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Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	4MHz
Connectivity	-
Peripherals	POR, WDT
Number of I/O	13
Program Memory Size	896B (512 x 14)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	80 x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 5.5V
Data Converters	-
Oscillator Type	External
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Through Hole
Package / Case	18-DIP (0.300", 7.62mm)
Supplier Device Package	18-PDIP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16c554-04-p

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6.0 SPECIAL FEATURES OF THE CPU

What sets a microcontroller apart from other processors are special circuits to deal with the needs of real-time applications. The PIC16C55X family has a host of such features intended to maximize system reliability, minimize cost through elimination of external components, provide power saving operating modes and offer code protection.

These are:

- 1. OSC selection
- 2. RESET
- 3. Power-on Reset (POR)
- 4. Power-up Timer (PWRT)
- 5. Oscillator Start-Up Timer (OST)
- 6. Interrupts
- 7. Watchdog Timer (WDT)
- 8. SLEEP
- 9. Code protection
- 10. ID Locations
- 11. In-circuit serial programming™

The PIC16C55X has a Watchdog Timer which is controlled by configuration bits. It runs off its own RC oscillator for added reliability. There are two timers that offer necessary delays on power-up. One is the Oscillator Start-up Timer (OST), which is intended to keep the chip in RESET until the crystal oscillator is stable. The other is the Power-up Timer (PWRT), which provides a fixed delay of 72 ms (nominal) on power-up only, designed to keep the part in RESET while the power supply stabilizes. With these two functions on-chip, most applications need no external RESET circuitry.

The SLEEP mode is designed to offer a very low current Power-down mode. The user can wake-up from SLEEP through external RESET, Watchdog Timer wake-up or through an interrupt. Several oscillator options are also made available to allow the part to fit the application. The RC oscillator option saves system cost while the LP crystal option saves power. A set of configuration bits are used to select various options.

6.1 Configuration Bits

The configuration bits can be programmed (read as '0') or left unprogrammed (read as '1') to select various device configurations. These bits are mapped in program memory location 2007h.

The user will note that address 2007h is beyond the user program memory space. In fact, it belongs to the special test/configuration memory space (2000h-3FFFh), which can be accessed only during programming.

6.3 RESET

The PIC16C55X differentiates between various kinds of RESET:

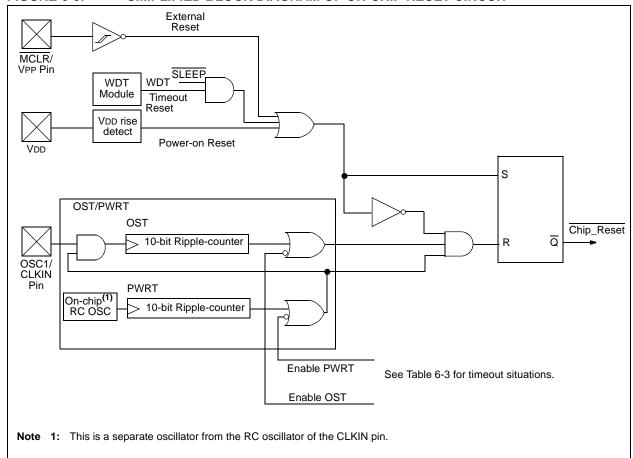
- Power-on Reset (POR)
- MCLR Reset during normal operation
- MCLR Reset during SLEEP
- WDT Reset (normal operation)
- WDT wake-up (SLEEP)

Some registers are not affected in any RESET condition; their status is unknown on POR and unchanged in any other RESET. Most other registers are reset to a "RESET state" on Power-on Reset, on MCLR or WDT Reset and on MCLR Reset during SLEEP. They are not affected by a WDT wake-up, since this is viewed as the resumption of normal operation. TO and PD bits are set or cleared differently in different RESET situations as indicated in Table 6-4. These bits are used in software to determine the nature of the RESET. See Table 6-6 for a full description of RESET states of all registers.

A simplified block diagram of the on-chip RESET circuit is shown in Figure 6-6.

The MCLR Reset path has a noise filter to detect and ignore small pulses. See Table 10-3 for pulse width specification.

FIGURE 6-6: SIMPLIFIED BLOCK DIAGRAM OF ON-CHIP RESET CIRCUIT



6.4 Power-on Reset (POR), Power-up Timer (PWRT), Oscillator Start-up Timer (OST)

6.4.1 POWER-ON RESET (POR)

A Power-on Reset pulse is generated on-chip when VDD rise is detected (in the range of 1.6V - 1.8V). To take advantage of the POR, just tie the $\overline{\text{MCLR}}$ pin through a resistor to VDD. This will eliminate external RC components usually needed to create Power-on Reset. A maximum rise time for VDD is required. See Electrical Specifications for details.

The POR circuit does not produce internal RESET when VDD declines.

When the device starts normal operation (exits the RESET condition), device operating parameters (voltage, frequency, temperature, etc.) must be met to ensure operation. If these conditions are not met, the device must be held in RESET until the operating conditions are met.

For additional information, refer to Application Note AN607 "Power-up Trouble Shooting".

6.4.2 POWER-UP TIMER (PWRT)

The Power-up Timer provides a fixed 72 ms (nominal) timeout on power-up only, from POR. The Power-up Timer operates on an internal RC oscillator. The chip is kept in RESET as long as PWRT is active. The PWRT delay allows the VDD to rise to an acceptable level. A configuration bit, PWRTE can disable (if set) or enable (if cleared or programmed) the Power-up Timer. The Power-Up Time delay will vary from chip to chip and due to VDD, temperature and process variation. See DC parameters for details.

6.4.3 OSCILLATOR START-UP TIMER (OST)

The Oscillator Start-Up Timer (OST) provides a 1024 oscillator cycle (from OSC1 input) delay after the PWRT delay is over. This ensures that the crystal oscillator or resonator has started and stabilized.

The OST timeout is invoked only for XT, LP and HS modes and only on Power-on Reset or wake-up from SLEEP.

6.4.4 TIMEOUT SEQUENCE

On power-up, the timeout sequence is as follows: First PWRT timeout is invoked after POR has expired, then OST is activated. The total timeout will vary based on oscillator configuration and PWRTE bit status. For example, in RC mode with PWRTE bit erased (PWRT disabled), there will be no timeout at all. Figure 6-7, Figure 6-8 and Figure 6-9 depict timeout sequences.

Since the timeouts occur from the POR pulse, if MCLR is kept low long enough, the timeouts will expire. Then bringing MCLR high will begin execution immediately (see Figure 6-8). This is useful for testing purposes or to synchronize more than one PIC16C55X device operating in parallel.

Table 6-5 shows the RESET conditions for some special registers, while Table 6-6 shows the RESET conditions for all the registers.

FIGURE 6-13: WATCHDOG TIMER BLOCK DIAGRAM

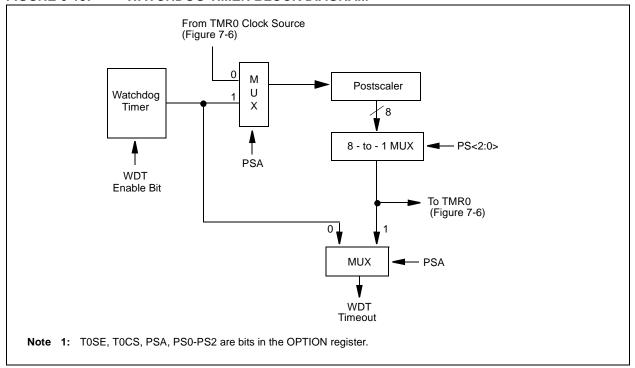


TABLE 6-7: SUMMARY OF WATCHDOG TIMER REGISTERS

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR	Value on all other RESETS
2007h	Config. bits	_	Reserved	CP1	CP0	PWRTE	WDTE	FOSC1	FOSC0		
81h	OPTION	RBPU	INTEDG	T0CS	T0SE	PSA	PS2	PS1	PS0	1111 1111	1111 1111

Legend: x = unknown, u = unchanged, q = value depends on condition, — = unimplemented, read as '0'. Shaded cells are not used by the Watchdog Timer.

NOTES:

TABLE 8-2: PIC16C55X INSTRUCTION SET

Mnemonic,		Description			14-Bit (Opcode	•	Status	Notes
Opera	nds	Description		MSb			LSb	Affected	Notes
	BYTE-ORIENTED FILE REGISTER OPERATIONS								
ADDWF	f, d	Add W and f	1	00	0111	dfff	ffff	C,DC,Z	1,2
ANDWF	f, d	AND W with f	1	00	0101	dfff	ffff	Z	1,2
CLRF	f	Clear f	1	00	0001	lfff	ffff	Z	2
CLRW	-	Clear W	1	00	0001	0000	0011	Z	
COMF	f, d	Complement f	1	00	1001	dfff	ffff	Z	1,2
DECF	f, d	Decrement f	1	00	0011	dfff	ffff	Z	1,2
DECFSZ	f, d	Decrement f, Skip if 0	1(2)	00	1011	dfff	ffff		1,2,3
INCF	f, d	Increment f	1	00	1010	dfff	ffff	Z	1,2
INCFSZ	f, d	Increment f, Skip if 0	1(2)	00	1111	dfff	ffff		1,2,3
IORWF	f, d	Inclusive OR W with f	1	00	0100	dfff	ffff	Z	1,2
MOVF	f, d	Move f	1	00	1000	dfff	ffff	Z	1,2
MOVWF	f	Move W to f	1	00	0000	lfff	ffff		
NOP	-	No Operation	1	00	0000	0xx0	0000		
RLF	f, d	Rotate Left f through Carry	1	00	1101	dfff	ffff	С	1,2
RRF	f, d	Rotate Right f through Carry	1	00	1100	dfff	ffff	С	1,2
SUBWF	f, d	Subtract W from f	1	00	0010	dfff	ffff	C,DC,Z	1,2
SWAPF	f, d	Swap nibbles in f	1	00	1110	dfff	ffff		1,2
XORWF	f, d	Exclusive OR W with f	1	00	0110	dfff	ffff	Z	1,2
		BIT-ORIENTED FILE REGIST	ER OPER	RATION	IS				
BCF	f, b	Bit Clear f	1	01	00bb	bfff	ffff		1,2
BSF	f, b	Bit Set f	1	01	01bb	bfff	ffff		1,2
BTFSC	f, b	Bit Test f, Skip if Clear	1(2)	01	10bb	bfff	ffff		3
BTFSS	f, b	Bit Test f, Skip if Set	1(2)	01	11bb	bfff	ffff		3
		LITERAL AND CONTROL	OPERAT	IONS					
ADDLW	k	Add literal and W	1	11	111x	kkkk	kkkk	C,DC,Z	
ANDLW	k	AND literal with W	1	11	1001	kkkk	kkkk	Z	
CALL	k	Call subroutine	2	10	0kkk	kkkk	kkkk		
CLRWDT	-	Clear Watchdog Timer	1	00	0000	0110	0100	TO,PD	
GOTO	k	Go to address	2	10	1kkk	kkkk	kkkk		
IORLW	k	Inclusive OR literal with W	1	11	1000	kkkk	kkkk	Z	
MOVLW	k	Move literal to W	1	11	00xx	kkkk	kkkk		
RETFIE	-	Return from interrupt	2	00	0000	0000	1001		
RETLW	k	Return with literal in W	2	11	01xx	kkkk	kkkk		
RETURN	-	Return from Subroutine	2	00	0000	0000	1000		
SLEEP	-	Go into Standby mode	1	00	0000	0110	0011	TO,PD	
SUBLW	k	Subtract W from literal	1	11	110x	kkkk	kkkk	C,DC,Z	
XORLW	k	Exclusive OR literal with W	1	11	1010	kkkk	kkkk	Z	

Note 1: When an I/O register is modified as a function of itself (e.g., MOVF PORTB, 1), the value used will be that value present on the pins themselves. For example, if the data latch is '1' for a pin configured as input and is driven low by an external device, the data will be written back with a '0'.

^{2:} If this instruction is executed on the TMR0 register (and, where applicable, d = 1), the prescaler will be cleared if assigned to the Timer0 Module.

^{3:} If Program Counter (PC) is modified or a conditional test is true, the instruction requires two cycles. The second cycle is executed as a NOP.

CLRW	Clear W	1						
Syntax:	[label]	CLRW						
Operands:	None							
Operation:	$00h \rightarrow (W)$ $1 \rightarrow Z$							
Status Affected:	Z							
Encoding:	00	0001	0000	0011				
Description:	W register set.	is clear	ed. Zero bit	(Z) is				
Words:	1							
Cycles:	1							
Example	CLRW							
	Before In	structio	n					
	W	=	0x5A					
	After Instruction							
	W	=	0x00					
	Z	=	1					

COMF	Complement f							
Syntax:	[label]	COMF	f,d					
Operands:	$0 \le f \le 127$ $d \in [0,1]$							
Operation:	$(\bar{f}) \rightarrow (dest)$							
Status Affected:	Z							
Encoding:	00 1001 dfff ffff							
Description:	The contents of register 'f' are complemented. If 'd' is 0 the result is stored in W. If 'd' is 1 the result is stored back in register 'f'.							
Words:	1							
Cycles:	1							
Example	COMF	REG1,0)					
	Before In REG After Insti REG W	1 = ruction	0x13 0x13 0xEC					

CLRWDT	Clear Watchdog Timer							
Syntax:	[label]	CLRWD	Т					
Operands:	None							
Operation:	00h → WDT 0 → WDT prescaler, 1 → \overline{TO} 1 → \overline{PD}							
Status Affected:	TO, PD							
Encoding:	00	0000	0110	0100				
Description:	CLRWDT instruction resets the Watchdog Timer. It also resets the prescaler of the WDT. Status bits TO and PD are set.							
Words:	1							
Cycles:	1							
Example	CLRWDT							
	After Inst	counter	= er = =	? 0x00 0 1				

DECF	Decrement f							
Syntax:	[label] DECF f,d							
Operands:	$0 \le f \le 127$ $d \in [0,1]$							
Operation:	(f) - 1 \rightarrow (dest)							
Status Affected:	Z							
Encoding:	00 0011 dfff ffff							
Description:	Decrement register 'f'. If 'd' is 0 the result is stored in the W register. If 'd' is 1 the result is stored back in register 'f'.							
Words:	1							
Cycles:	1							
Example	DECF CNT, 1							
	Before Instruction $CNT = 0x01$ $Z = 0$ After Instruction $CNT = 0x00$ $Z = 1$							

Decrement f, Skip if 0								
[label]	DECFS	Z f,d						
$0 \le f \le 12$ $d \in [0,1]$	7							
$(f) - 1 \rightarrow ($	(dest);	skip if re	sult = 0					
None								
00	1011	dfff	ffff					
decrement placed in the result is plated if the result which is all A NOP is each	ed. If 'd' i he W reg aced bac t is 0, the ready feto xecuted i	s 0 the resister. If 'd' ik in register next instruched, is disnisted ma	sult is is 1 the er 'f'. uction, scarded.					
1								
1(2)								
HERE		-	•					
CONTINU	JE • •							
Before In:	struction	1						
PC	= addr	ess HERE	ŀ					
After Insti	ruction							
if CNT PC	= 0, = add ≠ 0,	ress CON'						
	$ [\ label \] \\ 0 \le f \le 12 \\ d \in [0,1] \\ (f) - 1 \to (0) \\ None \\ \hline 00 \\ The content of the con$	$ [\ label] \ \ DECFS2 \\ 0 \leq f \leq 127 \\ d \in [0,1] \\ (f) -1 \rightarrow (dest); \\ None \\ \hline 00 $	$ [\textit{label}] \ DECFSZ \ f, d \\ 0 \leq f \leq 127 \\ d \in [0,1] \\ (f) - 1 \to (dest); \ skip if re \\ None \\ \hline 00 \qquad 1011 \qquad dfff \\ \hline The contents of register 'f' are \\ decremented. If 'd' is 0 the res \\ placed in the W register. If 'd' is \\ result is placed back in registe \\ If the result is 0, the next instruvhich is already fetched, is dis \\ A NOP is executed instead matwo-cycle instruction. \\ 1 \\ 1(2) \\ HERE DECFSZ CNT \\ GOTO LOCCONTINUE \bullet \\ \bullet \\ \bullet \\ \bullet \\ Before Instruction \\ PC e address HERE \\ After Instruction \\ CNT e CNT -1 \\ if CNT e 0, \\ PC e address CON' \\ if CNT \neq 0, \\ if CNT \neq 0, \\ \\ CNT e 0, \\ \\ if CNT e $					

GOTO	Unconditional Branch							
Syntax:	[label] GOTO k							
Operands:	$0 \leq k \leq 2047$							
Operation:	$k \rightarrow PC<10:0>$ PCLATH<4:3> \rightarrow PC<12:11>							
Status Affected:	None							
Encoding:	10 1kkk kkkk kkkk							
Description:	GOTO is an unconditional branch. The eleven bit immediate value is loaded into PC bits <10:0>. The upper bits of PC are loaded from PCLATH<4:3>. GOTO is a two-cycle instruction.							
Words:	1							
Cycles:	2							
Example	GOTO THERE							
	After Instruction							
	PC = Address THERE							
INCF	Increment f							
Syntax:	Increment f [label] INCF f,d							
_								
Syntax:	[$label$] INCF f,d $0 \le f \le 127$							
Syntax: Operands:	[$label$] INCF f,d $0 \le f \le 127$ $d \in [0,1]$							
Syntax: Operands: Operation:	[label] INCF f,d $0 \le f \le 127$ $d \in [0,1]$ $(f) + 1 \rightarrow (dest)$							
Syntax: Operands: Operation: Status Affected:	[$label$] INCF f,d $0 \le f \le 127$ $d \in [0,1]$ (f) + 1 \rightarrow (dest)							
Syntax: Operands: Operation: Status Affected: Encoding:	[label] INCF f,d $0 \le f \le 127$ $d \in [0,1]$ (f) + 1 → (dest) Z 00 1010 $dfff$ ffff The contents of register 'f' are incremented. If 'd' is 0 the result is placed in the W register. If 'd' is 1 the							
Syntax: Operands: Operation: Status Affected: Encoding: Description:	[label] INCF f,d $0 \le f \le 127$ d ∈ [0,1] (f) + 1 → (dest) Z							
Syntax: Operands: Operation: Status Affected: Encoding: Description: Words:	[label] INCF f,d $0 \le f \le 127$ $d \in [0,1]$ $(f) + 1 \rightarrow (dest)$ Z $00 \qquad 1010 \qquad dfff \qquad ffff$ The contents of register 'f' are incremented. If 'd' is 0 the result is placed in the W register. If 'd' is 1 the result is placed back in register 'f'. 1							
Syntax: Operands: Operation: Status Affected: Encoding: Description: Words: Cycles:	[label] INCF f,d $0 \le f \le 127$ d ∈ [0,1] (f) + 1 → (dest) Z							
Syntax: Operands: Operation: Status Affected: Encoding: Description: Words: Cycles:	$ [\ \textit{label} \] \text{INCF} f,d \\ 0 \leq f \leq 127 \\ d \in [0,1] \\ (f) + 1 \rightarrow (\text{dest}) \\ Z \\ \hline $							
Syntax: Operands: Operation: Status Affected: Encoding: Description: Words: Cycles:	[label] INCF f,d $0 \le f \le 127$ $d \in [0,1]$ $(f) + 1 \rightarrow (dest)$ Z $00 1010 dfff ffff$ The contents of register 'f' are incremented. If 'd' is 0 the result is placed in the W register. If 'd' is 1 the result is placed back in register 'f'. 1 INCF CNT, 1 Before Instruction $CNT = 0xFF$ $Z = 0$							
Syntax: Operands: Operation: Status Affected: Encoding: Description: Words: Cycles:	$ [\ label \] INCF f,d \\ 0 \leq f \leq 127 \\ d \in [0,1] \\ (f) + 1 \rightarrow (dest) \\ Z \\ \hline $							

XORLW	Exclusive OR Literal with W
AURLW	Exclusive OR Literal with W

Syntax: [label] XORLW k

Operands: $0 \le k \le 255$

Operation: (W) .XOR. $k \rightarrow (W)$

Status Affected: Z

Encoding: 11 1010 kkkk kkkk

Description: The contents of the W register are XOR'ed with the eight bit literal 'k'.

The result is placed in the W register.

Words: 1 Cycles: 1

Example: XORLW 0xAF

Before Instruction

W = 0xB5

After Instruction

W = 0x1A

XORWF Exclusive OR W with f

Syntax: [label] XORWF f,d

Operands: $0 \le f \le 127$

 $d \in [0,1]$

Operation: (W) .XOR. (f) \rightarrow (dest)

Status Affected: Z

Encoding:

Description: Exclusive OR the contents of the

00

W register with register 'f'. If 'd' is 0 the result is stored in the W register. If 'd' is 1 the result is stored back in register

dfff

ffff

0110

'f'.

Words: 1 Cycles: 1

Example XORWF REG 1

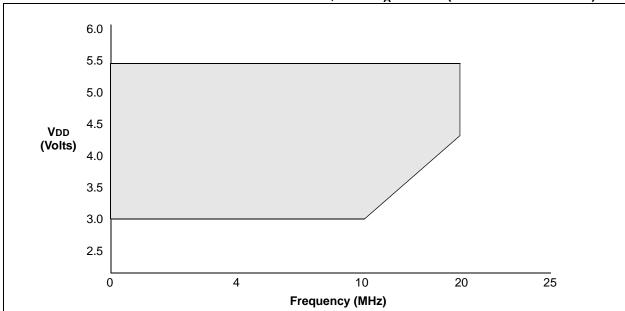
Before Instruction

REG = 0xAFW = 0xB5

After Instruction

REG = 0x1A W = 0xB5

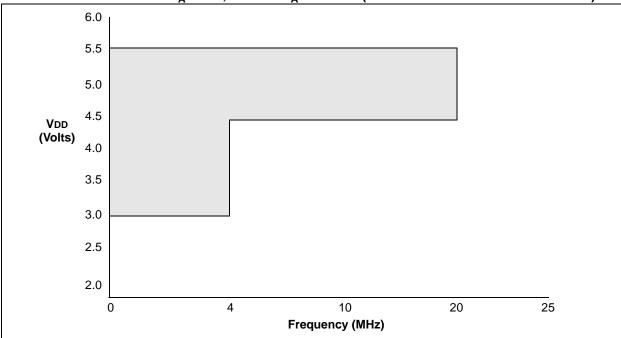




Note 1: The shaded region indicates the permissible combinations of voltage and frequency.

2: The maximum rated speed of the part limits the permissible combinations of voltage and frequency. Please reference the Product Identification System section for the maximum rated speed of the parts.

FIGURE 10-2: VOLTAGE-FREQUENCY GRAPH, $-40^{\circ}C \leq T_{A} < 0^{\circ}C, +70^{\circ}C < T_{A} \leq +125^{\circ}C \text{ (OUTSIDE OF COMMERCIAL TEMPS)}$



Note 1: The shaded region indicates the permissible combinations of voltage and frequency.

2: The maximum rated speed of the part limits the permissible combinations of voltage and frequency. Please reference the Product Identification System section for the maximum rated speed of the parts.

FIGURE 10-9: TIMERO CLOCK TIMING

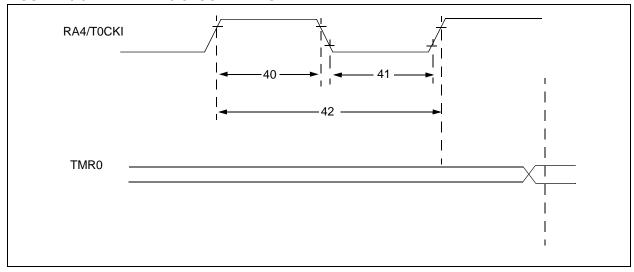
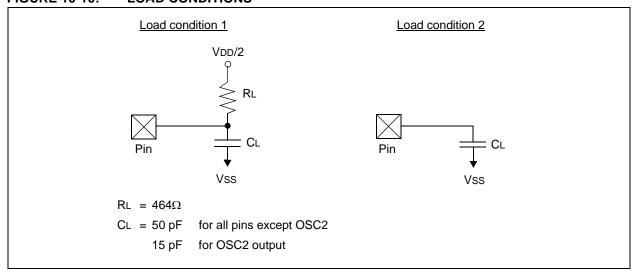


TABLE 10-4: TIMERO CLOCK REQUIREMENTS

Param No.	Sym	Characteristic		Min	Тур†	Max	Units	Conditions
40	Tt0H	T0CKI High Pulse Width	No Prescaler	0.5 Tcy + 20*	_	-	ns	
			With Prescaler	10*	_	_	ns	
41	Tt0L	T0CKI Low Pulse Width	No Prescaler	0.5 Tcy + 20*	_	_	ns	
			With Prescaler	10*	_	_	ns	
42	Tt0P	T0CKI Period		<u>Tcy + 40</u> * N	_	_	ns	N = prescale value (1, 2, 4,, 256)

^{*} These parameters are characterized but not tested.

FIGURE 10-10: LOAD CONDITIONS

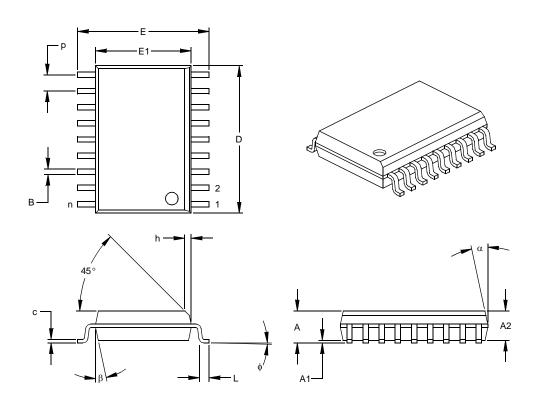


[†] Data in "Typ" column is at 5.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

NOTES:

18-Lead Plastic Small Outline (SO) - Wide, 300 mil (SOIC)

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units	INCHES*			MILLIMETERS		
Dimension Limits		MIN	NOM	MAX	MIN	NOM	MAX
Number of Pins	n		18			18	
Pitch	р		.050			1.27	
Overall Height	Α	.093	.099	.104	2.36	2.50	2.64
Molded Package Thickness	A2	.088	.091	.094	2.24	2.31	2.39
Standoff §	A1	.004	.008	.012	0.10	0.20	0.30
Overall Width	Е	.394	.407	.420	10.01	10.34	10.67
Molded Package Width	E1	.291	.295	.299	7.39	7.49	7.59
Overall Length	D	.446	.454	.462	11.33	11.53	11.73
Chamfer Distance	h	.010	.020	.029	0.25	0.50	0.74
Foot Length	L	.016	.033	.050	0.41	0.84	1.27
Foot Angle	ф	0	4	8	0	4	8
Lead Thickness	С	.009	.011	.012	0.23	0.27	0.30
Lead Width	В	.014	.017	.020	0.36	0.42	0.51
Mold Draft Angle Top	α	0	12	15	0	12	15
Mold Draft Angle Bottom	β	0	12	15	0	12	15

Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed

Preliminary

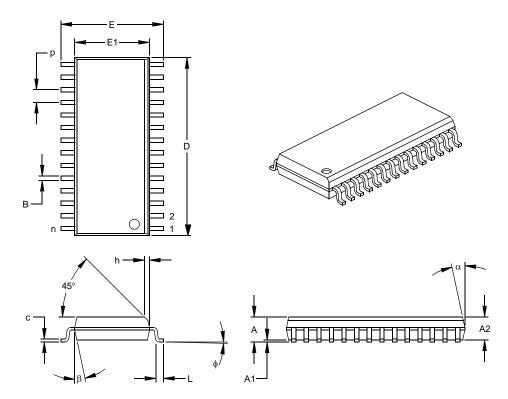
.010" (0.254mm) per side.

JEDEC Equivalent: MS-013 Drawing No. C04-051

^{*} Controlling Parameter § Significant Characteristic

28-Lead Plastic Small Outline (SO) - Wide, 300 mil (SOIC)

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units	INCHES*			MILLIMETERS		
Dimension Limits		MIN	NOM	MAX	MIN	NOM	MAX
Number of Pins	n		28			28	
Pitch	р		.050			1.27	
Overall Height	Α	.093	.099	.104	2.36	2.50	2.64
Molded Package Thickness	A2	.088	.091	.094	2.24	2.31	2.39
Standoff §	A1	.004	.008	.012	0.10	0.20	0.30
Overall Width	Е	.394	.407	.420	10.01	10.34	10.67
Molded Package Width	E1	.288	.295	.299	7.32	7.49	7.59
Overall Length	D	.695	.704	.712	17.65	17.87	18.08
Chamfer Distance	h	.010	.020	.029	0.25	0.50	0.74
Foot Length	L	.016	.033	.050	0.41	0.84	1.27
Foot Angle Top	ф	0	4	8	0	4	8
Lead Thickness	С	.009	.011	.013	0.23	0.28	0.33
Lead Width	В	.014	.017	.020	0.36	0.42	0.51
Mold Draft Angle Top	α	0	12	15	0	12	15
Mold Draft Angle Bottom	β	0	12	15	0	12	15

^{*} Controlling Parameter

Notes

Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" (0.254mm) per side.

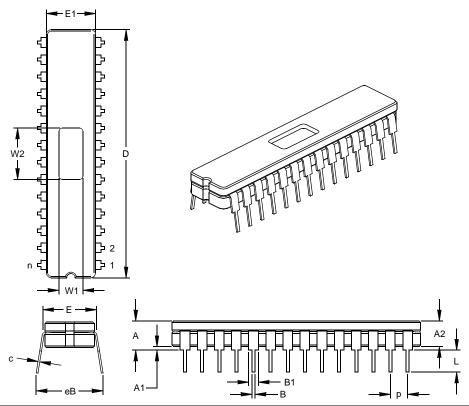
JEDEC Equivalent: MS-013

Drawing No. C04-052

[§] Significant Characteristic

28-Lead Ceramic Dual In-line with Window (JW) - 300 mil (CERDIP)

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging

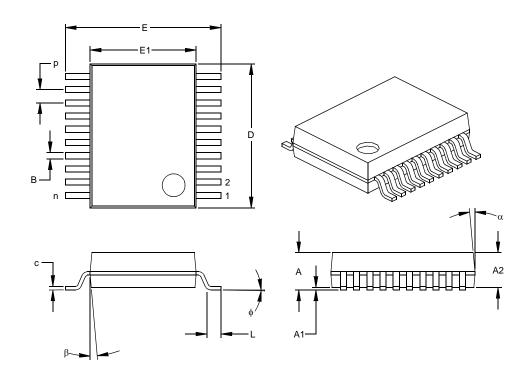


	Units	INCHES*			MILLIMETERS		
Dimension	Limits	MIN	NOM	MAX	MIN	NOM	MAX
Number of Pins	n		28			28	
Pitch	р		.100			2.54	
Top to Seating Plane	Α	.170	.183	.195	4.32	4.64	4.95
Ceramic Package Height	A2	.155	.160	.165	3.94	4.06	4.19
Standoff	A1	.015	.023	.030	0.38	0.57	0.76
Shoulder to Shoulder Width	Е	.300	.313	.325	7.62	7.94	8.26
Ceramic Pkg. Width	E1	.285	.290	.295	7.24	7.37	7.49
Overall Length	D	1.430	1.458	1.485	36.32	37.02	37.72
Tip to Seating Plane	L	.135	.140	.145	3.43	3.56	3.68
Lead Thickness	С	.008	.010	.012	0.20	0.25	0.30
Upper Lead Width	B1	.050	.058	.065	1.27	1.46	1.65
Lower Lead Width	В	.016	.019	.021	0.41	0.47	0.53
Overall Row Spacing §	eB	.345	.385	.425	8.76	9.78	10.80
Window Width	W1	.130	.140	.150	3.30	3.56	3.81
Window Length	W2	.290	.300	.310	7.37	7.62	7.87

 ^{*}Controlling Parameter
 \$ Significant Characteristic
 JEDEC Equivalent: MO-058
 Drawing No. C04-080

20-Lead Plastic Shrink Small Outline (SS) - 209 mil, 5.30 mm (SSOP)

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units	INCHES*			MILLIMETERS		
Dimension Limits		MIN	NOM	MAX	MIN	NOM	MAX
Number of Pins	n		20			20	
Pitch	р		.026			0.65	
Overall Height	Α	.068	.073	.078	1.73	1.85	1.98
Molded Package Thickness	A2	.064	.068	.072	1.63	1.73	1.83
Standoff §	A1	.002	.006	.010	0.05	0.15	0.25
Overall Width	Е	.299	.309	.322	7.59	7.85	8.18
Molded Package Width	E1	.201	.207	.212	5.11	5.25	5.38
Overall Length	D	.278	.284	.289	7.06	7.20	7.34
Foot Length	L	.022	.030	.037	0.56	0.75	0.94
Lead Thickness	С	.004	.007	.010	0.10	0.18	0.25
Foot Angle	ф	0	4	8	0.00	101.60	203.20
Lead Width	В	.010	.013	.015	0.25	0.32	0.38
Mold Draft Angle Top	α	0	5	10	0	5	10
Mold Draft Angle Bottom	β	0	5	10	0	5	10

^{*} Controlling Parameter

Notes

Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 010" (0.254mm) per side

.010" (0.254mm) per side. JEDEC Equivalent: MO-150 Drawing No. C04-072

[§] Significant Characteristic

PICSTART Plus Entry Level Development Programmer	
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PORTB	
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