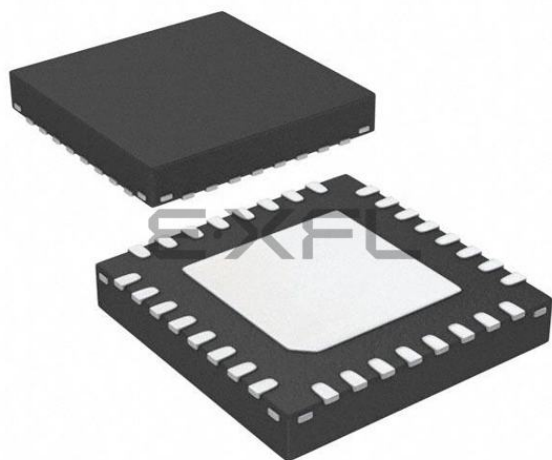




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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

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Details

Product Status	Active
Core Processor	ARM® Cortex®-M0
Core Size	32-Bit Single-Core
Speed	50MHz
Connectivity	I ² C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, WDT
Number of I/O	28
Program Memory Size	8KB (8K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	32-VQFN Exposed Pad
Supplier Device Package	32-HVQFN (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/lpc1111jhn33-203e

Table 1. Ordering information ...continued

Type number	Package		
	Name	Description	Version
LPC1115JBD48/303	LQFP48	LQFP48: plastic low profile quad flat package; 48 leads; body 7 × 7 × 1.4 mm	SOT313-2
LPC1115FET48/303	TFBGA48	plastic thin fine-pitch ball grid array package; 48 balls; body 4.5 × 4.5 × 0.7 mm	SOT1155-2
LPC1115JET48/303	TFBGA48	plastic thin fine-pitch ball grid array package; 48 balls; body 4.5 × 4.5 × 0.7 mm	SOT1155-2

4.1 Ordering options

Table 2. Ordering options

Type number	Series	Flash	Total SRAM	Power profiles	UART	I ² C/ Fast+	SPI	ADC channel	GPIO	Package	Temp ^[1]
LPC1110											
LPC1110FD20	LPC1100L	4 kB	1 kB	yes	1	1	1	5	16	SO20	F
LPC1111											
LPC1111FDH20/002	LPC1100L	8 kB	2 kB	yes	1	1	1	5	16	TSSOP20	F
LPC1111FHN33/101	LPC1100	8 kB	2 kB	no	1	1	1	8	28	HVQFN33	F
LPC1111FHN33/102	LPC1100L	8 kB	2 kB	yes	1	1	1	8	28	HVQFN33	F
LPC1111FHN33/103	LPC1100XL	8 kB	2 kB	yes	1	1	2	8	28	HVQFN33	F
LPC1111JHN33/103	LPC1100XL	8 kB	2 kB	yes	1	1	2	8	28	HVQFN33	J
LPC1111FHN33/201	LPC1100	8 kB	4 kB	no	1	1	1	8	28	HVQFN33	F
LPC1111FHN33/202	LPC1100L	8 kB	4 kB	yes	1	1	1	8	28	HVQFN33	F
LPC1111FHN33/203	LPC1100XL	8 kB	4 kB	yes	1	1	2	8	28	HVQFN33	F
LPC1111JHN33/203	LPC1100XL	8 kB	4 kB	yes	1	1	2	8	28	HVQFN33	J
LPC1112											
LPC1112FD20/102	LPC1100L	16 kB	4 kB	yes	1	1	1	5	16	SO20	F
LPC1112FDH20/102	LPC1100L	16 kB	4 kB	yes	1	-	1	5	14	TSSOP20	F
LPC1112FDH28/102	LPC1100L	16 kB	4 kB	yes	1	1	1	6	22	TSSOP28	F
LPC1112FHN24/202	LPC1100L	16 kB	4 kB	yes	1	1	1	6	19	HVQFN24	F
LPC1112FHN33/101	LPC1100	16 kB	2 kB	no	1	1	1	8	28	HVQFN33	F
LPC1112FHN33/102	LPC1100L	16 kB	2 kB	yes	1	1	1	8	28	HVQFN33	F
LPC1112FHN33/103	LPC1100XL	16 kB	2 kB	yes	1	1	2	8	28	HVQFN33	F
LPC1112JHN33/103	LPC1100XL	16 kB	2 kB	yes	1	1	2	8	28	HVQFN33	J
LPC1112FHN33/201	LPC1100	16 kB	4 kB	no	1	1	1	8	28	HVQFN33	F
LPC1112FHN33/202	LPC1100L	16 kB	4 kB	yes	1	1	1	8	28	HVQFN33	F
LPC1112FHN33/203	LPC1100XL	16 kB	4 kB	yes	1	1	2	8	28	HVQFN33	F
LPC1112JHN33/203	LPC1100XL	16 kB	4 kB	yes	1	1	2	8	28	HVQFN33	J
LPC1112FHI33/102	LPC1100L	16 kB	2 kB	yes	1	1	1	8	28	HVQFN33	F
LPC1112FHI33/202	LPC1100L	16 kB	4 kB	yes	1	1	1	8	28	HVQFN33	F
LPC1112FHI33/203	LPC1100XL	16 kB	4 kB	yes	1	1	2	8	28	HVQFN33	F
LPC1112JHI33/203	LPC1100XL	16 kB	4 kB	yes	1	1	2	8	28	HVQFN33	J

6. Pinning information

6.1 Pinning

Table 3. Pin description overview

Part	Pin description table	Pinning diagram
LPC1110FD20	Table 4	Figure 8
LPC1111FDH20/002	Table 4	Figure 9
LPC1112FD20/102	Table 4	Figure 10
LPC1112FDH20/102	Table 5	Figure 9
LPC1112FHN24/202	Table 6	Figure 11
LPC1112FDH28/102	Table 7	Figure 12
LPC1114FDH28/102	Table 7	Figure 13
LPC1114FN28/102	Table 7	Figure 13
LPC1111FHN33/101	Table 9	Figure 6
LPC1111FHN33/102	Table 9	Figure 6
LPC1111JHN33/103	Table 11	Figure 7
LPC1111FHN33/103	Table 11	Figure 7
LPC1111FHN33/201	Table 9	Figure 6
LPC1111FHN33/202	Table 9	Figure 6
LPC1111FHN33/203	Table 11	Figure 7
LPC1111JHN33/203	Table 11	Figure 7
LPC1112FHN33/101	Table 9	Figure 6
LPC1112FHN33/102	Table 9	Figure 6
LPC1112FHN33/103	Table 11	Figure 7
LPC1112JHN33/103	Table 11	Figure 7
LPC1112FHN33/201	Table 9	Figure 6
LPC1112FHN33/202	Table 9	Figure 6
LPC1112FHN33/203	Table 11	Figure 7
LPC1112JHN33/203	Table 11	Figure 7
LPC1112FHI33/202	Table 9	Figure 6
LPC1112FHI33/203	Table 11	Figure 7
LPC1112JHI33/203	Table 11	Figure 7
LPC1113FHN33/201	Table 9	Figure 6
LPC1113FHN33/202	Table 9	Figure 6
LPC1113FHN33/203	Table 11	Figure 7
LPC1113JHN33/203	Table 11	Figure 7
LPC1113FHN33/301	Table 9	Figure 6
LPC1113FHN33/302	Table 9	Figure 6
LPC1113FHN33/303	Table 11	Figure 7
LPC1113JHN33/303	Table 11	Figure 7
LPC1114FHN33/201	Table 9	Figure 6
LPC1114FHN33/202	Table 9	Figure 6

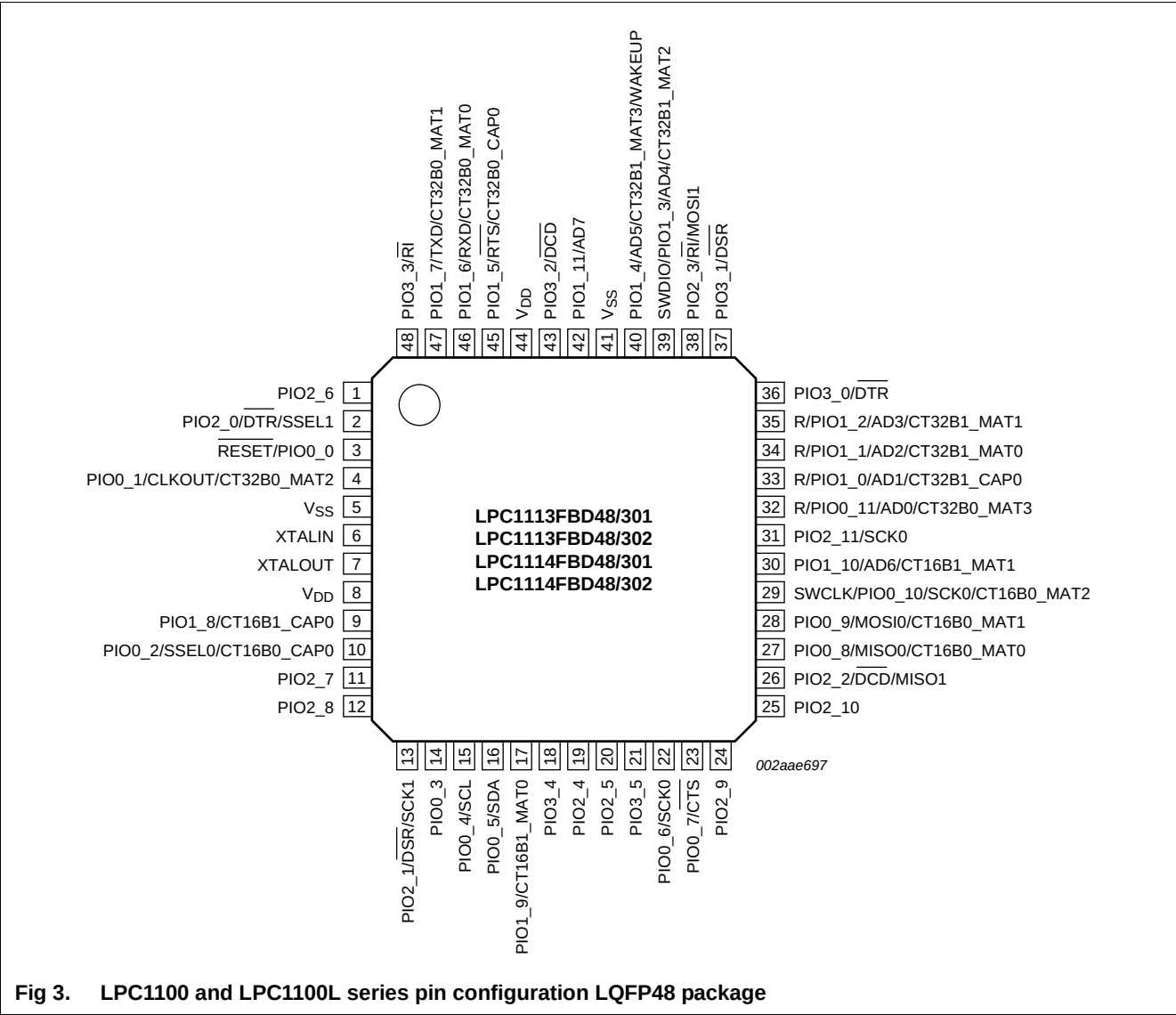


Fig 3. LPC1100 and LPC1100L series pin configuration LQFP48 package

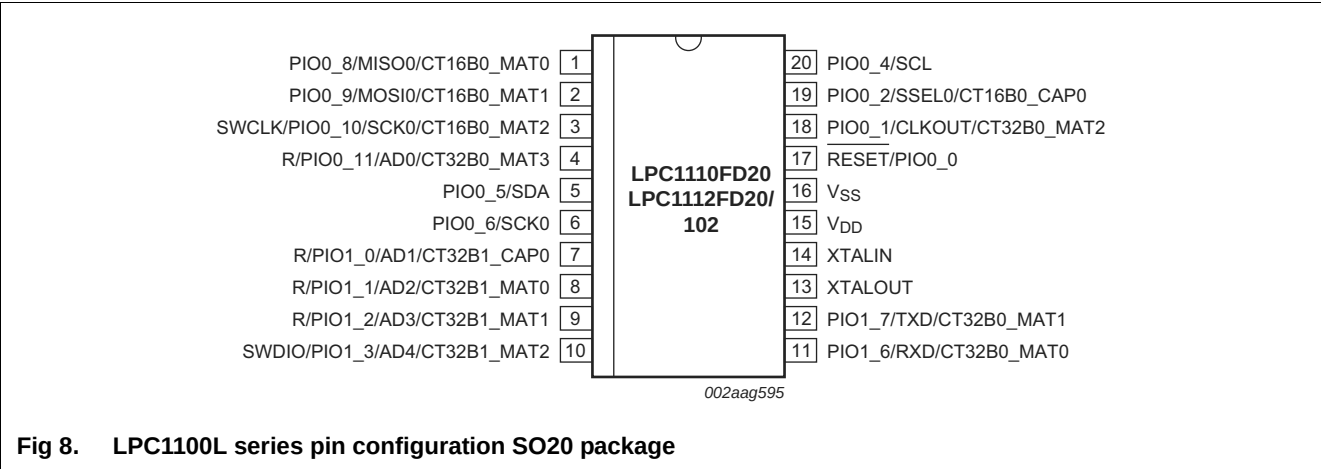
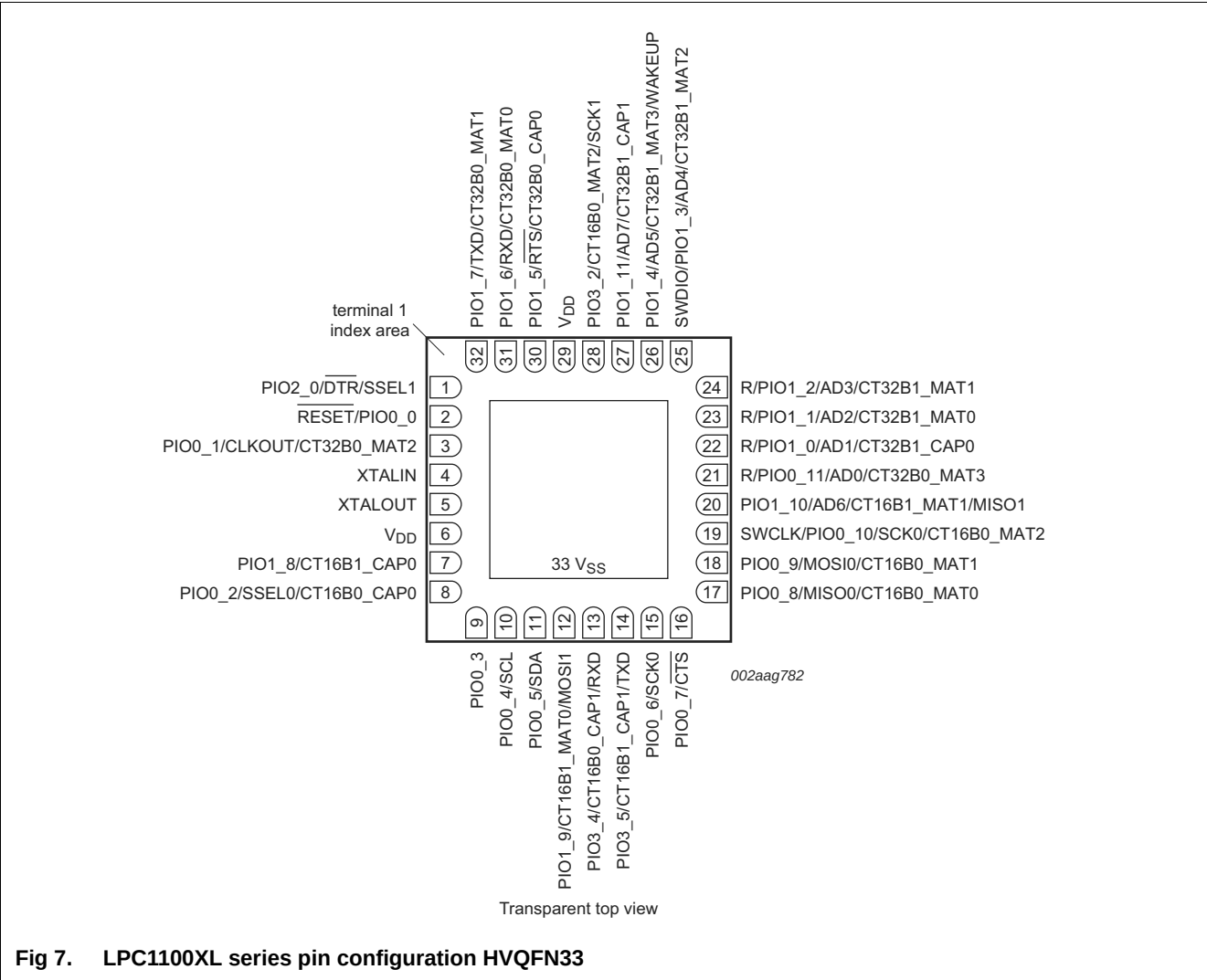


Table 5. LPC1100L series: LPC1112 pin description table (TSSOP20 with V_{DDA} and V_{SSA} pins) ...continued

Symbol	Pin TSSOP20	Start logic input	Type	Reset state [1]	Description
V _{DDA}	5	-	I	-	3.3 V supply voltage to the ADC. Also used as the ADC reference voltage.
XTALIN	14 [5]	-	I	-	Input to the oscillator circuit and internal clock generator circuits. Input voltage must not exceed 1.8 V.
XTALOUT	13 [5]	-	O	-	Output from the oscillator amplifier.
V _{SS}	16	-	I	-	Ground.
V _{SSA}	6	-	I	-	Analog ground.

- [1] Pin state at reset for default function: I = Input; O = Output; PU = internal pull-up enabled (pins pulled up to full V_{DD} level); IA = inactive, no pull-up/down enabled.
- [2] 5 V tolerant pad. RESET functionality is not available in Deep power-down mode.
- [3] 5 V tolerant pad providing digital I/O functions with configurable pull-up/pull-down resistors and configurable hysteresis (see Figure 51).
- [4] 5 V tolerant pad providing digital I/O functions with configurable pull-up/pull-down resistors, configurable hysteresis, and analog input. When configured as a ADC input, digital section of the pad is disabled and the pin is not 5 V tolerant (see Figure 51).
- [5] When the system oscillator is not used, connect XTALIN and XTALOUT as follows: XTALIN can be left floating or can be grounded (grounding is preferred to reduce susceptibility to noise). XTALOUT should be left floating.

Table 6. LPC1100L series: LPC1112 (HVQFN24 package)

Symbol	HVQFN pin	Start logic input	Type	Reset state [1]	Description
RESET/PIO0_0	1[2]	yes	I	I; PU	RESET — External reset input with 20 ns glitch filter. A LOW-going pulse as short as 50 ns on this pin resets the device, causing I/O ports and peripherals to take on their default states, and processor execution to begin at address 0. In deep power-down mode, this pin must be pulled HIGH externally. The RESET pin can be left unconnected or be used as a GPIO pin if an external RESET function is not needed and Deep power-down mode is not used.
			I/O	-	PIO0_0 — General purpose digital input/output pin with 10 ns glitch filter.
PIO0_1/CLKOUT/CT32B0_MAT2	2[3]	yes	I/O	I; PU	PIO0_1 — General purpose digital input/output pin. A LOW level on this pin during reset starts the ISP command handler.
			O	-	CLKOUT — Clockout pin.
			O	-	CT32B0_MAT2 — Match output 2 for 32-bit timer 0.
PIO0_2/SSEL0/CT16B0_CAP0	7[3]	yes	I/O	I; PU	PIO0_2 — General purpose digital input/output pin.
			I/O	-	SSEL0 — Slave Select for SPI0.
			I	-	CT16B0_CAP0 — Capture input 0 for 16-bit timer 0.
PIO0_4/SCL	8[4]	yes	I/O	I; IA	PIO0_4 — General purpose digital input/output pin (open-drain).
			I/O	-	SCL — I ² C-bus, open-drain clock input/output. High-current sink only if I ² C Fast-mode Plus is selected in the I/O configuration register.

Table 8. LPC1100 and LPC1100L series: LPC1113/14 pin description table (LQFP48 package)

Symbol	Pin	Start logic input	Type	Reset state [1]	Description
PIO0_0 to PIO0_11			I/O		Port 0 — Port 0 is a 12-bit I/O port with individual direction and function controls for each bit. The operation of port 0 pins depends on the function selected through the IOCONFIG register block.
RESET/PIO0_0	3 ^[2]	yes	I	I; PU	RESET — External reset input with 20 ns glitch filter. A LOW-going pulse as short as 50 ns on this pin resets the device, causing I/O ports and peripherals to take on their default states, and processor execution to begin at address 0. In deep power-down mode, this pin must be pulled HIGH externally. The RESET pin can be left unconnected or be used as a GPIO pin if an external RESET function is not needed and Deep power-down mode is not used.
			I/O	-	PIO0_0 — General purpose digital input/output pin with 10 ns glitch filter.
PIO0_1/CLKOUT/ CT32B0_MAT2	4 ^[3]	yes	I/O	I; PU	PIO0_1 — General purpose digital input/output pin. A LOW level on this pin during reset starts the ISP command handler.
			O	-	CLKOUT — Clockout pin.
			O	-	CT32B0_MAT2 — Match output 2 for 32-bit timer 0.
PIO0_2/SSEL0/ CT16B0_CAP0	10 ^[3]	yes	I/O	I; PU	PIO0_2 — General purpose digital input/output pin.
			I/O	-	SSEL0 — Slave Select for SPI0.
			I	-	CT16B0_CAP0 — Capture input 0 for 16-bit timer 0.
PIO0_3	14 ^[3]	yes	I/O	I; PU	PIO0_3 — General purpose digital input/output pin.
PIO0_4/SCL	15 ^[4]	yes	I/O	I; IA	PIO0_4 — General purpose digital input/output pin (open-drain).
			I/O	-	SCL — I ² C-bus, open-drain clock input/output. High-current sink only if I ² C Fast-mode Plus is selected in the I/O configuration register.
PIO0_5/SDA	16 ^[4]	yes	I/O	I; IA	PIO0_5 — General purpose digital input/output pin (open-drain).
			I/O	-	SDA — I ² C-bus, open-drain data input/output. High-current sink only if I ² C Fast-mode Plus is selected in the I/O configuration register.
PIO0_6/SCK0	22 ^[3]	yes	I/O	I; PU	PIO0_6 — General purpose digital input/output pin.
			I/O	-	SCK0 — Serial clock for SPI0.
PIO0_7/CTS	23 ^[3]	yes	I/O	I; PU	PIO0_7 — General purpose digital input/output pin (high-current output driver).
			I	-	CTS — Clear To Send input for UART.
PIO0_8/MISO0/ CT16B0_MAT0	27 ^[3]	yes	I/O	I; PU	PIO0_8 — General purpose digital input/output pin.
			I/O	-	MISO0 — Master In Slave Out for SPI0.
			O	-	CT16B0_MAT0 — Match output 0 for 16-bit timer 0.
PIO0_9/MOSI0/ CT16B0_MAT1	28 ^[3]	yes	I/O	I; PU	PIO0_9 — General purpose digital input/output pin.
			I/O	-	MOSI0 — Master Out Slave In for SPI0.
			O	-	CT16B0_MAT1 — Match output 1 for 16-bit timer 0.

Table 9. LPC1100 and LPC1100L series: LPC1111/12/13/14 pin description table (HVQFN33 package) ...continued

Symbol	Pin	Start logic input	Type	Reset state [1]	Description
PIO1_7/TXD/ CT32B0_MAT1	32 ^[3]	no	I/O	I;PU	PIO1_7 — General purpose digital input/output pin.
			O	-	TXD — Transmitter output for UART.
			O	-	CT32B0_MAT1 — Match output 1 for 32-bit timer 0.
PIO1_8/ CT16B1_CAP0	7 ^[3]	no	I/O	I;PU	PIO1_8 — General purpose digital input/output pin.
			I	-	CT16B1_CAP0 — Capture input 0 for 16-bit timer 1.
PIO1_9/ CT16B1_MAT0	12 ^[3]	no	I/O	I;PU	PIO1_9 — General purpose digital input/output pin.
			O	-	CT16B1_MAT0 — Match output 0 for 16-bit timer 1.
PIO1_10/AD6/ CT16B1_MAT1	20 ^[5]	no	I/O	I;PU	PIO1_10 — General purpose digital input/output pin.
			I	-	AD6 — A/D converter, input 6.
			O	-	CT16B1_MAT1 — Match output 1 for 16-bit timer 1.
PIO1_11/AD7	27 ^[5]	no	I/O	I;PU	PIO1_11 — General purpose digital input/output pin.
			I	-	AD7 — A/D converter, input 7.
PIO2_0					Port 2 — Port 2 is a 12-bit I/O port with individual direction and function controls for each bit. The operation of port 2 pins depends on the function selected through the IOCONFIG register block. Pins PIO2_1 to PIO2_11 are not available.
PIO2_0/DTR	1 ^[3]	no	I/O	I;PU	PIO2_0 — General purpose digital input/output pin.
			O	-	DTR — Data Terminal Ready output for UART.
PIO3_0 to PIO3_5					Port 3 — Port 3 is a 12-bit I/O port with individual direction and function controls for each bit. The operation of port 3 pins depends on the function selected through the IOCONFIG register block. Pins PIO3_0, PIO3_1, PIO3_3 and PIO3_6 to PIO3_11 are not available.
PIO3_2	28 ^[3]	no	I/O	I;PU	PIO3_2 — General purpose digital input/output pin.
PIO3_4	13 ^[3]	no	I/O	I;PU	PIO3_4 — General purpose digital input/output pin.
PIO3_5	14 ^[3]	no	I/O	I;PU	PIO3_5 — General purpose digital input/output pin.
V _{DD}	6; 29	-	I	-	3.3 V supply voltage to the internal regulator, the external rail, and the ADC. Also used as the ADC reference voltage.
XTALIN	4 ^[6]	-	I	-	Input to the oscillator circuit and internal clock generator circuits. Input voltage must not exceed 1.8 V.
XTALOUT	5 ^[6]	-	O	-	Output from the oscillator amplifier.
V _{SS}	33	-	-	-	Thermal pad. Connect to ground.

- [1] Pin state at reset for default function: I = Input; O = Output; PU = internal pull-up enabled (pins pulled up to 2.6 V for LPC111x/101/201/301, pins pulled up to full V_{DD} level on LPC111x/002/102/202/302 (V_{DD} = 3.3 V)); IA = inactive, no pull-up/down enabled.
- [2] 5 V tolerant pad. **RESET** functionality is not available in Deep power-down mode. Use the WAKEUP pin to reset the chip and wake up from Deep power-down mode. An external pull-up resistor is required on this pin for the Deep power-down mode. See Figure 52 for the reset pad configuration.
- [3] 5 V tolerant pad providing digital I/O functions with configurable pull-up/pull-down resistors and configurable hysteresis (see Figure 51).
- [4] I²C-bus pads compliant with the I²C-bus specification for I²C standard mode and I²C Fast-mode Plus. The pin requires an external pull-up to provide output functionality. When power is switched off, this pin is floating and does not disturb the I2C lines. Open-drain configuration applies to all functions on this pin.
- [5] 5 V tolerant pad providing digital I/O functions with configurable pull-up/pull-down resistors, configurable hysteresis, and analog input. When configured as a ADC input, digital section of the pad is disabled, and the pin is not 5 V tolerant (see Figure 51).

Table 10. LPC1100XL series: LPC1113/14/15 pin description table (LQFP48 and TFBGA48 package) ...continued

Symbol	LQFP48	TFBGA48	Start logic input	Type	Reset state [1]	Description
PIO2_2/ $\overline{\text{DCD}}$ /MISO1	26 ^[3]	G8 ^[3]	no	I/O	I; PU	PIO2_2 — General purpose digital input/output pin.
				I	-	DCD — Data Carrier Detect input for UART.
				I/O	-	MISO1 — Master In Slave Out for SPI1.
PIO2_3/ $\overline{\text{RI}}$ /MOSI1	38 ^[3]	A7 ^[3]	no	I/O	I; PU	PIO2_3 — General purpose digital input/output pin.
				I	-	RI — Ring Indicator input for UART.
				I/O	-	MOSI1 — Master Out Slave In for SPI1.
PIO2_4/ CT16B1_MAT1/ SSEL1	19 ^[3]	G5 ^[3]	no	I/O	I; PU	PIO2_4 — General purpose digital input/output pin.
				O	-	CT16B1_MAT1 — Match output 1 for 16-bit timer 1.
				O	-	SSEL1 — Slave Select for SPI1.
PIO2_5/ CT32B0_MAT0	20 ^[3]	H5 ^[3]	no	I/O	I; PU	PIO2_5 — General purpose digital input/output pin.
				O	-	CT32B0_MAT0 — Match output 0 for 32-bit timer 0.
PIO2_6/ CT32B0_MAT1	1 ^[3]	A1 ^[3]	no	I/O	I; PU	PIO2_6 — General purpose digital input/output pin.
				O	-	CT32B0_MAT1 — Match output 1 for 32-bit timer 0.
PIO2_7/ CT32B0_MAT2/RXD	11 ^[3]	G2 ^[3]	no	I/O	I; PU	PIO2_7 — General purpose digital input/output pin.
				O	-	CT32B0_MAT2 — Match output 2 for 32-bit timer 0.
				I	-	RXD — Receiver input for UART.
PIO2_8/ CT32B0_MAT3/TXD	12 ^[3]	G1 ^[3]	no	I/O	I; PU	PIO2_8 — General purpose digital input/output pin.
				O	-	CT32B0_MAT3 — Match output 3 for 32-bit timer 0.
				O	-	TXD — Transmitter output for UART.
PIO2_9/ CT32B0_CAP0	24 ^[3]	H7 ^[3]	no	I/O	I; PU	PIO2_9 — General purpose digital input/output pin.
				I	-	CT32B0_CAP0 — Capture input 0 for 32-bit timer 0.
PIO2_10	25 ^[3]	H8 ^[3]	no	I/O	I; PU	PIO2_10 — General purpose digital input/output pin.
PIO2_11/SCK0/ CT32B0_CAP1	31 ^[3]	D7 ^[3]	no	I/O	I; PU	PIO2_11 — General purpose digital input/output pin.
				I/O	-	SCK0 — Serial clock for SPI0.
				I	-	CT32B0_CAP1 — Capture input for 32-bit timer 0.
PIO3_0 to PIO3_5				I/O		Port 3 — Port 3 is a 12-bit I/O port with individual direction and function controls for each bit. The operation of port 3 pins depends on the function selected through the IOCONFIG register block. Pins PIO3_6 to PIO3_11 are not available.
PIO3_0/ $\overline{\text{DTR}}$ / CT16B0_MAT0/TXD	36 ^[3]	B8 ^[3]	no	I/O	I; PU	PIO3_0 — General purpose digital input/output pin.
				O	-	DTR — Data Terminal Ready output for UART.
				O	-	CT16B0_MAT0 — Match output 0 for 16-bit timer 0.
				O	-	TXD — Transmitter Output for UART.
PIO3_1/ $\overline{\text{DSR}}$ / CT16B0_MAT1/RXD	37 ^[3]	A8 ^[3]	no	I/O	I; PU	PIO3_1 — General purpose digital input/output pin.
				I	-	DSR — Data Set Ready input for UART.
				O	-	CT16B0_MAT1 — Match output 1 for 16-bit timer 0.
				I	-	RXD — Receiver input for UART.

Table 11. LPC1100XL series: LPC1111/12/13/14 pin description table (HVQFN33 package) ...continued

Symbol	Pin	Start logic input	Type	Reset state [1]	Description
V _{DD}	6; 29	-	I	-	3.3 V supply voltage to the internal regulator, the external rail, and the ADC. Also used as the ADC reference voltage.
XTALIN	4[6]	-	I	-	Input to the oscillator circuit and internal clock generator circuits. Input voltage must not exceed 1.8 V.
XTALOUT	5[6]	-	O	-	Output from the oscillator amplifier.
V _{SS}	33	-	-	-	Thermal pad. Connect to ground.

- [1] Pin state at reset for default function: I = Input; O = Output; PU = internal pull-up enabled (pins pulled up to full V_{DD} level (V_{DD} = 3.3 V)); IA = inactive, no pull-up/down enabled.
- [2] 5 V tolerant pad. **RESET** functionality is not available in Deep power-down mode. Use the WAKEUP pin to reset the chip and wake up from Deep power-down mode. An external pull-up resistor is required on this pin for the Deep power-down mode. See [Figure 52](#) for the reset pad configuration.
- [3] 5 V tolerant pad providing digital I/O functions with configurable pull-up/pull-down resistors and configurable hysteresis (see [Figure 51](#)).
- [4] I²C-bus pads compliant with the I²C-bus specification for I²C standard mode and I²C Fast-mode Plus. The pin requires an external pull-up to provide output functionality. When power is switched off, this pin is floating and does not disturb the I2C lines. Open-drain configuration applies to all functions on this pin.
- [5] 5 V tolerant pad providing digital I/O functions with configurable pull-up/pull-down resistors, configurable hysteresis, and analog input. When configured as a ADC input, digital section of the pad is disabled, and the pin is not 5 V tolerant (see [Figure 51](#)).
- [6] When the system oscillator is not used, connect XTALIN and XTALOUT as follows: XTALIN can be left floating or can be grounded (grounding is preferred to reduce susceptibility to noise). XTALOUT should be left floating.

- On the LPC1100L and LPC1100XL series, all GPIO pins (except PIO0_4 and PIO0_5) are pulled up to 3.3 V ($V_{DD} = 3.3$ V) if their pull-up resistor is enabled in the IOCONFIG block.
- Programmable open-drain mode for series LPC1100L and LPC1100XL.

7.8 UART

The LPC1110/11/12/13/14/15 contain one UART.

Support for RS-485/9-bit mode allows both software address detection and automatic address detection using 9-bit mode.

The UART includes a fractional baud rate generator. Standard baud rates such as 115200 Bd can be achieved with any crystal frequency above 2 MHz.

7.8.1 Features

- Maximum UART data bit rate of 3.125 MBit/s.
- 16 Byte Receive and Transmit FIFOs.
- Register locations conform to 16C550 industry standard.
- Receiver FIFO trigger points at 1 B, 4 B, 8 B, and 14 B.
- Built-in fractional baud rate generator covering wide range of baud rates without a need for external crystals of particular values.
- FIFO control mechanism that enables software flow control implementation.
- Support for RS-485/9-bit mode.
- Support for modem control.

7.9 SPI serial I/O controller

The LPC1100 and LPC1100L series contain two SPI controllers on the LQFP48 package and one SPI controller on the HVQFN33/TSSOP28/DIP28/TSSOP20/SO20 packages (SPI0).

The LPC1100XL series contain two SPI controllers.

Both SPI controllers support SSP features.

The SPI controller is capable of operation on a SSP, 4-wire SSI, or Microwire bus. It can interact with multiple masters and slaves on the bus. Only a single master and a single slave can communicate on the bus during a given data transfer. The SPI supports full duplex transfers, with frames of 4 bits to 16 bits of data flowing from the master to the slave and from the slave to the master. In practice, often only one of these data flows carries meaningful data.

7.9.1 Features

- Maximum SPI speed of 25 Mbit/s (master) or 4.17 Mbit/s (slave) (in SSP mode)
- Compatible with Motorola SPI, 4-wire Texas Instruments SSI, and National Semiconductor Microwire buses
- Synchronous serial communication

Table 16. Static characteristics (LPC1100, LPC1100L series) ...continued

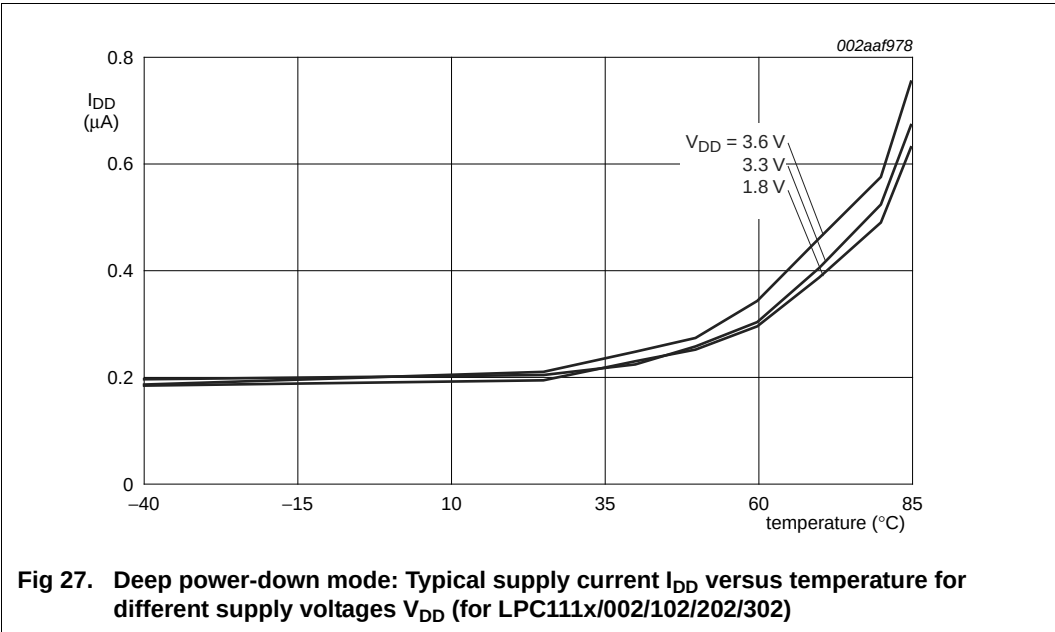
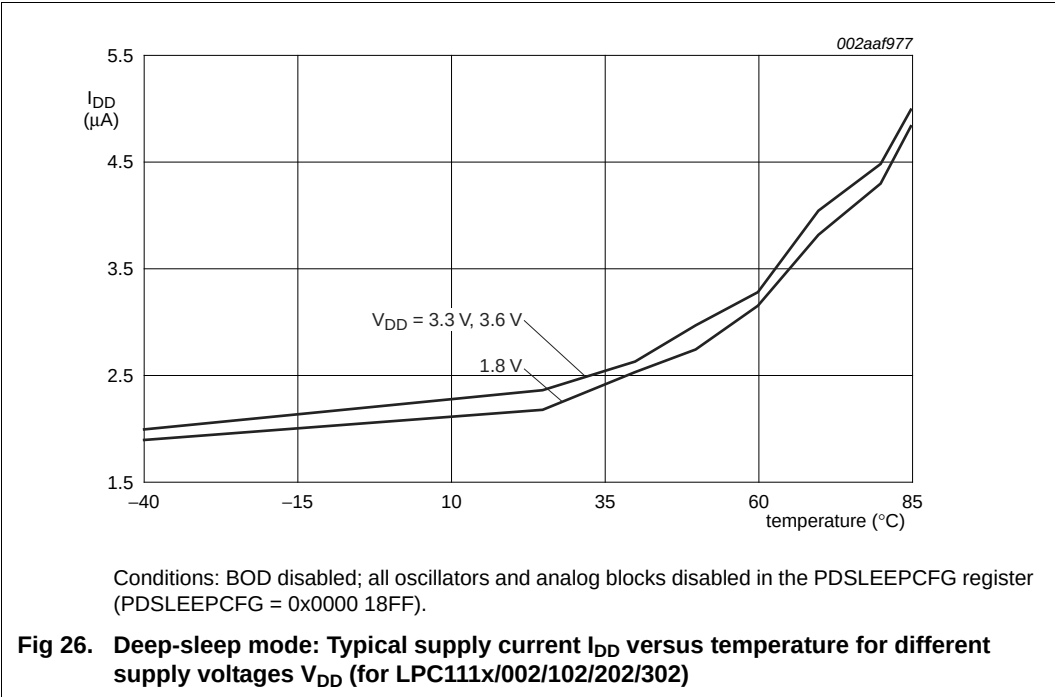
 $T_{amb} = -40\text{ }^{\circ}\text{C}$ to $+85\text{ }^{\circ}\text{C}$, unless otherwise specified.

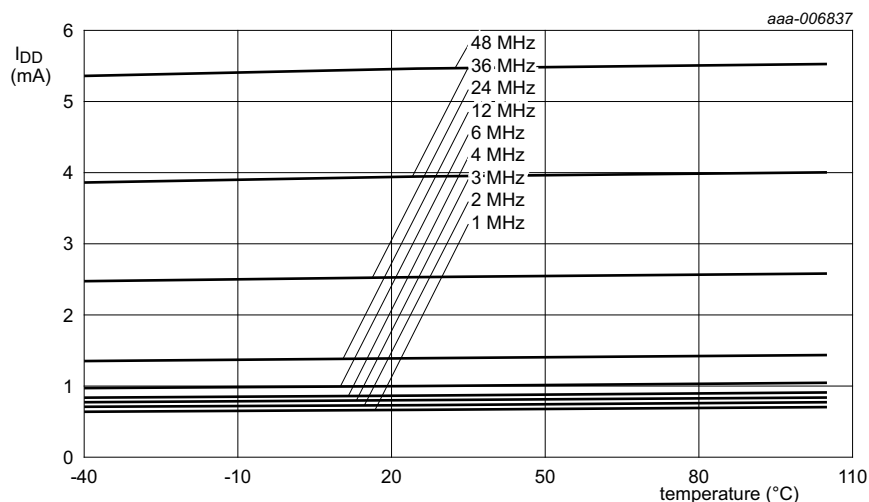
Symbol	Parameter	Conditions	Min	Typ ^[1]	Max	Unit
Standard port pins, RESET						
I _{IL}	LOW-level input current	V _I = 0 V; on-chip pull-up resistor disabled	-	0.5	10	nA
I _{IH}	HIGH-level input current	V _I = V _{DD} ; on-chip pull-down resistor disabled	-	0.5	10	nA
I _{OZ}	OFF-state output current	V _O = 0 V; V _O = V _{DD} ; on-chip pull-up/down resistors disabled	-	0.5	10	nA
V _I	input voltage	pin configured to provide a digital function ^{[12][13][14]}	0	-	5.0	V
V _O	output voltage	output active	0	-	V _{DD}	V
V _{IH}	HIGH-level input voltage		0.7V _{DD}	-	-	V
V _{IL}	LOW-level input voltage		-	-	0.3V _{DD}	V
V _{hys}	hysteresis voltage		-	0.4	-	V
V _{OH}	HIGH-level output voltage	2.5 V ≤ V _{DD} ≤ 3.6 V; I _{OH} = −4 mA	V _{DD} − 0.4	-	-	V
		1.8 V ≤ V _{DD} < 2.5 V; I _{OH} = −3 mA	V _{DD} − 0.4	-	-	V
V _{OL}	LOW-level output voltage	2.5 V ≤ V _{DD} ≤ 3.6 V; I _{OL} = 4 mA	-	-	0.4	V
		1.8 V ≤ V _{DD} < 2.5 V; I _{OL} = 3 mA	-	-	0.4	V
I _{OH}	HIGH-level output current	V _{OH} = V _{DD} − 0.4 V; 2.5 V ≤ V _{DD} ≤ 3.6 V	−4	-	-	mA
		1.8 V ≤ V _{DD} < 2.5 V	−3	-	-	mA
I _{OL}	LOW-level output current	V _{OL} = 0.4 V 2.5 V ≤ V _{DD} ≤ 3.6 V	4	-	-	mA
		1.8 V ≤ V _{DD} < 2.5 V	3	-	-	mA
I _{OHS}	HIGH-level short-circuit output current	V _{OH} = 0 V ^[15]	-	-	−45	mA
I _{OLS}	LOW-level short-circuit output current	V _{OL} = V _{DD} ^[15]	-	-	50	mA
I _{pd}	pull-down current	V _I = 5 V	10	50	150	μA
I _{pu}	pull-up current	V _I = 0 V; 2.0 V ≤ V _{DD} ≤ 3.6 V	−15	−50	−85	μA
		1.8 V ≤ V _{DD} < 2.0 V	−10	−50	−85	μA
		V _{DD} < V _I < 5 V	0	0	0	μA
High-drive output pin (PIO0_7)						
I _{IL}	LOW-level input current	V _I = 0 V; on-chip pull-up resistor disabled	-	0.5	10	nA
I _{IH}	HIGH-level input current	V _I = V _{DD} ; on-chip pull-down resistor disabled	-	0.5	10	nA

Table 16. Static characteristics (LPC1100, LPC1100L series) ...continued

 $T_{amb} = -40\text{ }^{\circ}\text{C}$ to $+85\text{ }^{\circ}\text{C}$, unless otherwise specified.

Symbol	Parameter	Conditions	Min	Typ ^[1]	Max	Unit
I _{OZ}	OFF-state output current	V _O = 0 V; V _O = V _{DD} ; on-chip pull-up/down resistors disabled	-	0.5	10	nA
V _I	input voltage	pin configured to provide a digital function ^{[12][13]} ^[14]	0	-	5.0	V
V _O	output voltage	output active	0	-	V _{DD}	V
V _{IH}	HIGH-level input voltage		0.7V _{DD}	-	-	V
V _{IL}	LOW-level input voltage		-	-	0.3V _{DD}	V
V _{hys}	hysteresis voltage		0.4	-	-	V
V _{OH}	HIGH-level output voltage	2.5 V ≤ V _{DD} ≤ 3.6 V; I _{OH} = −20 mA	V _{DD} − 0.4	-	-	V
		1.8 V ≤ V _{DD} < 2.5 V; I _{OH} = −12 mA	V _{DD} − 0.4	-	-	V
V _{OL}	LOW-level output voltage	2.5 V ≤ V _{DD} ≤ 3.6 V; I _{OL} = 4 mA	-	-	0.4	V
		1.8 V ≤ V _{DD} < 2.5 V; I _{OL} = 3 mA	-	-	0.4	V
I _{OH}	HIGH-level output current	V _{OH} = V _{DD} − 0.4 V; 2.5 V ≤ V _{DD} ≤ 3.6 V	20	-	-	mA
		1.8 V ≤ V _{DD} < 2.5 V	12	-	-	mA
I _{OL}	LOW-level output current	V _{OL} = 0.4 V 2.5 V ≤ V _{DD} ≤ 3.6 V	4	-	-	mA
		1.8 V ≤ V _{DD} < 2.5 V	3	-	-	mA
I _{OLS}	LOW-level short-circuit output current	V _{OL} = V _{DD} ^[15]	-	-	50	mA
I _{pd}	pull-down current	V _I = 5 V	10	50	150	μA
I _{pu}	pull-up current	V _I = 0 V 2.0 V ≤ V _{DD} ≤ 3.6 V	−15	−50	−85	μA
		1.8 V ≤ V _{DD} < 2.0 V	−10	−50	−85	μA
		V _{DD} < V _I < 5 V	0	0	0	μA
I ² C-bus pins (PIO0_4 and PIO0_5)						
V _{IH}	HIGH-level input voltage		0.7V _{DD}	-	-	V
V _{IL}	LOW-level input voltage		-	-	0.3V _{DD}	V
V _{hys}	hysteresis voltage		-	0.05V _{DD}	-	V
I _{OL}	LOW-level output current	V _{OL} = 0.4 V; I ² C-bus pins configured as standard mode pins 2.5 V ≤ V _{DD} ≤ 3.6 V	3.5	-	-	mA
		1.8 V ≤ V _{DD} < 2.5 V	3	-	-	





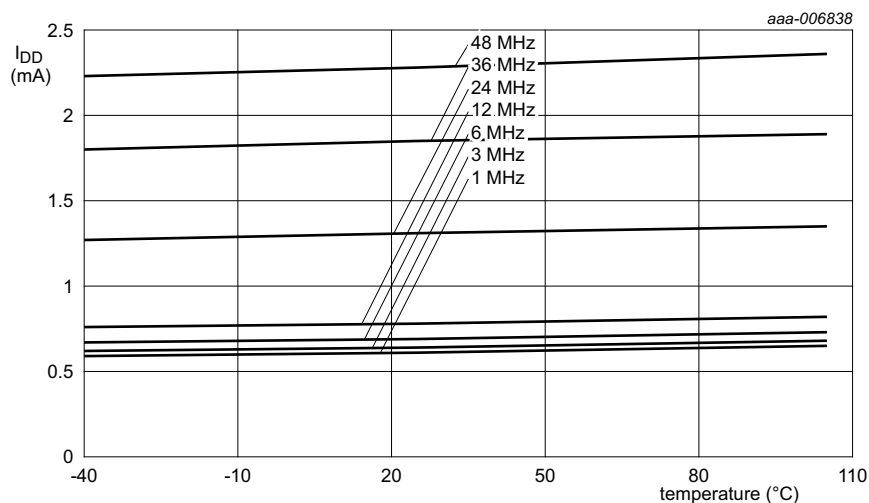
Conditions: $V_{DD} = 3.3$ V; active mode entered executing code `while(1){}` from flash; all peripherals disabled in the SYSAHBCLKCTRL register (SYSAHBCLKCTRL = 0x1F); all peripheral clocks disabled; internal pull-up resistors disabled; BOD disabled; low-current mode.

1 MHz to 6 MHz: system oscillator enabled; PLL, IRC disabled.

12 MHz: IRC enabled; system oscillator, PLL disabled.

24 MHz to 48 MHz: IRC disabled; system oscillator, PLL enabled.

Fig 29. Active mode: Typical supply current I_{DD} versus temperature for different system clock frequencies (for LPC111xXL)



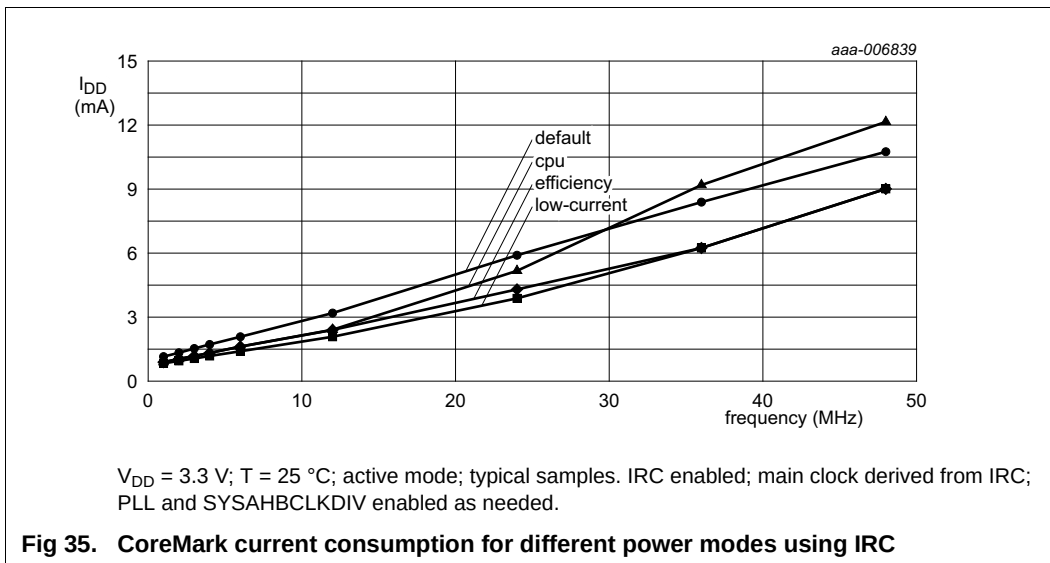
Conditions: $V_{DD} = 3.3$ V; sleep mode entered from flash; all peripherals disabled in the SYSAHBCLKCTRL register (SYSAHBCLKCTRL = 0x1F); all peripheral clocks disabled; internal pull-up resistors disabled; BOD disabled; low-current mode.

1 MHz to 6 MHz: system oscillator enabled; PLL, IRC disabled.

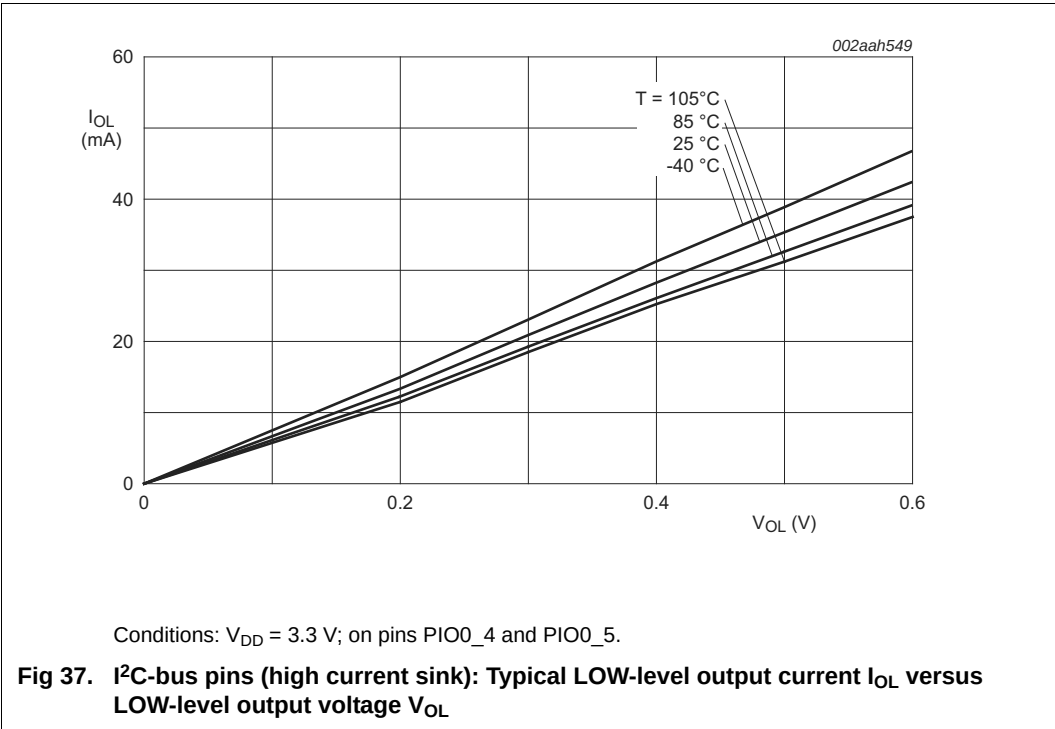
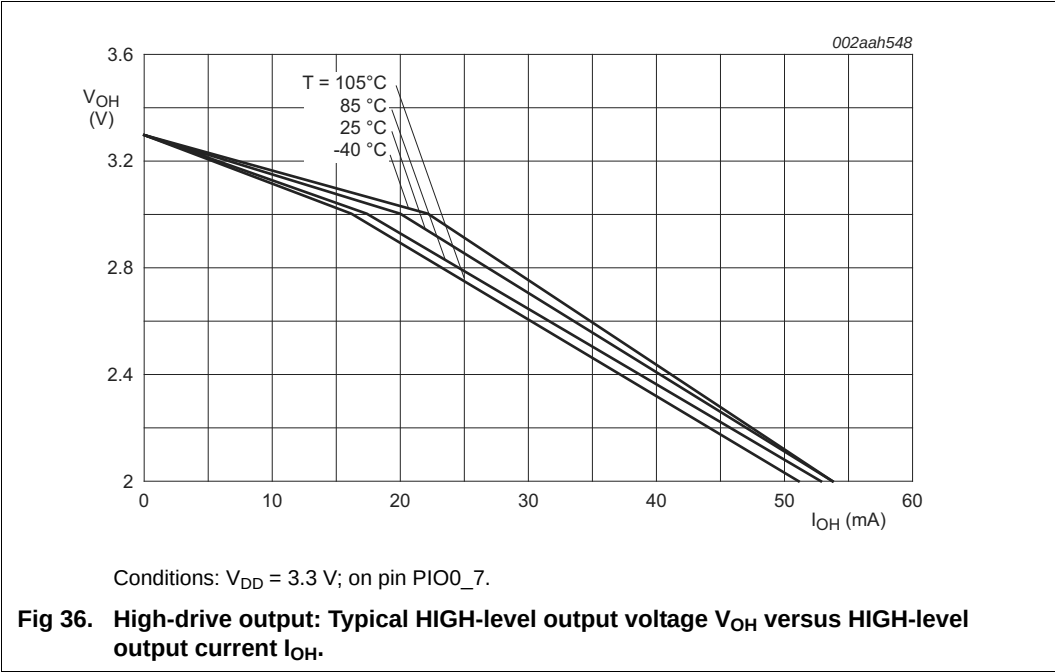
12 MHz: IRC enabled; system oscillator, PLL disabled.

24 MHz to 48 MHz: IRC disabled; system oscillator, PLL enabled.

Fig 30. Sleep mode: Typical supply current I_{DD} versus temperature for different system clock frequencies (for LPC111xXL)



10.10 Electrical pin characteristics



HVQFN33: plastic thermal enhanced very thin quad flat package; no leads;
33 terminals; body 7 x 7 x 0.85 mm

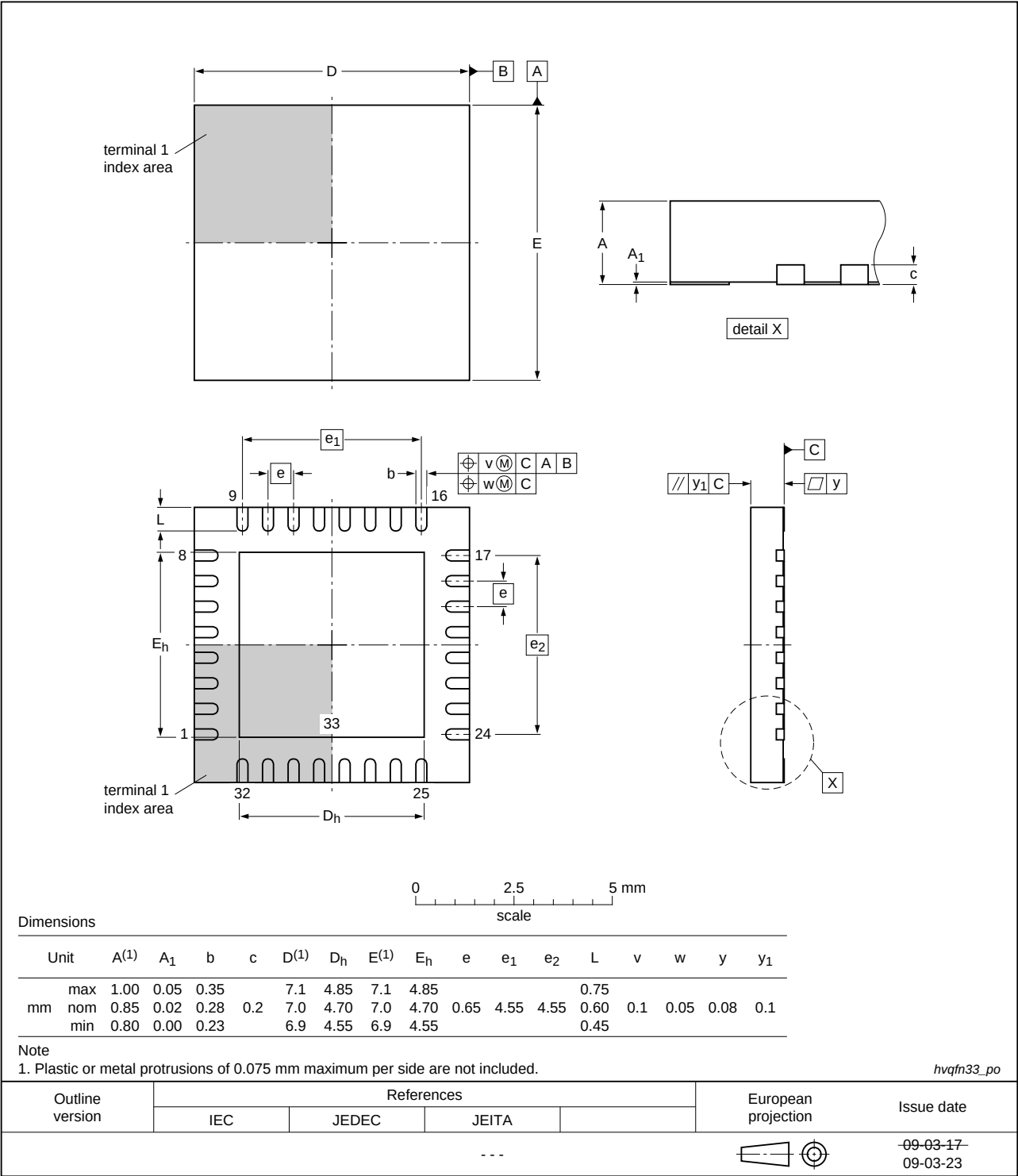


Fig 59. Package outline (HVQFN33 7x7)

TFBGA48: plastic thin fine-pitch ball grid array package; 48 balls; body 4.5 x 4.5 x 0.7 mm

SOT1155-2

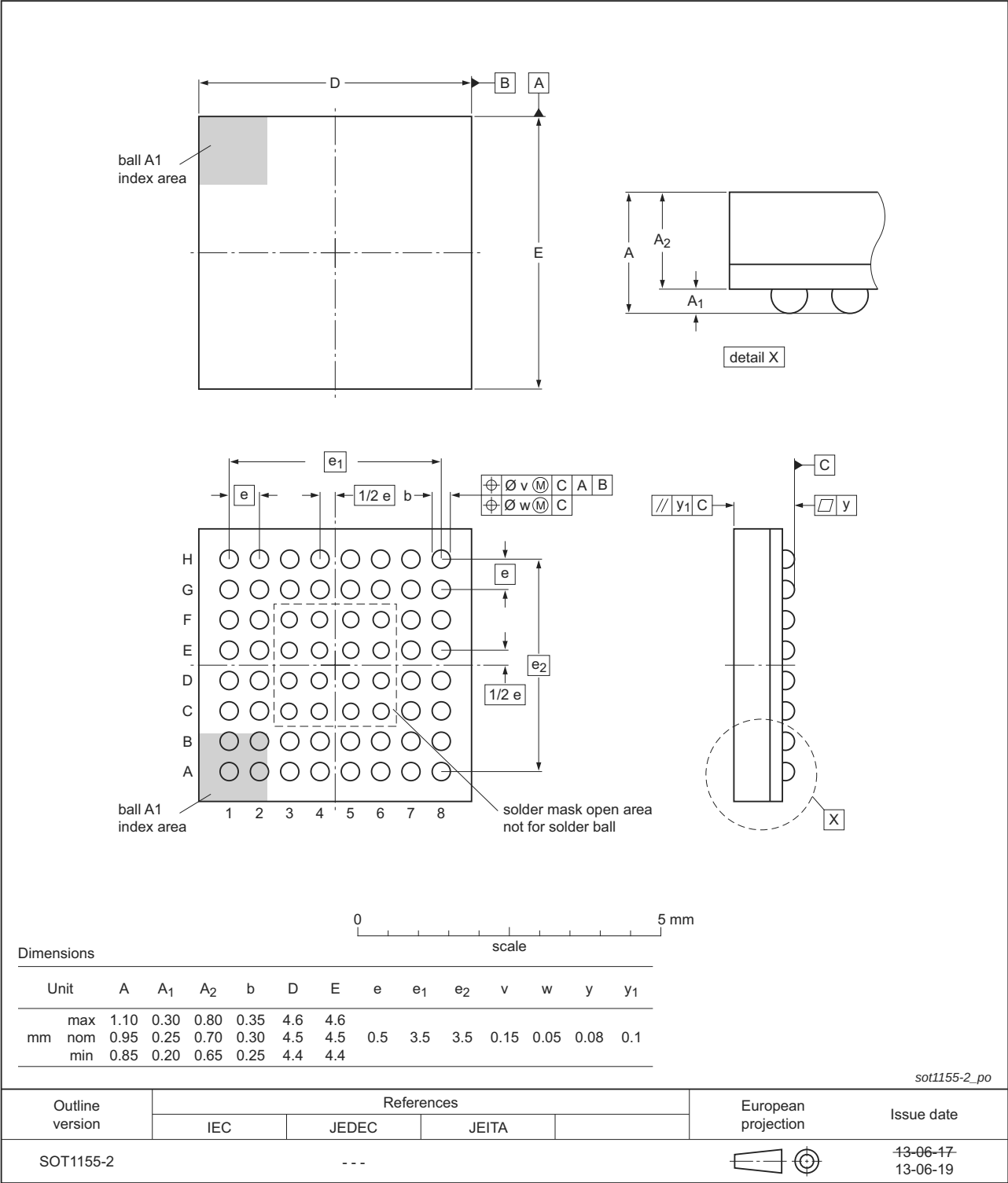


Fig 62. Package outline TFBGA48 (SOT1155-2)

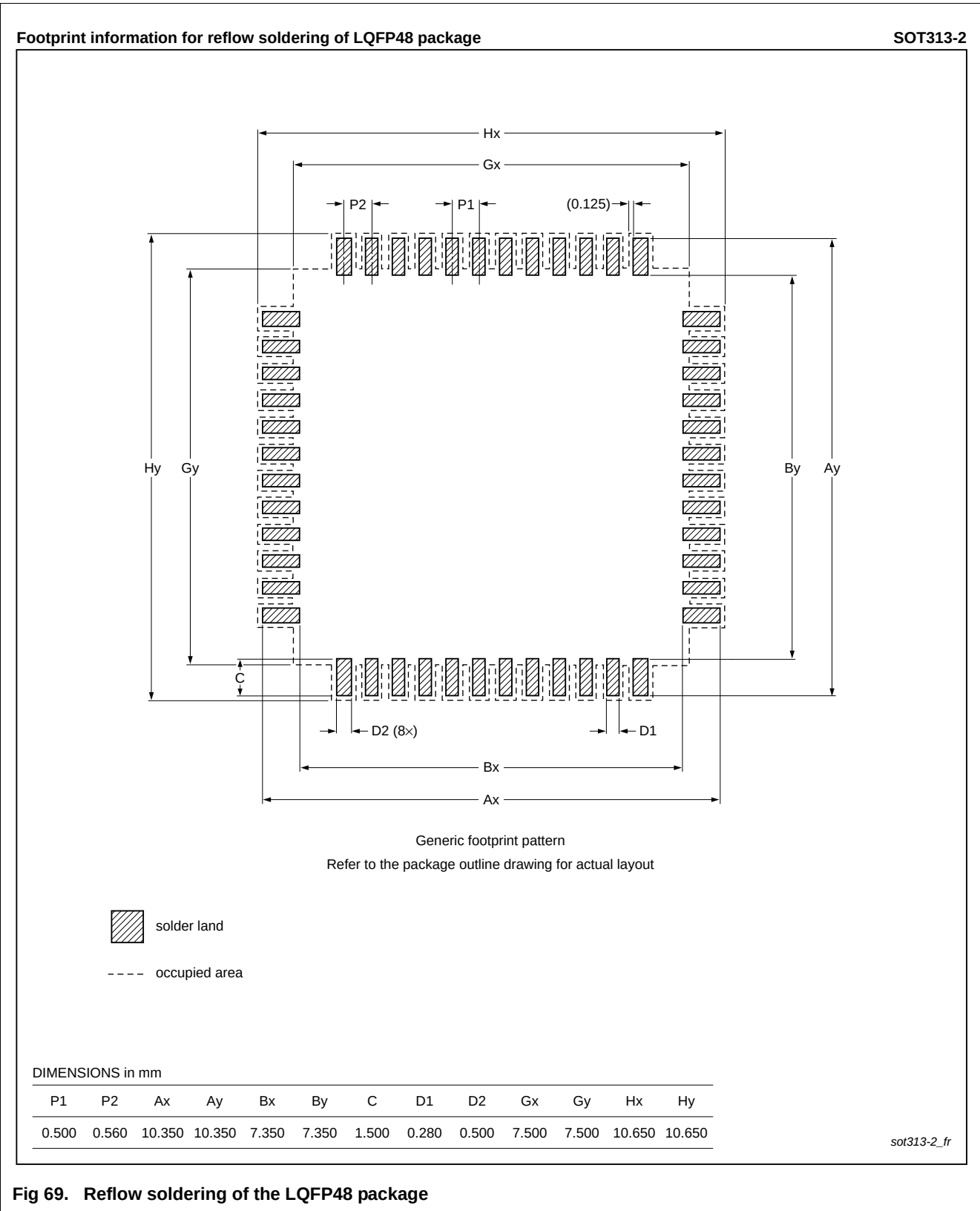


Fig 69. Reflow soldering of the LQFP48 package

Table 34. Revision history ...continued

Document ID	Release date	Data sheet status	Change notice	Supersedes
Modifications:	BOD level 0 for reset added in Table 15.			
LPC111X v.7.4	20120730	Product data sheet	-	LPC111X v.7.3
Modifications:	- Function SSEL1 added to pin PIO2_0 in Figure 6 "LPC1100XL series pin configuration HVQFN33" and Table 11 "LPC1100XL series: LPC1111/12/13/14 pin description table (HVQFN33 package)". - BOD level 0 for reset and interrupt removed.			
LPC111X v.7.3	20120706	Product data sheet	-	LPC111X v.7.2
Modifications:	Corrected pinout for part LPC1112FHN24/202. Pin XTALOUT replaced by V_{DD}. See Table 6 and Figure 10.			
LPC111X v.7.2	20120604	Product data sheet	-	LPC111X v.7.1
Modifications:	- For parameters I_{OL}, V_{OL}, I_{OH}, V_{OH}, changed conditions to 1.8 V ≤ V_{DD} < 2.5 V and 2.5 V ≤ V_{DD} ≤ 3.6 V in Table 13). - Capture-clear feature added to general-purpose counter/timers (see Section 7.12; LPC1100XL series only). - Figure 47 updated for parts with configurable open-drain mode. - Added Section 9.5 "CoreMark data" - Added LPC1100L series part (LPC1112FHN24/202). - WDOSc frequency range corrected.			
LPC111X v.7.1	20120401	Product data sheet	-	LPC111X v.7
Modifications:	Added HVQFN33 (5x5) reflow soldering information.			
LPC111X v.7	20120301	Product data sheet	-	LPC1110_11_12_13_14 v.6
Modifications:	LPC1100XL series parts added (LPC1111FHN33/103, LPC1111FHN33/203, LPC1112FHN33/103, LPC1112FHN33/203, LPC1112FHI33/203, LPC1113FBD48/303, LPC1113FHN33/203, LPC1113FHN33/303, LPC1114FBD48/303, LPC1114FHN33/203, LPC1114FHN33/303, LPC1114FHI33/303, LPC1114FBD48/323, LPC1114FBD48/333, LPC1114FHN33/333, LPC1115FBD48/303).			
LPC1110_11_12_13_14 v.6	20111102	Product data sheet	-	LPC1111_12_13_14 v.5
Modifications:	- Parts LPC1112FHI33/202 and LPC1114FHI33/302 added. - Parts LPC1112FDH28/102, LPC1114FDH28/102, LPC1114FN28/102, LPC1112FDH20/102, LPC1110FD20, LPC1111FDH20/002, LPC1112FD20/102 added.			
LPC1111_12_13_14 v.5	20110622	Product data sheet	-	LPC1111_12_13_14 v.4
Modifications:	- ADC sampling frequency corrected in Table 7 (Table note 7). - Pull-up level specified in Table 3 to Table 4 and Section 7.7.1. - Parameter T_{cy(clk)} corrected on Table 17. - WWDT for parts LPC111x/102/202/302 added in Section 2 and Section 7.15. - Programmable open-drain mode for parts LPC111x/102/202/302 added in Section 2 and Section 7.12. - Condition for parameter T_{stg} in Table 5 updated. - Table note 4 of Table 5 updated. - Section 13 added. - Removed PLCC44 package information.			
LPC1111_12_13_14 v.4	20110210	Product data sheet	-	LPC1111_12_13_14 v.3