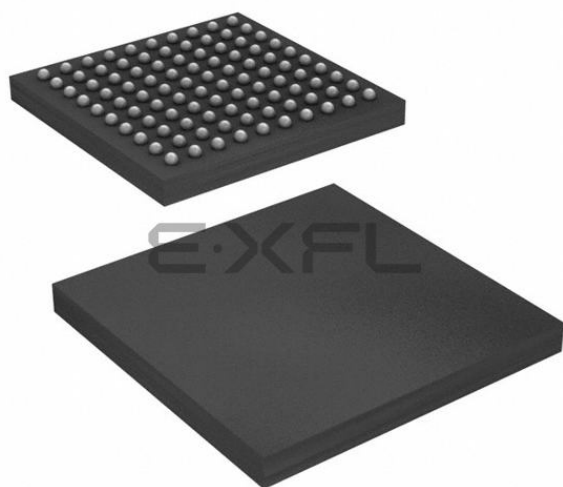




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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	e200z4
Core Size	32-Bit Single-Core
Speed	120MHz
Connectivity	CANbus, Ethernet, FlexRay, I ² C, LINbus, SPI
Peripherals	DMA, I ² S, POR, WDT
Number of I/O	-
Program Memory Size	2MB (2M x 8)
Program Memory Type	FLASH
EEPROM Size	64K x 8
RAM Size	256K x 8
Voltage - Supply (Vcc/Vdd)	3.15V ~ 5.5V
Data Converters	A/D 36x10b, 16x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LFBGA
Supplier Device Package	100-MAPBGA (11x11)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/spc5745bk1vmh2r

- Debug functionality
 - e200z2 core: NDI per IEEE-ISTO 5001-2008 Class3+
 - e200z4 core: NDI per IEEE-ISTO 5001-2008 Class 3+
- Timer
 - 16 Periodic Interrupt Timers (PITs)
 - Two System Timer Modules (STM)
 - Three Software Watchdog Timers (SWT)
 - 64 Configurable Enhanced Modular Input Output Subsystem (eMIOS) channels
- Device/board boundary Scan testing supported with Joint Test Action Group (JTAG) of IEEE 1149.1 and IEEE 1149.7 (CJTAG)
- Security
 - Hardware Security Module (HSMv2)
 - Password and Device Security (PASS) supporting advanced censorship and life-cycle management
 - One Fault Collection and Control Unit (FCCU) to collect faults and issue interrupts
- Functional Safety
 - ISO26262 ASIL-B compliance
- Multiple operating modes
 - Includes enhanced low power operation

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NOTE

All optional features (Flash memory, RAM, Peripherals) start with lowest number or address (e.g., FlexCAN0) and end at highest available number or address (e.g., MPC574xB/C have 6 CAN, ending with FlexCAN5).

Table 1. MPC5746C Family Comparison¹

Feature	MPC5745B	MPC5744B	MPC5746B	MPC5744C	MPC5745C	MPC5746C
CPU	e200z4	e200z4	e200z4	e200z4 e200z2	e200z4 e200z2	e200z4 e200z2
FPU	e200z4	e200z4	e200z4	e200z4	e200z4	e200z4
Maximum Operating Frequency ²	160MHz (Z4)	160MHz (Z4)	160MHz (Z4)	160MHz (Z4) 80MHz (Z2)	160MHz (Z4) 80MHz (Z2)	160MHz (Z4) 80MHz (Z2)
Flash memory	2 MB	1.5 MB	3 MB	1.5 MB	2 MB	3 MB
EEPROM support	Emulated up to 64K			Emulated up to 64K		
RAM	256 KB	192 KB	384 KB (Optional 512KB) ^{3, 3}	192 KB	256 KB	384 KB (Optional 512KB) ³
ECC	End to End					
SMPU	16 entry					
DMA	32 channels					
10-bit ADC	36 Standard channels 32 External channels					
12-bit ADC	15 Precision channels 16 Standard channels					
Analog Comparator	3					
BCTU	1					
SWT	1, SWT[0] ⁴			2 ⁴		
STM	1, STM[0]			2		
PIT-RTI	16 channels PIT 1 channels RTI					
RTC/API	1					
Total Timer I/O ⁵	64 channels 16-bits					
LINFlexD	1 Master and Slave (LINFlexD[0], 11 Master (LINFlexD[1:11]))			1 Master and Slave (LINFlexD[0], 15 Master (LINFlexD[1:15]))		
FlexCAN	6 with optional CAN FD support (FlexCAN[0:5])			8 with optional CAN FD support (FlexCAN[0:7])		
DSPI/SPI	4 x DSPI 4 x SPI					

Table continues on the next page...

Table 6. Recommended operating conditions ($V_{DD_HV_x} = 3.3\text{ V}$) (continued)

Symbol	Parameter	Conditions ¹	Min ²	Max	Unit
T_A ⁸	Ambient temperature under bias	$f_{CPU} \leq 160\text{ MHz}$	-40	125	°C
T_J	Junction temperature under bias	—	-40	150	°C

1. All voltages are referred to V_{SS_HV} unless otherwise specified
2. Device will be functional down (and electrical specifications as per various datasheet parameters will be guaranteed) to the point where one of the LVD/HVD resets the device. When voltage drops outside range for an LVD/HVD, device is reset.
3. $V_{DD_HV_FLA}$ must be connected to $V_{DD_HV_A}$ when $V_{DD_HV_A} = 3.3\text{ V}$
4. Only applicable when supplying from external source.
5. V_{DD_LV} supply pins should never be grounded (through a small impedance). If these are not driven, they should only be left floating.
6. $V_{IN1_CMP_REF} \leq V_{DD_HV_A}$
7. This supply is shorted $V_{DD_HV_A}$ on lower packages.
8. $T_J = 150^\circ\text{C}$. Assumes $T_A = 125^\circ\text{C}$
 - Assumes maximum θ_{JA} of 2s2p board. See [Thermal attributes](#)

NOTE

If $V_{DD_HV_A}$ is in 5V range, it is necessary to use internal Flash supply 3.3V regulator. $V_{DD_HV_FLA}$ should not be supplied externally and should only have decoupling capacitor.

Table 7. Recommended operating conditions ($V_{DD_HV_x} = 5\text{ V}$)

Symbol	Parameter	Conditions ¹	Min ²	Max	Unit
$V_{DD_HV_A}$ $V_{DD_HV_B}$ $V_{DD_HV_C}$	HV IO supply voltage	—	4.5	5.5	V
$V_{DD_HV_FLA}$ ³	HV flash supply voltage	—	3.15	3.6	V
$V_{DD_HV_ADC1_REF}$	HV ADC1 high reference voltage	—	3.15	5.5	V
$V_{DD_HV_ADC0}$ $V_{DD_HV_ADC1}$	HV ADC supply voltage	—	$\max(V_{DD_H_V_A}, V_{DD_H_V_B}, V_{DD_H_V_C}) - 0.05$	5.5	V
$V_{SS_HV_ADC0}$ $V_{SS_HV_ADC1}$	HV ADC supply ground	—	-0.1	0.1	V
V_{DD_LV} ⁴	Core supply voltage	—	1.2	1.32	V
$V_{IN1_CMP_REF}$ ^{5, 6}	Analog Comparator DAC reference voltage	—	3.15	5.5 ⁵	V
I_{INJPAD}	Injected input current on any pin during overload condition	—	-3.0	3.0	mA
T_A ⁷	Ambient temperature under bias	$f_{CPU} \leq 160\text{ MHz}$	-40	125	°C
T_J	Junction temperature under bias	—	-40	150	°C

1. All voltages are referred to V_{SS_HV} unless otherwise specified
2. Device will be functional down (and electrical specifications as per various datasheet parameters will be guaranteed) to the point where one of the LVD/HVD resets the device. When voltage drops outside range for an LVD/HVD, device is reset.
3. When V_{DD_HV} is in 5 V range, $V_{DD_HV_FLA}$ cannot be supplied externally. This pin is decoupled with C_{flash_reg} .

4. VDD_LV supply pins should never be grounded (through a small impedance). If these are not driven, they should only be left floating
5. $V_{IN1_CMP_REF} \leq V_{DD_HV_A}$
6. This supply is shorted VDD_HV_A on lower packages.
7. $T_J=150^{\circ}\text{C}$. Assumes $T_A=125^{\circ}\text{C}$
 - Assumes maximum θ_{JA} of 2s2p board. See [Thermal attributes](#)

4.3 Voltage regulator electrical characteristics

The voltage regulator is composed of the following blocks:

- Choice of generating supply voltage for the core area.
 - Control of external NPN ballast transistor
 - Generating core supply using internal ballast transistor
 - Connecting an external 1.25 V (nominal) supply directly without the NPN ballast
- Internal generation of the 3.3 V flash supply when device connected in 5V applications
- External bypass of the 3.3 V flash regulator when device connected in 3.3V applications
- Low voltage detector - low threshold (LVD_IO_A_LO) for $V_{DD_HV_IO_A}$ supply
- Low voltage detector - high threshold (LVD_IO_A_Hi) for $V_{DD_HV_IO_A}$ supply
- Low voltage detector (LVD_FLASH) for 3.3 V flash supply ($V_{DD_HV_FLA}$)
- Various low voltage detectors (LVD_LV_x)
- High voltage detector (HVD_LV_cold) for 1.2 V digital core supply (V_{DD_LV})
- Power on Reset (POR_LV) for 1.25 V digital core supply (V_{DD_LV})
- Power on Reset (POR_HV) for 3.3 V to 5 V supply ($V_{DD_HV_A}$)

The following bipolar transistors¹ are supported, depending on the device performance requirements. As a minimum the following must be considered when determining the most appropriate solution to maintain the device under its maximum power dissipation capability: current, ambient temperature, mounting pad area, duty cycle and frequency for I_{dd} , collector voltage, etc

1. BCP56, MCP68 and MJD31 are guaranteed ballasts.

Table 8. Voltage regulator electrical specifications (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$C_{\text{flash_reg}}$ ⁴	External decoupling / stability capacitor for internal Flash regulators	Min, max values shall be granted with respect to tolerance, voltage, temperature, and aging variations.	1.32	2.2	3	μF
	Combined ESR of external capacitor	—	0.001	—	0.03	Ohm
$C_{\text{HV_VDD_A}}$	VDD_HV_A supply capacitor ^{5, 5}	Min, max values shall be granted with respect to tolerance, voltage, temperature, and aging variations.	1	—	—	μF
$C_{\text{HV_VDD_B}}$	VDD_HV_B supply capacitor ⁵	Min, max values shall be granted with respect to tolerance, voltage, temperature, and aging variations.	1	—	—	μF
$C_{\text{HV_VDD_C}}$	VDD_HV_C supply capacitor ⁵	Min, max values shall be granted with respect to tolerance, voltage, temperature, and aging variations.	1	—	—	μF
$C_{\text{HV_ADC0}}$ $C_{\text{HV_ADC1}}$	HV ADC supply decoupling capacitances	Min, max values shall be granted with respect to tolerance, voltage, temperature, and aging variations.	1	—	—	μF
$C_{\text{HV_ADR}}$ ⁶	HV ADC SAR reference supply decoupling capacitances	Min, max values shall be granted with respect to tolerance, voltage, temperature, and aging variations.	0.47	—	—	μF
$V_{\text{DD_HV_BALLAST}}^{\text{AST}}$ ⁷	FPREG Ballast collector supply voltage	When collector of NPN ballast is directly supplied by an on board supply source (not shared with VDD_HV_A supply pin) without any series resistance, that is, $R_{\text{C_BALLAST}}$ less than 0.01 Ohm.	2.25	—	5.5	V
$R_{\text{C_BALLAST}}$	Series resistor on collector of FPREG ballast	When VDD_HV_BALLAST is shorted to VDD_HV_A on the board	—	—	0.1	Ohm
t_{SU}	Start-up time with external ballast after main supply (VDD_HV_A) stabilization	$C_{\text{fp_reg}} = 3 \mu\text{F}$	—	74	—	μs
$t_{\text{SU_int}}$	Start-up time with internal ballast after main supply (VDD_HV_A) stabilization	$C_{\text{fp_reg}} = 3 \mu\text{F}$	—	103	—	μs
t_{ramp}	Load current transient	Iload from 15% to 55% $C_{\text{fp_reg}} = 3 \mu\text{F}$		1.0		μs

1. Split capacitance on each pair VDD_LV pin should sum up to a total value of $C_{\text{fp_reg}}$
2. Typical values will vary over temperature, voltage, tolerance, drift, but total variation must not exceed minimum and maximum values.
3. Ceramic X7R or X5R type with capacitance-temperature characteristics +/-15% of -55 degC to +125degC is recommended. The tolerance +/-20% is acceptable.
4. It is required to minimize the board parasitic inductance from decoupling capacitor to VDD_HV_FL A pin and the routing inductance should be less than 1nH.

8. e200Z4 core, 160MHz, cache enabled; e200Z4 core, 80MHz; HSM fully operational (Z0 core @80MHz) FlexRay, 5x CAN, 5x LINFlexD, 2x SPI, 1x ADC used constantly, 1x eMIOS (5 ch), Memory: 3M flash, 384K RAM, Clocks: FIRC on, XOSC on, PLL on, SIRC on, no 32KHz crystal
9. Assuming $T_a = T_j$, as the device is in Stop mode. Assumes maximum θ_{JA} of 2s2p board. See [Thermal attributes](#).
10. Internal structures hold the input voltage less than $V_{DD_HV_ADC_REF} + 1.0$ V on all pads powered by V_{DDA} supplies, if the maximum injection current specification is met (3 mA for all pins) and V_{DDA} is within the operating voltage specifications.
11. This value is the total current for two ADCs. Each ADC might consume upto 2mA at max.
12. This assumes the default configuration of flash controller register. For more details, refer to [Flash memory program and erase specifications](#)

Table 11. Low Power Unit (LPU) Current consumption characteristics

Symbol	Parameter	Conditions ¹	Min	Typ	Max	Unit
LPU_RUN	with 256K RAM	$T_a = 25\text{ }^{\circ}\text{C}$ SYS_CLK = 16MHz ADC0 = OFF, SPI0 = OFF, LIN0 = OFF, CAN0 = OFF	—	10	—	mA
		$T_a = 85\text{ }^{\circ}\text{C}$ SYS_CLK = 16MHz ADC0 = ON, SPI0 = ON, LIN0 = ON, CAN0 = ON	—	10.5	—	
		$T_a = 105\text{ }^{\circ}\text{C}$ SYS_CLK = 16MHz ADC0 = ON, SPI0 = ON, LIN0 = ON, CAN0 = ON	—	11	—	
		$T_a = 125\text{ }^{\circ}\text{C}$ ^{2, 2} SYS_CLK = 16MHz ADC0 = ON, SPI0 = ON, LIN0 = ON, CAN0 = ON	—	—	26	
LPU_STOP	with 256K RAM	$T_a = 25\text{ }^{\circ}\text{C}$	—	0.18	—	mA
		$T_a = 85\text{ }^{\circ}\text{C}$	—	0.60	—	
		$T_a = 105\text{ }^{\circ}\text{C}$	—	1.00	—	
		$T_a = 125\text{ }^{\circ}\text{C}$ ²	—	—	10.6	

1. The content of the Conditions column identifies the components that draw the specific current.
2. Assuming $T_a = T_j$, as the device is in static (fully clock gated) mode. Assumes maximum θ_{JA} of 2s2p board. See [Thermal attributes](#)

Table 12. STANDBY Current consumption characteristics

Symbol	Parameter	Conditions ¹	Min	Typ	Max	Unit
STANDBY0	STANDBY with 8K RAM	$T_a = 25\text{ }^{\circ}\text{C}$	—	71	—	μA
		$T_a = 85\text{ }^{\circ}\text{C}$	—	125	700	
		$T_a = 105\text{ }^{\circ}\text{C}$	—	195	1225	
		$T_a = 125\text{ }^{\circ}\text{C}$ ^{2, 2}	—	314	2100	
STANDBY1	STANDBY with 64K RAM	$T_a = 25\text{ }^{\circ}\text{C}$	—	72	—	μA
		$T_a = 85\text{ }^{\circ}\text{C}$	—	140	715	
		$T_a = 105\text{ }^{\circ}\text{C}$	—	225	1275	
		$T_a = 125\text{ }^{\circ}\text{C}$ ²	—	358	2250	

Table continues on the next page...

Table 12. STANDBY Current consumption characteristics (continued)

Symbol	Parameter	Conditions ¹	Min	Typ	Max	Unit
STANDBY2	STANDBY with 128K RAM	T _a = 25 °C	—	75	—	μA
		T _a = 85 °C	—	155	730	
		T _a = 105 °C	—	255	1350	
		T _a = 125 °C ²	—	396	2600	
STANDBY3	STANDBY with 256K RAM	T _a = 25 °C	—	80	—	μA
		T _a = 85 °C	—	180	800	
		T _a = 105 °C	—	290	1425	
		T _a = 125 °C ²	—	465	2900	
STANDBY3	FIRC ON	T _a = 25 °C	—	500	—	μA

1. The content of the Conditions column identifies the components that draw the specific current.
2. Assuming T_a=T_j, as the device is in static (fully clock gated) mode. Assumes maximum θ_{JA} of 2s2p board. See [Thermal attributes](#)

4.6 Electrostatic discharge (ESD) characteristics

Electrostatic discharges (a positive then a negative pulse separated by 1 second) are applied to the pins of each sample according to each pin combination. The sample size depends on the number of supply pins in the device (3 parts × (n + 1) supply pin). This test conforms to the AEC-Q100-002/-003/-011 standard.

NOTE

A device will be defined as a failure if after exposure to ESD pulses the device no longer meets the device specification requirements. Complete DC parametric and functional testing shall be performed per applicable device specification at room temperature followed by hot temperature, unless specified otherwise in the device specification.

Table 13. ESD ratings

Symbol	Parameter	Conditions ¹	Class	Max value ²	Unit
V _{ESD(HBM)}	Electrostatic discharge (Human Body Model)	T _A = 25 °C conforming to AEC-Q100-002	H1C	2000	V
V _{ESD(CDM)}	Electrostatic discharge (Charged Device Model)	T _A = 25 °C conforming to AEC-Q100-011	C3A	500 750 (corners)	V

1. All ESD testing is in conformity with CDF-AEC-Q100 Stress Test Qualification for Automotive Grade Integrated Circuits.
2. Data based on characterization results, not tested in production.

4.7 Electromagnetic Compatibility (EMC) specifications

EMC measurements to IC-level IEC standards are available from NXP on request.

5 I/O parameters

5.1 AC specifications @ 3.3 V Range

Table 14. Functional Pad AC Specifications @ 3.3 V Range

Symbol	Prop. Delay (ns) ¹ L>H/H>L		Rise/Fall Edge (ns)		Drive Load (pF)	SIUL2_MSCRn[Src 1:0]
	Min	Max	Min	Max		MSB,LSB
pad_sr_hv (output)		6/6		1.9/1.5	25	11
	2.5/2.5	8.25/7.5	0.8/0.6	3.25/3	50	
	6.4/5	19.5/19.5	3.5/2.5	12/12	200	
	2.2/2.5	8/8	0.55/0.5	3.9/3.5	25	10
	0.090	1.1	0.035	1.1	asymmetry ²	
	2.9/3.5	12.5/11	1/1	7/6	50	
	11/8	35/31	7.7/5	25/21	200	
	8.3/9.6	45/45	4/3.5	25/25	50	01 ³
	13.5/15	65/65	6.3/6.2	30/30	200	
	13/13	75/75	6.8/6	40/40	50	00 ³
	21/22	100/100	11/11	51/51	200	
pad_i_hv/ pad_sr_hv (input) ⁴		2/2		0.5/0.5	0.5	NA

1. As measured from 50% of core side input to Voh/Vol of the output

2. This row specifies the min and max asymmetry between both the prop delay and the edge rates for a given PVT and 25pF load. Required for the Flexray spec.

3. Slew rate control modes

4. Input slope = 2ns

NOTE

The specification given above is based on simulation data into an ideal lumped capacitor. Customer should use IBIS models for their specific board/loading conditions to simulate the expected signal integrity and edge rates of their system.

NOTE

The specification given above is measured between 20% / 80%.

5.3 AC specifications @ 5 V Range

Table 16. Functional Pad AC Specifications @ 5 V Range

Symbol	Prop. Delay (ns) ¹ L>H/H>L		Rise/Fall Edge (ns)		Drive Load (pF)	SIUL2_MSCrN[Src 1:0]
	Min	Max	Min	Max		MSB,LSB
pad_sr_hv (output)		4.5/4.5		1.3/1.2	25	11
		6/6		2.5/2	50	
		13/13		9/9	200	
		5.25/5.25		3/2	25	
		9/8		5/4	50	10
		22/22		18/16	200	
		27/27		13/13	50	
		40/40		24/24	200	
		40/40		24/24	50	00 ²
		65/65		40/40	200	
pad_i_hv/ pad_sr_hv (input)		1.5/1.5		0.5/0.5	0.5	NA

1. As measured from 50% of core side input to Voh/Vol of the output

2. Slew rate control modes

NOTE

The above specification is based on simulation data into an ideal lumped capacitor. Customer should use IBIS models for their specific board/loading conditions to simulate the expected signal integrity and edge rates of their system.

NOTE

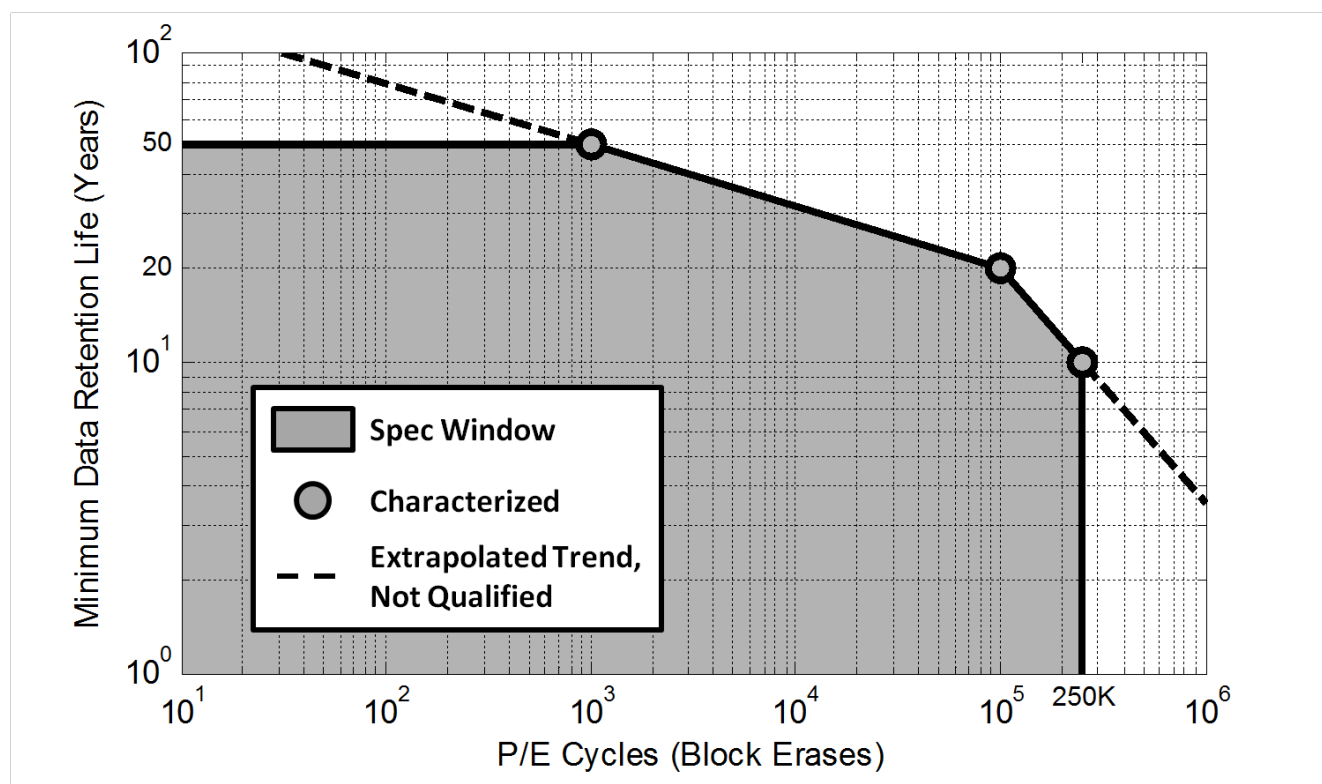
The above specification is measured between 20% / 80%.

5.4 DC electrical specifications @ 5 V Range

Table 17. DC electrical specifications @ 5 V Range

Symbol	Parameter	Value		Unit
		Min	Max	
Vih (pad_i_hv)	pad_i_hv Input Buffer High Voltage	0.7*VDD_HV_x	VDD_HV_x + 0.3	V

Table continues on the next page...



6.3.5 Flash memory AC timing specifications

Table 33. Flash memory AC timing specifications

Symbol	Characteristic	Min	Typical	Max	Units
t_{psus}	Time from setting the MCR-PSUS bit until MCR-DONE bit is set to a 1.	—	9.4 plus four system clock periods	11.5 plus four system clock periods	μs
t_{esus}	Time from setting the MCR-ESUS bit until MCR-DONE bit is set to a 1.	—	16 plus four system clock periods	20.8 plus four system clock periods	μs
t_{res}	Time from clearing the MCR-ESUS or PSUS bit with EHV = 1 until DONE goes low.	—	—	100	ns
t_{done}	Time from 0 to 1 transition on the MCR-EHV bit initiating a program/erase until the MCR-DONE bit is cleared.	—	—	5	ns
t_{dones}	Time from 1 to 0 transition on the MCR-EHV bit aborting a program/erase until the MCR-DONE bit is set to a 1.	—	16 plus four system clock periods	20.8 plus four system clock periods	μs

Table continues on the next page...

6.4 Communication interfaces

6.4.1 DSPI timing

Table 35. DSPI electrical specifications

No	Symbol	Parameter	Conditions	High Speed Mode		low Speed mode		Unit
				Min	Max	Min	Max	
1	t_{SCK}	DSPI cycle time	Master (MTFE = 0)	25	—	50	—	ns
			Slave (MTFE = 0)	40	—	60	—	
2	t_{CSC}	PCS to SCK delay	—	16	—	—	—	ns
3	t_{ASC}	After SCK delay	—	16	—	—	—	ns
4	t_{SDC}	SCK duty cycle	—	$t_{SCK}/2 - 10$	$t_{SCK}/2 + 10$	—	—	ns
5	t_A	Slave access time	SS active to SOUT valid	—	40	—	—	ns
6	t_{DIS}	Slave SOUT disable time	SS inactive to SOUT High-Z or invalid	—	10	—	—	ns
7	t_{PCSC}	PCSx to PCSS time	—	13	—	—	—	ns
8	t_{PASC}	PCSS to PCSx time	—	13	—	—	—	ns
9	t_{SUI}	Data setup time for inputs	Master (MTFE = 0)	NA	—	20	—	ns
			Slave	2	—	2	—	
			Master (MTFE = 1, CPHA = 0)	15	—	8 ^{1, 1}	—	
			Master (MTFE = 1, CPHA = 1)	15	—	20	—	
10	t_{HI}	Data hold time for inputs	Master (MTFE = 0)	NA	—	-5	—	ns
			Slave	4	—	4	—	
			Master (MTFE = 1, CPHA = 0)	0	—	11 ¹	—	
			Master (MTFE = 1, CPHA = 1)	0	—	-5	—	
11	t_{SUO}	Data valid (after SCK edge)	Master (MTFE = 0)	—	NA	—	4	ns
			Slave	—	15	—	23	
			Master (MTFE = 1, CPHA = 0)	—	4	—	16 ¹	
			Master (MTFE = 1, CPHA = 1)	—	4	—	4	

Table continues on the next page...

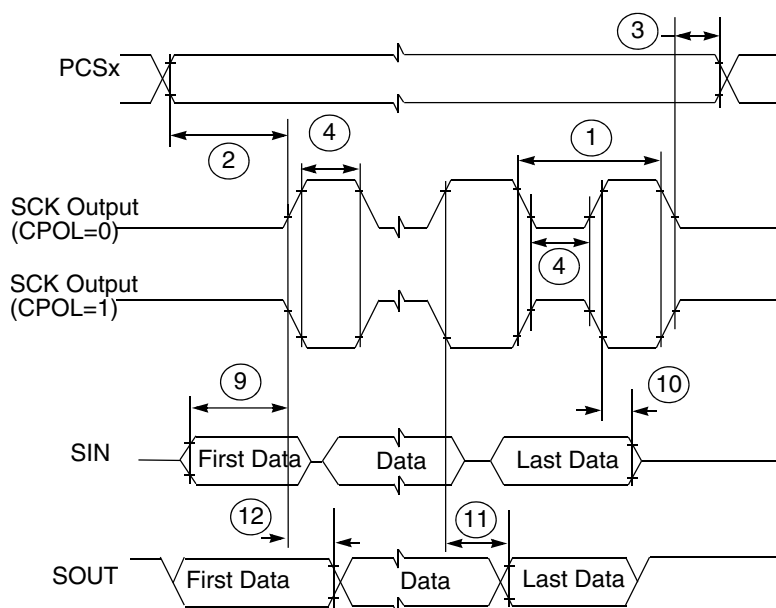


Figure 12. DSPI modified transfer format timing — master, CPHA = 0

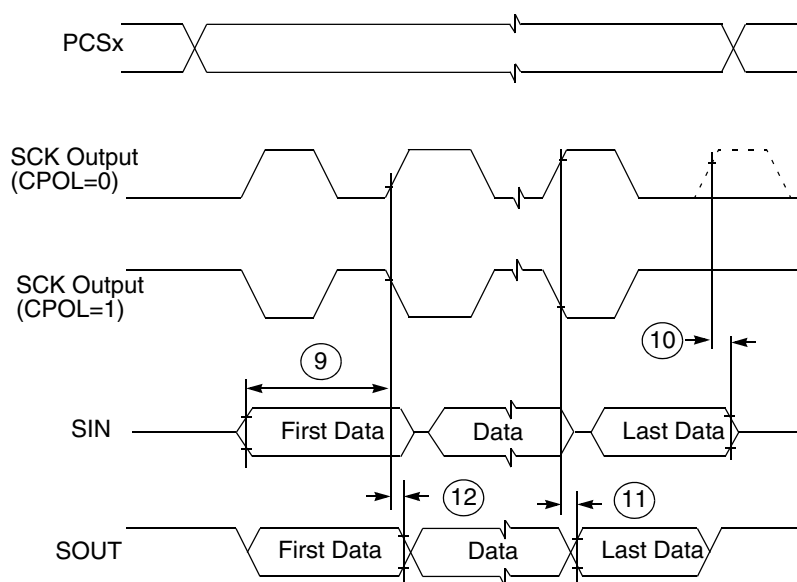
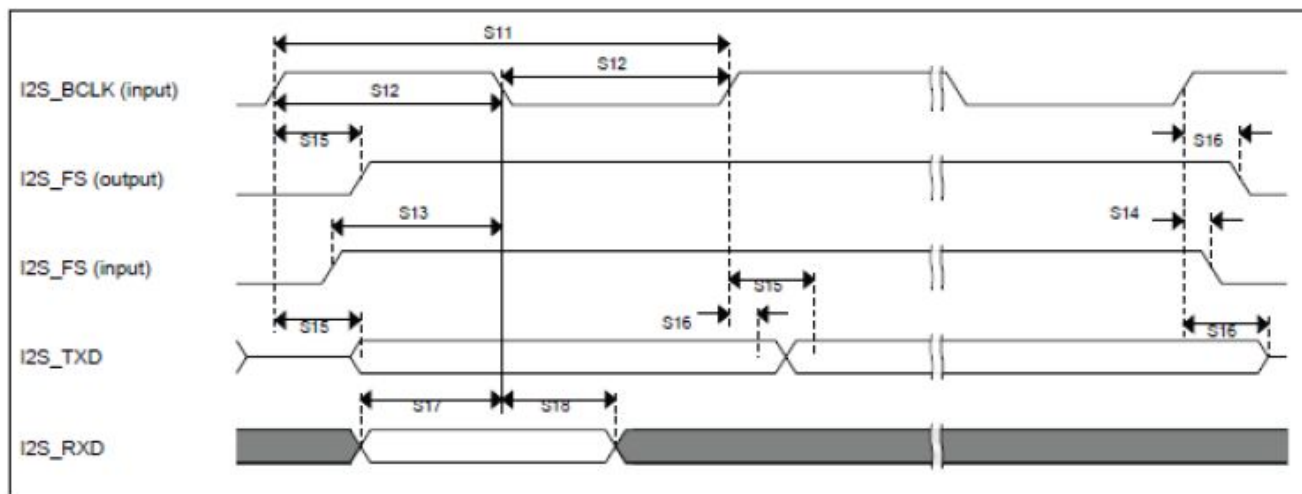


Figure 13. DSPI modified transfer format timing — master, CPHA = 1

Table 44. Slave mode SAI Timing (continued)

No	Parameter	Value		Unit
		Min	Max	
S15	SAI_BCLK to SAI_TXD/SAI_FS output valid	-	28	ns
S16	SAI_BCLK to SAI_TXD/SAI_FS output invalid	0	-	ns
S17	SAI_RXD setup before SAI_BCLK	10	-	ns
S18	SAI_RXD hold after SAI_BCLK	2	-	ns

**Figure 24. Slave mode SAI Timing**

6.5 Debug specifications

6.5.1 JTAG interface timing

Table 45. JTAG pin AC electrical characteristics ¹

#	Symbol	Characteristic	Min	Max	Unit
1	t_{JCYC}	TCK Cycle Time ^{2, 2}	62.5	—	ns
2	t_{JDC}	TCK Clock Pulse Width	40	60	%
3	$t_{TCKRISE}$	TCK Rise and Fall Times (40% - 70%)	—	3	ns
4	t_{TMSS}, t_{TDIS}	TMS, TDI Data Setup Time	5	—	ns
5	t_{TMSH}, t_{TDIH}	TMS, TDI Data Hold Time	5	—	ns
6	t_{TDOV}	TCK Low to TDO Data Valid	—	20 ^{3, 3}	ns
7	t_{TDOI}	TCK Low to TDO Data Invalid	0	—	ns
8	t_{TDOHZ}	TCK Low to TDO High Impedance	—	15	ns
11	t_{BSDV}	TCK Falling Edge to Output Valid	—	600 ^{4, 4}	ns

Table continues on the next page...

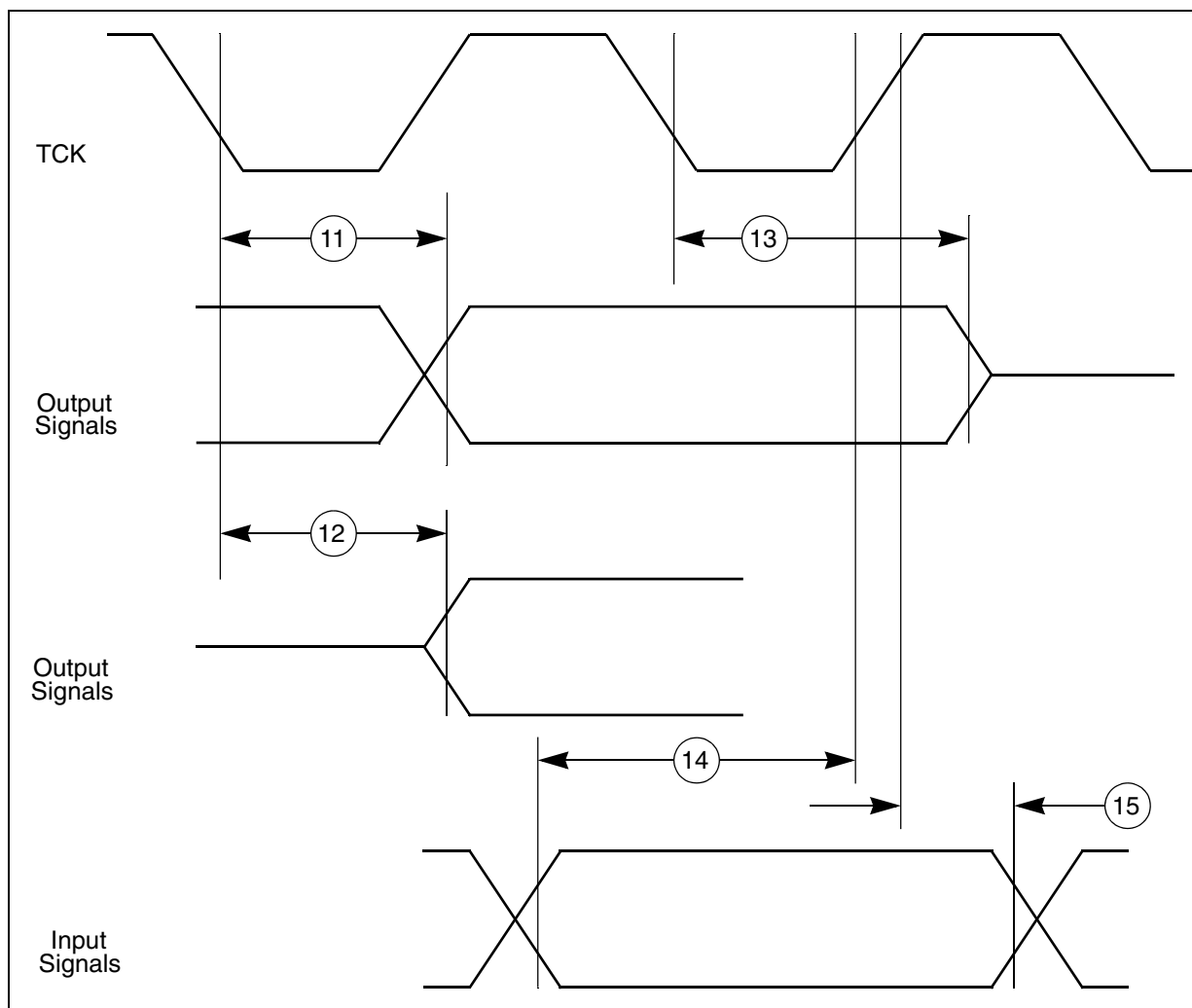


Figure 27. JTAG boundary scan timing

6.5.2 Nexus timing

Table 46. Nexus debug port timing ¹

No.	Symbol	Parameter	Condition s	Min	Max	Unit
1	t_{MCYC}	MCKO Cycle Time	—	15.6	—	ns
2	t_{MDC}	MCKO Duty Cycle	—	40	60	%
3	t_{MDOV}	MCKO Low to MDO, MSEO, EVTO Data Valid ²	—	-0.1	0.25	t_{MCYC}
4	t_{EVTIPW}	EVTI Pulse Width	—	4	—	t_{TCYC}
5	t_{EVTOPW}	EVTO Pulse Width	—	1	—	t_{MCYC}
6	t_{TCYC}	TCK Cycle Time ³	—	62.5	—	ns
7	t_{TDC}	TCK Duty Cycle	—	40	60	%
8	t_{NTDIS} , t_{NTMSS}	TDI, TMS Data Setup Time	—	8	—	ns

Table continues on the next page...

6.5.4 External interrupt timing (IRQ pin)

Table 48. External interrupt timing specifications

No.	Symbol	Parameter	Conditions	Min	Max	Unit
1	t_{IPWL}	IRQ pulse width low	—	3	—	t_{CYC}
2	t_{IPWH}	IRQ pulse width high	—	3	—	t_{CYC}
3	t_{ICYC}	IRQ edge to edge time	—	6	—	t_{CYC}

These values apply when IRQ pins are configured for rising edge or falling edge events, but not both.

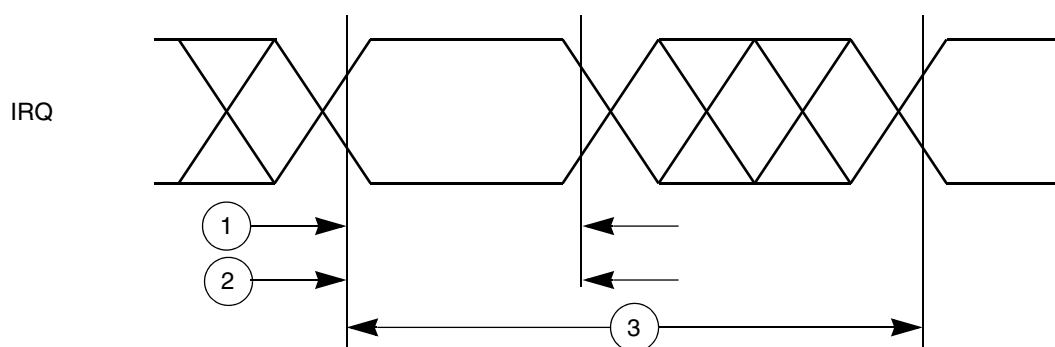


Figure 31. External interrupt timing

7 Thermal attributes

7.1 Thermal attributes

Board type	Symbol	Description	176LQFP	Unit	Notes
Single-layer (1s)	$R_{\theta JA}$	Thermal resistance, junction to ambient (natural convection)	50.7	$^{\circ}\text{C}/\text{W}$	11, 22
Four-layer (2s2p)	$R_{\theta JA}$	Thermal resistance, junction to ambient (natural convection)	24.2	$^{\circ}\text{C}/\text{W}$	1, 2, 33
Single-layer (1s)	$R_{\theta JMA}$	Thermal resistance, junction to ambient (200 ft./min. air speed)	38.1	$^{\circ}\text{C}/\text{W}$	1, 3

Table continues on the next page...

Package	NXP Document Number
176-pin LQFP-EP	98ASA00698D
256 MAPBGA	98ASA00346D
324 MAPBGA	98ASA10582D

9 Pinouts

9.1 Package pinouts and signal descriptions

For package pinouts and signal descriptions, refer to the Reference Manual.

10 Reset sequence

10.1 Reset sequence

This section describes different reset sequences and details the duration for which the device remains in reset condition in each of those conditions.

10.1.1 Reset sequence duration

[Table 49](#) specifies the reset sequence duration for the five different reset sequences described in [Reset sequence description](#).

Table 49. RESET sequences

No.	Symbol	Parameter	T _{Reset}			Unit
			Min	Typ 1, 1	Max	
1	T _{DRB}	Destructive Reset Sequence, BIST enabled	6.2	7.3	-	ms
2	T _{DR}	Destructive Reset Sequence, BIST disabled	110	182	-	us
3	T _{ERLB}	External Reset Sequence Long, Unsecure Boot	6.2	7.3	-	ms
4	T _{FRL}	Functional Reset Sequence Long, Unsecure Boot	110	182	-	us
5	T _{FRS}	Functional Reset Sequence Short, Unsecure Boot	7	9	-	us

1. The Typ value is applicable only if the reset sequence duration is not prolonged by an extended assertion of RESET_B by an external reset generator.

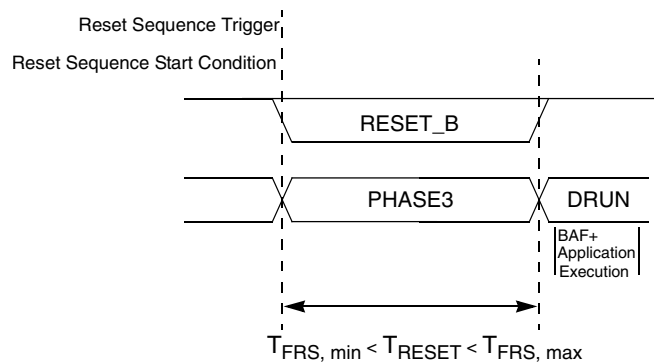


Figure 36. Functional reset sequence short

The reset sequences shown in [Figure 35](#) and [Figure 36](#) are triggered by functional reset events. RESET_B is driven low during these two reset sequences only if the corresponding functional reset source (which triggered the reset sequence) was enabled to drive RESET_B low for the duration of the internal reset sequence. See the RGM_FBRE register in the device reference manual for more information.

11 Revision History

11.1 Revision History

The following table provides a revision history for this document.

Table 51. Revision History

Rev. No.	Date	Substantial Changes
Rev 1	14 March 2013	Initial Release

Table continues on the next page...

Table 51. Revision History (continued)

Rev. No.	Date	Substantial Changes
Rev 3	2 March 2016	- In section, Recommended operating conditions - Added a new Note - In section, Voltage regulator electrical characteristics - In table, Voltage regulator electrical specifications: - Added a new row for $C_{HV_VDD_B}$ - Added a footnote on $V_{DD_HV_BALLAST}$ - Added a new Note at the end of this section - In section, Voltage monitor electrical characteristics - In table, Voltage monitor electrical characteristics: - Removed "V_{LVD_FLASH}" and "V_{LVD_FLASH} during low power mode using LPBG as reference" rows - Updated Fall and Rise trimmed Minimum values for $V_{HVD_LV_cold}$ - In section, Supply current characteristics - In table, Current consumption characteristics: - Updated the footnote mentioned in the Condition column of I_{DD_STOP} row - Updated all TBD values - In table, Low Power Unit (LPU) Current consumption characteristics: - Updated the typical value of LPU_STOP to 0.18 mA - Updated all TBD values - In table, STANDBY Current consumption characteristics: - Updated all TBD values - In section, AC specifications @ 3.3 V Range - In table, Functional Pad AC Specifications @ 3.3 V Range: - Updated Rise/Fall Edge values - In section, DC electrical specifications @ 3.3V Range - In table, DC electrical specifications @ 3.3V Range: - Updated Max value for Vol to $0.1 * V_{DD_HV_x}$ - In section, AC specifications @ 5 V Range - In table, Functional Pad AC Specifications @ 5 V Range: - Updated Rise/Fall Edge values - In section, DC electrical specifications @ 5 V Range - In table, DC electrical specifications @ 5 V Range: - Updated Min and Max values for Pull_Ioh and Pull_Iol rows - Updated Max value for Vol to $0.1 * V_{DD_HV_x}$ - In section, Reset pad electrical characteristics - In table, Functional reset pad electrical specifications: - Updated parameter column for V_{IH}, V_{IL} and V_{HYS} rows - Updated Min and Max values for V_{IH} and V_{IL} rows - In section, PORST electrical specifications - In table, PORST electrical specifications: - Updated Unit and Min/Max values for V_{IH} and V_{IL} rows - In section, Input equivalent circuit and ADC conversion characteristics - In table, ADC conversion characteristics (for 12-bit): - Updated "ADC Analog Pad (pad going to one ADC)" row - In table, ADC conversion characteristics (for 10-bit): - Updated "ADC Analog Pad (pad going to one ADC)" row - In section, Analog Comparator (CMP) electrical specifications - In table, Comparator and 6-bit DAC electrical specifications: - Updated Min and Max values for V_{AIO} to +47 mV - Updated Max Value for t_{PLS} to 21 μs
74		- In section, Main oscillator electrical characteristics - In table, Main oscillator electrical characteristics:

Table 51. Revision History (continued)

Rev. No.	Date	Substantial Changes
Rev 5.1	22 May 2017	- Removed the Introduction section from Section 4 "General". - In AC Specifications@3.3V section, removed note related to Cz results and added two notes. - In AC Specifications@5V section, added two notes. - In ADC Electrical Specifications section, added spec value of "ADC Analog Pad" at Max leakage (standard channel)@ 105 C T_A in "ADC conversion characteristics (for 10-bit)" table. - In PLL Electrical Specifications section, updated the first footnote of "Jitter calculation" table. - In Analog Comparator Electrical Specifications section, updated the TDLS (propagation delay, low power mode) max value in "Comparator and 6-bit DAC electrical specifications" table to 21 us. - In Recommended Operating Conditions section, updated the footnote link to T_A in "Recommended operating conditions (V_{DD_HV_x} = 5V)" table.