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Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	40MHz
Connectivity	I ² C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, HLVD, POR, PWM, WDT
Number of I/O	36
Program Memory Size	32KB (16K x 16)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	1.5K x 8
Voltage - Supply (Vcc/Vdd)	4.2V ~ 5.5V
Data Converters	A/D 13x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-VQFN Exposed Pad
Supplier Device Package	44-QFN (8x8)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic18f4523-i-ml

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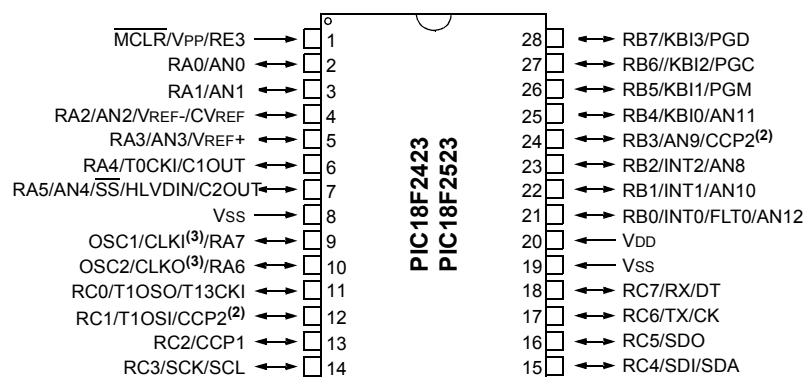
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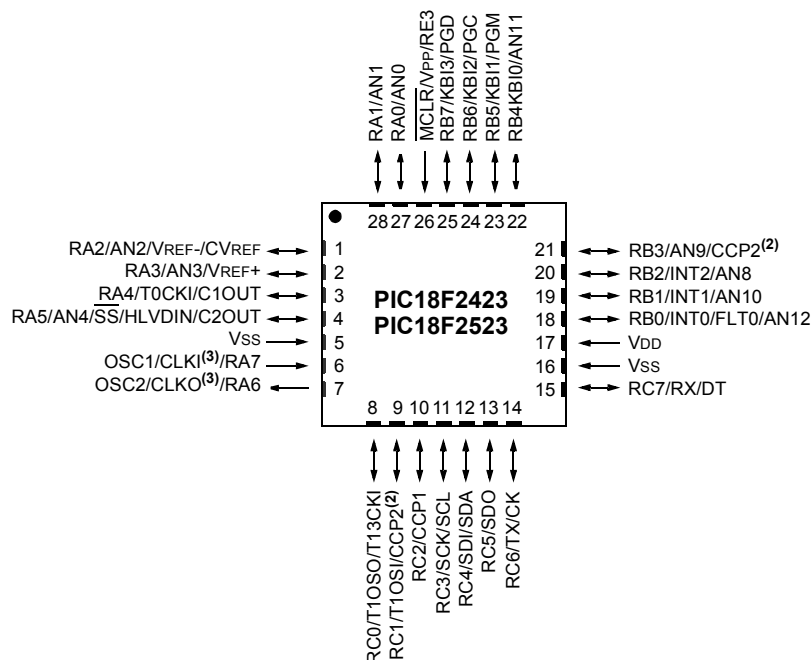
PIC18F2423/2523/4423/4523

Pin Diagrams

28-Pin PDIP, SOIC



28-Pin QFN⁽¹⁾



- Note**
- 1: It is recommended to connect the bottom pad of QFN package parts to Vss.
 - 2: RB3 is the alternate pin for CCP2 multiplexing.
 - 3: OSC1/CLKI and OSC2/CLKO are only available in select oscillator modes and when these pins are not being used as digital I/O. For additional information, see **Section 2.0 "Oscillator Configurations"** of the "PIC18F2420/2520/4420/4520 Data Sheet" (DS39631).

PIC18F2423/2523/4423/4523

1.2 Other Special Features

- **12-Bit A/D Converter:** This module incorporates programmable acquisition time, allowing for a channel to be selected and a conversion to be initiated without waiting for a sampling period, thereby reducing code overhead.
- **Memory Endurance:** The Enhanced Flash cells for both program memory and data EEPROM are rated to last for many thousands of erase/write cycles – up to 100,000 for program memory and 1,000,000 for EEPROM. Data retention without refresh is conservatively estimated to be greater than 40 years.
- **Self-Programmability:** These devices can write to their own program memory spaces under internal software control. By using a bootloader routine located in the protected Boot Block at the top of program memory, it is possible to create an application that can update itself in the field.
- **Extended Instruction Set:** The PIC18F2423/2523/4423/4523 family introduces an optional extension to the PIC18 instruction set that adds eight new instructions and an Indexed Addressing mode. This extension, enabled as a device configuration option, has been specifically designed to optimize re-entrant application code originally developed in high-level languages, such as C.
- **Enhanced CCP module:** In PWM mode, this module provides one, two or four modulated outputs for controlling half-bridge and full-bridge drivers. Other features include auto-shutdown, for disabling PWM outputs on interrupt or other select conditions, and auto-restart, to reactivate outputs once the condition has cleared.
- **Enhanced Addressable USART:** This serial communication module is capable of standard RS-232 operation and provides support for the LIN/J2602 bus protocol. Other enhancements include automatic baud rate detection and a 16-bit Baud Rate Generator for improved resolution. When the microcontroller is using the internal oscillator block, the EUSART provides stable operation for applications that talk to the outside world without using an external crystal (or its accompanying power requirement).
- **Extended Watchdog Timer (WDT):** This Enhanced version incorporates a 16-bit prescaler, allowing an extended time-out range that is stable across operating voltage and temperature. See **Section 4.0 “Electrical Characteristics”** for time-out periods.

1.3 Details on Individual Family Members

Devices in the PIC18F2423/2523/4423/4523 family are available in 28-pin and 40/44-pin packages. Block diagrams for the two groups are shown in Figure 1-1 and Figure 1-2.

The devices are differentiated from each other in these ways:

- Flash Program Memory:
 - PIC18F2423/4423 devices – 16 Kbytes
 - PIC18F2523/4523 devices – 32 Kbytes
- A/D Channels:
 - PIC18F2423/2523 devices – 10
 - PIC18F4423/4523 devices – 13
- I/O Ports:
 - PIC18F2423/2523 devices – Three bidirectional ports
 - PIC18F4423/4523 devices – Five bidirectional ports
- CCP and Enhanced CCP Implementation:
 - PIC18F2423/2523 devices – Two standard CCP modules
 - PIC18F4423/4523 devices – One standard CCP module and one ECCP module
- Parallel Slave Port – Present only on PIC18F4423/4523 devices

All other features for devices in this family are identical. These are summarized in Table 1-1.

The pinouts for all devices are listed in Table 1-2 and Table 1-3.

Members of the PIC18F2423/2523/4423/4523 family are available only as low-voltage devices, designated by “LF” (such as PIC18**LF**2423), and function over an extended VDD range of 2.0V to 5.5V.

PIC18F2423/2523/4423/4523

TABLE 1-2: PIC18F2423/2523 PINOUT I/O DESCRIPTIONS (CONTINUED)

Pin Name	Pin Number		Pin Type	Buffer Type	Description
	PDIP, SOIC	QFN			
RB0/INT0/FLT0/AN12	21	18	I/O I I I	TTL ST ST Analog	PORTB is a bidirectional I/O port. PORTB can be software programmed for internal weak pull-ups on all inputs. Digital I/O. External Interrupt 0. PWM Fault input for CCP1. Analog Input 12.
RB1/INT1/AN10	22	19	I/O I I	TTL ST Analog	Digital I/O. External Interrupt 1. Analog Input 10.
RB2/INT2/AN8	23	20	I/O I I	TTL ST Analog	Digital I/O. External Interrupt 2. Analog Input 8.
RB3/AN9/CCP2	24	21	I/O I I/O	TTL Analog ST	Digital I/O. Analog Input 9. Capture 2 input/Compare 2 output/PWM2 output.
RB4/KBI0/AN11	25	22	I/O I I	TTL TTL Analog	Digital I/O. Interrupt-on-change pin. Analog Input 11.
RB5/KBI1/PGM	26	23	I/O I I/O	TTL TTL ST	Digital I/O. Interrupt-on-change pin. Low-Voltage ICSP™ Programming enable pin.
RB6/KBI2/PGC	27	24	I/O I I/O	TTL TTL ST	Digital I/O. Interrupt-on-change pin. In-Circuit Debugger and ICSP programming clock pin.
RB7/KBI3/PGD	28	25	I/O I I/O	TTL TTL ST	Digital I/O. Interrupt-on-change pin. In-Circuit Debugger and ICSP programming data pin.

Legend: TTL = TTL compatible input CMOS = CMOS compatible input or output
ST = Schmitt Trigger input with CMOS levels I = Input
O = Output P = Power
I²C = I²C™/SMBus

Note 1: Default assignment for CCP2 when Configuration bit, CCP2MX, is set.
2: Alternate assignment for CCP2 when Configuration bit, CCP2MX, is cleared.

PIC18F2423/2523/4423/4523

TABLE 1-2: PIC18F2423/2523 PINOUT I/O DESCRIPTIONS (CONTINUED)

Pin Name	Pin Number		Pin Type	Buffer Type	Description
	PDIP, SOIC	QFN			
RC0/T1OSO/T13CKI RC0 T1OSO T13CKI	11	8	I/O O I	ST — ST	PORTC is a bidirectional I/O port. Digital I/O. Timer1 oscillator output. Timer1/Timer3 external clock input.
RC1/T1OSI/CCP2 RC1 T1OSI CCP2 ⁽²⁾	12	9	I/O I I/O	ST Analog ST	Digital I/O. Timer1 oscillator input. Capture 2 input/Compare 2 output/PWM2 output.
RC2/CCP1 RC2 CCP1	13	10	I/O I/O	ST ST	Digital I/O. Capture 1 input/Compare 1 output/PWM1 output.
RC3/SCK/SCL RC3 SCK SCL	14	11	I/O I/O I/O	ST ST I ² C	Digital I/O. Synchronous serial clock input/output for SPI mode. Synchronous serial clock input/output for I ² C™ mode.
RC4/SDI/SDA RC4 SDI SDA	15	12	I/O I I/O	ST ST I ² C	Digital I/O. SPI data in. I ² C data I/O.
RC5/SDO RC5 SDO	16	13	I/O O	ST —	Digital I/O. SPI data out.
RC6/TX/CK RC6 TX CK	17	14	I/O O I/O	ST — ST	Digital I/O. EUSART asynchronous transmit. EUSART synchronous clock (see related RX/DT).
RC7/RX/DT RC7 RX DT	18	15	I/O I I/O	ST ST ST	Digital I/O. EUSART asynchronous receive. EUSART synchronous data (see related TX/CK).
RE3	—	—	—	—	See MCLR/VPP/RE3 pin.
Vss	8, 19	5, 16	P	—	Ground reference for logic and I/O pins.
VDD	20	17	P	—	Positive supply for logic and I/O pins.

Legend: TTL = TTL compatible input CMOS = CMOS compatible input or output
ST = Schmitt Trigger input with CMOS levels I = Input
O = Output P = Power
I²C = I²C™/SMBus

Note 1: Default assignment for CCP2 when Configuration bit, CCP2MX, is set.

2: Alternate assignment for CCP2 when Configuration bit, CCP2MX, is cleared.

PIC18F2423/2523/4423/4523

TABLE 1-3: PIC18F4423/4523 PINOUT I/O DESCRIPTIONS

Pin Name	Pin Number			Pin Type	Buffer Type	Description
	PDIP	QFN	TQFP			
MCLR/VPP/RE3 MCLR VPP RE3	1	18	18	I P I	ST ST	Master Clear (input) or programming voltage (input). Master Clear (Reset) input. This pin is an active-low Reset to the device. Programming voltage input. Digital input.
OSC1/CLKI/RA7 OSC1 CLKI RA7	13	32	30	I I I/O	ST CMOS TTL	Oscillator crystal or external clock input. Oscillator crystal input or external clock source input. ST buffer when configured in RC mode; analog otherwise. External clock source input. Always associated with pin function, OSC1. (See related OSC1/CLKI, OSC2/CLKO pins.) General purpose I/O pin.
OSC2/CLKO/RA6 OSC2 CLKO RA6	14	33	31	O O I/O	— — TTL	Oscillator crystal or clock output. Oscillator crystal output. Connects to crystal or resonator in Crystal Oscillator mode. In RC mode, OSC2 pin outputs CLKO, which has 1/4 the frequency of OSC1 and denotes the instruction cycle rate. General purpose I/O pin.

Legend: TTL = TTL compatible input CMOS = CMOS compatible input or output
ST = Schmitt Trigger input with CMOS levels I = Input
O = Output P = Power
I²C = I²C™/SMBus

- Note 1:** Default assignment for CCP2 when Configuration bit, CCP2MX, is set.
2: Alternate assignment for CCP2 when Configuration bit, CCP2MX, is cleared.

PIC18F2423/2523/4423/4523

REGISTER 2-2: ADCON1: A/D CONTROL REGISTER 1

U-0	U-0	R/W-0	R/W-0	R/W-0 ⁽¹⁾	R/W ⁽¹⁾	R/W ⁽¹⁾	R/W ⁽¹⁾
—	—	VCFG1	VCFG0	PCFG3	PCFG2	PCFG1	PCFG0
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-6 **Unimplemented:** Read as '0'

bit 5 **VCFG1:** Voltage Reference Configuration bit (VREF- source)

1 = VREF- (AN2)

0 = VSS

bit 4 **VCFG0:** Voltage Reference Configuration bit (VREF+ source)

1 = VREF+ (AN3)

0 = VDD

bit 3-0 **PCFG<3:0>:** A/D Port Configuration Control bits:

PCFG<3:0>	AN12	AN11	AN10	AN9	AN8	AN7 ⁽²⁾	AN6 ⁽²⁾	AN5 ⁽²⁾	AN4	AN3	AN2	AN1	AN0
0000 ⁽¹⁾	A	A	A	A	A	A	A	A	A	A	A	A	A
0001	A	A	A	A	A	A	A	A	A	A	A	A	A
0010	A	A	A	A	A	A	A	A	A	A	A	A	A
0011	D	A	A	A	A	A	A	A	A	A	A	A	A
0100	D	D	A	A	A	A	A	A	A	A	A	A	A
0101	D	D	D	A	A	A	A	A	A	A	A	A	A
0110	D	D	D	D	A	A	A	A	A	A	A	A	A
0111 ⁽¹⁾	D	D	D	D	D	A	A	A	A	A	A	A	A
1000	D	D	D	D	D	D	A	A	A	A	A	A	A
1001	D	D	D	D	D	D	D	A	A	A	A	A	A
1010	D	D	D	D	D	D	D	D	A	A	A	A	A
1011	D	D	D	D	D	D	D	D	D	A	A	A	A
1100	D	D	D	D	D	D	D	D	D	D	A	A	A
1101	D	D	D	D	D	D	D	D	D	D	D	A	A
1110	D	D	D	D	D	D	D	D	D	D	D	D	A
1111	D	D	D	D	D	D	D	D	D	D	D	D	D

A = Analog input

D = Digital I/O

Note 1: The POR value of the PCFG bits depends on the value of the PBADEN Configuration bit. When PBADEN = 1, PCFG<3:0> = 0000; when PBADEN = 0, PCFG<3:0> = 0111.

2: AN5 through AN7 are only available on PIC18F4423/4523 devices.

PIC18F2423/2523/4423/4523

REGISTER 2-3: ADCON2: A/D CONTROL REGISTER 2

R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ADFM	—	ACQT2	ACQT1	ACQT0	ADCS2	ADCS1	ADCS0
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **ADFM:** A/D Result Format Select bit

1 = Right justified

0 = Left justified

bit 6 **Unimplemented:** Read as '0'

bit 5-3 **ACQT<2:0>:** A/D Acquisition Time Select bits

111 = 20 TAD

110 = 16 TAD

101 = 12 TAD

100 = 8 TAD

011 = 6 TAD

010 = 4 TAD

001 = 2 TAD

000 = 0 TAD⁽¹⁾

bit 2-0 **ADCS<2:0>:** A/D Conversion Clock Select bits

111 = FRC (clock derived from A/D RC oscillator)⁽¹⁾

110 = FOSC/64

101 = FOSC/16

100 = FOSC/4

011 = FRC (clock derived from A/D RC oscillator)⁽¹⁾

010 = FOSC/32

001 = FOSC/8

000 = FOSC/2

Note 1: If the A/D FRC clock source is selected, a delay of one T_{CY} (instruction cycle) is added before the A/D clock starts. This allows the **SLEEP** instruction to be executed before starting a conversion.

PIC18F2423/2523/4423/4523

The analog reference voltage is software selectable to either the device's positive and negative supply voltage (VDD and VSS), or the voltage level on the RA3/AN3/VREF+ and RA2/AN2/VREF-/CVREF pins.

The A/D Converter has a unique feature of being able to operate while the device is in Sleep mode. To operate in Sleep, the A/D conversion clock must be derived from the A/D's internal RC oscillator.

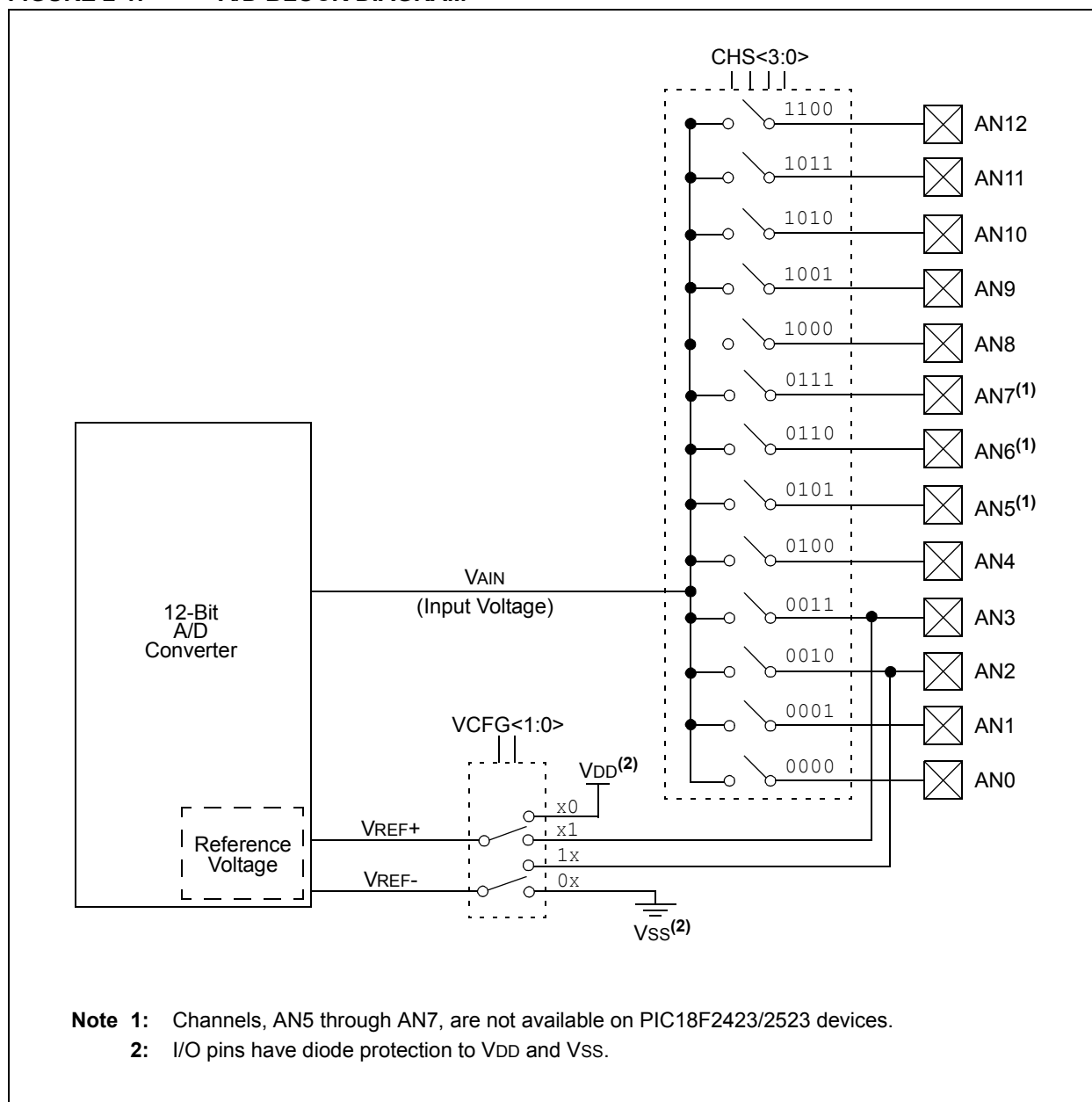
The output of the sample and hold is the input into the converter, which generates the result via successive approximation.

A device Reset forces all registers to their Reset state. This forces the A/D module to be turned off and any conversion in progress is aborted.

Each port pin associated with the A/D Converter can be configured as an analog input or as a digital I/O. The ADRESH and ADRESL registers contain the result of the A/D conversion. When the A/D conversion is complete, the result is loaded into the ADRESH:ADRESL register pair, the GO/DONE bit (ADCON0<1>) is cleared and A/D Interrupt Flag bit, ADIF, is set.

The block diagram of the A/D module is shown in Figure 2-1.

FIGURE 2-1: A/D BLOCK DIAGRAM



PIC18F2423/2523/4423/4523

The value in the ADRESH:ADRESL registers is unknown following POR and BOR Resets and is not affected by any other Reset.

After the A/D module has been configured as desired, the selected channel must be acquired before the conversion is started. The analog input channels must have their corresponding TRIS bits selected as inputs. To determine acquisition time, see **Section 2.1 “A/D Acquisition Requirements”**.

After this acquisition time has elapsed, the A/D conversion can be started. An acquisition time can be programmed to occur between setting the GO/DONE bit and the actual start of the conversion.

The following steps should be followed to perform an A/D conversion:

1. Configure the A/D module:
 - Configure analog pins, voltage reference and digital I/O (ADCON1)
 - Select A/D input channel (ADCON0)
 - Select A/D acquisition time (ADCON2)
 - Select A/D conversion clock (ADCON2)
 - Turn on the A/D module (ADCON0)
2. Configure the A/D interrupt (if desired):
 - Clear ADIF bit
 - Set ADIE bit
 - Set GIE bit
3. Wait the required acquisition time (if required).
4. Start conversion by setting the GO/DONE bit (ADCON0<1>).

5. Wait for the A/D conversion to complete by either:
 - Polling for the GO/DONE bit to be cleared
 OR
 - Waiting for the A/D interrupt
6. Read the A/D Result registers (ADRESH:ADRESL) and clear the ADIF bit, if required.
7. For the next conversion, go to step 1 or step 2, as required.

The A/D conversion time per bit is defined as TAD. A minimum wait of 2 TAD is required before the next acquisition starts.

FIGURE 2-2: A/D TRANSFER FUNCTION

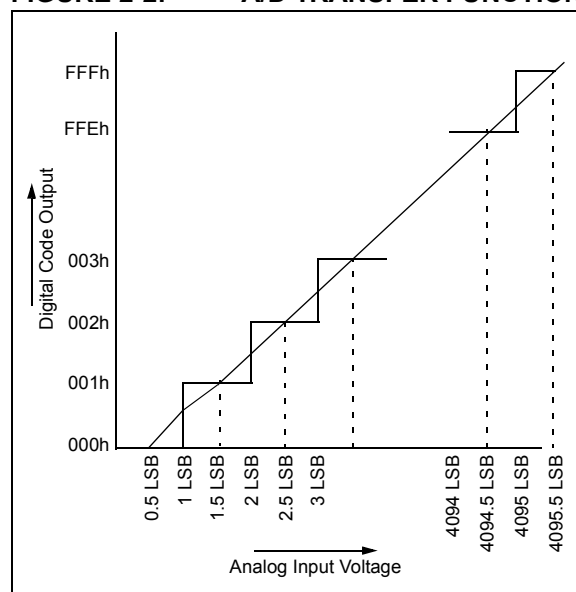
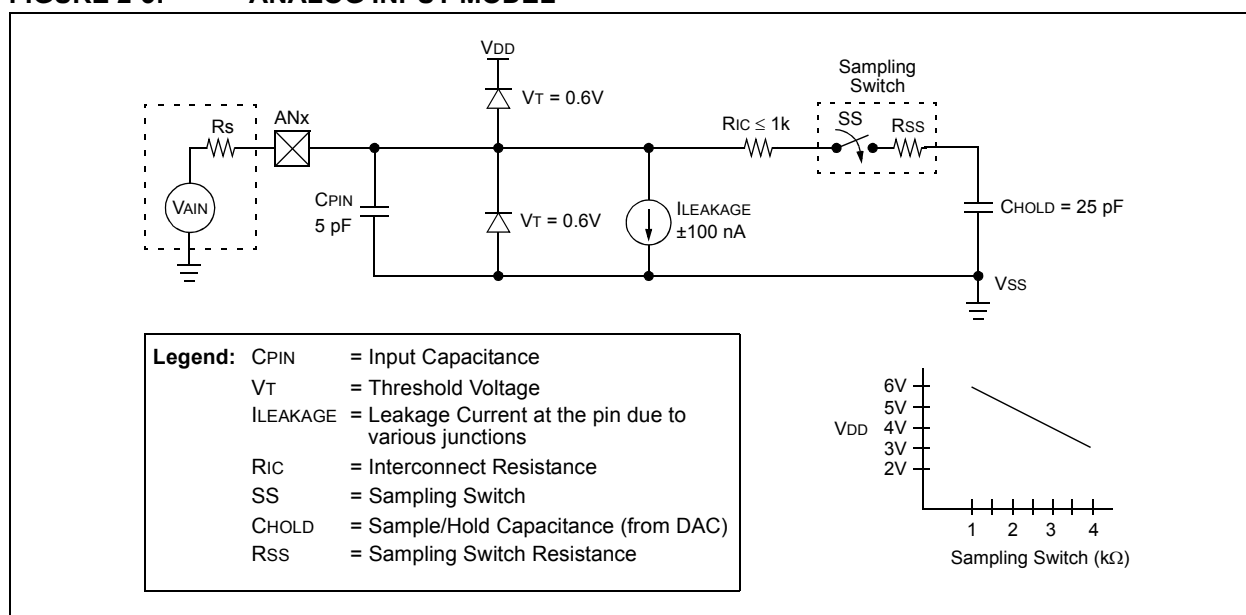


FIGURE 2-3: ANALOG INPUT MODEL



PIC18F2423/2523/4423/4523

2.1 A/D Acquisition Requirements

For the A/D Converter to meet its specified accuracy, the charge holding capacitor (CHOLD) must be allowed to fully charge to the input channel voltage level. The analog input model is shown in Figure 2-3.

The source impedance (Rs) and the internal sampling switch (Rss) impedance directly affect the time required to charge the capacitor, CHOLD. The sampling switch (Rss) impedance varies over the device voltage (VDD). The source impedance affects the offset voltage at the analog input (due to pin leakage current). **The maximum recommended impedance for analog sources is 2.5 kΩ.**

After the analog input channel is selected (changed), the channel must be sampled for at least the minimum acquisition time before starting a conversion.

Note: When the conversion is started, the holding capacitor is disconnected from the input pin.

To calculate the minimum acquisition time, Equation 2-1 may be used. This equation assumes that 1/2 LSb error is used (4,096 steps for the A/D). The 1/2 LSb error is the maximum error allowed for the A/D to meet its specified resolution.

Example 2-3 shows the calculation of the minimum required acquisition time, TACQ. This calculation is based on the application system assumptions shown in Table 2-1:

TABLE 2-1: TACQ ASSUMPTIONS

CHOLD	=	25 pF
Rs	=	2.5 kΩ
Conversion Error	≤	1/2 LSb
VDD	=	3V → Rss = 4 kΩ
Temperature	=	85°C (system maximum)

EQUATION 2-1: ACQUISITION TIME

$$\begin{aligned} \text{TACQ} &= \text{Amplifier Settling Time} + \text{Holding Capacitor Charging Time} + \text{Temperature Coefficient} \\ &= \text{TAMP} + \text{TC} + \text{TCOFF} \end{aligned}$$

EQUATION 2-2: A/D MINIMUM CHARGING TIME

$$\begin{aligned} \text{VHOLD} &= (\text{VREF} - (\text{VREF}/4096)) \cdot (1 - e^{-(\text{TC}/\text{CHOLD}(\text{RIC} + \text{RSS} + \text{RS})))} \\ \text{or} \\ \text{TC} &= -(\text{CHOLD})(\text{RIC} + \text{RSS} + \text{RS}) \ln(1/4096) \end{aligned}$$

EQUATION 2-3: CALCULATING THE MINIMUM REQUIRED ACQUISITION TIME

$$\begin{aligned} \text{TACQ} &= \text{TAMP} + \text{TC} + \text{TCOFF} \\ \text{TAMP} &= 0.2 \mu\text{s} \\ \text{TCOFF} &= (\text{Temp} - 25^\circ\text{C})(0.02 \mu\text{s}/^\circ\text{C}) \\ &\quad (85^\circ\text{C} - 25^\circ\text{C})(0.02 \mu\text{s}/^\circ\text{C}) \\ &\quad 1.2 \mu\text{s} \end{aligned}$$

Temperature coefficient is only required for temperatures > 25°C. Below 25°C, TCOFF = 0 ms.

$$\begin{aligned} \text{TC} &= -(\text{CHOLD})(\text{RIC} + \text{RSS} + \text{RS}) \ln(1/4096) \mu\text{s} \\ &\quad -(25 \text{ pF})(1 \text{ k}\Omega + 4 \text{ k}\Omega + 2.5 \text{ k}\Omega) \ln(0.0004883) \mu\text{s} \\ &\quad 1.56 \mu\text{s} \\ \text{TACQ} &= 0.2 \mu\text{s} + 1.56 \mu\text{s} + 1.2 \mu\text{s} \\ &\quad 2.96 \mu\text{s} \end{aligned}$$

2.2 Selecting and Configuring Acquisition Time

The ADCON2 register allows the user to select an acquisition time that occurs each time the GO/DONE bit is set. It also gives users the option of having an automatically determined acquisition time.

Acquisition time may be set with the ACQT<2:0> bits (ADCON2<5:3>), which provide a range of 2 to 20 TAD. When the GO/DONE bit is set, the A/D module continues to sample the input for the selected acquisition time, then automatically begins a conversion. Since the acquisition time is programmed, there may be no need to wait for an acquisition time between selecting a channel and setting the GO/DONE bit.

Manual acquisition time is selected when ACQT<2:0> = 000. When the GO/DONE bit is set, sampling is stopped and a conversion begins. The user is responsible for ensuring the required acquisition time has passed between selecting the desired input channel and setting the GO/DONE bit. This option is also the default Reset state of the ACQT<2:0> bits and is compatible with devices that do not offer programmable acquisition times.

In either case, when the conversion is completed, the GO/DONE bit is cleared, the ADIF flag is set and the A/D begins sampling the currently selected channel again. If an acquisition time is programmed, there is nothing to indicate if the acquisition time has ended or if the conversion has begun.

2.3 Selecting the A/D Conversion Clock

The A/D conversion time per bit is defined as TAD. The A/D conversion requires 13 TAD per 12-bit conversion. The source of the A/D conversion clock is software selectable.

There are seven possible options for TAD:

- 2 TOSC
- 4 TOSC
- 8 TOSC
- 16 TOSC
- 32 TOSC
- 64 TOSC
- Internal RC Oscillator

For correct A/D conversions, the A/D conversion clock (TAD) must be as short as possible, but greater than the minimum TAD. (For more information, see parameter 130 on page 41.)

Table 2-2 shows the resultant TAD times derived from the device operating frequencies and the A/D clock source selected.

TABLE 2-2: TAD vs. DEVICE OPERATING FREQUENCIES

A/D Clock Source (TAD)		Assumes TAD Min. = 0.8 μ s
Operation	ADCS<2:0>	Maximum Fosc
2 TOSC	000	2.50 MHz
4 TOSC	100	5.00 MHz
8 TOSC	001	10.00 MHz
16 TOSC	101	20.00 MHz
32 TOSC	010	40.00 MHz
64 TOSC	110	40.00 MHz
RC ⁽²⁾	x11	1.00 MHz ⁽¹⁾

Note 1: The RC source has a typical TAD time of 2.5 μ s.

2: For device frequencies above 1 MHz, the device must be in Sleep for the entire conversion or a Fosc divider should be used instead; otherwise, the A/D accuracy specification may not be met.

PIC18F2423/2523/4423/4523

REGISTER 3-2: DEVID2: DEVICE ID REGISTER 2 FOR PIC18F2423/2523/4423/4523

R	R	R	R	R	R	R	R
DEV11 ⁽¹⁾	DEV10 ⁽¹⁾	DEV9 ⁽¹⁾	DEV8 ⁽¹⁾	DEV7 ⁽¹⁾	DEV6 ⁽¹⁾	DEV5 ⁽¹⁾	DEV4 ⁽¹⁾
bit 7							bit 0

Legend:

R = Read-only bit

P = Programmable bit

U = Unimplemented bit, read as '0'

-n = Value when device is unprogrammed

u = Unchanged from programmed state

bit 7-0 **DEV<11:4>**: Device ID bits⁽¹⁾

These bits are used with the DEV<3:0> bits in Device ID Register 1 to identify the part number.

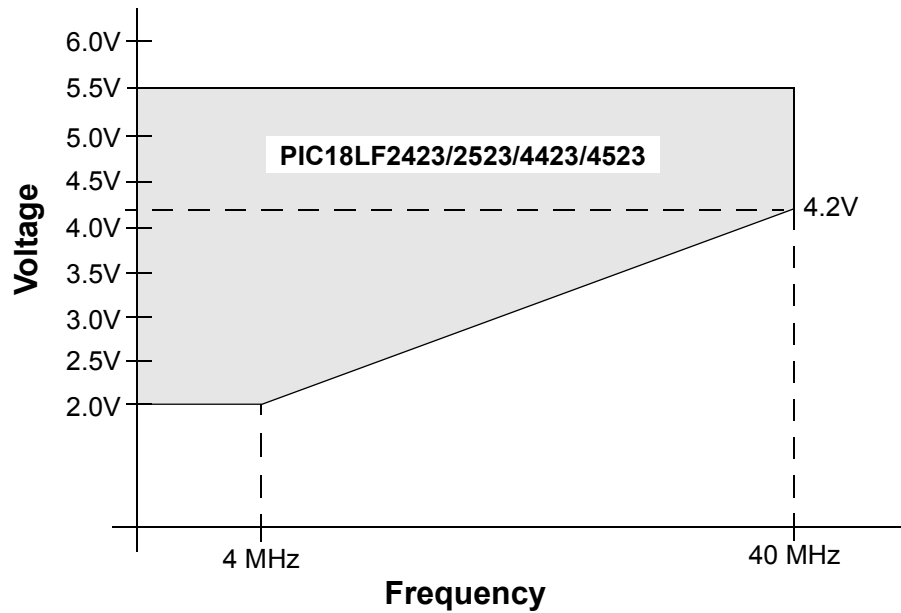
0001 0001 = PIC18F2423/2523 devices

0001 0000 = PIC18F4423/4523 devices

Note 1: These values for DEV<11:4> may be shared with other devices. The specific device is always identified by using the entire DEV<11:0> bit sequence.

PIC18F2423/2523/4423/4523

FIGURE 4-3: PIC18LF2423/2523/4423/4523 VOLTAGE-FREQUENCY GRAPH (INDUSTRIAL)



$$F_{MAX} = (16.36 \text{ MHz/V}) (V_{DDAPP\text{MIN}} - 2.0\text{V}) + 4 \text{ MHz}$$

Note: $V_{DDAPP\text{MIN}}$ is the minimum voltage of the PIC[®] device in the application.

PIC18F2423/2523/4423/4523

**TABLE 4-1: A/D CONVERTER CHARACTERISTICS: PIC18F2423/2523/4423/4523 (INDUSTRIAL)
PIC18LF2423/2523/4423/4523 (INDUSTRIAL)**

Param No.	Sym	Characteristic	Min	Typ	Max	Units	Conditions	
A01	NR	Resolution	—	—	12	bit		$\Delta V_{REF} \geq 3.0V$
A03	EIL	Integral Linearity Error	—	$<\pm 1$	± 2.0	LSB	$V_{DD} = 3.0V$	$\Delta V_{REF} \geq 3.0V$
			—	—	± 2.0	LSB	$V_{DD} = 5.0V$	
A04	EDL	Differential Linearity Error	—	$<\pm 1$	$+1.5/-1.0$	LSB	$V_{DD} = 3.0V$	$\Delta V_{REF} \geq 3.0V$
			—	—	$+1.5/-1.0$	LSB	$V_{DD} = 5.0V$	
A06	EOFF	Offset Error	—	$<\pm 1$	± 5	LSB	$V_{DD} = 3.0V$	$\Delta V_{REF} \geq 3.0V$
			—	—	± 3	LSB	$V_{DD} = 5.0V$	
A07	EGN	Gain Error	—	$<\pm 1$	± 1.25	LSB	$V_{DD} = 3.0V$	$\Delta V_{REF} \geq 3.0V$
			—	—	± 2.00	LSB	$V_{DD} = 5.0V$	
A10	—	Monotonicity	Guaranteed ⁽¹⁾			—		$V_{SS} \leq V_{AIN} \leq V_{REF}$
A20	ΔV_{REF}	Reference Voltage Range ($V_{REFH} - V_{REFL}$)	3	—	$V_{DD} - V_{SS}$	V		For 12-bit resolution.
A21	V_{REFH}	Reference Voltage High	$V_{SS} + 3.0V$	—	$V_{DD} + 0.3V$	V		For 12-bit resolution.
A22	V_{REFL}	Reference Voltage Low	$V_{SS} - 0.3V$	—	$V_{DD} - 3.0V$	V		For 12-bit resolution.
A25	V_{AIN}	Analog Input Voltage	V_{REFL}	—	V_{REFH}	V		
A30	Z_{AIN}	Recommended Impedance of Analog Voltage Source	—	—	2.5	k Ω		
A50	I_{REF}	V_{REF} Input Current ⁽²⁾	—	—	5	μA		During V_{AIN} acquisition. During A/D conversion cycle.
			—	—	150	μA		

- Note 1:** The A/D conversion result never decreases with an increase in the input voltage and has no missing codes.
- Note 2:** V_{REFH} current is from the RA3/AN3/ V_{REF+} pin or V_{DD} , whichever is selected as the V_{REFH} source. V_{REFL} current is from the RA2/AN2/ V_{REF-}/CV_{REF} pin or V_{SS} , whichever is selected as the V_{REFL} source.

APPENDIX E: MIGRATION FROM MID-RANGE TO ENHANCED DEVICES

A detailed discussion of the differences between the mid-range MCU devices (i.e., PIC16CXXX) and the enhanced devices (i.e., PIC18FXXX) is provided in AN716, *"Migrating Designs from PIC16C74A/74B to PIC18C442"*. The changes discussed, while device specific, are generally applicable to all mid-range to enhanced device migrations.

This Application Note is available as Literature Number DS00716.

APPENDIX F: MIGRATION FROM HIGH-END TO ENHANCED DEVICES

A detailed discussion of the migration pathway and differences between the high-end MCU devices (i.e., PIC17CXXX) and the enhanced devices (i.e., PIC18FXXX) is provided in AN726, *"PIC17CXXX to PIC18CXXX Migration"*. This Application Note is available as Literature Number DS00726.

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