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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Discontinued at Digi-Key
Core Processor	ARM® Cortex®-M3
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	I ² C, IrDA, SmartCard, SPI, UART/USART, USB
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	53
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	1.98V ~ 3.8V
Data Converters	A/D 8x12b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	64-QFN (9x9)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm32lg330f128g-e-qfn64r

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

3.1.13 Inter-Integrated Circuit Interface (I2C)

The I^2C module provides an interface between the MCU and a serial I^2C -bus. It is capable of acting as both a master and a slave, and supports multi-master buses. Both standard-mode, fast-mode and fastmode plus speeds are supported, allowing transmission rates all the way from 10 kbit/s up to 1 Mbit/s. Slave arbitration and timeouts are also provided to allow implementation of an SMBus compliant system. The interface provided to software by the I^2C module, allows both fine-grained control of the transmission process and close to automatic transfers. Automatic recognition of slave addresses is provided in all energy modes.

3.1.14 Universal Synchronous/Asynchronous Receiver/Transmitter (USART)

The Universal Synchronous Asynchronous serial Receiver and Transmitter (USART) is a very flexible serial I/O module. It supports full duplex asynchronous UART communication as well as RS-485, SPI, MicroWire and 3-wire. It can also interface with ISO7816 Smart-Cards, IrDA and I2S devices.

3.1.15 Pre-Programmed USB/UART Bootloader

The bootloader presented in application note AN0042 is pre-programmed in the device at factory. The bootloader enables users to program the EFM32 through a UART or a USB CDC class virtual UART without the need for a debugger. The autobaud feature, interface and commands are described further in the application note.

3.1.16 Universal Asynchronous Receiver/Transmitter (UART)

The Universal Asynchronous serial Receiver and Transmitter (UART) is a very flexible serial I/O module. It supports full- and half-duplex asynchronous UART communication.

3.1.17 Low Energy Universal Asynchronous Receiver/Transmitter (LEUART)

The unique LEUARTTM, the Low Energy UART, is a UART that allows two-way UART communication on a strict power budget. Only a 32.768 kHz clock is needed to allow UART communication up to 9600 baud/ s. The LEUART includes all necessary hardware support to make asynchronous serial communication possible with minimum of software intervention and energy consumption.

3.1.18 Timer/Counter (TIMER)

The 16-bit general purpose Timer has 3 compare/capture channels for input capture and compare/Pulse- Width Modulation (PWM) output. TIMER0 also includes a Dead-Time Insertion module suitable for motor control applications.

3.1.19 Real Time Counter (RTC)

The Real Time Counter (RTC) contains a 24-bit counter and is clocked either by a 32.768 kHz crystal oscillator, or a 32.768 kHz RC oscillator. In addition to energy modes EM0 and EM1, the RTC is also available in EM2. This makes it ideal for keeping track of time since the RTC is enabled in EM2 where most of the device is powered down.

3.1.20 Backup Real Time Counter (BURTC)

The Backup Real Time Counter (BURTC) contains a 32-bit counter and is clocked either by a 32.768 kHz crystal oscillator, a 32.768 kHz RC oscillator or a 1 kHz ULFRCO. The BURTC is available in all Energy Modes and it can also run in backup mode, making it operational even if the main power should drain out.

3.1.21 Low Energy Timer (LETIMER)

The unique LETIMERTM, the Low Energy Timer, is a 16-bit timer that is available in energy mode EM2 in addition to EM1 and EM0. Because of this, it can be used for timing and output generation when most of the device is powered down, allowing simple tasks to be performed while the power consumption of the system is kept at an absolute minimum. The LETIMER can be used to output a variety of waveforms with minimal software intervention. It is also connected to the Real Time Counter (RTC), and can be configured to start counting on compare matches from the RTC.

3.1.22 Pulse Counter (PCNT)

The Pulse Counter (PCNT) can be used for counting pulses on a single input or to decode quadrature encoded inputs. It runs off either the internal LFACLK or the PCNTn S0IN pin as external clock source. The module may operate in energy mode EM0 - EM3.

Module	Configuration	Pin Connections
OPAMP	Full configuration	Outputs: OPAMP_OUTx, OPAMP_OUTxALT, Inputs: OPAMP_Px, OPAMP_Nx
AES	Full configuration	NA
GPIO	50 pins	Available pins are shown in 5.7.3 GPIO Pinout Overview

Module	Configuration	Pin Connections
ACMP1	Full configuration	ACMP1_CH[7:0], ACMP1_O
VCMP	Full configuration	NA
ADC0	Full configuration	ADC0_CH[7:0]
DAC0	Full configuration	DAC0_OUT[1:0], DAC0_OUTxALT
OPAMP	Full configuration	Outputs: OPAMP_OUTx, OPAMP_OUTxALT, Inputs: OPAMP_Px, OPAMP_Nx
AES	Full configuration	NA
GPIO	86 pins	Available pins are shown in 5.21.3 GPIO Pinout Overview
LCD	Full configuration	LCD_SEG[33:0], LCD_COM[7:0], LCD_BCAP_P, LCD_BCAP_N, LCD_BEXT

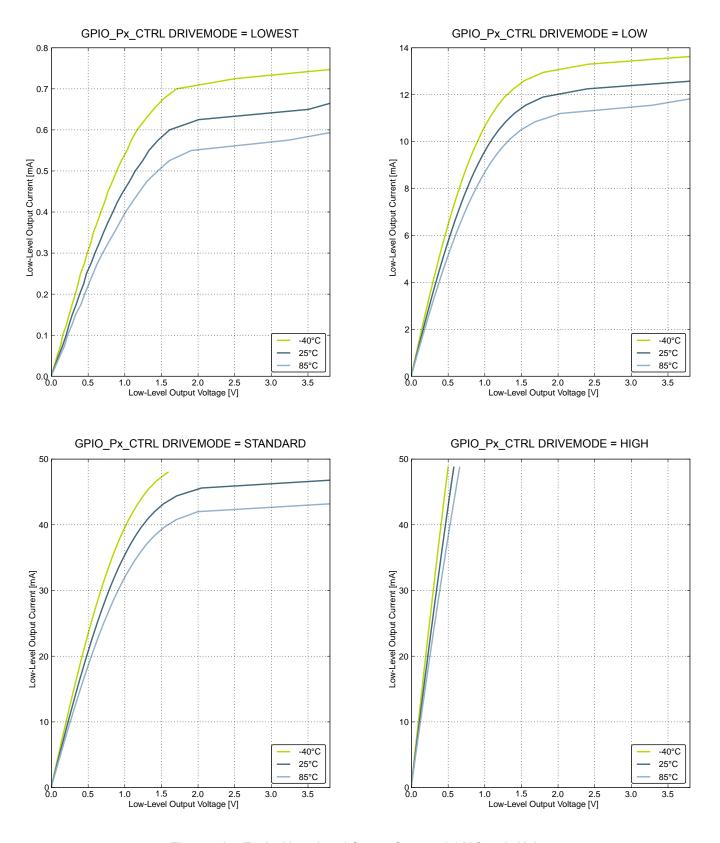
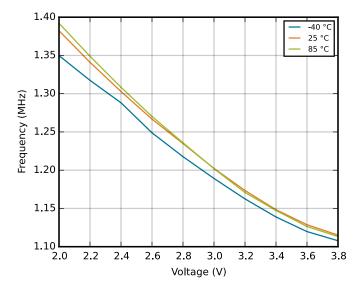


Figure 4.14. Typical Low-Level Output Current, 3.8 V Supply Voltage

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Voltage drift	V _{HFRCO_DRIFT}	f _{HFRCO} = 28 MHz	_	10768	_	ppm/V
		f _{HFRCO} = 21 MHz	_	8939	_	ppm/V
		f _{HFRCO} = 14 MHz	_	8040	_	ppm/V
		f _{HFRCO} = 11 MHz	_	7719	_	ppm/V
		f _{HFRCO} = 6.6 MHz	_	8491	_	ppm/V
		f _{HFRCO} = 1.2 MHz	_	-124035	_	ppm/V
Temperature drift	T _{HFRCO_DRIFT}	f _{HFRCO} = 28 MHz	_	91	_	ppm/°C
		f _{HFRCO} = 21 MHz	_	88	_	ppm/°C
		f _{HFRCO} = 14 MHz	_	43	_	ppm/°C
		f _{HFRCO} = 11 MHz	_	50	_	ppm/°C
		f _{HFRCO} = 6.6 MHz	_	-50	_	ppm/°C
		f _{HFRCO} = 1.2 MHz	_	83	_	ppm/°C
Frequency step for LSB change in TUNING value	TUNESTEPHERCO		_	0.3 ³	_	%

Note:

- 1. For devices with prod. rev. < 19, Typ = 7MHz and Min/Max values not applicable.
- 2. For devices with prod. rev. < 19, Typ = 1MHz and Min/Max values not applicable.
- 3. The TUNING field in the CMU_HFRCOCTRL register may be used to adjust the HFRCO frequency. There is enough adjustment range to ensure that the frequency bands above 7 MHz will always have some overlap across supply voltage and temperature. By using a stable frequency reference such as the LFXO or HFXO, a firmware calibration routine can vary the TUNING bits and the frequency band to maintain the HFRCO frequency at any arbitrary value between 7 MHz and 28 MHz across operating conditions.



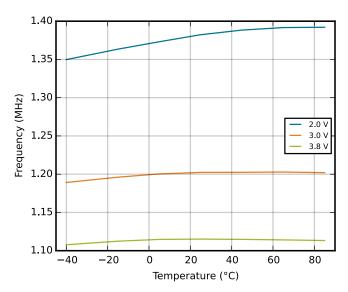


Figure 4.17. Calibrated HFRCO 1 MHz Band Frequency vs Supply Voltage and Temperature

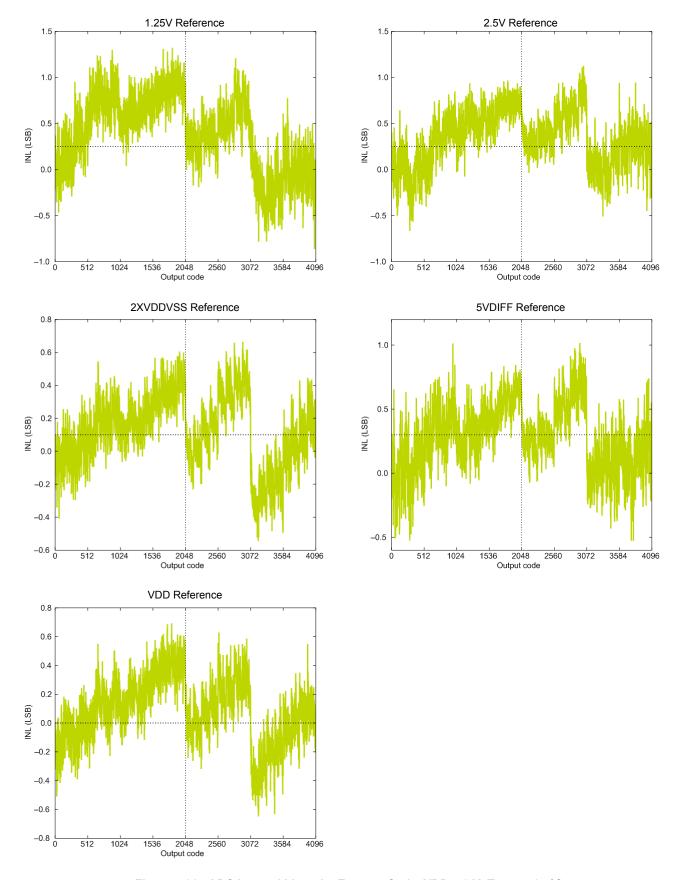


Figure 4.26. ADC Integral Linearity Error vs Code, VDD = 3 V, Temp = 25 °C

Table 4.25. I2C Standard-mode (Sm)

Parameter	Symbol	Min	Тур	Max	Unit
SCL clock frequency	f _{SCL}	0	_	100 ¹	kHz
SCL clock low time	t _{LOW}	4.7	_	_	μs
SCL clock high time	t _{HIGH}	4.0	_	_	μs
SDA set-up time	t _{SU,DAT}	250	_	_	ns
SDA hold time	t _{HD,DAT}	8	_	3450 ^{2,3}	ns
Repeated START condition set-up time	t _{SU,STA}	4.7	_	_	μs
(Repeated) START condition hold time	t _{HD,STA}	4.0	_	_	μs
STOP condition set-up time	t _{SU,STO}	4.0	_	_	μs
Bus free time between a STOP and a START condition	t _{BUF}	4.7	_	_	μs

Note:

- 1. For the minimum HFPERCLK frequency required in Standard-mode, see the I2C chapter in the EFM32LG Reference Manual.
- 2. The maximum SDA hold time (t_{HD.DAT}) needs to be met only when the device does not stretch the low time of SCL (t_{LOW}).
- 3. When transmitting data, this number is guaranteed only when I2Cn_CLKDIV < ((3450*10⁻⁹ [s] * f_{HFPERCLK} [Hz]) 4).

Table 4.26. I2C Fast-mode (Fm)

Parameter	Symbol	Min	Тур	Max	Unit
SCL clock frequency	f _{SCL}	0		400 ¹	kHz
SCL clock low time	t _{LOW}	1.3			μs
SCL clock high time	t _{HIGH}	0.6			μs
SDA set-up time	t _{SU,DAT}	100			ns
SDA hold time	t _{HD,DAT}	8		900 ^{2,3}	ns
Repeated START condition set-up time	t _{SU,STA}	0.6			μs
(Repeated) START condition hold time	t _{HD,STA}	0.6			μs
STOP condition set-up time	t _{SU,STO}	0.6			μs
Bus free time between a STOP and a START condition	t _{BUF}	1.3			μs

Note:

- 1. For the minimum HFPERCLK frequency required in Fast-mode, see the I2C chapter in the EFM32LG Reference Manual.
- 2. The maximum SDA hold time $(t_{HD,DAT})$ needs to be met only when the device does not stretch the low time of SCL (t_{LOW}) .
- 3. When transmitting data, this number is guaranteed only when I2Cn_CLKDIV < ($(900*10^{-9} [s] * f_{HFPERCLK} [Hz]) 4)$.

QFP6	64 Pin# and Name		Pin Alternate Funct	ionality / Description	
Pin #	Pin Name	Analog	Timers	Communication	Other
3	PA2		TIM0_CC2 #0/1		CMU_CLK0 #0 ETM_TD0 #3
4	PA3		TIM0_CDTI0 #0		LES_ALTEX2 #0 ETM_TD1 #3
5	PA4		TIM0_CDTI1 #0		LES_ALTEX3 #0 ETM_TD2 #3
6	PA5		TIM0_CDTI2 #0	LEU1_TX #1	LES_ALTEX4 #0 ETM_TD3 #3
7	IOVDD_0	Digital IO power supply 0.			
8	VSS	Ground.			
9	PC0	ACMP0_CH0 DAC0_OUT0ALT #0/ OPAMP_OUT0ALT	TIM0_CC1 #4 PCNT0_S0IN #2	US0_TX #5 US1_TX #0 I2C0_SDA #4	LES_CH0 #0 PRS_CH2 #0
10	PC1	ACMP0_CH1 DAC0_OUT0ALT #1/ OPAMP_OUT0ALT	TIM0_CC2 #4 PCNT0_S1IN #2	US0_RX #5 US1_RX #0 I2C0_SCL #4	LES_CH1 #0 PRS_CH3 #0
11	PC2	ACMP0_CH2 DAC0_OUT0ALT #2/ OPAMP_OUT0ALT	TIM0_CDTI0 #4	US2_TX #0	LES_CH2 #0
12	PC3	ACMP0_CH3DAC0_OU T0ALT #3/ OPAMP_OUT0ALT	TIM0_CDTI1 #4	US2_RX #0	LES_CH3 #0
13	PC4	ACMP0_CH4 OPAMP_P0	TIM0_CDTI2 #4 LE- TIM0_OUT0 #3 PCNT1_S0IN #0	US2_CLK #0 I2C1_SDA #0	LES_CH4 #0
14	PC5	ACMP0_CH5 OPAMP_N0	LETIM0_OUT1 #3 PCNT1_S1IN #0	US2_CS #0 I2C1_SCL #0	LES_CH5#0
15	PB7	LFXTAL_P	TIM1_CC0 #3	US0_TX #4 US1_CLK #0	
16	PB8	LFXTAL_N	TIM1_CC1 #3	US0_RX #4 US1_CS #0	
17	PA8		TIM2_CC0 #0		
18	PA9		TIM2_CC1 #0		
19	PA10		TIM2_CC2 #0		
20	RESETn	Reset input, active low. To low during reset, and let the		source to this pin, it is requi that reset is released.	red to only drive this pin
21	PB11	DAC0_OUT0 / OPAMP_OUT0	TIM1_CC2 #3 LE- TIM0_OUT0 #1	I2C1_SDA #1	
22	VSS	Ground.			
23	AVDD_1	Analog power supply 1.			
24	PB13	HFXTAL_P		US0_CLK #4/5 LEU0_TX #1	
25	PB14	HFXTAL_N		US0_CS #4/5 LEU0_RX #1	
26	IOVDD_3	Digital IO power supply 3.			

Alternate			L	OCATIO	N			
Functionality	0	1	2	3	4	5	6	Description
US1_TX	PC0	PD0	PD7					USART1 Asynchronous Transmit.Also used as receive input in half duplex communication.
001_17	1 00	1 20						USART1 Synchronous mode Master Output / Slave Input (MOSI).
US2_CLK	PC4							USART2 clock input / output.
US2_CS	PC5							USART2 chip select input / output.
								USART2 Asynchronous Receive.
US2_RX	PC3							USART2 Synchronous mode Master Input / Slave Output (MISO).
US2 TX	PC2							USART2 Asynchronous Transmit.Also used as receive input in half duplex communication.
032_17	FG2							USART2 Synchronous mode Master Output / Slave Input (MOSI).
USB_DM	PF10							USB D- pin.
USB_DMPU	PD2							USB D- Pullup control.
USB_DP	PF11							USB D+ pin.
USB_ID	PF12							USB ID pin. Used in OTG mode.
USB_VBUS	USB_V BUS							USB 5 V VBUS input.
USB_VBUSEN	PF5							USB 5 V VBUS enable.
USB_VREGI	USB_V REGI							USB Input to internal 3.3 V regulator
USB_VREGO	USB_V REGO							USB Decoupling for internal 3.3 V USB regulator and regulator output

5.7.3 GPIO Pinout Overview

The specific GPIO pins available in EFM32LG332 is shown in the following table. Each GPIO port is organized as 16-bit ports indicated by letters A through F, and the individual pin on this port is indicated by a number from 15 down to 0.

Table 5.21. GPIO Pinout

Port	Pin 15	Pin 14	Pin 13	Pin 12	Pin 11	Pin 10	Pin 9	Pin 8	Pin 7	Pin 6	Pin 5	Pin 4	Pin 3	Pin 2	Pin 1	Pin 0
Port A	-	-	-	-	-	PA10	PA9	PA8	-	-	PA5	PA4	PA3	PA2	PA1	PA0
Port B	-	PB14	PB13	-	PB11	-	-	PB8	PB7	-	-	-	-	-	-	-
Port C	-	-	-	-	PC11	PC10	PC9	PC8	PC7	PC6	PC5	PC4	PC3	PC2	PC1	PC0
Port D	-	-	-	-	-	-	-	PD8	PD7	PD6	PD5	PD4	PD3	PD2	PD1	PD0
Port E	PE15	PE14	PE13	PE12	PE11	PE10	PE9	PE8	-	-	-	-	-	-	-	-
Port F	-	-	-	PF12	PF11	PF10	-	-	-	-	PF5	-	-	PF2	PF1	PF0

CSP8	31 Pin# and Name		Pin Alternate Funct	ionality / Description	
Pin #	Pin Name	Analog	Timers	Communication	Other
A3	PF2		TIM0_CC2 #5	LEU0_TX #4	ACMP1_O #0 DBG_SWO #0 GPIO_EM4WU4
A4	VSS	Ground.			
A5	IOVDD_5	Digital IO power supply 5.			
A6	PE9		PCNT2_S1IN #1		
A7	PE11		TIM1_CC1 #1	US0_RX #0	LES_ALTEX5 #0 BOOT_RX
A8	PE12		TIM1_CC2 #1	US0_RX #3 US0_CLK #0 I2C0_SDA #6	CMU_CLK1 #2 LES_ALTEX6 #0
A9	PA15		TIM3_CC2 #0		
B1	USB_VREGI				
B2	USB_VBUS	USB 5.0 V VBUS input.			
В3	PC15	ACMP1_CH7 DAC0_OUT1ALT #3/ OPAMP_OUT1ALT	TIM0_CDTI2 #1/3 TIM1_CC2 #0	US0_CLK #3 U0_RX #3	LES_CH15 #0 DBG_SWO #1
B4	PF1		TIM0_CC1 #5 LE- TIM0_OUT1 #2	US1_CS #2 LEU0_RX #3 I2C0_SCL #5	DBG_SWDIO #0/1/2/3 GPIO_EM4WU3
B5	PF5		TIM0_CDTI2 #2/5	USB_VBUSEN #0	PRS_CH2 #1
В6	PE8		PCNT2_S0IN #1		PRS_CH3 #1
В7	PE13			US0_TX #3 US0_CS #0 I2C0_SCL #6	LES_ALTEX7 #0 ACMP0_O #0 GPIO_EM4WU5
В8	PA0		TIM0_CC0 #0/1/4	LEU0_RX #4 I2C0_SDA #0	PRS_CH0 #0 GPIO_EM4WU0
В9	PA2		TIM0_CC2 #0/1		CMU_CLK0 #0 ETM_TD0 #3
C1	USB_VREGO				
C2	PC13	ACMP1_CH5 DAC0_OUT1ALT #1/ OPAMP_OUT1ALT	TIM0_CDTI0 #1/3 TIM1_CC0 #0 TIM1_CC2 #4 PCNT0_S0IN #0	U1_RX #0	LES_CH13 #0
С3	PC14	ACMP1_CH6 DAC0_OUT1ALT #2/ OPAMP_OUT1ALT	TIM0_CDTI1 #1/3 TIM1_CC1 #0 PCNT0_S1IN #0	US0_CS #3 U0_TX #3	LES_CH14 #0
C4	PF0		TIM0_CC0 #5 LE- TIM0_OUT0 #2	US1_CLK #2 LEU0_TX #3 I2C0_SDA #5	DBG_SWCLK #0/1/2/3
C5	PF12			USB_ID	
C6	PE10		TIM1_CC0 #1	US0_TX #0	BOOT_TX
C7	PE14		TIM3_CC0 #0	LEU0_TX #2	
C8	PA1		TIM0_CC1 #0/1	I2C0_SCL #0	CMU_CLK1 #0 PRS_CH1 #0
С9	PA3		TIM0_CDTI0 #0	U0_TX #2	LES_ALTEX2 #0 ETM_TD1 #3

Alternate			L	OCATIO	N			
Functionality	0	1	2	3	4	5	6	Description
USB_VREGI	USB_V REGI							USB Input to internal 3.3 V regulator
USB_VREGO	USB_V REGO							USB Decoupling for internal 3.3 V USB regulator and regulator output

5.10.3 GPIO Pinout Overview

The specific GPIO pins available in EFM32LG390 is shown in the following table. Each GPIO port is organized as 16-bit ports indicated by letters A through F, and the individual pin on this port is indicated by a number from 15 down to 0.

Table 5.30. GPIO Pinout

Port	Pin 15	Pin 14	Pin 13	Pin 12	Pin 11	Pin 10	Pin 9	Pin 8	Pin 7	Pin 6	Pin 5	Pin 4	Pin 3	Pin 2	Pin 1	Pin 0
Port A	PA15	PA14	PA13	PA12	PA11	PA10	PA9	PA8	PA7	PA6	PA5	PA4	PA3	PA2	PA1	PA0
Port B	PB15	PB14	PB13	PB12	PB11	PB10	PB9	PB8	PB7	PB6	PB5	PB4	PB3	PB2	PB1	PB0
Port C	_	_	_	_	PC11	PC10	PC9	PC8	PC7	PC6	PC5	PC4	PC3	PC2	PC1	PC0
Port D	PD15	PD14	PD13	PD12	PD11	PD10	PD9	PD8	PD7	PD6	PD5	PD4	PD3	PD2	PD1	PD0
Port E	PE15	PE14	PE13	PE12	PE11	PE10	PE9	PE8	PE7	PE6	PE5	PE4	PE3	PE2	PE1	PE0
Port F	_	_	_	PF12	PF11	PF10	PF9	PF8	PF7	PF6	PF5		_	PF2	PF1	PF0

5.10.4 Opamp Pinout Overview

The specific opamp terminals available in EFM32LG390 is shown in the following figure.

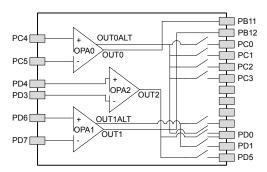


Figure 5.20. Opamp Pinout

5.13.2 Alternate Functionality Pinout

A wide selection of alternate functionality is available for multiplexing to various pins. This is shown in the following table. The table shows the name of the alternate functionality in the first column, followed by columns showing the possible LOCATION bitfield settings.

Note: Some functionality, such as analog interfaces, do not have alternate settings or a LOCATION bitfield. In these cases, the pinout is shown in the column corresponding to LOCATION 0.

Table 5.38. Alternate functionality overview

Alternate			L	OCATIC	DN			
Functionality	0	1	2	3	4	5	6	Description
ACMP0_CH4	PC4							Analog comparator ACMP0, channel 4.
ACMP0_CH5	PC5							Analog comparator ACMP0, channel 5.
ACMP0_CH6	PC6							Analog comparator ACMP0, channel 6.
ACMP0_CH7	PC7							Analog comparator ACMP0, channel 7.
ACMP0_O	PE13		PD6					Analog comparator ACMP0, digital output.
ACMP1_CH4	PC12							Analog comparator ACMP1, channel 4.
ACMP1_CH5	PC13							Analog comparator ACMP1, channel 5.
ACMP1_CH6	PC14							Analog comparator ACMP1, channel 6.
ACMP1_CH7	PC15							Analog comparator ACMP1, channel 7.
ACMP1_O	PF2		PD7					Analog comparator ACMP1, digital output.
ADC0_CH0	PD0							Analog to digital converter ADC0, input channel number 0.
ADC0_CH1	PD1							Analog to digital converter ADC0, input channel number 1.
ADC0_CH2	PD2							Analog to digital converter ADC0, input channel number 2.
ADC0_CH3	PD3							Analog to digital converter ADC0, input channel number 3.
ADC0_CH4	PD4							Analog to digital converter ADC0, input channel number 4.
ADC0_CH5	PD5							Analog to digital converter ADC0, input channel number 5.
ADC0_CH6	PD6							Analog to digital converter ADC0, input channel number 6.
ADC0_CH7	PD7							Analog to digital converter ADC0, input channel number 7.
BOOT_RX	PE11							Bootloader RX.
BOOT_TX	PE10							Bootloader TX.
BU_VIN	PD8							Battery input for Backup Power Domain
CMU_CLK0	PA2	PC12	PD7					Clock Management Unit, clock output number 0.
CMU_CLK1	PA1	PD8	PE12					Clock Management Unit, clock output number 1.
OPAMP_N0	PC5							Operational Amplifier 0 external negative input.
OPAMP_N1	PD7							Operational Amplifier 1 external negative input.

5.14 EFM32LG880 (LQFP100)

5.14.1 Pinout

The EFM32LG880 pinout is shown in the following figure and table. Alternate locations are denoted by "#" followed by the location number (Multiple locations on the same pin are split with "/"). Alternate locations can be configured in the LOCATION bitfield in the *_ROUTE register in the module in question.

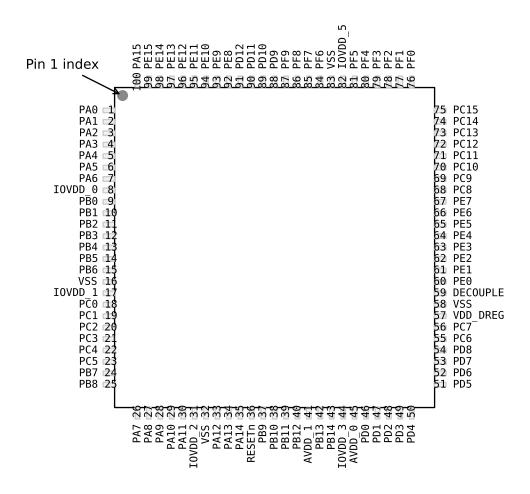


Figure 5.27. EFM32LG880 Pinout (top view, not to scale)

Table 5.40. Device Pinout

LQF	P100 Pin# and Name	Pin Alternate Functionality / Description								
Pin #	Pin Name	Pin Name Analog		Timers	Communication	Other				
1	PA0	LCD_SEG13	EBI_AD09 #0/1/2	TIM0_CC0 #0/1/4	LEU0_RX #4 I2C0_SDA #0	PRS_CH0 #0 GPIO_EM4WU0				
2	PA1	LCD_SEG14	EBI_AD10 #0/1/2	TIM0_CC1 #0/1	I2C0_SCL #0	CMU_CLK1 #0 PRS_CH1 #0				

Alternate			L	OCATIO	N			
Functionality	0	1	2	3	4	5	6	Description
PRS_CH1	PA1	PF4						Peripheral Reflex System PRS, channel 1.
PRS_CH2	PC0	PF5						Peripheral Reflex System PRS, channel 2.
PRS_CH3	PC1	PE8						Peripheral Reflex System PRS, channel 3.
TIM0_CC0	PA0	PA0	PF6	PD1	PA0	PF0		Timer 0 Capture Compare input / output channel 0.
TIM0_CC1	PA1	PA1	PF7	PD2	PC0	PF1		Timer 0 Capture Compare input / output channel 1.
TIM0_CC2	PA2	PA2	PF8	PD3	PC1	PF2		Timer 0 Capture Compare input / output channel 2.
TIM0_CDTI0	PA3	PC13	PF3	PC13	PC2	PF3		Timer 0 Complimentary Deat Time Insertion channel 0.
TIM0_CDTI1	PA4	PC14	PF4	PC14	PC3	PF4		Timer 0 Complimentary Deat Time Insertion channel 1.
TIM0_CDTI2	PA5	PC15	PF5	PC15	PC4	PF5		Timer 0 Complimentary Deat Time Insertion channel 2.
TIM1_CC0	PC13	PE10	PB0	PB7	PD6			Timer 1 Capture Compare input / output channel 0.
TIM1_CC1	PC14	PE11	PB1	PB8	PD7			Timer 1 Capture Compare input / output channel 1.
TIM1_CC2	PC15	PE12	PB2	PB11	PC13			Timer 1 Capture Compare input / output channel 2.
TIM2_CC0	PA8	PA12	PC8					Timer 2 Capture Compare input / output channel 0.
TIM2_CC1	PA9	PA13	PC9					Timer 2 Capture Compare input / output channel 1.
TIM2_CC2	PA10	PA14	PC10					Timer 2 Capture Compare input / output channel 2.
TIM3_CC0	PE14	PE0						Timer 3 Capture Compare input / output channel 0.
TIM3_CC1	PE15	PE1						Timer 3 Capture Compare input / output channel 1.
TIM3_CC2	PA15	PE2						Timer 3 Capture Compare input / output channel 2.
U0_RX	PF7	PE1	PA4	PC15				UART0 Receive input.
U0_TX	PF6	PE0	PA3	PC14				UART0 Transmit output. Also used as receive input in half duplex communication.
U1_RX	PC13		PB10	PE3				UART1 Receive input.
U1_TX	PC12		PB9	PE2				UART1 Transmit output. Also used as receive input in half duplex communication.
US0_CLK	PE12	PE5	PC9	PC15	PB13	PB13		USART0 clock input / output.
US0_CS	PE13	PE4	PC8	PC14	PB14	PB14		USART0 chip select input / output.
								USART0 Asynchronous Receive.
US0_RX	PE11	PE6	PC10	PE12	PB8	PC1		USART0 Synchronous mode Master Input / Slave Output (MISO).
US0_TX	PE10	PE7	PC11	PE13	PB7	PC0		USART0 Asynchronous Transmit.Also used as receive input in half duplex communication.
	1 210	/		1 2 10		1 30		USART0 Synchronous mode Master Output / Slave Input (MOSI).
US1_CLK	PB7	PD2	PF0					USART1 clock input / output.
US1_CS	PB8	PD3	PF1					USART1 chip select input / output.

BGA	A112 Pin# and Name	Pin Alternate Functionality / Description								
Pin#	Pin Name	Analog	EBI	Communication	Other					
L2	PC5	ACMP0_CH5 OPAMP_N0	EBI_NANDWEn #0/1/2	LETIM0_OUT1 #3 PCNT1_S1IN #0	US2_CS #0 I2C1_SCL #0	LES_CH5 #0				
L3	PA14	LCD_BEXT	EBI_A02 #0/1/2	TIM2_CC2 #1						
L4	IOVDD_1	Digital IO power supply 1.								
L5	PB11	DAC0_OUT0 / OPAMP_OUT0		TIM1_CC2 #3 LE- TIM0_OUT0 #1	I2C1_SDA #1					
L6	PB12	DAC0_OUT1 / OPAMP_OUT1		LETIM0_OUT1 #1	I2C1_SCL #1					
L7	AVSS_2	Analog ground 2.								
L8	PB13	HFXTAL_P			US0_CLK #4/5 LEU0_TX #1					
L9	PB14	HFXTAL_N			US0_CS #4/5 LEU0_RX #1					
L10	AVDD_0	Analog power supply	0.							
L11	PD0	ADC0_CH0 DAC0_OUT0ALT #4/ OPAMP_OUT0ALT OPAMP_OUT2 #1		PCNT2_S0IN #0	US1_TX#1					

Alternate	ernate LOCATION							
Functionality	0	1	2	3	4	5	6	Description
LCD_SEG15	PA2							LCD segment line 15. Segments 12, 13, 14 and 15 are controlled by SEGEN3.
LCD_SEG16	PA3							LCD segment line 16. Segments 16, 17, 18 and 19 are controlled by SEGEN4.
LCD_SEG17	PA4							LCD segment line 17. Segments 16, 17, 18 and 19 are controlled by SEGEN4.
LCD_SEG18	PA5							LCD segment line 18. Segments 16, 17, 18 and 19 are controlled by SEGEN4.
LCD_SEG19	PA6							LCD segment line 19. Segments 16, 17, 18 and 19 are controlled by SEGEN4.
LCD_SEG20/ LCD_COM4	РВ3							LCD segment line 20. Segments 20, 21, 22 and 23 are controlled by SEGEN5. This pin may also be used as LCD COM line 4
LCD_SEG21/ LCD_COM5	PB4							LCD segment line 21. Segments 20, 21, 22 and 23 are controlled by SEGEN5. This pin may also be used as LCD COM line 5
LCD_SEG22/ LCD_COM6	PB5							LCD segment line 22. Segments 20, 21, 22 and 23 are controlled by SEGEN5. This pin may also be used as LCD COM line 6
LCD_SEG23/ LCD_COM7	PB6							LCD segment line 23. Segments 20, 21, 22 and 23 are controlled by SEGEN5. This pin may also be used as LCD COM line 7
LES_ALTEX0	PD6							LESENSE alternate exite output 0.
LES_ALTEX1	PD7							LESENSE alternate exite output 1.
LES_ALTEX2	PA3							LESENSE alternate exite output 2.
LES_ALTEX3	PA4							LESENSE alternate exite output 3.
LES_ALTEX4	PA5							LESENSE alternate exite output 4.
LES_ALTEX5	PE11							LESENSE alternate exite output 5.
LES_ALTEX6	PE12							LESENSE alternate exite output 6.
LES_ALTEX7	PE13							LESENSE alternate exite output 7.
LES_CH4	PC4							LESENSE channel 4.
LES_CH5	PC5							LESENSE channel 5.
LES_CH6	PC6							LESENSE channel 6.
LES_CH7	PC7							LESENSE channel 7.
LETIMO_OUT0	PD6	PB11	PF0	PC4				Low Energy Timer LETIM0, output channel 0.
LETIM0_OUT1	PD7	PB12	PF1	PC5				Low Energy Timer LETIM0, output channel 1.
LEU0_RX	PD5	PB14	PE15	PF1	PA0			LEUART0 Receive input.
LEU0_TX	PD4	PB13	PE14	PF0	PF2			LEUART0 Transmit output. Also used as receive input in half duplex communication.
LEU1_RX	PC7	PA6						LEUART1 Receive input.
LEU1_TX	PC6	PA5						LEUART1 Transmit output. Also used as receive input in half duplex communication.

Alternate			L	OCATIO	N			
Functionality	0	1	2	3	4	5	6	Description
US1_TX		PD0	PD7					USART1 Asynchronous Transmit.Also used as receive input in half duplex communication.
001_17		1 50						USART1 Synchronous mode Master Output / Slave Input (MOSI).
US2_CLK	PC4	PB5						USART2 clock input / output.
US2_CS	PC5	PB6						USART2 chip select input / output.
								USART2 Asynchronous Receive.
US2_RX		PB4						USART2 Synchronous mode Master Input / Slave Output (MISO).
US2 TX		PB3						USART2 Asynchronous Transmit.Also used as receive input in half duplex communication.
032_17		F B 3						USART2 Synchronous mode Master Output / Slave Input (MOSI).
USB_DM	PF10							USB D- pin.
USB_DMPU	PD2							USB D- Pullup control.
USB_DP	PF11							USB D+ pin.
USB_ID	PF12							USB ID pin. Used in OTG mode.
USB_VBUS	USB_V BUS							USB 5 V VBUS input.
USB_VBUSEN	PF5							USB 5 V VBUS enable.
USB_VREGI	USB_V REGI							USB Input to internal 3.3 V regulator
USB_VREGO	USB_V REGO							USB Decoupling for internal 3.3 V USB regulator and regulator output

5.19.3 GPIO Pinout Overview

The specific GPIO pins available in EFM32LG942 is shown in the following table. Each GPIO port is organized as 16-bit ports indicated by letters A through F, and the individual pin on this port is indicated by a number from 15 down to 0.

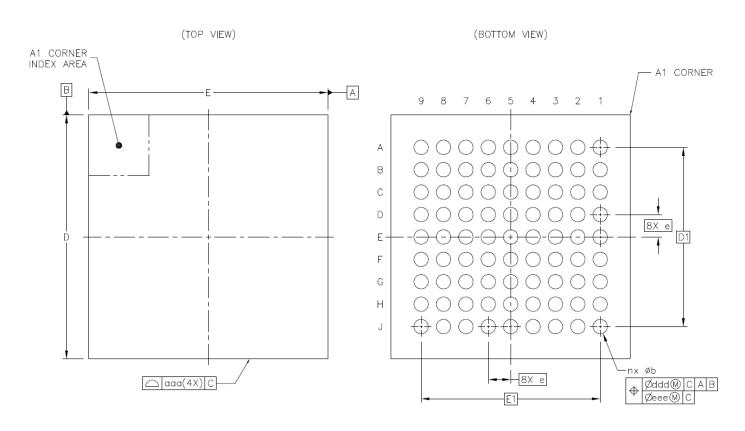
Table 5.57. GPIO Pinout

Port	Pin 15	Pin 14	Pin 13	Pin 12	Pin 11	Pin 10	Pin 9	Pin 8	Pin 7	Pin 6	Pin 5	Pin 4	Pin 3	Pin 2	Pin 1	Pin 0
Port A	_	PA14	PA13	PA12	_	_	_	_	_	_	PA5	PA4	PA3	PA2	PA1	PA0
Port B	_	PB14	PB13	_	PB11	_	_	PB8	PB7	PB6	PB5	PB4	PB3	_	_	_
Port C	_	_	_	_	_	_	_	_	PC7	PC6	PC5	PC4	_	_	_	_
Port D	_	_	_	_	_	_	_	PD8	PD7	PD6	PD5	PD4	PD3	PD2	PD1	PD0
Port E	PE15	PE14	PE13	PE12	PE11	PE10	PE9	PE8	PE7	PE6	PE5	PE4	_	_	_	_
Port F	_	_	_	PF12	PF11	PF10	_	_	_	_	PF5	_	_	PF2	PF1	PF0

Alternate	LOCATION								
Functionality	0	1	2	3	4	5	6	Description	
BU_STAT	PE3							Backup Power Domain status, whether or not the system is in backup mode	
BU_VIN	PD8							Battery input for Backup Power Domain	
BU_VOUT	PE2							Power output for Backup Power Domain	
CMU_CLK0	PA2		PD7					Clock Management Unit, clock output number 0.	
CMU_CLK1	PA1	PD8	PE12					Clock Management Unit, clock output number 1.	
OPAMP_N0	PC5							Operational Amplifier 0 external negative input.	
OPAMP_N1	PD7							Operational Amplifier 1 external negative input.	
OPAMP_N2	PD3							Operational Amplifier 2 external negative input.	
DAC0_OUT0 / OPAMP_OUT0	PB11							Digital to Analog Converter DAC0_OUT0 /OPAMP output channel number 0.	
DAC0_OUT0ALT OPAMP_OUT0A LT		PC1	PC2	PC3	PD0			Digital to Analog Converter DAC0_OUT0ALT / OPAMP alternative output for channel 0.	
DAC0_OUT1 / OPAMP_OUT1	PB12							Digital to Analog Converter DAC0_OUT1 /OPAMP output channel number 1.	
DAC0_OUT1ALT OPAMP_OUT1A LT	/				PD1			Digital to Analog Converter DAC0_OUT1ALT / OPAMP alternative output for channel 1.	
OPAMP_OUT2	PD5	PD0						Operational Amplifier 2 output.	
OPAMP_P0	PC4							Operational Amplifier 0 external positive input.	
OPAMP_P1	PD6							Operational Amplifier 1 external positive input.	
OPAMP_P2	PD4							Operational Amplifier 2 external positive input.	
								Debug-interface Serial Wire clock input.	
DBG_SWCLK	PF0	PF0	PF0	PF0				Note that this function is enabled to pin out of reset, and has a built-in pull down.	
								Debug-interface Serial Wire data input / output.	
DBG_SWDIO	PF1	PF1	PF1	PF1				Note that this function is enabled to pin out of reset, and has a built-in pull up.	
								Debug-interface Serial Wire viewer Output.	
DBG_SWO	PF2		PD1	PD2				Note that this function is not enabled after reset, and must be enabled by software to be used.	
EBI_A00	PA12	PA12	PA12					External Bus Interface (EBI) address output pin 00.	
EBI_A01	PA13	PA13	PA13					External Bus Interface (EBI) address output pin 01.	
EBI_A02	PA14	PA14	PA14					External Bus Interface (EBI) address output pin 02.	
EBI_A03	PB9	PB9	PB9					External Bus Interface (EBI) address output pin 03.	
EBI_A04	PB10	PB10	PB10					External Bus Interface (EBI) address output pin 04.	
EBI_A05	PC6	PC6	PC6					External Bus Interface (EBI) address output pin 05.	
EBI_A06	PC7	PC7	PC7					External Bus Interface (EBI) address output pin 06.	
EBI_A07	PE0	PE0	PE0					External Bus Interface (EBI) address output pin 07.	

8. CSP81 Package Specifications

8.1 CSP81 Package Dimensions



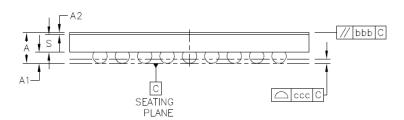


Figure 8.1. CSP81

Note:

- ${\it 1.\,AII\,dimensions\,shown\,are\,in\,millimeters\,(mm)\,unless\,otherwise\,noted.}\\$
- 2. Dimensioning and Tolerancing per ANSI Y14.5M-1994.
- 3. Primary datum "C" and seating plane are defined by the spherical crowns of the solder balls.
- 4. Dimension "b" is measured at the maximum solder bump diameter, parallel to primary datum "C".
- 5. Recommended card reflow profile is per the JEDEC/IPC J-STD-020C specification for Small BodyComponents.

Table 8.1. CSP81 (Dimensions in mm)

Symbol	Min	Nom	Max
А	0.491	0.55	0.609
A1	0.17	_	0.23

14.6 Revision 1.11

November 17th, 2010

This revision applies the following devices:

- EFM32G200
- EFM32G210
- EFM32G230
- EFM32G280
- EFM32G290
- EFM32G840
- EFM32G880
- EFM32G890

Corrected maximum DAC clock speed for continuous mode.

Added DAC sample-hold mode voltage drift rate.

Added pulse widths detected by the HFXO glitch detector.

Added power sequencing information to Power Management section.