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Applications of "**Embedded - Microcontrollers**"

Details	
Product Status	Obsolete
Core Processor	ARM7®
Core Size	16/32-Bit
Speed	55MHz
Connectivity	CANbus, Ethernet, I²C, SPI, SSC, UART/USART, USB
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	62
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	1.65V ~ 1.95V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-TFBGA
Supplier Device Package	100-TFBGA (9x9)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/at91sam7xc128-cu

1. Description

Atmel's AT91SAM7XC512/256/128 is a member of a series of highly integrated Flash microcontrollers based on the 32-bit ARM RISC processor. It features 512/256/128 Kbyte high-speed Flash and 128/64/32 Kbyte SRAM, a large set of peripherals, including an 802.3 Ethernet MAC, a CAN controller, an AES 128 Encryption accelerator and a Triple Data Encryption System. A complete set of system functions minimizes the number of external components.

The embedded Flash memory can be programmed in-system via the JTAG-ICE interface or via a parallel interface on a production programmer prior to mounting. Built-in lock bits and a security bit protect the firmware from accidental overwrite and preserve its confidentiality.

The AT91SAM7XC512/256/128 system controller includes a reset controller capable of managing the power-on sequence of the microcontroller and the complete system. Correct device operation can be monitored by a built-in brownout detector and a watchdog running off an integrated RC oscillator.

By combining the ARM7TDMI processor with on-chip Flash and SRAM, and a wide range of peripheral functions, including USART, SPI, CAN Controller, Ethernet MAC, AES 128 accelerator, TDES, Timer Counter, RTT and Analog-to-Digital Converters on a monolithic chip, the AT91SAM7XC512/256/128 is a powerful device that provides a flexible, cost-effective solution to many embedded control applications requiring secure communication over, for example, Ethernet, CAN wired and Zigbee™ wireless networks.

1.1 Configuration Summary of the AT91SAM7XC512/256/128

The AT91SAM7XC512, AT91SAM7XC256 and AT91SAM7XC128 differ only in memory sizes. Table 1-1 summarizes the configurations of the two devices.

Table 1-1. Configuration Summary

Device	Flash	Flash Organization	SRAM	AES	TDES
AT91SAM7XC512	512K bytes	dual plane	128K bytes	1 AES 256/192/128	1
AT91SAM7XC256	256K bytes	single plane	64K bytes	1 AES 128	1
AT91SAM7XC128	128K bytes	single plane	32K bytes	1 AES 128	1

2. AT91SAM7XC512/256/128 Block Diagram

Figure 2-1. AT91SAM7XC512/256/128 Block Diagram
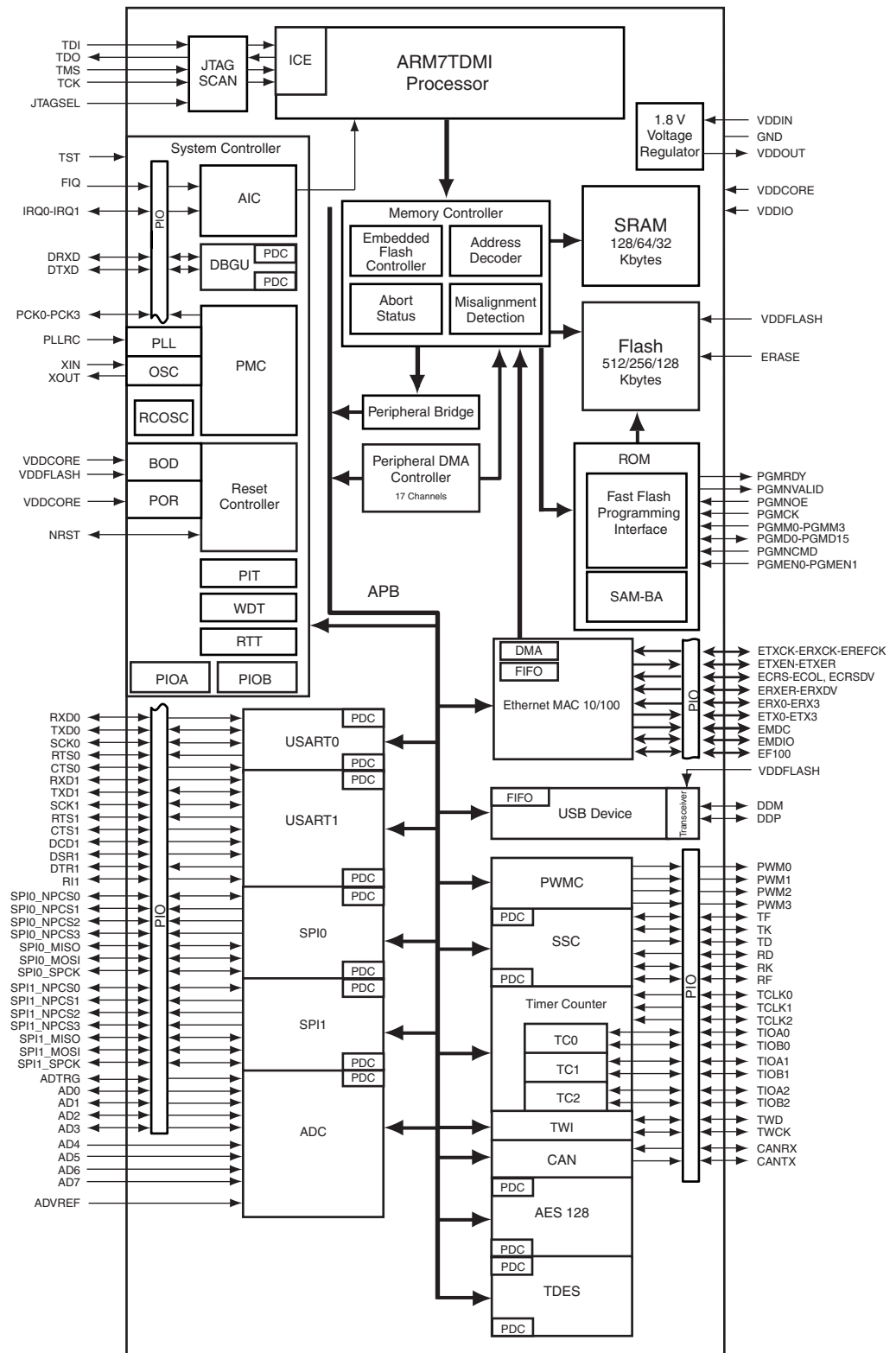
3. Signal Description

Table 3-1. Signal Description List

Signal Name	Function	Type	Active Level	Comments
Power				
VDDIN	Voltage Regulator and ADC Power Supply Input	Power		3V to 3.6V
VDDOUT	Voltage Regulator Output	Power		1.85V
VDDFLASH	Flash and USB Power Supply	Power		3V to 3.6V
VDDIO	I/O Lines Power Supply	Power		3V to 3.6V
VDDCORE	Core Power Supply	Power		1.65V to 1.95V
VDDPLL	PLL	Power		1.65V to 1.95V
GND	Ground	Ground		
Clocks, Oscillators and PLLs				
XIN	Main Oscillator Input	Input		
XOUT	Main Oscillator Output	Output		
PLLRC	PLL Filter	Input		
PCK0 - PCK3	Programmable Clock Output	Output		
ICE and JTAG				
TCK	Test Clock	Input		No pull-up resistor
TDI	Test Data In	Input		No pull-up resistor
TDO	Test Data Out	Output		
TMS	Test Mode Select	Input		No pull-up resistor
JTAGSEL	JTAG Selection	Input		Pull-down resistor[1]
Flash Memory				
ERASE	Flash and NVM Configuration Bits Erase Command	Input	High	Pull-down resistor[1]
Reset/Test				
NRST	Microcontroller Reset	I/O	Low	Pull-Up resistor, Open Drain Output.
TST	Test Mode Select	Input	High	Pull-down resistor[1]
Debug Unit				
DRXD	Debug Receive Data	Input		
DTXD	Debug Transmit Data	Output		
AIC				
IRQ0 - IRQ1	External Interrupt Inputs	Input		
FIQ	Fast Interrupt Input	Input		
PIO				
PA0 - PA30	Parallel IO Controller A	I/O		Pulled-up input at reset.
PB0 - PB30	Parallel IO Controller B	I/O		Pulled-up input at reset.

Table 3-1. Signal Description List (Continued)

Signal Name	Function	Type	Active Level	Comments
USB Device Port				
DDM	USB Device Port Data -	Analog		
DDP	USB Device Port Data +	Analog		
USART				
SCK0 - SCK1	Serial Clock	I/O		
TXD0 - TXD1	Transmit Data	I/O		
RXD0 - RXD1	Receive Data	Input		
RTS0 - RTS1	Request To Send	Output		
CTS0 - CTS1	Clear To Send	Input		
DCD1	Data Carrier Detect	Input		
DTR1	Data Terminal Ready	Output		
DSR1	Data Set Ready	Input		
RI1	Ring Indicator	Input		
Synchronous Serial Controller				
TD	Transmit Data	Output		
RD	Receive Data	Input		
TK	Transmit Clock	I/O		
RK	Receive Clock	I/O		
TF	Transmit Frame Sync	I/O		
RF	Receive Frame Sync	I/O		
Timer/Counter				
TCLK0 - TCLK2	External Clock Inputs	Input		
TIOA0 - TIOA2	I/O Line A	I/O		
TIOB0 - TIOB2	I/O Line B	I/O		
PWM Controller				
PWM0 - PWM3	PWM Channels	Output		
Serial Peripheral Interface - SPIx				
SPIx_MISO	Master In Slave Out	I/O		
SPIx_MOSI	Master Out Slave In	I/O		
SPIx_SPCK	SPI Serial Clock	I/O		
SPIx_NPCS0	SPI Peripheral Chip Select 0	I/O	Low	
SPIx_NPCS1-NPCS3	SPI Peripheral Chip Select 1 to 3	Output	Low	
Two-wire Interface				
TWD	Two-wire Serial Data	I/O		
TWCK	Two-wire Serial Clock	I/O		

5. Power Considerations

5.1 Power Supplies

The AT91SAM7XC512/256/128 has six types of power supply pins and integrates a voltage regulator, allowing the device to be supplied with only one voltage. The six power supply pin types are:

- VDDIN pin. It powers the voltage regulator and the ADC; voltage ranges from 3.0V to 3.6V, 3.3V nominal. In order to decrease current consumption, if the voltage regulator and the ADC are not used, VDDIN, ADVREF,AD4, AD5, AD6 and AD7 should be connected to GND. In this case, VDDOUT should be left unconnected.

- VDDOUT pin. It is the output of the 1.8V voltage regulator.

- VDDIO pin. It powers the I/O lines; voltage ranges from 3.0V to 3.6V, 3.3V nominal.

- VDDFLASH pin. It powers the USB transceivers and a part of the Flash and is required for the Flash to operate correctly; voltage ranges from 3.0V to 3.6V, 3.3V nominal.

- VDDCORE pins. They power the logic of the device; voltage ranges from 1.65V to 1.95V, 1.8V typical. It can be connected to the VDDOUT pin with decoupling capacitor. VDDCORE is required for the device, including its embedded Flash, to operate correctly.

- VDDPLL pin. It powers the oscillator and the PLL. It can be connected directly to the VDDOUT pin.

No separate ground pins are provided for the different power supplies. Only GND pins are provided and should be connected as shortly as possible to the system ground plane.

5.2 Power Consumption

The AT91SAM7XC512/256/128 has a static current of less than 60 μA on VDDCORE at 25°C, including the RC oscillator, the voltage regulator and the power-on reset when the brownout detector is deactivated. Activating the brownout detector adds 28 μA static current.

The dynamic power consumption on VDDCORE is less than 90 mA at full speed when running out of the Flash. Under the same conditions, the power consumption on VDDFLASH does not exceed 10 mA.

5.3 Voltage Regulator

The AT91SAM7XC512/256/128 embeds a voltage regulator that is managed by the System Controller.

In Normal Mode, the voltage regulator consumes less than 100 μA static current and draws 100 mA of output current.

The voltage regulator also has a Low-power Mode. In this mode, it consumes less than 25 μA static current and draws 1 mA of output current.

Adequate output supply decoupling is mandatory for VDDOUT to reduce ripple and avoid oscillations. The best way to achieve this is to use two capacitors in parallel: one external 470 pF (or 1 nF) NPO capacitor should be connected between VDDOUT and GND as close to the chip as possible. One external 2.2 μF (or 3.3 μF) X7R capacitor should be connected between VDDOUT and GND.

6. I/O Lines Considerations

6.1 JTAG Port Pins

TMS, TDI and TCK are schmitt trigger inputs and are not 5-V tolerant. TMS, TDI and TCK do not integrate a pull-up resistor.

TDO is an output, driven at up to VDDIO, and has no pull-up resistor.

The JTAGSEL pin is used to select the JTAG boundary scan when asserted at a high level. The JTAGSEL pin integrates a permanent pull-down resistor of about 15 kΩ

To eliminate any risk of spuriously entering the JTAG boundary scan mode due to noise on JTAGSEL, it should be tied externally to GND if boundary scan is not used, or pulled down with an external low-value resistor (such as 1 kΩ).

6.2 Test Pin

The TST pin is used for manufacturing test or fast programming mode of the AT91SAM7XC512/256/128 when asserted high. The TST pin integrates a permanent pull-down resistor of about 15 kΩ to GND.

To eliminate any risk of entering the test mode due to noise on the TST pin, it should be tied to GND if the FFPI is not used, or pulled down with an external low-value resistor (such as 1 kΩ).

To enter fast programming mode, the TST pin and the PA0 and PA1 pins should be tied high and PA2 tied to low.

Driving the TST pin at a high level while PA0 or PA1 is driven at 0 leads to unpredictable results.

6.3 Reset Pin

The NRST pin is bidirectional with an open drain output buffer. It is handled by the on-chip reset controller and can be driven low to provide a reset signal to the external components or asserted low externally to reset the microcontroller. There is no constraint on the length of the reset pulse, and the reset controller can guarantee a minimum pulse length. This allows connection of a simple push-button on the NRST pin as system user reset, and the use of the signal NRST to reset all the components of the system.

The NRST pin integrates a permanent pull-up resistor to VDDIO.

6.4 ERASE Pin

The ERASE pin is used to re-initialize the Flash content and some of its NVM bits. It integrates a permanent pull-down resistor of about 15 kΩ to GND.

To eliminate any risk of erasing the Flash due to noise on the ERASE pin, it shoul be tied externally to GND, which prevents erasing the Flash from the applicatiion, or pulled down with an external low-value resistor (such as 1 kΩ).

This pin is debounced by the RC oscillator to improve the glitch tolerance. Minimum debouncing time is 200 ms.

6.5 PIO Controller Lines

All the I/O lines, PA0 to PA30 and PB0 to PB30, are 5V-tolerant and all integrate a programmable pull-up resistor. Programming of this pull-up resistor is performed independently for each I/O line through the PIO controllers.

5V-tolerant means that the I/O lines can drive voltage level according to VDDIO, but can be driven with a voltage of up to 5.5V. However, driving an I/O line with a voltage over VDDIO while the programmable pull-up resistor is enabled will create a current path through the pull-up resistor from the I/O line to VDDIO. Care should be taken, in particular at reset, as all the I/O lines default to input with pull-up resistor enabled at reset.

6.6   I/O Lines Current Drawing

The PIO lines PA0 to PA3 are high-drive current capable. Each of these I/O lines can drive up to 16 mA permanently.

The remaining I/O lines can draw only 8 mA.

However, the total current drawn by all the I/O lines cannot exceed 200 mA.

- Embedded Flash Controller
  - Embedded Flash interface, up to three programmable wait states
  - Prefetch buffer, buffering and anticipating the 16-bit requests, reducing the required wait states
  - Key-protected program, erase and lock/unlock sequencer
  - Single command for erasing, programming and locking operations
  - Interrupt generation in case of forbidden operation

7.4 Peripheral DMA Controller

- Handles data transfer between peripherals and memories
- Seventeen channels
  - Two for each USART
  - Two for the Debug Unit
  - Two for the Serial Synchronous Controller
  - Two for each Serial Peripheral Interface
  - Two for the Advanced Encryption Standard 128-bit accelerator
  - Two for the Triple Data Encryption Standard 128-bit accelerator
  - One for the Analog-to-digital Converter
- Low bus arbitration overhead
  - One Master Clock cycle needed for a transfer from memory to peripheral
  - Two Master Clock cycles needed for a transfer from peripheral to memory
- Next Pointer management for reducing interrupt latency requirements

Flash Programming Interface, is forbidden. This ensures the confidentiality of the code programmed in the Flash.

This security bit can only be enabled, through the Command "Set Security Bit" of the EFC User Interface. Disabling the security bit can only be achieved by asserting the ERASE pin at 1, and after a full flash erase is performed. When the security bit is deactivated, all accesses to the flash are permitted.

It is important to note that the assertion of the ERASE pin should always be longer than 220 ms.

As the ERASE pin integrates a permanent pull-down, it can be left unconnected during normal operation. However, it is safer to connect it directly to GND for the final application.

8.5.5 Non-volatile Brownout Detector Control

Two general purpose NVM (GPNVM) bits are used for controlling the brownout detector (BOD), so that even after a power loss, the brownout detector operations remain in their state.

These two GPNVM bits can be cleared or set respectively through the commands "Clear General-purpose NVM Bit" and "Set General-purpose NVM Bit" of the EFC User Interface.

- GPNVM Bit 0 is used as a brownout detector enable bit. Setting the GPNVM Bit 0 enables the BOD, clearing it disables the BOD. Asserting ERASE clears the GPNVM Bit 0 and thus disables the brownout detector by default.

- The GPNVM Bit 1 is used as a brownout reset enable signal for the reset controller. Setting the GPNVM Bit 1 enables the brownout reset when a brownout is detected, Clearing the GPNVM Bit 1 disables the brownout reset. Asserting ERASE disables the brownout reset by default.

8.5.6 Calibration Bits

Eight NVM bits are used to calibrate the brownout detector and the voltage regulator. These bits are factory configured and cannot be changed by the user. The ERASE pin has no effect on the calibration bits.

8.6 Fast Flash Programming Interface

The Fast Flash Programming Interface allows programming the device through either a serial JTAG interface or through a multiplexed fully-handshaked parallel port. It allows gang-programming with market-standard industrial programmers.

The FFPI supports read, page program, page erase, full erase, lock, unlock and protect commands.

The Fast Flash Programming Interface is enabled and the Fast Programming Mode is entered when the TST pin and the PA0 and PA1 pins are all tied high.

8.7 SAM-BA Boot Assistant

The SAM-BA Boot Assistant is a default Boot Program that provides an easy way to program in-situ the on-chip Flash memory.

The SAM-BA Boot Assistant supports serial communication via the DBGU or the USB Device Port.

- Communication via the DBGU supports a wide range of crystals from 3 to 20 MHz via software auto-detection.

9.2 Clock Generator

The Clock Generator embeds one low-power RC Oscillator, one Main Oscillator and one PLL with the following characteristics:

- RC Oscillator ranges between 22 KHz and 42 KHz
- Main Oscillator frequency ranges between 3 and 20 MHz
- Main Oscillator can be bypassed
- PLL output ranges between 80 and 200 MHz

It provides SLCK, MAINCK and PLLCK.

Figure 9-2. Clock Generator Block Diagram
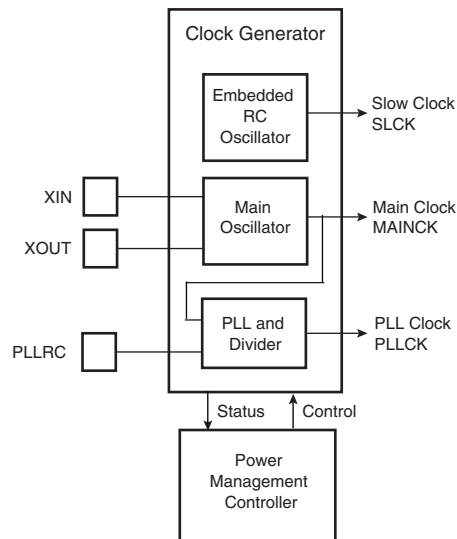
• Programmable 16-bit prescaler for SLCK accuracy compensation

9.9   PIO Controllers

• Two PIO Controllers, each controlling 31 I/O lines

• Fully programmable through set/clear registers

• Multiplexing of two peripheral functions per I/O line

• For each I/O line (whether assigned to a peripheral or used as general-purpose I/O)

– Input change interrupt

– Half a clock period glitch filter

– Multi-drive option enables driving in open drain

– Programmable pull-up on each I/O line

– Pin data status register, supplies visibility of the level on the pin at any time

• Synchronous output, provides Set and Clear of several I/O lines in a single write

9.10   Voltage Regulator Controller

The purpose of this controller is to select the Power Mode of the Voltage Regulator between Normal Mode (bit 0 is cleared) or Standby Mode (bit 0 is set).

10.3 Peripheral Multiplexing on PIO Lines

The AT91SAM7XC512/256/128 features two PIO controllers, PIOA and PIOB, that multiplex the I/O lines of the peripheral set.

Each PIO Controller controls 31 lines. Each line can be assigned to one of two peripheral functions, A or B. Some of them can also be multiplexed with the analog inputs of the ADC Controller.

Table 10-2 on page 34 and Table 10-3 on page 35 defines how the I/O lines of the peripherals A, B or the analog inputs are multiplexed on the PIO Controller A and PIO Controller B. The two columns "Function" and "Comments" have been inserted for the user's own comments; they may be used to track how pins are defined in an application.

Note that some peripheral functions that are output only, may be duplicated in the table.

At reset, all I/O lines are automatically configured as input with the programmable pull-up enabled, so that the device is maintained in a static state as soon as a reset is detected.

10.4 PIO Controller A Multiplexing

Table 10-2. Multiplexing on PIO Controller A

	PIO Controller A			Application Usage	
I/O Line	Peripheral A	Peripheral B	Comments	Function	Comments
PA0	RXD0		High-Drive		
PA1	TXD0		High-Drive		
PA2	SCK0	SPI1_NPCS1	High-Drive		
PA3	RTS0	SPI1_NPCS2	High-Drive		
PA4	CTS0	SPI1_NPCS3			
PA5	RXD1				
PA6	TXD1				
PA7	SCK1	SPI0_NPCS1			
PA8	RTS1	SPI0_NPCS2			
PA9	CTS1	SPI0_NPCS3			
PA10	TWD				
PA11	TWCK				
PA12	SPI_NPCS0				
PA13	SPI0_NPCS1	PCK1			
PA14	SPI0_NPCS2	IRQ1			
PA15	SPI0_NPCS3	TCLK2			
PA16	SPI0_MISO				
PA17	SPI0_MOSI				
PA18	SPI0_SPCK				
PA19	CANRX				
PA20	CANTX				
PA21	TF	SPI1_NPCS0			
PA22	TK	SPI1_SPCK			
PA23	TD	SPI1_MOSI			
PA24	RD	SPI1_MISO			
PA25	RK	SPI1_NPCS1			
PA26	RF	SPI1_NPCS2			
PA27	DRXD	PCK3			
PA28	DTXD				
PA29	FIQ	SPI1_NPCS3			
PA30	IRQ0	PCK2			

10.8 Two-wire Interface

- Master Mode only
- Compatibility with I^{2}C compatible devices (refer to the TWI section of the datasheet)
- One, two or three bytes internal address registers for easy Serial Memory access
- 7-bit or 10-bit slave addressing
- Sequential read/write operations

10.9 USART

- Programmable Baud Rate Generator
- 5- to 9-bit full-duplex synchronous or asynchronous serial communications
    - 1, 1.5 or 2 stop bits in Asynchronous Mode
    - 1 or 2 stop bits in Synchronous Mode
    - Parity generation and error detection
    - Framing error detection, overrun error detection
    - MSB or LSB first
    - Optional break generation and detection
    - By 8 or by 16 over-sampling receiver frequency
    - Hardware handshaking RTS - CTS
    - Modem Signals Management DTR-DSR-DCD-RI on USART1
    - Receiver time-out and transmitter timeguard
    - Multi-drop Mode with address generation and detection
- RS485 with driver control signal
- ISO7816, T = 0 or T = 1 Protocols for interfacing with smart cards
    - NACK handling, error counter with repetition and iteration limit
- IrDA modulation and demodulation
    - Communication at up to 115.2 Kbps
- Test Modes
    - Remote Loopback, Local Loopback, Automatic Echo

10.10 Serial Synchronous Controller

- Provides serial synchronous communication links used in audio and telecom applications
- Contains an independent receiver and transmitter and a common clock divider
- Offers a configurable frame sync and data length
- Receiver and transmitter can be programmed to start automatically or on detection of different event on the frame sync signal
- Receiver and transmitter include a data signal, a clock signal and a frame synchronization signal

10.11 Timer Counter

- Three 16-bit Timer Counter Channels
    - Two output compare or one input capture per channel
- Wide range of functions including:
    - Frequency measurement
    - Event counting
    - Interval measurement
    - Pulse generation
    - Delay timing
    - Pulse Width Modulation
    - Up/down capabilities
- Each channel is user-configurable and contains:
    - Three external clock inputs
- Five internal clock inputs, as defined in Table 10-4

Table 10-4. Timer Counter Clocks Assignment

TC Clock input	Clock
TIMER_CLOCK1	MCK/2
TIMER_CLOCK2	MCK/8
TIMER_CLOCK3	MCK/32
TIMER_CLOCK4	MCK/128
TIMER_CLOCK5	MCK/1024

- Two multi-purpose input/output signals
- Two global registers that act on all three TC channels

10.12 Pulse Width Modulation Controller

- Four channels, one 16-bit counter per channel
- Common clock generator, providing thirteen different clocks
    - One Modulo n counter providing eleven clocks
    - Two independent linear dividers working on modulo n counter outputs
- Independent channel programming
    - Independent enable/disable commands
    - Independent clock selection
    - Independent period and duty cycle, with double buffering
    - Programmable selection of the output waveform polarity
    - Programmable center or left aligned output waveform

– Counter (CTR)

- 8-, 16-, 32-, 64- and 128-bit Data Sizes Possible in CFB Mode

- Last Output Data Mode allowing Message Authentication Code (MAC) generation

- Hardware Countermeasures against Differential Power Analysis attacks

- Connection to PDC Channel Capabilities Optimizes Data Transfers for all Operating Modes:
    – One Channel for the Receiver, One Channel for the Transmitter
    – Next Buffer Support

10.16 Triple Data Encryption Standard

- Single Data Encryption Standard (DES) and Triple Data Encryption

- Algorithm (TDEA or TDES) supports

- Compliant with FIPS Publication 46-3, Data Encryption Standard (DES)

- 64-bit Cryptographic Key

- Two-key or Three-key Algorithms

- 18-clock Cycles Encryption/Decryption Processing Time for DES

- 50-clock Cycles Encryption/Decryption Processing Time for TDES

- Support the Four Standard Modes of Operation specified in the FIPS Publication 81, DES

- Modes of Operation:
    – Electronic Codebook (ECB)
    – Cipher Block Chaining (CBC)
    – Cipher Feedback (CFB)
    – Output Feedback (OFB)

- 8-, 16-, 32- and 64- Data Sizes Possible in CFB Mode

- Last Output Data Mode allowing Optimized Message (Data) Authentication Code (MAC) generation

- Connection to PDC Channel Capabilities Optimizes Data Transfers for all Operating Modes:
    – One Channel for the Receiver, One Channel for the Transmitter
    – Next Buffer Support

10.17 Analog-to-Digital Converter

- 8-channel ADC

- 10-bit 384 Ksamples/sec. Successive Approximation Register ADC

- ±2 LSB Integral Non Linearity, ±1 LSB Differential Non Linearity

- Integrated 8-to-1 multiplexer, offering eight independent 3.3V analog inputs

- External voltage reference for better accuracy on low voltage inputs

- Individual enable and disable of each channel

- Multiple trigger sources
    – Hardware or software trigger
    – External trigger pin
    – Timer Counter 0 to 2 outputs TIOA0 to TIOA2 trigger

- Sleep Mode and conversion sequencer

– Automatic wakeup on trigger and back to sleep mode after conversions of all enabled channels

• Four of eight analog inputs shared with digital signals

Table 11-1. 100-lead LQFP Package Dimensions

	Millimeter			Inch		
Symbol	**Min**	**Nom**	**Max**	**Min**	**Nom**	**Max**
A			1.60			0.63
A1	0.05		0.15	0.002		0.006
A2	1.35	1.40	1.45	0.053	0.055	0.057
D	16.00 BSC			0.630 BSC		
D1	14.00 BSC			0.551 BSC		
E	16.00 BSC			0.630 BSC		
E1	14.00 BSC			0.551 BSC		
R2	0.08		0.20	0.003		0.008
R1	0.08			0.003		
Q	0·	3.5·	7·	0·	3.5·	7·
θ1	0·			0·		
θ2	11·	12·	13·	11·	12·	13·
θ3	11·	12·	13·	11·	12·	13·
c	0.09		0.20	0.004		0.008
L	0.45	0.60	0.75	0.018	0.024	0.030
L1	1.00 REF			0.039 REF		
S	0.20			0.008		
b	0.17	0.20	0.27	0.007	0.008	0.011
e	0.50 BSC			0.020 BSC		
D2	12.00			0.472		
E2	12.00			0.472		
Tolerances of Form and Position						
aaa	0.20			0.008		
bbb	0.20			0.008		
ccc	0.08			0.003		
ddd	0.08			0.003		

Revision History

Table 13-1. Revision History

Doc. Rev	Comments	Change Request Ref.
6209S	First issue - Unqualified on Intranet Legal page updated.Qualified on Intranet	
6209BS	Added AT91SAM7XC512 to product family."Features" on page 1 and global Reformatted Memories Section 8. "Memory" on page 18. Reordered sub sections in Peripherals Section 10. "Peripherals" on page 32 Consolidated Memory Mapping in Figure 8-1 on page 19. Added package drawings Section 11. "Package Drawings" on page 42. Consolidated Memory Mapping in Figure 8-1 on page 19. Added TFBGA information Section 4.3 "100-ball TFBGA Package Outline" on page 11. and Section 4.4 on page 10 and "Features" on page 1 Added LQFP and TFBGA package drawings Section 11. on page 42. System Controller block diagram Figure 9-1 on page 26, "ice_nreset" signals changed to "power_on_reset".	2729
6209CS	"Features", TWI updated to include Atmel TWI compatibility with I^{2}C Standard. "Features", "Debug Unit (DBGU)" added "Mode for General Purpose 2-wire UART Serial Communication". Section 10.8 "Two-wire Interface", updated. Section 10.11 "Timer Counter",The TC has Two output compare or one input capture per channel. Section 10.17 "Analog-to-Digital Converter",INL and DNL updated. Figure 3-1,"Signal Description List", footnote added to JTAGSEL, ERASE and TST pin comments Section 6.1 "JTAG Port Pins", Section 6.2 "Test Pin" and Section 6.4 "ERASE Pin"updated. Figure 9-1,"System Controller Block Diagram", RTT is reset by power_on_reset. Figure 8-1,"AT91SAM7XC512/256/128 Memory Mapping",TDES base address is 0xFFFA 8000 Section 8.4.3 "Internal Flash",updated: "At any time, the Flash is mapped ... if GPNVM bit 2 is set and before the Remap Command."	4247 5846 4211 4008 5068 5225 5257 5850
6209DS	Section 12. "AT91SAM7XC512/256/128 Ordering Information", MLR B chip revision added to ordering information.	6064

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