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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M0
Core Size	32-Bit Single-Core
Speed	50MHz
Connectivity	I ² C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, WDT
Number of I/O	28
Program Memory Size	24KB (24K x 8)
Program Memory Type	FLASH
EEPROM Size	<u>.</u>
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	48-LQFP
Supplier Device Package	48-LQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/lpc1113jbd48-303ql

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

32-bit ARM Cortex-M0 microcontroller

- LPC1100L series available as TSSOP28 package, DIP28 package, TSSOP20 package, and SO20 package.
- Extended temperature (-40 °C to +105 °C) for selected parts (see <u>Table 2</u>).

3. Applications

- eMetering
- Alarm systems

- Lighting
- White goods

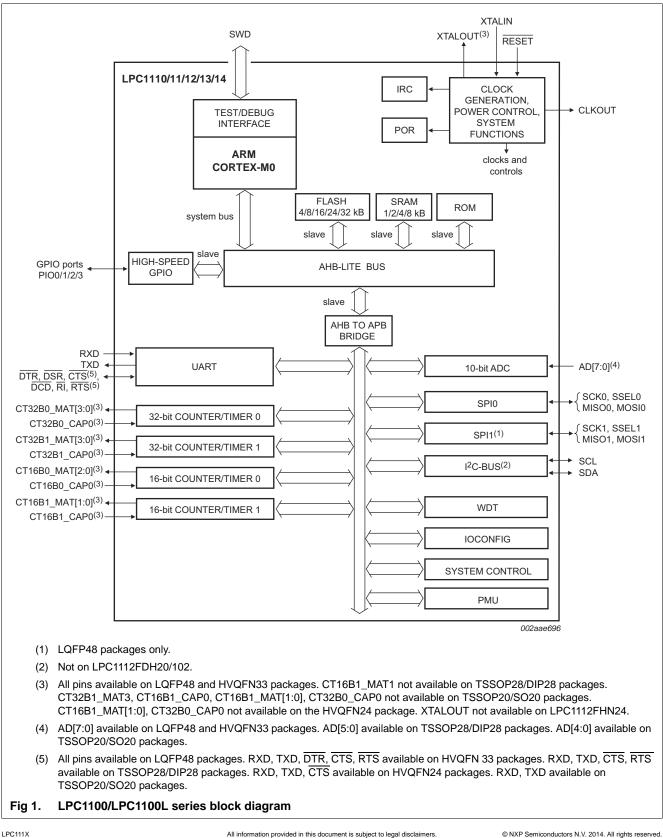
4. Ordering information

Type number	Package		
	Name	Description	Version
SO20, TSSOP20, TSS	OP28, and DI	P28 packages	
LPC1110FD20	SO20	SO20: plastic small outline package; 20 leads; body width 7.5 mm	SOT163-1
LPC1111FDH20/002	TSSOP20	TSSOP20: plastic thin shrink small outline package; 20 leads; body width 4.4 mm	SOT360-1
LPC1112FD20/102	SO20	SO20: plastic small outline package; 20 leads; body width 7.5 mm	SOT163-1
LPC1112FDH20/102	TSSOP20	TSSOP20: plastic thin shrink small outline package; 20 leads; body width 4.4 mm	SOT360-1
LPC1112FDH28/102	TSSOP28	TSSOP28: plastic thin shrink small outline package; 28 leads; body width 4.4 mm	SOT361-1
LPC1114FDH28/102	TSSOP28	TSSOP28: plastic thin shrink small outline package; 28 leads; body width 4.4 mm	SOT361-1
LPC1114FN28/102	DIP28	DIP28: plastic dual in-line package; 28 leads (600 mil)	SOT117-1
HVQFN24/33, LQFP48	3, and TFBGA	48 packages	
LPC1111FHN33/101	HVQFN33	HVQFN: plastic thermal enhanced very thin quad flat package; no leads; 33 terminals; body $7 \times 7 \times 0.85$ mm	n/a
LPC1111FHN33/102	HVQFN33	HVQFN: plastic thermal enhanced very thin quad flat package; no leads; 33 terminals; body $7 \times 7 \times 0.85$ mm	n/a
LPC1111FHN33/201	HVQFN33	HVQFN: plastic thermal enhanced very thin quad flat package; no leads; 33 terminals; body $7 \times 7 \times 0.85$ mm	n/a
LPC1111FHN33/202	HVQFN33	HVQFN: plastic thermal enhanced very thin quad flat package; no leads; 33 terminals; body $7 \times 7 \times 0.85$ mm	n/a
LPC1111FHN33/103	HVQFN33	HVQFN: plastic thermal enhanced very thin quad flat package; no leads; 33 terminals; body $7 \times 7 \times 0.85$ mm	n/a
LPC1111JHN33/103	HVQFN33	HVQFN: plastic thermal enhanced very thin quad flat package; no leads; 33 terminals; body $7 \times 7 \times 0.85$ mm	n/a
LPC1111FHN33/203	HVQFN33	HVQFN: plastic thermal enhanced very thin quad flat package; no leads; 33 terminals; body $7 \times 7 \times 0.85$ mm	n/a
LPC1111JHN33/203	HVQFN33	HVQFN: plastic thermal enhanced very thin quad flat package; no leads; 33 terminals; body $7 \times 7 \times 0.85$ mm	n/a
LPC1112FHN33/101	HVQFN33	HVQFN: plastic thermal enhanced very thin quad flat package; no leads; 33 terminals; body $7 \times 7 \times 0.85$ mm	n/a
LPC1112FHN33/102	HVQFN33	HVQFN: plastic thermal enhanced very thin quad flat package; no leads; 33 terminals; body $7 \times 7 \times 0.85$ mm	n/a

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32-bit ARM Cortex-M0 microcontroller

5. Block diagram



32-bit ARM Cortex-M0 microcontroller

Symbol	Pin TSSOP20		Start logic input	Туре	Reset state [1]	Description
SWCLK/PIO0_10/	3	[3]	yes	I	I; PU	SWCLK — Serial wire clock.
SCK0/ CT16B0_MAT2				I/O	-	PIO0_10 — General purpose digital input/output pin.
CTIODU_WATZ				I/O	-	SCK0 — Serial clock for SPI0.
				0	-	CT16B0_MAT2 — Match output 2 for 16-bit timer 0.
R/PIO0_11/ AD0/CT32B0_MAT3	4	[4]	yes	I	I; PU	R — Reserved. Configure for an alternate function in the IOCONFIG block.
				I/O	-	PIO0_11 — General purpose digital input/output pin.
				I	-	AD0 — A/D converter, input 0.
				0	-	CT32B0_MAT3 — Match output 3 for 32-bit timer 0.
PIO1_0 to PIO1_7				I/O		Port 1 — Port 1 is a 12-bit I/O port with individual direction and function controls for each bit. The operation of port 1 pins depends on the function selected through the IOCONFIG register block.
R/PIO1_0/ AD1/CT32B1_CAP0	7	[4]	yes	I	I; PU	R — Reserved. Configure for an alternate function in the IOCONFIG block.
				I/O	-	PIO1_0 — General purpose digital input/output pin.
				I	-	AD1 — A/D converter, input 1.
				I	-	CT32B1_CAP0 — Capture input 0 for 32-bit timer 1.
R/PIO1_1/ AD2/CT32B1_MAT0	8	[4]	no	0	I; PU	R — Reserved. Configure for an alternate function in the IOCONFIG block.
				I/O	-	PIO1_1 — General purpose digital input/output pin.
				I	-	AD2 — A/D converter, input 2.
				0	-	CT32B1_MAT0 — Match output 0 for 32-bit timer 1.
R/PIO1_2/ AD3/CT32B1_MAT1	9	[4]	no	I	I; PU	 R — Reserved. Configure for an alternate function in the IOCONFIG block.
				I/O	-	PIO1_2 — General purpose digital input/output pin.
				I	-	AD3 — A/D converter, input 3.
				0	-	CT32B1_MAT1 — Match output 1 for 32-bit timer 1.
SWDIO/PIO1_3/	10	[4]	no	I/O	I; PU	SWDIO — Serial wire debug input/output.
AD4/CT32B1_MAT2				I/O	-	PIO1_3 — General purpose digital input/output pin.
				I	-	AD4 — A/D converter, input 4.
				0	-	CT32B1_MAT2 — Match output 2 for 32-bit timer 1.
PIO1_6/RXD/	11	[3]	no	I/O	I; PU	PIO1_6 — General purpose digital input/output pin.
CT32B0_MAT0				I	-	RXD — Receiver input for UART.
				0	-	CT32B0_MAT0 — Match output 0 for 32-bit timer 0.
PIO1_7/TXD/	12	[3]	no	I/O	I; PU	PIO1_7 — General purpose digital input/output pin.
CT32B0_MAT1				0	-	TXD — Transmitter output for UART.
				0	-	CT32B0_MAT1 — Match output 1 for 32-bit timer 0.
V _{DD}	15		-	I	-	3.3 V supply voltage to the internal regulator and the external rail.

Table 5. LPC1100L series: LPC1112 pin description table (TSSOP20 with V_{DDA} and V_{SSA} pins) ...continued

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Symbol	Pin TSSOP20	Start logic input	Туре	Reset state [1]	Description
V _{DDA}	5	-	I	-	3.3 V supply voltage to the ADC. Also used as the ADC reference voltage.
XTALIN	14 <u>[5]</u>	-	I	-	Input to the oscillator circuit and internal clock generator circuits. Input voltage must not exceed 1.8 V.
XTALOUT	13 <u>[5]</u>	-	0	-	Output from the oscillator amplifier.
V _{SS}	16	-	I	-	Ground.
V _{SSA}	6	-	I	-	Analog ground.

Table 5. LPC1100L series: LPC1112 pin description table (TSSOP20 with VDDA and VSSA pins) ... continued

[1] Pin state at reset for default function: I = Input; O = Output; PU = internal pull-up enabled (pins pulled up to full V_{DD} level); IA = inactive, no pull-up/down enabled.

[2] 5 V tolerant pad. RESET functionality is not available in Deep power-down mode.

[3] 5 V tolerant pad providing digital I/O functions with configurable pull-up/pull-down resistors and configurable hysteresis (see Figure 51).

[4] 5 V tolerant pad providing digital I/O functions with configurable pull-up/pull-down resistors, configurable hysteresis, and analog input. When configured as a ADC input, digital section of the pad is disabled and the pin is not 5 V tolerant (see Figure 51).

[5] When the system oscillator is not used, connect XTALIN and XTALOUT as follows: XTALIN can be left floating or can be grounded (grounding is preferred to reduce susceptibility to noise). XTALOUT should be left floating.

Symbol	HVQFN pin	Start logic input	Туре	Reset state [1]	Description
RESET/PIO0_0	1[2]	yes	I	I; PU	RESET — External reset input with 20 ns glitch filter. A LOW-going pulse as short as 50 ns on this pin resets the device, causing I/O ports and peripherals to take on their default states, and processor execution to begin at address 0.
					In deep power- <u>down mode</u> , this pin must be pulled HIGH externally. The RESET pin can be left unconnected or be used as a GPIO pin if an external RESET function is not needed and Deep power-down mode is not used.
			I/O	-	PIO0_0 — General purpose digital input/output pin with 10 ns glitch filter.
PIO0_1/CLKOUT/ CT32B0_MAT2	2 <u>[3]</u>	yes	I/O	I; PU	PIO0_1 — General purpose digital input/output pin. A LOW level on this pin during reset starts the ISP command handler.
			0	-	CLKOUT — Clockout pin.
			0	-	CT32B0_MAT2 — Match output 2 for 32-bit timer 0.
PIO0_2/SSEL0/	7 <u>[3]</u>	yes	I/O	I; PU	PIO0_2 — General purpose digital input/output pin.
CT16B0_CAP0			I/O	-	SSEL0 — Slave Select for SPI0.
			I	-	CT16B0_CAP0 — Capture input 0 for 16-bit timer 0.
PIO0_4/SCL	8 <u>[4]</u>	yes	I/O	I; IA	PIO0_4 — General purpose digital input/output pin (open-drain).
			I/O	-	SCL — I ² C-bus, open-drain clock input/output. High-current sink only if I ² C Fast-mode Plus is selected in the I/O configuration register.

Table 6. LPC1100L series: LPC1112 (HVQFN24 package)

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Symbol	Pin	Start logic input	Туре	Reset state [1]	Description
PIO0_0 to PIO0_11					Port 0 — Port 0 is a 12-bit I/O port with individual direction and function controls for each bit. The operation of port 0 pins depends on the function selected through the IOCONFIG register block.
RESET/PIO0_0	2[2]	yes	1	I;PU	RESET — External reset input with 20 ns glitch filter. A LOW-going pulse as short as 50 ns on this pin resets the device, causing I/O ports and peripherals to take on their default states and processor execution to begin at address 0.
					In deep power-down mode, this pin must be pulled HIGH externally. The RESET pin can be left unconnected or be used as a GPIO pin if an external RESET function is not needed and Deep power-down mode is not used.
			I/O	-	PIO0_0 — General purpose digital input/output pin with 10 ns glitch filter.
PIO0_1/CLKOUT/ CT32B0_MAT2	3 <u>[3]</u>	yes	I/O	I;PU	PIO0_1 — General purpose digital input/output pin. A LOW level on this pin during reset starts the ISP command handler.
			0	-	CLKOUT — Clock out pin.
			0	-	CT32B0_MAT2 — Match output 2 for 32-bit timer 0.
PIO0_2/SSEL0/	8 <u>[3]</u>	yes	I/O	I;PU	PIO0_2 — General purpose digital input/output pin.
CT16B0_CAP0			I/O	-	SSEL0 — Slave select for SPI0.
			I	-	CT16B0_CAP0 — Capture input 0 for 16-bit timer 0.
PIO0_3	9 <u>[3]</u>	yes	I/O	I;PU	PIO0_3 — General purpose digital input/output pin.
PIO0_4/SCL	10 <u>[4]</u>	yes	I/O	I;IA	PIO0_4 — General purpose digital input/output pin (open-drain).
			I/O	-	$\label{eq:scl} \begin{array}{l} \textbf{SCL} & = I^2 C \text{-bus, open-drain clock input/output. High-current sink only} \\ \text{if } I^2 C \text{ Fast-mode Plus is selected in the I/O configuration register.} \end{array}$
PIO0_5/SDA	11 <u>^[4]</u>	yes	I/O	I;IA	PIO0_5 — General purpose digital input/output pin (open-drain).
			I/O	-	SDA — I^2C -bus, open-drain data input/output. High-current sink only if I^2C Fast-mode Plus is selected in the I/O configuration register.
PIO0_6/SCK0	15 <u>[3]</u>	yes	I/O	I;PU	PIO0_6 — General purpose digital input/output pin.
			I/O	-	SCK0 — Serial clock for SPI0.
PIO0_7/CTS	16 <u>[3]</u>	yes	I/O	I;PU	PIO0_7 — General purpose digital input/output pin (high-current output driver).
			I	-	CTS — Clear To Send input for UART.
PIO0_8/MISO0/	17 <u>[3]</u>	yes	I/O	I;PU	PIO0_8 — General purpose digital input/output pin.
CT16B0_MAT0			I/O	-	MISO0 — Master In Slave Out for SPI0.
			0	-	CT16B0_MAT0 — Match output 0 for 16-bit timer 0.
PIO0_9/MOSI0/	18 <u>[3]</u>	yes	I/O	I;PU	PIO0_9 — General purpose digital input/output pin.
CT16B0_MAT1			I/O	-	MOSI0 — Master Out Slave In for SPI0.
			0	-	CT16B0_MAT1 — Match output 1 for 16-bit timer 0.
SWCLK/PIO0_10/	19 <u>[3]</u>	yes	I	I;PU	SWCLK — Serial wire clock.
SCK0/			I/O	-	PIO0_10 — General purpose digital input/output pin.
CT16B0_MAT2			I/O	-	SCK0 — Serial clock for SPI0.
			0	-	CT16B0_MAT2 — Match output 2 for 16-bit timer 0.

Table 9. LPC1100 and LPC1100L series: LPC1111/12/13/14 pin description table (HVQFN33 package)

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Symbol	Pin	Start logic input	Туре	Reset state [1]	Description		
R/PIO0_11/AD0/ CT32B0_MAT3	21 <u>5</u>	yes	-	I;PU	R — Reserved. Configure for an alternate function in the IOCONFIG block.		
			I/O	-	PIO0_11 — General purpose digital input/output pin.		
			I	-	AD0 — A/D converter, input 0.		
			0	-	CT32B0_MAT3 — Match output 3 for 32-bit timer 0.		
PIO1_0 to PIO1_11					Port 1 — Port 1 is a 12-bit I/O port with individual direction and function controls for each bit. The operation of port 1 pins depends on the function selected through the IOCONFIG register block.		
R/PIO1_0/AD1/ CT32B1_CAP0	22 <u>^[5]</u>	yes	-	I;PU	R — Reserved. Configure for an alternate function in the IOCONFIG block.		
			I/O	-	PIO1_0 — General purpose digital input/output pin.		
			I	-	AD1 — A/D converter, input 1.		
			I	-	CT32B1_CAP0 — Capture input 0 for 32-bit timer 1.		
R/PIO1_1/AD2/ CT32B1_MAT0	23 <u>[5]</u>	no	-	I;PU	R — Reserved. Configure for an alternate function in the IOCONFIG block.		
			I/O	-	PIO1_1 — General purpose digital input/output pin.		
			I	-	AD2 — A/D converter, input 2.		
			0	-	CT32B1_MAT0 — Match output 0 for 32-bit timer 1.		
R/PIO1_2/AD3/ CT32B1_MAT1	24 <u>^[5]</u>	no	-	I;PU	R — Reserved. Configure for an alternate function in the IOCONFIG block.		
			I/O	-	PIO1_2 — General purpose digital input/output pin.		
			I	-	AD3 — A/D converter, input 3.		
			0	-	CT32B1_MAT1 — Match output 1 for 32-bit timer 1.		
SWDIO/PIO1_3/	25 <u>[5]</u>	no	I/O	I;PU	SWDIO — Serial wire debug input/output.		
AD4/CT32B1_MAT2			I/O	-	PIO1_3 — General purpose digital input/output pin.		
			I	-	AD4 — A/D converter, input 4.		
			0	-	CT32B1_MAT2 — Match output 2 for 32-bit timer 1.		
PIO1_4/AD5/ CT32B1_MAT3/ WAKEUP	26 ^[5]	no	I/O	I;PU	PIO1_4 — General purpose digital input/output pin with 10 ns glitch filter. In Deep power-down mode, this pin serves as the Deep power-down mode wake-up pin with 20 ns glitch filter. Pull this pin HIGH externally before entering Deep power-down mode. Pull this pin LOW to exit Deep power-down mode. A LOW-going pulse as short as 50 ns wakes up the part.		
			I	-	AD5 — A/D converter, input 5.		
			0	-	CT32B1_MAT3 — Match output 3 for 32-bit timer 1.		
PIO1_5/RTS/ 30		no	I/O	I;PU	PIO1_5 — General purpose digital input/output pin.		
CT32B0_CAP0			0	-	RTS — Request To Send output for UART.		
			I	-	CT32B0_CAP0 — Capture input 0 for 32-bit timer 0.		
PIO1_6/RXD/	31 <u>[3]</u>	no	I/O	I;PU	PIO1_6 — General purpose digital input/output pin.		
CT32B0_MAT0			I	-	RXD — Receiver input for UART.		
			0	-	CT32B0_MAT0 — Match output 0 for 32-bit timer 0.		

Table 9. LPC1100 and LPC1100L series: LPC1111/12/13/14 pin description table (HVQFN33 package) ...continued

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[6] When the system oscillator is not used, connect XTALIN and XTALOUT as follows: XTALIN can be left floating or can be grounded (grounding is preferred to reduce susceptibility to noise). XTALOUT should be left floating.

Symbol	LQFP48	TFBGA48	Start logic input	Туре	Reset state [1]	Description
PIO0_0 to PIO0_11				I/O		Port 0 — Port 0 is a 12-bit I/O port with individual direction and function controls for each bit. The operation of port 0 pins depends on the function selected through the IOCONFIG register block.
RESET/PIO0_0	3 <u>[2]</u>	C1[2]	yes	I	I; PU	RESET — External reset input with 20 ns glitch filter. A LOW-going pulse as short as 50 ns on this pin resets the device, causing I/O ports and peripherals to take on their default states, and processor execution to begin at address 0.
						In deep power-down mode, this pin must be pulled HIGH externally. The RESET pin can be left unconnected or be used as a GPIO pin if an external RESET function is not needed and Deep power-down mode is not used.
				I/O	-	PIO0_0 — General purpose digital input/output pin with 10 ns glitch filter.
PIO0_1/CLKOUT/ CT32B0_MAT2	/ 4 <u>^[3] C2^[3]</u>		yes	I/O I; PU		PIO0_1 — General purpose digital input/output pin. A LOW level on this pin during reset starts the ISP command handler.
				0	-	CLKOUT — Clockout pin.
				0	-	CT32B0_MAT2 — Match output 2 for 32-bit timer 0.
PIO0_2/SSEL0/	10 <u>^[3]</u>	F1 <u>[3]</u>	yes	I/O	I; PU	PIO0_2 — General purpose digital input/output pin.
CT16B0_CAP0				I/O	-	SSEL0 — Slave Select for SPI0.
				I	-	CT16B0_CAP0 — Capture input 0 for 16-bit timer 0.
PIO0_3	14 <u>^[3]</u>	H2 ^[3]	yes	I/O	I; PU	PIO0_3 — General purpose digital input/output pin.
PIO0_4/SCL	15 <u>^[4]</u>	G3 <u>[4]</u>	yes	I/O	I; IA	PIO0_4 — General purpose digital input/output pin (open-drain).
				I/O	-	SCL — I ² C-bus, open-drain clock input/output. High-current sink only if I ² C Fast-mode Plus is selected in the I/O configuration register.
PIO0_5/SDA	16 <u>^[4]</u>	H3 <u>^[4]</u>	yes	I/O	I; IA	PIO0_5 — General purpose digital input/output pin (open-drain).
				I/O	-	SDA — I ² C-bus, open-drain data input/output. High-current sink only if I ² C Fast-mode Plus is selected in the I/O configuration register.
PIO0_6/SCK0	22 <u>[3]</u>	H6 <u>[3]</u>	yes	I/O	I; PU	PIO0_6 — General purpose digital input/output pin.
				I/O	-	SCK0 — Serial clock for SPI0.
PIO0_7/CTS	23 <u>[3]</u>	G7 <u>[3]</u>	yes	I/O	I; PU	PIO0_7 — General purpose digital input/output pin (high-current output driver).
				I	-	CTS — Clear To Send input for UART.

Table 10. LPC1100XL series: LPC1113/14/15 pin description table (LQFP48 and TFBGA48 package)

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- In the LPC1110/11/12/13/14/15, the NVIC supports 32 vectored interrupts including up to 13 inputs to the start logic from individual GPIO pins.
- Four programmable interrupt priority levels with hardware priority level masking.
- Software interrupt generation.

7.5.2 Interrupt sources

Each peripheral device has one interrupt line connected to the NVIC but may have several interrupt flags. Individual interrupt flags may also represent more than one interrupt source.

Any GPIO pin (total of up to 42 pins) regardless of the selected function, can be programmed to generate an interrupt on a level, or rising edge or falling edge, or both.

7.6 IOCONFIG block

The IOCONFIG block allows selected pins of the microcontroller to have more than one function. Configuration registers control the multiplexers to allow connection between the pin and the on-chip peripherals.

Peripherals should be connected to the appropriate pins prior to being activated and prior to any related interrupt(s) being enabled. Activity of any enabled peripheral function that is not mapped to a related pin should be considered undefined.

7.7 Fast general purpose parallel I/O

Device pins that are not connected to a specific peripheral function are controlled by the GPIO registers. Pins may be dynamically configured as inputs or outputs. Multiple outputs can be set or cleared in one write operation.

LPC1110/11/12/13/14/15 use accelerated GPIO functions:

- GPIO registers are a dedicated AHB peripheral so that the fastest possible I/O timing can be achieved.
- Entire port value can be written in one instruction.

Additionally, any GPIO pin (total of up to 42 pins) providing a digital function can be programmed to generate an interrupt on a level, a rising or falling edge, or both.

7.7.1 Features

- Bit level port registers allow a single instruction to set or clear any number of bits in one write operation.
- Direction control of individual bits.
- All I/O default to inputs with pull-ups enabled after reset with the exception of the I²C-bus pins PIO0_4 and PIO0_5.
- Pull-up/pull-down resistor configuration can be programmed through the IOCONFIG block for each GPIO pin (except for pins PIO0_4 and PIO0_5).
- On the LPC1100, all GPIO pins (except PIO0_4 and PIO0_5) are pulled up to 2.6 V (V_{DD} = 3.3 V) if their pull-up resistor is enabled in the IOCONFIG block.

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The start logic must be configured in the system configuration block and in the NVIC before being used.

7.17.2 Reset

Reset has four sources on the LPC1110/11/12/13/14/15: the RESET pin, the Watchdog reset, Power-On Reset (POR), and the BrownOut Detection (BOD) circuit. The RESET pin is a Schmitt trigger input pin. Assertion of chip reset by any source, once the operating voltage attains a usable level, starts the IRC and initializes the flash controller.

A LOW-going pulse as short as 50 ns resets the part.

When the internal Reset is removed, the processor begins executing at address 0, which is initially the Reset vector mapped from the boot block. At that point, all of the processor and peripheral registers have been initialized to predetermined values.

An external pull-up resistor is required on the RESET pin if Deep power-down mode is used.

7.17.3 Brownout detection

The LPC1110/11/12/13/14/15 includes up to four levels for monitoring the voltage on the V_{DD} pin. If this voltage falls below one of the selected levels, the BOD asserts an interrupt signal to the NVIC. This signal can be enabled for interrupt in the Interrupt Enable Register in the NVIC in order to cause a CPU interrupt; if not, software can monitor the signal by reading a dedicated status register. Four threshold levels can be selected to cause a forced reset of the chip.

7.17.4 Code security (Code Read Protection - CRP)

This feature of the LPC1110/11/12/13/14/15 allows user to enable different levels of security in the system so that access to the on-chip flash and use of the Serial Wire Debugger (SWD) and In-System Programming (ISP) can be restricted. When needed, CRP is invoked by programming a specific pattern into a dedicated flash location. IAP commands are not affected by the CRP.

In addition, ISP entry via the PIO0_1 pin can be disabled without enabling CRP. For details see the *LPC111x user manual*.

There are three levels of Code Read Protection:

- CRP1 disables access to the chip via the SWD and allows partial flash update (excluding flash sector 0) using a limited set of the ISP commands. This mode is useful when CRP is required and flash field updates are needed but all sectors can not be erased.
- 2. CRP2 disables access to the chip via the SWD and only allows full flash erase and update using a reduced set of the ISP commands.
- 3. Running an application with level CRP3 selected fully disables any access to the chip via the SWD pins and the ISP. This mode effectively disables ISP override using PIO0_1 pin, too. It is up to the user's application to provide (if needed) flash update mechanism using IAP calls or call reinvoke ISP command to enable flash update via the UART.

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10. Static characteristics

10.1 LPC1100, LPC1100L series

Table 16. Static characteristics (LPC1100, LPC1100L series)

 $T_{amb} = -40 \$ °C to +85 °C, unless otherwise specified.

Symbol	Parameter	Conditions		Min	Typ <u>[1]</u>	Max	Unit
V _{DD}	supply voltage (core and external rail)			1.8	3.3	3.6	V
LPC1100 se	ries (LPC111x/101/201/301) power consumption			U		
I _{DD}	supply current	Active mode; code					
		while(1){}					
		executed from flash					
		system clock = 12 MHz	[2][3][4]	-	3	-	mA
		V _{DD} = 3.3 V	[5][6]				
		system clock = 50 MHz	[2][3][5]	-	9	-	mA
		V _{DD} = 3.3 V	<u>[6][7]</u>				
		Sleep mode;	[2][3][4]	-	2	-	mA
		system clock = 12 MHz	[5][6]				
		V _{DD} = 3.3 V					
		Deep-sleep mode; V _{DD} = 3.3 V	[2][3][8]	-	6	-	μΑ
		Deep power-down mode; $V_{DD} = 3.3 V$	<u>[2][9]</u>	-	220	-	nA
LPC1100L s	eries (LPC111x/002/102/20	2/302) power consumption	in low-c	urrent m	ode ^[11]		4
I _{DD}	supply current	Active mode; code					
		while(1){}					
		executed from flash					
		system clock = 1 MHz	[2][3][5]	-	840	-	μA
		V _{DD} = 3.3 V	[6][10]	1			
		system clock = 6 MHz	[2][3][5]	-	1	-	mA
		$V_{DD} = 3.3 V$	<u>[6][10]</u>				
		system clock = 12 MHz	[2][3][4]	-	2	-	mA
		$V_{DD} = 3.3 V$	[5][6]				
		system clock = 50 MHz	[2][3][5]	-	7	-	mA
		$V_{DD} = 3.3 V$	[6][7]				
		Sleep mode;	[2][3][4]	-	1	-	mA
		system clock = 12 MHz	[5][6]				
		V _{DD} = 3.3 V					
		system clock = 50 MHz	[2][3][4]	-	5	-	mA
		V _{DD} = 3.3 V	[5][6]				
		Deep-sleep mode; V _{DD} = 3.3 V	<u>[2][3][8]</u>	-	2	-	μΑ
		Deep power-down mode; $V_{DD} = 3.3 V$	[2][9]	-	220	-	nA

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Table 16. Static characteristics (LPC1100, LPC1100L series) ... continued

 $T_{amb} = -40 \ ^{\circ}C$ to +85 $^{\circ}C$, unless otherwise specified.

Symbol	Parameter	Conditions	Min	Typ <u>[1]</u>	Max	Unit
I _{OZ}	OFF-state output current	$V_O = 0 V; V_O = V_{DD};$ on-chip pull-up/down resistors disabled	-	0.5	10	nA
VI	input voltage	pin configured to provide [12][13] a digital function [14]	-	-	5.0	V
Vo	output voltage	output active	0	-	V _{DD}	V
V _{IH}	HIGH-level input voltage		0.7V _{DD}	-	-	V
V _{IL}	LOW-level input voltage		-	-	$0.3V_{DD}$	V
V _{hys}	hysteresis voltage		0.4	-	-	V
V _{OH}	HIGH-level output voltage	$\begin{array}{l} 2.5 \ V \leq V_{DD} \leq 3.6 \ V; \\ I_{OH} = -20 \ mA \end{array} \label{eq:VDD}$	$V_{DD}-0.4$	-	-	V
		$\begin{array}{l} 1.8 \ \text{V} \leq \text{V}_{\text{DD}} < 2.5 \ \text{V}; \\ \text{I}_{\text{OH}} = -12 \ \text{mA} \end{array}$	V _{DD} – 0.4	-	-	V
V _{OL}	LOW-level output voltage	$\begin{array}{l} 2.5 \ \text{V} \leq \text{V}_{\text{DD}} \leq 3.6 \ \text{V}; \\ \text{I}_{\text{OL}} = 4 \ \text{mA} \end{array}$	-	-	0.4	V
		$\begin{array}{l} 1.8 \text{ V} \leq \text{V}_{\text{DD}} < 2.5 \text{ V}; \\ \text{I}_{\text{OL}} = 3 \text{ mA} \end{array}$	-	-	0.4	V
I _{OH}	HIGH-level output current	$V_{OH} = V_{DD} - 0.4 V;$ 2.5 V $\leq V_{DD} \leq 3.6 V$	20	-	-	mA
		$1.8 \text{ V} \leq \text{V}_{\text{DD}} < 2.5 \text{ V}$	12	-	-	mA
I _{OL}	LOW-level output current	$\label{eq:Volume} \begin{split} V_{OL} &= 0.4 \ V \\ &2.5 \ V \leq V_{DD} \leq 3.6 \ V \end{split}$	4	-	-	mA
		$1.8 \text{ V} \le \text{V}_{\text{DD}}$ < 2.5 V	3	-	-	mA
I _{OLS}	LOW-level short-circuit output current	$V_{OL} = V_{DD} $ ^[15]	-	-	50	mA
I _{pd}	pull-down current	V ₁ = 5 V	10	50	150	μA
I _{pu}	pull-up current	$V_{I} = 0 V$ 2.0 V $\leq V_{DD} \leq 3.6 V$	-15	-50	-85	μΑ
		$1.8 \text{ V} \le \text{V}_{\text{DD}}$ < 2.0 V	-10	-50	-85	μA
		$V_{DD} < V_{I} < 5 V$	0	0	0	μA
I ² C-bus pins	(PIO0_4 and PIO0_5)	1				
V _{IH}	HIGH-level input voltage		0.7V _{DD}	-	-	V
V _{IL}	LOW-level input voltage		-	-	0.3V _{DD}	V
V _{hys}	hysteresis voltage		-	0.05V _{DD}	-	V
I _{OL}	LOW-level output current	$\label{eq:Volume} \begin{array}{l} V_{OL} = 0.4 \ \text{V}; \ l^2C\text{-bus pins} \\ \text{configured as standard} \\ \text{mode pins} \\ 2.5 \ \text{V} \leq V_{DD} \leq 3.6 \ \text{V} \end{array}$	3.5	-	-	mA
		$1.8 \text{ V} \le \text{V}_{\text{DD}}$ < 2.5 V	3	-	-	

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10.2 LPC1100XL series

Table 17. Static characteristics (LPC1100XL series)

 $T_{amb} = -40 \text{ °C to } +105 \text{ °C}$, unless otherwise specified.

Symbol	Parameter	Conditions		Min	Typ <u>[1]</u>	Max	Unit		
V _{DD}	supply voltage (core and external rail)		1.8	3.3	3.6	V			
LPC1100XL	series (LPC111x/103/203/30	3/323/333) power consum	ption in	low-current mode ^[2]					
I _{DD}	supply current	Active mode; code							
		while(1){}							
		executed from flash							
		system clock = 3 MHz	[3][4][5]	-	600	-	μA		
		V _{DD} = 3.3 V	[6][7]						
		system clock = 6 MHz	[3][4][5]	-	850	-	μA		
		V _{DD} = 3.3 V	<u>[6][7]</u>						
		system clock = 12 MHz	[3][4][6]	-	1.4	-	mA		
		V _{DD} = 3.3 V	[7][8]						
		system clock = 50 MHz	[3][4][6]	-	5.8	-	mA		
		V _{DD} = 3.3 V	[7][9]						
		Sleep mode;	[3][4][6]	-	700	-	μA		
		system clock = 12 MHz	[7][8]						
		V _{DD} = 3.3 V							
		system clock = 50 MHz	[3][4][6]	-	2.2	-	mA		
		V _{DD} = 3.3 V	[7][8]						
		Deep-sleep mode;	[3][4]	-	1.8	15	μA		
		V _{DD} = 3.3 V; 25 °C	[10]						
		Deep-sleep mode;	[4][10] [11]	-	-	50	μA		
		V _{DD} = 3.3 V; 105 °C				4000			
		Deep power-down mode; V _{DD} = 3.3 V; 25 °C	[3][12]	-	220	1000	nA		
		Deep power-down mode;	[11][12]	-		3	μA		
		$V_{DD} = 3.3 \text{ V}; 105 \text{ °C}$				Ũ	μ		
Standard po	rt pins, RESET								
I _{IL}	LOW-level input current	$V_{I} = 0 V$; on-chip pull-up		-	0.5	10	nA		
-		resistor disabled							
I _{IH}	HIGH-level input	$V_I = V_{DD}$; on-chip		-	0.5	10	nA		
	current	pull-down resistor disabled							
1		$V_{O} = 0 V; V_{O} = V_{DD};$			0.5	10	۳A		
l _{oz}	OFF-state output current	$v_0 = 0 v, v_0 = v_{DD},$ on-chip pull-up/down		-	0.5	10	nA		
		resistors disabled							
VI	input voltage	pin configured to provide	[13][14]	0	-	5.0	V		
		a digital function	[15]						
N/				0		N/	17		
Vo	output voltage	output active		0	-	V _{DD}	V		
V _{IH}	HIGH-level input voltage			0.7V _{DD}	-	-	V		

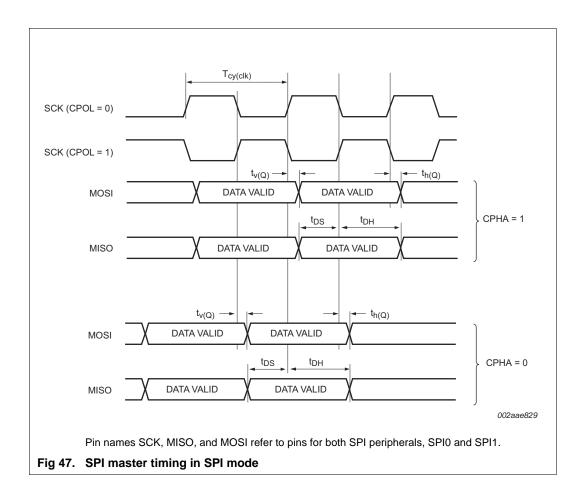
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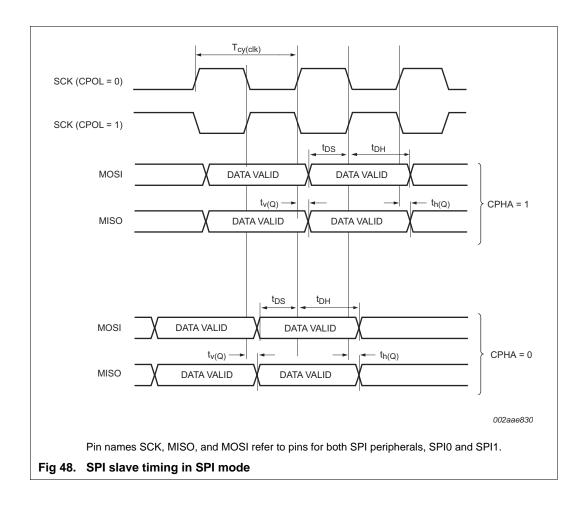
Symbol	Parameter	Conditions	Min	Typ[1]	Max	Unit
V _{OH}	HIGH-level output voltage	$\begin{array}{l} 2.5 \ V \leq V_{DD} \leq 3.6 \ V; \\ I_{OH} = -20 \ mA \end{array} \label{eq:VDD}$	$V_{DD} - 0.4$	-	-	V
		$\begin{array}{l} 1.8 \ \text{V} \leq \text{V}_{\text{DD}} < 2.5 \ \text{V}; \\ \text{I}_{\text{OH}} = -12 \ \text{mA} \end{array}$	$V_{DD}-0.4$	-	-	V
V _{OL}	LOW-level output voltage	$\begin{array}{l} 2.5 \ V \leq V_{DD} \leq 3.6 \ V; \\ I_{OL} = 4 \ mA \end{array} \label{eq:VDD}$	-	-	0.4	V
		$\begin{array}{l} 1.8 \ \text{V} \leq \text{V}_{\text{DD}} < 2.5 \ \text{V}; \\ \text{I}_{\text{OL}} = 3 \ \text{mA} \end{array}$	-	-	0.4	V
I _{OH}	HIGH-level output current		20	-	-	mA
		$1.8 \text{ V} \leq \text{V}_{\text{DD}} < 2.5 \text{ V}$	12	-	-	mA
I _{OL}	LOW-level output current	$V_{OL} = 0.4 \text{ V}$ 2.5 V $\leq V_{DD} \leq 3.6 \text{ V}$	4	-	-	mA
		$1.8 \text{ V} \leq \text{V}_{\text{DD}}$ < 2.5 V	3	-	-	mA
I _{OLS}	LOW-level short-circuit output current	$V_{OL} = V_{DD} $ ^[16]	-	-	50	mA
I _{pd}	pull-down current	V ₁ = 5 V	10	50	150	μA
I _{pu}	pull-up current	$V_{I} = 0 V$ $2.0 V \leq V_{DD} \leq 3.6 V$	-15	-50	-85	μA
		$1.8 \text{ V} \le \text{V}_{\text{DD}}$ < 2.0 V	-10	-50	-85	μA
		$V_{DD} < V_I < 5 V$	0	0	0	μA
I ² C-bus pin	ns (PIO0_4 and PIO0_5)	l	1	1		
V _{IH}	HIGH-level input voltage		$0.7V_{DD}$	-	-	V
V _{IL}	LOW-level input voltage		-	-	0.3V _{DD}	V
V _{hys}	hysteresis voltage		-	$0.05V_{DD}$	-	V
I _{OL}	LOW-level output current	$V_{OL} = 0.4$ V; l ² C-bus pins configured as standard mode pins	3.5	-	-	mA
		$2.5 V \le V_{DD} \le 3.6 V$ 1.8 V \le V_{DD} < 2.5 V	3			
I _{OL}	LOW-level output	V _{OL} = 0.4 V; I ² C-bus pins	20	-	-	mA
	current	configured as Fast-mode Plus pins				
		$2.5~V \leq V_{DD} \leq 3.6~V$				
		$1.8 \text{ V} \leq \text{V}_{\text{DD}} < 2.5 \text{ V}$	16	-	-	
ILI	input leakage current	$V_{I} = V_{DD} $ [17]	-	2	4	μA
		$V_{I} = 5 V$	-	10	22	μA

Table 17. Static characteristics (LPC1100XL series) ... continued $r_{\rm mb} = -40 \,^{\circ}{\rm C}$ to +105 $\,^{\circ}{\rm C}$, unless otherwise specified. Τ

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12.7 ElectroMagnetic Compatibility (EMC)

Radiated emission measurements according to the IEC61967-2 standard using the TEM-cell method are shown for the LPC1114FBD48/302 in Table 32.

Table 32. ElectroMagnetic Compatibility (EMC) for part LPC1114FBD48/302 (TEM-cell method)

 $V_{DD} = 3.3 V; T_{amb} = 25 °C.$

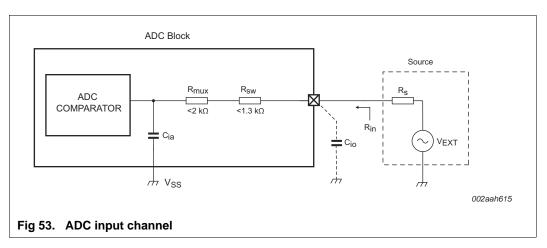
Parameter	Frequency band	System clock =			Unit
		12 MHz	24 MHz	48 MHz	
Input clock:	IRC (12 MHz)		I		I
maximum peak level	150 kHz to 30 MHz	-7	-5	-7	dBμV
	30 MHz to 150 MHz	-2	1	10	dBμV
	150 MHz to 1 GHz	4	8	16	dBμV
IEC level ^[1]	-	0	Ν	Μ	-
Input clock:	crystal oscillator (12	MHz)			I
maximum peak level	150 kHz to 30 MHz	-7	-7	-7	dBμV
	30 MHz to 150 MHz	-2	1	8	dBμV
	150 MHz to 1 GHz	4	7	14	dBμV
IEC level ^[1]	-	0	Ν	М	-

[1] IEC levels refer to Appendix D in the IEC61967-2 Specification.

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12.8 ADC effective input impedance

A simplified diagram of the ADC input channels can be used to determine the effective input impedance seen from an external voltage source. See Figure 53.



The effective input impedance, R_{in} , seen by the external voltage source, V_{EXT} , is the parallel impedance of ((1/f_s x C_{ia}) + R_{mux} + R_{sw}) and (1/f_s x C_{io}), and can be calculated using <u>Equation 2</u> with

fs = sampling frequency

 $C_{ia} = ADC$ analog input capacitance

R_{mux} = analog mux resistance

 R_{sw} = switch resistance

 C_{io} = pin capacitance

$$R_{in} = \left(\frac{1}{f_s \times C_{ia}} + R_{mux} + R_{sw}\right) \parallel \left(\frac{1}{f_s \times C_{io}}\right)$$
(2)

Under nominal operating condition $V_{DD} = 3.3$ V and with the maximum sampling frequency fs = 400 kHz, the parameters assume the following values:

$$\begin{split} C_{ia} &= 1 \text{ pF (max)} \\ R_{mux} &= 2 \text{ k}\Omega \text{ (max)} \\ R_{sw} &= 1.3 \text{ k}\Omega \text{ (max)} \\ C_{io} &= 7.1 \text{ pF (max)} \end{split}$$

The effective input impedance with these parameters is $R_{in} = 308 \text{ k}\Omega$.

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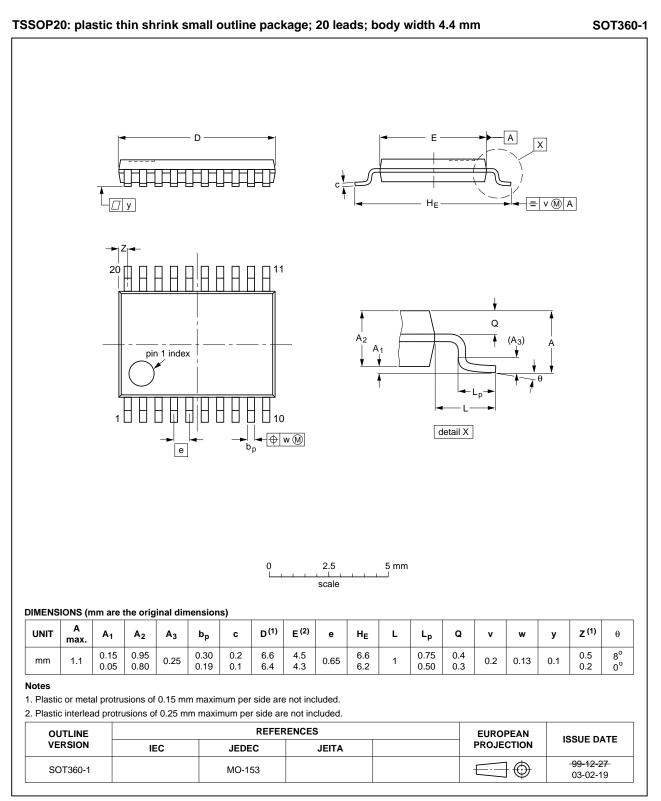
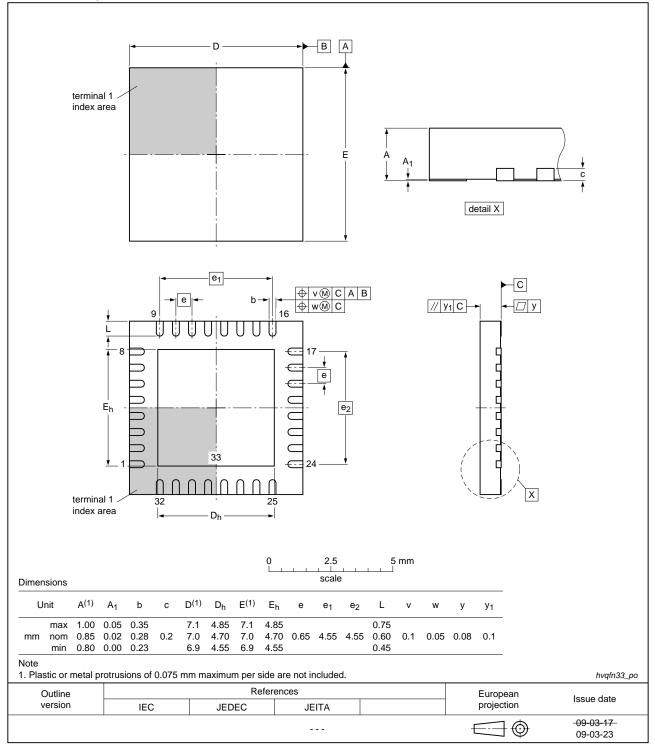


Fig 55. Package outline SOT360-1 (TSSOP20)

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HVQFN33: plastic thermal enhanced very thin quad flat package; no leads; 33 terminals; body 7 x 7 x 0.85 mm

Fig 59. Package outline (HVQFN33 7x7)

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18. Legal information

18.1 Data sheet status

Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL <u>http://www.nxp.com</u>.

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