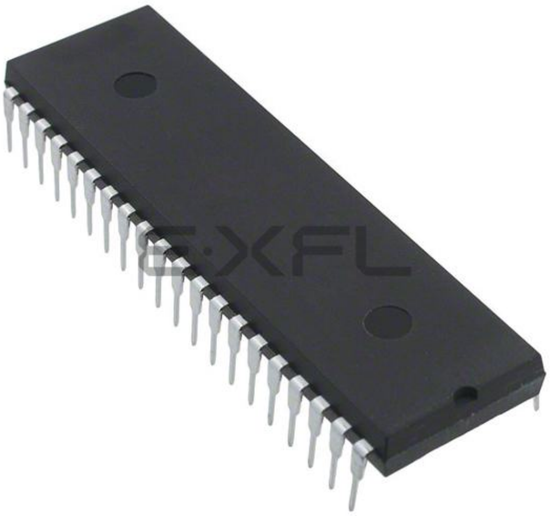

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	40MHz
Connectivity	I²C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, HLVD, POR, PWM, WDT
Number of I/O	36
Program Memory Size	32KB (16K x 16)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	1.5K x 8
Voltage - Supply (Vcc/Vdd)	4.2V ~ 5.5V
Data Converters	A/D 13x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Through Hole
Package / Case	40-DIP (0.600", 15.24mm)
Supplier Device Package	40-PDIP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic18f4523-i-p

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Table of Contents

1.0 DEVICE OVERVIEW

This document contains device-specific information for the following devices:

• PIC18F2423	• PIC18LF2423
• PIC18F2523	• PIC18LF2523
• PIC18F4423	• PIC18LF4423
• PIC18F4523	• PIC18LF4523

> **Note:** This data sheet documents only the devices' features and specifications that are in addition to, or different from, the features and specifications of the PIC18F2420/2520/4420/4520 devices. For information on the features and specifications shared by the PIC18F2423/2523/4423/4523 and PIC18F2420/2520/4420/4520 devices, see the *"PIC18F2420/2520/4420/4520 Data Sheet"* (DS39631).

This family offers the advantages of all PIC18 microcontrollers – namely, high computational performance at an economical price – with the addition of high-endurance, Enhanced Flash program memory. On top of these features, the PIC18F2423/2523/4423/4523 family introduces design enhancements that make these microcontrollers a logical choice for many high-performance, power-sensitive applications.

1.1 New Core Features

1.1.1 nanoWatt TECHNOLOGY

All of the devices in the PIC18F2423/2523/4423/4523 family incorporate a range of features that can significantly reduce power consumption during operation. Key items include:

- **Alternate Run Modes:** By clocking the controller from the Timer1 source or the internal oscillator block, power consumption during code execution can be reduced by as much as 90%.
- **Multiple Idle Modes:** The controller also can run with its CPU core disabled and the peripherals still active. In these states, power consumption can be reduced even further, to as little as 4% of normal operation requirements.
- **On-the-Fly Mode Switching:** The power-managed modes are invoked by user code during operation, allowing the user to incorporate power-saving ideas into their application's software design.
- **Low Consumption in Key Modules:** The power requirements for both Timer1 and the Watchdog Timer are minimized. See **Section 4.0 "Electrical Characteristics"** for values.

1.1.2 MULTIPLE OSCILLATOR OPTIONS AND FEATURES

All of the devices in the PIC18F2423/2523/4423/4523 family offer ten different oscillator options, allowing users a wide range of choices in developing application hardware. These include:

- Four Crystal modes, using crystals or ceramic resonators.
- Two External Clock modes, offering the option of using two pins (oscillator input and a divide-by-4 clock output) or one pin (oscillator input, with the second pin reassigned as general I/O).
- Two External RC Oscillator modes with the same pin options as the External Clock modes.
- An internal oscillator block that offers eight clock frequencies: an 8 MHz clock and an INTRC source (approximately 31 kHz), as well as a range of six user-selectable clock frequencies, between 125 kHz to 4 MHz. This option frees the two oscillator pins for use as additional general purpose I/O.
- A Phase Lock Loop (PLL) frequency multiplier, available to both the High-Speed Crystal and Internal Oscillator modes, allowing clock speeds of up to 40 MHz from the HS clock source. Used with the internal oscillator, the PLL gives users a complete selection of clock speeds, from 31 kHz to 32 MHz, all without using an external crystal or clock circuit.

Besides its availability as a clock source, the internal oscillator block provides a stable reference source that gives the family additional features for robust operation:

- **Fail-Safe Clock Monitor:** Constantly monitors the main clock source against a reference signal provided by the internal oscillator. If a clock failure occurs, the controller is switched to the internal oscillator block, allowing for continued operation or a safe application shutdown.
- **Two-Speed Start-up:** Allows the internal oscillator to serve as the clock source from Power-on Reset, or wake-up from Sleep mode, until the primary clock source is available.

TABLE 1-2: PIC18F2423/2523 PINOUT I/O DESCRIPTIONS

Pin Name	Pin Number		Pin Type	Buffer Type	Description
	PDIP, SOIC	QFN			
$\overline{\text{MCLR}}$/VPP/RE3	1	26			Master Clear (input) or programming voltage (input).
$\overline{\text{MCLR}}$			I	ST	Master Clear (Reset) input. This pin is an active-low Reset to the device.
VPP			P		Programming voltage input.
RE3			I	ST	Digital input.
OSC1/CLKI/RA7	9	6			Oscillator crystal or external clock input.
OSC1			I	ST	Oscillator crystal input or external clock source input. ST buffer when configured in RC mode; CMOS otherwise.
CLKI			I	CMOS	External clock source input. Always associated with pin function, OSC1. (See related OSC1/CLKI, OSC2/CLKO pins.)
RA7			I/O	TTL	General purpose I/O pin.
OSC2/CLKO/RA6	10	7			Oscillator crystal or clock output.
OSC2			O	—	Oscillator crystal output. Connects to crystal or resonator in Crystal Oscillator mode.
CLKO			O	—	In RC mode, OSC2 pin outputs CLKO, which has 1/4 the frequency of OSC1 and denotes the instruction cycle rate.
RA6			I/O	TTL	General purpose I/O pin.

Legend:
TTL = TTL compatible input
ST = Schmitt Trigger input with CMOS levels
O = Output
I^2C = I^2C™/SMBus
CMOS = CMOS compatible input or output
I = Input
P = Power

Note 1: Default assignment for CCP2 when Configuration bit, CCP2MX, is set.

2: Alternate assignment for CCP2 when Configuration bit, CCP2MX, is cleared.

TABLE 1-3: PIC18F4423/4523 PINOUT I/O DESCRIPTIONS

Pin Name	Pin Number			Pin Type	Buffer Type	Description
	PDIP	QFN	TQFP			
$\overline{\text{MCLR}}$/V_{PP}/RE3	1	18	18			Master Clear (input) or programming voltage (input).
$\overline{\text{MCLR}}$				I	ST	Master Clear (Reset) input. This pin is an active-low Reset to the device.
V_{PP}				P		Programming voltage input.
RE3				I	ST	Digital input.
OSC1/CLKI/RA7	13	32	30			Oscillator crystal or external clock input.
OSC1				I	ST	Oscillator crystal input or external clock source input. ST buffer when configured in RC mode; analog otherwise.
CLKI				I	CMOS	External clock source input. Always associated with pin function, OSC1. (See related OSC1/CLKI, OSC2/CLKO pins.)
RA7				I/O	TTL	General purpose I/O pin.
OSC2/CLKO/RA6	14	33	31			Oscillator crystal or clock output.
OSC2				O	—	Oscillator crystal output. Connects to crystal or resonator in Crystal Oscillator mode.
CLKO				O	—	In RC mode, OSC2 pin outputs CLKO, which has 1/4 the frequency of OSC1 and denotes the instruction cycle rate.
RA6				I/O	TTL	General purpose I/O pin.

Legend: TTL = TTL compatible input
ST = Schmitt Trigger input with CMOS levels
O = Output
I^2C = I^2C™/SMBus
CMOS = CMOS compatible input or output
I = Input
P = Power

Note 1: Default assignment for CCP2 when Configuration bit, CCP2MX, is set.

2: Alternate assignment for CCP2 when Configuration bit, CCP2MX, is cleared.

TABLE 1-3: PIC18F4423/4523 PINOUT I/O DESCRIPTIONS (CONTINUED)

Pin Name	Pin Number			Pin Type	Buffer Type	Description
	PDIP	QFN	TQFP			
						PORTA is a bidirectional I/O port.
RA0/AN0	2	19	19			
RA0				I/O	TTL	Digital I/O.
AN0				I	Analog	Analog Input 0.
RA1/AN1	3	20	20			
RA1				I/O	TTL	Digital I/O.
AN1				I	Analog	Analog Input 1.
RA2/AN2/VREF-/CVREF	4	21	21			
RA2				I/O	TTL	Digital I/O.
AN2				I	Analog	Analog Input 2.
VREF-				I	Analog	A/D reference voltage (low) input.
CVREF				O	Analog	Comparator reference voltage output.
RA3/AN3/VREF+	5	22	22			
RA3				I/O	TTL	Digital I/O.
AN3				I	Analog	Analog Input 3.
VREF+				I	Analog	A/D reference voltage (high) input.
RA4/T0CKI/C1OUT	6	23	23			
RA4				I/O	ST	Digital I/O.
T0CKI				I	ST	Timer0 external clock input.
C1OUT				O	—	Comparator 1 output.
RA5/AN4/$\overline{\text{SS}}$/HLVDIN/C2OUT	7	24	24			
RA5				I/O	TTL	Digital I/O.
AN4				I	Analog	Analog Input 4.
$\overline{\text{SS}}$				I	TTL	SPI slave select input.
HLVDIN				I	Analog	High/Low-Voltage Detect input.
C2OUT				O	—	Comparator 2 output.
RA6						See the OSC2/CLKO/RA6 pin.
RA7						See the OSC1/CLKI/RA7 pin.

Legend:
TTL = TTL compatible input
ST = Schmitt Trigger input with CMOS levels
O = Output
I^{2}C = I^{2}C™/SMBus
CMOS = CMOS compatible input or output
I = Input
P = Power

Note 1: Default assignment for CCP2 when Configuration bit, CCP2MX, is set.

2: Alternate assignment for CCP2 when Configuration bit, CCP2MX, is cleared.

TABLE 1-3: PIC18F4423/4523 PINOUT I/O DESCRIPTIONS (CONTINUED)

Pin Name	Pin Number			Pin Type	Buffer Type	Description
	PDIP	QFN	TQFP			
						PORTC is a bidirectional I/O port.
RC0/T1OSO/T13CKI	15	34	32			
RC0				I/O	ST	Digital I/O.
T1OSO				O	—	Timer1 oscillator output.
T13CKI				I	ST	Timer1/Timer3 external clock input.
RC1/T1OSI/CCP2	16	35	35			
RC1				I/O	ST	Digital I/O.
T1OSI				I	CMOS	Timer1 oscillator input.
CCP2(2)				I/O	ST	Capture 2 input/Compare 2 output/PWM2 output.
RC2/CCP1/P1A	17	36	36			
RC2				I/O	ST	Digital I/O.
CCP1				I/O	ST	Capture 1 input/Compare 1 output/PWM1 output.
P1A				O	—	Enhanced CCP1 output.
RC3/SCK/SCL	18	37	37			
RC3				I/O	ST	Digital I/O.
SCK				I/O	ST	Synchronous serial clock input/output for SPI mode.
SCL				I/O	I^2C	Synchronous serial clock input/output for I^2C™ mode.
RC4/SDI/SDA	23	42	42			
RC4				I/O	ST	Digital I/O.
SDI				I	ST	SPI data in.
SDA				I/O	I^2C	I^2C data I/O.
RC5/SDO	24	43	43			
RC5				I/O	ST	Digital I/O.
SDO				O	—	SPI data out.
RC6/TX/CK	25	44	44			
RC6				I/O	ST	Digital I/O.
TX				O	—	EUSART asynchronous transmit.
CK				I/O	ST	EUSART synchronous clock (see related RX/DT).
RC7/RX/DT	26	1	1			
RC7				I/O	ST	Digital I/O.
RX				I	ST	EUSART asynchronous receive.
DT				I/O	ST	EUSART synchronous data (see related TX/CK).

Legend:
TTL = TTL compatible input
ST = Schmitt Trigger input with CMOS levels
O = Output
I^2C = I^2C™/SMBus
CMOS = CMOS compatible input or output
I = Input
P = Power

Note 1: Default assignment for CCP2 when Configuration bit, CCP2MX, is set.

2: Alternate assignment for CCP2 when Configuration bit, CCP2MX, is cleared.

TABLE 1-3: PIC18F4423/4523 PINOUT I/O DESCRIPTIONS (CONTINUED)

Pin Name	Pin Number			Pin Type	Buffer Type	Description
	PDIP	QFN	TQFP			
						PORTD is a bidirectional I/O port or a Parallel Slave Port (PSP) for interfacing to a microprocessor port. These pins have TTL input buffers when the PSP module is enabled.
RD0/PSP0	19	38	38			
RD0				I/O	ST	Digital I/O.
PSP0				I/O	TTL	Parallel Slave Port data.
RD1/PSP1	20	39	39			
RD1				I/O	ST	Digital I/O.
PSP1				I/O	TTL	Parallel Slave Port data.
RD2/PSP2	21	40	40			
RD2				I/O	ST	Digital I/O.
PSP2				I/O	TTL	Parallel Slave Port data.
RD3/PSP3	22	41	41			
RD3				I/O	ST	Digital I/O.
PSP3				I/O	TTL	Parallel Slave Port data.
RD4/PSP4	27	2	2			
RD4				I/O	ST	Digital I/O.
PSP4				I/O	TTL	Parallel Slave Port data.
RD5/PSP5/P1B	28	3	3			
RD5				I/O	ST	Digital I/O.
PSP5				I/O	TTL	Parallel Slave Port data.
P1B				O	—	Enhanced CCP1 output.
RD6/PSP6/P1C	29	4	4			
RD6				I/O	ST	Digital I/O.
PSP6				I/O	TTL	Parallel Slave Port data.
P1C				O	—	Enhanced CCP1 output.
RD7/PSP7/P1D	30	5	5			
RD7				I/O	ST	Digital I/O.
PSP7				I/O	TTL	Parallel Slave Port data.
P1D				O	—	Enhanced CCP1 output.

Legend:
TTL = TTL compatible input
ST = Schmitt Trigger input with CMOS levels
O = Output
I^{2}C = I^{2}C™/SMBus
CMOS = CMOS compatible input or output
I = Input
P = Power

Note 1: Default assignment for CCP2 when Configuration bit, CCP2MX, is set.

2: Alternate assignment for CCP2 when Configuration bit, CCP2MX, is cleared.

NOTES:

The analog reference voltage is software selectable to either the device's positive and negative supply voltage (VDD and VSS), or the voltage level on the RA3/AN3/VREF+ and RA2/AN2/VREF-/CVREF pins.

The A/D Converter has a unique feature of being able to operate while the device is in Sleep mode. To operate in Sleep, the A/D conversion clock must be derived from the A/D's internal RC oscillator.

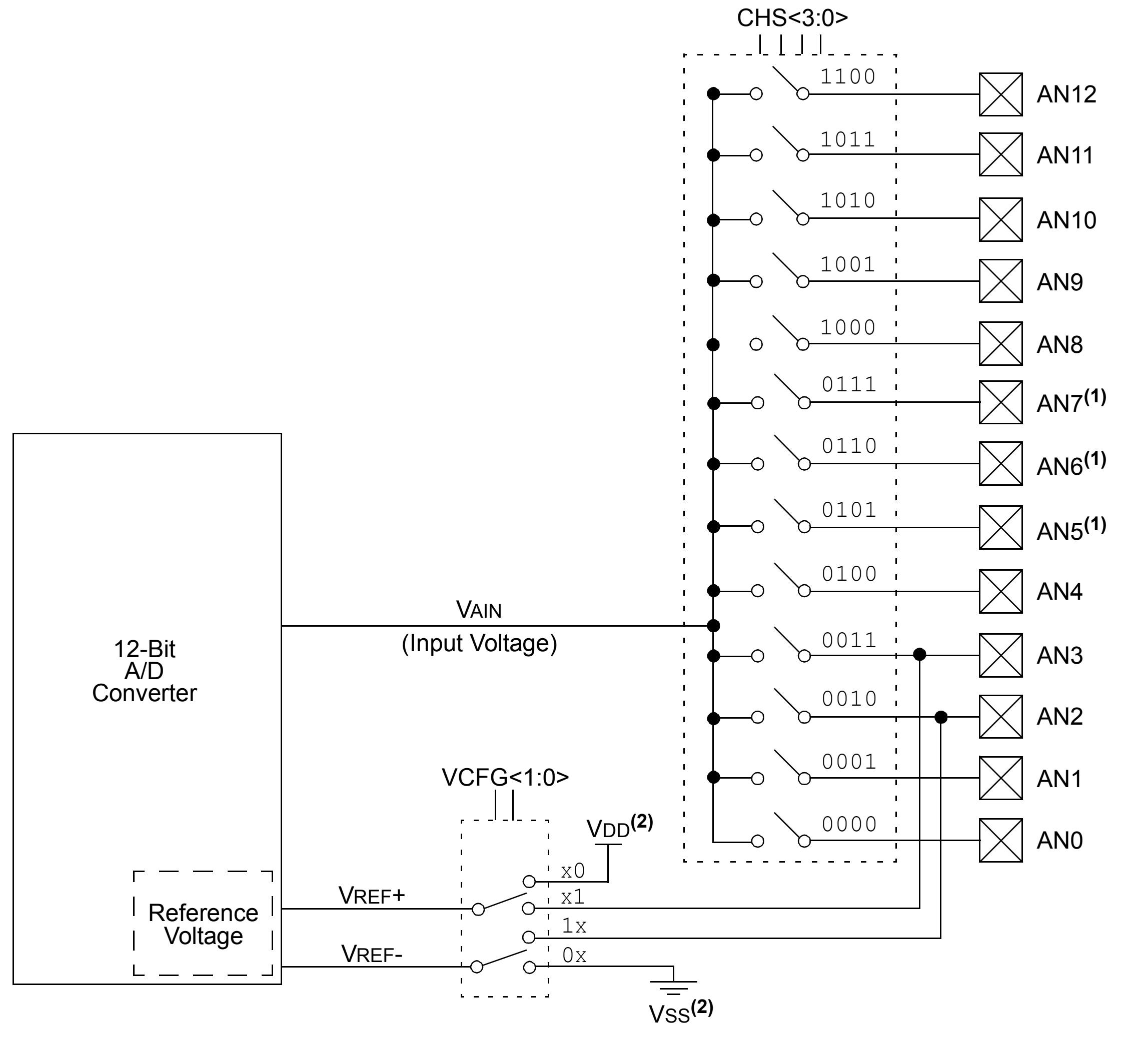
The output of the sample and hold is the input into the converter, which generates the result via successive approximation.

A device Reset forces all registers to their Reset state. This forces the A/D module to be turned off and any conversion in progress is aborted.

Each port pin associated with the A/D Converter can be configured as an analog input or as a digital I/O. The ADRESH and ADRESL registers contain the result of the A/D conversion. When the A/D conversion is complete, the result is loaded into the ADRESH:ADRESL register pair, the GO/$\overline{\text{DONE}}$ bit (ADCON0<1>) is cleared and A/D Interrupt Flag bit, ADIF, is set.

The block diagram of the A/D module is shown in Figure 2-1.

FIGURE 2-1: A/D BLOCK DIAGRAM



Note 1: Channels, AN5 through AN7, are not available on PIC18F2423/2523 devices.

2: I/O pins have diode protection to VDD and VSS.

The value in the ADRESH:ADRESL registers is unknown following POR and BOR Resets and is not affected by any other Reset.

After the A/D module has been configured as desired, the selected channel must be acquired before the conversion is started. The analog input channels must have their corresponding TRIS bits selected as inputs. To determine acquisition time, see **Section 2.1 “A/D Acquisition Requirements”**.

After this acquisition time has elapsed, the A/D conversion can be started. An acquisition time can be programmed to occur between setting the GO/$\overline{\text{DONE}}$ bit and the actual start of the conversion.

The following steps should be followed to perform an A/D conversion:

1. Configure the A/D module:
   - Configure analog pins, voltage reference and digital I/O (ADCON1)
   - Select A/D input channel (ADCON0)
   - Select A/D acquisition time (ADCON2)
   - Select A/D conversion clock (ADCON2)
   - Turn on the A/D module (ADCON0)
2. Configure the A/D interrupt (if desired):
   - Clear ADIF bit
   - Set ADIE bit
   - Set GIE bit
3. Wait the required acquisition time (if required).
4. Start conversion by setting the GO/$\overline{\text{DONE}}$ bit (ADCON0<1>).
5. Wait for the A/D conversion to complete by either:
   - Polling for the GO/$\overline{\text{DONE}}$ bit to be cleared

   OR

   - Waiting for the A/D interrupt
6. Read the A/D Result registers (ADRESH:ADRESL) and clear the ADIF bit, if required.
7. For the next conversion, go to step 1 or step 2, as required.

   The A/D conversion time per bit is defined as TAD. A minimum wait of 2 TAD is required before the next acquisition starts.

FIGURE 2-2: A/D TRANSFER FUNCTION

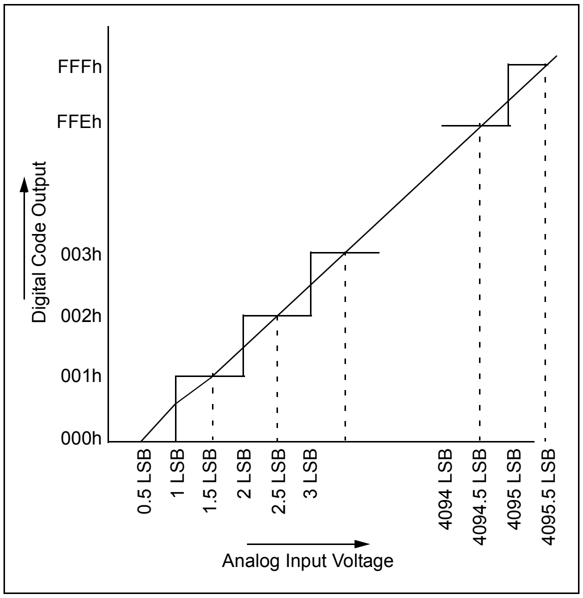
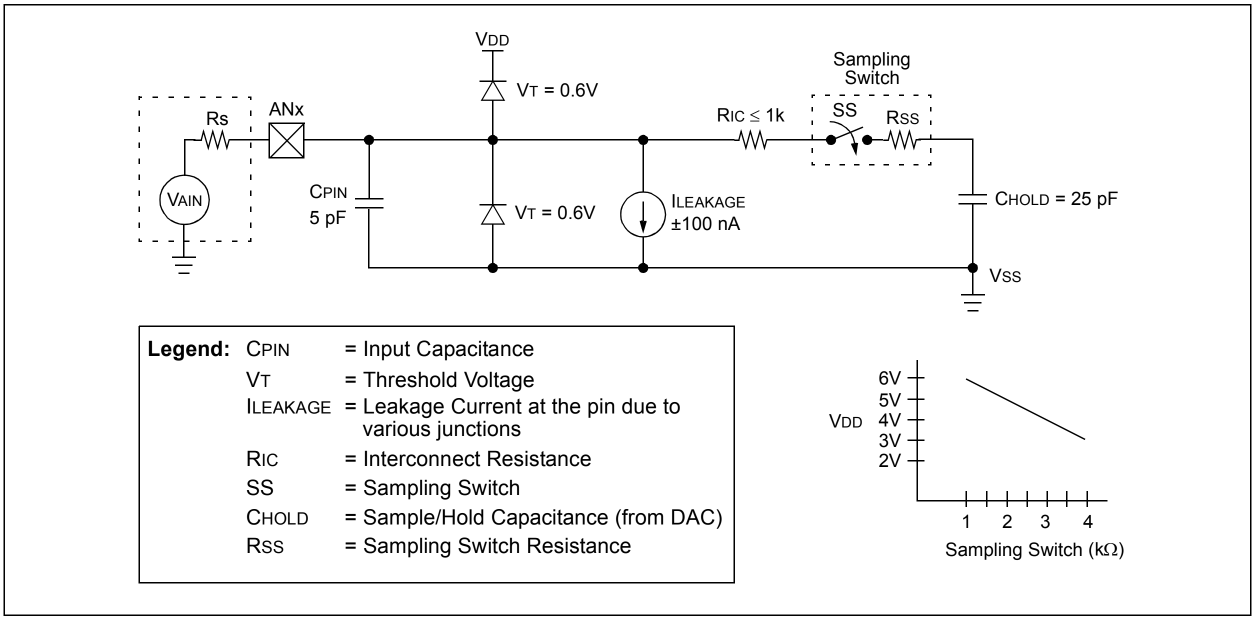


FIGURE 2-3: ANALOG INPUT MODEL



2.1 A/D Acquisition Requirements

For the A/D Converter to meet its specified accuracy, the charge holding capacitor (C_{HOLD}) must be allowed to fully charge to the input channel voltage level. The analog input model is shown in Figure 2-3.

The source impedance (R_S) and the internal sampling switch (R_{SS}) impedance directly affect the time required to charge the capacitor, C_{HOLD}. The sampling switch (R_{SS}) impedance varies over the device voltage (V_{DD}). The source impedance affects the offset voltage at the analog input (due to pin leakage current). **The maximum recommended impedance for analog sources is 2.5 kΩ**.

After the analog input channel is selected (changed), the channel must be sampled for at least the minimum acquisition time before starting a conversion.

Note:	When the conversion is started, the holding capacitor is disconnected from the input pin.

To calculate the minimum acquisition time, Equation 2-1 may be used. This equation assumes that 1/2 LSb error is used (4,096 steps for the A/D). The 1/2 LSb error is the maximum error allowed for the A/D to meet its specified resolution.

Example 2-3 shows the calculation of the minimum required acquisition time, T_{ACQ}. This calculation is based on the application system assumptions shown in Table 2-1:

TABLE 2-1: T_{ACQ} ASSUMPTIONS

C_{HOLD}	=	25 pF
Rs	=	2.5 kΩ
Conversion Error	≤	1/2 LSb
V_{DD}	=	3V → Rss = 4 kΩ
Temperature	=	85°C (system maximum)

EQUATION 2-1: ACQUISITION TIME

$$\begin{aligned} T_{ACQ} &= \text{Amplifier Settling Time} + \text{Holding Capacitor Charging Time} + \text{Temperature Coefficient} \\ &= T_{AMP} + T_C + T_{COFF} \end{aligned}$$

EQUATION 2-2: A/D MINIMUM CHARGING TIME

$$V_{HOLD} = (V_{REF} - (V_{REF}/4096)) \bullet (1 - e^{(-T_C/C_{HOLD}(R_{IC} + R_{SS} + R_S))})$$

or

$$T_C = -(C_{HOLD})(R_{IC} + R_{SS} + R_S)\ \ln(1/4096)$$

EQUATION 2-3: CALCULATING THE MINIMUM REQUIRED ACQUISITION TIME

$$\begin{aligned} T_{ACQ} &= T_{AMP} + T_C + T_{COFF} \\ T_{AMP} &= 0.2\ \mu s \\ T_{COFF} &= (\text{Temp} - 25°C)(0.02\ \mu s/°C) \\ & (85°C - 25°C)(0.02\ \mu s/°C) \\ & 1.2\ \mu s \end{aligned}$$

Temperature coefficient is only required for temperatures > 25°C. Below 25°C, T_{COFF} = 0 ms.

$$\begin{aligned} T_C &= -(C_{HOLD})(R_{IC} + R_{SS} + R_S)\ \ln(1/4095)\ \mu s \\ & -(25\ pF)\ (1\ k\Omega + 4\ k\Omega + 2.5\ k\Omega)\ \ln(0.0004883)\ \mu s \\ & 1.56\ \mu s \\ T_{ACQ} &= 0.2\ \mu s + 1.56\ \mu s + 1.2\ \mu s \\ & 2.96\ \mu s \end{aligned}$$

2.2 Selecting and Configuring Acquisition Time

The ADCON2 register allows the user to select an acquisition time that occurs each time the GO/$\overline{\text{DONE}}$ bit is set. It also gives users the option of having an automatically determined acquisition time.

Acquisition time may be set with the ACQT<2:0> bits (ADCON2<5:3>), which provide a range of 2 to 20 TAD. When the GO/$\overline{\text{DONE}}$ bit is set, the A/D module continues to sample the input for the selected acquisition time, then automatically begins a conversion. Since the acquisition time is programmed, there may be no need to wait for an acquisition time between selecting a channel and setting the GO/$\overline{\text{DONE}}$ bit.

Manual acquisition time is selected when ACQT<2:0> = `000`. When the GO/$\overline{\text{DONE}}$ bit is set, sampling is stopped and a conversion begins. The user is responsible for ensuring the required acquisition time has passed between selecting the desired input channel and setting the GO/$\overline{\text{DONE}}$ bit. This option is also the default Reset state of the ACQT<2:0> bits and is compatible with devices that do not offer programmable acquisition times.

In either case, when the conversion is completed, the GO/$\overline{\text{DONE}}$ bit is cleared, the ADIF flag is set and the A/D begins sampling the currently selected channel again. If an acquisition time is programmed, there is nothing to indicate if the acquisition time has ended or if the conversion has begun.

2.3 Selecting the A/D Conversion Clock

The A/D conversion time per bit is defined as TAD. The A/D conversion requires 13 TAD per 12-bit conversion. The source of the A/D conversion clock is software selectable.

There are seven possible options for TAD:

- 2 TOSC
- 4 TOSC
- 8 TOSC
- 16 TOSC
- 32 TOSC
- 64 TOSC
- Internal RC Oscillator

For correct A/D conversions, the A/D conversion clock (TAD) must be as short as possible, but greater than the minimum TAD. (For more information, see parameter 130 on page 41.)

Table 2-2 shows the resultant TAD times derived from the device operating frequencies and the A/D clock source selected.

TABLE 2-2: TAD vs. DEVICE OPERATING FREQUENCIES

A/D Clock Source (TAD)		**Assumes TAD Min. = 0.8 μs**
Operation	**ADCS<2:0>**	**Maximum FOSC**
2 TOSC	`000`	2.50 MHz
4 TOSC	`100`	5.00 MHz
8 TOSC	`001`	10.00 MHz
16 TOSC	`101`	20.00 MHz
32 TOSC	`010`	40.00 MHz
64 TOSC	`110`	40.00 MHz
RC[2]	`x11`	1.00 MHz[1]

Note 1: The RC source has a typical TAD time of 2.5 μs.

2: For device frequencies above 1 MHz, the device must be in Sleep for the entire conversion or a FOSC divider should be used instead; otherwise, the A/D accuracy specification may not be met.

TABLE 4-1: A/D CONVERTER CHARACTERISTICS: PIC18F2423/2523/4423/4523 (INDUSTRIAL)
PIC18LF2423/2523/4423/4523 (INDUSTRIAL)

Param No.	Sym	Characteristic	Min	Typ	Max	Units	Conditions	
A01	NR	Resolution	—	—	12	bit		ΔVREF ≥ 3.0V
A03	EIL	Integral Linearity Error	—	<±1	±2.0	LSB	VDD = 3.0V	ΔVREF ≥ 3.0V
			—	—	±2.0	LSB	VDD = 5.0V	
A04	EDL	Differential Linearity Error	—	<±1	+1.5/-1.0	LSB	VDD = 3.0V	ΔVREF ≥ 3.0V
			—	—	+1.5/-1.0	LSB	VDD = 5.0V	
A06	EOFF	Offset Error	—	<±1	±5	LSB	VDD = 3.0V	ΔVREF ≥ 3.0V
			—	—	±3	LSB	VDD = 5.0V	
A07	EGN	Gain Error	—	<±1	±1.25	LSB	VDD = 3.0V	ΔVREF ≥ 3.0V
			—	—	±2.00	LSB	VDD = 5.0V	
A10	—	Monotonicity	Guaranteed(1)			—		VSS ≤ VAIN ≤ VREF
A20	ΔVREF	Reference Voltage Range (VREFH – VREFL)	3	—	VDD – VSS	V		For 12-bit resolution.
A21	VREFH	Reference Voltage High	VSS + 3.0V	—	VDD + 0.3V	V		For 12-bit resolution.
A22	VREFL	Reference Voltage Low	VSS – 0.3V	—	VDD – 3.0V	V		For 12-bit resolution.
A25	VAIN	Analog Input Voltage	VREFL	—	VREFH	V		
A30	ZAIN	Recommended Impedance of Analog Voltage Source	—	—	2.5	kΩ		
A50	IREF	VREF Input Current(2)	— —	— —	5 150	μA μA		During VAIN acquisition. During A/D conversion cycle.

Note 1: The A/D conversion result never decreases with an increase in the input voltage and has no missing codes.

2: VREFH current is from the RA3/AN3/VREF+ pin or VDD, whichever is selected as the VREFH source. VREFL current is from the RA2/AN2/VREF-/CVREF pin or VSS, whichever is selected as the VREFL source.

APPENDIX C: CONVERSION CONSIDERATIONS

This appendix discusses the considerations for converting from previous versions of a device to the ones listed in this data sheet. Typically, these changes are due to the differences in the process technology used. An example of this type of conversion is from a PIC16C74A to a PIC16C74B.

Not Applicable

APPENDIX D: MIGRATION FROM BASELINE TO ENHANCED DEVICES

This section discusses how to migrate from a Baseline device (i.e., PIC16C5X) to an Enhanced MCU device (i.e., PIC18FXXX).

The following are the list of modifications over the PIC16C5X microcontroller family:

Not Currently Available

APPENDIX E: MIGRATION FROM MID-RANGE TO ENHANCED DEVICES

A detailed discussion of the differences between the mid-range MCU devices (i.e., PIC16CXXX) and the enhanced devices (i.e., PIC18FXXX) is provided in *AN716, "Migrating Designs from PIC16C74A/74B to PIC18C442"*. The changes discussed, while device specific, are generally applicable to all mid-range to enhanced device migrations.

This Application Note is available as Literature Number DS00716.

APPENDIX F: MIGRATION FROM HIGH-END TO ENHANCED DEVICES

A detailed discussion of the migration pathway and differences between the high-end MCU devices (i.e., PIC17CXXX) and the enhanced devices (i.e., PIC18FXXX) is provided in *AN726, "PIC17CXXX to PIC18CXXX Migration*". This Application Note is available as Literature Number DS00726.

NOTES:

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