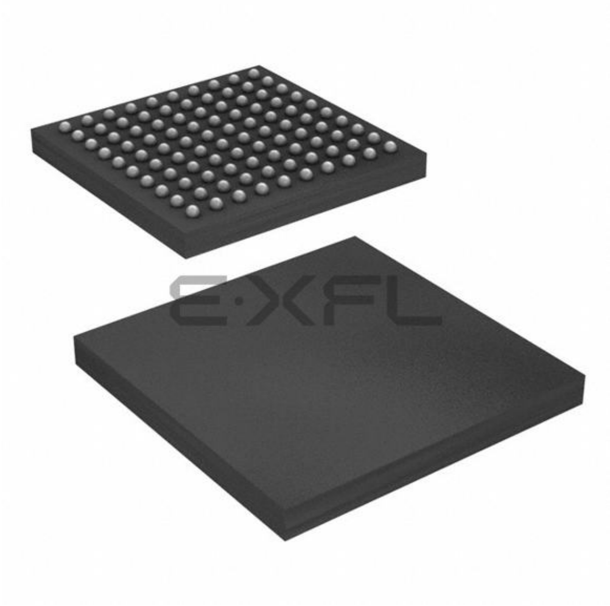
NXP USA Inc. - SPC5744BSK1AMMH2 Datasheet



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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	e200z4
Core Size	32-Bit Single-Core
Speed	120MHz
Connectivity	CANbus, Ethernet, FlexRay, I²C, LINbus, SPI
Peripherals	DMA, I²S, POR, WDT
Number of I/O	-
Program Memory Size	1.5MB (1.5M x 8)
Program Memory Type	FLASH
EEPROM Size	64K x 8
RAM Size	192K x 8
Voltage - Supply (Vcc/Vdd)	3.15V ~ 5.5V
Data Converters	A/D 36x10b, 16x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LFBGA
Supplier Device Package	100-MAPBGA (11x11)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/spc5744bsk1ammh2

Table 4. MPC5746C Family Comparison - RAM Memory Map (continued)

Start Address	End Address	Allocated size	Description	MPC5744	MPC5745	MPC5746
0x40030000	0x4003FFFF	64 KB	SRAM4	not available	available	available
0x40040000	0x4004FFFF	64 KB	SRAM5	not available	not available	available
0x40050000	0x4005FFFF	64 KB	SRAM6	not available	not available	available
0x40060000	0x4006FFFF	64 KB	SRAM7	not available	not available	optional
0x40070000	0x4007FFFF	64 KB	SRAM8	not available	not available	optional

3 Ordering parts

3.1 Determining valid orderable parts

To determine the orderable part numbers for this device, go to www.nxp.com and perform a part number search for the following device number: MPC5746C.

Table 6. Recommended operating conditions ($V_{DD\_HV\_x}$ = 3.3 V) (continued)

Symbol	Parameter	Conditions[1]	Min[2]	Max	Unit
T_A[8]	Ambient temperature under bias	f_{CPU} ≤ 160 MHz	–40	125	°C
T_J	Junction temperature under bias	—	–40	150	°C

1. All voltages are referred to V_{SS_HV} unless otherwise specified
2. Device will be functional down (and electrical specifications as per various datasheet parameters will be guaranteed) to the point where one of the LVD/HVD resets the device. When voltage drops outside range for an LVD/HVD, device is reset.
3. VDD_HV_FLA must be connected to VDD_HV_A when VDD_HV_A = 3.3V
4. Only applicable when supplying from external source.
5. VDD_LV supply pins should never be grounded (through a small impedance). If these are not driven, they should only be left floating.
6. VIN1_CMP_REF ≤ VDD_HV_A
7. This supply is shorted VDD_HV_A on lower packages.
8. T_J=150°C. Assumes T_A=125°C
    - Assumes maximum θJA of 2s2p board. See Thermal attributes

NOTE

If VDD_HV_A is in 5V range, it is necessary to use internal Flash supply 3.3V regulator. VDD_HV_FLA should not be supplied externally and should only have decoupling capacitor.

Table 7. Recommended operating conditions ($V_{DD\_HV\_x}$ = 5 V)

Symbol	Parameter	Conditions [1]	Min[2]	Max	Unit
$V_{DD\_HV\_A}$ $V_{DD\_HV\_B}$ $V_{DD\_HV\_C}$	HV IO supply voltage	—	4.5	5.5	V
$V_{DD\_HV\_FLA}$[3]	HV flash supply voltage	—	3.15	3.6	V
$V_{DD\_HV\_ADC1\_REF}$	HV ADC1 high reference voltage	—	3.15	5.5	V
$V_{DD\_HV\_ADC0}$ $V_{DD\_HV\_ADC1}$	HV ADC supply voltage	—	max(VDD_HV_A,VDD_HV_B,VDD_HV_C) - 0.05	5.5	V
$V_{SS\_HV\_ADC0}$ $V_{SS\_HV\_ADC1}$	HV ADC supply ground	—	-0.1	0.1	V
V_{DD_LV}[4]	Core supply voltage	—	1.2	1.32	V
$V_{IN1\_CMP\_REF}$[5, 6]	Analog Comparator DAC reference voltage	—	3.15	5.5[5]	V
I_{INJPAD}	Injected input current on any pin during overload condition	—	-3.0	3.0	mA
T_A[7]	Ambient temperature under bias	f_{CPU} ≤ 160 MHz	–40	125	°C
T_J	Junction temperature under bias	—	–40	150	°C

1. All voltages are referred to V_{SS_HV} unless otherwise specified
2. Device will be functional down (and electrical specifications as per various datasheet parameters will be guaranteed) to the point where one of the LVD/HVD resets the device. When voltage drops outside range for an LVD/HVD, device is reset.
3. When VDD_HV is in 5 V range, VDD_HV_FLA cannot be supplied externally.This pin is decoupled with C_{flash_reg}.

Table 8. Voltage regulator electrical specifications (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
C_{flash_reg}[4]	External decoupling / stability capacitor for internal Flash regulators	Min, max values shall be granted with respect to tolerance, voltage, temperature, and aging variations.	1.32	2.2	3	µF
	Combined ESR of external capacitor	—	0.001	—	0.03	Ohm
$C_{HV\_VDD\_A}$	VDD_HV_A supply capacitor [5, 5]	Min, max values shall be granted with respect to tolerance, voltage, temperature, and aging variations.	1	—	—	µF
$C_{HV\_VDD\_B}$	VDD_HV_B supply capacitor[5]	Min, max values shall be granted with respect to tolerance, voltage, temperature, and aging variations.	1	—	—	µF
$C_{HV\_VDD\_C}$	VDD_HV_C supply capacitor[5]	Min, max values shall be granted with respect to tolerance, voltage, temperature, and aging variations.	1	—	—	µF
C_{HV_ADC0} C_{HV_ADC1}	HV ADC supply decoupling capacitances	Min, max values shall be granted with respect to tolerance, voltage, temperature, and aging variations.	1	—	—	µF
C_{HV_ADR}[6]	HV ADC SAR reference supply decoupling capacitances	Min, max values shall be granted with respect to tolerance, voltage, temperature, and aging variations.	0.47	—	—	µF
$V_{DD\_HV\_BALLAST}$[7]	FPREG Ballast collector supply voltage	When collector of NPN ballast is directly supplied by an on board supply source (not shared with VDD_HV_A supply pin) without any series resistance, that is, $R_{C\_BALLAST}$ less than 0.01 Ohm.	2.25	—	5.5	V
$R_{C\_BALLAST}$	Series resistor on collector of FPREG ballast	When VDD_HV_BALLAST is shorted to VDD_HV_A on the board	—	—	0.1	Ohm
t_{SU}	Start-up time with external ballastafter main supply (VDD_HV_A) stabilization	Cfp_reg = 3 µF	—	74	—	µs
t_{SU_int}	Start-up time with internal ballast after main supply (VDD_HV_A) stabilization	Cfp_reg = 3 µF	—	103	—	µs
t_{ramp}	Load current transient	Iload from 15% to 55% C_{fp_reg} = 3 µF		1.0		µs

---

1. Split capacitance on each pair VDD_LV pin should sum up to a total value of C_{fp_reg}
2. Typical values will vary over temperature, voltage, tolerance, drift, but total variation must not exceed minimum and maximum values.
3. Ceramic X7R or X5R type with capacitance-temperature characteristics +/-15% of -55 degC to +125degC is recommended. The tolerance +/-20% is acceptable.
4. It is required to minimize the board parasitic inductance from decoupling capacitor to VDD_HV_FLA pin and the routing inductance should be less than 1nH.

5.
    1. For VDD_HV_x, 1µf on each side of the chip
        a. 0.1 µf close to each VDD/VSS pin pair.
        b. 10 µf near for each power supply source
        c. For VDD_LV, 0.1uf close to each VDD/VSS pin pair is required. Depending on the the selected regulation mode, this amount of capacitance will need to be subtracted from the total capacitance required by the regulator for e.g., as specified by CFP_REG parameter.
    2. For VDD_LV, 0.1uf close to each VDD/VSS pin pair is required. Depending on the the selected regulation mode, this amount of capacitance will need to be subtracted from the total capacitance required by the regulator for e.g., as specified by CFP_REG parameter
6. Only applicable to ADC1
7. In external ballast configuration the following must be ensured during power-up and power-down (Note: If $V_{DD\_HV\_BALLAST}$ is supplied from the same source as VDD_HV_A this condition is implicitly met):
    - During power-up, $V_{DD\_HV\_BALLAST}$ must have met the min spec of 2.25V before VDD_HV_A reaches the POR_HV_RISE min of 2.75V.
    - During power-down, $V_{DD\_HV\_BALLAST}$ must not drop below the min spec of 2.25V until VDD_HV_A is below POR_HV_FALL min of 2.7V.

NOTE

For a typical configuration using an external ballast transistor with separate supply for VDD_HV_A and the ballast collector, a bulk storage capacitor (as defined in Table 8) is required on VDD_HV_A close to the device pins to ensure a stable supply voltage.

Extra care must be taken if the VDD_HV_A supply is also being used to power the external ballast transistor or the device is running in internal regulation mode. In these modes, the inrush current on device Power Up or on exit from Low Power Modes is significant and may case the VDD_HV_A voltage to drop resulting in an LVD reset event. To avoid this, the board layout should be optimized to reduce common trace resistance or additional capacitance at the ballast transistor collector (or VDD_HV_A pins in the case of internal regulation mode) is required. NXP recommends that customers simulate the external voltage supply circuitry.

In all circumstances, the voltage on VDD_HV_A must be maintained within the specified operating range (see Recommended operating conditions) to prevent LVD events.

4.4 Voltage monitor electrical characteristics

Table 9. Voltage monitor electrical characteristics

Symbol	Parameter	State	Conditions	Configuration			Threshold			Unit
				Power Up [1]	Mask Opt[2, 2]	Reset Type	Min	Typ	Max	V
V_{POR_LV}	LV supply power on reset detector	Fall	Untrimmed	Yes	No	Destructive	0.930	0.979	1.028	V
			Trimmed				-	-	-	V
		Rise	Untrimmed				0.980	1.029	1.078	V
			Trimmed				-	-	-	V
$V_{HVD\_LV\_cold}$	LV supply high voltage monitoring, detecting at device pin	Fall	Untrimmed	No	Yes	Functional	Disabled at Start			
			Trimmed				1.325	1.345	1.375	V
		Rise	Untrimmed				Disabled at Start			
			Trimmed				1.345	1.365	1.395	V
$V_{LVD\_LV\_PD2\_hot}$	LV supply low voltage monitoring, detecting on the PD2 core (hot) area	Fall	Untrimmed	Yes	No	Destructive	1.0800	1.1200	1.1600	V
			Trimmed				1.1250	1.1425	1.1600	V
		Rise	Untrimmed				1.1000	1.1400	1.1800	V
			Trimmed				1.1450	1.1625	1.1800	V
$V_{LVD\_LV\_PD1\_hot\ (BGFP)}$	LV supply low voltage monitoring, detecting on the PD1 core (hot) area	Fall	Untrimmed	Yes	No	Destructive	1.0800	1.1200	1.1600	V
			Trimmed				1.1140	1.1370	1.1600	V
		Rise	Untrimmed				1.1000	1.140	1.1800	V
			Trimmed				1.1340	1.1570	1.1800	V
$V_{LVD\_LV\_PD0\_hot\ (BGFP)}$	LV supply low voltage monitoring, detecting on the PD0 core (hot) area	Fall	Untrimmed	Yes	No	Destructive	1.0800	1.1200	1.1600	V
			Trimmed				1.1140	1.1370	1.1600	V
		Rise	Untrimmed				1.1000	1.1400	1.1800	V
			Trimmed				1.1340	1.1570	1.1800	V
V_{POR_HV}	HV supply power on reset detector	Fall	Untrimmed	Yes	No	Destructive	2.7000	2.8500	3.0000	V
			Trimmed				-	-	-	V
		Rise	Untrimmed				2.7500	2.9000	3.0500	V
			Trimmed				-	-	-	V
$V_{LVD\_IO\_A\_LO}$[3, 3]	HV IO_A supply low voltage monitoring - low range	Fall	Untrimmed	Yes	No	Destructive	2.7500	2.9230	3.0950	V
			Trimmed				2.9780	3.0390	3.1000	V
		Rise	Untrimmed				2.7800	2.9530	3.1250	V
			Trimmed				3.0080	3.0690	3.1300	V
$V_{LVD\_IO\_A\_HI}$[3]	HV IO_A supply low voltage monitoring - high range	Fall	Trimmed	No	Yes	Destructive	Disabled at Start			
							4.0600	4.151	4.2400	V
		Rise	Trimmed				Disabled at Start			
							4.1150	4.2010	4.3000	V

Table continues on the next page...

5.2 DC electrical specifications @ 3.3V Range

Table 15. DC electrical specifications @ 3.3V Range

Symbol	Parameter	Value		Unit
		Min	Max	
Vih (pad_i_hv)	Pad_I_HV Input Buffer High Voltage	0.72*VDD_HV_x	VDD_HV_x + 0.3	V
Vil (pad_i_hv)	Pad_I_HV Input Buffer Low Voltage	VDD_HV_x - 0.3	0.45*VDD_HV_x	V
Vhys (pad_i_hv)	Pad_I_HV Input Buffer Hysteresis	0.11*VDD_HV_x		V
Vih_hys	CMOS Input Buffer High Voltage (with hysteresis enabled)	0.67*VDD_HV_x	VDD_HV_x + 0.3	V
Vil_hys	CMOS Input Buffer Low Voltage (with hysteresis enabled)	VDD_HV_x - 0.3	0.35*VDD_HV_x	V
Vih	CMOS Input Buffer High Voltage (with hysteresis disabled)	0.57 * VDD_HV_x[1, 1]	VDD_HV_x[1] + 0.3	V
Vil	CMOS Input Buffer Low Voltage (with hysteresis disabled)	VDD_HV_x - 0.3	0.4 * VDD_HV_x[1]	V
Vhys	CMOS Input Buffer Hysteresis	0.09 * VDD_HV_x[1]		V
Pull_IIH (pad_i_hv)	Weak Pullup Current[2, 2] Low	15		μA
Pull_IIH (pad_i_hv)	Weak Pullup Current[3, 3] High		55	μA
Pull_IIL (pad_i_hv)	Weak Pulldown Current[3] Low	28		μA
Pull_IIL (pad_i_hv)	Weak Pulldown Current[2] High		85	μA
Pull_Ioh	Weak Pullup Current[4]	15	50	μA
Pull_Iol	Weak Pulldown Current[5]	15	50	μA
Iinact_d	Digital Pad Input Leakage Current (weak pull inactive)	-2.5	2.5	μA
Voh	Output High Voltage[6]	0.8 *VDD_HV_x[1]	—	V
Vol	Output Low Voltage[7] Output Low Voltage[8]	—	0.2 *VDD_HV_x[1] 0.1 *VDD_HV_x	V
Ioh_f	Full drive Ioh[9, 9] (SIUL2_MSCRn.SRC[1:0] = 11)	18	70	mA
Iol_f	Full drive Iol[9] (SIUL2_MSCRn.SRC[1:0] = 11)	21	120	mA
Ioh_h	Half drive Ioh[9] (SIUL2_MSCRn.SRC[1:0] = 10)	9	35	mA
Iol_h	Half drive Iol[9] (SIUL2_MSCRn.SRC[1:0] = 10)	10.5	60	mA

1. VDD_HV_x = VDD_HV_A, VDD_HV_B, VDD_HV_C
2. Measured when pad=0.69*VDD_HV_x
3. Measured when pad=0.49*VDD_HV_x
4. Measured when pad = 0 V
5. Measured when pad = VDD_HV_x
6. Measured when pad is sourcing 2 mA
7. Measured when pad is sinking 2 mA
8. Measured when pad is sinking 1.5 mA
9. Ioh/Iol is derived from spice simulations. These values are NOT guaranteed by test.

5.3 AC specifications @ 5 V Range

Table 16. Functional Pad AC Specifications @ 5 V Range

Symbol	Prop. Delay (ns)[1] L>H/H>L		Rise/Fall Edge (ns)		Drive Load (pF)	SIUL2_MSCRn[SRC 1:0]
	Min	Max	Min	Max		MSB,LSB
pad_sr_hv (output)		4.5/4.5		1.3/1.2	25	11
		6/6		2.5/2	50	
		13/13		9/9	200	
		5.25/5.25		3/2	25	10
		9/8		5/4	50	
		22/22		18/16	200	
		27/27		13/13	50	01[2, 2]
		40/40		24/24	200	
		40/40		24/24	50	00[2]
		65/65		40/40	200	
pad_i_hv/ pad_sr_hv (input)		1.5/1.5		0.5/0.5	0.5	NA

1. As measured from 50% of core side input to Voh/Vol of the output
2. Slew rate control modes

NOTE

The above specification is based on simulation data into an ideal lumped capacitor. Customer should use IBIS models for their specific board/loading conditions to simulate the expected signal integrity and edge rates of their system.

NOTE

The above specification is measured between 20% / 80%.

5.4 DC electrical specifications @ 5 V Range

Table 17. DC electrical specifications @ 5 V Range

Symbol	Parameter	Value		Unit
		Min	Max	
Vih (pad_i_hv)	pad_i_hv Input Buffer High Voltage	0.7*VDD_HV_x	VDD_HV_x + 0.3	V

Table continues on the next page...

Table 18. Functional reset pad electrical specifications (continued)

Symbol	Parameter	Conditions	Value			Unit
			Min	Typ	Max	
V_{HYS}	CMOS Input Buffer hysterisis	—	300	—	—	mV
V_{DD_POR}	Minimum supply for strong pull-down activation	—	—	—	1.2	V
I_{OL_R}	Strong pull-down current [1], [1]	Device under power-on reset $V_{DD\_HV\_A}$= V $_{DD\_POR}$ V_{OL} = 0.35*$V_{DD\_HV\_A}$	0.2	—	—	mA
		Device under power-on reset $V_{DD\_HV\_A}$= V $_{DD\_POR}$ V_{OL} = 0.35*$V_{DD\_HV\_IO}$	11	—	—	mA
W_{FRST}	$\overline{\text{RESET}}$ input filtered pulse	—	—	—	500	ns
W_{NFRST}	$\overline{\text{RESET}}$ input not filtered pulse	—	2000	—	—	ns
$\|I_{WPU}\|$	Weak pull-up current absolute value	RESET pin V_{IN} = V_{DD}	23	—	82	µA

1. Strong pull-down is active on PHASE0, PHASE1, PHASE2, and the beginning of PHASE3 for RESET.

5.6 PORST electrical specifications

Table 19. PORST electrical specifications

Symbol	Parameter	Value			Unit
		Min	Typ	Max	
W_{FPORST}	$\overline{\text{PORST}}$ input filtered pulse	—	—	200	ns
$W_{NFPORST}$	$\overline{\text{PORST}}$ input not filtered pulse	1000	—	—	ns
V_{IH}	Input high level	0.65 x $V_{DD\_HV\_A}$	—	—	V
V_{IL}	Input low level	—	—	0.35 x $V_{DD\_HV\_A}$	V

6 Peripheral operating requirements and behaviours

6.1 Analog

6.1.1 ADC electrical specifications

The device provides a 12-bit Successive Approximation Register (SAR) Analog-to-Digital Converter.

6.4 Communication interfaces

6.4.1 DSPI timing

Table 35. DSPI electrical specifications

No	Symbol	Parameter	Conditions	High Speed Mode		low Speed mode		Unit
				Min	Max	Min	Max	
1	t_{SCK}	DSPI cycle time	Master (MTFE = 0)	25	—	50	—	ns
			Slave (MTFE = 0)	40	—	60	—	
2	t_{CSC}	PCS to SCK delay	—	16	—	—	—	ns
3	t_{ASC}	After SCK delay	—	16	—	—	—	ns
4	t_{SDC}	SCK duty cycle	—	$t_{SCK}/2 - 10$	$t_{SCK}/2 + 10$	—	—	ns
5	t_A	Slave access time	$\overline{SS}$ active to SOUT valid	—	40	—	—	ns
6	t_{DIS}	Slave SOUT disable time	SS inactive to SOUT High-Z or invalid	—	10	—	—	ns
7	t_{PCSC}	PCSx to $\overline{PCSS}$ time	—	13	—	—	—	ns
8	t_{PASC}	$\overline{PCSS}$ to PCSx time	—	13	—	—	—	ns
9	t_{SUI}	Data setup time for inputs	Master (MTFE = 0)	NA	—	20	—	ns
			Slave	2	—	2	—	
			Master (MTFE = 1, CPHA = 0)	15	—	8[1, 1]	—	
			Master (MTFE = 1, CPHA = 1)	15	—	20	—	
10	t_{HI}	Data hold time for inputs	Master (MTFE = 0)	NA	—	–5	—	ns
			Slave	4	—	4	—	
			Master (MTFE = 1, CPHA = 0)	0	—	11[1]	—	
			Master (MTFE = 1, CPHA = 1)	0	—	-5	—	
11	t_{SUO}	Data valid (after SCK edge)	Master (MTFE = 0)	—	NA	—	4	ns
			Slave	—	15	—	23	
			Master (MTFE = 1, CPHA = 0)	—	4	—	16[1]	
			Master (MTFE = 1, CPHA = 1)	—	4	—	4	

Table continues on the next page...

Table 35. DSPI electrical specifications (continued)

No	Symbol	Parameter	Conditions	High Speed Mode		low Speed mode		Unit
				Min	Max	Min	Max	
12	t_{HO}	Data hold time for outputs	Master (MTFE = 0)	NA	—	–2	—	ns
			Slave	4	—	6	—	
			Master (MTFE = 1, CPHA = 0)	-2	—	10[1]	—	
			Master (MTFE = 1, CPHA = 1)	–2	—	–2	—	

1. SMPL_PTR should be set to 1

NOTE

Restriction For High Speed modes

- DSPI2, DSPI3, SPI1 and SPI2 will support 40MHz Master mode SCK
- DSPI2, DSPI3, SPI1 and SPI2 will support 25MHz Slave SCK frequency
- Only one {SIN,SOUT and SCK} group per DSPI/SPI will support high frequency mode
- For Master mode MTFE will be 1 for high speed mode
- For high speed slaves, their master have to be in MTFE=1 mode or should be able to support 15ns tSUO delay

NOTE

For numbers shown in the following figures, see Table 35

Table 36. Continuous SCK timing

Spec	Characteristics	Pad Drive/Load	Value	
			Min	Max
tSCK	SCK cycle timing	strong/50 pF	100 ns	-
-	PCS valid after SCK	strong/50 pF	-	15 ns
-	PCS valid after SCK	strong/50 pF	-4 ns	-

Table 37. DSPI high speed mode I/Os

DSPI	High speed SCK	High speed SIN	High speed SOUT
DSPI2	GPIO[78]	GPIO[76]	GPIO[77]
DSPI3	GPIO[100]	GPIO[101]	GPIO[98]
SPI1	GPIO[173]	GPIO[175]	GPIO[176]
SPI2	GPIO[79]	GPIO[110]	GPIO[111]

6.4.2 FlexRay electrical specifications

6.4.2.1 FlexRay timing

This section provides the FlexRay Interface timing characteristics for the input and output signals. It should be noted that these are recommended numbers as per the FlexRay EPL v3.0 specification, and subject to change per the final timing analysis of the device.

6.4.2.2 TxEN

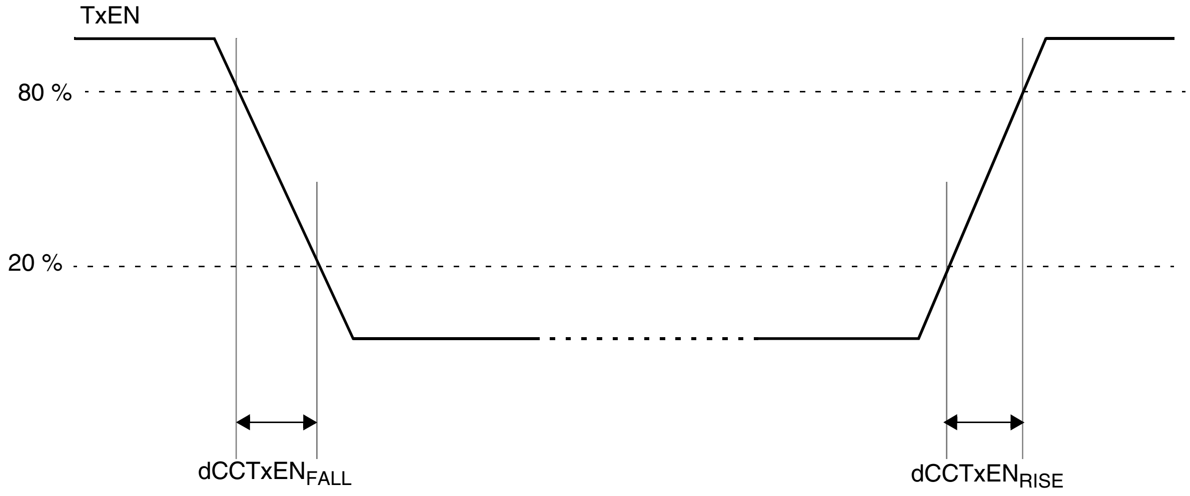

Figure 17. TxEN signal

Table 38. TxEN output characteristics[1]

Name	Description	Min	Max	Unit
dCCTxEN$_{RISE25}$	Rise time of TxEN signal at CC	—	9	ns
dCCTxEN$_{FALL25}$	Fall time of TxEN signal at CC	—	9	ns
dCCTxEN$_{01}$	Sum of delay between Clk to Q of the last FF and the final output buffer, rising edge	—	25	ns
dCCTxEN$_{10}$	Sum of delay between Clk to Q of the last FF and the final output buffer, falling edge	—	25	ns

1. All parameters specified for $V_{DD\_HV\_IOx}$ = 3.3 V -5%, +±10%, TJ = –40 °C / 150 °C, TxEN pin load maximum 25 pF

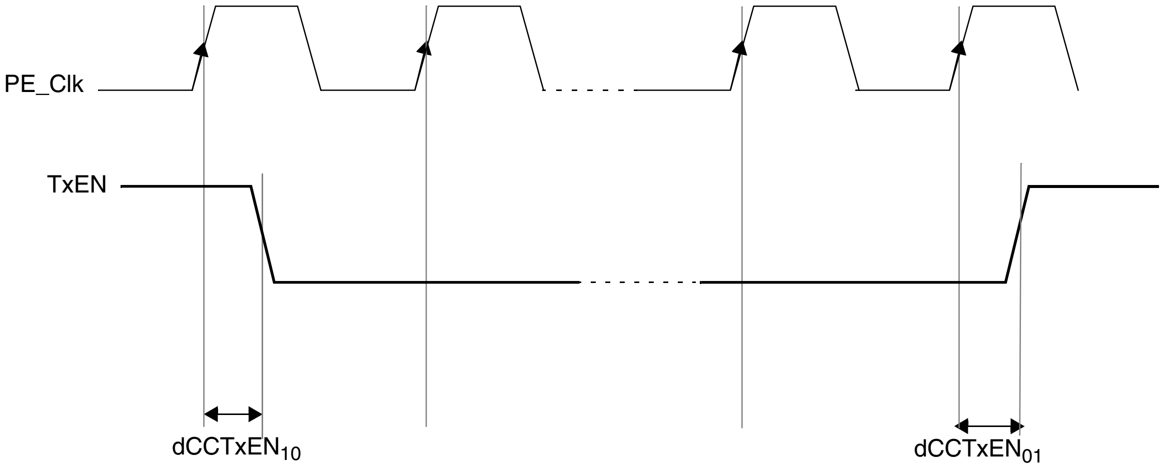

Figure 18. TxEN signal propagation delays

6.4.2.3 TxD

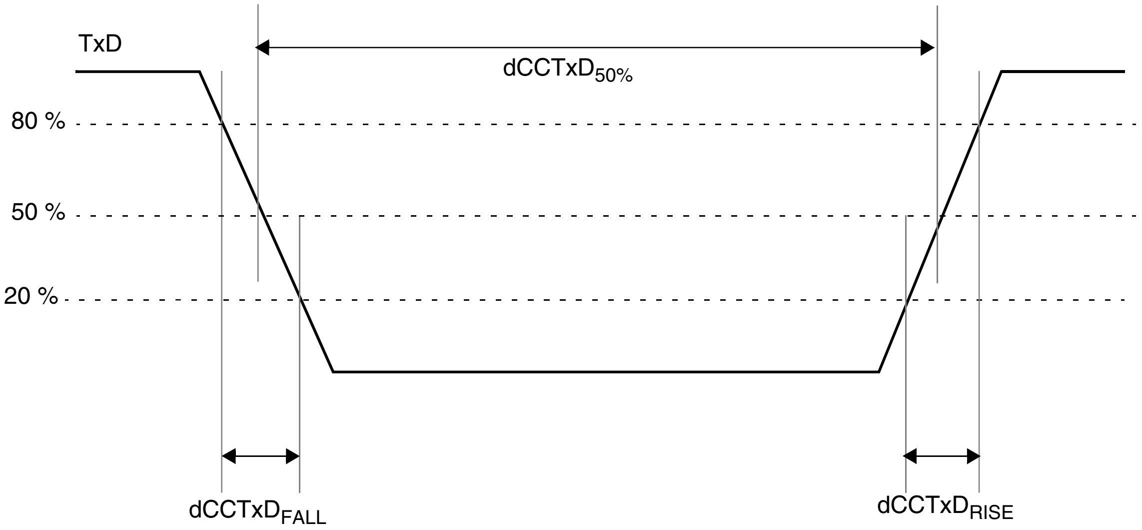

Figure 19. TxD Signal

Table 39. TxD output characteristics

Name	Description[1]	Min	Max	Unit
$dCCT_{xAsym}$	Asymmetry of sending CC @ 25 pF load (=dCCTxD50% - 100 ns)	–2.45	2.45	ns
$dCCTxD_{RISE25}+dCCTxD_{FALL25}$	Sum of Rise and Fall time of TxD signal at the output	—	9[2]	ns

Table continues on the next page...

1. All parameters specified for VDD_HV_IOx = 3.3 V -5%, +±10%, TJ = –40 oC / 150 oC.

6.4.3 Ethernet switching specifications

The following timing specs are defined at the chip I/O pin and must be translated appropriately to arrive at timing specs/constraints for the physical interface.

6.4.3.1 MII signal switching specifications

The following timing specs meet the requirements for MII style interfaces for a range of transceiver devices.

Table 41. MII signal switching specifications

Symbol	Description	Min.	Max.	Unit
—	RXCLK frequency	—	25	MHz
MII1	RXCLK pulse width high	35%	65%	RXCLK period
MII2	RXCLK pulse width low	35%	65%	RXCLK period
MII3	RXD[3:0], RXDV, RXER to RXCLK setup	5	—	ns
MII4	RXCLK to RXD[3:0], RXDV, RXER hold	5	—	ns
—	TXCLK frequency	—	25	MHz
MII5	TXCLK pulse width high	35%	65%	TXCLK period
MII6	TXCLK pulse width low	35%	65%	TXCLK period
MII7	TXCLK to TXD[3:0], TXEN, TXER invalid	2	—	ns
MII8	TXCLK to TXD[3:0], TXEN, TXER valid	—	25	ns

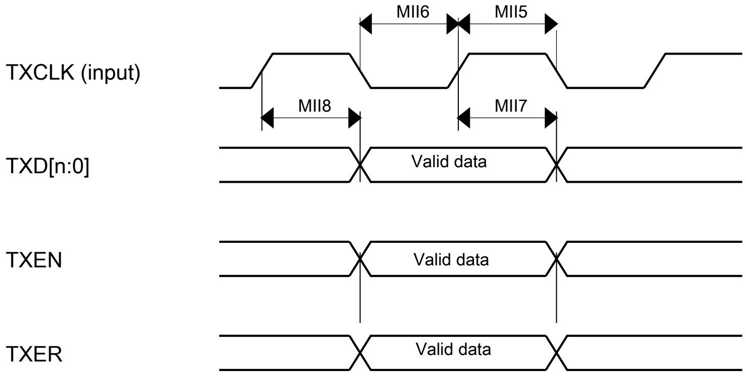

Figure 21. RMII/MII transmit signal timing diagram

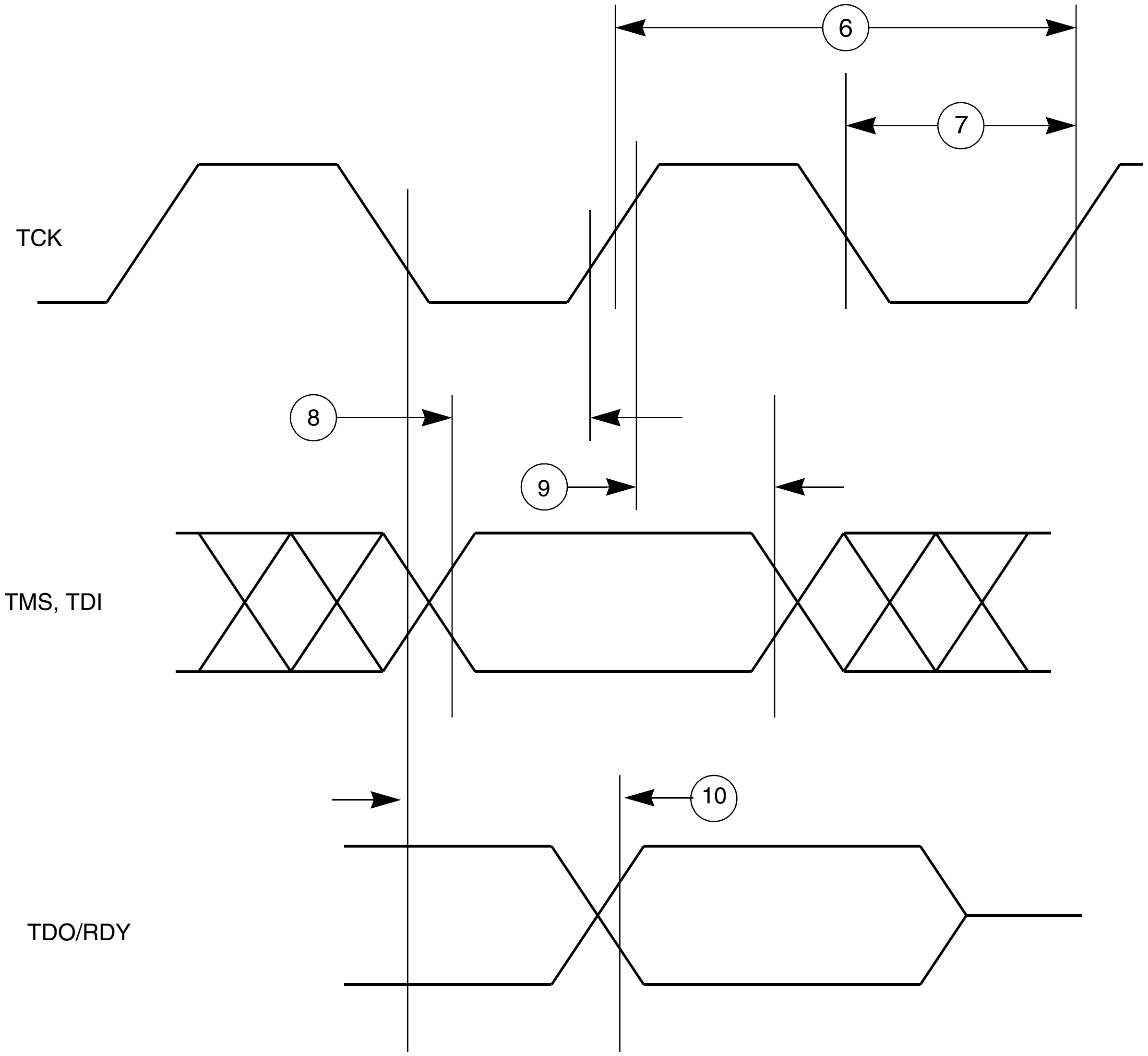

Figure 30. Nexus TDI, TMS, TDO timing

6.5.3 WKPU/NMI timing

Table 47. WKPU/NMI glitch filter

No.	Symbol	Parameter	Min	Typ	Max	Unit
1	W_{FNMI}	NMI pulse width that is rejected	—	—	20	ns
2	$W_{NFNMI}D$	NMI pulse width that is passed	400	—	—	ns

6.5.4 External interrupt timing (IRQ pin)

Table 48. External interrupt timing specifications

No.	Symbol	Parameter	Conditions	Min	Max	Unit
1	t_{IPWL}	IRQ pulse width low	—	3	—	t_{CYC}
2	t_{IPWH}	IRQ pulse width high	—	3	—	t_{CYC}
3	t_{ICYC}	IRQ edge to edge time	—	6	—	t_{CYC}

These values applies when IRQ pins are configured for rising edge or falling edge events, but not both.

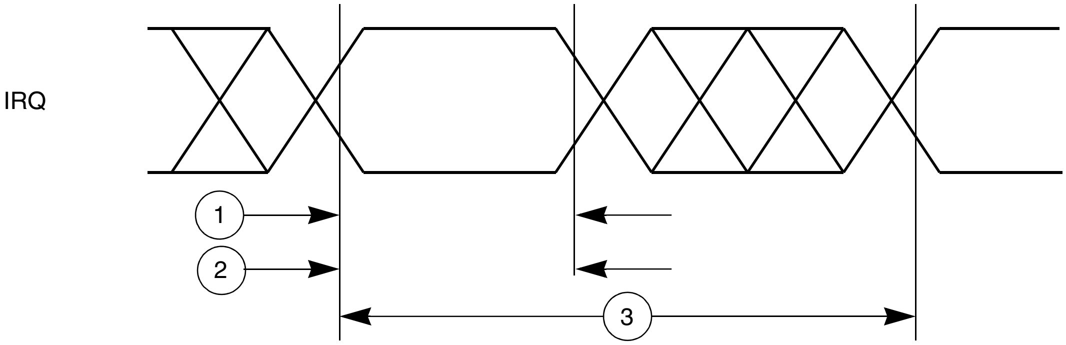

Figure 31. External interrupt timing

7 Thermal attributes

7.1 Thermal attributes

Board type	Symbol	Description	176LQFP	Unit	Notes
Single-layer (1s)	$R_{\theta JA}$	Thermal resistance, junction to ambient (natural convection)	50.7	°C/W	11, 22
Four-layer (2s2p)	$R_{\theta JA}$	Thermal resistance, junction to ambient (natural convection)	24.2	°C/W	1, 2, 33
Single-layer (1s)	$R_{\theta JMA}$	Thermal resistance, junction to ambient (200 ft./ min. air speed)	38.1	°C/W	1, 3

Table continues on the next page...

Package	NXP Document Number
176-pin LQFP-EP	98ASA00698D
256 MAPBGA	98ASA00346D
324 MAPBGA	98ASA10582D

9 Pinouts

9.1 Package pinouts and signal descriptions

For package pinouts and signal descriptions, refer to the Reference Manual.

10 Reset sequence

10.1 Reset sequence

This section describes different reset sequences and details the duration for which the device remains in reset condition in each of those conditions.

10.1.1 Reset sequence duration

Table 49 specifies the reset sequence duration for the five different reset sequences described in Reset sequence description.

Table 49. RESET sequences

No.	Symbol	Parameter	T_{Reset}			Unit
			Min	Typ [1], [1]	Max	
1	T_{DRB}	Destructive Reset Sequence, BIST enabled	6.2	7.3	-	ms
2	T_{DR}	Destructive Reset Sequence, BIST disabled	110	182	-	us
3	T_{ERLB}	External Reset Sequence Long, Unsecure Boot	6.2	7.3	-	ms
4	T_{FRL}	Functional Reset Sequence Long, Unsecure Boot	110	182	-	us
5	T_{FRS}	Functional Reset Sequence Short, Unsecure Boot	7	9	-	us

1. The Typ value is applicable only if the reset sequence duration is not prolonged by an extended assertion of RESET_B by an external reset generator.

10.1.2 BAF execution duration

Following table specifies the typical BAF execution time in case BAF boot header is present at first location (Typical) and last location (worst case). Total Boot time is the sum of reset sequence duration and BAF execution time.

Table 50. BAF execution duration

BAF execution duration	Min	Typ	Max	Unit
BAF execution time (boot header at first location)	—	200	—	µs
BAF execution time (boot header at last location)	—	—	320	µs

10.1.3 Reset sequence description

The figures in this section show the internal states of the device during the five different reset sequences. The dotted lines in the figures indicate the starting point and the end point for which the duration is specified in .

With the beginning of DRUN mode, the first instruction is fetched and executed. At this point, application execution starts and the internal reset sequence is finished.

The following figures show the internal states of the device during the execution of the reset sequence and the possible states of the RESET_B signal pin.

NOTE

RESET_B is a bidirectional pin. The voltage level on this pin can either be driven low by an external reset generator or by the device internal reset circuitry. A high level on this pin can only be generated by an external pullup resistor which is strong enough to overdrive the weak internal pulldown resistor. The rising edge on RESET_B in the following figures indicates the time when the device stops driving it low. The reset sequence durations given in are applicable only if the internal reset sequence is not prolonged by an external reset generator keeping RESET_B asserted low beyond the last Phase3.

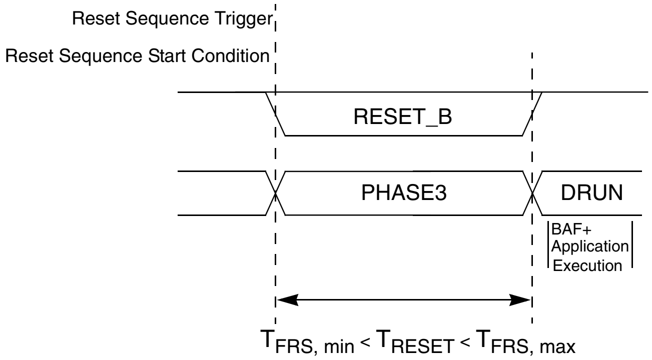

Figure 36. Functional reset sequence short

The reset sequences shown in Figure 35 and Figure 36 are triggered by functional reset events. RESET_B is driven low during these two reset sequences only if the corresponding functional reset source (which triggered the reset sequence) was enabled to drive RESET_B low for the duration of the internal reset sequence. See the RGM_FBRE register in the device reference manual for more information.

11 Revision History

11.1 Revision History

The following table provides a revision history for this document.

Table 51. Revision History

Rev. No.	Date	Substantial Changes
Rev 1	14 March 2013	Initial Release

Table continues on the next page...

Table 51. Revision History (continued)

Rev. No.	Date	Substantial Changes
Rev 3	2 March 2016	• In section, Recommended operating conditions • Added a new Note • In section, Voltage regulator electrical characteristics • In table, Voltage regulator electrical specifications: • Added a new row for $C_{HV\_VDD\_B}$ • Added a footnote on $V_{DD\_HV\_BALLAST}$ • Added a new Note at the end of this section • In section, Voltage monitor electrical characteristics • In table, Voltage monitor electrical characteristics: • Removed "V_{LVD_FLASH}" and "V_{LVD_FLASH} during low power mode using LPBG as reference" rows • Updated Fall and Rise trimmed Minimum values for $V_{HVD\_LV\_cold}$ • In section, Supply current characteristics • In table, Current consumption characteristics: • Updated the footnote mentioned in the Condition column of I_{DD_STOP} row • Updated all TBD values • In table, Low Power Unit (LPU) Current consumption characteristics: • Updated the typical value of LPU_STOP to 0.18 mA • Updated all TBD values • In table, STANDBY Current consumption characteristics: • Updated all TBD values • In section, AC specifications @ 3.3 V Range • In table, Functional Pad AC Specifications @ 3.3 V Range: • Updated Rise/Fall Edge values • In section, DC electrical specifications @ 3.3V Range • In table, DC electrical specifications @ 3.3V Range: • Updated Max value for Vol to 0.1 * VDD_HV_x • In section, AC specifications @ 5 V Range • In table, Functional Pad AC Specifications @ 5 V Range: • Updated Rise/Fall Edge values • In section, DC electrical specifications @ 5 V Range • In table, DC electrical specifications @ 5 V Range: • Updated Min and Max values for Pull_Ioh and Pull_Iol rows • Updated Max value for Vol to 0.1 * VDD_HV_x • In section, Reset pad electrical characteristics • In table, Functional reset pad electrical specifications: • Updated parameter column for V_{IH}, V_{IL} and V_{HYS} rows • Updated Min and Max values for V_{IH} and V_{IL} rows • In section, PORST electrical specifications • In table, PORST electrical specifications: • Updated Unit and Min/Max values for V_{IH} and V_{IL} rows • In section, Input equivalent circuit and ADC conversion characteristics • In table, ADC conversion characteristics (for 12-bit): • Updated "ADC Analog Pad (pad going to one ADC)" row • In table, ADC conversion characteristics (for 10-bit): • Updated "ADC Analog Pad (pad going to one ADC)" row • In section, Analog Comparator (CMP) electrical specifications • In table, Comparator and 6-bit DAC electrical specifications: • Updated Min and Max values for V_{AIO} to ±47 mV • Updated Max value for t_{DLS} to 21 µs • In section, Main oscillator electrical characteristics • In table, Main oscillator electrical characteristics:

Table 51. Revision History (continued)

Rev. No.	Date	Substantial Changes

Rev 4	9 March 2016	• In section, Voltage regulator electrical characteristics
		  • In table, Voltage regulator electrical specifications:
		    • Updated the footnote on $V_{DD\_HV\_BALLAST}$

Rev 5	27 February 2017	• In Family Comparison section:
		  • Updated the "MPC5746C Family Comparison" table.
		  • added "NVM Memory Map 1", "NVM Memory Map 2", and "RAM Memory Map" tables.
		• Updated the product version, flash memory size and optional fields information in Ordering Information section.
		• In Recommended Operating Conditions section, removed the note related to additional crossover current.
		• VDD_HV_C row added in "Voltage regulator electrical specifications" table in Voltage regulator electrical characteristics section.
		• In Voltage Monitor Electrical Characteristics section, updated the "Trimmed" Fall and Rise specs of VHVD_LV_cold parameter in "Voltage Monitor Electrical Characteristics" table.
		• In AC Electrical Specifications: 3.3 V Range section, changed the occurrences of “ipp_sre[1:0]” to “SIUL2_MSCRn.SRC[1:0]” in the table.
		• In DC Electrical Specifications: 3.3 V Range section, changed the occurrences of “ipp_sre[1:0]” to “SIUL2_MSCRn.SRC[1:0]” and updated "Vol min and max" values in the table.
		• In AC Electrical Specifications: 5 V Range section, changed the occurrences of “ipp_sre[1:0]” to “SIUL2_MSCRn.SRC[1:0]” in the table.
		• In DC Electrical Specifications: 5 V Range section, changed the occurrences of “ipp_sre[1:0]” to “SIUL2_MSCRn.SRC[1:0]” and updated "Vol min and max" values in the table.
		• In "Flash memory AC timing specifications" table in Flash memory AC timing specifications section:
		  • Updated the "t_{psus}" typ value from 7 us to 9.4 us.
		  • Updated the "t_{psus}" max value from 9.1 us to 11.5 us.
		• Added "Continuous SCK Timing" table in DSPI timing section.
		• Added "ADC pad leakage" at 105°C TA conditions in "ADC conversion characteristics (for 12-bit)" table in ADC electrical specifications section.
		• In "STANDBY Current consumption characteristics" table in Supply current characteristics section:
		  • Updated the Typ and max values of IDD Standby current.
		  • Added IDD Standby3 current spec for FIRC ON.
		• Removed IVDDHV and IVDDLV specs in 16 MHz RC Oscillator electrical specifications section.
		• Added Reset Sequence section, with Reset Sequence Duration, BAF execution duration section, and Reset Sequence Distribution as its sub-sections.

Table continues on the next page...