



Welcome to [E-XFL.COM](http://www.e-xfl.com)

What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	e200z0h
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	CANbus, I ² C, LINbus, SCI, SPI
Peripherals	DMA, POR, PWM, WDT
Number of I/O	149
Program Memory Size	768KB (768K x 8)
Program Memory Type	FLASH
EEPROM Size	64K x 8
RAM Size	64K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 5.5V
Data Converters	A/D 29x10b, 5x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	176-LQFP
Supplier Device Package	176-LQFP (24x24)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/ppc5605bclu48

Table of Contents

1	Introduction	3
1.1	Document overview	3
1.2	Description	3
2	Block diagram	5
3	Package pinouts and signal descriptions	8
3.1	Package pinouts	8
3.2	Pad configuration during reset phases	12
3.3	Pad configuration during standby mode exit	13
3.4	Voltage supply pins	13
3.5	Pad types	14
3.6	System pins	14
3.7	Functional port pins	15
3.8	Nexus 2+ pins	34
4	Electrical characteristics	35
4.1	Parameter classification	35
4.2	NVUSRO register	35
4.2.1	NVUSRO[PAD3V5V] field description	35
4.2.2	NVUSRO[OSCILLATOR_MARGIN] field description	36
4.2.3	NVUSRO[WATCHDOG_EN] field description	36
4.3	Absolute maximum ratings	36
4.4	Recommended operating conditions	37
4.5	Thermal characteristics	40
4.5.1	External ballast resistor recommendations	40
4.5.2	Package thermal characteristics	40
4.5.3	Power considerations	41
4.6	I/O pad electrical characteristics	42
4.6.1	I/O pad types	42
4.6.2	I/O input DC characteristics	42
4.6.3	I/O output DC characteristics	43
4.6.4	Output pin transition times	46
4.6.5	I/O pad current specification	46
4.7	RESET electrical characteristics	54
4.8	Power management electrical characteristics	57
4.8.1	Voltage regulator electrical characteristics	57
4.8.2	Low voltage detector electrical characteristics	59
4.9	Power consumption	60
4.10	Flash memory electrical characteristics	62
4.10.1	Program/erase characteristics	62
4.10.2	Flash power supply DC characteristics	63
4.10.3	Start-up/Switch-off timings	64
4.11	Electromagnetic compatibility (EMC) characteristics	64
4.11.1	Designing hardened software to avoid noise problems	64
4.11.2	Electromagnetic interference (EMI)	65
4.11.3	Absolute maximum ratings (electrical sensitivity)	65
4.12	Fast external crystal oscillator (4 to 16 MHz) electrical characteristics	66
4.13	Slow external crystal oscillator (32 kHz) electrical characteristics	69
4.14	FMPLL electrical characteristics	71
4.15	Fast internal RC oscillator (16 MHz) electrical characteristics	72
4.16	Slow internal RC oscillator (128 kHz) electrical characteristics	73
4.17	ADC electrical characteristics	74
4.17.1	Introduction	74
4.17.2	Input impedance and ADC accuracy	75
4.17.3	ADC electrical characteristics	80
4.18	On-chip peripherals	85
4.18.1	Current consumption	85
4.18.2	DSPI characteristics	87
4.18.3	Nexus characteristics	93
4.18.4	JTAG characteristics	94
5	Package characteristics	96
5.1	Package mechanical data	96
5.1.1	176 LQFP	96
5.1.2	144 LQFP	100
5.1.3	100 LQFP	102
5.1.4	208 MAPBGA	105
6	Ordering information	107
Appendix A	Abbreviations	108
7	Revision history	109

2 Block diagram

Figure 1 shows a top-level block diagram of the MPC5607B.

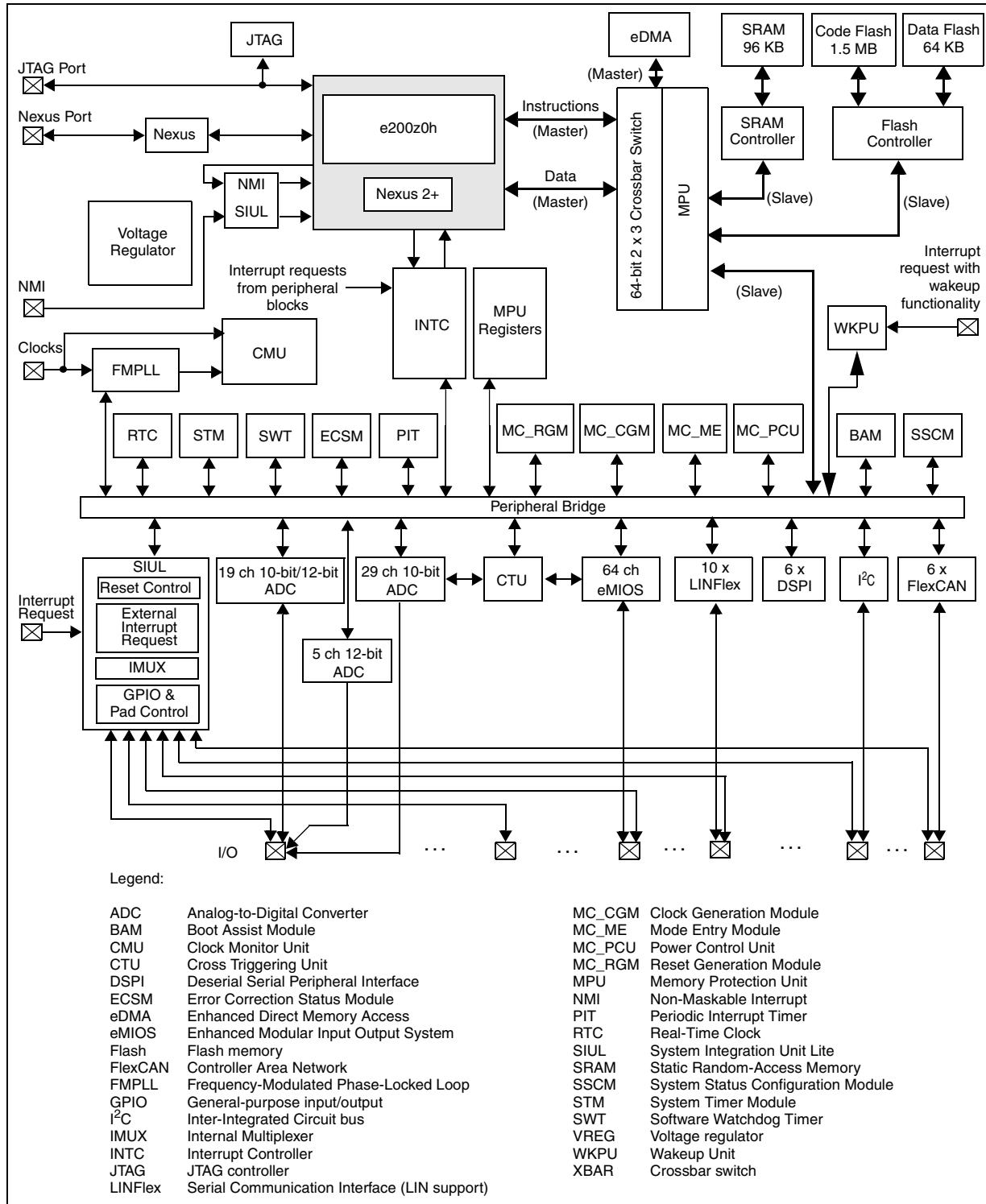


Figure 1. MPC5607B block diagram

Package pinouts and signal descriptions

Table 5. Functional port pin descriptions (continued)

Port pin	PCR	Alternate function ¹	Function	Peripheral	I/O direction ²	Pad type	RESET configuration ³	Pin number			
								100 LQFP	144 LQFP	176 LQFP	208 MAP BGA ⁴
PC[11]	PCR[43]	AF0	GPIO[43]	SIUL	I/O	S	Tristate	21	27	35	M4
		AF1	—	—	—	—					
		AF2	—	—	—	—					
		AF3	MA[2]	ADC_0	O						
		—	WKPU[5] ⁵	WKPU	I						
		—	CAN1RX	FlexCAN_1	I						
PC[12]	PCR[44]	AF0	GPIO[44]	SIUL	I/O	M	Tristate	97	141	173	B4
		AF1	E0UC[12]	eMIOS_0	I/O						
		AF2	—	—	—	—					
		AF3	—	—	—	—					
		—	EIRQ[19]	SIUL	I						
		—	SIN_2	DSPI_2	I						
PC[13]	PCR[45]	AF0	GPIO[45]	SIUL	I/O	S	Tristate	98	142	174	A2
		AF1	E0UC[13]	eMIOS_0	I/O						
		AF2	SOUT_2	DSPI_2	O						
		AF3	—	—	—	—					
PC[14]	PCR[46]	AF0	GPIO[46]	SIUL	I/O	S	Tristate	3	3	3	C1
		AF1	E0UC[14]	eMIOS_0	I/O						
		AF2	SCK_2	DSPI_2	I/O						
		AF3	—	SIUL	I						
PC[15]	PCR[47]	AF0	GPIO[47]	SIUL	I/O	M	Tristate	4	4	4	D3
		AF1	E0UC[15]	eMIOS_0	I/O						
		AF2	CS0_2	DSPI_2	I/O						
		AF3	—	—	—	—					
PD[0]	PCR[48]	AF0	GPIO[48]	SIUL	I	I	Tristate	41	63	77	P12
		AF1	—	—	—	—					
		AF2	—	—	—	—					
		AF3	—	—	—	—					
		—	WKPU[27] ⁵	WKPU	I						
		—	ADC0_P[4]	ADC_0	I						
PD[1]	PCR[49]	AF0	GPIO[49]	SIUL	I	I	Tristate	42	64	78	T12
		AF1	—	—	—	—					
		AF2	—	—	—	—					
		AF3	—	—	—	—					
		—	WKPU[28] ⁵	WKPU	I						
		—	ADC0_P[5]	ADC_0	I						
		—	ADC1_P[5]	ADC_1	I						

Package pinouts and signal descriptions

Table 5. Functional port pin descriptions (continued)

Port pin	PCR	Alternate function ¹	Function	Peripheral	I/O direction ²	Pad type	RESET configuration ³	Pin number			
								100 LQFP	144 LQFP	176 LQFP	208 MAP BGA ⁴
PF[8]	PCR[88]	AF0 AF1 AF2 AF3	GPIO[88] CAN3TX CS4_0 CAN2TX	SIUL FlexCAN_3 O O O	I/O O O O	M	Tristate	—	34	42	P1
PF[9]	PCR[89]	AF0 AF1 AF2 AF3 — — —	GPIO[89] E1UC[1] CS5_0 — WKPU[22] ⁵ CAN2RX CAN3RX	SIUL eMIOS_1 DSPI_0 — WKPU FlexCAN_2 FlexCAN_3	I/O I/O O — — — —	S	Tristate	—	33	41	N2
PF[10]	PCR[90]	AF0 AF1 AF2 AF3	GPIO[90] CS1_0 LIN4TX E1UC[2]	SIUL DSPI_0 LINFlex_4 eMIOS_1	I/O O O I/O	M	Tristate	—	38	46	R3
PF[11]	PCR[91]	AF0 AF1 AF2 AF3 — —	GPIO[91] CS2_0 E1UC[3] — WKPU[15] ⁵ LIN4RX	SIUL DSPI_0 eMIOS_1 — WKPU LINFlex_4	I/O O I/O — — —	S	Tristate	—	39	47	R4
PF[12]	PCR[92]	AF0 AF1 AF2 AF3	GPIO[92] E1UC[25] LIN5TX —	SIUL eMIOS_1 LINFlex_5 —	I/O I/O O —	M	Tristate	—	35	43	R1
PF[13]	PCR[93]	AF0 AF1 AF2 AF3 — —	GPIO[93] E1UC[26] — — WKPU[16] ⁵ LIN5RX	SIUL eMIOS_1 — — WKPU LINFlex_5	I/O I/O — — — —	S	Tristate	—	41	49	T6
PF[14]	PCR[94]	AF0 AF1 AF2 AF3	GPIO[94] CAN4TX E1UC[27] CAN1TX	SIUL FlexCAN_4 eMIOS_1 FlexCAN_1	I/O O I/O O	M	Tristate	—	102	126	D14
PF[15]	PCR[95]	AF0 AF1 AF2 AF3 — — —	GPIO[95] E1UC[4] — — EIRQ[13] CAN1RX CAN4RX	SIUL eMIOS_1 — — SIUL FlexCAN_1 FlexCAN_4	I/O I/O — — — — —	S	Tristate	—	101	125	E15
Port G											

Table 5. Functional port pin descriptions (continued)

Port pin	PCR	Alternate function ¹	Function	Peripheral	I/O direction ²	Pad type	RESET configuration ³	Pin number			
								100 LQFP	144 LQFP	176 LQFP	208 MAP BGA ⁴
PG[0]	PCR[96]	AF0 AF1 AF2 AF3	GPIO[96] CAN5TX E1UC[23] —	SIUL FlexCAN_5 eMIOS_1 —	I/O O I/O —	M	Tristate	—	98	122	E14
PG[1]	PCR[97]	AF0 AF1 AF2 AF3 — —	GPIO[97] — E1UC[24] — EIRQ[14] CAN5RX	SIUL — eMIOS_1 — SIUL FlexCAN_5	I/O — I/O — I I	S	Tristate	—	97	121	E13
PG[2]	PCR[98]	AF0 AF1 AF2 AF3	GPIO[98] E1UC[11] SOUT_3 —	SIUL eMIOS_1 DSPI_3 —	I/O I/O O —	M	Tristate	—	8	16	E4
PG[3]	PCR[99]	AF0 AF1 AF2 AF3 —	GPIO[99] E1UC[12] CS0_3 — WKPU[17] ⁵	SIUL eMIOS_1 DSPI_3 — WKPU	I/O I/O I/O — I	S	Tristate	—	7	15	E3
PG[4]	PCR[100]	AF0 AF1 AF2 AF3	GPIO[100] E1UC[13] SCK_3 —	SIUL eMIOS_1 DSPI_3 —	I/O I/O I/O —	M	Tristate	—	6	14	E1
PG[5]	PCR[101]	AF0 AF1 AF2 AF3 — —	GPIO[101] E1UC[14] — — WKPU[18] ⁵ SIN_3	SIUL eMIOS_1 — — WKPU DSPI_3	I/O I/O — — I I	S	Tristate	—	5	13	E2
PG[6]	PCR[102]	AF0 AF1 AF2 AF3	GPIO[102] E1UC[15] LIN6TX —	SIUL eMIOS_1 LINFlex_6 —	I/O I/O O —	M	Tristate	—	30	38	M2
PG[7]	PCR[103]	AF0 AF1 AF2 AF3 — —	GPIO[103] E1UC[16] E1UC[30] — WKPU[20] ⁵ LIN6RX	SIUL eMIOS_1 eMIOS_1 — WKPU LINFlex_6	I/O I/O I/O — I I	S	Tristate	—	29	37	M1

Table 5. Functional port pin descriptions (continued)

Port pin	PCR	Alternate function ¹	Function	Peripheral	I/O direction ²	Pad type	RESET configuration ³	Pin number			
								100 LQFP	144 LQFP	176 LQFP	208 MAP BGA ⁴
PI[4]	PCR[132]	AF0 AF1 AF2 AF3	GPIO[132] E1UC[28] SOUT_4 —	SIUL eMIOS_1 DSPI_4 —	I/O I/O O —	S	Tristate	—	—	143	A12
PI[5]	PCR[133]	AF0 AF1 AF2 AF3	GPIO[133] E1UC[29] SCK_4 —	SIUL eMIOS_1 DSPI_4 —	I/O I/O I/O —	S	Tristate	—	—	142	C12
PI[6]	PCR[134]	AF0 AF1 AF2 AF3	GPIO[134] E1UC[30] CS0_4 —	SIUL eMIOS_1 DSPI_4 —	I/O I/O I/O —	S	Tristate	—	—	11	D2
PI[7]	PCR[135]	AF0 AF1 AF2 AF3	GPIO[135] E1UC[31] CS1_4 —	SIUL eMIOS_1 DSPI_4 —	I/O I/O O —	S	Tristate	—	—	12	D3
PI[8]	PCR[136]	AF0 AF1 AF2 AF3 —	GPIO[136] — — — ADC0_S[16]	SIUL — — — ADC_0	I/O — — — —	J	Tristate	—	—	108	J13
PI[9]	PCR[137]	AF0 AF1 AF2 AF3 —	GPIO[137] — — — ADC0_S[17]	SIUL — — — ADC_0	I/O — — — —	J	Tristate	—	—	109	J14
PI[10]	PCR[138]	AF0 AF1 AF2 AF3 —	GPIO[138] — — — ADC0_S[18]	SIUL — — — ADC_0	I/O — — — —	J	Tristate	—	—	110	J15
PI[11]	PCR[139]	AF0 AF1 AF2 AF3 — —	GPIO[139] — — — ADC0_S[19] SIN_3	SIUL — — — ADC_0 DSPI_3	I/O — — — — —	J	Tristate	—	—	111	J16
PI[12]	PCR[140]	AF0 AF1 AF2 AF3 —	GPIO[140] CS0_3 — — ADC0_S[20]	SIUL DSPI_3 — — ADC_0	I/O I/O — — —	J	Tristate	—	—	112	G14

Table 12. Recommended operating conditions (3.3 V) (continued)

Symbol	Parameter	Conditions	Value		Unit	
			Min	Max		
V_{SS_ADC}	SR	Voltage on $V_{SS_HV_ADC0}$, $V_{SS_HV_ADC1}$ (ADC reference) pin with respect to ground (V_{SS})	—	$V_{SS} - 0.1$	$V_{SS} + 0.1$	V
$V_{DD_ADC}^4$	SR	Voltage on $V_{DD_HV_ADC0}$, $V_{DD_HV_ADC1}$ (ADC reference) with respect to ground (V_{SS})	—	3.0 ⁵	3.6	V
			Relative to V_{DD}	$V_{DD} - 0.1$	$V_{DD} + 0.1$	
V_{IN}	SR	Voltage on any GPIO pin with respect to ground (V_{SS})	—	$V_{SS} - 0.1$	—	V
			Relative to V_{DD}	—	$V_{DD} + 0.1$	
I_{INJPAD}	SR	Injected input current on any pin during overload condition	—	-5	5	mA
I_{INJSUM}	SR	Absolute sum of all injected input currents during overload condition	—	-50	50	
TV_{DD}	SR	V_{DD} slope to ensure correct power up ⁶	—	—	0.25	V/ μ s
T_A C-Grade Part	SR	Ambient temperature under bias	$f_{CPU} < 64 \text{ MHz}^7$	-40	85	°C
T_J C-Grade Part	SR	Junction temperature under bias	—	-40	110	
T_A V-Grade Part	SR	Ambient temperature under bias	$f_{CPU} < 64 \text{ MHz}^7$	-40	105	
T_J V-Grade Part	SR	Junction temperature under bias	—	-40	130	
T_A M-Grade Part	SR	Ambient temperature under bias	$f_{CPU} < 64 \text{ MHz}^7$	-40	125	
T_J M-Grade Part	SR	Junction temperature under bias	—	-40	150	

¹ 100 nF capacitance needs to be provided between each V_{DD}/V_{SS} pair.

² 330 nF capacitance needs to be provided between each V_{DD_LV}/V_{SS_LV} supply pair.

³ 470 nF capacitance needs to be provided between V_{DD_BV} and the nearest V_{SS_LV} (higher value may be needed depending on external regulator characteristics). Supply ramp slope on V_{DD_BV} should always be faster or equal to slope of V_{DD_HV} . Otherwise, device may enter regulator bypass mode if slope on V_{DD_BV} is slower.

⁴ 100 nF capacitance needs to be provided between V_{DD_ADC}/V_{SS_ADC} pair.

⁵ Full electrical specification cannot be guaranteed when voltage drops below 3.0 V. In particular, ADC electrical characteristics and I/Os DC electrical specification may not be guaranteed. When voltage drops below V_{LVDHVL} , device is reset.

⁶ Guaranteed by device validation

⁷ This frequency includes the 4% frequency modulation guardband.

Table 13. Recommended operating conditions (5.0 V)

Symbol	Parameter	Conditions	Value		Unit	
			Min	Max		
V_{SS}	SR	Digital ground on V_{SS_HV} pins	—	0	0	V
V_{DD}^1	SR	Voltage on V_{DD_HV} pins with respect to ground (V_{SS})	—	4.5	5.5	V
			Voltage drop ²	3.0	5.5	
$V_{SS_LV}^3$	SR	Voltage on V_{SS_LV} (low voltage digital supply) pins with respect to ground (V_{SS})	—	$V_{SS} - 0.1$	$V_{SS} + 0.1$	V

Electrical characteristics

Table 13. Recommended operating conditions (5.0 V) (continued)

Symbol	Parameter	Conditions	Value		Unit	
			Min	Max		
$V_{DD_BV}^4$	Voltage on V_{DD_BV} pin (regulator supply) with respect to ground (V_{SS})	—	4.5	5.5	V	
		Voltage drop ²	3.0	5.5		
		Relative to V_{DD}	3.0	$V_{DD} + 0.1$		
V_{SS_ADC}	SR	Voltage on $V_{SS_HV_ADC0}$, $V_{SS_HV_ADC1}$ (ADC reference) pin with respect to ground (V_{SS})	—	$V_{SS} - 0.1$	$V_{SS} + 0.1$	V
$V_{DD_ADC}^5$	Voltage on $V_{DD_HV_ADC0}$, $V_{DD_HV_ADC1}$ (ADC reference) with respect to ground (V_{SS})	—	4.5	5.5	V	
		Voltage drop ²	3.0	5.5		
		Relative to V_{DD}	$V_{DD} - 0.1$	$V_{DD} + 0.1$		
V_{IN}	SR	Voltage on any GPIO pin with respect to ground (V_{SS})	—	$V_{SS} - 0.1$	—	V
			Relative to V_{DD}	—	$V_{DD} + 0.1$	
I_{INJPAD}	SR	Injected input current on any pin during overload condition	—	-5	5	mA
I_{INJSUM}	SR	Absolute sum of all injected input currents during overload condition	—	-50	50	
TV_{DD}	SR	V_{DD} slope to ensure correct power up ⁶	—	—	0.25	
T_A C-Grade Part	SR	Ambient temperature under bias	$f_{CPU} < 64 \text{ MHz}^7$	-40	85	
T_J C-Grade Part	SR	Junction temperature under bias	—	-40	110	
T_A V-Grade Part	SR	Ambient temperature under bias	$f_{CPU} < 64 \text{ MHz}^7$	-40	105	
T_J V-Grade Part	SR	Junction temperature under bias	—	-40	130	
T_A M-Grade Part	SR	Ambient temperature under bias	$f_{CPU} < 64 \text{ MHz}^7$	-40	125	°C
T_J M-Grade Part	SR	Junction temperature under bias	—	-40	150	

¹ 100 nF capacitance needs to be provided between each V_{DD}/V_{SS} pair.

² Full device operation is guaranteed by design when the voltage drops below 4.5 V down to 3.0 V. However, certain analog electrical characteristics will not be guaranteed to stay within the stated limits.

³ 330 nF capacitance needs to be provided between each V_{DD_LV}/V_{SS_LV} supply pair.

⁴ 470 nF capacitance needs to be provided between V_{DD_BV} and the nearest V_{SS_LV} (higher value may be needed depending on external regulator characteristics). While the supply voltage ramps up, the slope on V_{DD_BV} should be less than $0.9V_{DD_HV}$ in order to ensure the device does not enter regulator bypass mode.

⁵ 100 nF capacitance needs to be provided between V_{DD_ADC}/V_{SS_ADC} pair.

⁶ Guaranteed by device validation. Please refer to [Section 4.5.1, "External ballast resistor recommendations](#) for minimum V_{DD} slope to be guaranteed to ensure correct power up in case of external resistor usage.

⁷ This frequency includes the 4% frequency modulation guardband.

NOTE

RAM data retention is guaranteed with V_{DD_LV} not below 1.08 V.

Electrical characteristics

Table 15. I/O input DC electrical characteristics

Symbol	C	Parameter	Conditions ¹	Value			Unit	
				Min	Typ	Max		
V _{IH}	SR	P	Input high level CMOS (Schmitt Trigger)	—	0.65V _{DD}	—	V _{DD} + 0.4	
V _{IL}	SR	P	Input low level CMOS (Schmitt Trigger)	—	-0.4	—	0.35V _{DD}	
V _{HYS}	CC	C	Input hysteresis CMOS (Schmitt Trigger)	—	0.1V _{DD}	—	—	
I _{LKG}	CC	D	Digital input leakage	No injection on adjacent pin	T _A = -40 °C	—	200	nA
					T _A = 25 °C	—	200	
					T _A = 85 °C	—	300	
					T _A = 105 °C	—	500	
					T _A = 125 °C	—	1000	
W _{FI} ²	SR	P	Wakeup input filtered pulse	—	—	—	40	ns
W _{NFI} ²	SR	P	Wakeup input not filtered pulse	—	1000	—	—	ns

¹ V_{DD} = 3.3 V ± 10% / 5.0 V ± 10%, T_A = -40 to 125 °C, unless otherwise specified

² In the range from 40 to 1000 ns, pulses can be filtered or not filtered, according to operating temperature and voltage.

4.6.3 I/O output DC characteristics

The following tables provide DC characteristics for bidirectional pads:

- Table 16 provides weak pull figures. Both pull-up and pull-down resistances are supported.
- Table 17 provides output driver characteristics for I/O pads when in SLOW configuration.
- Table 18 provides output driver characteristics for I/O pads when in MEDIUM configuration.
- Table 19 provides output driver characteristics for I/O pads when in FAST configuration.

Table 16. I/O pull-up/pull-down DC electrical characteristics

Symbol	C	Parameter	Conditions ¹	Value			Unit	
				Min	Typ	Max		
I _{WPUI}	CC	P	Weak pull-up current absolute value	V _{IN} = V _{IL} , V _{DD} = 5.0 V ± 10%	PAD3V5V = 0	10	—	µA
					PAD3V5V = 1 ²	10	—	
				V _{IN} = V _{IL} , V _{DD} = 3.3 V ± 10%	PAD3V5V = 1	10	—	
I _{WPD}	CC	P	Weak pull-down current absolute value	V _{IN} = V _{IH} , V _{DD} = 5.0 V ± 10%	PAD3V5V = 0	10	—	µA
					PAD3V5V = 1	10	—	
				V _{IN} = V _{IH} , V _{DD} = 3.3 V ± 10%	PAD3V5V = 1	10	—	

¹ V_{DD} = 3.3 V ± 10% / 5.0 V ± 10%, T_A = -40 to 125 °C, unless otherwise specified.

² The configuration PAD3V5 = 1 when V_{DD} = 5 V is only a transient configuration during power-up. All pads but RESET and Nexus output (MDOx, EVTO, MCKO) are configured in input or in high impedance state.

Table 22. I/O consumption (continued)

Symbol	C	Parameter	Conditions ¹			Value			Unit	
			Min	Typ	Max					
I_{RMSFST}	CC	Root mean square I/O current for FAST configuration	$C_L = 25 \text{ pF}, 40 \text{ MHz}$	$V_{DD} = 5.0 \text{ V} \pm 10\%, \text{PAD3V5V} = 0$	—	—	22	mA		
			$C_L = 25 \text{ pF}, 64 \text{ MHz}$		—	—	33			
			$C_L = 100 \text{ pF}, 40 \text{ MHz}$		—	—	56			
			$C_L = 25 \text{ pF}, 40 \text{ MHz}$	$V_{DD} = 3.3 \text{ V} \pm 10\%, \text{PAD3V5V} = 1$	—	—	14			
			$C_L = 25 \text{ pF}, 64 \text{ MHz}$		—	—	20			
			$C_L = 100 \text{ pF}, 40 \text{ MHz}$		—	—	35			
I_{AVGSEG}	SR	D	Sum of all the static I/O current within a supply segment	$V_{DD} = 5.0 \text{ V} \pm 10\%, \text{PAD3V5V} = 0$			—	—	70	mA
				$V_{DD} = 3.3 \text{ V} \pm 10\%, \text{PAD3V5V} = 1$			—	—	65	

¹ $V_{DD} = 3.3 \text{ V} \pm 10\% / 5.0 \text{ V} \pm 10\%$, $T_A = -40$ to 125°C , unless otherwise specified

² Stated maximum values represent peak consumption that lasts only a few ns during I/O transition.

Table 23 provides the weight of concurrent switching I/Os.

Due to the dynamic current limitations, the sum of the weight of concurrent switching I/Os on a single segment must not exceed 100% to ensure device functionality.

Table 23. I/O weight¹

Supply segment			Pad	176 LQFP				144/100 LQFP				
176 LQFP	144 LQFP	100 LQFP		Weight 5 V		Weight 3.3 V		Weight 5 V		Weight 3.3 V		
				SRC ² = 0	SRC = 1	SRC = 0	SRC = 1	SRC = 0	SRC = 1	SRC = 0	SRC = 1	
6	4	4	PB[3]	5%	—	6%	—	13%	—	15%	—	
			PC[9]	4%	—	5%	—	13%	—	15%	—	
			PC[14]	4%	—	4%	—	13%	—	15%	—	
			PC[15]	3%	4%	4%	4%	12%	18%	15%	16%	
	—	—	PJ[4]	3%	4%	3%	3%	—	—	—	—	

Table 23. I/O weight¹ (continued)

Supply segment			Pad	176 LQFP				144/100 LQFP			
				Weight 5 V		Weight 3.3 V		Weight 5 V		Weight 3.3 V	
176 LQFP	144 LQFP	100 LQFP		SRC ² = 0	SRC = 1	SRC = 0	SRC = 1	SRC = 0	SRC = 1	SRC = 0	SRC = 1
2	1	—	PG[9]	9%	—	10%	—	9%	—	10%	—
		—	PG[8]	9%	—	11%	—	9%	—	11%	—
		1	PC[11]	9%	—	11%	—	9%	—	11%	—
			PC[10]	9%	13%	11%	12%	9%	13%	11%	12%
		—	PG[7]	9%	—	11%	—	9%	—	11%	—
		—	PG[6]	10%	14%	11%	12%	10%	14%	11%	12%
		1	PB[0]	10%	14%	12%	12%	10%	14%	12%	12%
			PB[1]	10%	—	12%	—	10%	—	12%	—
		—	PF[9]	10%	—	12%	—	10%	—	12%	—
		—	PF[8]	10%	14%	12%	13%	10%	14%	12%	13%
		—	PF[12]	10%	15%	12%	13%	10%	15%	12%	13%
		1	PC[6]	10%	—	12%	—	10%	—	12%	—
			PC[7]	10%	—	12%	—	10%	—	12%	—
		—	PF[10]	10%	14%	11%	12%	10%	14%	11%	12%
		—	PF[11]	9%	—	11%	—	9%	—	11%	—
		1	PA[15]	8%	12%	10%	10%	8%	12%	10%	10%
		—	PF[13]	8%	—	10%	—	8%	—	10%	—
		1	PA[14]	8%	11%	9%	10%	8%	11%	9%	10%
			PA[4]	7%	—	9%	—	7%	—	9%	—
			PA[13]	7%	10%	8%	9%	7%	10%	8%	9%
			PA[12]	7%	—	8%	—	7%	—	8%	—

4.8 Power management electrical characteristics

4.8.1 Voltage regulator electrical characteristics

The device implements an internal voltage regulator to generate the low voltage core supply V_{DD_LV} from the high voltage ballast supply V_{DD_BV} . The regulator itself is supplied by the common I/O supply V_{DD} . The following supplies are involved:

- HV: High voltage external power supply for voltage regulator module. This must be provided externally through V_{DD} power pin.
- BV: High voltage external power supply for internal ballast module. This must be provided externally through V_{DD_BV} power pin. Voltage values should be aligned with V_{DD} .
- LV: Low voltage internal power supply for core, FMPLL and Flash digital logic. This is generated by the internal voltage regulator but provided outside to connect stability capacitor. It is further split into four main domains to ensure noise isolation between critical LV modules within the device:
 - LV_COR: Low voltage supply for the core. It is also used to provide supply for FMPLL through double bonding.
 - LV_CFLA: Low voltage supply for code flash module. It is supplied with dedicated ballast and shorted to LV_COR through double bonding.
 - LV_DFLA: Low voltage supply for data flash module. It is supplied with dedicated ballast and shorted to LV_COR through double bonding.
 - LV_PLL: Low voltage supply for FMPLL. It is shorted to LV_COR through double bonding.

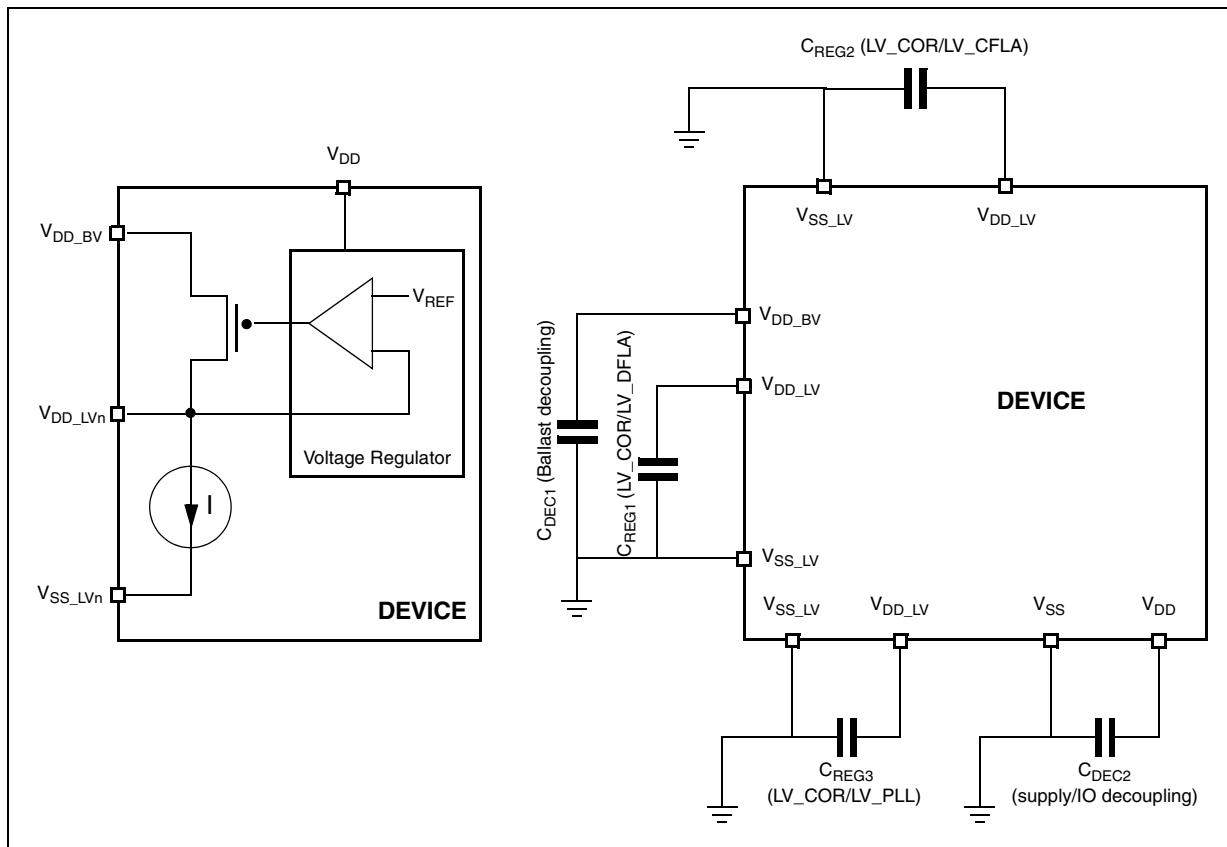


Figure 9. Voltage regulator capacitance connection

The internal voltage regulator requires external capacitance (C_{REGn}) to be connected to the device in order to provide a stable low voltage digital supply to the device. Capacitances should be placed on the board as near as possible to the associated pins. Care should also be taken to limit the serial inductance of the board to less than 5 nH.

Table 31. Flash power supply DC electrical characteristics

Symbol	Parameter	Conditions ¹	Value			Unit
			Min	Typ	Max	
I _{CFREAD}	CC Sum of the current consumption on V _{DD_HV} and V _{DD_BV} on read access	Flash module read f _{CPU} = 64 MHz	Code Flash	—	—	mA
I _{DFREAD}			Data Flash	—	—	
I _{CFMOD}	CC Sum of the current consumption on V _{DD_HV} and V _{DD_BV} on matrix modification (program/erase)	Program/Erase on-going while reading Flash registers f _{CPU} = 64 MHz	Code Flash	—	—	mA
I _{DFMOD}			Data Flash	—	—	
I _{CFLPW}	CC Sum of the current consumption on V _{DD_HV} and V _{DD_BV} during Flash low power mode	—	Code Flash	—	—	mA
I _{DFLPW}			Data Flash	—	—	
I _{CFPWD}	CC Sum of the current consumption on V _{DD_HV} and V _{DD_BV} during Flash power down mode	—	Code Flash	—	—	μA
I _{DFPWD}			Data Flash	—	—	

¹ V_{DD} = 3.3 V ± 10% / 5.0 V ± 10%, T_A = –40 to 125 °C, unless otherwise specified

4.10.3 Start-up/Switch-off timings

Table 32. Start-up time/Switch-off time

Symbol	C	Parameter	Conditions ¹	Value			Unit
				Min	Typ	Max	
t _{FLARSTEXIT}	CC T	Delay for Flash module to exit reset mode	—	—	—	—	μs
t _{FLALPEXIT}		Delay for Flash module to exit low-power mode		—	—	—	
t _{FLAPDEXIT}		Delay for Flash module to exit power-down mode		—	—	—	
t _{FLALPENTRY}		Delay for Flash module to enter low-power mode		—	—	—	
t _{FLAPDENTRY}		Delay for Flash module to enter power-down mode		—	—	—	

¹ V_{DD} = 3.3 V ± 10% / 5.0 V ± 10%, T_A = –40 to 125 °C, unless otherwise specified

4.11 Electromagnetic compatibility (EMC) characteristics

Susceptibility tests are performed on a sample basis during product characterization.

4.11.1 Designing hardened software to avoid noise problems

EMC characterization and optimization are performed at component level with a typical application environment and simplified MCU software. It should be noted that good EMC performance is highly dependent on the user application and the software in particular.

Therefore it is recommended that the user apply EMC software optimization and prequalification tests in relation with the EMC level requested for the application.

- Software recommendations – The software flowchart must include the management of runaway conditions such as:
 - Corrupted program counter

Electrical characteristics

- Unexpected reset
- Critical data corruption (control registers...)
- Prequalification trials – Most of the common failures (unexpected reset and program counter corruption) can be reproduced by manually forcing a low state on the reset pin or the oscillator pins for 1 second.
To complete these trials, ESD stress can be applied directly on the device. When unexpected behavior is detected, the software can be hardened to prevent unrecoverable errors occurring.

4.11.2 Electromagnetic interference (EMI)

The product is monitored in terms of emission based on a typical application. This emission test conforms to the IEC61967-1 standard, which specifies the general conditions for EMI measurements.

Table 33. EMI radiated emission measurement^{1,2}

Symbol	C	Parameter	Conditions	Value			Unit
				Min	Typ	Max	
—	SR	Scan range	—	0.150		1000	MHz
f_{CPU}	SR	Operating frequency	—	—	64	—	MHz
V_{DD_LV}	SR	LV operating voltages	—	—	1.28	—	V
S_{EMI}	CC	T	Peak level $V_{DD} = 5\text{ V}$, $T_A = 25^\circ\text{C}$, LQFP144 package Test conforming to IEC 61967-2, $f_{OSC} = 8\text{ MHz}$ / $f_{CPU} = 64\text{ MHz}$	No PLL frequency modulation $\pm 2\%$ PLL frequency modulation	—	18	$\text{dB}\mu\text{V}$

¹ EMI testing and I/O port waveforms per IEC 61967-1, -2, -4

² For information on conducted emission and susceptibility measurement (norm IEC 61967-4), please contact your local marketing representative.

4.11.3 Absolute maximum ratings (electrical sensitivity)

Based on two different tests (ESD and LU) using specific measurement methods, the product is stressed in order to determine its performance in terms of electrical sensitivity.

4.11.3.1 Electrostatic discharge (ESD)

Electrostatic discharges (a positive then a negative pulse separated by 1 second) are applied to the pins of each sample according to each pin combination. The sample size depends on the number of supply pins in the device (3 parts×(n + 1) supply pin). This test conforms to the AEC-Q100-002/-003/-011 standard.

Electrical characteristics

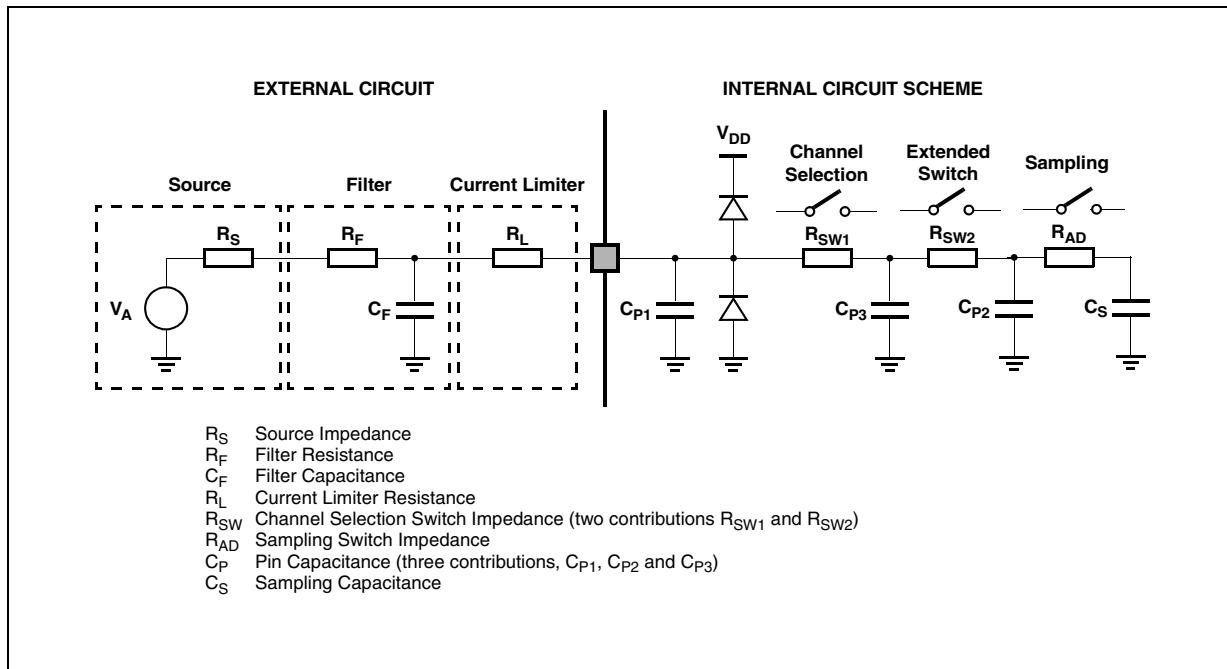


Figure 18. Input equivalent circuit (extended channels)

A second aspect involving the capacitance network shall be considered. Assuming the three capacitances C_F , C_{P1} and C_{P2} are initially charged at the source voltage V_A (refer to the equivalent circuit reported in Figure 17): A charge sharing phenomenon is installed when the sampling phase is started (A/D switch close).

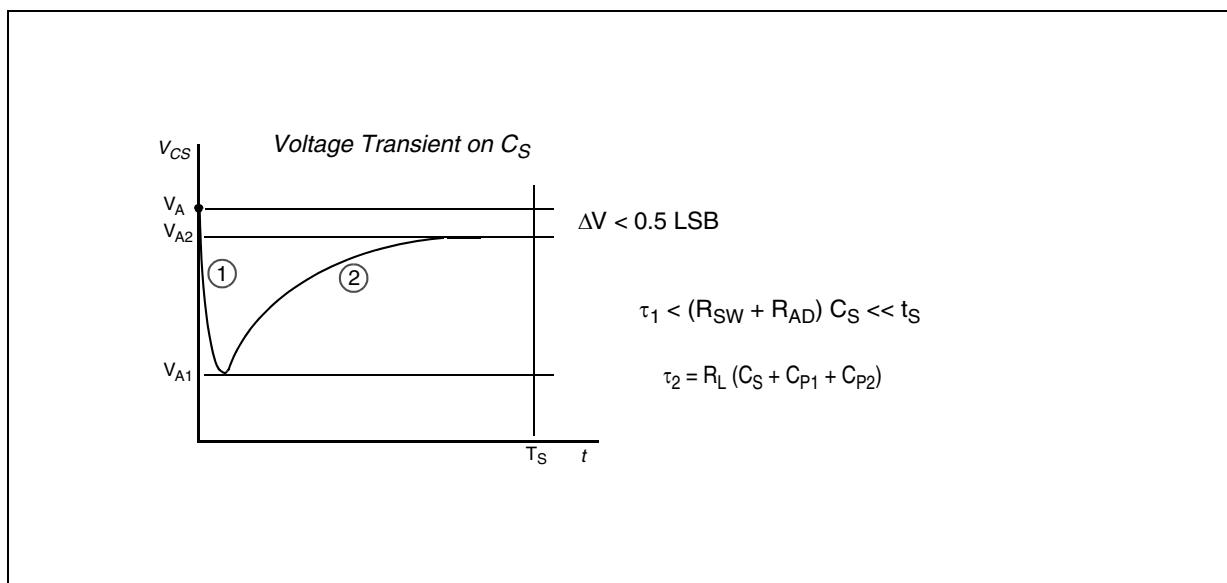


Figure 19. Transient behavior during sampling phase

In particular two different transient periods can be distinguished:

1. A first and quick charge transfer from the internal capacitance C_{P1} and C_{P2} to the sampling capacitance C_S occurs (C_S is supposed initially completely discharged): considering a worst case (since the time constant in reality would be faster) in which C_{P2} is reported in parallel to C_{P1} (call $C_P = C_{P1} + C_{P2}$), the two capacitances C_P and C_S are in series, and the time constant is

4.18 On-chip peripherals

4.18.1 Current consumption

Table 46. On-chip peripherals current consumption¹

Symbol	C	Parameter	Conditions		Typical value ²	Unit
$I_{DD_BV(CAN)}$	CC	CAN (FlexCAN) supply current on V_{DD_BV}	Bitrate: 500 Kbyte/s	Total (static + dynamic) consumption: • FlexCAN in loop-back mode • XTAL at 8 MHz used as CAN engine clock source • Message sending period is 580 μ s	$8 * f_{periph} + 85$	μ A
			Bitrate: 125 Kbyte/s		$8 * f_{periph} + 27$	
$I_{DD_BV(eMIOS)}$	CC	eMIOS supply current on V_{DD_BV}	Static consumption: • eMIOS channel OFF • Global prescaler enabled		$29 * f_{periph}$	μ A
			Dynamic consumption: • It does not change varying the frequency (0.003 mA)		3	
$I_{DD_BV(SCI)}$	CC	SCI (LINFlex) supply current on V_{DD_BV}	Total (static + dynamic) consumption: • LIN mode • Baudrate: 20 Kbyte/s		$5 * f_{periph} + 31$	μ A
$I_{DD_BV(SPI)}$	CC	SPI (DSPI) supply current on V_{DD_BV}	Ballast static consumption (only clocked)		1	μ A
			Ballast dynamic consumption (continuous communication): • Baudrate: 2 Mbit/s • Transmission every 8 μ s • Frame: 16 bits		$16 * f_{periph}$	
$I_{DD_BV(ADC_0/ADC_1)}$	CC	ADC_0/ADC_1 supply current on V_{DD_BV}	$V_{DD} = 5.5$ V	Ballast static consumption (no conversion) ³	$41 * f_{periph}$	μ A
				Ballast dynamic consumption (continuous conversion) ³	$46 * f_{periph}$	
$I_{DD_HV_ADC0}$	CC	ADC_0 supply current on $V_{DD_HV_ADC0}$	$V_{DD} = 5.5$ V	Analog static consumption (no conversion)	200	μ A
				Analog dynamic consumption (continuous conversion)	3	
$I_{DD_HV_ADC1}$	CC	ADC_1 supply current on $V_{DD_HV_ADC1}$	$V_{DD} = 5.5$ V	Analog static consumption (no conversion)	$300 * f_{periph}$	μ A
				Analog dynamic consumption (continuous conversion)	4	
$I_{DD_HV(FLASH)}$	CC	CFlash + DFlash supply current on V_{DD_HV}	$V_{DD} = 5.5$ V	—	12	mA
$I_{DD_HV(PLL)}$	CC	PLL supply current on V_{DD_HV}	$V_{DD} = 5.5$ V	—	$30 * f_{periph}$	μ A

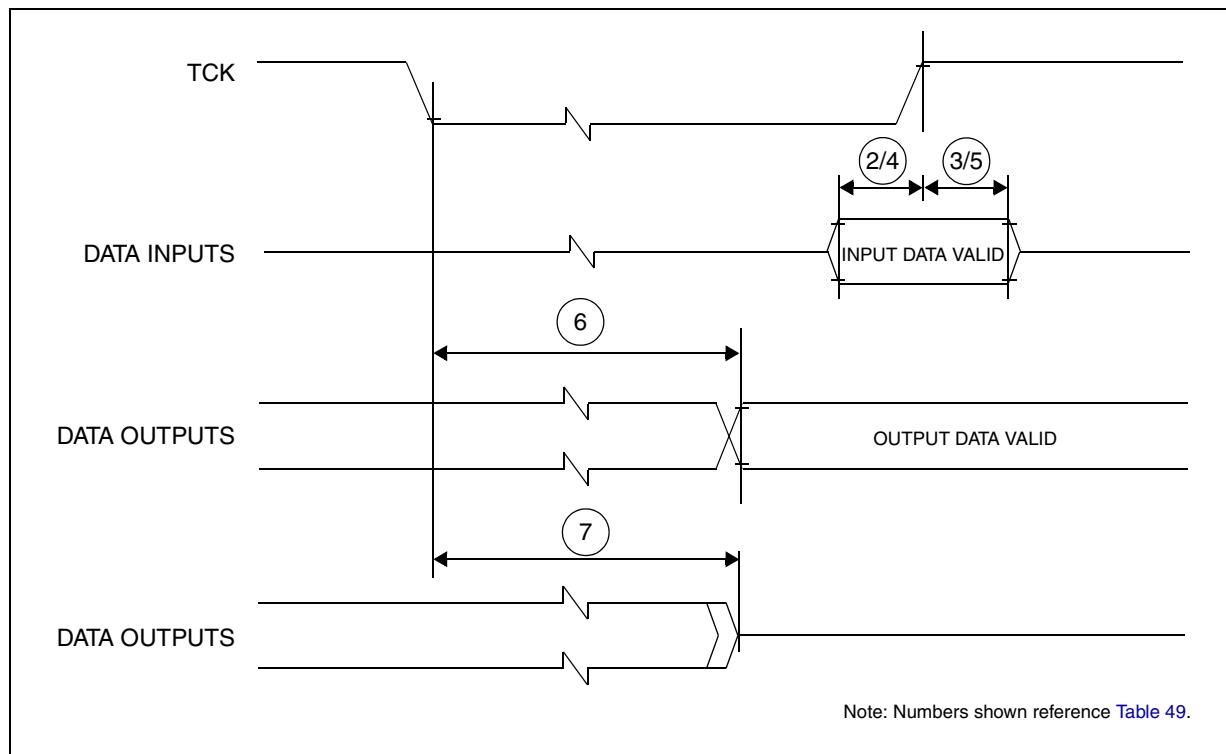


Figure 32. Timing diagram — JTAG boundary scan

7 Revision history

Table 51 summarizes revisions to this document.

Table 51. Revision history

Revision	Date	Substantive changes
1	12-Jan-2009	Initial release
2	09 Nov-2009	<ul style="list-style-type: none"> Updated Features Replaced 27 IRQs in place of 23 ADC features External Ballast resistor support conditions Updated device summary-added 208 BGA details Updated block diagram to include WKUP Updated block diagram to include 5 ch ADC 12-bit Updated Block summary table Updated LQFP 144, 176 and 100 pinouts. Applied new naming convention for ADC signals as ADCx_P[x] and ADCx_S[x] Section 1, "General description" Updated MPC5607B device comparison table Updated block diagram-aligned with 512k Updated block summary-aligned with 512k Section 2, "Package pinouts" Updated 100,144,176,208 packages according to cut2.0 changes Added Section 3.5.1, "External ballast resistor recommendations" Added NVUSRO [WATCHDOG_EN] field description Updated Absolute maximum ratings Updated LQFP thermal characteristics Updated I/O supply segments Updated Voltage regulator capacitance connection Updated Low voltage monitor electrical characteristics Updated Low voltage power domain electrical characteristics Updated DC electrical characteristics Updated Program/Erase specifications Updated Conversion characteristics (10 bit ADC) Updated FMPLL electrical characteristics Updated Fast RC oscillator electrical characteristics-aligned with MPC5604B Updated On-chip peripherals current consumption Updated ADC characteristics and error definitions diagram Updated ADC conversion characteristics (10 bit and 12 bit) Added ADC characteristics and error definitions diagram for 12 bit ADC
3	25 Jan-2010	<ul style="list-style-type: none"> Updated Features Updated block diagram to connect peripherals to pad I/O Updated block summary to include ADC 12-bit Updated 144, 176 and 100 pinouts to adjust format issues Table 26 Flash module life-retention value changed from 1-5 to 5 yrs Minor editing changes

Table 51. Revision history (continued)

Revision	Date	Substantive changes
4	24 Aug 2010	<p>Editorial changes and improvements.</p> <p>Updated “Features” section</p> <p>Table 1: updated footnote concerning 208 MAPBGA</p> <p>In the block diagram:</p> <ul style="list-style-type: none"> • Added “5ch 12-bit ADC“ block. • Updated Legend. • Added “Interrupt request with wakeup functionality” as an input to the WKPU block. <p>Figure 2: removed alternate functions</p> <p>Figure 3: removed alternate functions</p> <p>Figure 4: removed alternate functions</p> <p>Table 2: added contents concerning the following blocks: CMU, eDMA, ECSM, MC_ME, MC_PCU, NMI, SSCM, SWT and WKPU</p> <p>Added Section 3.2, Pin muxing</p> <p>Section 4, “Electrical characteristics: removed “Caution” note</p> <p>Section 4.2, “NVUSRO register: removed “NVUSRO[WATCHDOG_EN] field description” section</p> <p>Table 11: V_{IN}: removed min value in “relative to V_{DD}” row</p> <p>Table 12</p> <ul style="list-style-type: none"> • T_AC-Grade Part, T_JC-Grade Part, T_AV-Grade Part, T_JV-Grade Part, T_AM-Grade Part, T_JM-Grade Part: added new rows • $T_{V_{DD}}$: contents merged into one row • V_{DD_BV}: changed min value in “relative to V_{DD}” row <p>Section 4.5, “Thermal characteristics</p> <ul style="list-style-type: none"> • Section 4.5.1, “External ballast resistor recommendations: added new paragraph about power supply • Table 14: added $R_{\mu B}$ and $R_{\mu C}$ rows • Removed “208 MAPBGA thermal characteristics” table <p>Table 15: rewrote parameter description of W_FI and W_NFI</p> <p>Section 4.6.5, “I/O pad current specification</p> <ul style="list-style-type: none"> • Removed I_{DYNSEG} information • Updated “I/O supply segments” table <p>Table 22: removed I_{DYNSEG} row</p> <p>Added Table 23</p> <p>Table 25</p> <ul style="list-style-type: none"> • Updated all values • Removed $I_{VREGREF}$ and $I_{VREDLVD12}$ rows • Added the footnote “The duration of the in-rush current depends on the capacitance placed on LV pins. BV decaps must be sized accordingly. Refer to IMREG value for minimum amount of current to be provided in cc.” to the I_{DD_BV} specification. <p>Table 26</p> <ul style="list-style-type: none"> • Updated V_{PORH} min/max value • Updated $V_{LVDLVCORL}$ min value <p>Updated Table 27</p> <p>Table 28</p> <ul style="list-style-type: none"> • $T_{dwprogram}$: added initial max value • Inserted T_{eslat} row <p>Table 29: removed the “To be confirmed” footnote</p> <p>In the “Crystal oscillator and resonator connection scheme” figure, removed R_P</p> <p>Table 39</p> <ul style="list-style-type: none"> • Removed g_{mSXOSC} row • $I_{SXOSCBIAS}$: added min/typ/max value

Table 51. Revision history (continued)

Revision	Date	Substantive changes
6 (cont'd)	08 Jul 2011	<p>Section “External ballast resistor recommendations”: replaced “low voltage monitor” with “low voltage detector (LVD)”</p> <p>“I/O input DC electrical characteristics” table: updated I_{LKG} characteristics</p> <p>“MEDIUM configuration output buffer electrical characteristics” table: changed “$I_{OH} = 100 \mu A$” to “$I_{OL} = 100 \mu A$” in V_{OL} conditions</p> <p>I/O weight: updated table (includes replacing instances of bit “SRE” with “SRC”)</p> <p>“Reset electrical characteristics” table: updated parameter classification for II_{WPU}</p> <p>Updated voltage regulator electrical characteristics</p> <p>Section “Low voltage detector electrical characteristics”: changed title (was “Voltage monitor electrical characteristics”); changed “as well as four low voltage detectors” to “as well as five low voltage detectors”; added event status flag names found in RGM chapter of device reference manual to POR module and LVD descriptions; replaced instances of “Low voltage monitor” with “Low voltage detector”; updated values for $V_{LVDLVBKPL}$ and $V_{LVDLVCORL}$</p> <p>Updated section “Power consumption”</p> <p>Section “Program/erase characteristics”: removed table “FLASH_BIU settings vs. frequency of operation” and associated introduction</p> <p>“Program and erase specifications” table: updated symbols</p> <p>PFCRn settings vs. frequency of operation: replaced “FLASH_BIU” with “PFCRn” in table title; updated field names and frequencies</p> <p>“Flash power supply DC electrical characteristics” table: deleted footnote 2</p> <p>Crystal oscillator and resonator connection scheme: inserted footnote about possibly requiring a series resistor</p> <p>Fast external crystal oscillator (4 to 16 MHz) electrical characteristics: updated parameter classification for $V_{FXOSCOP}$</p> <p>Slow external crystal oscillator (32 kHz) electrical characteristics: updated footnote 1</p> <p>Section “ADC electrical characteristics”: updated symbols for offset error and gain error</p> <p>Section “Input impedance and ADC accuracy”: changed “V_A/V_{A2}” to “V_{A2}/V_A” in Equation 11</p> <p>ADC input leakage current: updated I_{LKG} characteristics</p> <p>ADC_0 conversion characteristics table: replaced instances of “$ADCx_conf_sample_input$” with “INPSAMP”, replaced instances of “$ADCx_conf_comp$” with “INPCMP”</p> <p>ADC_1 characteristic and error definitions: replaced “AVDD” with “V_{DD_ADC}”</p> <p>ADC_1 conversion characteristics table: replaced instances of “$ADCx_conf_sample_input$” with “INPSAMP”; replaced instances of “$ADCx_conf_comp$” with “INPCMP”</p> <p>Updated “On-chip peripherals current consumption” table</p>