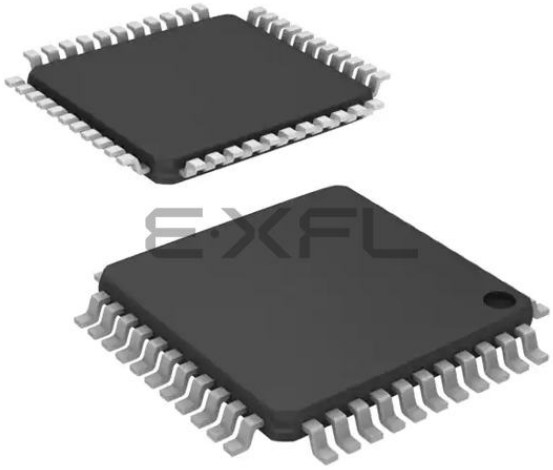

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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	40MHz
Connectivity	I²C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, HLVD, POR, PWM, WDT
Number of I/O	36
Program Memory Size	32KB (16K x 16)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	1.5K x 8
Voltage - Supply (Vcc/Vdd)	4.2V ~ 5.5V
Data Converters	A/D 13x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-TQFP
Supplier Device Package	44-TQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic18f4523t-i-pt

PIC18F2423/2523/4423/4523

28/40/44-Pin, Enhanced Flash Microcontrollers with 12-Bit A/D and nanoWatt Technology

Power Management Features:

- Run: CPU on, Peripherals on
- Idle: CPU off, Peripherals on
- Sleep: CPU off, Peripherals off
- Ultra Low 50 nA Input Leakage
- Run mode Currents Down to 11 μA Typical
- Idle mode Currents Down to 2.5 μA Typical
- Sleep mode Current Down to 100 μA Typical
- Timer1 Oscillator: 900 nA, 32 kHz, 2V
- Watchdog Timer: 1.4 μA, 2V Typical
- Two-Speed Oscillator Start-up

Flexible Oscillator Structure:

- Four Crystal modes, up to 40 MHz
- 4x Phase Lock Loop (PLL) – Available for Crystal and Internal Oscillators
- Two External RC modes, up to 4 MHz
- Two External Clock modes, up to 40 MHz
- Internal Oscillator Block:
  - Fast wake from Sleep and Idle, 1 μs typical
  - 8 user-selectable frequencies, from 31 kHz to 8 MHz
  - Provides a complete range of clock speeds, from 31 kHz to 32 MHz, when used with PLL
  - User-tunable to Compensate for Frequency Drift
- Secondary Oscillator using Timer1 @ 32 kHz
- Fail-Safe Clock Monitor:
  - Allows for safe shutdown if peripheral clock stops

Peripheral Highlights:

- 12-Bit, Up to 13-Channel Analog-to-Digital Converter module (A/D):
  - Auto-acquisition capability
  - Conversion available during Sleep mode
- Dual Analog Comparators with Input Multiplexing
- High-Current Sink/Source 25 mA/25 mA
- Three Programmable External Interrupts
- Four Input Change Interrupts
- Up to Two Capture/Compare/PWM (CCP) modules, One with Auto-Shutdown (28-pin devices)
- Enhanced Capture/Compare/PWM (ECCP) module (40/44-pin devices only):
  - One, two or four PWM outputs
  - Selectable polarity
  - Programmable dead time
  - Auto-shutdown and auto-restart

Peripheral Highlights (Continued):

- Master Synchronous Serial Port (MSSP) module Supporting 3-Wire SPI (all four modes) and I^2C™ Master and Slave modes
- Enhanced USART module:
  - Support for RS-485, RS-232 and LIN/J2602
  - RS-232 operation using internal oscillator block (no external crystal required)
  - Auto-wake-up on Start bit
  - Auto-Baud Detect (ABD)

Special Microcontroller Features:

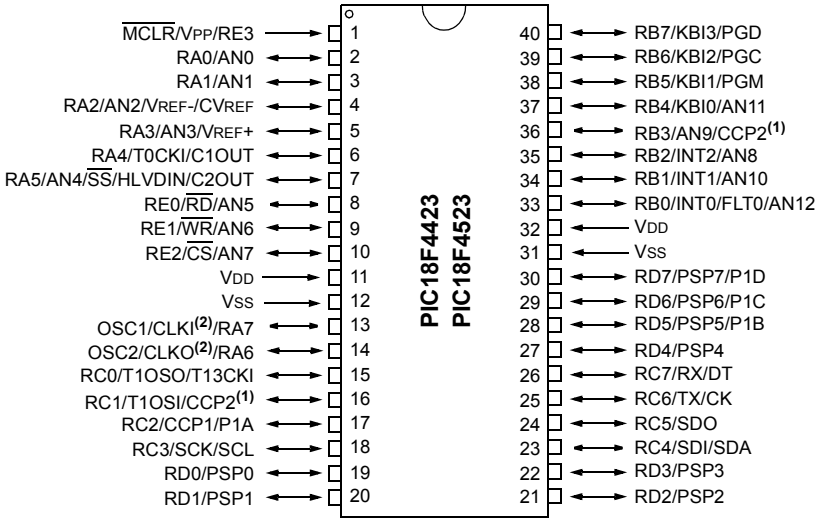
- C Compiler Optimized Architecture: Optional Extended Instruction Set Designed to Optimize Re-Entrant Code
- 100,000 Erase/Write Cycle, Enhanced Flash Program Memory Typical
- 1,000,000 Erase/Write Cycle, Data EEPROM Memory Typical
- Flash/Data EEPROM Retention: 100 Years Typical
- Self-Programmable under Software Control
- Priority Levels for Interrupts
- 8 x 8 Single-Cycle Hardware Multiplier
- Extended Watchdog Timer (WDT): Programmable Period, from 4 ms to 131s
- Single-Supply In-Circuit Serial Programming™ (ICSP™) via Two Pins
- In-Circuit Debug (ICD) via Two Pins
- Operating Voltage Range: 2.0V to 5.5V
- Programmable, 16-Level High/Low-Voltage Detection (HLVD) module: Supports Interrupt on High/Low-Voltage Detection
- Programmable Brown-out Reset (BOR): With Software-Enable Option

Note: This document is supplemented by the *"PIC18F2420/2520/4420/4520 Data Sheet"* (DS39631). See **Section 1.0 "Device Overview"**.

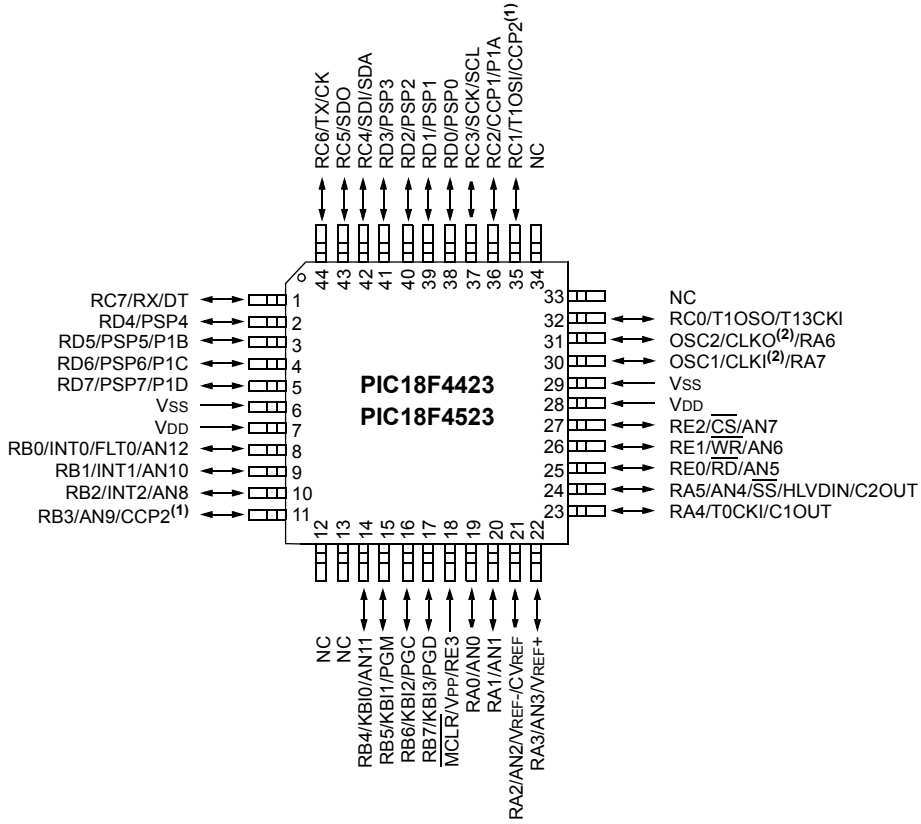
Device	Program Memory		Data Memory		I/O	12-Bit A/D (ch)	CCP/ ECCP (PWM)	MSSP		EUSART	Comp.	Timers 8/16-Bit
	Flash (bytes)	# Single-Word Instructions	SRAM (bytes)	EEPROM (bytes)				SPI	Master I^2C™			
PIC18F2423	16K	8192	768	256	25	10	2/0	Y	Y	1	2	1/3
PIC18F2523	32K	16384	1536	256	25	10	2/0	Y	Y	1	2	1/3
PIC18F4423	16K	8192	768	256	36	13	1/1	Y	Y	1	2	1/3
PIC18F4523	32K	16384	1536	256	36	13	1/1	Y	Y	1	2	1/3

Pin Diagrams (Continued)

40-Pin PDIP



44-Pin TQFP

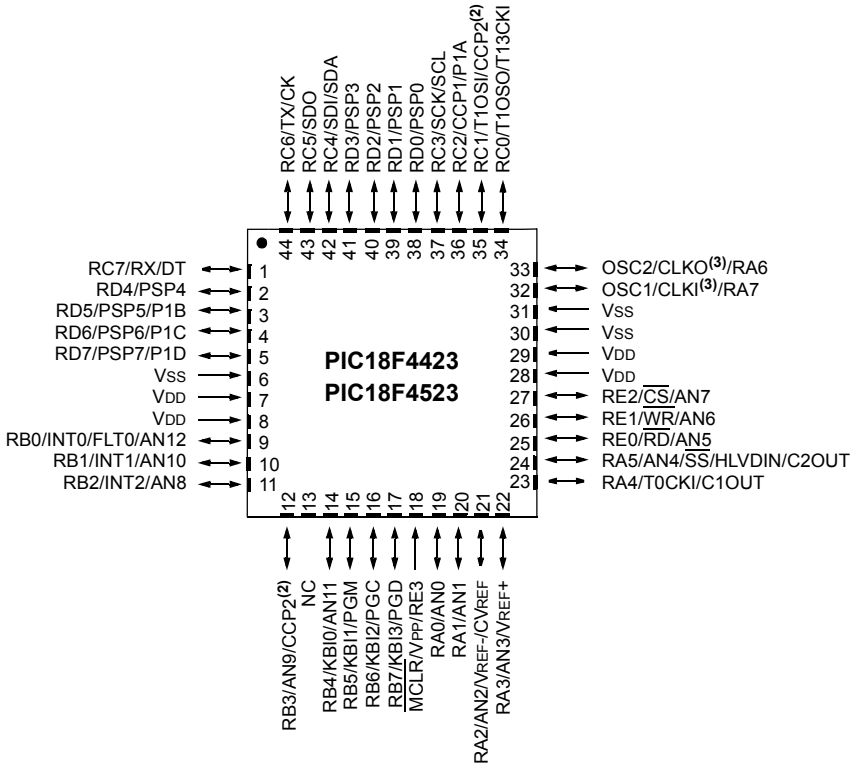


Note 1: RB3 is the alternate pin for CCP2 multiplexing.

2: OSC1/CLKI and OSC2/CLKO are only available in select oscillator modes and when these pins are not being used as digital I/O. For additional information, see **Section 2.0 "Oscillator Configurations"** of the *"PIC18F2420/2520/4420/4520 Data Sheet"* (DS39631).

Pin Diagrams (Continued)

44-Pin QFN(1)



Note 1: It is recommended to connect the bottom pad of QFN package parts to VSS.

2: RB3 is the alternate pin for CCP2 multiplexing.

3: OSC1/CLKI and OSC2/CLKO are only available in select oscillator modes and when these pins are not being used as digital I/O. For additional information, see **Section 2.0 "Oscillator Configurations"** of the *"PIC18F2420/2520/4420/4520 Data Sheet"* (DS39631).

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TABLE 1-2: PIC18F2423/2523 PINOUT I/O DESCRIPTIONS

Pin Name	Pin Number		Pin Type	Buffer Type	Description
	PDIP, SOIC	QFN			
MCLR/VPP/RE3	1	26			Master Clear (input) or programming voltage (input).
MCLR			I	ST	Master Clear (Reset) input. This pin is an active-low Reset to the device.
VPP			P		Programming voltage input.
RE3			I	ST	Digital input.
OSC1/CLKI/RA7	9	6			Oscillator crystal or external clock input.
OSC1			I	ST	Oscillator crystal input or external clock source input. ST buffer when configured in RC mode; CMOS otherwise.
CLKI			I	CMOS	External clock source input. Always associated with pin function, OSC1. (See related OSC1/CLKI, OSC2/CLKO pins.)
RA7			I/O	TTL	General purpose I/O pin.
OSC2/CLKO/RA6	10	7			Oscillator crystal or clock output.
OSC2			O	—	Oscillator crystal output. Connects to crystal or resonator in Crystal Oscillator mode.
CLKO			O	—	In RC mode, OSC2 pin outputs CLKO, which has 1/4 the frequency of OSC1 and denotes the instruction cycle rate.
RA6			I/O	TTL	General purpose I/O pin.

Legend: TTL = TTL compatible input; CMOS = CMOS compatible input or output; ST = Schmitt Trigger input with CMOS levels; I = Input; O = Output; P = Power; I^2C = I^2C™/SMBus

Note 1: Default assignment for CCP2 when Configuration bit, CCP2MX, is set.

2: Alternate assignment for CCP2 when Configuration bit, CCP2MX, is cleared.

TABLE 1-2: PIC18F2423/2523 PINOUT I/O DESCRIPTIONS (CONTINUED)

Pin Name	Pin Number		Pin Type	Buffer Type	Description
	PDIP, SOIC	QFN			
					PORTB is a bidirectional I/O port. PORTB can be software programmed for internal weak pull-ups on all inputs.
RB0/INT0/FLT0/AN12	21	18			
RB0			I/O	TTL	Digital I/O.
INT0			I	ST	External Interrupt 0.
FLT0			I	ST	PWM Fault input for CCP1.
AN12			I	Analog	Analog Input 12.
RB1/INT1/AN10	22	19			
RB1			I/O	TTL	Digital I/O.
INT1			I	ST	External Interrupt 1.
AN10			I	Analog	Analog Input 10.
RB2/INT2/AN8	23	20			
RB2			I/O	TTL	Digital I/O.
INT2			I	ST	External Interrupt 2.
AN8			I	Analog	Analog Input 8.
RB3/AN9/CCP2	24	21			
RB3			I/O	TTL	Digital I/O.
AN9			I	Analog	Analog Input 9.
CCP2(1)			I/O	ST	Capture 2 input/Compare 2 output/PWM2 output.
RB4/KBI0/AN11	25	22			
RB4			I/O	TTL	Digital I/O.
KBI0			I	TTL	Interrupt-on-change pin.
AN11			I	Analog	Analog Input 11.
RB5/KBI1/PGM	26	23			
RB5			I/O	TTL	Digital I/O.
KBI1			I	TTL	Interrupt-on-change pin.
PGM			I/O	ST	Low-Voltage ICSP™ Programming enable pin.
RB6/KBI2/PGC	27	24			
RB6			I/O	TTL	Digital I/O.
KBI2			I	TTL	Interrupt-on-change pin.
PGC			I/O	ST	In-Circuit Debugger and ICSP programming clock pin.
RB7/KBI3/PGD	28	25			
RB7			I/O	TTL	Digital I/O.
KBI3			I	TTL	Interrupt-on-change pin.
PGD			I/O	ST	In-Circuit Debugger and ICSP programming data pin.

Legend: TTL = TTL compatible input; CMOS = CMOS compatible input or output; ST = Schmitt Trigger input with CMOS levels; I = Input; O = Output; P = Power; I^2C = I^2C™/SMBus

Note 1: Default assignment for CCP2 when Configuration bit, CCP2MX, is set.

2: Alternate assignment for CCP2 when Configuration bit, CCP2MX, is cleared.

TABLE 1-3: PIC18F4423/4523 PINOUT I/O DESCRIPTIONS (CONTINUED)

Pin Name	Pin Number			Pin Type	Buffer Type	Description
	PDIP	QFN	TQFP			
						PORTB is a bidirectional I/O port. PORTB can be software programmed for internal weak pull-ups on all inputs.
RB0/INT0/FLT0/AN12	33	9	8			
RB0				I/O	TTL	Digital I/O.
INT0				I	ST	External Interrupt 0.
FLT0				I	ST	PWM Fault input for Enhanced CCP1.
AN12				I	Analog	Analog Input 12.
RB1/INT1/AN10	34	10	9			
RB1				I/O	TTL	Digital I/O.
INT1				I	ST	External Interrupt 1.
AN10				I	Analog	Analog Input 10.
RB2/INT2/AN8	35	11	10			
RB2				I/O	TTL	Digital I/O.
INT2				I	ST	External Interrupt 2.
AN8				I	Analog	Analog Input 8.
RB3/AN9/CCP2	36	12	11			
RB3				I/O	TTL	Digital I/O.
AN9				I	Analog	Analog Input 9.
CCP2(1)				I/O	ST	Capture 2 input/Compare 2 output/PWM2 output.
RB4/KBI0/AN11	37	14	14			
RB4				I/O	TTL	Digital I/O.
KBI0				I	TTL	Interrupt-on-change pin.
AN11				I	Analog	Analog Input 11.
RB5/KBI1/PGM	38	15	15			
RB5				I/O	TTL	Digital I/O.
KBI1				I	TTL	Interrupt-on-change pin.
PGM				I/O	ST	Low-Voltage ICSP™ Programming enable pin.
RB6/KBI2/PGC	39	16	16			
RB6				I/O	TTL	Digital I/O.
KBI2				I	TTL	Interrupt-on-change pin.
PGC				I/O	ST	In-Circuit Debugger and ICSP programming clock pin.
RB7/KBI3/PGD	40	17	17			
RB7				I/O	TTL	Digital I/O.
KBI3				I	TTL	Interrupt-on-change pin.
PGD				I/O	ST	In-Circuit Debugger and ICSP programming data pin.

Legend: TTL = TTL compatible input; CMOS = CMOS compatible input or output; ST = Schmitt Trigger input with CMOS levels; I = Input; O = Output; P = Power; I^2C = I^2C™/SMBus

Note 1: Default assignment for CCP2 when Configuration bit, CCP2MX, is set.

2: Alternate assignment for CCP2 when Configuration bit, CCP2MX, is cleared.

2.2 Selecting and Configuring Acquisition Time

The ADCON2 register allows the user to select an acquisition time that occurs each time the GO/DONE bit is set. It also gives users the option of having an automatically determined acquisition time.

Acquisition time may be set with the ACQT<2:0> bits (ADCON2<5:3>), which provide a range of 2 to 20 TAD. When the GO/DONE bit is set, the A/D module continues to sample the input for the selected acquisition time, then automatically begins a conversion. Since the acquisition time is programmed, there may be no need to wait for an acquisition time between selecting a channel and setting the GO/DONE bit.

Manual acquisition time is selected when ACQT<2:0> = 000. When the GO/DONE bit is set, sampling is stopped and a conversion begins. The user is responsible for ensuring the required acquisition time has passed between selecting the desired input channel and setting the GO/DONE bit. This option is also the default Reset state of the ACQT<2:0> bits and is compatible with devices that do not offer programmable acquisition times.

In either case, when the conversion is completed, the GO/DONE bit is cleared, the ADIF flag is set and the A/D begins sampling the currently selected channel again. If an acquisition time is programmed, there is nothing to indicate if the acquisition time has ended or if the conversion has begun.

2.3 Selecting the A/D Conversion Clock

The A/D conversion time per bit is defined as TAD. The A/D conversion requires 13 TAD per 12-bit conversion. The source of the A/D conversion clock is software selectable.

There are seven possible options for TAD:

- 2 TOSC
- 4 TOSC
- 8 TOSC
- 16 TOSC
- 32 TOSC
- 64 TOSC
- Internal RC Oscillator

For correct A/D conversions, the A/D conversion clock (TAD) must be as short as possible, but greater than the minimum TAD. (For more information, see parameter 130 on page 41.)

Table 2-2 shows the resultant TAD times derived from the device operating frequencies and the A/D clock source selected.

TABLE 2-2: TAD vs. DEVICE OPERATING FREQUENCIES

A/D Clock Source (TAD)		Assumes TAD Min. = 0.8 μs
Operation	**ADCS<2:0>**	**Maximum FOSC**
2 TOSC	000	2.50 MHz
4 TOSC	100	5.00 MHz
8 TOSC	001	10.00 MHz
16 TOSC	101	20.00 MHz
32 TOSC	010	40.00 MHz
64 TOSC	110	40.00 MHz
RC(2)	x11	1.00 MHz(1)

Note 1: The RC source has a typical TAD time of 2.5 μs.

2: For device frequencies above 1 MHz, the device must be in Sleep for the entire conversion or a FOSC divider should be used instead; otherwise, the A/D accuracy specification may not be met.

2.4 Operation in Power-Managed Modes

The selection of the automatic acquisition time and A/D conversion clock is determined in part by the clock source and frequency while in a power-managed mode.

If the A/D is expected to operate while the device is in a power-managed mode, the ADCS<2:0> bits in ADCON2 should be updated in accordance with the clock source to be used. The ACQT<2:0> bits do not need to be adjusted as the ADCS<2:0> bits adjust the TAD time for the new clock speed. After entering the mode, an A/D acquisition or conversion may be started. Once started, the device should continue to be clocked by the same clock source until the conversion has been completed.

If desired, the device may be placed into the corresponding Idle mode during the conversion. If the device clock frequency is less than 1 MHz, the A/D RC clock source should be selected.

Operation in Sleep mode requires the A/D FRC clock to be selected. If bits, ACQT<2:0>, are set to '000' and a conversion is started, the conversion will be delayed one instruction cycle to allow execution of the SLEEP instruction and entry to Sleep mode. The IDLEN bit (OSCCON<7>) must have already been cleared prior to starting the conversion.

2.5 Configuring Analog Port Pins

The ADCON1, TRISA, TRISB and TRISE registers all configure the A/D port pins. The port pins needed as analog inputs must have their corresponding TRIS bits set (input). If the TRIS bit is cleared (output), the digital output level (VOH or VOL) will be converted.

The A/D operation is independent of the state of the CHS<3:0> bits and the TRIS bits.

Note 1:	When reading the PORT register, all pins configured as analog input channels will read as cleared (a low level). Analog conversion on pins configured as digital pins can be performed. The voltage on the pin will be accurately converted.
2:	Analog levels on any pin defined as a digital input may cause the digital input buffer to consume current out of the device's specification limits.
3:	The PBADEN bit in Configuration Register 3H configures PORTB pins to reset as analog or digital pins by controlling how the PCFG<3:0> bits in ADCON1 are reset.

2.8 Use of the CCP2 Trigger

An A/D conversion can be started by the Special Event Trigger of the CCP2 module. This requires that the CCP2M<3:0> bits (CCP2CON<3:0>) be programmed as '1011' and that the A/D module is enabled (ADON bit is set). When the trigger occurs, the GO/$\overline{\text{DONE}}$ bit will be set, starting the A/D acquisition and conversion, and the Timer1 (or Timer3) counter will be reset to zero. Timer1 (or Timer3) is reset to automatically repeat the A/D acquisition period with minimal software overhead (moving ADRESH:ADRESL to the desired location). The appropriate analog input channel must be selected and the minimum acquisition period is either timed by the user or an appropriate TACQ time is selected before the Special Event Trigger sets the GO/$\overline{\text{DONE}}$ bit (starts a conversion).

If the A/D module is not enabled (ADON is cleared), the Special Event Trigger will be ignored by the A/D module, but will still reset the Timer1 (or Timer3) counter.

TABLE 2-3: REGISTERS ASSOCIATED WITH A/D OPERATION

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Reset Values on page
INTCON	GIE/GIEH	PEIE/GIEL	TMR0IE	INT0IE	RBIE	TMR0IF	INT0IF	RBIF	**(Note 4)**
PIR1	PSPIF(1)	ADIF	RCIF	TXIF	SSPIF	CCP1IF	TMR2IF	TMR1IF	**(Note 4)**
PIE1	PSPIE(1)	ADIE	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	**(Note 4)**
IPR1	PSPIP(1)	ADIP	RCIP	TXIP	SSPIP	CCP1IP	TMR2IP	TMR1IP	**(Note 4)**
PIR2	OSCFIF	CMIF	—	EEIF	BCLIF	HLVDIF	TMR3IF	CCP2IF	**(Note 4)**
PIE2	OSCFIE	CMIE	—	EEIE	BCLIE	HLVDIE	TMR3IE	CCP2IE	**(Note 4)**
IPR2	OSCFIP	CMIP	—	EEIP	BCLIP	HLVDIP	TMR3IP	CCP2IP	**(Note 4)**
ADRESH	A/D Result Register High Byte								**(Note 4)**
ADRESL	A/D Result Register Low Byte								**(Note 4)**
ADCON0	—	—	CHS3	CHS2	CHS1	CHS0	GO/$\overline{\text{DONE}}$	ADON	**(Note 4)**
ADCON1	—	—	VCFG1	VCFG0	PCFG3	PCFG2	PCFG1	PCFG0	**(Note 4)**
ADCON2	ADFM	—	ACQT2	ACQT1	ACQT0	ADCS2	ADCS1	ADCS0	**(Note 4)**
PORTA	RA7(2)	RA6(2)	RA5	RA4	RA3	RA2	RA1	RA0	**(Note 4)**
TRISA	TRISA7(2)	TRISA6(2)	PORTA Data Direction Control Register						**(Note 4)**
PORTB	RB7	RB6	RB5	RB4	RB3	RB2	RB1	RB0	**(Note 4)**
TRISB	PORTB Data Direction Control Register								**(Note 4)**
LATB	PORTB Data Latch Register (Read and Write to Data Latch)								**(Note 4)**
PORTE(1)	—	—	—	—	RE3(3)	RE2	RE1	RE0	**(Note 4)**
TRISE(1)	IBF	OBF	IBOV	PSPMODE	—	TRISE2	TRISE1	TRISE0	**(Note 4)**
LATE(1)	—	—	—	—	—	PORTE Data Latch Register			**(Note 4)**

Legend: — = unimplemented, read as '0'. Shaded cells are not used for A/D conversion.

Note 1: These registers and/or bits are not implemented on PIC18F2423/2523 devices and are read as '0'.

2: PORTA<7:6> and their direction bits are individually configured as port pins based on various primary oscillator modes. When disabled, these bits read as '0'.

3: RE3 port bit is available only as an input pin when the MCLRE Configuration bit is '0'.

4: For these Reset values, see **Section 4.0 "Reset"** of the *"PIC18F2420/2520/4420/4520 Data Sheet"* (DS39631).

REGISTER 3-2: DEVID2: DEVICE ID REGISTER 2 FOR PIC18F2423/2523/4423/4523

R	R	R	R	R	R	R	R
DEV11(1)	DEV10(1)	DEV9(1)	DEV8(1)	DEV7(1)	DEV6(1)	DEV5(1)	DEV4(1)
bit 7							bit 0

Legend:		
R = Read-only bit	P = Programmable bit	U = Unimplemented bit, read as '0'
-n = Value when device is unprogrammed		u = Unchanged from programmed state

bit 7-0 **DEV<11:4>:** Device ID bits(1)

These bits are used with the DEV<3:0> bits in Device ID Register 1 to identify the part number.

0001 0001 = PIC18F2423/2523 devices

0001 0000 = PIC18F4423/4523 devices

Note 1: These values for DEV<11:4> may be shared with other devices. The specific device is always identified by using the entire DEV<11:0> bit sequence.

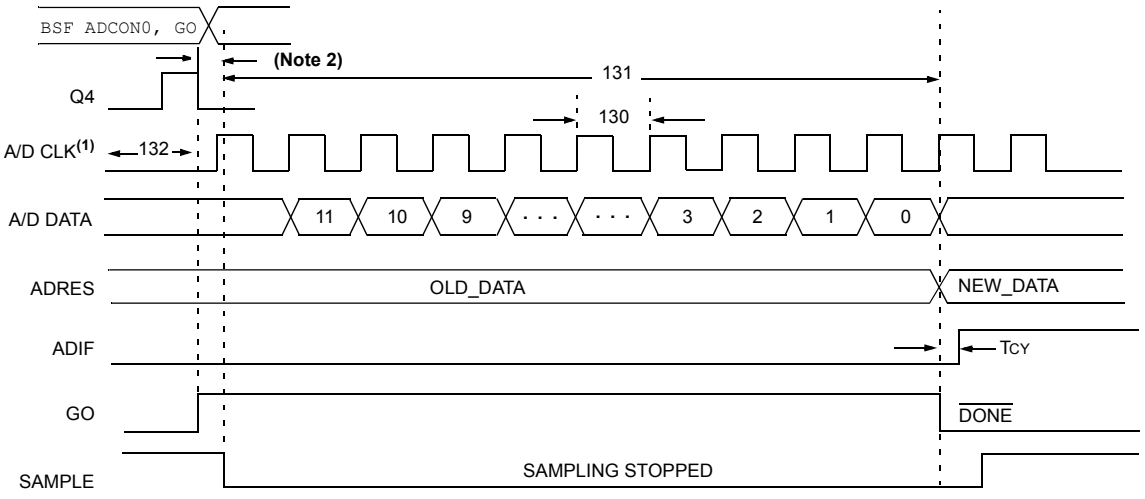
TABLE 4-1: A/D CONVERTER CHARACTERISTICS: PIC18F2423/2523/4423/4523 (INDUSTRIAL) PIC18LF2423/2523/4423/4523 (INDUSTRIAL)

Param No.	Sym	Characteristic	Min	Typ	Max	Units	Conditions	
A01	NR	Resolution	—	—	12	bit		ΔVREF ≥ 3.0V
A03	EIL	Integral Linearity Error	—	<±1	±2.0	LSB	VDD = 3.0V	ΔVREF ≥ 3.0V
			—	—	±2.0	LSB	VDD = 5.0V	
A04	EDL	Differential Linearity Error	—	<±1	+1.5/-1.0	LSB	VDD = 3.0V	ΔVREF ≥ 3.0V
			—	—	+1.5/-1.0	LSB	VDD = 5.0V	
A06	EOFF	Offset Error	—	<±1	±5	LSB	VDD = 3.0V	ΔVREF ≥ 3.0V
			—	—	±3	LSB	VDD = 5.0V	
A07	EGN	Gain Error	—	<±1	±1.25	LSB	VDD = 3.0V	ΔVREF ≥ 3.0V
			—	—	±2.00	LSB	VDD = 5.0V	
A10	—	Monotonicity	Guaranteed(1)			—		VSS ≤ VAIN ≤ VREF
A20	ΔVREF	Reference Voltage Range (VREFH – VREFL)	3	—	VDD – VSS	V		For 12-bit resolution.
A21	VREFH	Reference Voltage High	VSS + 3.0V	—	VDD + 0.3V	V		For 12-bit resolution.
A22	VREFL	Reference Voltage Low	VSS – 0.3V	—	VDD – 3.0V	V		For 12-bit resolution.
A25	VAIN	Analog Input Voltage	VREFL	—	VREFH	V		
A30	ZAIN	Recommended Impedance of Analog Voltage Source	—	—	2.5	kΩ		
A50	IREF	VREF Input Current(2)	— —	— —	5 150	μA μA		During VAIN acquisition. During A/D conversion cycle.

Note 1: The A/D conversion result never decreases with an increase in the input voltage and has no missing codes.

2: VREFH current is from the RA3/AN3/VREF+ pin or VDD, whichever is selected as the VREFH source. VREFL current is from the RA2/AN2/VREF-/CVREF pin or VSS, whichever is selected as the VREFL source.

FIGURE 4-4: A/D CONVERSION TIMING



Note 1: If the A/D clock source is selected as RC, a time of TCY is added before the A/D clock starts. This allows the SLEEP instruction to be executed.

2: This is a minimal RC delay (typically 100 ns), which also disconnects the holding capacitor from the analog input.

TABLE 4-2: A/D CONVERSION REQUIREMENTS

Param No.	Symbol	Characteristic		Min	Max	Units	Conditions
130	TAD	A/D Clock Period	PIC18**F**XXXX	0.8	12.5(1)	µs	TOSC based, VREF ≥ 3.0V
			PIC18**LF**XXXX	1.4	25.0(1)	µs	VDD = 3.0V; TOSC based, VREF full range
			PIC18**F**XXXX	—	1	µs	A/D RC mode
			PIC18**LF**XXXX	—	3	µs	VDD = 3.0V; A/D RC mode
131	TCNV	Conversion Time (not including acquisition time)(2)		13	14	TAD	
132	TACQ	Acquisition Time(3)		1.4	—	µs	
135	TSWC	Switching Time from Convert → Sample		—	**(Note 4)**		
137	TDIS	Discharge Time		0.2	—	µs	

Note 1: The time of the A/D clock period is dependent on the device frequency and the TAD clock divider.

2: ADRES registers may be read on the following TCY cycle.

3: The time for the holding capacitor to acquire the "New" input voltage when the voltage changes full scale after the conversion (VDD to VSS or VSS to VDD). The source impedance (RS) on the input channels is 50Ω.

4: On the following cycle of the device clock.

NOTES:

NOTES:

APPENDIX A: REVISION HISTORY

Revision A (June 2006)

Original data sheet for PIC18F2423/2523/4423/4523 devices.

Revision B (January 2007)

This revision includes updates to the packaging diagrams.

Revision C (September 2009)

Electrical specifications updated. Preliminary condition status removed. Converted document to the “mini data sheet” format.

APPENDIX B: DEVICE DIFFERENCES

The differences between the devices listed in this data sheet are shown in Table B-1.

TABLE B-1: DEVICE DIFFERENCES

Features	PIC18F2423	PIC18F2523	PIC18F4423	PIC18F4523
Program Memory (Bytes)	16384	32768	16384	32768
Program Memory (Instructions)	8192	16384	8192	16384
Interrupt Sources	19	19	20	20
I/O Ports	Ports A, B, C, (E)	Ports A, B, C, (E)	Ports A, B, C, D, E	Ports A, B, C, D, E
Capture/Compare/PWM Modules	2	2	1	1
Enhanced Capture/Compare/PWM Modules	0	0	1	1
Parallel Communications (PSP)	No	No	Yes	Yes
12-Bit Analog-to-Digital Module	10 Input Channels	10 Input Channels	13 Input Channels	13 Input Channels
Packages	28-Pin PDIP 28-Pin SOIC 28-Pin QFN	28-Pin PDIP 28-Pin SOIC 28-Pin QFN	40-Pin PDIP 44-Pin TQFP 44-Pin QFN	40-Pin PDIP 44-Pin TQFP 44-Pin QFN

APPENDIX E: MIGRATION FROM MID-RANGE TO ENHANCED DEVICES

A detailed discussion of the differences between the mid-range MCU devices (i.e., PIC16CXXX) and the enhanced devices (i.e., PIC18FXXX) is provided in *AN716, "Migrating Designs from PIC16C74A/74B to PIC18C442"*. The changes discussed, while device specific, are generally applicable to all mid-range to enhanced device migrations.

This Application Note is available as Literature Number DS00716.

APPENDIX F: MIGRATION FROM HIGH-END TO ENHANCED DEVICES

A detailed discussion of the migration pathway and differences between the high-end MCU devices (i.e., PIC17CXXX) and the enhanced devices (i.e., PIC18FXXX) is provided in *AN726, "PIC17CXXX to PIC18CXXX Migration*". This Application Note is available as Literature Number DS00726.

NOTES:

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PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.

PART NO.	X	/XX	XXX
Device	Temperature Range	Package	Pattern

Device	PIC18F2423(1), PIC18F2523(1), PIC18F4423T(2), PIC18F4523T(2); VDD range 4.2V to 5.5V PIC18F2423(1), PIC18F2523(1), PIC18F4423T(2), PIC18F4523T(2); VDD range 2.0V to 5.5V
Temperature Range	I = -40°C to +85°C (Industrial) E = -40°C to +125°C (Extended)
Package	PT = TQFP (Thin Quad Flat pack) ML = QFN SO = SOIC SP = Skinny Plastic DIP P = PDIP
Pattern	QTP, SQTP, Code or Special Requirements (blank otherwise)

Examples:

a) PIC18F4523-I/P 301 = Industrial temp., PDIP package, Extended VDD limits, QTP pattern #301.

b) PIC18F4523-I/PT = Industrial temp., TQFP package, Extended VDD limits.

c) PIC18F4523-E/P = Extended temp., PDIP package, normal VDD limits.

Note 1: F = Standard Voltage Range
LF = Wide Voltage Range

2: T = In tape and reel PLCC, and TQFP packages only.