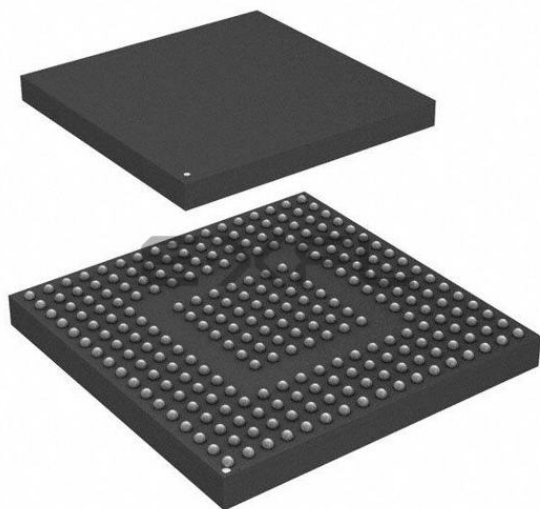




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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	e200z4
Core Size	32-Bit Dual-Core
Speed	200MHz
Connectivity	CANbus, Ethernet, FlexRay, LINbus, SPI, UART/USART
Peripherals	DMA, LVD, POR, WDT
Number of I/O	-
Program Memory Size	2.5MB (2.5M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	384K x 8
Voltage - Supply (Vcc/Vdd)	3.15V ~ 5.5V
Data Converters	A/D 64x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	257-LFBGA
Supplier Device Package	257-LFBGA (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/spc5744pk1ammm9

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1 Introduction

1.1 Features

The following table summarizes the features of the MPC5744P.

Table 1. MPC5744P feature summary

Feature	Details
CPU	
Power Architecture	2 x e200z4 in delayed lock step
Architecture	Harvard
Execution speed	0 MHz to 200 MHz (+2% FM)
Embedded FPU	Yes
Core MPU	24 regions
Instruction Set PPC	No
Instruction Set VLE	Yes
Instruction cache	8 KB, EDC
Data cache	4 KB, EDC
Data local memory	64 KB, ECC
System MPU	Yes (16 regions)
Buses	
Core bus	AHB, 32-bit address, 64-bit data, e2e ECC
Internal peripheral bus	32-bit address, 32-bit data
Crossbar	
Master x slave ports	4 x 5
Memory —see Table 2 for additional details	
Code/data flash memory	2.5 MB , ECC, RWW
Data flash memory	Supported with RWW
SRAM	384 KB , ECC
Overlay access to SRAM from Flash Memory Controller	Yes
Modules	
Interrupt controller	32 interrupt priority levels, 16 SW programmable interrupts
PIT	1 module with 4 channels
System Timer Module (STM)	1 module with 4 channels
Software Watchdog Timer (SWT)	Yes
eDMA	32 channels, in delayed lock step
FlexRay	1 module with 64 message buffer, dual channel
FlexCAN	3 modules with 64 message buffer
LINFlexD (UART and LIN with DMA support)	2 modules

Table continues on the next page...

2 Pinouts

2.1 Package pinouts and ballmap

The following figures show the LQFP pinout and the BGA ballmap.

--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--

Figure 2. 144LQFP pinout

Table 8. Pin muxing (continued)

Port Pin	SIUL2 MSCR/ IMCR Number	MSCR/ IMCR SSS Value ¹	Signal	Module	Short Signal Description	Dir	LQFP144	BGA257
	IMCR[73]	0001	ETC2	eTimer_2	eTimer_2 Input Data Channel 2	I		
	IMCR[179]	0001	REQ6	SIUL2	SIUL2 External Interrupt Source 6	I		
A[7]	MSCR[7]	0000 (Default)	GPIO[7]	SIUL2-GPIO[7]	General Purpose IO A[7]	I/O	10	G4
		0001	SOUT	DSPI1	DSPI 1 Serial Data Out	O		
		0010	ETC3	eTimer_2	eTimer_2 Input/Output Data Channel 3	I/O		
		0011-1111	—	Reserved	—	—		
	IMCR[74]	0001	ETC3	eTimer_2	eTimer_2 Input Data Channel 3	I		
	IMCR[180]	0001	REQ7	SIUL2	SIUL2 External Interrupt Source 7	I		
A[8]	MSCR[8]	0000 (Default)	GPIO[8]	SIUL2-GPIO[8]	General Purpose IO A[8]	I/O	12	H1
		0001	—	Reserved	—	—		
		0010	ETC4	eTimer_2	eTimer_2 Input/Output Data Channel 4	I/O		
		0011-1111	—	Reserved	—	—		
	IMCR[44]	0001	SIN	DSPI1	DSPI 1 Serial Data Input	I		
	IMCR[75]	0001	ETC4	eTimer_2	eTimer_2 Input Data Channel 4	I		
	IMCR[181]	0001	REQ8	SIUL2	SIUL2 External Interrupt Source 8	I		
A[9]	MSCR[9]	0000 (Default)	GPIO[9]	SIUL2-GPIO[9]	General Purpose IO A[9]	I/O	134	A4
		0001	CS1	DSPI2	DSPI 2 Peripheral Chip Select 1	O		
		0010	ETC5	eTimer_2	eTimer_2 Input/Output Data Channel 5	I/O		
		0011	B3	FlexPWM_0	FlexPWM_0 Channel B Input/Output 3	I/O		
		0100-1111	—	Reserved	—	—		
	IMCR[76]	0001	ETC5	eTimer_2	eTimer_2 Input Data Channel 5	I		
	IMCR[98]	0010	B3	FlexPWM_0	FlexPWM_0 Channel B Input 3	I		
	IMCR[83]	0001	FAULT0	FlexPWM_0	FlexPWM_0 Fault Input 0	I		
	IMCR[206]	0011	SENT_RX[1]	SENT_0	SENT 0 Receiver channel 1	I		
A[10]	MSCR[10]	0000 (Default)	GPIO[10]	SIUL2-GPIO[10]	General Purpose IO A[10]	I/O	118	B11
		0001	CS0	DSPI2	DSPI 2 Peripheral Chip Select 0	O		
		0010	B0	FlexPWM_0	FlexPWM_0 Channel B Input/Output 0	I/O		

Table continues on the next page...

Table 8. Pin muxing (continued)

Port Pin	SIUL2 MSCR/ IMCR Number	MSCR/ IMCR SSS Value ¹	Signal	Module	Short Signal Description	Dir	LQFP144	BGA257
		0100-1111	—	Reserved	—	—		
	IMCR[68]	0010	ETC3	eTimer_1	eTimer_1 Input Data Channel 3	I		
	IMCR[99]	0001	X3	FlexPWM_0	FlexPWM_0 Auxiliary Input 3	I		
	IMCR[137]	0001	FR_B_RX	FLEXRAY	FlexRay Channel B Receive Pin	I		
D[3]	MSCR[51]	0000 (Default)	GPIO[51]	SIUL2-GPIO[51]	General Purpose IO D[3]	I/O	128	A5
		0001	FR_B_TX	FLEXRAY	FlexRay Transmit Data Channel B	O		
		0010	ETC4	eTimer_1	eTimer_1 Input/Output Data Channel 4	I/O		
		0011	A3	FlexPWM_0	FlexPWM_0 Channel A Input/Output 3	I/O		
		0100-1111	—	Reserved	—	—		
	IMCR[69]	0010	ETC4	eTimer_1	eTimer_1 Input Data Channel 4	I		
	IMCR[97]	0011	A3	FlexPWM_0	FlexPWM_0 Channel A Input 3	I		
D[4]	MSCR[52]	0000 (Default)	GPIO[52]	SIUL2-GPIO[52]	General Purpose IO D[4]	I/O	129	B7
		0001	FR_B_TXEN	FLEXRAY	FlexRay Transmit Enable Channel B	O		
		0010	ETC5	eTimer_1	eTimer_1 Input/Output Data Channel 5	I/O		
		0011	B3	FlexPWM_0	FlexPWM_0 Channel B Input/Output 3	I/O		
		0100-1111	—	Reserved	—	—		
	IMCR[70]	0011	ETC5	eTimer_1	eTimer_1 Input Data Channel 5	I		
	IMCR[98]	0011	B3	FlexPWM_0	FlexPWM_0 Channel B Input 3	I		
D[5]	MSCR[53]	0000 (Default)	GPIO[53]	SIUL2-GPIO[53]	General Purpose IO D[5]	I/O	33	M4
		0001	CS3	DSPI0	DSPI 0 Peripheral Chip Select 3	O		
		0010	—	Reserved	—	—		
		0100	SOUT	DSPI3	DSPI 3 Serial Data Out	O		
		0101-1111	—	Reserved	—	—		
	IMCR[85]	0001	FAULT2	FlexPWM_0	FlexPWM_0 Fault Input 2	I		
	IMCR[205]	0001	SENT_RX[0]	SENT0	SENT 0 Receiver channel 0	I		
	IMCR[227]	0001	RX_D1	ENET_0	Ethernet MII/RMII receive data 1	I		
D[6]	MSCR[54]	0000 (Default)	GPIO[54]	SIUL2-GPIO[54]	General Purpose IO D[6]	I/O	34	P3

Table continues on the next page...

Table 8. Pin muxing (continued)

Port Pin	SIUL2 MSCR/ IMCR Number	MSCR/ IMCR SSS Value ¹	Signal	Module	Short Signal Description	Dir	LQFP144	BGA257
		0010	CS5	DSPI0	DSPI 0 Peripheral Chip Select 5	O		
		0011-1111	—	Reserved	—	—		
	IMCR[72]	0010	ETC1	eTimer_2	eTimer_2 Input Data Channel 1	I		
	IMCR[101]	0001	FAULT1	FlexPWM_1	FlexPWM_1 Fault Input 1	I		
	IMCR[232]	0001	RX_ER	ENET_0	Ethernet Receive Data Error	I		
I[2]	MSCR[130]	0000 (Default)	GPIO[130]	SIUL2-GPIO[130]	General Purpose IO I[2]	I/O		D11
		0001	ETC2	eTimer_2	eTimer_2 Input/Output Data Channel 2	I/O		
		0010	CS6	DSPI0	DSPI 0 Peripheral Chip Select 6	O		
		0011-1111	—	Reserved	—	—		
		IMCR[73]	0011	ETC2	eTimer_2 Input Data Channel 2	I		
		IMCR[102]	0001	FAULT2	FlexPWM_1 Fault Input 2	I		
I[3]	MSCR[131]	0000 (Default)	GPIO[131]	SIUL2-GPIO[131]	General Purpose IO I[3]	I/O		A10
		0001	ETC3	eTimer_2	eTimer_2 Input/Output Data Channel 3	I/O		
		0010	CS7	DSPI0	DSPI 0 Peripheral Chip Select 7	O		
		0011	EXT_TGR	CTU_0	CTU0 External Trigger Output	O		
		0100	TIMER0	ENET_0	Ethernet TIMER Outputs 0 (Output Compare Events)	O		
		0101-1111	—	Reserved	—	—		
		IMCR[74]	0011	ETC3	eTimer_2 Input Data Channel 3	I		
		IMCR[103]	0001	FAULT3	FlexPWM_1 Fault Input 3	I		
RDY_B/I[4]	MSCR[132]	0000 (Default)	GPIO[132]	SIUL2-GPIO[132]	General Purpose IO I[4]	I/O		J2
		0001	—	Reserved	—	—		
		0010	NEX_RDY_B	NPC_WRAPPER	Nexus data ready for transfer (RDY_B)	O		
		0011-1111	—	Reserved	—	—		
I[5] ⁵	MSCR[133]	0000 (Default)	GPIO[133]	SIUL2-GPIO[133]	General Purpose IO I[5] ¹⁰	I/O		N15
		0001	TXD	CAN2	CAN 2 Transmit Pin	O		
		0010	—	Reserved	—	—		
		0011	LFAST_TXN	LFAST	SIPI/LFAST LVDS transmit negative terminal	O		
		0100-1111	—	Reserved	—	—		

Table continues on the next page...

Table 10. Peripheral muxing (continued)

Destination peripheral	Destination functions	IMCR number	IMCR[SSS] field value	Source peripherals	Source functions
			0100-1111	—	Reserved
FlexPWM_0	X2	IMCR[96]	0000 (Default)	—	Disable
			0001	I/O-Pad	A[10]
			0010	I/O-Pad	G[2]
			0011-1111	—	Reserved
FlexPWM_0	A3	IMCR[97]	0000 (Default)	—	Disable
			0001	I/O-Pad	A[2]
			0010	I/O-Pad	C[10]
			0011	I/O-Pad	D[3]
			0100	I/O-Pad	G[6]
			0101-1111	—	Reserved
FlexPWM_0	B3	IMCR[98]	0000 (Default)	—	Disable
			0001	I/O-Pad	A[3]
			0010	I/O-Pad	A[9]
			0011	I/O-Pad	D[4]
			0100	I/O-Pad	G[7]
			0101-1111	—	Reserved
FlexPWM_0	X3	IMCR[99]	0000 (Default)	—	Disable
			0001	I/O-Pad	D[2]
			0010	I/O-Pad	D[6]
			0011	I/O-Pad	G[5]
			0100-1111	—	Reserved
FlexPWM_1	FAULT0	IMCR[100]	0000 (Default)	—	Disable
			0001	I/O-Pad	I[0]
			0010-1111	—	Reserved
FlexPWM_1	FAULT1	IMCR[101]	0000 (Default)	—	Disable
			0001	I/O-Pad	I[1]
			0010-1111	—	Reserved
FlexPWM_1	FAULT2	IMCR[102]	0000 (Default)	—	Disable
			0001	I/O-Pad	I[2]
			0010-1111	—	Reserved
FlexPWM_1	FAULT3	IMCR[103]	0000 (Default)	—	Disable
			0001	I/O-Pad	I[3]
			0010-1111	—	Reserved
FlexPWM_1	A0	IMCR[105]	0000 (Default)	—	Disable
			0001	I/O-Pad	C[13]
			0010	I/O-Pad	H[5]
			0011-1111	—	Reserved
FlexPWM_1	B0	IMCR[106]	0000 (Default)	—	Disable

Table continues on the next page...

- Absolute maximum supply: $V_{DD_HV_ADREx} = 6.0\text{ V}$ (10 hours, device in reset—no switching)
- Absolute maximum supply: $V_{DD_HV_ADREx} = 5.5\text{ V}$ (always)
- Absolute maximum ADC input pin voltage = 7.0 V (60 seconds lifetime), when V_{DD_HV} is connected to the 5 V
- Absolute maximum ADC input pin voltage = 6.5 V (always while respecting 5 mA maximum injection), when V_{DD_HV} is connected to the 5 V

3.4 Recommended operating conditions

NOTE

Full functionality cannot be guaranteed when voltage drops below 3.0 V . In particular, ADC electrical characteristics and DC electrical specifications for I/Os might not be guaranteed.

Table 13. Recommended operating conditions ($V_{DD_HV_xx} = 3.3\text{ V}$)

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{DD_HV_PMU}^1$	3.3 V voltage regulator supply voltage	—	3.15	3.6	V
$V_{DD_HV_IO}^2$	3.3 V input/output supply voltage	—	3.15	3.6	V
$V_{SS_HV_IO}$	Input/output ground voltage	—	0	0	V
$V_{DD_HV_FLA}^3$	3.3 V flash supply voltage	—	3.15	3.6	V
$V_{SS_HV_FLA}$	Flash memory ground	—	0	0	V
$V_{DD_HV_OSC}^4$	3.3 V crystal oscillator amplifier supply voltage	—	3.15	3.6	V
$V_{SS_HV_OSC}$	3.3 V crystal oscillator amplifier ground	—	0	0	V
$V_{DD_HV_ADRE0}$ $V_{DD_HV_ADRE1}$	3.3 V / 5.0 V ADC_0 high reference voltage 3.3 V / 5.0 V ADC_1 high reference voltage	$T_J \leq 150^\circ\text{C}$	3.15 to 5.5		V
$V_{DD_HV_ADRE0}^5$ $V_{DD_HV_ADRE1}$	3.3 V / 5.0 V ADC_0 high reference voltage 3.3 V / 5.0 V ADC_1 high reference voltage	$150^\circ\text{C} < T_J < 165^\circ\text{C}$ (only for corresponding marked parts)	3.15 to 5.25		V
$V_{SS_HV_ADRE0}^5$ $V_{SS_HV_ADRE1}$	ADC_0 ground and low reference voltage ADC_1 ground and low reference voltage	—	0	0	V
$V_{DD_HV_ADV}^6$	3.3 V ADC supply voltage	—	3.15	3.6	V
$V_{SS_HV_ADV}$	3.3 V ADC supply ground	—	0	0	V
$V_{DD_LV_COR}^7$	Core supply, $1.25\text{ V} \pm 5\%$	—	1.19	1.32	V
$V_{DD_LV_CORx}$	Internal supply voltage	—	—	—	V
$V_{SS_LV_CORx}$	Internal reference voltage	—	0	0	V
$V_{DD_LV_PLL}$	Internal PLL supply voltage	—	1.19	1.32	V
$V_{SS_LV_PLL}$	Internal PLL reference voltage	—	0	0	V
$V_{DD_LV_NEXUS}$	Aurora LVDS supply voltage	—	1.19	1.32	V
$V_{SS_LV_NEXUS}$	Aurora LVDS supply ground	—	0	0	V
$V_{DD_LV_LFAST}$	LFAST PLL supply voltage	—	1.19	1.32	V
$V_{SS_LV_LFAST}$	LFAST PLL supply ground	—	0	0	V
I_{IC}	DC injection current per pin ^{8, 9, 10}	Digital pins	-3.0	3.0	mA
		Analog pins	-3.0	3.0	

Table continues on the next page...

Table 13. Recommended operating conditions ($V_{DD_HV_xx} = 3.3\text{ V}$) (continued)

Symbol	Parameter	Conditions	Min	Max	Unit
		Shared analog pins	-3.6	3.6	
T_A	Ambient temperature under bias	$f_{CPU} \leq 200\text{MHz}$	-40	135 ¹¹	°C
T_J	Junction temperature under bias	—	-40	165 ^{12, 13}	°C

1. The chip functions down to the point where LVD_PMC resets the chip. When the voltage drops below LVD_PMC, the chip resets.
2. The chip functions down to the point where LVD_IO resets the chip. When the voltage drops below LVD_IO, the chip resets.
3. The chip functions down to the point where LVD_FLASH resets the chip. When the voltage drops below LVD_FLASH, the chip resets.
4. The chip functions down to the point where LVD_OSC resets the chip. When the voltage drops below LVD_OSC, the chip resets.
5. $V_{DD_HV_ADRE0}$ and $V_{DD_HV_ADRE1}$ cannot be operated at different voltages and need to be supplied by the same voltage source.
6. The chip functions down to the point where LVD_ADC resets the chip. When the voltage drops below LVD_ADC, the chip resets.
7. The chip functions down to the point where LVD_CORE or up to the point where HVD_CORE resets the chip by default.
8. I/O and analog input specifications are valid only if the injection current on adjacent pins is within these limits. See the absolute maximum ratings table for maximum input current for reliability requirements.
9. Full device lifetime without performance degradation.
10. The I/O pins on the device are clamped to the I/O supply rails for ESD protection. When the voltage of the input pin is above the supply rail, current will be injected through the clamp diode to the supply rail. For external RC network calculation, assume typical 0.3 V drop across the active diode. The diode voltage drop varies with temperature.
11. For a maximum T_J of 150°C, the corresponding maximum T_A is 125°C.
12. Some orderable parts have a maximum T_J value of 150°C. See the device marking for the applicable temperature range.
13. For devices supporting the 165°C junction temperature option: Operation at 150°C < T_J < 165°C is allowed for a maximum cumulative time of 200 hours over the device lifetime.

3.5 Thermal characteristics

Table 14. Thermal characteristics for 144LQFP and 257MAPBGA packages

Symbol	Parameter	Conditions	144LQFP	257MAPBGA	Unit
$R_{\theta JA}$	Thermal resistance, junction-to-ambient natural convection ²	Single layer board - 1s	39	45	°C/W
		Four layer board - 2s2p	31	25	
$R_{\theta JMA}$	Thermal resistance, junction-to-ambient forced convection at 200 ft/min ¹	Single layer board - 1s ³	31	36	°C/W
		Four layer board - 2s2p ⁴	25	21	
$R_{\theta JB}$	Thermal resistance junction-to-board ⁵	—	18	13	°C/W
$R_{\theta JC}$	Thermal resistance junction-to-case ⁶	—	8	8	°C/W
Ψ_{JT}	Junction-to-package-top natural convection ⁷	—	2	2	°C/W

1. Junction temperature is a function of die size, on-chip power dissipation, package thermal resistance, mounting site (board) temperature, ambient temperature, air flow, power dissipation of other components on the board, and board thermal resistance.
2. Junction-to-Ambient thermal resistance determined per JEDEC JESD51-3 and JESD51-6. Thermal test board meets JEDEC specification for this package.
3. Per JEDEC JESD51-2 with the single layer board horizontal. Board meets JESD51-9 specification.
4. Per JEDEC JESD51-6 with the board horizontal.

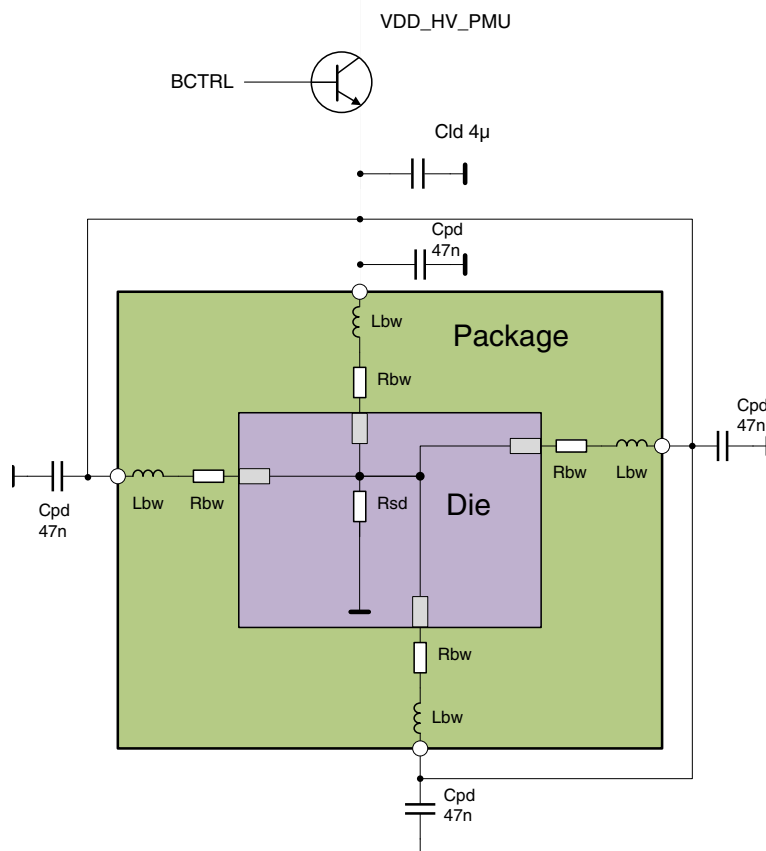


Figure 4. Core supply decoupling and parasitics

3.9 DC electrical characteristics

The following tables provide DC characteristics for bidirectional pads:

- [Table 18](#) provides output driver characteristics FlexRay I/Os (SYM).
- [Table 19](#) provides output driver characteristics for LFAST I/Os.

NOTE

See the FlexRay section for parameters dedicated to this interface.

Table 18. FlexRay (SYM) configuration output buffer electrical characteristics

Symbol	Parameter	Conditions ¹	Value			Unit
			Min	Typ	Max	
R _{OH_Y}	PMOS output impedance SYM configuration	Push Pull, I _{OH} = 2 mA, V _{OH} = V _{DD_HV_IO} - (0.28...0.52V)	35	50	65	Ω
R _{OL_Y}	PMOS output impedance SYM configuration	Push Pull, I _{OL} = 2 mA, V _{OL} = 0.28...0.52 V	35	50	65	Ω

Table continues on the next page...

3.15.1 Input equivalent circuit and ADC conversion characteristics

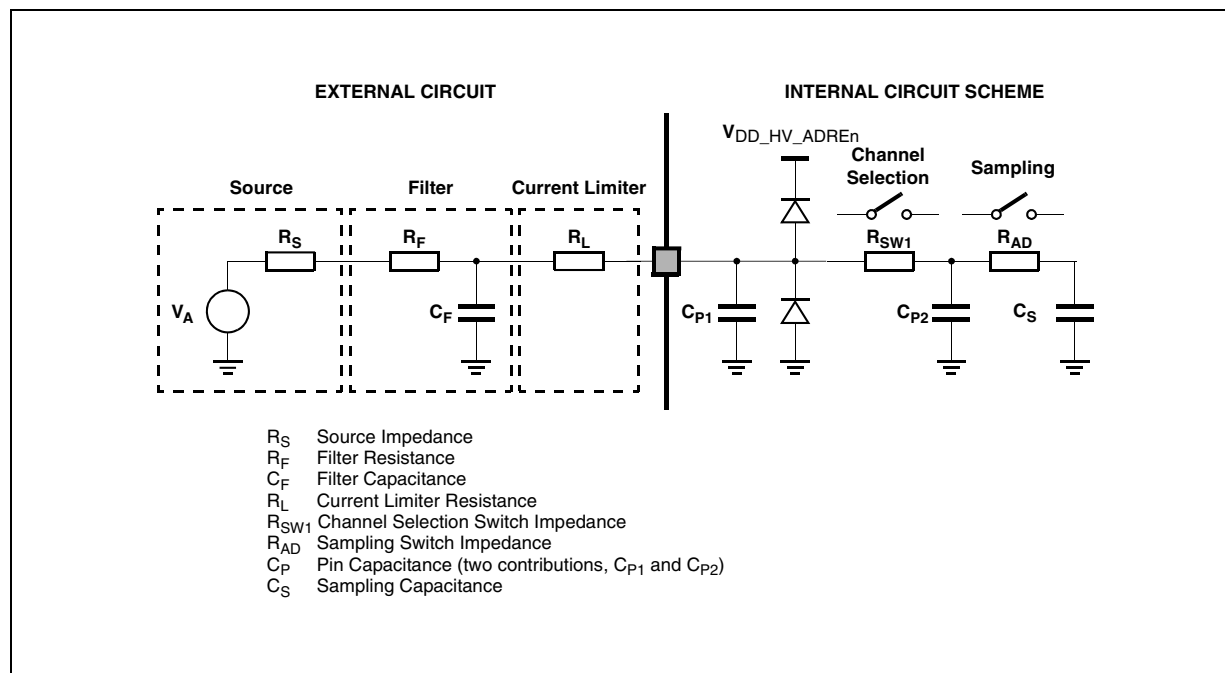


Figure 8. Input equivalent circuit

NOTE

Unless noted otherwise, the specifications in [Table 27](#) assume the use of 12-bit resolution (high accuracy, recommended): In ADC_CALBISTREG, set OPMODE to 110b.

Table 27. ADC conversion characteristics

Symbol	Parameter	Conditions ¹	Min	Typ	Max	Unit
f_{CK}	ADC Clock frequency (depends on ADC configuration) (The duty cycle depends on AD_CK ² frequency.)	—	20	—	80	MHz
f_s	Sampling frequency	—	—	—	1.00	MHz
t_{sample}	Sample time ³	80 MHz, 12-bit resolution	250	—	—	ns
		80 MHz, 12-bit resolution (high accuracy, recommended)	250	—	—	
t_{conv}	Conversion time ⁴	80 MHz, 12-bit resolution	650	—	—	ns
		80 MHz, 12-bit resolution (high accuracy, recommended)	700	—	—	
C_S	ADC input sampling capacitance	—	—	3	5	pF
C_{P1} ⁵	ADC input pin capacitance 1	—	—	—	5 ⁶	pF

Table continues on the next page...

Table 27. ADC conversion characteristics (continued)

Symbol	Parameter	Conditions ¹	Min	Typ	Max	Unit
C _{P2} ⁵	ADC input pin capacitance 2	—	—	—	0.8	pF
R _{SW1} ⁵	Internal resistance of analog source	V _{REF} range = 4.5 to 5.5 V	—	—	0.3	kΩ
		V _{REF} range = 3.15 to 3.6 V	—	—	875	Ω
R _{AD} ⁵	Internal resistance of analog source	—	—	—	825	Ω
INL	Integral non-linearity	—	−2	—	2	LSB
DNL	Differential non-linearity	—	−1	—	1	LSB
OFS	Offset error	—	−4	—	4	LSB
GNE	Gain error	—	−4	—	4	LSB
Input (single ADC channel)	Max leakage	150 °C	—	—	250	nA
	Max positive/negative injection	—	−3	—	3	mA
Input (double ADC channel)	Max leakage	150 °C	—	—	300	nA
	Max positive/negative injection	V _{REF_AD0} - V _{REF_AD1} < 150mV	−3.6	—	3.6	mA
SNR	Signal-to-noise ratio	V _{REF} = 3.3 V, Fin < 125kHz	67	—	—	dB
SNR ⁷	Signal-to-noise ratio	V _{REF} = 5.0 V, Fin < 125kHz	69	—	—	dB
THD	Total harmonic distortion	Fin ≤ 125 kHz	65	70	—	dB
ENOB	Effective number of bits	Fin < 125 kHz	10.5	—	—	bits
SINAD	Signal-to-noise and distortion	See ENOB	(6.02 * ENOB) + 1.76			dB
TUE _{IS1WINJ}	Total unadjusted error for IS1WINJ (single ADC channels)	Without current injection	−6	—	6	LSB
TUE _{IS1WINJ}	Total unadjusted error for IS1WINJ (single ADC channels)	Current injection: ±3 mA for each channel, max 3 channels	−8	—	8	LSB

1. V_{DD_HV_IO} = 3.3 V -5%,+10%, T_J = −40 to +165 °C, unless otherwise specified, and analog input voltage from V_{AGND} to V_{AREF}
2. AD_CK clock is always half of the ADC module input clock defined via the auxiliary clock divider for the ADC.
3. During the sample time the input capacitance C_S can be charged/discharged by the external source. The internal resistance of the analog source must allow the capacitance to reach its final voltage level within t_{sample}. After the end of the sample time t_{sample}, changes of the analog input voltage have no effect on the conversion result. Values for the sample clock t_{sample} depend on programming.
4. This parameter does not include the sample time t_{sample}, but only the time for determining the digital result and the time to load the result register with the conversion result.
5. See Figure 2.
6. For the 144-pin package.
7. Test conditions have an influence on the achieved performance. Please contact FSL personnel to share the conditions for these results.

NOTE

The ADC performance specifications are not guaranteed if two ADCs simultaneously sample the same shared channel.

3.16.1.2 Flash memory Array Integrity and Margin Read specifications

Table 29. Flash memory Array Integrity and Margin Read specifications

Symbol	Characteristic	Min	Typical	Max ¹	Units ²
$t_{ai16kseq}$	Array Integrity time for sequential sequence on 16 KB block.	—	—	$512 \times T_{period} \times N_{read}$	—
$t_{ai32kseq}$	Array Integrity time for sequential sequence on 32 KB block.	—	—	$1024 \times T_{period} \times N_{read}$	—
$t_{ai64kseq}$	Array Integrity time for sequential sequence on 64 KB block.	—	—	$2048 \times T_{period} \times N_{read}$	—
$t_{ai256kseq}$	Array Integrity time for sequential sequence on 256 KB block.	—	—	$8192 \times T_{period} \times N_{read}$	—
$t_{mr16kseq}$	Margin Read time for sequential sequence on 16 KB block.	73.81	—	110.7	μs
$t_{mr32kseq}$	Margin Read time for sequential sequence on 32 KB block.	128.43	—	192.6	μs
$t_{mr64kseq}$	Margin Read time for sequential sequence on 64 KB block.	237.65	—	356.5	μs
$t_{mr256kseq}$	Margin Read time for sequential sequence on 256 KB block.	893.01	—	1,339.5	μs

1. Array Integrity times need to be calculated and is dependent on system frequency and number of clocks per read. The equation presented require T_{period} (which is the unit accurate period, thus for 200 MHz, T_{period} would equal $5e-9$) and N_{read} (which is the number of clocks required for read, including pipeline contribution. Thus for a read setup that requires 6 clocks to read with no pipeline, N_{read} would equal 6. For a read setup that requires 6 clocks to read, and has the address pipeline set to 2, N_{read} would equal 4 (or $6 - 2$).)
2. The units for Array Integrity are determined by the period of the system clock. If unit accurate period is used in the equation, the results of the equation are also unit accurate.

3.16.1.3 Flash memory module life specifications

Table 30. Flash memory module life specifications

Symbol	Characteristic	Conditions	Min	Typical	Units
Array P/E cycles	Number of program/erase cycles per block for 16 KB, 32 KB and 64 KB blocks. ¹	—	250,000	—	P/E cycles
	Number of program/erase cycles per block for 256 KB blocks. ²	—	1,000	250,000	P/E cycles
Data retention	Minimum data retention.	Blocks with 0 - 1,000 P/E cycles.	50	—	Years
		Blocks with 100,000 P/E cycles.	20	—	Years
		Blocks with 250,000 P/E cycles.	10	—	Years

1. Program and erase supported across standard temperature specs.
2. Program and erase supported across standard temperature specs.

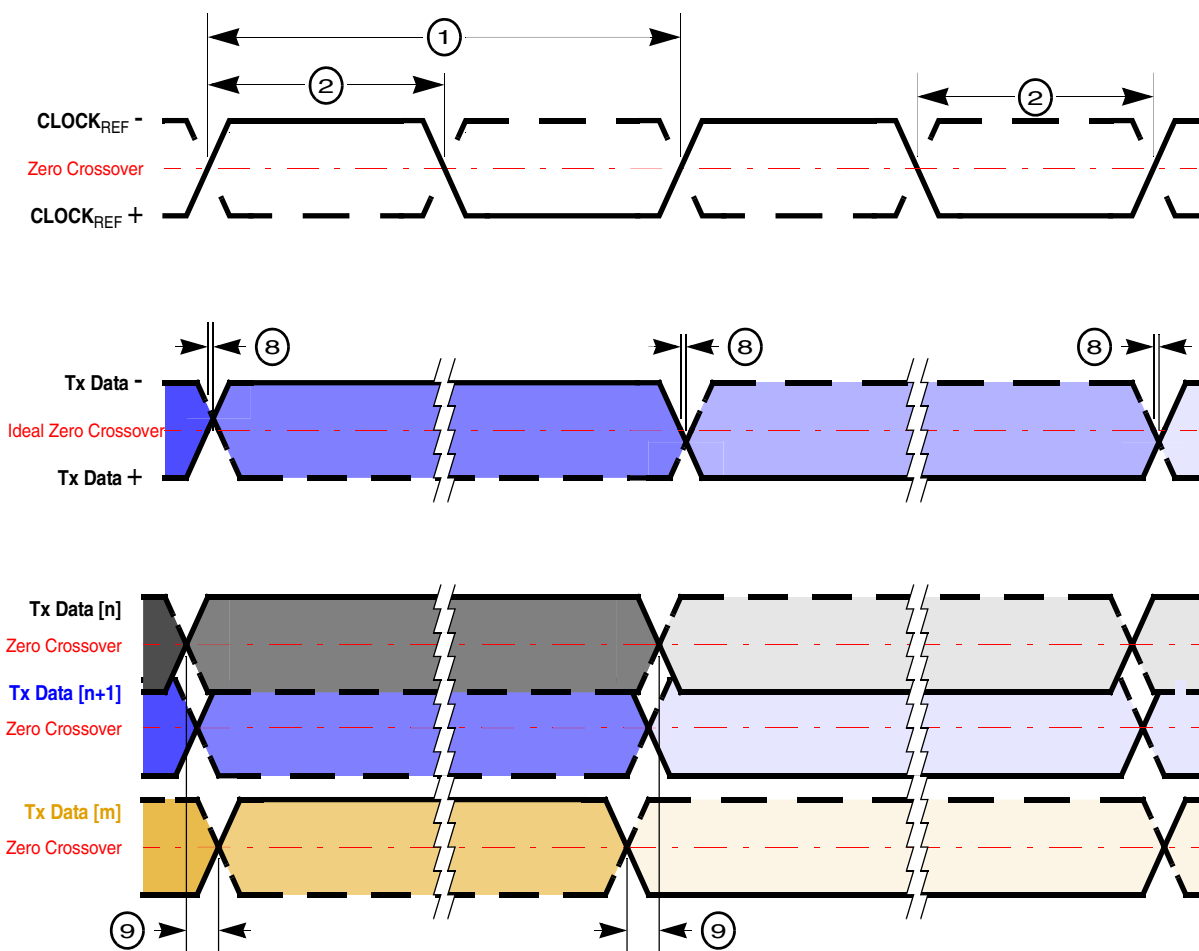


Figure 18. Nexus Aurora timings

Rise/fall timing for the Nexus Aurora debug port reference clock must conform to the area between the minimum and maximum value ranges shown in the following receiver "eye" diagram.

Table 48. SPI timing (continued)

#	Symbol	Parameter	Conditions	Min	Max	Unit
			Master (MTFE = 1, CPHA = 0)	-4	—	
			Master (MTFE = 1, CPHA = 1)	-4	—	

1. Slave Receive Only Mode can operate at a maximum frequency of 60 MHz. In this mode, the SPI can receive data on SIN, but no valid data is transmitted on SOUT.
2. P is the number of clock cycles added to delay the SPI input sample point and is software programmable.
3. t_{SYS} is the period of the DSPI_CLKn clock, the input clock to the SPI module. Maximum frequency is 50 MHz (min t_{SYS} = 20 ns).

NOTE

For numbers shown in the following figures, see [Table 48](#).

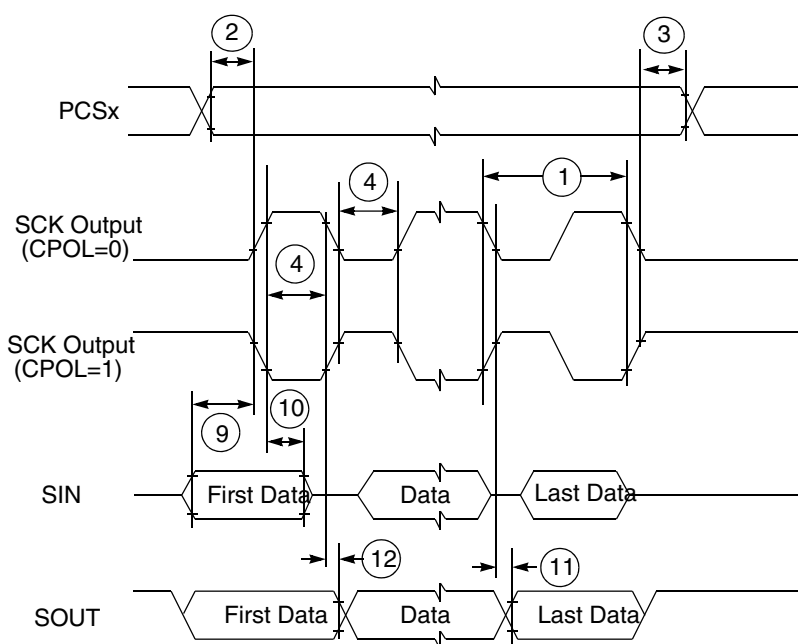
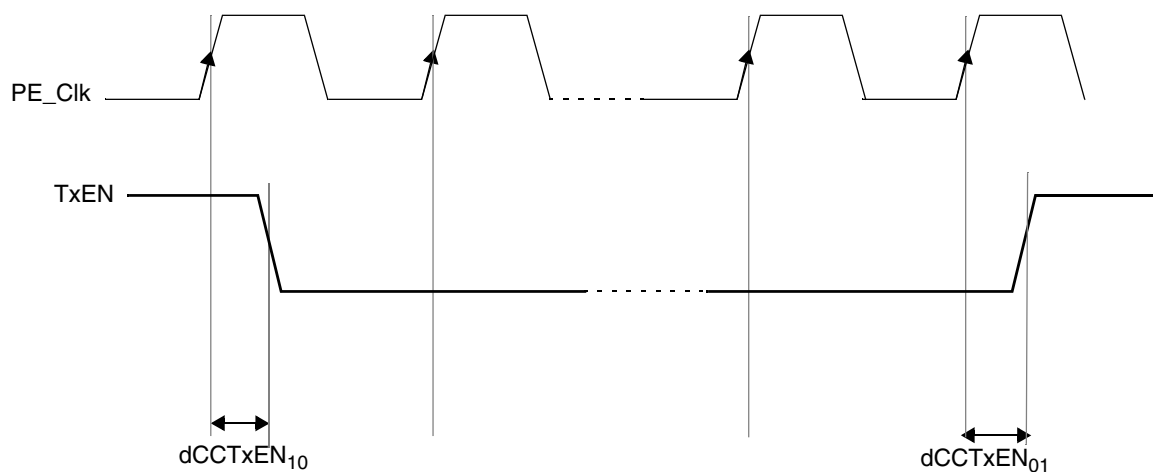
**Figure 21. DSPI classic SPI timing — master, CPHA = 0**

Table 51. TxEN output characteristics¹

Name	Description	Min	Max	Unit
dCCTxEN _{RISE25}	Rise time of TxEN signal at CC	—	9	ns
dCCTxEN _{FALL25}	Fall time of TxEN signal at CC	—	9	ns
dCCTxEN ₀₁	Sum of delay between Clk to Q of the last FF and the final output buffer, rising edge	—	25	ns
dCCTxEN ₁₀	Sum of delay between Clk to Q of the last FF and the final output buffer, falling edge	—	25	ns

1. All parameters specified for $V_{DD_HV_IO} = 3.3\text{ V} -5\%, +10\%$, $T_J = -40\text{ }^{\circ}\text{C} / 165\text{ }^{\circ}\text{C}$, TxEN pin load maximum 25 pF

**Figure 34. FlexRay TxEN signal propagation delays**

3.19.7.3 TxD

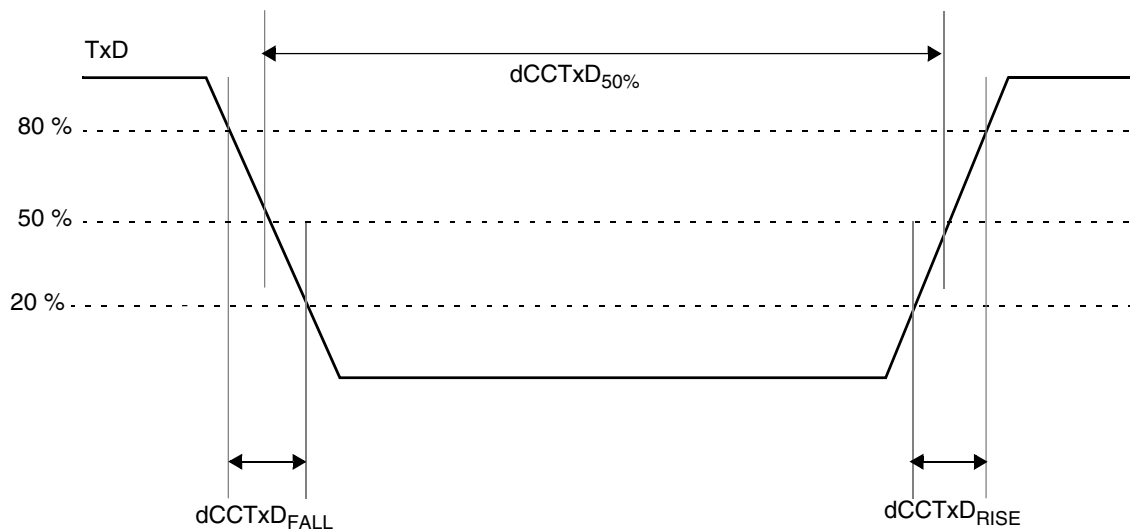
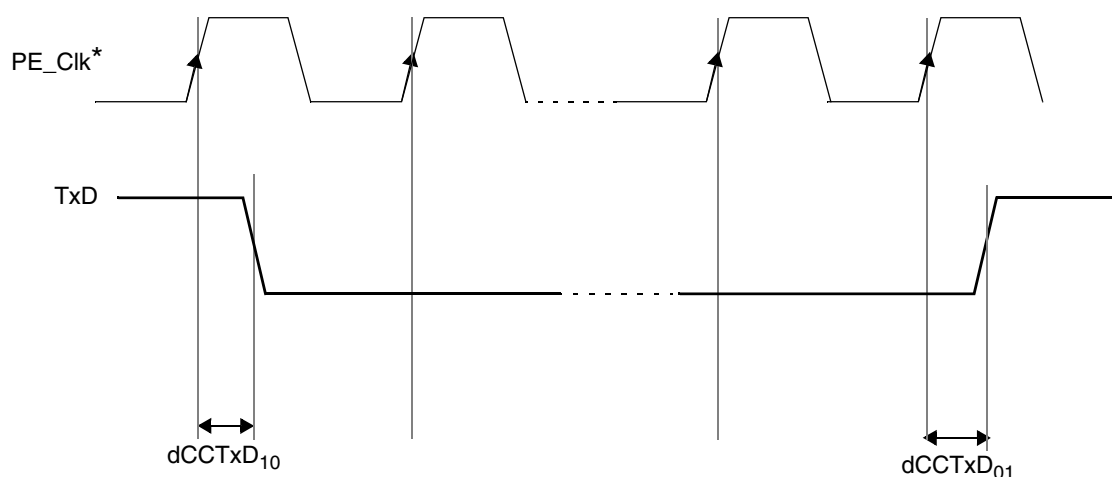


Figure 35. FlexRay TxD signal

Table 52. TxD output characteristics

Name	Description ¹	Min	Max	Unit
$dCCT_{xAsym}$	Asymmetry of sending CC @ 25 pF load (= $dCCTxD_{50\%}$ - 100 ns)	-2.45	2.45	ns
$dCCTxD_{RISE25} + dCCTxD_{FALL25}$	Sum of Rise and Fall time of TxD signal at the output	—	9	ns
$dCCTxD_{01}$	Sum of delay between Clk to Q of the last FF and the final output buffer, rising edge	—	25	ns
$dCCTxD_{10}$	Sum of delay between Clk to Q of the last FF and the final output buffer, falling edge	—	25	ns

1. All parameters specified for $V_{DD_HV_IO} = 3.3\text{ V} -5\%, +10\%$, $T_J = -40\text{ }^{\circ}\text{C} / 165\text{ }^{\circ}\text{C}$, TxD pin load maximum 25 pF



*FlexRay Protocol Engine Clock

Figure 36. FlexRay TxD signal propagation delays

3.19.7.4 RxD

Table 53. RxD input characteristic

Name	Description ¹	Min	Max	Unit
C_CCRxD	Input capacitance on RxD pin	—	7	pF
uCCLogic_1	Threshold for detecting logic high	35	70	%
uCCLogic_0	Threshold for detecting logic low	30	65	%
dCCRxD ₀₁	Sum of delay from actual input to the D input of the first FF, rising edge	—	10	ns
dCCRxD ₁₀	Sum of delay from actual input to the D input of the first FF, falling edge	—	10	ns

1. All parameters specified for $V_{DD_HV_IO} = 3.3\text{ V} -5\%, +10\%$, $T_J = -40 / 165\text{ °C}$

3.19.7.5 Receiver asymmetry

Table 54. Receiver asymmetry

Name	Description	Min	Max	Unit
dCCRxAsymAccept ₁₅	Acceptance of asymmetry at receiving CC with 15 pF load (*)	−31.5	+44.0	ns
dCCRxAsymAccept ₂₅	Acceptance of asymmetry at receiving CC with 25 pF load (*)	−30.5	+43.0	ns

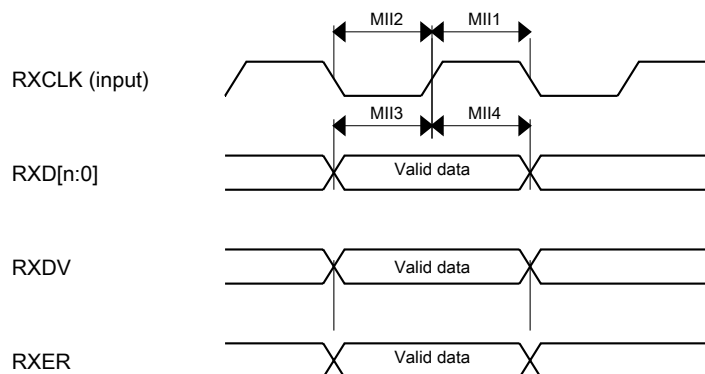


Figure 38. RMII/MII receive signal timing diagram

3.19.8.2 RMII signal switching specifications

The following timing specs meet the requirements for RMII style interfaces for a range of transceiver devices.

Table 56. RMII signal switching specifications

Num	Description	Min.	Max.	Unit
—	EXTAL frequency (RMII input clock RMII_CLK)	—	50	MHz
RMII1	RMII_CLK pulse width high	35%	65%	RMII_CLK period
RMII2	RMII_CLK pulse width low	35%	65%	RMII_CLK period
RMII3	RXD[1:0], CRS_DV, RXER to RMII_CLK setup	4	—	ns
RMII4	RMII_CLK to RXD[1:0], CRS_DV, RXER hold	2	—	ns
RMII7	RMII_CLK to TXD[1:0], TXEN invalid	4	—	ns
RMII8	RMII_CLK to TXD[1:0], TXEN valid	—	15	ns

4 Obtaining package dimensions

Package dimensions are provided in package drawings.

To find a package drawing, go to <http://www.nxp.com> and perform a keyword search for the drawing's document number:

If you want the drawing for this package	Then use this document number
144-pin LQFP	98ASS23177W
257-ball MAPBGA	98ASA00081D

Table 58. Revision history (continued)

Revision	Date	Description of changes
		- Changed Typical from 7 μs plus four system clock periods to 9.4 μs plus four system clock periods - Changed Max from 9.1 μs plus four system clock periods to 11.5 μs plus four system clock periods SGEN electrical characteristics - Extensively updated the Table 37 LFAST interface electrical characteristics - In Table 49 for row set $I\Delta_{VOD_DRF}$ deleted the $\pm$ from the Max, Typ, and Min values. - In Table 49, removed the row set V_{HYS_DRF}
6.1	10/2017	In Voltage regulator electrical characteristics changed the note, from "The device has to.....which drives the EXT_POR" to "When the external regulator.....regulator modes for safety operation".