

Welcome to E-XFL.COM

#### What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

#### Details

E·XFI

Details	
Product Status	Active
Core Processor	MIPS32® M4K™
Core Size	32-Bit Single-Core
Speed	50MHz
Connectivity	I <sup>2</sup> C, IrDA, LINbus, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, I <sup>2</sup> S, POR, PWM, WDT
Number of I/O	19
Program Memory Size	256KB (256K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	64K x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 3.6V
Data Converters	A/D 9x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SOIC (0.295", 7.50mm Width)
Supplier Device Package	28-SOIC
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic32mx270f256b-50i-so

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

## TABLE 6: PIN NAMES FOR 28-PIN USB DEVICES

## 28-PIN QFN (TOP VIEW)<sup>(1,2,3,4)</sup>

PIC32MX210F016B PIC32MX220F032B PIC32MX230F064B PIC32MX230F256B PIC32MX250F128B PIC32MX250F128B

28

1

Pin #	Full Pin Name	Pin #	Full Pin Name
1	PGED1/AN2/C1IND/C2INB/C3IND/RPB0/PMD0/RB0	15	TDO/RPB9/SDA1/CTED4/PMD3/RB9
2	PGEC1/AN3/C1INC/C2INA/RPB1/CTED12/PMD1/RB1	16	Vss
3	AN4/C1INB/C2IND/RPB2/SDA2/CTED13/PMD2/RB2	17	VCAP
4	AN5/C1INA/C2INC/RTCC/RPB3/SCL2/PMWR/RB3	18	PGED2/RPB10/D+/CTED11/RB10
5	Vss	19	PGEC2/RPB11/D-/RB11
6	OSC1/CLKI/RPA2/RA2	20	VUSB3V3
7	OSC2/CLKO/RPA3/PMA0/RA3	21	AN11/RPB13/CTPLS/PMRD/RB13
8	SOSCI/RPB4/RB4	22	CVREFOUT/AN10/C3INB/RPB14/VBUSON/SCK1/CTED5/RB14
9	SOSCO/RPA4/T1CK/CTED9/PMA1/RA4	23	AN9/C3INA/RPB15/SCK2/CTED6/PMCS1/RB15
10	Vdd	24	AVss
11	TMS/RPB5/USBID/RB5	25	AVDD
12	VBUS	26	MCLR
13	TDI/RPB7/CTED3/PMD5/INT0/RB7	27	PGED3/VREF+/CVREF+/AN0/C3INC/RPA0/CTED1/PMD7/RA0
14	TCK/RPB8/SCL1/CTED10/PMD4/RB8	28	PGEC3/VREF-/CVREF-/AN1/RPA1/CTED2/PMD6/RA1

1: The RPn pins can be used by remappable peripherals. See Table 1 for the available peripherals and Section 11.3 "Peripheral Pin Select" for restrictions.

2: Every I/O port pin (RAx-RCx) can be used as a change notification pin (CNAx-CNCx). See Section 11.0 "I/O Ports" for more information.

3: The metal plane at the bottom of the device is not connected to any pins and is recommended to be connected to Vss externally.

4: Shaded pins are 5V tolerant.

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0		
24.24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0		
31:24	—	—	—	—	—		—	—		
	U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1		
23:16	_	—	_	BMX ERRIXI	BMX ERRICD	BMX ERRDMA	BMX ERRDS	BMX ERRIS		
45.0	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0		
15:8	—	—	—	-	—	_		—		
	U-0	R/W-1	U-0	U-0	U-0	R/W-0	R/W-0	R/W-1		
7:0	_	BMX WSDRM	_	_	_	E	3MXARB<2:0	>		

## REGISTER 4-1: BMXCON: BUS MATRIX CONFIGURATION REGISTER

## Legend:

5		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared

## bit 31-21 Unimplemented: Read as '0'

	Ommplemented. Read as 0
bit 20	BMXERRIXI: Enable Bus Error from IXI bit
	<ul> <li>1 = Enable bus error exceptions for unmapped address accesses initiated from IXI shared bus</li> <li>0 = Disable bus error exceptions for unmapped address accesses initiated from IXI shared bus</li> </ul>
bit 19	BMXERRICD: Enable Bus Error from ICD Debug Unit bit
	<ul> <li>1 = Enable bus error exceptions for unmapped address accesses initiated from ICD</li> <li>0 = Disable bus error exceptions for unmapped address accesses initiated from ICD</li> </ul>
bit 18	BMXERRDMA: Bus Error from DMA bit
	<ul> <li>1 = Enable bus error exceptions for unmapped address accesses initiated from DMA</li> <li>0 = Disable bus error exceptions for unmapped address accesses initiated from DMA</li> </ul>
bit 17	BMXERRDS: Bus Error from CPU Data Access bit (disabled in Debug mode)
	<ul> <li>1 = Enable bus error exceptions for unmapped address accesses initiated from CPU data access</li> <li>0 = Disable bus error exceptions for unmapped address accesses initiated from CPU data access</li> </ul>
bit 16	BMXERRIS: Bus Error from CPU Instruction Access bit (disabled in Debug mode)
	<ul> <li>1 = Enable bus error exceptions for unmapped address accesses initiated from CPU instruction access</li> <li>0 = Disable bus error exceptions for unmapped address accesses initiated from CPU instruction access</li> </ul>
bit 15-7	Unimplemented: Read as '0'
bit 6	BMXWSDRM: CPU Instruction or Data Access from Data RAM Wait State bit
	<ul> <li>1 = Data RAM accesses from CPU have one wait state for address setup</li> <li>0 = Data RAM accesses from CPU have zero wait states for address setup</li> </ul>
bit 5-3	Unimplemented: Read as '0'
bit 2-0	BMXARB<2:0>: Bus Matrix Arbitration Mode bits
	111 = Reserved (using these Configuration modes will produce undefined behavior)
	•
	•
	<ul><li>011 = Reserved (using these Configuration modes will produce undefined behavior)</li><li>010 = Arbitration Mode 2</li></ul>
	001 = Arbitration Mode 1 (default) 000 = Arbitration Mode 0

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
24.04	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
31:24	—	—	_	—	—		_	
00.40	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
23:16	—	—	—	—	—	—	—	—
45.0	R/W-0	R/W-0	R-0	R-0	R-0	U-0	U-0	U-0
15:8	WR	WREN	WRERR <sup>(1)</sup>	LVDERR <sup>(1)</sup>	LVDSTAT <sup>(1)</sup>		_	
7.0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
7:0	_	—		—		NVMOF	P<3:0>	

#### REGISTER 5-1: NVMCON: PROGRAMMING CONTROL REGISTER

## Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, re-	ad as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-16 Unimplemented: Read as '0'

011 31-10	Unimplemented. Read as 0
bit 15	WR: Write Control bit
	This bit is writable when WREN = 1 and the unlock sequence is followed.
	1 = Initiate a Flash operation. Hardware clears this bit when the operation completes
	0 = Flash operation is complete or inactive
bit 14	WREN: Write Enable bit
	This is the only bit in this register reset by a device Reset.
	1 = Enable writes to WR bit and enables LVD circuit
	0 = Disable writes to WR bit and disables LVD circuit
bit 13	WRERR: Write Error bit <sup>(1)</sup>
	This bit is read-only and is automatically set by hardware.
	1 = Program or erase sequence did not complete successfully
	0 = Program or erase sequence completed normally
bit 12	LVDERR: Low-Voltage Detect Error bit (LVD circuit must be enabled) <sup>(1)</sup>
	This bit is read-only and is automatically set by hardware.
	1 = Low-voltage detected (possible data corruption, if WRERR is set)
	0 = Voltage level is acceptable for programming
bit 11	LVDSTAT: Low-Voltage Detect Status bit (LVD circuit must be enabled) <sup>(1)</sup>
	This bit is read-only and is automatically set and cleared by the hardware.
	1 = Low-voltage event is active
hit 10 1	0 = Low-voltage event is not active
bit 10-4 bit 3-0	Unimplemented: Read as '0'
0-6 110	<b>NVMOP&lt;3:0&gt;:</b> NVM Operation bits These bits are writable when WREN = 0.
	1111 = Reserved
	•
	•
	0111 = Reserved 0110 = No operation
	0101 = Program Flash Memory (PFM) erase operation: erases PFM, if all pages are not write-protected
	0100 = Page erase operation: erases page selected by NVMADDR, if it is not write-protected
	0011 = Row program operation: programs row selected by NVMADDR, if it is not write-protected
	0010 = No operation
	0001 = Word program operation: programs word selected by NVMADDR, if it is not write-protected 0000 = No operation

**Note 1:** This bit is cleared by setting NVMOP == `b0000, and initiating a Flash operation (i.e., WR).

## 9.0 DIRECT MEMORY ACCESS (DMA) CONTROLLER

Note: This data sheet summarizes the features of the PIC32MX1XX/2XX 28/36/44-pin Family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to Section 31. "Direct Memory Access (DMA) Controller" (DS60001117), which is available from the Documentation > Reference Manual section of the Microchip PIC32 web site (www.microchip.com/pic32).

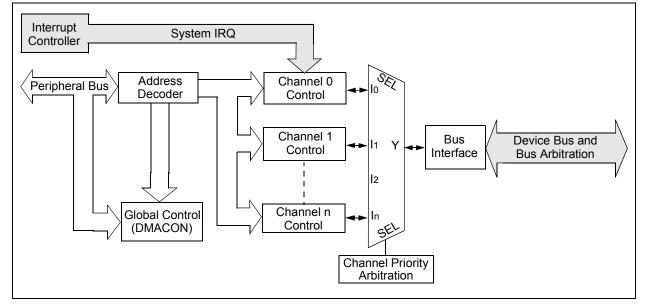
The PIC32 Direct Memory Access (DMA) controller is a bus master module useful for data transfers between different devices without CPU intervention. The source and destination of a DMA transfer can be any of the memory mapped modules existent in the PIC32, such as Peripheral Bus devices: SPI, UART, PMP, etc., or memory itself. Figure 9-1 show a block diagram of the DMA Controller module.

The DMA Controller module has the following key features:

- Four identical channels, each featuring:
  - Auto-increment source and destination address registers
  - Source and destination pointers
  - Memory to memory and memory to peripheral transfers
- Automatic word-size detection:
  - Transfer granularity, down to byte level
  - Bytes need not be word-aligned at source and destination

#### FIGURE 9-1: DMA BLOCK DIAGRAM

- Fixed priority channel arbitration
- · Flexible DMA channel operating modes:
  - Manual (software) or automatic (interrupt) DMA requests
  - One-Shot or Auto-Repeat Block Transfer modes
  - Channel-to-channel chaining
- · Flexible DMA requests:
  - A DMA request can be selected from any of the peripheral interrupt sources
  - Each channel can select any (appropriate) observable interrupt as its DMA request source
  - A DMA transfer abort can be selected from any of the peripheral interrupt sources
  - Pattern (data) match transfer termination
- · Multiple DMA channel status interrupts:
  - DMA channel block transfer complete
  - Source empty or half empty
  - Destination full or half full
  - DMA transfer aborted due to an external event
  - Invalid DMA address generated
- DMA debug support features:
  - Most recent address accessed by a DMA channel
  - Most recent DMA channel to transfer data
- · CRC Generation module:
  - CRC module can be assigned to any of the available channels
  - CRC module is highly configurable



## 11.4 Ports Control Registers

## TABLE 11-3: PORTA REGISTER MAP

ess		0								Bits	6								6
Virtual Address (BF88_#)	Register Name <sup>(1)</sup>	Bit Range	31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	All Resets
6000 ANSEL	ANSELA	31:16	_	—	—	—	_	_	_	_	—		_	_	_	—	—	_	0000
		15:0	_	—	—	—	—	-			—	_	_	—	_	_	ANSA1	ANSA0	0003
6010	TRISA	31:16	_	—	—	—	—	—			—	_	_		—	_	_	—	0000
0010		15:0	—	—	—	—	_	TRISA10 <sup>(2)</sup>	TRISA9 <sup>(2)</sup>	TRISA8 <sup>(2)</sup>	TRISA7 <sup>(2)</sup>	_	—	TRISA4	TRISA3	TRISA2	TRISA1	TRISA0	079F
6020	PORTA	31:16	—	—	—	—	_	—	—	_	—	_	—						0000
0020	1 01(1)(	15:0	—	—	—	—	_	RA10 <sup>(2)</sup>	RA9 <sup>(2)</sup>	RA8 <sup>(2)</sup>	RA7 <sup>(2)</sup>	_	—	RA4	RA3	RA2	RA1	RA0	xxxx
6030	LATA	31:16	_	—	—	—	_		_	_	—	—	—	_	_	_		_	0000
0000		15:0	—	—	—	—	—	LATA10 <sup>(2)</sup>	LATA9 <sup>(2)</sup>	LATA8 <sup>(2)</sup>	LATA7 <sup>(2)</sup>	—	—	LATA4	LATA3	LATA2	LATA1	LATA0	xxxx
6040	ODCA	31:16	—	—	—	—	—	—	_	_	—	—	—	—		—			0000
0040	ODOA	15:0	—	—	—	—	—	ODCA10 <sup>(2)</sup>	ODCA9 <sup>(2)</sup>	ODCA8 <sup>(2)</sup>	ODCA7 <sup>(2)</sup>	—	—	ODCA4	ODCA3	ODCA2	ODCA1	ODCA0	0000
6050	CNPUA	31:16	—	—	—	—	—	—	_	_	—	—	—	—		—			0000
0030	CINFUA	15:0	_	_	—	—	_	CNPUA10 <sup>(2)</sup>	CNPUA9 <sup>(2)</sup>	CNPUA8 <sup>(2)</sup>	CNPUA7 <sup>(2)</sup>	_	—	CNPUA4	CNPUA3	CNPUA2	CNPUA1	CNPUA0	0000
6060	CNPDA	31:16	—	—	—	—		_				—	—			—			0000
0000	CINFDA	15:0	_	_	—	—	_	CNPDA10 <sup>(2)</sup>	CNPDA9 <sup>(2)</sup>	CNPDA8 <sup>(2)</sup>	CNPDA7 <sup>(2)</sup>	_	—	CNPDA4	CNPDA3	CNPDA2	CNPDA1	CNPDA0	0000
6070	CNCONA	31:16	—	—	—	—		_		_	_	—	—			—			0000
0070	CINCONA	15:0	ON	—	SIDL	—	_	_	_	_	—	_	_	_	—	—	—	—	0000
6080	CNENA	31:16	_	—	—	—	_	_	_	_	—	_	—	—	_	_	_	_	0000
0000	CINEINA	15:0	_	_	—	—		CNIEA10 <sup>(2)</sup>	CNIEA9 <sup>(2)</sup>	CNIEA8 <sup>(2)</sup>	CNIEA7 <sup>(2)</sup>			CNIEA4	CNIEA3	CNIEA2	CNIEA1	CNIEA0	0000
6000	CNISTATA	31:16	_	_	—	—					_		_			—	_		0000
0090	CNSTATA	15:0	_	_	—	—		CNSTATA10 <sup>(2)</sup>	CNSTATA9(2)	CNSTATA8 <sup>(2)</sup>	CNSTATA7 <sup>(2)</sup>			CNSTATA4	CNSTATA3	CNSTATA2	CNSTATA1	CNSTATA0	0000

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: All registers in this table have corresponding CLR, SET and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively. See Section 11.2 "CLR, SET and INV Registers" for more information.

2: This bit is only available on 44-pin devices.

## 14.0 WATCHDOG TIMER (WDT)

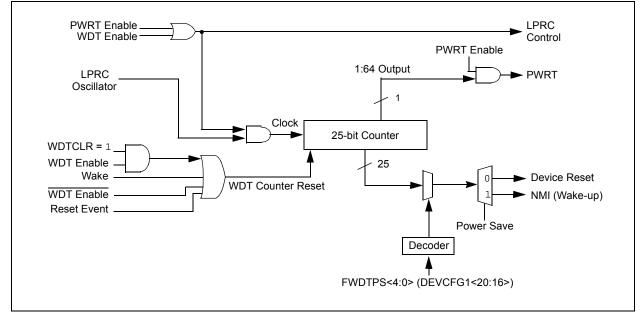
Note: This data sheet summarizes the features of the PIC32MX1XX/2XX 28/36/44-pin Family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to Section 9. "Watchdog, Deadman, and Power-up Timers" (DS60001114), which are available from the Documentation > Reference Manual section of the Microchip PIC32 web site (www.microchip.com/pic32). The WDT, when enabled, operates from the internal Low-Power Oscillator (LPRC) clock source and can be used to detect system software malfunctions by resetting the device if the WDT is not cleared periodically in software. Various WDT time-out periods can be selected using the WDT postscaler. The WDT can also be used to wake the device from Sleep or Idle mode.

The following are some of the key features of the WDT module:

- · Configuration or software controlled
- User-configurable time-out period
- Can wake the device from Sleep or Idle mode

Figure 14-1 illustrates a block diagram of the WDT and Power-up timer.

## FIGURE 14-1: WATCHDOG TIMER AND POWER-UP TIMER BLOCK DIAGRAM



#### 15.1 **Input Capture Control Registers**

	ABLE 15-1: INPUT CAPTURE 1-INPUT CAPTURE 5 REGISTER MAP																
ess										Bi	ts						
Virtual Address (BF80_#)	Register Name	Bit Range	31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1
	IC1CON <sup>(1)</sup>	31:16		_	—	—	—	—	_	—	—	—		—	—	—	—
2000		15:0	ON	—	SIDL	—	—	—	FEDGE	C32	ICTMR	ICI<	1:0>	ICOV	ICBNE		ICM<2:0>
2010	010 IC1BUF 31:16 15:0 IC1BUF<31:0>																
2200	IC2CON <sup>(1)</sup>	31:16		—	_	—	—	—	—	—	_	—	_	—	_	—	—
	1020011	15:0	ON	—	SIDL	—		—	FEDGE	C32	ICTMR	ICI<	1:0>	ICOV	ICBNE		ICM<2:0>
2210	IC2BUF	31:16 15:0		IC2BUF<31:0>													
2400	IC3CON <sup>(1)</sup>	31:16		_	—	_	-	_	—	_	—	-	_	—	_	_	—
2400	1030011	15:0	ON	—	SIDL	—		—	FEDGE	C32	ICTMR	ICI<	1:0>	ICOV	ICBNE		ICM<2:0>
2410	IC3BUF	31:16 15:0								IC3BUF	<31:0>						
2600	IC4CON <sup>(1)</sup>	31:16	-	_	—	_	-	_	—	—	_	_	_	—	—	_	—
2000	1040010	15:0	ON	—	SIDL	—		—	FEDGE	C32	ICTMR	ICI<	1:0>	ICOV	ICBNE		ICM<2:0>
2610 IC4BUF 31:16 15:0 IC4BUF<31:0>																	
2800	IC5CON <sup>(1)</sup>	31:16	-	_	—	_	-	_	—	—	_	_	_	—	—	_	—
2000	1030011	15:0	ON	—	SIDL	—	—	—	FEDGE	C32	ICTMR	ICI<	1:0>	ICOV	ICBNE		ICM<2:0>
2810	IC5BUF	31:16 15:0								IC5BUF	<31:0>						

#### Т

Legend:

This register has corresponding CLR, SET and INV registers at its virtual address, plus an offset of 0x4, 0x8 and 0xC, respectively. See Section 11.2 "CLR, SET and INV Registers" for more information. Note 1:

All Resets

0000

0000 xxxx xxxx 0000 0000 xxxx xxxx 0000 0000 xxxx xxxx 0000 0000 xxxx xxxx 0000 0000 xxxx xxxx

16/0

—

# PIC32MX1XX/2XX 28/36/44-PIN FAMILY

#### REGISTER 17-2: SPIxCON2: SPI CONTROL REGISTER 2

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
31.24	—	—	—	—	—	—	_	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
23.10	—	—	—	—	—	—	_	—
15:8	R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
10.0	SPISGNEXT	—	—	FRMERREN	SPIROVEN	SPITUREN	IGNROV	IGNTUR
7:0	R/W-0	U-0	U-0	U-0	R/W-0	U-0	R/W-0	R/W-0
7:0	AUDEN <sup>(1)</sup>	_	_	—	AUDMONO <sup>(1,2)</sup>	—	AUDMOD	)<1:0> <sup>(1,2)</sup>

#### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'				
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown			

bit 31-16 Unimplemented: Read as '0'

- bit 15 SPISGNEXT: Sign Extend Read Data from the RX FIFO bit
  - 1 = Data from RX FIFO is sign extended
  - 0 = Data from RX FIFO is not sign extended
- bit 14-13 Unimplemented: Read as '0'
- bit 12 **FRMERREN:** Enable Interrupt Events via FRMERR bit
  - 1 = Frame Error overflow generates error events
  - 0 = Frame Error does not generate error events
- bit 11 SPIROVEN: Enable Interrupt Events via SPIROV bit
  - 1 = Receive overflow generates error events
    - 0 = Receive overflow does not generate error events
- bit 10 SPITUREN: Enable Interrupt Events via SPITUR bit
  - 1 = Transmit underrun generates error events
  - 0 = Transmit underrun does not generate error events
- bit 9 IGNROV: Ignore Receive Overflow bit (for Audio Data Transmissions)
  - 1 = A ROV is not a critical error; during ROV data in the FIFO is not overwritten by receive data
     0 = A ROV is a critical error that stops SPI operation
- bit 8 **IGNTUR:** Ignore Transmit Underrun bit (for Audio Data Transmissions)
  - 1 = A TUR is not a critical error and zeros are transmitted until the SPIxTXB is not empty
  - 0 = A TUR is a critical error that stops SPI operation
- bit 7 AUDEN: Enable Audio CODEC Support bit<sup>(1)</sup>
- 1 = Audio protocol enabled
  - 0 = Audio protocol disabled
- bit 6-5 Unimplemented: Read as '0'
- bit 3 AUDMONO: Transmit Audio Data Format bit<sup>(1,2)</sup>
  - 1 = Audio data is mono (Each data word is transmitted on both left and right channels)
  - 0 = Audio data is stereo
- bit 2 Unimplemented: Read as '0'
- bit 1-0 AUDMOD<1:0>: Audio Protocol Mode bit<sup>(1,2)</sup>
  - 11 = PCM/DSP mode
  - 10 = Right-Justified mode
  - 01 = Left-Justified mode
  - $00 = I^2S \mod$
- **Note 1:** This bit can only be written when the ON bit = 0.
  - **2:** This bit is only valid for AUDEN = 1.

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
24.24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
31:24	—	—	—	_	_	_	-	_
00.40	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
23:16	—	—	—	_	_	_	-	_
45.0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
15:8	0N <sup>(1)</sup>	_	SIDL	ADRMU	JX<1:0>	PMPTTL	PTWREN	PTRDEN
7.0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	U-0	R/W-0	R/W-0
7:0	CSF<	1:0> <b>(2)</b>	ALP <sup>(2)</sup>	_	CS1P <sup>(2)</sup>	_	WRSP	RDSP

#### REGISTER 20-1: PMCON: PARALLEL PORT CONTROL REGISTER

#### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, r	ead as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

#### bit 31-16 Unimplemented: Read as '0'

- bit 15 **ON:** Parallel Master Port Enable bit<sup>(1)</sup>
  - 1 = PMP enabled
  - 0 = PMP disabled, no off-chip access performed
- bit 14 Unimplemented: Read as '0'
- bit 13 **SIDL:** Stop in Idle Mode bit
  - 1 = Discontinue module operation when the device enters Idle mode
  - 0 = Continue module operation when the device enters Idle mode
- bit 12-11 ADRMUX<1:0>: Address/Data Multiplexing Selection bits
  - 11 = Lower 8 bits of address are multiplexed on PMD<7:0> pins; upper 8 bits are not used
  - 10 = All 16 bits of address are multiplexed on PMD<7:0> pins
  - 01 = Lower 8 bits of address are multiplexed on PMD<7:0> pins, upper bits are on PMA<10:8> and PMA<14>
  - 00 = Address and data appear on separate pins
- bit 10 **PMPTTL:** PMP Module TTL Input Buffer Select bit
  - 1 = PMP module uses TTL input buffers
  - 0 = PMP module uses Schmitt Trigger input buffer
- bit 9 **PTWREN:** Write Enable Strobe Port Enable bit
  - 1 = PMWR/PMENB port enabled
  - 0 = PMWR/PMENB port disabled
- bit 8 PTRDEN: Read/Write Strobe Port Enable bit
  - 1 = PMRD/PMWR port enabled
  - 0 = PMRD/PMWR port disabled
- bit 7-6 CSF<1:0>: Chip Select Function bits<sup>(2)</sup>
  - 11 = Reserved
  - 10 = PMCS1 functions as Chip Select
  - 01 = PMCS1 functions as PMA<14>
  - 00 = PMCS1 functions as PMA<14>
- bit 5 ALP: Address Latch Polarity bit<sup>(2)</sup>
  - 1 = Active-high (PMALL and PMALH)
  - $0 = \text{Active-low} (\overline{\text{PMALL}} \text{ and } \overline{\text{PMALH}})$
  - **Note 1:** When using 1:1 PBCLK divisor, the user's software should not read/write the peripheral's SFRs in the SYSCLK cycle immediately following the instruction that clears the module's ON control bit.
    - 2: These bits have no effect when their corresponding pins are used as address lines.

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
04.04	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
31:24	_	_	_	—	—	_	—	—
00.40	U-0	U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
23:16		—	_	MONTH10		MONTH	01<3:0>	
45.0	U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
15:8		_	DAY1	0<1:0>		DAY01	<3:0>	
7.0	U-0	U-0	U-0	U-0	U-0	R/W-x	R/W-x	R/W-x
7:0	—	_	_	_	—	V	VDAY01<2:0	>

## REGISTER 21-6: ALRMDATE: ALARM DATE VALUE REGISTER

## Legend:

Legena:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, r	ead as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-21 Unimplemented: Read as '0'

bit 20 MONTH10: Binary Coded Decimal value of months bits, 10s place digit; contains a value of 0 or 1

bit 19-16 **MONTH01<3:0>:** Binary Coded Decimal value of months bits, 1s place digit; contains a value from 0 to 9 bit 15-14 **Unimplemented:** Read as '0'

bit 13-12 DAY10<1:0>: Binary Coded Decimal value of days bits, 10s place digit; contains a value from 0 to 3

bit 11-8 **DAY01<3:0>:** Binary Coded Decimal value of days bits, 1s place digit; contains a value from 0 to 9

bit 7-3 Unimplemented: Read as '0'

bit 2-0 WDAY01<2:0>: Binary Coded Decimal value of weekdays bits; contains a value from 0 to 6

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
51.24	_	—		—	_		-	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
23.10	_	—		—	_	_	_	—
15:8	U-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
15.6	-	—	SIDL	—	_	_		—
7:0	U-0	U-0	U-0	U-0	U-0	R-0	R-0	R-0
7.0					_	C3OUT	C2OUT	C10UT

## REGISTER 23-2: CMSTAT: COMPARATOR STATUS REGISTER

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, re	ead as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

#### bit 31-14 Unimplemented: Read as '0'

#### bit 13 SIDL: Stop in Idle Control bit

1 = All Comparator modules are disabled when the device enters Idle mode

0 = All Comparator modules continue to operate when the device enters Idle mode

#### bit 12-3 Unimplemented: Read as '0'

#### bit 2 C3OUT: Comparator Output bit

- 1 = Output of Comparator 3 is a '1'
- 0 = Output of Comparator 3 is a '0'

#### bit 1 C2OUT: Comparator Output bit

- 1 = Output of Comparator 2 is a '1'
- 0 = Output of Comparator 2 is a '0'

#### bit 0 **C1OUT:** Comparator Output bit

- 1 = Output of Comparator 1 is a '1'
- 0 = Output of Comparator 1 is a '0'

The processor will exit, or 'wake-up', from Sleep on one of the following events:

- On any interrupt from an enabled source that is operating in Sleep. The interrupt priority must be greater than the current CPU priority.
- · On any form of device Reset
- On a WDT time-out

If the interrupt priority is lower than or equal to the current priority, the CPU will remain Halted, but the PBCLK will start running and the device will enter into Idle mode.

## 26.3.2 IDLE MODE

In Idle mode, the CPU is Halted but the System Clock (SYSCLK) source is still enabled. This allows peripherals to continue operation when the CPU is Halted. Peripherals can be individually configured to Halt when entering Idle by setting their respective SIDL bit. Latency, when exiting Idle mode, is very low due to the CPU oscillator source remaining active.

- Note 1: Changing the PBCLK divider ratio requires recalculation of peripheral timing. For example, assume the UART is configured for 9600 baud with a PB clock ratio of 1:1 and a Posc of 8 MHz. When the PB clock divisor of 1:2 is used, the input frequency to the baud clock is cut in half; therefore, the baud rate is reduced to 1/2 its former value. Due to numeric truncation in calculations (such as the baud rate divisor), the actual baud rate may be a tiny percentage different than expected. For this reason, any timing calculation required for a peripheral should be performed with the new PB clock frequency instead of scaling the previous value based on a change in the PB divisor ratio.
  - 2: Oscillator start-up and PLL lock delays are applied when switching to a clock source that was disabled and that uses a crystal and/or the PLL. For example, assume the clock source is switched from Posc to LPRC just prior to entering Sleep in order to save power. No oscillator startup delay would be applied when exiting Idle. However, when switching back to Posc, the appropriate PLL and/or oscillator start-up/lock delays would be applied.

The device enters Idle mode when the SLPEN (OSCCON<4>) bit is clear and a WAIT instruction is executed.

The processor will wake or exit from Idle mode on the following events:

- On any interrupt event for which the interrupt source is enabled. The priority of the interrupt event must be greater than the current priority of the CPU. If the priority of the interrupt event is lower than or equal to current priority of the CPU, the CPU will remain Halted and the device will remain in Idle mode.
- On any form of device Reset
- On a WDT time-out interrupt

### 26.3.3 PERIPHERAL BUS SCALING METHOD

Most of the peripherals on the device are clocked using the PBCLK. The Peripheral Bus can be scaled relative to the SYSCLK to minimize the dynamic power consumed by the peripherals. The PBCLK divisor is controlled by PBDIV<1:0> (OSCCON<20:19>), allowing SYSCLK to PBCLK ratios of 1:1, 1:2, 1:4 and 1:8. All peripherals using PBCLK are affected when the divisor is changed. Peripherals such as the USB, Interrupt Controller, DMA, and the bus matrix are clocked directly from SYSCLK. As a result, they are not affected by PBCLK divisor changes.

Changing the PBCLK divisor affects:

- The CPU to peripheral access latency. The CPU has to wait for next PBCLK edge for a read to complete. In 1:8 mode, this results in a latency of one to seven SYSCLKs.
- The power consumption of the peripherals. Power consumption is directly proportional to the frequency at which the peripherals are clocked. The greater the divisor, the lower the power consumed by the peripherals.

To minimize dynamic power, the PB divisor should be chosen to run the peripherals at the lowest frequency that provides acceptable system performance. When selecting a PBCLK divider, peripheral clock requirements, such as baud rate accuracy, should be taken into account. For example, the UART peripheral may not be able to achieve all baud rate values at some PBCLK divider depending on the SYSCLK value.

## TABLE 26-2: PERIPHERAL MODULE DISABLE REGISTER MAP

ess				Bits									6						
Virtual Address (BF80_#)	Register Name <sup>(1)</sup>	Bit Range	31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	All Resets
5040	PMD1	31:16	—	—	_	—	_	_	_	—	—	—	—	—	—	—	—	—	0000
F240	FIVIDI	15:0	-			CVRMD	Ι			CTMUMD	—	-		-	—		—	AD1MD	0000
5250	PMD2	31:16	—	—		—	_	_		—	—	—	—	—	—	—	—	—	0000
F250	FIVIDZ	15:0	-			—				—	—	-		-	—	CMP3MD	CMP2MD	CMP1MD	0000
F260	PMD3	31:16	_			_	-			_	_		_	OC5MD	OC4MD	OC3MD	OC2MD	OC1MD	0000
F200	FIVIDS	15:0	_			_	-			_	_		_	IC5MD	IC4MD	IC3MD	IC2MD	IC1MD	0000
F270	PMD4	31:16	_			_	-			_	_		_	-	_	_	—	_	0000
F270	F IVID4	15:0	_			_	-			_	_		_	T5MD	T4MD	T3MD	T2MD	T1MD	0000
F280	PMD5	31:16	_			_	-			USB1MD	_		_	-	_	_	I2C1MD	I2C1MD	0000
F200	FIVIDS	15:0	_			_	-		SPI2MD	SPI1MD	_		_	-	_	_	U2MD	U1MD	0000
F200	PMD6	31:16	_	—		—	_	_		_	—	_	—	—	—	—	—	PMPMD	0000
F290	I WD0	15:0	—	_	_	—	_	_	-	—	—	_	_	_	—	_	REFOMD	RTCCMD	0000

Legend: x = unknown value on Reset; -- = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: All registers in this table have corresponding CLR, SET and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively. See Section 11.2 "CLR, SET and INV Registers" for more information.

# PIC32MX1XX/2XX 28/36/44-PIN FAMILY

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0	
04.04	r-1	r-1	r-1	r-1	r-1	r-1	r-1	r-1	
31:24	—			-	_		_	-	
00.40	r-1	r-1	r-1	r-1	r-1	R/P	R/P	R/P	
23:16	—	_	—	-	—	FI	PLLODIV<2:(	LLODIV<2:0>	
45.0	R/P	r-1	r-1	r-1	r-1	R/P	R/P	R/P	
15:8	UPLLEN <sup>(1)</sup>	N <sup>(1)</sup>		_	_	UF	PLLIDIV<2:0>	.(1)	
7.0	r-1	R/P-1	R/P	R/P-1	r-1	R/P	R/P	R/P	
7:0	— FPLLMUL<2:0>				_	F	PLLIDIV<2:0	>	

#### **DEVCFG2: DEVICE CONFIGURATION WORD 2 REGISTER 27-3:**

Legend:	r = Reserved bit	P = Programmable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared x = Bit is unknown

#### bit 31-19 Reserved: Write '1'

bit 15

bit 7

bit 18-16 FPLLODIV<2:0>: Default PLL Output Divisor bits

- 111 = PLL output divided by 256 110 = PLL output divided by 64 101 = PLL output divided by 32 100 = PLL output divided by 16 011 = PLL output divided by 8 010 = PLL output divided by 4 001 = PLL output divided by 2 000 = PLL output divided by 1 UPLLEN: USB PLL Enable bit<sup>(1)</sup> 1 = Disable and bypass USB PLL 0 = Enable USB PLL bit 14-11 Reserved: Write '1' bit 10-8 UPLLIDIV<2:0>: USB PLL Input Divider bits<sup>(1)</sup> 111 = 12x divider 110 = 10x divider 101 = 6x divider100 = 5x divider 011 = 4x divider 010 = 3x divider 010 = 3x divider 001 = 2x divider000 = 1x divider Reserved: Write '1'
- bit 6-4 FPLLMUL<2:0>: PLL Multiplier bits
  - 111 = 24x multiplier 110 = 21x multiplier
  - 101 = 20x multiplier
  - 100 = 19x multiplier
  - 011 = 18x multiplier
  - 010 = 17x multiplier
  - 001 = 16x multiplier
  - 000 = 15x multiplier
- bit 3 Reserved: Write '1'

Note 1: This bit is only available on PIC32MX2XX devices.

## 29.0 DEVELOPMENT SUPPORT

The PIC<sup>®</sup> microcontrollers (MCU) and dsPIC<sup>®</sup> digital signal controllers (DSC) are supported with a full range of software and hardware development tools:

- Integrated Development Environment
- MPLAB<sup>®</sup> X IDE Software
- Compilers/Assemblers/Linkers
  - MPLAB XC Compiler
  - MPASM<sup>™</sup> Assembler
  - MPLINK<sup>™</sup> Object Linker/ MPLIB<sup>™</sup> Object Librarian
  - MPLAB Assembler/Linker/Librarian for Various Device Families
- Simulators
  - MPLAB X SIM Software Simulator
- Emulators
  - MPLAB REAL ICE™ In-Circuit Emulator
- In-Circuit Debuggers/Programmers
  - MPLAB ICD 3
  - PICkit™ 3
- Device Programmers
  - MPLAB PM3 Device Programmer
- Low-Cost Demonstration/Development Boards, Evaluation Kits and Starter Kits
- Third-party development tools

## 29.1 MPLAB X Integrated Development Environment Software

The MPLAB X IDE is a single, unified graphical user interface for Microchip and third-party software, and hardware development tool that runs on Windows<sup>®</sup>, Linux and Mac OS<sup>®</sup> X. Based on the NetBeans IDE, MPLAB X IDE is an entirely new IDE with a host of free software components and plug-ins for high-performance application development and debugging. Moving between tools and upgrading from software simulators to hardware debugging and programming tools is simple with the seamless user interface.

With complete project management, visual call graphs, a configurable watch window and a feature-rich editor that includes code completion and context menus, MPLAB X IDE is flexible and friendly enough for new users. With the ability to support multiple tools on multiple projects with simultaneous debugging, MPLAB X IDE is also suitable for the needs of experienced users.

Feature-Rich Editor:

- · Color syntax highlighting
- Smart code completion makes suggestions and provides hints as you type
- Automatic code formatting based on user-defined rules
- · Live parsing

User-Friendly, Customizable Interface:

- Fully customizable interface: toolbars, toolbar buttons, windows, window placement, etc.
- Call graph window
- Project-Based Workspaces:
- Multiple projects
- Multiple tools
- · Multiple configurations
- · Simultaneous debugging sessions

File History and Bug Tracking:

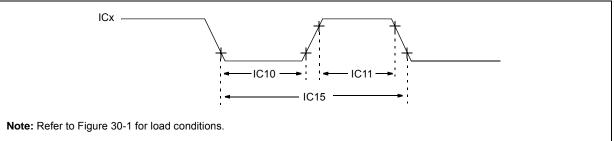
- · Local file history feature
- Built-in support for Bugzilla issue tracker

## TABLE 30-24: TIMER2, 3, 4, 5 EXTERNAL CLOCK TIMING REQUIREMENTS

AC CHA	ARACTERIS	TICS		(unless	Standard Operating Conditions: 2.3V to 3.6V(unless otherwise stated)Operating temperature $-40^{\circ}C \le TA \le +85^{\circ}C$ for Industrial $-40^{\circ}C \le TA \le +105^{\circ}C$ for V-temp						
Param. No.	Symbol	Characteristics <sup>(1)</sup>			Min.	Max. Units Condition		ions			
TB10	ТтхН	TxCK High Time	Synchron prescaler	ous, with	[(12.5 ns or 1 TPB)/N] + 25 ns	—	ns	Must also meet parameter TB15	value (1, 2, 4, 8,		
TB11	ΤτχL	TxCK Low Time	Synchron prescaler	ous, with	[(12.5 ns or 1 ТРВ)/N] + 25 ns	_	ns	Must also meet parameter TB15	16, 32, 64, 256)		
TB15	ΤτχΡ	TxCK Input	Synchrono prescaler	ous, with	[(Greater of [(25 ns or 2 Трв)/N] + 30 ns	-	ns	VDD > 2.7V			
		Period			[(Greater of [(25 ns or 2 ТРВ)/N] + 50 ns	—	ns	VDD < 2.7V			
TB20	TCKEXTMRL	Delay from Clock Edge				1	Трв	_			

Note 1: These parameters are characterized, but not tested in manufacturing.

## FIGURE 30-7: INPUT CAPTURE (CAPx) TIMING CHARACTERISTICS



#### TABLE 30-25: INPUT CAPTURE MODULE TIMING REQUIREMENTS

AC CHARACTERISTICS			(unless oth	$\begin{array}{l} \mbox{Standard Operating Conditions: 2.3V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +105^{\circ}C \mbox{ for V-temp} \end{array}$							
Param. No.	Symbol	I Characteristics <sup>(1)</sup>		Min.	Max.	Units	Con	ditions			
IC10	TccL	ICx Input	Low Time	[(12.5 ns or 1 ТРВ)/N] + 25 ns	_	ns	Must also meet parameter IC15.	N = prescale value (1, 4, 16)			
IC11	ТссН	ICx Input High Time		Time [(12.5 ns or 1 TPB)/N] + 25 ns		ns	Must also meet parameter IC15.				
IC15	TCCP	ICx Input	Period	[(25 ns or 2 Трв)/N] + 50 ns	_	ns	—				

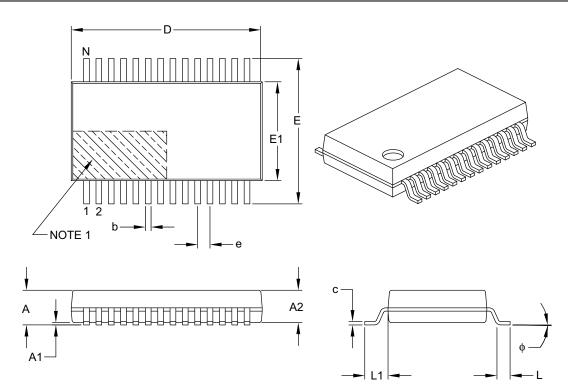
Note 1:	These parameters are	characterized, but not	t tested in manufacturing.
---------	----------------------	------------------------	----------------------------

## 33.2 Package Details

This section provides the technical details of the packages.

## 28-Lead Plastic Shrink Small Outline (SS) – 5.30 mm Body [SSOP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units		MILLIMETERS		
	Dimension Limits	MIN	NOM	MAX	
Number of Pins	N	28			
Pitch	e	0.65 BSC			
Overall Height	A	-	-	2.00	
Molded Package Thickness	A2	1.65	1.75	1.85	
Standoff	A1	0.05	-	-	
Overall Width	E	7.40	7.80	8.20	
Molded Package Width	E1	5.00	5.30	5.60	
Overall Length	D	9.90	10.20	10.50	
Foot Length	L	0.55	0.75	0.95	
Footprint	L1	1.25 REF			
Lead Thickness	С	0.09	-	0.25	
Foot Angle	φ	0°	4°	8°	
Lead Width	b	0.22	-	0.38	

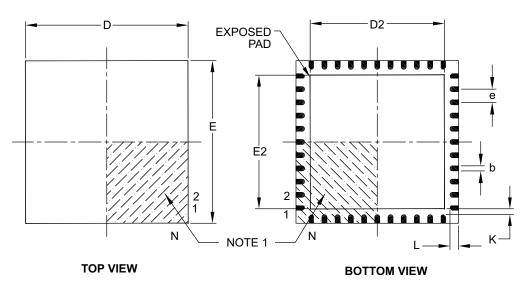
#### Notes:

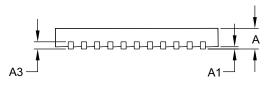
- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.20 mm per side.
   Dimensioning and tolerancing per ASME Y14.5M.
  - BSC: Basic Dimension. Theoretically exact value shown without tolerances.
  - REF: Reference Dimension, usually without tolerance, for information purposes only.

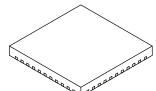
Microchip Technology Drawing C04-073B

## 44-Lead Plastic Quad Flat, No Lead Package (ML) – 8x8 mm Body [QFN]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging







	Units	MILLIMETERS		
	Dimension Limits	MIN	NOM	MAX
Number of Pins	N	44		
Pitch	е	0.65 BSC		
Overall Height	A	0.80	0.90	1.00
Standoff	A1	0.00	0.02	0.05
Contact Thickness	A3		0.20 REF	
Overall Width	E		8.00 BSC	
Exposed Pad Width	E2	6.30	6.45	6.80
Overall Length	D	8.00 BSC		
Exposed Pad Length	D2	6.30	6.45	6.80
Contact Width	b	0.25	0.30	0.38
Contact Length	L	0.30	0.40	0.50
Contact-to-Exposed Pad	К	0.20	-	-

#### Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.

2. Package is saw singulated.

- 3. Dimensioning and tolerancing per ASME Y14.5M.
  - BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-103B

# PIC32MX1XX/2XX 28/36/44-PIN FAMILY

U1OTGSTAT (USB OTG Status)	110
U1PWRC (USB Power Control)	112
U1SOF (USB SOF Threshold)	123
U1STAT (USB Status)	118
U1TOK (USB Token)	122
UxMODE (UARTx Mode)	183
UxSTA (UARTx Status and Control)	185
WDTCON (Watchdog Timer Control)	155
Resets	
Revision History	329
RTCALRM (RTC ALARM Control)	203

## S

Serial Peripheral Interface (SPI)	165
Software Simulator (MPLAB SIM)	
Special Features	239

## Т

Timer1 Module Timer2/3, Timer4/5 Modules Timing Diagrams	
10-Bit Analog-to-Digital Conversion	
(ASAM = 0, SSRC<2:0> = 000)	293
10-Bit Analog-to-Digital Conversion (ASAM = 1,	
SSRC<2:0> = 111, SAMC<4:0> = 00001)	294
EJTAG	300
External Clock	269
I/O Characteristics	272
I2Cx Bus Data (Master Mode)	283
I2Cx Bus Data (Slave Mode)	286
I2Cx Bus Start/Stop Bits (Master Mode)	283
I2Cx Bus Start/Stop Bits (Slave Mode)	286
Input Capture (CAPx)	276
OCx/PWM	
Output Compare (OCx)	277
Parallel Master Port Read	296
Parallel Master Port Write	297

Parallel Slave Port	. 295
SPIx Master Mode (CKE = 0)	. 278
SPIx Master Mode (CKE = 1)	. 279
SPIx Slave Mode (CKE = 0)	. 280
SPIx Slave Mode (CKE = 1)	. 281
Timer1, 2, 3, 4, 5 External Clock	. 275
UART Reception	. 187
UART Transmission (8-bit or 9-bit Data)	. 187
Timing Requirements	
CLKO and I/O	. 272
Timing Specifications	
I2Cx Bus Data Requirements (Master Mode)	
I2Cx Bus Data Requirements (Slave Mode)	
Input Capture Requirements	
Output Compare Requirements	
Simple OCx/PWM Mode Requirements	
SPIx Master Mode (CKE = 0) Requirements	
SPIx Master Mode (CKE = 1) Requirements	
SPIx Slave Mode (CKE = 1) Requirements	
SPIx Slave Mode Requirements (CKE = 0)	. 280
Timing Specifications (50 MHz)	
SPIx Master Mode (CKE = 0) Requirements	
SPIx Master Mode (CKE = 1) Requirements	
SPIx Slave Mode (CKE = 1) Requirements	
SPIx Slave Mode Requirements (CKE = 0)	. 305
U	
	101

UART	
USB On-The-Go (OTG)	103
V	
VCAP nin	250

VCAP pin	
Voltage Regulator (On-Chip)	250
W	
M/M/M/ Addross	2/1

WWW Address	. 341
WWW, On-Line Support	16

#### Note the following details of the code protection feature on Microchip devices:

- Microchip products meet the specification contained in their particular Microchip Data Sheet.
- Microchip believes that its family of products is one of the most secure families of its kind on the market today, when used in the intended manner and under normal conditions.
- There are dishonest and possibly illegal methods used to breach the code protection feature. All of these methods, to our knowledge, require using the Microchip products in a manner outside the operating specifications contained in Microchip's Data Sheets. Most likely, the person doing so is engaged in theft of intellectual property.
- Microchip is willing to work with the customer who is concerned about the integrity of their code.
- Neither Microchip nor any other semiconductor manufacturer can guarantee the security of their code. Code protection does not mean that we are guaranteeing the product as "unbreakable."

Code protection is constantly evolving. We at Microchip are committed to continuously improving the code protection features of our products. Attempts to break Microchip's code protection feature may be a violation of the Digital Millennium Copyright Act. If such acts allow unauthorized access to your software or other copyrighted work, you may have a right to sue for relief under that Act.

Information contained in this publication regarding device applications and the like is provided only for your convenience and may be superseded by updates. It is your responsibility to ensure that your application meets with your specifications. MICROCHIP MAKES NO REPRESENTATIONS OR WARRANTIES OF ANY KIND WHETHER EXPRESS OR IMPLIED, WRITTEN OR ORAL, STATUTORY OR OTHERWISE, RELATED TO THE INFORMATION, INCLUDING BUT NOT LIMITED TO ITS CONDITION, QUALITY, PERFORMANCE, MERCHANTABILITY OR FITNESS FOR PURPOSE. Microchip disclaims all liability arising from this information and its use. Use of Microchip devices in life support and/or safety applications is entirely at the buyer's risk, and the buyer agrees to defend, indemnify and hold harmless Microchip from any and all damages, claims, suits, or expenses resulting from such use. No licenses are conveyed, implicitly or otherwise, under any Microchip intellectual property rights unless otherwise stated.

Microchip received ISO/TS-16949:2009 certification for its worldwide headquarters, design and wafer fabrication facilities in Chandler and Tempe, Arizona; Gresham, Oregon and design centers in California and India. The Company's quality system processes and procedures are for its PIC® MCUs and dsPIC® DSCs, KEELoQ® code hopping devices, Serial EEPROMs, microperipherals, nonvolatile memory and analog products. In addition, Microchip's quality system for the design and manufacture of development systems is ISO 9001:2000 certified.

## QUALITY MANAGEMENT SYSTEM CERTIFIED BY DNV = ISO/TS 16949=

#### Trademarks

The Microchip name and logo, the Microchip logo, AnyRate, dsPIC, FlashFlex, flexPWR, Heldo, JukeBlox, KeeLoq, KeeLoq logo, Kleer, LANCheck, LINK MD, MediaLB, MOST, MOST logo, MPLAB, OptoLyzer, PIC, PICSTART, PIC32 logo, RightTouch, SpyNIC, SST, SST Logo, SuperFlash and UNI/O are registered trademarks of Microchip Technology Incorporated in the U.S.A. and other countries.

ClockWorks, The Embedded Control Solutions Company, ETHERSYNCH, Hyper Speed Control, HyperLight Load, IntelliMOS, mTouch, Precision Edge, and QUIET-WIRE are registered trademarks of Microchip Technology Incorporated in the U.S.A.

Analog-for-the-Digital Age, Any Capacitor, AnyIn, AnyOut, BodyCom, chipKIT, chipKIT logo, CodeGuard, dsPICDEM, dsPICDEM.net, Dynamic Average Matching, DAM, ECAN, EtherGREEN, In-Circuit Serial Programming, ICSP, Inter-Chip Connectivity, JitterBlocker, KleerNet, KleerNet logo, MiWi, motorBench, MPASM, MPF, MPLAB Certified logo, MPLIB, MPLINK, MultiTRAK, NetDetach, Omniscient Code Generation, PICDEM, PICDEM.net, PICkit, PICtail, PureSilicon, RightTouch logo, REAL ICE, Ripple Blocker, Serial Quad I/O, SQI, SuperSwitcher, SuperSwitcher II, Total Endurance, TSHARC, USBCheck, VariSense, ViewSpan, WiperLock, Wireless DNA, and ZENA are trademarks of Microchip Technology Incorporated in the U.S.A. and other countries.

 $\ensuremath{\mathsf{SQTP}}$  is a service mark of Microchip Technology Incorporated in the U.S.A.

Silicon Storage Technology is a registered trademark of Microchip Technology Inc. in other countries.

GestIC is a registered trademarks of Microchip Technology Germany II GmbH & Co. KG, a subsidiary of Microchip Technology Inc., in other countries.

All other trademarks mentioned herein are property of their respective companies.

© 2011-2016, Microchip Technology Incorporated, Printed in the U.S.A., All Rights Reserved.

ISBN:978-1-5224-0471-2