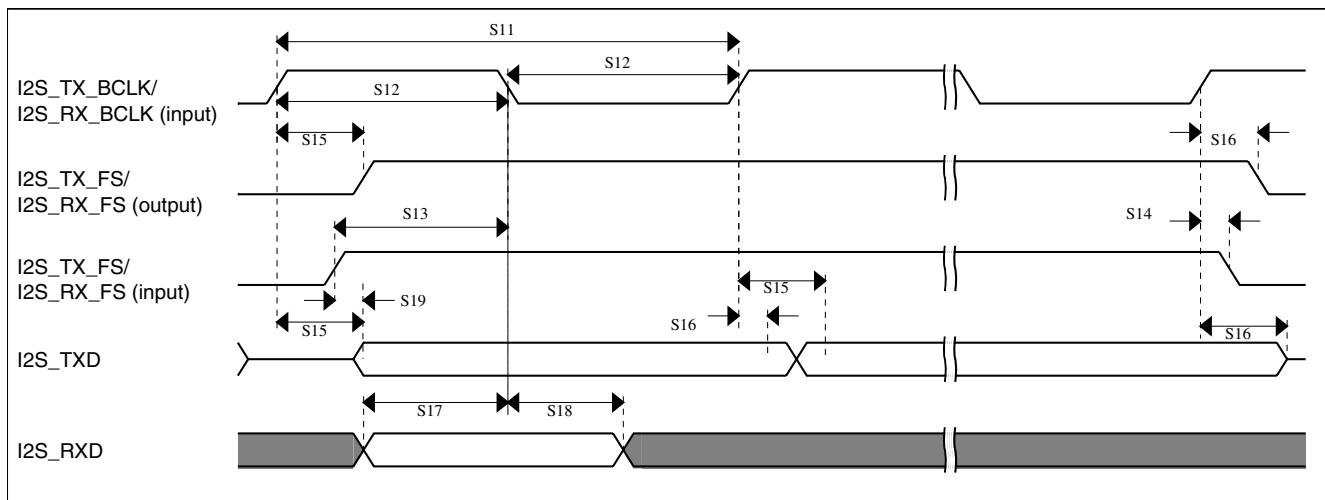


Figure 22. I2S/SAI timing — slave modes

## 6.9 Human-machine interfaces (HMI)

### 6.9.1 TSI electrical specifications

Table 40. TSI electrical specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$V_{DDTSI}$	Operating voltage	1.71	—	3.6	V	
$C_{ELE}$	Target electrode capacitance range	1	20	500	pF	1
$f_{REFmax}$	Reference oscillator frequency	—	8	15	MHz	2, 3
$f_{ELEmax}$	Electrode oscillator frequency	—	1	1.8	MHz	2, 4
$C_{REF}$	Internal reference capacitor	—	1	—	pF	
$V_{\Delta}$	Oscillator delta voltage	—	500	—	mV	2, 5
$I_{REF}$	Reference oscillator current source base current • 2 $\mu$ A setting (REFCHRG = 0) • 32 $\mu$ A setting (REFCHRG = 15)	—	2	3	$\mu$ A	2, 6
$I_{ELE}$	Electrode oscillator current source base current • 2 $\mu$ A setting (EXTCHRG = 0) • 32 $\mu$ A setting (EXTCHRG = 15)	—	36	50	$\mu$ A	2, 7
Pres5	Electrode capacitance measurement precision	—	8.3333	38400	fF/count	8
Pres20	Electrode capacitance measurement precision	—	8.3333	38400	fF/count	9
Pres100	Electrode capacitance measurement precision	—	8.3333	38400	fF/count	10
MaxSens	Maximum sensitivity	0.008	1.46	—	fF/count	11
Res	Resolution	—	—	16	bits	

Table continues on the next page...

**Table 40. TSI electrical specifications (continued)**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
T <sub>Con20</sub>	Response time @ 20 pF	8	15	25	μs	12
I <sub>TSI_RUN</sub>	Current added in run mode	—	55	—	μA	
I <sub>TSI_LP</sub>	Low power mode current adder	—	1.3	2.5	μA	13

1. The TSI module is functional with capacitance values outside this range. However, optimal performance is not guaranteed.
2. Fixed external capacitance of 20 pF.
3. REFCHRG = 2, EXTCHRG=0.
4. REFCHRG = 0, EXTCHRG = 10.
5. V<sub>DD</sub> = 3.0 V.
6. The programmable current source value is generated by multiplying the SCANC[REFCHRG] value and the base current.
7. The programmable current source value is generated by multiplying the SCANC[EXTCHRG] value and the base current.
8. Measured with a 5 pF electrode, reference oscillator frequency of 10 MHz, PS = 128, NSCN = 8; Iext = 16.
9. Measured with a 20 pF electrode, reference oscillator frequency of 10 MHz, PS = 128, NSCN = 2; Iext = 16.
10. Measured with a 20 pF electrode, reference oscillator frequency of 10 MHz, PS = 16, NSCN = 3; Iext = 16.
11. Sensitivity defines the minimum capacitance change when a single count from the TSI module changes. Sensitivity depends on the configuration used. The documented values are provided as examples calculated for a specific configuration of operating conditions using the following equation: (C<sub>ref</sub> \* I<sub>ext</sub>)/(I<sub>ref</sub> \* PS \* NSCN)

The typical value is calculated with the following configuration:

I<sub>ext</sub> = 6 μA (EXTCHRG = 2), PS = 128, NSCN = 2, I<sub>ref</sub> = 16 μA (REFCHRG = 7), C<sub>ref</sub> = 1.0 pF

The minimum value is calculated with the following configuration:

I<sub>ext</sub> = 2 μA (EXTCHRG = 0), PS = 128, NSCN = 32, I<sub>ref</sub> = 32 μA (REFCHRG = 15), C<sub>ref</sub> = 0.5 pF

The highest possible sensitivity is the minimum value because it represents the smallest possible capacitance that can be measured by a single count.

12. Time to do one complete measurement of the electrode. Sensitivity resolution of 0.0133 pF, PS = 0, NSCN = 0, 1 electrode, EXTCHRG = 7.
13. REFCHRG=0, EXTCHRG=4, PS=7, NSCN=0F, LPSCNITV=F, LPO is selected (1 kHz), and fixed external capacitance of 20 pF. Data is captured with an average of 7 periods window.

## 7 Dimensions

### 7.1 Obtaining package dimensions

Package dimensions are provided in package drawings.

To find a package drawing, go to <http://www.freescale.com> and perform a keyword search for the drawing's document number:

If you want the drawing for this package	Then use this document number
64-pin LQFP	98ASS23234W
64-pin MAPBGA	98ASA00420D

## 8 Pinout

### 8.1 K20 Signal Multiplexing and Pin Assignments

The following table shows the signals available on each pin and the locations of these pins on the devices supported by this document. The Port Control Module is responsible for selecting which ALT functionality is available on each pin.

64 MAP BGA	64 LQFP	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7	EzPort
A1	1	PTE0	DISABLED		PTE0		UART1_TX				RTC_CLKOUT	
B1	2	PTE1/ LLWU_P0	DISABLED		PTE1/ LLWU_P0		UART1_RX					
C5	3	VDD	VDD	VDD								
C4	4	VSS	VSS	VSS								
E1	5	USB0_DP	USB0_DP	USB0_DP								
D1	6	USB0_DM	USB0_DM	USB0_DM								
E2	7	VOUT33	VOUT33	VOUT33								
D2	8	VREGIN	VREGIN	VREGIN								
G1	9	ADC0_DPO	ADC0_DPO	ADC0_DPO								
F1	10	ADC0_DM0	ADC0_DM0	ADC0_DM0								
G2	11	ADC0_DP3	ADC0_DP3	ADC0_DP3								
F2	12	ADC0_DM3	ADC0_DM3	ADC0_DM3								
F4	13	VDDA	VDDA	VDDA								
G4	14	VREFH	VREFH	VREFH								
G3	15	VREFL	VREFL	VREFL								
F3	16	VSSA	VSSA	VSSA								
H1	17	VREF_OUT/ CMP1_IN5/ CMP0_IN5	VREF_OUT/ CMP1_IN5/ CMP0_IN5	VREF_OUT/ CMP1_IN5/ CMP0_IN5								
H2	18	CMP1_IN3/ ADC0_SE23	CMP1_IN3/ ADC0_SE23	CMP1_IN3/ ADC0_SE23								
H3	19	XTAL32	XTAL32	XTAL32								
H4	20	EXTAL32	EXTAL32	EXTAL32								
H5	21	VBAT	VBAT	VBAT								
D3	22	PTA0	JTAG_TCLK/ SWD_CLK/ EZP_CLK	TSI0_CH1	PTA0	UART0_CTS_b/ UART0_COL_b	FTM0_CH5			JTAG_TCLK/ SWD_CLK	EZP_CLK	
D4	23	PTA1	JTAG_TDI/ EZP_DI	TSI0_CH2	PTA1	UART0_RX	FTM0_CH6			JTAG_TDI	EZP_DI	

64 MAP BGA	64 LQFP	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7	EzPort
E5	24	PTA2	JTAG_TDO/ TRACE_SWO/ EZP_DO	TSI0_CH3	PTA2	UART0_TX	FTM0_CH7				JTAG_TDO/ TRACE_SWO	EZP_DO
D5	25	PTA3	JTAG_TMS/ SWD_DIO	TSI0_CH4	PTA3	UART0_RTS_b	FTM0_CH0				JTAG_TMS/ SWD_DIO	
G5	26	PTA4/ LLWU_P3	NMI_b/ EZP_CS_b	TSI0_CH5	PTA4/ LLWU_P3		FTM0_CH1				NMI_b	EZP_CS_b
F5	27	PTA5	DISABLED		PTA5	USB_CLKIN	FTM0_CH2			I2S0_TX_BCLK	JTAG_TRST_b	
H6	28	PTA12	DISABLED		PTA12		FTM1_CH0			I2S0_TXD0	FTM1_QD_PHA	
G6	29	PTA13/ LLWU_P4	DISABLED		PTA13/ LLWU_P4		FTM1_CH1			I2S0_TX_FS	FTM1_QD_PHB	
G7	30	VDD	VDD	VDD								
H7	31	VSS	VSS	VSS								
H8	32	PTA18	EXTAL0	EXTAL0	PTA18		FTM0_FLT2	FTM_CLKIN0				
G8	33	PTA19	XTAL0	XTAL0	PTA19		FTM1_FLT0	FTM_CLKIN1		LPTMR0_ALT1		
F8	34	RESET_b	RESET_b	RESET_b								
F7	35	PTB0/ LLWU_P5	ADC0_SE8/ TSI0_CH0	ADC0_SE8/ TSI0_CH0	PTB0/ LLWU_P5	I2C0_SCL	FTM1_CH0			FTM1_QD_PHA		
F6	36	PTB1	ADC0_SE9/ TSI0_CH6	ADC0_SE9/ TSI0_CH6	PTB1	I2C0_SDA	FTM1_CH1			FTM1_QD_PHB		
E7	37	PTB2	ADC0_SE12/ TSI0_CH7	ADC0_SE12/ TSI0_CH7	PTB2	I2C0_SCL	UART0_RTS_b			FTM0_FLT3		
E8	38	PTB3	ADC0_SE13/ TSI0_CH8	ADC0_SE13/ TSI0_CH8	PTB3	I2C0_SDA	UART0_CTS_b/ UART0_COL_b			FTM0_FLT0		
E6	39	PTB16	TSI0_CH9	TSI0_CH9	PTB16		UART0_RX			EWM_IN		
D7	40	PTB17	TSI0_CH10	TSI0_CH10	PTB17		UART0_TX			EWM_OUT_b		
D6	41	PTB18	TSI0_CH11	TSI0_CH11	PTB18			I2S0_TX_BCLK				
C7	42	PTB19	TSI0_CH12	TSI0_CH12	PTB19			I2S0_TX_FS				
D8	43	PTC0	ADC0_SE14/ TSI0_CH13	ADC0_SE14/ TSI0_CH13	PTC0	SPI0_PCS4	PDB0_EXTRG					
C6	44	PTC1/ LLWU_P6	ADC0_SE15/ TSI0_CH14	ADC0_SE15/ TSI0_CH14	PTC1/ LLWU_P6	SPI0_PCS3	UART1_RTS_b	FTM0_CH0		I2S0_TXD0		
B7	45	PTC2	ADC0_SE4b/ CMP1_IN0/ TSI0_CH15	ADC0_SE4b/ CMP1_IN0/ TSI0_CH15	PTC2	SPI0_PCS2	UART1_CTS_b	FTM0_CH1		I2S0_TX_FS		
C8	46	PTC3/ LLWU_P7	CMP1_IN1	CMP1_IN1	PTC3/ LLWU_P7	SPI0_PCS1	UART1_RX	FTM0_CH2		I2S0_TX_BCLK		
E3	47	VSS	VSS	VSS								
E4	48	VDD	VDD	VDD								

## Pinout

64 MAP BGA	64 LQFP	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7	EzPort
B8	49	PTC4/ LLWU_P8	DISABLED		PTC4/ LLWU_P8	SPI0_PCS0	UART1_TX	FTM0_CH3		CMP1_OUT		
A8	50	PTC5/ LLWU_P9	DISABLED		PTC5/ LLWU_P9	SPI0_SCK	LPTMR0_ ALT2	I2S0_RXD0		CMP0_OUT		
A7	51	PTC6/ LLWU_P10	CMP0_IN0	CMP0_IN0	PTC6/ LLWU_P10	SPI0_SOUT	PDB0_EXTRG	I2S0_RX_ BCLK		I2S0_MCLK		
B6	52	PTC7	CMP0_IN1	CMP0_IN1	PTC7	SPI0_SIN	USB_SOF_ OUT	I2S0_RX_FS				
A6	53	PTC8	CMP0_IN2	CMP0_IN2	PTC8			I2S0_MCLK				
B5	54	PTC9	CMP0_IN3	CMP0_IN3	PTC9			I2S0_RX_ BCLK				
B4	55	PTC10	DISABLED		PTC10			I2S0_RX_FS				
A5	56	PTC11/ LLWU_P11	DISABLED		PTC11/ LLWU_P11							
C3	57	PTD0/ LLWU_P12	DISABLED		PTD0/ LLWU_P12	SPI0_PCS0	UART2_RTS_ b					
A4	58	PTD1	ADC0_SE5b	ADC0_SE5b	PTD1	SPI0_SCK	UART2_CTS_ b					
C2	59	PTD2/ LLWU_P13	DISABLED		PTD2/ LLWU_P13	SPI0_SOUT	UART2_RX					
B3	60	PTD3	DISABLED		PTD3	SPI0_SIN	UART2_TX					
A3	61	PTD4/ LLWU_P14	DISABLED		PTD4/ LLWU_P14	SPI0_PCS1	UART0_RTS_ b	FTM0_CH4		EWM_IN		
C1	62	PTD5	ADC0_SE6b	ADC0_SE6b	PTD5	SPI0_PCS2	UART0_CTS_ b/ UART0_COL_ b	FTM0_CH5		EWM_OUT_b		
B2	63	PTD6/ LLWU_P15	ADC0_SE7b	ADC0_SE7b	PTD6/ LLWU_P15	SPI0_PCS3	UART0_RX	FTM0_CH6		FTM0_FLT0		
A2	64	PTD7	DISABLED		PTD7	CMT_IRO	UART0_TX	FTM0_CH7		FTM0_FLT1		

## 8.2 K20 Pinouts

The below figure shows the pinout diagram for the devices supported by this document. Many signals may be multiplexed onto a single pin. To determine what signals can be used on which pin, see the previous section.

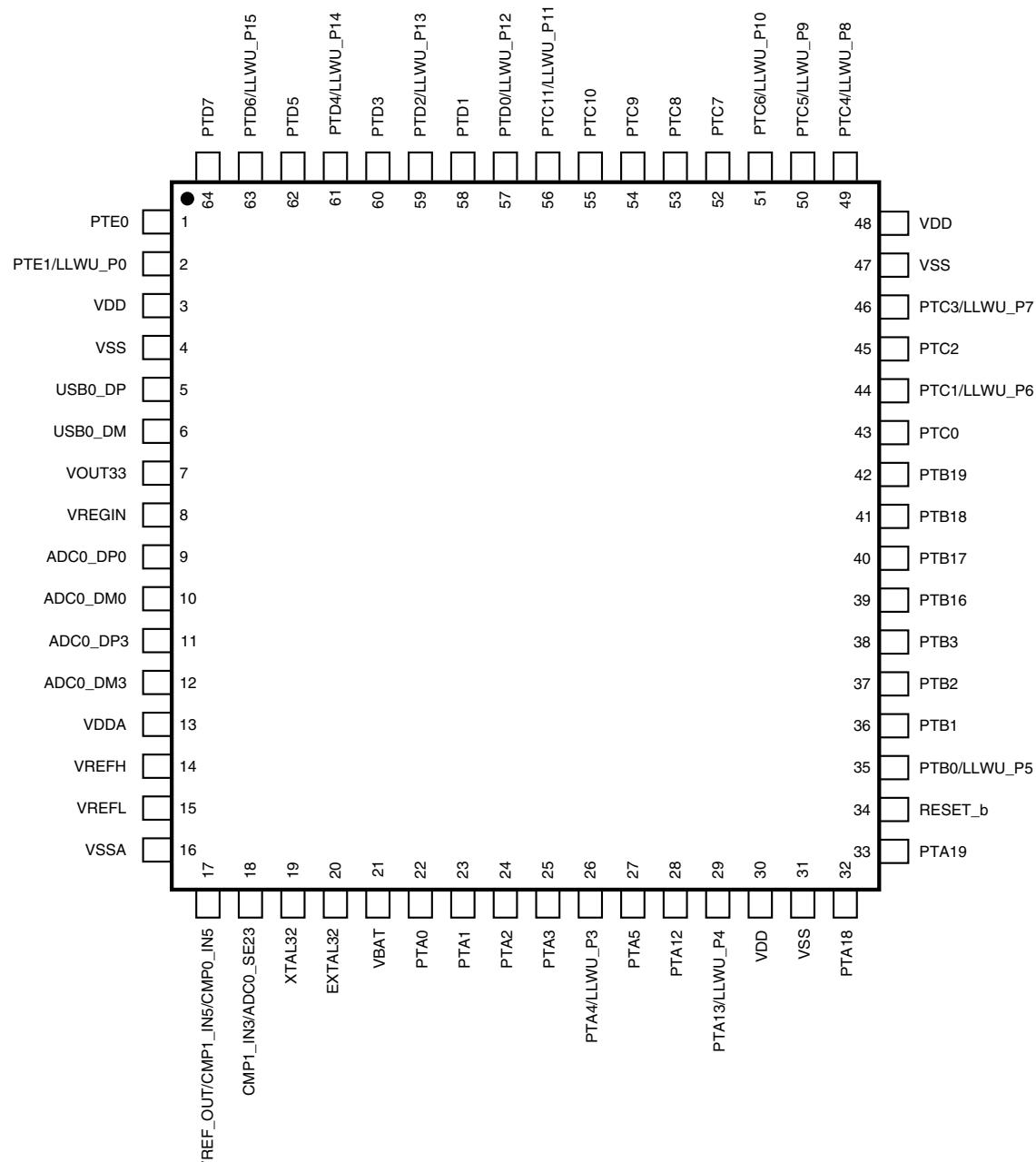


Figure 23. K20 64 LQFP Pinout Diagram

**Table 41. Revision History (continued)**

<b>Rev. No.</b>	<b>Date</b>	<b>Substantial Changes</b>
4	5/2012	<ul style="list-style-type: none"> <li>• For the "32kHz oscillator frequency specifications", added specifications for an externally driven clock.</li> <li>• Renamed section "Flash current and power specifications" to section "Flash high voltage current behaviors" and improved the specifications.</li> <li>• For the "VREF full-range operating behaviors" table, removed the Ac (aging coefficient) specification.</li> <li>• Corrected the following DSPI switching specifications: tightened DS5, DS6, and DS7; relaxed DS11 and DS13.</li> <li>• For the "TSI electrical specifications", changed and clarified the example calculations for the MaxSens specification.</li> </ul>