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### Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

### Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

#### Details

Product Status	Obsolete
Number of LABs/CLBs	2400
Number of Logic Elements/Cells	10800
Total RAM Bits	573440
Number of I/O	404
Number of Gates	129600
Voltage - Supply	1.71V ~ 1.89V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	676-BGA
Supplier Device Package	676-FBGA (27x27)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/xilinx/xcv405e-6fg676i">https://www.e-xfl.com/product-detail/xilinx/xcv405e-6fg676i</a>

DLL provides four quadrature phases of the source clock, and can double the clock or divide the clock by 1.5, 2, 2.5, 3, 4, 5, 8, or 16.

The DLL also operates as a clock mirror. By driving the output from a DLL off-chip and then back on again, the DLL can be used to de-skew a board level clock among multiple devices.

In order to guarantee that the system clock is operating correctly prior to the FPGA starting up after configuration, the DLL can delay the completion of the configuration process until after it has achieved lock.

For more information about DLL functionality, see the Design Consideration section of the data sheet.

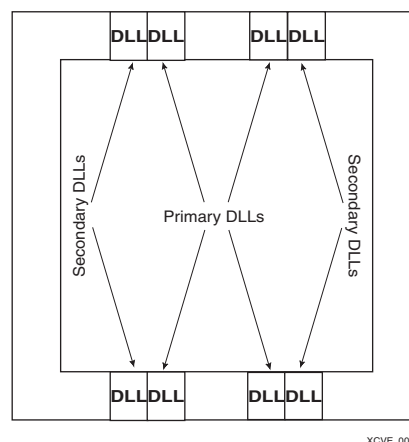


Figure 10: DLL Locations

## Boundary Scan

Virtex-E devices support all the mandatory boundary-scan instructions specified in the IEEE standard 1149.1. A Test Access Port (TAP) and registers are provided that implement the EXTEST, INTEST, SAMPLE/PRELOAD, BYPASS, IDCODE, USERCODE, and HIGHZ instructions. The TAP also supports two internal scan chains and configuration/readback of the device.

The JTAG input pins (TDI, TMS, TCK) do not have a  $V_{CCO}$  requirement, and operate with either 2.5 V or 3.3 V input signalling levels. The output pin (TDO) is sourced from the  $V_{CCO}$  in bank 2, and for proper operation of LVTTTL 3.3 V levels, the bank should be supplied with 3.3 V.

Boundary-scan operation is independent of individual IOB configurations, and unaffected by package type. All IOBs, including un-bonded ones, are treated as independent 3-state bidirectional pins in a single scan chain. Retention of the bidirectional test capability after configuration facilitates

the testing of external interconnections, provided the user design or application is turned off.

Table 6 lists the boundary-scan instructions supported in Virtex-E FPGAs. Internal signals can be captured during EXTEST by connecting them to un-bonded or unused IOBs. They can also be connected to the unused outputs of IOBs defined as unidirectional input pins.

Before the device is configured, all instructions except USER1 and USER2 are available. After configuration, all instructions are available. During configuration, it is recommended that those operations using the boundary-scan register (SAMPLE/PRELOAD, INTEST, EXTEST) not be performed.

In addition to the test instructions outlined above, the boundary-scan circuitry can be used to configure the FPGA, and also to read back the configuration data.

tions and the desired performance. Finally, the router interconnects the blocks.

The PAR algorithms support fully automatic implementation of most designs. For demanding applications, however, the user can exercise various degrees of control over the process. User partitioning, placement, and routing information is optionally specified during the design-entry process. The implementation of highly structured designs can benefit greatly from basic floor planning.

The implementation software incorporates Timing Wizard® timing-driven placement and routing. Designers specify timing requirements along entire paths during design entry. The timing path analysis routines in PAR then recognize these user-specified requirements and accommodate them.

Timing requirements are entered on a schematic in a form directly relating to the system requirements, such as the targeted clock frequency, or the maximum allowable delay between two registers. In this way, the overall performance of the system along entire signal paths is automatically tailored to user-generated specifications. Specific timing information for individual nets is unnecessary.

## Configuration

Virtex-E devices are configured by loading configuration data into the internal configuration memory. Note that attempting to load an incorrect bitstream causes configuration to fail and can damage the device.

Some of the pins used for configuration are dedicated pins, while others can be re-used as general purpose inputs and outputs once configuration is complete.

The following are dedicated pins:

- Mode pins (M2, M1, M0)
- Configuration clock pin (CCLK)
- PROGRAM pin
- DONE pin
- Boundary-scan pins (TDI, TDO, TMS, TCK)

Depending on the configuration mode chosen, CCLK can be an output generated by the FPGA, or it can be generated externally and provided to the FPGA as an input. The PROGRAM pin must be pulled High prior to reconfiguration. Note that some configuration pins can act as outputs. For correct operation, these pins require a  $V_{CCO}$  of 3.3 V to permit LVTTTL operation. All of the pins affected are in banks 2

Table 8: Configuration Codes

Configuration Mode	M2	M1	M0	CCLK Direction	Data Width	Serial D <sub>out</sub>	Configuration Pull-ups
Master-serial mode	0	0	0	Out	1	Yes	No
Boundary-scan mode	1	0	1	N/A	1	No	No
SelectMAP mode	1	1	0	In	8	No	No
Slave-serial mode	1	1	1	In	1	Yes	No
Master-serial mode	1	0	0	Out	1	Yes	Yes

## Design Verification

In addition to conventional software simulation, FPGA users can use in-circuit debugging techniques. Because Xilinx devices are infinitely reprogrammable, designs can be verified in real time without the need for extensive sets of software simulation vectors.

The development system supports both software simulation and in-circuit debugging techniques. For simulation, the system extracts the post-layout timing information from the design database, and back-annotates this information into the net list for use by the simulator. Alternatively, the user can verify timing-critical portions of the design using the TRCE® static timing analyzer.

For in-circuit debugging, an optional download and read-back cable is available. This cable connects the FPGA in the target system to a PC or workstation. After downloading the design into the FPGA, the designer can single-step the logic, readback the contents of the flip-flops, and so observe the internal logic state. Simple modifications can be downloaded into the system in a matter of minutes.

or 3. The configuration pins needed for SelectMap (CS, Write) are located in bank 1.

## Configuration Modes

Virtex-E supports the following four configuration modes.

- Slave-serial mode
- Master-serial mode
- SelectMAP mode
- Boundary-scan mode (JTAG)

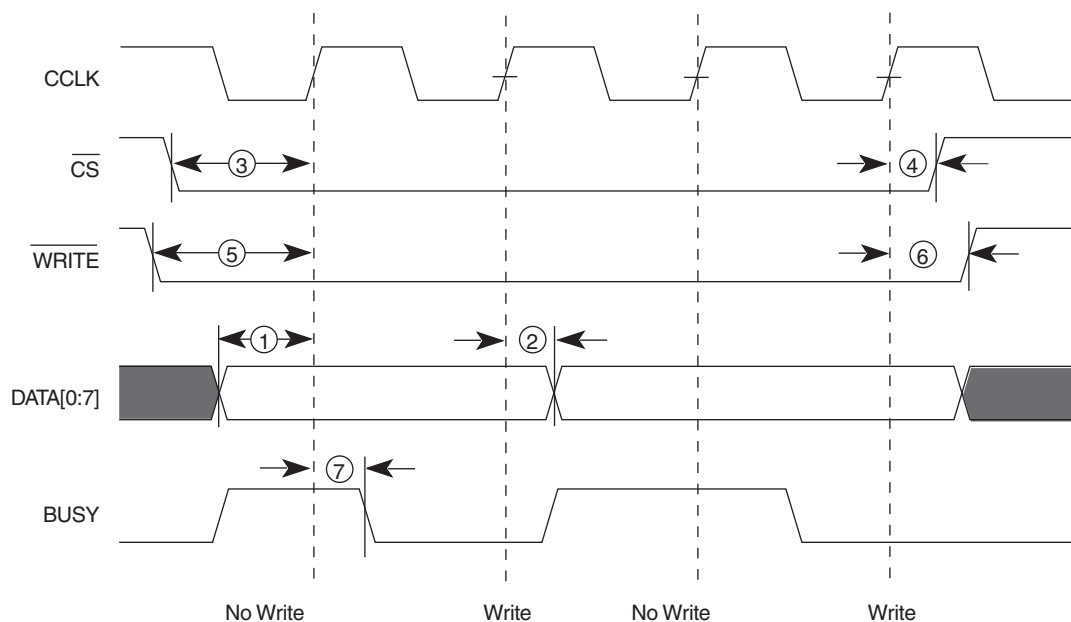
The Configuration mode pins (M2, M1, M0) select among these configuration modes with the option in each case of having the IOB pins either pulled up or left floating prior to configuration. The selection codes are listed in Table 8.

Configuration through the boundary-scan port is always available, independent of the mode selection. Selecting the boundary-scan mode simply turns off the other modes. The three mode pins have internal pull-up resistors, and default to a logic High if left unconnected. However, it is recommended to drive the configuration mode pins externally.

- either asserted or de-asserted. Otherwise an abort is initiated, as described below.
2. Drive data onto D[7:0]. Note that to avoid contention, the data source should not be enabled while  $\overline{\text{CS}}$  is Low and  $\overline{\text{WRITE}}$  is High. Similarly, while  $\overline{\text{WRITE}}$  is High, no more than one  $\overline{\text{CS}}$  should be asserted.
  3. At the rising edge of CCLK: If BUSY is Low, the data is accepted on this clock. If BUSY is High (from a previous write), the data is not accepted. Acceptance instead occurs on the first clock after BUSY goes Low, and the data must be held until this has happened.
  4. Repeat steps 2 and 3 until all the data has been sent.
  5. De-assert  $\overline{\text{CS}}$  and  $\overline{\text{WRITE}}$ .

Table 11: SelectMAP Write Timing Characteristics

	Description		Symbol	Values	Units
CCLK	D <sub>0-7</sub> Setup/Hold	1/2	T <sub>SMDCC</sub> /T <sub>SMCCD</sub>	5.0 / 1.7	ns, min
	$\overline{\text{CS}}$ Setup/Hold	3/4	T <sub>SMCSCC</sub> /T <sub>SMCCCS</sub>	7.0 / 1.7	ns, min
	$\overline{\text{WRITE}}$ Setup/Hold	5/6	T <sub>SMCCW</sub> /T <sub>SMWCC</sub>	7.0 / 1.7	ns, min
	BUSY Propagation Delay	7	T <sub>SMCKBY</sub>	12.0	ns, max
	Maximum Frequency		F <sub>CC</sub>	66	MHz, max
	Maximum Frequency with no handshake		F <sub>CCNH</sub>	50	MHz, max



DS022\_45\_071702

Figure 17: Write Operations

A flowchart for the write operation appears in [Figure 18](#). Note that if CCLK is slower than  $f_{\text{CCNH}}$ , the FPGA never asserts BUSY. In this case, the above handshake is unnecessary, and data can simply be entered into the FPGA every CCLK cycle.

### Abort

During a given assertion of  $\overline{\text{CS}}$ , the user cannot switch from a write to a read, or vice-versa. This action causes the cur-

rent packet command to be aborted. The device remains BUSY until the aborted operation has completed. Following an abort, data is assumed to be unaligned to word boundaries, and the FPGA requires a new synchronization word prior to accepting any new packets.

To initiate an abort during a write operation, de-assert  $\overline{\text{WRITE}}$ . At the rising edge of CCLK, an abort is initiated, as shown in [Figure 19](#).

## Initialization

The block SelectRAM+ memory can initialize during the device configuration sequence. The 16 initialization properties of 64 hex values each (a total of 4096 bits) set the initialization of each RAM. These properties appear in Table 17. Any initialization properties not explicitly set configure as zeros. Partial initialization strings pad with zeros. Initialization strings greater than 64 hex values generate an error. The RAMs can be simulated with the initialization values using generics in VHDL simulators and parameters in Verilog simulators.

## Initialization in VHDL and Synopsys

The block SelectRAM+ structures can be initialized in VHDL for both simulation and synthesis for inclusion in the EDIF output file. The simulation of the VHDL code uses a generic to pass the initialization. Synopsys FPGA compiler does not presently support generics. The initialization values instead attach as attributes to the RAM by a built-in Synopsys dc\_script. The translate\_off statement stops synthesis translation of the generic statements. The following code illustrates a module that employs these techniques.

Table 17: RAM Initialization Properties

Property	Memory Cells
INIT_00	255 to 0
INIT_01	511 to 256
INIT_02	767 to 512
INIT_03	1023 to 768
INIT_04	1279 to 1024
INIT_05	1535 to 1280
INIT_06	1791 to 2047
INIT_07	2047 to 1792
INIT_08	2303 to 2048
INIT_09	2559 to 2304
INIT_0a	2815 to 2560
INIT_0b	3071 to 2816
INIT_0c	3327 to 3072
INIT_0d	3583 to 3328
INIT_0e	3839 to 3584
INIT_0f	4095 to 3840

## Initialization in Verilog and Synopsys

The block SelectRAM+ structures can be initialized in Verilog for both simulation and synthesis for inclusion in the EDIF output file. The simulation of the Verilog code uses a defparam to pass the initialization. The Synopsys FPGA compiler does not presently support defparam. The initialization values instead attach as attributes to the RAM by a built-in Synopsys dc\_script. The translate\_off statement stops synthesis translation of the defparam statements. The following code illustrates a module that employs these techniques.

## Design Examples

### Creating a 32-bit Single-Port RAM

The true dual-read/write port functionality of the block SelectRAM+ memory allows a single port, 128 deep by 32-bit wide RAM to be created using a single block SelectRAM+ cell as shown in Table 35.

Interleaving the memory space, setting the LSB of the address bus of Port A to 1 ( $V_{CC}$ ), and the LSB of the address bus of Port B to 0 (GND), allows a 32-bit wide single port RAM to be created.

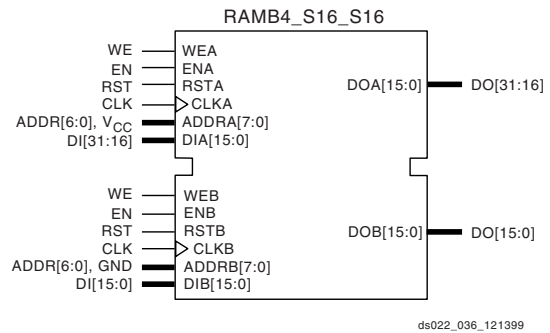


Figure 35: Single Port 128 x 32 RAM

### Creating Two Single-Port RAMs

The true dual-read/write port functionality of the block SelectRAM+ memory allows a single RAM to be split into two single port memories of 2K bits each as shown in Figure 36.

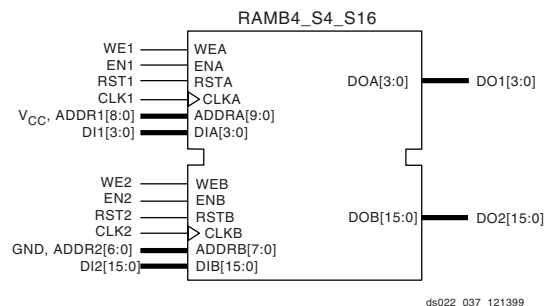


Figure 36: 512 x 4 RAM and 128 x 16 RAM

In this example, a 512K x 4 RAM (Port A) and a 128 x 16 RAM (Port B) are created out of a single block SelectRAM+. The address space for the RAM is split by fixing the MSB of Port A to 1 ( $V_{CC}$ ) for the upper 2K bits and the MSB of Port B to 0 (GND) for the lower 2K bits.

## Block Memory Generation

The CoreGen program generates memory structures using the block SelectRAM+ features. This program outputs VHDL or Verilog simulation code templates and an EDIF file for inclusion in a design.

## DS025-2 (v2.3) November 19, 2002



## Fundamentals

Modern bus applications, pioneered by the largest and most influential companies in the digital electronics industry, are commonly introduced with a new I/O standard tailored specifically to the needs of that application. The bus I/O standards provide specifications to other vendors who create products designed to interface with these applications. Each standard often has its own specifications for current, voltage, I/O buffering, and termination techniques.

The ability to provide the flexibility and time-to-market advantages of programmable logic is increasingly dependent on the capability of the programmable logic device to support an ever increasing variety of I/O standards

The SelectI/O resources feature highly configurable input and output buffers which provide support for a wide variety of I/O standards. As shown in [Table 18](#), each buffer type can support a variety of voltage requirements.

**Table 18: Virtex-E Supported I/O Standards**

I/O Standard	Output $V_{CCO}$	Input $V_{CCO}$	Input $V_{REF}$	Board Termination Voltage ( $V_{TT}$ )
LVTTTL	3.3	3.3	N/A	N/A
LVC MOS2	2.5	2.5	N/A	N/A
LVC MOS18	1.8	1.8	N/A	N/A
SSTL3 I & II	3.3	N/A	1.50	1.50
SSTL2 I & II	2.5	N/A	1.25	1.25
GTL	N/A	N/A	0.80	1.20
GTL+	N/A	N/A	1.0	1.50
HSTL I	1.5	N/A	0.75	0.75
HSTL III & IV	1.5	N/A	0.90	1.50
CTT	3.3	N/A	1.50	1.50
AGP-2X	3.3	N/A	1.32	N/A
PCI33_3	3.3	3.3	N/A	N/A
PCI66_3	3.3	3.3	N/A	N/A
BLVDS & LVDS	2.5	N/A	N/A	N/A
LVPECL	3.3	N/A	N/A	N/A

## Overview of Supported I/O Standards

This section provides a brief overview of the I/O standards supported by all Virtex-E devices.

While most I/O standards specify a range of allowed voltages, this document records typical voltage values only. Detailed information on each specification can be found on the Electronic Industry Alliance Jedec website at:

<http://www.jedec.org>

### LVTTTL — Low-Voltage TTL

The Low-Voltage TTL, or LVTTTL standard is a general purpose EIA/JESDSA standard for 3.3 V applications that uses an LVTTTL input buffer and a Push-Pull output buffer. This standard requires a 3.3 V output source voltage ( $V_{CCO}$ ), but does not require the use of a reference voltage ( $V_{REF}$ ) or a termination voltage ( $V_{TT}$ ).

### LVC MOS2 — Low-Voltage CMOS for 2.5 Volts

The Low-Voltage CMOS for 2.5 Volts or lower, or LVC MOS2 standard is an extension of the LVC MOS standard (JESD 8.-5) used for general purpose 2.5 V applications. This standard requires a 2.5 V output source voltage ( $V_{CCO}$ ), but does not require the use of a reference voltage ( $V_{REF}$ ) or a board termination voltage ( $V_{TT}$ ).

### LVC MOS18 — 1.8 V Low Voltage CMOS

This standard is an extension of the LVC MOS standard. It is used in general purpose 1.8 V applications. The use of a reference voltage ( $V_{REF}$ ) or a board termination voltage ( $V_{TT}$ ) is not required.

### PCI — Peripheral Component Interface

The Peripheral Component Interface, or PCI standard specifies support for both 33 MHz and 66 MHz PCI bus applications. It uses a LVTTTL input buffer and a Push-Pull output buffer. This standard does not require the use of a reference voltage ( $V_{REF}$ ) or a board termination voltage ( $V_{TT}$ ), however, it does require a 3.3 V output source voltage ( $V_{CCO}$ ).

### GTL — Gunning Transceiver Logic Terminated

The Gunning Transceiver Logic, or GTL standard is a high-speed bus standard (JESD8.3) invented by Xerox. Xilinx has implemented the terminated variation for this standard. This standard requires a differential amplifier input buffer and a Open Drain output buffer.

### GTL+ — Gunning Transceiver Logic Plus

The Gunning Transceiver Logic Plus, or GTL+ standard is a high-speed bus standard (JESD8.3) first used by the Pentium Pro processor.

### HSTL — High-Speed Transceiver Logic

The High-Speed Transceiver Logic, or HSTL standard is a general purpose high-speed, 1.5 V bus standard sponsored by IBM (EIA/JESD 8-6). This standard has four variations or classes. SelectI/O devices support Class I, III, and IV. This

The LVTTTL OBUFT additionally can support one of two slew rate modes to minimize bus transients. By default, the slew rate for each output buffer is reduced to minimize power bus transients when switching non-critical signals.

LVTTTL 3-state output buffers have selectable drive strengths.

The format for LVTTTL OBUFT symbol names is as follows.

OBUFT\_<slew\_rate>\_<drive\_strength>

<slew\_rate> can be either F (Fast), or S (Slow) and <drive\_strength> is specified in milliamps (2, 4, 6, 8, 12, 16, or 24).

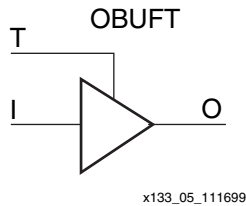


Figure 41: 3-State Output Buffer Symbol (OBUFT)

The following list details variations of the OBUFT symbol.

- OBUFT
- OBUFT\_S\_2
- OBUFT\_S\_4
- OBUFT\_S\_6
- OBUFT\_S\_8
- OBUFT\_S\_12
- OBUFT\_S\_16
- OBUFT\_S\_24
- OBUFT\_F\_2
- OBUFT\_F\_4
- OBUFT\_F\_6
- OBUFT\_F\_8
- OBUFT\_F\_12
- OBUFT\_F\_16
- OBUFT\_F\_24
- OBUFT\_LVCMOS2
- OBUFT\_PCI33\_3
- OBUFT\_PCI66\_3
- OBUFT\_GTL
- OBUFT\_GTLP
- OBUFT\_HSTL\_I
- OBUFT\_HSTL\_III
- OBUFT\_HSTL\_IV
- OBUFT\_SSTL3\_I
- OBUFT\_SSTL3\_II
- OBUFT\_SSTL2\_I
- OBUFT\_SSTL2\_II
- OBUFT\_CTT
- OBUFT\_AGP
- OBUFT\_LVCMOS18
- OBUFT\_LVDS
- OBUFT\_LVPECL

The Virtex-E series supports eight banks for the HQ and PQ packages. The CS package supports four  $V_{CCO}$  banks.

The SelectI/O OBUFT placement restrictions require that within a given  $V_{CCO}$  bank each OBUFT share the same output source drive voltage. Input buffers of any type and output buffers that do not require  $V_{CCO}$  can be placed within the same  $V_{CCO}$  bank.

The LOC property can specify a location for the OBUFT.

3-state output buffers and bidirectional buffers can have either a weak pull-up resistor, a weak pull-down resistor, or a weak “keeper” circuit. Control this feature by adding the appropriate symbol to the output net of the OBUFT (PULLUP, PULLDOWN, or KEEPER).

The weak “keeper” circuit requires the input buffer within the IOB to sample the I/O signal. So, OBUFTs programmed for an I/O standard that requires a  $V_{REF}$  have automatic placement of a  $V_{REF}$  in the bank with an OBUFT configured with a weak “keeper” circuit. This restriction does not affect most circuit design as applications using an OBUFT configured with a weak “keeper” typically implement a bidirectional I/O. In this case the IBUF (and the corresponding  $V_{REF}$ ) are explicitly placed.

The LOC property can specify a location for the OBUFT.

### IOBUF

Use the IOBUF symbol for bidirectional signals that require both an input buffer and a 3-state output buffer with an active high 3-state pin. The generic input/output buffer IOBUF appears in Figure 42.

The extension to the base name defines which I/O standard the IOBUF uses. With no extension specified for the generic IOBUF symbol, the assumed standard is LVTTTL input buffer and slew rate limited LVTTTL with 12 mA drive strength for the output buffer.

The LVTTTL IOBUF additionally can support one of two slew rate modes to minimize bus transients. By default, the slew rate for each output buffer is reduced to minimize power bus transients when switching non-critical signals.

LVTTTL bidirectional buffers have selectable output drive strengths.

The format for LVTTTL IOBUF symbol names is as follows.

IOBUF\_<slew\_rate>\_<drive\_strength>

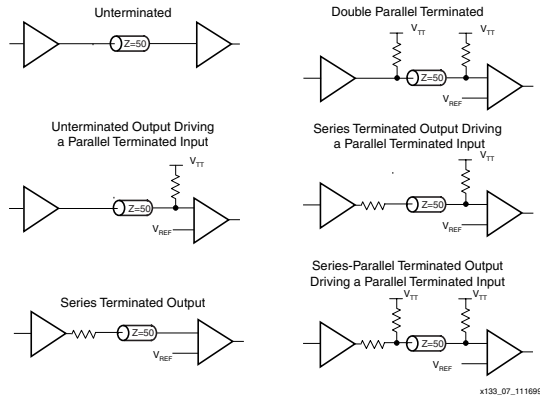
<slew\_rate> can be either F (Fast), or S (Slow) and <drive\_strength> is specified in milliamps (2, 4, 6, 8, 12, 16, or 24).



Input termination techniques include the following:

- None
- Parallel (Shunt)

These termination techniques can be applied in any combination. A generic example of each combination of termination methods appears in **Figure 43**.



**Figure 43: Overview of Standard Input and Output Termination Methods**

### Simultaneous Switching Guidelines

Ground bounce can occur with high-speed digital ICs when multiple outputs change states simultaneously, causing undesired transient behavior on an output, or in the internal logic. This problem is also referred to as the Simultaneous Switching Output (SSO) problem.

Ground bounce is primarily due to current changes in the combined inductance of ground pins, bond wires, and ground metallization. The IC internal ground level deviates from the external system ground level for a short duration (a few nanoseconds) after multiple outputs change state simultaneously.

Ground bounce affects stable Low outputs and all inputs because they interpret the incoming signal by comparing it to the internal ground. If the ground bounce amplitude exceeds the actual instantaneous noise margin, then a non-changing input can be interpreted as a short pulse with a polarity opposite to the ground bounce.

**Table 21** provides the guidelines for the maximum number of simultaneously switching outputs allowed per output power/ground pair to avoid the effects of ground bounce. Refer to **Table 22** for the number of effective output power/ground pairs for each Virtex-E device and package combination.

**Table 21: Guidelines for Maximum Number of Simultaneously Switching Outputs per Power/Ground Pair**

Standard	Package
	BGA, FGA
LVTTL Slow Slew Rate, 2 mA drive	68
LVTTL Slow Slew Rate, 4 mA drive	41
LVTTL Slow Slew Rate, 6 mA drive	29
LVTTL Slow Slew Rate, 8 mA drive	22
LVTTL Slow Slew Rate, 12 mA drive	17
LVTTL Slow Slew Rate, 16 mA drive	14
LVTTL Slow Slew Rate, 24 mA drive	9
LVTTL Fast Slew Rate, 2 mA drive	40
LVTTL Fast Slew Rate, 4 mA drive	24
LVTTL Fast Slew Rate, 6 mA drive	17
LVTTL Fast Slew Rate, 8 mA drive	13
LVTTL Fast Slew Rate, 12 mA drive	10
LVTTL Fast Slew Rate, 16 mA drive	8
LVTTL Fast Slew Rate, 24 mA drive	5
LVC MOS	10
PCI	8
GTL	4
GTL+	4
HSTL Class I	18
HSTL Class III	9
HSTL Class IV	5
SSTL2 Class I	15
SSTL2 Class II	10
SSTL3 Class I	11
SSTL3 Class II	7
CTT	14
AGP	9

Note: This analysis assumes a 35 pF load for each output.

**Table 22: Virtex-E Extended Memory Family Equivalent Power/Ground Pairs**

Pkg/Part	XCV405E	XCV812E
BG560		56
FG676	56	
FG900		

## Application Examples

Creating a design with the SelectI/O features requires the instantiation of the desired library symbol within the design code. At the board level, designers need to know the termination techniques required for each I/O standard.

This section describes some common application examples illustrating the termination techniques recommended by each of the standards supported by the SelectI/O features.

### Termination Examples

Circuit examples involving typical termination techniques for each of the SelectI/O standards follow. For a full range of accepted values for the DC voltage specifications for each standard, refer to the table associated with each figure.

The resistors used in each termination technique example and the transmission lines depicted represent board level components and are not meant to represent components on the device.

#### GTL

A sample circuit illustrating a valid termination technique for GTL is shown in Figure 44. Table 23 lists DC voltage specifications.

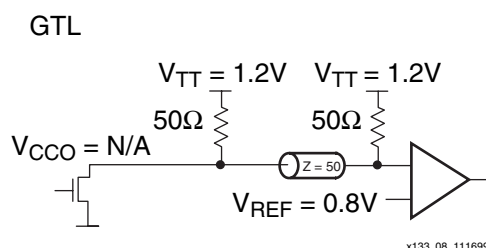


Figure 44: Terminated GTL

Table 23: GTL Voltage Specifications

Parameter	Min	Typ	Max
$V_{CCO}$	-	N/A	-
$V_{REF} = N \times V_{TT}^1$	0.74	0.8	0.86
$V_{TT}$	1.14	1.2	1.26
$V_{IH} = V_{REF} + 0.05$	0.79	0.85	-
$V_{IL} = V_{REF} - 0.05$	-	0.75	0.81
$V_{OH}$	-	-	-
$V_{OL}$	-	0.2	0.4
$I_{OH}$ at $V_{OH}$ (mA)	-	-	-
$I_{OL}$ at $V_{OL}$ (mA) at 0.4V	32	-	-
$I_{OL}$ at $V_{OL}$ (mA) at 0.2V	-	-	40

Note: N must be greater than or equal to 0.653 and less than or equal to 0.68.

#### GTL+

A sample circuit illustrating a valid termination technique for GTL+ appears in Figure 45. DC voltage specifications appear in Table 24.

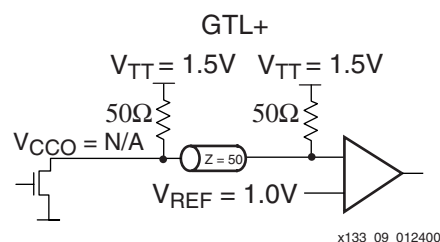


Figure 45: Terminated GTL+

Table 24: GTL+ Voltage Specifications

Parameter	Min	Typ	Max
$V_{CCO}$	-	-	-
$V_{REF} = N \times V_{TT}^1$	0.88	1.0	1.12
$V_{TT}$	1.35	1.5	1.65
$V_{IH} = V_{REF} + 0.1$	0.98	1.1	-
$V_{IL} = V_{REF} - 0.1$	-	0.9	1.02
$V_{OH}$	-	-	-
$V_{OL}$	0.3	0.45	0.6
$I_{OH}$ at $V_{OH}$ (mA)	-	-	-
$I_{OL}$ at $V_{OL}$ (mA) at 0.6V	36	-	-
$I_{OL}$ at $V_{OL}$ (mA) at 0.3V	-	-	48

Note: N must be greater than or equal to 0.653 and less than or equal to 0.68.

## SSTL2\_II

A sample circuit illustrating a valid termination technique for SSTL2\_II appears in Figure 52. DC voltage specifications appear in Table 31.

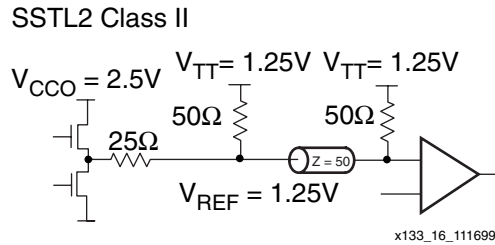


Figure 52: Terminated SSTL2 Class II

Table 31: SSTL2\_II Voltage Specifications

Parameter	Min	Typ	Max
$V_{CCO}$	2.3	2.5	2.7
$V_{REF} = 0.5 \times V_{CCO}$	1.15	1.25	1.35
$V_{TT} = V_{REF} + N^{(1)}$	1.11	1.25	1.39
$V_{IH} = V_{REF} + 0.18$	1.33	1.43	3.0 <sup>(2)</sup>
$V_{IL} = V_{REF} - 0.18$	-0.3 <sup>(3)</sup>	1.07	1.17
$V_{OH} = V_{REF} + 0.8$	1.95	-	-
$V_{OL} = V_{REF} - 0.8$	-	-	0.55
$I_{OH}$ at $V_{OH}$ (mA)	-15.2	-	-
$I_{OL}$ at $V_{OL}$ (mA)	15.2	-	-

### Notes:

- N must be greater than or equal to -0.04 and less than or equal to 0.04.
- $V_{IH}$  maximum is  $V_{CCO} + 0.3$ .
- $V_{IL}$  minimum does not conform to the formula.

## CTT

A sample circuit illustrating a valid termination technique for CTT appear in Figure 53. DC voltage specifications appear in Table 32.

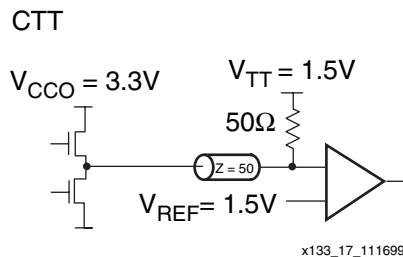


Figure 53: Terminated CTT

Table 32: CTT Voltage Specifications

Parameter	Min	Typ	Max
$V_{CCO}$	2.05 <sup>(1)</sup>	3.3	3.6
$V_{REF}$	1.35	1.5	1.65
$V_{TT}$	1.35	1.5	1.65
$V_{IH} = V_{REF} + 0.2$	1.55	1.7	-
$V_{IL} = V_{REF} - 0.2$	-	1.3	1.45
$V_{OH} = V_{REF} + 0.4$	1.75	1.9	-
$V_{OL} = V_{REF} - 0.4$	-	1.1	1.25
$I_{OH}$ at $V_{OH}$ (mA)	-8	-	-
$I_{OL}$ at $V_{OL}$ (mA)	8	-	-

### Notes:

- Timing delays are calculated based on  $V_{CCO}$  min of 3.0V.

## PCI33\_3 & PCI66\_3

PCI33\_3 or PCI66\_3 require no termination. DC voltage specifications appear in Table 33.

Table 33: PCI33\_3 and PCI66\_3 Voltage Specifications

Parameter	Min	Typ	Max
$V_{CCO}$	3.0	3.3	3.6
$V_{REF}$	-	-	-
$V_{TT}$	-	-	-
$V_{IH} = 0.5 \times V_{CCO}$	1.5	1.65	$V_{CCO} + 0.5$
$V_{IL} = 0.3 \times V_{CCO}$	-0.5	0.99	1.08
$V_{OH} = 0.9 \times V_{CCO}$	2.7	-	-
$V_{OL} = 0.1 \times V_{CCO}$	-	-	0.36
$I_{OH}$ at $V_{OH}$ (mA)	Note 1	-	-
$I_{OL}$ at $V_{OL}$ (mA)	Note 1	-	-

Note 1: Tested according to the relevant specification.

Table 44: Bidirectional I/O Library Macros (Continued)

Name	Inputs	Bidirectional	Outputs
IOBUFDS_LD_LVDS	D, T, G	IO, IOB	Q
IOBUFDS_LDE_LVDS	D, T, GE, G	IO, IOB	Q
IOBUFDS_LDC_LVDS	D, T, G, CLR	IO, IOB	Q
IOBUFDS_LDCE_LVDS	D, T, GE, G, CLR	IO, IOB	Q
IOBUFDS_LDP_LVDS	D, T, G, PRE	IO, IOB	Q
IOBUFDS_LDPE_LVDS	D, T, GE, G, PRE	IO, IOB	Q

## Revision History

The following table shows the revision history for this document.

Date	Version	Revision
03/23/00	1.0	Initial Xilinx release.
08/01/00	1.1	Accumulated edits and fixes. Upgrade to Preliminary. Preview -8 numbers added. Reformatted to adhere to corporate documentation style guidelines. Minor changes in BG560 pin-out table.
09/19/00	1.2	<ul style="list-style-type: none"> <li>In Table 3 (Module 4), <b>FG676 Fine-Pitch BGA — XCV405E</b>, the following pins are no longer labeled as VREF: B7, G16, G26, W26, AF20, AF8, Y1, H1.</li> <li>Min values added to <b>Virtex-E Electrical Characteristics</b> tables.</li> </ul>
11/20/00	1.3	<ul style="list-style-type: none"> <li>Updated speed grade -8 numbers in <b>Virtex-E Electrical Characteristics</b> tables (Module 3).</li> <li>Updated minimums in Table 11 (Module 2), and added notes to Table 12 (Module 2).</li> <li>Added to note 2 of <b>Absolute Maximum Ratings</b> (Module 3).</li> <li>Changed all minimum hold times to –0.4 for <b>Global Clock Set-Up and Hold for LVTTTL Standard, with DLL</b> (Module 3).</li> <li>Revised maximum T<sub>DLLPW</sub> in -6 speed grade for <b>DLL Timing Parameters</b> (Module 3).</li> </ul>
04/02/01	1.4	<ul style="list-style-type: none"> <li>In <b>Table 4, FG676 Fine-Pitch BGA — XCV405E</b>, pin B19 is no longer labeled as VREF, and pin G16 is now labeled as VREF.</li> <li>Updated values in <b>Virtex-E Switching Characteristics</b> tables.</li> <li>Converted data sheet to modularized format.</li> </ul>
04/19/01	1.5	Modified <b>Figure 30</b> , which shows “DLL Generation of 4x Clock in Virtex-E Devices.”
07/23/01	1.6	Made minor edits to text under <b>Configuration</b> .
11/16/01	2.0	Added warning under <b>Configuration</b> section that attempting to load an incorrect bitstream causes configuration to fail and can damage the device.
07/17/02	2.1	Data sheet designation upgraded from Preliminary to Production.
09/10/02	2.2	Added clarifications in the <b>Input/Output Block</b> , <b>Configuration</b> , <b>Boundary-Scan Mode</b> , and <b>Block SelectRAM+ Memory</b> sections. Revised <b>Figure 18</b> , <b>Table 11</b> , and <b>Table 36</b> .
11/19/02	2.3	<ul style="list-style-type: none"> <li>Added clarification in the <b>Boundary Scan</b> section.</li> <li>Removed last sentence regarding deactivation of duty-cycle correction in <b>Duty Cycle Correction Property</b> section.</li> </ul>

## Virtex-E Switching Characteristics

All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation net list. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). Values apply to all Virtex-E devices unless otherwise noted.

### IOB Input Switching Characteristics

Input delays associated with the pad are specified for LVTTTL levels. For other standards, adjust the delays with the values shown in “IOB Input Switching Characteristics Standard Adjustments” on page 6.

			Speed Grade <sup>(2)</sup>				Units
Description <sup>(1)</sup>	Symbol	Device	Min	-8	-7	-6	
Propagation Delays							
Pad to I output, no delay	T <sub>IOPI</sub>	All	0.43	0.8	0.8	0.8	ns, max
Pad to I output, with delay	T <sub>IOPID</sub>	XCV405E	0.51	1.0	1.0	1.0	ns, max
		XCV812E	0.55	1.1	1.1	1.1	ns, max
Pad to output IQ via transparent latch, no delay	T <sub>IOPLI</sub>	All	0.75	1.4	1.5	1.6	ns, max
Pad to output IQ via transparent latch, with delay	T <sub>IOPLID</sub>	XCV405E	1.55	3.5	3.6	3.7	ns, max
		XCV812E	1.55	3.5	3.6	3.7	ns, max
Propagation Delays							
Clock							
Minimum Pulse Width, High	T <sub>CH</sub>	All	0.56	1.2	1.3	1.4	ns, min
Minimum Pulse Width, Low	T <sub>CL</sub>		0.56	1.2	1.3	1.4	ns, min
Clock CLK to output IQ	T <sub>IOCKIQ</sub>		0.18	0.4	0.7	0.7	ns, max
Setup and Hold Times with respect to Clock at IOB Input Register							
Pad, no delay	T <sub>IO PICK</sub> / T <sub>IOICKP</sub>	All	0.69 / 0	1.3 / 0	1.4 / 0	1.5 / 0	ns, min
Pad, with delay	T <sub>IO PICKD</sub> / T <sub>IOICKPD</sub>	XCV405E	1.49 / 0	3.4 / 0	3.5 / 0	3.5 / 0	ns, min
		XCV812E	1.49 / 0	3.4 / 0	3.5 / 0	3.5 / 0	ns, min
ICE input	T <sub>IOICECK</sub> / T <sub>IOCKICE</sub>	All	0.28 / 0.0	0.55 / 0.01	0.7 / 0.01	0.7 / 0.01	ns, min
SR input (IFF, synchronous)	T <sub>IOSRCKI</sub>	All	0.38	0.8	0.9	1.0	ns, min
Set/Reset Delays							
SR input to IQ (asynchronous)	T <sub>IOSRIQ</sub>	All	0.54	1.1	1.2	1.4	ns, max
GSR to output IQ	T <sub>GSRQ</sub>	All	3.88	7.6	8.5	9.7	ns, max

#### Notes:

1. A Zero “0” Hold Time listing indicates no hold time or a negative hold time. Negative values can not be guaranteed “best-case”, but if a “0” is listed, there is no positive hold time.
2. Input timing i for LVTTTL is measured at 1.4 V. For other I/O standards, see Table 3.

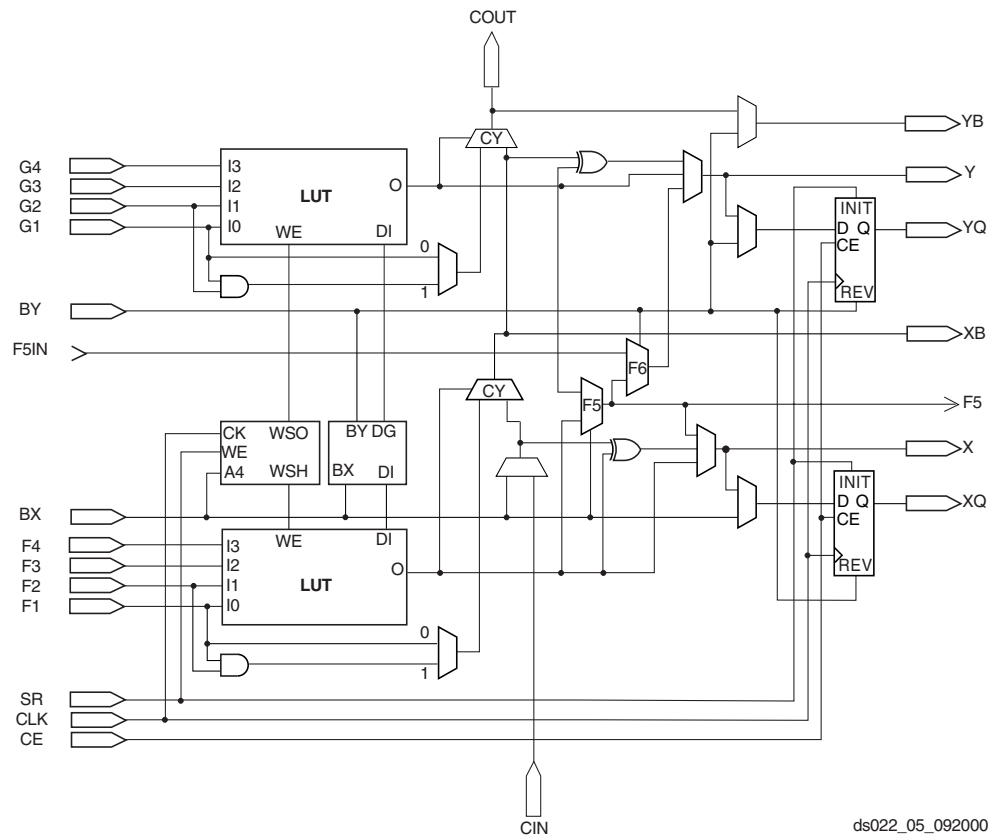


Figure 2: Detailed View of Virtex-E Slice



## CLB Distributed RAM Switching Characteristics

Description <sup>(1)</sup>	Symbol	Speed Grade				Units
		Min	-8	-7	-6	
Sequential Delays						
Clock CLK to X/Y outputs (WE active) 16 x 1 mode	T <sub>SHCKO16</sub>	0.67	1.38	1.5	1.7	ns, max
Clock CLK to X/Y outputs (WE active) 32 x 1 mode	T <sub>SHCKO32</sub>	0.84	1.66	1.9	2.1	ns, max
Shift-Register Mode						
Clock CLK to X/Y outputs	T <sub>REG</sub>	1.25	2.39	2.9	3.2	ns, max
Setup and Hold Times before/after Clock CLK						
F/G address inputs	T <sub>AS</sub> /T <sub>AH</sub>	0.19 / 0	0.38 / 0	0.42 / 0	0.47 / 0	ns, min
BX/BY data inputs (DIN)	T <sub>DS</sub> /T <sub>DH</sub>	0.44 / 0	0.87 / 0	0.97 / 0	1.09 / 0	ns, min
SR input (WE)	T <sub>WS</sub> /T <sub>WH</sub>	0.29 / 0	0.57 / 0	0.7 / 0	0.8 / 0	ns, min
Clock CLK						
Minimum Pulse Width, High	T <sub>WPH</sub>	0.96	1.9	2.1	2.4	ns, min
Minimum Pulse Width, Low	T <sub>WPL</sub>	0.96	1.9	2.1	2.4	ns, min
Minimum clock period to meet address write cycle time	T <sub>WC</sub>	1.92	3.8	4.2	4.8	ns, min
Shift-Register Mode						
Minimum Pulse Width, High	T <sub>SRPH</sub>	1.0	1.9	2.1	2.4	ns, min
Minimum Pulse Width, Low	T <sub>SRPL</sub>	1.0	1.9	2.1	2.4	ns, min

### Notes:

1. A Zero "0" Hold Time listing indicates no hold time or a negative hold time. Negative values can not be guaranteed "best-case", but if a "0" is listed, there is no positive hold time.

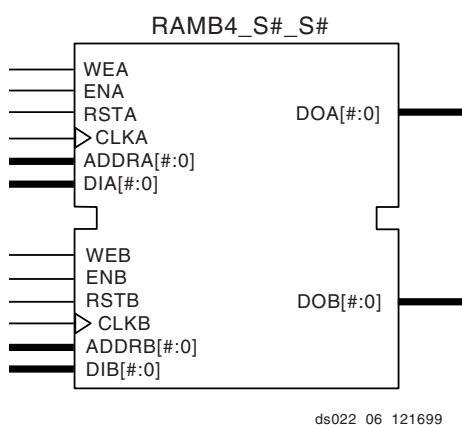


Figure 3: Dual-Port Block SelectRAM

## Virtex-E Pin-to-Pin Input Parameter Guidelines

All devices are 100% functionally tested. Listed below are representative values for typical pin locations and normal clock loading. Values are expressed in nanoseconds unless otherwise noted.

### Global Clock Set-Up and Hold for LVTTTL Standard, *with* DLL

Description <sup>(1)</sup>	Symbol	Device <sup>(3)</sup>	Speed Grade <sup>(2)</sup>				Units
			Min	-8	-7	-6	
Input Setup and Hold Time Relative to Global Clock Input Signal for LVTTTL Standard.  For data input with different standards, adjust the setup time delay by the values shown in “IOB Input Switching Characteristics Standard Adjustments” on page 6.							
No Delay	T <sub>PSDLL</sub> /T <sub>PHDLL</sub>	XCV405E	1.5 / –0.4	1.5 / –0.4	1.6 / –0.4	1.7 / –0.4	ns
Global Clock and IFF, with DLL		XCV812E	1.5 / –0.4	1.5 / –0.4	1.6 / –0.4	1.7 / –0.4	ns

#### Notes:

1. IFF = Input Flip-Flop or Latch
2. Setup time is measured relative to the Global Clock input signal with the fastest route and the lightest load. Hold time is measured relative to the Global Clock input signal with the slowest route and heaviest load.
3. DLL output jitter is already included in the timing calculation.

### Global Clock Set-Up and Hold for LVTTTL Standard, *without* DLL

Description <sup>(1)</sup>	Symbol	Device <sup>(3)</sup>	Speed Grade <sup>(2)</sup>				Units
			Min	-8	-7	-6	
Input Setup and Hold Time Relative to Global Clock Input Signal for LVTTTL Standard.  For data input with different standards, adjust the setup time delay by the values shown in “IOB Input Switching Characteristics Standard Adjustments” on page 6.							
Full Delay	T <sub>PSFD</sub> /T <sub>PHFD</sub>	XCV405E	2.3 / 0	2.3 / 0	2.3 / 0	2.3 / 0	ns
Global Clock and IFF, without DLL		XCV812E	2.5 / 0	2.5 / 0	2.5 / 0	2.5 / 0	ns

#### Notes:

1. IFF = Input Flip-Flop or Latch
2. Setup time is measured relative to the Global Clock input signal with the fastest route and the lightest load. Hold time is measured relative to the Global Clock input signal with the slowest route and heaviest load.
3. A Zero “0” Hold Time listing indicates no hold time or a negative hold time. Negative values can not be guaranteed “best-case”, but if a “0” is listed, there is no positive hold time.

## DLL Clock Tolerance, Jitter, and Phase Information

All DLL output jitter and phase specifications determined through statistical measurement at the package pins using a clock mirror configuration and matched drivers.

Description	Symbol	$F_{CLKIN}$	CLKDLLHF		CLKDLL		Units
			Min	Max	Min	Max	
Input Clock Period Tolerance	$T_{IPTOL}$		-	1.0	-	1.0	ns
Input Clock Jitter Tolerance (Cycle to Cycle)	$T_{IJITCC}$		-	± 150	-	± 300	ps
Time Required for DLL to Acquire Lock <sup>(6)</sup>	$T_{LOCK}$	> 60 MHz	-	20	-	20	μs
		50 - 60 MHz	-	-	-	25	μs
		40 - 50 MHz	-	-	-	50	μs
		30 - 40 MHz	-	-	-	90	μs
		25 - 30 MHz	-	-	-	120	μs
Output Jitter (cycle-to-cycle) for any DLL Clock Output <sup>(1)</sup>	$T_{OJITCC}$			± 60		± 60	ps
Phase Offset between CLKIN and CLKO <sup>(2)</sup>	$T_{PHIO}$			± 100		± 100	ps
Phase Offset between Clock Outputs on the DLL <sup>(3)</sup>	$T_{PHOO}$			± 140		± 140	ps
Maximum Phase Difference between CLKIN and CLKO <sup>(4)</sup>	$T_{PHIOM}$			± 160		± 160	ps
Maximum Phase Difference between Clock Outputs on the DLL <sup>(5)</sup>	$T_{PHOOM}$			± 200		± 200	ps

### Notes:

- Output Jitter** is cycle-to-cycle jitter measured on the DLL output clock and is based on a maximum tap delay resolution, *excluding* input clock jitter.
- Phase Offset between CLKIN and CLKO** is the worst-case fixed time difference between rising edges of CLKIN and CLKO, *excluding* Output Jitter and input clock jitter.
- Phase Offset between Clock Outputs on the DLL** is the worst-case fixed time difference between rising edges of any two DLL outputs, *excluding* Output Jitter and input clock jitter.
- Maximum Phase Difference between CLKIN and CLKO** is the sum of Output Jitter and Phase Offset between CLKIN and CLKO, or the greatest difference between CLKIN and CLKO rising edges due to DLL alone (*excluding* input clock jitter).
- Maximum Phase Difference between Clock Outputs on the DLL** is the sum of Output Jitter and Phase Offset between any two DLL clock outputs, or the greatest difference between any two DLL output rising edges due to DLL alone (*excluding* input clock jitter).
- Add 30% to the value for Industrial grade parts.

## Revision History

The following table shows the revision history for this document.

Date	Version	Revision
03/23/00	1.0	Initial Xilinx release.
08/01/00	1.1	Accumulated edits and fixes. Upgrade to Preliminary. Preview -8 numbers added. Reformatted to adhere to corporate documentation style guidelines. Minor changes in BG560 pin-out table.
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Table 3: FG676 Fine-Pitch BGA — XCV405E

Bank	Pin Description	Pin #
7	IO_L182P_YY	E4
2	CCLK	D24
3	DONE	AB21
NA	DXN	AB7
NA	DXP	Y8
NA	M0	AD4
NA	M1	W7
NA	M2	AB6
NA	PROGRAM	AA22
NA	TCK	E6
NA	TDI	D22
2	TDO	C23
NA	TMS	F5
0	NC	A9
0	NC	A10
0	NC	B4
0	NC	B12
0	NC	D13
1	NC	A13
1	NC	A16
1	NC	A24
1	NC	B15
1	NC	B17
2	NC	D25
2	NC	H26
2	NC	K26
2	NC	M25
2	NC	N26
3	NC	AC25
3	NC	P26
3	NC	R26
3	NC	T26
3	NC	U26

Table 3: FG676 Fine-Pitch BGA — XCV405E

Bank	Pin Description	Pin #
4	NC	AE15
4	NC	AF14
4	NC	AF16
4	NC	AF18
4	NC	AF23
5	NC	AE12
5	NC	AF3
5	NC	AF10
5	NC	AF11
5	NC	Y13
6	NC	AC1
6	NC	P1
6	NC	R2
6	NC	T1
6	NC	V1
7	NC	D1
7	NC	J1
7	NC	L1
7	NC	M1
7	NC	N1
NA	NC	T25
NA	NC	T2
NA	NC	P2
NA	NC	N25
NA	NC	L25
NA	NC	L2
NA	NC	F6
NA	NC	F25
NA	NC	F21
NA	NC	F2
NA	NC	C26
NA	NC	C25
NA	NC	C2
NA	NC	C1
NA	NC	B6

## FG676 Differential Pin Pairs

Virtex-E Extended Memory devices have differential pin pairs that can also provide other functions when not used as a differential pair. A ✓ in the AO column indicates that the pin pair can be used as an asynchronous output for all devices provided in this package.

Pairs with a note number in the AO column are device dependent. They can have asynchronous outputs if the pin pair is in the same CLB row and column in the device. Numbers in this column refer to footnotes that indicate which devices have pin pairs that can be asynchronous outputs. The Other Functions column indicates alternative function(s) not available when the pair is used as a differential pair or differential clock.

**Table 4: FG676 Fine-Pitch BGA Differential Pin Pair Summary — XCV405E**

Pair	Bank	P Pin	N Pin	AO	Other Functions
Global Differential Clock					
3	0	E13	B13	NA	IO_DLL_L21N
2	1	C13	F14	NA	IO_DLL_L21P
1	5	AB13	AF13	NA	IO_DLL_L115N
0	4	AA14	AC14	NA	IO_DLL_L115P
IOLVDS					
Total Pairs: 183, Asynchronous Output Pairs: 97					
0	0	F7	C4	NA	-
1	0	C5	G8	✓	-
2	0	E7	D6	✓	VREF
3	0	F8	A4	NA	-
4	0	D7	B5	NA	-
5	0	G9	E8	✓	VREF
6	0	F9	A5	✓	-
7	0	C7	D8	NA	-
8	0	E9	B7	NA	-
9	0	D9	A7	NA	-
10	0	G10	B8	NA	VREF
11	0	F10	C9	✓	-
12	0	E10	A8	NA	-
13	0	D10	G11	✓	-
14	0	F11	B10	✓	-
15	0	E11	C10	NA	-

**Table 4: FG676 Fine-Pitch BGA Differential Pin Pair Summary — XCV405E**

Pair	Bank	P Pin	N Pin	AO	Other Functions
16	0	D11	G12	✓	-
17	0	F12	C11	✓	VREF
18	0	E12	A11	✓	-
19	0	C12	D12	NA	-
20	0	H13	A12	NA	VREF
21	1	F14	B13	NA	IO_LVDS_DLL
22	1	F13	E14	NA	-
23	1	A14	D14	NA	VREF
24	1	H14	C14	NA	-
25	1	C15	G14	✓	-
26	1	D15	E15	✓	VREF
27	1	F15	C16	✓	-
28	1	D16	G15	-	-
29	1	A17	E16	✓	-
30	1	E17	C17	✓	-
31	1	D17	F16	NA	-
32	1	C18	F17	✓	-
33	1	G16	A18	✓	VREF
34	1	G17	C19	✓	-
35	1	B19	D18	NA	-
36	1	E18	D19	NA	-
37	1	B20	F18	✓	-
38	1	C20	G19	✓	VREF
39	1	E19	G18	✓	-
40	1	D20	A21	✓	-
41	1	C21	F19	✓	VREF
42	1	E20	B22	✓	-
43	1	D21	A23	2	-
44	1	E21	C22	✓	CS
45	2	E23	F22	✓	DIN, D0
46	2	E24	F20	✓	-
47	2	G21	G22	2	-
48	2	F24	H20	1	VREF
49	2	E25	H21	1	-

**Table 4: FG676 Fine-Pitch BGA Differential Pin Pair Summary — XCV405E**

Pair	Bank	P Pin	N Pin	AO	Other Functions
118	5	AA12	AD12	√	-
119	5	AC12	AB12	√	VREF
120	5	AD11	Y12	√	-
121	5	AB11	AD10	NA	-
122	5	AC11	AE10	√	-
123	5	AC10	AA11	√	-
124	5	Y11	AD9	NA	-
125	5	AB10	AF9	√	-
126	5	AD8	AA10	√	VREF
127	5	AE8	Y10	√	-
128	5	AC9	AF8	NA	-
129	5	AF7	AB9	NA	-
130	5	AA9	AF6	√	-
131	5	AC8	AC7	√	VREF
132	5	AD6	Y9	√	-
133	5	AE5	AA8	√	-
134	5	AC6	AB8	√	VREF
135	5	AD5	AA7	√	-
136	5	AF4	AC5	NA	-
137	6	AC3	AA5	√	-
138	6	AB4	AC2	√	-
139	6	AA4	W6	NA	-
140	6	Y5	AB3	NA	VREF
141	6	V7	AB2	NA	-
142	6	Y4	AB1	√	-
143	6	W5	V5	√	VREF
144	6	V6	AA1	√	-
145	6	Y3	W4	NA	-
146	6	U7	Y1	NA	-
147	6	V4	W1	√	-
148	6	U6	W2	√	VREF
149	6	T5	V3	√	-
150	6	U4	U5	√	-
151	6	U3	T7	NA	-

**Table 4: FG676 Fine-Pitch BGA Differential Pin Pair Summary — XCV405E**

Pair	Bank	P Pin	N Pin	AO	Other Functions
152	6	T6	U2	NA	-
153	6	T4	U1	NA	-
154	6	T3	R7	NA	-
155	6	R6	R4	√	VREF
156	6	R5	R3	√	-
157	6	P7	P8	NA	-
158	6	P6	R1	NA	VREF
159	6	P4	P5	√	-
160	7	N8	N5	√	-
161	7	N3	N6	√	-
162	7	M2	N4	NA	VREF
163	7	M7	N7	NA	-
164	7	M3	M6	√	-
165	7	M5	M4	√	VREF
166	7	L7	L3	NA	-
167	7	K2	L6	NA	-
168	7	K1	L4	NA	-
169	7	L5	K3	NA	-
170	7	J3	K5	√	-
171	7	J4	K4	√	-
172	7	K6	H3	√	VREF
173	7	G3	K7	√	-
174	7	H1	J5	NA	-
175	7	J6	G2	NA	-
176	7	F1	J7	√	-
177	7	G4	H4	√	VREF
178	7	H5	F3	NA	-
179	7	H6	E2	NA	-
180	7	F4	G5	NA	VREF
181	7	G6	H7	NA	-
182	7	E4	E3	√	-



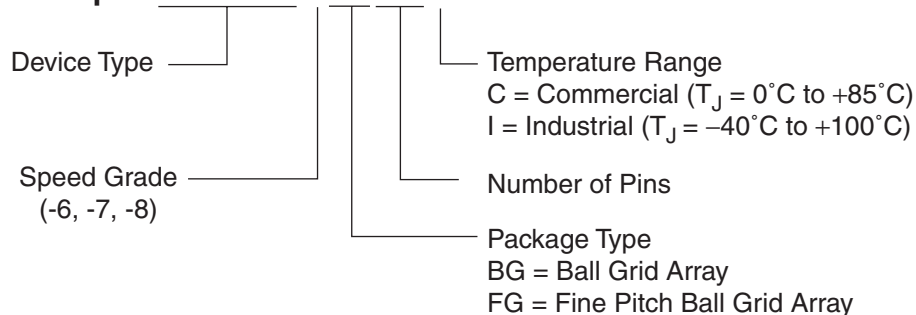
## Virtex-E Extended Memory Device/Package Combinations and Maximum I/O

Virtex-E Extended Memory Series Maximum User I/O by Device/Package (Excluding Dedicated Clock Pins)		
Package	XCV405E	XCV812E
BG560	404	404
FG676	404	
FG900		556

## Virtex-E Ordering Information

Virtex-II ordering information is shown in [Figure 1](#)

### Example: XCV405E-6BG560C



DS025\_001\_112000

Figure 1: Virtex Ordering Information