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### Applications of "[Embedded - Microcontrollers](#)"

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	64MHz
Connectivity	I <sup>2</sup> C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, LVD, POR, PWM, WDT
Number of I/O	44
Program Memory Size	64KB (32K x 16)
Program Memory Type	FLASH
EEPROM Size	1K x 8
RAM Size	4K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 43x12b; D/A 1x5b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	48-TQFP Exposed Pad
Supplier Device Package	48-TQFP-EP (7x7)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic18lf56k42-i-pt">https://www.e-xfl.com/product-detail/microchip-technology/pic18lf56k42-i-pt</a>

# PIC18(L)F26/27/45/46/47/55/56/57K42

## 9.2 Interrupt Vector Table (IVT)

The interrupt controller supports an Interrupt Vector Table (IVT) that contains the vector address location for each interrupt request source.

The Interrupt Vector Table (IVT) resides in program memory, starting at address location determined by the IVTBASE registers; refer to [Register 9-36](#), [Register 9-37](#) and [Register 9-38](#) for details. The IVT contains 68 vectors, one for each source of interrupt. Each interrupt vector location contains the starting address of the associated Interrupt Service Routine (ISR).

The MVECEN bit in Configuration Word 2L controls the availability of the vector table.

### 9.2.1 INTERRUPT VECTOR TABLE BASE ADDRESS (IVTBASE)

The start address of the vector table is user programmable through the IVTBASE registers. The user must ensure the start address is such that it can encompass the entire vector table inside the program memory.

Each vector address is a 16-bit word (or two address locations on PIC18 devices). So for  $n$  interrupt sources, there are  $2n$  address locations necessary to hold the table starting from IVTBASE as the first location. So the starting address of IVTBASE should be chosen such that the address range from IVTBASE to  $(IVTBASE + 2n - 1)$  can be encompassed inside the program flash memory.

For example, the K42 devices have the highest vector number: 81. So IVTBASE should be chosen such that  $(IVTBASE + 0xA1)$  is less than the last memory location in program flash memory.

A programmable vector table base address is useful in situations to switch between different sets of vector tables, depending on the application. It can also be used when the application program needs to update the existing vector table (vector address values).

**Note:** It is required that the user assign an even address to the IVTBASE register for correct operation.

### 9.2.2 INTERRUPT VECTOR TABLE CONTENTS

#### MVECEN = 0

When  $MVECEN = 0$ , the address location pointed by the IVTBASE registers has a `GOTO` instruction for a high priority interrupt. Similarly, the corresponding low priority vector location also has a `GOTO` instruction, which is executed in case of a low priority interrupt.

#### MVECEN = 1

When  $MVECEN = 1$ , the value in the vector table of each interrupt, points to the address location of the first instruction of the interrupt service routine.

ISR Location = Interrupt Vector Table entry  $\ll 2$ .

### 9.2.3 INTERRUPT VECTOR TABLE (IVT) ADDRESS CALCULATION

#### MVECEN = 0

When the  $MVECEN$  bit in Configuration Word 2L ([Register 5-3](#)) is cleared, the address pointed by IVTBASE registers is used as the high priority interrupt vector address. The low priority interrupt vector address is offset eight instruction words from the address in IVTBASE registers.

For PIC18 devices the IVTBASE registers default to 00 0008h, the high priority interrupt vector address will be 00 0008h and the low priority interrupt vector address will be 00 0018h.

#### MVECEN = 1

Each interrupt has a unique vector number associated with it as defined in [Table 9-2](#). This vector number is used for calculating the location of the interrupt vector for a particular interrupt source.

Interrupt Vector Address =  $IVTBASE + (2 * \text{Vector Number})$ .

This calculated Interrupt Vector Address value is stored in the IVTAD<20:0> registers when an interrupt is received ([Registers 9-39](#) through [9-41](#)).

User-assigned software priority assigned using the IPRx registers does not affect address calculation and is only used to resolve concurrent interrupts.

If for any reason the address of the ISR could not be fetched from the vector table, it will cause the system to reset and clear the memory execution violation flag (MEMV bit) in PCON1 register ([Register 6-3](#)). This occurs due to any one of the following:

- The entry for the interrupt in the vector table lies outside the executable PFM area (SAF area is non-executable when  $SAFEN = 1$ ).
- ISR pointed by the vector table lies outside the executable PFM area (SAF area is non-executable when  $SAFEN = 1$ ).

# PIC18(L)F26/27/45/46/47/55/56/57K42

**TABLE 9-1: IVT ADDRESS CALCULATION SUMMARY**

IVT Address Calculation		Interrupt Priority INTCON0 Register, IPEN bit	
		0	1
Multi-Vector Enable CONFIG 2L register MVECEN bit	0	IVTBASE	High Priority IVTBASE
			Low Priority IVTBASE + 8 words
	1	IVTBASE + 2*(Vector Number)	

## 9.2.4 ACCESS CONTROL FOR IVTBASE REGISTERS

The Interrupt controller has an IVTLOCKED bit which can be set to avoid inadvertent changes to the IVTBASE registers contents. Setting and clearing this bit requires a special sequence as an extra precaution against inadvertent changes.

To allow writes to IVTBASE registers, the interrupts must be disabled (GIEH = 0) and the IVTLOCKED bit must be cleared. The user must follow the sequence shown in [Example 9-1](#) to clear the IVTLOCKED bit.

### EXAMPLE 9-1: IVT UNLOCK SEQUENCE

```

; Disable Interrupts:
    BCF          INTCON0, GIE;
; Bank to IVTLOCK register
    BANKSEL     IVTLOCK;
    MOVLW      55h;

; Required sequence, next 4 instructions
    MOVWF      IVTLOCK;
    MOVLW     AAh;
    MOVWF      IVTLOCK;

; Clear IVTLOCKED bit to enable writes
    BCF          IVTLOCK, IVTLOCKED;

; Enable Interrupts
    BSF          INTCON0, GIE;
    
```

The user must follow the sequence shown in [Example 9-2](#) to set the IVTLOCKED bit.

### EXAMPLE 9-2: IVT LOCK SEQUENCE

```

; Disable Interrupts:
    BCF          INTCON0, GIE;
; Bank to IVTLOCK register
    BANKSEL     IVTLOCK;
    MOVLW      55h;

; Required sequence, next 4 instructions
    MOVWF      IVTLOCK;
    MOVLW     AAh;
    MOVWF      IVTLOCK;

; Set IVTLOCKED bit to enable writes
    BSF          IVTLOCK, IVTLOCKED;

; Enable Interrupts
    BSF          INTCON0, GIE;
    
```

When the IVT1WAY Configuration bit is set, the IVTLOCKED bit can be cleared and set only once after a device Reset. The unlock operation in [Example 9-1](#) will have no effect after the lock sequence in [Example 9-2](#) is used to set the IVTLOCK. Unlocking is inhibited until a system Reset occurs.

# PIC18(L)F26/27/45/46/47/55/56/57K42

## REGISTER 9-8: PIR5: PERIPHERAL INTERRUPT REGISTER 5<sup>(1)</sup>

R-0/0	R-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0
I2C2TXIF <sup>(2)</sup>	I2C2RXIF <sup>(2)</sup>	DMA2AIF	DMA2ORIF	DMA2DCNTIF	DMA2SCNTIF	C2IF	INT1IF <sup>(3)</sup>
bit 7							bit 0

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	HS = Bit is set in hardware

- bit 7      **I2C2TXIF:** I<sup>2</sup>C2 Transmit Interrupt Flag bit<sup>(2)</sup>  
 1 = Interrupt has occurred  
 0 = Interrupt event has not occurred
- bit 6      **I2C2RXIF:** I<sup>2</sup>C2 Receive Interrupt Flag bit<sup>(2)</sup>  
 1 = Interrupt has occurred  
 0 = Interrupt event has not occurred
- bit 5      **DMA2AIF:** DMA2 Abort Interrupt Flag bit  
 1 = Interrupt has occurred (must be cleared by software)  
 0 = Interrupt event has not occurred
- bit 4      **DMA2ORIF:** DMA2 Overrun Interrupt Flag bit  
 1 = Interrupt has occurred (must be cleared by software)  
 0 = Interrupt event has not occurred
- bit 3      **DMA2DCNTIF:** DMA2 Destination Count Interrupt Flag bit  
 1 = Interrupt has occurred (must be cleared by software)  
 0 = Interrupt event has not occurred
- bit 2      **DMA2SCNTIF:** DMA2 Source Count Interrupt Flag bit  
 1 = Interrupt has occurred (must be cleared by software)  
 0 = Interrupt event has not occurred
- bit 1      **C2IF:** C2 Interrupt Flag bit  
 1 = Interrupt has occurred (must be cleared by software)  
 0 = Interrupt event has not occurred
- bit 0      **INT1IF:** External Interrupt 1 Interrupt Flag bit<sup>(3)</sup>  
 1 = Interrupt has occurred (must be cleared by software)  
 0 = Interrupt event has not occurred

- Note 1:** Interrupt flag bits get set when an interrupt condition occurs, regardless of the state of its corresponding enable bit, or the global enable bit. User software should ensure the appropriate interrupt flag bits are clear prior to enabling an interrupt.
- 2:** I2CxTXIF and I2CxRXIF are read-only bits. To clear the interrupt condition, the CLRBF bit in I2CxSTAT1 register must be set.
- 3:** The external interrupt GPIO pin is selected by the INTxPPS register.

# PIC18(L)F26/27/45/46/47/55/56/57K42

**REGISTER 9-16: PIE2: PERIPHERAL INTERRUPT ENABLE REGISTER 2**

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
I2C1RXIE	SPI1IE	SPI1TXIE	SPI1RXIE	DMA1AIE	DMA1ORIE	DMA1DCNTIE	DMA1SCNTIE
bit 7							bit 0

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
u = Bit is unchanged                  x = Bit is unknown                  -n/n = Value at POR and BOR/Value at all other Resets  
'1' = Bit is set                            '0' = Bit is cleared

- bit 7            **I2C1RXIE:** I<sup>2</sup>C1 Receive Interrupt Enable bit  
                  1 = Enabled  
                  0 = Disabled
- bit 6            **SPI1IE:** SPI1 Interrupt Enable bit  
                  1 = Enabled  
                  0 = Disabled
- bit 5            **SPI1TXIE:** SPI1 Transmit Interrupt Enable bit  
                  1 = Enabled  
                  0 = Disabled
- bit 4            **SPI1RXIE:** SPI1 Receive Interrupt Enable bit  
                  1 = Enabled  
                  0 = Disabled
- bit 3            **DMA1AIE:** DMA1 Abort Interrupt Enable bit  
                  1 = Enabled  
                  0 = Disabled
- bit 2            **DMA1ORIE:** DMA1 Overrun Interrupt Enable bit  
                  1 = Enabled  
                  0 = Disabled
- bit 1            **DMA1DCNTIE:** DMA1 Destination Count Interrupt Enable bit  
                  1 = Enabled  
                  0 = Disabled
- bit 0            **DMA1SCNTIE:** DMA1 Source Count Interrupt Enable bit  
                  1 = Enabled  
                  0 = Disabled

# PIC18(L)F26/27/45/46/47/55/56/57K42

## REGISTER 9-19: PIE5: PERIPHERAL INTERRUPT ENABLE REGISTER 5

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
I2C2TXIE	I2C2RXIE	DMA2AIE	DMA2ORIE	DMA2DCNTIE	DMA2SCNTIE	C2IE	INT1IE
bit 7						bit 0	

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

- bit 7      **I2C2TXIE:** I<sup>2</sup>C2 Transmit Interrupt Enable bit  
           1 = Enabled  
           0 = Disabled
- bit 6      **I2C2RXIE:** I<sup>2</sup>C2 Receive Interrupt Enable bit  
           1 = Enabled  
           0 = Disabled
- bit 5      **DMA2AIE:** DMA2 Abort Interrupt Enable bit  
           1 = Enabled  
           0 = Disabled
- bit 4      **DMA2ORIE:** DMA2 Overrun Interrupt Enable bit  
           1 = Enabled  
           0 = Disabled
- bit 3      **DMA2DCNTIE:** DMA2 Destination Count Interrupt Enable bit  
           1 = Enabled  
           0 = Disabled
- bit 2      **DMA2SCNTIE:** DMA2 Source Count Interrupt Enable bit  
           1 = Enabled  
           0 = Disabled
- bit 1      **C2IE:** C2 Interrupt Enable bit  
           1 = Enabled  
           0 = Disabled
- bit 0      **INT1IE:** External Interrupt 1 Enable bit  
           1 = Enabled  
           0 = Disabled

# PIC18(L)F26/27/45/46/47/55/56/57K42

## REGISTER 13-2: NVMCON2: NONVOLATILE MEMORY CONTROL 2 REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NVMCON2<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
x = Bit is unknown                      '0' = Bit is cleared                      '1' = Bit is set  
-n = Value at POR

bit 7-0                      **NVMCON2<7:0>**:  
Refer to [Section 13.1.4 "NVM Unlock Sequence"](#).

**Note 1:** This register always reads zeros, regardless of data written.

## Register 13-3: NVMADRL: Data EEPROM Memory Address Low

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
ADR<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
x = Bit is unknown                      '0' = Bit is cleared                      '1' = Bit is set  
-n = Value at POR

bit 7-0                      **ADR<7:0>**: EEPROM Read Address bits

## REGISTER 13-4: NVMADRH: DATA EEPROM MEMORY ADDRESS HIGH<sup>(1)</sup>

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0/0	R/W-0/0
—	—	—	—	—	—	ADR<9:8>	
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
x = Bit is unknown                      '0' = Bit is cleared                      '1' = Bit is set  
-n = Value at POR

bit 7-2                      **Unimplemented:** Read as '0'  
bit 1-0                      **ADR<9:8>**: EEPROM Read Address bits

**Note 1:** The NVMADRH register is not implemented on PIC18(L)F45/55K42.

# PIC18(L)F26/27/45/46/47/55/56/57K42

## REGISTER 14-6: CRCACCL: CRC ACCUMULATOR LOW BYTE REGISTER

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
ACC<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
u = Bit is unchanged                  x = Bit is unknown                    -n/n = Value at POR and BOR/Value at all other Resets  
'1' = Bit is set                          '0' = Bit is cleared

bit 7-0                      **ACC<7:0>**: CRC Accumulator Register bits

## REGISTER 14-7: CRCSHIFTH: CRC SHIFT HIGH BYTE REGISTER

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
SHIFT<15:8>							
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
u = Bit is unchanged                  x = Bit is unknown                    -n/n = Value at POR and BOR/Value at all other Resets  
'1' = Bit is set                          '0' = Bit is cleared

bit 7-0                      **SHIFT<15:8>**: CRC Shifter Register bits  
Reading from this register reads the CRC Shifter.

## REGISTER 14-8: CRCSHIFTL: CRC SHIFT LOW BYTE REGISTER

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
SHIFT<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
u = Bit is unchanged                  x = Bit is unknown                    -n/n = Value at POR and BOR/Value at all other Resets  
'1' = Bit is set                          '0' = Bit is cleared

bit 7-0                      **SHIFT<7:0>**: CRC Shifter Register bits  
Reading from this register reads the CRC Shifter.



# PIC18(L)F26/27/45/46/47/55/56/57K42

**REGISTER 16-8: INLVLx: INPUT LEVEL CONTROL REGISTER**

R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1
INLVLx7	INLVLx6	INLVLx5	INLVLx4	INLVLx3	INLVLx2	INLVLx1	INLVLx0
bit 7							bit 0

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 '1' = Bit is set                          '0' = Bit is cleared                      x = Bit is unknown  
 -n/n = Value at POR and BOR/Value at all other Resets

bit 7-0                      **INLVLx<7:0>**: Input Level Select on Pins Rx<7:0>, respectively  
 1 = ST input used for port reads and interrupt-on-change  
 0 = TTL input used for port reads and interrupt-on-change

**TABLE 16-9: INPUT LEVEL PORT REGISTERS**

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
INLVLA	INLVLA7	INLVLA6	INLVLA5	INLVLA4	INLVLA3	INLVLA2	INLVLA1	INLVLA0
INVLVB	INVLVB7	INVLVB6	INVLVB5	INVLVB4	INVLVB3	INVLVB2 <sup>(1)</sup>	INVLVB1 <sup>(1)</sup>	INVLVB0
INLVLC	INLVLC7	INLVLC6	INLVLC5	INLVLC4 <sup>(1)</sup>	INLVLC3 <sup>(1)</sup>	INLVLC2	INLVLC1	INLVLC0
INLVLD <sup>(2)</sup>	INLVLD7	INLVLD6	INLVLD5	INLVLD4	INLVLD3	INLVLD2	INLVLD1 <sup>(1)</sup>	INLVLD0 <sup>(1)</sup>
INLVLE	—	—	—	—	INLVLE3	INLVLE2 <sup>(2)</sup>	INLVLE1 <sup>(2)</sup>	INLVLE0 <sup>(2)</sup>
INLVLF <sup>(3)</sup>	INLVLF7	INLVLF6	INLVLF5	INLVLF4	INLVLF3	INLVLF2	INLVLF1	INLVLF0

**Note 1:** Any peripheral using the I<sup>2</sup>C pins read the I<sup>2</sup>C ST inputs when enabled via RxyI2C.  
**Note 2:** Unimplemented in PIC18(L)F26/27K42.  
**Note 3:** Unimplemented in PIC18(L)F26/27/45/46/47K42.

## 17.0 PERIPHERAL PIN SELECT (PPS) MODULE

The Peripheral Pin Select (PPS) module connects peripheral inputs and outputs to the device I/O pins. Only digital signals are included in the selections. All analog inputs and outputs remain fixed to their assigned pins. Input and output selections are independent as shown in the simplified block diagram [Figure 17-1](#).

The peripheral input is selected with the peripheral xxxPPS register ([Register 17-1](#)), and the peripheral output is selected with the PORT RxyPPS register ([Register 17-2](#)). For example, to select PORTC<7> as the UART1 RX input, set U1RXPPS to 0b1 0111, and to select PORTC<6> as the UART1 TX output set RC6PPS to 0b01 0011.

### 17.1 PPS Inputs

Each peripheral has a PPS register with which the inputs to the peripheral are selected. Inputs include the device pins.

Multiple peripherals can operate from the same source simultaneously. Port reads always return the pin level regardless of peripheral PPS selection. If a pin also has analog functions associated, the ANSEL bit for that pin must be cleared to enable the digital input buffer.

Although every peripheral has its own PPS input selection register, the selections are identical for every peripheral as shown in [Register 17-1](#).

<b>Note:</b> The notation “xxx” in the register name is a place holder for the peripheral identifier. For example, INT0PPS.
---

### 17.2 PPS Outputs

Each I/O pin has a PPS register with which the pin output source is selected. With few exceptions, the port TRIS control associated with that pin retains control over the pin output driver. Peripherals that control the pin output driver as part of the peripheral operation will override the TRIS control as needed. These peripherals include:

- UART

Although every pin has its own PPS peripheral selection register, the selections are identical for every pin as shown in [Register 17-2](#).

<b>Note:</b> The notation “Rxy” is a place holder for the pin identifier. For example, RA0PPS.
--

# PIC18(L)F26/27/45/46/47/55/56/57K42

## 17.8 Register Definitions: PPS Input Selection

**REGISTER 17-1: xxxPPS: PERIPHERAL xxx INPUT SELECTION**

U-0	U-0	R/W-m/u <sup>(1,3)</sup>	R/W-m/u <sup>(1)</sup>	R/W-m/u <sup>(1)</sup>	R/W-m/u <sup>(1)</sup>	R/W-m/u <sup>(1)</sup>	R/W-m/u <sup>(1)</sup>
—	—	xxxPPS<5:0>					
bit 7							bit 0

**Legend:**

R = Readable bit	W = Writable bit	-n/n = Value at POR and BOR/Value at all other Resets
u = Bit is unchanged	x = Bit is unknown	q = value depends on peripheral
'1' = Bit is set	U = Unimplemented bit, read as '0'	m = value depends on default location for that input
'0' = Bit is cleared		

bit 7-6 **Unimplemented:** Read as '0'

bit 5-3 **xxxPPS<5:3>:** Peripheral xxx Input PORTx Pin Selection bits

See [Table 17-1](#) for the list of available ports and default pin locations.

101 = PORTF<sup>(2)</sup>

100 = PORTE<sup>(3)</sup>

011 = PORTD<sup>(3)</sup>

010 = PORTC

001 = PORTB

000 = PORTA

bit 2-0 **xxxPPS<2:0>:** Peripheral xxx Input PORTx Pin Selection bits

111 = Peripheral input is from PORTx Pin 7 (Rx7)

110 = Peripheral input is from PORTx Pin 6 (Rx6)

101 = Peripheral input is from PORTx Pin 5 (Rx5)

100 = Peripheral input is from PORTx Pin 4 (Rx4)

011 = Peripheral input is from PORTx Pin 3 (Rx3)

010 = Peripheral input is from PORTx Pin 2 (Rx2)

001 = Peripheral input is from PORTx Pin 1 (Rx1)

000 = Peripheral input is from PORTx Pin 0 (Rx0)

**Note 1:** The Reset value 'm' of this register is determined by device default locations for that input.

**2:** Reserved on PIC18LF26/27/45/46/57K42 parts.

**3:** Reserved on PIC18LF26/27K42 parts.

# PIC18(L)F26/27/45/46/47/55/56/57K42

**REGISTER 21-4: TxGATE: TIMERx GATE ISM REGISTER**

U-0	U-0	U-0	R/W-0/u	R/W-0/u	R/W-0/u	R/W-0/u	R/W-0/u
—	—	—	GSS<4:0>				
bit 7							bit 0

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      u = unchanged

bit 7-5                      **Unimplemented:** Read as '0'  
 bit 4-0                      **GSS<4:0>:** Timerx Gate Source Selection bits

GSS	Timer1	Timer3	Timer5
	Gate Source	Gate Source	Gate Source
11111-11011	Reserved	Reserved	Reserved
11010	CLC4_out	CLC4_out	CLC4_out
11001	CLC3_out	CLC3_out	CLC3_out
11000	CLC2_out	CLC2_out	CLC2_out
10111	CLC1_out	CLC1_out	CLC1_out
10110	ZCDOUT	ZCDOUT	ZCDOUT
10101	CMP2OUT	CMP2OUT	CMP2OUT
10100	CMP1OUT	CMP1OUT	CMP1OUT
10011	NCO1OUT	NCO1OUT	NCO1OUT
10010-10001	Reserved	Reserved	Reserved
10000	PWM8OUT	PWM8OUT	PWM8OUT
01111	PWM7OUT	PWM7OUT	PWM7OUT
01110	PWM6OUT	PWM6OUT	PWM6OUT
01101	PWM5OUT	PWM5OUT	PWM5OUT
01100	CCP4OUT	CCP4OUT	CCP4OUT
01011	CCP3OUT	CCP3OUT	CCP3OUT
01010	CCP2OUT	CCP2OUT	CCP2OUT
01001	CCP1OUT	CCP1OUT	CCP1OUT
01000	SMT1_match	SMT1_match	SMT1_match
00111	TMR6OUT (postscaled)	TMR6OUT (postscaled)	TMR6OUT (postscaled)
00110	TMR5 overflow	TMR5 overflow	Reserved
00101	TMR4OUT (postscaled)	TMR4OUT (postscaled)	TMR4OUT (postscaled)
00100	TMR3 overflow	Reserved	TMR3 overflow
00011	TMR2OUT (postscaled)	TMR2OUT (postscaled)	TMR2OUT (postscaled)
00010	Reserved	TMR1 overflow	TMR1 overflow
00001	TMR0 overflow	TMR0 overflow	TMR0 overflow
00000	Pin selected by T1GPPS	Pin selected by T3GPPS	Pin selected by T5GPPS

## 22.5 Operation Examples

Unless otherwise specified, the following notes apply to the following timing diagrams:

- Both the prescaler and postscaler are set to 1:1 (both the CKPS and OUTPS bits in the T2CON register are cleared).
- The diagrams illustrate any clock except FOSC/4 and show clock-sync delays of at least two full cycles for both ON and T2TMR\_ers. When using FOSC/4, the clock-sync delay is at least one instruction period for T2TMR\_ers; ON applies in the next instruction period.
- ON and T2TMR\_ers are somewhat generalized, and clock-sync delays may produce results that are slightly different than illustrated.
- The PWM Duty Cycle and PWM output are illustrated assuming that the timer is used for the PWM function of the CCP module as described in [Section 23.0 “Capture/Compare/PWM Module”](#) and [Section 24.0 “Pulse-Width Modulation \(PWM\)”](#). The signals are not a part of the T2TMR module.

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## 22.5.2 HARDWARE GATE MODE

The Hardware Gate modes operate the same as the Software Gate mode except the T2TMR\_ers external signal can also gate the timer. When used with the CCP the gating extends the PWM period. If the timer is stopped when the PWM output is high, then the duty cycle is also extended.

When MODE<4:0> = 00001, then the timer is stopped when the external signal is high. When MODE<4:0> = 00010, then the timer is stopped when the external signal is low.

Figure 22-5 illustrates the Hardware Gating mode for MODE<4:0> = 00001 in which a high input level starts the counter.

**FIGURE 22-5: HARDWARE GATE MODE TIMING DIAGRAM (MODE = 00001)**



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## 22.5.3 EDGE-TRIGGERED HARDWARE LIMIT MODE

In Hardware Limit mode the timer can be reset by the TMRx\_ers external signal before the timer reaches the period count. Three types of Resets are possible:

- Reset on rising or falling edge (MODE<4:0> = 00011)
- Reset on rising edge (MODE<4:0> = 0010)
- Reset on falling edge (MODE<4:0> = 00101)

When the timer is used in conjunction with the CCP in PWM mode then an early Reset shortens the period and restarts the PWM pulse after a two clock delay. Refer to [Figure 22-6](#).

**FIGURE 22-6: EDGE TRIGGERED HARDWARE LIMIT MODE TIMING DIAGRAM (MODE=00100)**



# PIC18(L)F26/27/45/46/47/55/56/57K42

## REGISTER 27-3: CLCxSEL0: GENERIC CLCx DATA 0 SELECT REGISTER

U-0	U-0	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u
—	—	D1S<5:0>					
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
u = Bit is unchanged                  x = Bit is unknown                      -n/n = Value at POR and BOR/Value at all other Resets  
'1' = Bit is set                          '0' = Bit is cleared

bit 7-6                      **Unimplemented:** Read as '0'  
bit 5-0                      **D1S<5:0>**: CLCx Data1 Input Selection bits  
See [Table 27-1](#).

## REGISTER 27-4: CLCxSEL1: GENERIC CLCx DATA 1 SELECT REGISTER

U-0	U-0	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u
—	—	D2S<5:0>					
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
u = Bit is unchanged                  x = Bit is unknown                      -n/n = Value at POR and BOR/Value at all other Resets  
'1' = Bit is set                          '0' = Bit is cleared

bit 7-6                      **Unimplemented:** Read as '0'  
bit 5-0                      **D2S<5:0>**: CLCx Data 2 Input Selection bits  
See [Table 27-1](#).

## REGISTER 27-5: CLCxSEL2: GENERIC CLCx DATA 2 SELECT REGISTER

U-0	U-0	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u
—	—	D3S<5:0>					
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
u = Bit is unchanged                  x = Bit is unknown                      -n/n = Value at POR and BOR/Value at all other Resets  
'1' = Bit is set                          '0' = Bit is cleared

bit 7-6                      **Unimplemented:** Read as '0'  
bit 5-0                      **D3S<5:0>**: CLCx Data 3 Input Selection bits  
See [Table 27-1](#).

## REGISTER 27-6: CLCxSEL3: GENERIC CLCx DATA 3 SELECT REGISTER

U-0	U-0	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u
—	—	D4S<5:0>					
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
u = Bit is unchanged                  x = Bit is unknown                      -n/n = Value at POR and BOR/Value at all other Resets  
'1' = Bit is set                          '0' = Bit is cleared

bit 7-6                      **Unimplemented:** Read as '0'  
bit 5-0                      **D4S<5:0>**: CLCx Data 4 Input Selection bits  
See [Table 27-1](#).



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## 32.6 Slave Mode

### 32.6.1 SLAVE MODE TRANSMIT OPTIONS

The SDO output of the SPI module in Slave mode is controlled by the TXR bit of SPIxCON2, the TRIS bit associated with the SDO pin, the Slave Select input, and the current state of the TXFIFO. This control is summarized in Table 32-2. In this table, TRISxn refers to the bit in the TRIS register corresponding to the pin that SDO has been assigned with PPS, TXR is the Transmit Data Required Control bit of SPIxCON2, SS is the state of the Slave Select input, and TXBE is the TXFIFO Buffer Empty bit of SPIxSTATUS.

#### 32.6.1.1 SDO Drive/Tri-state

The TRIS bit associated with the SDO pin controls whether the SDO pin will tri-state. When this TRIS bit is cleared, the pin will always be driving to a level, even when the SPI module is inactive. When the SPI module is inactive (either due to the master not clocking the SCK line or the SS being false), the SDO pin will be driven to the value of the LAT bit associated with the

SDO pin. When the SPI module is active, its output is determined by both TXR and whether there is data in the TXFIFO.

When the TRIS bit associated with the SDO pin is set, the pin will only have an output level driven to it when TXR = 1 and the slave select input is true. In all other cases, the pin will be tri-stated.

#### 32.6.1.2 SDO Output Data

The TXR bit controls the nature of the data that is transmitted in Slave mode. When TXR is set, transmitted data is taken from the TXFIFO. If the FIFO is empty, the most recently received data will be transmitted and the TXUIF flag will be set to indicate that a transmit FIFO underflow has occurred.

When TXR is cleared, the data will be taken from the TXFIFO, and the TXFIFO occupancy will not decrease. If the TXFIFO is empty, the most recently received data will be transmitted, and the TXUIF bit will not be set. However, if the TRIS bit associated with the SDO pin is set, clearing the TXR bit will cause the SPI module to not output any data to the SDO pin.

**TABLE 32-2: SLAVE MODE TRANSMIT**

TRISxn <sup>(1)</sup>	TXR	SS	TXBE	SDO State
0	0	FALSE	0	Drives state determined by LATxn(2)
0	0	FALSE	1	Drives state determined by LATxn(2)
0	0	TRUE	0	Outputs the oldest byte in the TXFIFO Does not remove data from the TXFIFO
0	0	TRUE	1	Outputs the most recently received byte
0	1	FALSE	0	Drives state determined by LATxn(2)
0	1	FALSE	1	Drives state determined by LATxn(2)
0	1	TRUE	0	Outputs the oldest byte in the TXFIFO Removes transmitted byte from the TXFIFO Decrements occupancy of TXFIFO
0	1	TRUE	1	Outputs the most recently received byte Sets the TXUIF bit of SPIxINTF
1	0	FALSE	0	Tri-stated
1	0	FALSE	1	Tri-stated
1	0	TRUE	0	Tri-stated
1	0	TRUE	1	Tri-stated
1	1	FALSE	0	Tri-stated
1	1	FALSE	1	Tri-stated
1	1	TRUE	0	Outputs the oldest byte in the TXFIFO Removes transmitted byte from the TXFIFO Decrements occupancy of TXFIFO
1	1	TRUE	1	Outputs the most recently received byte Sets the TXUIF bit of SPIxINTF

**Note 1:** TRISxn is the bit in the TRISx register corresponding to the pin that SDO has been assigned with PPS.

**Note 2:** LATxn is the bit in the LATx register corresponding to the pin that SDO has been assigned with PPS.

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**TABLE 32-3: SUMMARY OF REGISTERS ASSOCIATED WITH SPI**

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on page
SPIxINTF	SRMTIF	TCZIF	SOSIF	EOSIF	—	RXOIF	TXUIF	—	535
SPIxINTE	SRMTIE	TCZIE	SOSIE	EOSIE	—	RXOIE	TXUIE	—	536
SPIxTCNTH	—	—	—	—	—	TCNT10	TCNT9	TCNT8	537
SPIxTCNTL	TCNT7	TCNT6	TCNT5	TCNT4	TCNT3	TCNT2	TCNT1	TCNT0	536
SPIxTWIDTH	—	—	—	—	—	TWIDTH2	TWIDTH1	TWIDH0	537
SPIxBAUD	BAUD7	BAUD6	BAUD5	BAUD4	BAUD3	BAUD2	BAUD1	BAUD0	538
SPIxCON0	EN	—	—	—	—	LSBF	MST	BMODE	538
SPIxCON1	SMP	CKE	CKP	FST	—	SSP	SDIP	SDOP	539
SPIxCON2	BUSY	SSFLT	—	—	—	SSET	TXR	RXR	540
SPIxSTATUS	TXWE	—	TXBE	—	RXRE	CLRBF	—	RXBF	541
SPIxRXB	RXB7	RXB6	RXB5	RXB4	RXB3	RXB2	RXB1	RXB0	541
SPIxTXB	TXB7	TXB6	TXB5	TXB4	TXB3	TXB2	TXB1	TXB0	542
SPIxCLK	—	—	—	—	CLKSEL3	CLKSEL2	CLKSEL1	CLKSEL0	542

**Legend:** — = unimplemented, read as '0'. Shaded cells are unused by the SPI module.

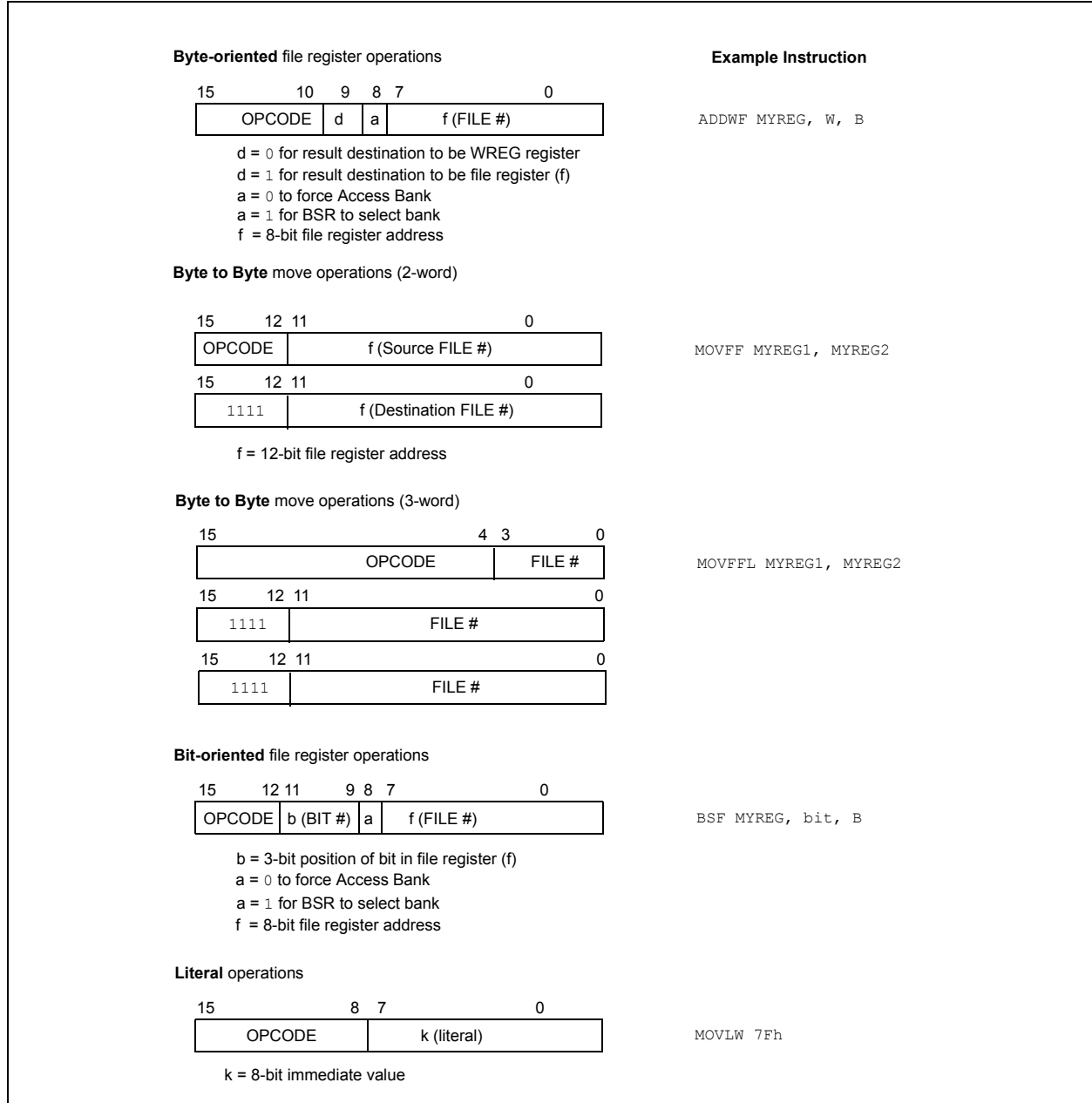


# PIC18(L)F26/27/45/46/47/55/56/57K42

**TABLE 41-1: OPCODE FIELD DESCRIPTIONS (CONTINUED)**

Field	Description
< >	Register bit field
∈	In the set of
<i>italics</i>	User defined term (font is courier)

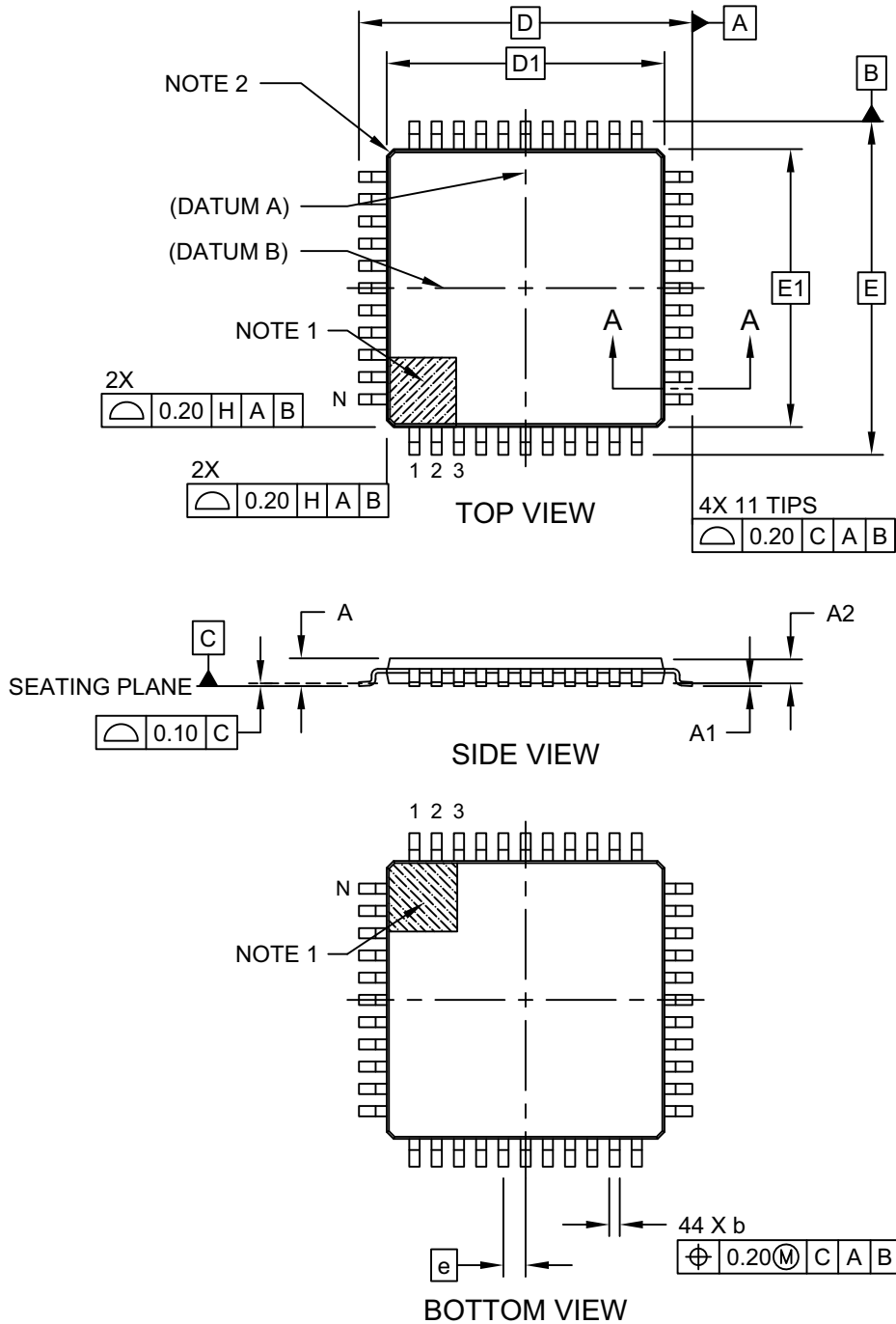
**FIGURE 41-1: General Format for Instructions (1/2)**



# PIC18(L)F26/27/45/46/47/55/56/57K42

## 44-Lead Plastic Thin Quad Flatpack (PT) - 10x10x1.0 mm Body [TQFP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



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