



Welcome to [E-XFL.COM](https://www.e-xfl.com)

### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	64MHz
Connectivity	I <sup>2</sup> C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, HLVD, POR, PWM, WDT
Number of I/O	44
Program Memory Size	128KB (64K x 16)
Program Memory Type	FLASH
EEPROM Size	1K x 8
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 5.5V
Data Converters	A/D 43x12b; D/A 1x5b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	48-UFQFN Exposed Pad
Supplier Device Package	48-UQFN (6x6)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic18f57k42-e-mv">https://www.e-xfl.com/product-detail/microchip-technology/pic18f57k42-e-mv</a>

TABLE 2: 40/44-PIN ALLOCATION TABLE FOR PIC18(L)F4XK42

I/O	40-Pin PDIP	44-Pin TQFP	40-Pin UQFN	44-Pin QFN	ADC	Voltage Reference	DAC	Comparators	Zero Cross Detect	I <sup>2</sup> C	SPI	UART	DSM	Timers/SMT	CCP and PWM	CWG	CLC	NCO	Clock Reference (CLKR)	Interrupt-on-Change	Basic
RA0	2	19	17	19	ANA0	—	—	C1IN0- C2IN0-	—	—	—	—	—	—	—	—	CLCIN0 <sup>(1)</sup>	—	—	IOCA0	—
RA1	3	20	18	20	ANA1	—	—	C1IN1- C2IN1-	—	—	—	—	—	—	—	—	CLCIN1 <sup>(1)</sup>	—	—	IOCA1	—
RA2	4	21	19	21	ANA2	VREF-	DAC1OUT1	C1IN0+ C2IN0+	—	—	—	—	—	—	—	—	—	—	—	IOCA2	—
RA3	5	22	20	22	ANA3	VREF+	—	C1IN1+	—	—	—	—	MDCARL <sup>(1)</sup>	—	—	—	—	—	—	IOCA3	—
RA4	6	23	21	23	ANA4	—	—	—	—	—	—	—	MDCARH <sup>(1)</sup>	T0CKI <sup>(1)</sup>	—	—	—	—	—	IOCA4	—
RA5	7	24	22	24	ANA5	—	—	—	—	—	SS1 <sup>(1)</sup>	—	MDSRC <sup>(1)</sup>	—	—	—	—	—	—	IOCA5	—
RA6	14	31	29	33	ANA6	—	—	—	—	—	—	—	—	—	—	—	—	—	—	IOCA6	OSC2 CLKOUT
RA7	13	30	28	32	ANA7	—	—	—	—	—	—	—	—	—	—	—	—	—	—	IOCA7	OSC1 CLKIN
RB0	33	8	8	9	ANB0	—	—	C2IN1+	ZCD	—	—	—	—	—	CCP4 <sup>(1)</sup>	CWG1IN <sup>(1)</sup>	—	—	—	INT0 <sup>(1)</sup> IOCB0	—
RB1	34	9	9	10	ANB1	—	—	C1IN3- C2IN3-	—	SCL2 <sup>(3,4)</sup>	—	—	—	—	—	CWG2IN <sup>(1)</sup>	—	—	—	INT1 <sup>(1)</sup> IOCB1	—
RB2	35	10	10	11	ANB2	—	—	—	—	SDA2 <sup>(3,4)</sup>	—	—	—	—	—	CWG3IN <sup>(1)</sup>	—	—	—	INT2 <sup>(1)</sup> IOCB2	—
RB3	36	11	11	12	ANB3	—	—	C1IN2- C2IN2-	—	—	—	—	—	—	—	—	—	—	—	IOCB3	—
RB4	37	14	12	14	ANB4 ADCACT <sup>(1)</sup>	—	—	—	—	—	—	—	—	T5G <sup>(1)</sup>	—	—	—	—	—	IOCB4	—
RB5	38	15	13	15	ANB5	—	—	—	—	—	—	—	—	T1G <sup>(1)</sup>	CCP3 <sup>(1)</sup>	—	—	—	—	IOCB5	—
RB6	39	16	14	16	ANB6	—	—	—	—	—	—	CTS2 <sup>(1)</sup>	—	—	—	—	CLCIN2 <sup>(1)</sup>	—	—	IOCB6	ICSPCLK
RB7	40	17	15	17	ANB7	—	DAC1OUT2	—	—	—	—	RX2 <sup>(1)</sup>	—	T6IN <sup>(1)</sup>	—	—	CLCIN3 <sup>(1)</sup>	—	—	IOCB7	ICSPDAT
RC0	15	32	30	34	ANC0	—	—	—	—	—	—	—	—	T1CKI <sup>(1)</sup> T3CKI <sup>(1)</sup> T3G <sup>(1)</sup> SMTWIN1 <sup>(1)</sup>	—	—	—	—	—	IOCC0	SOSCO
RC1	16	35	31	35	ANC1	—	—	—	—	—	—	—	—	SMTSIG1 <sup>(1)</sup>	CCP2 <sup>(1)</sup>	—	—	—	—	IOCC1	SOSCI
RC2	17	36	32	36	ANC2	—	—	—	—	—	—	—	—	T5CKI <sup>(1)</sup>	CCP1 <sup>(1)</sup>	—	—	—	—	IOCC2	—

- Note**
- 1: This is a PPS remappable input signal. The input function may be moved from the default location shown to one of several other PORTx pins.
  - 2: All output signals shown in this row are PPS remappable.
  - 3: This is a bidirectional signal. For normal module operation, the firmware should map this signal to the same pin in both the PPS input and PPS output registers.
  - 4: These pins can be configured for I<sup>2</sup>C and SMB™ 3.0/2.0 logic levels; The SCLx/SDAx signals may be assigned to any of the RB1/RB2/RC3/RC4/RD0/RD1 pins. PPS assignments to the other pins (e.g., RA5) will operate, but input logic levels will be standard TTL/ST as selected by the INLV register, instead of the I<sup>2</sup>C specific or SMBus input buffer thresholds.

# PIC18(L)F26/27/45/46/47/55/56/57K42

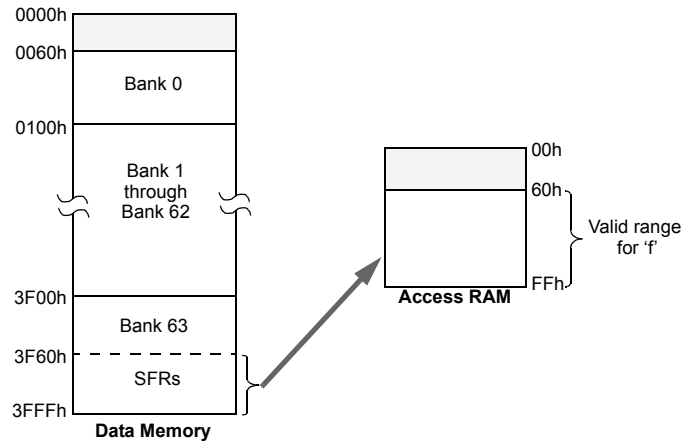
**FIGURE 4-7: COMPARING ADDRESSING OPTIONS FOR BIT-ORIENTED AND BYTE-ORIENTED INSTRUCTIONS (EXTENDED INSTRUCTION SET ENABLED)**

**EXAMPLE INSTRUCTION:** `ADDWF, f, d, a` (Opcode: `0010 01da ffff ffff`)

**When 'a' = 0 and  $f \geq 60h$ :**

The instruction executes in Direct Forced mode. 'f' is interpreted as a location in the Access RAM between 060h and 0FFh. This is the same as locations 3F60h to 3FFFh (Bank 63) of data memory.

Locations below 60h are not available in this Addressing mode.



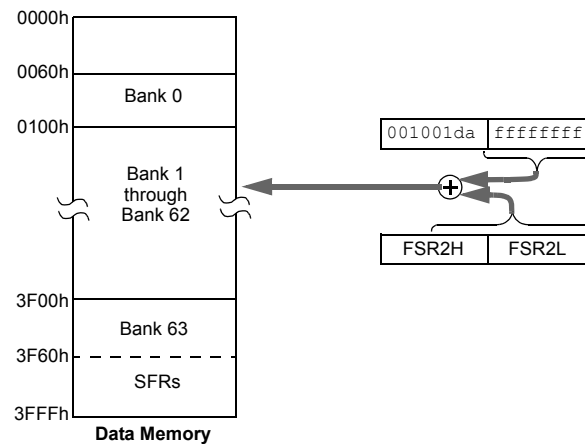
**When 'a' = 0 and  $f \leq 5Fh$ :**

The instruction executes in Indexed Literal Offset mode. 'f' is interpreted as an offset to the address value in FSR2. The two are added together to obtain the address of the target register for the instruction. The address can be anywhere in the data memory space.

Note that in this mode, the correct syntax is now:

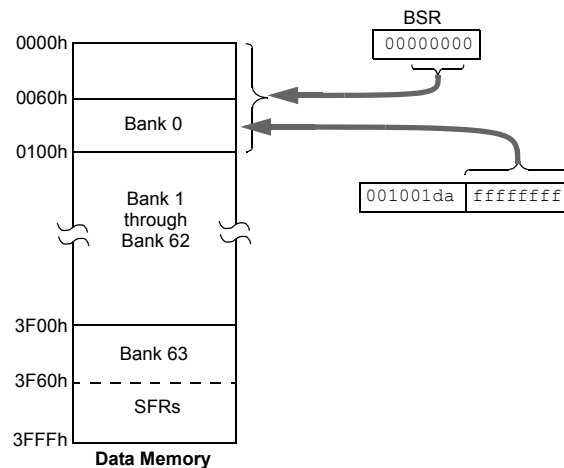
`ADDWF [k], d`

where 'k' is the same as 'f'.



**When 'a' = 1 (all values of f):**

The instruction executes in Direct mode (also known as Direct Long mode). 'f' is interpreted as a location in one of the 63 banks of the data memory space. The bank is designated by the Bank Select Register (BSR). The address can be in any implemented bank in the data memory space.



## 5.0 DEVICE CONFIGURATION

Device configuration consists of the Configuration Words, User ID, Device ID, Rev ID, Device Information Area (DIA), (see [Section 5.7 “Device Information Area”](#)), and the Device Configuration Information (DCI) regions, (see [Section 5.8 “Device Configuration Information”](#)).

### 5.1 Configuration Words

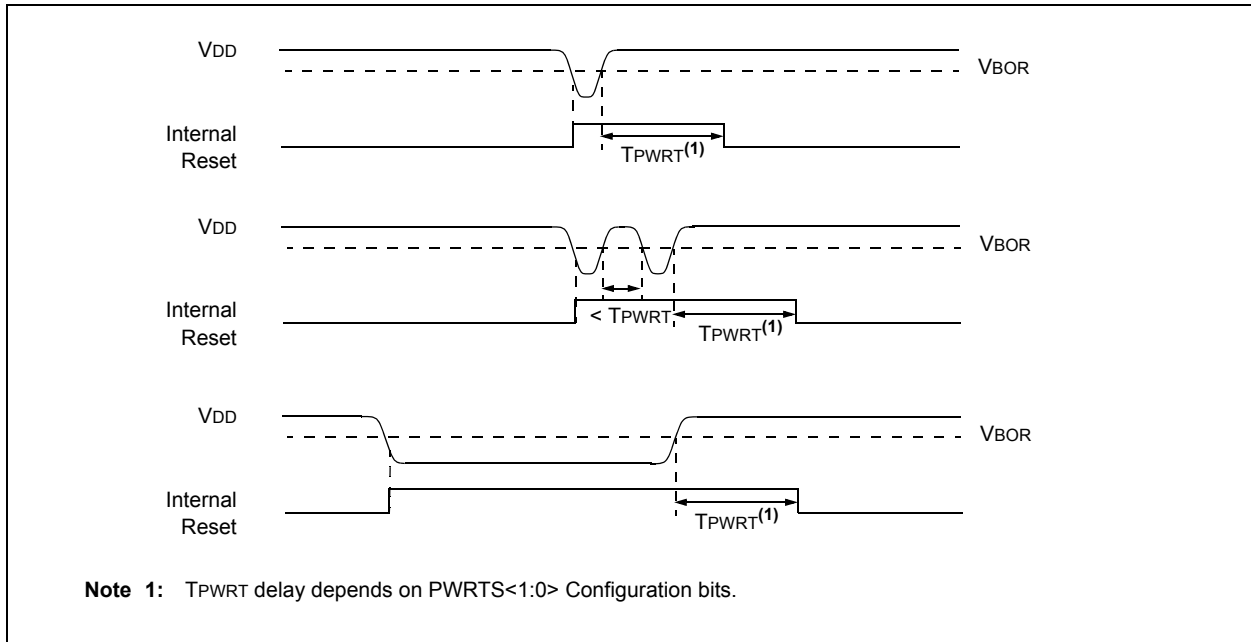
There are six Configuration Word bits that allow the user to setup the device with several choices of oscillators, Resets and memory protection options. These are implemented as Configuration Word 1 through Configuration Word 6 at 300000h through 30000Bh.

# PIC18(L)F26/27/45/46/47/55/56/57K42

**TABLE 6-1: BOR OPERATING MODES**

BOREN<1:0>	SBOREN	Device Mode	BOR Mode	Instruction Execution upon:	
				Release of POR	Wake-up from Sleep
11	X	X	Active	Wait for release of BOR (BORRDY = 1)	Begins immediately
10	X	Awake	Active	Wait for release of BOR (BORRDY = 1)	N/A
		Sleep	Hibernate	N/A	Wait for release of BOR (BORRDY = 1)
01	1	X	Active	Wait for release of BOR (BORRDY = 1)	Begins immediately
	0	X	Hibernate		
00	X	X	Disabled	Begins immediately	

**FIGURE 6-3: BROWN-OUT SITUATIONS**



# PIC18(L)F26/27/45/46/47/55/56/57K42

**REGISTER 9-16: PIE2: PERIPHERAL INTERRUPT ENABLE REGISTER 2**

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
I2C1RXIE	SPI1IE	SPI1TXIE	SPI1RXIE	DMA1AIE	DMA1ORIE	DMA1DCNTIE	DMA1SCNTIE
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7	<b>I2C1RXIE:</b> I <sup>2</sup> C1 Receive Interrupt Enable bit 1 = Enabled 0 = Disabled
bit 6	<b>SPI1IE:</b> SPI1 Interrupt Enable bit 1 = Enabled 0 = Disabled
bit 5	<b>SPI1TXIE:</b> SPI1 Transmit Interrupt Enable bit 1 = Enabled 0 = Disabled
bit 4	<b>SPI1RXIE:</b> SPI1 Receive Interrupt Enable bit 1 = Enabled 0 = Disabled
bit 3	<b>DMA1AIE:</b> DMA1 Abort Interrupt Enable bit 1 = Enabled 0 = Disabled
bit 2	<b>DMA1ORIE:</b> DMA1 Overrun Interrupt Enable bit 1 = Enabled 0 = Disabled
bit 1	<b>DMA1DCNTIE:</b> DMA1 Destination Count Interrupt Enable bit 1 = Enabled 0 = Disabled
bit 0	<b>DMA1SCNTIE:</b> DMA1 Source Count Interrupt Enable bit 1 = Enabled 0 = Disabled

# PIC18(L)F26/27/45/46/47/55/56/57K42

## REGISTER 11-3: WDTPSL: WWDT PRESCALE SELECT LOW BYTE REGISTER (READ-ONLY)

R-0/0	R-0/0	R-0/0	R-0/0	R-0/0	R-0/0	R-0/0	R-0/0
PSCNT<7:0>							
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-0 **PSCNT<7:0>**: Prescale Select Low Byte bits<sup>(1)</sup>

**Note 1:** The 18-bit WDT prescale value, PSCNT<17:0> includes the WDTPSL, WDTPSH and the lower bits of the WDTTMR registers. PSCNT<17:0> is intended for debug operations and should not be read during normal operation.

## REGISTER 11-4: WDTPSH: WWDT PRESCALE SELECT HIGH BYTE REGISTER (READ-ONLY)

R-0/0	R-0/0	R-0/0	R-0/0	R-0/0	R-0/0	R-0/0	R-0/0
PSCNT<15:8>							
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-0 **PSCNT<15:8>**: Prescale Select High Byte bits<sup>(1)</sup>

**Note 1:** The 18-bit WDT prescale value, PSCNT<17:0> includes the WDTPSL, WDTPSH and the lower bits of the WDTTMR registers. PSCNT<17:0> is intended for debug operations and should not be read during normal operation.

# PIC18(L)F26/27/45/46/47/55/56/57K42

## 13.0 NONVOLATILE MEMORY (NVM) CONTROL

Nonvolatile Memory (NVM) is separated into two types: Program Flash Memory (PFM) and Data EEPROM Memory.

PFM, Data EEPROM, User IDs and Configuration bits can all be accessed using the REG<1:0> bits of the NVMCON1 register.

The write time is controlled by an on-chip timer. The write/erase voltages are generated by an on-chip charge pump rated to operate over the operating voltage range of the device.

NVM can be protected in two ways, by either code protection or write protection. Code protection ( $\overline{CP}$  and  $\overline{CPD}$  bits in Configuration Word 5L) disables access, reading and writing to both PFM and Data EEPROM Memory via external device programmers. Code protection does not affect the self-write and erase functionality. Code protection can only be reset by a device programmer performing a Bulk Erase to the device, clearing all nonvolatile memory, Configuration bits and User IDs.

Write protection prohibits self-write and erase to a portion or all of the PFM, as defined by the WRT bits of Configuration Word 4H. Write protection does not affect a device programmer's ability to read, write or erase the device.

**TABLE 13-1: NVM ORGANIZATION AND ACCESS INFORMATION**

Memory	PC<20:0> ICSP™ Addr<21:0> TBLPTR<21:0> NVMADDR<9:0>	Execution	User Access		
		CPU Execution	REG	TABLAT	NVMDAT
Program Flash Memory (PFM)	00 0000h ... 01 FFFFh	Read	10	Read/ Write <sup>(1)</sup>	— <sup>(3)</sup>
User IDs <sup>(2)</sup>	20 0000h ... 20 000Fh	No Access	x1	Read/ Write	— <sup>(3)</sup>
Reserved	20 0010h ... 2F FFFFh	No Access	— <sup>(3)</sup>		
Configuration	30 0000h ... 30 0009h	No Access	x1	Read/ Write <sup>(1)</sup>	— <sup>(3)</sup>
Reserved	30 000Ah ... 30 FFFFh	No Access	— <sup>(3)</sup>		
User Data Memory (Data EEPROM)	31 0000h ... 31 03FFh	No Access	00	— <sup>(3)</sup>	Read/ Write <sup>(1)</sup>
Reserved	31 0400h ... 3E FFFFh	No Access	— <sup>(3)</sup>		
Device Information Area (DIA)	3F 0000h ... 3F 003Fh	No Access	x1	Read	— <sup>(3)</sup>
Reserved	3F 0040h ... 3F FF09h	No Access	— <sup>(3)</sup>		
Device Configuration Information (DCI)	3F FF00h ... 3F FF09h	No Access	x1	Read	— <sup>(3)</sup>
Reserved	3F FF0Ah ... 3F FFFBh	No Access	— <sup>(3)</sup>		
Revision ID/ Device ID	3F FFFCh ... 3F FFFFh	No Access	x1	Read	— <sup>(3)</sup>

**Note 1:** Subject to Memory Write Protection settings.

**Note 2:** User IDs are eight words ONLY. There is no code protection, table read protection or write protection implemented for this region.

**Note 3:** Reads as '0', writes clear the WR bit and WRERR bit is set.



## 13.1.4 NVM UNLOCK SEQUENCE

The unlock sequence is a mechanism that protects the NVM from unintended self-write programming or erasing. The sequence must be executed and completed without interruption to successfully complete any of the following operations:

- PFM Row Erase
- Write of PFM write latches to PFM memory
- Write of PFM write latches to User IDs
- Write to Data EEPROM Memory
- Write to Configuration Words

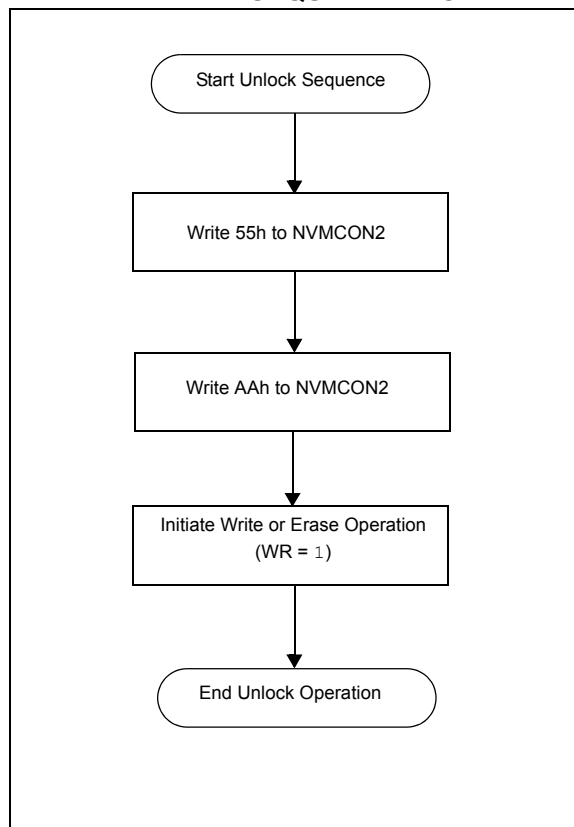
The unlock sequence consists of the following steps and must be completed in order:

- Write 55h to NVMCON2
- Write AAh to NVMCON2
- Set the WR bit of NVMCON1

Once the WR bit is set, the processor will stall internal operations until the operation is complete and then resume with the next instruction.

Since the unlock sequence must not be interrupted, global interrupts should be disabled prior to the unlock sequence and re-enabled after the unlock sequence is completed.

**FIGURE 13-6: NVM UNLOCK SEQUENCE FLOWCHART**



### EXAMPLE 13-2: NVM UNLOCK SEQUENCE

BCF	INTCON0,GIE	; Recommended so sequence is not interrupted
BANKSEL	NVMCON1	
BSF	NVMCON1,WREN	; Enable write/erase
MOVLW	55h	; Load 55h
MOVWF	NVMCON2	; Step 1: Load 55h into NVMCON2
MOVLW	AAh	; Step 2: Load W with AAh
MOVWF	NVMCON2	; Step 3: Load AAh into NVMCON2
BSF	INTCON1,WR	; Step 4: Set WR bit to begin write/erase
BSF	INTCON0,GIE	; Re-enable interrupts

**Note 1:** Sequence begins when NVMCON2 is written; steps 1-4 must occur in the cycle-accurate order shown. If the timing of the steps 1 to 4 is corrupted by an interrupt or a debugger Halt, the action will not take place.

**2:** Opcodes shown are illustrative; any instruction that has the indicated effect may be used.

# PIC18(L)F26/27/45/46/47/55/56/57K42

## 16.0 I/O PORTS

The PIC18(L)F26/27/45/46/47/55/56/57K42 devices have six I/O ports, allocated as shown in [Table 16-1](#).

**TABLE 16-1: PORT ALLOCATION TABLE FOR PIC18(L)F26/27/45/46/47/55/56/57K42 DEVICES**

Device	PORTA	PORTB	PORTC	PORTD	PORTE	PORTF
PIC18(L)F26K42	•	•	•		.(1)	
PIC18(L)F27K42	•	•	•		.(1)	
PIC18(L)F45K42	•	•	•	•	.(2)	
PIC18(L)F46K42	•	•	•	•	.(2)	
PIC18(L)F47K42	•	•	•	•	.(2)	
PIC18(L)F55K42	•	•	•	•	.(2)	•
PIC18(L)F56K42	•	•	•	•	.(2)	•
PIC18(L)F57K42	•	•	•	•	.(2)	•

**Note 1:** Pin RE3 only.

**2:** Pins RE0, RE1, RE2 and RE3 only.

Each port has ten registers to control the operation. These registers are:

- PORTx registers (reads the levels on the pins of the device)
- LATx registers (output latch)
- TRISx registers (data direction)
- ANSELx registers (analog select)
- WPUx registers (weak pull-up)
- INLVx registers (input level control)
- SLRCONx registers (slew rate control)
- ODCONx registers (open-drain control)

Most port pins share functions with device peripherals, both analog and digital. In general, when a peripheral is enabled on a port pin, that pin cannot be used as a general purpose output; however, the pin can still be read.

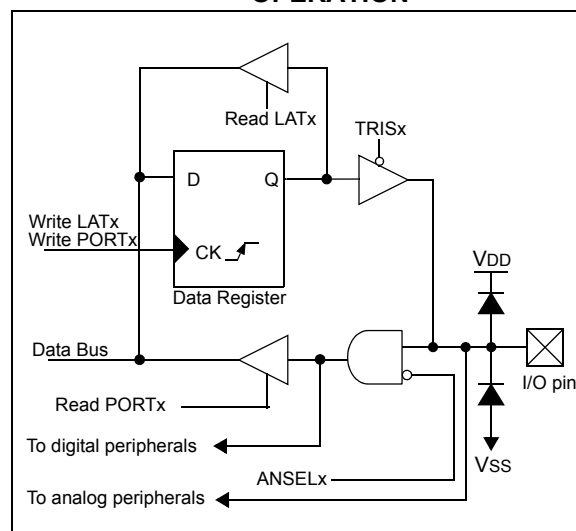
The Data Latch (LATx registers) is useful for read-modify-write operations on the value that the I/O pins are driving.

A write operation to the LATx register has the same effect as a write to the corresponding PORTx register. A read of the LATx register reads of the values held in the I/O PORT latches, while a read of the PORTx register reads the actual I/O pin value.

Ports that support analog inputs have an associated ANSELx register. When an ANSELx bit is set, the digital input buffer associated with that bit is disabled.

Disabling the input buffer prevents analog signal levels on the pin between a logic high and low from causing excessive current in the logic input circuitry. A simplified model of a generic I/O port, without the interfaces to other peripherals, is shown in [Figure 16-1](#).

**FIGURE 16-1: GENERIC I/O PORT OPERATION**



## 16.1 I/O Priorities

Each pin defaults to the PORT data latch after Reset. Other functions are selected with the peripheral pin select logic. See [Section 17.0 “Peripheral Pin Select \(PPS\) Module”](#) for more information.

Analog input functions, such as ADC and comparator inputs, are not shown in the peripheral pin select lists. These inputs are active when the I/O pin is set for Analog mode using the ANSELx register. Digital output functions may continue to control the pin when it is in Analog mode.

Analog outputs, when enabled, take priority over digital outputs and force the digital output driver into a high-impedance state.

The pin function priorities are as follows:

1. Configuration bits
2. Analog outputs (disable the input buffers)
3. Analog inputs
4. Port inputs and outputs from PPS

## 16.2 PORTx Registers

In this section, the generic names such as PORTx, LATx, TRISx, etc. can be associated with PORTA, PORTB, and PORTC. The functionality of PORTE is different compared to other ports and is explained in a separate section.

# PIC18(L)F26/27/45/46/47/55/56/57K42

**TABLE 18-1: IOC REGISTERS**

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
IOCAP	IOCAP7	IOCAP6	IOCAP5	IOCAP4	IOCAP3	IOCAP2	IOCAP1	IOCAP0
IOCAN	IOCAN7	IOCAN6	IOCAN5	IOCAN4	IOCAN3	IOCAN2	IOCAN1	IOCAN0
IOCAF	IOCAF7	IOCAF6	IOCAF5	IOCAF4	IOCAF3	IOCAF2	IOCAF1	IOCAF0
IOCBP	IOCBP7	IOCBP6	IOCBP5	IOCBP4	IOCBP3	IOCBP2	IOCBP1	IOCBP0
IOCBN	IOCBN7	IOCBN6	IOCBN5	IOCBN4	IOCBN3	IOCBN2	IOCBN1	IOCBN0
IOCBF	IOCBF7	IOCBF6	IOCBF5	IOCBF4	IOCBF3	IOCBF2	IOCBF1	IOCBF0
IOCCP	IOCCP7	IOCCP6	IOCCP5	IOCCP4	IOCCP3	IOCCP2	IOCCP1	IOCCP0
IOCCN	IOCCN7	IOCCN6	IOCCN5	IOCCN4	IOCCN3	IOCCN2	IOCCN1	IOCCN0
IOCCF	IOCCF7	IOCCF6	IOCCF5	IOCCF4	IOCCF3	IOCCF2	IOCCF1	IOCCF0
IOCEP	—	—	—	—	IOCEP3 <sup>(1)</sup>	—	—	—
IOCEN	—	—	—	—	IOCEN3 <sup>(1)</sup>	—	—	—
IOCEF	—	—	—	—	IOCEF3 <sup>(1)</sup>	—	—	—

**Note 1:** If MCLRE = 1 or LVP = 1, RE3 port functionality is disabled and IOC on RE3 is not available.

**TABLE 18-2: SUMMARY OF REGISTERS ASSOCIATED WITH INTERRUPT-ON-CHANGE**

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
IOCF	IOCF7	IOCF6	IOCF5	IOCF4	IOCF3	IOCF2	IOCF1	IOCF0	<a href="#">287</a>
IOCN	IOCN7	IOCN6	IOCN5	IOCN4	IOCN3	IOCN2	IOCN1	IOCN0	<a href="#">287</a>
IOCP	IOCP7	IOCP6	IOCP5	IOCP4	IOCP3	IOCP2	IOCP1	IOCP0	<a href="#">287</a>

**Legend:** — = unimplemented location, read as '0'. Shaded cells are not used by interrupt-on-change.

# PIC18(L)F26/27/45/46/47/55/56/57K42

## REGISTER 21-2: TxGCON: TIMERx GATE CONTROL REGISTER

R/W-0/u	R/W-0/u	R/W-0/u	R/W-0/u	R/W-0/u	R-x	U-0	U-0
GE	GPOL	GTM	GSPM	GGO/DONE	GVAL	—	—
bit 7						bit 0	

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7

**GE:** Timerx Gate Enable bit

If TMRxON = 1:

1 = Timerx counting is controlled by the Timerx gate function

0 = Timerx is always counting

If TMRxON = 0:

This bit is ignored

bit 6

**GPOL:** Timerx Gate Polarity bit

1 = Timerx gate is active-high (Timerx counts when gate is high)

0 = Timerx gate is active-low (Timerx counts when gate is low)

bit 5

**GTM:** Timerx Gate Toggle Mode bit

1 = Timerx Gate Toggle mode is enabled

0 = Timerx Gate Toggle mode is disabled and Toggle flip-flop is cleared

Timerx Gate Flip Flop Toggles on every rising edge

bit 4

**GSPM:** Timerx Gate Single Pulse Mode bit

1 = Timerx Gate Single Pulse mode is enabled and is controlling Timerx gate)

0 = Timerx Gate Single Pulse mode is disabled

bit 3

**GGO/DONE:** Timerx Gate Single Pulse Acquisition Status bit

1 = Timerx Gate Single Pulse Acquisition is ready, waiting for an edge

0 = Timerx Gate Single Pulse Acquisition has completed or has not been started.

This bit is automatically cleared when TxGSPM is cleared.

bit 2

**GVAL:** Timerx Gate Current State bit

Indicates the current state of the Timerx gate that could be provided to TMRxH:TMRxL

Unaffected by Timerx Gate Enable (TMRxGE)

bit 1-0

**Unimplemented:** Read as '0'

# PIC18(L)F26/27/45/46/47/55/56/57K42

## REGISTER 28-5: NCO1ACCU: NCO1 ACCUMULATOR REGISTER – UPPER BYTE<sup>(1)</sup>

U-0	U-0	U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	—	—	—	ACC<19:16>			
bit 7				bit 0			

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-4 **Unimplemented:** Read as '0'

bit 3-0 **ACC<19:16>:** NCO1 Accumulator, Upper Byte

**Note 1:** The accumulator spans registers NCO1ACCU:NCO1ACCH:NCO1ACCL. The 24 bits are reserved but not all are used. This register updates in real time, asynchronously to the CPU; there is no provision to guarantee atomic access to this 24-bit space using an 8-bit bus. Writing to this register while the module is operating will produce undefined results.

## REGISTER 28-6: NCO1INCL: NCO1 INCREMENT REGISTER – LOW BYTE<sup>(1,2)</sup>

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-1/1
INC<7:0>							
bit 7				bit 0			

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-0 **INC<7:0>:** NCO1 Increment, Low Byte

**Note 1:** The logical increment spans NCO1INCUC:NCO1INCH:NCO1INCL.

**2:** NCO1INC is double-buffered as INCBUF; INCBUF is updated on the next falling edge of NCOCLK after writing to NCO1INCL; NCO1INCUC and NCO1INCH should be written prior to writing NCO1INCL.

## REGISTER 28-7: NCO1INCH: NCO1 INCREMENT REGISTER – HIGH BYTE<sup>(1)</sup>

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
INC<15:8>							
bit 7				bit 0			

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-0 **INC<15:8>:** NCO1 Increment, High Byte

**Note 1:** The logical increment spans NCO1INCUC:NCO1INCH:NCO1INCL.

# PIC18(L)F26/27/45/46/47/55/56/57K42

**REGISTER 33-5: I2Cx BTO: I<sup>2</sup>C BUS TIMEOUT SELECTION REGISTER**

U-0	U-0	U-0	U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0
—	—	—	—	—	BTO<2:0>		
bit 7						bit 0	

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

HS = Hardware set

HC = Hardware clear

bit 7-3

**Unimplemented:** Read as '0'

bit 2-0

**BTO<2:0>:** I<sup>2</sup>C Bus Timeout Selection bits

BTO<2:0>	I <sup>2</sup> Cx Bus Timeout Selection
111	CLC4OUT
110	CLC3OUT
101	CLC2OUT
100	CLC1OUT
011	TMR6 post scaled output
010	TMR4 post scaled output
001	TMR2 post scaled output
000	Reserved

# PIC18(L)F26/27/45/46/47/55/56/57K42

**REGISTER 33-16: I2CxADB0: I<sup>2</sup>C ADDRESS DATA BUFFER 0 REGISTER<sup>(1)</sup>**

R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u
ADB7	ADB6	ADB5	ADB4	ADB3	ADB2	ADB1	ADB0
bit 7							bit 0

**Legend:**

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	HS = Hardware set HC = Hardware clear

bit 7-0      MODE<2:0> = 00x  
             **ADB<7:1>:** Address Data byte  
             Received matching 7-bit slave address data  
             **R/W:** Read/not-Write Data bit  
             Received read/write value from 7-bit address byte  
             MODE<2:0> = 01x  
             **ADB<7:0>:** Address Data byte  
             Received matching lower 8-bits of 10-bit slave address data  
             MODE<2:0> = 100  
             Unused in this mode; bit state is a don't care  
             MODE<2:0> = 101  
             **ADB<7:0>:** Low Address Data byte  
             Low 10-bit address value copied to transmit shift register  
             MODE<2:0> = 11x  
             **ADB<7:1>:** Address Data byte  
             Received matching 7-bit slave address  
             **R/W:** Read/not-Write Data bit  
             Received read/write value received 7-bit slave address byte

**Note 1:** This register is read only except in master, 10-bit Address mode (MODE<2:0> = 101).

## 36.2 ADC Operation

### 36.2.1 STARTING A CONVERSION

To enable the ADC module, the ON bit of the ADCON0 register must be set to a '1'. A conversion may be started by any of the following:

- Software setting the GO bit of ADCON0 to '1'
- An external trigger (selected by [Register 36-3](#))
- A continuous-mode retrigger (see section [Section 36.6.8 "Continuous Sampling mode"](#))

**Note:** The GO bit should not be set in the same instruction that turns on the ADC. Refer to [Section 36.2.6 "ADC Conversion Procedure \(Basic Mode\)"](#).

### 36.2.2 COMPLETION OF A CONVERSION

When any individual conversion is complete, the value already in ADRES is written into PREV (if ADPSIS = 1) and the new conversion results appear in ADRES. When the conversion completes, the ADC module will:

- Clear the GO bit (unless the CONT bit of ADCON0 is set)
- Set the ADIF Interrupt Flag bit
- Set the MATH bit
- Update ACC

When ADDSEN = 0 then after every conversion, or when ADDSEN = 1 then after every other conversion, the following events occur:

- ERR is calculated
- ADTIF is set if ERR calculation meets threshold comparison

Importantly, filter and threshold computations occur after the conversion itself is complete. As such, interrupt handlers responding to ADIF should check ADTIF before reading filter and threshold results.

### 36.2.3 ADC OPERATION DURING SLEEP

The ADC module can operate during Sleep. This requires the ADC clock source to be set to the FRC option. When the FRC oscillator source is selected, the ADC waits one additional instruction before starting the conversion. This allows the SLEEP instruction to be executed, which can reduce system noise during the conversion. If the ADC interrupt is enabled, the device will wake-up from Sleep when the conversion completes. If the ADC interrupt is disabled, the ADC module is turned off after the conversion completes, although the ON bit remains set.

### 36.2.4 EXTERNAL TRIGGER DURING SLEEP

If the external trigger is received during sleep while ADC clock source is set to the FRC, ADC module will perform the conversion and set the ADIF bit upon completion.

If an external trigger is received when the ADC clock source is something other than FRC, the trigger will be recorded, but the conversion will not begin until the device exits Sleep.



# PIC18(L)F26/27/45/46/47/55/56/57K42

**REGISTER 36-13: ADCAP: ADC ADDITIONAL SAMPLE CAPACITOR SELECTION REGISTER**

U-0	U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	—	—	ADCAP<4:0>				
bit 7							
							bit 0

**Legend:**

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **ADCAP<4:0>:** ADC Additional Sample Capacitor Selection bits

11111 = 31 pF

11110 = 30 pF

11101 = 29 pF

•

•

•

00011 = 3 pF

00010 = 2 pF

00001 = 1 pF

00000 = No additional capacitance

**REGISTER 36-14: ADRPT: ADC REPEAT SETTING REGISTER**

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
RPT<7:0>							
bit 7							
							bit 0

**Legend:**

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-0 **RPT<7:0>:** ADC Repeat Threshold bits

Determines the number of times that the ADC is triggered before the threshold is checked when the computation is Low-pass Filter, Burst Average, or Average modes. See [Table 36-2](#) for more details.

# PIC18(L)F26/27/45/46/47/55/56/57K42

## REGISTER 36-32: ADLTHL: ADC LOWER THRESHOLD LOW BYTE REGISTER

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
LTH<7:0>							
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-0

**LTH<7:0>**: ADC Lower Threshold LSB. LTH and UTH are compared with ERR to set the ADUTHR and ADLTHR bits of ADSTAT. Depending on the setting of ADTMD, an interrupt may be triggered by the results of this comparison.

## REGISTER 36-33: ADUTHH: ADC UPPER THRESHOLD HIGH BYTE REGISTER

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
UTH<15:8>							
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-0

**UTH<15:8>**: ADC Upper Threshold MSB. LTH and UTH are compared with ERR to set the ADUTHR and ADLTHR bits of ADSTAT. Depending on the setting of ADTMD, an interrupt may be triggered by the results of this comparison.

## REGISTER 36-34: ADUTHL: ADC UPPER THRESHOLD LOW BYTE REGISTER

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
UTH<7:0>							
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-0

**UTH<7:0>**: ADC Upper Threshold LSB. LTH and UTH are compared with ERR to set the ADUTHR and ADLTHR bits of ADSTAT. Depending on the setting of ADTMD, an interrupt may be triggered by the results of this comparison.

# PIC18(L)F26/27/45/46/47/55/56/57K42

**TABLE 42-1: REGISTER FILE SUMMARY FOR PIC18(L)F26/27/45/46/47/55/56/57K42 DEVICES**

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on page
3BFEh	DMA1AIRQ	—	AIRQ							256
3BFDh	DMA1CON1	EN	SIRQEN	DGO	—	—	AIRQEN	—	XIP	249
3BFCCh	DMA1CON0	DMODE		DSTP	SMR		SMODE		SSTP	248
3BFBh	DMA1SSAU	—	—	SSA						251
3BFAh	DMA1SSAH	SSA								250
3BF9h	DMA1SSAL	SSA								250
3BF8h	DMA1SSZH	—	—	—	—	SSZ				252
3BF7h	DMA1SSZL	SSZ								252
3BF6h	DMA1SPTRU	—	—	SPTR						252
3BF5h	DMA1SPTRH	SPTR								251
3BF4h	DMA1SPTRL	SPTR								251
3BF3h	DMA1SCNTH	—	—	—	—	SCNT				253
3BF2h	DMA1SCNTL	SCNT								253
3BF1h	DMA1DSAH	DSA								254
3BF0h	DMA1DSAL	SSA								253
3BEFh	DMA1DSZH	—	—	—	—	DSZ				255
3BEEh	DMA1DSZL	DSZ								255
3BEDh	DMA1DPTRH	DPTR								254
3BECCh	DMA1DPTRL	DPTR								254
3BEBh	DMA1DCNTH	—	—	—	—	DCNT				256
3BEAh	DMA1DCNTL	DCNT								255
3BE9h	DMA1BUF	BUF								250
3BE8h - 3BE0h	—	Unimplemented								
3BDFh	DMA2SIRQ	—	SIRQ							256
3BDEh	DMA2AIRQ	—	AIRQ							256
3BDDh	DMA2CON1	EN	SIRQEN	DGO	—	—	AIRQEN	—	XIP	249
3BDCCh	DMA2CON0	DMODE		DSTP	SMR		SMODE		SSTP	248
3BDBh	DMA2SSAU	—	—	SSA						251
3BDAh	DMA2SSAH	SSA								250
3BD9h	DMA2SSAL	SSA								250
3BD8h	DMA2SSZH	—	—	—	—	SSZ				252
3BD7h	DMA2SSZL	SSZ								252
3BD6h	DMA2SPTRU	—	—	SPTR						252
3BD5h	DMA2SPTRH	SPTR								251
3BD4h	DMA2SPTRL	SPTR								251
3BD3h	DMA2SCNTH	—	—	—	—	SCNT				253
3BD2h	DMA2SCNTL	SCNT								253
3BD1h	DMA2DSAH	DSA								254
3BD0h	DMA2DSAL	SSA								253
3BCFh	DMA2DSZH	—	—	—	—	DSZ				255
3BCEh	DMA2DSZL	DSZ								255
3BCDh	DMA2DPTRH	DPTR								254
3BCCCh	DMA2DPTRL	DPTR								254
3BCBh	DMA2DCNTH	—	—	—	—	DCNT				256
3BCAh	DMA2DCNTL	DCNT								255
3BC9h	DMA2BUF	BUF								250

**Legend:** x = unknown, u = unchanged, — = unimplemented, q = value depends on condition

- Note**
- 1: Unimplemented in LF devices.
  - 2: Unimplemented in PIC18(L)F26/27K42.
  - 3: Unimplemented on PIC18(L)F26/27/45/46/47K42 devices.
  - 4: Unimplemented in PIC18(L)F45/55K42.

## 43.6 MPLAB X SIM Software Simulator

The MPLAB X SIM Software Simulator allows code development in a PC-hosted environment by simulating the PIC MCUs and dsPIC DSCs on an instruction level. On any given instruction, the data areas can be examined or modified and stimuli can be applied from a comprehensive stimulus controller. Registers can be logged to files for further run-time analysis. The trace buffer and logic analyzer display extend the power of the simulator to record and track program execution, actions on I/O, most peripherals and internal registers.

The MPLAB X SIM Software Simulator fully supports symbolic debugging using the MPLAB XC Compilers, and the MPASM and MPLAB Assemblers. The software simulator offers the flexibility to develop and debug code outside of the hardware laboratory environment, making it an excellent, economical software development tool.

## 43.7 MPLAB REAL ICE In-Circuit Emulator System

The MPLAB REAL ICE In-Circuit Emulator System is Microchip's next generation high-speed emulator for Microchip Flash DSC and MCU devices. It debugs and programs all 8, 16 and 32-bit MCU, and DSC devices with the easy-to-use, powerful graphical user interface of the MPLAB X IDE.

The emulator is connected to the design engineer's PC using a high-speed USB 2.0 interface and is connected to the target with either a connector compatible with in-circuit debugger systems (RJ-11) or with the new high-speed, noise tolerant, Low-Voltage Differential Signal (LVDS) interconnection (CAT5).

The emulator is field upgradable through future firmware downloads in MPLAB X IDE. MPLAB REAL ICE offers significant advantages over competitive emulators including full-speed emulation, run-time variable watches, trace analysis, complex breakpoints, logic probes, a ruggedized probe interface and long (up to three meters) interconnection cables.

## 43.8 MPLAB ICD 3 In-Circuit Debugger System

The MPLAB ICD 3 In-Circuit Debugger System is Microchip's most cost-effective, high-speed hardware debugger/programmer for Microchip Flash DSC and MCU devices. It debugs and programs PIC Flash microcontrollers and dsPIC DSCs with the powerful, yet easy-to-use graphical user interface of the MPLAB IDE.

The MPLAB ICD 3 In-Circuit Debugger probe is connected to the design engineer's PC using a high-speed USB 2.0 interface and is connected to the target with a connector compatible with the MPLAB ICD 2 or MPLAB REAL ICE systems (RJ-11). MPLAB ICD 3 supports all MPLAB ICD 2 headers.

## 43.9 PICkit 3 In-Circuit Debugger/Programmer

The MPLAB PICkit 3 allows debugging and programming of PIC and dsPIC Flash microcontrollers at a most affordable price point using the powerful graphical user interface of the MPLAB IDE. The MPLAB PICkit 3 is connected to the design engineer's PC using a full-speed USB interface and can be connected to the target via a Microchip debug (RJ-11) connector (compatible with MPLAB ICD 3 and MPLAB REAL ICE). The connector uses two device I/O pins and the Reset line to implement in-circuit debugging and In-Circuit Serial Programming™ (ICSP™).

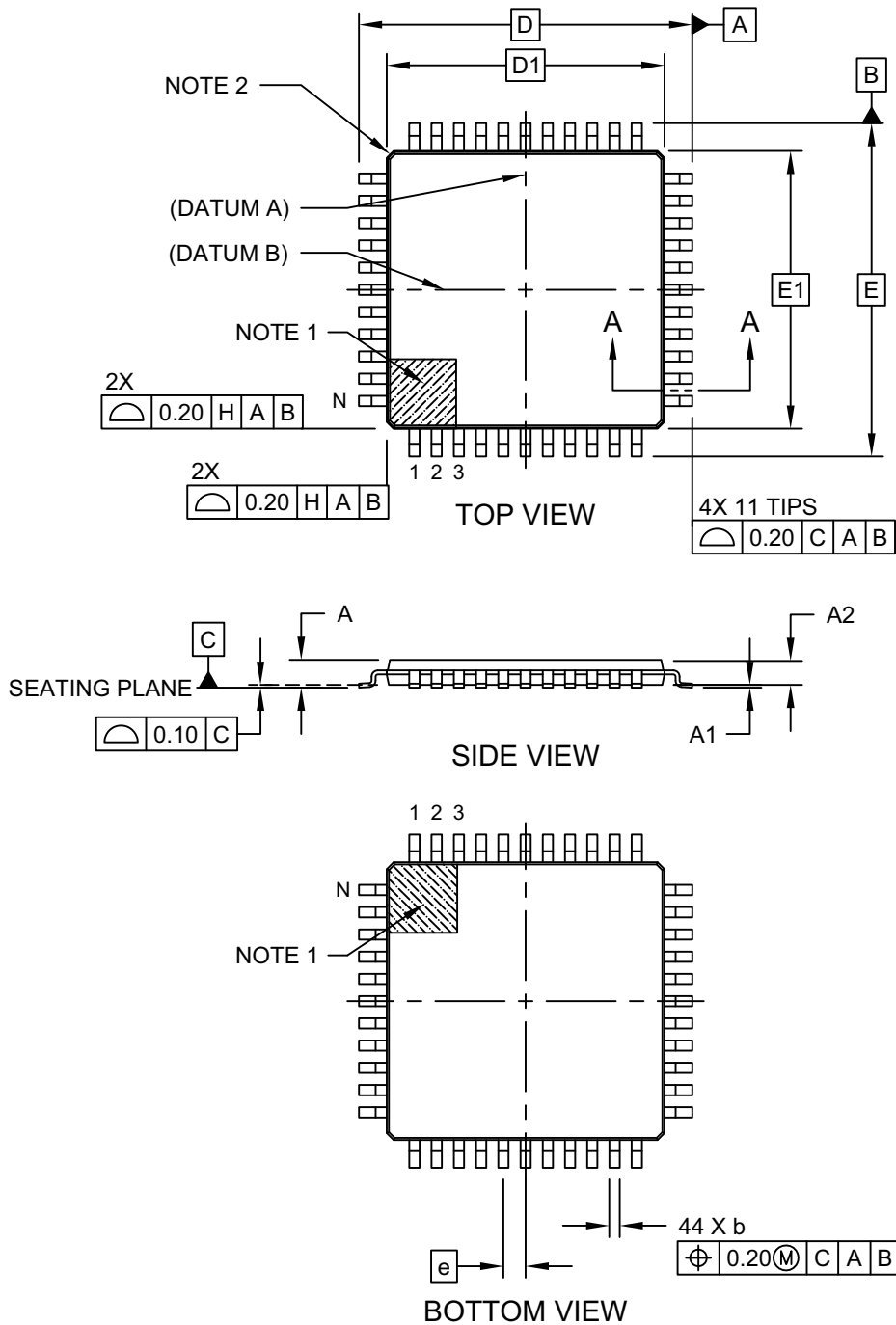
## 43.10 MPLAB PM3 Device Programmer

The MPLAB PM3 Device Programmer is a universal, CE compliant device programmer with programmable voltage verification at VDDMIN and VDDMAX for maximum reliability. It features a large LCD display (128 x 64) for menus and error messages, and a modular, detachable socket assembly to support various package types. The ICSP cable assembly is included as a standard item. In Stand-Alone mode, the MPLAB PM3 Device Programmer can read, verify and program PIC devices without a PC connection. It can also set code protection in this mode. The MPLAB PM3 connects to the host PC via an RS-232 or USB cable. The MPLAB PM3 has high-speed communications and optimized algorithms for quick programming of large memory devices, and incorporates an MMC card for file storage and data applications.

# PIC18(L)F26/27/45/46/47/55/56/57K42

## 44-Lead Plastic Thin Quad Flatpack (PT) - 10x10x1.0 mm Body [TQFP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Microchip Technology Drawing C04-076C Sheet 1 of 2