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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	M8C
Core Size	8-Bit
Speed	24MHz
Connectivity	SPI, UART/USART
Peripherals	LVD, POR, PWM, WDT
Number of I/O	6
Program Memory Size	4KB (4K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 5.25V
Data Converters	A/D 1x8b, 1x11b, 1x12b; D/A 1x9b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Through Hole
Package / Case	8-DIP (0.300", 7.62mm)
Supplier Device Package	8-PDIP
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/cy8c25122-24pxi

1.0 Functional Overview

The CPU heart of this next generation family of micro-controllers is a high performance, 8-bit, M8C Harvard architecture microprocessor. Separate program and memory busses allow for faster overall throughput. Processor clock speeds to 24 MHz are available. The processor may also be run at lower clock speeds for power-sensitive applications. A rich instruction set allows for efficient low-level language support.

All devices in this family include both analog and digital configurable peripherals (PSoC blocks). These blocks enable the user to define unique functions during configuration of the device. Included are twelve analog PSoC blocks and eight digital PSoC blocks. Potential applications for the digital PSoC blocks are timers, counters, UARTs, CRC generators, PWMs, and other functions. The analog PSoC blocks can be used for SAR ADCs, Multi-slope ADCs, programmable gain amplifiers, programmable filters, DACs, and other functions. Higher order User Modules such as modems, complex motor controllers, and complete sensor signal chains can be created from these building blocks. This allows for an unprecedented level of flexibility and integration in micro-controller-based systems.

A Multiplier/Accumulator (MAC) is available on all devices in this family. The MAC is implemented on this device as a peripheral that is mapped into the register space. When an instruction writes to the MAC input registers, the result of an 8x8 multiply and a 32-bit accumulate are available to be read from the output registers on the next instruction cycle.

The number of general purpose I/Os available in this family of parts range from 6 to 44. Each of these I/O pins has a variety of programmable options. In the output

mode, the user can select the drive strength desired. Any pin can serve as an interrupt source, and can be selected to trigger on positive edges, negative edges, or any change. Digital signal sources can be routed directly from a pin to the digital PSoC blocks. Some pins have additional capability to route analog signals to the analog PSoC blocks.

Multiple oscillator options are available for use in clocking the CPU, analog PSoC blocks and digital PSoC blocks. These options include an internal main oscillator running at 48/24 MHz, an external crystal oscillator for use with a 32.768 kHz watch crystal, and an internal low-speed oscillator for use in clocking the PSoC blocks and the Watchdog/Sleep timer. User selectable clock divisors allow for optimizing code execution speed and power trade-offs.

The different device types in this family provide various amounts of code and data memory. The code space ranges in size from 4K to 16K bytes of user programmable Flash memory. This memory can be programmed serially in either a programming Pod or on the user board. The endurance on the Flash memory is 50,000 erase/write cycles. The data space is 256 bytes of user SRAM.

A powerful and flexible protection model secures the user's sensitive information. This model allows the user to selectively lock blocks of memory for read and write protection. This allows partial code updates without exposing proprietary information.

Devices in this family range from 8 pins through 48 pins in PDIP, SOIC and SSOP packages.

1.1 Key Features

Table 1: Device Family Key Features

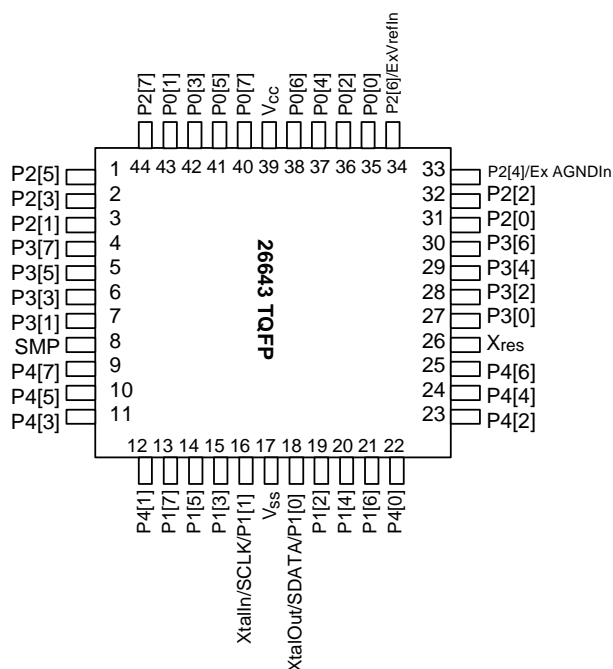
	CY8C25122	CY8C26233	CY8C26443	CY8C26643
Operating Frequency	93.7kHz - 24MHz	93.7kHz - 24MHz	93.7kHz - 24MHz	93.7kHz - 24MHz
Operating Voltage	3.0 - 5.25V	3.0 - 5.25V	3.0 - 5.25V	3.0 - 5.25V
Program Memory (KBytes)	4	8	16	16
Data Memory (Bytes)	256	256	256	256
Digital PSoC Blocks	8	8	8	8
Analog PSoC Blocks	12	12	12	12
I/O Pins	6	16	24	40/44
External Switch Mode Pump	No	Yes	Yes	Yes
Available Packages	8 PDIP	20 PDIP	28 PDIP	48 PDIP
		20 SOIC	28 SOIC	48 SSOP
		20 SSOP	28 SSOP	44 TQFP

Table 5: Pin-out 44 Pin, continued

P4[6]	I/O	25	Port 4[6]
XRES	I	26	External Reset
P3[0]	I/O	27	Port 3[0]
P3[2]	I/O	28	Port 3[2]
P3[4]	I/O	29	Port 3[4]
P3[6]	I/O	30	Port 3[6]
P2[0]	I/O	31	Port 2[0] (Non-Multiplexed Analog Input)
P2[2]	I/O	32	Port 2[2] (Non-Multiplexed Analog Input)
P2[4]	I/O	33	Port 2[4] / External AGNDIn
P2[6]	I/O	34	Port 2[6] / External VREFIn
P0[0]	I/O	35	Port 0[0] (Analog Input)
P0[2]	I/O	36	Port 0[2] (Analog Input/Output)
P0[4]	I/O	37	Port 0[4] (Analog Input/Output)
P0[6]	I/O	38	Port 0[6] (Analog Input)
Vcc	Power	39	Supply Voltage
P0[7]	I/O	40	Port 0[7] (Analog Input)
P0[5]	I/O	41	Port 0[5] (Analog Input/Output)
P0[3]	I/O	42	Port 0[3] (Analog Input/Output)
P0[1]	I/O	43	Port 0[1] (Analog Input)
P2[7]	I/O	44	Port 2[7]

Table 6: Pin-out 48 Pin

Name	I/O	Pin	Description
P0[7]	I/O	1	Port 0[7] (Analog Input)
P0[5]	I/O	2	Port 0[5] (Analog Input/Output)
P0[3]	I/O	3	Port 0[3] (Analog Input/Output)
P0[1]	I/O	4	Port 0[1] (Analog Input)
P2[7]	I/O	5	Port 2[7]
P2[5]	I/O	6	Port 2[5]
P2[3]	I/O	7	Port 2[3] (Non-Multiplexed Analog Input)
P2[1]	I/O	8	Port 2[1] (Non-Multiplexed Analog Input)
P3[7]	I/O	9	Port 3[7]
P3[5]	I/O	10	Port 3[5]
P3[3]	I/O	11	Port 3[3]
P3[1]	I/O	12	Port 3[1]
SMP	O	13	Switch Mode Pump
P4[7]	I/O	14	Port 4[7]
P4[5]	I/O	15	Port 4[5]
P4[3]	I/O	16	Port 4[3]
P4[1]	I/O	17	Port 4[1]
P5[3]	I/O	18	Port 5[3]
P5[1]	I/O	19	Port 5[1]
P1[7]	I/O	20	Port 1[7]
P1[5]	I/O	21	Port 1[5]
P1[3]	I/O	22	Port 1[3]
P1[1]	I/O	23	Port 1[1] / XtalIn / SCLK
Vss	Power	24	Ground
P1[0]	I/O	25	Port 1[0] / XtalOut / SDATA
P1[2]	I/O	26	Port 1[2]
P1[4]	I/O	27	Port 1[4]
P1[6]	I/O	28	Port 1[6]

**Figure 5: 26643 TQFP**

2.2.3 Index Register

Table 10: Index Register (CPU_X)

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/Write	System ¹	System ¹	System ¹	System ¹	System ¹	System ¹	System ¹	System ¹
Bit Name	Data [7]	Data [6]	Data [5]	Data [4]	Data [3]	Data [2]	Data [1]	Data [0]
Bit [7:0]: Data [7:0] 8-bit data value holds an index for any instruction that uses an indexed addressing mode								

1. System - not directly accessible by the user

2.2.4 Stack Pointer Register

Table 11: Stack Pointer Register (CPU_SP)

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/Write	System ¹	System ¹	System ¹	System ¹	System ¹	System ¹	System ¹	System ¹
Bit Name	Data [7]	Data [6]	Data [5]	Data [4]	Data [3]	Data [2]	Data [1]	Data [0]
Bit [7:0]: Data [7:0] 8-bit data value holds a pointer to the current top-of-stack								

1. System - not directly accessible by the user

2.2.5 Program Counter Register

Table 12: Program Counter Register (CPU_PC)

Bit #	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
Read/Write	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
Bit Name	Data [15]	Data [14]	Data [13]	Data [12]	Data [11]	Data [10]	Data [9]	Data [8]	Data [7]	Data [6]	Data [5]	Data [4]	Data [3]	Data [2]	Data [1]	Data [0]
Bit [15:0]: Data [15:0] 16-bit data value is the low-order/high-order byte of the Program Counter																

1. System - not directly accessible by the user

2.3 Addressing Modes

2.3.1 Source Immediate

The result of an instruction using this addressing mode is placed in the A register, the F register, the SP register, or the X register, which is specified as part of the instruction opcode. Operand 1 is an immediate value that serves as a source for the instruction. Arithmetic instructions

require two sources. Instructions using this addressing mode are two bytes in length.

Table 13: Source Immediate

Opcode	Operand 1
Instruction	Immediate Value

6.0 I/O Registers

6.1 Port Data Registers

Table 28: Port Data Registers

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/Write	RW	RW	RW	RW	RW	RW	RW	RW
Bit Name	Data [7]	Data [6]	Data [5]	Data [4]	Data [3]	Data [2]	Data [1]	Data [0]
Bit [7:0]: <u>Data [7:0]</u> When written is the bits for output on port pins. When read is the state of the port pins								

Port 0 Data Register (PRT0DR, Address = Bank 0, 00h)

Port 1 Data Register (PRT1DR, Address = Bank 0, 04h)

Port 2 Data Register (PRT2DR, Address = Bank 0, 08h)

Port 3 Data Register (PRT3DR, Address = Bank 0, 0Ch)

Port 4 Data Register (PRT4DR, Address = Bank 0, 10h)

Port 5 Data Register (PRT5DR, Address = Bank 0, 14h) **Note:** Port 5 is 4-bits wide, Bit [3:0]

6.2 Port Interrupt Enable Registers

Table 29: Port Interrupt Enable Registers

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/Write	W	W	W	W	W	W	W	W
Bit Name	Int En [7]	Int En [6]	Int En [5]	Int En [4]	Int En [3]	Int En [2]	Int En [1]	Int En [0]
Bit [7:0]: <u>Int En [7:0]</u> When written sets the pin interrupt state 0 = Interrupt disabled for pin 1 = Interrupt enabled for pin								

Port 0 Interrupt Enable Register (PRT0IE, Address = Bank 0, 01h)

Port 1 Interrupt Enable Register (PRT1IE, Address = Bank 0, 05h)

Port 2 Interrupt Enable Register (PRT2IE, Address = Bank 0, 09h)

Port 3 Interrupt Enable Register (PRT3IE, Address = Bank 0, 0Dh)

Port 4 Interrupt Enable Register (PRT4IE, Address = Bank 0, 11h)

Port 5 Interrupt Enable Register (PRT5IE, Address = Bank 0, 15h) **Note:** Port 5 is 4-bits wide

7.0 Clocking

7.1 Oscillator Options

7.1.1 Internal Main Oscillator

The internal main oscillator outputs two frequencies, 48 MHz and 24 MHz. In the absence of a high-precision input source from the external oscillator, the accuracy of this circuit is +/- 2.5% (between 0°C and +85°C). No external components are required to achieve this level of accuracy. The Internal Main Oscillator Trim Register (IMO_TR) is used to calibrate this oscillator into specified tolerance. Factory-programmed trim values are available for 5.0V and 3.3V operation. The 5.0V value is loaded in the IMO_TR register upon reset. This register must be adjusted when the operating voltage is outside the range

for which factory calibration was set. The factory-programmed trim value is selected using the Table Read Supervisor Call, and is documented in 11.8.

There is an option to phase lock this oscillator to the External Crystal Oscillator. The choice of crystal and its inherent accuracy will determine the overall accuracy of the oscillator. The External Crystal Oscillator must be stable prior to locking the frequency of the Internal Main Oscillator to this reference source.

Table 35: Internal Main Oscillator Trim Register

Bit #	7	6	5	4	3	2	1	0
POR	FS ¹	FS ¹	FS ¹	FS ¹	FS ¹	FS ¹	FS ¹	FS ¹
Read/Write	W	W	W	W	W	W	W	W
Bit Name	IMO Trim [7]	IMO Trim [6]	IMO Trim [5]	IMO Trim [4]	IMO Trim [3]	IMO Trim [2]	IMO Trim [1]	IMO Trim [0]
Bit [7:0]: IMO Trim [7:0] Data value stored will alter the trimmed frequency of the Internal Main Oscillator. A larger value in this register will increase the speed of the Internal Main Oscillator								

1. FS = Factory set trim value

Internal Main Oscillator Trim Register (IMO_TR, Address = Bank 1, E8h)

7.1.2 Internal Low Speed Oscillator

An internal low speed oscillator of nominally 32 kHz is available to generate sleep wake-up interrupts and Watchdog resets if the user does not want to attach a 32.768 kHz watch crystal. This oscillator can also be used as a clocking source for the digital PSoC blocks.

The oscillator operates in two different modes. A trim value is written to the Internal Low Speed Oscillator Trim Register (ILO_TR), shown below, upon reset. See section 13.0 for accuracy information. When the IC is put into sleep mode this oscillator drops into an ultra low current state and the accuracy is reduced.

This register sets the adjustment for the Internal Low Speed Oscillator. The value placed in this register is based on factory testing. It is recommended that the user not alter this value.

only be input from GPIO input pins (Global Input Bus). There is no way to enable the SS_internally. In SPI modes 2 & 3, where SS is not required between each byte, the external pin may be grounded.

Important: The AUX Out Enable bit (bit 5) of the Output Register (DCA04OU-DCA07OU) must be set to 0 to disable it.

9.5.9.4 Outputs

The function output is the MISO (master-in, slave-out) signal, which may be driven on the Global Output bus and is selected by Output Register (DCA04OU-DCA07OU).

9.5.9.5 Interrupts

When enabled, the function generates an interrupt on RX Reg Full status (Data Register 2 full). If Mode[1] of the Function Register is set, the interrupt will be generated on SPI Complete status.

9.5.9.6 Usage Notes

1. Reading the Status

Reading Control Register 0, which contains the status bits, automatically resets the status bits to 0 with the exception of TX Reg Empty, which is cleared when a byte is written to the TX Data Register (Data Register 1), and the RX Reg Full, which is cleared when a byte is read from the RX Data Register (Data Register 2).

2. Multi-Slave Environment

The SS_ signal does not have any affect on the output from the slave. The output of the slave at the end of a reception/transmission is always the first bit sent (the MSB, unless LSBF option is selected, then it's the LSB). To implement a multi-slave environment, a GPIO interrupt may be configured on the SS_ input, and the Slave output strength may be toggled between driving and High Z in firmware.

3. Using Interrupts

RX Reg Full status or SPI Complete status generates an interrupt. Executing the interrupt routine does not automatically clear status. If SPI Complete is selected as the interrupt source, Control Register 0 (status) must be read in the interrupt routine to clear the status. If RX Reg Full status is selected, a byte must be read from the RX Data Register (Data

Register 2) to clear the status. If the interrupting status is not cleared further interrupts will be suppressed.

4. Synchronization of CPU Interaction

Because the SPI Slave is clocked asynchronously by the master SCLK, transfer of data between the TX Register to shifter and shifter to RX Register occurs asynchronously.

Either polling or interrupts can be used to detect that a byte has been received and is ready to read. However, on the TX side, the user is responsible for implementing a protocol that ensures there is enough set-up time from the TX Data Register write to the first clock (mode 2, 3) or SS_ (mode 0, 1) from the master.

10.0 Analog PSoC Blocks

10.1 Introduction

PSoC blocks are user configurable system resources. On-chip analog PSoC blocks reduce the need for many MCU part types and external peripheral components. Analog PSoC blocks can be configured to provide a wide variety of peripheral functions. PSoC Designer Software Integrated Development Environment provides automated configuration of PSoC blocks by simply selecting the desired functions. PSoC Designer then generates the proper configuration information and can print a device data sheet unique to that configuration.

Each of the analog blocks has many potential inputs and several outputs. The inputs to these blocks include analog signals from external sources, intrinsic analog signals driven from neighboring analog blocks or various voltage reference sources.

There are three discrete outputs from each analog block (there are an additional two discrete outputs in the Continuous Time blocks), 1) the analog output bus (ABUS), which is an analog bus resource that is shared by all of the analog blocks in a column, 2) the comparator bus (CBUS), which is a digital bus resource that is shared by all of the analog blocks in a column, and 3) the output bus (OUT, (plus GOUT and LOUT in the Continuous Time blocks)), which is an analog bus resource that is shared by all of the analog blocks in a column and connects to one of the analog output buffers, to send a signal externally to the device. There are also intrinsic outputs that connect to neighboring analog blocks.

Twelve analog PSoC blocks are available separately or combined with the digital PSoC blocks. A precision internal voltage reference provides accurate analog comparisons. A temperature sensor input is provided to the analog PSoC block array supporting applications like battery chargers and data acquisition without requiring external components.

There are three analog PSoC block types: Continuous Time (CT) blocks, and Type A and Type B Switch Capacitor (SC) blocks. CT blocks provide continuous time analog functions. SC blocks provide ADC and DAC analog functions. Currently, supported analog functions are 12-

bit Incremental and 11-bit Delta-Sigma ADC, successive approximation ADCs up to 6 bits, DACs up to 8 bits, programmable gain stages, sample and hold circuits, programmable filters, comparators, and a temperature sensor.

The analog functionality provided is as follows:

- A/D and D/A converters, programmable gain blocks, comparators, and switched capacitor filters.
- Single ended configuration is cost effective for reasonable speed / accuracy, and provides simple interface to most real-world analog inputs and outputs.
- Support is provided for sensor interfaces, audio codes, embedded modems, and general-purpose op amp circuits.
- Flexible, System on-a-Chip programmability, providing variations in functions.
- For a given function, easily selected trade-offs of accuracy and resolution with speed, resources (number of analog blocks), and power dissipated for that application.
- The analog section is an "Analog Computation Unit," providing programmed steering of signal flow and selecting functionality through register-based control of analog switches. It also sets coefficients in Switched Capacitor Filters and noise shaping (Delta-Sigma) modulators, as well as programs gain or attenuation settings in amplifier configurations.
- The architecture provides continuous time blocks and discrete time (Switched Capacitor) blocks. The continuous time blocks allow selection of precision amplifier or comparator circuitry using programmable resistors as passive configuration and parameter setting elements. The Switched Capacitor (SC) blocks allow configuration of DACs, Delta Sigma, incremental or Successive Approximation ADCs, or Switched Capacitor filters with programmable coefficients.

10.6 Analog Clock Select Register

Table 65: Analog Clock Select Register

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/Write	RW	RW	RW	RW	RW	RW	RW	RW
Bit Name	Reserved	SHDIS	ACLK1 [2]	ACLK1 [1]	ACLK1 [0]	ACLK0 [2]	ACLK0 [1]	ACLK0 [0]

Bit 7: Reserved

Bit 6: SHDIS During normal operation of an SC block for the amplifier of a column enabled to drive the output bus, the connection is only made for the last half of PHI2 (during PHI1 and for the first half of PHI2, the output bus floats at the last voltage to which it was driven). This forms a sample and hold operation using the output bus and its associated capacitance. This design prevents the output bus from being perturbed by the intermediate states of the SC operation (often a reset state for PHI1 and settling to the valid state during PHI2)

Following are the exceptions: 1) If the ClockPhase bit in CR0 (for the SC block in question) is set to 1, then the output is enabled for the whole of PHI2. 2) If the SHDIS signal is set in bit 6 of the Analog Clock Select Register, then sample and hold operation is disabled for all columns and all enabled outputs of SC blocks are connected to their respective output busses for the entire period of their respective PHI2s

0 = Sample and hold function enabled
1 = Sample and hold function disabled

Bit [5:3]: ACLK1 [2:0]

0 0 0 = Digital Basic Type A Block 00
0 0 1 = Digital Basic Type A Block 01
0 1 0 = Digital Basic Type A Block 02
0 1 1 = Digital Basic Type A Block 03
1 0 0 = Digital Communications Type A Block 04
1 0 1 = Digital Communications Type A Block 05
1 1 0 = Digital Communications Type A Block 06
1 1 1 = Digital Communications Type A Block 07

Bit [2:0]: ACLK0 [2:0] Same configurations as ACLK1 [2:0]

0 0 0 = Digital Basic Type A Block 00
0 0 1 = Digital Basic Type A Block 01
0 1 0 = Digital Basic Type A Block 02
0 1 1 = Digital Basic Type A Block 03
1 0 0 = Digital Communications Type A Block 04
1 0 1 = Digital Communications Type A Block 05
1 1 0 = Digital Communications Type A Block 06
1 1 1 = Digital Communications Type A Block 07

Analog Clock Select Register (CLK_CR1, Address = Bank 1, 61h)

There are a total of twelve analog PSoC blocks implemented for each of the following types; Analog Continuous Time Type A (ACAxx), Analog Switch Cap Type A (ASAxx), and Analog Switch Cap Type B (ASBxx). These blocks are arranged in an array of three rows by four columns. Each column has one of each type of PSoC block, and the individual PSoC blocks are identified by the row and column in which they reside.

There are two primary types of analog PSoC blocks. Both types contain one op-amp but their principles of operation are quite different. Continuous-time PSoC blocks employ three configuration registers and use resistors to condition amplifier response. Switched capacitor blocks have one comparator and four configuration registers and operate as discrete-time sampling operators. In both types, the configuration registers are

Table 71: Analog Switch Cap Type A Block xx Control 2 Register

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/ Write	RW	RW	RW	RW	RW	RW	RW	RW
Bit Name	AnalogBus	CompBus	AutoZero	CCap[4]	CCap[3]	CCap[2]	CCap[1]	CCap[0]

Bit 7: AnalogBus Enable output to the analog bus

0 = Disable output to analog column bus

1 = Enable output to analog column bus

(The output on the analog column bus is affected by the state of the ClockPhase bit in Control 0 Register (ASA10CR0, ASA12CR0, ASA21CR0, ASA23CR0). If AnalogBus is set to 0, the output to the analog column bus is tri-stated. If AnalogBus is set to 1, the signal that is output to the analog column bus is selected by the ClockPhase bit. If the ClockPhase bit is 0, the block output is gated by sampling clock on last part of PHI2. If the ClockPhase bit is 1, the block output continuously drives the analog column bus.)

Bit 6: CompBus Enable output to the comparator bus

0 = Disable output to comparator bus

1 = Enable output to comparator bus

Bit 5: AutoZero Bit for controlling gated switches

0 = Shorting switch is not active. Input cap branches shorted to op-amp input

1 = Shorting switch is enabled during internal PHI1. Input cap branches shorted to analog ground during internal PHI1 and to op-amp input during internal PHI2.

Bit [4:0]: CCap [4:0] Binary encoding for 32 possible capacitor sizes for C Capacitor:

0 0 0 0 0 = 0 Capacitor units in array	1 0 0 0 0 = 16 Capacitor units in array
0 0 0 0 1 = 1 Capacitor units in array	1 0 0 0 1 = 17 Capacitor units in array
0 0 0 1 0 = 2 Capacitor units in array	1 0 0 1 0 = 18 Capacitor units in array
0 0 0 1 1 = 3 Capacitor units in array	1 0 0 1 1 = 19 Capacitor units in array
0 0 1 0 0 = 4 Capacitor units in array	1 0 1 0 0 = 20 Capacitor units in array
0 0 1 0 1 = 5 Capacitor units in array	1 0 1 0 1 = 21 Capacitor units in array
0 0 1 1 0 = 6 Capacitor units in array	1 0 1 1 0 = 22 Capacitor units in array
0 0 1 1 1 = 7 Capacitor units in array	1 0 1 1 1 = 23 Capacitor units in array
0 1 0 0 0 = 8 Capacitor units in array	1 1 0 0 0 = 24 Capacitor units in array
0 1 0 0 1 = 9 Capacitor units in array	1 1 0 0 1 = 25 Capacitor units in array
0 1 0 1 0 = 10 Capacitor units in array	1 1 0 1 0 = 26 Capacitor units in array
0 1 0 1 1 = 11 Capacitor units in array	1 1 0 1 1 = 27 Capacitor units in array
0 1 1 0 0 = 12 Capacitor units in array	1 1 1 0 0 = 28 Capacitor units in array
0 1 1 0 1 = 13 Capacitor units in array	1 1 1 0 1 = 29 Capacitor units in array
0 1 1 1 0 = 14 Capacitor units in array	1 1 1 1 0 = 30 Capacitor units in array
0 1 1 1 1 = 15 Capacitor units in array	1 1 1 1 1 = 31 Capacitor units in array

Analog Switch Cap Type A Block 10 Control 2 Register (ASA10CR2, Address = Bank 0/1, 82h)

Analog Switch Cap Type A Block 12 Control 2 Register (ASA12CR2, Address = Bank 0/1, 8Ah)

Analog Switch Cap Type A Block 21 Control 2 Register (ASA21CR2, Address = Bank 0/1, 96h)

Analog Switch Cap Type A Block 23 Control 2 Register (ASA23CR2, Address = Bank 0/1, 9Eh)

10.8.3.4 Analog Switch Cap Type A Block xx Control 3 Register

ARefMux selects the reference input of the A capacitor branch.

FSW1 is used to control a switch in the integrator capacitor path. It connects the output of the op-amp to the integrating cap. The state of the switch is affected by the state of the AutoZero bit in Control 2 Register (ASA10CR2, ASA12CR2, ASA21CR2, ASA23CR2). If the FSW1 bit is set to 0, the switch is always disabled. If the FSW1 bit is set to 1, the AutoZero bit determines the state of the switch. If the AutoZero bit is 0, the switch is

enabled at all times. If the AutoZero bit is 1, the switch is enabled only when the internal PHI2 is high.

FSW0 is used to control a switch in the integrator capacitor path. It connects the output of the op-amp to analog ground.

BMuxSCA controls the muxing to the input of the B capacitor branch.

Power – encoding for selecting 1 of 4 power levels. The block always powers up in the off state.

Table 72: Analog Switch Cap Type A Block xx Control 3 Register

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/ Write	RW	RW	RW	RW	RW	RW	RW	RW
Bit Name	ARefMux[1]	ARefMux[0]	FSW[1]	FSW[0]	BMuxSCA[1]	BMuxSCA[0]	Power[1]	Power[0]

Bit [7:6]: ARefMux [1:0] Encoding for selecting reference input
0 0 = Analog ground is selected
0 1 = REFHI input selected (This is usually the high reference)
1 0 = REFLO input selected (This is usually the low reference)
1 1 = Reference selection is driven by the comparator (When output comparator node is set high, the input is set to REFHI. When set low, the input is set to REFLO)

Bit 5: FSW1 Bit for controlling gated switches
0 = Switch is disabled
1 = If the FSW1 bit is set to 1, the state of the switch is determined by the AutoZero bit. If the AutoZero bit is 0, the switch is enabled at all times. If the AutoZero bit is 1, the switch is enabled only when the internal PHI2 is high

Bit 4: FSW0 Bits for controlling gated switches
0 = Switch is disabled
1 = Switch is enabled when PHI1 is high

Bit [3:2]: BMuxSCA [1:0] Encoding for selecting B inputs. (Note that the available mux inputs vary by individual PSoC block.)

<u>ASA10</u>	<u>ASA21</u>	<u>ASA12</u>	<u>ASA23</u>
0 0 = ACA00	ASB11	ACA02	ASB13
0 1 = ASB11	ASB20	ASB13	ASB22
1 0 = P2.3	ASB22	ASB11	P2.0
1 1 = ASB20	T _{ref} GND	ASB22	ABUS3

Bit [1:0]: Power [1:0] Encoding for selecting 1 of 4 power levels
0 0 = Off
0 1 = 10 μ A, typical
1 0 = 50 μ A, typical
1 1 = 200 μ A, typical

Analog Switch Cap Type A Block 10 Control 3 Register (ASA10CR3, Address = Bank 0/1, 83h)

Analog Switch Cap Type A Block 12 Control 3 Register (ASA12CR3, Address = Bank 0/1, 8Bh)

Analog Switch Cap Type A Block 21 Control 3 Register (ASA21CR3, Address = Bank 0/1, 97h)

Analog Switch Cap Type A Block 23 Control 3 Register (ASA23CR3, Address = Bank 0/1, 9Fh)

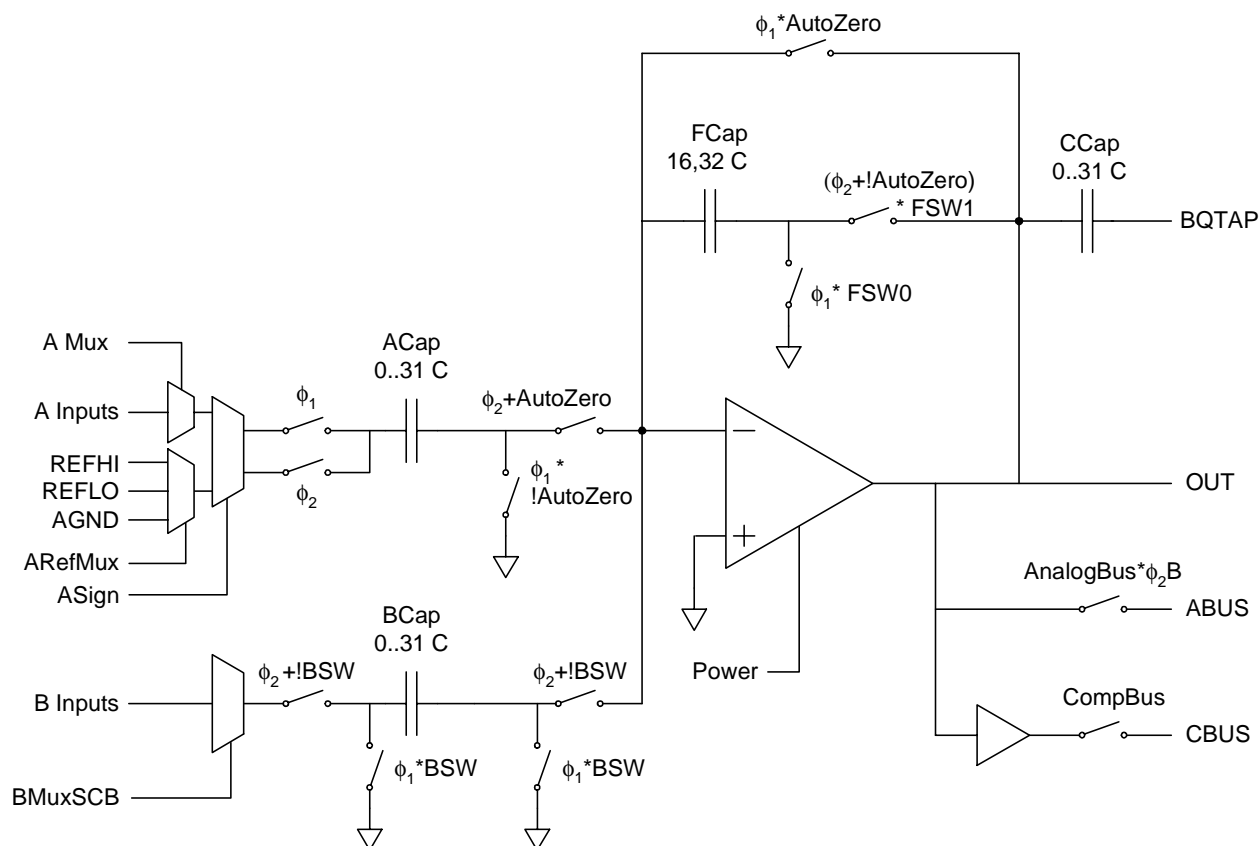


Figure 26: Analog Switch Cap Type B PSoC Blocks

10.9.2 Registers

10.9.2.1 Analog Switch Cap Type B Block xx Control 0 Register

FCap controls the size of the switched feedback capacitor in the integrator.

ClockPhase controls the internal clock phasing relative to the input clock phasing. ClockPhase affects the output of the analog column bus which is controlled by the AnalogBus bit in Control 2 Register (ASB11CR2, ASB13CR2, ASB20CR2, ASB22CR2).

ASign controls the switch phasing of the switches on the bottom plate of the A capacitor. The bottom plate samples the input or the reference.

The ACap bits set the value of the capacitor in the A path.

Table 73: Analog Switch Cap Type B Block xx Control 0 Register

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/Write	RW	RW	RW	RW	RW	RW	RW	RW
Bit Name	FCap	ClockPhase	ASign	ACap[4]	ACap[3]	ACap[2]	ACap[1]	ACap[0]

10.9.2.4 Analog Switch Cap Type B Block xx Control 3 Register

ARefMux selects the reference input of the A capacitor branch.

FSW1 is used to control a switch in the integrator capacitor path. It connects the output of the op-amp to the integrating cap. The state of the switch is affected by the state of the AutoZero bit in Control 2 Register (ASB11CR2, ASB13CR2, ASB20CR2, ASB22CR2). If the FSW1 bit is set to 0, the switch is always disabled. If the FSW1 bit is set to 1, the AutoZero bit determines the state of the switch. If the AutoZero bit is 0, the switch is enabled at all times. If the AutoZero bit is 1, the switch is enabled only when the internal PHI2 is high.

FSW0 is used to control a switch in the integrator capacitor path. It connects the output of the op-amp to analog ground.

BSW is used to control switching in the B branch. If disabled, the B capacitor branch is a continuous time branch like the C branch of the SC A Block. If enabled, then on internal PHI1, both ends of the cap are switched to analog ground. On internal PHI2, one end is switched to the B input and the other end is switched to the summing node.

BMuxSCB controls muxing to the input of the B capacitor branch. The B branch can be switched or unswitched.

Table 76: Analog Switch Cap Type B Block xx Control 3 Register

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/Write	RW	RW	RW	RW	RW	RW	RW	RW
Bit Name	ARefMux[1]	ARefMux[0]	FSW[1]	FSW[0]	BSW	BMuxSCB	Power[1]	Power[0]

Bit [7:6]: ARefMux [1:0] Encoding for selecting reference input

0 0 = Analog ground is selected

0 1 = REFHI input selected (This is usually the high reference)

1 0 = REFLO input selected (This is usually the low reference)

1 1 = Reference selection is driven by the comparator (When output comparator node is set high, the input is set to REFHI. When set low, the input is set to REFLO)

Bit 5: FSW1 Bit for controlling gated switches

0 = Switch is disabled

FSW1 bit is set to 1; the state of the switch is determined by the AutoZero bit. If the AutoZero bit is 0, the switch is enabled at all times. If the AutoZero bit is 1, the switch is enabled only when the internal PHI2 is high

Bit 4: FSW0 Bits for controlling gated switches

0 = Switch is disabled

1 = Switch is enabled when PHI1 is high

Bit 3: BSW Enable switching in branch

0 = B branch is a continuous time path

1 = B branch is switched with internal PHI2 sampling

Bit 2: BMuxSCB Encoding for selecting B inputs. (Note that the available mux inputs vary by individual PSoC block)

ASB11 ASB13 ASB20 ASB22

0 = ACA00 ACA02 ASB11 ASB13

1 = ACA01 ACA03 ASA10 ASA12

Bit [1:0]: Power [1:0] Encoding for selecting 1 of 4 power levels

0 0 = Off

0 1 = 10 μ A, typical

1 0 = 50 μ A, typical

1 1 = 200 μ A, typical

Analog Switch Cap Type B Block 11 Control 3 Register (ASB11CR3, Address = Bank 0/1, 87h)

Analog Switch Cap Type B Block 13 Control 3 Register (ASB13CR3, Address = Bank 0/1, 8Fh)

Analog Switch Cap Type B Block 20 Control 3 Register (ASB20CR3, Address = Bank 0/1, 93h)

Analog Switch Cap Type B Block 22 Control 3 Register (ASB22CR3, Address = Bank 0/1, 9Bh)

10.12.3 Analog Output Buffers

The user has the option to output up to four analog signals on the pins of the device. This is done by enabling the analog output buffers associated with each Analog

Column. The enable bits for the analog output buffers are contained in the Analog Output Buffer Control Register (ABF_CR).

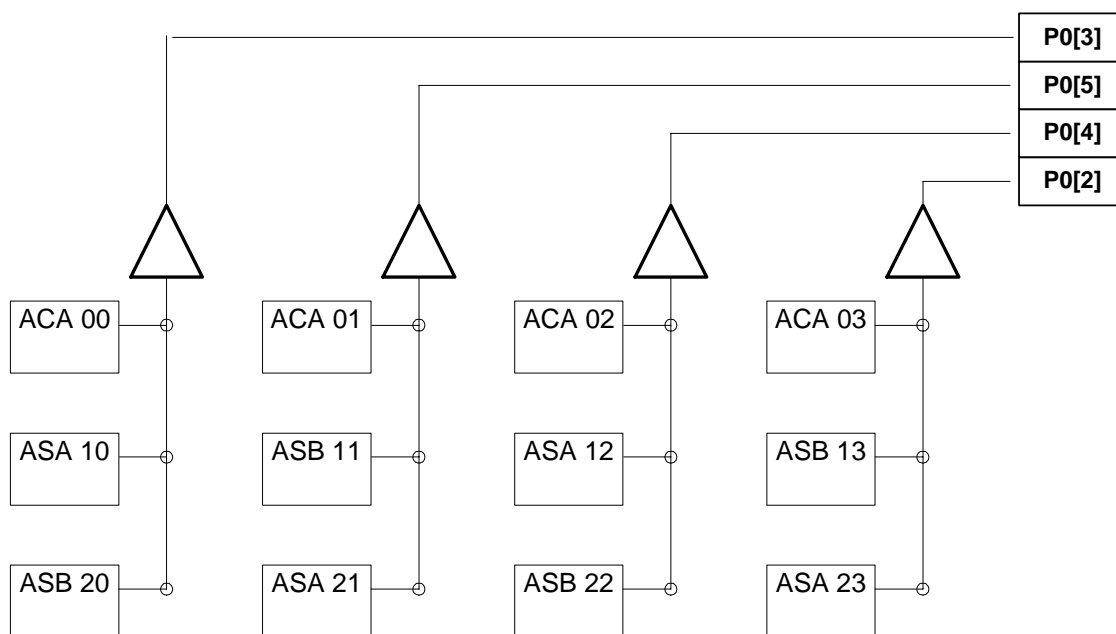


Figure 28: Analog Output Buffers

10.12.4 Analog Output Buffer Control Register

Table 81: Analog Output Buffer Control Register

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/ Write	W	W	W	W	W	W	--	W
Bit Name	ACol1Mux	ACol2Mux	ABUF1EN	ABUF2EN	ABUF0EN	ABUF3EN	Reserved	PWR

Bit 7: ACol1Mux

0 = Set column 1 input to column 1 input mux output
1 = Set column 1 input to column 0 input mux output

Bit 6: ACol2Mux

0 = Set column 2 input to column 2 input mux output
1 = Set column 2 input to column 3 input mux output

Bit 5: ABUF1EN Enables the analog output buffer for Analog Column 1 (Pin P0[5])

0 = Disable analog output buffer
1 = Enable analog output buffer

Bit 4: ABUF2EN Enables the analog output buffer for Analog Column 2 (Pin P0[4])

0 = Disable analog output buffer
1 = Enable analog output buffer

Bit 3: ABUF0EN Enables the analog output buffer for Analog Column 0 (Pin P0[3])

0 = Disable analog output buffer
1 = Enable analog output buffer

Bit 2: ABUF3EN Enables the analog output buffer for Analog Column 3 (Pin P0[2])

0 = Disable analog output buffer
1 = Enable analog output buffer

Bit [1]: Reserved Must be left as 0

Bit [0]: PWR Determines power level of all output buffers

0 = Low output power
1 = High output power

Analog Output Buffer Control Register (ABF_CR, Address = Bank 1, 62h)

10.13 Analog Modulator

The user has the capability to use the Analog Switch Cap Type A PSoC Blocks in Columns 0 and 2 as amplitude modulators. The Analog Modulator Control Register (AMD_CR) allows the user to select the appropriate modulating signal. When the modulating signal is low, the polarity follows the setting of the ASign bit set in the Analog Switch Cap Type A Control 0 Register (ASAxCR0). When this signal is high, the normal gain polarity of the PSoC block is inverted.

interrupt will wake the part from sleep. The Stop bit in the Status and Control Register (CPU_SCR) must be cleared for a part to resume out of sleep.

Any digital PSoC block that is clocked by a System Clock other than the **32K** system-clocking signal or external pins will be stopped, as these clocks do not run in sleep mode.

The Internal Main Oscillator restarts immediately on exiting either the Full Sleep or CPU Sleep modes. Analog functions must be re-enabled by firmware. If the External Crystal Oscillator is used and the internal PLL is enabled, the PLL will take many cycles to change from its initial 2.5% accuracy to track that of the External Crystal Oscillator. If the PLL is enabled, there will be a 30μs (one full **32K** cycle) delay hold-off time for the CPU to let the VCO and PLL stabilize. If the PLL is not enabled, the hold-off time is one half of the **32K** cycle. For further details on PLL, see 7.0.

The Sleep interrupt allows the microcontroller to wake up periodically and poll system components while maintaining very low average power consumption. The sleep interrupt may also be used to provide periodic interrupts during non-sleep modes.

In System Sleep State, GPIO Pins P2[4] and P2[6] should be held to a logic low or a false Low Voltage Detect interrupt may be triggered. The cause is in the System Sleep State, the internal Bandgap reference generator is turned off and the reference voltage is maintained on a capacitor.

The circumstances are that during sleep, the reference voltage on the capacitor is refreshed periodically at the sleep system duty cycle. Between refresh cycles, this voltage may leak slightly to either the positive supply or ground. If pins P2[4] or P2[6] are in a high state, the leakage to the positive supply is accelerated (especially at high temperature). Since the reference voltage is compared to the supply to detect a low voltage condition, this accelerated leakage to the positive supply voltage will cause that voltage to appear lower than it actually is, leading to the generation of a false Low Voltage Detect interrupt.

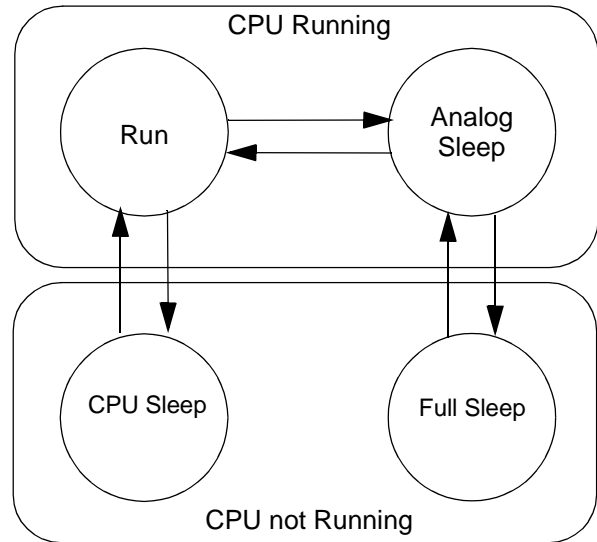


Figure 32: Three Sleep States

13.2 DC Characteristics

Table 104: DC Operating Specifications

Symbol	DC Operating Specifications	Minimum	Typical	Maximum	Unit
V_{CC}	Supply Voltage	3.00	-	5.25	V
I_{CC}	Supply Current	-	5	8 ¹	mA
I_{sb}	Sleep (Mode) Current	-	-	5 ²	μ A
I_{sbxtl}	Sleep (Mode) Current with Crystal Oscillator	-	3	5 ³	μ A
V_{ref}	Reference Voltage (Bandgap)	1.275	1.3	1.325 ⁴	V
V_{il}	Input Low Voltage	-	-	0.8	V
V_{ih}	Input High Voltage	2.2	-	-	V
V_h	Hysteresis Voltage	-	60	-	mV
V_{ol}	Output Low Voltage	-	-	$V_{SS}+0.75$ ⁵	V
V_{oh}	Output High Voltage	$V_{CC}-1.0$ ⁶	-	-	V
R_{pu}	Pull Up Resistor Value	4000	5600	8000	Ω
R_{pd}	Pull Down Resistor Value	4000	5600	8000	Ω
I_{il}	Input Leakage (Absolute Value)	-	0.1	5	μ A
C_{in}	Capacitive Load on Pins as Input	0.5	1.7	10 ⁷	pF
C_{out}	Capacitive Load on Pins as Output	0.5	1.7	10 ⁷	pF
V_{LVD}	LVD and SMP Tolerance ⁸	0.95 x Ideal ⁸	Ideal	1.05 x Ideal ⁸	V

1. Conditions are 5.0V, 25 °C, 3 MHz.
2. Without Crystal Oscillator, $V_{CC} = 3.3$ V, $T_A \leq 85$ °C.
3. Conditions are $3.0V \leq V_{CC} \leq 3.6V$, -40 °C $\leq T_A \leq 85$ °C. Correct operation assumes a properly loaded, 1 μ W maximum drive level, 32.768 kHz crystal.
4. Trimmed for appropriate V_{CC} .
5. $I_{sink} = 25$ mA, $V_{CC} = 4.5$ V (maximum of 8 IO sinking, 4 on each side of the IC).
6. $I_{source} = 10$ mA, $V_{CC} = 4.5$ V (maximum of 8 IO sourcing, 4 on each side of the IC).
7. Package dependent.
8. Ideal values are +/- 5% absolute tolerance and +/- 1% tolerance relative to each other (for adjacent levels).

13.2.2 Analog Input Pin with Multiplexer Specifications

Table 107: DC Analog Input Pin with Multiplexer Specifications

Symbol	DC Analog Input Pin with Multiplexer Specifications	Minimum	Typical	Maximum	Unit
	Input Leakage (Absolute Value)	-	0.1	5	μA
	Input Capacitance	0.5	1.7	8	pF
	Bandwidth	-	10	-	MHz
	Input Voltage Range	0	-	V _{CC}	V

13.2.3 Analog Input Pin to Switch Cap Block Specifications

Table 108: DC Analog Input Pin to SC Block Specifications

Symbol	DC Analog Input Pin to SC Block Specifications	Minimum	Typical	Maximum	Unit
	Effective input resistance = $1/(f \times c)$	-	5 ¹	-	MΩ
	Input Capacitance	0.5	-	10	pF
	Bandwidth	-	-	100 ²	kHz
	Input Voltage Range	0	-	V _{CC}	V

1. Assumes 2 pF cap selected and 100 kHz sample frequency.
2. This is a sampled input. Recommendation is $F_s/F_{in} > 10$ and for $F_s = 1$ MHz $F_{in} < 100$ kHz.

13.2.4 DC Analog Output Buffer Specifications

The following table lists guaranteed maximum and minimum specifications for the voltage and temperature ranges, 5V +/- 5% and -40°C ≤ T_A ≤ 85°C. Typical parameters apply to 5V at 25°C and are for design guidance only. For 3.3V operation, see [Table 110 on page 133](#).

Table 109: 5V DC Analog Output Buffer Specifications

Symbol	5V DC Analog Output Buffer Specifications	Minimum	Typical	Maximum	Unit
	Input Offset Voltage (Absolute Value)	-	3	12	mV
	Average Input Offset Voltage Drift	-	+6	-	μV/°C
	Common-Mode Input Voltage Range	.5	-	V _{CC} - 1.0	V
	Output Resistance				
	Bias = Low	-	1	-	Ω
	Bias = High	-	1	-	Ω
	High Output Voltage Swing (Load = 32 ohms to V _{CC} /2)				
	Bias = Low	.5 x V _{CC} + 1.3	-	-	V
	Bias = High	.5 x V _{CC} + 1.3	-	-	V
	Low Output Voltage Swing (Load = 32 ohms to V _{CC} /2)				
	Bias = Low	-	-	.5 x V _{CC} - 1.3	V
	Bias = High	-	-	.5 x V _{CC} - 1.3	V
	Supply Current Including Bias Cell (No Load)				
	Bias = Low	-	1.1	5.1	mA
	Bias = High	-	2.6	8.8	mA
	Supply Voltage Rejection Ratio	80	-	-	dB

13.2.5 Switch Mode Pump Specifications

Table 111: DC Switch Mode Pump Specifications

Symbol	DC Switch Mode Pump Specifications	Minimum	Typical	Maximum	Unit
	Output Voltage ¹	3.07	-	5.15	V
	Available Output Current $V_i = 1.5\text{ V}$, $V_o = 3.25\text{ V}$ $V_i = 1.5\text{ V}$, $V_o = 5.0\text{ V}$	8 ² 5	- -	- -	mA mA
	Short Circuit Current ($V_i = 3.3\text{ V}$)	-	12	-	mA
	Input Voltage Range (During sustained operation)	1.0	-	3.3	V
	Minimum Input Voltage to Start Pump	1.1	1.2	-	
	Output Voltage Tolerance (Over V_i Range)	-	5	-	% V_o
	Line Regulation (Over V_i Range)	-	5	-	% V_o
	Load Regulation	-	5	-	% V_o
	Output Voltage Ripple (Depends on capacitor and load)	-	25 ³	-	mV _{pp}
	Transient Response 50% Load Change to 5% error envelope V_o Over/Undershoot for 50% Load Change	- -	1 1	- -	μs % V_o
	Efficiency	35 ⁴	50	-	%
	Switching Frequency	-	1.3	-	MHz
	Switching Duty Cycle	-	50	-	%

1. Average, neglecting ripple.
2. For implementation, which includes 2 μH inductor, 1 μF capacitor, and Schottkey diode. Performance is significantly a function of external components. Specifications guaranteed for inductors with series resistance less than 0.1 W, with a current rating of > 250 mA, a capacitor with less than 1 μA leakage at 5V, and Schottkey diode with less than 0.6V of drop at 50 mA.
3. Configuration of note 2. Load is 5 mA.
4. Configuration of note 2. Load is 5 mA. V_{out} is 3.25V.

13.3.1 AC Operational Amplifier Specifications

The following table lists guaranteed maximum and minimum specifications for the voltage and temperature ranges, 5V +/- 5% and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$. Typical parameters are provided for design guidance only. Typical parameters apply to 5V and 25°C . Settling times and slew rates are based on the Analog Switch Cap PSoC

block. The block is configured as an auto zeroed, gain of 0.5, output sampled amplifier. All 32-feedback caps are on, 16 input caps are used (divide by 2), and the output steps of 0.625V. Gain bandwidth is based on Analog Continuous Time PSoC blocks. For 3.3V operation, see [Table 118 on page 140](#).

Table 117: 5V AC Operational Amplifier Specifications

Symbol	5V AC Operational Amplifier Specifications	Minimum	Typical	Maximum	Unit
	Rising Settling Time to 0.1%				
	Bias = Low	-	-	2.7	μs
	Bias = Medium	-	-	1.4	μs
	Bias = High	-	-	0.6	μs
	Falling Settling Time to 0.1%				
	Bias = Low	-	-	1.7	μs
	Bias = Medium	-	-	0.9	μs
	Bias = High	-	-	0.5	μs
	Rising Slew Rate (20% to 80%)				
	Bias = Low	0.4	-	-	V/ μs
	Bias = Medium	0.7	-	-	V/ μs
	Bias = High	2.0	-	-	V/ μs
	Falling Slew Rate (80% to 20%)				
	Bias = Low	0.7	-	-	V/ μs
	Bias = Medium	1.7	-	-	V/ μs
	Bias = High	2.5	-	-	V/ μs
	Gain Bandwidth Product				
	Bias = Low	1.7	-	-	MHz
	Bias = Medium	4.6	-	-	MHz
	Bias = High	8.9	-	-	MHz

13.3.2 AC Analog Output Buffer Specifications

The following table lists guaranteed maximum and minimum specifications for the voltage and temperature ranges, 5V +/- 5% and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$. Typical parameters are provided for design guidance only. Typical parameters apply to 5V and 25°C . For 3.3V operation, see [Table 120 on page 142](#).

Table 119: 5V AC Analog Output Buffer Specifications

Symbol	5V AC Analog Output Buffer Specifications	Minimum	Typical	Maximum	Unit
	Rising Settling Time to 0.1%, 1V Step, 100pF Load Bias = Low	-	-	2.5	μs
	Bias = High	-	-	2.5	μs
	Falling Settling Time to 0.1%, 1V Step, 100pF Load Bias = Low	-	-	2.2	μs
	Bias = High	-	-	2.2	μs
	Rising Slew Rate (20% to 80%), 1V Step, 100pF Load Bias = Low	.9	-	-	V/ μs
	Bias = High	.9	-	-	V/ μs
	Falling Slew Rate (80% to 20%), 1V Step, 100pF Load Bias = Low	.9	-	-	V/ μs
	Bias = High	.9	-	-	V/ μs
	Small Signal Bandwidth, 20mV _{pp} , 3dB BW, 100pF Load Bias = Low	1.5	-	-	MHz
	Bias = High	1.5	-	-	MHz
	Large Signal Bandwidth, 1V _{pp} , 3dB BW, 100pF Load Bias = Low	600	-	-	kHz
	Bias = High	600	-	-	kHz