



Welcome to **E-XFL.COM**

What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	40MHz
Connectivity	I ² C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, HLVD, POR, PWM, WDT
Number of I/O	36
Program Memory Size	16KB (8K x 16)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	768 x 8
Voltage - Supply (Vcc/Vdd)	4.2V ~ 5.5V
Data Converters	A/D 13x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-TQFP
Supplier Device Package	44-TQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic18f4423t-i-pt

Note the following details of the code protection feature on Microchip devices:

- Microchip products meet the specification contained in their particular Microchip Data Sheet.
- Microchip believes that its family of products is one of the most secure families of its kind on the market today, when used in the intended manner and under normal conditions.
- There are dishonest and possibly illegal methods used to breach the code protection feature. All of these methods, to our knowledge, require using the Microchip products in a manner outside the operating specifications contained in Microchip's Data Sheets. Most likely, the person doing so is engaged in theft of intellectual property.
- Microchip is willing to work with the customer who is concerned about the integrity of their code.
- Neither Microchip nor any other semiconductor manufacturer can guarantee the security of their code. Code protection does not
 mean that we are guaranteeing the product as "unbreakable."

Code protection is constantly evolving. We at Microchip are committed to continuously improving the code protection features of our products. Attempts to break Microchip's code protection feature may be a violation of the Digital Millennium Copyright Act. If such acts allow unauthorized access to your software or other copyrighted work, you may have a right to sue for relief under that Act.

Information contained in this publication regarding device applications and the like is provided only for your convenience and may be superseded by updates. It is your responsibility to ensure that your application meets with your specifications. MICROCHIP MAKES NO REPRESENTATIONS WARRANTIES OF ANY KIND WHETHER EXPRESS OR IMPLIED, WRITTEN OR ORAL, STATUTORY OR OTHERWISE, RELATED TO THE INFORMATION, INCLUDING BUT NOT LIMITED TO ITS CONDITION. QUALITY, PERFORMANCE, MERCHANTABILITY FITNESS FOR PURPOSE. Microchip disclaims all liability arising from this information and its use. Use of Microchip devices in life support and/or safety applications is entirely at the buyer's risk, and the buyer agrees to defend, indemnify and hold harmless Microchip from any and all damages, claims, suits, or expenses resulting from such use. No licenses are conveyed, implicitly or otherwise, under any Microchip intellectual property rights.

Trademarks

The Microchip name and logo, the Microchip logo, dsPIC, Keeloq, Keeloq logo, MPLAB, PIC, PICmicro, PICSTART, rfPIC and UNI/O are registered trademarks of Microchip Technology Incorporated in the U.S.A. and other countries.

FilterLab, Hampshire, HI-TECH C, Linear Active Thermistor, MXDEV, MXLAB, SEEVAL and The Embedded Control Solutions Company are registered trademarks of Microchip Technology Incorporated in the U.S.A.

Analog-for-the-Digital Age, Application Maestro, CodeGuard, dsPICDEM, dsPICDEM.net, dsPICworks, dsSPEAK, ECAN, ECONOMONITOR, FanSense, HI-TIDE, In-Circuit Serial Programming, ICSP, Mindi, MiWi, MPASM, MPLAB Certified logo, MPLIB, MPLINK, mTouch, Octopus, Omniscient Code Generation, PICC, PICC-18, PICDEM, PICDEM.net, PICkit, PICtail, PIC³² logo, REAL ICE, rfLAB, Select Mode, Total Endurance, TSHARC, UniWinDriver, WiperLock and ZENA are trademarks of Microchip Technology Incorporated in the U.S.A. and other countries.

 $\ensuremath{\mathsf{SQTP}}$ is a service mark of Microchip Technology Incorporated in the U.S.A.

All other trademarks mentioned herein are property of their respective companies.

© 2009, Microchip Technology Incorporated, Printed in the U.S.A., All Rights Reserved.

Printed on recycled paper.

QUALITY MANAGEMENT SYSTEM

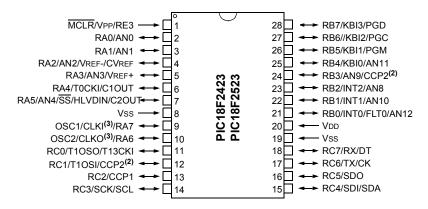
CERTIFIED BY DNV

ISO/TS 16949:2002

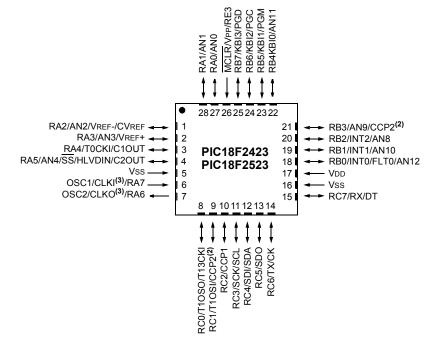
Microchip received ISO/TS-16949:2002 certification for its worldwide headquarters, design and wafer fabrication facilities in Chandler and Tempe, Arizona; Gresham, Oregon and design centers in California and India. The Company's quality system processes and procedures are for its PIC® MCUs and dsPIC® DSCs, KEELOQ® code hopping devices, Serial EEPROMs, microperipherals, nonvolatile memory and analog products. In addition, Microchip's quality system for the design and manufacture of development systems is ISO 9001:2000 certified.

Pin Diagrams

28-Pin PDIP, SOIC



28-Pin QFN⁽¹⁾



- Note 1: It is recommended to connect the bottom pad of QFN package parts to Vss.
 - 2: RB3 is the alternate pin for CCP2 multiplexing.
 - 3: OSC1/CLKI and OSC2/CLKO are only available in select oscillator modes and when these pins are not being used as digital I/O. For additional information, see Section 2.0 "Oscillator Configurations" of the "PIC18F2420/2520/4420/4520 Data Sheet" (DS39631).

TO OUR VALUED CUSTOMERS

It is our intention to provide our valued customers with the best documentation possible to ensure successful use of your Microchip products. To this end, we will continue to improve our publications to better suit your needs. Our publications will be refined and enhanced as new volumes and updates are introduced.

If you have any questions or comments regarding this publication, please contact the Marketing Communications Department via E-mail at **docerrors@microchip.com** or fax the **Reader Response Form** in the back of this data sheet to (480) 792-4150. We welcome your feedback.

Most Current Data Sheet

To obtain the most up-to-date version of this data sheet, please register at our Worldwide Web site at:

http://www.microchip.com

You can determine the version of a data sheet by examining its literature number found on the bottom outside corner of any page. The last character of the literature number is the version number, (e.g., DS30000A is version A of document DS30000).

Errata

An errata sheet, describing minor operational differences from the data sheet and recommended workarounds, may exist for current devices. As device/documentation issues become known to us, we will publish an errata sheet. The errata will specify the revision of silicon and revision of document to which it applies.

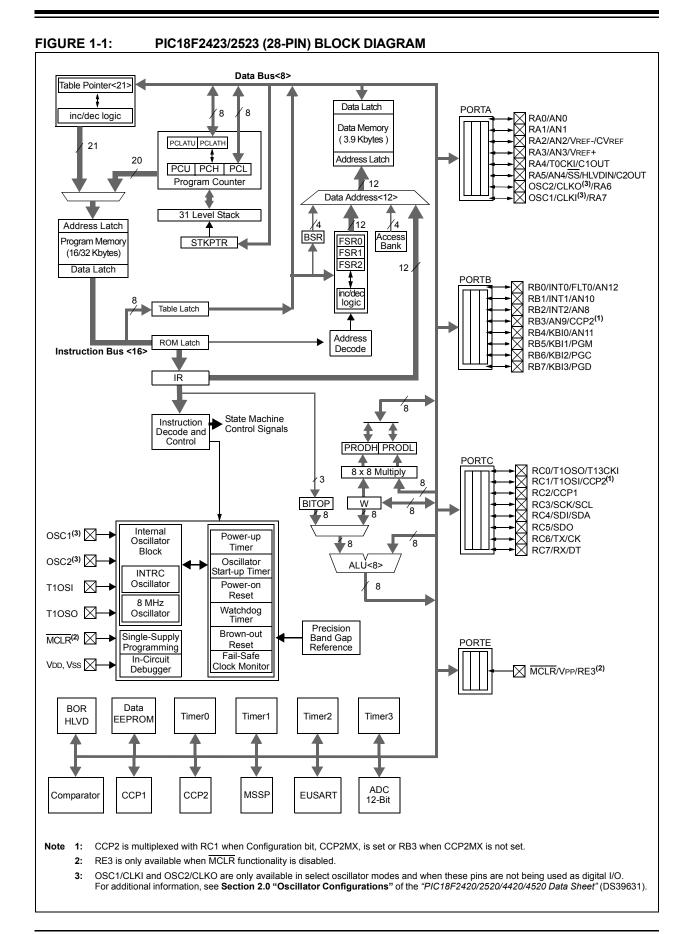
To determine if an errata sheet exists for a particular device, please check with one of the following:

- Microchip's Worldwide Web site; http://www.microchip.com
- · Your local Microchip sales office (see last page)

When contacting a sales office, please specify which device, revision of silicon and data sheet (include literature number) you are using.

Customer Notification System

Register on our web site at www.microchip.com to receive the most current information on all of our products.



DS39755C-page 12

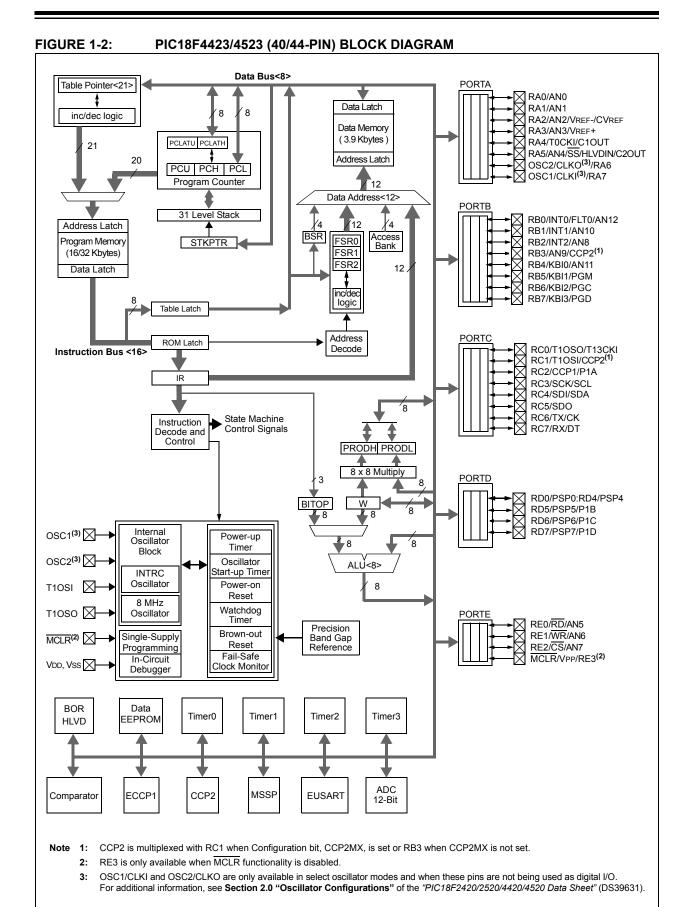


TABLE 1-2: PIC18F2423/2523 PINOUT I/O DESCRIPTIONS (CONTINUED)

	Pin N	umber	Pin	Buffer	
Pin Name	PDIP, SOIC	QFN	Туре	Туре	Description
					PORTB is a bidirectional I/O port. PORTB can be software programmed for internal weak pull-ups on all inputs.
RB0/INT0/FLT0/AN12 RB0	21	18	I/O	TTL	Digital I/O.
INTO FLTO AN12			 	ST ST Analog	External Interrupt 0. PWM Fault input for CCP1. Analog Input 12.
RB1/INT1/AN10 RB1	22	19	I/O	TTL	Digital I/O.
INT1 AN10			l I	ST Analog	External Interrupt 1. Analog Input 10.
RB2/INT2/AN8 RB2 INT2 AN8	23	20	I/O I	TTL ST Analog	Digital I/O. External Interrupt 2. Analog Input 8.
RB3/AN9/CCP2 RB3 AN9 CCP2 ⁽¹⁾	24	21	I/O I I/O	TTL Analog ST	Digital I/O.
RB4/KBI0/AN11 RB4 KBI0	25	22	I/O I	TTL TTL	Digital I/O. Interrupt-on-change pin.
AN11 RB5/KBI1/PGM RB5 KBI1	26	23	I/O I	Analog TTL TTL	Digital I/O. Interrupt-on-change pin.
PGM RB6/KBI2/PGC RB6	27	24	I/O	ST	Low-Voltage ICSP™ Programming enable pin. Digital I/O.
KBI2 PGC			I/O	TTL ST	Interrupt-on-change pin. In-Circuit Debugger and ICSP programming clock pin.
RB7/KBI3/PGD RB7 KBI3 PGD	28	25	I/O I I/O	TTL TTL ST	Digital I/O. Interrupt-on-change pin. In-Circuit Debugger and ICSP programming data pin.

Legend: TTL = TTL compatible input

CMOS = CMOS compatible input or output

ST = Schmitt Trigger input with CMOS levels

I = Input

O = Output

P = Power

 $I^2C = I^2C^{\dagger M}/SMBus$

Note 1: Default assignment for CCP2 when Configuration bit, CCP2MX, is set.

TABLE 1-2: PIC18F2423/2523 PINOUT I/O DESCRIPTIONS (CONTINUED)

	Pin N	umber	Pin	Buffer		
Pin Name	PDIP, SOIC	QFN	Туре	Type	Description	
					PORTC is a bidirectional I/O port.	
RC0/T10SO/T13CKI	11	8				
RC0			I/O	ST	Digital I/O.	
T10S0			0	_	Timer1 oscillator output.	
T13CKI			I	ST	Timer1/Timer3 external clock input.	
RC1/T1OSI/CCP2	12	9				
RC1 T10SI			I/O	ST	Digital I/O.	
CCP2 ⁽²⁾			I I/O	Analog ST	Timer1 oscillator input. Capture 2 input/Compare 2 output/PWM2 output.	
	40	40	1/0	31		
RC2/CCP1 RC2	13	10	I/O	ST	Digital I/O.	
CCP1			1/0	ST	Capture 1 input/Compare 1 output/PWM1 output.	
RC3/SCK/SCL	14	11			Captaro i inpat compare i catpati vivii catpati	
RC3	'-	11	I/O	ST	Digital I/O.	
SCK			I/O	ST	Synchronous serial clock input/output for SPI mode.	
SCL			I/O	I ² C	Synchronous serial clock input/output for I ² C™ mode.	
RC4/SDI/SDA	15	12				
RC4			I/O	ST	Digital I/O.	
SDI			1	ST	SPI data in.	
SDA			I/O	I ² C	I ² C data I/O.	
RC5/SDO	16	13				
RC5			1/0	ST	Digital I/O.	
SDO	4=	4.4	0		SPI data out.	
RC6/TX/CK RC6	17	14	I/O	ST	Digital I/O.	
TX			0	31	EUSART asynchronous transmit.	
CK			1/0	ST	EUSART synchronous clock (see related RX/DT).	
RC7/RX/DT	18	15			.,	
RC7	.0	.0	I/O	ST	Digital I/O.	
RX			Ī	ST	EUSART asynchronous receive.	
DT			I/O	ST	EUSART synchronous data (see related TX/CK).	
RE3	_				See MCLR/VPP/RE3 pin.	
Vss	8, 19	5, 16	Р	_	Ground reference for logic and I/O pins.	
VDD	20	17	Р	_	Positive supply for logic and I/O pins.	

Legend: TTL = TTL compatible input

CMOS = CMOS compatible input or output

ST = Schmitt Trigger input with CMOS levels

I = Input

= Power

O = Output

 $I^2C = I^2C^{\dagger M}/SMBus$

Note 1: Default assignment for CCP2 when Configuration bit, CCP2MX, is set.

TABLE 1-3: PIC18F4423/4523 PINOUT I/O DESCRIPTIONS (CONTINUED)

Din Nama	Pi	n Numb	er	Pin	Buffer	Boo and add and
Pin Name	PDIP	QFN	TQFP	Туре	Type	Description
						PORTB is a bidirectional I/O port. PORTB can be software programmed for internal weak pull-ups on all inputs.
RB0/INT0/FLT0/AN12 RB0 INT0 FLT0 AN12	33	9	8	I/O I I	TTL ST ST Analog	Digital I/O. External Interrupt 0. PWM Fault input for Enhanced CCP1. Analog Input 12.
RB1/INT1/AN10 RB1 INT1 AN10	34	10	9	I/O I I	TTL ST Analog	Digital I/O. External Interrupt 1. Analog Input 10.
RB2/INT2/AN8 RB2 INT2 AN8	35	11	10	I/O I I	TTL ST Analog	Digital I/O. External Interrupt 2. Analog Input 8.
RB3/AN9/CCP2 RB3 AN9 CCP2 ⁽¹⁾	36	12	11	I/O I I/O	TTL Analog ST	Digital I/O. Analog Input 9. Capture 2 input/Compare 2 output/PWM2 output.
RB4/KBI0/AN11 RB4 KBI0 AN11	37	14	14	I/O I I	TTL TTL Analog	Digital I/O. Interrupt-on-change pin. Analog Input 11.
RB5/KBI1/PGM RB5 KBI1 PGM	38	15	15	I/O I I/O	TTL TTL ST	Digital I/O. Interrupt-on-change pin. Low-Voltage ICSP™ Programming enable pin.
RB6/KBI2/PGC RB6 KBI2 PGC	39	16	16	I/O I I/O	TTL TTL ST	Digital I/O. Interrupt-on-change pin. In-Circuit Debugger and ICSP programming clock pin.
RB7/KBI3/PGD RB7 KBI3 PGD	40	17	17	I/O I I/O	TTL TTL ST	Digital I/O. Interrupt-on-change pin. In-Circuit Debugger and ICSP programming data pin.

Legend: TTL = TTL compatible input

ST = Schmitt Trigger input with CMOS levels

O = Output

 $I^2C = I^2C^{TM}/SMBus$

CMOS = CMOS compatible input or output

I = Input
P = Power

Note 1: Default assignment for CCP2 when Configuration bit, CCP2MX, is set.

TABLE 1-3: PIC18F4423/4523 PINOUT I/O DESCRIPTIONS (CONTINUED)

Pin Name	Piı	n Numb	oer	Pin	Buffer	Description
Pin Name	PDIP	QFN	TQFP	Туре	Type	Description
						PORTD is a bidirectional I/O port or a Parallel Slave Port (PSP) for interfacing to a microprocessor port. These pins have TTL input buffers when the PSP module is enabled.
RD0/PSP0 RD0 PSP0	19	38	38	I/O I/O	ST TTL	Digital I/O. Parallel Slave Port data.
RD1/PSP1 RD1 PSP1	20	39	39	I/O I/O	ST TTL	Digital I/O. Parallel Slave Port data.
RD2/PSP2 RD2 PSP2	21	40	40	I/O I/O	ST TTL	Digital I/O. Parallel Slave Port data.
RD3/PSP3 RD3 PSP3	22	41	41	I/O I/O	ST TTL	Digital I/O. Parallel Slave Port data.
RD4/PSP4 RD4 PSP4	27	2	2	I/O I/O	ST TTL	Digital I/O. Parallel Slave Port data.
RD5/PSP5/P1B RD5 PSP5 P1B	28	3	3	I/O I/O O	ST TTL	Digital I/O. Parallel Slave Port data. Enhanced CCP1 output.
RD6/PSP6/P1C RD6 PSP6 P1C	29	4	4	I/O I/O O	ST TTL —	Digital I/O. Parallel Slave Port data. Enhanced CCP1 output.
RD7/PSP7/P1D RD7 PSP7 P1D	30	5	5	I/O I/O O	ST TTL —	Digital I/O. Parallel Slave Port data. Enhanced CCP1 output.

Legend: TTL = TTL compatible input

ST = Schmitt Trigger input with CMOS levels

O = Output

 $I^2C = I^2C^{TM}/SMBus$

CMOS = CMOS compatible input or output

I = Input P = Power

... ------

Note 1: Default assignment for CCP2 when Configuration bit, CCP2MX, is set.

NOTES:

REGISTER 2-2: ADCON1: A/D CONTROL REGISTER 1

U-0	U-0	R/W-0	R/W-0	R/W-0 ⁽¹⁾	R/W ⁽¹⁾	R/W ⁽¹⁾	R/W ⁽¹⁾
_	_	VCFG1	VCFG0	PCFG3	PCFG2	PCFG1	PCFG0
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 7-6 Unimplemented: Read as '0'

bit 5 VCFG1: Voltage Reference Configuration bit (VREF- source)

1 = VREF- (AN2)

0 **= V**ss

bit 4 VCFG0: Voltage Reference Configuration bit (VREF+ source)

1 = VREF+ (AN3)

0 = VDD

bit 3-0 **PCFG<3:0>:** A/D Port Configuration Control bits:

PCFG<3:0>	AN12	AN11	AN10	6NA	AN8	AN7 ⁽²⁾	AN6 ⁽²⁾	AN5 ⁽²⁾	AN4	AN3	AN2	AN1	ANO
	٧	∢	٧	4	4	⋖	⋖	٧	٧	٧	٧	٧	٧
0000(1)	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α
0001	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α
0010	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α
0011	D	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α
0100	D	D	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α
0101	D	D	D	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α
0110	D	D	D	D	Α	Α	Α	Α	Α	Α	Α	Α	Α
0111(1)	D	D	D	D	D	Α	Α	Α	Α	Α	Α	Α	Α
1000	D	D	D	D	D	D	Α	Α	Α	Α	Α	Α	Α
1001	D	D	D	D	D	D	D	Α	Α	Α	Α	Α	Α
1010	D	D	D	D	D	D	D	D	Α	Α	Α	Α	Α
1011	D	D	D	D	D	D	D	D	D	Α	Α	Α	Α
1100	D	D	D	D	D	D	D	D	D	D	Α	Α	Α
1101	D	D	D	D	D	D	D	D	D	D	D	Α	Α
1110	D	D	D	D	D	D	D	D	D	D	D	D	Α
1111	D	D	D	D	D	D	D	D	D	D	D	D	D

A = Analog input

D = Digital I/O

Note 1: The POR value of the PCFG bits depends on the value of the PBADEN Configuration bit. When PBADEN = 1, PCFG<3:0> = 0000; when PBADEN = 0, PCFG<3:0> = 0111.

2: AN5 through AN7 are only available on PIC18F4423/4523 devices.

2.1 A/D Acquisition Requirements

For the A/D Converter to meet its specified accuracy, the charge holding capacitor (CHOLD) must be allowed to fully charge to the input channel voltage level. The analog input model is shown in Figure 2-3.

The source impedance (Rs) and the internal sampling switch (Rss) impedance directly affect the time required to charge the capacitor, CHOLD. The sampling switch (Rss) impedance varies over the device voltage (VDD). The source impedance affects the offset voltage at the analog input (due to pin leakage current). The maximum recommended impedance for analog sources is 2.5 k Ω .

After the analog input channel is selected (changed), the channel must be sampled for at least the minimum acquisition time before starting a conversion.

Note: When the conversion is started, the holding capacitor is disconnected from the input pin.

To calculate the minimum acquisition time, Equation 2-1 may be used. This equation assumes that 1/2 LSb error is used (4,096 steps for the A/D). The 1/2 LSb error is the maximum error allowed for the A/D to meet its specified resolution.

Example 2-3 shows the calculation of the minimum required acquisition time, TACQ. This calculation is based on the application system assumptions shown in Table 2-1:

TABLE 2-1: TACQ ASSUMPTIONS

CHOLD	=	25 pF
Rs	=	2.5 kΩ
Conversion Error	≤	1/2 LSb
VDD	=	$3V \rightarrow Rss = 4 \text{ k}\Omega$
Temperature	=	85°C (system maximum)

EQUATION 2-1: ACQUISITION TIME

```
TACQ = Amplifier Settling Time + Holding Capacitor Charging Time + Temperature Coefficient
= TAMP + TC + TCOFF
```

EQUATION 2-2: A/D MINIMUM CHARGING TIME

```
V_{HOLD} = (V_{REF} - (V_{REF}/4096)) \cdot (1 - e^{(-T_{C}/C_{HOLD}(R_{IC} + R_{SS} + R_{S}))})
or
T_{C} = -(C_{HOLD})(R_{IC} + R_{SS} + R_{S}) \ln(1/4096)
```

EQUATION 2-3: CALCULATING THE MINIMUM REQUIRED ACQUISITION TIME

```
TACQ = TAMP + TC + TCOFF

TAMP = 0.2 \,\mu s

TCOFF = (Temp - 25°C)(0.02 \,\mu s/°C)
(85^{\circ}C - 25^{\circ}C)(0.02 \,\mu s/°C)
1.2 \,\mu s

Temperature coefficient is only required for temperatures > 25°C. Below 25°C, TCOFF = 0 ms.

TC = -(CHOLD)(RIC + RSS + RS) ln(1/4095) \mu s
-(25 \,p F) (1 \,k \Omega + 4 \,k \Omega + 2.5 \,k \Omega) ln(0.0004883) \,\mu s
1.56 \,\mu s

TACQ = 0.2 \,\mu s + 1.56 \,\mu s + 1.2 \,\mu s
2.96 \,\mu s
```

2.4 Operation in Power-Managed Modes

The selection of the automatic acquisition time and A/D conversion clock is determined in part by the clock source and frequency while in a power-managed mode.

If the A/D is expected to operate while the device is in a power-managed mode, the ADCS<2:0> bits in ADCON2 should be updated in accordance with the clock source to be used. The ACQT<2:0> bits do not need to be adjusted as the ADCS<2:0> bits adjust the TAD time for the new clock speed. After entering the mode, an A/D acquisition or conversion may be started. Once started, the device should continue to be clocked by the same clock source until the conversion has been completed.

If desired, the device may be placed into the corresponding Idle mode during the conversion. If the device clock frequency is less than 1 MHz, the A/D RC clock source should be selected.

Operation in Sleep mode requires the A/D FRC clock to be selected. If bits, ACQT<2:0>, are set to '000' and a conversion is started, the conversion will be delayed one instruction cycle to allow execution of the SLEEP instruction and entry to Sleep mode. The IDLEN bit (OSCCON<7>) must have already been cleared prior to starting the conversion.

2.5 Configuring Analog Port Pins

The ADCON1, TRISA, TRISB and TRISE registers all configure the A/D port pins. The port pins needed as analog inputs must have their corresponding TRIS bits set (input). If the TRIS bit is cleared (output), the digital output level (VOH or VOL) will be converted.

The A/D operation is independent of the state of the CHS<3:0> bits and the TRIS bits.

- Note 1: When reading the PORT register, all pins configured as analog input channels will read as cleared (a low level). Analog conversion on pins configured as digital pins can be performed. The voltage on the pin will be accurately converted.
 - 2: Analog levels on any pin defined as a digital input may cause the digital input buffer to consume current out of the device's specification limits.
 - **3:** The PBADEN bit in Configuration Register 3H configures PORTB pins to reset as analog or digital pins by controlling how the PCFG<3:0> bits in ADCON1 are reset.

2.8 Use of the CCP2 Trigger

An A/D conversion can be started by the Special Event Trigger of the CCP2 module. This requires that the CCP2M<3:0> bits (CCP2CON<3:0>) be programmed as '1011' and that the A/D module is enabled (ADON bit is set). When the trigger occurs, the GO/DONE bit will be set, starting the A/D acquisition and conversion, and the Timer1 (or Timer3) counter will be reset to zero. Timer1 (or Timer3) is reset to automatically repeat the A/D acquisition period with minimal software overhead (moving ADRESH:ADRESL to the desired location).

The appropriate analog input channel must be selected and the minimum acquisition period is either timed by the user or an appropriate TACQ time is selected before the Special Event Trigger sets the GO/DONE bit (starts a conversion).

If the A/D module is not enabled (ADON is cleared), the Special Event Trigger will be ignored by the A/D module, but will still reset the Timer1 (or Timer3) counter.

TABLE 2-3: REGISTERS ASSOCIATED WITH A/D OPERATION

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Reset Values on page
INTCON	GIE/GIEH	PEIE/GIEL	TMR0IE	INT0IE	RBIE	TMR0IF	INT0IF	RBIF	(Note 4)
PIR1	PSPIF ⁽¹⁾	ADIF	RCIF	TXIF	SSPIF	CCP1IF	TMR2IF	TMR1IF	(Note 4)
PIE1	PSPIE ⁽¹⁾	ADIE	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	(Note 4)
IPR1	PSPIP ⁽¹⁾	ADIP	RCIP	TXIP	SSPIP	CCP1IP	TMR2IP	TMR1IP	(Note 4)
PIR2	OSCFIF	CMIF	_	EEIF	BCLIF	HLVDIF	TMR3IF	CCP2IF	(Note 4)
PIE2	OSCFIE	CMIE	_	EEIE	BCLIE	HLVDIE	TMR3IE	CCP2IE	(Note 4)
IPR2	OSCFIP	CMIP	_	EEIP	BCLIP	HLVDIP	TMR3IP	CCP2IP	(Note 4)
ADRESH	A/D Result	Register Hig	gh Byte						(Note 4)
ADRESL	A/D Result	Register Lo	w Byte						(Note 4)
ADCON0	_	_	CHS3	CHS2	CHS1	CHS0	GO/DONE	ADON	(Note 4)
ADCON1	_	_	VCFG1	VCFG0	PCFG3	PCFG2	PCFG1	PCFG0	(Note 4)
ADCON2	ADFM	_	ACQT2	ACQT1	ACQT0	ADCS2	ADCS1	ADCS0	(Note 4)
PORTA	RA7 ⁽²⁾	RA6 ⁽²⁾	RA5	RA4	RA3	RA2	RA1	RA0	(Note 4)
TRISA	TRISA7 ⁽²⁾	TRISA6 ⁽²⁾	PORTA Da	ata Direction	Control Re	gister			(Note 4)
PORTB	RB7	RB6	RB5	RB4	RB3	RB2	RB1	RB0	(Note 4)
TRISB	PORTB Dat	a Direction (Control Reg	ister					(Note 4)
LATB	PORTB Dat	a Latch Reg	ister (Read	and Write to	Data Latc	h)			(Note 4)
PORTE ⁽¹⁾	_	_	_	_	RE3 ⁽³⁾	RE2	RE1	RE0	(Note 4)
TRISE ⁽¹⁾	IBF	OBF	IBOV	PSPMODE	_	TRISE2	TRISE1	TRISE0	(Note 4)
LATE ⁽¹⁾	_	_		_	_	PORTE D	ata Latch Re	gister	(Note 4)

Legend: — = unimplemented, read as '0'. Shaded cells are not used for A/D conversion.

- Note 1: These registers and/or bits are not implemented on PIC18F2423/2523 devices and are read as '0'.
 - 2: PORTA<7:6> and their direction bits are individually configured as port pins based on various primary oscillator modes. When disabled, these bits read as '0'.
 - 3: RE3 port bit is available only as an input pin when the MCLRE Configuration bit is '0'.
 - **4:** For these Reset values, see **Section 4.0 "Reset"** of the "*PIC18F2420/2520/4420/4520 Data Sheet"* (DS39631).

FIGURE 4-1: PIC18F2423/2523/4423/4523 VOLTAGE-FREQUENCY GRAPH (INDUSTRIAL)

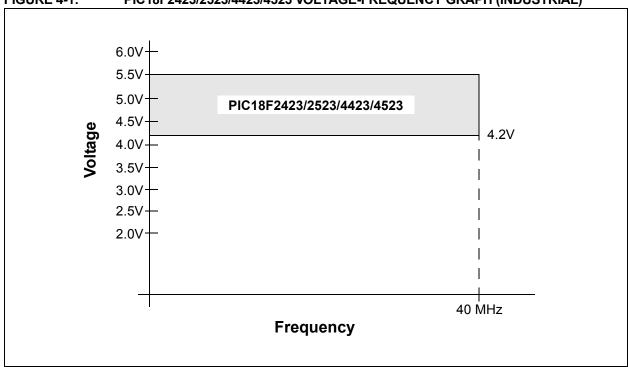
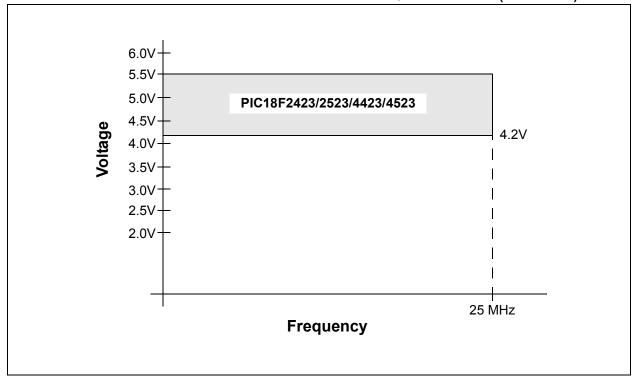


FIGURE 4-2: PIC18F2423/2523/4423/4523 VOLTAGE-FREQUENCY GRAPH (EXTENDED)



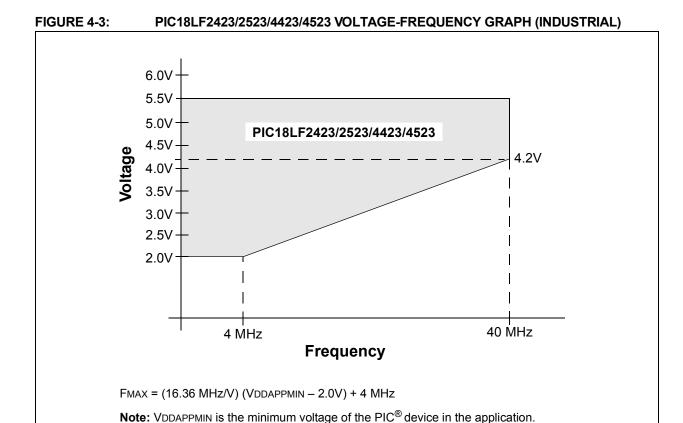


FIGURE 4-4: A/D CONVERSION TIMING

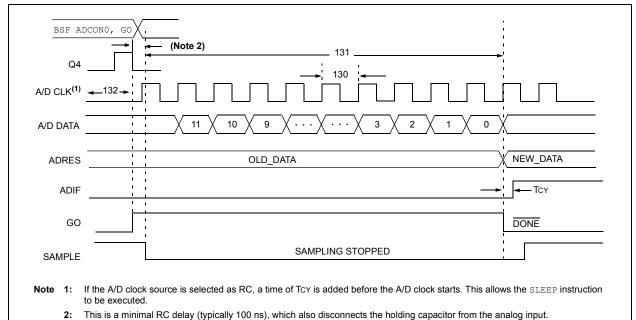


TABLE 4-2: A/D CONVERSION REQUIREMENTS

Param No.	Symbol	Characte	Min	Max	Units	Conditions	
130	TAD	A/D Clock Period	PIC18FXXXX	8.0	12.5 ⁽¹⁾	μS	Tosc based, VREF ≥ 3.0V
			PIC18 LF XXXX	1.4	25.0 ⁽¹⁾	μS	V _{DD} = 3.0V; Tosc based, V _{REF} full range
			PIC18FXXXX	_	1	μS	A/D RC mode
			PIC18 LF XXXX	_	3	μS	VDD = 3.0V; A/D RC mode
131	TCNV	Conversion Time (not including acquisition	on time) ⁽²⁾	13	14	TAD	
132	TACQ	Acquisition Time ⁽³⁾		1.4	_	μS	
135	Tswc	Switching Time from C	_	(Note 4)			
137	TDIS	Discharge Time		0.2	_	μS	

Note 1: The time of the A/D clock period is dependent on the device frequency and the TAD clock divider.

- 2: ADRES registers may be read on the following TcY cycle.
- 3: The time for the holding capacitor to acquire the "New" input voltage when the voltage changes full scale after the conversion (VDD to Vss or Vss to VDD). The source impedance (Rs) on the input channels is 50Ω.
- 4: On the following cycle of the device clock.

NOTES:

5.0 PACKAGING INFORMATION

For packaging information, see **Section 28.0 "Packaging Information"** in the "PIC18F2420/2520/4420/4520 Data Sheet" (DS39631).

APPENDIX C: CONVERSION CONSIDERATIONS

This appendix discusses the considerations for converting from previous versions of a device to the ones listed in this data sheet. Typically, these changes are due to the differences in the process technology used. An example of this type of conversion is from a PIC16C74A to a PIC16C74B.

Not Applicable

APPENDIX D: MIGRATION FROM BASELINE TO ENHANCED DEVICES

This section discusses how to migrate from a Baseline device (i.e., PIC16C5X) to an Enhanced MCU device (i.e., PIC18FXXX).

The following are the list of modifications over the PIC16C5X microcontroller family:

Not Currently Available