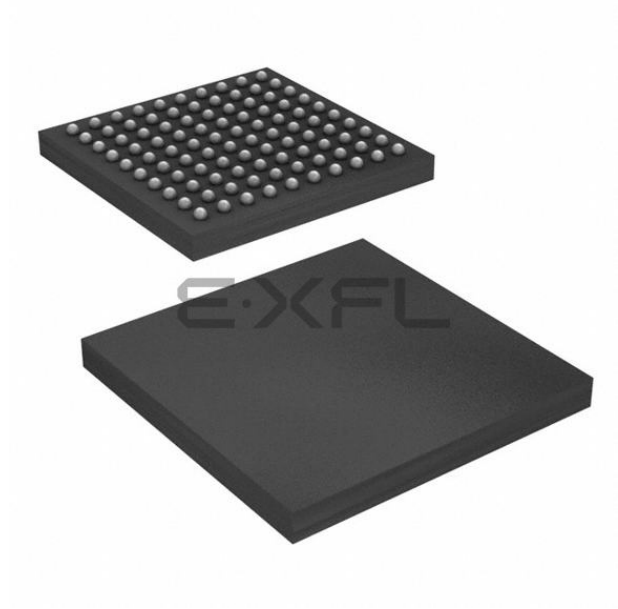

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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	e200z4
Core Size	32-Bit Single-Core
Speed	160MHz
Connectivity	CANbus, Ethernet, FlexRay, I²C, LINbus, SPI
Peripherals	DMA, I²S, POR, WDT
Number of I/O	-
Program Memory Size	2MB (2M x 8)
Program Memory Type	FLASH
EEPROM Size	64K x 8
RAM Size	256K x 8
Voltage - Supply (Vcc/Vdd)	3.15V ~ 5.5V
Data Converters	A/D 36x10b, 16x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LFBGA
Supplier Device Package	100-MAPBGA (11x11)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/spc5745bbk1avmh6

- Debug functionality
  - e200z2 core:NDI per IEEE-ISTO 5001-2008 Class3+
  - e200z4 core: NDI per IEEE-ISTO 5001-2008 Class 3+

- Timer
  - 16 Periodic Interrupt Timers (PITs)
  - Two System Timer Modules (STM)
  - Three Software Watchdog Timers (SWT)
  - 64 Configurable Enhanced Modular Input Output Subsystem (eMIOS) channels

- Device/board boundary Scan testing supported with Joint Test Action Group (JTAG) of IEEE 1149.1 and IEEE 1149.7 (CJTAG)

- Security
  - Hardware Security Module (HSMv2)
  - Password and Device Security (PASS) supporting advanced censorship and life-cycle management
  - One Fault Collection and Control Unit (FCCU) to collect faults and issue interrupts

- Functional Safety
  - ISO26262 ASIL-B compliance

- Multiple operating modes
  - Includes enhanced low power operation

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NOTE

All optional features (Flash memory, RAM, Peripherals) start with lowest number or address (e.g., FlexCAN0) and end at highest available number or address (e.g., MPC574xB/C have 6 CAN, ending with FlexCAN5).

Table 1. MPC5746C Family Comparison[1]

Feature	MPC5745B	MPC5744B	MPC5746B	MPC5744C	MPC5745C	MPC5746C
CPUs	e200z4	e200z4	e200z4	e200z4 e200z2	e200z4 e200z2	e200z4 e200z2
FPU	e200z4	e200z4	e200z4	e200z4	e200z4	e200z4
Maximum Operating Frequency[2]	160MHz (Z4)	160MHz (Z4)	160MHz (Z4)	160MHz (Z4) 80MHz (Z2)	160MHz (Z4) 80MHz (Z2)	160MHz (Z4) 80MHz (Z2)
Flash memory	2 MB	1.5 MB	3 MB	1.5 MB	2 MB	3 MB
EEPROM support	Emulated up to 64K			Emulated up to 64K		
RAM	256 KB	192 KB	384 KB (Optional 512KB)[3, 3]	192 KB	256 KB	384 KB (Optional 512KB)[3]
ECC	End to End					
SMPU	16 entry					
DMA	32 channels					
10-bit ADC	36 Standard channels 32 External channels					
12-bit ADC	15 Precision channels 16 Standard channels					
Analog Comparator	3					
BCTU	1					
SWT	1, SWT[0][4]			2[4]		
STM	1, STM[0]			2		
PIT-RTI	16 channels PIT 1 channels RTI					
RTC/API	1					
Total Timer I/O[5]	64 channels 16-bits					
LINFlexD	1 Master and Slave (LINFlexD[0], 11 Master (LINFlexD[1:11])			1 Master and Slave (LINFlexD[0], 15 Master (LINFlexD[1:15])		
FlexCAN	6 with optional CAN FD support (FlexCAN[0:5])			8 with optional CAN FD support (FlexCAN[0:7])		
DSPI/SPI	4 x DSPI 4 x SPI					

Table continues on the next page...

Table 4. MPC5746C Family Comparison - RAM Memory Map (continued)

Start Address	End Address	Allocated size	Description	MPC5744	MPC5745	MPC5746
0x40030000	0x4003FFFF	64 KB	SRAM4	not available	available	available
0x40040000	0x4004FFFF	64 KB	SRAM5	not available	not available	available
0x40050000	0x4005FFFF	64 KB	SRAM6	not available	not available	available
0x40060000	0x4006FFFF	64 KB	SRAM7	not available	not available	optional
0x40070000	0x4007FFFF	64 KB	SRAM8	not available	not available	optional

3 Ordering parts

3.1 Determining valid orderable parts

To determine the orderable part numbers for this device, go to www.nxp.com and perform a part number search for the following device number: MPC5746C.

Table 8. Voltage regulator electrical specifications (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
C_{flash_reg}[4]	External decoupling / stability capacitor for internal Flash regulators	Min, max values shall be granted with respect to tolerance, voltage, temperature, and aging variations.	1.32	2.2	3	µF
	Combined ESR of external capacitor	—	0.001	—	0.03	Ohm
$C_{HV\_VDD\_A}$	VDD_HV_A supply capacitor [5, 5]	Min, max values shall be granted with respect to tolerance, voltage, temperature, and aging variations.	1	—	—	µF
$C_{HV\_VDD\_B}$	VDD_HV_B supply capacitor[5]	Min, max values shall be granted with respect to tolerance, voltage, temperature, and aging variations.	1	—	—	µF
$C_{HV\_VDD\_C}$	VDD_HV_C supply capacitor[5]	Min, max values shall be granted with respect to tolerance, voltage, temperature, and aging variations.	1	—	—	µF
C_{HV_ADC0} C_{HV_ADC1}	HV ADC supply decoupling capacitances	Min, max values shall be granted with respect to tolerance, voltage, temperature, and aging variations.	1	—	—	µF
C_{HV_ADR}[6]	HV ADC SAR reference supply decoupling capacitances	Min, max values shall be granted with respect to tolerance, voltage, temperature, and aging variations.	0.47	—	—	µF
$V_{DD\_HV\_BALLAST}$[7]	FPREG Ballast collector supply voltage	When collector of NPN ballast is directly supplied by an on board supply source (not shared with VDD_HV_A supply pin) without any series resistance, that is, $R_{C\_BALLAST}$ less than 0.01 Ohm.	2.25	—	5.5	V
$R_{C\_BALLAST}$	Series resistor on collector of FPREG ballast	When VDD_HV_BALLAST is shorted to VDD_HV_A on the board	—	—	0.1	Ohm
t_{SU}	Start-up time with external ballastafter main supply (VDD_HV_A) stabilization	Cfp_reg = 3 µF	—	74	—	µs
t_{SU_int}	Start-up time with internal ballast after main supply (VDD_HV_A) stabilization	Cfp_reg = 3 µF	—	103	—	µs
t_{ramp}	Load current transient	Iload from 15% to 55% C_{fp_reg} = 3 µF		1.0		µs

1. Split capacitance on each pair VDD_LV pin should sum up to a total value of C_{fp_reg}
2. Typical values will vary over temperature, voltage, tolerance, drift, but total variation must not exceed minimum and maximum values.
3. Ceramic X7R or X5R type with capacitance-temperature characteristics +/-15% of -55 degC to +125degC is recommended. The tolerance +/-20% is acceptable.
4. It is required to minimize the board parasitic inductance from decoupling capacitor to VDD_HV_FLA pin and the routing inductance should be less than 1nH.

5. 1. For VDD_HV_x, 1µf on each side of the chip
      a. 0.1 µf close to each VDD/VSS pin pair.
      b. 10 µf near for each power supply source
      c. For VDD_LV, 0.1uf close to each VDD/VSS pin pair is required. Depending on the the selected regulation mode, this amount of capacitance will need to be subtracted from the total capacitance required by the regulator for e.g., as specified by CFP_REG parameter.
   2. For VDD_LV, 0.1uf close to each VDD/VSS pin pair is required. Depending on the the selected regulation mode, this amount of capacitance will need to be subtracted from the total capacitance required by the regulator for e.g., as specified by CFP_REG parameter
6. Only applicable to ADC1
7. In external ballast configuration the following must be ensured during power-up and power-down (Note: If $V_{DD\_HV\_BALLAST}$ is supplied from the same source as VDD_HV_A this condition is implicitly met):
   - During power-up, $V_{DD\_HV\_BALLAST}$ must have met the min spec of 2.25V before VDD_HV_A reaches the POR_HV_RISE min of 2.75V.
   - During power-down, $V_{DD\_HV\_BALLAST}$ must not drop below the min spec of 2.25V until VDD_HV_A is below POR_HV_FALL min of 2.7V.

NOTE

For a typical configuration using an external ballast transistor with separate supply for VDD_HV_A and the ballast collector, a bulk storage capacitor (as defined in Table 8) is required on VDD_HV_A close to the device pins to ensure a stable supply voltage.

Extra care must be taken if the VDD_HV_A supply is also being used to power the external ballast transistor or the device is running in internal regulation mode. In these modes, the inrush current on device Power Up or on exit from Low Power Modes is significant and may case the VDD_HV_A voltage to drop resulting in an LVD reset event. To avoid this, the board layout should be optimized to reduce common trace resistance or additional capacitance at the ballast transistor collector (or VDD_HV_A pins in the case of internal regulation mode) is required. NXP recommends that customers simulate the external voltage supply circuitry.

In all circumstances, the voltage on VDD_HV_A must be maintained within the specified operating range (see Recommended operating conditions) to prevent LVD events.

Table 17. DC electrical specifications @ 5 V Range (continued)

Symbol	Parameter	Value		Unit
		Min	Max	
Vil (pad_i_hv)	pad_i_hv Input Buffer Low Voltage	VDD_HV_x - 0.3	0.45*VDD_HV_x	V
Vhys (pad_i_hv)	pad_i_hv Input Buffer Hysteresis	0.09*VDD_HV_x		V
Vih_hys	CMOS Input Buffer High Voltage (with hysteresis enabled)	0.65* VDD_HV_x	VDD_HV_x + 0.3	V
Vil_hys	CMOS Input Buffer Low Voltage (with hysteresis enabled)	VDD_HV_x - 0.3	0.35*VDD_HV_x	V
Vih	CMOS Input Buffer High Voltage (with hysteresis disabled)	0.55 * VDD_HV_x[1, 1]	VDD_HV_x[1] + 0.3	V
Vil	CMOS Input Buffer Low Voltage (with hysteresis disabled)	VDD_HV_x - 0.3	0.40 * VDD_HV_x[1]	V
Vhys	CMOS Input Buffer Hysteresis	0.09 * VDD_HV_x[1]		V
Pull_IIH (pad_i_hv)	Weak Pullup Current[2, 2] Low	23		µA
Pull_IIH (pad_i_hv)	Weak Pullup Current[3, 3] High		82	µA
Pull_IIL (pad_i_hv)	Weak Pulldown Current[3] Low	40		µA
Pull_IIL (pad_i_hv)	Weak Pulldown Current[2] High		130	µA
Pull_Ioh	Weak Pullup Current[4]	30	80	µA
Pull_Iol	Weak Pulldown Current[5]	30	80	µA
Iinact_d	Digital Pad Input Leakage Current (weak pull inactive)	-2.5	2.5	µA
Voh	Output High Voltage[6]	0.8 * VDD_HV_x[1]	—	V
Vol	Output Low Voltage[7] Output Low Voltage[8]	—	0.2*VDD_HV_x 0.1*VDD_HV_x	V
Ioh_f	Full drive Ioh[9, 9] (SIUL2_MSCRn.SRC[1:0] = 11)	18	70	mA
Iol_f	Full drive Iol[9] (SIUL2_MSCRn.SRC[1:0] = 11)	21	120	mA
Ioh_h	Half drive Ioh[9] (SIUL2_MSCRn.SRC[1:0] = 10)	9	35	mA
Iol_h	Half drive Iol[9] (SIUL2_MSCRn.SRC[1:0] = 10)	10.5	60	mA

1. VDD_HV_x = VDD_HV_A, VDD_HV_B, VDD_HV_C
2. Measured when pad=0.69*VDD_HV_x
3. Measured when pad=0.49*VDD_HV_x
4. Measured when pad = 0 V
5. Measured when pad = VDD_HV_x
6. Measured when pad is sourcing 2 mA
7. Measured when pad is sinking 2 mA
8. Measured when pad is sinking 1.5 mA
9. Ioh/Iol is derived from spice simulations. These values are NOT guaranteed by test.

5.5 Reset pad electrical characteristics

The device implements a dedicated bidirectional RESET pin.

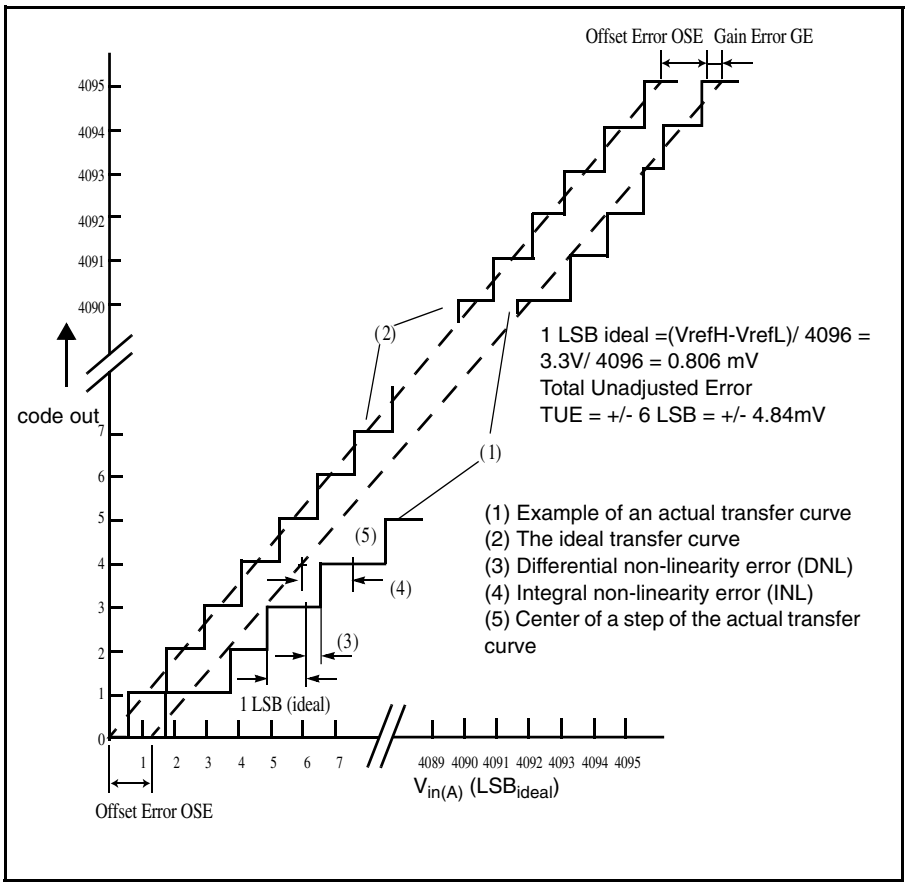


Figure 5. ADC characteristics and error definitions

6.1.2 Analog Comparator (CMP) electrical specifications

Table 22. Comparator and 6-bit DAC electrical specifications

Symbol	Description	Min.	Typ.	Max.	Unit
I_{DDHS}	Supply current, High-speed mode (EN=1, PMODE=1)	—	—	250	µA
I_{DDLS}	Supply current, low-speed mode (EN=1, PMODE=0)	—	5	11	µA
V_{AIN}	Analog input voltage	V_{SS}	—	$V_{IN1\_CMP\_REF}$	V
V_{AIO}	Analog input offset voltage [1, 1]	-47	—	47	mV
V_H	Analog comparator hysteresis [2, 2]	—	1	25	mV
	• CR0[HYSTCTR] = 00	—	20	50	mV
	• CR0[HYSTCTR] = 01	—	40	70	mV
	• CR0[HYSTCTR] = 10	—	60	105	mV
	• CR0[HYSTCTR] = 11				
t_{DHS}	Propagation Delay, High Speed Mode (Full Swing) [1, 3, 3]	—	—	250	ns
t_{DLS}	Propagation Delay, Low power Mode (Full Swing) [1, 3]	—	5	21	µs
	Analog comparator initialization delay, High speed mode[4, 4]	—	4		µs
	Analog comparator initialization delay, Low speed mode [4]	—	100		µs
I_{DAC6b}	6-bit DAC current adder (when enabled)				
	3.3V Reference Voltage	—	6	9	µA
	5V Reference Voltage	—	10	16	µA
INL	6-bit DAC integral non-linearity	–0.5	—	0.5	LSB[5]
DNL	6-bit DAC differential non-linearity	–0.8	—	0.8	LSB

1. Measured with hysteresis mode of 00
2. Typical hysteresis is measured with input voltage range limited to 0.6 to $V_{DD\_HV\_A}$-0.6V
3. Full swing = VIH, VIL
4. Comparator initialization delay is defined as the time between software writes to change control inputs (Writes to DACEN, VRSEL, PSEL, MSEL, VOSEL) and the comparator output settling to a stable level.
5. 1 LSB = $V_{reference}/64$

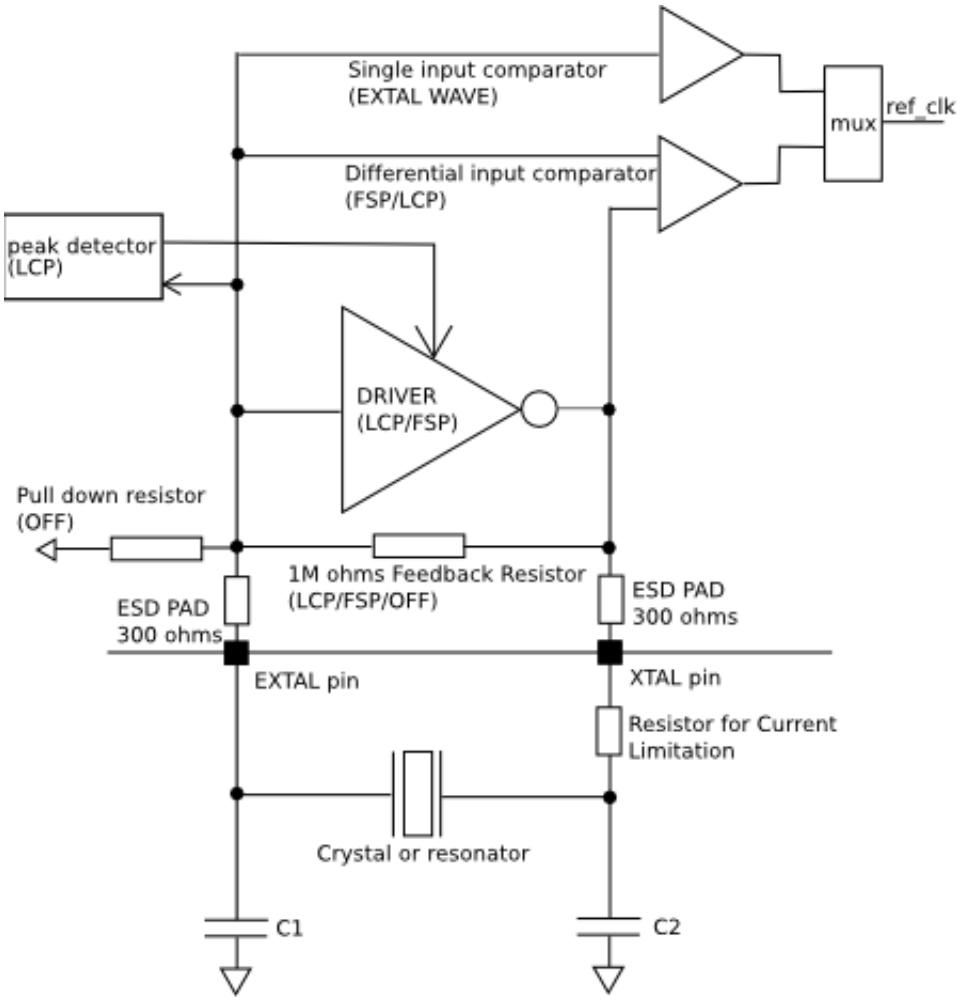
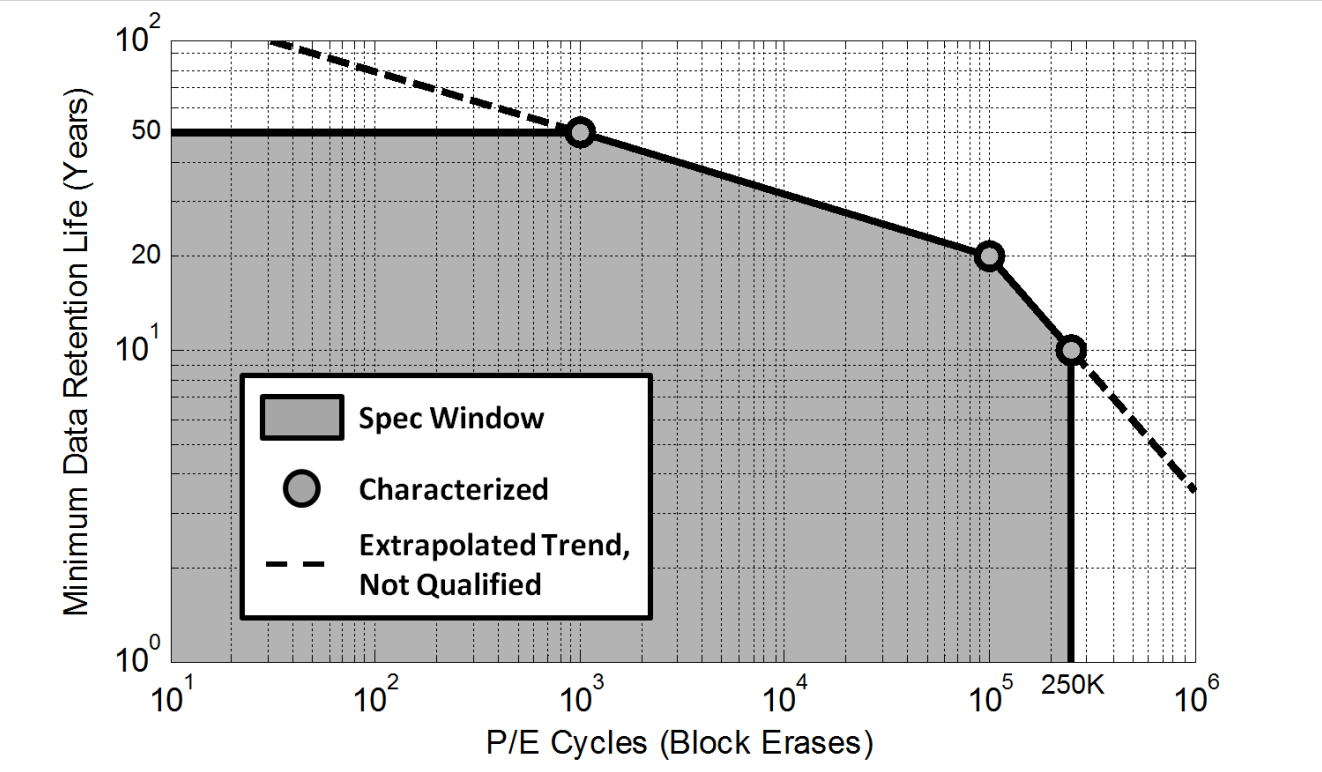


Figure 7. Oscillator connections scheme

Table 23. Main oscillator electrical characteristics

Symbol	Parameter	Mode	Conditions	Min	Typ	Max	Unit
f_{XOSCHS}	Oscillator frequency	FSP/LCP		8		40	MHz
$g_{mXOSCHS}$	Driver Transconductance	LCP			23		mA/V
		FSP			33		
V_{XOSCHS}	Oscillation Amplitude	LCP[1, 2, 1, 2]	8 MHz		1.0		V_{PP}
			16 MHz		1.0		
			40 MHz		0.8		
$T_{XOSCHSSU}$	Startup time	FSP/LCP[1]	8 MHz		2		ms
			16 MHz		1		
			40 MHz		0.5		

Table continues on the next page...



6.3.5 Flash memory AC timing specifications

Table 33. Flash memory AC timing specifications

Symbol	Characteristic	Min	Typical	Max	Units
t_{psus}	Time from setting the MCR-PSUS bit until MCR-DONE bit is set to a 1.	—	9.4 plus four system clock periods	11.5 plus four system clock periods	µs
t_{esus}	Time from setting the MCR-ESUS bit until MCR-DONE bit is set to a 1.	—	16 plus four system clock periods	20.8 plus four system clock periods	µs
t_{res}	Time from clearing the MCR-ESUS or PSUS bit with EHV = 1 until DONE goes low.	—	—	100	ns
t_{done}	Time from 0 to 1 transition on the MCR-EHV bit initiating a program/erase until the MCR-DONE bit is cleared.	—	—	5	ns
t_{dones}	Time from 1 to 0 transition on the MCR-EHV bit aborting a program/erase until the MCR-DONE bit is set to a 1.	—	16 plus four system clock periods	20.8 plus four system clock periods	µs

Table continues on the next page...

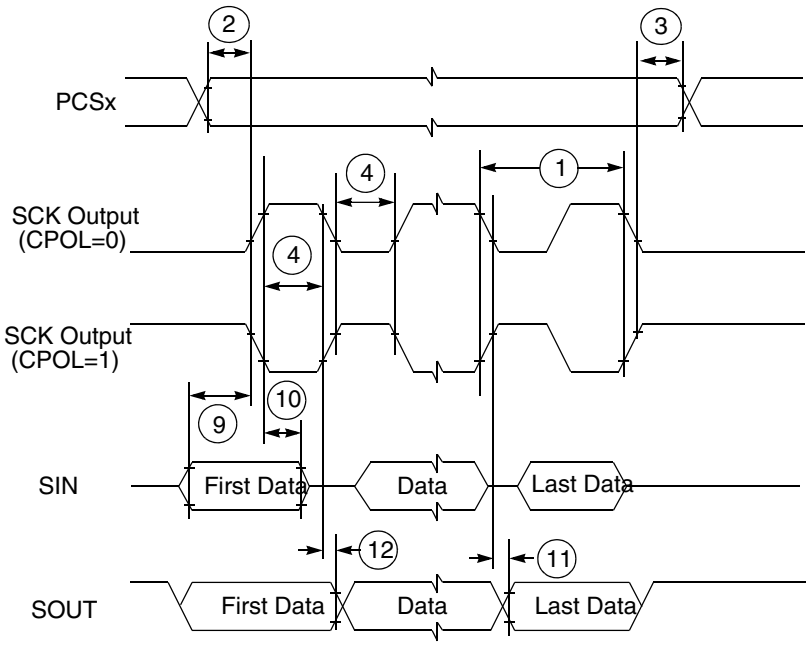


Figure 8. DSPI classic SPI timing — master, CPHA = 0

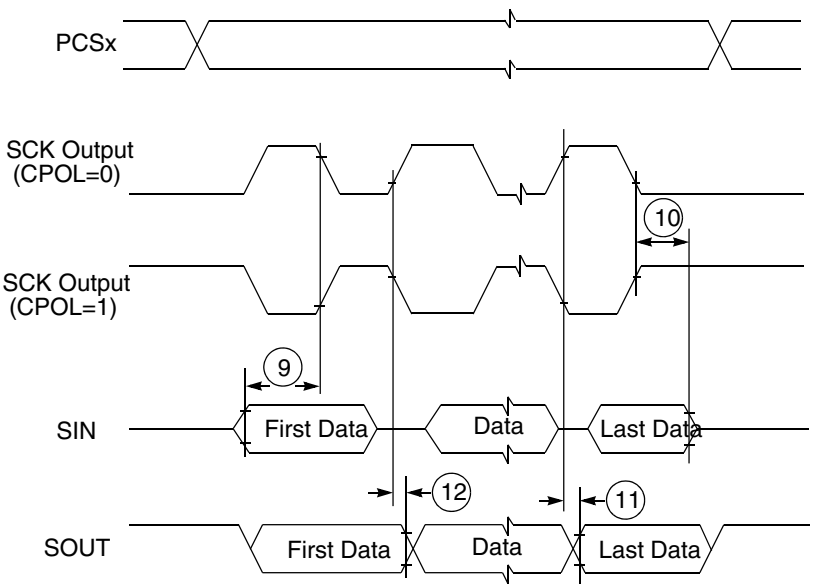


Figure 9. DSPI classic SPI timing — master, CPHA = 1

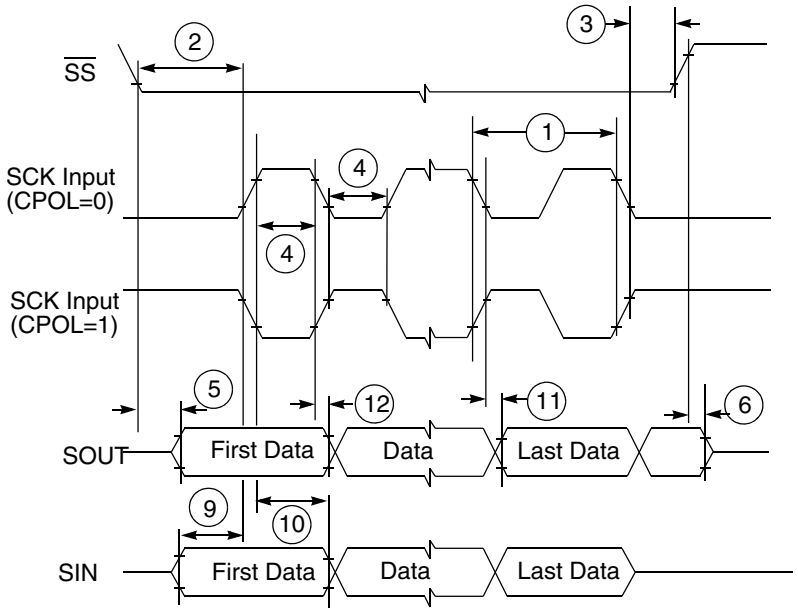


Figure 10. DSPI classic SPI timing — slave, CPHA = 0

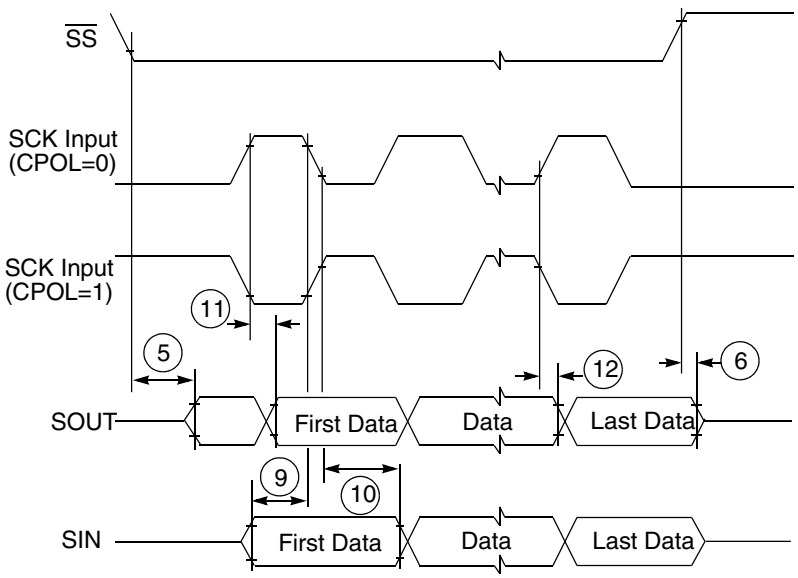


Figure 11. DSPI classic SPI timing — slave, CPHA = 1

Table 43. Master mode SAI Timing (continued)

no	Parameter	Value		Unit
		Min	Max	
S2	SAI_MCLK pulse width high/low	45%	55%	MCLK period
S3	SAI_BCLK cycle time	80	-	BCLK period
S4	SAI_BCLK pulse width high/low	45%	55%	ns
S5	SAI_BCLK to SAI_FS output valid	-	15	ns
S6	SAI_BCLK to SAI_FS output invalid	0	-	ns
S7	SAI_BCLK to SAI_TXD valid	-	15	ns
S8	SAI_BCLK to SAI_TXD invalid	0	-	ns
S9	SAI_RXD/SAI_FS input setup before SAI_BCLK	28	-	ns
S10	SAI_RXD/SAI_FS input hold after SAI_BCLK	0	-	ns

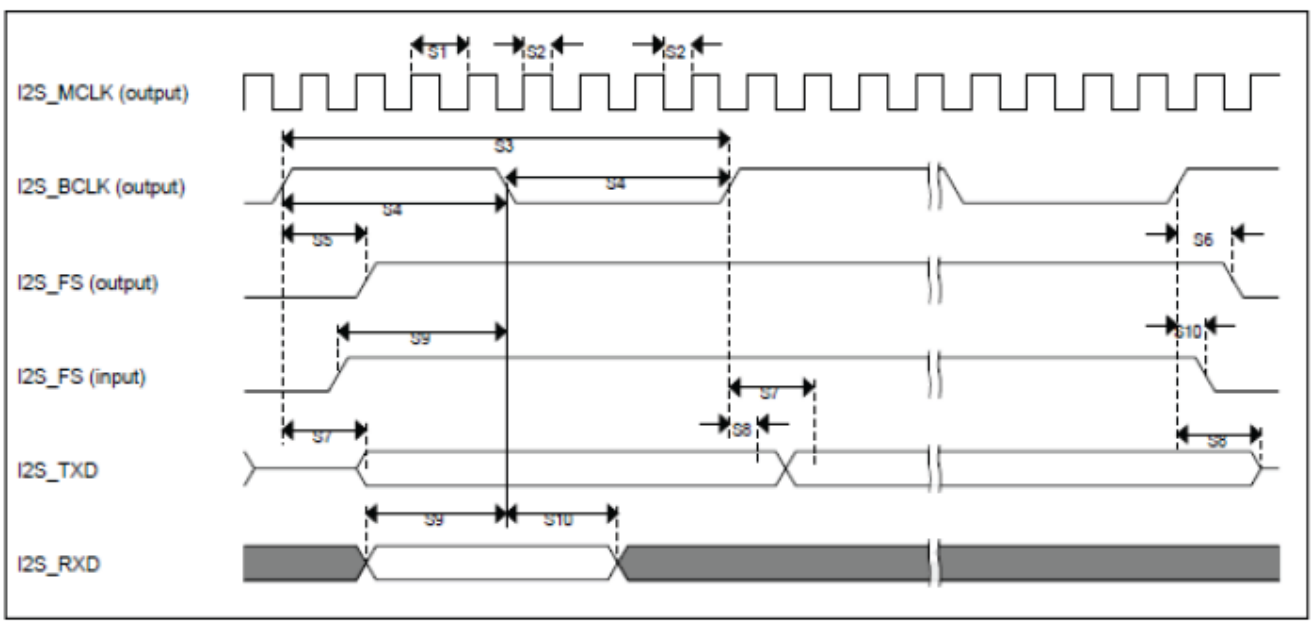


Figure 23. Master mode SAI Timing

Table 44. Slave mode SAI Timing

No	Parameter	Value		Unit
		Min	Max	
	Operating Voltage	2.7	3.6	V
S11	SAI_BCLK cycle time (input)	80	-	ns
S12	SAI_BCLK pulse width high/low (input)	45%	55%	BCLK period
S13	SAI_FS input setup before SAI_BCLK	10	-	ns
S14	SAI_FS input hold after SAI_BCLK	2	-	ns

Table continues on the next page...

Table 44. Slave mode SAI Timing (continued)

No	Parameter	Value		Unit
		Min	Max	
S15	SAI_BCLK to SAI_TXD/SAI_FS output valid	-	28	ns
S16	SAI_BCLK to SAI_TXD/SAI_FS output invalid	0	-	ns
S17	SAI_RXD setup before SAI_BCLK	10	-	ns
S18	SAI_RXD hold after SAI_BCLK	2	-	ns

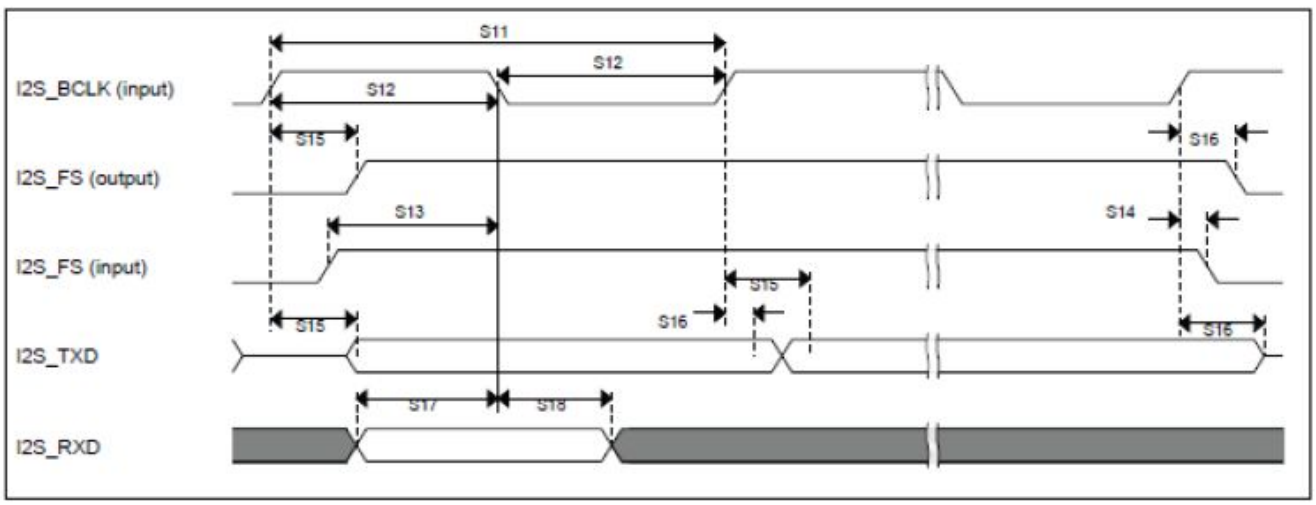


Figure 24. Slave mode SAI Timing

6.5 Debug specifications

6.5.1 JTAG interface timing

Table 45. JTAG pin AC electrical characteristics [1]

#	Symbol	Characteristic	Min	Max	Unit
1	t_{JCYC}	TCK Cycle Time [2, 2]	62.5	—	ns
2	t_{JDC}	TCK Clock Pulse Width	40	60	%
3	$t_{TCKRISE}$	TCK Rise and Fall Times (40% - 70%)	—	3	ns
4	t_{TMSS}, t_{TDIS}	TMS, TDI Data Setup Time	5	—	ns
5	t_{TMSH}, t_{TDIH}	TMS, TDI Data Hold Time	5	—	ns
6	t_{TDOV}	TCK Low to TDO Data Valid	—	20[3, 3]	ns
7	t_{TDOI}	TCK Low to TDO Data Invalid	0	—	ns
8	t_{TDOHZ}	TCK Low to TDO High Impedance	—	15	ns
11	t_{BSDV}	TCK Falling Edge to Output Valid	—	600[4, 4]	ns

Table continues on the next page...

Table 46. Nexus debug port timing [1] (continued)

No.	Symbol	Parameter	Conditions	Min	Max	Unit
9	t_{NTDIH}, t_{NTMSH}	TDI, TMS Data Hold Time	—	5	—	ns
10	t_{JOV}	TCK Low to TDO/RDY Data Valid	—	0	25	ns

1. JTAG specifications in this table apply when used for debug functionality. All Nexus timing relative to MCKO is measured from 50% of MCKO and 50% of the respective signal.
2. For all Nexus modes except DDR mode, MDO, $\overline{\text{MSEO}}$, and $\overline{\text{EVTO}}$ data is held valid until next MCKO low cycle.
3. The system clock frequency needs to be four times faster than the TCK frequency.

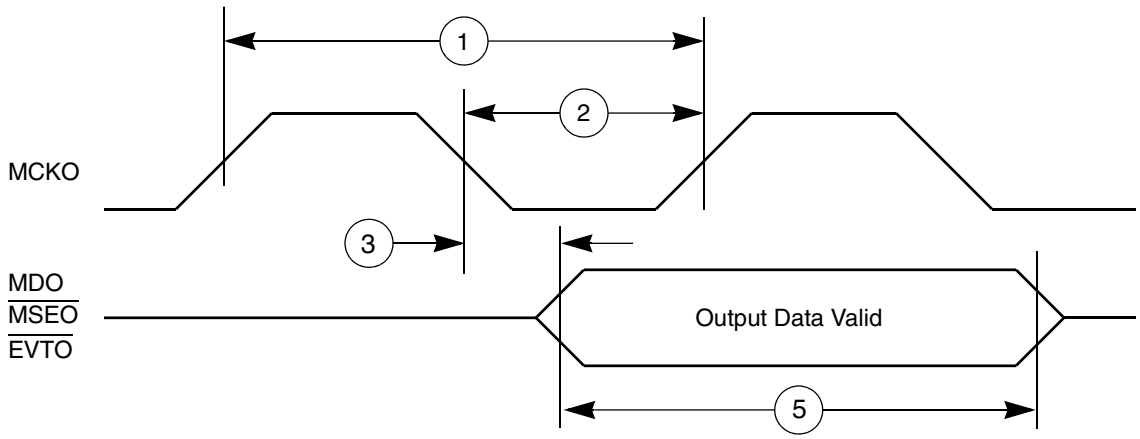


Figure 28. Nexus output timing

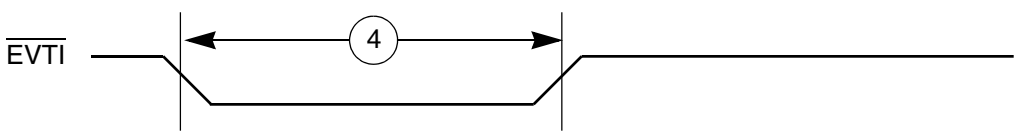


Figure 29. Nexus EVTI Input Pulse Width

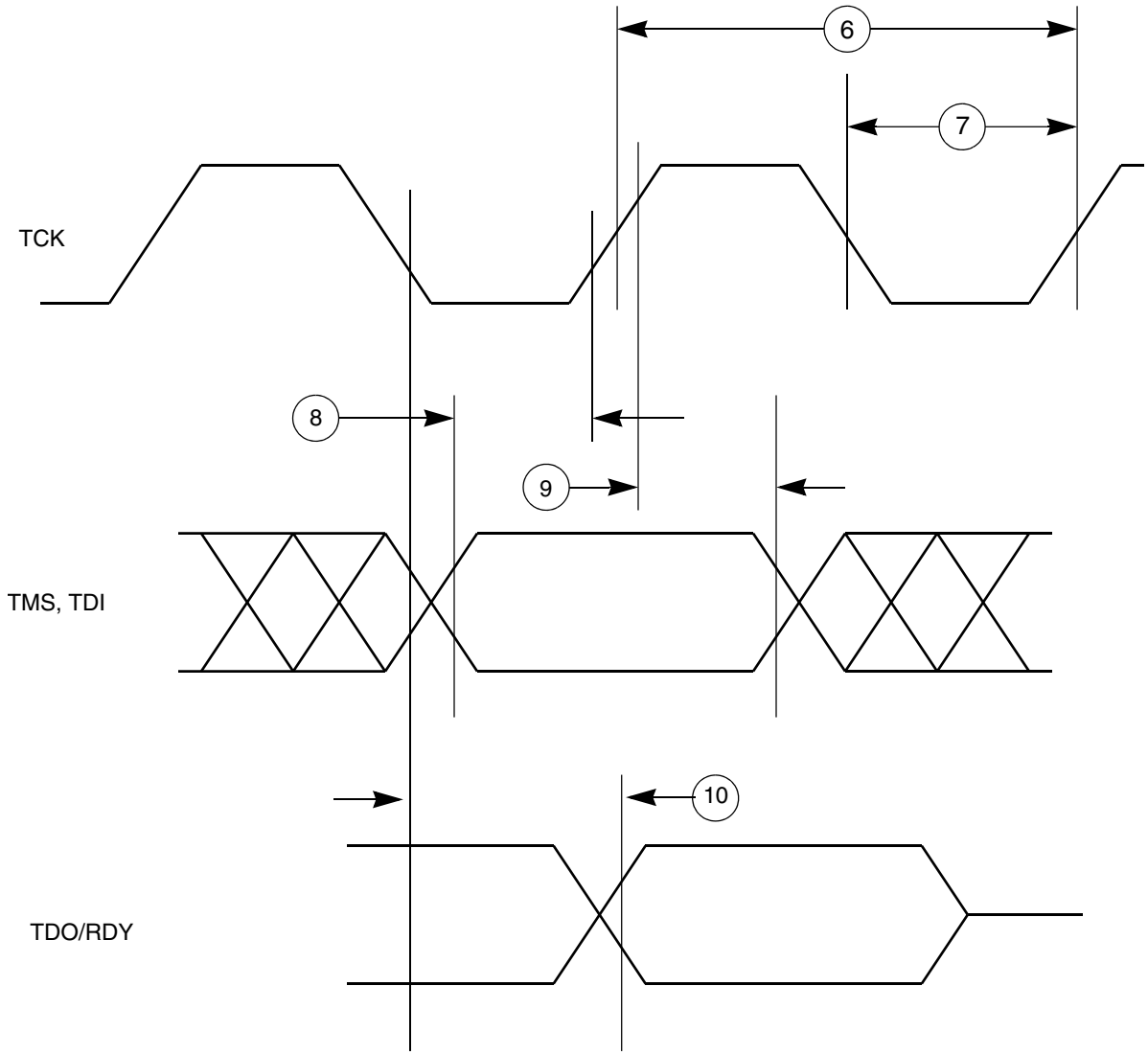


Figure 30. Nexus TDI, TMS, TDO timing

6.5.3 WKPU/NMI timing

Table 47. WKPU/NMI glitch filter

No.	Symbol	Parameter	Min	Typ	Max	Unit
1	W_{FNMI}	NMI pulse width that is rejected	—	—	20	ns
2	$W_{NFNMI}D$	NMI pulse width that is passed	400	—	—	ns

Thermal attributes

Board type	Symbol	Description	256 MAPBGA	Unit	Notes
—	$R_{\theta JC}$	Thermal resistance, junction to case	7.9	°C/W	55
—	Ψ_{JT}	Thermal characterization parameter, junction to package top outside center (natural convection)	0.2	°C/W	66
—	$R_{\theta JB\_CSB}$	Thermal characterization parameter, junction to package bottom outside center (natural convection)	9.0	°C/W	77

1. Junction temperature is a function of die size, on-chip power dissipation, package thermal resistance, mounting site (board) temperature, ambient temperature, air flow, power dissipation of other components on the board, and board thermal resistance.
2. Per SEMI G38-87 and JEDEC JESD51-2 with the single layer board horizontal.
3. Per JEDEC JESD51-6 with the board horizontal
4. Thermal resistance between the die and the printed circuit board per JEDEC JESD51-8. Board temperature is measured on the top surface of the board near the package.
5. Thermal resistance between the die and the case top surface as measured by the cold plate method (MIL SPEC-883 Method 1012.1).
6. Thermal characterization parameter indicating the temperature difference between package top and the junction temperature per JEDEC JESD51-2. When Greek letters are not available, the thermal characterization parameter is written as Psi-JT.
7. Thermal characterization parameter indicating the temperature difference between package bottom center and the junction temperature per JEDEC JESD51-12. When Greek letters are not available, the thermal characterization parameter is written as Psi-JB.

Board type	Symbol	Description	100 MAPBGA	Unit	Notes
Single-layer (1s)	$R_{\theta JA}$	Thermal resistance, junction to ambient (natural convection)	50.9	°C/W	1, 21,2
Four-layer (2s2p)	$R_{\theta JA}$	Thermal resistance, junction to ambient (natural convection)	27.0	°C/W	1,2,33
Single-layer (1s)	$R_{\theta JMA}$	Thermal resistance, junction to ambient (200 ft./ min. air speed)	38.0	°C/W	1,3
Four-layer (2s2p)	$R_{\theta JMA}$	Thermal resistance, junction to ambient (200 ft./ min. air speed)	22.2	°C/W	1,3

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Table 51. Revision History (continued)

Rev. No.	Date	Substantial Changes

		• In section: Voltage monitor electrical characteristics
		  • Updated description for Low Voltage detector block.
		  • Added note, BCP56, MCP68 and MJD31 are guaranteed ballasts.
		  • In table: Voltage regulator electrical specifications
		  • Added footnote, Ceramic X7R or X5R type with capacitance-temperature characteristics +/-15% of -55 degC to +125degC is recommended. The tolerance +/-20% is acceptable.
		  • Revised table, Voltage monitor electrical characteristics

		• In section: Supply current characteristics
		  • In table: Current consumption characteristics
		  • $I_{DD\_BODY\_4}$: Updated SYS_CLK to 120 MHz.
		  • $I_{DD\_BODY\_4}$: Updated Max for T_a= 105 °C fand 85 °C)
		  • I_{dd_STOP}: Added condition for T_a= 105 °C and removed Max value for T_a= 85 °C.
		  • $I_{DD\_HV\_ADC\_REF}$: Added condition for T_a= 105 °C and 85 °C and removed Max value for T_a= 25 °C.
		  • $I_{DD\_HV\_FLASH}$: Added condition for T_a= 105 °C and 85 °C
		  • In table: Low Power Unit (LPU) Current consumption characteristics
		  • LPU_RUN and LPU_STOP: Added condition for T_a= 105 °C and 85 °C
		  • In table: STANDBY Current consumption characteristics
		  • Added condition for T_a= 105 °C and 85 °C for all entries.
		
		• In section: I/O parameters
		  • In table: Functional Pad AC Specifications @ 3.3 V Range
		  • Updated values for 'pad_sr_hv (output)'
		  • In table: DC electrical specifications @ 3.3V Range
		  • Updateded Min and Max values for Vih and Vil respectively.
		  • In table: Functional Pad AC Specifications @ 5 V Range
		  • Updated values for 'pad_sr_hv (output)'
		  • In table DC electrical specifications @ 5 V Range
		  • Updated Min value for Vhys

Table continues on the next page...

Table 51. Revision History (continued)

Rev. No.	Date	Substantial Changes

		• In section: Reset pad electrical characteristics
		  • Revised table, Reset electrical characteristics
		  • Deleted note, There are some specific ports that supports TTL functionality. These ports are, PB[4], PB[5], PB[6], PB[7], PB[8], PB[9], PD[0], PD[1], PD[2], PD[3], PD[4], PD[5], PD[6], PD[7], PD[8], PD[9], PD[10], and PD[11].
		• In section: PORST electrical specifications
		  • In table: PORST electrical specifications
		  • Updated 'Min' value for $W_{NFPORST}$
		• In section: Peripheral operating requirements and behaviours
		  • Changed section title from Input impedance and ADC accuracy to Input equivalent circuit and ADC conversion characteristics.
		  • Revised table: ADC conversion characteristics (for 12-bit) and ADC conversion characteristics (for 10-bit)
		  • Removed table, ADC supply configurations.
		• In section: Analogue Comparator (CMP) electrical specifications
		  • In table: Comparator and 6-bit DAC electrical specifications
		  • Updated 'Max' value of I_{DDLS}
		  • Updated 'Min' and 'Max' for V_{AIO} and DNL
		  • Updated 'Descripton' 'Min' 'Max' od V_H
		  • Updated row for t_{DHS}
		  • Added row for t_{DLS}
		  • Removed row for V_{CMPOh} and V_{CMPOl}
		• In section: Clocks and PLL interfaces modules
		  • In table: Main oscillator electrical characteristics
		  • V_{XOSCHS}: Removed values for 4 MHz.
		  • $T_{XOSCHSSU}$: Updated range to 8-40 MHz.
		  • In table: 16 MHz RC Oscillator electrical specifications
		  • Updated 'Max' for $T_{startup}$ and T_{LTJIT}
		  • Removed $F_{Untrimmed}$ row
		  • In table: 128 KHz Internal RC oscillator electrical specifications
		  • Fosc: Removed Uncaliberated 'Condition' and updated 'Min', 'Typ', and 'Max' for Caliberated condition
		  • Fosc: Updated 'Temperature dependence' and 'Supply dependence' Max values
		  • In table: PLL electrical specifications
		  • Removed entries for Input Clock Low Level, Input Clock High Level, Power consumption, Regulator Maximum Output Current, Analog Supply, Digital Supply (V_{DD_LV}), Modulation Depth (Down Spread), PLL reset assertion time, and Power Consumption
		  • Removed 'Typ' value for Duty Cycle at pllclkout
		  • Removed 'Min' value for Lock Time in calibration mode.
		  • In table: Jitter calculation
		  • Added 1 Sigma Random Jitter and Total Period Jitter values for Long Term Jitter (Interger and Fractional Mode) rows.

		• In section Flash read wait state and address pipeline control settings • In Flash Read Wait State and Address Pipeline Control: Updated APC for 40 MHz. • Removed section: On-chip peripherals

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