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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M0+
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	I ² C, LINbus, SPI, UART/USART, USB
Peripherals	Brown-out Detect/Reset, DMA, I ² S, POR, PWM, WDT
Number of I/O	52
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	1.62V ~ 3.6V
Data Converters	A/D 20x12b; D/A 1x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-UFBGA
Supplier Device Package	64-UFBGA (5x5)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/atsamd21j17a-cut

32-bit ARM-Based Microcontrollers

Device Variant	DID.DEVSEL	Device ID (DID)
Reserved	0x25	
SAMD21E16B	0x26	0x10011426 (die revision E) 0x10011526 (die revision F)
SAMD21E15B	0x27	0x10011427 (die revision E) 0x10011527 (die revision F)
Reserved	0x28-0x54	
SAMD21E16B (WLCSP)	0x55	0x10011455 (die revision E)
SAMD21E15B (WLCSP)	0x56	0x10011456 (die revision E)
Reserved	0x57 - 0x61	
SAMD21E16C (WLCSP)	0x62	0x10011562 (die revision F)
SAMD21E15C (WLCSP)	0x63	0x10011563 (die revision F)
Reserved	0x64-0xFF	

Note: The device variant (last letter of the ordering number) is independent of the die revision (DSU.DID.REVISION): The device variant denotes functional differences, whereas the die revision marks evolution of the die. The device variant denotes functional differences, whereas the die revision marks evolution of the die.

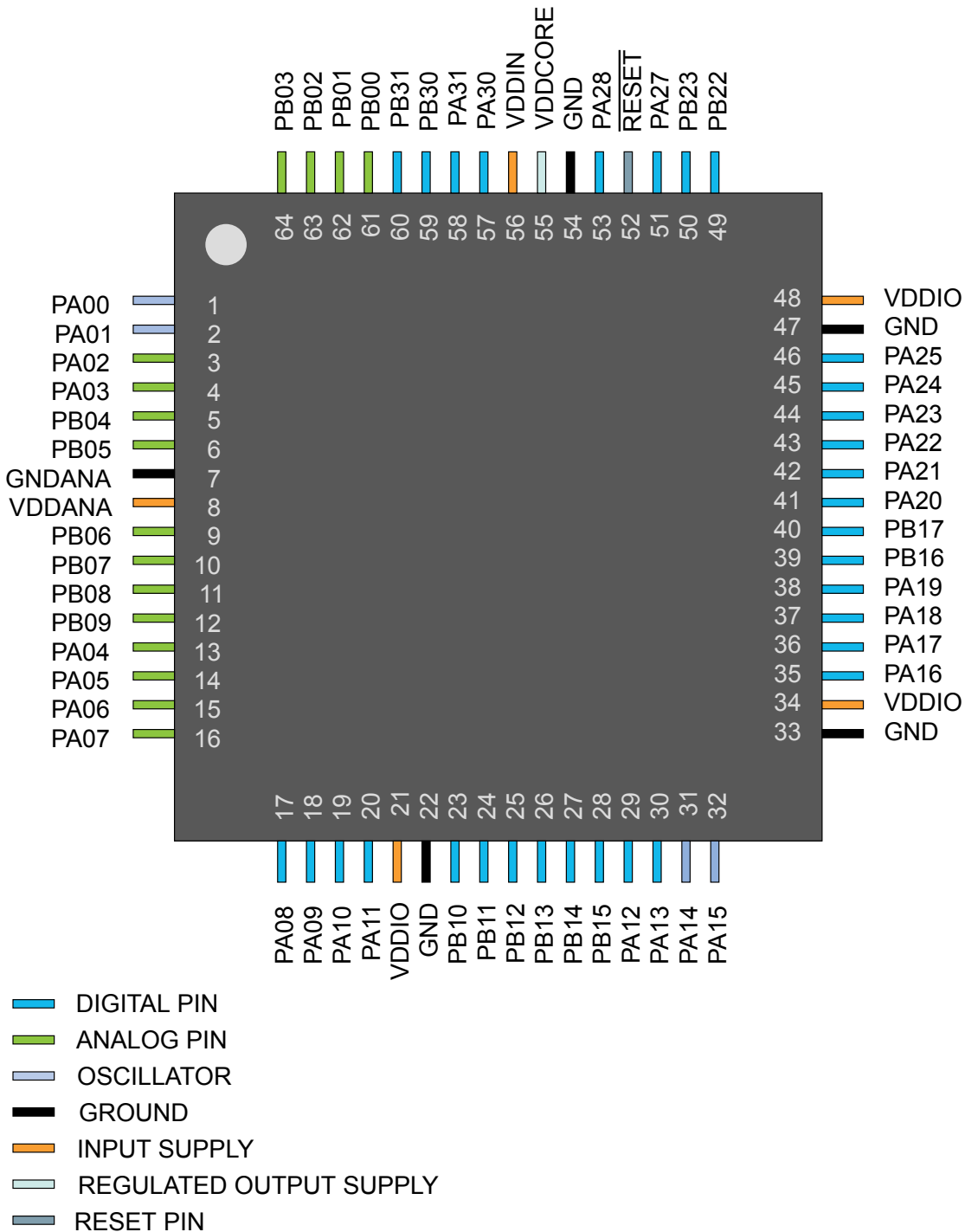
Related Links

[DID](#)

Pinout

SAM D21J

QFN64 / TQFP64



11.2.2 Interrupt Line Mapping

Each of the 28 interrupt lines is connected to one peripheral instance, as shown in the table below. Each peripheral can have one or more interrupt flags, located in the peripheral's Interrupt Flag Status and Clear (INTFLAG) register. The interrupt flag is set when the interrupt condition occurs. Each interrupt in the peripheral can be individually enabled by writing a one to the corresponding bit in the peripheral's Interrupt Enable Set (INTENSET) register, and disabled by writing a one to the corresponding bit in the peripheral's Interrupt Enable Clear (INTENCLR) register. An interrupt request is generated from the peripheral when the interrupt flag is set and the corresponding interrupt is enabled. The interrupt requests for one peripheral are ORed together on system level, generating one interrupt request for each peripheral. An interrupt request will set the corresponding interrupt pending bit in the NVIC interrupt pending registers (SETPEND/CLRPEND bits in ISPR/ICPR). For the NVIC to activate the interrupt, it must be enabled in the NVIC interrupt enable register (SETENA/CLRENA bits in ISER/ICER). The NVIC interrupt priority registers IPR0-IPR7 provide a priority field for each interrupt.

Table 11-3. Interrupt Line Mapping (Continued)

Peripheral Source	NVIC Line
EIC NMI – External Interrupt Controller	NMI
PM – Power Manager	0
SYSCTRL – System Control	1
WDT – Watchdog Timer	2
RTC – Real Time Counter	3
EIC – External Interrupt Controller	4
NVMCTRL – Non-Volatile Memory Controller	5
DMAC - Direct Memory Access Controller	6
USB - Universal Serial Bus	7
EVSYS – Event System	8
SERCOM0 – Serial Communication Interface 0	9
SERCOM1 – Serial Communication Interface 1	10
SERCOM2 – Serial Communication Interface 2	11
SERCOM3 – Serial Communication Interface 3	12
SERCOM4 – Serial Communication Interface 4	13
SERCOM5 – Serial Communication Interface 5	14
TCC0 – Timer Counter for Control 0	15
TCC1 – Timer Counter for Control 1	16
TCC2 – Timer Counter for Control 2	17
TC3 – Timer Counter 3	18
TC4 – Timer Counter 4	19
TC5 – Timer Counter 5	20

Bit 13 – FORCELDO: Force LDO Voltage Regulator

Value	Description
0	The voltage regulator is in low power and low drive configuration in standby sleep mode.
1	The voltage regulator is in low power and high drive configuration in standby sleep mode.

Bit 6 – RUNSTDBY: Run in Standby

Value	Description
0	The voltage regulator is in low power configuration in standby sleep mode.
1	The voltage regulator is in normal configuration in standby sleep mode.

17.8.16 Voltage References System (VREF) Control

Name: VREF

Offset: 0x40

Reset: 0x0XXX0000

Property: Write-Protected

Bit	31	30	29	28	27	26	25	24
						CALIB[10:8]		
Access						R/W	R/W	R/W
Reset						x	x	x
Bit	23	22	21	20	19	18	17	16
	CALIB[7:0]							
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	x	x	x	x	x	x	x	x
Bit	15	14	13	12	11	10	9	8
Access								
Reset								
Bit	7	6	5	4	3	2	1	0
						BGOUTEN	TSEN	
Access						R/W	R/W	
Reset						0	0	

Bits 26:16 – CALIB[10:0]: Bandgap Voltage Generator Calibration

These bits are used to calibrate the output level of the bandgap voltage reference. These bits are loaded from Flash Calibration Row at startup.

Bit 2 – BGOUTEN: Bandgap Output Enable

Value	Description
0	The bandgap output is not available as an ADC input channel.
1	The bandgap output is routed to an ADC input channel.

Bit 1 – TSEN: Temperature Sensor Enable

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Reset: 0x00

Property: Write-Protected

Bit	7	6	5	4	3	2	1	0
	OVF	SYNCRDY						ALARM0
Access	R/W	R/W						R/W
Reset	0	0						0

Bit 7 – OVF: Overflow Interrupt Enable

Writing a zero to this bit has no effect.

Writing a one to this bit will set the Overflow Interrupt Enable bit and enable the Overflow interrupt.

Value	Description
0	The overflow interrupt is disabled.
1	The overflow interrupt is enabled.

Bit 6 – SYNCRDY: Synchronization Ready Interrupt Enable

Writing a zero to this bit has no effect.

Writing a one to this bit will set the Synchronization Ready Interrupt bit and enable the Synchronization Ready interrupt.

Value	Description
0	The synchronization ready interrupt is disabled.
1	The synchronization ready interrupt is enabled.

Bit 0 – ALARM0: Alarm 0 Interrupt Enable

Writing a zero to this bit has no effect.

Writing a one to this bit will set the Alarm 0 Interrupt Enable bit and enable the Alarm 0 interrupt.

Value	Description
0	The alarm 0 interrupt is disabled.
1	The alarm 0 interrupt is enabled.

19.8.14 Interrupt Flag Status and Clear - MODE0

Name: INTFLAG

Offset: 0x08

Reset: 0x00

Property: -

Bit	7	6	5	4	3	2	1	0
	OVF	SYNCRDY						CMP0
Access	R/W	R/W						R/W
Reset	0	0						0

Bit 7 – OVF: Overflow

This flag is cleared by writing a one to the flag.

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Value	Description
0	The correction value is positive, i.e., frequency will be increased.
1	The correction value is negative, i.e., frequency will be decreased.

Bits 6:0 – VALUE[6:0]: Correction Value

These bits define the amount of correction applied to the RTC prescaler.

1–127: The RTC frequency is adjusted according to the value.

Value	Description
0	Correction is disabled and the RTC frequency is unchanged.

19.8.20 Counter Value - MODE0

Name: COUNT

Offset: 0x10

Reset: 0x00000000

Property: Read-Synchronized, Write-Protected, Write-Synchronized

Bit	31	30	29	28	27	26	25	24
	COUNT[31:24]							
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0
Bit	23	22	21	20	19	18	17	16
	COUNT[23:16]							
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0
Bit	15	14	13	12	11	10	9	8
	COUNT[15:8]							
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0
Bit	7	6	5	4	3	2	1	0
	COUNT[7:0]							
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0

Bits 31:0 – COUNT[31:0]: Counter Value

These bits define the value of the 32-bit RTC counter.

19.8.21 Counter Value - MODE1

Name: COUNT

Offset: 0x10

Reset: 0x0000

Property: Read-Synchronized, Write-Protected, Write-Synchronized

20.6.6 Events

The DMAC can generate the following output events:

- Channel (CH): Generated when a block transfer for a given channel has been completed, or when a beat transfer within a block transfer for a given channel has been completed. Refer to Event Output Selection section for details.

Setting the Channel Control B Event Output Enable bit (CHCTRLB.EVOE=1) enables the corresponding output event configured in the Event Output Selection bit group in the Block Transfer Control register (BTCTRL.EVOSEL). Clearing CHCTRLB.EVOE=0 disables the corresponding output event.

The DMAC can take the following actions on an input event:

- Transfer and Periodic Transfer Trigger (TRIG): normal transfer or periodic transfers on peripherals are enabled
- Conditional Transfer Trigger (CTRIG): conditional transfers on peripherals are enabled
- Conditional Block Transfer Trigger (CBLOCK): conditional block transfers on peripherals are enabled
- Channel Suspend Operation (SUSPEND): suspend a channel operation
- Channel Resume Operation (RESUME): resume a suspended channel operation
- Skip Next Block Suspend Action (SSKIP): skip the next block suspend transfer condition
- Increase Priority (INCPRI): increase channel priority

Setting the Channel Control B Event Input Enable bit (CHCTRLB.EVIE=1) enables the corresponding action on input event. Clearing this bit disables the corresponding action on input event. Note that several actions can be enabled for incoming events. If several events are connected to the peripheral, any enabled action will be taken for any of the incoming events. For further details on event input actions, refer to Event Input Action section.

Related Links

[EVSYS – Event System](#)

20.6.7 Sleep Mode Operation

Each DMA channel can be configured to operate in any sleep mode. To be able to run in standby, the RUNSTDBY bit in Channel Control A register (CHCTRLA.RUNSTDBY) must be written to '1'. The DMAC can wake up the device using interrupts from any sleep mode or perform actions through the Event System.

For channels with CHCTRLA.RUNSTDBY=0, it is up to software to stop DMA transfers on these channels and wait for completion before going to standby mode using the following sequence:

1. Suspend the DMAC channels for which CHCTRLA.RUNSTDBY=0.
2. Check the SYNCBUSY bits of registers accessed by the DMAC channels being suspended.
3. Go to sleep
4. When the device wakes up, resume the suspended channels.

Note: In standby sleep mode, the DMAC can only access RAM when it is not back biased (PM.STDBYCFG.BBIASxx=0x0)

20.6.8 Synchronization

Not applicable.

Value	Name	Description
0x0	BYTE	8-bit bus transfer
0x1	HWORD	16-bit bus transfer
0x2	WORD	32-bit bus transfer
other		Reserved

Bits 4:3 – BLOCKACT[1:0]: Block Action

These bits define what actions the DMAC should take after a block transfer has completed.

BLOCKACT[1:0]	Name	Description
0x0	NOACT	Channel will be disabled if it is the last block transfer in the transaction
0x1	INT	Channel will be disabled if it is the last block transfer in the transaction and block interrupt
0x2	SUSPEND	Channel suspend operation is completed
0x3	BOTH	Both channel suspend operation and block interrupt

Bits 2:1 – EVOSEL[1:0]: Event Output Selection

These bits define the event output selection.

EVOSEL[1:0]	Name	Description
0x0	DISABLE	Event generation disabled
0x1	BLOCK	Event strobe when block transfer complete
0x2		Reserved
0x3	BEAT	Event strobe when beat transfer complete

Bit 0 – VALID: Descriptor Valid

Writing a '0' to this bit in the Descriptor or Write-Back memory will suspend the DMA channel operation when fetching the corresponding descriptor.

The bit is automatically cleared in the Write-Back memory section when channel is aborted, when an error is detected during the block transfer, or when the block transfer is completed.

Value	Description
0	The descriptor is not valid.
1	The descriptor is valid.

20.10.2 Block Transfer Count

The BTCNT register offset is relative to (BASEADDR or WRBADDR) + Channel Number * 0x10

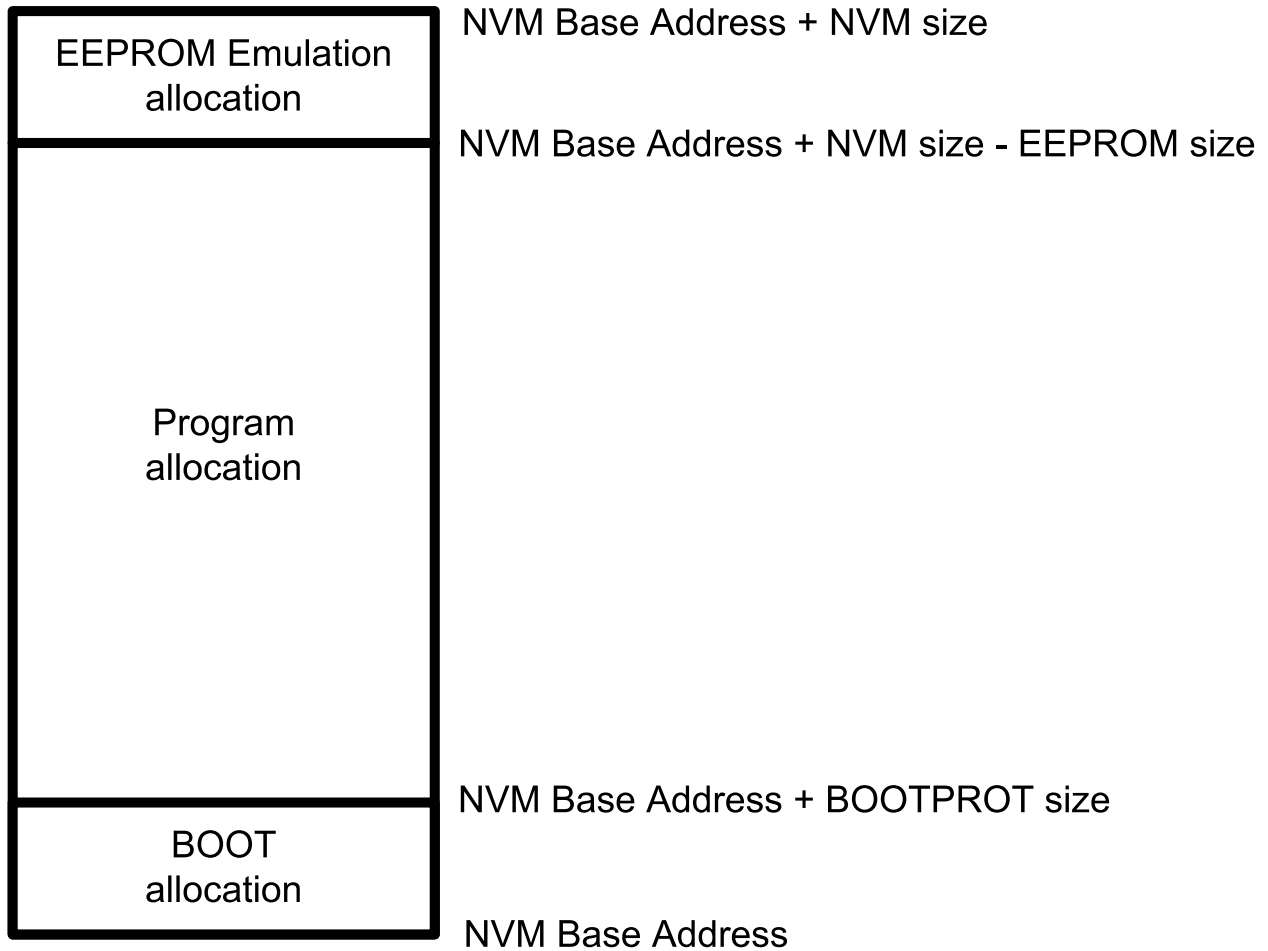
Name: BTCNT

Offset: 0x02

Reset: -

Property: -

Figure 22-4. EEPROM and Boot Loader Allocation



Related Links

[Physical Memory Map](#)

22.6.3 Region Lock Bits

The NVM block is grouped into 16 equally sized regions. The region size is dependent on the Flash memory size, and is given in the table below. Each region has a dedicated lock bit preventing writing and erasing pages in the region. After production, all regions will be unlocked.

Table 22-1. Region Size

Memory Size [KB]	Region Size [KB]
256	16
128	8
64	4
32	2

To lock or unlock a region, the Lock Region and Unlock Region commands are provided. Writing one of these commands will temporarily lock/unlock the region containing the address loaded in the ADDR register. ADDR can be written by software, or the automatically loaded value from a write operation can be used. The new setting will stay in effect until the next Reset, or until the setting is changed again using

24.4 Signal Description

Not applicable.

24.5 Product Dependencies

In order to use this peripheral, other parts of the system must be configured correctly, as described below.

24.5.1 I/O Lines

Not applicable.

24.5.2 Power Management

The EVSYS can be used to wake up the CPU from all sleep modes, even if the clock used by the EVSYS channel and the EVSYS bus clock are disabled. Refer to the *PM – Power Manager* for details on the different sleep modes.

In all sleep modes, although the clock for the EVSYS is stopped, the device still can wake up the EVSYS clock. Some event generators can generate an event when their clocks are stopped.

Related Links

[PM – Power Manager](#)

24.5.3 Clocks

The EVSYS bus clock (CLK_EVSYS_APB) can be enabled and disabled in the Main Clock module, and the default state of CLK_EVSYS_APB can be found in *Peripheral Clock Masking*.

Each EVSYS channel has a dedicated generic clock (GCLK_EVSYS_CHANNEL_n). These are used for event detection and propagation for each channel. These clocks must be configured and enabled in the generic clock controller before using the EVSYS. Refer to *GCLK - Generic Clock Controller* for details.

Related Links

[Peripheral Clock Masking](#)

[GCLK - Generic Clock Controller](#)

24.5.4 DMA

Not applicable.

24.5.5 Interrupts

The interrupt request line is connected to the Interrupt Controller. Using the EVSYS interrupts requires the interrupt controller to be configured first. Refer to *Nested Vector Interrupt Controller* for details.

Related Links

[Nested Vector Interrupt Controller](#)

24.5.6 Events

Not applicable.

24.5.7 Debug Operation

When the CPU is halted in debug mode, this peripheral will continue normal operation. If the peripheral is configured to require periodical service by the CPU through interrupts or similar, improper operation or data loss may result during debugging. This peripheral can be forced to halt operation during debugging.

Bits 19,18,17,16,7,6,5,4,3,2,1,0 – OVRn : Channel n Overrun [n=11..0]

This flag is set on the next CLK_EVSYS cycle after an overrun channel condition occurs, and an interrupt request will be generated if INTENCLR/SET.OVRn is one.

When the event channel path is asynchronous, the OVRn interrupt flag will not be set.

Writing a zero to this bit has no effect.

Writing a one to this bit will clear the Overrun Channel n interrupt flag.

26.7 Register Summary

Offset	Name	Bit Pos.								
0x00	CTRLA	7:0	RUNSTDBY			MODE[2:0]		ENABLE	SWRST	
0x01		15:8	SAMPR[2:0]							IBON
0x02		23:16	SAMPA[1:0]		RXPO[1:0]				TXPO[1:0]	
0x03		31:24		DORD	CPOL	CMODE	FORM[3:0]			
0x04	CTRLB	7:0		SBMODE				CHSIZE[2:0]		
0x05		15:8			PMODE			ENC	SFDE	COLDEN
0x06		23:16							RXEN	TXEN
0x07		31:24								
0x08 ... 0x0B	Reserved									
0x0C	BAUD	7:0	BAUD[7:0]							
0x0D		15:8	BAUD[15:8]							
0x0E	RXPL	7:0	RXPL[7:0]							
0x0F ... 0x13	Reserved									
0x14	INTENCLR	7:0	ERROR		RXBRK	CTSIC	RXS	RXC	TXC	DRE
0x15	Reserved									
0x16	INTENSET	7:0	ERROR		RXBRK	CTSIC	RXS	RXC	TXC	DRE
0x17	Reserved									
0x18	INTFLAG	7:0	ERROR		RXBRK	CTSIC	RXS	RXC	TXC	DRE
0x19	Reserved									
0x1A	STATUS	7:0			COLL	ISF	CTS	BUFOVF	FERR	PERR
0x1B		15:8								
0x1C	SYNCBUSY	7:0						CTRLB	ENABLE	SWRST
0x1D		15:8								
0x1E		23:16								
0x1F		31:24								
0x20 ... 0x27	Reserved									
0x28	DATA	7:0	DATA[7:0]							
0x29		15:8								DATA[8:8]
0x2A ... 0x2F	Reserved									
0x30	DBGCTRL	7:0								DBGSTOP

26.8 Register Description

Registers can be 8, 16, or 32 bits wide. Atomic 8-, 16-, and 32-bit accesses are supported. In addition, the 8-bit quarters and 16-bit halves of a 32-bit register, and the 8-bit halves of a 16-bit register can be accessed directly.

28.7 Register Summary - I2C Slave

Offset	Name	Bit Pos.									
0x00	CTRLA	7:0	RUNSTDBY			MODE[2:0]		ENABLE	SWRST		
0x01		15:8									
0x02		23:16	SEXTTOEN		SDAHOLD[1:0]					PINOUT	
0x03		31:24		LOWTOUT			SCLSM		SPEED[1:0]		
0x04	CTRLB	7:0									
0x05		15:8	AMODE[1:0]					AACKEN	GCMD	SMEN	
0x06		23:16						ACKACT	CMD[1:0]		
0x07		31:24									
0x08 ... 0x13	Reserved										
0x14	INTENCLR	7:0	ERROR					DRDY	AMATCH	PREC	
0x15	Reserved										
0x16	INTENSET	7:0	ERROR					DRDY	AMATCH	PREC	
0x17	Reserved										
0x18	INTFLAG	7:0	ERROR					DRDY	AMATCH	PREC	
0x19	Reserved										
0x1A	STATUS	7:0	CLKHOLD	LOWTOUT		SR	DIR	RXNACK	COLL	BUSERR	
0x1B		15:8						LENERR	SEXTTOUT		
0x1C	SYNCBUSY	7:0							ENABLE	SWRST	
0x1D		15:8									
0x1E		23:16									
0x1F		31:24									
0x20 ... 0x23	Reserved										
0x24	ADDR	7:0	ADDR[6:0]							GENCEN	
0x25		15:8	TENBITEN						ADDR[9:7]		
0x26		23:16	ADDRMASK[6:0]								
0x27		31:24							ADDRMASK[9:7]		
0x28	DATA	7:0	DATA[7:0]								
0x29		15:8									

28.8 Register Description - I²C Slave

Registers can be 8, 16, or 32 bits wide. Atomic 8-, 16- and 32-bit accesses are supported. In addition, the 8-bit quarters and 16-bit halves of a 32-bit register, and the 8-bit halves of a 16-bit register can be accessed directly.

Some registers are optionally write-protected by the Peripheral Access Controller (PAC). Optional PAC write-protection is denoted by the "PAC Write-Protection" property in each individual register description. For details, refer to [Register Access Protection](#).

Some registers are synchronized when read and/or written. Synchronization is denoted by the "Write-Synchronized" or the "Read-Synchronized" property in each individual register description. For details, refer to [Synchronization](#).

Value	Description
0	The CCBx, PERB, PGVB, PGOB, and SWAPBx buffer registers values <i>are</i> copied into the corresponding CCx, PER, PGV, PGO and SWAPx registers on hardware update condition.
1	The CCBx, PERB, PGVB, PGOB, and SWAPBx buffer registers values are <i>not</i> copied into the corresponding CCx, PER, PGV, PGO and SWAPx registers on hardware update condition.

Bit 0 – DIR: Counter Direction

This bit is used to change the direction of the counter.

Writing a '0' to this bit has no effect

Writing a '1' to this bit will clear the bit and make the counter count up.

Value	Description
0	The timer/counter is counting up (incrementing).
1	The timer/counter is counting down (decrementing).

31.8.3 Control B Set

This register allows the user to change this register without doing a read-modify-write operation. Changes in this register will also be reflected in the Control B Set (CTRLBCLR) register.

Name: CTRLBSET

Offset: 0x05

Reset: 0x00

Property: PAC Write-Protection, Write-Synchronized, Read-Synchronized

Bit	7	6	5	4	3	2	1	0
	CMD[2:0]			IDXCMD[1:0]		ONESHOT	LUPD	DIR
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0

Bits 7:5 – CMD[2:0]: TCC Command

These bits can be used for software control of re-triggering and stop commands of the TCC. When a command has been executed, the CMD bit field will be read back as zero. The commands are executed on the next prescaled GCLK_TCC clock cycle.

Writing zero to this bit group has no effect

Writing a valid value to this bit group will set the associated command.

Value	Name	Description
0x0	NONE	No action
0x1	RETRIGGER	Force start, restart or retrigger
0x2	STOP	Force stop
0x3	UPDATE	Force update of double buffered registers
0x4	READSYNC	Force a read synchronization of COUNT

Bits 4:3 – IDXCMD[1:0]: Ramp Index Command

These bits can be used to force cycle A and cycle B changes in RAMP2 and RAMP2A operation. On timer/counter update condition, the command is executed, the IDX flag in STATUS register is updated and the IDXCMD command is cleared.

32.6.3 Host Operations

This section gives an overview of the USB module Host operation during normal transactions. For more details on general USB and USB protocol, refer to Universal Serial Bus Specification revision 2.1.

32.6.3.1 Device Detection and Disconnection

Prior to device detection the software must set the VBUS is OK bit in CTRLB (CTRLB.VBUSOK) register when the VBUS is available. This notifies the USB host that USB operations can be started. When the bit CTRLB.VBUSOK is zero and even if the USB HOST is configured and enabled, host operation is halted. Setting the bit CTRLB.VBUSOK will allow host operation when the USB is configured.

The Device detection is managed by the software using the Line State field in the Host Status (STATUS.LINESTATE) register. The device connection is detected by the host controller when DP or DM is pulled high, depending of the speed of the device.

The device disconnection is detected by the host controller when both DP and DM are pulled down using the STATUS.LINESTATE registers.

The Device Connection Interrupt bit in INTFLAG (INTFLAG.DCONN) is set if a device connection is detected.

The Device Disconnection Interrupt bit in INTFLAG (INTFLAG.DDISC) is set if a device disconnection is detected.

32.6.3.2 Host Terminology

In host mode, the term pipe is used instead of endpoint. A host pipe corresponds to a device endpoint, refer to "Universal Serial Bus Specification revision 2.1." for more information.

32.6.3.3 USB Reset

The USB sends a USB reset signal when the user writes a one to the USB Reset bit in CTRLB (CTRLB.BUSRESET). When the USB reset has been sent, the USB Reset Sent Interrupt bit in the INTFLAG (INTFLAG.RST) is set and all pipes will be disabled.

If the bus was previously in a suspended state (Start of Frame Generation Enable bit in CTRLB (CTRLB.SOFE) is zero) the USB will switch it to the Resume state, causing the bus to asynchronously set the Host Wakeup Interrupt flag (INTFLAG.WAKEUP). The CTRLB.SOFE bit will be set in order to generate SOFs immediately after the USB reset.

During USB reset the following registers are cleared:

- All Host Pipe Configuration register (PCFG)
- Host Frame Number register (FNUM)
- Interval for the Bulk-Out/Ping transaction register (BINTERVAL)
- Host Start-of-Frame Control register (HSOFC)
- Pipe Interrupt Enable Clear/Set register (PINTENCLR/SET)
- Pipe Interrupt Flag register (PINTFLAG)
- Pipe Freeze bit in Pipe Status register (PSTATUS.FREEZE)

After the reset the user should check the Speed Status field in the Status register (STATUS.SPEED) to find out the current speed according to the capability of the peripheral.

32.6.3.4 Pipe Configuration

Pipe data can be placed anywhere in the RAM. The USB controller accesses these pipes directly through the AHB master (built-in DMA) with the help of the pipe descriptors. The base address of the pipe descriptors needs to be written in the Descriptor Address register (DESCADD) by the user. Refer also to [Pipe Descriptor Structure](#).

Bit 6 – UPRSM: Upstream Resume from Device Interrupt Disable

Writing a zero to this bit has no effect.

Writing a one to this bit will clear the Upstream Resume interrupt Enable bit and disable the corresponding interrupt request.

Value	Description
0	The Upstream Resume interrupt is disabled.
1	The Upstream Resume interrupt is enabled and an interrupt request will be generated when the Upstream Resume interrupt Flag is set.

Bit 5 – DNRSM: Down Resume Interrupt Disable

Writing a zero to this bit has no effect.

Writing a one to this bit will clear the Down Resume interrupt Enable bit and disable the corresponding interrupt request.

Value	Description
0	The Down Resume interrupt is disabled.
1	The Down Resume interrupt is enabled and an interrupt request will be generated when the Down Resume interrupt Flag is set.

Bit 4 – WAKEUP: Wake Up Interrupt Disable

Writing a zero to this bit has no effect.

Writing a one to this bit will clear the Wake Up interrupt Enable bit and disable the corresponding interrupt request.

Value	Description
0	The Wake Up interrupt is disabled.
1	The Wake Up interrupt is enabled and an interrupt request will be generated when the Wake Up interrupt Flag is set.

Bit 3 – RST: BUS Reset Interrupt Disable

Writing a zero to this bit has no effect.

Writing a one to this bit will clear the Bus Reset interrupt Enable bit and disable the corresponding interrupt request.

Value	Description
0	The Bus Reset interrupt is disabled.
1	The Bus Reset interrupt is enabled and an interrupt request will be generated when the Bus Reset interrupt Flag is set.

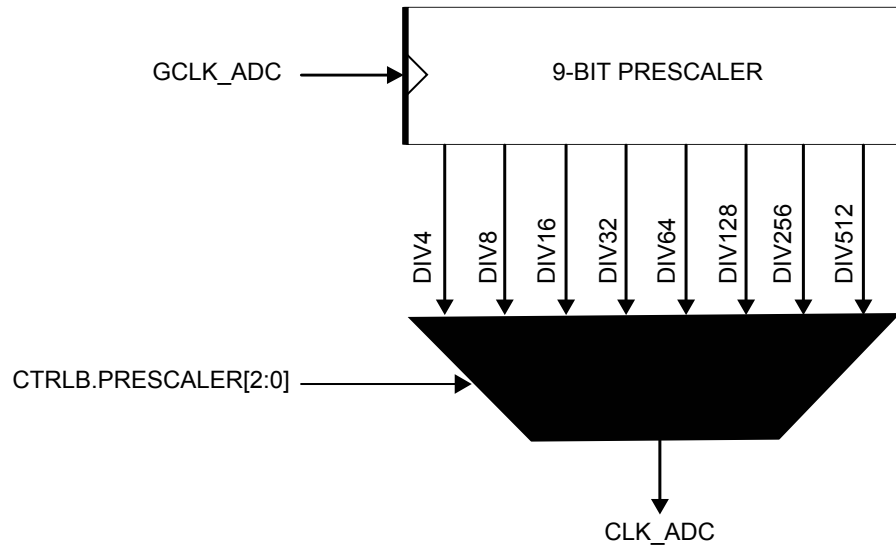
Bit 2 – HSOF: Host Start-of-Frame Interrupt Disable

Writing a zero to this bit has no effect.

Writing a one to this bit will clear the Host Start-of-Frame interrupt Enable bit and disable the corresponding interrupt request.

Value	Description
0	The Host Start-of-Frame interrupt is disabled.
1	The Host Start-of-Frame interrupt is enabled and an interrupt request will be generated when the Host Start-of-Frame interrupt Flag is set.

Figure 33-2. ADC Prescaler



The propagation delay of an ADC measurement depends on the selected mode and is given by:

- Single-shot mode:

$$\text{PropagationDelay} = \frac{1 + \frac{\text{Resolution}}{2} + \text{DelayGain}}{f_{\text{CLK+} - \text{ADC}}}$$

- Free-running mode:

$$\text{PropagationDelay} = \frac{\frac{\text{Resolution}}{2} + \text{DelayGain}}{f_{\text{CLK+} - \text{ADC}}}$$

Table 33-1. Delay Gain

Name	INTPUTCTRL.GAIN[3:0]	Delay Gain (in CLK_ADC Period)			
		Free-running mode		Single shot mode	
		Differential Mode	Single-Ended Mode	Differential mode	Single-Ended mode
1X	0x0	0	0	0	1
2X	0x1	0	1	0.5	1.5
4X	0x2	1	1	1	2
8X	0x3	1	2	1.5	2.5
16X	0x4	2	2	2	3
Reserved	0x5 ... 0xE	Reserved	Reserved	Reserved	Reserved
DIV2	0xF	0	1	0.5	1.5

33.6.4 ADC Resolution

The ADC supports 8-bit, 10-bit or 12-bit resolution. Resolution can be changed by writing the Resolution bit group in the Control B register (CTRLB.RESSEL). By default, the ADC resolution is set to 12 bits.

33.6.5 Differential and Single-Ended Conversions

The ADC has two conversion options: differential and single-ended:

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Value	Description
0	The ADC is halted during standby sleep mode.
1	The ADC continues normal operation during standby sleep mode.

Bit 1 – ENABLE: Enable

Due to synchronization, there is a delay from writing CTRLA.ENABLE until the peripheral is enabled/disabled. The value written to CTRLA.ENABLE will read back immediately and the Synchronization Busy bit in the Status register (STATUS.SYNCBUSY) will be set. STATUS.SYNCBUSY will be cleared when the operation is complete.

Value	Description
0	The ADC is disabled.
1	The ADC is enabled.

Bit 0 – SWRST: Software Reset

Writing a zero to this bit has no effect.

Writing a one to this bit resets all registers in the ADC, except DBGCTRL, to their initial state, and the ADC will be disabled.

Writing a one to CTRLA.SWRST will always take precedence, meaning that all other writes in the same write-operation will be discarded.

Due to synchronization, there is a delay from writing CTRLA.SWRST until the reset is complete. CTRLA.SWRST and STATUS.SYNCBUSY will both be cleared when the reset is complete.

Value	Description
0	There is no reset operation ongoing.
1	The reset operation is ongoing.

33.8.2 Reference Control

Name: REFCTRL

Offset: 0x01

Reset: 0x00

Property: Write-Protected

Bit	7	6	5	4	3	2	1	0
	REFCOMP				REFSEL[3:0]			
Access	R/W				R/W	R/W	R/W	R/W
Reset	0				0	0	0	0

Bit 7 – REFCOMP: Reference Buffer Offset Compensation Enable

The accuracy of the gain stage can be increased by enabling the reference buffer offset compensation. This will decrease the input impedance and thus increase the start-up time of the reference.

Value	Description
0	Reference buffer offset compensation is disabled.
1	Reference buffer offset compensation is enabled.

Bits 3:0 – REFSEL[3:0]: Reference Selection

These bits select the reference for the ADC.

MUXPOS[4:0]	Group configuration	Description
0x03	PIN3	ADC AIN3 pin
0x04	PIN4	ADC AIN4 pin
0x05	PIN5	ADC AIN5 pin
0x06	PIN6	ADC AIN6 pin
0x07	PIN7	ADC AIN7 pin
0x08	PIN8	ADC AIN8 pin
0x09	PIN9	ADC AIN9 pin
0x0A	PIN10	ADC AIN10 pin
0x0B	PIN11	ADC AIN11 pin
0x0C	PIN12	ADC AIN12 pin
0x0D	PIN13	ADC AIN13 pin
0x0E	PIN14	ADC AIN14 pin
0x0F	PIN15	ADC AIN15 pin
0x10	PIN16	ADC AIN16 pin
0x11	PIN17	ADC AIN17 pin
0x12	PIN18	ADC AIN18 pin
0x13	PIN19	ADC AIN19 pin
0x14-0x17		Reserved
0x18	TEMP	Temperature reference
0x19	BANDGAP	Bandgap voltage
0x1A	SCALED COREVCC	1/4 scaled core supply
0x1B	SCALED I/OVCC	1/4 scaled I/O supply
0x1C	DAC	DAC output
0x1D-0x1F		Reserved

33.8.9 Event Control

Name: EVCTRL

Offset: 0x14

Reset: 0x00

Property: Write-Protected

4 – In TWI master mode, an ongoing transaction should be stalled immediately when DBGCTRL.DBGSTOP is set and the CPU enters debug mode. Instead, it is stopped when the current byte transaction is completed and the corresponding interrupt is triggered if enabled.

Errata reference: 12499

Fix/Workaround:

In TWI master mode, keep DBGCTRL.DBGSTOP=0 when in debug mode.

40.1.4.12 TC

1 – Spurious TC overflow and Match/Capture events may occur.

Errata reference: 13268

Fix/Workaround:

Do not use the TC overflow and Match/Capture events. Use the corresponding Interrupts instead.

40.1.4.13 TCC

1 – Using TCC in dithering mode with external retrigger events can lead to unexpected stretch of right aligned pulses, or shrink of left aligned pulses.

Errata reference: 15625

Fix/Workaround:

Do not use retrigger events/actions when TCC is configured in dithering mode.

2 – Advance capture mode (CAPTMIN CAPTMAX LOCMIN LOCMAX DERIV0) doesn't work if an upper channel is not in one of these mode.

Example: when CC[0]=CAPTMIN, CC[1]=CAPTMAX, CC[2]=CAPTEN, and CC[3]=CAPTEN, CAPTMIN and CAPTMAX won't work.

Errata reference: 14817

Fix/Workaround:

Basic capture mode must be set in lower channel and advance capture mode in upper channel.

Example: CC[0]=CAPTEN, CC[1]=CAPTEN, CC[2]=CAPTMIN, CC[3]=CAPTMAX

All capture will be done as expected.

3 – In RAMP 2 mode with Fault keep, qualified and restart:

If a fault occurred at the end of the period during the qualified state, the switch to the next ramp can have two restarts.

Errata reference: 13262

Fix/Workaround:

Avoid faults few cycles before the end or the beginning of a ramp.

4 – With blanking enabled, a recoverable fault that occurs during the first increment of a rising TCC is not blanked.

Errata reference: 12519

Fix/Workaround:

None

5 – In Dual slope mode a Retrigger Event does not clear the TCC counter.

Errata reference: 12354

Fix/Workaround:

None