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Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M3
Core Size	32-Bit Single-Core
Speed	72MHz
Connectivity	I ² C, Microwire, SPI, SSI, SSP, UART/USART, USB
Peripherals	Brown-out Detect/Reset, POR, WDT
Number of I/O	28
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	4K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	32-VQFN Exposed Pad
Supplier Device Package	32-HVQFN (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/lpc1342fhn33-551

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

NXP Semiconductors

LPC1311/13/42/43

32-bit ARM Cortex-M3 microcontroller



32-bit ARM Cortex-M3 microcontroller

6.2 Pin description

Table 3. LPC1313/42	Fable 3. LPC1313/42/43 LQFP48 pin description table					
Symbol	Pin	Start logic input	Туре	Reset state [1]	Description	
RESET/PIO0_0	3 <u>[2]</u>	yes	I	I; PU	RESET — External reset input with 20 ns glitch filter. A LOW-going pulse as short as 50 ns on this pin resets the device, causing I/O ports and peripherals to take on their default states, and processor execution to begin at address 0.	
			I/O	-	PIO0_0 — General purpose digital input/output pin with 10 ns glitch filter.	
PIO0_1/CLKOUT/ CT32B0_MAT2/ USB_FTOGGLE	4 <u>[3]</u>	yes	I/O	I; PU	PIO0_1 — General purpose digital input/output pin. A LOW level on this pin during reset starts the ISP command handler or the USB device enumeration (USB on LPC1342/43 only, see description of PIO0_3).	
			0	-	CLKOUT — Clockout pin.	
			0	-	CT32B0_MAT2 — Match output 2 for 32-bit timer 0.	
			0	-	USB_FTOGGLE — USB 1 ms Start-of-Frame signal (LPC1342/43 only).	
PIO0_2/SSEL0/	10 <u>^[3]</u>	yes	I/O	I; PU	PIO0_2 — General purpose digital input/output pin.	
CT16B0_CAP0			I/O	-	SSEL0 — Slave select for SSP0.	
			I	-	CT16B0_CAP0 — Capture input 0 for 16-bit timer 0.	
PIO0_3/USB_VBUS	14 <u>^[3]</u>	yes	I/O	I; PU	PIO0_3 — General purpose digital input/output pin. LPC1342/43 only: A LOW level on this pin during reset starts the ISP command handler, a HIGH level starts the USB device enumeration.	
			I	-	USB_VBUS — Monitors the presence of USB bus power (LPC1342/43 only).	
PIO0_4/SCL	15 <u>^[4]</u>	yes	I/O	I; IA	PIO0_4 — General purpose digital input/output pin (open-drain).	
			I/O	-	SCL — I ² C-bus clock input/output (open-drain). High-current sink only if I ² C Fast-mode Plus is selected in the I/O configuration register.	
PIO0_5/SDA	16 <u>^[4]</u>	yes	I/O	I; IA	PIO0_5 — General purpose digital input/output pin (open-drain).	
			I/O	-	SDA — I^2C -bus data input/output (open-drain). High-current sink only if I^2C Fast-mode Plus is selected in the I/O configuration register.	
PIO0_6/	22 <u>[3]</u>	yes	I/O	I; PU	PIO0_6 — General purpose digital input/output pin.	
USB_CONNECT/ SCK0			0	-	USB_CONNECT — Signal used to switch an external 1.5 k Ω resistor under software control. Used with the SoftConnect USB feature (LPC1342/43 only).	
			I/O	-	SCK0 — Serial clock for SSP0.	
PIO0_7/CTS	23 <u>[3]</u>	yes	I/O	I; PU	PIO0_7 — General purpose digital input/output pin (high-current output driver).	
			I	-	CTS — Clear To Send input for UART.	
PIO0_8/MISO0/	27 <u>[3]</u>	yes	I/O	I; PU	PIO0_8 — General purpose digital input/output pin.	
CT16B0_MAT0			I/O	-	MISO0 — Master In Slave Out for SSP0.	
			0	-	CT16B0_MAT0 — Match output 0 for 16-bit timer 0.	

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Symbol	Pin	Start logic input	Туре	Reset state [1]	Description
PIO0_9/MOSI0/	28 <u>[3]</u>	yes	I/O	I; PU	PIO0_9 — General purpose digital input/output pin.
CT16B0_MAT1/			I/O	-	MOSI0 — Master Out Slave In for SSP0.
300			0	-	CT16B0_MAT1 — Match output 1 for 16-bit timer 0.
			0	-	SWO — Serial wire trace output.
SWCLK/PIO0_10/	29 <u>[3]</u>	yes	I	I; PU	SWCLK — Serial wire clock.
SCK0/CT16B0_MAT2			I/O	-	PIO0_10 — General purpose digital input/output pin.
			I/O	-	SCK0 — Serial clock for SSP0.
			0	-	CT16B0_MAT2 — Match output 2 for 16-bit timer 0.
R/PIO0_11/ AD0/CT32B0_MAT3	32 <u>[5]</u>	yes	-	I; PU	${\bf R}$ — Reserved. Configure for an alternate function in the IOCONFIG block.
			I/O	-	PIO0_11 — General purpose digital input/output pin.
			I	-	AD0 — A/D converter, input 0.
			0	-	CT32B0_MAT3 — Match output 3 for 32-bit timer 0.
R/PIO1_0/ AD1/CT32B1_CAP0	33 <u>[5]</u>	yes	-	I; PU	${\bf R}$ — Reserved. Configure for an alternate function in the IOCONFIG block.
			I/O	-	PIO1_0 — General purpose digital input/output pin.
			I	-	AD1 — A/D converter, input 1.
			I	-	CT32B1_CAP0 — Capture input 0 for 32-bit timer 1.
R/PIO1_1/ AD2/CT32B1_MAT0	34 <u>[5]</u>	yes	-	I; PU	R — Reserved. Configure for an alternate function in the IOCONFIG block.
			I/O	-	PIO1_1 — General purpose digital input/output pin.
			I	-	AD2 — A/D converter, input 2.
			0	-	CT32B1_MAT0 — Match output 0 for 32-bit timer 1.
R/PIO1_2/ AD3/CT32B1_MAT1	35 <u>[5]</u>	yes	-	I; PU	R — Reserved. Configure for an alternate function in the IOCONFIG block.
			I/O	-	PIO1_2 — General purpose digital input/output pin.
			I	-	AD3 — A/D converter, input 3.
			0	-	CT32B1_MAT1 — Match output 1 for 32-bit timer 1.
SWDIO/PIO1_3/	39 <u>[5]</u>	yes	I/O	I; PU	SWDIO — Serial wire debug input/output.
AD4/ CT32B1 MAT2			I/O	-	PIO1_3 — General purpose digital input/output pin.
••••==• <u>-</u>			I	-	AD4 — A/D converter, input 4.
			0	-	CT32B1_MAT2 — Match output 2 for 32-bit timer 1.
PIO1_4/AD5/ CT32B1_MAT3/	40 <u>^[5]</u>	yes	I/O	I; PU	PIO1_4 — General purpose digital input/output pin.
WAKEUP			1	-	AD5 — A/D converter, input 5.
			0	-	CT32B1_MAT3 — Match output 3 for 32-bit timer 1.
			I	-	WAKEUP — Deep power-down mode wake-up pin with 20 ns glitch filter. This pin must be pulled HIGH externally to enter Deep power-down mode and pulled LOW to exit Deep power-down mode. A LOW-going pulse as short as 50 ns wakes up the part.

Table 3. LPC1313/42/43 LQFP48 pin description table ...continued

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	/10/42	740 110		pin ac	
Symbol	Pin	Start logic input	Туре	Reset state [1]	Description
RESET/PIO0_0 2		yes	I	I; PU	RESET — External reset input with 20 ns glitch filter. A LOW-going pulse as short as 50 ns on this pin resets the device, causing I/O ports and peripherals to take on their default states, and processor execution to begin at address 0.
			I/O	-	PIO0_0 — General purpose digital input/output pin with 10 ns glitch filter.
PIO0_1/CLKOUT/ CT32B0_MAT2/ USB_FTOGGLE	3 <u>[3]</u>	yes	I/O	I; PU	PIO0_1 — General purpose digital input/output pin. A LOW level on this pin during reset starts the ISP command handler or the USB device enumeration (USB on LPC1342/43 only, see description of PIO0_3).
			0	-	CLKOUT — Clock out pin.
			0	-	CT32B0_MAT2 — Match output 2 for 32-bit timer 0.
			0	-	USB_FTOGGLE — USB 1 ms Start-of-Frame signal (LPC1342/43 only).
PIO0_2/SSEL0/	8 <u>[3]</u>	yes	I/O	I; PU	PIO0_2 — General purpose digital input/output pin.
CT16B0_CAP0			I/O	-	SSEL0 — Slave select for SSP0.
			I	-	CT16B0_CAP0 — Capture input 0 for 16-bit timer 0.
PIO0_3/ 9[3] USB_VBUS		yes	I/O	I; PU	PIO0_3 — General purpose digital input/output pin. LPC1342/43 only: A LOW level on this pin during reset starts the ISP command handler, a HIGH level starts the USB device enumeration.
			I	-	USB_VBUS — Monitors the presence of USB bus power (LPC1342/43 only).
PIO0_4/SCL	10 <u>[4]</u>	yes	I/O	I; IA	PIO0_4 — General purpose digital input/output pin (open-drain).
			I/O	-	$\label{eq:scl} \begin{array}{l} \textbf{SCL} - I^2 C \text{-bus clock input/output (open-drain). High-current sink only if} \\ I^2 C \text{ Fast-mode Plus is selected in the I/O configuration register.} \end{array}$
PIO0_5/SDA	11 <u>[4]</u>	yes	I/O	I; IA	PIO0_5 — General purpose digital input/output pin (open-drain).
			I/O	-	SDA — I^2C -bus data input/output (open-drain). High-current sink only if I^2C Fast-mode Plus is selected in the I/O configuration register.
PIO0_6/	15 <u>[3]</u>	yes	I/O	I; PU	PIO0_6 — General purpose digital input/output pin.
USB_CONNECT/ SCK0			0	-	USB_CONNECT — Signal used to switch an external 1.5 k Ω resistor under software control. Used with the SoftConnect USB feature (LPC1342/43 only).
			I/O	-	SCK0 — Serial clock for SSP0.
PIO0_7/CTS	16 <u>[3]</u>	yes	I/O	I; PU	PIO0_7 — General purpose digital input/output pin (high-current output driver).
			I	-	CTS — Clear To Send input for UART.
PIO0_8/MISO0/	17 <u>[3]</u>	yes	I/O	I; PU	PIO0_8 — General purpose digital input/output pin.
CT16B0_MAT0			I/O	-	MISO0 — Master In Slave Out for SSP0.
			0	-	CT16B0_MAT0 — Match output 0 for 16-bit timer 0.
PIO0_9/MOSI0/	18 <u>[3]</u>	yes	I/O	I; PU	PIO0_9 — General purpose digital input/output pin.
CT16B0_MAT1/ SWO			I/O	-	MOSI0 — Master Out Slave In for SSP0.
			0	-	CT16B0_MAT1 — Match output 1 for 16-bit timer 0.
			0	-	SWO — Serial wire trace output.

Table 4 LPC1311/13/42/43 HVQFN33 pin description table

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Symbol	Pin	Start logic input	Туре	Reset state [1]	Description	
PIO1_7/TXD/	32 <u>[3]</u>	yes	I/O	I; PU	PIO1_7 — General purpose digital input/output pin.	
CT32B0_MAT1			0	-	TXD — Transmitter output for UART.	
			0	-	CT32B0_MAT1 — Match output 1 for 32-bit timer 0.	
PIO1_8/	7 <u>[3]</u>	yes	I/O	I; PU	PIO1_8 — General purpose digital input/output pin.	
CT16B1_CAP0			I	-	CT16B1_CAP0 — Capture input 0 for 16-bit timer 1.	
PIO1_9/	12 <u>[3]</u>	yes	I/O	I; PU	PIO1_9 — General purpose digital input/output pin.	
CT16B1_MAT0			0	-	CT16B1_MAT0 — Match output 0 for 16-bit timer 1.	
PIO1_10/AD6/	20 <u>[5]</u>	yes	I/O	I; PU	PIO1_10 — General purpose digital input/output pin.	
CT16B1_MAT1			Ι	-	AD6 — A/D converter, input 6.	
			0	-	CT16B1_MAT1 — Match output 1 for 16-bit timer 1.	
PIO1_11/AD7 27 ^[5]		yes	I/O	I; PU	PIO1_11 — General purpose digital input/output pin.	
			Ι	-	AD7 — A/D converter, input 7.	
PIO2_0/DTR	1 <u>[3]</u>	yes	I/O	I; PU	PIO2_0 — General purpose digital input/output pin.	
			0	-	DTR — Data Terminal Ready output for UART.	
PIO3_2	28 <u>[3]</u>	yes	I/O	I; PU	PIO3_2 — General purpose digital input/output pin.	
PIO3_4	13 <u>[3]</u>	no	I/O	I; PU	PIO3_4 — General purpose digital input/output pin (LPC1311/13 only).	
PIO3_5	14 <u>[3]</u>	no	I/O	I; PU	PIO3_5 — General purpose digital input/output pin (LPC1311/13 only).	
USB_DM	13 <u>[6]</u>	no	I/O	F	USB_DM — USB bidirectional D- line (LPC1342/43 only).	
USB_DP	14 <u>^[6]</u>	no	I/O	F	USB_DP — USB bidirectional D+ line (LPC1342/43 only).	
V _{DD}	6; 29	-	I	-	3.3 V supply voltage to the internal regulator, the external rail, and the ADC. Also used as the ADC reference voltage.	
XTALIN	4 <u>[7]</u>	-	I	-	Input to the oscillator circuit and internal clock generator circuits. Input voltage must not exceed 1.8 V.	
XTALOUT	5 <u>[7]</u>	-	0	-	Output from the oscillator amplifier.	
V _{SS}	33	-	-	-	Thermal pad. Connect to ground.	

Table 4. LPC1311/13/42/43 HVQFN33 pin description table ...continued

[1] Pin state at reset for default function: I = Input; O = Output; PU = internal pull-up enabled (for V_{DD} = 3.3 V, pin is pulled up to 2.6 V for parts LPC1311/13/42/43 and pulled up to 3.3 V for parts LPC1311/01 and LPC1313/01); IA = inactive, no pull-up/down enabled. F = floating; floating pins, if not used, should be tied to ground or power to minimize power consumption.

[2] 5 V tolerant pad. See <u>Figure 37</u> for pad characteristics. RESET functionality is not available in Deep power-down mode. Use the WAKEUP pin to reset the chip and wake up from Deep power-down mode. An external pull-up resistor is required on this pin for the Deep power-down mode.

[3] 5 V tolerant pad providing digital I/O functions with configurable pull-up/pull-down resistors and configurable hysteresis (see Figure 36).

[4] I²C-bus pads compliant with the I²C-bus specification for I²C standard mode and I²C Fast-mode Plus.

[5] 5 V tolerant pad providing digital I/O functions with configurable pull-up/pull-down resistors, configurable hysteresis, and analog input. When configured as a ADC input, digital section of the pad is disabled, and the pin is not 5 V tolerant (see <u>Figure 36</u>).

[6] Pad provides USB functions. It is designed in accordance with the USB specification, revision 2.0 (Full-speed and Low-speed mode only). This pad is not 5 V tolerant.

[7] When the system oscillator is not used, connect XTALIN and XTALOUT as follows: XTALIN can be left floating or can be grounded (grounding is preferred to reduce susceptibility to noise). XTALOUT should be left floating.

7.10 UART

The LPC1311/13/42/43 contains one UART.

Support for RS-485/9-bit mode allows both software address detection and automatic address detection using 9-bit mode.

The UART includes a fractional baud rate generator. Standard baud rates such as 115200 Bd can be achieved with any crystal frequency above 2 MHz.

7.10.1 Features

- Maximum UART data bit rate of 4.5 MBit/s.
- 16-byte receive and transmit FIFOs.
- Register locations conform to 16C550 industry standard.
- Receiver FIFO trigger points at 1 B, 4 B, 8 B, and 14 B.
- Built-in fractional baud rate generator covering wide range of baud rates without a need for external crystals of particular values.
- Fractional divider for baud rate control, auto baud capabilities and FIFO control mechanism that enables software flow control implementation.
- Support for RS-485/9-bit mode.
- Support for modem control.

7.11 SSP serial I/O controller

The LPC1311/13/42/43 contain one SSP controller. An additional SSP controller is available on the LPC1313FBD48/01 package.

The SSP controller is capable of operation on a SSP, 4-wire SSI, or Microwire bus. It can interact with multiple masters and slaves on the bus. Only a single master and a single slave can communicate on the bus during a given data transfer. The SSP supports full duplex transfers, with frames of 4 bits to 16 bits of data flowing from the master to the slave and from the slave to the master. In practice, often only one of these data flows carries meaningful data.

7.11.1 Features

- Maximum SSP speed of 36 Mbit/s (master) or 6 Mbit/s (slave)
- Compatible with Motorola SPI, 4-wire Texas Instruments SSI, and National Semiconductor Microwire buses
- Synchronous serial communication
- Master or slave operation
- 8-frame FIFOs for both transmit and receive
- 4-bit to 16-bit frame

7.12 I²C-bus serial I/O controller

The LPC1311/13/42/43 contain one I²C-bus controller.

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7.18.5 Power control

The LPC1311/13/42/43 support a variety of power control features. There are three special modes of processor power reduction: Sleep mode, Deep-sleep mode, and Deep power-down mode. The CPU clock rate may also be controlled as needed by changing clock sources, reconfiguring PLL values, and/or altering the CPU clock divider value. This allows a trade-off of power versus processing speed based on application requirements. In addition, a register is provided for shutting down the clocks to individual on-chip peripherals, allowing fine tuning of power consumption by eliminating all dynamic power use in any peripherals that are not required for the application. Selected peripherals have their own clock divider which provides even better power control.

7.18.5.1 Power profiles (LPC1300L series, LPC1311/01 and LPC1313/01 only)

The power consumption in Active and Sleep modes can be optimized for the application through simple calls to the power profile. The power configuration routine configures the LPC1311/01 and the LPC1313/01 for one of the following power modes:

- Default mode corresponding to power configuration after reset.
- CPU performance mode corresponding to optimized processing capability.
- Efficiency mode corresponding to optimized balance of current consumption and CPU performance.
- Low-current mode corresponding to lowest power consumption.

In addition, the power profile includes routines to select the optimal PLL settings for a given system clock and PLL input clock.

7.18.5.2 Sleep mode

When Sleep mode is entered, the clock to the core is stopped. Resumption from the Sleep mode does not need any special sequence but re-enabling the clock to the ARM core.

In Sleep mode, execution of instructions is suspended until either a reset or interrupt occurs. Peripheral functions continue operation during Sleep mode and may generate interrupts to cause the processor to resume execution. Sleep mode eliminates dynamic power used by the processor itself, memory systems and related controllers, and internal buses.

7.18.5.3 Deep-sleep mode

In Deep-sleep mode, the chip is in Sleep mode, and in addition all analog blocks are shut down. As an exception, the user has the option to keep the watchdog oscillator and the BOD circuit running for self-timed wake-up and BOD protection. Deep-sleep mode allows for additional power savings.

Up to 40 pins total can serve as external wake-up pins to the start logic to wake up the chip from Deep-sleep mode (see <u>Section 7.19.1</u>).

Unless the watchdog oscillator is selected to run in Deep-sleep mode, the clock source should be switched to IRC before entering Deep-sleep mode, because the IRC can be switched on and off glitch-free.

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There are three levels of Code Read Protection:

- 1. CRP1 disables access to chip via the SWD and allows partial flash update (excluding flash sector 0) using a limited set of the ISP commands. This mode is useful when CRP is required and flash field updates are needed but all sectors can not be erased.
- 2. CRP2 disables access to chip via the SWD and only allows full flash erase and update using a reduced set of the ISP commands.
- Running an application with level CRP3 selected fully disables any access to chip via the SWD pins and the ISP. This mode effectively disables ISP override using PIO0_1 pin, too. It is up to the user's application to provide (if needed) flash update mechanism using IAP calls or call reinvoke ISP command to enable flash update via UART.

CAUTION



If level three Code Read Protection (CRP3) is selected, no future factory testing can be performed on the device.

7.19.5 Boot loader

The boot loader controls initial operation after reset and also provides the means to program the flash memory. This could be initial programming of a blank device, erasure and re-programming of a previously programmed device, or programming of the flash memory by the application program in a running system.

The boot loader code is executed every time the part is reset or powered up. The loader can either execute the ISP command handler or the user application code, or, on the LPC1342/43, it can program the flash image via an attached MSC device through USB (Windows operating system only). A LOW level during reset applied to the PIO0_1 pin is considered as an external hardware request to start the ISP command handler or the USB device enumeration. The state of PIO0_3 determines whether the UART or USB interface will be used (LPC1342/43 only).

7.19.6 APB interface

The APB peripherals are located on one APB bus.

7.19.7 AHB-Lite

The AHB-Lite connects the instruction (I-code) and data (D-code) CPU buses of the ARM Cortex-M3 to the flash memory, the main static RAM, and the boot ROM.

7.19.8 External interrupt inputs

All GPIO pins can be level or edge sensitive interrupt inputs. In addition, start logic inputs serve as external interrupts (see <u>Section 7.19.1</u>).

7.19.9 Memory mapping control

The Cortex-M3 incorporates a mechanism that allows remapping the interrupt vector table to alternate locations in the memory map. This is controlled via the Vector Table Offset Register contained in the NVIC.

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$T_{amb} = -4$	40 °C to +85 °C, unless o	otherwise specified.					
Symbol	Parameter	Conditions		Min	Typ <u>[1]</u>	Max	Unit
I _{OH}	HIGH-level output current	$\begin{array}{l} 2.5 \ \text{V} \leq \text{V}_{\text{DD}} \leq 3.6 \ \text{V}; \\ \text{V}_{\text{OH}} = \text{V}_{\text{DD}} - 0.4 \ \text{V} \end{array}$		20	-	-	mA
	$\begin{array}{l} 2.0 \ \text{V} \leq \text{V}_{\text{DD}} < 2.5 \ \text{V}; \\ \text{V}_{\text{OH}} = \text{V}_{\text{DD}} - 0.4 \ \text{V}; \end{array}$		12	-	-	mA	
I _{OL}	LOW-level output	$2.5~\text{V} \leq \text{V}_{\text{DD}} \leq 3.6~\text{V};~\text{V}_{\text{OL}} = 0.4~\text{V}$		4	-	-	mA
	current	$2.0~\text{V} \leq \text{V}_{\text{DD}}$ < 2.5 V; V_{OL} = 0.4 V		3	-	-	mA
I _{pd}	pull-down current	V _I = 5 V		10	50	150	μA
I _{pu}	pull-up current	$V_I = 0 V$		–15	-50	-85	μA
		$V_{DD} < V_I < 5 V$		0	0	0	μA
I ² C-bus	pins (PIO0_4 and PIO0	_5); see <u>Figure 20</u>					
V _{IH}	HIGH-level input voltage			$0.7 V_{DD}$	-	-	V
V _{IL}	LOW-level input voltage	e		-	-	0.3V _{DD}	V
V _{hys}	hysteresis voltage			-	0.05V _{DD}	-	V
I _{OL}	LOW-level output current	V_{OL} = 0.4 V; I ² C-bus pins configured as standard mode pins					
		$2.5~\text{V} \leq \text{V}_{\text{DD}} \leq 3.6~\text{V}$		3.5	-	-	mA
		$2.0~\textrm{V} \leq \textrm{V}_\textrm{DD} < 2.5~\textrm{V}$		3.0	-	-	mA
I _{OL}	LOW-level output current	V _{OL} = 0.4 V; I ² C-bus pins configured as Fast-mode Plus pins					
		$2.5~\text{V} \leq \text{V}_{\text{DD}} \leq 3.6~\text{V}$		20	-	-	mA
		$2.0 \text{ V} \leq \text{V}_{\text{DD}} < 2.5 \text{ V}$		16	-	-	
ILI	input leakage current	$V_I = V_{DD}$	[16]	-	2	4	μA
		V _I = 5 V		-	10	22	μA
Oscillate	or pins						
V _{i(xtal)}	crystal input voltage			-0.5	+1.8	+1.95	V
V _{o(xtal)}	crystal output voltage			-0.5	+1.8	+1.95	V
USB pin	is (LPC1342/43 only)						
I _{OZ}	OFF-state output current	0 V < V _I < 3.3 V	<u>[17]</u>	-	-	±10	μA
V _{BUS}	bus supply voltage		[17]	-	-	5.25	V
V _{DI}	differential input sensitivity voltage	(D+) – (D–)	[17]	0.2	-	-	V
V _{CM}	differential common mode voltage range	includes V _{DI} range	[17]	0.8	-	2.5	V
V _{th(rs)se}	single-ended receiver switching threshold voltage		[17]	0.8	-	2.0	V
V _{OL}	LOW-level output voltage	for low-/full-speed; R _L of 1.5 k Ω to 3.6 V	[17]	-	-	0.18	V

Table 7. Static characteristics ...continued

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9.4 Power consumption for LPC1300L series (LPC1311/01 and LPC1313/01)

Remark: Applies to parts LPC1311/01 and LPC1313/01 and all their packages.

Power measurements in Active, Sleep, and Deep-sleep modes were performed under the following conditions (see *LPC13xx user manual*):

- Configure all pins as GPIO with pull-up resistor disabled in the IOCONFIG block.
- Configure GPIO pins as outputs using the GPIOnDIR registers.
- Write 0 to all GPIOnDATA registers to drive the outputs LOW.

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10.3 External clock

Table 14. Dynamic characteristic: external clock

 $T_{amb} = -40 \circ C$ to +85 $\circ C$; V_{DD} over specified ranges.^[1]

Symbol	Parameter	Conditions	Min	Typ <u>[2]</u>	Max	Unit
f _{osc}	oscillator frequency		1	-	25	MHz
T _{cy(clk)}	clock cycle time		40	-	1000	ns
t _{CHCX}	clock HIGH time		$T_{cy(clk)} imes 0.4$	-	-	ns
t _{CLCX}	clock LOW time		$T_{cy(clk)} imes 0.4$	-	-	ns
t _{CLCH}	clock rise time		-	-	5	ns
t _{CHCL}	clock fall time		-	-	5	ns

[1] Parameters are valid over operating temperature range unless otherwise specified.

[2] Typical ratings are not guaranteed. The values listed are at room temperature (25 °C), nominal supply voltages.



10.7 SSP0/1 interface

Remark: The SSP1 interface is available on the LPC1313FBD48/01 only.

Table 19. Dynamic characteristics: SSP pins in SPI mode

Symbol	Parameter	Conditions		Min	Max	Unit
SSP master						
T _{cy(clk)}	clock cycle time	full-duplex mode	[1]	40	-	ns
		when only transmitting	[1]	27.8	-	ns
t _{DS}	data set-up time	in SPI mode;	[2]	15	-	ns
		$2.4~V \leq V_{DD} \leq 3.6~V$				
		$2.0~\textrm{V} \leq \textrm{V}_\textrm{DD} < 2.4~\textrm{V}$	[2]	20	-	ns
t _{DH}	data hold time	in SPI mode	[2]	0	-	ns
t _{v(Q)}	data output valid time	in SPI mode	[2]	-	10	ns
t _{h(Q)}	data output hold time	in SPI mode	[2]	0	-	ns
SSP slave						
T _{cy(PCLK)}	PCLK cycle time			13.9	-	ns
t _{DS}	data set-up time	in SPI mode	[3][4]	0	-	ns
t _{DH}	data hold time	in SPI mode	[3][4]	$3 \times T_{cy(PCLK)}$ + 4	-	ns
t _{v(Q)}	data output valid time	in SPI mode	[3][4]	-	$3 \times T_{cy(PCLK)}$ + 11	ns
t _{h(Q)}	data output hold time	in SPI mode	[3][4]	-	$2 \times T_{cy(PCLK)}$ + 5	ns

[1] T_{cy(clk)} = (SSPCLKDIV × (1 + SCR) × CPSDVSR) / f_{main}. The clock cycle time derived from the SPI bit rate T_{cy(clk)} is a function of the main clock frequency f_{main}, the SSP peripheral clock divider (SSPCLKDIV), the SSP SCR parameter (specified in the SSP0CR0 register), and the SSP CPSDVSR parameter (specified in the SSP clock prescale register).

[2] $T_{amb} = -40 \ ^{\circ}C$ to +85 $^{\circ}C$.

 $[3] \quad T_{cy(clk)} = 12 \times T_{cy(PCLK)}.$

[4] $T_{amb} = 25 \ ^{\circ}C; V_{DD} = 3.3 \ V.$

11. Application information







11.2 XTAL input

The input voltage to the on-chip oscillators is limited to 1.8 V. If the oscillator is driven by a clock in slave mode, it is recommended that the input be coupled through a capacitor with $C_i = 100 \text{ pF}$. To limit the input voltage to the specified range, choose an additional capacitor to ground C_g which attenuates the input voltage by a factor $C_i/(C_i + C_g)$. In slave mode, a minimum of 200 mV(RMS) is needed.

components parameters) low mequency mode				
Fundamental oscillation frequency F _{OSC}	Crystal load capacitance C _L	Maximum crystal series resistance R _S	External load capacitors C _{X1} , C _{X2}	
1 MHz - 5 MHz	10 pF	< 300 Ω	18 pF, 18 pF	
	20 pF	< 300 Ω	39 pF, 39 pF	
	30 pF	< 300 Ω	57 pF, 57 pF	
5 MHz - 10 MHz	10 pF	< 300 Ω	18 pF, 18 pF	
	20 pF	< 200 Ω	39 pF, 39 pF	
	30 pF	< 100 Ω	57 pF, 57 pF	
10 MHz - 15 MHz	10 pF	< 160 Ω	18 pF, 18 pF	
	20 pF	< 60 Ω	39 pF, 39 pF	
15 MHz - 20 MHz	10 pF	< 80 Ω	18 pF, 18 pF	

Table 21.	Recommended values for C_{X1}/C_{X2} in oscillation mode (crystal and external
	components parameters) low frequency mode

Table 22. Recommended values for C_{χ_1}/C_{χ_2} in oscillation mode (crystal and external components parameters) high frequency mode

Fundamental oscillation frequency F _{OSC}	Crystal load capacitance C _L	Maximum crystal series resistance R _S	External load capacitors C _{X1} , C _{X2}
15 MHz - 20 MHz	10 pF	< 180 Ω	18 pF, 18 pF
	20 pF	< 100 Ω	39 pF, 39 pF
20 MHz - 25 MHz	10 pF	< 160 Ω	18 pF, 18 pF
	20 pF	< 80 Ω	39 pF, 39 pF

11.3 XTAL Printed-Circuit Board (PCB) layout guidelines

The crystal should be connected on the PCB as close as possible to the oscillator input and output pins of the chip. Take care that the load capacitors C_{x1} , C_{x2} , and C_{x3} in case of third overtone crystal usage have a common ground plane. The external components must also be connected to the ground plain. Loops must be made as small as possible in order to keep the noise coupled in via the PCB as small as possible. Also parasitics should stay as small as possible. Values of C_{x1} and C_{x2} should be chosen smaller accordingly to the increase in parasitics of the PCB layout.

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HVQFN33: plastic thermal enhanced very thin quad flat package; no leads; 33 terminals; body 7 x 7 x 0.85 mm

Fig 39. Package outline (HVQFN33)

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14. Abbreviations

Table 24.	Abbrev	viations
Acronym		Description
A/D		Analog-to-Digital
ADC		Analog-to-Digital Converter
AHB		Advanced High-performance Bus
AMBA		Advanced Microcontroller Bus Architecture
APB		Advanced Peripheral Bus
BOD		BrownOut Detection
EOP		End Of Packet
ETM		Embedded Trace Macrocell
FIFO		First-In, First-Out
GPIO		General Purpose Input/Output
HID		Human Interface Device
I/O		Input/Output
LSB		Least Significant Bit
MSC		Mass Storage Class
PHY		Physical Layer
PLL		Phase-Locked Loop
SE0		Single Ended Zero
SPI		Serial Peripheral Interface
SSI		Serial Synchronous Interface
SSP		Synchronous Serial Port
SoF		Start-of-Frame
ТСМ		Tightly-Coupled Memory
TTL		Transistor-Transistor Logic
UART		Universal Asynchronous Receiver/Transmitter
USB		Universal Serial Bus

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