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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

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Details	
Product Status	Active
Core Processor	MIPS32® M4K™
Core Size	32-Bit Single-Core
Speed	40MHz
Connectivity	I ² C, IrDA, LINbus, PMP, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, I ² S, POR, PWM, WDT
Number of I/O	21
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 3.6V
Data Converters	A/D 10x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SOIC (0.295", 7.50mm Width)
Supplier Device Package	28-SOIC
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic32mx150f128b-v-so

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

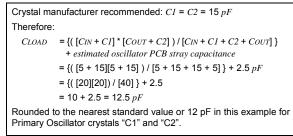
PIC32MX1XX/2XX 28/36/44-PIN FAMILY

2.8.1 CRYSTAL OSCILLATOR DESIGN CONSIDERATION

The following example assumptions are used to calculate the Primary Oscillator loading capacitor values:

- CIN = PIC32_OSC2_Pin Capacitance = ~4-5 pF
- COUT = PIC32_OSC1_Pin Capacitance = ~4-5 pF
- C1 and C2 = XTAL manufacturing recommended loading capacitance
- Estimated PCB stray capacitance, (i.e.,12 mm length) = 2.5 pF

EXAMPLE 2-1: CRYSTAL LOAD CAPACITOR CALCULATION

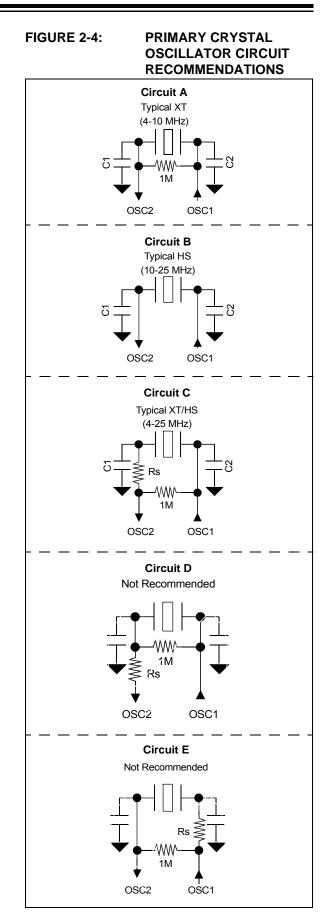


The following tips are used to increase oscillator gain, (i.e., to increase peak-to-peak oscillator signal):

- Select a crystal with a lower "minimum" power drive rating
- Select an crystal oscillator with a lower XTAL manufacturing "ESR" rating.
- Add a parallel resistor across the crystal. The smaller the resistor value the greater the gain. It is recommended to stay in the range of 600k to 1M
- C1 and C2 values also affect the gain of the oscillator. The lower the values, the higher the gain.
- C2/C1 ratio also affects gain. To increase the gain, make C1 slightly smaller than C2, which will also help start-up performance.
- Note: Do not add excessive gain such that the oscillator signal is clipped, flat on top of the sine wave. If so, you need to reduce the gain or add a series resistor, RS, as shown in circuit "C" in Figure 2-4. Failure to do so will stress and age the crystal, which can result in an early failure. Adjust the gain to trim the max peak-to-peak to ~VDD-0.6V. When measuring the oscillator signal you must use a FET scope probe or a probe with ≤ 1.5 pF or the scope probe itself will unduly change the gain and peak-to-peak levels.

2.8.1.1 Additional Microchip References

- AN588 "PICmicro[®] Microcontroller Oscillator Design Guide"
- AN826 "Crystal Oscillator Basics and Crystal Selection for rfPIC[™] and PICmicro[®] Devices"
- AN849 "Basic PICmicro[®] Oscillator Design"



NOTES:

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
04.04	U-0	U-0						
31:24	_	_	_	_	_		-	—
22:16	U-0	U-0						
23:16	_	_	_	_	_		-	—
45.0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0, HS	R/W-0
15:8		_	_	-	_	_	CMR	VREGS
7.0	R/W-0, HS	R/W-0, HS	U-0	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-1, HS	R/W-1, HS
7:0	EXTR	SWR	_	WDTO	SLEEP	IDLE	BOR ⁽¹⁾	POR ⁽¹⁾

REGISTER 6-1: RCON: RESET CONTROL REGISTER

Legend:HS = Set by hardware			
R = Readable bit	W = Writable bit	U = Unimplemented bit, re	ead as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-10 Unimplemented: Read as '0'

bit 9	CMR: Configuration Mismatch Reset Flag bit
	1 = Configuration mismatch Reset has occurred
	0 = Configuration mismatch Reset has not occurred
bit 8	VREGS: Voltage Regulator Standby Enable bit
	1 = Regulator is enabled and is on during Sleep mode
	0 = Regulator is disabled and is off during Sleep mode
bit 7	EXTR: External Reset (MCLR) Pin Flag bit
	1 = Master Clear (pin) Reset has occurred
	0 = Master Clear (pin) Reset has not occurred
bit 6	SWR: Software Reset Flag bit
	1 = Software Reset was executed
	0 = Software Reset as not executed
bit 5	Unimplemented: Read as '0'
bit 4	WDTO: Watchdog Timer Time-out Flag bit
	1 = WDT Time-out has occurred
	0 = WDT Time-out has not occurred
bit 3	SLEEP: Wake From Sleep Flag bit
	1 = Device was in Sleep mode
	0 = Device was not in Sleep mode
bit 2	IDLE: Wake From Idle Flag bit
	1 = Device was in Idle mode
	0 = Device was not in Idle mode
bit 1	BOR: Brown-out Reset Flag bit ⁽¹⁾
	1 = Brown-out Reset has occurred
	0 = Brown-out Reset has not occurred
bit 0	POR: Power-on Reset Flag bit ⁽¹⁾
	1 = Power-on Reset has occurred
	0 = Power-on Reset has not occurred

Note 1: User software must clear this bit to view next detection.

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0			
	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
31:24	_	RODIV<14:8> ^(1,3)									
	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
23:16	RODIV<7:0> ^(1,3)										
45.0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0, HC	R-0, HS, HC			
15:8	ON	_	SIDL	OE	RSLP ⁽²⁾	_	DIVSWEN	ACTIVE			
	U-0	U-0 U-0		U-0	R/W-0	R/W-0	R/W-0	R/W-0			
7:0						ROSEL	.<3:0>(1)				

REGISTER 8-3: REFOCON: REFERENCE OSCILLATOR CONTROL REGISTER

Legend:	HC = Hardware Clearable	HS = Hardware Settable	
R = Readable bit	W = Writable bit	U = Unimplemented bit, r	ead as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31 Unimplemented: Read as '0'

bit 30-16	RODIV<14:0> Reference Clock Divider bits ^(1,3)
	The value selects the reference clock divider bits. See Figure 8-1 for information.
bit 15	ON: Output Enable bit
	1 = Reference Oscillator module is enabled
	0 = Reference Oscillator module is disabled
bit 14	Unimplemented: Read as '0'
bit 13	SIDL: Peripheral Stop in Idle Mode bit

- 1 = Discontinue module operation when the device enters Idle mode
 - 0 =Continue module operation when the device enters lide mode
- bit 12 **OE:** Reference Clock Output Enable bit
 - 1 = Reference clock is driven out on REFCLKO pin
 - 0 = Reference clock is not driven out on REFCLKO pin
- bit 11 RSLP: Reference Oscillator Module Run in Sleep bit⁽²⁾
 - 1 = Reference Oscillator module output continues to run in Sleep
 - 0 = Reference Oscillator module output is disabled in Sleep
- bit 10 Unimplemented: Read as '0'
- bit 9 DIVSWEN: Divider Switch Enable bit
 - 1 = Divider switch is in progress
 - 0 = Divider switch is complete
- bit 8 ACTIVE: Reference Clock Request Status bit
 - 1 = Reference clock request is active
 - 0 = Reference clock request is not active
- bit 7-4 Unimplemented: Read as '0'
- **Note 1:** The ROSEL and RODIV bits should not be written while the ACTIVE bit is '1', as undefined behavior may result.
 - **2:** This bit is ignored when the ROSEL<3:0> bits = 0000 or 0001.
 - 3: While the ON bit is set to '1', writes to these bits do not take effect until the DIVSWEN bit is also set to '1'.

TABLE 9-3: DMA CHANNELS 0-3 REGISTER MAP (CONTINUED)

ess										Bi	ts								
Virtual Address (BF88_#)	Register Name ⁽¹⁾	Bit Range	31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	All Resets
3170	DCH1SSIZ	31:16	—	_	—	_		_	_	_	_		-	_	-	—	_	_	0000
5170	DOITIOUZ	15:0								CHSSIZ	2<15:0>								0000
3180	DCH1DSIZ	31:16	_	_	—	—	—	—	_	-	—	—	_		_	—	_	—	0000
5100	DOITIDOIZ	15:0								CHDSIZ	2<15:0>								0000
3190	DCH1SPTR	31:16	_	—	—	—	—	—	—	—	—	—	—	—	—	—	_	_	0000
0100		15:0								CHSPTI	R<15:0>								0000
31A0	DCH1DPTR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
017.00		15:0								CHDPT	R<15:0>								0000
31B0	DCH1CSIZ	31:16	_	_	—	—	—	—	_	_	—	—	_	—	—	—	—	-	0000
0.20		15:0								CHCSIZ	2<15:0>								0000
31C0	DCH1CPTR	31:16	_	_	_	—	—	—	_	_	—	—	—		—	—	—		0000
0.00		15:0								CHCPTI	R<15:0>								0000
31D0	DCH1DAT	31:16	—	_	—	—	—	—	—	_	_	—	—		—	—	—		0000
0.20		15:0	—	_	—	—	—	—	—	_				CHPDA					0000
31F0	DCH2CON	31:16	—	_	—	—	—	—	—	_			_	_	_	—	—		0000
0.20			CHBUSY	_	_	—	_	_		CHCHNS	CHEN	CHAED	CHCHN	CHAEN	—	CHEDET	CHPR	<1:0>	0000
31F0	DCH2ECON	31:16	_	_	—	—	—	—	_	_				CHAIR					00FF
		15:0				CHSIR	Q<7:0>				CFORCE	CABORT	PATEN	SIRQEN	AIRQEN	_	—	—	FF00
3200	DCH2INT	31:16	—	—	—	—	—	—	_	—	CHSDIE	CHSHIE	CHDDIE	CHDHIE	CHBCIE	CHCCIE	CHTAIE	CHERIE	0000
		15:0	_	_		—	—	—			CHSDIF	CHSHIF	CHDDIF	CHDHIF	CHBCIF	CHCCIF	CHTAIF	CHERIF	0000
3210	DCH2SSA	31:16								CHSSA	<31:0>								0000
		15:0																	0000
3220		31:16								CHDSA	<31:0>								0000
		15:0								1									0000
3230	DCH2SSIZ	31:16		—	—	—	—	—	—		—	—	—	—	—	—	—	—	0000
		15:0								CHSSIZ	2<15:0>								0000
3240	DCH2DSIZ	31:16			—	_	—	_	_	<u> </u>	—	—	—	—	—	—	_	—	0000
		15:0								CHDSIZ	2<15:0>								0000
3250	DCH2SPTR	31:16			—	_	—	_	_	<u> </u>	—	—	—	—	—	—	_		0000
		15:0								CHSPTI	≺<15:0>								0000
3260	DCH2DPTR	31:16			—	_	—	_	_	—	—	—	—	—	—	—	—	—	0000
		15:0								CHDPTI	R<15:0>								0000
3270	DCH2CSIZ	31:16		_	—	—	—	—	—		—	—	—	—	—	—	_		0000
		15:0								CHCSI2 exadecimal									0000

Legend:

x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: All registers in this table have corresponding CLR, SET and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively. See Section 11.2 "CLR, SET and INV Registers" for more information.

PIC32MX1XX/2XX 28/36/44-PIN FAMILY

REGIOTE	CEGISTER 3-12. DOTASSIZ: DINA CHANNEL X SOURCE SIZE REGISTER										
Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0			
24.24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0			
31:24	—	—	_	_	—	_	—	—			
22:46	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0			
23:16		_		_	_		_	—			
45.0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
15:8	CHSSIZ<15:8>										
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
7:0				CHSSIZ	<7:0>						

REGISTER 9-12: DCHxSSIZ: DMA CHANNEL 'x' SOURCE SIZE REGISTER

Legend:R = Readable bitW = Writable bitU = Unimplemented bit, read as '0'-n = Value at POR'1' = Bit is set'0' = Bit is clearedx = Bit is unknown

bit 31-16 Unimplemented: Read as '0'

bit 15-0 CHSSIZ<15:0>: Channel Source Size bits

1111111111111111 = 65,535 byte source size

REGISTER 9-13: DCHxDSIZ: DMA CHANNEL 'x' DESTINATION SIZE REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0		
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0		
	—	_	—	_	_	—	_	—		
00.40	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0		
23:16	—	—	—	—	_	—	_	—		
45.0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		
15:8	CHDSIZ<15:8>									
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		
7:0				CHDSIZ	<7:0>					

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, r	ead as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-16 Unimplemented: Read as '0'

NOTES:

PIC32MX1XX/2XX 28/36/44-PIN FAMILY

REGISTER 10-3: U1OTGSTAT: USB OTG STATUS REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0			
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0			
51.24	-	—	—	—	_	—	—	—			
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0			
23.10	-	—	—	—	_	—	—	—			
15:8	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0			
15.0		—	—	—	_	—		—			
7.0	R-0	U-0	R-0	U-0	R-0	R-0	U-0	R-0			
7:0	ID		LSTATE	_	SESVD	SESEND	_	VBUSVD			

Legend:

Logona.							
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'					
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown				

bit 31-8 Unimplemented: Read as '0'

- bit 7 ID: ID Pin State Indicator bit
 - 1 = No cable is attached or a "type B" cable has been inserted into the USB receptacle
 - 0 = A "type A" OTG cable has been inserted into the USB receptacle
- bit 6 Unimplemented: Read as '0'
- bit 5 LSTATE: Line State Stable Indicator bit
 - 1 = USB line state (SE0 (U1CON<6>) bit and JSTATE (U1CON<7>)) bit has been stable for previous 1 ms 0 = USB line state (SE0 and JSTATE) has not been stable for previous 1 ms

bit 4 Unimplemented: Read as '0'

- bit 3 SESVD: Session Valid Indicator bit
 - 1 = VBUS voltage is above Session Valid on the A or B device
 - 0 = VBUS voltage is below Session Valid on the A or B device
- bit 2 SESEND: B-Device Session End Indicator bit
 - 1 = VBUS voltage is below Session Valid on the B device
 - 0 = VBUS voltage is above Session Valid on the B device

bit 1 Unimplemented: Read as '0'

- bit 0 VBUSVD: A-Device VBUS Valid Indicator bit
 - 1 = VBUS voltage is above Session Valid on the A device
 - 0 = VBUS voltage is below Session Valid on the A device

11.3 Peripheral Pin Select

A major challenge in general purpose devices is providing the largest possible set of peripheral features while minimizing the conflict of features on I/O pins. The challenge is even greater on low pin-count devices. In an application where more than one peripheral needs to be assigned to a single pin, inconvenient workarounds in application code or a complete redesign may be the only option.

The Peripheral Pin Select (PPS) configuration provides an alternative to these choices by enabling peripheral set selection and their placement on a wide range of I/O pins. By increasing the pinout options available on a particular device, users can better tailor the device to their entire application, rather than trimming the application to fit the device.

The PPS configuration feature operates over a fixed subset of digital I/O pins. Users may independently map the input and/or output of most digital peripherals to these I/O pins. PPS is performed in software and generally does not require the device to be reprogrammed. Hardware safeguards are included that prevent accidental or spurious changes to the peripheral mapping once it has been established.

11.3.1 AVAILABLE PINS

The number of available pins is dependent on the particular device and its pin count. Pins that support the PPS feature include the designation "RPn" in their full pin designation, where "RP" designates a remappable peripheral and "n" is the remappable port number.

11.3.2 AVAILABLE PERIPHERALS

The peripherals managed by the PPS are all digitalonly peripherals. These include general serial communications (UART and SPI), general purpose timer clock inputs, timer-related peripherals (input capture and output compare) and interrupt-on-change inputs.

In comparison, some digital-only peripheral modules are never included in the PPS feature. This is because the peripheral's function requires special I/O circuitry on a specific port and cannot be easily connected to multiple pins. These modules include I²C among others. A similar requirement excludes all modules with analog inputs, such as the Analog-to-Digital Converter (ADC).

A key difference between remappable and non-remappable peripherals is that remappable peripherals are not associated with a default I/O pin. The peripheral must always be assigned to a specific I/O pin before it can be used. In contrast, non-remappable peripherals are always available on a default pin, assuming that the peripheral is active and not conflicting with another peripheral.

When a remappable peripheral is active on a given I/O pin, it takes priority over all other digital I/O and digital communication peripherals associated with the pin.

Priority is given regardless of the type of peripheral that is mapped. Remappable peripherals never take priority over any analog functions associated with the pin.

11.3.3 CONTROLLING PERIPHERAL PIN SELECT

PPS features are controlled through two sets of SFRs: one to map peripheral inputs, and one to map outputs. Because they are separately controlled, a particular peripheral's input and output (if the peripheral has both) can be placed on any selectable function pin without constraint.

The association of a peripheral to a peripheral-selectable pin is handled in two different ways, depending on whether an input or output is being mapped.

11.3.4 INPUT MAPPING

The inputs of the PPS options are mapped on the basis of the peripheral. That is, a control register associated with a peripheral dictates the pin it will be mapped to. The [*pin name*]R registers, where [*pin name*] refers to the peripheral pins listed in Table 11-1, are used to configure peripheral input mapping (see Register 11-1). Each register contains sets of 4 bit fields. Programming these bit fields with an appropriate value maps the RPn pin with the corresponding value to that peripheral. For any given device, the valid range of values for any bit field is shown in Table 11-1.

For example, Figure 11-2 illustrates the remappable pin selection for the U1RX input.

FIGURE 11-2: REMAPPABLE INPUT EXAMPLE FOR U1RX

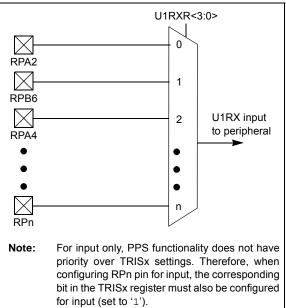


TABLE 11-5: PORTC REGISTER MAP

ess	-											Bits							<i>"</i>
Virtual Address (BF88_#)	Register Name ^(1,2)	Bit Range	31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	All Resets
6200	ANSELC	31:16		_			—	—	_		_		_	_	—	_	—		0000
0200	,	15:0	—	—	—	—	—	—			—			_	ANSC3(4)	ANSC2 ⁽³⁾	ANSC1	ANSC0	000F
6210	TRISC	31:16	_	_	—	—	—	—	—	—	—	—	—	—	—	—	—		0000
0210	11100	15:0	_	_	—	—	—	—	TRISC9	TRISC8 ⁽³⁾	TRISC7 ⁽³⁾	TRISC6 ⁽³⁾	TRISC5 ⁽³⁾	TRISC4 ⁽³⁾	TRISC3	TRISC2 ⁽³⁾	TRISC1	TRISC0	03FF
6220	PORTC	31:16	—	—	—	—	—	—	_		_		_						0000
0220		15:0	_	_	—	—	—	—	RC9	RC8 ⁽³⁾	RC7 ⁽³⁾	RC6 ⁽³⁾	RC5 ⁽³⁾	RC4 ⁽³⁾	RC3	RC2 ⁽³⁾	RC1	RC0	xxxx
6230	LATC	31:16	_	_	—	—	—	—	_		_			_	—		—	—	0000
0230	LAIC	15:0			_	_	_	_	LATC9	LATC8 ⁽³⁾	LATC7 ⁽³⁾	LATC6 ⁽³⁾	LATC5 ⁽³⁾	LATC4 ⁽³⁾	LATC3	LATC2 ⁽³⁾	LATC1	LATC0	xxxx
6240	ODCC	31:16			_	_	_	_	—						_		_	_	0000
6240	ODCC	15:0			_	_	_	_	ODCC9	ODCC8 ⁽³⁾	ODCC7 ⁽³⁾	ODCC6 ⁽³⁾	ODCC5 ⁽³⁾	ODCC4 ⁽³⁾	ODCC3	ODCC2 ⁽³⁾	ODCC1	ODCC0	0000
0050		31:16			—	—	—	-	—	-	_	-	—	—	—	—	—	—	0000
6250	CNPUC	15:0	_	_	_	_	—	—	CNPUC9	CNPUC8 ⁽³⁾	CNPUC7 ⁽³⁾	CNPUC6 ⁽³⁾	CNPUC5 ⁽³⁾	CNPUC4 ⁽³⁾	CNPUC3	CNPUC2 ⁽³⁾	CNPUC1	CNPUC0	0000
0000		31:16	_	_	_	_	_	_	—	_	_	_	_	—	_	—	_	_	0000
6260	CNPDC	15:0	_	_	—	_	—	—	CNPDC9	CNPDC8 ⁽³⁾	CNPDC7 ⁽³⁾	CNPDC6 ⁽³⁾	CNPDC5 ⁽³⁾	CNPDC4 ⁽³⁾	CNPDC3	CNPDC2 ⁽³⁾	CNPDC1	CNPDC0	0000
0070	anaana	31:16	_	_	—	_	—	—	_	_	_	_	—	—	—	_	—	—	0000
6270	CNCONC	15:0	ON	_	SIDL	_	—	—	_	_	_	_	_	—	_	_	—	_	0000
		31:16	_	_	_		—	_			_		_	_	_	_	—	—	0000
6280	CNENC	15:0	_	_	_		—	_	CNIEC9	CNIEC8(3)	CNIEC7 ⁽³⁾	CNIEC6(3)	CNIEC5 ⁽³⁾	CNIEC4 ⁽³⁾	CNIEC3	CNIEC2 ⁽³⁾	CNIEC1	CNIEC0	0000
		31:16	_	_	_	_	_	_	_		_		_	_	—		—	—	0000
6290	CNSTATC	15:0	_	_	_	_	_	_	CNSTATC9	CNSTATC8(3)	CNSTATC7 ⁽³⁾	CNSTATC6(3)	CNSTATC5(3)	CNSTATC4 ⁽³⁾	CNSTATC3	CNSTATC2(3)	CNSTATC1	CNSTATC0	0000

Legend: x = unknown value on Reset; - = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: All registers in this table have corresponding CLR, SET and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively. See Section 11.2 "CLR, SET and INV Registers" for more information.

2: PORTC is not available on 28-pin devices.

3: This bit is only available on 44-pin devices.

4: This bit is only available on USB-enabled devices with 36 or 44 pins.

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
24.04	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
31:24	—	_	_	_	_	_	—	_
00.40	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
23:16	—	_	_	_	_	_	—	_
45.0	R/W-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
15:8	ON ^(1,2)	_	_	_	—	_	—	_
7.0	U-0	R-y	R-y	R-y	R-y	R-y	R/W-0	R/W-0
7:0	_		S	WDTPS<4:0	>		WDTWINEN	WDTCLR

REGISTER 14-1: WDTCON: WATCHDOG TIMER CONTROL REGISTER

Legend:	y = Values set from Configuration bits on POR							
R = Readable bit	W = Writable bit U = Unimplemented bit, read as '0'							
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown					

bit 31-16 Unimplemented: Read as '0'

- bit 15 **ON:** Watchdog Timer Enable bit^(1,2)
 - 1 = Enables the WDT if it is not enabled by the device configuration
 - 0 = Disable the WDT if it was enabled in software
- bit 14-7 Unimplemented: Read as '0'
- bit 6-2 **SWDTPS<4:0>:** Shadow Copy of Watchdog Timer Postscaler Value from Device Configuration bits On reset, these bits are set to the values of the WDTPS <4:0> of Configuration bits.
- bit 1 WDTWINEN: Watchdog Timer Window Enable bit
 - 1 = Enable windowed Watchdog Timer
 - 0 = Disable windowed Watchdog Timer
- bit 0 **WDTCLR:** Watchdog Timer Reset bit
 - 1 = Writing a '1' will clear the WDT
 - 0 = Software cannot force this bit to a '0'
- **Note 1:** A read of this bit results in a '1' if the Watchdog Timer is enabled by the device configuration or software.
 - 2: When using the 1:1 PBCLK divisor, the user's software should not read or write the peripheral's SFRs in the SYSCLK cycle immediately following the instruction that clears the module's ON bit.

REGISTER 15-1: ICXCON: INPUT CAPTURE 'x' CONTROL REGISTER (CONTINUED)

ICM<2:0>: Input Capture Mode Select bits

bit 2-0

- 111 = Interrupt-Only mode (only supported while in Sleep mode or Idle mode)
- 110 = Simple Capture Event mode every edge, specified edge first and every edge thereafter
- 101 = Prescaled Capture Event mode every sixteenth rising edge
- 100 = Prescaled Capture Event mode every fourth rising edge
- 011 = Simple Capture Event mode every rising edge
- 010 = Simple Capture Event mode every falling edge
- 001 = Edge Detect mode every edge (rising and falling)
- 000 = Input Capture module is disabled
- **Note 1:** When using 1:1 PBCLK divisor, the user's software should not read/write the peripheral's SFRs in the SYSCLK cycle immediately following the instruction that clears the module's ON bit.

20.1 PMP Control Registers

TABLE 20-1: PARALLEL MASTER PORT REGISTER MAP

ess		0								Bi	ts								
Virtual Address (BF80_#)	Register Name ⁽¹⁾	Bit Range	31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	All Resets
7000	PMCON	31:16	—	_	-	_			-	_	—	—	—			—	—	_	0000
7000	FINCON	15:0	ON	_	SIDL	ADRML	IX<1:0>	PMPTTL	PTWREN	PTRDEN	CSF∙	<1:0>	ALP		CS1P	_	WRSP	RDSP	0000
7010	PMMODE	31:16	—	_		_	_		_	_	—	_	—			_	—	_	0000
7010	FININODE	15:0	BUSY	IRQM	<1:0>	INCM	INCM<1:0> — MODE<1:0> WAITB<1:0> WAITM<3:0> WAITE<1:0> 000							0000					
		31:16	_	—	—	_	—	_	—	_	_	_	_	—	—	_	_	—	0000
7020	PMADDR	15:0	_	CS1 ADDR14	_	_	_					/	ADDR<10:0	>					0000
7030	PMDOUT	31:16 15:0								DATAOU	T<31:0>								0000
7040	PMDIN	31:16 15:0		DATAIN<31:0>															
7050		31:16	_	_		_	-		-	_	_	_	—			_	_		0000
7050	PMAEN	15:0	_	PTEN14	_	_	_						PTEN<10:0	>					0000
7060	PMSTAT	31:16				_			_	_			—	_	_		—	_	0000
1000	FINISTAT	15:0	IBF	IBOV	_	_	IB3F	IB2F	IB1F	IB0F	OBE	OBUF	—	_	OB3E	OB2E	OB1E	OB0E	008F

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: All registers in this table have corresponding CLR, SET and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively. See Section 11.2 "CLR, SET and INV Registers" for more information.

23.0 COMPARATOR

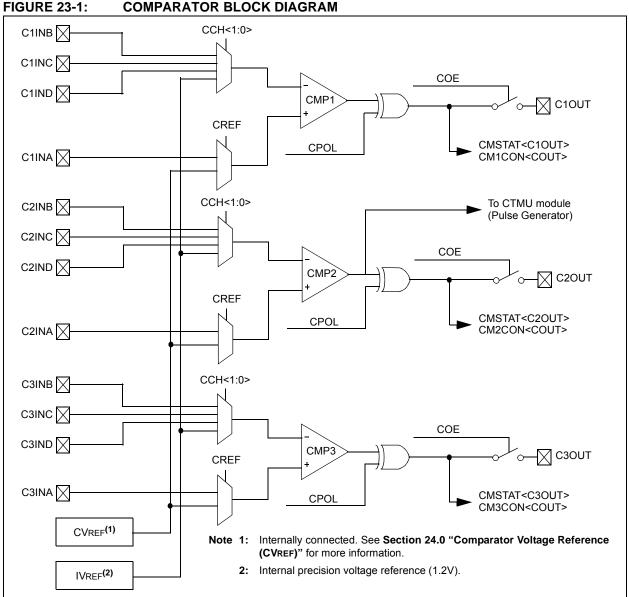
Note: This data sheet summarizes the features of the PIC32MX1XX/2XX 28/36/44-pin Family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer Section 19. to "Comparator" (DS60001110), which is available from the Documentation > Reference Manual section of the Microchip PIC32 web site (www.microchip.com/pic32).

The Analog Comparator module contains three comparators that can be configured in a variety of ways.

Following are some of the key features of this module:

- Selectable inputs available include:
 - Analog inputs multiplexed with I/O pins
 - On-chip internal absolute voltage reference (IVREF)
 - Comparator voltage reference (CVREF)
- · Outputs can be Inverted
- Selectable interrupt generation

A block diagram of the comparator module is provided in Figure 23-1.



The processor will exit, or 'wake-up', from Sleep on one of the following events:

- On any interrupt from an enabled source that is operating in Sleep. The interrupt priority must be greater than the current CPU priority.
- · On any form of device Reset
- On a WDT time-out

If the interrupt priority is lower than or equal to the current priority, the CPU will remain Halted, but the PBCLK will start running and the device will enter into Idle mode.

26.3.2 IDLE MODE

In Idle mode, the CPU is Halted but the System Clock (SYSCLK) source is still enabled. This allows peripherals to continue operation when the CPU is Halted. Peripherals can be individually configured to Halt when entering Idle by setting their respective SIDL bit. Latency, when exiting Idle mode, is very low due to the CPU oscillator source remaining active.

- Note 1: Changing the PBCLK divider ratio requires recalculation of peripheral timing. For example, assume the UART is configured for 9600 baud with a PB clock ratio of 1:1 and a Posc of 8 MHz. When the PB clock divisor of 1:2 is used, the input frequency to the baud clock is cut in half; therefore, the baud rate is reduced to 1/2 its former value. Due to numeric truncation in calculations (such as the baud rate divisor), the actual baud rate may be a tiny percentage different than expected. For this reason, any timing calculation required for a peripheral should be performed with the new PB clock frequency instead of scaling the previous value based on a change in the PB divisor ratio.
 - 2: Oscillator start-up and PLL lock delays are applied when switching to a clock source that was disabled and that uses a crystal and/or the PLL. For example, assume the clock source is switched from Posc to LPRC just prior to entering Sleep in order to save power. No oscillator startup delay would be applied when exiting Idle. However, when switching back to Posc, the appropriate PLL and/or oscillator start-up/lock delays would be applied.

The device enters Idle mode when the SLPEN (OSCCON<4>) bit is clear and a WAIT instruction is executed.

The processor will wake or exit from Idle mode on the following events:

- On any interrupt event for which the interrupt source is enabled. The priority of the interrupt event must be greater than the current priority of the CPU. If the priority of the interrupt event is lower than or equal to current priority of the CPU, the CPU will remain Halted and the device will remain in Idle mode.
- On any form of device Reset
- On a WDT time-out interrupt

26.3.3 PERIPHERAL BUS SCALING METHOD

Most of the peripherals on the device are clocked using the PBCLK. The Peripheral Bus can be scaled relative to the SYSCLK to minimize the dynamic power consumed by the peripherals. The PBCLK divisor is controlled by PBDIV<1:0> (OSCCON<20:19>), allowing SYSCLK to PBCLK ratios of 1:1, 1:2, 1:4 and 1:8. All peripherals using PBCLK are affected when the divisor is changed. Peripherals such as the USB, Interrupt Controller, DMA, and the bus matrix are clocked directly from SYSCLK. As a result, they are not affected by PBCLK divisor changes.

Changing the PBCLK divisor affects:

- The CPU to peripheral access latency. The CPU has to wait for next PBCLK edge for a read to complete. In 1:8 mode, this results in a latency of one to seven SYSCLKs.
- The power consumption of the peripherals. Power consumption is directly proportional to the frequency at which the peripherals are clocked. The greater the divisor, the lower the power consumed by the peripherals.

To minimize dynamic power, the PB divisor should be chosen to run the peripherals at the lowest frequency that provides acceptable system performance. When selecting a PBCLK divider, peripheral clock requirements, such as baud rate accuracy, should be taken into account. For example, the UART peripheral may not be able to achieve all baud rate values at some PBCLK divider depending on the SYSCLK value.

28.0 INSTRUCTION SET

The PIC32MX1XX/2XX family instruction set complies with the MIPS32[®] Release 2 instruction set architecture. The PIC32 device family does not support the following features:

- · Core extend instructions
- Coprocessor 1 instructions
- Coprocessor 2 instructions

Note: Refer to "*MIPS32*[®] Architecture for Programmers Volume II: The MIPS32[®] Instruction Set" at www.imgtec.com for more information.

TABLE 30-18: PLL CLOCK TIMING SPECIFICATIONS

AC CHA	RACTERI	STICS	(unless ot	$\begin{array}{l} \mbox{Standard Operating Conditions: 2.3V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +105^{\circ}C \mbox{ for V-temp} \end{array}$							
Param. No.	Symbol	Characteristi	cs ⁽¹⁾	Min.	Typical	Max.	Units	Conditions			
OS50	Fplli	PLL Voltage Control Oscillator (VCO) Inp Frequency Range	3.92	_	5	MHz	ECPLL, HSPLL, XTPLL, FRCPLL modes				
OS51	Fsys	On-Chip VCO Syste Frequency	m	60	—	120	MHz	_			
OS52	TLOCK	PLL Start-up Time (L	ock Time)	_	_	2	ms	—			
OS53	DCLK	CLKO Stability ⁽²⁾ (Period Jitter or Cum	-0.25	—	+0.25	%	Measured over 100 ms period				

Note 1: These parameters are characterized, but not tested in manufacturing.

2: This jitter specification is based on clock-cycle by clock-cycle measurements. To get the effective jitter for individual time-bases on communication clocks, use the following formula:

$$EffectiveJitter = \frac{D_{CLK}}{\sqrt{\frac{SYSCLK}{CommunicationClock}}}$$

For example, if SYSCLK = 40 MHz and SPI bit rate = 20 MHz, the effective jitter is as follows:

$$EffectiveJitter = \frac{D_{CLK}}{\sqrt{\frac{40}{20}}} = \frac{D_{CLK}}{1.41}$$

TABLE 30-19: INTERNAL FRC ACCURACY

АС СНА	RACTERISTICS	Standard Operating Conditions: 2.3V to 3.6V(unless otherwise stated)Operating temperature $-40^{\circ}C \le TA \le +85^{\circ}C$ for Industrial $-40^{\circ}C \le TA \le +105^{\circ}C$ for V-temp								
Param. No.	Characteristics	Min.	Typical	Max.	Units	Conditions				
Internal FRC Accuracy @ 8.00 MHz ⁽¹⁾										
F20b	FRC	-0.9		+0.9	%	_				

Note 1: Frequency calibrated at 25°C and 3.3V. The TUN bits can be used to compensate for temperature drift.

TABLE 30-20: INTERNAL LPRC ACCURACY

АС СНА	RACTERISTICS	(unless	$\begin{array}{l} \mbox{Standard Operating Conditions: 2.3V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +105^{\circ}C \mbox{ for V-temp} \end{array}$								
Param. No.	Characteristics		Typical	Max.	Units	Conditions					
LPRC @ 31.25 kHz ⁽¹⁾											
F21	LPRC -15 — +15 % —										

Note 1: Change of LPRC frequency as VDD changes.

AC CHARAG	CTERISTIC	S ⁽²⁾	$\begin{array}{l} \mbox{Standard Operating Conditions (see Note 3): 2.5V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +105^{\circ}C \mbox{ for V-temp} \end{array}$						
ADC Speed	TAD Min.	Sampling Time Min.	Rs Max.	Vdd	ADC Channels Configuration				
1 Msps to 400 ksps ⁽¹⁾	65 ns	132 ns	500Ω	3.0V to 3.6V	ANX CHX ADC				
Up to 400 ksps	200 ns	200 ns	5.0 kΩ	2.5V to 3.6V	ANX CHX ANX OF VREF-				

TABLE 30-35:10-BIT CONVERSION RATE PARAMETERS

Note 1: External VREF- and VREF+ pins must be used for correct operation.

2: These parameters are characterized, but not tested in manufacturing.

3: The ADC module is functional at VBORMIN < VDD < 2.5V, but with degraded performance. Unless otherwise stated, module functionality is tested, but not characterized.

TABLE 31-3: DC CHARACTERISTICS: IDLE CURRENT (IIDLE)

DC CHARACT	ERISTICS		Standard Operating Conditions: 2.3V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}C \le TA \le +85^{\circ}C$ for Industrial					
Parameter No.	Typical ⁽²⁾	Max.	Units Conditions					
Idle Current (IIDLE): Core Off, Clock on Base Current (Note 1)								
MDC34a	8	13	mA 50 MHz					

Note 1: The test conditions for IIDLE current measurements are as follows:

- Oscillator mode is EC (for 8 MHz and below) and EC+PLL (for above 8 MHz) with OSC1 driven by external square wave from rail-to-rail, (OSC1 input clock input over/undershoot < 100 mV required)
- OSC2/CLKO is configured as an I/O input pin
- USB PLL oscillator is disabled if the USB module is implemented, PBCLK divisor = 1:8
- CPU is in Idle mode (CPU core Halted), and SRAM data memory Wait states = 1
- No peripheral modules are operating, (ON bit = 0), but the associated PMD bit is cleared
- WDT, Clock Switching, Fail-Safe Clock Monitor, and Secondary Oscillator are disabled
- All I/O pins are configured as inputs and pulled to Vss
- MCLR = VDD
- RTCC and JTAG are disabled
- 2: Data in the "Typical" column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

DC CHAR	ACTERIST	ICS	Standard Operating Conditions: 2.3V to 3.6V (unless otherwise stated)Operating temperature $-40^{\circ}C \le TA \le +85^{\circ}C$ for Industrial							
Param. No.	Typical ⁽²⁾	Max.	Units	Conditions						
Power-Down Current (IPD) (Note 1)										
MDC40k	10	25	μA	-40°C Base Power-Down Current						
MDC40n	250	500	μA	+85°C	Base Power-Down Current					
Module D	ifferential (Current								
MDC41e	10	55	μA	3.6V	Watchdog Timer Current: AIWDT (Note 3)					
MDC42e	23	55	μA	3.6V RTCC + Timer1 w/32 kHz Crystal: ∆IRTCC (Note 3)						
MDC43d	1100	1300	μA	3.6V ADC: △IADC (Notes 3,4)						

TABLE 31-4: DC CHARACTERISTICS: POWER-DOWN CURRENT (IPD)

Note 1: The test conditions for IPD current measurements are as follows:

• Oscillator mode is EC (for 8 MHz and below) and EC+PLL (for above 8 MHz) with OSC1 driven by external square wave from rail-to-rail, (OSC1 input clock input over/undershoot < 100 mV required)

- · OSC2/CLKO is configured as an I/O input pin
- USB PLL oscillator is disabled if the USB module is implemented, PBCLK divisor = 1:8
- CPU is in Sleep mode, and SRAM data memory Wait states = 1
- No peripheral modules are operating, (ON bit = 0), but the associated PMD bit is set
- WDT, Clock Switching, Fail-Safe Clock Monitor, and Secondary Oscillator are disabled
- · All I/O pins are configured as inputs and pulled to Vss
- MCLR = VDD
- RTCC and JTAG are disabled
- 2: Data in the "Typical" column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.
- **3:** The ∆ current is the additional current consumed when the module is enabled. This current should be added to the base IPD current.
- 4: Test conditions for ADC module differential current are as follows: Internal ADC RC oscillator enabled.

TABLE 31-8:SPIX MODULE SLAVE MODE (CKE = 0) TIMING REQUIREMENTS

АС СНА	ARACTERIS	TICS	Standard Operating Conditions: 2.3V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}C \le TA \le +85^{\circ}C$ for Industrial $-40^{\circ}C \le TA \le +105^{\circ}C$ for V-temp						
Param. No.	Symbol	Characteristics	Min.	Тур.	Max.	Units	Conditions		
MSP70	TscL	SCKx Input Low Time (Note 1,2)	Tsck/2		_	ns	_		
MSP71	TscH	SCKx Input High Time (Note 1,2)	Tsck/2	—		ns	—		
MSP51	TssH2doZ	SSx ↑ to SDOx Output High-Impedance (Note 2)	5		25	ns	—		

Note 1: These parameters are characterized, but not tested in manufacturing.

2: The minimum clock period for SCKx is 40 ns.

TABLE 31-9: SPIX MODULE SLAVE MODE (CKE = 1) TIMING REQUIREMENTS

AC CHARACTERISTICS			Standard Operating Conditions: 2.3V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}C \le TA \le +85^{\circ}C$ for Industrial				
Param. No.	Symbol	Characteristics	Min.	Typical	Max.	Units	Conditions
SP70	TscL	SCKx Input Low Time (Note 1,2)	Tsck/2			ns	
SP71	TscH	SCKx Input High Time (Note 1,2)	Tsck/2	_	_	ns	_

Note 1: These parameters are characterized, but not tested in manufacturing.

2: The minimum clock period for SCKx is 40 ns.