



Welcome to [E-XFL.COM](https://www.e-xfl.com)

### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	64MHz
Connectivity	I <sup>2</sup> C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, HLVD, POR, PWM, WDT
Number of I/O	36
Program Memory Size	32KB (16K x 16)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 5.5V
Data Converters	A/D 35x12b; D/A 1x5b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Through Hole
Package / Case	40-DIP (0.600", 15.24mm)
Supplier Device Package	40-PDIP
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic18f45k42-i-p">https://www.e-xfl.com/product-detail/microchip-technology/pic18f45k42-i-p</a>

## 4.5.2 GENERAL PURPOSE REGISTER FILE

General Purpose RAM is available starting Bank 0 of data memory. GPRs are not initialized by a Power-on Reset and are unchanged on all other Resets.

## 4.5.3 SPECIAL FUNCTION REGISTERS

The Special Function Registers (SFRs) are registers used by the CPU and peripheral modules for controlling the desired operation of the device. These registers are implemented as static RAM. SFRs start at the top of data memory (3FFFh) and extend downward to occupy Bank 56 through 63 (3800h to 3FFFh). A list of these registers is given in [Table 4-3](#) to [Table 4-11](#). A bitwise summary of these registers can be found in [Section 42.0 “Register Summary”](#).

## 4.5.4 ACCESS BANK

To streamline access for the most commonly used data memory locations, the data memory is configured with an Access Bank, which allows users to access a mapped block of memory without specifying a BSR. The Access Bank consists of the first 96 bytes of memory (00h-5Fh) in Bank 0 and the last 160 bytes of memory (60h-FFh) in Bank 63. The lower half is known as the “Access RAM” and is composed of GPRs. This upper half is also where some of the SFRs of the device are mapped. These two areas are mapped contiguously in the Access Bank and can be addressed linearly by an 8-bit address ([Figure 4-4](#)).

The Access Bank is used by core PIC18 instructions that include the Access RAM bit (the ‘a’ parameter in the instruction). When ‘a’ is equal to ‘1’, the instruction uses the BSR and the 8-bit address included in the opcode for the data memory address. When ‘a’ is ‘0’, however, the instruction uses the Access Bank address map; the current value of the BSR is ignored.

Using this “forced” addressing allows the instruction to operate on a data address in a single cycle, without updating the BSR first. For 8-bit addresses of 60h and above, this means that users can evaluate and operate on SFRs more efficiently. The Access RAM below 60h is a good place for data values that the user might need to access rapidly, such as immediate computational results or common program variables. Access RAM also allows for faster and more code efficient and switching of variables.

The mapping of the Access Bank is slightly different when the extended instruction set is enabled (XINST Configuration bit = 1). This is discussed in more detail in [Section 4.8.3 “Mapping the Access Bank in Indexed Literal Offset Mode”](#).

# PIC18(L)F26/27/45/46/47/55/56/57K42

## 6.14 Register Definitions: Power Control

### REGISTER 6-2: PCON0: POWER CONTROL REGISTER 0

R/W/HS-0/q	R/W/HS-0/q	R/W/HC-1/q	R/W/HC-1/q	R/W/HC-1/q	R/W/HC-1/q	R/W/HC-0/u	R/W/HC-q/u
STKOVF	STKUNF	WDTWV	RWDT	RMCLR	RI	POR	BOR
bit 7							bit 0

#### Legend:

HC = Bit is cleared by hardware

HS = Bit is set by hardware

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-m/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

q = Value depends on condition

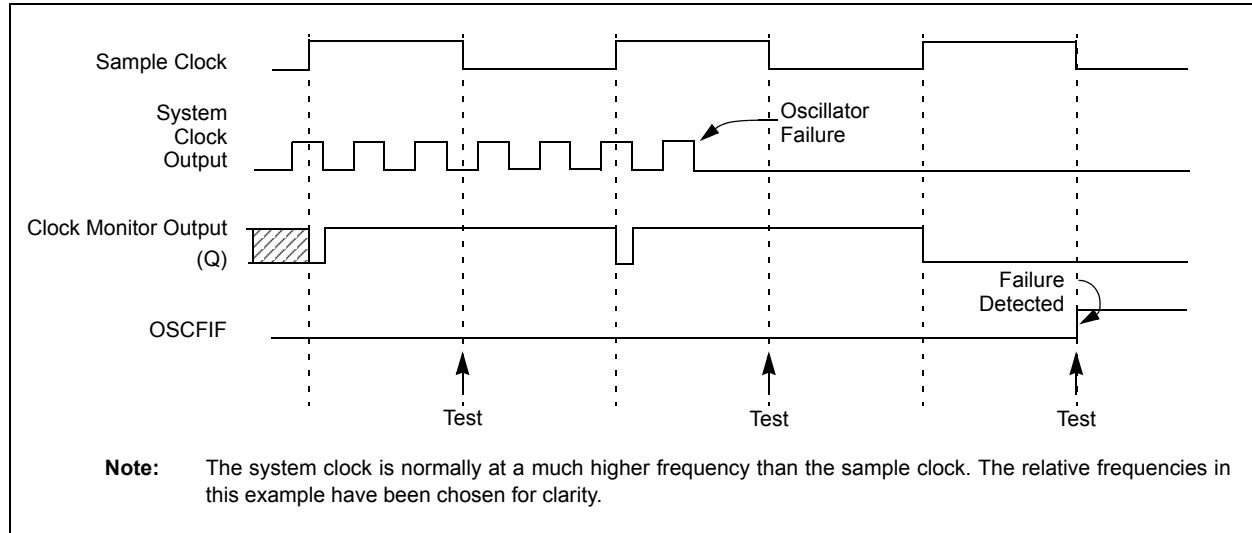
- bit 7 **STKOVF**: Stack Overflow Flag bit  
 1 = A Stack Overflow occurred (more CALLs than fit on the stack)  
 0 = A Stack Overflow has not occurred or set to '0' by firmware
- bit 6 **STKUNF**: Stack Underflow Flag bit  
 1 = A Stack Underflow occurred (more RETURNS than CALLs)  
 0 = A Stack Underflow has not occurred or set to '0' by firmware
- bit 5 **WDTWV**: Watchdog Window Violation bit  
 1 = A WDT window violation has not occurred or set to '1' by firmware  
 0 = A CLRWD instruction was issued when the WDT Reset window was closed (set to '0' in hardware when a WDT window violation Reset occurs)
- bit 4 **RWDT**: WDT Reset Flag bit  
 1 = A WDT overflow/time-out Reset has not occurred or set to '1' by firmware  
 0 = A WDT overflow/time-out Reset has occurred (set to '0' in hardware when a WDT Reset occurs)
- bit 3 **RMCLR**: MCLR Reset Flag bit  
 1 = A MCLR Reset has not occurred or set to '1' by firmware  
 0 = A MCLR Reset has occurred (set to '0' in hardware when a MCLR Reset occurs)
- bit 2 **RI**: RESET Instruction Flag bit  
 1 = A RESET instruction has not been executed or set to '1' by firmware  
 0 = A RESET instruction has been executed (set to '0' in hardware upon executing a RESET instruction)
- bit 1 **POR**: Power-on Reset Status bit  
 1 = No Power-on Reset occurred or set to '1' by firmware  
 0 = A Power-on Reset occurred (set to '0' in hardware when a Power-on Reset occurs)
- bit 0 **BOR**: Brown-out Reset Status bit  
 1 = No Brown-out Reset occurred or set to '1' by firmware  
 0 = A Brown-out Reset occurred (set to '0' in hardware when a Brown-out Reset occurs)

# PIC18(L)F26/27/45/46/47/55/56/57K42

## 7.4.4 RESET OR WAKE-UP FROM SLEEP

The FSCM is designed to detect an oscillator failure after the Oscillator Start-up Timer (OST) has expired. The OST is used after waking up from Sleep and after any type of Reset. The OST is not used with the EC Clock modes so that the FSCM will be active as soon as the Reset or wake-up has completed.

**FIGURE 7-10: FSCM TIMING DIAGRAM**



**TABLE 7-1: NOSC/COSC AND NDIV/CDIV BIT SETTINGS**

NOSC<2:0> COSC<2:0>	Clock Source	NDIV<3:0> CDIV<3:0>	Clock Divider
111	EXTOSC <sup>(1)</sup>	1111-1010	Reserved
110	HFINTOSC <sup>(2)</sup>	1001	512
101	LFINTOSC	1000	256
100	SOSC	0111	128
011	Reserved	0110	64
010	EXTOSC + 4x PLL <sup>(3)</sup>	0101	32
001	Reserved	0100	16
000	Reserved	0011	8
		0010	4
		0001	2
		0000	1

- Note 1:** EXTOSC configured by the FEXTOSC bits of Configuration Word 1 ([Register 5-1](#)).  
**Note 2:** HFINTOSC frequency is set with the FRQ bits of the OSCFRQ register ([Register 7-5](#)).  
**Note 3:** EXTOSC must meet the PLL specifications ([Table 44-11](#)).

# PIC18(L)F26/27/45/46/47/55/56/57K42

## REGISTER 9-3: PIR0: PERIPHERAL INTERRUPT REQUEST REGISTER 0

R-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0
IOCIF <sup>(2)</sup>	CRCIF	SCANIF	NVMIF	CSWIF <sup>(3)</sup>	OSFIF	HLVDIF	SWIF
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

HS = Bit is set in hardware

bit 7 **IOCIF:** Interrupt-on-Change Interrupt Flag bit<sup>(2)</sup>

1 = Interrupt has occurred

0 = Interrupt event has not occurred

bit 6 **CRCIF:** CRC Interrupt Flag bit

1 = Interrupt has occurred (must be cleared by software)

0 = Interrupt event has not occurred

bit 5 **SCANIF:** Memory Scanner Interrupt Flag bit

1 = Interrupt has occurred (must be cleared by software)

0 = Interrupt event has not occurred

bit 4 **NVMIF:** NVM Interrupt Flag bit

1 = Interrupt has occurred (must be cleared by software)

0 = Interrupt event has not occurred

bit 3 **CSWIF:** Clock Switch Interrupt Flag bit<sup>(3)</sup>

1 = Interrupt has occurred (must be cleared by software)

0 = Interrupt event has not occurred

bit 2 **OSFIF:** Oscillator Fail Interrupt Flag bit

1 = Interrupt has occurred (must be cleared by software)

0 = Interrupt event has not occurred

bit 1 **HLVDIF:** HLVD Interrupt Flag bit

1 = Interrupt has occurred (must be cleared by software)

0 = Interrupt event has not occurred

bit 0 **SWIF:** Software Interrupt Flag bit

1 = Software Interrupt Flag Enable

0 = Software Interrupt Flag Disable

**Note 1:** Interrupt flag bits get set when an interrupt condition occurs, regardless of the state of its corresponding enable bit, or the global enable bit. User software should ensure the appropriate interrupt flag bits are clear prior to enabling an interrupt.

**2:** IOCIF is a read-only bit. To clear the interrupt condition, all bits in the IOCxF registers must be cleared.

**3:** The CSWIF interrupt will not wake the system from Sleep. The system will sleep until another interrupt causes the wake-up.

# PIC18(L)F26/27/45/46/47/55/56/57K42

**REGISTER 9-18: PIE4: PERIPHERAL INTERRUPT ENABLE REGISTER 4**

R/W-0/0	R/W-0/0	R/W-0/0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
CLC1IE	CWG1IE	NCO1IE	—	CCP1IE	TMR2IE	TMR1GIE	TMR1IE
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7	<b>CLC1IE:</b> CLC1 Interrupt Enable bit 1 = Enabled 0 = Disabled
bit 6	<b>CWG1IE:</b> CWG1 Interrupt Enable bit 1 = Enabled 0 = Disabled
bit 5	<b>NCO1IE:</b> NCO1 Interrupt Enable bit 1 = Enabled 0 = Disabled
bit 4	<b>Unimplemented:</b> Read as '0'
bit 3	<b>CCP1IE:</b> CCP1 Interrupt Enable bit 1 = Enabled 0 = Disabled
bit 2	<b>TMR2IE:</b> TMR2 Interrupt Enable bit 1 = Enabled 0 = Disabled
bit 1	<b>TMR1GIE:</b> TMR1 Gate Interrupt Enable bit 1 = Enabled 0 = Disabled
bit 0	<b>TMR1IE:</b> TMR1 Interrupt Enable bit 1 = Enabled 0 = Disabled

# PIC18(L)F26/27/45/46/47/55/56/57K42

**REGISTER 9-25: IPR0: PERIPHERAL INTERRUPT PRIORITY REGISTER 0**

R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1
IOCIP	CRCIP	SCANIP	NVMIP	CSWIP	OSFIP	HLVDIP	SWIP
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

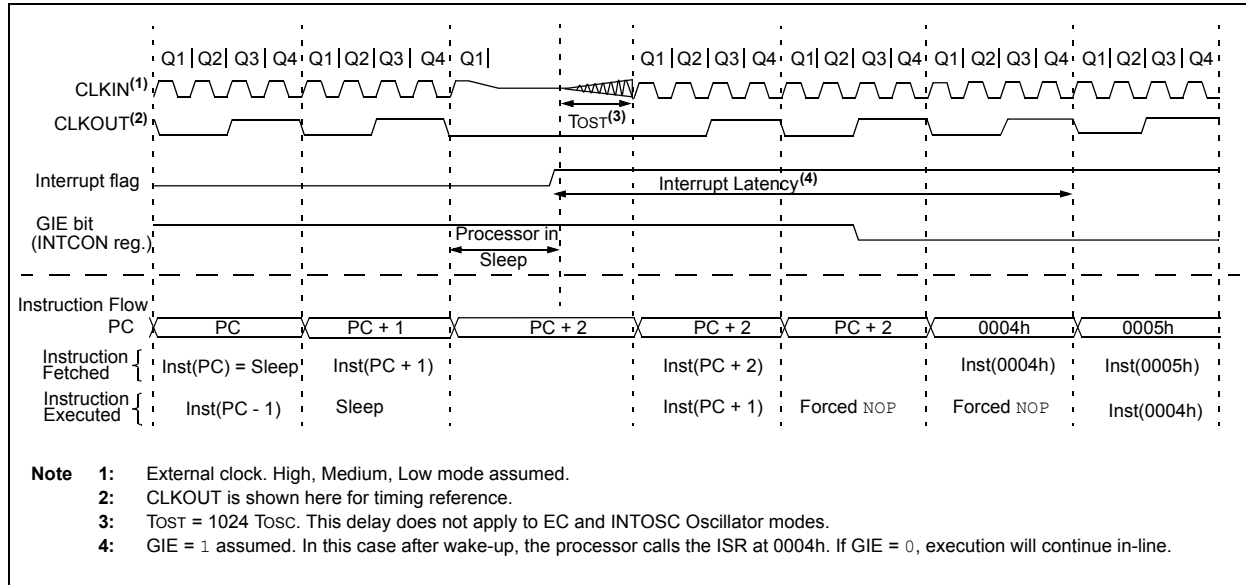
-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7	<b>IOCIP:</b> Interrupt-on-Change Priority bit 1 = High priority 0 = Low priority
bit 6	<b>CRCIP:</b> CRC Interrupt Priority bit 1 = High priority 0 = Low priority
bit 5	<b>SCANIP:</b> Memory Scanner Interrupt Priority bit 1 = High priority 0 = Low priority
bit 4	<b>NVMIP:</b> NVM Interrupt Priority bit 1 = High priority 0 = Low priority
bit 3	<b>CSWIP:</b> Clock Switch Interrupt Priority bit 1 = High priority 0 = Low priority
bit 2	<b>OSFIP:</b> Oscillator Fail Interrupt Priority bit 1 = High priority 0 = Low priority
bit 1	<b>HLVDIP:</b> HLVD Interrupt Priority bit 1 = High priority 0 = Low priority
bit 0	<b>SWIP:</b> Software Interrupt Priority bit 1 = High priority 0 = Low priority

**FIGURE 10-2: WAKE-UP FROM SLEEP THROUGH INTERRUPT**



## 10.2.3 LOW-POWER SLEEP MODE

The PIC18F26/27/45/46/47/55/56/57K42 device family contains an internal Low Dropout (LDO) voltage regulator, which allows the device I/O pins to operate at voltages up to 5.5V while the internal device logic operates at a lower voltage. The LDO and its associated reference circuitry must remain active when the device is in Sleep mode.

The PIC18F26/27/45/46/47/55/56/57K42 devices allow the user to optimize the operating current in Sleep, depending on the application requirements.

Low-Power Sleep mode can be selected by setting the VREGPM bit of the VREGCON register.

### 10.2.3.1 Sleep Current vs. Wake-up Time

In the default operating mode, the LDO and reference circuitry remain in the normal configuration while in Sleep. The device is able to exit Sleep mode quickly since all circuits remain active. In Low-Power Sleep mode, when waking-up from Sleep, an extra delay time is required for these circuits to return to the normal configuration and stabilize.

The Low-Power Sleep mode is beneficial for applications that stay in Sleep mode for long periods of time. The Normal mode is beneficial for applications that need to wake from Sleep quickly and frequently.



# PIC18(L)F26/27/45/46/47/55/56/57K42

**FIGURE 15-3: DMA COUNTERS BLOCK DIAGRAM**

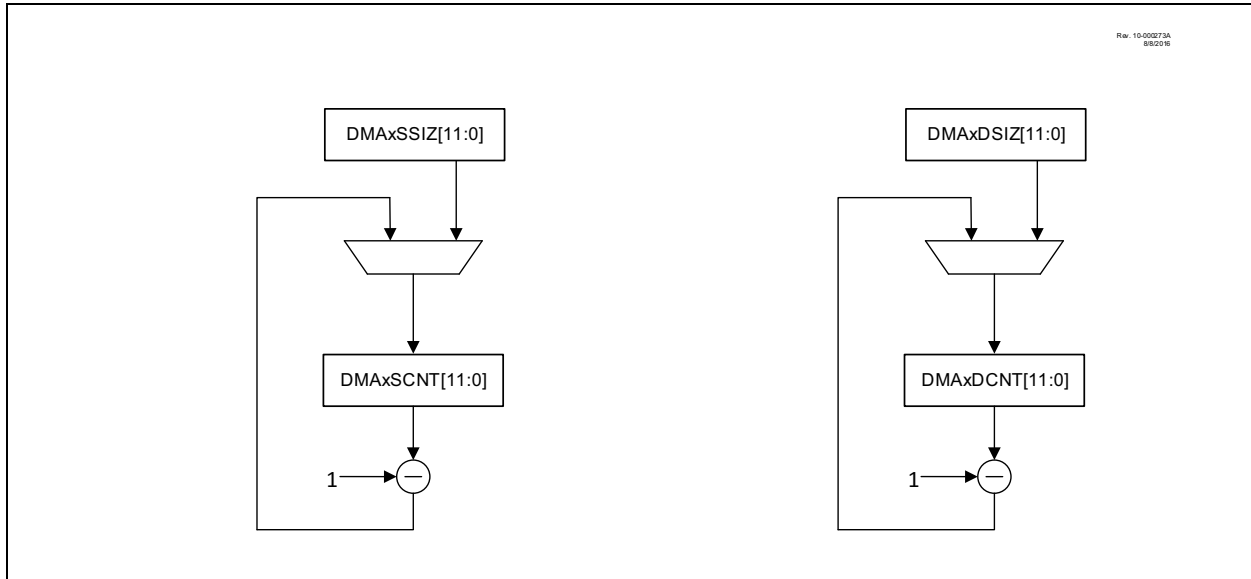


Table 15-2 has a few examples of configuring DMA Message sizes.

**TABLE 15-2: EXAMPLE MESSAGE SIZE TABLE**

Operation	Example	SCNT	DCNT	Comments
Read from single SFR location to RAM	U1RXB	1	N	N equals the number of bytes desired in the destination buffer. $N \geq 1$ .
Write to single SFR location from RAM	U1TXB	N	1	N equals the number of bytes desired in the source buffer. $N \geq 1$ .
Read from multiple SFR location	ADRES[H:L]	2	$2*N$	N equals the number of ADC results to be stored in memory. $N \geq 1$
	TMR1[H:L]	2	$2*N$	N equals the number of TMR1 Acquisition results to be stored in memory. $N \geq 1$
	SMT1CPR[U:H:L]	3	$3*N$	N equals the number of Capture Pulse Width measurements to be stored in memory. $N \geq 1$
Write to Multiple SFR registers	PWMDC[H:L]	$2*N$	2	N equals the number of PWM duty cycle values to be loaded from a memory table. $N \geq 1$
	All ADC registers	$N*31$	31	Using the DMA to transfer a complete ADC context from RAM to the ADC registers. $N \geq 1$

# PIC18(L)F26/27/45/46/47/55/56/57K42

**REGISTER 15-1: DMAxCON0: DMAx CONTROL REGISTER 0**

R/W-0/0	R/W/HC-0/0	R/W/HS/HC-0/0	U-0	U-0	R/W/HC-0/0	U-0	R/HS/HC-0/0
EN	SIRQEN	DGO	—	—	AIRQEN	—	XIP
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n/n = Value at POR  
and BOR/Value at all  
other Resets

0 = bit is cleared

x = bit is unknown

u = bit is unchanged

bit 7 **EN:** DMA Module Enable bit

1 = Enables module

0 = Disables module

bit 6 **SIRQEN:** Start of Transfer Interrupt Request Enable bits

1 = Hardware triggers are allowed to start DMA transfers

0 = Hardware triggers are not allowed to start DMA transfers

bit 5 **DGO:** DMA transaction bit

1 = DMA transaction is in progress

0 = DMA transaction is not in progress

bit 4-3 **Unimplemented:** Read as '0'

bit 2 **AIRQEN:** Abort of Transfer Interrupt Request Enable bits

1 = Hardware triggers are allowed to abort DMA transfers

0 = Hardware triggers are not allowed to abort DMA transfers

bit 1 **Unimplemented:** Read as '0'

bit 0 **XIP:** Transfer in Progress Status bit

1 = The DMAxBUF register currently holds contents from a read operation and has not transferred data to the destination.

0 = The DMAxBUF register is empty or has successfully transferred data to the destination address

# PIC18(L)F26/27/45/46/47/55/56/57K42

**TABLE 21-3: SUMMARY OF REGISTERS ASSOCIATED WITH TIMER1/3/5 AS A TIMER/COUNTER**

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Reset Values on Page
TxCON	—	—	CKPS<1:0>		—	SYNC	RD16	ON	313
TxGCON	GE	GPOL	GTM	GSPM	GO/DONE	GVAL	—	—	314
TxCLK	—	—	—	CS<4:0>					315
TxGATE	—	—	—	GSS<4:0>					316
TMRxL	Least Significant Byte of the 16-bit TMR3 Register								317
TMRxH	Holding Register for the Most Significant Byte of the 16-bit TMR3 Register								317

**Legend:** — = Unimplemented location, read as '0'. Shaded cells are not used by TIMER1/3/5.

## 23.2 Capture Mode

Capture mode makes use of the 16-bit Timer1 resource. When an event occurs on the capture source, the 16-bit CCPRxH:CCPRxL register pair captures and stores the 16-bit value of the TMRxH:TMRxL register pair, respectively. An event is defined as one of the following and is configured by the MODE<3:0> bits of the CCPxCON register:

- Every falling edge of CCPx input
- Every rising edge of CCPx input
- Every 4th rising edge of CCPx input
- Every 16th rising edge of CCPx input
- Every edge of CCPx input (rising or falling)

When a capture is made, the Interrupt Request Flag bit CCPxIF of the respective PIR register is set. The interrupt flag must be cleared in software. If another capture occurs before the value in the CCPRxH:CCPRxL register pair is read, the old captured value is overwritten by the new captured value.

**Note:** If an event occurs during a 2-byte read, the high and low-byte data will be from different events. It is recommended while reading the CCPRxH:CCPRxL register pair to either disable the module or read the register pair twice for data integrity.

Figure 23-1 shows a simplified diagram of the capture operation.

### 23.2.1 CAPTURE SOURCES

In Capture mode, the CCPx pin should be configured as an input by setting the associated TRIS control bit.

**Note:** If the CCPx pin is configured as an output, a write to the port can cause a capture condition.

The capture source is selected by configuring the CTS<2:0> bits of the CCPxCAP register. Refer to CCPxCAP register (Register 23-3) for a list of sources that can be selected.

### 23.2.2 TIMER1 MODE RESOURCE

Timer1 must be running in Timer mode or Synchronized Counter mode for the CCP module to use the capture feature. In Asynchronous Counter mode, the capture operation may not work.

- See Section 21.0 “Timer1/3/5 Module with Gate Control” for more information on configuring Timer1.

**Note:** Clocking Timer1 from the system clock (Fosc) should not be used in Capture mode. In order for Capture mode to recognize the trigger event on the CCPx pin, Timer1 must be clocked from the instruction clock (Fosc/4) or from an external clock source.

# PIC18(L)F26/27/45/46/47/55/56/57K42

**TABLE 25-3: SUMMARY OF REGISTERS ASSOCIATED WITH SMT1**

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
SMT1CON0	EN	—	STP	WPOL	SPOL	CPOL	SMT1PS<1:0>		<a href="#">394</a>
SMT1CON1	GO	REPEAT	—	—	MODE<3:0>				<a href="#">395</a>
SMT1STAT	CPRUP	CPWUP	RST	—	—	TS	WS	AS	<a href="#">396</a>
SMT1CLK	—	—	—	—	—	CSEL<2:0>			<a href="#">397</a>
SMT1SIG	—	—	—	SSEL<4:0>					<a href="#">399</a>
SMT1WIN	—	—	—	WSEL<4:0>					<a href="#">398</a>
SMT1TMRL	TMR<7:0>								<a href="#">400</a>
SMT1TMRH	TMR<15:8>								<a href="#">400</a>
SMT1TMRU	TMR<23:16>								<a href="#">400</a>
SMT1CPRL	CPR<7:0>								<a href="#">401</a>
SMT1CPRH	CPR<15:8>								<a href="#">401</a>
SMT1CPRU	CPR<23:16>								<a href="#">401</a>
SMT1CPWL	CPW<7:0>								<a href="#">402</a>
SMT1CPWH	CPW<15:8>								<a href="#">402</a>
SMT1CPWU	CPW<23:16>								<a href="#">402</a>
SMT1PRL	PR<7:0>								<a href="#">403</a>
SMT1PRH	PR<15:8>								<a href="#">403</a>
SMT1PRU	PR<23:16>								<a href="#">403</a>

**Legend:** — = unimplemented read as '0'. Shaded cells are not used for SMT1 module.

## 33.4.3 SLAVE OPERATION IN 7-BIT ADDRESSING MODE

The 8th bit in an address byte transmitted by the master is used to determine if the Master wants to read from or write to the Slave device. If set, it denotes that the Master wants to read from the slave and if cleared it means the master wants to write to the slave device. If there is an address match, the R/W bit is copied to the R/W bit of the I2CxSTAT0 register.

### 33.4.3.1 Slave Reception (7-bit Addressing Mode)

This section describes the sequence of events for the I<sup>2</sup>C module configured as an I<sup>2</sup>C slave in 7-bit Addressing mode and is receiving data. [Figure 33-6](#), [Figure 33-7](#), and [Figure 33-8](#) are used as a visual reference for this description.

1. Master asserts Start condition (can also be a restart) on the bus. Start condition Interrupt Flag (SCIF) in I2CxPIR register is set.
2. If Start condition interrupt is enabled (SCIE bit is set), generic interrupt I2CxIF is set.
3. Master transmits eight bits – 7-bit address and R/W = 0.
4. Received address is compared with the values in I2CxADR0/I2CxADR1/I2CxADR2/I2CxADR3 registers. Refer to section [Section 33.4.1 “Slave Addressing Modes”](#) for slave addressing modes.
5. If address matches; SMA in I2CxSTAT0 register is set, R/W is copied to R/W bit, D/A bit is cleared. If the address does not match; module becomes idle.
6. The matched address data is loaded into I2CxADB0 and ADRIF in I2CxPIR register is set.
7. If Address hold interrupt is enabled (ADRIE = 1), CSTR is set. I2CxIF is set. Slave software can read address from I2CxADB0 and set/clear ACKDT before releasing SCL.
8. If there are any previous error conditions, e.g., Receive buffer overflow or transmit buffer under-flow errors, Slave will force a NACK and the module becomes idle.
9. ACKDT value is copied out to SDA for ACK pulse to be read by the Master on the 9th SCL pulse.
10. If the Acknowledge interrupt and hold is enabled (ACKTIE = 1), CSTR is set, I2CxIF is set, then Slave software can read address from I2CxADB0 register and change the value of ACKDT before releasing SCL by clearing CSTR.
11. Master sends first seven SCL pulses of the data byte or a Stop condition (in the case of NACK).
12. If Stop condition; PCIF in I2CxPIR register is set, module becomes idle.
13. If the receive buffer is full from the previous transaction i.e. RXBF = 1 (I2CxRXIF = 1), CSTR is set. Slave software must read data out of I2CxRXB to resume communication.
14. Master sends 8th SCL pulse of the data byte. D/A bit is set, WRIF is set.
15. I2CxRXB is loaded with new data, RXBF bit is set, I2CxRXIF is set.
16. If Data write interrupt and hold is enabled (WRIE = 1), CSTR is set, I2CxIF is set. Slave software can read data from I2CxRXB and set/clear ACKDT before releasing SCL by clearing CSTR.
17. If I2CxCNT = 0, the ACKCNT value is output to the SDA; else, if I2CxCNT != 0, the ACKDT value is used and the value of I2CxCNT is decremented.
18. The ACK value is copied out to SDA to be read by the Master on the 9th SCL pulse.
19. If I2CxCNT = 0, CNTIF is set.
20. If a NACK was sent, NACKIF is set, module becomes idle.
21. If ACKTIE = 1, CSTR is set, I2CxIF is set. Slave software can read data from I2CxRXB clearing RXBF, before releasing SCL by clearing CSTR.
22. Go to step 11.

## 33.5.12 MASTER RECEPTION IN 10-BIT ADDRESSING MODE

This section describes the sequence of events for the I<sup>2</sup>C module configured as an I<sup>2</sup>C master in 10-bit Addressing mode and is receiving data. Figure 33-22 is used as a visual reference for this description.

1. Master software loads high address byte in I2CxADB1 and low address byte in I2CxADB0 for write and sets restart enable (RSTEN) bit.
2. Master software sets START bit.
3. Master hardware waits for BFRE bit to be set; then shifts out start, high address and waits for acknowledge.
4. If slave responds with a NACK, master hardware sends Stop and ends communication.
5. If slave responds with ACK, master hardware shifts out the low address.
6. If the transmit buffer empty flag (TXBE) is set and I2CxCNT! = 0, the clock is stretched on 8th falling SCL edge. Allowing master software writes next data to I2CxTXB.
7. Master hardware sends 9th SCL pulse for ACK from slave and loads the shift register from I2CxTXB.
8. If slave responds with a NACK, master hardware sends Stop and ends communication.
9. If slave responds with an ACK and I2CxCNT = 0, master hardware sets MDR bit, go to Step 11.
10. If slave responds with an ACK and I2CxCNT! = 0, master hardware outputs data in shift register on SDA and waits for ACK from slave. Go to step 4.
11. Master software loads I2CxADB0 for read, and I2CCNT with the number of bytes to be received in the current transaction.
12. Master software sets Start bit.
13. Master hardware shifts out Restart and high address with R/W = 1.
14. Master sends out 9th SCL pulse for ACK from Slave.
15. If slave responds with a NACK, master hardware sends Stop or sets MDR (RSEN bit).
16. If slave responds with an ACK, master hardware shifts 7 bits of data into the shift register from the slave.
17. If the receive buffer full flag (RXBF) is set, clock is stretched on seventh falling SCL edge.
18. Master software can clear clock stretching by reading the previous data in the receive buffer.
19. Master hardware shifts 8th bit of data into the shift register from slave and loads it into I2CxRXB.
20. Master software reads data from I2CxRXB register.

21. If I2CxCNT! = 0, master hardware clocks out ACKDT as ACK value to slave.
22. If I2CxCNT = 0, master hardware clocks out ACKCNT as ACK value to slave
23. Go to step 4.

# PIC18(L)F26/27/45/46/47/55/56/57K42

## REGISTER 33-15: I2CXADR3: I<sup>2</sup>C ADDRESS 3 REGISTER

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	U-0
ADR14	ADR13	ADR12	ADR11	ADR10	ADR9	ADR8	—
bit 15							bit 8
R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	U-0
ADR7	ADR6	ADR5	ADR4	ADR3	ADR2	ADR1	—
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

HS = Hardware set

HC = Hardware clear

bit 7-0

**ADR<7-0>**: Address 3 bits

MODE<2:0> = 000 | 110 - 7-bit Slave/Multi-Master Modes

**ADR<7:1>**: 7-bit Slave Address

**ADR<0>**: Unused in this mode; bit state is a don't care

MODE<2:0> = 001 | 111 - 7-bit Slave/Multi-Master Mode with Masking

**MSK1<7:1>**: 7-bit Slave Address

**MSK1<0>**: Unused in this mode; bit state is a don't care

MODE<2:0> = 010 - 10-Bit Slave Mode

**ADR<14-10>**: Bit pattern sent by master is fixed by I<sup>2</sup>C specification and must be equal to '11110'. However, these bit values are compared by hardware to the received data to determine a match. It is up to the user to set these bits as '11110'

**ADR<9-8>**: Two Most Significant bits of 10-bit address

MODE<2:0> = 011 - 10-Bit Slave Mode with Masking

**MSK0<14-8>**: The received address byte, bit *n*, is compared to I2CxADR0 to detect I<sup>2</sup>C address match



# PIC18(L)F26/27/45/46/47/55/56/57K42

## REGISTER 36-35: ADACT: ADC AUTO CONVERSION TRIGGER CONTROL REGISTER

U-0	U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	—	—	ACT<4:0>				
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-5      **Unimplemented:** Read as '0'

bit 4-0      **ADACT<4:0>:** Auto-Conversion Trigger Select Bits

11111 = Reserved, do not use

- 
- 
- 

11110 = Reserved, do not use

11101 = Software write to ADPCH

11100 = Reserved, do not use

11011 = Software read of ADRESH

11010 = Software read of ADERRH

11001 = CLC4\_out

11000 = CLC3\_out

10111 = CLC2\_out

10110 = CLC1\_out

10101 = Logical OR of all Interrupt-on-change Interrupt Flags

10100 = CMP2\_out

10011 = CMP1\_out

10010 = NCO1\_out

10001 = PWM8\_out

10000 = PWM7\_out

01111 = PWM6\_out

01110 = PWM5\_out

01101 = CCP4\_trigger

01100 = CCP3\_trigger

01011 = CCP2\_trigger

01010 = CCP1\_trigger

01001 = SMT1\_trigger

01000 = TMR6\_postscaled

00111 = TMR5\_overflow

00110 = TMR4\_postscaled

00101 = TMR3\_overflow

00100 = TMR2\_postscaled

00011 = TMR1\_overflow

00010 = TMR0\_overflow

00001 = Pin selected by ADACTPPS

00000 = External Trigger Disabled

# PIC18(L)F26/27/45/46/47/55/56/57K42

**TABLE 44-6: I/O PORTS**

Standard Operating Conditions (unless otherwise stated)							
Param No.	Sym.	Characteristic	Min.	Typ†	Max.	Units	Conditions
D300	V <sub>IL</sub>	<b>Input Low Voltage</b>					
		I/O PORT:					
		with TTL buffer	—	—	0.8	V	4.5V ≤ V <sub>DD</sub> ≤ 5.5V
			—	—	0.15 V <sub>DD</sub>	V	1.8V ≤ V <sub>DD</sub> < 4.5V
		with Schmitt Trigger buffer	—	—	0.2 V <sub>DD</sub>	V	2.0V ≤ V <sub>DD</sub> ≤ 5.5V
		with I <sup>2</sup> C levels	—	—	0.3 V <sub>DD</sub>	V	
		with SMBus 2.0	—	—	0.8	V	2.7V ≤ V <sub>DD</sub> ≤ 5.5V
D305		with SMBus 3.0	—	—	0.8	V	1.8V ≤ V <sub>DD</sub> ≤ 5.5V
D306		MCLR	—	—	0.2 V <sub>DD</sub>	V	
D320	V <sub>IH</sub>	<b>Input High Voltage</b>					
		I/O PORT:					
		with TTL buffer	2.0	—	—	V	4.5V ≤ V <sub>DD</sub> ≤ 5.5V
			0.25 V <sub>DD</sub> + 0.8	—	—	V	1.8V ≤ V <sub>DD</sub> < 4.5V
		with Schmitt Trigger buffer	0.8 V <sub>DD</sub>	—	—	V	2.0V ≤ V <sub>DD</sub> ≤ 5.5V
		with I <sup>2</sup> C levels	0.7 V <sub>DD</sub>	—	—	V	
		with SMBus 2.0	2.1	—	—	V	2.7V ≤ V <sub>DD</sub> ≤ 5.5V
D325		with SMBus 3.0	1.35	—	—	V	1.8V ≤ V <sub>DD</sub> ≤ 5.5V
D326		MCLR	0.7 V <sub>DD</sub>	—	—	V	
D340	I <sub>IL</sub>	<b>Input Leakage Current<sup>(1)</sup></b>					
		I/O Ports	—	± 5	± 125	nA	V <sub>SS</sub> ≤ V <sub>PIN</sub> ≤ V <sub>DD</sub> , Pin at high-impedance, 85°C
			—	± 5	± 1000	nA	V <sub>SS</sub> ≤ V <sub>PIN</sub> ≤ V <sub>DD</sub> , Pin at high-impedance, 125°C
D342		MCLR <sup>(2)</sup>	—	± 50	± 200	nA	V <sub>SS</sub> ≤ V <sub>PIN</sub> ≤ V <sub>DD</sub> , Pin at high-impedance, 85°C
D350	I <sub>PUR</sub>	<b>Weak Pull-up Current</b>					
			25	120	200	μA	V <sub>DD</sub> = 3.0V, V <sub>PIN</sub> = V <sub>SS</sub>
D360	V <sub>OL</sub>	<b>Output Low Voltage</b>					
		I/O ports	—	—	0.6	V	I <sub>OL</sub> = 10.0mA, V <sub>DD</sub> = 3.0V
D370	V <sub>OH</sub>	<b>Output High Voltage</b>					
		I/O ports	V <sub>DD</sub> - 0.7	—	—	V	I <sub>OH</sub> = 6.0 mA, V <sub>DD</sub> = 3.0V
D380	C <sub>IO</sub>	All I/O pins	—	5	50	pF	

† Data in "Typ" column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

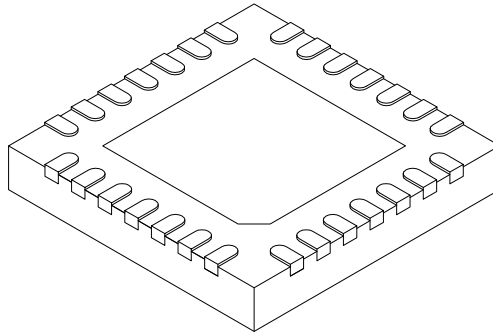
**Note 1:** Negative current is defined as current sourced by the pin.

**Note 2:** The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltages.

# PIC18(L)F26/27/45/46/47/55/56/57K42

## 28-Lead Plastic Quad Flat, No Lead Package (ML) - 6x6 mm Body [QFN] With 0.55 mm Terminal Length

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Dimension	Units	MILLIMETERS		
	Limits	MIN	NOM	MAX
Number of Pins	N	28		
Pitch	e	0.65 BSC		
Overall Height	A	0.80	0.90	1.00
Standoff	A1	0.00	0.02	0.05
Terminal Thickness	A3	0.20 REF		
Overall Width	E	6.00 BSC		
Exposed Pad Width	E2	3.65	3.70	4.20
Overall Length	D	6.00 BSC		
Exposed Pad Length	D2	3.65	3.70	4.20
Terminal Width	b	0.23	0.30	0.35
Terminal Length	L	0.50	0.55	0.70
Terminal-to-Exposed Pad	K	0.20	-	-

### Notes:

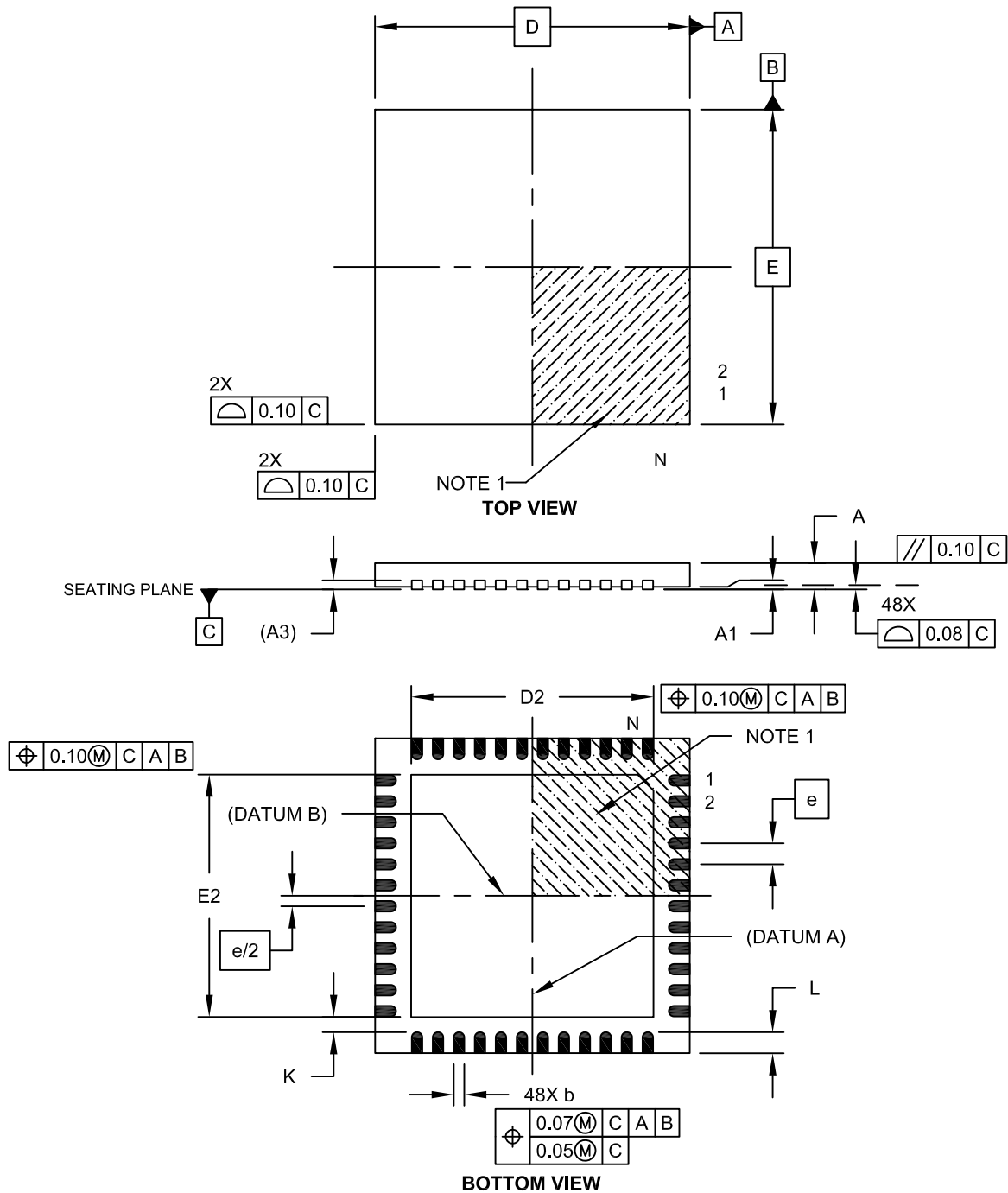
- Pin 1 visual index feature may vary, but must be located within the hatched area.
- Package is saw singulated
- Dimensioning and tolerancing per ASME Y14.5M.  
BSC: Basic Dimension. Theoretically exact value shown without tolerances.  
REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-105C Sheet 2 of 2

# PIC18(L)F26/27/45/46/47/55/56/57K42

## 48-Lead Plastic Ultra Thin Quad Flat, No Lead Package (MV) – 6x6x0.5 mm Body [UQFN]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>

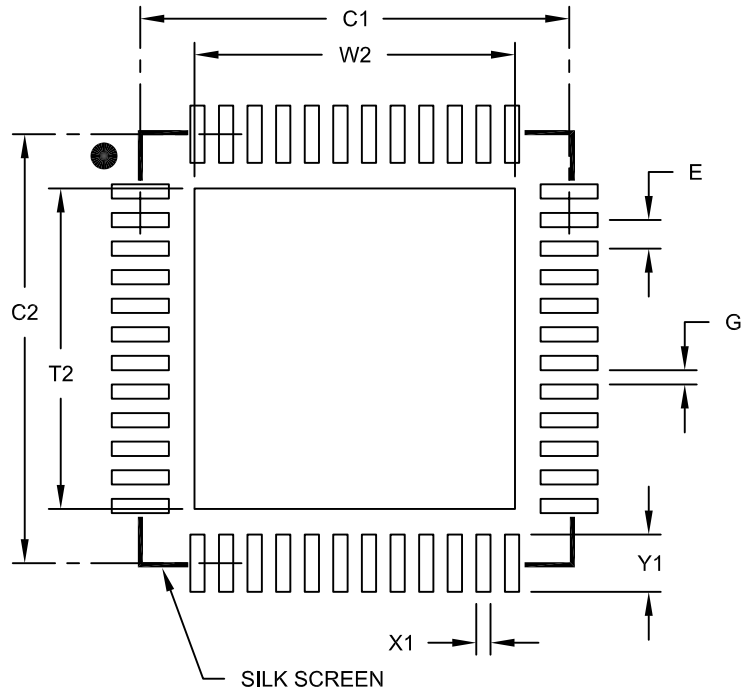


Microchip Technology Drawing C04-153A Sheet 1 of 2

# PIC18(L)F26/27/45/46/47/55/56/57K42

48-Lead Ultra Thin Plastic Quad Flat, No Lead Package (MV) - 6x6 mm Body [UQFN]  
With 0.40 mm Contact Length

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

Dimension Limits	Units	MILLIMETERS		
		MIN	NOM	MAX
Contact Pitch	E	0.40 BSC		
Optional Center Pad Width	W2			4.45
Optional Center Pad Length	T2			4.45
Contact Pad Spacing	C1		6.00	
Contact Pad Spacing	C2		6.00	
Contact Pad Width (X28)	X1			0.20
Contact Pad Length (X28)	Y1			0.80
Distance Between Pads	G	0.20		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2153A