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Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

#### Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	4MHz
Connectivity	-
Peripherals	POR, WDT
Number of I/O	13
Program Memory Size	3.5KB (2K x 14)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	128 x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 5.5V
Data Converters	-
Oscillator Type	External
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Surface Mount
Package / Case	18-SOIC (0.295", 7.50mm Width)
Supplier Device Package	18-SOIC
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16c558-04-so

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

#### **Table of Contents**

	_
.0 General Description	. 5
.0 PIC16C55X Device Varieties	. 7
.0 Architectural Overview	. 9
.0 Memory Organization	13
.0 I/O Ports	23
.0 Special Features of the CPU	31
.0 Timer0 Module	47
.0 Instruction Set Summary	53
.0 Development Support	67
0.0 Electrical Specifications	73
1.0 Packaging Information	87
vppendix A: Enhancements	97
vppendix B: Compatibility	97
ndex	99
Dn-Line Support 1	01
Systems Information and Upgrade Hot Line	01
Reader Response	02
Product Identification System 1	03

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NOTES:

## 2.0 PIC16C55X DEVICE VARIETIES

A variety of frequency ranges and packaging options are available. Depending on application and production requirements, the proper device option can be selected using the information in the PIC16C55X Product Identification System section at the end of this data sheet. When placing orders, please use this page of the data sheet to specify the correct part number.

## 2.1 UV Erasable Devices

The UV erasable version, offered in CERDIP package, is optimal for prototype development and pilot programs. This version can be erased and reprogrammed to any of the oscillator modes.

Microchip's PICSTART<sup>®</sup> and PROMATE<sup>®</sup> programmers both support programming of the PIC16C55X.

## 2.2 One-Time Programmable (OTP) Devices

The availability of OTP devices is especially useful for customers who need the flexibility for frequent code updates and small volume applications. In addition to the program memory, the configuration bits must also be programmed.

## 2.3 Quick-Turnaround Production (QTP) Devices

Microchip offers a QTP Programming Service for factory production orders. This service is made available for users who choose not to program a medium-to-high quantity of units and whose code patterns have stabilized. The devices are identical to the OTP devices, but with all EPROM locations and configuration options already programmed by the factory. Certain code and prototype verification procedures apply before production shipments are available. Please contact your Microchip Technology sales office for more details.

## 2.4 Serialized Quick-Turnaround Production (SQTP<sup>™</sup>) Devices

Microchip offers a unique programming service where a few user-defined locations in each device are programmed with different serial numbers. The serial numbers may be random, pseudo-random or sequential.

Serial programming allows each device to have a unique number which can serve as an entry code, password or ID number.

## PIC16C55X

## FIGURE 3-1: BLOCK DIAGRAM



#### 4.2.2.4 PCON Register

The PCON register contains a flag bit to differentiate between a Power-on Reset, an external MCLR Reset or WDT Reset. See Section 6.3 and Section 6.4 for detailed RESET operation.

#### **REGISTER 4-4:** PCON REGISTER (ADDRESS 8Eh) U-0 U-0 U-0 R/W-0 U-0 U-0 U-0 U-0 POR bit7 bit 7-2 Unimplemented: Read as '0' bit 1 POR: Power-on Reset status bit 1 = No Power-on Reset occurred 0 = Power-on Reset occurred bit 0 Unimplemented: Read as '0' Legend: R = Readable bit W = Writable bit U = Unimplemented bit, read as '0' - n = Value at POR reset '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit0

## 5.0 I/O PORTS

The PIC16C554 and PIC16C558 have two ports, PORTA and PORTB. The PIC16C557 has three ports, PORTA, PORTB and PORTC.

## 5.1 PORTA and TRISA Registers

PORTA is a 5-bit wide latch. RA4 is a Schmitt Trigger input and an open-drain output. Port RA4 is multiplexed with the T0CKI clock input. All other RA port pins have Schmitt Trigger input levels and full CMOS output drivers. All pins have data direction bits (TRIS registers) which can configure these pins as input or output.

A '1' in the TRISA register puts the corresponding output driver in a Hi-impedance mode. A '0' in the TRISA register puts the contents of the output latch on the selected pin(s).

Reading the PORTA register reads the status of the pins, whereas writing to it will write to the port latch. All write operations are read-modify-write operations. So a write to a port implies that the port pins are first read, then this value is modified and written to the port data latch.

Note 1: On RESET, the TRISA register is set to all inputs.

FIGURE 5-1: BLOCK DIAGRAM OF PORT PINS RA<3:0>



## FIGURE 5-2: BL

BLOCK DIAGRAM OF RA4



#### 6.5 Interrupts

The PIC16C55X has 3 sources of interrupt:

- External interrupt RB0/INT
- TMR0 overflow interrupt
- PORTB change interrupts (pins RB7:RB4)

The interrupt control register (INTCON) records individual interrupt requests in flag bits. It also has individual and global interrupt enable bits.

A global interrupt enable bit, GIE (INTCON<7>) enables (if set) all un-masked interrupts or disables (if cleared) all interrupts. Individual interrupts can be disabled through their corresponding enable bits in INTCON register. GIE is cleared on RESET.

The "Return from Interrupt" instruction, RETFIE, exits the interrupt routine as well as sets the GIE bit, which re-enables RB0/INT interrupts.

The INT pin interrupt, the RB port change interrupt and the TMR0 overflow interrupt flags are contained in the INTCON register.

When an interrupt is responded to, the GIE is cleared to disable any further interrupt, the return address is pushed into the stack and the PC is loaded with 0004h. Once in the interrupt service routine the source(s) of the interrupt can be determined by polling the interrupt flag bits. The interrupt flag bit(s) must be cleared in software before re-enabling interrupts to avoid RB0/INT recursive interrupts. For external interrupt events, such as the INT pin or PORTB change interrupt, the interrupt latency will be three or four instruction cycles. The exact latency depends when the interrupt event occurs (Figure 6-12). The latency is the same for one or two cycle instructions. Once in the interrupt service routine, the source(s) of the interrupt can be determined by polling the interrupt flag bits. The interrupt flag bit(s) must be cleared in software before re-enabling interrupts to avoid multiple interrupt requests. Individual interrupt flag bits are set regardless of the status of their corresponding mask bit or the GIE bit.

- Note 1: Individual interrupt flag bits are set regardless of the status of their corresponding mask bit or the GIE bit.
  - 2: When an instruction that clears the GIE bit is executed, any interrupts that were pending for execution in the next cycle are ignored. The CPU will execute a NOP in the cycle immediately following the instruction which clears the GIE bit. The interrupts which were ignored are still pending to be serviced when the GIE bit is set again.



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## 7.2 Using Timer0 with External Clock

When an external clock input is used for Timer0, it must meet certain requirements. The external clock requirement is due to internal phase clock (Tosc) synchronization. Also, there is a delay in the actual incrementing of Timer0 after synchronization.

#### 7.2.1 EXTERNAL CLOCK SYNCHRONIZATION

When no prescaler is used, the external clock input is the same as the prescaler output. The synchronization of T0CKI with the internal phase clocks is accomplished by sampling the prescaler output on the Q2 and Q4 cycles of the internal phase clocks (Figure 7-5). Therefore, it is necessary for T0CKI to be high for at least 2Tosc (and a small RC delay of 20 ns) and low for at least 2Tosc (and a small RC delay of 20 ns). Refer to the electrical specification of the desired device. When a prescaler is used, the external clock input is divided by the asynchronous ripple-counter type prescaler so that the prescaler output is symmetrical. For the external clock to meet the sampling requirement, the ripple-counter must be taken into account. Therefore, it is necessary for TOCKI to have a period of at least 4TOSC (and a small RC delay of 40 ns) divided by the prescaler value. The only requirement on TOCKI high and low time is that they do not violate the minimum pulse width requirement of 10 ns. Refer to parameters 40, 41 and 42 in the electrical specification of the desired device.

#### 7.2.2 TIMER0 INCREMENT DELAY

Since the prescaler output is synchronized with the internal clocks, there is a small delay from the time the external clock edge occurs to the time the TMR0 is actually incremented. Figure 7-5 shows the delay from the external clock edge to the timer incrementing.



## 7.3 Prescaler

An 8-bit counter is available as a prescaler for the Timer0 module, or as a postscaler for the Watchdog Timer, respectively (Figure 7-6). For simplicity, this counter is being referred to as "prescaler" throughout this data sheet.

Note: There is only one prescaler available which is mutually exclusive between the Timer0 module and the Watchdog Timer. Thus, a prescaler assignment for the Timer0 module means that there is no prescaler for the Watchdog Timer, and vice-versa. The PSA and PS2:PS0 bits (OPTION<3:0>) determine the prescaler assignment and prescale ratio.

When assigned to the Timer0 module, all instructions writing to the TMR0 register (e.g., CLRF 1, MOVWF 1, BSF 1, x....etc.) will clear the prescaler. When assigned to WDT, a CLRWDT instruction will clear the prescaler along with the Watchdog Timer. The prescaler is not readable or writable.

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# PIC16C55X

BCF	Bit Clea	ar f		
Syntax:	[ label ]	BCF 1	f,b	
Operands:	$0 \le f \le 1$ $0 \le b \le 1$	127 7		
Operation:	$0 \rightarrow (f <$	b>)		
Status Affected:	None			
Encoding:	01	00bb	bfff	ffff
Description:	Bit 'b' in re	gister 'f' is	s cleared.	
Words:	1			
Cycles:	1			
Example	BCF	FLAG_F	REG, 7	
	Before In FLA After Inst FLA	struction G_REG ruction G_REG	= 0x = 0x	C7 47

Bit S	et f
-------	------

BSF

Syntax:	[ <i>label</i> ]BSF f,b				
Operands:	$\begin{array}{l} 0 \leq f \leq 127 \\ 0 \leq b \leq 7 \end{array}$				
Operation:	$1 \rightarrow (f < b;$	>)			
Status Affected:	None				
Encoding:	01	01bb	bfff	ffff	
Description:	Bit 'b' in register 'f' is set.				
Words:	1				
Cycles:	1				
Example	BSF	FLAG_F	REG, 7	,	
	Before Instruction				
	FLAG_REG = 0x0A				
	After Instruction				
	FLAG_REG = 0x8A				

BTFSC	Bit Tes	t, Skip if C	Clear		
Syntax:	[ <i>label</i> ] B	BTFSC f,t	)		
Operands:	$\begin{array}{l} 0 \leq f \leq 12 \\ 0 \leq b \leq 7 \end{array}$	27			
Operation:	skip if (f<	b>) = 0			
Status Affected:	None				
Encoding:	01	10bb	bfff	ffff	
Description:	If bit 'b' in register 'f' is '0' then the next instruction is skipped. If bit 'b' is '0' then the next instruction fetched during the current instruction execution is dis- carded, and a NOP is executed instead, making this a two-cycle instruction.				
Words:	1				
Cycles:	1(2)				
Example	HERE FALSE TRUE	BTFSC GOTO • •	FLAG,1 PROCES	S_CODE	
	Before In	struction			
	PC = address HERE				
	After Instruction				
	if FL	AG<1> = (	), Idress TD	TTF	
	if FL	_ au AG<1> = <sup>^</sup>	1,		
	PC	= ad	dress FA	LSE	

XORLW	Exclusi	ive OR	Literal w	ith W	
Syntax:	[ <i>label</i> ] XORLW k				
Operands:	$0 \le k \le 25$	55			
Operation:	(W) .XOF	R. $k \rightarrow (N)$	N)		
Status Affected:	Z				
Encoding:	11	1010	kkkk	kkkk	
Description:	The contents of the W register are XOR'ed with the eight bit literal 'k'. The result is placed in the W register.				
Words:	1				
Cycles:	1				
Example:	XORLW	0xAF			
	Before Instruction				
	W	=	0xB5		
	After Instruction				
	W	=	0x1A		

XORWF	Exclusive OR W with f		
Syntax:	[ <i>label</i> ] XORWF f,d		
Operands:	0 ≤ f ≤ 127 d ∈ [0,1]		
Operation:	(W) .XOR. (f) $\rightarrow$ (dest)		
Status Affected:	Z		
Encoding:	00 0110 dfff ffff		
Description:	Exclusive OR the contents of the W register with register 'f'. If 'd' is 0 the result is stored in the W register. If 'd' is 1 the result is stored back in register 'f'.		
Words:	1		
Cycles:	1		
Example	XORWF REG 1		
	Before Instruction		
	REG = 0xAF $W = 0xB5$		
	After Instruction		
	REG = 0x1A		
	W = 0xB5		

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NOTES:

## 9.0 DEVELOPMENT SUPPORT

The PIC<sup>®</sup> microcontrollers are supported with a full range of hardware and software development tools:

- Integrated Development Environment
  - MPLAB<sup>®</sup> IDE Software
- Assemblers/Compilers/Linkers
  - MPASM<sup>™</sup> Assembler
  - MPLAB C17 and MPLAB C18 C Compilers
  - MPLINK™ Object Linker/
  - MPLIB<sup>™</sup> Object Librarian
- Simulators
  - MPLAB SIM Software Simulator
- Emulators
  - MPLAB ICE 2000 In-Circuit Emulator
  - ICEPIC<sup>™</sup> In-Circuit Emulator
- In-Circuit Debugger
- MPLAB ICD
- Device Programmers
  - PRO MATE® II Universal Device Programmer
- PICSTART<sup>®</sup> Plus Entry-Level Development Programmer
- Low Cost Demonstration Boards
  - PICDEM<sup>™</sup>1 Demonstration Board
  - PICDEM 2 Demonstration Board
  - PICDEM 3 Demonstration Board
  - PICDEM 17 Demonstration Board
  - KEELOQ<sup>®</sup> Demonstration Board

#### 9.1 MPLAB Integrated Development Environment Software

The MPLAB IDE software brings an ease of software development previously unseen in the 8-bit microcontroller market. The MPLAB IDE is a Windows<sup>®</sup>-based application that contains:

- · An interface to debugging tools
  - simulator
  - programmer (sold separately)
  - emulator (sold separately)
  - in-circuit debugger (sold separately)
- A full-featured editor
- · A project manager
- Customizable toolbar and key mapping
- · A status bar
- On-line help

The MPLAB IDE allows you to:

- Edit your source files (either assembly or 'C')
- One touch assemble (or compile) and download to PIC MCU emulator and simulator tools (automatically updates all project information)
- Debug using:
  - source files
  - absolute listing file
  - machine code

The ability to use MPLAB IDE with multiple debugging tools allows users to easily switch from the costeffective simulator to a full-featured emulator with minimal retraining.

## 9.2 MPASM Assembler

The MPASM assembler is a full-featured universal macro assembler for all PIC MCUs.

The MPASM assembler has a command line interface and a Windows shell. It can be used as a stand-alone application on a Windows 3.x or greater system, or it can be used through MPLAB IDE. The MPASM assembler generates relocatable object files for the MPLINK object linker, Intel<sup>®</sup> standard HEX files, MAP files to detail memory usage and symbol reference, an absolute LST file that contains source lines and generated machine code, and a COD file for debugging.

The MPASM assembler features include:

- Integration into MPLAB IDE projects.
- User-defined macros to streamline assembly code.
- Conditional assembly for multi-purpose source files.
- Directives that allow complete control over the assembly process.

## 9.3 MPLAB C17 and MPLAB C18 C Compilers

The MPLAB C17 and MPLAB C18 Code Development Systems are complete ANSI 'C' compilers for Microchip's PIC17CXXX and PIC18CXXX family of microcontrollers, respectively. These compilers provide powerful integration capabilities and ease of use not found with other compilers.

For easier source level debugging, the compilers provide symbol information that is compatible with the MPLAB IDE memory display.

## 9.13 PICDEM 3 Low Cost PIC16CXXX Demonstration Board

The PICDEM 3 demonstration board is a simple demonstration board that supports the PIC16C923 and PIC16C924 in the PLCC package. It will also support future 44-pin PLCC microcontrollers with an LCD Module. All the necessary hardware and software is included to run the basic demonstration programs. The user can program the sample microcontrollers provided with the PICDEM 3 demonstration board on a PRO MATE II device programmer, or a PICSTART Plus development programmer with an adapter socket, and easily test firmware. The MPLAB ICE in-circuit emulator may also be used with the PICDEM 3 demonstration board to test firmware. A prototype area has been provided to the user for adding hardware and connecting it to the microcontroller socket(s). Some of the features include a RS-232 interface, push button switches, a potentiometer for simulated analog input, a thermistor and separate headers for connection to an external LCD module and a keypad. Also provided on the PICDEM 3 demonstration board is a LCD panel, with 4 commons and 12 segments, that is capable of displaying time, temperature and day of the week. The PICDEM 3 demonstration board provides an additional RS-232 interface and Windows software for showing the demultiplexed LCD signals on a PC. A simple serial interface allows the user to construct a hardware demultiplexer for the LCD signals.

## 9.14 PICDEM 17 Demonstration Board

The PICDEM 17 demonstration board is an evaluation board that demonstrates the capabilities of several Microchip microcontrollers, including PIC17C752, PIC17C756A, PIC17C762 and PIC17C766. All necessary hardware is included to run basic demo programs, which are supplied on a 3.5-inch disk. A programmed sample is included and the user may erase it and program it with the other sample programs using the PRO MATE II device programmer, or the PICSTART Plus development programmer, and easily debug and test the sample code. In addition, the PICDEM 17 demonstration board supports downloading of programs to and executing out of external FLASH memory on board. The PICDEM 17 demonstration board is also usable with the MPLAB ICE in-circuit emulator, or the PICMASTER emulator and all of the sample programs can be run and modified using either emulator. Additionally, a generous prototype area is available for user hardware.

## 9.15 KEELOQ Evaluation and Programming Tools

KEELOQ evaluation and programming tools support Microchip's HCS Secure Data Products. The HCS evaluation kit includes a LCD display to show changing codes, a decoder to decode transmissions and a programming interface to program test transmitters.

## 10.3 Timing Parameter Symbology

The timing parameter symbols have been created with one of the following formats:

#### 1. TppS2ppS

2. TppS

Т			
F	Frequency	Т	Time
Lowercas	e subscripts (pp) and their meanings:		
рр			
ck	CLKOUT	OS	OSC1
io	I/O port	t0	ТОСКІ
mc	MCLR		
Uppercas	e letters and their meanings:		
S			
F	Fall	Р	Period
Н	High	R	Rise
I	Invalid (Hi-impedance)	V	Valid
L	Low	Z	Hi-impedance

## FIGURE 10-5: LOAD CONDITIONS



Watchdog Timer RESET

I/O Pins



#### **FIGURE 10-8:** RESET, WATCHDOG TIMER, OSCILLATOR START-UP TIMER AND POWER-UP

#### **TABLE 10-3**: RESET, WATCHDOG TIMER, OSCILLATOR START-UP TIMER AND POWER-UP TIMER REQUIREMENTS

34 —

31

34

Param No.	Sym	Characteristic	Min	Тур†	Max	Units	Conditions
30	TmcL	MCLR Pulse Width (low)	2000		—	ns	-40° to +85°C
31	Twdt	Watchdog Timer Timeout Period (No Prescaler)	7*	18	33*	ms	VDD = 5.0V, -40° to +85°C
32	Tost	Oscillation Start-up Timer Period	—	1024 Tosc	—	—	Tosc = OSC1 period
33	Tpwrt	Power-up Timer Period	28*	72	132*	ms	$VDD = 5.0V, -40^{\circ} \text{ to } +85^{\circ}C$
34	Tioz	I/O hi-impedance from MCLR low			2.0*	μs	
*							

These parameters are characterized but not tested.

Data in "Typ" column is at 5.0V, 25°C unless otherwise stated. These parameters are for design guidance † only and are not tested.

## **11.0 PACKAGING INFORMATION**

## 11.1 Package Marking Information

#### 18-Lead PDIP



#### 28-Lead PDIP



#### 20-Lead SSOP



#### 28-Lead SSOP



#### Example



#### Example



#### Example



#### Example



Legend	: XXX Y YY WW NNN @3 *	Customer-specific information Year code (last digit of calendar year) Year code (last 2 digits of calendar year) Week code (week of January 1 is week '01') Alphanumeric traceability code Pb-free JEDEC designator for Matte Tin (Sn) This package is Pb-free. The Pb-free JEDEC designator (e3) can be found on the outer packaging for this package.	
Note:	In the event the full Microchip part number cannot be marked on one line, it will be carried over to the next line, thus limiting the number of available characters for customer-specific information.		

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## **PRODUCT IDENTIFICATION SYSTEM**

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.

PART NO.	<u>x /xx xxx</u>	Examples:
Device	Temperature Package Pattern Range	a) PIC17C756–16L Commercial Temp., PLCC package, 16 MHz, normal VDD limits
Device	PIC17C756: Standard VDD range PIC17C756T: (Tape and Reel) PIC17LC756: Extended VDD range	<ul> <li>b) PIC17LC756–08/PT Commercial Temp., TQFP package, 8MHz, extended VDD limits</li> <li>c) PIC17C756–33I/PT Industrial Temp., TQFP content of the set that the set the set that the set that the set that the</li></ul>
Temperature Range	$\begin{array}{rcl} - & = & 0^{\circ}C \text{ to } +70^{\circ}C \\ I & = & -40^{\circ}C \text{ to } +85^{\circ}C \end{array}$	I QFP package, 33 MHz, normal VDD limits
Package	CL = Windowed LCC PT = TQFP L = PLCC	
Pattern	QTP, SQTP, ROM Code (factory specified) or Special Requirements. Blank for OTP and Windowed devices.	

\* JW Devices are UV erasable and can be programmed to any device configuration. JW Devices meet the electrical requirement of each oscillator type.

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Products supported by a preliminary Data Sheet may have an errata sheet describing minor operational differences and recommended workarounds. To determine if an errata sheet exists for a particular device, please contact one of the following:

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