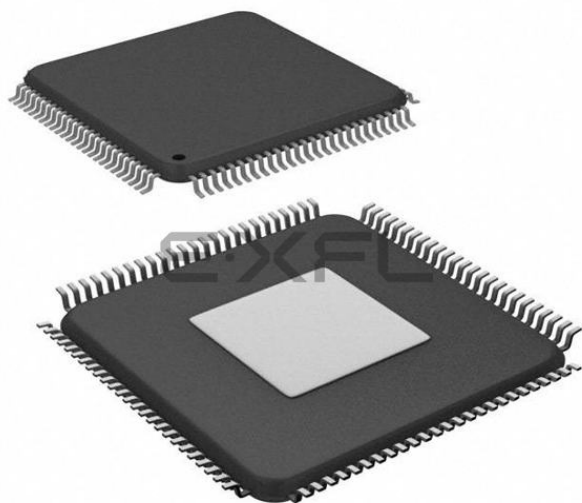




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Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	120MHz
Connectivity	CANbus, EBI/EMI, I ² C, LINbus, SPI, UART, USB
Peripherals	DMA, I ² S, LED, POR, PWM, WDT
Number of I/O	55
Program Memory Size	768KB (768K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	160K x 8
Voltage - Supply (Vcc/Vdd)	3.13V ~ 3.63V
Data Converters	A/D 24x12b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP Exposed Pad
Supplier Device Package	PG-LQFP-100-11
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/xmc4502f100f768acxqma1

Table of Contents

3.3.6	JTAG Interface Timing	76
3.3.7	Serial Wire Debug Port (SW-DP) Timing	78
3.3.8	Embedded Trace Macro Cell (ETM) Timing	79
3.3.9	Peripheral Timing	80
3.3.9.1	Delta-Sigma Demodulator Digital Interface Timing	80
3.3.9.2	Synchronous Serial Interface (USIC SSC) Timing	81
3.3.9.3	Inter-IC (IIC) Interface Timing	84
3.3.9.4	Inter-IC Sound (IIS) Interface Timing	86
3.3.9.5	SDMMC Interface Timing	88
3.3.10	EBU Timing	96
3.3.10.1	EBU Asynchronous Timing	96
3.3.10.2	EBU Burst Mode Access Timing	103
3.3.10.3	EBU Arbitration Signal Timing	105
3.3.10.4	EBU SDRAM Access Timing	106
3.3.11	USB Interface Characteristics	110
3.3.12	Ethernet Interface (ETH) Characteristics	111
3.3.12.1	ETH Measurement Reference Points	111
3.3.12.2	ETH Management Signal Parameters (ETH_MDC, ETH_MDIO) . .	112
3.3.12.3	ETH MII Parameters	113
3.3.12.4	ETH RMII Parameters	114
4	Package and Reliability	115
4.1	Package Parameters	115
4.1.1	Thermal Considerations	115
4.2	Package Outlines	117
4.3	Quality Declarations	122

Input/Output Lines

- Programmable port driver control module (PORTS)
- Individual bit addressability
- Tri-stated in input mode
- Push/pull or open drain output mode
- Boundary scan test support over JTAG interface

On-Chip Debug Support

- Full support for debug features: 8 breakpoints, CoreSight, trace
- Various interfaces: ARM-JTAG, SWD, single wire trace

1.1 Ordering Information

The ordering code for an Infineon microcontroller provides an exact reference to a specific product. The code "XMC4<DDD>-<Z><PPP><T><FFFF>" identifies:

- <DDD> the derivatives function set
- <Z> the package variant
 - E: LFBGA
 - F: LQFP
 - Q: VQFN
- <PPP> package pin count
- <T> the temperature range:
 - F: -40°C to 85°C
 - X: -40°C to 105°C
 - K: -40°C to 125°C
- <FFFF> the Flash memory size.

For ordering codes for the XMC4500 please contact your sales representative or local distributor.

This document describes several derivatives of the XMC4500 series, some descriptions may not apply to a specific product.

For simplicity the term **XMC4500** is used for all derivatives throughout this document.

Summary of Features
Table 2 Features of XMC4500 Device Types (cont'd)

Derivative ¹⁾	LEDTS Intf.	SDMMC Intf.	EBU Intf. ²⁾	ETH Intf. ³⁾	USB Intf.	USIC Chan.	MultiCAN Nodes, MO
XMC4504-F144x512	1	1	SDM	-	-	3 x 2	-
XMC4504-F100x512	1	1	M16	-	-	3 x 2	-

1) x is a placeholder for the supported temperature range.

2) Memory types supported S=SDRAM, D=DEMUX, M=MUX 16-bit and 32-bit, M16=MUX 16-bit

3) Supported interfaces, M=MII, R=RMII.

Table 3 Features of XMC4500 Device Types

Derivative ¹⁾	ADC Chan.	DSD Chan.	DAC Chan.	CCU4 Slice	CCU8 Slice	POSIF Intf.
XMC4500-E144x1024	32	4	2	4 x 4	2 x 4	2
XMC4500-F144x1024	32	4	2	4 x 4	2 x 4	2
XMC4500-F100x1024	24	4	2	4 x 4	2 x 4	2
XMC4500-F144x768	32	4	2	4 x 4	2 x 4	2
XMC4500-F100x768	24	4	2	4 x 4	2 x 4	2
XMC4502-F100x768	24	4	2	4 x 4	2 x 4	2
XMC4504-F144x512	32	4	2	4 x 4	2 x 4	2
XMC4504-F100x512	24	4	2	4 x 4	2 x 4	2

1) x is a placeholder for the supported temperature range.

1.4 Definition of Feature Variants

The XMC4500 types are offered with several memory sizes and number of available VADC channels. [Table 4](#) describes the location of the available Flash memory, [Table 5](#) describes the location of the available SRAMs, [Table 6](#) the available VADC channels.

Table 4 Flash Memory Ranges

Total Flash Size	Cached Range	Uncached Range
512 Kbytes	0800 0000 _H – 0807 FFFF _H	0C00 0000 _H – 0C07 FFFF _H

General Device Information

	1	2	3	4	5	6	7	8	9	10	11	12	
A	VSS	VDDC	P0.2	P0.3	P0.5	P0.6	P3.6	P0.8	P4.1	P1.8	VDDP	VSS	A
B	VDDP	P3.1	P3.2	P0.10	P0.4	P3.5	P0.7	P4.0	P1.6	P1.7	P1.9	VDDC	B
C	P3.0	P3.13	P0.1	P0.0	P0.13	P0.15	P4.4	P4.6	P4.7	P1.4	P1.2	P1.3	C
D	USB_D M	P3.12	P3.11	P0.9	P0.12	P3.14	P3.15	P4.5	P1.0	P1.5	P1.11	P1.10	D
E	USB_D P	VBUS	P3.8	P3.7	P0.11	P0.14	P3.4	P4.2	P1.1	P1.14	P1.12	P1.13	E
F	RTC_X TAL2	RTC_X TAL1	HIB_I O_1	HIB_I O_0	P3.9	P3.10	P3.3	P4.3	P6.1	P6.4	P6.5	P6.6	F
G	VBAT	P15.3	P15.5	P15.4	P15.6	P15.7	TMS	TCK	P6.3	P6.0	PORST	P1.15	G
H	P15.2	P14.15	P14.14	P14.13	P5.10	P5.8	P5.2	P5.1	P5.0	P6.2	XTAL1	XTAL2	H
J	P14.12	P14.7	P14.6	P14.3	P5.11	P2.15	P5.7	P5.5	P2.6	P5.3	P2.0	VSSO	J
K	P14.4	P14.5	P14.2	P15.15	P15.12	P5.9	P2.14	P5.6	P2.7	P5.4	P2.2	P2.1	K
L	VDDA	P14.1	P14.0	P15.14	P14.9	P15.9	P2.12	P2.10	P2.8	P2.4	P2.3	VDDP	L
M	VSSA	VAGND	VAREF	P15.13	P14.8	P15.8	P2.13	P2.11	P2.9	P2.5	VDDC	VSS	M
	1	2	3	4	5	6	7	8	9	10	11	12	

XMC4500- (top view)

Figure 6 XMC4500 PG-LFBGA-144 Pin Configuration (top view)

General Device Information
Table 9 Package Pin Mapping (cont'd)

Function	LQFP-144	LFBGA-144	LQFP-100	Pad Type	Notes
P0.11	139	E5	95	A1+	
P0.12	138	D5	94	A1+	
P0.13	137	C5	-	A1+	
P0.14	136	E6	-	A1+	
P0.15	135	C6	-	A1+	
P1.0	112	D9	79	A1+	
P1.1	111	E9	78	A1+	
P1.2	110	C11	77	A2	
P1.3	109	C12	76	A2	
P1.4	108	C10	75	A1+	
P1.5	107	D10	74	A1+	
P1.6	116	B9	83	A2	
P1.7	115	B10	82	A2	
P1.8	114	A10	81	A2	
P1.9	113	B11	80	A2	
P1.10	106	D12	73	A1+	
P1.11	105	D11	72	A1+	
P1.12	104	E11	71	A2	
P1.13	103	E12	70	A2	
P1.14	102	E10	69	A2	
P1.15	94	G12	68	A2	
P2.0	74	J11	52	A2	
P2.1	73	K12	51	A2	After a system reset, via HWSEL this pin selects the DB.TDO function.
P2.2	72	K11	50	A2	
P2.3	71	L11	49	A2	
P2.4	70	L10	48	A2	
P2.5	69	M10	47	A2	
P2.6	76	J9	54	A1+	
P2.7	75	K9	53	A1+	
P2.8	68	L9	46	A2	
P2.9	67	M9	45	A2	

Table 11 Port I/O Functions (cont'd)

Function	Outputs						Inputs								
	ALT1	ALT2	ALT3	ALT4	HWO0	HWO1	HWI0	HWI1	Input	Input	Input	Input	Input	Input	Input
P15.12												VADC_G3CH4			
P15.13												VADC_G3CH5			
P15.14												VADC_G3CH6			
P15.15												VADC_G3CH7			
USB_DP															
USB_DM															
HIB_IO_0	HIBOUT	WWDT_SERVICE_OUT							WAKEUPA						
HIB_IO_1	HIBOUT	WWDT_SERVICE_OUT							WAKEUPB						
TCK							DB.TCK/ SWCLK								
TMS					DB.TMS/ SWDIO										
PORST															
XTAL1									U0C0. DX0F	U0C1. DX0F	U1C0. DX0F	U1C1. DX0F	U2C0. DX0F	U2C1. DX0F	
XTAL2															
RTC_XTAL1											ERU0. 1B1				
RTC_XTAL2															

3 Electrical Parameters

3.1 General Parameters

3.1.1 Parameter Interpretation

The parameters listed in this section partly represent the characteristics of the XMC4500 and partly its requirements on the system. To aid interpreting the parameters easily when evaluating them for a design, they are marked with a two-letter abbreviation in column "Symbol":

- **CC**
Such parameters indicate **C**ontroller **C**haracteristics, which are a distinctive feature of the XMC4500 and must be regarded for system design.
- **SR**
Such parameters indicate **S**ystem **R**equirements, which must be provided by the application system in which the XMC4500 is designed in.

3.1.2 Absolute Maximum Ratings

Stresses above the values listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions may affect device reliability.

Table 12 Absolute Maximum Rating Parameters

Parameter	Symbol		Values			Unit	Note / Test Condition
			Min.	Typ.	Max.		
Storage temperature	T_{ST}	SR	-65	–	150	°C	–
Junction temperature	T_J	SR	-40	–	150	°C	–
Voltage at 3.3 V power supply pins with respect to V_{SS}	V_{DDP}	SR	–	–	4.3	V	–
Voltage on any Class A and dedicated input pin with respect to V_{SS}	V_{IN}	SR	-1.0	–	$V_{DDP} + 1.0$ or max. 4.3	V	whichever is lower
Voltage on any analog input pin with respect to V_{AGND}	V_{AIN} V_{AREF}	SR	-1.0	–	$V_{DDP} + 1.0$ or max. 4.3	V	whichever is lower
Input current on any pin during overload condition	I_{IN}	SR	-10	–	+10	mA	
Absolute maximum sum of all input circuit currents for one port group during overload condition ¹⁾	ΣI_{IN}	SR	-25	–	+25	mA	
Absolute maximum sum of all input circuit currents during overload condition	ΣI_{IN}	SR	-100	–	+100	mA	

1) The port groups are defined in [Table 16](#).

Figure 10 explains the input voltage ranges of V_{IN} and V_{AIN} and its dependency to the supply level of V_{DDP} . The input voltage must not exceed 4.3 V, and it must not be more than 1.0 V above V_{DDP} . For the range up to $V_{DDP} + 1.0$ V also see the definition of the overload conditions in [Section 3.1.3](#).

3.1.4 Pad Driver and Pad Classes Summary

This section gives an overview on the different pad driver classes and their basic characteristics.

Table 17 Pad Driver and Pad Classes Overview

Class	Power Supply	Type	Sub-Class	Speed Grade	Load	Termination
A	3.3 V	LVTTTL I/O	A1 (e.g. GPIO)	6 MHz	100 pF	No
			A1+ (e.g. serial I/Os)	25 MHz	50 pF	Series termination recommended
			A2 (e.g. ext. Bus)	80 MHz	15 pF	Series termination recommended

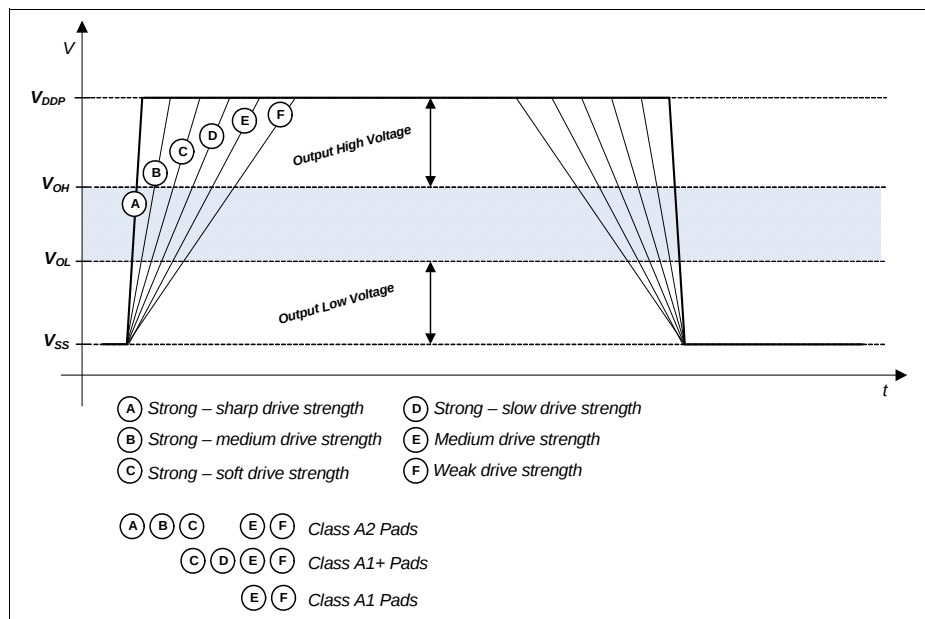


Figure 12 Output Slopes with different Pad Driver Modes

Figure 12 is a qualitative display of the resulting output slope performance with different output driver modes. The detailed input and output characteristics are listed in [Section 3.2.1](#).

Electrical Parameters
Table 23 VADC Parameters (Operating Conditions apply)

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Total Unadjusted Error	TUE_{CC}	-4	—	4	LSB	12-bit resolution; $V_{DDA} = 3.3 V$; $V_{AREF} = V_{DDA}$ ⁷⁾
Differential Non-Linearity Error ⁸⁾	$EA_{DNL_{CC}}$	-3	—	3	LSB	
Gain Error ⁸⁾	$EA_{GAIN_{CC}}$	-4	—	4	LSB	
Integral Non-Linearity ⁸⁾	$EA_{INL_{CC}}$	-3	—	3	LSB	
Offset Error ⁸⁾	$EA_{OFF_{CC}}$	-4	—	4	LSB	
Worst case ADC V_{DDA} power supply current per active converter	$I_{DDAA_{CC}}$	—	1.5	2	mA	during conversion $V_{DDP} = 3.6 V$, $T_j = 150 ^\circ C$
Charge consumption on V_{AREF} per conversion ⁵⁾	$Q_{CONV_{CC}}$	—	30	—	pC	$0 V \leq V_{AREF} \leq V_{DDA}$ ⁹⁾
ON resistance of the analog input path	$R_{AIN_{CC}}$	—	700	1 700	Ohm	
ON resistance for the ADC test (pull down for AIN7)	$R_{AIN7T_{CC}}$	180	550	900	Ohm	
Resistance of the reference voltage input path	$R_{AREF_{CC}}$	—	700	1 700	Ohm	

- 1) A running conversion may become imprecise in case the normal conditions are violated (voltage overshoot).
- 2) If the analog reference voltage is below V_{DDA} , then the ADC converter errors increase. If the reference voltage is reduced by the factor k ($k < 1$), TUE, DNL, INL, Gain, and Offset errors increase also by the factor $1/k$.
- 3) The leakage current definition is a continuous function, as shown in figure ADCx Analog Inputs Leakage. The numerical values defined determine the characteristic points of the given continuous linear approximation - they do not define step function (see [Figure 16](#)).
- 4) The sampling capacity of the conversion C-network is pre-charged to $V_{AREF}/2$ before the sampling moment. Because of the parasitic elements, the voltage measured at AINx can deviate from $V_{AREF}/2$.
- 5) Applies to AINx, when used as alternate reference input.
- 6) This represents an equivalent switched capacitance. This capacitance is not switched to the reference voltage at once. Instead, smaller capacitances are successively switched to the reference voltage.
- 7) For 10-bit conversions, the errors are reduced to 1/4; for 8-bit conversions, the errors are reduced to 1/16. Never less than ± 1 LSB.
- 8) The sum of DNL/INL/GAIN/OFF errors does not exceed the related total unadjusted error TUE.
- 9) The resulting current for a conversion can be calculated with $I_{AREF} = Q_{CONV} / t_c$.
The fastest 12-bit post-calibrated conversion of $t_c = 550$ ns results in a typical average current of $I_{AREF} = 54.5 \mu A$.

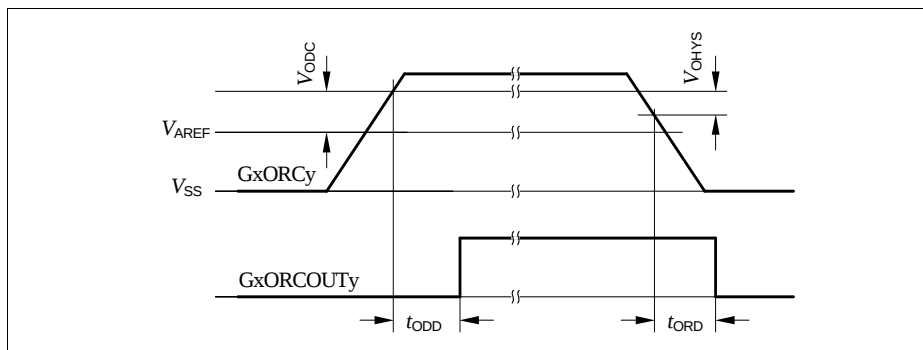


Figure 18 GxORCOUTy Trigger Generation

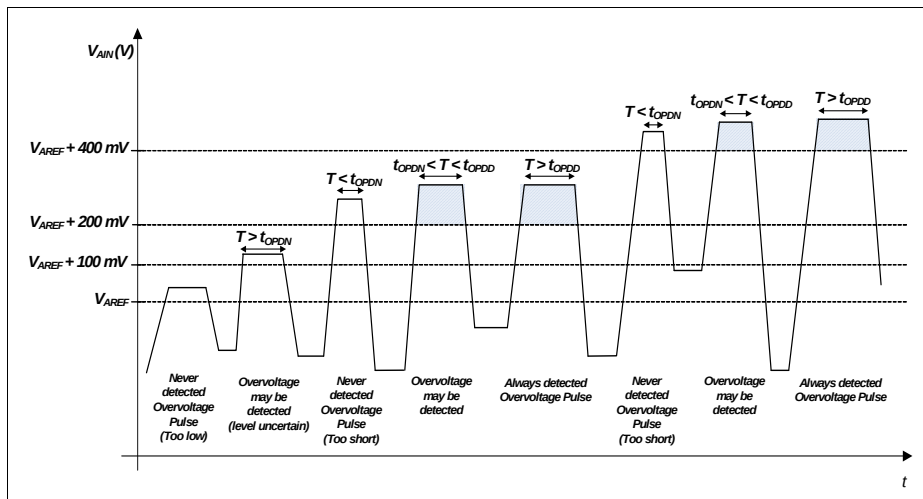


Figure 19 ORC Detection Ranges

Electrical Parameters

Table 32 Power Supply Parameters

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Wake-up time from Deep Sleep to Active mode		—	—	—	ms	Defined by the wake-up of the Flash module, see Section 3.2.9
Wake-up time from Hibernate mode		—	—	—	ms	Wake-up via power-on reset event, see Section 3.3.2

- 1) CPU executing code from Flash, all peripherals idle.
- 2) CPU executing code from Flash.
- 3) CPU in sleep, all peripherals idle, Flash in Active mode.
- 4) CPU in sleep, Flash in Active mode.
- 5) CPU in sleep, peripherals disabled, after wake-up code execution from RAM.
- 6) To wake-up the Flash from its Sleep mode, $f_{CPU} \geq 1$ MHz is required.
- 7) OSC_ULP operating with external crystal on RTC_XTAL
- 8) OSC_ULP off, Hibernate domain operating with OSC_SI clock
- 9) Test Power Loop: $f_{SYS} = 120$ MHz, CPU executing benchmark code from Flash, all CCUs in 100kHz timer mode, all ADC groups in continuous conversion mode, USICs as SPI in internal loop-back mode, CAN in 500kHz internal loop-back mode, interrupt triggered DMA block transfers to parity protected RAMs and FCE, DTS measurements and FPU calculations.
The power consumption of each customer application will most probably be lower than this value, but must be evaluated separately.
- 10) I_{DDP} decreases typically by approximately 6 mA when f_{SYS} decreases by 10 MHz, at constant T_j
- 11) Sum of currents of all active converters (ADC and DAC)

Table 35 Power Sequencing Parameters

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Positive Load Step Current	ΔI_{PLS} SR	-	-	50	mA	Load increase on V_{DDP} $\Delta t \leq 10$ ns
Negative Load Step Current	ΔI_{NLS} SR	-	-	150	mA	Load decrease on V_{DDP} $\Delta t \leq 10$ ns
V_{DDC} Voltage Over- / Undershoot from Load Step	ΔV_{LS} CC	-	-	± 100	mV	For maximum positive or negative load step
Positive Load Step Settling Time	t_{PLSS} SR	50	-	-	μ s	
Negative Load Step Settling Time	t_{NLSS} SR	100	-	-	μ s	
External Buffer Capacitor on V_{DDC}	C_{EXT} SR	-	10	-	μ F	In addition $C = 100$ nF capacitor on each V_{DDC} pin

Positive Load Step Examples

System assumptions:

$f_{CPU} = f_{SYS}$, target frequency $f_{CPU} = 120$ MHz, main PLL $f_{VCO} = 480$ MHz, stepping done by K2 divider, t_{PLSS} between individual steps:

24 MHz - 48 MHz - 68 MHz - 96 MHz - 120 MHz (K2 steps 20 - 10 - 7 - 5 - 4)

24 MHz - 68 MHz - 96 MHz - 120 MHz (K2 steps 20 - 7 - 5 - 4)

24 MHz - 68 MHz - 120 MHz (K2 steps 20 - 7 - 4)

3.3.5 Internal Clock Source Characteristics

Note: These parameters are not subject to production test, but verified by design and/or characterization.

Fast Internal Clock Source

Table 37 Fast Internal Clock Parameters

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Nominal frequency	$f_{\text{OFINC CC}}$	–	36.5	–	MHz	not calibrated
		–	24	–	MHz	calibrated
Accuracy	$\Delta f_{\text{OFI CC}}$	-0.5	–	0.5	%	automatic calibration ¹⁾²⁾
		-15	–	15	%	factory calibration, $V_{\text{DDP}} = 3.3 \text{ V}$
		-25	–	25	%	no calibration, $V_{\text{DDP}} = 3.3 \text{ V}$
		-7	–	7	%	Variation over voltage range ³⁾ $3.13 \text{ V} \leq V_{\text{DDP}} \leq 3.63 \text{ V}$
Start-up time	$t_{\text{OFIS CC}}$	–	50	–	μs	

1) Error in addition to the accuracy of the reference clock.

2) Automatic calibration compensates variations of the temperature and in the V_{DDP} supply voltage.

3) Deviations from the nominal V_{DDP} voltage induce an additional error to the uncalibrated and/or factory calibrated oscillator frequency.

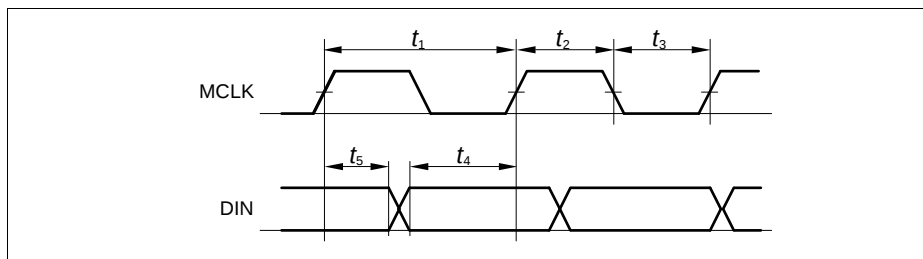


Figure 32 DSD Data Timing

3.3.9.2 Synchronous Serial Interface (USIC SSC) Timing

The following parameters are applicable for a USIC channel operated in SSC mode.

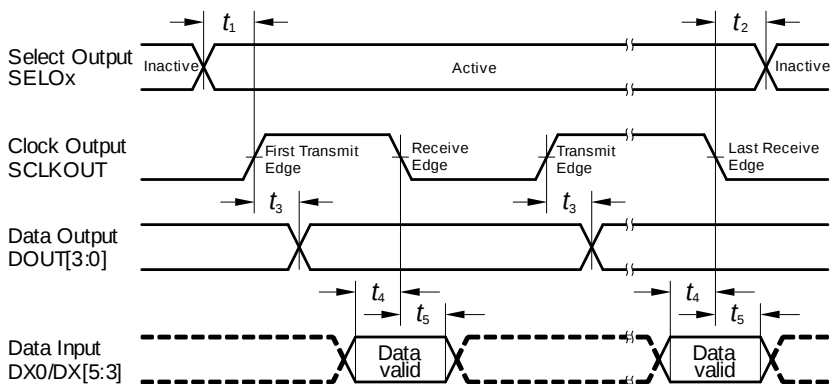
Note: These parameters are not subject to production test, but verified by design and/or characterization.

Table 43 USIC SSC Master Mode Timing

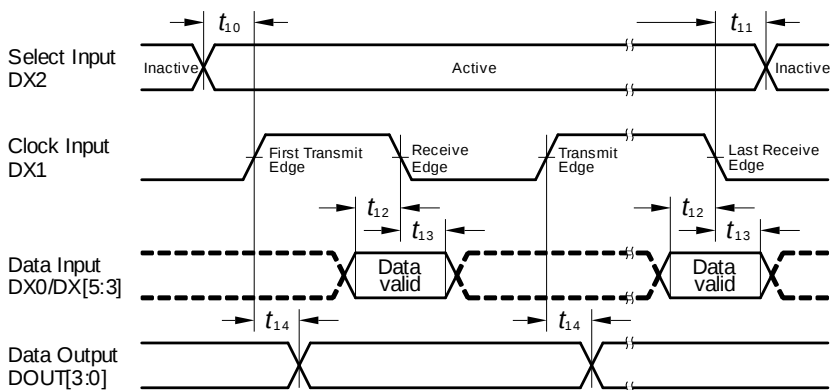
Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
SCLKOUT master clock period	t_{CLK} CC	33.3	–	–	ns	
Slave select output SELO active to first SCLKOUT transmit edge	t_1 CC	$t_{PB} - 6.5^{1)}$	–	–	ns	
Slave select output SELO inactive after last SCLKOUT receive edge	t_2 CC	$t_{PB} - 8.5^{1)}$	–	–	ns	
Data output DOUT[3:0] valid time	t_3 CC	-6	–	8	ns	
Receive data input DX0/DX[5:3] setup time to SCLKOUT receive edge	t_4 SR	23	–	–	ns	
Data input DX0/DX[5:3] hold time from SCLKOUT receive edge	t_5 SR	1	–	–	ns	

1) $t_{PB} = 1 / f_{PB}$

Master Mode Timing



Slave Mode Timing



Transmit Edge: with this clock edge transmit data is shifted to transmit data output

Receive Edge: with this clock edge receive data at receive data input is latched

Drawn for BRGH.SCLKCFG = 00b. Also valid for for SCLKCFG = 01b with inverted SCLKOUT signal

USIC_SSC_TMGX.VSD

Figure 33 USIC - SSC Master/Slave Mode Timing

Note: This timing diagram shows a standard configuration, for which the slave select signal is low-active, and the serial clock signal is not shifted and not inverted.

Table 52 SD Card Bus Timing for High-Speed Mode¹⁾

Parameter	Symbol	Values		Unit	Note/ Test Condition
		Min.	Max.		
SD card input setup time	t_{ISU}	6	–	ns	
SD card input hold time	t_{IH}	2	–	ns	
SD card output valid time	t_{ODLY}	–	14	ns	
SD card output hold time	t_{OH}	2.5	–	ns	

1) Reference card timing values for calculation examples. Not subject to production test and not characterized.

High-Speed Output Path (Write)

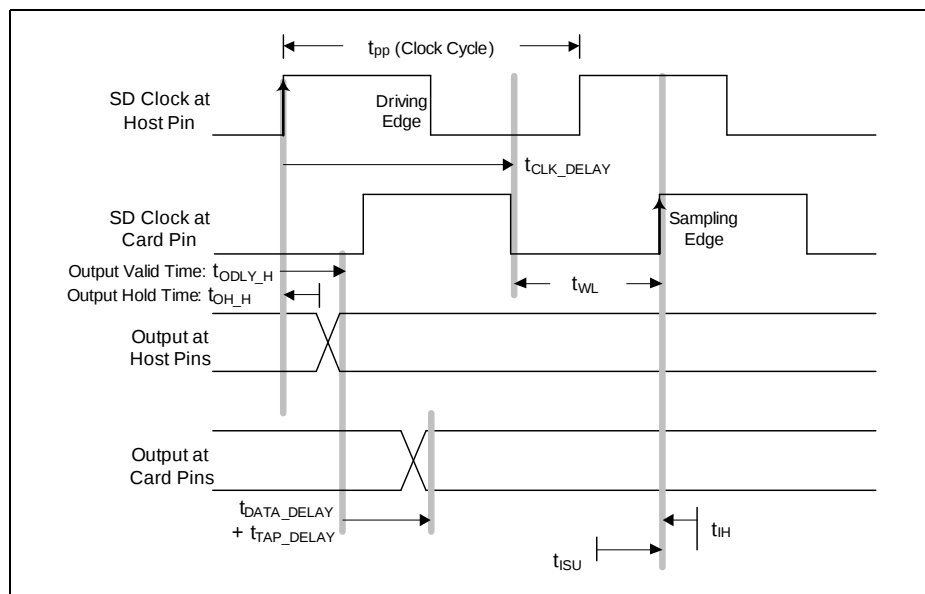


Figure 39 High-Speed Output Path

High-Speed Write Meeting Setup (Maximum Delay)

The following equations show how to calculate the allowed skew range between the SD_CLK and SD_DAT/CMD signals on the PCB.

4.2 Package Outlines

Table 65 Differences PG-LQFP-14-18 to PG-LQFP-144-24

Change	PG-LQFP-144-18	PG-LQFP-144-24
Thermal Resistance Junction Ambient ($R_{\Theta JA}$)	22.4 K/W	21.0 K/W
Lead Width	0.22 ^{+0.05} mm	0.2 ^{+0.07} _{-0.03} mm
Lead Thickness	0.15 ^{+0.05} _{-0.06} mm	0.127 ^{+0.073} _{-0.037} mm
Exposed Die Pad outer dimensions	6.5 mm × 6.5 mm	6.5 mm × 6.5 mm
Exposed Die Pad U-Groove inner dimensions	n.a.	5.7 mm × 5.7 mm

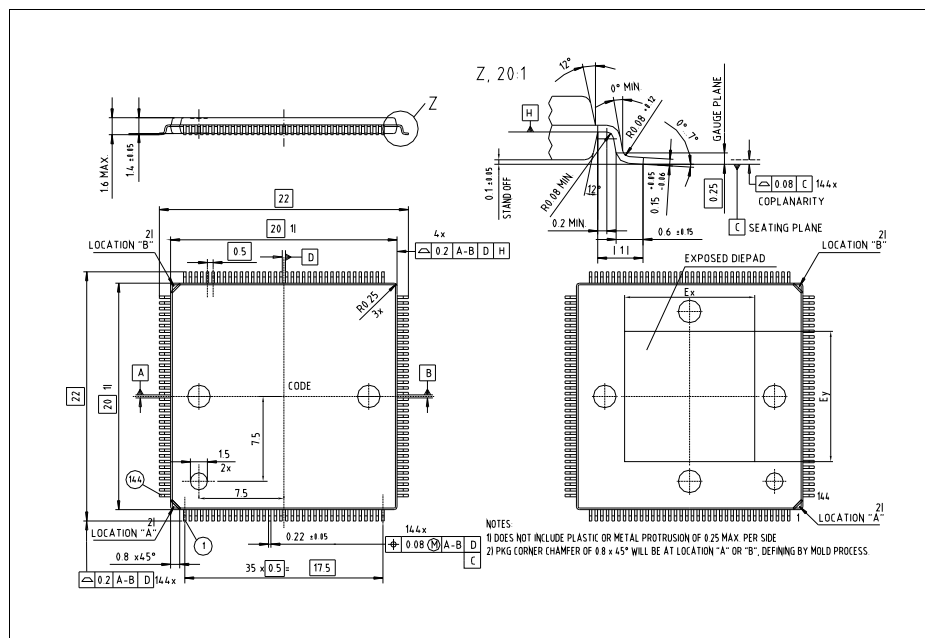


Figure 55 PG-LQFP-144-18 (Plastic Green Low Profile Quad Flat Package)

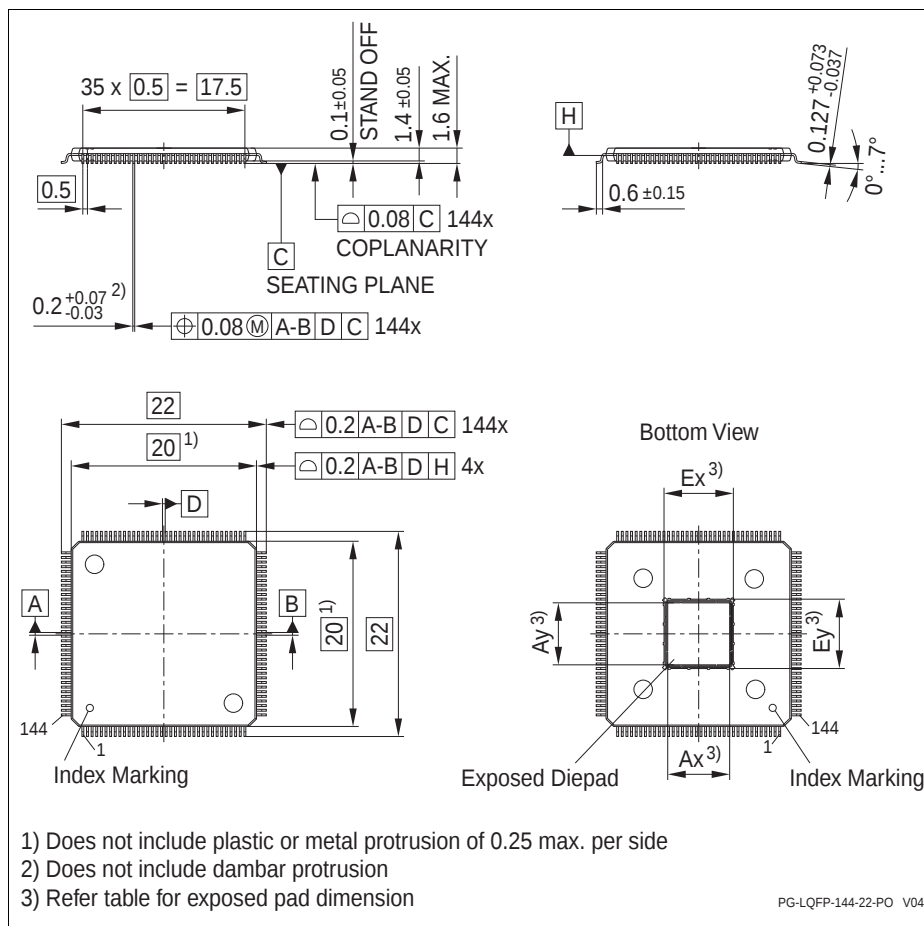


Figure 56 PG-LQFP-144-24 (Plastic Green Low Profile Quad Flat Package)

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