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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	eZ8
Core Size	8-Bit
Speed	5MHz
Connectivity	IrDA, UART/USART
Peripherals	Brown-out Detect/Reset, LED, POR, PWM, WDT
Number of I/O	6
Program Memory Size	8KB (8K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 3.6V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	8-SOIC (0.154", 3.90mm Width)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/z8f0813sb005eg

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Table 3. Signal Descriptions (Continued)

Signal Mnemonic	I/O	Description
COUT	O	Comparator Output. This is the output of the comparator.
Analog		
ANA[7:0]	I	Analog port. These signals are used as inputs to the ADC. The ANA0, ANA1, and ANA2 pins can also access the inputs and output of the integrated transimpedance amplifier.
VREF	I/O	Analog-to-Digital Converter reference voltage input.
Clock Input		
CLKIN	I	Clock Input Signal. This pin can be used to input a TTL-level signal to be used as the system clock.
LED Drivers		
LED	O	Direct LED drive capability. All port C pins have the capability to drive an LED without any other external components. These pins have programmable drive strengths set by the GPIO block.
On-Chip Debugger		
DBG	I/O	Debug. This signal is the control and data input and output to and from the OCD. Caution: The DBG pin is open-drain and requires an external pull-up resistor to ensure proper operation.
Reset		
RESET	I/O	RESET. Generates a reset when asserted (driven Low). Also serves as a reset indicator; the Z8 Encore! XP forces this pin Low when in reset. This pin is open-drain and features an enabled internal pull-up resistor.
Power Supply		
V _{DD}	I	Digital Power Supply.
AV _{DD} ²	I	Analog Power Supply.
V _{SS}	I	Digital Ground.
AV _{SS}	I	Analog Ground.

Notes:

1. PB6 and PB7 are only available in 28-pin packages without ADC. In 28-pin packages with ADC, they are replaced by AV_{DD} and AV_{SS}.
2. The AV_{DD} and AV_{SS} signals are available only in 28-pin packages with ADC. They are replaced by PB6 and PB7 on 28-pin packages without ADC.

During a System Reset or Stop Mode Recovery, the IPO requires 4 μ s to start up. Then the Z8 Encore! XP F0823 Series device is held in Reset for 66 cycles of the Internal Precision Oscillator. If the crystal oscillator is enabled in the Flash option bits, this reset period is increased to 5000 IPO cycles. When a reset occurs because of a low voltage condition or Power-On Reset, this delay is measured from the time that the supply voltage first exceeds the POR level. If the external pin reset remains asserted at the end of the reset period, the device remains in reset until the pin is deasserted.

At the beginning of Reset, all GPIO pins are configured as inputs with pull-up resistor disabled.

During Reset, the eZ8 CPU and on-chip peripherals are idle; however, the on-chip crystal oscillator and Watchdog Timer oscillator continue to run.

Upon Reset, control registers within the Register File that have a defined Reset value are loaded with their reset values. Other control registers (including the Stack Pointer, Register Pointer, and Flags) and general-purpose RAM are undefined following Reset. The eZ8 CPU fetches the Reset vector at Program Memory addresses 0002H and 0003H and loads that value into the Program Counter. Program execution begins at the Reset vector address.

When the control registers are re-initialized by a system reset, the system clock after reset is always the IPO. The software must reconfigure the oscillator control block, such that the correct system clock source is enabled and selected.

Bit	Description (Continued)
[4] EXT	External Reset Indicator If this bit is set to 1, a Reset initiated by the external <u>RESET</u> pin occurred. A Power-On Reset or a Stop Mode Recovery from a change in an input pin resets this bit. Reading this register resets this bit. For POR/Stop Mode Recover event values, please see Table 13.
[3:0]	Reserved These bits are reserved and must be programmed to 0000 when read.

Table 13. POR Indicator Values

Reset or Stop Mode Recovery Event	POR	STOP	WDT	EXT
Power-On Reset	1	0	0	0
Reset using <u>RESET</u> pin assertion	0	0	0	1
Reset using WDT time-out	0	0	1	0
Reset using the OCD (OCTCTL[1] set to 1)	1	0	0	0
Reset from STOP Mode using DBG Pin driven Low	1	0	0	0
Stop Mode Recovery using GPIO pin transition	0	1	0	0
Stop Mode Recovery using WDT time-out	0	1	1	0

Table 17. Port Alternate Function Mapping (Non 8-Pin Parts)

Port	Pin	Mnemonic	Alternate Function Description	Alternate Function Set Register AFS1
Port A ¹	PA0	T0IN/T0OUT Reserved	Timer 0 Input/Timer 0 Output Complement	N/A
	PA1	T0OUT Reserved	Timer 0 Output	
	PA2	DE0 Reserved	UART 0 Driver Enable	
	PA3	CTS0 Reserved	UART 0 Clear to Send	
	PA4	RXD0/IRRX0 Reserved	UART 0 / IrDA 0 Receive Data	
	PA5	TXD0/IRTX0 Reserved	UART 0 / IrDA 0 Transmit Data	
	PA6	T1IN/T1OUT ² Reserved	Timer 1 Input/Timer 1 Output Complement	
	PA7	T1OUT Reserved	Timer 1 Output	

Notes:

1. Because there is only a single alternate function for each Port A pin, the Alternate Function Set registers are not implemented for Port A. Enabling alternate function selections as described in the [Port A–C Alternate Function Subregisters](#) section on page 43 automatically enables the associated alternate function.
2. Whether PA0/PA6 take on the timer input or timer output complement function depends on the timer configuration as described in the [Timer Pin Signal Operation](#) section on page 83.
3. Because there are at most two choices of alternate function for any pin of Port B, the Alternate Function Set register AFS2 is implemented but not used to select the function. Also, alternate function selection as described in the [Port A–C Alternate Function Subregisters](#) section on page 43 must also be enabled.
4. V_{REF} is available on PB5 in 28-pin products only.
5. Because there are at most two choices of alternate function for any pin of Port C, the Alternate Function Set register AFS2 is implemented but not used to select the function. Also, Alternate Function selection as described in the [Port A–C Alternate Function Subregisters](#) section on page 43 must also be enabled.
6. V_{REF} is available on PC2 in 20-pin parts only.

Timer 0–1 PWM High and Low Byte Registers

The Timer 0–1 PWM High and Low Byte (TxPWMH and TxPWML) registers (Table 55 and Table 56) control pulse-width modulator (PWM) operations. These registers also store the capture values for the CAPTURE and CAPTURE/COMPARE modes.

Table 55. Timer 0–1 PWM High Byte Register (TxPWMH)

Bit	7	6	5	4	3	2	1	0
Field	PWMH							
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Address	F04H, F0CH							

Table 56. Timer 0–1 PWM Low Byte Register (TxPWML)

Bit	7	6	5	4	3	2	1	0
Field	PWML							
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Address	F05H, F0DH							

Bit	Description
[7:0] PWMH, PWML	Pulse-Width Modulator High and Low Bytes These two bytes, {PWMH[7:0], PWML[7:0]}, form a 16-bit value that is compared to the current 16-bit timer count. When a match occurs, the PWM output changes state. The PWM output value is set by the TPOL bit in the Timer Control Register (TxCTL1) register.

These TxPWMH and TxPWML registers also store the 16-bit captured timer value when operating in CAPTURE or CAPTURE/COMPARE modes.

Timer 0–1 Control Registers

The Timer Control registers are 8-bit read/write registers that control the operation of their associated counter/timers.

Timer 0–1 Control Register 0

The Timer Control Register 0 (TxCTL0) and Timer Control Register 1 (TxCTL1) determine the timer operating mode. It also includes a programmable PWM deadband delay,

WDT Reset in NORMAL Operation

If configured to generate a Reset when a time-out occurs, the Watchdog Timer forces the device into the System Reset state. The WDT status bit in the Watchdog Timer Control Register is set to 1. For more information about System Reset, see **the Reset and Stop Mode Recovery** chapter on page 21.

WDT Reset in STOP Mode

If configured to generate a Reset when a time-out occurs and the device is in STOP Mode, the Watchdog Timer initiates a Stop Mode Recovery. Both the WDT status bit and the STOP bit in the Watchdog Timer Control Register are set to 1 following WDT time-out in STOP Mode. For more information, see **the Reset and Stop Mode Recovery** chapter on page 21.

Watchdog Timer Reload Unlock Sequence

Writing the unlock sequence to the Watchdog Timer Control Register (WDTCTL) address unlocks the three Watchdog Timer Reload Byte Registers (WDTU, WDTH, and WDTL) to allow changes to the time-out period. These write operations to the WDTCTL Register address produce no effect on the bits in the WDTCTL Register. The locking mechanism prevents spurious writes to the Reload registers. The following sequence is required to unlock the Watchdog Timer Reload Byte Registers (WDTU, WDTH, and WDTL) for write access.

1. Write 55H to the Watchdog Timer Control Register (WDTCTL).
2. Write AAH to the Watchdog Timer Control Register (WDTCTL).
3. Write the Watchdog Timer Reload Upper Byte register (WDTU).
4. Write the Watchdog Timer Reload High Byte register (WDTH).
5. Write the Watchdog Timer Reload Low Byte register (WDTL).

All three Watchdog Timer Reload registers must be written in the order just listed. There must be no other register writes between each of these operations. If a register write occurs, the lock state machine resets and no further writes can occur unless the sequence is restarted. The value in the Watchdog Timer Reload registers is loaded into the counter when the Watchdog Timer is first enabled and every time a WDT instruction is executed.

Watchdog Timer Control Register Definitions

This section defines the features of the following Watchdog Timer Control registers.

Watchdog Timer Control Register (WDTCTL): see page 94

Watchdog Timer Reload Upper Byte Register (WDTU): see page 95

Software Compensation Procedure

The value read from the ADC high and low byte registers are uncompensated. The user mode software must apply gain and offset correction to this uncompensated value for maximum accuracy. The following formula yields the compensated value:

$$ADC_{comp} = (ADC_{uncomp} - OFFCAL) + ((ADC_{uncomp} - OFFCAL) * GAINCAL) / 2$$

where GAINCAL is the gain calibration byte, OFFCAL is the offset calibration byte and ADC_{uncomp} is the uncompensated value read from the ADC. The OFFCAL value is in two's complement format, as are the compensated and uncompensated ADC values.

► **Note:** The offset compensation is performed first, followed by the gain compensation. One bit of resolution is lost because of rounding on both the offset and gain computations. As a result the ADC registers read back 13 bits: 1 sign bit, two calibration bits lost to rounding and 10 data bits. Also note that in the second term, the multiplication must be performed before the division by 2^{16} . Otherwise, the second term evaluates to zero incorrectly.

! **Caution:** Although the ADC can be used without the gain and offset compensation, it does exhibit non-unity gain. Designing the ADC with sub-unity gain reduces noise across the ADC range but requires the ADC results to be scaled by a factor of 8/7.

ADC Control Register Definitions

The following sections define the ADC Control registers.

ADC Control Register 0

The ADC Control Register selects the analog input channel and initiates the analog-to-digital conversion.

Bit	Description (Continued)
[3:0] ANAIN	<p>Analog Input Select</p> <p>These bits select the analog input for conversion. Not all port pins in this list are available in all packages for Z8 Encore! XP F0823 Series. For information about the port pins available with each package style, see the Pin Description section on page 7. Do not enable unavailable analog inputs. Usage of these bits changes depending on the buffer mode selected in ADC Control/Status Register 1.</p> <p>For the reserved values, all input switches are disabled to avoid leakage or other undesirable operation. ADC samples taken with reserved bit settings are undefined.</p> <p>Single-Ended:</p> <p>0000 = ANA0. 0001 = ANA1. 0010 = ANA2. 0011 = ANA3. 0100 = ANA4. 0101 = ANA5. 0110 = ANA6. 0111 = ANA7. 1000 = Reserved. 1001 = Reserved. 1010 = Reserved. 1011 = Reserved. 1100 = Reserved. 1101 = Reserved. 1110 = Reserved. 1111 = Reserved.</p>

Table 80. Flash Code Protection Using the Flash Option Bits

FWP	Flash Code Protection Description
0	Programming and erasing disabled for all of Flash Program Memory. In user code programming, Page Erase, and Mass Erase are all disabled. Mass Erase is available through the On-Chip Debugger.
1	Programming, Page Erase, and Mass Erase are enabled for all of Flash Program Memory.

Flash Code Protection Using the Flash Controller

At Reset, the Flash Controller locks to prevent accidental program or erasure of the Flash memory. To program or erase the Flash memory, first write the Page Select Register with the target page. Unlock the Flash Controller by making two consecutive writes to the Flash Control Register with the values 73H and 8CH, sequentially. The Page Select Register must be rewritten with the same page previously stored there. If the two Page Select writes do not match, the controller reverts to a locked state. If the two writes match, the selected page becomes active. For more details, see Figure 21.

After unlocking a specific page, you can enable either Page Program or Erase. Writing the value 95H causes a Page Erase only if the active page resides in a sector that is not protected. Any other value written to the Flash Control Register locks the Flash Controller. Mass Erase is not allowed in the user code but only in through the Debug Port.

After unlocking a specific page, you can also write to any byte on that page. After a byte is written, the page remains unlocked, allowing for subsequent writes to other bytes on the same page. Further writes to the Flash Control Register cause the active page to revert to a locked state.

Sector-Based Flash Protection

The final protection mechanism is implemented on a per-sector basis. The Flash memories of Z8 Encore! XP devices are divided into maximum number of 8 sectors. A sector is 1/8 of the total Flash memory size unless this value is smaller than the page size – in which case, the sector and page sizes are equal. On Z8 Encore! F0823 Series devices, the sector size is varied according to the Flash memory configuration shown in [Table 79](#) on page 134.

The Flash Sector Protect Register can be configured to prevent sectors from being programmed or erased. After a sector is protected, it cannot be unprotected by user code. The Flash Sector Protect Register is cleared after reset, and any previously-written protection values are lost. User code must write this register in their initialization routine if they prefer to enable sector protection.

The Flash Sector Protect Register shares its Register File address with the Page Select Register. The Flash Sector Protect Register is accessed by writing the Flash Control Register with 5EH. After the Flash Sector Protect Register is selected, it can be accessed at the Page Select Register address. When user code writes the Flash Sector Protect Register,

conditions, do not enable the clock failure circuitry (POFEN must be deasserted in the OSCCTL Register).

Watchdog Timer Failure

In the event of a Watchdog Timer oscillator failure, a similar non-maskable interrupt-like event is issued. This event does not trigger an attendant clock switch-over, but alerts the CPU of the failure. After a Watchdog Timer failure, it is no longer possible to detect a primary oscillator failure. The failure detection circuitry does not function if the Watchdog Timer is used as the primary oscillator or if the Watchdog Timer oscillator has been disabled. For either of these cases, it is necessary to disable the detection circuitry by deasserting the WDFEN bit of the OSCCTL Register.

The Watchdog Timer oscillator failure detection circuit counts system clocks while searching for a Watchdog Timer clock. The logic counts 8004 system clock cycles before determining that a failure has occurred. The system clock rate determines the speed at which the Watchdog Timer failure can be detected. A very slow system clock results in very slow detection times.

! **Caution:** It is possible to disable the clock failure detection circuitry as well as all functioning clock sources. In this case, the Z8 Encore! XP F0823 Series device ceases functioning and can only be recovered by Power-On Reset.

Oscillator Control Register Definitions

The following section provides the bit definitions for the Oscillator Control Register.

Oscillator Control Register

The Oscillator Control Register (OSCCTL) enables/disables the various oscillator circuits, enables/disables the failure detection/recovery circuitry and selects the primary oscillator, which becomes the system clock.

The Oscillator Control Register must be unlocked before writing. Writing the two step sequence E7H followed by 18H to the Oscillator Control Register unlocks it. The register is locked at successful completion of a register write to the OSCCTL.

Assembly Language Source Program Example

```
JP START      ; Everything after the semicolon is a comment.
START:        ; A label called 'START'. The first instruction (JP START) in this
              ; example causes program execution to jump to the point within the
              ; program where the START label occurs.

LD R4, R7     ; A Load (LD) instruction with two operands. The first operand,
              ; Working Register R4, is the destination. The second operand,
              ; Working Register R7, is the source. The contents of R7 is
              ; written into R4.

LD 234H, #01  ; Another Load (LD) instruction with two operands.
              ; The first operand, Extended Mode Register Address 234H,
              ; identifies the destination. The second operand, Immediate Data
              ; value 01H, is the source. The value 01H is written into the
              ; Register at address 234H.
```

Assembly Language Syntax

For proper instruction execution, eZ8 CPU assembly language syntax requires that the operands be written as 'destination, source'. After assembly, the object code usually has the operands in the order 'source, destination', but ordering is opcode-dependent. The following instruction examples illustrate the format of some basic assembly instructions and the resulting object code produced by the assembler. You must follow this binary format if you prefer manual program coding or intend to implement your own assembler.

Example 1

If the contents of registers 43H and 08H are added and the result is stored in 43H, the assembly syntax and resulting object code is shown in Table 106.

Table 106. Assembly Language Syntax Example 1

Assembly Language Code	ADD	43H,	08H	(ADD dst, src)
Object Code	04	08	43	(OPC src, dst)

Example 2

In general, when an instruction format requires an 8-bit register address, that address can specify any register location in the range 0–255 or, using Escaped Mode Addressing, a Working Register R0–R15. If the contents of Register 43H and Working Register R8 are added and the result is stored in 43H, the assembly syntax and resulting object code is shown in Table 107.

Table 118. eZ8 CPU Instruction Summary (Continued)

Assembly Mnemonic	Symbolic Operation	Address Mode		Opcode(s) (Hex)	Flags						Fetch Cycles	Instr. Cycles
		dst	src		C	Z	S	V	D	H		
DA dst	$\text{dst} \leftarrow \text{DA}(\text{dst})$	R		40	*	*	*	X	–	–	2	2
		IR		41							2	3
DEC dst	$\text{dst} \leftarrow \text{dst} - 1$	R		30	–	*	*	*	–	–	2	2
		IR		31							2	3
DECW dst	$\text{dst} \leftarrow \text{dst} - 1$	RR		80	–	*	*	*	–	–	2	5
		IRR		81							2	6
DI	$\text{IRQCTL}[7] \leftarrow 0$			8F	–	–	–	–	–	–	1	2
DJNZ dst, RA	$\text{dst} \leftarrow \text{dst} - 1$ if $\text{dst} \neq 0$ $\text{PC} \leftarrow \text{PC} + X$	r		0A-FA	–	–	–	–	–	–	2	3
EI	$\text{IRQCTL}[7] \leftarrow 1$			9F	–	–	–	–	–	–	1	2
HALT	HALT Mode			7F	–	–	–	–	–	–	1	2
INC dst	$\text{dst} \leftarrow \text{dst} + 1$	R		20	–	*	*	–	–	–	2	2
		IR		21							2	3
		r		0E-FE							1	2
INCW dst	$\text{dst} \leftarrow \text{dst} + 1$	RR		A0	–	*	*	*	–	–	2	5
		IRR		A1							2	6
IRET	$\text{FLAGS} \leftarrow @\text{SP}$ $\text{SP} \leftarrow \text{SP} + 1$ $\text{PC} \leftarrow @\text{SP}$ $\text{SP} \leftarrow \text{SP} + 2$ $\text{IRQCTL}[7] \leftarrow 1$			BF	*	*	*	*	*	*	1	5
JP dst	$\text{PC} \leftarrow \text{dst}$	DA		8D	–	–	–	–	–	–	3	2
		IRR		C4							2	3
JP cc, dst	if cc is true $\text{PC} \leftarrow \text{dst}$	DA		0D-FD	–	–	–	–	–	–	3	2
JR dst	$\text{PC} \leftarrow \text{PC} + X$	DA		8B	–	–	–	–	–	–	2	2
JR cc, dst	if cc is true $\text{PC} \leftarrow \text{PC} + X$	DA		0B-FB	–	–	–	–	–	–	2	2

Note: Flags Notation:

* = Value is a function of the result of the operation.


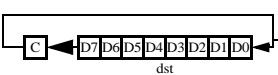
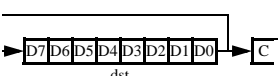
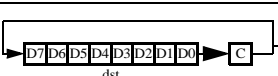
– = Unaffected.

X = Undefined.

0 = Reset to 0.

1 = Set to 1.

Table 118. eZ8 CPU Instruction Summary (Continued)

Assembly Mnemonic	Symbolic Operation	Address Mode		Opcode(s) (Hex)	Flags						Fetch Cycles	Instr. Cycles
		dst	src		C	Z	S	V	D	H		
POPX dst	dst ← @SP SP ← SP + 1	ER		D8	–	–	–	–	–	–	3	2
PUSH src	SP ← SP – 1 @SP ← src	R		70	–	–	–	–	–	–	2	2
		IR		71							2	3
		IM		IF70							3	2
PUSHX src	SP ← SP – 1 @SP ← src	ER		C8	–	–	–	–	–	–	3	2
RCF	C ← 0			CF	0	–	–	–	–	–	1	2
RET	PC ← @SP SP ← SP + 2			AF	–	–	–	–	–	–	1	4
RL dst		R		90	*	*	*	*	–	–	2	2
		IR		91							2	3
RLC dst		R		10	*	*	*	*	–	–	2	2
		IR		11							2	3
RR dst		R		E0	*	*	*	*	–	–	2	2
		IR		E1							2	3
RRC dst		R		C0	*	*	*	*	–	–	2	2
		IR		C1							2	3

Note: Flags Notation:

* = Value is a function of the result of the operation.

– = Unaffected.

X = Undefined.

0 = Reset to 0.

1 = Set to 1.

General Purpose I/O Port Output Timing

Figure 30 and Table 131 provide timing information for GPIO Port pins.

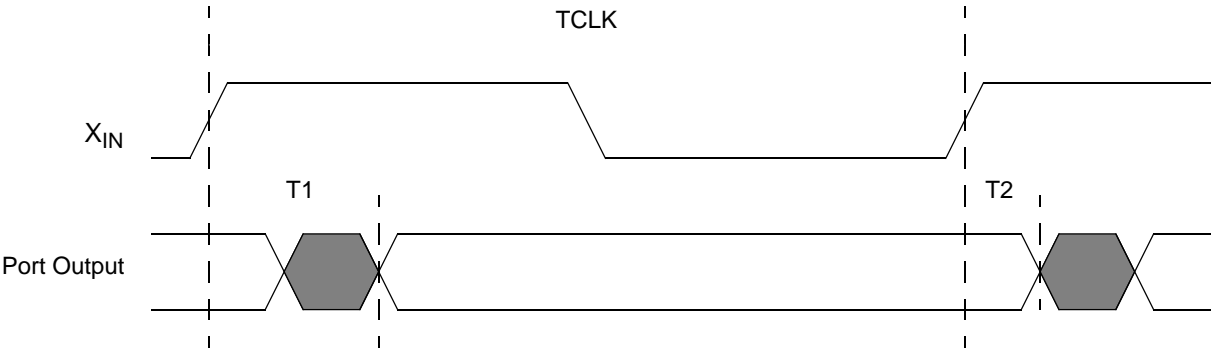


Figure 30. GPIO Port Output Timing

Table 131. GPIO Port Output Timing

Parameter	Abbreviation	Delay (ns)	
		Minimum	Maximum
GPIO Port pins			
T ₁	X _{IN} Rise to Port Output Valid Delay	–	15
T ₂	X _{IN} Rise to Port Output Hold Time	2	–

On-Chip Debugger Timing

Figure 31 and Table 132 provide timing information for the DBG pin. The DBG pin timing specifications assume a 4 ns maximum rise and fall time.

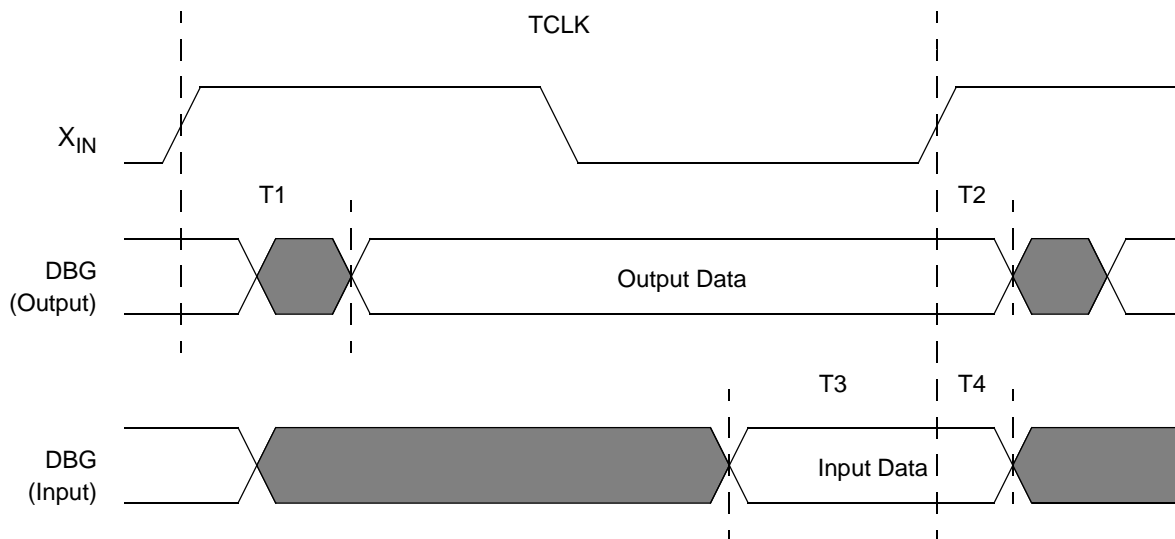


Figure 31. On-Chip Debugger Timing

Table 132. On-Chip Debugger Timing

Parameter	Abbreviation	Delay (ns)	
		Minimum	Maximum
DBG			
T ₁	X _{IN} Rise to DBG Valid Delay	—	15
T ₂	X _{IN} Rise to DBG Output Hold Time	2	—
T ₃	DBG to X _{IN} Rise Input Setup Time	5	—
T ₄	DBG to X _{IN} Rise Input Hold Time	5	—

UART Timing

Figure 32 and Table 133 provide timing information for UART pins for the case where CTS is used for flow control. The CTS to DE assertion delay (T₁) assumes the transmit data register has been loaded with data prior to CTS assertion.

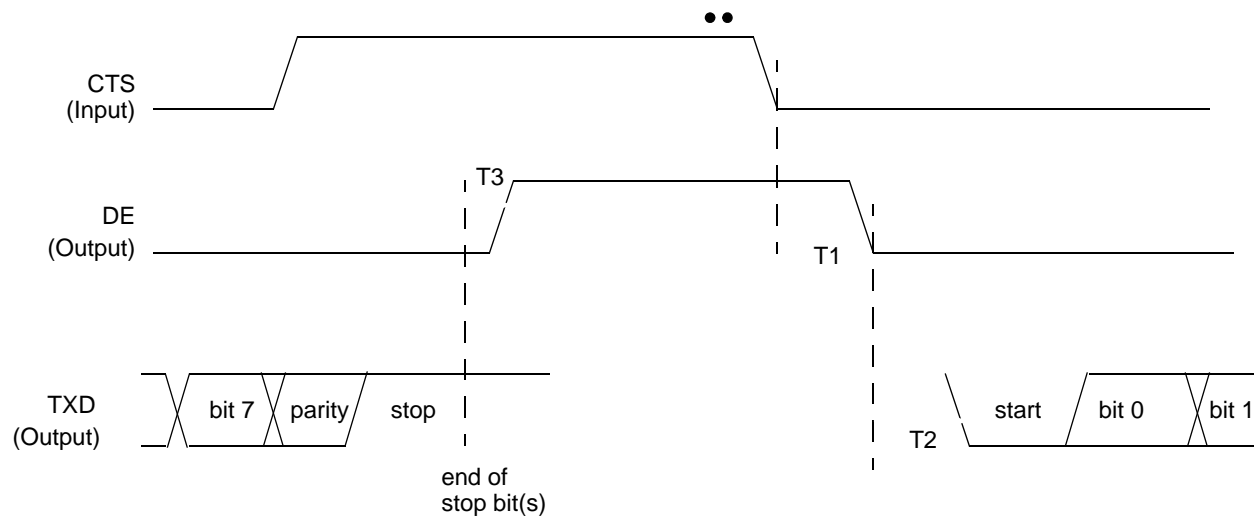


Figure 32. UART Timing With CTS

Table 133. UART Timing With CTS

Parameter	Abbreviation	Delay (ns)	
		Minimum	Maximum
UART			
T ₁	CTS Fall to DE output delay	2 * X _{IN} period	2 * X _{IN} period + 1 bit time
T ₂	DE assertion to TXD falling edge (start bit) delay		± 5
T ₃	End of Stop Bit(s) to DE deassertion delay		± 5

Figure 33 and Table 134 provide timing information for UART pins for the case where CTS is not used for flow control. DE asserts after the transmit data register has been written. DE remains asserted for multiple characters as long as the transmit data register is written with the next character before the current character has completed.

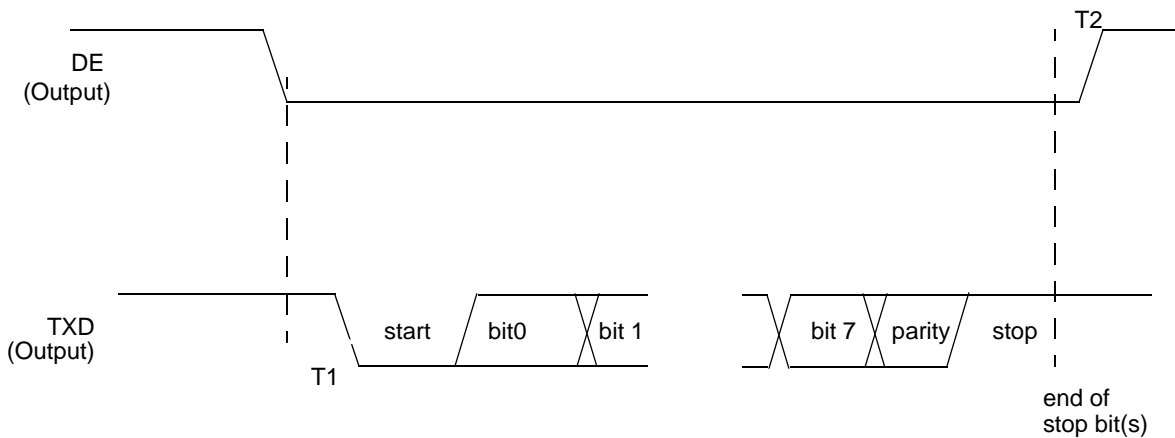


Figure 33. UART Timing Without CTS

Table 134. UART Timing Without CTS

Parameter	Abbreviation	Delay (ns)	
		Minimum	Maximum
UART			
T ₁	DE assertion to TXD falling edge (start bit) delay	1 * X _{IN} period	1 bit time
T ₂	End of Stop Bit(s) to DE deassertion delay (Tx data register is empty)	± 5	

Table 135. Z8 Encore! XP F0823 Series Ordering Matrix (Continued)

Part Number	Flash	RAM	I/O Lines	Interrupts	16-Bit Timers w/PWM	10-Bit A/D Channels	UART with IrDA	Description
Z8 Encore! XP F0823 Series with 4 KB Flash								
Standard Temperature: 0°C to 70°C								
Z8F0413PB005SG	4 KB	1 KB	6	12	2	0	1	PDIP 8-pin package
Z8F0413QB005SG	4 KB	1 KB	6	12	2	0	1	QFN 8-pin package
Z8F0413SB005SG	4 KB	1 KB	6	12	2	0	1	SOIC 8-pin package
Z8F0413SH005SG	4 KB	1 KB	16	18	2	0	1	SOIC 20-pin package
Z8F0413HH005SG	4 KB	1 KB	16	18	2	0	1	SSOP 20-pin package
Z8F0413PH005SG	4 KB	1 KB	16	18	2	0	1	PDIP 20-pin package
Z8F0413SJ005SG	4 KB	1 KB	24	18	2	0	1	SOIC 28-pin package
Z8F0413HJ005SG	4 KB	1 KB	24	18	2	0	1	SSOP 28-pin package
Z8F0413PJ005SG	4 KB	1 KB	24	18	2	0	1	PDIP 28-pin package
Extended Temperature: -40°C to 105°C								
Z8F0413PB005EG	4 KB	1 KB	6	12	2	0	1	PDIP 8-pin package
Z8F0413QB005EG	4 KB	1 KB	6	12	2	0	1	QFN 8-pin package
Z8F0413SB005EG	4 KB	1 KB	6	12	2	0	1	SOIC 8-pin package
Z8F0413SH005EG	4 KB	1 KB	16	18	2	0	1	SOIC 20-pin package
Z8F0413HH005EG	4 KB	1 KB	16	18	2	0	1	SSOP 20-pin package
Z8F0413PH005EG	4 KB	1 KB	16	18	2	0	1	PDIP 20-pin package
Z8F0413SJ005EG	4 KB	1 KB	24	18	2	0	1	SOIC 28-pin package
Z8F0413HJ005EG	4 KB	1 KB	24	18	2	0	1	SSOP 28-pin package
Z8F0413PJ005EG	4 KB	1 KB	24	18	2	0	1	PDIP 28-pin package