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#### Details

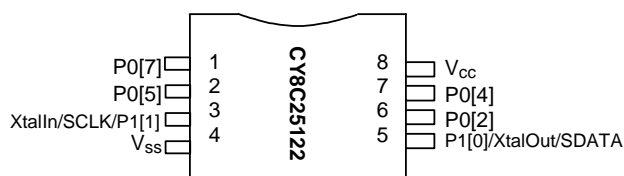
Product Status	Obsolete
Core Processor	M8C
Core Size	8-Bit
Speed	24MHz
Connectivity	SPI, UART/USART
Peripherals	LVD, POR, PWM, WDT
Number of I/O	24
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 5.25V
Data Converters	A/D 1x8b, 1x11b, 1x12b; D/A 1x9b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SOIC (0.295", 7.50mm Width)
Supplier Device Package	28-SOIC
Purchase URL	<a href="https://www.e-xfl.com/product-detail/infineon-technologies/cy8c26443-24sxi">https://www.e-xfl.com/product-detail/infineon-technologies/cy8c26443-24sxi</a>

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## 1.2 Pin-out Descriptions

**Table 2: Pin-out 8 Pin**

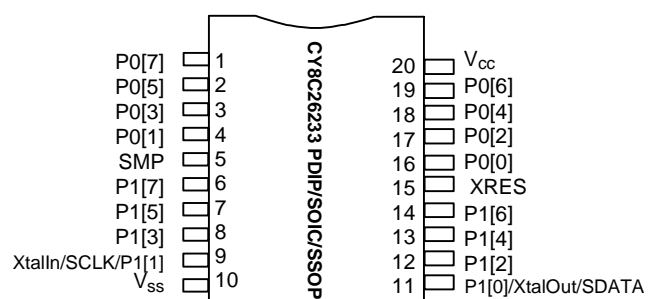
Name	I/O	Pin	Description
P0[7]	I/O	1	Port 0[7] (Analog Input)
P0[5]	I/O	2	Port 0[5] (Analog Input/Output)
P1[1]	I/O	3	Port 1[1] / XtalIn / SCLK
Vss	Power	4	Ground
P1[0]	I/O	5	Port 1[0] / XtalOut / SDATA
P0[2]	I/O	6	Port 0[2] (Analog Input/Output)
P0[4]	I/O	7	Port 0[4] (Analog Input/Output)
Vcc	Power	8	Supply Voltage



**Figure 2: CY8C25122**

**Table 3: Pin-out 20 Pin**

Name	I/O	Pin	Description
P0[7]	I/O	1	Port 0[7] (Analog Input)
P0[5]	I/O	2	Port 0[5] (Analog Input/Output)
P0[3]	I/O	3	Port 0[3] (Analog Input/Output)
P0[1]	I/O	4	Port 0[1] (Analog Input)
SMP	O	5	Switch Mode Pump
P1[7]	I/O	6	Port 1[7]
P1[5]	I/O	7	Port 1[5]
P1[3]	I/O	8	Port 1[3]
P1[1]	I/O	9	Port 1[1] / XtalIn / SCLK
Vss	Power	10	Ground
P1[0]	I/O	11	Port 1[0] / XtalOut / SDATA
P1[2]	I/O	12	Port 1[2]
P1[4]	I/O	13	Port 1[4]
P1[6]	I/O	14	Port 1[6]
XRES	I	15	External Reset
P0[0]	I/O	16	Port 0[0] (Analog Input)
P0[2]	I/O	17	Port 0[2] (Analog Input/Output)
P0[4]	I/O	18	Port 0[4] (Analog Input/Output)
P0[6]	I/O	19	Port 0[6] (Analog Input)
Vcc	Power	20	Supply Voltage



**Figure 3: CY8C26233**

**Examples:**

```

;In this case, the immediate
;value of 7 is added with the
ADD  A,  7 ;Accumulator, and the result
;is placed in the
;Accumulator.

;In this case, the immediate
;value of 8 is moved to the X
MOV  X,  8 ;register.

;In this case, the immediate
;value of 9 is logically
AND  F,  9 ;ANDed with the F register
;and the result is placed in
;the F register.

```

**2.3.2 Source Direct**

The result of an instruction using this addressing mode is placed in either the A register or the X register, which is specified as part of the instruction opcode. Operand 1 is an address that points to a location in either the RAM memory space or the register space that is the source for the instruction. Arithmetic instructions require two sources, the second source is the A register or X register specified in the opcode. Instructions using this addressing mode are two bytes in length.

**Table 14: Source Direct**

Opcode	Operand 1
Instruction	Source Address

**Examples:**

```

;In this case, the
;value in the RAM
;memory location at
;address 7 is added
;with the Accumulator,
;and the result is
;placed in the
;Accumulator.
ADD  A,  [7]

;In this case, the
;value in the register
;space at address 8 is
;moved to the X
;register.
MOV  X,  REG[8]

```

**2.3.3 Source Indexed**

The result of an instruction using this addressing mode is placed in either the A register or the X register, which is specified as part of the instruction opcode. Operand 1 is

added to the X register forming an address that points to a location in either the RAM memory space or the register space that is the source for the instruction. Arithmetic instructions require two sources, the second source is the A register or X register specified in the opcode. Instructions using this addressing mode are two bytes.

**Table 15: Source Indexed**

Opcode	Operand 1
Instruction	Source Index

**Examples:**

```

;In this case, the
;value in the memory
;location at address
;X + 7 is added with
;the Accumulator, and
;the result is placed
;in the Accumulator.
ADD  A,  [X+7]

;In this case, the
;value in the
;register space at
;address X + 8 is
;moved to the X
;register.
MOV  X,  REG[X+8]

```

**2.3.4 Destination Direct**

The result of an instruction using this addressing mode is placed within either the RAM memory space or the register space. Operand 1 is an address that points to the location of the result. The source for the instruction is either the A register or the X register, which is specified as part of the instruction opcode. Arithmetic instructions require two sources, the second source is the location specified by Operand 1. Instructions using this addressing mode are two bytes in length.

**Table 16: Destination Direct**

Opcode	Operand 1
Instruction	Destination Address

## 4.2 Register Bank 0 Map

Table 26: Bank 0

Register Name	Address	Data Sheet Page	Access	Register Name	Address	Data Sheet Page	Access	Register Name	Address	Data Sheet Page	Access	Register Name	Address	Data Sheet Page	Access
PRT0DR	00h	31	RW	Reserved	40h			ASA10CR0	80h	88	RW	Reserved	C0h		
PRT0IE	01h	31	W		41h			ASA10CR1	81h	90	RW		C1h		
PRT0GS	02h	32	W		42h			ASA10CR2	82h	92	RW		C2h		
Reserved	03h				43h			ASA10CR3	83h	93	RW		C3h		
PRT1DR	04h	31	RW		44h			ASB11CR0	84h	95	RW		C4h		
PRT1IE	05h	31	W		45h			ASB11CR1	85h	97	RW		C5h		
PRT1GS	06h	32	W		46h			ASB11CR2	86h	99	RW		C6h		
Reserved	07h				47h			ASB11CR3	87h	100	RW		C7h		
PRT2DR	08h	31	RW		48h			ASA12CR0	88h	88	RW		C8h		
PRT2IE	09h	31	W		49h			ASA12CR1	89h	90	RW		C9h		
PRT2GS	0Ah	32	W		4Ah			ASA12CR2	8Ah	92	RW		CAh		
Reserved	0Bh				4Bh			ASA12CR3	8Bh	93	RW		CBh		
PRT3DR	0Ch	31	RW		4Ch			ASB13CR0	8Ch	95	RW		CCh		
PRT3IE	0Dh	31	W		4Dh			ASB13CR1	8Dh	97	RW		CDh		
PRT3GS	0Eh	32	W		4Eh			ASB13CR2	8Eh	99	RW		CEh		
Reserved	0Fh				4Fh			ASB13CR3	8Fh	100	RW		CFh		
PRT4DR	10h	31	RW		50h			ASB20CR0	90h	95	RW		D0h		
PRT4IE	11h	31	W		51h			ASB20CR1	91h	97	RW		D1h		
PRT4GS	12h	32	W		52h			ASB20CR2	92h	99	RW		D2h		
Reserved	13h				53h			ASB20CR3	93h	100	RW		D3h		
PRT5DR	14h	31	RW		54h			ASA21CR0	94h	88	RW		D4h		
PRT5IE	15h	31	W		55h			ASA21CR1	95h	90	RW		D5h		
PRT5GS	16h	32	W		56h			ASA21CR2	96h	92	RW		D6h		
Reserved	17h				57h			ASA21CR3	97h	93	RW		D7h		
	18h				58h			ASB22CR0	98h	95	RW		D8h		
	19h				59h			ASB22CR1	99h	97	RW		D9h		
	1Ah				5Ah			ASB22CR2	9Ah	99	RW		DAh		
	1Bh				5Bh			ASB22CR3	9Bh	100	RW		DBh		
	1Ch				5Ch			ASA23CR0	9Ch	88	RW		DCh		
	1Dh				5Dh			ASA23CR1	9Dh	90	RW		DDh		
Reserved	1Eh				5Eh			ASA23CR2	9Eh	92	RW	Reserved	DEh		
	1Fh				5Fh			ASA23CR3	9Fh	93	RW		DFh		
DBA00DR0	20h	54	1	AMX_IN	60h	104	RW	Reserved	A0h			INT_MSK0	E0h	45	RW
DBA00DR1	21h	54	1	Reserved	61h				A1h			INT_MSK1	E1h	46	RW
DBA00DR2	22h	54	1		62h				A2h			INT_VC	E2h	46	RW
DBA00CR0	23h	55	1	ARF_CR	63h	73	RW		A3h			RES_WDT	E3h	116	RW
DBA01DR0	24h	54	1	CMP_CR	64h	101	1		A4h			DEC_DH/DEC_CL	E4h	113	RW
DBA01DR1	25h	54	1	ASY_CR	65h	102	1		A5h			DEC_DL	E5h	113	R
DBA01DR2	26h	54	1	Reserved	66h				A6h			DEC_CR	E6h	113	RW
DBA01CR0	27h	55	1		67h				A7h			Reserved	E7h		
DBA02DR0	28h	54	1		68h				A8h			MUL_X	E8h	110	W
DBA02DR1	29h	54	1		69h				A9h			MUL_Y	E9h	110	W
DBA02DR2	2Ah	54	1		6Ah				AAh			MUL_DH	EAh	111	R
DBA02CR0	2Bh	55	1		6Bh				ABh			MUL_DL	EBh	111	R
DBA03DR0	2Ch	54	1		6Ch				ACH			ACC_DR1/MAC_X	ECh	111	RW
DBA03DR1	2Dh	54	1		6Dh				ADh			ACC_DR0/MAC_Y	EDh	111	RW
DBA03DR2	2Eh	54	1		6Eh				AEh			ACC_DR3/MAC_CL0	EEh	112	RW
DBA03CR0	2Fh	55	1		6Fh				AFh			ACC_DR2/MAC_CL1	EFh	112	RW
DCA04DR0	30h	54	1		70h				B0h			Reserved	F0h		
DCA04DR1	31h	54	1	ACA00CR0	71h	82	RW		B1h				F1h		
DCA04DR2	32h	54	1	ACA00CR1	72h	83	RW		B2h				F2h		
DCA04CR0	33h	55	1	ACA00CR2	73h	84	RW		B3h				F3h		
DCA05DR0	34h	54	1	Reserved	74h				B4h				F4h		
DCA05DR1	35h	54	1	ACA01CR0	75h	82	RW		B5h				F5h		
DCA05DR2	36h	54	1	ACA01CR1	76h	83	RW		B6h				F6h		
DCA05CR0	37h	55	1	ACA01CR2	77h	84	RW		B7h				F7h		
DCA06DR0	38h	54	1	Reserved	78h				B8h				F8h		
DCA06DR1	39h	54	1	ACA02CR0	79h	82	RW		B9h				F9h		
DCA06DR2	3Ah	54	1	ACA02CR1	7Ah	83	RW		BAh				FAh		
DCA06CR0	3Bh	55	1	ACA02CR2	7Bh	84	RW		BBh				FBh		
DCA07DR0	3Ch	54	1	Reserved	7Ch				BCh				FCh		
DCA07DR1	3Dh	54	1	ACA03CR0	7Dh	82	RW		BDh				FDh		
DCA07DR2	3Eh	54	1	ACA03CR1	7Eh	83	RW		BEh				FEh		
DCA07CR0	3Fh	55	1	ACA03CR2	7Fh	84	RW		BFh			CPU_SCR	FFh	114	1

### 4.3 Register Bank 1 Map

Table 27: Bank 1

Access	Data Sheet Page	Address	Register Name	Access	Data Sheet Page	Address	Register Name	Access	Data Sheet Page	Address	Register Name	Access	Data Sheet Page	Address	Register Name				
			Reserved				Reserved				Reserved				Reserved				

1. Read/Write access is bit-specific or varies by function. See register.



**Table 47: Digital Basic Type A/ Communications Type A Block xx Function Register**

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/Write	RW	RW	RW	RW	RW	RW	RW	RW
Bit Name	Reserved	Reserved	End	Mode 1	Mode 0	Function [2]	Function [1]	Function [0]
<p><b>Bit 7: Reserved</b>  <b>Bit 6: Reserved</b></p> <p><b>Bit 5: End</b>  0 = PSoc block is not the end of a chained function (End should not be set to 0 in block DCA07)  1 = PSoc block is the end of a chained function, or is an unchained PSoc block</p> <p><b>Bit 4: Mode 1</b> The definition of the Mode [1] bit depends on the block function selected  Timer: The Mode [1] bit signifies the Compare Type  0 = Less Than or Equal  1 = Less Than  Counter: The Mode [1] bit signifies the Compare Type  0 = Less Than or Equal  1 = Less Than  CRC/PRS: The Mode [1] bit is unused in this function  Deadband: The Mode [1] bit is unused in this function  UART: The Mode[1] bit signifies the Interrupt Type (Transmitter only)  0 = Transmit: Interrupt on TX_Reg Empty  1 = Transmit: Interrupt on TX Complete  SPI: The Mode[1] bit signifies the Interrupt Type  0 = Master: Interrupt on TX Reg Empty, Slave: Interrupt on RX Reg Full  1 = Master: Interrupt on SPI Complete, Slave: Interrupt on SPI Complete</p> <p><b>Bit 3: Mode 0</b> The definition of the Mode [0] bit depends on the block function selected  Timer: The Mode [0] bit signifies Interrupt Type  0 = Terminal Count  1 = Compare True  Counter: The Mode [0] bit signifies Interrupt Type  0 = Terminal Count  1 = Compare True  CRC/PRS: The Mode [0] bit is unused in this function  Deadband: The Mode [0] bit is unused in this function  UART: The Mode [0] bit signifies the Direction  0 = Receive  1 = Transmit  SPI: The Mode [0] bit signifies the Type  0 = Master  1 = Slave</p> <p><b>Bit [2:0]: Function [2:0]</b> The Function [2:0] bits select the block function which determines the basic hardware configuration  0 0 0 = Timer (chainable)  0 0 1 = Counter (chainable)  0 1 0 = CRC/PRS (Cyclical Redundancy Checker or Pseudo Random Sequencer) (chainable)  0 1 1 = Reserved  1 0 0 = Deadband for Pulse Width Modulator  1 0 1 = UART (function only available on DCA type blocks)  1 1 0 = SPI (function only available on DCA type blocks)  1 1 1 = Reserved</p>								

Digital Basic Type A Block 00 Function Register	(DBA00FN, Address = Bank 1, 20h)
Digital Basic Type A Block 01 Function Register	(DBA01FN, Address = Bank 1, 24h)
Digital Basic Type A Block 02 Function Register	(DBA02FN, Address = Bank 1, 28h)
Digital Basic Type A Block 03 Function Register	(DBA03FN, Address = Bank 1, 2Ch)
Digital Communications Type A Block 04 Function Register	(DCA04FN, Address = Bank 1, 30h)

Digital Communications Type A Block 05 Function Register (DCA05FN, Address = Bank 1, 34h)  
 Digital Communications Type A Block 06 Function Register (DCA06FN, Address = Bank 1, 38h)  
 Digital Communications Type A Block 07 Function Register (DCA07FN, Address = Bank 1, 3Ch)

## 9.2.2 Digital Basic Type A / Communications Type A Block xx Input Register

The Digital Basic Type A / Communications Type A Block xx Input Register (DBA00IN-DCA07IN) consists of 4 bits [3:0] to select the block input clock and 4 bits [7:4] to select the primary data/enable input. The actual usage of the input data/enable is function dependent.

**Table 48: Digital Basic Type A / Communications Type A Block xx Input Register**

Bit #	7	6	5	4	3	2	1	0
<b>POR</b>	0	0	0	0	0	0	0	0
<b>Read/Write</b>	RW	RW	RW	RW	RW	RW	RW	RW
<b>Bit Name</b>	Data [3]	Data [2]	Data [1]	Data [0]	Clock [3]	Clock [2]	Clock [1]	Clock [0]
<p><b>Bit [7:4]: Data [3:0] Data Enable Source Select</b>            0 0 0 0 = Data = 0            0 0 0 1 = Data = 1            0 0 1 0 = Digital Block 03            0 0 1 1 = Chain Function to Previous Block            0 1 0 0 = Analog Column Comparator 0            0 1 0 1 = Analog Column Comparator 1            0 1 1 0 = Analog Column Comparator 2            0 1 1 1 = Analog Column Comparator 3            1 0 0 0 = Global Output[0] (for Digital Blocks 00 to 03) <b>or</b> Global Output[4] (for Digital Blocks 04 to 07)            1 0 0 1 = Global Output[1] (for Digital Blocks 00 to 03) <b>or</b> Global Output[5] (for Digital Blocks 04 to 07)            1 0 1 0 = Global Output[2] (for Digital Blocks 00 to 03) <b>or</b> Global Output[6] (for Digital Blocks 04 to 07)            1 0 1 1 = Global Output[3] (for Digital Blocks 00 to 03) <b>or</b> Global Output[7] (for Digital Blocks 04 to 07)            1 1 0 0 = Global Input[0] (for Digital Blocks 00 to 03) <b>or</b> Global Input[4] (for Digital Blocks 04 to 07)            1 1 0 1 = Global Input[1] (for Digital Blocks 00 to 03) <b>or</b> Global Input[5] (for Digital Blocks 04 to 07)            1 1 1 0 = Global Input[2] (for Digital Blocks 00 to 03) <b>or</b> Global Input[6] (for Digital Blocks 04 to 07)            1 1 1 1 = Global Input[3] (for Digital Blocks 00 to 03) <b>or</b> Global Input[7] (for Digital Blocks 04 to 07)</p> <p><b>Bit [3:0]: Clock [3:0] Clock Source Select</b>            0 0 0 0 = Clock Disabled            0 0 0 1 = Global Output[4] (for Digital Blocks 00 to 03) <b>or</b> Global Output[0] (for Digital Blocks 04 to 07)            0 0 1 0 = Digital Block 03 (Primary Output)            0 0 1 1 = Previous Digital PSoC block (Primary Output)            0 1 0 0 = 48M            0 1 0 1 = 24V1            0 1 1 0 = 24V2            0 1 1 1 = 32k            1 0 0 0 = Global Output[0] (for Digital Blocks 00 to 03) <b>or</b> Global Output[4] (for Digital Blocks 04 to 07)            1 0 0 1 = Global Output[1] (for Digital Blocks 00 to 03) <b>or</b> Global Output[5] (for Digital Blocks 04 to 07)            1 0 1 0 = Global Output[2] (for Digital Blocks 00 to 03) <b>or</b> Global Output[6] (for Digital Blocks 04 to 07)            1 0 1 1 = Global Output[3] (for Digital Blocks 00 to 03) <b>or</b> Global Output[7] (for Digital Blocks 04 to 07)            1 1 0 0 = Global Input[0] (for Digital Blocks 00 to 03) <b>or</b> Global Input[4] (for Digital Blocks 04 to 07)            1 1 0 1 = Global Input[1] (for Digital Blocks 00 to 03) <b>or</b> Global Input[5] (for Digital Blocks 04 to 07)            1 1 1 0 = Global Input[2] (for Digital Blocks 00 to 03) <b>or</b> Global Input[6] (for Digital Blocks 04 to 07)            1 1 1 1 = Global Input[3] (for Digital Blocks 00 to 03) <b>or</b> Global Input[7] (for Digital Blocks 04 to 07)</p>								

Digital Basic Type A Block 00 Input Register (DBA00IN, Address = Bank 1, 21h)  
 Digital Basic Type A Block 01 Input Register (DBA01IN, Address = Bank 1, 25h)  
 Digital Basic Type A Block 02 Input Register (DBA02IN, Address = Bank 1, 29h)  
 Digital Basic Type A Block 03 Input Register (DBA03IN, Address = Bank 1, 2Dh)  
 Digital Communications Type A Block 04 Input Register (DCA04IN, Address = Bank 1, 31h)  
 Digital Communications Type A Block 05 Input Register (DCA05IN, Address = Bank 1, 35h)



Digital Communications Type A Block 06 Input Register  
Digital Communications Type A Block 07 Input Register

(DCA06IN, Address = Bank 1, 39h)  
(DCA07IN, Address = Bank 1, 3Dh)

The Data/Enable source select [3:0] bits select between multiple inputs to the Digital PSoC Blocks. These inputs serve as Clock Enables or Data Input depending on the Digital PSoC Block's programmed function. If "Chain Function to Previous" data input is selected for Data/Enable then the selected Digital PSoC block receives its Data, Enable, Zero Detect, and all chaining information from the previous digital PSoC block. The data inputs that are selected from the GPIO pins (through the Global Input Bus) are synchronized to the 24 MHz clock. The following table shows the function dependent meaning of the data input.

**Table 49: Digital Function Data Input Definitions**

Function	Data Input
Timer	Positive Edge Capture
Counter	Count Enable (Active High)
CRC	Data Input
PRS	N/A
Deadband	Kill Signal (Active High)
TX UART	N/A
RX UART	RX Data In
SPI Master	MISO (Master In/Slave Out)
SPI Slave	MOSI (Master Out/Slave In)

The Clock[3:0] bits select multiple sources for the clock for each digital PSoC block. The sources for each digital PSoC block clock are selected from the Global Input Bus, System Clocks, and other neighboring digital PSoC blocks. As shown in the table, Digital PSoC Blocks 0-3 can interface to Global I/Os 00-03, and Digital PSoC block 04-07 can interface to Global I/Os 4-7. It is important to note that clock inputs selected from the GPIO pins (through the Global Input Bus) are not synchronized. This may cause indeterminate results if the CPU reads a block register as it is changing in response to an external clock. CPU reads must be manually synchronized, either through the block interrupt, or through a multiple read and voting scheme.

### 9.2.3 Digital Basic Type A / Communications Type A Block xx Output Register

The digital PSoC block's outputs can be selected to drive associated Global Output Bus signals via the Output Select bits. In addition, the output drive can be selectively enabled in this register. The SPI Slave has an auxiliary input which is also controlled by selections in this register.

**Table 62: AGND, RefHI, RefLO Operating Parameters**

	AGND		RefHI		RefLO		Notes
	Source	Voltage	Source	Voltage	Source	Voltage	
000	$V_{cc}/2$	2.5 V 1.65 V	$V_{cc}+V_{bg}$	3.8 V 2.95 V	$V_{cc}-V_{bg}$	1.2 V 0.35 V	5.0 V System 3.3 V System
001	P2[4]	2.2 V <sup>1</sup>	P2[4]+P2[6]	3.2 V <sup>1</sup>	P2[4]-P2[6]	1.2 V <sup>1</sup>	User Adjustable
010	$V_{cc}/2$	2.5 V 1.65 V	$V_{cc}$	5.0 V 3.3 V	$V_{ss}$	0.0 V 0.0 V	5.0 V System 3.3 V System
011	2* $V_{bg}$	2.6 V	2* $V_{bg}+V_{bg}$	3.9 V	2* $V_{bg}-V_{bg}$	1.3 V	Not for 3.3 V Systems
100	2* $V_{bg}$	2.6 V	2* $V_{bg}+P2[6]$	3.6 V <sup>1</sup>	2* $V_{bg}-P2[6]$	1.6 V <sup>1</sup>	Not for 3.3 V Systems
101	P2[4]	2.2 V <sup>1</sup>	P2[4]+ $V_{bg}$	3.5 V <sup>1</sup>	P2[4]- $V_{bg}$	0.9 V <sup>1</sup>	User Adjustable
110	Reserved						
111	Reserved						

1. Example shown for AGND P2[4] = 2.2 V and Ref P2[6] = 1.0 V

#### 10.4.4 Analog Array Power Control

**PWR** Sets Analog Array Power Control. Analog array power is controlled through the bias circuits in the Continuous Time blocks and separate bias circuits in the Switched Capacitor blocks. Continuous Time blocks (ACAxx) can be operated to make low power comparators independent of Switched Capacitor (ASAxx and ASBxx) blocks, without their power consumption.

The reference array supplies voltage to all blocks and current to the Switched Capacitor blocks. At higher block clock rates, there is increased reference current demand; the reference power should be set equal to the highest power level of the analog blocks used.

## 10.5 Analog PSoC Block Clocking Options

All analog PSoC blocks in a particular Analog Column share the same clock signal. Choosing the clocking for an analog PSoC block is a two-step process.

1. First, if the user wants to use the **ACLK0** and **ACLK1** system-clocking signals, the digital PSoC blocks that serve as the source for these signals must be selected. This selection is made in the Analog Clock Select Register (CLK\_CR1).
2. Next, the user must select the source for the **Acolumn0**, **Acolumn1**, **Acolumn2**, and **Acolumn3** system-clocking signals. The user will choose the clock for Acolumnx[1:0] bits in the Analog Column Clock Select Register (CLK\_CR0). Each analog PSoC block in a particular Analog Column is clocked from the **Acolumn[x]** system-clocking signal for that column. (Note that the Acolumn[x] signals have a 1:4 divider on them.)

### 10.5.1 Analog Column Clock Select Register

**Table 64: Analog Column Clock Select Register**

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/Write	RW	RW	RW	RW	RW	RW	RW	RW
Bit Name	Acolumn3 [1]	Acolumn3 [0]	Acolumn2 [1]	Acolumn2 [0]	Acolumn1 [1]	Acolumn1 [0]	Acolumn0 [1]	Acolumn0 [0]
<p><b>Bit [7:6]: Acolumn3 [1:0]</b>            0 0 = 24V1            0 1 = 24V2            1 0 = ACLK0            1 1 = ACLK1</p> <p><b>Bit [5:4]: Acolumn2 [1:0]</b>            0 0 = 24V1            0 1 = 24V2            1 0 = ACLK0            1 1 = ACLK1</p> <p><b>Bit [3:2]: Acolumn1 [1:0]</b>            0 0 = 24V1            0 1 = 24V2            1 0 = ACLK0            1 1 = ACLK1</p> <p><b>Bit [1:0]: Acolumn0 [1:0]</b>            0 0 = 24V1            0 1 = 24V2            1 0 = ACLK0            1 1 = ACLK1</p>								

Analog Column Clock Select Register (CLK\_CR0, Address = Bank 1, 60h)

### 10.7.2.2 Analog Continuous Time Block xx Control 1 Register

The PMux bits control the multiplexing of inputs to the non-inverting input of the op-amp. There are physically only 7 inputs.

The 8<sup>th</sup> code (111) will leave the input floating. This is not desirable, and should be avoided.

The NMux bits control the multiplexing of inputs to the inverting input of the op-amp. There are physically only 7 inputs.

CompBus controls a tri-state buffer that drives the comparator logic. If no PSoC block in the analog column is driving the comparator bus, it will be driven low externally to the blocks.

AnalogBus controls the analog output bus. A CMOS switch connects the op-amp output to the analog bus.

**Table 67: Analog Continuous Time Block xx Control 1 Register**

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/Write	RW	RW	RW	RW	RW	RW	RW	RW
Bit Name	AnalogBus	CompBus	NMux2	NMux1	NMux0	PMux2	PMux1	PMux0

**Bit 7: AnalogBus** Enable output to the analog bus  
0 = Disable analog bus driven by this block  
1 = Enable analog bus driven by this block

**Bit 6: CompBus** Enable output to the comparator bus  
0 = Disable comparator bus driven by this block  
1 = Enable comparator bus driven by this block

**Bit [5:3]: NMux [2:0]** Encoding for negative input select

	<u>ACA00</u>	<u>ACA01</u>	<u>ACA02</u>	<u>ACA03</u>
0 0 0 =	ACA01	ACA00	ACA03	ACA02
0 0 1 =	AGND	AGND	AGND	AGND
0 1 0 =	REFLO	REFLO	REFLO	REFLO
0 1 1 =	REFHI	REFHI	REFHI	REFHI
1 0 0 <sup>1</sup> =	ACA00	ACA01	ACA02	ACA03
1 0 1 =	ASA10	ASB11	ASA12	ASB13
1 1 0 =	ASB11	ASA10	ASB13	ASA12
1 1 1 =	Reserved	Reserved	Reserved	Reserved

**Bit [2:0]: PMux [2:0]** Encoding for positive input select

	<u>ACA00</u>	<u>ACA01</u>	<u>ACA02</u>	<u>ACA03</u>
0 0 0 =	REFLO	ACA02	ACA01	REFLO
0 0 1 =	Port Inputs	Port Inputs	Port Inputs	Port Inputs
0 1 0 =	ACA01	ACA00	ACA03	ACA02
0 1 1 =	AGND	AGND	AGND	AGND
1 0 0 =	ASA10	ASB11	ASA12	ASB13
1 0 1 =	ASB11	ASA10	ASB13	ASA12
1 1 0 =	ABUS0	ABUS1	ABUS2	ABUS3
1 1 1 =	Reserved	Reserved	Reserved	Reserved

1. This in fact is the feedback input of the MUX.

Analog Continuous Time Block 00 Control 1 Register (ACA00CR1, Address = Bank 0/1, 72h)  
Analog Continuous Time Block 01 Control 1 Register (ACA01CR1, Address = Bank 0/1, 76h)  
Analog Continuous Time Block 02 Control 1 Register (ACA02CR1, Address = Bank 0/1, 7Ah)  
Analog Continuous Time Block 03 Control 1 Register (ACA03CR1, Address = Bank 0/1, 7Eh)

## 10.9 Analog Switch Cap Type B PSoC Blocks

### 10.9.1 Introduction

The Analog Switch Cap Type B PSoC blocks are built around an operational amplifier. There are several analog muxes that are controlled by register-bit settings in the control registers that determine the signal topology inside the block. There are also four arrays of unit value capacitors that are located in the feedback path for the op-amp, and are switched by two phase clocks, PHI1 and PHI2. These four capacitor arrays are labeled A Cap Array, B Cap Array, C Cap Array, and F Cap Array. There is also an analog comparator connected to the output OUT, which converts analog comparisons into digital signals.

There are three discrete outputs from this block. These outputs are:

1. The analog output bus (ABUS), which is an analog bus resource that is shared by all of the analog blocks in the analog column for that block.
2. The comparator bus (CBUS), which is a digital bus that is a resource that is shared by all of the analog blocks in a column for that block.
3. The output bus (OUT), which is an analog bus resource that is shared by all of the analog blocks in a column and connects to one of the analog output buffers, to send a signal externally to the device.

The SCB block also supports Delta-Sigma, Successive Approximation and Incremental A/D Conversion, Capacitor DACs, and SC filters. It has two input arrays of switched capacitors, and a Non-Switched capacitor feedback array from the output. When preceded by an SC Block A Integrator, the combination can be used to provide a full Switched Capacitor Biquad.

## 10.10 Analog Comparator Bus

Each analog column has a dedicated comparator bus associated with it. Every analog PSoC block has a comparator output that can drive out on this bus, but the comparator output from only one analog block in a column can be actively driving the comparator bus for that column at any one time. The output on the comparator bus can drive into the digital blocks, and is also available to be read in the Analog Comparator Control Register (CMP\_CR, Address = Bank 0,64H).

The comparator bus is latched before it is available to either drive the digital blocks, or be read in the Analog Comparator Control Register. The latch for each comparator bus is transparent (the output tracks the input) during the high period of PHI2. During the low period of PHI2 the latch retains the value on the comparator bus during the high to low transition of PHI2.

The output from the analog block that is actively driving the bus may also be latched internal to the analog block itself.

In the Continuous Time analog blocks, the CPhase and CLatch bits inside the Analog Continuous Time Type A Block xx Control Register 2 determine whether the output signal on the comparator bus is latched inside the block, and if it is, which clock phase it is latched on.

In the Switched Capacitor analog blocks, the output on the comparator bus is always latched. The ClockPhase bit in the Analog SwitchCap Type A Block xx Control Register 0 or the Analog SwitchCap Type B Block xx Control Register 0 determines the phase on which this data is latched and available.

**Table 77: Analog Comparator Control Register**

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/Write	R	R	R	R	RW	RW	RW	RW
Bit Name	COMP 3	COMP 2	COMP 1	COMP 0	AINT 3	AINT 2	AINT 1	AINT 0
<p>Bit 7: COMP 3 COMP 3 bit [0] indicates the state of the analog comparator bus for the Analog Column x</p> <p>Bit 6: COMP 2 COMP 2 bit [0] indicates the state of the analog comparator bus for the Analog Column x</p> <p>Bit 5: COMP 1 COMP 1 bit [0] indicates the state of the analog comparator bus for the Analog Column x</p> <p>Bit 4: COMP 0 COMP 0 bit [0] indicates the state of the analog comparator bus for the Analog Column x</p> <p>Bit 3: AINT 3 AINT 3 bit [0] or [1] (as defined below) selects the Analog Interrupt Source for the Analog Column x</p> <p>Bit 2: AINT 2 AINT 2 bit [0] or [1] (as defined below) selects the Analog Interrupt Source for the Analog Column x</p> <p>Bit 1: AINT 1 AINT 1 bit [0] or [1] (as defined below) selects the Analog Interrupt Source for the Analog Column x</p> <p>Bit 0: AINT 0 AINT 0 bit [0] or [1] (as defined below) selects the Analog Interrupt Source for the Analog Column x</p> <p>0 = Comparator bus</p> <p>1 = PHI2 (Falling edge of PHI2 causes an interrupt)</p>								

Analog Comparator Control Register (CMP\_CR, Address = Bank 0, 64h)

## 10.11 Analog Synchronization

For high precision analog operation, it may be necessary to precisely time when updated register values are available to the analog PSOC blocks. The optimum time to update values in Switch Cap registers is at the beginning of the PHI1 active period. The SYNCEN bit in the Analog Synchronization Control Register is designed to address this. (The AINT bits of the Analog Comparator Register

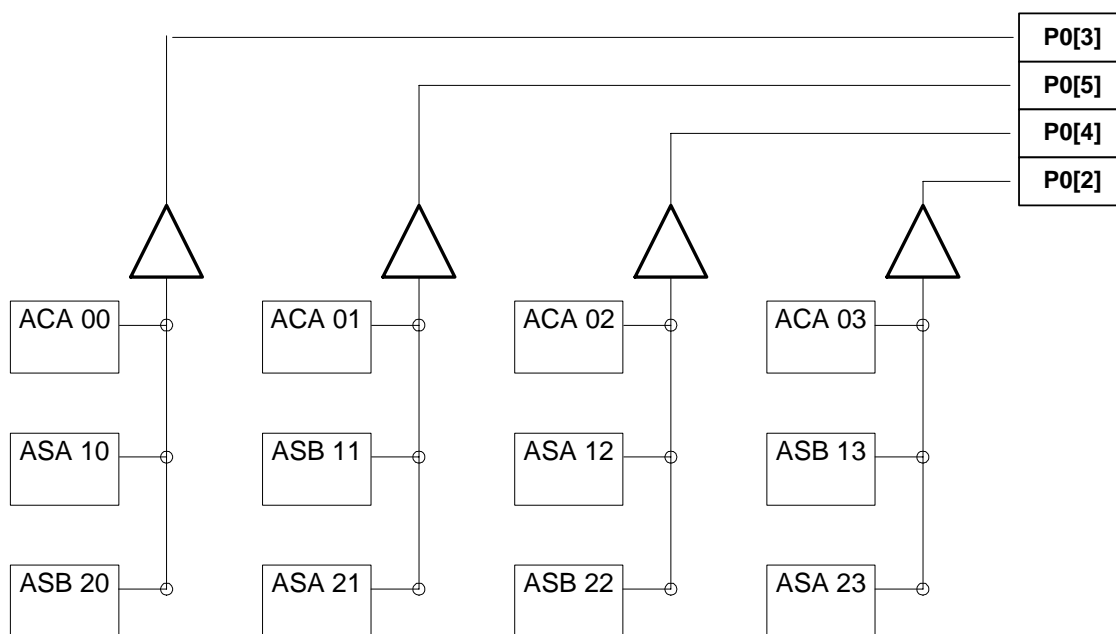
(CMP\_CR) are another way to address it with interrupts.) When the SYNCEN bit is set, a subsequent write instruction to any register in a Switch Cap block will cause the CPU to stall until the rising edge of PHI1. This mode is in effect until the SYNCEN bit is cleared.



### 10.12.3 Analog Output Buffers

The user has the option to output up to four analog signals on the pins of the device. This is done by enabling the analog output buffers associated with each Analog

Column. The enable bits for the analog output buffers are contained in the Analog Output Buffer Control Register (ABF\_CR).



**Figure 28: Analog Output Buffers**

### 10.12.4 Analog Output Buffer Control Register

**Table 81: Analog Output Buffer Control Register**

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/ Write	W	W	W	W	W	W	--	W
Bit Name	ACol1Mux	ACol2Mux	ABUF1EN	ABUF2EN	ABUF0EN	ABUF3EN	Reserved	PWR

**Bit 7: ACol1Mux**

0 = Set column 1 input to column 1 input mux output

1 = Set column 1 input to column 0 input mux output

**Bit 6: ACol2Mux**

0 = Set column 2 input to column 2 input mux output

1 = Set column 2 input to column 3 input mux output

**Bit 5: ABUF1EN** Enables the analog output buffer for Analog Column 1 (Pin P0[5])

0 = Disable analog output buffer

1 = Enable analog output buffer

**Bit 4: ABUF2EN** Enables the analog output buffer for Analog Column 2 (Pin P0[4])

0 = Disable analog output buffer

1 = Enable analog output buffer

**Bit 3: ABUF0EN** Enables the analog output buffer for Analog Column 0 (Pin P0[3])

0 = Disable analog output buffer

1 = Enable analog output buffer

**Bit 2: ABUF3EN** Enables the analog output buffer for Analog Column 3 (Pin P0[2])

0 = Disable analog output buffer

1 = Enable analog output buffer

**Bit [1]: Reserved** Must be left as 0

**Bit [0]: PWR** Determines power level of all output buffers

0 = Low output power

1 = High output power

Analog Output Buffer Control Register (ABF\_CR, Address = Bank 1, 62h)

### 10.13 Analog Modulator

The user has the capability to use the Analog Switch Cap Type A PSoC Blocks in Columns 0 and 2 as amplitude modulators. The Analog Modulator Control Register (AMD\_CR) allows the user to select the appropriate modulating signal. When the modulating signal is low, the polarity follows the setting of the ASign bit set in the Analog Switch Cap Type A Control 0 Register (ASAxCR0). When this signal is high, the normal gain polarity of the PSoC block is inverted.

**Table 82: Analog Modulator Control Register**

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	0	0	0	0	0
Read/Write	RW	RW	RW	RW	RW	RW	RW	RW
Bit Name	Reserved	Reserved	Reserved	Reserved	AMOD2[1]	AMOD2[0]	AMOD0[1]	AMOD0[0]

**Bit 7: Reserved**  
**Bit 6: Reserved**  
**Bit 5: Reserved**  
**Bit 4: Reserved**

**Bit [3:2]: AMOD2[1], AMOD2[0]** Selects the modulation signal for Analog Column 2  
 0 0 = No Modulation  
 0 1 = Global Output [0]  
 1 0 = Global Output [4]  
 1 1 = Digital Basic Type A Block 03

**Bit [1:0]: AMOD0[1], AMOD0[0]** Selects the modulation signal for Analog Column 0  
 0 0 = No Modulation  
 0 1 = Global Output [0]  
 1 0 = Global Output [4]  
 1 1 = Digital Basic Type A Block 03

Analog Modulator Control Register (AMD\_CR, Address = Bank 1, 63h)

## 10.14 Analog PSoC Block Functionality

The analog PSoC blocks can be used to implement a wide range of functions, limited only by the designer's imagination. The following functions operate within the capability of the analog PSoC blocks using one analog PSoC block, multiple analog blocks, a combination of more than one *type* of analog block, or a combination of analog and digital PSoC blocks. Most of these functions are currently available as User Modules in PSoC Designer. Others will be added in the future.

- Delta-Sigma A/D Converters
- Successive Approximation A/D Converters
- Incremental A/D Converters
- Programmable Gain/Loss Stage
- Analog Comparators
- Zero-Crossing Detectors
- Low-Pass Filter
- Band-Pass Filter
- Notch Filter

- Amplitude Modulators
- Amplitude Demodulators
- Sine-Wave Generators
- Sine-Wave Detectors
- Sideband Detection
- Sideband Stripping
- Audio Output Drive
- DTMF Generator
- FSK Modulator

By modifying registers, as described in this Data Sheet, users can configure PSoC blocks to perform these functions and more.

## 11.3 Reset

### 11.3.1 Overview

The microcontroller supports two types of resets. When reset is initiated, all registers are restored to their default states and all interrupts are disabled.

**Reset Types:** Power On Reset (POR), External Reset ( $X_{res}$ ), and Watchdog Reset (WDR).

The occurrence of a reset is recorded in the Status and Control Register (CPU\_SCR). Bits within this register record the occurrence of POR and WDR Reset respec-

tively. The firmware can interrogate these bits to determine the cause of a reset.

The microcontroller resumes execution from ROM address 0x0000 after a reset. The internal clocking mode is active after a reset, until changed by user firmware. In addition, the Sleep / Watchdog Timer is reset to its minimum interval count.

**Important:** The CPU clock defaults to divide by 8 mode at POR to guarantee operation at the low  $V_{cc}$  that might be present during the supply ramp.

**Table 94: Processor Status and Control Register**

Bit #	7	6	5	4	3	2	1	0
POR	0	0	0	1	0	0	0	0
Read/ Write	R	--	R/C <sup>1</sup>	R/C <sup>1</sup>	RW	--	--	RW
Bit Name	IES	Reserved	WDRS	PORS	Sleep	Reserved	Reserved	Stop

**Bit 7: IES** Global interrupt enable status from CPU Flag register

0 = Global interrupts disabled

1 = Global interrupts enabled

**Bit 6: Reserved**

**Bit 5: WDRS**

WDRS is set by the CPU to indicate that a Watchdog Reset event has occurred. The user can read this bit to determine the type of reset that has occurred. The user can clear but not set this bit

0 = No WDR

1 = A WDR event has occurred

**Bit 4: PORS**

PORS is set by the CPU to indicate that a Power On Reset event has occurred. The user can read this bit to determine the type of reset that has occurred. The user can clear but not set this bit

0 = No POR

1 = A POR event has occurred. (Note that WDR events will not occur until this bit is cleared)

**Bit 3: Sleep** Set by the user to enable CPU sleep state. CPU will remain in sleep mode until any interrupt is pending

0 = Normal operation

1 = Sleep

**Bit 2: Reserved**

**Bit 1: Reserved**

**Bit 0: Stop** Set by the user to halt the CPU. The CPU will remain halted until a reset (WDR or POR) has taken place

0 = Normal CPU operation

1 = CPU is halted (not recommended)

1. C = Clear

Status and Control Register (CPU\_SCR, Address = Bank 0/1, FFh)

## 11.6 Switch Mode Pump

This feature is available on the CY8C26xxx versions within this family. During the time  $V_{CC}$  is ramping from 0 Volts to POR  $V_{trip}$  (2.2V +/- 12%), IC operation is held off by the POR circuit and the Switch Mode Pump is enabled. The pump is realized by connecting an external inductor between the battery voltage and SMP, with an external diode pointing from SMP to the  $V_{CC}$  pin (which must have a bypass capacitance of at least 0.1uF connected to  $V_{CC}$ ). This circuitry will pump  $V_{CC}$  to the Switch Mode Pump value specified in the Voltage Monitor Control Register (VLT\_CR), shown above. Battery voltage values down to 0.9 V during operation are supported, but this circuitry is not guaranteed to start for battery voltages below 1.2 V. Once the IC is enabled after its power

up and boot sequence, firmware can disable the SMP function by writing Voltage Monitor Control Register (VLT\_CR) bit 7 to a 1.

When the IC is put into sleep mode, the power supply pump will remain running to maintain voltage. This may result in higher than specification sleep current depending upon application. If the user desires, the pump may be disabled during precision measurements (such as A/D conversions) and then re-enabled (writing B7 to 1 and then back to 0 again). The user, however, is responsible for making the operation happen quickly enough to guarantee supply holdup (by the bypass capacitor) sufficient for continued operation.

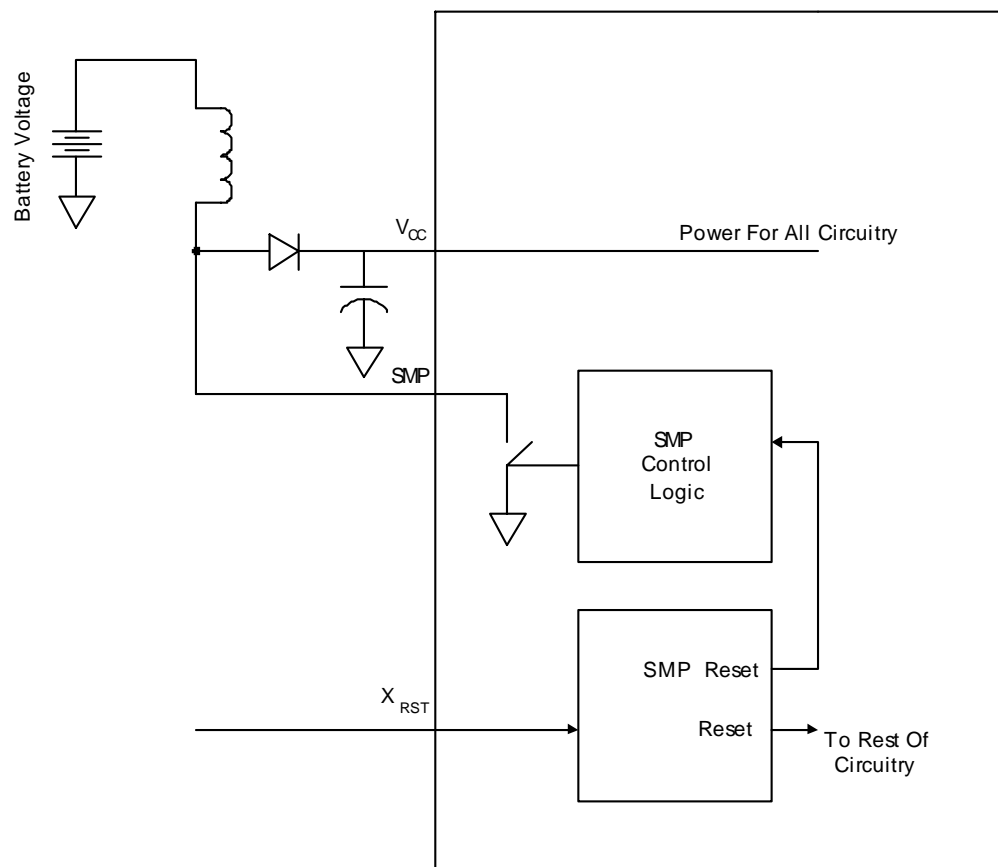


Figure 33: Switch Mode Pump

## 11.7 Internal Voltage Reference

An internal bandgap voltage reference source is provided on-chip. This reference is used for the Supply Voltage Monitor, and can also be accessed by the user as a reference voltage for analog operations. There is a Bandgap Oscillator Trim Register (BDG\_TR) used to calibrate this reference into specified tolerance. Factory-programmed trim values are available for 5.0V and 3.3V

operation. The 5.0V value is loaded in the BDG\_TR register upon reset. This register must be adjusted when operating voltage outside the range for which factory calibration was set. Changing the factory-programmed trim value is done using the Table Read Supervisor Call routine, and is documented in [11.8](#).

**Table 97: Bandgap Trim Register**

Bit #	7	6	5	4	3	2	1	0
POR	FS <sup>1</sup>	FS <sup>1</sup>	FS <sup>1</sup>	FS <sup>1</sup>	FS <sup>1</sup>	FS <sup>1</sup>	FS <sup>1</sup>	FS <sup>1</sup>
Read/Write	W	W	W	W	W	W	W	W
Bit Name	FMRD	BGT[2]	BGT[1]	BGT[0]	BGO[3]	BGO[2]	BGO[1]	BGO[0]
<p><b>Bit 7: FMRD</b>            0 = Enable voltage divider between BG and Flash (User must not use other than this setting)            1 = Disable voltage divider between BG and Flash (Test purposes only)</p> <p><b>Bit [6:4]: BGT [2:0]</b> Provides Temperature Curve compensation</p> <p><b>Bit [3:0]: BGO [3:0]</b> Provides +/- 5% Offset Trim to center V<sub>bg</sub> to 1.30V</p>								

1. FS = Factory set trim value

Bandgap Trim Register (BDG\_TR, Address = Bank 1, EAh)

## 11.8 Supervisor ROM/System Supervisor Call Instruction

The parts in this family have a Supervisor ROM to manage the programming, erasure, and protection of the on-chip Flash user program space. The Supervisor ROM also gives the user the capability to read the internal product ID, access factory trim values, as well as calculate checksums on blocks of the Flash memory space.

The System Supervisor Call instruction (SSC, opcode/byte 00h) provides the method for the user to access the pre-existing routines in the Supervisor ROM to implement these functions. This instruction sets the Flags Register (CPU\_F) bit 3 to 1 and performs an interrupt to address 0000 into the Supervisory ROM. The flag and old PC are pushed onto the Stack. The fact that the flag pushed has F[3] = 1 is irrelevant as the RETI instruction always clears F[3]. The Supervisory code at 0000 does a JACC table lookup based on the Accumulator value, which is effectively another level of instruction encoding. This service table implements the vectors to the various supervisory functions. The user must set several param-

eters when utilizing these functions. The parameters are written to 5 bytes of an 8-byte block near the top of RAM memory space.

Access to these functions must be through the Flash APIs provided in PSoC Designer and described in Application Note AN2015.

The following table documents each function, as well as the required parameter values:



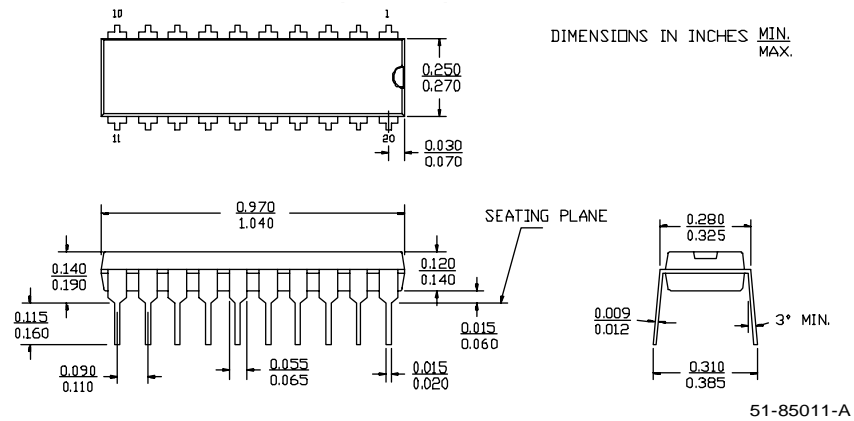


Figure 41: 20-Lead (300-Mil) Molded DIP P5

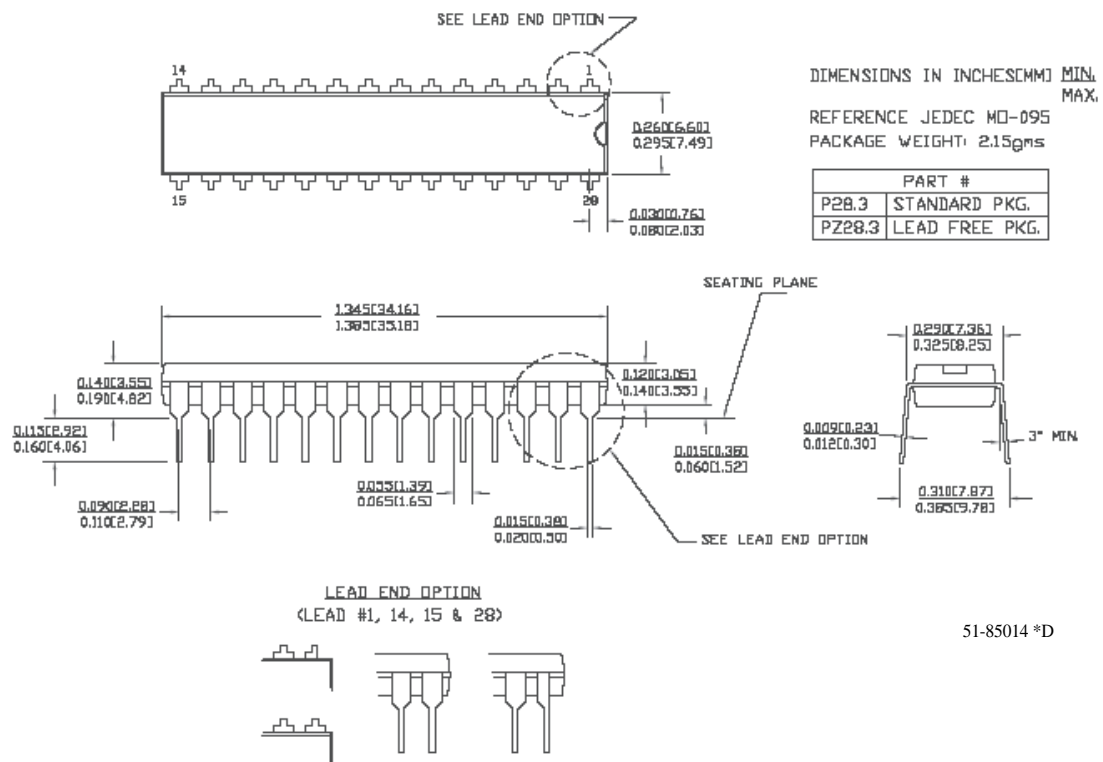


Figure 42: 28-Lead (300-Mil) Molded DIP P21