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Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	40MHz
Connectivity	I ² C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, HLVD, POR, PWM, WDT
Number of I/O	36
Program Memory Size	32KB (16K x 16)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	1.5K x 8
Voltage - Supply (Vcc/Vdd)	4.2V ~ 5.5V
Data Converters	A/D 13x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-VQFN Exposed Pad
Supplier Device Package	44-QFN (8x8)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic18f4523t-i-ml



MICROCHIP

PIC18F2423/2523/4423/4523

28/40/44-Pin, Enhanced Flash Microcontrollers with 12-Bit A/D and nanoWatt Technology

Power Management Features:

- Run: CPU on, Peripherals on
- Idle: CPU off, Peripherals on
- Sleep: CPU off, Peripherals off
- Ultra Low 50 nA Input Leakage
- Run mode Currents Down to 11 μ A Typical
- Idle mode Currents Down to 2.5 μ A Typical
- Sleep mode Current Down to 100 μ A Typical
- Timer1 Oscillator: 900 nA, 32 kHz, 2V
- Watchdog Timer: 1.4 μ A, 2V Typical
- Two-Speed Oscillator Start-up

Flexible Oscillator Structure:

- Four Crystal modes, up to 40 MHz
- 4x Phase Lock Loop (PLL) – Available for Crystal and Internal Oscillators
- Two External RC modes, up to 4 MHz
- Two External Clock modes, up to 40 MHz
- Internal Oscillator Block:
 - Fast wake from Sleep and Idle, 1 μ s typical
 - 8 user-selectable frequencies, from 31 kHz to 8 MHz
 - Provides a complete range of clock speeds, from 31 kHz to 32 MHz, when used with PLL
 - User-tunable to Compensate for Frequency Drift
- Secondary Oscillator using Timer1 @ 32 kHz
- Fail-Safe Clock Monitor:
 - Allows for safe shutdown if peripheral clock stops

Peripheral Highlights:

- 12-Bit, Up to 13-Channel Analog-to-Digital Converter module (A/D):
 - Auto-acquisition capability
 - Conversion available during Sleep mode
- Dual Analog Comparators with Input Multiplexing
- High-Current Sink/Source 25 mA/25 mA
- Three Programmable External Interrupts
- Four Input Change Interrupts
- Up to Two Capture/Compare/PWM (CCP) modules, One with Auto-Shutdown (28-pin devices)
- Enhanced Capture/Compare/PWM (ECCP) module (40/44-pin devices only):
 - One, two or four PWM outputs
 - Selectable polarity
 - Programmable dead time
 - Auto-shutdown and auto-restart

Peripheral Highlights (Continued):

- Master Synchronous Serial Port (MSSP) module Supporting 3-Wire SPI (all four modes) and I²C™ Master and Slave modes
- Enhanced USART module:
 - Support for RS-485, RS-232 and LIN/J2602
 - RS-232 operation using internal oscillator block (no external crystal required)
 - Auto-wake-up on Start bit
 - Auto-Baud Detect (ABD)

Special Microcontroller Features:

- C Compiler Optimized Architecture: Optional Extended Instruction Set Designed to Optimize Re-Entrant Code
- 100,000 Erase/Write Cycle, Enhanced Flash Program Memory Typical
- 1,000,000 Erase/Write Cycle, Data EEPROM Memory Typical
- Flash/Data EEPROM Retention: 100 Years Typical
- Self-Programmable under Software Control
- Priority Levels for Interrupts
- 8 x 8 Single-Cycle Hardware Multiplier
- Extended Watchdog Timer (WDT): Programmable Period, from 4 ms to 131s
- Single-Supply In-Circuit Serial Programming™ (ICSP™) via Two Pins
- In-Circuit Debug (ICD) via Two Pins
- Operating Voltage Range: 2.0V to 5.5V
- Programmable, 16-Level High/Low-Voltage Detection (HLVD) module: Supports Interrupt on High/Low-Voltage Detection
- Programmable Brown-out Reset (BOR): With Software-Enable Option

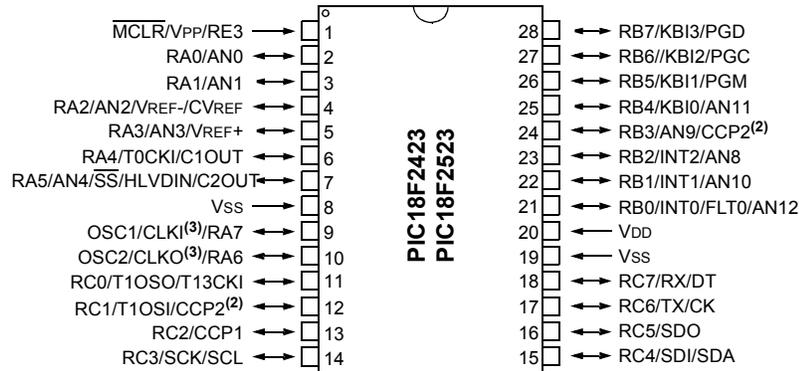
Note: This document is supplemented by the "PIC18F2420/2520/4420/4520 Data Sheet" (DS39631). See **Section 1.0 "Device Overview"**.

Device	Program Memory		Data Memory		I/O	12-Bit A/D (ch)	CCP/ECCP (PWM)	MSSP		EUSART	Comp.	Timers 8/16-Bit
	Flash (bytes)	# Single-Word Instructions	SRAM (bytes)	EEPROM (bytes)				SPI	Master I ² C™			
PIC18F2423	16K	8192	768	256	25	10	2/0	Y	Y	1	2	1/3
PIC18F2523	32K	16384	1536	256	25	10	2/0	Y	Y	1	2	1/3
PIC18F4423	16K	8192	768	256	36	13	1/1	Y	Y	1	2	1/3
PIC18F4523	32K	16384	1536	256	36	13	1/1	Y	Y	1	2	1/3

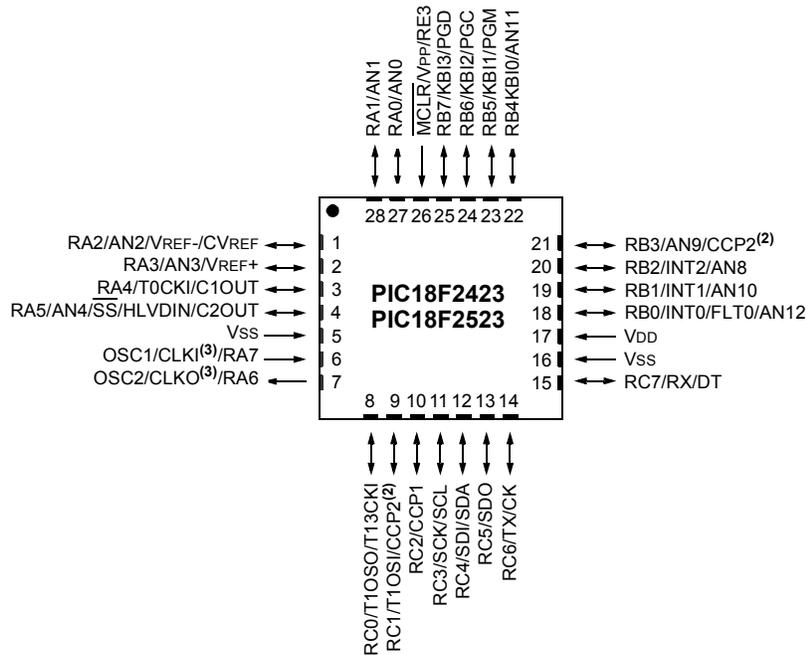
PIC18F2423/2523/4423/4523

Pin Diagrams

28-Pin PDIP, SOIC



28-Pin QFN⁽¹⁾

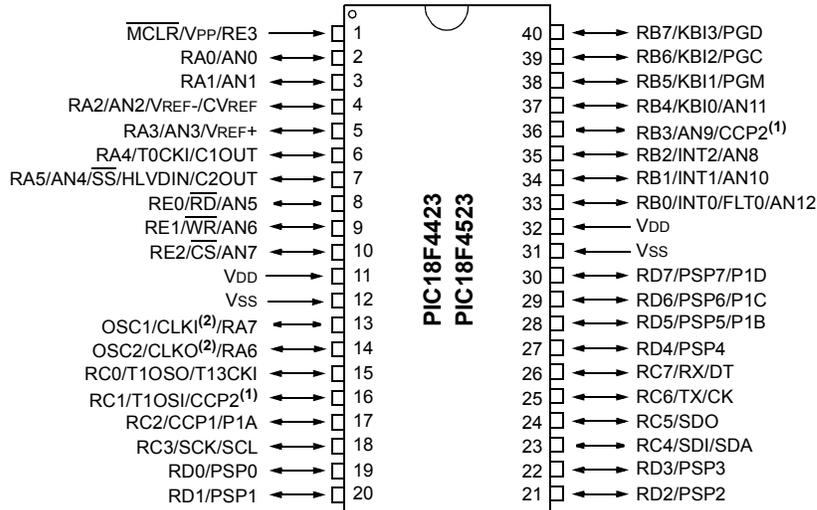


- Note 1:** It is recommended to connect the bottom pad of QFN package parts to Vss.
Note 2: RB3 is the alternate pin for CCP2 multiplexing.
Note 3: OSC1/CLKI and OSC2/CLKO are only available in select oscillator modes and when these pins are not being used as digital I/O. For additional information, see **Section 2.0 "Oscillator Configurations"** of the "PIC18F2420/2520/4420/4520 Data Sheet" (DS39631).

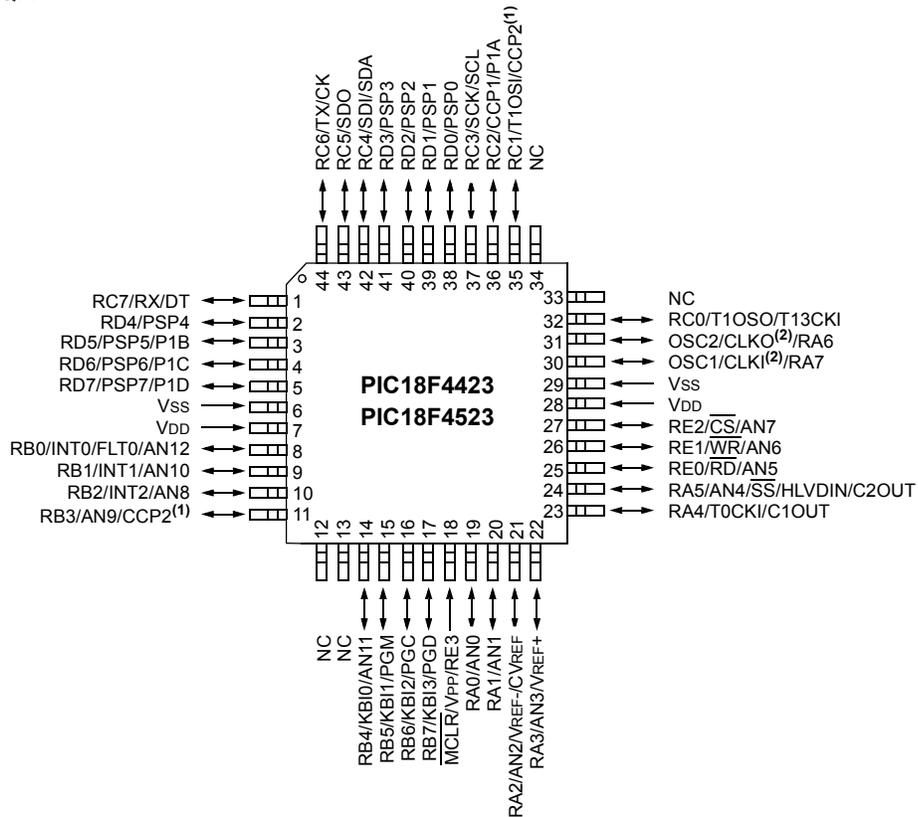
PIC18F2423/2523/4423/4523

Pin Diagrams (Continued)

40-Pin PDIP



44-Pin TQFP



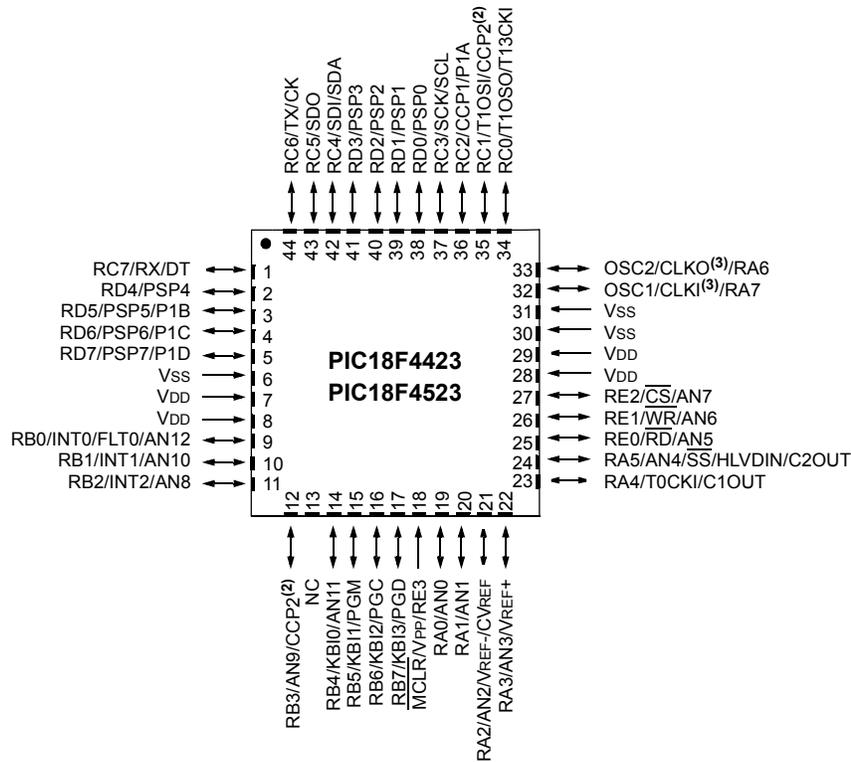
Note 1: RB3 is the alternate pin for CCP2 multiplexing.

Note 2: OSC1/CLKI and OSC2/CLKO are only available in select oscillator modes and when these pins are not being used as digital I/O. For additional information, see **Section 2.0 "Oscillator Configurations"** of the "PIC18F2420/2520/4420/4520 Data Sheet" (DS39631).

PIC18F2423/2523/4423/4523

Pin Diagrams (Continued)

44-Pin QFN⁽¹⁾



- Note 1:** It is recommended to connect the bottom pad of QFN package parts to VSS.
- Note 2:** RB3 is the alternate pin for CCP2 multiplexing.
- Note 3:** OSC1/CLKI and OSC2/CLKO are only available in select oscillator modes and when these pins are not being used as digital I/O. For additional information, see **Section 2.0 "Oscillator Configurations"** of the "PIC18F2420/2520/4420/4520 Data Sheet" (DS39631).

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An errata sheet, describing minor operational differences from the data sheet and recommended workarounds, may exist for current devices. As device/documentation issues become known to us, we will publish an errata sheet. The errata will specify the revision of silicon and revision of document to which it applies.

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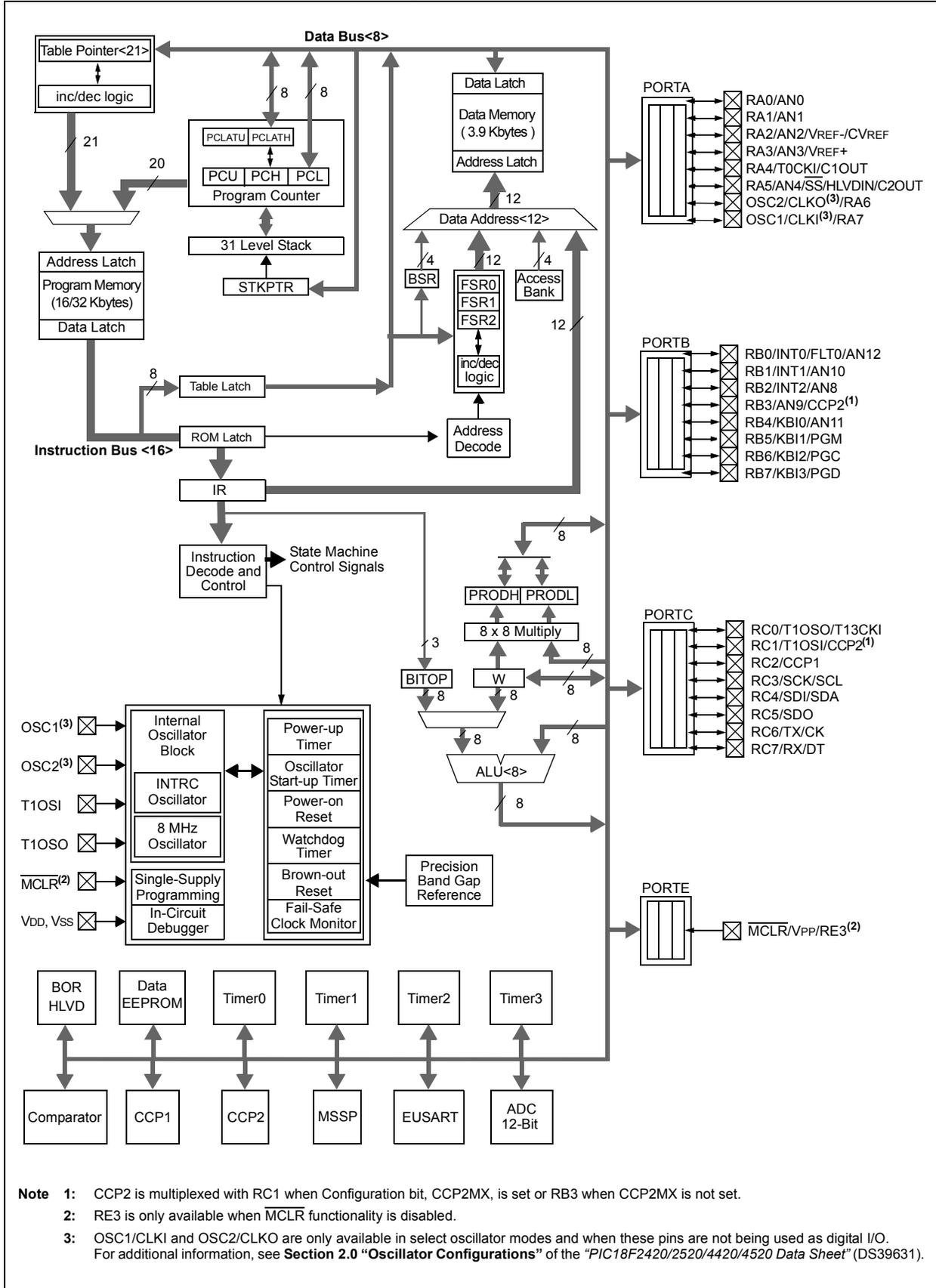
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PIC18F2423/2523/4423/4523

FIGURE 1-1: PIC18F2423/2523 (28-PIN) BLOCK DIAGRAM



PIC18F2423/2523/4423/4523

TABLE 1-3: PIC18F4423/4523 PINOUT I/O DESCRIPTIONS

Pin Name	Pin Number			Pin Type	Buffer Type	Description
	PDIP	QFN	TQFP			
MCLR/VPP/RE3 MCLR VPP RE3	1	18	18	I P I	ST ST	Master Clear (input) or programming voltage (input). Master Clear (Reset) input. This pin is an active-low Reset to the device. Programming voltage input. Digital input.
OSC1/CLKI/RA7 OSC1 CLKI RA7	13	32	30	I I I/O	ST CMOS TTL	Oscillator crystal or external clock input. Oscillator crystal input or external clock source input. ST buffer when configured in RC mode; analog otherwise. External clock source input. Always associated with pin function, OSC1. (See related OSC1/CLKI, OSC2/CLKO pins.) General purpose I/O pin.
OSC2/CLKO/RA6 OSC2 CLKO RA6	14	33	31	O O I/O	— — TTL	Oscillator crystal or clock output. Oscillator crystal output. Connects to crystal or resonator in Crystal Oscillator mode. In RC mode, OSC2 pin outputs CLKO, which has 1/4 the frequency of OSC1 and denotes the instruction cycle rate. General purpose I/O pin.

Legend: TTL = TTL compatible input CMOS = CMOS compatible input or output
 ST = Schmitt Trigger input with CMOS levels I = Input
 O = Output P = Power
 I²C = I²C™/SMBus

- Note 1:** Default assignment for CCP2 when Configuration bit, CCP2MX, is set.
2: Alternate assignment for CCP2 when Configuration bit, CCP2MX, is cleared.

PIC18F2423/2523/4423/4523

TABLE 1-3: PIC18F4423/4523 PINOUT I/O DESCRIPTIONS (CONTINUED)

Pin Name	Pin Number			Pin Type	Buffer Type	Description
	PDIP	QFN	TQFP			
RB0/INT0/FLT0/AN12	33	9	8	I/O	TTL	PORTB is a bidirectional I/O port. PORTB can be software programmed for internal weak pull-ups on all inputs. Digital I/O. External Interrupt 0. PWM Fault input for Enhanced CCP1. Analog Input 12.
RB0				I	ST	
INT0				I	ST	
FLT0				I	Analog	
AN12				I	Analog	
RB1/INT1/AN10	34	10	9	I/O	TTL	Digital I/O. External Interrupt 1. Analog Input 10.
RB1				I	ST	
INT1				I	Analog	
AN10						
RB2/INT2/AN8	35	11	10	I/O	TTL	Digital I/O. External Interrupt 2. Analog Input 8.
RB2				I	ST	
INT2				I	Analog	
AN8						
RB3/AN9/CCP2	36	12	11	I/O	TTL	Digital I/O. Analog Input 9. Capture 2 input/Compare 2 output/PWM2 output.
RB3				I	Analog	
AN9				I/O	ST	
CCP2 ⁽¹⁾						
RB4/KBI0/AN11	37	14	14	I/O	TTL	Digital I/O. Interrupt-on-change pin. Analog Input 11.
RB4				I	TTL	
KBI0				I	Analog	
AN11						
RB5/KBI1/PGM	38	15	15	I/O	TTL	Digital I/O. Interrupt-on-change pin. Low-Voltage ICSP™ Programming enable pin.
RB5				I	TTL	
KBI1				I/O	ST	
PGM						
RB6/KBI2/PGC	39	16	16	I/O	TTL	Digital I/O. Interrupt-on-change pin. In-Circuit Debugger and ICSP programming clock pin.
RB6				I	TTL	
KBI2				I/O	ST	
PGC						
RB7/KBI3/PGD	40	17	17	I/O	TTL	Digital I/O. Interrupt-on-change pin. In-Circuit Debugger and ICSP programming data pin.
RB7				I	TTL	
KBI3				I/O	ST	
PGD						

Legend: TTL = TTL compatible input CMOS = CMOS compatible input or output
 ST = Schmitt Trigger input with CMOS levels I = Input
 O = Output P = Power
 I²C = I²C™/SMBus

Note 1: Default assignment for CCP2 when Configuration bit, CCP2MX, is set.
2: Alternate assignment for CCP2 when Configuration bit, CCP2MX, is cleared.

PIC18F2423/2523/4423/4523

2.0 12-BIT ANALOG-TO-DIGITAL CONVERTER (A/D) MODULE

The Analog-to-Digital (A/D) Converter module has 10 inputs for the PIC18F2423/2523 devices and 13 for the PIC18F4423/4523 devices. This module allows conversion of an analog input signal to a corresponding 12-bit digital number.

The module has five registers:

- A/D Result High Register (ADRESH)
- A/D Result Low Register (ADRESL)
- A/D Control Register 0 (ADCON0)
- A/D Control Register 1 (ADCON1)
- A/D Control Register 2 (ADCON2)

Of the ADCONx registers:

- ADCON0 (shown in Register 2-1) – Controls the module's operation
- ADCON1 (Register 2-2) – Configures the functions of the port pins
- ADCON2 (Register 2-3) – Configures the A/D clock source, programmed acquisition time and justification

REGISTER 2-1: ADCON0: A/D CONTROL REGISTER 0

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	CHS3	CHS2	CHS1	CHS0	GO/DONE	ADON
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

bit 7-6 **Unimplemented:** Read as '0'

bit 5-2 **CHS<3:0>:** Analog Channel Select bits

0000 = Channel 0 (AN0)
 0001 = Channel 1 (AN1)
 0010 = Channel 2 (AN2)
 0011 = Channel 3 (AN3)
 0100 = Channel 4 (AN4)
 0101 = Channel 5 (AN5)^(1,2)
 0110 = Channel 6 (AN6)^(1,2)
 0111 = Channel 7 (AN7)^(1,2)
 1000 = Channel 8 (AN8)
 1001 = Channel 9 (AN9)
 1010 = Channel 10 (AN10)
 1011 = Channel 11 (AN11)
 1100 = Channel 12 (AN12)
 1101 = Unimplemented⁽²⁾
 1110 = Unimplemented⁽²⁾
 1111 = Unimplemented⁽²⁾

bit 1 **GO/DONE:** A/D Conversion Status bit

When ADON = 1:

1 = A/D conversion in progress
 0 = A/D Idle

bit 0 **ADON:** A/D On bit

1 = A/D Converter module is enabled
 0 = A/D Converter module is disabled

Note 1: These channels are not implemented on PIC18F2423/2523 devices.

2: Performing a conversion on unimplemented channels will return a floating input measurement.

PIC18F2423/2523/4423/4523

REGISTER 2-3: ADCON2: A/D CONTROL REGISTER 2

R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ADFM	—	ACQT2	ACQT1	ACQT0	ADCS2	ADCS1	ADCS0
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

- bit 7 **ADFM:** A/D Result Format Select bit
 1 = Right justified
 0 = Left justified
- bit 6 **Unimplemented:** Read as '0'
- bit 5-3 **ACQT<2:0>:** A/D Acquisition Time Select bits
 111 = 20 TAD
 110 = 16 TAD
 101 = 12 TAD
 100 = 8 TAD
 011 = 6 TAD
 010 = 4 TAD
 001 = 2 TAD
 000 = 0 TAD⁽¹⁾
- bit 2-0 **ADCS<2:0>:** A/D Conversion Clock Select bits
 111 = FRC (clock derived from A/D RC oscillator)⁽¹⁾
 110 = FOSC/64
 101 = FOSC/16
 100 = FOSC/4
 011 = FRC (clock derived from A/D RC oscillator)⁽¹⁾
 010 = FOSC/32
 001 = FOSC/8
 000 = FOSC/2

Note 1: If the A/D FRC clock source is selected, a delay of one T_{CY} (instruction cycle) is added before the A/D clock starts. This allows the *SLEEP* instruction to be executed before starting a conversion.

PIC18F2423/2523/4423/4523

The value in the ADRESH:ADRESL registers is unknown following POR and BOR Resets and is not affected by any other Reset.

After the A/D module has been configured as desired, the selected channel must be acquired before the conversion is started. The analog input channels must have their corresponding TRIS bits selected as inputs. To determine acquisition time, see **Section 2.1 “A/D Acquisition Requirements”**.

After this acquisition time has elapsed, the A/D conversion can be started. An acquisition time can be programmed to occur between setting the GO/DONE bit and the actual start of the conversion.

The following steps should be followed to perform an A/D conversion:

1. Configure the A/D module:
 - Configure analog pins, voltage reference and digital I/O (ADCON1)
 - Select A/D input channel (ADCON0)
 - Select A/D acquisition time (ADCON2)
 - Select A/D conversion clock (ADCON2)
 - Turn on the A/D module (ADCON0)
2. Configure the A/D interrupt (if desired):
 - Clear ADIF bit
 - Set ADIE bit
 - Set GIE bit
3. Wait the required acquisition time (if required).
4. Start conversion by setting the GO/DONE bit (ADCON0<1>).

5. Wait for the A/D conversion to complete by either:
 - Polling for the GO/DONE bit to be cleared
 OR
 - Waiting for the A/D interrupt
6. Read the A/D Result registers (ADRESH:ADRESL) and clear the ADIF bit, if required.
7. For the next conversion, go to step 1 or step 2, as required.

The A/D conversion time per bit is defined as TAD. A minimum wait of 2 TAD is required before the next acquisition starts.

FIGURE 2-2: A/D TRANSFER FUNCTION

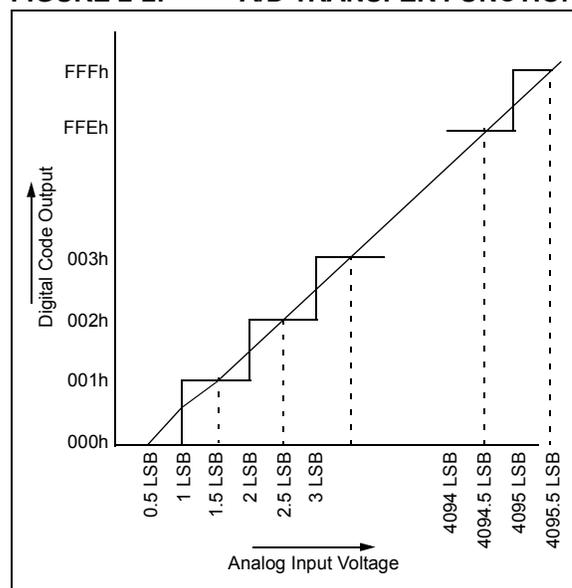
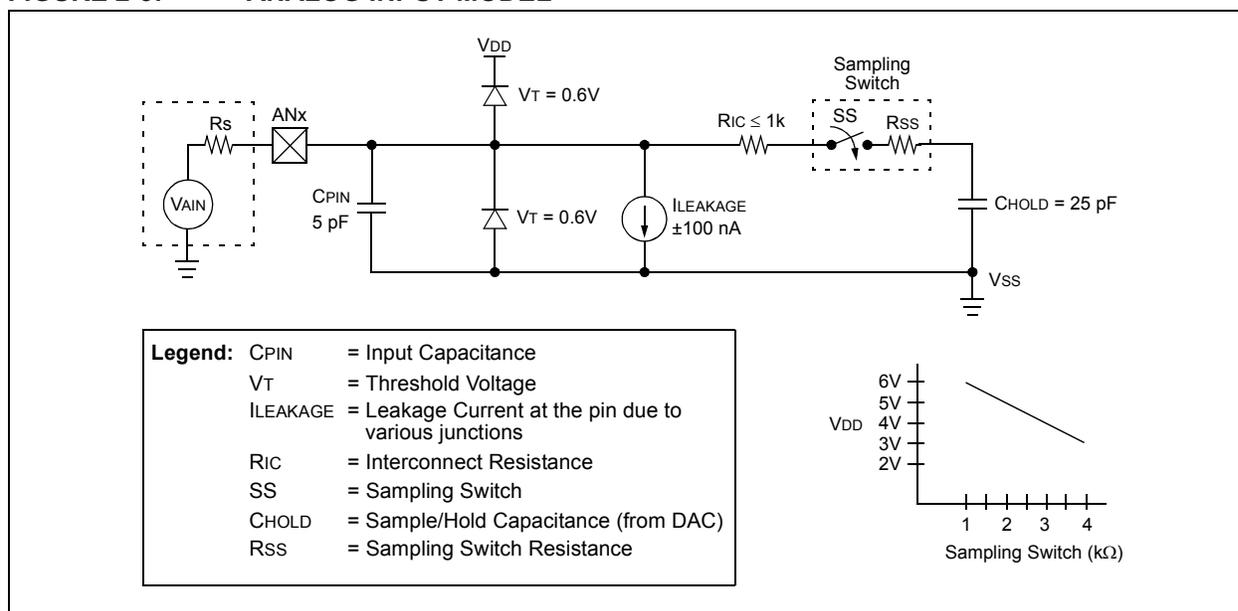


FIGURE 2-3: ANALOG INPUT MODEL



PIC18F2423/2523/4423/4523

2.8 Use of the CCP2 Trigger

An A/D conversion can be started by the Special Event Trigger of the CCP2 module. This requires that the CCP2M<3:0> bits (CCP2CON<3:0>) be programmed as '1011' and that the A/D module is enabled (ADON bit is set). When the trigger occurs, the GO/DONE bit will be set, starting the A/D acquisition and conversion, and the Timer1 (or Timer3) counter will be reset to zero. Timer1 (or Timer3) is reset to automatically repeat the A/D acquisition period with minimal software overhead (moving ADRESH:ADRESL to the desired location).

The appropriate analog input channel must be selected and the minimum acquisition period is either timed by the user or an appropriate TACQ time is selected before the Special Event Trigger sets the GO/DONE bit (starts a conversion).

If the A/D module is not enabled (ADON is cleared), the Special Event Trigger will be ignored by the A/D module, but will still reset the Timer1 (or Timer3) counter.

TABLE 2-3: REGISTERS ASSOCIATED WITH A/D OPERATION

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Reset Values on page
INTCON	GIE/GIEH	PEIE/GIEL	TMR0IE	INT0IE	RBIE	TMR0IF	INT0IF	RBFIF	(Note 4)
PIR1	PSPIF ⁽¹⁾	ADIF	RCIF	TXIF	SSPIF	CCP1IF	TMR2IF	TMR1IF	(Note 4)
PIE1	PSPIE ⁽¹⁾	ADIE	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	(Note 4)
IPR1	PSPPIP ⁽¹⁾	ADIP	RCIP	TXIP	SSPIP	CCP1IP	TMR2IP	TMR1IP	(Note 4)
PIR2	OSCFIF	CMIF	—	EEIF	BCLIF	HLVDIF	TMR3IF	CCP2IF	(Note 4)
PIE2	OSCFIE	CMIE	—	EEIE	BCLIE	HLVDIE	TMR3IE	CCP2IE	(Note 4)
IPR2	OSCFIP	CMIP	—	EEIP	BCLIP	HLVDIP	TMR3IP	CCP2IP	(Note 4)
ADRESH	A/D Result Register High Byte								(Note 4)
ADRESL	A/D Result Register Low Byte								(Note 4)
ADCON0	—	—	CHS3	CHS2	CHS1	CHS0	GO/DONE	ADON	(Note 4)
ADCON1	—	—	VCFG1	VCFG0	PCFG3	PCFG2	PCFG1	PCFG0	(Note 4)
ADCON2	ADFM	—	ACQT2	ACQT1	ACQT0	ADCS2	ADCS1	ADCS0	(Note 4)
PORTA	RA7 ⁽²⁾	RA6 ⁽²⁾	RA5	RA4	RA3	RA2	RA1	RA0	(Note 4)
TRISA	TRISA7 ⁽²⁾	TRISA6 ⁽²⁾	PORTA Data Direction Control Register						(Note 4)
PORTB	RB7	RB6	RB5	RB4	RB3	RB2	RB1	RB0	(Note 4)
TRISB	PORTB Data Direction Control Register								(Note 4)
LATB	PORTB Data Latch Register (Read and Write to Data Latch)								(Note 4)
PORTE ⁽¹⁾	—	—	—	—	RE3 ⁽³⁾	RE2	RE1	RE0	(Note 4)
TRISE ⁽¹⁾	IBF	OBF	IBOV	PSPMODE	—	TRISE2	TRISE1	TRISE0	(Note 4)
LATE ⁽¹⁾	—	—	—	—	—	PORTE Data Latch Register			(Note 4)

Legend: — = unimplemented, read as '0'. Shaded cells are not used for A/D conversion.

- Note 1:** These registers and/or bits are not implemented on PIC18F2423/2523 devices and are read as '0'.
- 2:** PORTA<7:6> and their direction bits are individually configured as port pins based on various primary oscillator modes. When disabled, these bits read as '0'.
- 3:** RE3 port bit is available only as an input pin when the MCLRE Configuration bit is '0'.
- 4:** For these Reset values, see **Section 4.0 "Reset"** of the "PIC18F2420/2520/4420/4520 Data Sheet" (DS39631).

PIC18F2423/2523/4423/4523

3.0 SPECIAL FEATURES OF THE CPU

Note: For additional details on the Configuration bits, refer to **Section 23.1 “Configuration Bits”** in the “PIC18F2420/2520/4420/4520 Data Sheet” (DS39631). Device ID information presented in this section is for the PIC18F2423/2523/4423/4523 devices only.

3.1 Device ID Registers

The Device ID registers are read-only registers. They identify the device type and revision for device programmers and can be read by firmware using table reads.

TABLE 3-1: DEVICE IDs

File Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default/ Unprogrammed Value	
3FFFFEh	DEVID1 ⁽¹⁾	DEV3	DEV2	DEV1	DEV0	REV3	REV2	REV1	REV0	xxxx xxxx ⁽²⁾
3FFFFFh	DEVID2 ⁽¹⁾	DEV11	DEV10	DEV9	DEV8	DEV7	DEV6	DEV5	DEV4	xxxx xxxx ⁽²⁾

Legend: x = unknown, u = unchanged, — = unimplemented. Shaded cells are unimplemented, read as '0'.

Note 1: DEVID registers are read-only and cannot be programmed by the user.

2: See Register 3-1 and Register 3-2 for DEVID1 and DEVID2 values.

REGISTER 3-1: DEVID1: DEVICE ID REGISTER 1 FOR PIC18F2423/2523/4423/4523

R	R	R	R	R	R	R	R
DEV3	DEV2	DEV1	DEV0	REV3	REV2	REV1	REV0
bit 7							bit 0

Legend:

R = Read-only bit

P = Programmable bit

U = Unimplemented bit, read as '0'

-n = Value when device is unprogrammed

u = Unchanged from programmed state

bit 7-4 **DEV<3:0>**: Device ID bits

1101 = PIC18F4423

1001 = PIC18F4523

0101 = PIC18F2423

0001 = PIC18F2523

bit 3-0 **REV<3:0>**: Revision ID bits

These bits are used to indicate the device revision.

PIC18F2423/2523/4423/4523

NOTES:

APPENDIX E: MIGRATION FROM MID-RANGE TO ENHANCED DEVICES

A detailed discussion of the differences between the mid-range MCU devices (i.e., PIC16CXXX) and the enhanced devices (i.e., PIC18FXXX) is provided in AN716, "*Migrating Designs from PIC16C74A/74B to PIC18C442*". The changes discussed, while device specific, are generally applicable to all mid-range to enhanced device migrations.

This Application Note is available as Literature Number DS00716.

APPENDIX F: MIGRATION FROM HIGH-END TO ENHANCED DEVICES

A detailed discussion of the migration pathway and differences between the high-end MCU devices (i.e., PIC17CXXX) and the enhanced devices (i.e., PIC18FXXX) is provided in AN726, "*PIC17CXXX to PIC18CXXX Migration*". This Application Note is available as Literature Number DS00726.

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PIC18F2423/2523/4423/4523

PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.

<u>PART NO.</u>	<u>X</u>	<u>/XX</u>	<u>XXX</u>
Device	Temperature Range	Package	Pattern
Device	PIC18F2423 ⁽¹⁾ , PIC18F2523 ⁽¹⁾ , PIC18F4423T ⁽²⁾ , PIC18F4523T ⁽²⁾ ; VDD range 4.2V to 5.5V PIC18F2423 ⁽¹⁾ , PIC18F2523 ⁽¹⁾ , PIC18F4423T ⁽²⁾ , PIC18F4523T ⁽²⁾ ; VDD range 2.0V to 5.5V		
Temperature Range	I = -40°C to +85°C (Industrial) E = -40°C to +125°C (Extended)		
Package	PT = TQFP (Thin Quad Flat pack) ML = QFN SO = SOIC SP = Skinny Plastic DIP P = PDIP		
Pattern	QTP, SQTP, Code or Special Requirements (blank otherwise)		

Examples:

- a) PIC18F4523-I/P 301 = Industrial temp., PDIP package, Extended VDD limits, QTP pattern #301.
- b) PIC18F4523-I/PT = Industrial temp., TQFP package, Extended VDD limits.
- c) PIC18F4523-E/P = Extended temp., PDIP package, normal VDD limits.

- Note 1:** F = Standard Voltage Range
 LF = Wide Voltage Range
2: T = In tape and reel PLCC, and TQFP packages only.