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Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

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Betans	
Product Status	Obsolete
Core Processor	dsPIC
Core Size	16-Bit
Speed	30 MIPs
Connectivity	CANbus, I ² C, SPI, UART/USART
Peripherals	AC'97, Brown-out Detect/Reset, I ² S, LVD, POR, PWM, WDT
Number of I/O	52
Program Memory Size	66KB (22K x 24)
Program Memory Type	FLASH
EEPROM Size	1K x 8
RAM Size	4K x 8
Voltage - Supply (Vcc/Vdd)	2.5V ~ 5.5V
Data Converters	A/D 16x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-TQFP
Supplier Device Package	64-TQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic30f5011t-30i-ptg

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

5.6.3 PROGRAMMING VERIFICATION

Once the data EEPROM is programmed, the contents of memory can be verified to ensure that the programming was successful. Verification requires the data EEPROM to be read back and compared against the copy held in the programmer's buffer. The READD command reads back the programmed data EEPROM.

Alternatively, the programmer can perform the verification once the entire device is programmed using a checksum computation, as described in **Section 6.8 "Checksum Computation"**.

Note: TBLRDL instructions executed within a REPEAT loop must not be used to read from Data EEPROM. Instead, it is recommended to use PSV access.

5.7 Configuration Bits Programming

5.7.1 OVERVIEW

The dsPIC30F has Configuration bits stored in seven 16-bit registers. These bits can be set or cleared to select various device configurations. There are two types of Configuration bits: system-operation bits and code-protect bits. The system-operation bits determine the power-on settings for system-level components such as the oscillator and Watchdog Timer. The codeprotect bits prevent program memory from being read and written. The FOSC Configuration register has three different register descriptions, based on the device. The FOSC Configuration register description for the dsPIC30F2010 and dsPIC30F6010/6011/6012/6013/ 6014 devices are shown in Table 5-4.

Note: If user software performs an erase operation on the configuration fuse, it must be followed by a write operation to this fuse with the desired value, even if the desired value is the same as the state of the erased fuse.

The FOSC Configuration register description for the dsPIC30F4011/4012 and dsPIC30F5011/5013 devices is shown in Table 5-5.

The FOSC Configuration register description for all remaining devices (dsPIC30F2011/2012, dsPIC30F3010/3011/3012/3013, dsPIC30F3014/ 4013, dsPIC30F5015 and dsPIC30F6011A/6012A/ 6013A/ 6014A) is shown in Table 5-6. Always use the correct register descriptions for your target processor.

The FWDT, FBORPOR, FBS, FSS, FGS and FICD Configuration registers are not device-dependent. The register descriptions for these Configuration registers are shown in Table 5-7.

The Device Configuration register maps are shown in Table 5-8 through Table 5-11.

TABLE 5-4:	FOSC CONFIGURATION BITS DESCRIPTION FOR dsPIC30F2010 AND
	dsPIC30F6010/6011/6012/6013/6014

Bit Field	Register	Description
FCKSM<1:0>	FOSC	Clock Switching Mode 1x = Clock switching is disabled, Fail-Safe Clock Monitor is disabled 01 = Clock switching is enabled, Fail-Safe Clock Monitor is disabled 00 = Clock switching is enabled, Fail-Safe Clock Monitor is enabled
FOS<1:0>	FOSC	Oscillator Source Selection on POR 11 = Primary Oscillator 10 = Internal Low-Power RC Oscillator 01 = Internal Fast RC Oscillator 00 = Low-Power 32 kHz Oscillator (Timer1 Oscillator)
FPR<3:0>	FOSC	 Primary Oscillator Mode 1111 = ECIO w/PLL 16X – External Clock mode with 16X PLL. OSC2 pin is I/O 110 = ECIO w/PLL 8X – External Clock mode with 8X PLL. OSC2 pin is I/O 101 = ECIO w/PLL 4X – External Clock mode with 4X PLL. OSC2 pin is I/O 100 = ECIO – External Clock mode. OSC2 pin is I/O 101 = EC – External Clock mode. OSC2 pin is system clock output (Fosc/4) 101 = ERC – External RC Oscillator mode. OSC2 pin is system clock output (Fosc/4) 1000 = ERCIO – External RC Oscillator mode. OSC2 pin is I/O 0111 = XT w/PLL 16X – XT Crystal Oscillator mode with 16X PLL 0101 = XT w/PLL 8X – XT Crystal Oscillator mode with 8X PLL 0101 = XT w/PLL 4X – XT Crystal Oscillator mode with 4X PLL 0101 = XT w/PLL 4X – XT Crystal Oscillator mode with 4X PLL 0101 = XT - XT Crystal Oscillator mode (4 MHz-10 MHz crystal) 001x = HS – HS Crystal Oscillator mode (200 kHz-4 MHz crystal)

TABLE 5-6: FOSC CONFIGURATION BITS DESCRIPTION FOR dsPIC30F2011/2012, dsPIC30F3010/3011/3012/3013/3014, dsPIC30F4013, dsPIC30F5015/5016, dsPIC30F6010A/6011A/6012A/6013A/6014A AND dsPIC30F6015

	Description
OSC	Clock Switching Mode 1x = Clock switching is disabled, Fail-Safe Clock Monitor is disabled 01 = Clock switching is enabled, Fail-Safe Clock Monitor is disabled 00 = Clock switching is enabled, Fail-Safe Clock Monitor is enabled
OSC	Oscillator Source Selection on POR 111 = Primary Oscillator 110 = Reserved 101 = Reserved 100 = Reserved 011 = Reserved 010 = Internal Low-Power RC Oscillator 001 = Internal Fast RC Oscillator (no PLL) 000 = Low-Power 32 kHz Oscillator (Timer1 Oscillator)
DSC	Primary Oscillator Mode (when FOS<2:0> = 111b) 11xxx = Reserved (do not use) 10111 = HS/3 w/PLL 16X – HS/3 crystal oscillator with 16X PLL (10 MHz-25 MHz crystal) 10101 = HS/3 w/PLL 8X – HS/3 crystal oscillator with 8X PLL (10 MHz-25 MHz crystal) 10101 = HS/3 w/PLL 4X – HS/3 crystal oscillator with 4X PLL (10 MHz-25 MHz crystal) 10100 = Reserved (do not use) 10011 = HS/2 w/PLL 16X – HS/2 crystal oscillator with 16X PLL (10 MHz-25 MHz crystal) 10010 = HS/2 w/PLL 8X – HS/2 crystal oscillator with 8X PLL (10 MHz-25 MHz crystal) 10001 = HS/2 w/PLL 8X – HS/2 crystal oscillator with 8X PLL (10 MHz-25 MHz crystal) 10001 = HS/2 w/PLL 4X – HS/2 crystal oscillator with 4X PLL (10 MHz-25 MHz crystal) 10000 = Reserved (do not use) 01111 = ECIO w/PLL 16x – External clock with 16x PLL. OSC2 pin is I/O 01101 = ECIO w/PLL 16x – External clock with 8x PLL. OSC2 pin is I/O 01101 = ECIO w/PLL 4x – External clock with 4x PLL. OSC2 pin is I/O 01101 = ECIO w/PLL 4x – External clock with 4x PLL. OSC2 pin is I/O 01101 = ECIO w/PLL 8x – Internal fast RC oscillator with 8x PLL. OSC2 pin is I/O 01010 = Reserved (do not use) 01011 = Reserved (do not use) 01011 = XT w/PLL 16X – XT crystal oscillator with 16X PLL 0110 = XT w/PLL 4X – XT crystal oscillator with 8X PLL 0110 = XT w/PLL 4X – XT crystal oscillator with 8X PLL 0110 = XT w/PLL 4X – XT crystal oscillator with 8X PLL 0110 = TRC w/PLL 4X – Internal fast RC oscillator with 8x PLL. OSC2 pin is I/O 0111 = FRC w/PLL 4X – XT crystal oscillator with 8X PLL 0100 = Reserved (do not use) 00011 = FRC w/PLL 4X – Internal fast RC oscillator with 8x PLL. OSC2 pin is I/O 00010 = Reserved (do not use) 00011 = FRC w/PLL 4X – Internal fast RC oscillator with 4x PLL. OSC2 pin is I/O 00010 = Reserved (do not use)

TABLE 5-6: FOSC CONFIGURATION BITS DESCRIPTION FOR dsPIC30F2011/2012, dsPIC30F3010/3011/3012/3013/3014, dsPIC30F4013, dsPIC30F5015/5016, dsPIC30F6010A/6011A/6012A/6013A/6014A AND dsPIC30F6015 (CONTINUED)

Bit Field	Register	Description
FPR<4:0>	FOSC	Alternate Oscillator Mode (when FOS<2:0> = 011b)
		1xxxx = Reserved (do not use)
		0111x = Reserved (do not use)
		01101 = Reserved (do not use)
		01100 = ECIO – External clock. OSC2 pin is I/O
		01011 = EC – External clock. OSC2 pin is system clock output (Fosc/4)
		01010 = Reserved (do not use)
		01001 = ERC – External RC oscillator. OSC2 pin is system clock output (Fosc/4)
		01000 = ERCIO – External RC oscillator. OSC2 pin is I/O
		00111 = Reserved (do not use)
		00110 = Reserved (do not use)
		00101 = Reserved (do not use)
		00100 = XT – XT crystal oscillator (4 MHz-10 MHz crystal)
		00010 = HS – HS crystal oscillator (10 MHz-25 MHz crystal)
		00001 = Reserved (do not use)
		00000 = XTL – XTL crystal oscillator (200 kHz-4 MHz crystal)

TABLE 5-7:	CONFIGUR	ATION BITS DESCRIPTION (CONTINUED)
Bit Field	Register	Description
SSS<2:0>	FSS	 Secure Segment Program Memory Code Protection (only present in dsPIC30F5011/5013/6010A/6011A/6012A/6013A/6014A/6015) 111 = No Secure Segment 110 = Standard security; Small-sized Secure Program Flash [Secure Segment starts after BS and ends at 0x001FFF] 101 = Standard security; Medium-sized Secure Program Flash [Secure Segment starts after BS and ends at 0x003FFF] 100 = Standard security; Large-sized Secure Program Flash [Secure Segment starts after BS and ends at 0x007FFF] 011 = No Secure Segment 010 = High security; Small-sized Secure Program Flash [Secure Segment starts after BS and ends at 0x007FFF] 011 = No Secure Segment 010 = High security; Medium-sized Secure Program Flash [Secure Segment starts after BS and ends at 0x001FFF] 001 = High security; Medium-sized Secure Program Flash [Secure Segment starts after BS and ends at 0x001FFF] 001 = High security; Medium-sized Secure Program Flash [Secure Segment starts after BS and ends at 0x003FFF] 001 = High security; Medium-sized Secure Program Flash [Secure Segment starts after BS and ends at 0x003FFF] 001 = High security; Large-sized Secure Program Flash [Secure Segment starts after BS and ends at 0x003FFF]
SWRP	FSS	Secure Segment Program Memory Write Protection (only present in dsPIC30F5011/5013/6010A/6011A/6012A/6013A/6014A/6015) 1 = Secure Segment program memory is not write-protected 0 = Secure program memory is write-protected
GSS<1:0>	FGS	General Segment Program Memory Code Protection (only present in dsPIC30F5011/5013/6010A/6011A/6012A/6013A/6014A/6015) 11 = Code protection is disabled 10 = Standard security code protection is enabled 0x = High security code protection is enabled
GCP	FGS	General Segment Program Memory Code Protection (present in all devices except dsPIC30F5011/5013/6010A/6011A/6012A/6013A/6014A/6015) 1 = General Segment program memory is not code-protected 0 = General Segment program memory is code-protected
GWRP	FGS	General Segment Program Memory Write Protection 1 = General Segment program memory is not write-protected 0 = General Segment program memory is write-protected
BKBUG	FICD	Debugger/Emulator Enable 1 = Device will reset into Operational mode 0 = Device will reset into Debug/Emulation mode
COE	FICD	Debugger/Emulator Enable 1 = Device will reset into Operational mode 0 = Device will reset into Clip-on Emulation mode
ICS<1:0>	FICD	ICD Communication Channel Select 11 = Communicate on PGC/EMUC and PGD/EMUD 10 = Communicate on EMUC1 and EMUD1 01 = Communicate on EMUC2 and EMUD2 00 = Communicate on EMUC3 and EMUD3
RESERVED	FBS, FSS, FGS	Reserved (read as '1', write as '1')
—	All	Unimplemented (read as '0', write as '0')

TABLE 5-7: CONFIGURATION BITS DESCRIPTION (CONTINUED)

TABLE 5-8: dsPIC30F CONFIGURATION REGISTERS (FOR dsPIC30F2010, dsPIC30F4011/4012 AND dsPIC30F6010/ 6011/6012/6013/ 6014)

Address	Name	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0xF80000	FOSC	FCKSN	1<1:0>	—	_	-	_	FOS	<1:0>	—	_	—	—		FPR<	3:0>	
0xF80002	FWDT	FWDTEN	_	_	_	_	_			_	_	FWPSA<1:0>		FWPSB<3:0>			
0xF80004	FBORPOR	MCLREN	_	_	_	_	PWMPIN ⁽¹⁾	HPOL ⁽¹⁾	LPOL ⁽¹⁾	BOREN	_	BORV	/<1:0>	_	_	FPWR	T<1:0>
0xF80006	FBS	—	_	Reser	ved ⁽²⁾	_	_	_	Reserved ⁽²⁾	_	_	_	_		Reserv	/ed ⁽²⁾	
0xF80008	FSS	—	_	Reser	ved ⁽²⁾	-	_	Rese	rved ⁽²⁾	—	_	_	_		Reserv	/ed ⁽²⁾	
0xF8000A	FGS	—	_	_	_	-	_	—	—	_	_	_	_	_	Reserved ⁽²⁾	GCP	GWRP
0xF8000C	FICD	BKBUG	COE	_	_	—	—	—	—	_	—	_	_	_	_	ICS<	:1:0>

 On the 6011, 6012, 6013 and 6014, these bits are reserved (read as '1' and must be programmed as '1').
 Reserved bits read as '1' and must be programmed as '1'. Note

TABLE 5-9: dsPIC30F CONFIGURATION REGISTERS (FOR dsPIC30F5011/5013)

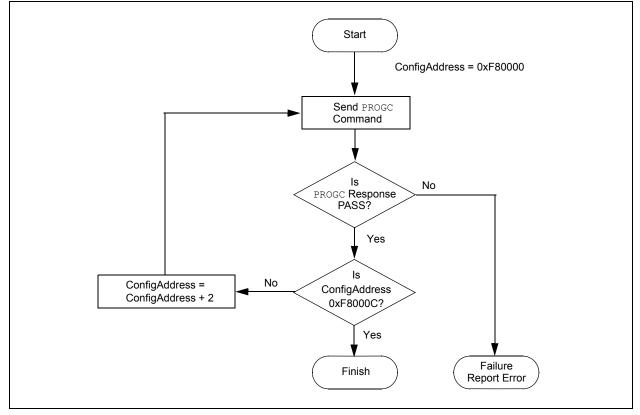
Address	Name	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0xF80000	FOSC	FCKSM	1<1:0>	—	—	-	_	FOS	i<1:0>	—	_	—	—		FPR<	3:0>	
0xF80002	FWDT	FWDTEN	_	_	_	—	_	_	_	_	_	FWPS	A<1:0>		FWPSE	3<3:0>	
0xF80004	FBORPOR	MCLREN	_	_	_	—	F	Reserved ⁽¹⁾		BOREN	_	BOR\	/<1:0>	—	_	FPWR	T<1:0>
0xF80006	FBS	_	_	RBS	<1:0>	_	_	—	EBS	—	_	—	—		BSS<2:0>		BWRP
0xF80008	FSS	_	_	RSS	<1:0>	_	—	ESS	<1:0>	_	_	_	_		SSS<2:0>		SWRP
0xF8000A	FGS	_		—	_	—	_	_	_	_	_	—	—	_	GSS<	1:0>	GWRP
0xF8000C	FICD	BKBUG	COE	_	_	—	_	_	_	_	_	_	_	—	_	ICS<	<1:0>

Note 1: Reserved bits read as '1' and must be programmed as '1'.

5.8 Exiting Enhanced ICSP Mode

The Enhanced ICSP mode is exited by removing power from the device or bringing MCLR to VIL. When normal user mode is next entered, the program that was stored using Enhanced ICSP will execute.

FIGURE 5-5: CONFIGURATION BIT PROGRAMMING FLOW



6.6 Configuration Information in the Hexadecimal File

To allow portability of code, the programmer must read the Configuration register locations from the hexadecimal file. If configuration information is not present in the hexadecimal file, a simple warning message should be issued by the programmer. Similarly, while saving a hexadecimal file, all configuration information must be included. An option to not include the configuration information can be provided.

Microchip Technology Inc. feels strongly that this feature is important for the benefit of the end customer.

6.7 Unit ID

The dsPIC30F devices contain 32 instructions of Unit ID. These are located at addresses 0x8005C0 through 0x8005FF. The Unit ID can be used for storing product information such as serial numbers, system manufacturing dates, manufacturing lot numbers and other such application-specific information.

A Bulk Erase does not erase the Unit ID locations. Instead, erase all executive memory using steps 1-4 as shown in Table 12-1, and program the Unit ID along with the programming executive. Alternately, use a Row Erase to erase the row containing the Unit ID locations.

6.8 Checksum Computation

Checksums for the dsPIC30F are 16 bits in size. The checksum is to total sum of the following:

- · Contents of code memory locations
- · Contents of Configuration registers

Table A-1 describes how to calculate the checksum for each device. All memory locations are summed one byte at a time, using only their native data size. More specifically, Configuration and device ID registers are summed by adding the lower two bytes of these locations (the upper byte is ignored), while code memory is summed by adding all three bytes of code memory.

Note: The checksum calculation differs depending on the code-protect setting. Table A-1 describes how to compute the checksum for an unprotected device and a read-protected device. Regardless of the code-protect setting, the Configuration registers can always be read.

7.0 PROGRAMMER – PROGRAMMING EXECUTIVE COMMUNICATION

7.1 Communication Overview

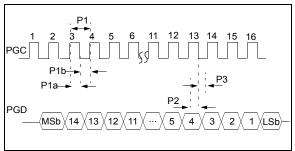
The programmer and programming executive have a master-slave relationship, where the programmer is the master programming device and the programming executive is the slave.

All communication is initiated by the programmer in the form of a command. Only one command at a time can be sent to the programming executive. In turn, the programming executive only sends one response to the programmer after receiving and processing a command. The programming executive command set is described in Section 8.0 "Programming Executive Commands". The response set is described in Section 9.0 "Programming Executive Responses".

7.2 Communication Interface and Protocol

The Enhanced ICSP interface is a 2-wire SPI interface implemented using the PGC and PGD pins. The PGC pin is used as a clock input pin, and the clock source must be provided by the programmer. The PGD pin is used for sending command data to, and receiving response data from, the programming executive. All serial data is transmitted on the falling edge of PGC and latched on the rising edge of PGC. All data transmissions are sent Most Significant bit (MSb) first, using 16-bit mode (see Figure 7-1).

FIGURE 7-1: PROGRAMMING EXECUTIVE SERIAL TIMING



Since a 2-wire SPI interface is used, and data transmissions are bidirectional, a simple protocol is used to control the direction of PGD. When the programmer completes a command transmission, it releases the PGD line and allows the programming executive to drive this line high. The programming executive keeps the PGD line high to indicate that it is processing the command.

After the programming executive has processed the command, it brings PGD low for 15 μ sec to indicate to the programmer that the response is available to be

Opcode	Mnemonic	Length (16-bit words)	Time Out	Description
0x0	SCHECK	1	1 ms	Sanity check.
0x1	READD	4	1 ms/row	Read N 16-bit words of data EEPROM, Configuration registers or device ID starting from specified address.
0x2	READP	4	1 ms/row	Read N 24-bit instruction words of code memory starting from specified address.
0x3	Reserved	N/A	N/A	This command is reserved. It will return a NACK.
0x4	PROGD ⁽²⁾	19	5 ms	Program one row of data EEPROM at the specified address, then verify.
0x5	PROGP(1)	51	5 ms	Program one row of code memory at the specified address, then verify.
0x6	PROGC	4	5 ms	Write byte or 16-bit word to specified Configuration register.
0x7	ERASEB	2	5 ms	Bulk Erase (entire code memory or data EEPROM), or erase by segment.
0x8	ERASED ⁽²⁾	3	5 ms/row	Erase rows of data EEPROM from specified address.
0x9	ERASEP(1)	3	5 ms/row	Erase rows of code memory from specified address.
0xA	QBLANK	3	300 ms	Query if the code memory and data EEPROM are blank.
0xB	QVER	1	1 ms	Query the programming executive software version.

TABLE 8-1: PROGRAMMING EXECUTIVE COMMAND SET

Note 1: One row of code memory consists of (32) 24-bit words. Refer to Table 5-2 for device-specific information.
2: One row of data EEPROM consists of (16) 16-bit words. Refer to Table 5-3 for device-specific information.

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8.5.11 QVER COMMAND

15	12	11

15 12	11 0
Opcode	Length

Field	Description
Opcode	0xB
Length	0x1

The QVER command queries the version of the programming executive software stored in test memory. The "version.revision" information is returned in the response's QE Code using a single byte with the following format: main version in upper nibble and revision in the lower nibble (i.e., 0x23 is version 2.3 of programming executive software).

Expected Response (2 words):

0x1BMN (where "MN" stands for version M.N) 0x0002

9.0 **PROGRAMMING EXECUTIVE** RESPONSES

9.1 Overview

The programming executive sends a response to the programmer for each command that it receives. The response indicates if the command was processed correctly, and includes any required response or error data.

The programming executive response set is shown in Table 9-1. This table contains the opcode, mnemonic and description for each response. The response format is described in Section 9.2 "Response Format".

TABLE 9-1: PROGRAMMING EXECUTIVE RESPONSE SET

Opcode	Mnemonic	Description
0x1	PASS	Command successfully processed.
0x2	FAIL	Command unsuccessfully processed.
0x3	NACK	Command not known.

9.2 **Response Format**

As shown in Example 9-1, all programming executive responses have a general format consisting of a two word header and any required data for the command. Table 9-2 lists the fields and their descriptions.

EXAMPLE 9-1: FORMAT

15 12	11 8	7	0
Opcode	Last_Cmd	QE_Code	
	Lenç	gth	
D_1 (if applicable)			
D_N (if applicable)			

TABLE 9-2: FIELDS AND DESCRIPTIONS

Field	Description
Opcode	Response opcode.
Last_Cmd	Programmer command that generated the response.
QE_Code	Query code or Error code.
Length	Response length in 16-bit words (includes 2 header words.)
D_1	First 16-bit data word (if applicable).
D_N	Last 16-bit data word (if applicable).

9.2.1 Opcode FIELD

The Opcode is a 4-bit field in the first word of the response. The Opcode indicates how the command was processed (see Table 9-1). If the command is processed successfully, the response opcode is PASS. If there is an error in processing the command, the response opcode is FAIL, and the QE Code indicates the reason for the failure. If the command sent to the programming executive is not identified, the programming executive returns a NACK response.

9.2.2 Last Cmd FIELD

The Last Cmd is a 4-bit field in the first word of the response and indicates the command that the programming executive processed. Since the programming executive can only process one command at a time, this field is technically not required. However, it can be used to verify whether the programming executive correctly received the command that the programmer transmitted.

11.4 Flash Memory Programming in ICSP Mode

Programming in ICSP mode is described in Section 11.4.1 "Programming Operations" through Section 11.4.3 "Starting and Stopping a Programming Cycle". Step-by-step procedures are described in Section 11.5 "Erasing Program Memory in Normal-Voltage Systems" through Section 11.13 "Reading the Application ID Word". All programming operations must use serial execution, as described in Section 11.2 "ICSP Operation".

11.4.1 PROGRAMMING OPERATIONS

Flash memory write and erase operations are controlled by the NVMCON register. Programming is performed by setting NVMCON to select the type of erase operation (Table 11-2) or write operation (Table 11-3), writing a key sequence to enable the programming and initiating the programming by setting the WR control bit, NVMCON<15>.

In ICSP mode, all programming operations are externally timed. An external 2 ms delay must be used between setting the WR control bit and clearing the WR control bit to complete the programming operation.

TABLE 11-2: NVMCON ERASE OPERATIONS

NVMCON Value	Erase Operation
0x407F	Erase all code memory, data memory (does not erase UNIT ID).
0x4075	Erase 1 row (16 words) of data EEPROM.
0x4074	Erase 1 word of data EEPROM.
0x4072	Erase all executive memory.
0x4071	Erase 1 row (32 instruction words) from 1 panel of code memory.
0x406E	Erase Boot Secure and General Segments, then erase FBS, FSS and FGS configuration registers.
0x4066	Erase all Data EEPROM allocated to Boot Segment.
0x405E	Erase Secure and General Segments, then erase FSS and FGS configuration registers.
0x4056	Erase all Data EEPROM allocated to Secure Segment.
0x404E	Erase General Segment, then erase FGS configuration register.
0x4046	Erase all Data EEPROM allocated to General Segment.

TABLE 11-3: NVMCON WRITE OPERATIONS

NVMCON Value	Write Operation
0x4008	Write 1 word to configuration
	memory.
0x4005	Write 1 row (16 words) to data memory.
0x4004	Write 1 word to data memory.
0x4001	Write 1 row (32 instruction words) into 1 panel of program memory.

11.4.2 UNLOCKING NVMCON FOR PROGRAMMING

Writes to the WR bit (NVMCON<15>) are locked to prevent accidental programming from taking place. Writing a key sequence to the NVMKEY register unlocks the WR bit and allows it to be written to. The unlock sequence is performed as follows:

MOV MOV	#0x55, W8 W8, NVMKEY
MOV	#0xAA, W9
MOV	W9, NVMKEY
Note:	Any working register, or working register pair, can be used to write the unlock sequence.

11.4.3 STARTING AND STOPPING A PROGRAMMING CYCLE

Once the unlock key sequence has been written to the NVMKEY register, the WR bit (NVMCON<15>) is used to start and stop an erase or write cycle. Setting the WR bit initiates the programming cycle. Clearing the WR bit terminates the programming cycle.

All erase and write cycles must be externally timed. An external delay must be used between setting and clearing the WR bit. Starting and stopping a programming cycle is performed as follows:

BSET	NVMCON,	#WR
<wait< td=""><td>2 ms></td><td></td></wait<>	2 ms>	
BCLR	NVMCON,	#WR

11.5 Erasing Program Memory in Normal-Voltage Systems

The procedure for erasing program memory (all code memory, data memory, executive memory and codeprotect bits) consists of setting NVMCON to 0x407F, unlocking NVMCON for erasing and then executing the programming cycle. This method of bulk erasing program memory only works for systems where VDD is between 4.5 volts and 5.5 volts. The method for erasing program memory for systems with a lower VDD (3.0 volts-4.5 volts) is described in Section 6.1 "Erasing Memory".

11.6 Erasing Program Memory in Low-Voltage Systems

The procedure for erasing program memory (all code memory and data memory) in low-voltage systems (with VDD between 2.5 volts and 4.5 volts) is quite different than the procedure for erasing program memory in normal-voltage systems. Instead of using a Bulk Erase operation, each region of memory must be individually erased by row. Namely, all of the code memory, executive memory and data memory must be erased one row at a time. This procedure is detailed in Table 11-5.

Due to security restrictions, the FBS, FSS and FGS register cannot be erased in low-voltage systems. Once any bits in the FGS register are programmed to '0', they can only be set back to '1' by performing a Bulk Erase in a normal-voltage system. Alternatively, a Segment Erase operation can be performed instead of a Bulk Erase.

Normal-voltage systems can also be used to erase program memory as shown in Table 11-5. However, since this method is more time-consuming and does not clear the code-protect bits, it is not recommended.

Note: Program memory must be erased before writing any data to program memory.

TABLE 11-5:SERIAL INSTRUCTION EXECUTION FOR ERASING PROGRAM MEMORY
(EITHER IN LOW-VOLTAGE OR NORMAL-VOLTAGE SYSTEMS)

Command (Binary)	Data (Hexadecimal)	Description
Step 1: Exit th	e Reset vector.	
0000	040100	GOTO 0x100
0000	040100 000000	GOTO 0x100 NOP
		/MADRU to erase code memory and initialize W7 for row address updates.
0000	EB0300 883B16	CLR W6 MOV W6, NVMADR
0000 0000	883B26 200407	MOV W6, NVMADRU MOV #0x40, W7
Step 3: Set N	VMCON to erase 1 r	ow of code memory.
0000 0000	24071A 883B0A	MOV #0x4071, W10 MOV W10, NVMCON
Step 4: Unloc	k the NVMCON to e	rase 1 row of code memory.
0000 0000 0000 0000	200558 883B38 200AA9 883B39	MOV #0x55, W8 MOV W8, NVMKEY MOV #0xAA, W9 MOV W9, NVMKEY
Step 5: Initiate	e the erase cycle.	
0000 0000 0000 	A8E761 000000 000000 -	BSET NVMCON, #WR NOP NOP Externally time 'P13a' ms (see Section 13.0 "AC/DC Characteristics and Timing Requirements")
0000 0000 0000 0000 0000	000000 000000 A9E761 000000 000000	NOP NOP BCLR NVMCON, #WR NOP NOP

11.8 Writing Code Memory

The procedure for writing code memory is similar to the procedure for clearing the Configuration registers, except that 32 instruction words are programmed at a time. To facilitate this operation, working registers W0:W5 are used as temporary holding registers for the data to be programmed.

Table 11-8 shows the ICSP programming details, including the serial pattern with the ICSP command code, which must be transmitted Least Significant bit first using the PGC and PGD pins (see Figure 11-2). In Step 1, the Reset vector is exited. In Step 2, the NVMCON register is initialized for single-panel programming of code memory. In Step 3, the 24-bit starting destination address for programming is loaded into the TBLPAG register and W7 register. The upper byte of the starting destination address is stored to TBLPAG, while the lower 16 bits of the destination address are stored to W7.

To minimize the programming time, the same packed instruction format that the programming executive uses is utilized (Figure 8-2). In Step 4, four packed instruction words are stored to working registers W0:W5 using the MOV instruction and the read pointer W6 is initialized. The contents of W0:W5 holding the packed instruction word data is shown in Figure 11-4.

In Step 5, eight TBLWT instructions are used to copy the data from W0:W5 to the write latches of code memory. Since code memory is programmed 32 instruction words at a time, Steps 4 and 5 are repeated eight times to load all the write latches (Step 6).

After the write latches are loaded, programming is initiated by writing to the NVMKEY and NVMCON registers in Steps 7 and 8. In Step 9, the internal PC is reset to 0x100. This is a precautionary measure to prevent the PC from incrementing into unimplemented memory when large devices are being programmed. Lastly, in Step 10, Steps 2-9 are repeated until all of code memory is programmed.

FIGURE 11-5: PACKED INSTRUCTION WORDS IN W0:W5

	15		8	7		0
W0			lsv	v0		
W1		MSB1			MSB0	
W2			lsv	v1		
W3			lsv	v2		
W4		MSB3			MSB2	
W5			lsv	v3		

Command (Binary)	Data (Hexadecimal)	Description	
Step 1: Exit th	e Reset vector.		
0000	040100	GOTO 0x100	
0000	040100	GOTO 0x100	
0000	000000	NOP	
Step 2: Set th	e NVMCON to progr	am 32 instruction words.	
0000	24001A	MOV #0x4001, W10	
0000	883B0A	MOV W10, NVMCON	
Step 3: Initiali	ze the write pointer (W7) for TBLWT instruction.	
0000	200xx0	MOV # <destinationaddress23:16>, W0</destinationaddress23:16>	
0000	880190	MOV W0, TBLPAG	
0000	2xxxx7	MOV # <destinationaddress15:0>, W7</destinationaddress15:0>	
Step 4: Initializ	Step 4: Initialize the read pointer (W6) and load W0:W5 with the next 4 instruction words to program.		
0000	2xxxx0	MOV # <lsw0>, W0</lsw0>	
0000	2xxxx1	MOV # <msb1:msb0>, W1</msb1:msb0>	
0000	2xxxx2	MOV # <lsw1>, W2</lsw1>	
0000	2xxxx3	MOV # <lsw2>, W3</lsw2>	
0000	2xxxx4	MOV # <msb3:msb2>, W4</msb3:msb2>	
0000	2xxxx5	MOV # <lsw3>, W5</lsw3>	

TABLE 11-8: SERIAL INSTRUCTION EXECUTION FOR WRITING CODE MEMORY

11.9 Writing Data EEPROM

The procedure for writing data EEPROM is very similar to the procedure for writing code memory, except that fewer words are programmed in each operation. When writing data EEPROM, one row of data EEPROM is programmed at a time. Each row consists of sixteen 16-bit data words. Since fewer words are programmed during each operation, only working registers W0:W3 are used as temporary holding registers for the data to be programmed.

Table 11-9 shows the ICSP programming details for writing data EEPROM. Note that a different NVMCON value is required to write to data EEPROM, and that the TBLPAG register is hard-coded to 0x7F (the upper byte address of all locations of data EEPROM).

	OFRIAL INOTRUCTION EVECUTION FOR WRITING RATA FERROM
TABLE 11-9:	SERIAL INSTRUCTION EXECUTION FOR WRITING DATA EEPROM

Command (Binary)	Data (Hexadecimal)	Description			
Step 1: Exit th	Step 1: Exit the Reset vector.				
0000	040100	GOTO 0x100			
0000	040100	GOTO 0x100			
0000	000000	NOP			
Step 2: Set the	e NVMCON to write	16 data words.			
0000	24005A	MOV #0x4005, W10			
0000	883B0A	MOV W10, NVMCON			
Step 3: Initializ	ze the write pointer	W7) for TBLWT instruction.			
0000	2007F0	MOV #0x7F, WO			
0000	880190	MOV W0, TBLPAG			
0000	2xxxx7	MOV # <destinationaddress15:0>, W7</destinationaddress15:0>			
Step 4: Load \	W0:W3 with the nex	4 data words to program.			
0000	2xxxx0	MOV # <wordo>, WO</wordo>			
0000	2xxxx1	MOV # <word1>, W1</word1>			
0000	2xxxx2	MOV # <word2>, W2</word2>			
0000	2xxxx3	MOV # <word3>, W3</word3>			
Step 5: Set the	e read pointer (W6)	and load the (next set of) write latches.			
0000	EB0300	CLR W6			
0000	000000	NOP			
0000	BB1BB6	TBLWTL [W6++], [W7++]			
0000	000000	NOP			
0000	000000	NOP			
0000	BB1BB6	TBLWTL [W6++], [W7++]			
0000	000000	NOP			
0000	000000	NOP			
0000	BB1BB6	TBLWTL [W6++], [W7++]			
0000	000000	NOP			
0000	000000	NOP			
0000	BB1BB6	TBLWTL [W6++], [W7++]			
0000	000000	NOP			
0000	000000	NOP			
Step 6: Repea	at steps 4-5 four time	es to load the write latches for 16 data words.			

Command (Binary)	Data (Hexadecimal)	Description	
Step 4: Output	Step 4: Output W0:W5 using the VISI register and REGOUT command.		
0000	883C20	MOV W0, VISI	
0000	000000	NOP	
0001	<visi></visi>	Clock out contents of VISI register	
0000	000000	NOP	
0000	883C21	MOV W1, VISI	
0000	000000	NOP	
0001	<visi></visi>	Clock out contents of VISI register	
0000	000000	NOP	
0000	883C22	MOV W2, VISI	
0000	000000	NOP	
0001	<visi></visi>	Clock out contents of VISI register	
0000	000000	NOP	
0000	883C23	MOV W3, VISI	
0000	000000	NOP	
0001	<visi></visi>	Clock out contents of VISI register	
0000	000000	NOP	
0000	883C24	MOV W4, VISI	
0000	000000	NOP	
0001	<visi></visi>	Clock out contents of VISI register	
0000	000000	NOP	
0000	883C25	MOV W5, VISI	
0000	000000	NOP	
0001	<visi></visi>	Clock out contents of VISI register	
0000	000000	NOP	
Step 5: Reset	the device intern	al PC.	
0000	040100	GOTO 0x100	
0000	000000	NOP	
Step 6: Repea	at steps 3-5 until a	all desired code memory is read.	

TABLE 11-10: SERIAL INSTRUCTION EXECUTION FOR READING CODE MEMORY (CONTINUED)

11.11 Reading Configuration Memory

The procedure for reading configuration memory is similar to the procedure for reading code memory, except that 16-bit data words are read instead of 24-bit words. Since there are seven Configuration registers, they are read one register at a time. Table 11-11 shows the ICSP programming details for reading all of the configuration memory. Note that the TBLPAG register is hard-coded to 0xF8 (the upper byte address of configuration memory), and the read pointer W6 is initialized to 0x0000.

TABLE 11-11: SERIAL INSTRUCTION EXECUTION FOR READING ALL CONFIGURATION MEMORY

Step 1: Exit the Reset vector. 0000 040100 GOTO 0x100 0000 040100 GOTO 0x100 0000 00000 NOP Step 2: Initialize TBLPAG, and the read pointer (W6) and the write pointer (W7) for TBLRD instruction. 0000 200F80 MOV #0xF8, W0 0000 200F80 MOV #0xF8, W0 0000 EB0300 CLR W6 0000 EB0380 CLR W7 0000 000000 NOP Step 3: Read the Configuration register and write it to the VISI register (located at 0x784). 0000 000000 NOP NOP 0000 000000 NOP NOP 0000 883C20 MOV W0, VISI 0000 000000 NOP NOP 0000 000000 NOP NOP 0000 Step 4: Output the VISI register using the REGOUT command. NOP 0001 <visi> Clock out contents of VISI register 0001 Step 5: Reset device internal PC. VISI <th>Command (Binary)</th><th>Data (Hexadecimal)</th><th>Description</th></visi>	Command (Binary)	Data (Hexadecimal)	Description	
0000 040100 GOTO 0x100 Step 2: Initializ TBLPAG, and the read pointer (W6) and the write pointer (W7) for TBLRD instruction. 0000 200F80 MoV #0xF8, W0 0000 B80190 MOV W0, TBLPAG 0000 EB0300 CLR W6 0000 EB0380 CLR W7 0000 B0080 CLR W7 0000 D00000 NOP Step 3: Read the Configuration register and write it to the VISI register (located at 0x784). 0000 BA0BB6 TBLRDL [W6++], [W7] 0000 D00000 NOP MOV W0, VISI 0000 BA0BB6 TBLRDL [W6++], [W7] 0000 D00000 NOP MOV W0, VISI 0000 Ba3220 MOV W0, VISI MOV Step 4: Output the VISI register using the REGOUT command. 0001 Clock out contents of VISI register 0000 NOP Step 5: Reset device intermal P	Step 1: Exit th	ne Reset vector.		
0000 00000 NOP Step 2: Initialize TBLPAG, and the read pointer (W6) and the write pointer (W7) for TBLRD instruction. 0000 200F80 MOV #0xF8, W0 0000 880190 MOV W0, TBLPAG 0000 EB0300 CLR W6 0000 EB0380 CLR W7 0000 O00000 NOP V Step 3: Read the Configuration register and write it to the VISI register (located at 0x784). 0000 BA0BB6 TBLRDL [W6++], [W7] 0000 000000 NOP Step 4: Output the VISI register using the REGOUT command. 0001 <visi> Olock out contents of VISI register 0000 NOP Step 5: Reset device internal PC.</visi>	0000	040100	GOTO 0x100	
Step 2: Initialize TBLPAG, and the read pointer (W6) and the write pointer (W7) for TBLRD instruction. 0000 200F80 MOV #0xF8, W0 0000 880190 MOV W0, TBLPAG 0000 EB0300 CLR W6 0000 EB0380 CLR W7 0000 00000 NOP V Step 3: Read the Configuration register and write it to the VISI register (located at 0x784). 0000 000000 NOP Step 3: Read the Configuration register and write it to the VISI register (located at 0x784). 0000 000000 NOP 0000 000000 NOP 0000 000000 NOP 0000 883c20 MOV W0, VISI 0000 000000 NOP Step 4: Output the VISI register using the REGOUT command. 0001 <visi> Clock out contents of VISI register 0000 00000 NOP Step 5: Reset device internal PC.</visi>				
0000 200F80 MOV #0xF8, W0 0000 880190 MOV W0, TBLPAG 0000 EB0300 CLR W6 0000 EB0380 CLR W7 0000 D00000 NOP NOP Step 3: Read the Configuration register and write it to the VISI register (located at 0x784). 0000 BA0BB6 TBLRDL [W6++], [W7] 0000 000000 NOP 0001 <visi command.<="" register="" regout="" td="" the="" using=""> 0001 <visi> Clock out contents of VISI register 0000 NOP NOP Step 5: Reset device internal PC. VISI ></visi></visi>				
0000 880190 MOV W0, TBLPAG 0000 EB0300 CLR W6 0000 EB0380 CLR W7 0000 000000 NOP Step 3: Read the Configuration register and write it to the VISI register (located at 0x784). 0000 BA0BB6 TBLRDL [W6++], [W7] 0000 000000 NOP 0000 883C20 MOV W0, VISI 0000 000000 NOP Step 4: Output the VISI register using the REGOUT command. Clock out contents of VISI register 0001 <visi> Clock out contents of VISI register 0000 00000 NOP</visi>	Step 2: Initiali	ze TBLPAG, and	the read pointer (W6) and the write pointer (W7) for TBLRD instruction.	
0000 EB0300 CLR W6 0000 EB0380 CLR W7 0000 00000 NOP Step 3: Read the Configuration register and write it to the VISI register (located at 0x784). 0000 BA0BB6 TBLRDL [W6++], [W7] 0000 000000 NOP 0001 CVISI register using the REGOUT command. 0001 <visi> Clock out contents of VISI register 0000 000000 NOP Step 5: Reset device internal PC. VISI register</visi>	0000	200F80	MOV #0xF8, WO	
0000 0000 EB 0380 00000 CLR NOP W7 NOP Step 3: Read Configuration register and write it to the VISI register (located at 0x784). 0000 BA0BB6 TBLRDL [W6++], [W7] 0000 000000 NOP 0001 CVISI Clock out contents of VISI register 0001 CVISI> Clock out contents of VISI register 0001 Step 5: Reset texter internal PC	0000	880190	MOV W0, TBLPAG	
0000 00000 NoP Step 3: Read UCONFiguration register and write it to the VISI register (located at 0x784). 0000 BA0BB6 TBLRDL [W6++], [W7] 0000 000000 NoP Step 4: Output: the VISI register using the REGOUT command. 0001 <visi> Clock out contents of VISI register 0001 <visi> Clock out contents of VISI register 0000 NoP NoP</visi></visi>	0000	EB0300	CLR W6	
Step 3: Read UP Configuration Get Configuration 0000 BA0BB6 TBLRDL [W6++], [W7] 0000 000000 NOP	0000	EB0380	CLR W7	
0000 BA0BB6 TBLRDL [W6++], [W7] 0000 000000 NOP 0000 000000 NOP 0000 883C20 MOV W0, VISI 0000 000000 NOP 0000 000000 NOP Step 4: Output the VISI register using the REGOUT command. 0001 0001 <visi> Clock out contents of VISI register 0000 000000 NOP</visi>	0000	000000	NOP	
0000 00000 NOP 0000 00000 NOP 0000 883c20 MOV W0, VISI 0000 000000 NOP Step 4: Output the VISI register using the REGOUT command. 0001 <visi> Clock out contents of VISI register 0000 000000 NOP</visi>	Step 3: Read	the Configuration	register and write it to the VISI register (located at 0x784).	
0000 00000 NOP 0000 883C20 MOV W0, VISI 0000 000000 NOP Step 4: Output the VISI register using the REGOUT command. 0001 <visi> Clock out contents of VISI register 0000 NOP NOP</visi>	0000	BA0BB6	TBLRDL [W6++], [W7]	
0000 883C20 MOV W0, VISI 0000 000000 NOP Step 4: Output the VISI register using the REGOUT command. 0001 <visi> Clock out contents of VISI register 0000 000000 NOP Step 5: Reset device internal PC.</visi>	0000	000000	NOP	
0000 NOP Step 4: Output the VISI register using the REGOUT command. 0001 <visi> Clock out contents of VISI register 0000 000000 NOP</visi>	0000		NOP	
Step 4: Output the VISI register using the REGOUT command. 0001 <visi> Clock out contents of VISI register 0000 000000 NOP Step 5: Reset device internal PC.</visi>			MOV W0, VISI	
0001 <visi> Clock out contents of VISI register 0000 000000 NOP Step 5: Reset device internal PC.</visi>	0000	000000	NOP	
0000 00000 NOP Step 5: Reset device internal PC. Image: Control of the second sec	Step 4: Output the VISI register using the REGOUT command.			
Step 5: Reset device internal PC.	0001	<visi></visi>	Clock out contents of VISI register	
	0000	000000	NOP	
	Step 5: Reset	device internal F	С.	
0000 040100 GOTO 0x100	0000	040100	GOTO 0x100	
0000 000000 NOP	0000	000000	NOP	
Step 6: Repeat steps 3-5 six times to read all of configuration memory.	Step 6: Repea	Step 6: Repeat steps 3-5 six times to read all of configuration memory.		

11.12 Reading Data Memory

The procedure for reading data memory is similar to that of reading code memory, except that 16-bit data words are read instead of 24-bit words. Since less data is read in each operation, only working registers W0:W3 are used as temporary holding registers for the data to be read.

Table 11-12 shows the ICSP programming details for reading data memory. Note that the TBLPAG register is hard-coded to 0x7F (the upper byte address of all locations of data memory).

TABLE 11-12: SERIAL INSTRUCTION EXECUTION FOR READING DATA MEMORY

Command (Binary)	Data (Hexadecimal)	Description
Step 1: Exit t	he Reset vector.	
0000	040100	GOTO 0x100
0000	040100	GOTO 0x100
0000	000000	NOP
Step 2: Initial	ize TBLPAG and t	the read pointer (W6) for TBLRD instruction.
0000	2007F0	MOV #0x7F, WO
0000	880190	MOV W0, TBLPAG
0000	2xxxx6	MOV # <sourceaddress15:0>, W6</sourceaddress15:0>
Step 3: Initial		er (W7) and store the next four locations of code memory to W0:W5.
	EB0380	CLR W7
0000	000000	NOP
0000	BA1BB6	TBLRDL [W6++], [W7++]
0000	000000	NOP
0000	000000	NOP
0000	BA1BB6	TBLRDL [W6++], [W7++]
0000	000000	NOP
0000	000000	NOP
0000	BA1BB6	TBLRDL [W6++], [W7++]
0000	000000	NOP
0000	000000	NOP
0000	BA1BB6	TBLRDL [W6++], [W7++]
0000	000000	NOP
0000	000000	NOP
		ne VISI register and REGOUT command.
0000	883C20	MOV W0, VISI
0000	000000	NOP
0001	<visi></visi>	Clock out contents of VISI register
0000	000000	NOP
0000	883C21	MOV W1, VISI
0000	000000	NOP
0000	<visi></visi>	NOP Clock out contents of VISI register
0001	000000	NOP
0000	883C22	MOV W2, VISI
0000	000000	NOP W2, VISI
0000	<visi></visi>	
0001	000000	Clock out contents of VISI register NOP
0000	883C23	
0000	000000	MOV W3, VISI NOP
0000	<visi></visi>	
0000	000000	Clock out contents of VISI register NOP
	t device internal F	
0000	040100	GOTO 0x100
0000	000000	NOP
0000	00000	101

11.13 Reading the Application ID Word

The application ID word is stored at address 0x8005BE in executive code memory. To read this memory location, you must use the SIX control code to move this program memory location to the VISI register. The REGOUT control code must then be used to clock the contents of the VISI register out of the device. The corresponding control and instruction codes that must be serially transmitted to the device to perform this operation are shown in Table 11-13.

Once the programmer has clocked-out the application ID word, it must be inspected. If the application ID has the value 0xBB, the programming executive is resident in memory and the device can be programmed using the mechanism described in Section 5.0 "Device Programming". However, if the application ID has any other value, the programming executive is not resident in memory. It must be loaded to memory before the device can be programming executive to the memory is described in Section 12.0 "Programming the Programming the Programming Executive to Memory".

11.14 Exiting ICSP Mode

After confirming that the programming executive is resident in memory, or loading the programming executive, ICSP mode is exited by removing power to the device or bringing MCLR to VIL. Programming can then take place by following the procedure outlined in **Section 5.0 "Device Programming"**.

Command (Binary)	Data (Hexadecimal)	Description
Step 1: Exit th	e Reset vector.	
0000 0000 0000	040100 040100 000000	GOTO 0x100 GOTO 0x100 NOP
Step 2: Initiali	ze TBLPAG and th	e read pointer (W0) for TBLRD instruction.
0000 0000 0000 0000 0000 0000 0000 0000	200800 880190 205BE0 207841 000000 BA0890 000000 000000	MOV #0x80, W0 MOV W0, TBLPAG MOV #0x5BE, W0 MOV VISI, W1 NOP TBLRDL [W0], [W1] NOP NOP
Step 3: Output	t the VISI register	using the REGOUT command.
0001 0000	<visi> 000000</visi>	Clock out contents of the VISI register NOP

TABLE 11-13: SERIAL INSTRUCTION EXECUTION FOR READING THE APPLICATION ID WORD

(Binary)	d Data (Hexadecim	nal) Description
	•	/W6) and load the (next four write) latches.
•		
0000 0000	EB0300 000000	CLR W6 NOP
0000		
	BB0BB6 000000	TBLWTL [W6++], [W7]
0000		NOP
0000	000000	NOP TBLWTH.B [W6++], [W7++]
0000	BBDBB6	
0000	000000	NOP
0000	000000 BBEBB6	
0000	-	TBLWTH.B [W6++], [++W7]
0000	000000	NOP
0000	000000	NOP
0000	BB1BB6	TBLWTL [W6++], [W7++]
0000	000000	NOP
0000	000000	NOP
0000	BB0BB6	TBLWTL [W6++], [W7]
0000	000000	NOP
0000	000000	NOP
0000	BBDBB6	TBLWTH.B [W6++], [W7++]
0000	000000	NOP
0000	000000	NOP
0000	BBEBB6	TBLWTH.B [W6++], [++W7]
0000	000000	NOP
0000	000000	NOP
0000	BB1BB6	TBLWTL [W6++], [W7++]
0000	000000	NOP
0000	000000	NOP
		ht times to load the write latches for the 32 instructions.
Step 10: 0		N for programming.
0000	200558	MOV #0x55, W8
0000	883B38	MOV W8, NVMKEY
0000	200AA9	MOV #0xAA, W9
0000	883B39	MOV W9, NVMKEY
		ming cycle
Step 11: In	itiate the programr	
-	A8E761	BSET NVMCON, #15
0000		
0000	A8E761	BSET NVMCON, #15
0000 0000 0000	A8E761 000000	BSET NVMCON, #15 NOP
0000 0000 0000	A8E761 000000 000000	BSET NVMCON, #15 NOP NOP Externally time 'P12a' ms (see Section 13.0 "AC/DC Characteristics and
-	A8E761 000000 000000	BSET NVMCON, #15 NOP NOP
- 0000 0000 - 0000	A8E761 000000 000000 -	BSET NVMCON, #15 NOP NOP Externally time 'P12a' ms (see Section 13.0 "AC/DC Characteristics and Timing Requirements")
0000 0000 0000 	A8E761 000000 000000 - 000000	BSET NVMCON, #15 NOP NOP Externally time `P12a' ms (see Section 13.0 "AC/DC Characteristics and Timing Requirements") NOP
0000 0000 	A8E761 000000 000000 - 000000 000000	BSET NVMCON, #15 NOP NOP Externally time `P12a' ms (see Section 13.0 "AC/DC Characteristics and Timing Requirements") NOP NOP
Step 11: In 0000 0000 0000 	A8E761 000000 000000 - 000000 000000 A9E761	BSET NVMCON, #15 NOP NOP Externally time 'P12a' ms (see Section 13.0 "AC/DC Characteristics and Timing Requirements") NOP NOP BCLR NVMCON, #15
0000 0000 	A8E761 000000 000000 - 000000 000000 A9E761 000000	BSET NVMCON, #15 NOP NOP Externally time 'P12a' ms (see Section 13.0 "AC/DC Characteristics and Timing Requirements") NOP NOP BCLR NVMCON, #15 NOP NOP
0000 0000 	A8E761 000000 000000 - 000000 000000 A9E761 000000 000000	BSET NVMCON, #15 NOP NOP Externally time 'P12a' ms (see Section 13.0 "AC/DC Characteristics and Timing Requirements") NOP NOP BCLR NVMCON, #15 NOP NOP

TABLE 12-1: PROGRAMMING THE PROGRAMMING EXECUTIVE (CONTINUED)

Command (Binary)	Data (Hexadecimal)	Description
Step 4: Outpu	t W0:W5 using th	ne VISI register and REGOUT command.
0000	883C20	MOV W0, VISI
0000	000000	NOP
0001	-	Clock out contents of VISI register
0000	883C21	MOV W1, VISI
0000	000000	NOP
0001	-	Clock out contents of VISI register
0000	883C22	MOV W2, VISI
0000	000000	NOP
0001	-	Clock out contents of VISI register
0000	883C23	MOV W3, VISI
0000	000000	NOP
0001	-	Clock out contents of VISI register
0000	883C24	MOV W4, VISI
0000	000000	NOP
0001	-	Clock out contents of VISI register
0000	883C25	MOV W5, VISI
0000	000000	NOP
0001	-	Clock out contents of VISI register
Step 5: Reset	the device intern	al PC.
0000	040100	GOTO 0x100
0000	000000	NOP
Step 6: Repeat Steps 3-5 until all 736 instruction words of executive memory are read.		

TABLE 12-2: READING EXECUTIVE MEMORY (CONTINUED)

Note the following details of the code protection feature on Microchip devices:

- · Microchip products meet the specification contained in their particular Microchip Data Sheet.
- Microchip believes that its family of products is one of the most secure families of its kind on the market today, when used in the intended manner and under normal conditions.
- There are dishonest and possibly illegal methods used to breach the code protection feature. All of these methods, to our knowledge, require using the Microchip products in a manner outside the operating specifications contained in Microchip's Data Sheets. Most likely, the person doing so is engaged in theft of intellectual property.
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