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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	M8C
Core Size	8-Bit
Speed	24MHz
Connectivity	SPI, UART/USART
Peripherals	LVD, POR, PWM, WDT
Number of I/O	6
Program Memory Size	4KB (4K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 5.25V
Data Converters	A/D 1x8b, 1x11b, 1x12b; D/A 1x9b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Through Hole
Package / Case	8-DIP (0.300", 7.62mm)
Supplier Device Package	8-PDIP
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/cy8c25122-24pi

Getting Started in the PSoC World!

The award winning PSoC Designer software and PSoC silicon are an integrated unit. The quickest path to understanding the PSoC silicon is through the PSoC Designer software GUI. This data sheet is useful for understanding the details of the PSoC integrated circuit, but is not a good starting point for a new PSoC developer seeking to get a general overview of this new technology.

PSoC developers are NOT required to build their own ADCs, DACs, and other peripherals. Embedded in the PSoC Designer software are the individual data sheets, performance graphs, and PSoC User Modules (graphically selected code packets) for the peripherals, such as the incremental ADCs, DACs, LCD controllers, op amps, low-pass filters, etc. **With simple GUI-based selection, placement, and connection, the basic architecture of a design may be developed within PSoC Designer software without ever writing a single line of code.**

Development Kits are available from the following distributors: Digi-Key, Avnet, Arrow, and Future. The Cypress Online Store also contains development kits, C compilers, and all accessories for PSoC development. Go to the Cypress Online Store web site at <http://www.cypress.com>, click the Online Store shopping cart icon at the bottom of the web page, and click *PSoC (Programmable System-on-Chip)* to view a current list of available items.

Free PSoC technical training is available for beginners and is taught by a marketing or application engineer over the phone. PSoC training classes cover designing, debugging, advanced analog, as well as application-specific classes covering topics such as PSoC and the LIN bus. Go to <http://www.cypress.com>, click on Design Support located on the left side of the web page, and select Technical Training for more details.

Certified PSoC Consultants offer everything from technical assistance to completed PSoC designs. To contact or become a PSoC Consultant go to <http://www.cypress.com>, click on Design Support located on the left side of the web page, and select CYPros Consultants.

PSoC application engineers take pride in fast and accurate response. They can be reached with a 4-hour guaranteed response at <http://www.cypress.com/support/login.cfm>.

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The PSoC™ CY8C25122/CY8C26233/CY8C26443/CY8C26643 family of programmable system-on-chip devices replace multiple MCU-based system components with one single-chip, configurable device. A PSoC device includes configurable analog and digital peripheral blocks, a fast CPU, Flash program memory, and SRAM data memory in a range of convenient pin-outs and memory sizes. The driving force behind this innovative programmable system-on-chip comes from user configurability of the analog and digital arrays: the PSoC blocks.

Programmable System-on-Chip (PSoC™) Blocks

- On-chip, user configurable analog and digital peripheral blocks
- PSoC blocks can be used individually or in combination
- 12 Analog PSoC blocks provide:
 - Up to 11-bit Delta-Sigma ADC
 - Up to 8-bit Successive Approximation ADC
 - Up to 12-bit Incremental ADC
 - Up to 9-bit DAC
 - Programmable gain amplifier
 - Programmable filters
 - Differential comparators
- 8 Digital PSoC blocks provide:
 - Multipurpose timers: event timing, real-time clock, pulse width modulation (PWM) and PWM with deadband
 - CRC modules
 - Full-duplex UARTs
 - SPI™ master or slave configuration
 - Flexible clocking sources for analog PSoC blocks

Powerful Harvard Architecture Processor with Fast Multiply/Accumulate

- M8C processor instruction set
- Processor speeds to 24 MHz
- Register speed memory transfers
- Flexible addressing modes
- Bit manipulation on I/O and memory
- 8x8 multiply, 32-bit accumulate

Flexible On-Chip Memory

- Flash program storage, 4K to 16K bytes, depending on device
- 50,000 erase/write cycles
- 256 bytes SRAM data storage
- In-System Serial Programming (ISSP™)

- Partial Flash updates
- Flexible protection modes
- EEPROM emulation in Flash, up to 2,304 bytes

Programmable Pin Configurations

- Schmitt trigger TTL I/O pins
- Logic output drive to 25 mA with internal pull-up or pull-down resistors, High Z, or strong driver
- Interrupt on pin change
- Analog output drive to 40 mA

Precision, Programmable Clocking

- Internal 24/48 MHz Oscillator (+/- 2.5%, no external components)
- External 32.768 kHz Crystal Oscillator (optional precision source for PLL)
- Internal Low Speed Oscillator for Watchdog and Sleep

Dedicated Peripherals

- Watchdog and Sleep Timers
- Low Voltage Detection with user-configurable threshold voltages
- On-chip voltage reference

Fully Static CMOS Devices using advanced Flash technology

- Low power at high speed
- Operating voltage from 3.0 to 5.25 V
- Operating voltage down to 1.0 V using on-chip switch mode voltage pump
- Wide temperature range: -40 °C to + 85 °C

Complete Development Tools

- Powerful integrated development environment (PSoC™ Designer)
- Low-cost, in-circuit emulator and programmer

4.3 Register Bank 1 Map

Table 27: Bank 1

Access	Data Sheet	Page	Address	Register Name	Access	Data Sheet	Page	Address	Register Name	Access	Data Sheet	Page	Address	Register Name	Access	Data Sheet	Page	Address	Register Name				
				Reserved					ASA10CR0		88	RW	80h		Reserved				C0h				
									ASA10CR1		90	RW	81h							C1h			
									ASA10CR2		92	RW	82h							C2h			
									ASA10CR3		93	RW	83h							C3h			
									ASB11CR0		95	RW	84h							C4h			
									ASB11CR1		97	RW	85h							C5h			
									ASB11CR2		99	RW	86h							C6h			
									ASB11CR3		100	RW	87h							C7h			
									ASA12CR0		88	RW	88h							C8h			
									ASA12CR1		90	RW	89h							C9h			
									ASA12CR2		92	RW	8Ah							CAh			
									ASA12CR3		93	RW	8Bh							CBh			
									ASB13CR0		95	RW	8Ch							CCh			
									ASB13CR1		97	RW	8Dh							CDh			
									ASB13CR2		99	RW	8Eh							CEh			
									ASB13CR3		100	RW	8Fh							CFh			
									ASB20CR0		95	RW	90h							D0h			
									ASB20CR1		97	RW	91h							D1h			
									ASB20CR2		99	RW	92h							D2h			
									ASB20CR3		100	RW	93h							D3h			
									ASA21CR0		88	RW	94h							D4h			
									ASA21CR1		90	RW	95h							D5h			
									ASA21CR2		92	RW	96h							D6h			
									ASA21CR3		93	RW	97h							D7h			
									ASB22CR0		95	RW	98h							D8h			
									ASB22CR1		97	RW	99h							D9h			
									ASB22CR2		99	RW	9Ah							DAh			
									ASB22CR3		100	RW	9Bh							DBh			
									ASA23CR0		88	RW	9Ch							DCh			
									ASA23CR1		90	RW	9Dh							DDh			
									ASA23CR2		92	RW	9Eh							DEh			
									ASA23CR3		93	RW	9Fh							DFh			
				Reserved									A0h		Reserved				OSC_CR0	E0h	40	RW	
														A1h						OSC_CR1	E1h	40	RW
														A2h					Reserved	E2h			
														A3h					VLT_CR	E3h	118	RW	
														A4h					Reserved	E4h			
														A5h					Reserved	E5h			
														A6h					Reserved	E6h			
														A7h					Reserved	E7h			
														A8h					IMO_TR	E8h	35	W	
														A9h					ILO_TR	E9h	36	W	
														AAh					BDG_TR	EAh	120	W	
														ABh					ECO_TR	EBh	37	W	
														ACh						ECh			
				Reserved									ADh		Reserved				EDh				
														AEh						EEh			
														AFh						EFh			
														B0h						FOh			
														B1h						F1h			
														B2h						F2h			
														B3h						F3h			
														B4h						F4h			
														B5h						F5h			
														B6h						F6h			
														B7h						F7h			
														B8h						F8h			
														B9h						F9h			
													BAh					FAh					
													BBh					FBh					
													BCh					FCh					
													BDh					FDh					
													BEh					FEh					
													BFh					CPU_SCR	FFh	114	1		

1. Read/Write access is bit-specific or varies by function. See register.

6.3.2 Port Drive Mode 1 Registers

Table 32: Port Drive Mode 1 Registers

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/Write	W	W	W	W	W	W	W	W
Bit Name	DM1 [7]	DM1 [6]	DM1 [5]	DM1 [4]	DM1 [3]	DM1 [2]	DM1 [1]	DM1 [0]
Bit [7:0]: <u>DM1 [7:0]</u> See truth table for Port Drive Mode 0 Registers, above								

Port 0 Drive Mode 1 Register (PRT0DM1, Address = Bank 1, 01h)

Port 1 Drive Mode 1 Register (PRT1DM1, Address = Bank 1, 05h)

Port 2 Drive Mode 1 Register (PRT2DM1, Address = Bank 1, 09h)

Port 3 Drive Mode 1 Register (PRT3DM1, Address = Bank 1, 0Dh)

Port 4 Drive Mode 1 Register (PRT4DM1, Address = Bank 1, 11h)

Port 5 Drive Mode 1 Register (PRT5DM1, Address = Bank 1, 15h) **Note:** Port 5 is 4-bits wide

6.3.3 Port Interrupt Control 0 Registers

Table 33: Port Interrupt Control 0 Registers

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/Write	W	W	W	W	W	W	W	W
Bit Name	IC0 [7]	IC0 [6]	IC0 [5]	IC0 [4]	IC0 [3]	IC0 [2]	IC0 [1]	IC0 [0]
Bit [7:0]: <u>IC0 [7:0]</u> The two Interrupt Control bits that control a particular port pin are treated as a pair and are decoded as follows: IC1 [x], IC0 [x] = 0 0 = Disabled (Default) IC1 [x], IC0 [x] = 0 1 = Falling Edge (-) IC1 [x], IC0 [x] = 1 0 = Rising Edge (+) IC1 [x], IC0 [x] = 1 1 = Change from Last Direct Read								

Port 0 Interrupt Control 0 Register (PRT0IC0, Address = Bank 1, 02h)

Port 1 Interrupt Control 0 Register (PRT1IC0, Address = Bank 1, 06h)

Port 2 Interrupt Control 0 Register (PRT2IC0, Address = Bank 1, 0Ah)

Port 3 Interrupt Control 0 Register (PRT3IC0, Address = Bank 1, 0Eh)

Port 4 Interrupt Control 0 Register (PRT4IC0, Address = Bank 1, 12h)

Port 5 Interrupt Control 0 Register (PRT5IC0, Address = Bank 1, 16h) **Note:** Port 5 is 4-bits wide

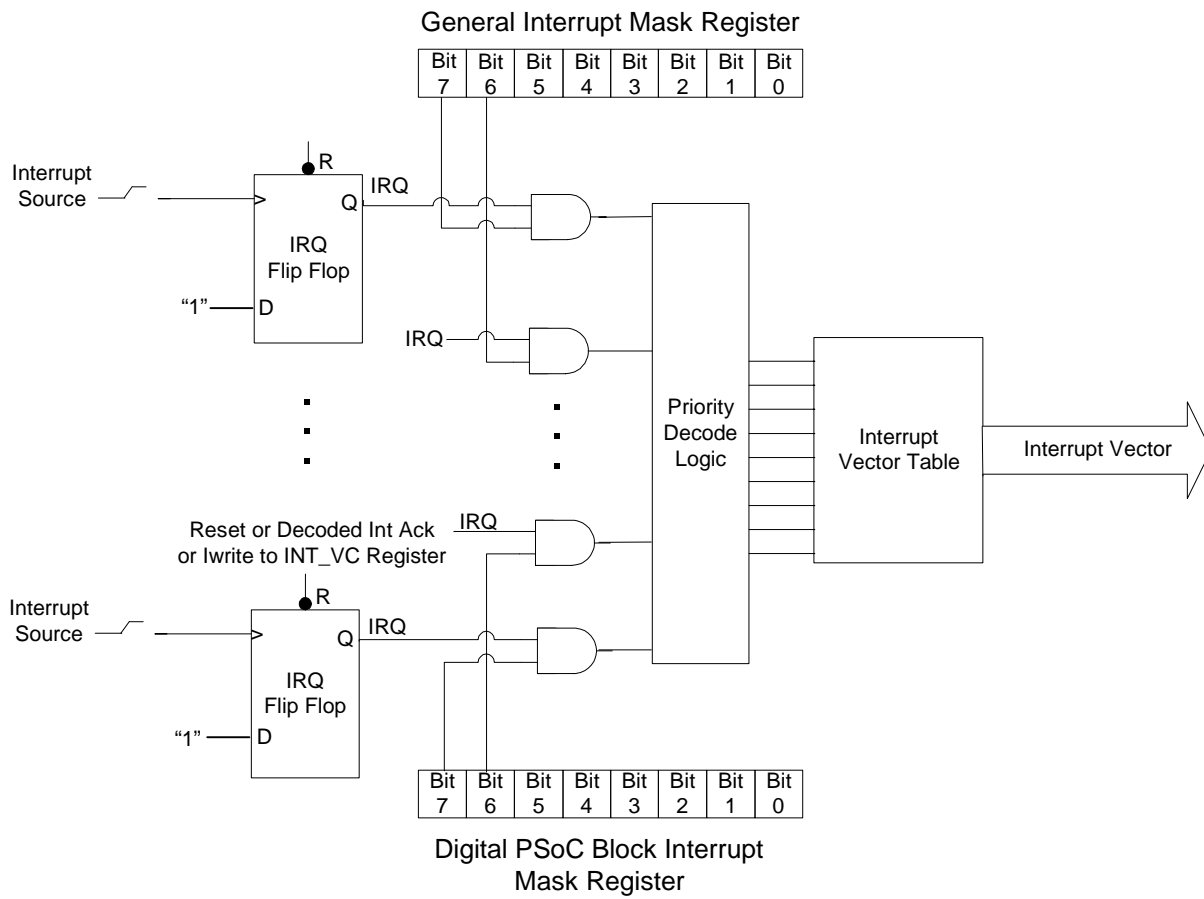


Figure 10: Interrupts Overview

8.6 GPIO Interrupt

GPIO Interrupts are polarity configurable and pin-wise maskable (within each Port's pin configuration registers). They all share the same interrupt priority and vector.

Any general purpose I/O can be used as an interrupt source. The GPIO bit in the General Interrupt Mask Register (INT_MSK0) must be set to enable pin interrupts, as well as the enable bits for each pin, which are located in

the Port x Interrupt Enable Registers (PRTxIE). There are user selectable options to generate an interrupt on 1) any change from the last read state, 2) rising edge, and 3) falling edge.

When Interrupt on Change is selected, the state of the GPIO pin is stored when the port is read. Changes from this state will then assert the interrupt, if enabled.

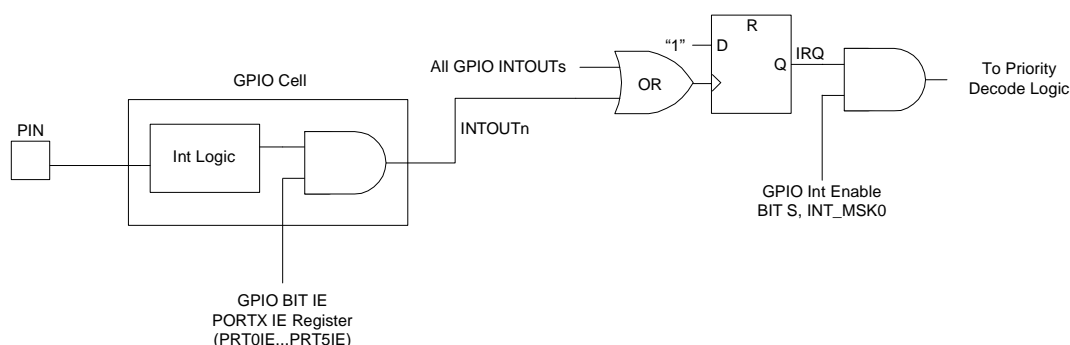


Figure 11: GPIO Interrupt Enable Diagram

For a GPIO interrupt to occur, the following steps must be taken:

1. The pin Drive Mode must be set so the pin can be an input.
2. The pin must be enabled to generate an interrupt by setting the appropriate bit in the Port interrupt Enable Register (PRTxIE).
3. The edge type for the interrupt must be set in the Port Interrupt Control 0 and Control 1 Registers (PRTxIC0 and PRTxIC1). Edge type must be set to a value other than 00.
4. The GPIO bit must be set in the General Interrupt Mask Register (INT_MSK0).
5. The Global Interrupt Enable bit must be set.
6. Because the GPIO interrupts all share the same interrupt vector, the source for the GPIO interrupt must be cleared before any other GPIO interrupt will occur (i.e., the OR gate in Figure 11: "ors" all of the INTOUTn signals together). If any of the INTOUTn signals are high, the flip-flop in Figure 11: will not see a rising edge and no IRQ will occur.

9.0 Digital PSoC Blocks

9.1 Introduction

PSoC blocks are user configurable system resources. On-chip digital PSoC blocks reduce the need for many MCU part types and external peripheral components. Digital PSoC blocks can be configured to provide a wide variety of peripheral functions. PSoC Designer Software Integrated Development Environment provides automated configuration of PSoC blocks by simply selecting the desired functions. PSoC Designer then generates the proper configuration information and can print a device data sheet unique to that configuration.

Digital PSoC blocks provide up to eight, 8-bit multipurpose timers/counters supporting multiple event timers, real-time clocks, Pulse Width Modulators (PWM), and CRCs. In addition to all PSoC block functions, communication PSoC blocks support full-duplex UARTs and SPI master or slave functions.

As shown in [Figure 12](#), there are a total of eight 8-bit digital PSoC blocks in this device family configured as a linear array. Four of these are the Digital Basic Type A blocks and four are the Digital Communications Type A blocks. Each of these digital PSoC blocks can be configured independently, or used in combination.

Each digital PSoC block has a unique Interrupt Vector and Interrupt Enable bit. Functions can be stopped or started with a user-accessible Enable bit.

The Timer/Counter/CRC/PRS/Deadband functions are available on the Digital Basic Type A blocks and also the Digital Communications Type A blocks. The UART and SPI communications functions are only available on the Digital Communications Type A blocks.

There are three configuration registers: the Function Register (DBA00FN-DCA07FN) to select the block function and mode, the Input Register (DBA00IN-DCA07IN) to select data input and clock selection, and the Output Register (DBA00OU-DCA07OU) to select and enable function outputs.

The three data registers are designated Data 0 (DBA00DR0-DCA07DR0), Data 1 (DBA00DR1-DCA07DR1), and Data 2 (DBA00DR2-DCA07DR2). The function of these registers and their bit mapping is

dependent on the overall block function selected by the user.

The one Control Register (DBA00CR0-DCA07CR0) is designated Control 0. The function of this register and its bit mapping is dependent on the overall block function selected by the user.

If the CPU frequency is 24 MHz and a PSoC timer/counter of 24-bits or longer is operating at 48 MHz, a write to the block Control Register to enable it (for example, a call to `Timer_1_Start`) may not start the block properly. In the failure case, the first count will typically be indeterminate as the upper bytes fail to make the first count correctly. However, on the first terminal count, the correct period will be loaded and counted thereafter.

Digital Communications Type A Block 05 Function Register (DCA05FN, Address = Bank 1, 34h)
 Digital Communications Type A Block 06 Function Register (DCA06FN, Address = Bank 1, 38h)
 Digital Communications Type A Block 07 Function Register (DCA07FN, Address = Bank 1, 3Ch)

9.2.2 Digital Basic Type A / Communications Type A Block xx Input Register

The Digital Basic Type A / Communications Type A Block xx Input Register (DBA00IN-DCA07IN) consists of 4 bits [3:0] to select the block input clock and 4 bits [7:4] to select the primary data/enable input. The actual usage of the input data/enable is function dependent.

Table 48: Digital Basic Type A / Communications Type A Block xx Input Register

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/Write	RW	RW	RW	RW	RW	RW	RW	RW
Bit Name	Data [3]	Data [2]	Data [1]	Data [0]	Clock [3]	Clock [2]	Clock [1]	Clock [0]
Bit [7:4]: Data [3:0] Data Enable Source Select 0 0 0 0 = Data = 0 0 0 0 1 = Data = 1 0 0 1 0 = Digital Block 03 0 0 1 1 = Chain Function to Previous Block 0 1 0 0 = Analog Column Comparator 0 0 1 0 1 = Analog Column Comparator 1 0 1 1 0 = Analog Column Comparator 2 0 1 1 1 = Analog Column Comparator 3 1 0 0 0 = Global Output[0] (for Digital Blocks 00 to 03) or Global Output[4] (for Digital Blocks 04 to 07) 1 0 0 1 = Global Output[1] (for Digital Blocks 00 to 03) or Global Output[5] (for Digital Blocks 04 to 07) 1 0 1 0 = Global Output[2] (for Digital Blocks 00 to 03) or Global Output[6] (for Digital Blocks 04 to 07) 1 0 1 1 = Global Output[3] (for Digital Blocks 00 to 03) or Global Output[7] (for Digital Blocks 04 to 07) 1 1 0 0 = Global Input[0] (for Digital Blocks 00 to 03) or Global Input[4] (for Digital Blocks 04 to 07) 1 1 0 1 = Global Input[1] (for Digital Blocks 00 to 03) or Global Input[5] (for Digital Blocks 04 to 07) 1 1 1 0 = Global Input[2] (for Digital Blocks 00 to 03) or Global Input[6] (for Digital Blocks 04 to 07) 1 1 1 1 = Global Input[3] (for Digital Blocks 00 to 03) or Global Input[7] (for Digital Blocks 04 to 07)								
Bit [3:0]: Clock [3:0] Clock Source Select 0 0 0 0 = Clock Disabled 0 0 0 1 = Global Output[4] (for Digital Blocks 00 to 03) or Global Output[0] (for Digital Blocks 04 to 07) 0 0 1 0 = Digital Block 03 (Primary Output) 0 0 1 1 = Previous Digital PSoC block (Primary Output) 0 1 0 0 = 48M 0 1 0 1 = 24V1 0 1 1 0 = 24V2 0 1 1 1 = 32k 1 0 0 0 = Global Output[0] (for Digital Blocks 00 to 03) or Global Output[4] (for Digital Blocks 04 to 07) 1 0 0 1 = Global Output[1] (for Digital Blocks 00 to 03) or Global Output[5] (for Digital Blocks 04 to 07) 1 0 1 0 = Global Output[2] (for Digital Blocks 00 to 03) or Global Output[6] (for Digital Blocks 04 to 07) 1 0 1 1 = Global Output[3] (for Digital Blocks 00 to 03) or Global Output[7] (for Digital Blocks 04 to 07) 1 1 0 0 = Global Input[0] (for Digital Blocks 00 to 03) or Global Input[4] (for Digital Blocks 04 to 07) 1 1 0 1 = Global Input[1] (for Digital Blocks 00 to 03) or Global Input[5] (for Digital Blocks 04 to 07) 1 1 1 0 = Global Input[2] (for Digital Blocks 00 to 03) or Global Input[6] (for Digital Blocks 04 to 07) 1 1 1 1 = Global Input[3] (for Digital Blocks 00 to 03) or Global Input[7] (for Digital Blocks 04 to 07)								

Digital Basic Type A Block 00 Input Register (DBA00IN, Address = Bank 1, 21h)
 Digital Basic Type A Block 01 Input Register (DBA01IN, Address = Bank 1, 25h)
 Digital Basic Type A Block 02 Input Register (DBA02IN, Address = Bank 1, 29h)
 Digital Basic Type A Block 03 Input Register (DBA03IN, Address = Bank 1, 2Dh)
 Digital Communications Type A Block 04 Input Register (DCA04IN, Address = Bank 1, 31h)
 Digital Communications Type A Block 05 Input Register (DCA05IN, Address = Bank 1, 35h)

Table 50: Digital Basic Type A / Communications Type A Block xx Output Register

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/Write	RW	RW	RW	RW	RW	RW	RW	RW
Bit Name	Reserved	Reserved	AUX Out Enable	AUX IO Sel [1]	AUX IO Sel [0]	Out Enable	Out Sel [1]	Out Sel [0]

Bit 7: Reserved

Bit 6: Reserved

Bit 5: AUX Out Enable

0 = Disable Auxiliary Output

1 = Enable Auxiliary Output (function dependent)

Bit [4:3]: AUX IO Sel [1:0] Function-dependent selection of auxiliary input or output

0 0 = Drive Global Output[0] (for Digital Blocks 00 to 03) **or**
Input from Global Input[4] or Drive Global Output [4] (for Digital Blocks 04 to 07)

0 1 = Drive Global Output[1] (for Digital Blocks 00 to 03) **or**
Input from Global Input[5] or Drive Global Output[5] (for Digital Blocks 04 to 07)

1 0 = Drive Global Output[2] (for Digital Blocks 00 to 03) **or**
Input from Global Input[6] or Drive Global Output[6] (for Digital Blocks 04 to 07)

1 1 = Drive Global Output[3] (for Digital Blocks 00 to 03) **or**
Input from Global Input[7] or Drive Global Output[7] (for Digital Blocks 04 to 07)

Bit 2: Out Enable

0 = Disable Primary Output

1 = Enable Primary Output (function dependant)

Bit [1:0]: Out Sel [1:0] Primary Output

0 0 = Drive Global Output[0] (for Digital Blocks 00 to 03) **or** Drive Global Output[4] (for Digital Blocks 04 to 07)

0 1 = Drive Global Output[1] (for Digital Blocks 00 to 03) **or** Drive Global Output[5] (for Digital Blocks 04 to 07)

1 0 = Drive Global Output[2] (for Digital Blocks 00 to 03) **or** Drive Global Output[6] (for Digital Blocks 04 to 07)

1 1 = Drive Global Output[3] (for Digital Blocks 00 to 03) **or** Drive Global Output[7] (for Digital Blocks 04 to 07)

Digital Basic Type A Block 00 Output Register	(DBA00OU, Address = Bank 1, 22h)
Digital Basic Type A Block 01 Output Register	(DBA01OU, Address = Bank 1, 26h)
Digital Basic Type A Block 02 Output Register	(DBA02OU, Address = Bank 1, 2Ah)
Digital Basic Type A Block 03 Output Register	(DBA03OU, Address = Bank 1, 2Eh)
Digital Communications Type A Block 04 Output Register	(DCA04OU, Address = Bank 1, 32h)
Digital Communications Type A Block 05 Output Register	(DCA05OU, Address = Bank 1, 36h)
Digital Communications Type A Block 06 Output Register	(DCA06OU, Address = Bank 1, 3Ah)
Digital Communications Type A Block 07 Output Register	(DCA07OU, Address = Bank 1, 3Eh)

The Primary Output is the source for “Previous Digital PSoC Block” or “Digital Block 03,” selections for the “Clock Source Select” in the Digital Basic Type A/Communications Type A Block xx Input Register ([Table 48 on page 51](#)).

A digital PSoC block may have 0, 1, or 2 outputs depending on its function, as shown in the following table:

9.5.4.6 Determining the Polynomial

A simple linear-feedback shift register, or LFSR, uses an XOR gate to “add” the values of one or more bits and feed the result back into the least-significant bit. One possible realization of a 6-bit LFSR providing a maximal sequence of 63 six-bit values is shown here:

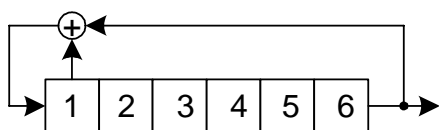


Figure 13: Polynomial LFSR

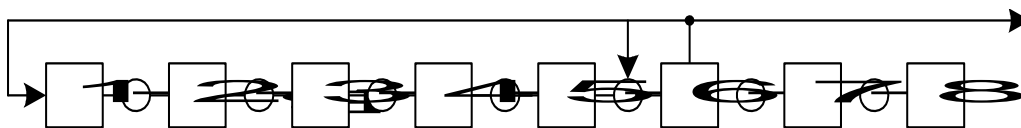


Figure 14: Polynomial PRS

Denote the first implementation as a (6, 1) LFSR, where 6 gives the length of the output codes and 1 indicates the tap which feeds the XOR gate along with the final bit. Then the modular form just shown is denoted as a [6, 5] LFSR. In general, the equivalent modular form of a simple N bit LFSR with M taps denoted by $(N, t_1, t_2, \dots, t_M)$ is given by the notation $[N, N-t_1, N-t_2, \dots, N-t_M]$. Once the form (and thus the notation) is determined, the value of Data Register 1 is easily determined. The bit corresponding to the length and all tap bits are turned on; the others are zero. Thus, the polynomial specification for Data Register 1 to implement a [6, 5] LFSR is 00110000b, or 30h. A maximal sequence PRS for 8-bits giving 255 codes is [8, 4, 3, 2] with polynomial 10001110b or 8Eh.

9.5.4.7 Usage Notes

1. Disabled State

When the Control Register Enable bit is set to '0', the internal block clock is turned off. A write to Data Register 2 (Seed) is loaded directly into Data Register 0 (LFSR) to initialize or reset the seed value. All outputs are low and the block interrupt is held low.

2. Reading the LFSR

The PRS function utilizes a different “modular” architecture with one XOR gate between each bit of the shift register. A maximal sequence equivalent to that produced by the previous realization is generated by the following modular LFSR

The current LFSR value can only be read when the block is disabled by setting the Control Register bit 0 to low. Each byte of the current LFSR value (in the case of a multi-byte block) must be read individually. The Data Register 0 byte (LFSR), which returns 0, then the Data Register 1 byte, which returns the actual value.

9.5.5 CRC - Cyclic Redundancy Check

9.5.5.1 Summary

The CRC uses a shift register and XOR gates like the PRS function. However, instead of an output bit stream, the CRC function expects an input bit stream. Functionally the CRC block is identical to the PRS with the exception of the selected input data. Input data must be presented synchronously to the clock. A polynomial specification permits the length of the input sequence over which the cyclic redundancy check computes a result to be varied. CRC-configured PSoC blocks can be chained to form longer results.

9.5.5.2 Registers

Data Register 0 implements a linear-feedback shift register. Data Register 2 holds the “seed” value and when the block is disabled, a write to Data Register 2 is loaded

10.8.3.3 Analog Switch Cap Type A Block xx Control 2 Register

AnalogBus gates the output to the analog column bus. The output on the analog column bus is affected by the state of the ClockPhase bit in Control 0 Register (ASA10CR0, ASA12CR0, ASA21CR0, ASA23CR0). If AnalogBus is set to 0, the output to the analog column bus is tri-stated. If AnalogBus is set to 1, the signal that is output to the analog column bus is selected by the ClockPhase bit. If the ClockPhase bit is 0, the block output is gated by sampling clock on last part of PHI2. If the ClockPhase bit is 1, the block output continuously drives the analog column bus.

CompBus controls the output to the column comparator bus. Note that if the comparator bus is not driven by anything in the column, it is pulled low. The comparator output is evaluated on the rising edge of internal PHI1 and is latched so it is available during internal PHI2.

AutoZero controls the shorting of the output to the inverting input of the op-amp. When shorted, the op-amp is basically a follower. The output is the op-amp offset. By using the feedback capacitor of the integrator, the block can memorize the offset and create an offset cancellation scheme. AutoZero also controls a pair of switches between the A and B branches and the summing node of the op-amp. If AutoZero is enabled, then the pair of switches is active. AutoZero also affects the function of the FSW1 bit in Control 3 Register.

The CCap bits set the value of the capacitor in the C path.

10.9.2.2 Analog Switch Cap Type B Block xx Control 1 Register

AMux controls the input muxing for the A capacitor The BCap bits set the value of the capacitor in the B path.

Table 74: Analog Switch Cap Type B Block xx Control 1 Register

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/Write	RW	RW	RW	RW	RW	RW	RW	RW
Bit Name	AMux[2]	AMux[1]	AMux[0]	BCap[4]	BCap[3]	BCap[2]	BCap[1]	BCap[0]

Bit [7:5]: AMux [2:0] Input muxing select for A capacitor branch. (Note that available mux inputs vary by individual PSoC block.)

<u>ASB11</u>	<u>ASB13</u>	<u>ASB20</u>	<u>ASB22</u>
0 0 0 = ACA01	ACA03	ASA10	ASA12
0 0 1 = ASA12	P2.2	P2.1	ASA21
0 1 0 = ASA10	ASA12	ASA21	ASA23
0 1 1 = ASA21	ASA23	ABUS0	ABUS2
1 0 0 = REFHI	REFHI	REFHI	REFHI
1 0 1 = ACA00	ACA02	ASB11	ASB13
1 1 0 = Reserved	Reserved	Reserved	Reserved
1 1 1 = Reserved	Reserved	Reserved	Reserved

Bit [4:0]: BCap [4:0] Binary encoding for 32 possible capacitor sizes for B Capacitor:

0 0 0 0 0 = 0 Capacitor units in array	1 0 0 0 0 = 16 Capacitor units in array
0 0 0 0 1 = 1 Capacitor units in array	1 0 0 0 1 = 17 Capacitor units in array
0 0 0 1 0 = 2 Capacitor units in array	1 0 0 1 0 = 18 Capacitor units in array
0 0 0 1 1 = 3 Capacitor units in array	1 0 0 1 1 = 19 Capacitor units in array
0 0 1 0 0 = 4 Capacitor units in array	1 0 1 0 0 = 20 Capacitor units in array
0 0 1 0 1 = 5 Capacitor units in array	1 0 1 0 1 = 21 Capacitor units in array
0 0 1 1 0 = 6 Capacitor units in array	1 0 1 1 0 = 22 Capacitor units in array
0 0 1 1 1 = 7 Capacitor units in array	1 0 1 1 1 = 23 Capacitor units in array
0 1 0 0 0 = 8 Capacitor units in array	1 1 0 0 0 = 24 Capacitor units in array
0 1 0 0 1 = 9 Capacitor units in array	1 1 0 0 1 = 25 Capacitor units in array
0 1 0 1 0 = 10 Capacitor units in array	1 1 0 1 0 = 26 Capacitor units in array
0 1 0 1 1 = 11 Capacitor units in array	1 1 0 1 1 = 27 Capacitor units in array
0 1 1 0 0 = 12 Capacitor units in array	1 1 1 0 0 = 28 Capacitor units in array
0 1 1 0 1 = 13 Capacitor units in array	1 1 1 0 1 = 29 Capacitor units in array
0 1 1 1 0 = 14 Capacitor units in array	1 1 1 1 0 = 30 Capacitor units in array
0 1 1 1 1 = 15 Capacitor units in array	1 1 1 1 1 = 31 Capacitor units in array

Analog Switch Cap Type B Block 11 Control 1 Register (ASB11CR1, Address = Bank 0/1, 85h)

Analog Switch Cap Type B Block 13 Control 1 Register (ASB13CR1, Address = Bank 0/1, 8Dh)

Analog Switch Cap Type B Block 20 Control 1 Register (ASB20CR1, Address = Bank 0/1, 91h)

Analog Switch Cap Type B Block 22 Control 1 Register (ASB22CR1, Address = Bank 0/1, 99h)

10.9.2.4 Analog Switch Cap Type B Block xx Control 3 Register

ARefMux selects the reference input of the A capacitor branch.

FSW1 is used to control a switch in the integrator capacitor path. It connects the output of the op-amp to the integrating cap. The state of the switch is affected by the state of the AutoZero bit in Control 2 Register (ASB11CR2, ASB13CR2, ASB20CR2, ASB22CR2). If the FSW1 bit is set to 0, the switch is always disabled. If the FSW1 bit is set to 1, the AutoZero bit determines the state of the switch. If the AutoZero bit is 0, the switch is enabled at all times. If the AutoZero bit is 1, the switch is enabled only when the internal PHI2 is high.

FSW0 is used to control a switch in the integrator capacitor path. It connects the output of the op-amp to analog ground.

BSW is used to control switching in the B branch. If disabled, the B capacitor branch is a continuous time branch like the C branch of the SC A Block. If enabled, then on internal PHI1, both ends of the cap are switched to analog ground. On internal PHI2, one end is switched to the B input and the other end is switched to the summing node.

BMuxSCB controls muxing to the input of the B capacitor branch. The B branch can be switched or unswitched.

Table 76: Analog Switch Cap Type B Block xx Control 3 Register

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/Write	RW	RW	RW	RW	RW	RW	RW	RW
Bit Name	ARefMux[1]	ARefMux[0]	FSW[1]	FSW[0]	BSW	BMuxSCB	Power[1]	Power[0]

Bit [7:6]: ARefMux [1:0] Encoding for selecting reference input

0 0 = Analog ground is selected

0 1 = REFHI input selected (This is usually the high reference)

1 0 = REFLO input selected (This is usually the low reference)

1 1 = Reference selection is driven by the comparator (When output comparator node is set high, the input is set to REFHI. When set low, the input is set to REFLO)

Bit 5: FSW1 Bit for controlling gated switches

0 = Switch is disabled

FSW1 bit is set to 1; the state of the switch is determined by the AutoZero bit. If the AutoZero bit is 0, the switch is enabled at all times. If the AutoZero bit is 1, the switch is enabled only when the internal PHI2 is high

Bit 4: FSW0 Bits for controlling gated switches

0 = Switch is disabled

1 = Switch is enabled when PHI1 is high

Bit 3: BSW Enable switching in branch

0 = B branch is a continuous time path

1 = B branch is switched with internal PHI2 sampling

Bit 2: BMuxSCB Encoding for selecting B inputs. (Note that the available mux inputs vary by individual PSoC block)

ASB11 ASB13 ASB20 ASB22

0 = ACA00 ACA02 ASB11 ASB13

1 = ACA01 ACA03 ASA10 ASA12

Bit [1:0]: Power [1:0] Encoding for selecting 1 of 4 power levels

0 0 = Off

0 1 = 10 μ A, typical

1 0 = 50 μ A, typical

1 1 = 200 μ A, typical

Analog Switch Cap Type B Block 11 Control 3 Register (ASB11CR3, Address = Bank 0/1, 87h)

Analog Switch Cap Type B Block 13 Control 3 Register (ASB13CR3, Address = Bank 0/1, 8Fh)

Analog Switch Cap Type B Block 20 Control 3 Register (ASB20CR3, Address = Bank 0/1, 93h)

Analog Switch Cap Type B Block 22 Control 3 Register (ASB22CR3, Address = Bank 0/1, 9Bh)

The SAR hardware accelerator is a block of specialized hardware designed to sequence the SAR algorithm for efficient A/D conversion. A SAR ADC is implemented conceptually with a DAC of the desired precision, and a comparator. This functionality can be configured from one or more PSoC blocks. For each conversion, the firmware should initialize the ASY_CR register as defined below, and set the sign bit of the DAC as the first guess in the algorithm. A sequence of OR instructions (Read, Modify, Write) to the DAC (CR0) register is then executed. Each of these OR instructions causes the SAR hardware to read the current state of the comparator, checking the validity of the previous guess. It either clears it or leaves it set, accordingly. The next LSB in the DAC register is also set as the next guess. Six OR instructions will complete the conversion of a 6-bit DAC. The resulting DAC code, which matches the input voltage to within 1 LSB, is then read back from the DAC CR0 register.

10.11.1 Analog Stall and Analog Stall Lockup

Stall lockup affects the operation of stalled IO writes, such as DAC writes and the stalled IOR of the SAR hardware accelerator.

The DAC and SAR User Modules operate in this mode. The analog column clock frequency must not be a power of two multiple (2, 4, 8...) higher than the CPU clock frequency. Under this condition, the CPU will never recover from a stall.

See the list of relationships (in MHz) that will fail:

Table 78: Analog Frequency Relationships

Analog Column Clock	CPU Clock
3.	1.5, 0.75, .018, 0.093
1.5	0.75, 0.18, 0.093
0.75	0.18, 0.093
0.37	0.18, 0.093
0.18	0.093

You can still run the CPU clock slower than the column clock if the relationship is not a power of two multiple. For example, you can run at 0.6 MHz, which is not a power of two multiple of any CPU frequency and therefore any CPU frequency can be selected. If the CPU frequency is greater than or equal to the analog column clock, there is not a problem.

Table 79: Analog Synchronization Control Register

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/Write	--	W	W	W	RW	RW	RW	RW
Bit Name	Reserved	SARCOUNT [2]	SARCOUNT [1]	SARCOUNT [0]	SAR-SIGN	SARCOL [1]	SARCOL [0]	SYNCEN

Bit 7: Reserved

Bit [6:4]: SARCOUNT [2:0] Initial SAR count. Load this field with the number of bits to process. In a typical 6-bit SAR, the value would be 6

Bit 3: SARSIGN Adjust the SAR comparator based on the type of block addressed. In a DAC configuration with more than one PSoC block (more than 6-bits), this bit would be 0 when processing the most significant block and 1 when processing the least significant block. This is because the least significant block of a DAC is an inverting input to the most significant block

Bit [2:1]: SARCOL [1:0] Column select for SAR comparator input. The DAC portion of the SAR can reside in any of the appropriate positions in the analog PSOC block array. However, once the comparator block is positioned (and it is possible to have the DAC and comparator in the same block), this should be the column selected

Bit 0: SYNCEN Set to 1, will stall the CPU until the rising edge of PHI1, if a write to a register within an analog Switch Cap block takes place

Analog Synchronization Control Register (ASY_CR, Address = Bank 0, 65h)

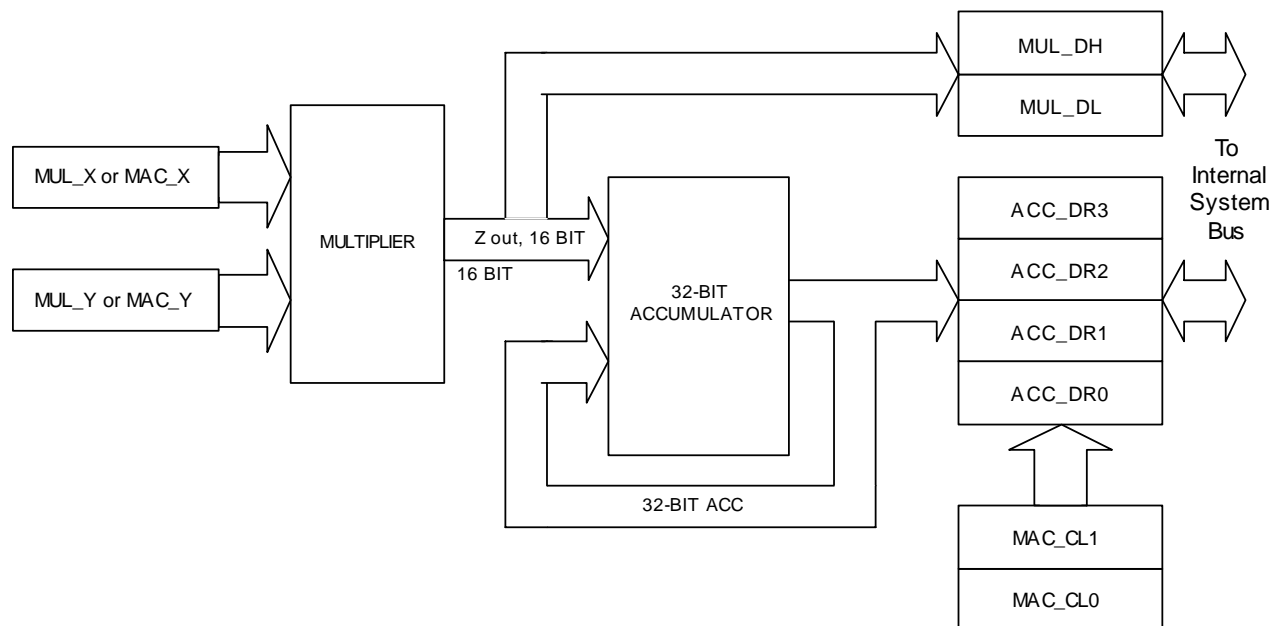


Figure 29: Multiply/Accumulate Block Diagram

Table 83: Multiply Input X Register

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/Write	W	W	W	W	W	W	W	W
Name	Data [7]	Data [6]	Data [5]	Data [4]	Data [3]	Data [2]	Data [1]	Data [0]
Bit [7:0]: Data [7:0] 8-bit data is the input value for X multiplier								

Multiply Input X Register (MUL_X, Address = Bank 0, E8h)

Table 84: Multiply Input Y Register

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/Write	W	W	W	W	W	W	W	W
Bit Name	Data [7]	Data [6]	Data [5]	Data [4]	Data [3]	Data [2]	Data [1]	Data [0]
Bit [7:0]: Data [7:0] 8-bit data is the input value for Y multiplier								

Multiply Input Y Register (MUL_Y, Address = Bank 0, E9h)

This filter is implemented using a combination of hardware and software resources. Hardware is used to accumulate the high-speed in-coming data while the software

is used to process the lower speed, enhanced resolution data for output.

Table 91: Decimator/Incremental Control Register

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/Write	RW	RW	RW	RW	RW	RW	RW	RW
Bit Name	IGEN [3]	IGEN [2]	IGEN [1]	IGEN [0]	ICCKSEL	DCol [1]	DCol [0]	DCLKSEL
<p>Bit [7:4]: IGEN [3:0] Individual enables for each analog column that gates the Analog Comparator based on the ICCKSEL input (Bit 3)</p> <p>Bit 3: ICCKSEL Clock select for Incremental gate function 0 = Digital Basic Type A Block 02 1 = Digital Communications Type A Block 06</p> <p>Bit [2:1]: DCol [1:0] Selects Analog Column Comparator source 0 0 = Analog Column Comparator 0 0 1 = Analog Column Comparator 1 1 0 = Analog Column Comparator 2 1 1 = Analog Column Comparator 3</p> <p>Bit 0: DCLKSEL Clock select for Decimator latch 0 = Digital Basic Type A Block 02 1 = Digital Communications Type A Block 06</p>								

Decimator Incremental Register (DEC_CR, Address = Bank 0, E6h)

Table 92: Decimator Data High Register

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/Write	RW	RW	RW	RW	RW	RW	RW	RW
Bit Name	Data [7]	Data [6]	Data [5]	Data [4]	Data [3]	Data [2]	Data [1]	Data [0]
<p>Bit [7:0]: Data [7:0] 8-bit data value when read is the high order byte within the 16-bit decimator data registers Any 8-bit data value when written will cause both the Decimator Data High (DEC_DH) and Decimator Data Low (DEC_DL) registers to be cleared</p>								

Decimator High Register (DEC_DH / DEC_CL, Address = Bank 0, E4h)

Table 93: Decimator Data Low Register

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/Write	R	R	R	R	R	R	R	R
Bit Name	Data [7]	Data [6]	Data [5]	Data [4]	Data [3]	Data [2]	Data [1]	Data [0]
<p>Bit [7:0]: Data [7:0] 8-bit data value when read is the low order byte within the 16 bit decimator data registers</p>								

Decimator Data Low Register (DEC_DL, Address = Bank 0, E5h)

11.6 Switch Mode Pump

This feature is available on the CY8C26xxx versions within this family. During the time V_{CC} is ramping from 0 Volts to POR V_{trip} (2.2V +/- 12%), IC operation is held off by the POR circuit and the Switch Mode Pump is enabled. The pump is realized by connecting an external inductor between the battery voltage and SMP, with an external diode pointing from SMP to the V_{CC} pin (which must have a bypass capacitance of at least 0.1uF connected to V_{CC}). This circuitry will pump V_{CC} to the Switch Mode Pump value specified in the Voltage Monitor Control Register (VLT_CR), shown above. Battery voltage values down to 0.9 V during operation are supported, but this circuitry is not guaranteed to start for battery voltages below 1.2 V. Once the IC is enabled after its power

up and boot sequence, firmware can disable the SMP function by writing Voltage Monitor Control Register (VLT_CR) bit 7 to a 1.

When the IC is put into sleep mode, the power supply pump will remain running to maintain voltage. This may result in higher than specification sleep current depending upon application. If the user desires, the pump may be disabled during precision measurements (such as A/D conversions) and then re-enabled (writing B7 to 1 and then back to 0 again). The user, however, is responsible for making the operation happen quickly enough to guarantee supply holdup (by the bypass capacitor) sufficient for continued operation.

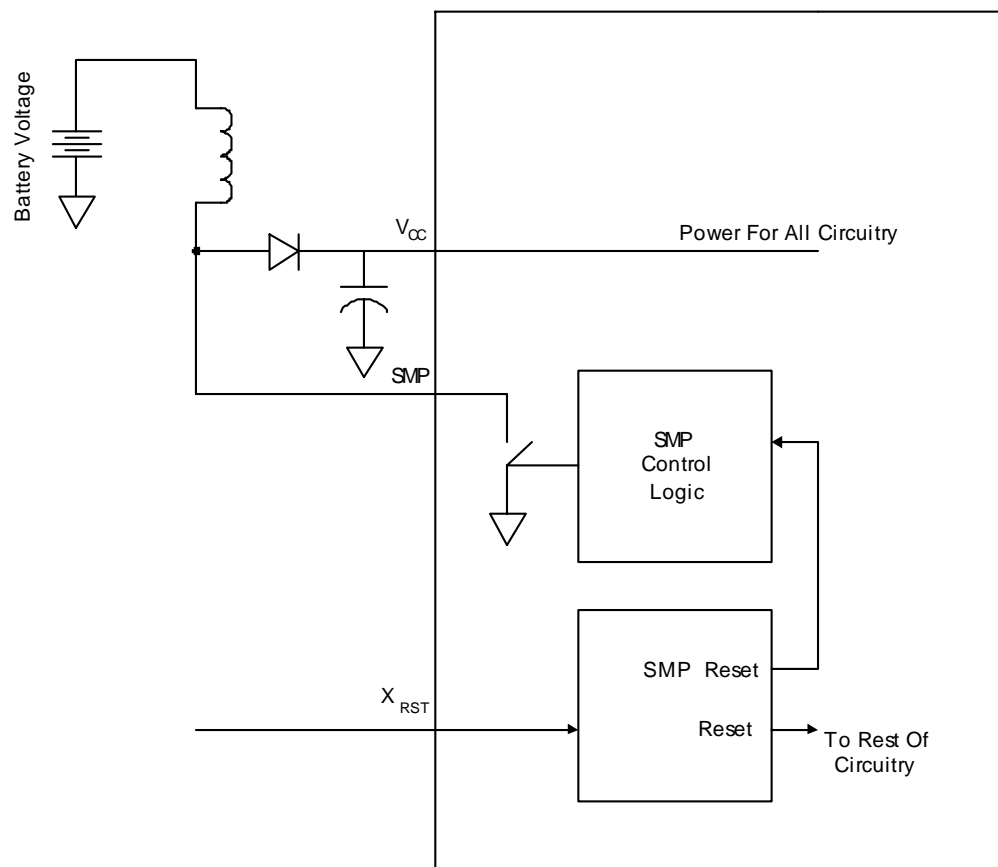


Figure 33: Switch Mode Pump

13.2.1 DC Operational Amplifier Specifications

13.2.1.1 5V Specifications

The following table lists guaranteed maximum and minimum specifications for the voltage and temperature ranges, 5V +/- 5% and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$. The Operational Amplifier is a component of both the Analog Continuous Time PSoC blocks and the Analog Switch Cap

PSoC blocks. The guaranteed specifications are measured in the Analog Continuous Time PSoC block. Typical parameters apply to 5V at 25°C and are for design guidance only. For 3.3V operation, see [Table 106 on page 131](#).

Table 105: 5V DC Operational Amplifier Specifications

Symbol	5V DC Operational Amplifier Specifications	Minimum	Typical	Maximum	Unit
	Input Offset Voltage (Absolute Value)	-	7	30	mV
	Average Input Offset Voltage Drift	-	+24	-	$\mu\text{V}/^{\circ}\text{C}$
	Input Leakage Current ¹	-	3	1000	nA
	Input Capacitance ²	.30	.34	.40	pF
	Common Mode Voltage Range ³	.5	-	$V_{CC} - 1.0$	VDC
	Common Mode Rejection Ratio	80	-	-	dB
	Open Loop Gain	80	-	-	dB
	High Output Voltage Swing (Worst Case Internal Load)				
	Bias = Low	$V_{CC} - .4$	-	-	V
	Bias = Medium	$V_{CC} - .4$	-	-	V
	Bias = High	$V_{CC} - .4$	-	-	V
	Low Output Voltage Swing (Worst Case Internal Load)				
	Bias = Low	-	-	0.1	V
	Bias = Medium	-	-	0.1	V
	Bias = High	-	-	0.1	V
	Supply Current (Including Associated AGND Buffer)				
	Bias = Low	-	125	300	μA
	Bias = Medium	-	280	600	μA
	Bias = High	-	760	1500	μA
	Supply Voltage Rejection Ratio	60	-	-	dB

1. The leakage current includes the Analog Continuous Time PSoC block mux and the analog input mux. The leakage related to the General Purpose I/O pins is not included here.
2. The Input Capacitance includes the Analog Continuous Time PSoC block mux and the analog input mux. The capacitance of the General Purpose I/O pins is not included here.
3. The common-mode input voltage range is measured through an analog output buffer. The specification includes the limitations imposed by the characteristics of the analog output buffer.

15.0 Ordering Guide

Table 123: Ordering Guide (Leaded)¹

Type	Ordering Code	Flash (KBytes)	RAM (Bytes)	SMP	Temperature Range
8 Pin (300 Mil) Molded DIP	CY8C25122-24PI	4	256	No	Ind. -40C to +85C
20 Pin (300 Mil) Molded DIP	CY8C26233-24PI	8	256	Yes	Ind. -40C to +85C
20 Pin (300 Mil) Molded SOIC	CY8C26233-24SI	8	256	Yes	Ind. -40C to +85C
20 Pin (210 Mil) SSOP	CY8C26233-24PVI	8	256	Yes	Ind. -40C to +85C
28 Pin (300 Mil) Molded DIP	CY8C26443-24PI	16	256	Yes	Ind. -40C to +85C
28 Pin (300 Mil) Molded SOIC	CY8C26443-24SI	16	256	Yes	Ind. -40C to +85C
28 Pin (210 Mil) SSOP	CY8C26443-24PVI	16	256	Yes	Ind. -40C to +85C
48 Pin (600 Mil) Molded DIP	CY8C26643-24PI ²	16	256	Yes	Ind. -40C to +85C
48 Pin (300 Mil) SSOP	CY8C26643-24PVI	16	256	Yes	Ind. -40C to +85C
44 Pin Thin Plastic Quad Flatpack	CY8C26643-24AI	16	256	Yes	Ind. -40C to +85C

1. Orders for leaded devices will not be accepted after July 2005.

2. 48-PDIP package not offered Pb-Free.

Table 124: Ordering Guide (Pb-Free Denoted with an “X” in Ordering Code)

Type	Ordering Code	Flash (KBytes)	RAM (Bytes)	SMP	Temperature Range
8 Pin (300 Mil) Molded DIP	CY8C25122-24PXI	4	256	No	Ind. -40C to +85C
20 Pin (300 Mil) Molded DIP	CY8C26233-24PXI	8	256	Yes	Ind. -40C to +85C
20 Pin (300 Mil) Molded SOIC	CY8C26233-24SXI	8	256	Yes	Ind. -40C to +85C
20 Pin (300 Mil) Molded SOIC Tape and Reel	CY8C26233-24SXIT	8	256	Yes	Ind. -40C to +85C
20 Pin (210 Mil) SSOP	CY8C26233-24PVXI	8	256	Yes	Ind. -40C to +85C
20 Pin (210 Mil) SSOP Tape and Reel	CY8C26233-24PVXIT	8	256	Yes	Ind. -40C to +85C
28 Pin (300 Mil) Molded DIP	CY8C26443-24PXI	16	256	Yes	Ind. -40C to +85C
28 Pin (300 Mil) Molded SOIC	CY8C26443-24SXI	16	256	Yes	Ind. -40C to +85C
28 Pin (300 Mil) Molded SOIC Tape and Reel	CY8C26443-24SXIT	16	256	Yes	Ind. -40C to +85C
28 Pin (210 Mil) SSOP	CY8C26443-24PVXI	16	256	Yes	Ind. -40C to +85C
28 Pin (210 Mil) SSOP Tape and Reel	CY8C26443-24PVXIT	16	256	Yes	Ind. -40C to +85C
48 Pin (300 Mil) SSOP	CY8C26643-24PVXI	16	256	Yes	Ind. -40C to +85C
48 Pin (300 Mil) SSOP Tape and Reel	CY8C26643-24PVXIT	16	256	Yes	Ind. -40C to +85C
44 Pin Thin Plastic Quad Flatpack	CY8C26643-24AXI	16	256	Yes	Ind. -40C to +85C
44 Pin Thin Plastic Quad Flatpack Tape and Reel	CY8C26643-24AXIT	16	256	Yes	Ind. -40C to +85C

16.0 Document Revision History

Table 125: Document Revision History

Document Title: CY8C25122, CY8C26233, CY8C26443, CY8C26643 Device Data Sheet for Silicon Revision D Document Number: 38-12010				
Revision	ECN #	Issue Date	Origin of Change	Description of Change
**	116628	6/17/2002	CMS Cypress Management. New Silicon Revision.	New document to CY Document Control (Revision **). Revision 3.20 for CMS customers.
*A	127231	5/22/2003	HMT.	Implementing new error tracking and document release procedure. Changes in red for Document #: 38-12010 CY Rev. *A CMS Rev. 3.20a. Changes include: --Bit 6 of the VLT_CR register is RW. Should be changed from "RW" to "--." --Analog Output Buffer Control Register ABF_CR Read/Write in Bank 1 table was corrected to Write Only. --Rewrite of section 10.4 Analog Reference Control . --AC Char. Spec. table changed .080 to 80 in "Vdd Rise Rate at Power Up." On features pg. 2, changed "Up to 10 bit DAC" to "Up to 8 bit DAC." --Adding temp. spec. for 24 MHz at beginning of AC/DC Characteristics section and Absolute Maximum Value table. --In AC Operating Spec. table fixed footnote for Output Rise Time minimum. --In AC Operating Spec. table fixed value for External Reset Pulse Width. --Changed uS to us units in tables. --New intro. --In the Analog Reference Control Register, ARF_CR, state 100 for bits 2:0 should be described as "All Analog Off." --Rework title pgs.
*B	127231	5/22/2003	HMT.	Several updates including Thermal Impedances table, 8 PDIP diagram and company address. OSC_CR0 register name.
*C	362598	See ECN	HMT.	Add Pb-Free table. Add "Not Recommended for New Designs" banner. Update package revisions. Fix register typo's.
Distribution: External/Public Posting: None				