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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Discontinued at Digi-Key
Core Processor	ARM® Cortex®-M0+
Core Size	32-Bit Single-Core
Speed	24MHz
Connectivity	I <sup>2</sup> C, IrDA, SmartCard, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, I <sup>2</sup> S, POR, PWM, WDT
Number of I/O	17
Program Memory Size	8KB (8K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	1.98V ~ 3.8V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	24-VQFN Exposed Pad
Supplier Device Package	24-QFN (5x5)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/silicon-labs/efm32zg108f8-qfn24">https://www.e-xfl.com/product-detail/silicon-labs/efm32zg108f8-qfn24</a>

### 2.1.12 Pre-Programmed UART Bootloader

The bootloader presented in application note AN0003 is pre-programmed in the device at factory. Auto-baud and destructive write are supported. The autobaud feature, interface and commands are described further in the application note.

### 2.1.13 Low Energy Universal Asynchronous Receiver/Transmitter (LEUART)

The unique LEUART<sup>™</sup>, the Low Energy UART, is a UART that allows two-way UART communication on a strict power budget. Only a 32.768 kHz clock is needed to allow UART communication up to 9600 baud/s. The LEUART includes all necessary hardware support to make asynchronous serial communication possible with minimum of software intervention and energy consumption.

### 2.1.14 Timer/Counter (TIMER)

The 16-bit general purpose Timer has 3 compare/capture channels for input capture and compare/Pulse-Width Modulation (PWM) output.

### 2.1.15 Real Time Counter (RTC)

The Real Time Counter (RTC) contains a 24-bit counter and is clocked either by a 32.768 kHz crystal oscillator, or a 32.768 kHz RC oscillator. In addition to energy modes EM0 and EM1, the RTC is also available in EM2. This makes it ideal for keeping track of time since the RTC is enabled in EM2 where most of the device is powered down.

### 2.1.16 Pulse Counter (PCNT)

The Pulse Counter (PCNT) can be used for counting pulses on a single input or to decode quadrature encoded inputs. It runs off either the internal LFACLK or the PCNTn\_S0IN pin as external clock source. The module may operate in energy mode EM0 - EM3.

### 2.1.17 Analog Comparator (ACMP)

The Analog Comparator is used to compare the voltage of two analog inputs, with a digital output indicating which input voltage is higher. Inputs can either be one of the selectable internal references or from external pins. Response time and thereby also the current consumption can be configured by altering the current supply to the comparator.

### 2.1.18 Voltage Comparator (VCMP)

The Voltage Supply Comparator is used to monitor the supply voltage from software. An interrupt can be generated when the supply falls below or rises above a programmable threshold. Response time and thereby also the current consumption can be configured by altering the current supply to the comparator.

### 2.1.19 General Purpose Input/Output (GPIO)

In the EFM32ZG108, there are 17 General Purpose Input/Output (GPIO) pins, which are divided into ports with up to 16 pins each. These pins can individually be configured as either an output or input. More advanced configurations like open-drain, filtering and drive strength can also be configured individually for the pins. The GPIO pins can also be overridden by peripheral pin connections, like Timer PWM outputs or USART communication, which can be routed to several locations on the device. The GPIO supports up to 11 asynchronous external pin interrupts, which enables interrupts from any pin on the device. Also, the input value of a pin can be routed through the Peripheral Reflex System to other peripherals.

## 3 Electrical Characteristics

### 3.1 Test Conditions

#### 3.1.1 Typical Values

The typical data are based on  $T_{AMB}=25^{\circ}\text{C}$  and  $V_{DD}=3.0\text{ V}$ , as defined in Table 3.2 (p. 8), by simulation and/or technology characterisation unless otherwise specified.

#### 3.1.2 Minimum and Maximum Values

The minimum and maximum values represent the worst conditions of ambient temperature, supply voltage and frequencies, as defined in Table 3.2 (p. 8), by simulation and/or technology characterisation unless otherwise specified.

### 3.2 Absolute Maximum Ratings

The absolute maximum ratings are stress ratings, and functional operation under such conditions are not guaranteed. Stress beyond the limits specified in Table 3.1 (p. 8) may affect the device reliability or cause permanent damage to the device. Functional operating conditions are given in Table 3.2 (p. 8).

**Table 3.1. Absolute Maximum Ratings**

Symbol	Parameter	Condition	Min	Typ	Max	Unit
$T_{STG}$	Storage temperature range		-40		150 <sup>1</sup>	$^{\circ}\text{C}$
$T_S$	Maximum soldering temperature	Latest IPC/JEDEC J-STD-020 Standard			260	$^{\circ}\text{C}$
$V_{DDMAX}$	External main supply voltage		0		3.8	V
$V_{IOPIN}$	Voltage on any I/O pin		-0.3		$V_{DD}+0.3$	V

<sup>1</sup>Based on programmed devices tested for 10000 hours at  $150^{\circ}\text{C}$ . Storage temperature affects retention of preprogrammed calibration values stored in flash. Please refer to the Flash section in the Electrical Characteristics for information on flash data retention for different temperatures.

### 3.3 General Operating Conditions

#### 3.3.1 General Operating Conditions

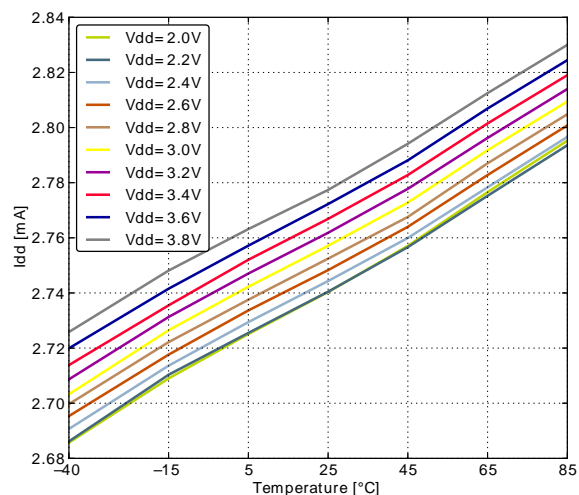
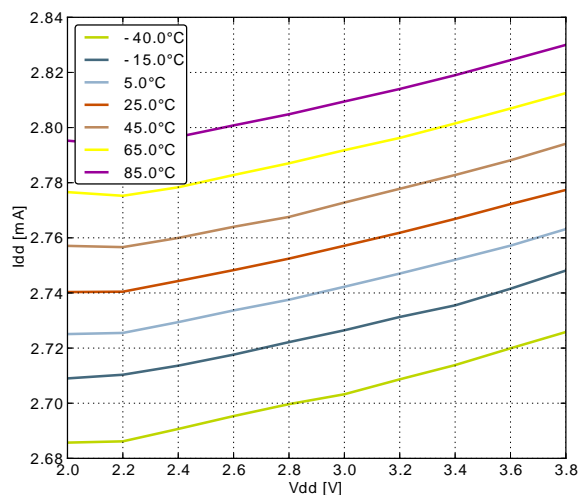
**Table 3.2. General Operating Conditions**

Symbol	Parameter	Min	Typ	Max	Unit
$T_{AMB}$	Ambient temperature range	-40		85	$^{\circ}\text{C}$
$V_{DDOP}$	Operating supply voltage	1.98		3.8	V
$f_{APB}$	Internal APB clock frequency			24	MHz
$f_{AHB}$	Internal AHB clock frequency			24	MHz

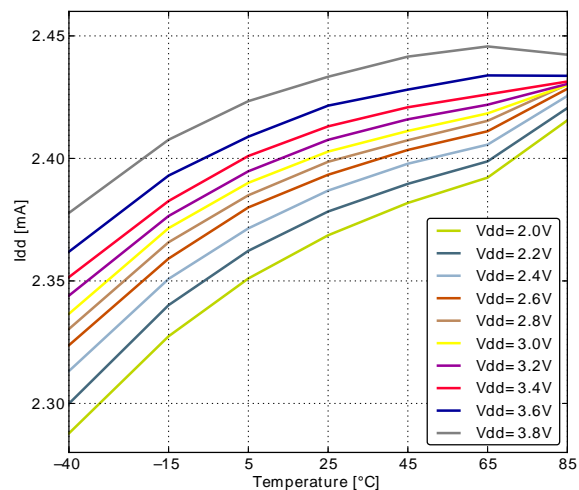
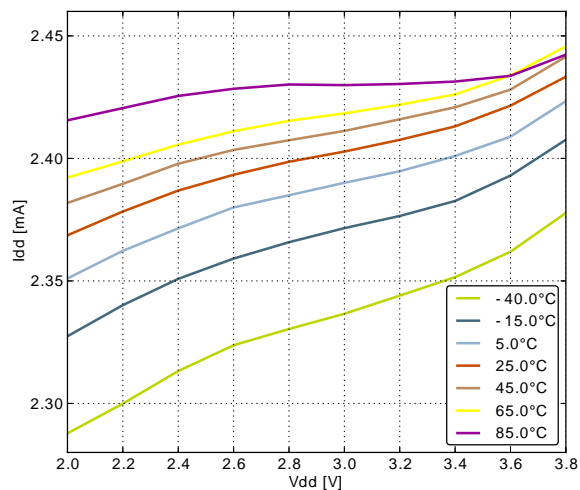
Symbol	Parameter	Condition	Min	Typ	Max	Unit
		14 MHz HFRCO, all peripheral clocks disabled, $V_{DD}=3.0\text{ V}$ , $T_{AMB}=25^{\circ}\text{C}$		50	54	$\mu\text{A}/\text{MHz}$
		14 MHz HFRCO, all peripheral clocks disabled, $V_{DD}=3.0\text{ V}$ , $T_{AMB}=85^{\circ}\text{C}$		51	56	$\mu\text{A}/\text{MHz}$
		11 MHz HFRCO, all peripheral clocks disabled, $V_{DD}=3.0\text{ V}$ , $T_{AMB}=25^{\circ}\text{C}$		52	56	$\mu\text{A}/\text{MHz}$
		11 MHz HFRCO, all peripheral clocks disabled, $V_{DD}=3.0\text{ V}$ , $T_{AMB}=85^{\circ}\text{C}$		53	58	$\mu\text{A}/\text{MHz}$
		6.6 MHz HFRCO, all peripheral clocks disabled, $V_{DD}=3.0\text{ V}$ , $T_{AMB}=25^{\circ}\text{C}$		57	63	$\mu\text{A}/\text{MHz}$
		6.6 MHz HFRCO, all peripheral clocks disabled, $V_{DD}=3.0\text{ V}$ , $T_{AMB}=85^{\circ}\text{C}$		59	66	$\mu\text{A}/\text{MHz}$
		1.2 MHz HFRCO. all peripheral clocks disabled, $V_{DD}=3.0\text{ V}$ , $T_{AMB}=25^{\circ}\text{C}$		89	99	$\mu\text{A}/\text{MHz}$
		1.2 MHz HFRCO. all peripheral clocks disabled, $V_{DD}=3.0\text{ V}$ , $T_{AMB}=85^{\circ}\text{C}$		92	103	$\mu\text{A}/\text{MHz}$
$I_{EM2}$	EM2 current	EM2 current with RTC prescaled to 1 Hz, 32.768 kHz LFRCO, $V_{DD}=3.0\text{ V}$ , $T_{AMB}=25^{\circ}\text{C}$		0.9	1.25	$\mu\text{A}$
		EM2 current with RTC prescaled to 1 Hz, 32.768 kHz LFRCO, $V_{DD}=3.0\text{ V}$ , $T_{AMB}=85^{\circ}\text{C}$		1.7	2.35	$\mu\text{A}$
$I_{EM3}$	EM3 current	EM3 current (ULFRCO enabled, LFRCO/LFXO disabled), $V_{DD}=3.0\text{ V}$ , $T_{AMB}=25^{\circ}\text{C}$		0.5	0.9	$\mu\text{A}$
		EM3 current (ULFRCO enabled, LFRCO/LFXO disabled), $V_{DD}=3.0\text{ V}$ , $T_{AMB}=85^{\circ}\text{C}$		1.3	2.0	$\mu\text{A}$
$I_{EM4}$	EM4 current	$V_{DD}=3.0\text{ V}$ , $T_{AMB}=25^{\circ}\text{C}$		0.02	0.035	$\mu\text{A}$
		$V_{DD}=3.0\text{ V}$ , $T_{AMB}=85^{\circ}\text{C}$		0.29	0.700	$\mu\text{A}$

### 3.4.1 EM0 Current Consumption

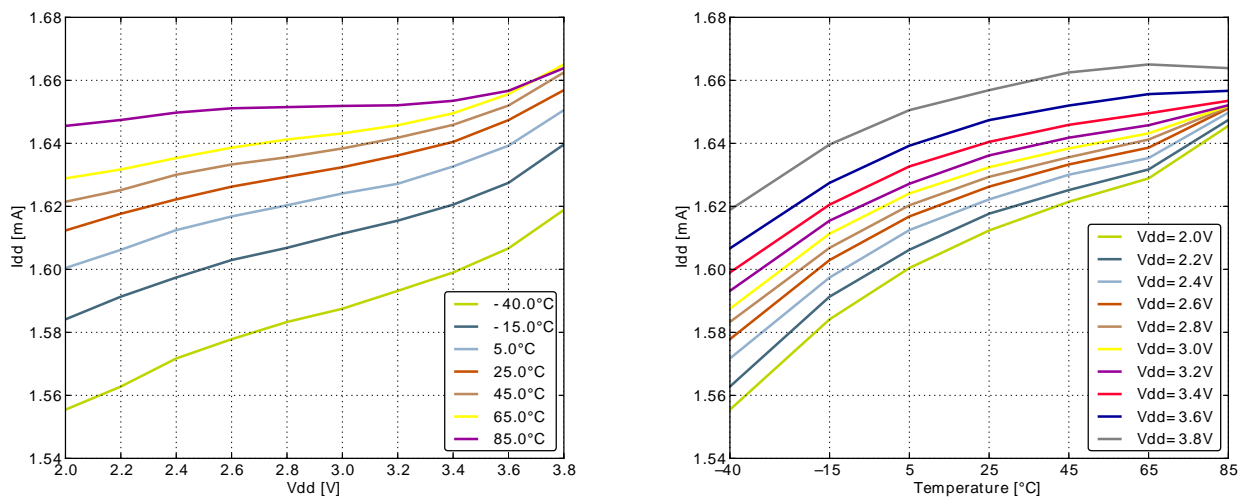
**Figure 3.1. EM0 Current consumption while executing prime number calculation code from flash with HFRCO running at 24 MHz**



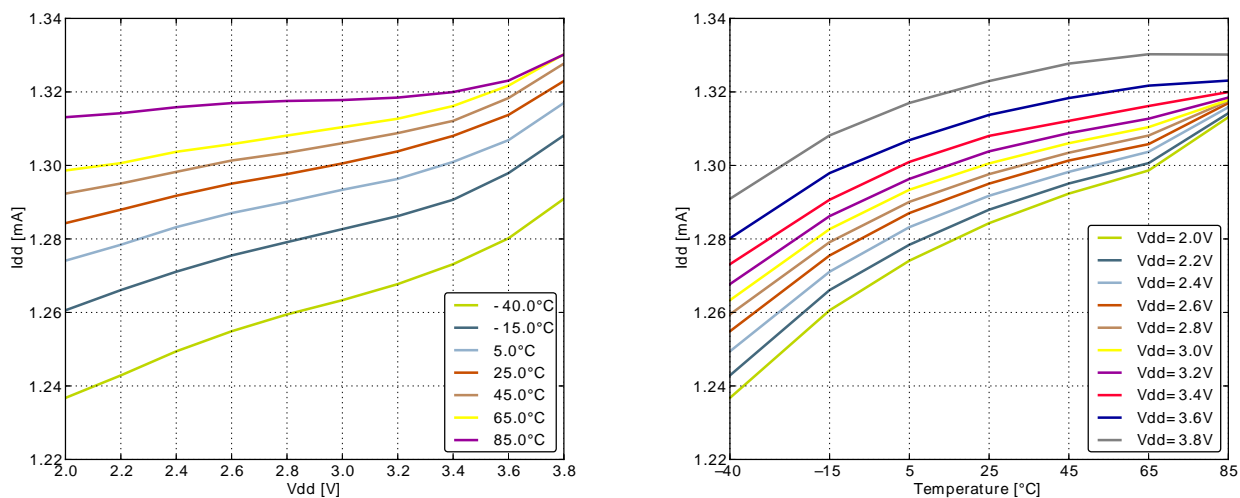
**Figure 3.2. EM0 Current consumption while executing prime number calculation code from flash with HFRCO running at 21 MHz**



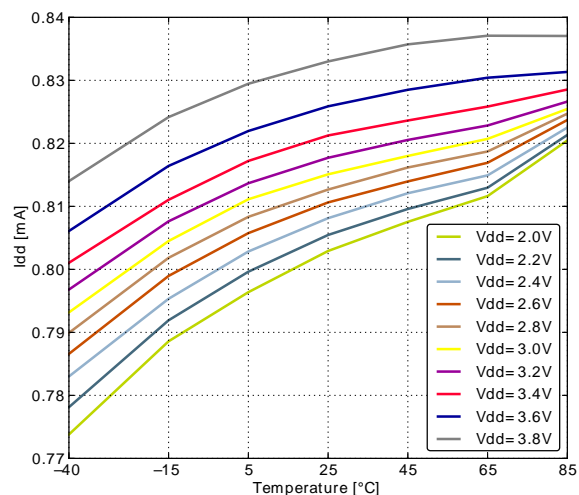
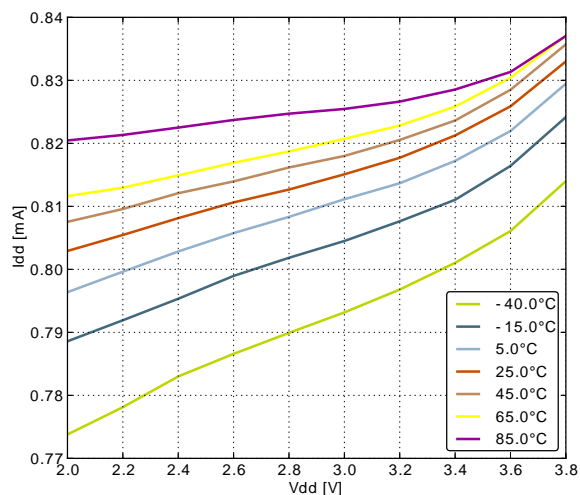
**Figure 3.3. EM0 Current consumption while executing prime number calculation code from flash with HFRCO running at 14 MHz**



**Figure 3.4. EM0 Current consumption while executing prime number calculation code from flash with HFRCO running at 11 MHz**

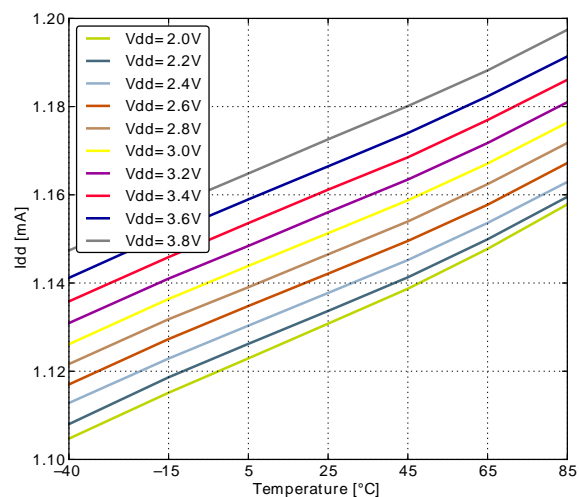
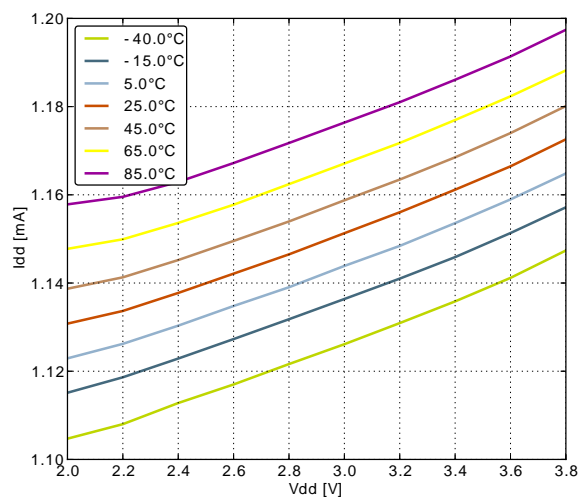


**Figure 3.5. EM0 Current consumption while executing prime number calculation code from flash with HFRCO running at 6.6 MHz**

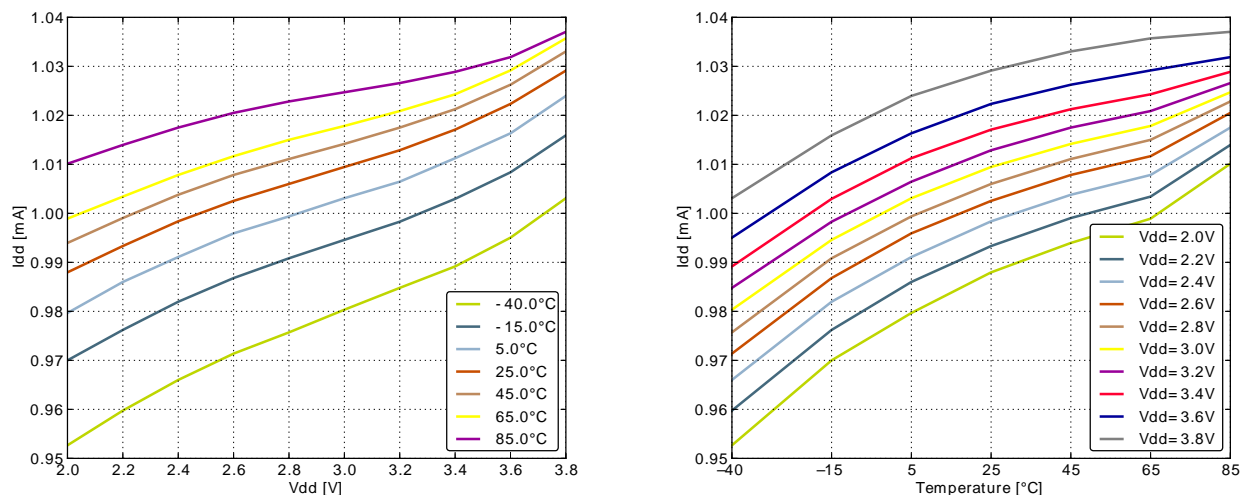


### 3.4.2 EM1 Current Consumption

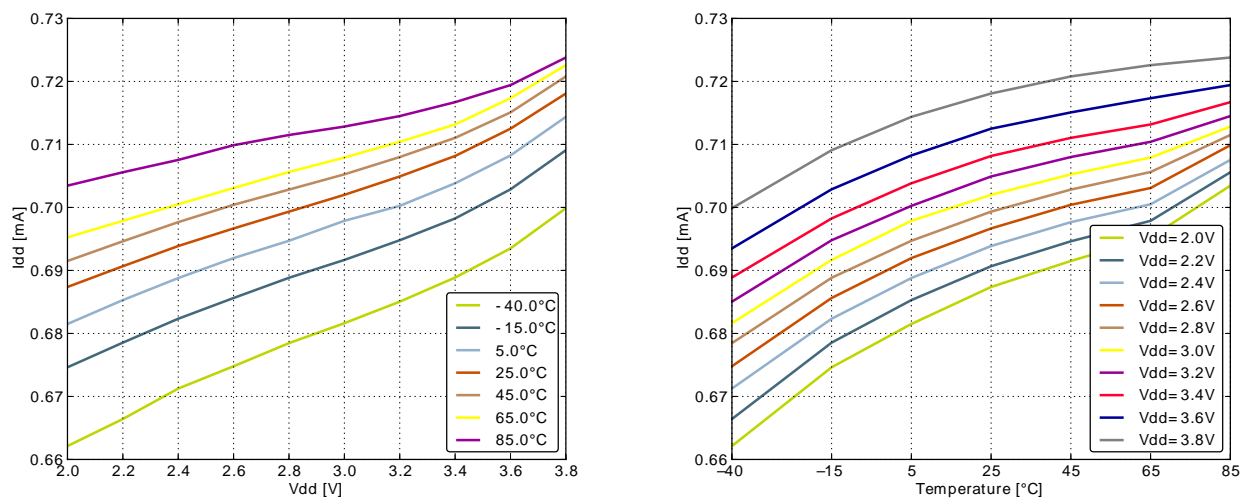
**Figure 3.6. EM1 Current consumption with all peripheral clocks disabled and HFRCO running at 24 MHz**



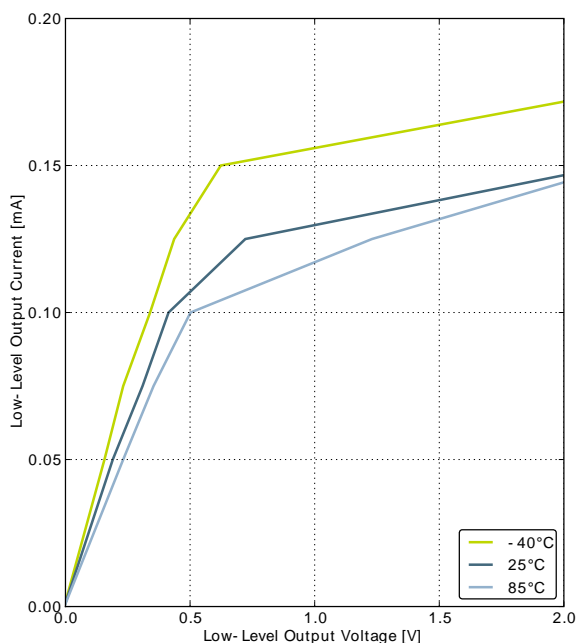
**Figure 3.7. EM1 Current consumption with all peripheral clocks disabled and HFRCO running at 21 MHz**



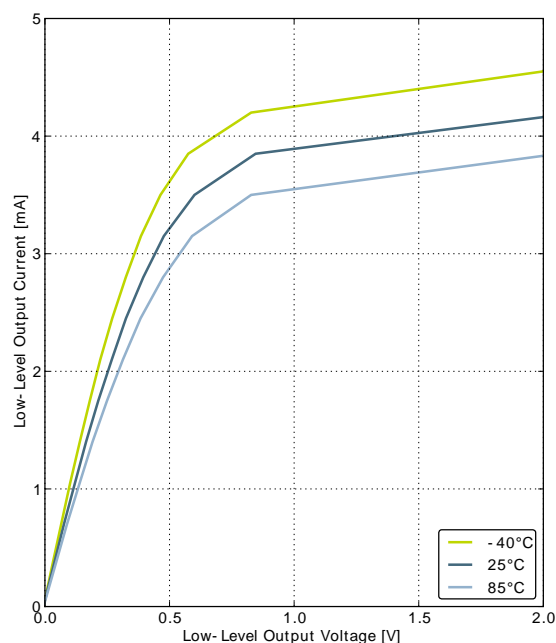
**Figure 3.8. EM1 Current consumption with all peripheral clocks disabled and HFRCO running at 14 MHz**



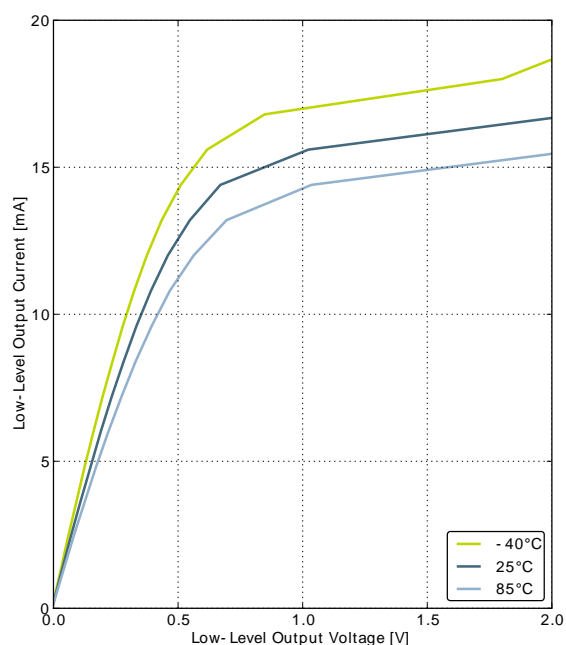


**Figure 3.14. Typical Low-Level Output Current, 2V Supply Voltage**

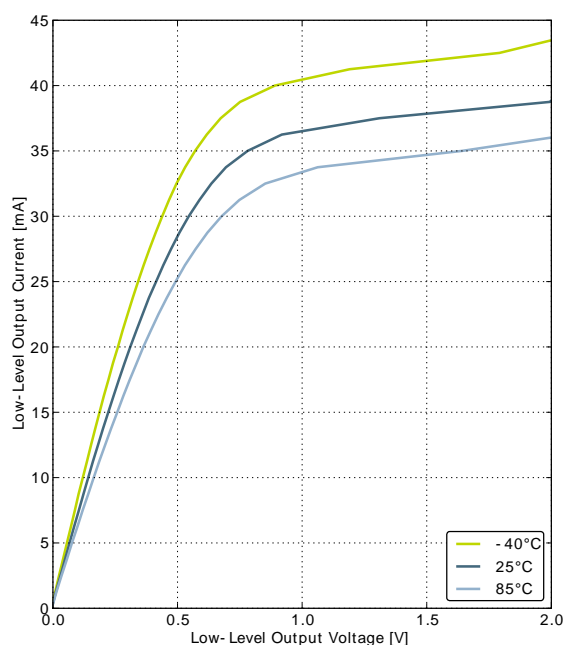
GPIO\_Px\_CTRL DRIVEMODE = LOWEST



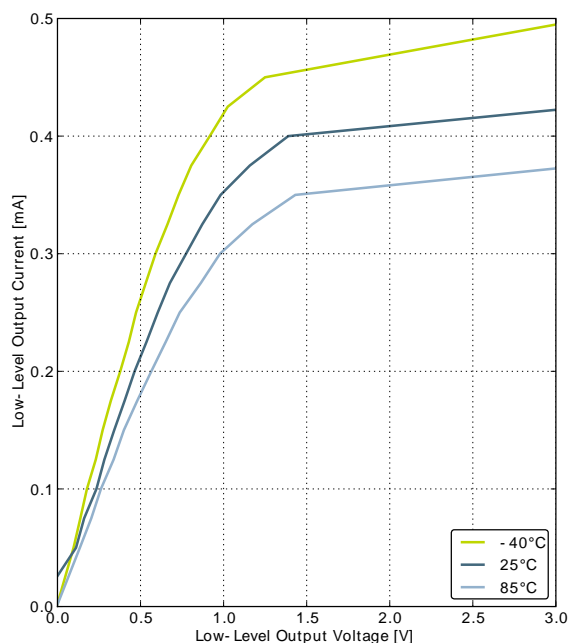
GPIO\_Px\_CTRL DRIVEMODE = LOW



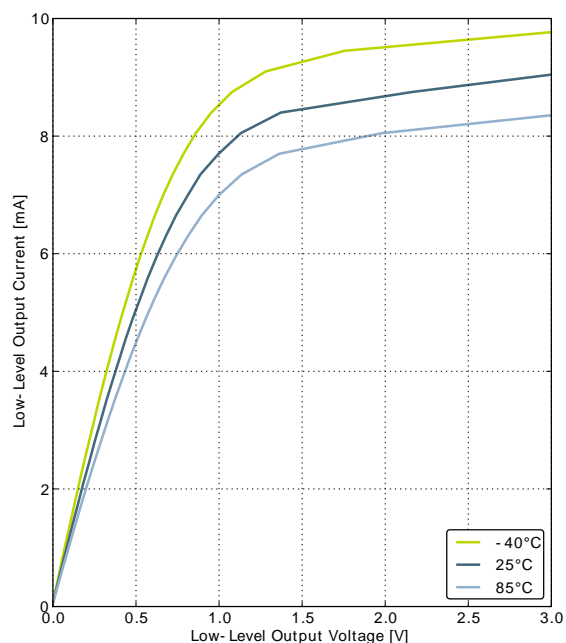
GPIO\_Px\_CTRL DRIVEMODE = STANDARD



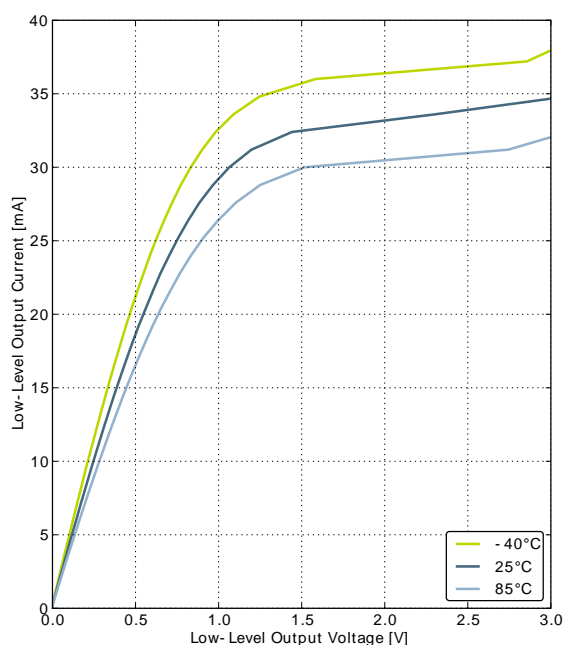
GPIO\_Px\_CTRL DRIVEMODE = HIGH

**Figure 3.16. Typical Low-Level Output Current, 3V Supply Voltage**

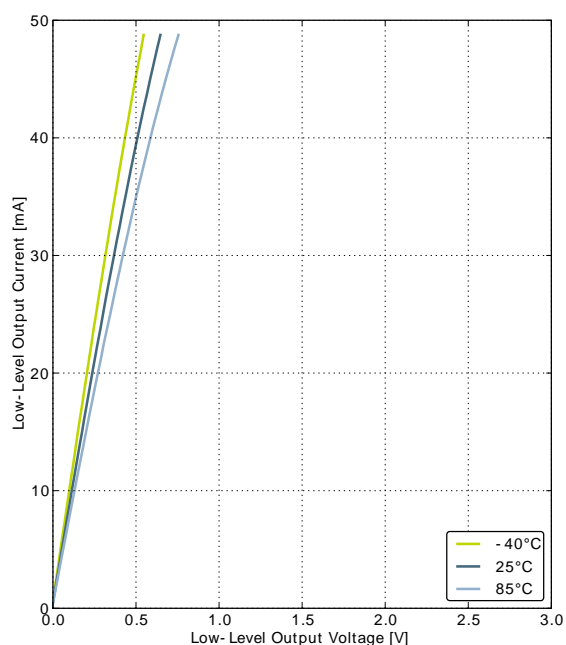
GPIO\_Px\_CTRL DRIVEMODE = LOWEST



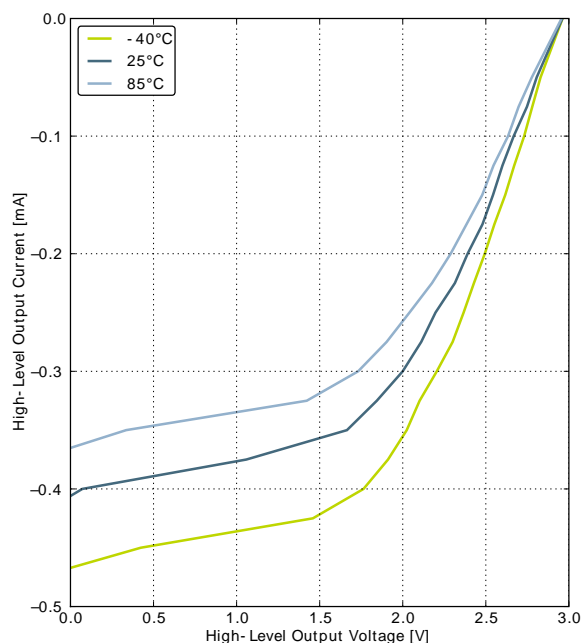
GPIO\_Px\_CTRL DRIVEMODE = LOW



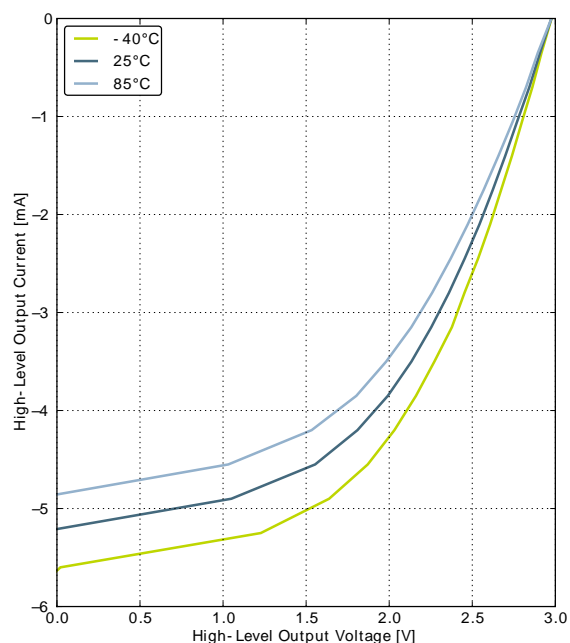
GPIO\_Px\_CTRL DRIVEMODE = STANDARD



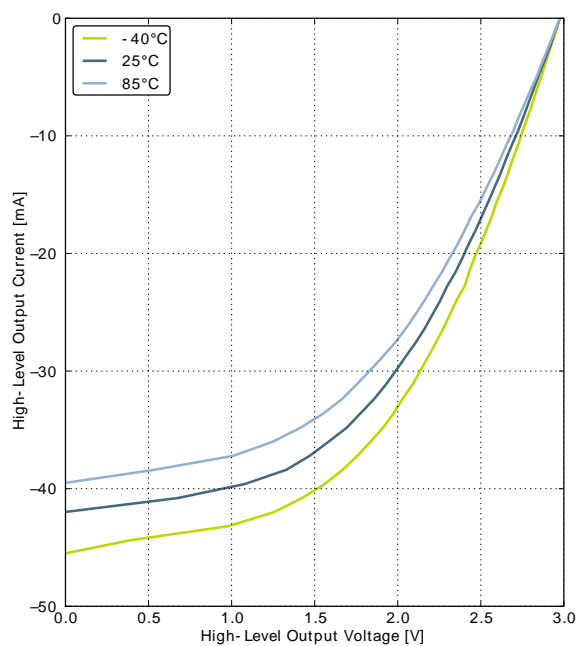
GPIO\_Px\_CTRL DRIVEMODE = HIGH

**Figure 3.17. Typical High-Level Output Current, 3V Supply Voltage**

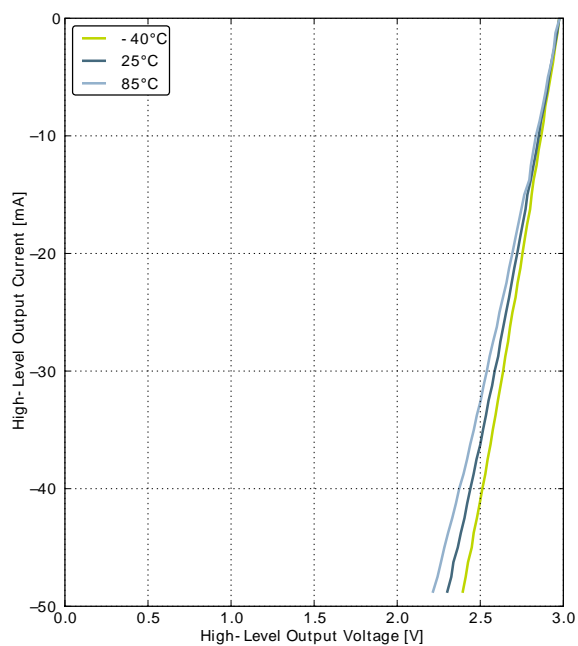
GPIO\_Px\_CTRL DRIVEMODE = LOWEST



GPIO\_Px\_CTRL DRIVEMODE = LOW



GPIO\_Px\_CTRL DRIVEMODE = STANDARD



GPIO\_Px\_CTRL DRIVEMODE = HIGH

## 3.9 Oscillators

### 3.9.1 LFXO

**Table 3.8. LFXO**

Symbol	Parameter	Condition	Min	Typ	Max	Unit
$f_{LFXO}$	Supported nominal crystal frequency			32.768		kHz
$ESR_{LFXO}$	Supported crystal equivalent series resistance (ESR)			30	120	kOhm
$C_{LFXOL}$	Supported crystal external load range		5		25	pF
$I_{LFXO}$	Current consumption for core and buffer after startup.	ESR=30 kOhm, $C_L$ =10 pF, LFXOBOOST in CMU_CTRL is 1		190		nA
$t_{LFXO}$	Start- up time.	ESR=30 kOhm, $C_L$ =10 pF, 40% - 60% duty cycle has been reached, LFXOBOOST in CMU_CTRL is 1		1100		ms

For safe startup of a given crystal, the energyAware Designer in Simplicity Studio contains a tool to help users configure both load capacitance and software settings for using the LFXO. For details regarding the crystal configuration, the reader is referred to application note "AN0016 EFM32 Oscillator Design Consideration".

### 3.9.2 HFXO

**Table 3.9. HFXO**

Symbol	Parameter	Condition	Min	Typ	Max	Unit
$f_{HFXO}$	Supported nominal crystal Frequency		4		24	MHz
$ESR_{HFXO}$	Supported crystal equivalent series resistance (ESR)	Crystal frequency 24 MHz		30	100	Ohm
		Crystal frequency 4 MHz		400	1500	Ohm
$g_{mHFXO}$	The transconductance of the HFXO input transistor at crystal startup	HFXOBOOST in CMU_CTRL equals 0b11	20			mS
$C_{HFXOL}$	Supported crystal external load range		5		25	pF
$I_{HFXO}$	Current consumption for HFXO after startup	4 MHz: ESR=400 Ohm, $C_L$ =20 pF, HFXOBOOST in CMU_CTRL equals 0b11		85		$\mu$ A
		24 MHz: ESR=30 Ohm, $C_L$ =10 pF, HFXOBOOST in CMU_CTRL equals 0b11		165		$\mu$ A
$t_{HFXO}$	Startup time	24 MHz: ESR=30 Ohm, $C_L$ =10 pF, HFXOBOOST in CMU_CTRL equals 0b11		785		$\mu$ s

## 3.10 Analog Comparator (ACMP)

**Table 3.14. ACMP**

Symbol	Parameter	Condition	Min	Typ	Max	Unit
$V_{ACMPIN}$	Input voltage range		0		$V_{DD}$	V
$V_{ACMPCM}$	ACMP Common Mode voltage range		0		$V_{DD}$	V
$I_{ACMP}$	Active current	BIASPROG=0b0000, FULL-BIAS=0 and HALFBIAS=1 in ACMPn_CTRL register		0.1	0.4	$\mu A$
		BIASPROG=0b1111, FULL-BIAS=0 and HALFBIAS=0 in ACMPn_CTRL register		2.87	15	$\mu A$
		BIASPROG=0b1111, FULL-BIAS=1 and HALFBIAS=0 in ACMPn_CTRL register		195	520	$\mu A$
$I_{ACMPREF}$	Current consumption of internal voltage reference	Internal voltage reference off. Using external voltage reference		0		$\mu A$
		Internal voltage reference		5		$\mu A$
$V_{ACMPOFFSET}$	Offset voltage	BIASPROG= 0b1010, FULL-BIAS=0 and HALFBIAS=0 in ACMPn_CTRL register	-12	0	12	mV
$V_{ACMPHYST}$	ACMP hysteresis	Programmable		17		mV
$R_{CSRES}$	Capacitive Sense Internal Resistance	CSRESSEL=0b00 in ACMPn_INPUTSEL		39		kOhm
		CSRESSEL=0b01 in ACMPn_INPUTSEL		71		kOhm
		CSRESSEL=0b10 in ACMPn_INPUTSEL		104		kOhm
		CSRESSEL=0b11 in ACMPn_INPUTSEL		136		kOhm
$t_{ACMPSTART}$	Startup time				10	$\mu s$

The total ACMP current is the sum of the contributions from the ACMP and its internal voltage reference as given in Equation 3.1 (p. 32) .  $I_{ACMPREF}$  is zero if an external voltage reference is used.

### Total ACMP Active Current

$$I_{ACMPTOTAL} = I_{ACMP} + I_{ACMPREF} \quad (3.1)$$

**Table 3.17. I2C Fast-mode (Fm)**

Symbol	Parameter	Min	Typ	Max	Unit
f <sub>SCL</sub>	SCL clock frequency	0		400 <sup>1</sup>	kHz
t <sub>LOW</sub>	SCL clock low time	1.3			μs
t <sub>HIGH</sub>	SCL clock high time	0.6			μs
t <sub>SU,DAT</sub>	SDA set-up time	100			ns
t <sub>HD,DAT</sub>	SDA hold time	8		900 <sup>2,3</sup>	ns
t <sub>SU,STA</sub>	Repeated START condition set-up time	0.6			μs
t <sub>HD,STA</sub>	(Repeated) START condition hold time	0.6			μs
t <sub>SU,STO</sub>	STOP condition set-up time	0.6			μs
t <sub>BUF</sub>	Bus free time between a STOP and START condition	1.3			μs

<sup>1</sup>For the minimum HFPERCLK frequency required in Fast-mode, see the I2C chapter in the EFM32ZG Reference Manual.

<sup>2</sup>The maximum SDA hold time (t<sub>HD,DAT</sub>) needs to be met only when the device does not stretch the low time of SCL (t<sub>LOW</sub>).

<sup>3</sup>When transmitting data, this number is guaranteed only when I2Cn\_CLKDIV < ((900\*10<sup>-9</sup> [s] \* f<sub>HFPERCLK</sub> [Hz]) - 5).

**Table 3.18. I2C Fast-mode Plus (Fm+)**

Symbol	Parameter	Min	Typ	Max	Unit
f <sub>SCL</sub>	SCL clock frequency	0		1000 <sup>1</sup>	kHz
t <sub>LOW</sub>	SCL clock low time	0.5			μs
t <sub>HIGH</sub>	SCL clock high time	0.26			μs
t <sub>SU,DAT</sub>	SDA set-up time	50			ns
t <sub>HD,DAT</sub>	SDA hold time	8			ns
t <sub>SU,STA</sub>	Repeated START condition set-up time	0.26			μs
t <sub>HD,STA</sub>	(Repeated) START condition hold time	0.26			μs
t <sub>SU,STO</sub>	STOP condition set-up time	0.26			μs
t <sub>BUF</sub>	Bus free time between a STOP and START condition	0.5			μs

<sup>1</sup>For the minimum HFPERCLK frequency required in Fast-mode Plus, see the I2C chapter in the EFM32ZG Reference Manual.

## 3.13 Digital Peripherals

**Table 3.19. Digital Peripherals**

Symbol	Parameter	Condition	Min	Typ	Max	Unit
I <sub>USART</sub>	USART current	USART idle current, clock enabled		7.5		μA/ MHz
I <sub>LEUART</sub>	LEUART current	LEUART idle current, clock enabled		150		nA
I <sub>I2C</sub>	I2C current	I2C idle current, clock enabled		6.25		μA/ MHz
I <sub>TIMER</sub>	TIMER current	TIMER_0 idle current, clock enabled		8.75		μA/ MHz
I <sub>PCNT</sub>	PCNT current	PCNT idle current, clock enabled		100		nA
I <sub>RTC</sub>	RTC current	RTC idle current, clock enabled		100		nA

**Table 4.2. Alternate functionality overview**

Alternate	LOCATION							
Functionality	0	1	2	3	4	5	6	Description
ACMP0_CH0	PC0							Analog comparator ACMP0, channel 0.
ACMP0_CH1	PC1							Analog comparator ACMP0, channel 1.
ACMP0_O	PE13		PD6					Analog comparator ACMP0, digital output.
BOOT_RX	PF1							Bootloader RX.
BOOT_TX	PF0							Bootloader TX.
CMU_CLK0			PD7					Clock Management Unit, clock output number 0.
CMU_CLK1			PE12					Clock Management Unit, clock output number 1.
DBG_SWCLK	PF0							Debug-interface Serial Wire clock input. Note that this function is enabled to pin out of reset, and has a built-in pull down.
DBG_SWDIO	PF1							Debug-interface Serial Wire data input / output. Note that this function is enabled to pin out of reset, and has a built-in pull up.
GPIO_EM4WU0	PA0							Pin can be used to wake the system up from EM4
GPIO_EM4WU3	PF1							Pin can be used to wake the system up from EM4
GPIO_EM4WU4	PF2							Pin can be used to wake the system up from EM4
GPIO_EM4WU5	PE13							Pin can be used to wake the system up from EM4
HFX TAL_N	PB14							High Frequency Crystal negative pin. Also used as external optional clock input pin.
HFX TAL_P	PB13							High Frequency Crystal positive pin.
I2C0_SCL		PD7			PC1	PF1	PE13	I2C0 Serial Clock Line input / output.
I2C0_SDA	PA0	PD6			PC0	PF0	PE12	I2C0 Serial Data input / output.
LEU0_RX		PB14		PF1	PA0			LEUART0 Receive input.
LEU0_TX		PB13		PF0	PF2			LEUART0 Transmit output. Also used as receive input in half duplex communication.
LFXTAL_N	PB8							Low Frequency Crystal (typically 32.768 kHz) negative pin. Also used as an optional external clock input pin.
LFXTAL_P	PB7							Low Frequency Crystal (typically 32.768 kHz) positive pin.
PCNT0_S0IN			PC0	PD6				Pulse Counter PCNT0 input number 0.
PCNT0_S1IN	PC14		PC1	PD7				Pulse Counter PCNT0 input number 1.
PRS_CH0	PA0		PC14					Peripheral Reflex System PRS, channel 0.
PRS_CH1			PC15					Peripheral Reflex System PRS, channel 1.
PRS_CH2	PC0							Peripheral Reflex System PRS, channel 2.
PRS_CH3	PC1							Peripheral Reflex System PRS, channel 3.
TIM0_CC0	PA0	PA0			PA0	PF0		Timer 0 Capture Compare input / output channel 0.
TIM0_CC1					PC0	PF1		Timer 0 Capture Compare input / output channel 1.
TIM0_CC2					PC1	PF2		Timer 0 Capture Compare input / output channel 2.
TIM1_CC0				PB7	PD6			Timer 1 Capture Compare input / output channel 0.
TIM1_CC1	PC14			PB8	PD7			Timer 1 Capture Compare input / output channel 1.
TIM1_CC2	PC15	PE12		PB11				Timer 1 Capture Compare input / output channel 2.
US1_CLK	PB7		PF0	PC15				USART1 clock input / output.
US1_CS	PB8		PF1	PC14				USART1 chip select input / output.
US1_RX	PC1		PD6	PD6				USART1 Asynchronous Receive.

Alternate	LOCATION							Description
Functionality	0	1	2	3	4	5	6	
								USART1 Synchronous mode Master Input / Slave Output (MISO).
US1_TX	PC0		PD7	PD7				USART1 Asynchronous Transmit. Also used as receive input in half duplex communication. USART1 Synchronous mode Master Output / Slave Input (MOSI).

## 4.3 GPIO Pinout Overview

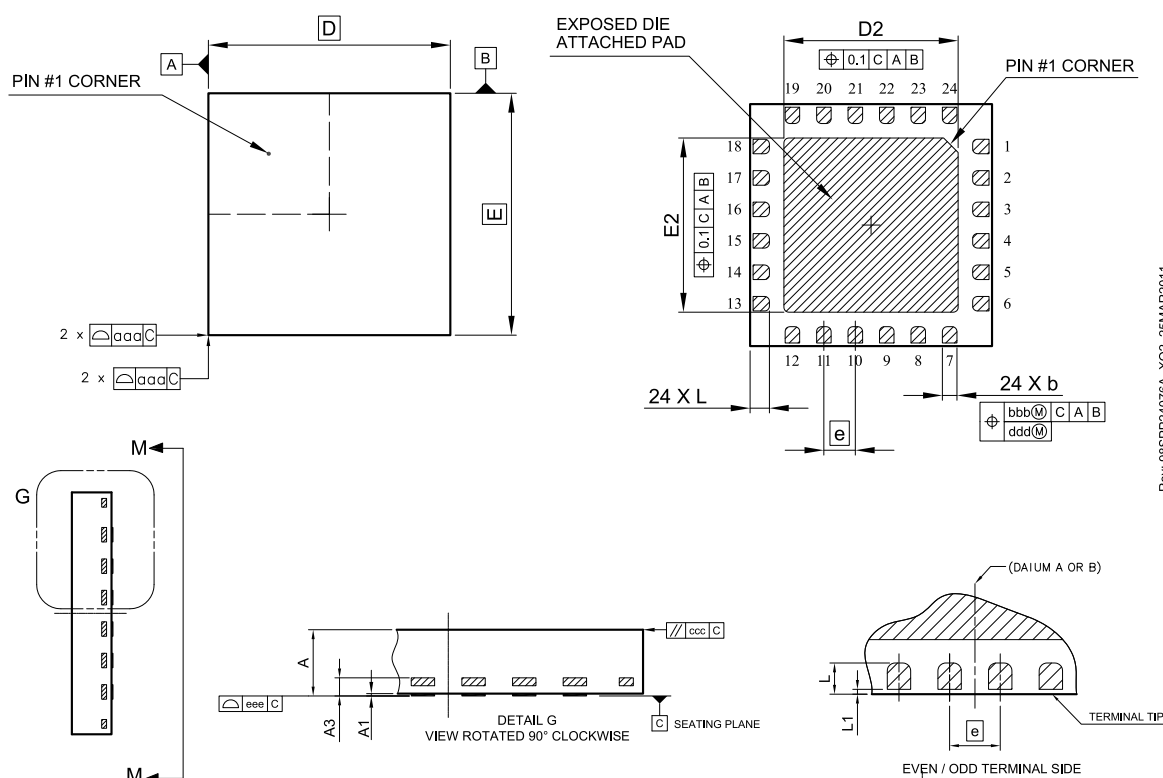
The specific GPIO pins available in *EFM32ZG108* is shown in Table 4.3 (p. 40). Each GPIO port is organized as 16-bit ports indicated by letters A through F, and the individual pin on this port is indicated by a number from 15 down to 0.

**Table 4.3. GPIO Pinout**

Port	Pin 15	Pin 14	Pin 13	Pin 12	Pin 11	Pin 10	Pin 9	Pin 8	Pin 7	Pin 6	Pin 5	Pin 4	Pin 3	Pin 2	Pin 1	Pin 0
Port A	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	PA0
Port B	-	PB14	PB13	-	PB11	-	-	PB8	PB7	-	-	-	-	-	-	-
Port C	PC15	PC14	-	-	-	-	-	-	-	-	-	-	-	-	PC1	PC0
Port D	-	-	-	-	-	-	-	-	PD7	PD6	-	-	-	-	-	-
Port E	-	-	PE13	PE12	-	-	-	-	-	-	-	-	-	-	-	-
Port F	-	-	-	-	-	-	-	-	-	-	-	-	-	PF2	PF1	PF0

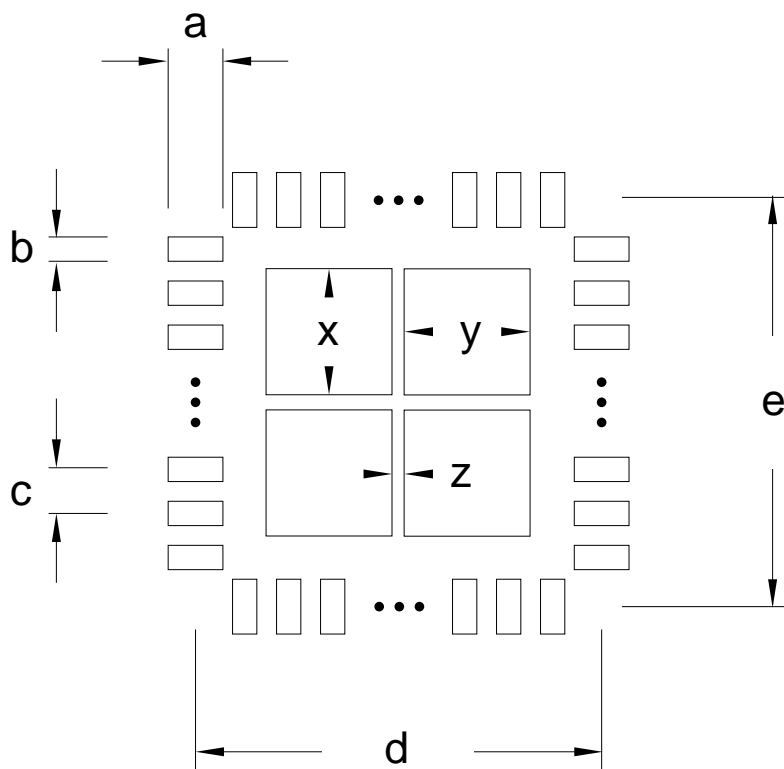
## 4.4 QFN24 Package

**Figure 4.2. QFN24**



Rev: 98SP24076A\_X02\_25MAR2011



**Figure 5.3. QFN24 PCB Stencil Design****Table 5.3. QFN24 PCB Stencil Design Dimensions (Dimensions in mm)**

Symbol	Dim. (mm)	Symbol	Dim. (mm)
a	0.60	e	5.00
b	0.25	x	1.00
c	0.65	y	1.00
d	5.00	z	0.50

1. The drawings are not to scale.
2. All dimensions are in millimeters.
3. All drawings are subject to change without notice.
4. The PCB Land Pattern drawing is in compliance with IPC-7351B.
5. Stencil thickness 0.125 mm.
6. For detailed pin-positioning, see Figure 4.2 (p. 40) .

## 5.2 Soldering Information

The latest IPC/JEDEC J-STD-020 recommendations for Pb-Free reflow soldering should be followed.

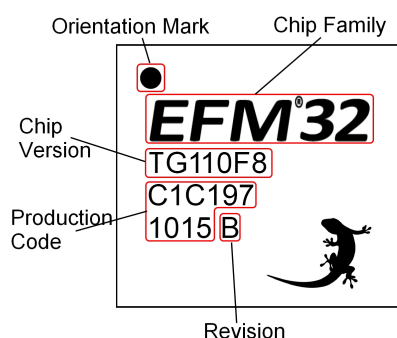
The packages have a Moisture Sensitivity Level rating of 3, please see the latest IPC/JEDEC J-STD-033 standard for MSL description and level 3 bake conditions. Place as many and as small as possible vias underneath each of the solder patches under the ground pad.

## 6 Chip Marking, Revision and Errata

### 6.1 Chip Marking

In the illustration below package fields and position are shown.

**Figure 6.1. Example Chip Marking (top view)**



### 6.2 Revision

The revision of a chip can be determined from the "Revision" field in Figure 6.1 (p. 45) .

### 6.3 Errata

Please see the errata document for EFM32ZG108 for description and resolution of device erratas. This document is available in Simplicity Studio and online at:

<http://www.silabs.com/support/pages/document-library.aspx?p=MCUs--32-bit>

## 7 Revision History

### 7.1 Revision 1.10

March 6th, 2015

Updated Max ESR<sub>HFXO</sub> value for Crystal Frequency of 24 MHz.

Updated current consumption.

Updated LFXO and HFXO data.

Updated LFRCO and HFRCO data.

Updated ACMP data.

Updated VCMP data.

Updated Memory Map.

Added DMA current in Digital Peripherals section.

Added AUXHFRCO to block diagram and Electrical Characteristics.

Updated Package dimensions table.

Updated block diagram.

### 7.2 Revision 1.00

July 2nd, 2014

Corrected single power supply voltage minimum value from 1.85V to 1.98V.

Removed "Preliminary" markings.

Updated current consumption.

Updated transition between energy modes.

Updated power management data.

Updated GPIO data.

Updated LFXO, HFXO, HFRCO and ULFRCO data.

Updated LFRCO and HFRCO plots.

Updated ACMP data.

### 7.3 Revision 0.61

November 21st, 2013

Updated figures.

Updated errata-link.

Updated chip marking.

Added link to Environmental and Quality information.

## 7.4 Revision 0.60

October 9th, 2013

Added I2C characterization data.

Updated current consumption table and figures in Electrical characteristics section.

Removed Environmental information.

Updated trademark, disclaimer and contact information.

Other minor corrections.

## 7.5 Revision 0.50

April 22nd, 2013

Updated HFCORE max frequency from 32 MHz to 24 MHz.

Updated pinout.

Other minor corrections.

## 7.6 Revision 0.40

September 11th, 2012

Updated CPU core from Cortex M0 to Cortex M0+.

Updated the HFRCO 1 MHz band typical value to 1.2 MHz.

Updated the HFRCO 7 MHz band typical value to 6.6 MHz.

Corrected operating voltage from 1.8 V to 1.85 V.

Other minor corrections.

## 7.7 Revision 0.30

July 16th, 2011

Updated the Electrical Characteristics section.

## 7.8 Revision 0.20

June 8th, 2011

Corrected all current values in Electrical Characteristics section.

Updated Cortex M0 related items in the memory map.

## 7.9 Revision 0.10

June 7th, 2011

Initial preliminary release.

## A Disclaimer and Trademarks

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