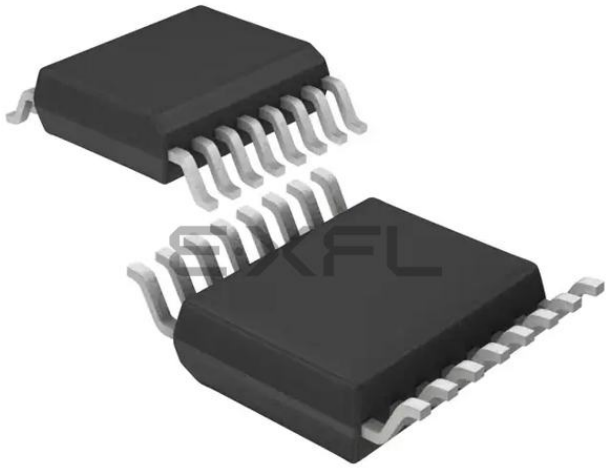

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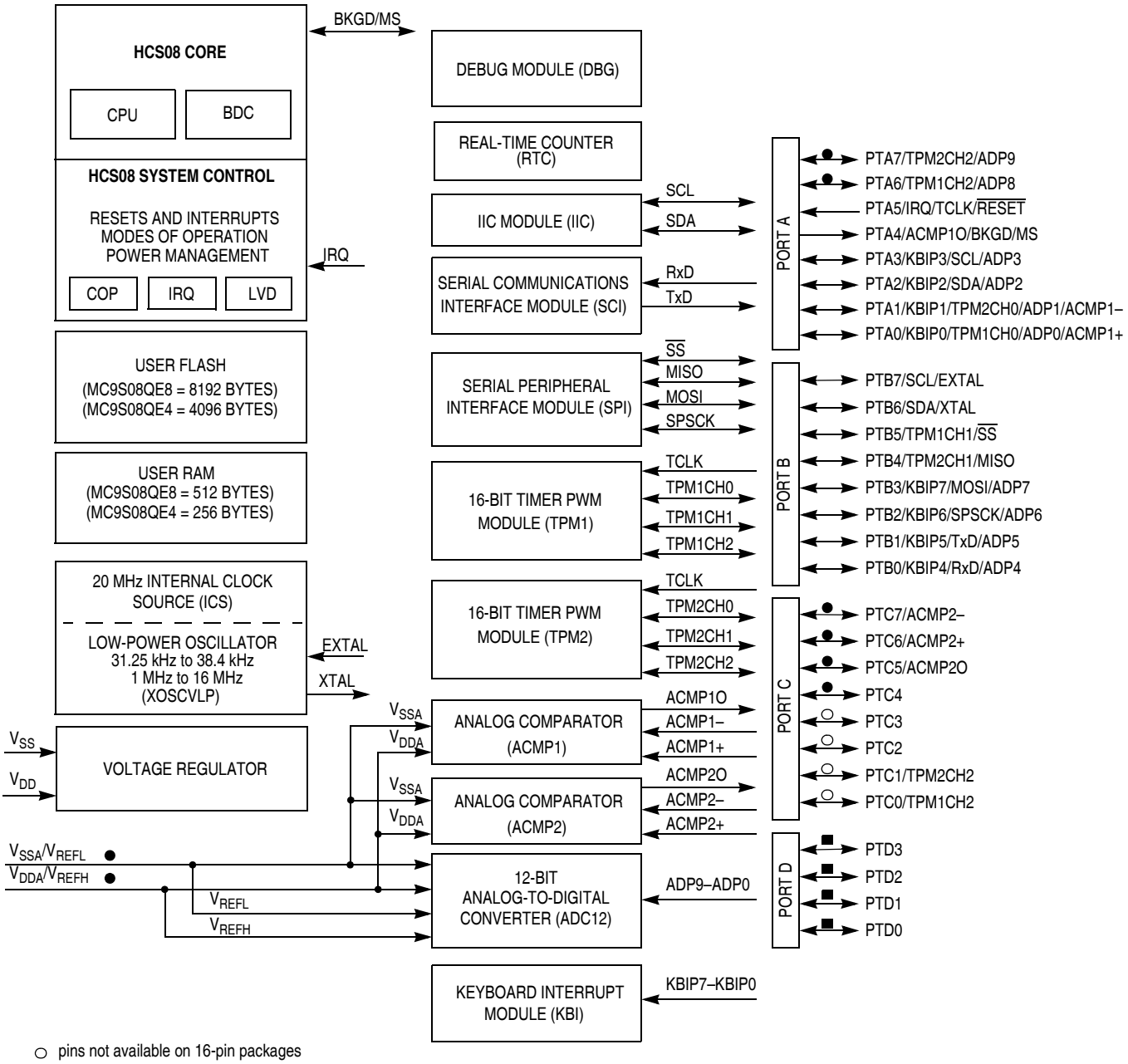
Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	S08
Core Size	8-Bit
Speed	20MHz
Connectivity	I²C, LINbus, SCI, SPI
Peripherals	LVD, PWM, WDT
Number of I/O	12
Program Memory Size	4KB (4K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 8x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	16-TSSOP (0.173", 4.40mm Width)
Supplier Device Package	16-TSSOP
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/mc9s08qe4ctg

1 MCU Block Diagram

The block diagram, Figure 1, shows the structure of MC9S08QE8 series MCU.



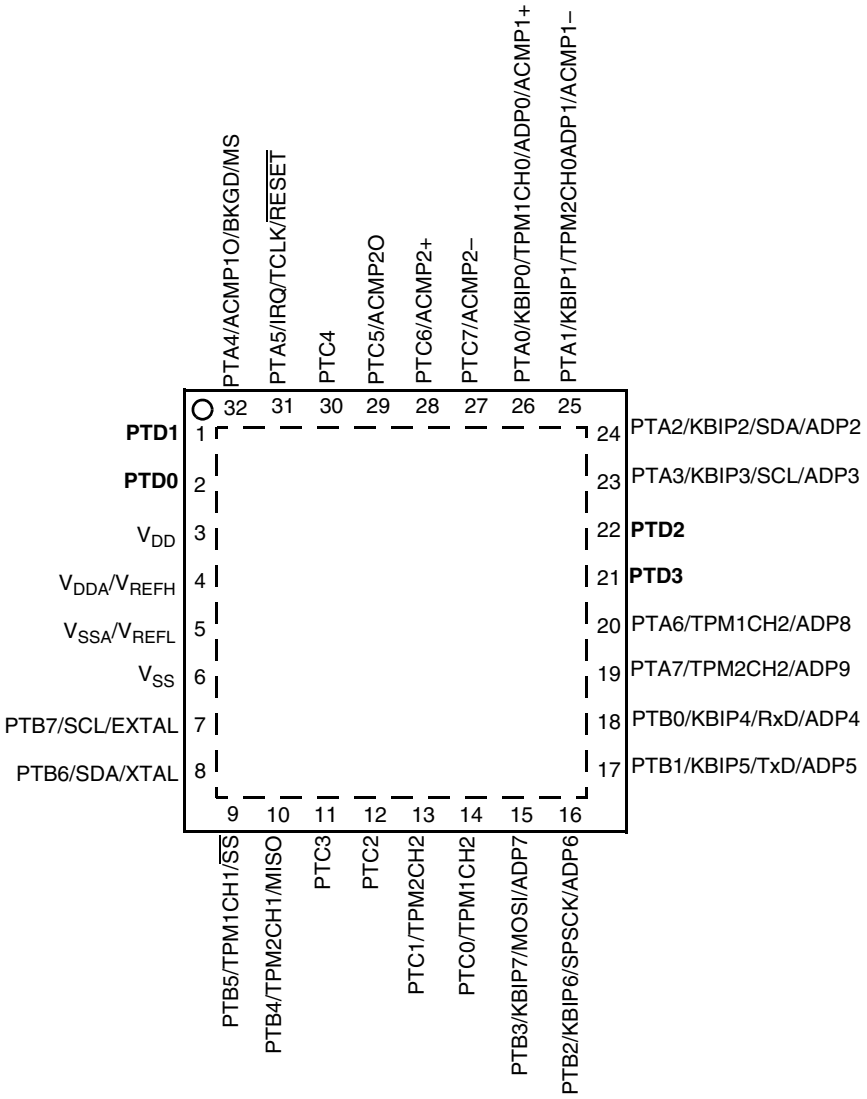
○ pins not available on 16-pin packages
● pins not available on 16-pin or 20-pin packages
■ pins not available on 16-pin, 20-pin or 28-pin packages

Notes: When PTA5 is configured as $\overline{\text{RESET}}$, pin becomes bi-directional with output being open-drain drive containing an internal pullup device.
When PTA4 is configured as BKGD, pin becomes bi-directional.
For the 16-pin and 20-pin packages, V_{SSA}/V_{REFL} and V_{DDA}/V_{REFH} are double bonded to V_{SS} and V_{DD} respectively.

Figure 1. MC9S08QE8 Series Block Diagram

2 Pin Assignments

This section shows the pin assignments for the MC9S08QE8 series devices.



Pins shown in bold type are lost in the next lower pin count package.

Figure 2. MC9S08QE8 Series in 32-Pin LQFP/QFN Package

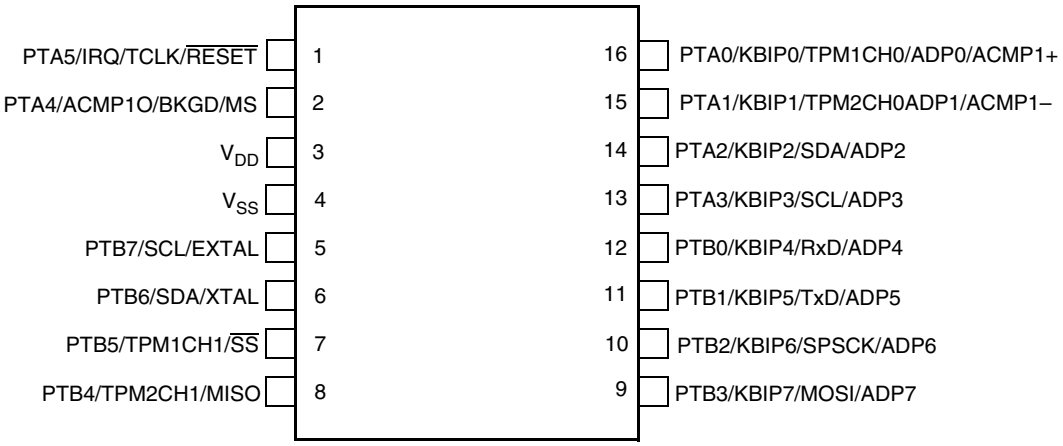


Figure 5. MC9S08QE8 Series in 16-pin PDIP and TSSOP Packages

Table 1. Pin Availability by Package Pin-Count

Pin Number				<-- Lowest **Priority** --> Highest				
32	**28**	**20**	**16**	**Port Pin**	**Alt 1**	**Alt 2**	**Alt 3**	**Alt 4**
1	—	—	—	PTD1				
2	—	—	—	PTD0				
3	5	3	3					V_{DD}
4	6	—	—					V_{DDA}/V_{REFH}
5	7	—	—					V_{SSA}/V_{REFL}
6	8	4	4					V_{SS}
7	9	5	5	PTB7	SCL[1]			EXTAL
8	10	6	6	PTB6	SDA[1]			XTAL
9	11	7	7	PTB5	TPM1CH1	$\overline{SS}$		
10	12	8	8	PTB4	TPM2CH1	MISO		
11	13	9	—	PTC3				
12	14	10	—	PTC2				
13	15	11	—	PTC1	TPM2CH2[2]			
14	16	12	—	PTC0	TPM1CH2[3]			
15	17	13	9	PTB3	KBIP7	MOSI	ADP7	
16	18	14	10	PTB2	KBIP6	SPSCK	ADP6	
17	19	15	11	PTB1	KBIP5	TxD	ADP5	
18	20	16	12	PTB0	KBIP4	RxD	ADP4	
19	21	—	—	PTA7	TPM2CH2[2]		ADP9	
20	22	—	—	PTA6	TPM1CH2[3]		ADP8	
21	—	—	—	PTD3				
22	—	—	—	PTD2				
23	23	17	13	PTA3	KBIP3	SCL[1]	ADP3	
24	24	18	14	PTA2	KBIP2	SDA[1]	ADP2	
25	25	19	15	PTA1	KBIP1	TPM2CH0	ADP1[4]	ACMP1–[4]

Table 1. Pin Availability by Package Pin-Count (continued)

Pin Number				<-- Lowest **Priority** --> Highest				
32	**28**	**20**	**16**	**Port Pin**	**Alt 1**	**Alt 2**	**Alt 3**	**Alt 4**
26	26	20	16	PTA0	KBIP0	TPM1CH0	ADP0[4]	ACMP1+[4]
27	27	—	—	PTC7				ACMP2–
28	28	—	—	PTC6				ACMP2+
29	1	—	—	PTC5				ACMP2O
30	2	—	—	PTC4				
31	3	1	1	PTA5	IRQ	TCLK	$\overline{\text{RESET}}$	
32	4	2	2	PTA4	ACMP1O	BKGD	MS	

1 IIC pins, SCL and SDA can be repositioned using IICPS in SOPT2, default reset locations are PTA3 and PTA2.

2 TPM2CH2 pin can be repositioned using TPM2CH2PS in SOPT2, default reset location is PTA7.

3 TPM1CH2 pin can be repositioned using TPM1CH2PS in SOPT2, default reset location is PTA6.

4 If ADC and ACMP1 are enabled, both modules will have access to the pin.

3 Electrical Characteristics

3.1 Introduction

This section contains electrical and timing specifications for the MC9S08QE8 series of microcontrollers available at the time of publication.

3.2 Parameter Classification

The electrical parameters shown in this supplement are guaranteed by various methods. To give the customer a better understanding the following classification is used and the parameters are tagged accordingly in the tables where appropriate:

Table 2. Parameter Classifications

P	Those parameters are guaranteed during production testing on each individual device.
C	Those parameters are achieved by the design characterization by measuring a statistically relevant sample size across process variations.
T	Those parameters are achieved by design characterization on a small sample size from typical devices under typical conditions unless otherwise noted. All values shown in the typical column are within this category.
D	Those parameters are derived mainly from simulations.

NOTE

The classification is shown in the column labeled “C” in the parameter tables where appropriate.

3.3 Absolute Maximum Ratings

Absolute maximum ratings are stress ratings only, and functional operation at the maxima is not guaranteed. Stress beyond the limits specified in Table 3 may affect device reliability or cause permanent damage to the device. For functional operating conditions, refer to the remaining tables in this section.

This device contains circuitry protecting against damage due to high static voltage or electrical fields; however, it is advised that normal precautions be taken to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage level (for instance, either V_{SS} or V_{DD}) or the programmable pullup resistor associated with the pin is enabled.

Table 3. Absolute Maximum Ratings

Rating	Symbol	Value	Unit
Supply voltage	V_{DD}	–0.3 to 3.8	V
Maximum current into V_{DD}	I_{DD}	120	mA
Digital input voltage	V_{In}	–0.3 to V_{DD} + 0.3	V
Instantaneous maximum current Single pin limit (applies to all port pins)[1, 2, 3]	I_D	±25	mA
Storage temperature range	T_{stg}	–55 to 150	°C

1 Input must be current limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive (V_{DD}) and negative (V_{SS}) clamp voltages, then use the larger of the two resistance values.

2 All functional non-supply pins, except for PTA5 are internally clamped to V_{SS} and V_{DD}.

3 Power supply must maintain regulation within operating V_{DD} range during instantaneous and operating maximum current conditions. If positive injection current ($V_{In} > V_{DD}$) is greater than I_{DD}, the injection current may flow out of V_{DD} and could result in external power supply going out of regulation. Ensure external V_{DD} load will shunt current greater than maximum injection current. This will be the greatest risk when the MCU is not consuming power. Examples are: if no system clock is present, or if the clock rate is very low (which would reduce overall power consumption).

3.4 Thermal Characteristics

This section provides information about operating temperature range, power dissipation, and package thermal resistance. Power dissipation on I/O pins is usually small compared to the power dissipation in on-chip logic and voltage regulator circuits, and it is user-determined rather than being controlled by the MCU design. To take $P_{I/O}$ into account in power calculations, determine the difference between actual pin voltage and V_{SS} or V_{DD} and multiply by the pin current for each I/O pin. Except in cases of unusually high pin current (heavy loads), the difference between pin voltage and V_{SS} or V_{DD} will be very small.

3.6 DC Characteristics

This section includes information about power supply requirements and I/O pin characteristics.

Table 7. DC Characteristics

Num	C	Characteristic		Symbol	Condition	Min.	Typical[1]	Max.	Unit
1		Operating voltage V_{DD} rising V_{DD} falling				2.0[2] 1.8		3.6	V
2	C	Output high voltage	All I/O pins, low-drive strength	V_{OH}	V_{DD} > 1.8 V, I_{Load} = –2 mA	V_{DD} – 0.5	—	—	V
	P		All I/O pins, high-drive strength		V_{DD} > 2.7 V, I_{Load} = –10 mA	V_{DD} – 0.5	—	—	
	C				V_{DD} > 1.8V, I_{Load} = –2 mA	V_{DD} – 0.5	—	—	
3	D	Output high current	Max total I_{OH} for all ports	I_{OHT}	—	—	—	100	mA
4	C	Output low voltage	All I/O pins, low-drive strength	V_{OL}	V_{DD} > 1.8 V, I_{Load} = 0.6 mA	—	—	0.5	V
	P		All I/O pins, high-drive strength		V_{DD} > 2.7 V, I_{Load} = 10 mA	—	—	0.5	
	C				V_{DD} > 1.8 V, I_{Load} = 3 mA	—	—	0.5	
5	D	Output low current	Max total I_{OL} for all ports	I_{OLT}	—	—	—	100	mA
6	P	Input high voltage	All digital inputs	V_{IH}	V_{DD} > 2.7 V	0.70 × V_{DD}	—	—	V
	C				V_{DD} > 1.8 V	0.85 × V_{DD}	—	—	
7	P	Input low voltage	All digital inputs	V_{IL}	V_{DD} > 2.7 V	—	—	0.35 × V_{DD}	
	C				V_{DD} > 1.8 V	—	—	0.30 × V_{DD}	
8	C	Input hysteresis	All digital inputs	V_{hys}	—	0.06 x V_{DD}	—	—	mV
9	P	Input leakage current	All input only pins (per pin)	$\lvert I_{In} \rvert$	V_{In} = V_{DD} or V_{SS}	—	—	1	µA
10	P	Hi-Z (off-state) leakage current	All input/output (per pin)	$\lvert I_{OZ} \rvert$	V_{In} = V_{DD} or V_{SS}	—	—	1	µA
11	P	Total leakage combined for all inputs and Hi-Z pins	All input only and I/O	$\lvert I_{OZTOT} \rvert$	V_{In} = V_{DD} or V_{SS}	—	—	2	µA
12a	P	Pullup, pulldown resistors	All digital inputs, when enabled (all I/O pins other than PTA5/IRQ/TCLK/$\overline{\text{RESET}}$)	R_{PU}, R_{PD}	—	17.5	—	52.5	kΩ

Table 7. DC Characteristics (continued)

Num	C	Characteristic		Symbol	Condition	Min.	Typical[1]	Max.	Unit
12b	C	Pullup, pulldown resistors	(PTA5/IRQ/TCLK/$\overline{\text{RESET}}$)	R_{PU}, R_{PD} (Note[3])	—	17.5	—	52.5	kΩ
13	C	DC injection current [4, 5, 6]	Single pin limit	I_{IC}	$V_{IN} < V_{SS}$, $V_{IN} > V_{DD}$	–0.2	—	0.2	mA
			Total MCU limit, includes sum of all stressed pins			–5	—	5	mA
14	C	Input capacitance, all pins		C_{In}	—	—	—	8	pF
15	C	RAM retention voltage		V_{RAM}	—	—	0.6	1.0	V
16	C	POR re-arm voltage[7]		V_{POR}	—	0.9	1.4	2.0	V
17	D	POR re-arm time		t_{POR}	—	10	—	—	µs
18	P	Low-voltage detection threshold		V_{LVD}	V_{DD} falling V_{DD} rising	1.80 1.88	1.84 1.92	1.88 1.96	V
19	P	Low-voltage warning threshold		V_{LVW}	V_{DD} falling V_{DD} rising	2.08	2.14	2.24	V
20	P	Low-voltage inhibit reset/recover hysteresis		V_{hys}	—	—	80	—	mV
21	P	Bandgap voltage reference[8]		V_{BG}	—	1.15	1.17	1.18	V

1 Typical values are measured at 25 °C. Characterized, not tested

2 As the supply voltage rises, the LVD circuit will hold the MCU in reset until the supply has risen above V_{LVDL}.

3 The specified resistor value is the actual value internal to the device. The pullup or pulldown value may appear higher when measured externally on the pin.

4 All functional non-supply pins, except for PTA5 are internally clamped to V_{SS} and V_{DD}.

5 Input must be current limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive and negative clamp voltages, then use the larger of the two values.

6 Power supply must maintain regulation within operating V_{DD} range during instantaneous and operating maximum current conditions. If the positive injection current ($V_{In} > V_{DD}$) is greater than I_{DD}, the injection current may flow out of V_{DD} and could result in external power supply going out of regulation. Ensure that external V_{DD} load will shunt current greater than maximum injection current. This will be the greatest risk when the MCU is not consuming power. Examples are: if no system clock is present, or if clock rate is very low (which would reduce overall power consumption).

7 Maximum is highest voltage that POR is guaranteed.

8 Factory trimmed at V_{DD} = 3.0 V, Temp = 25 °C

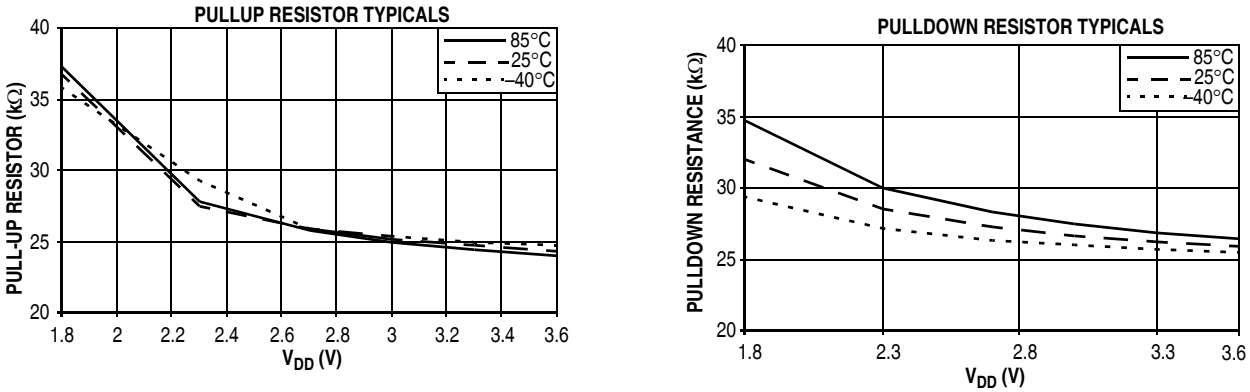


Figure 6. Pullup and Pulldown Typical Resistor Values (V_{DD} = 3.0 V)

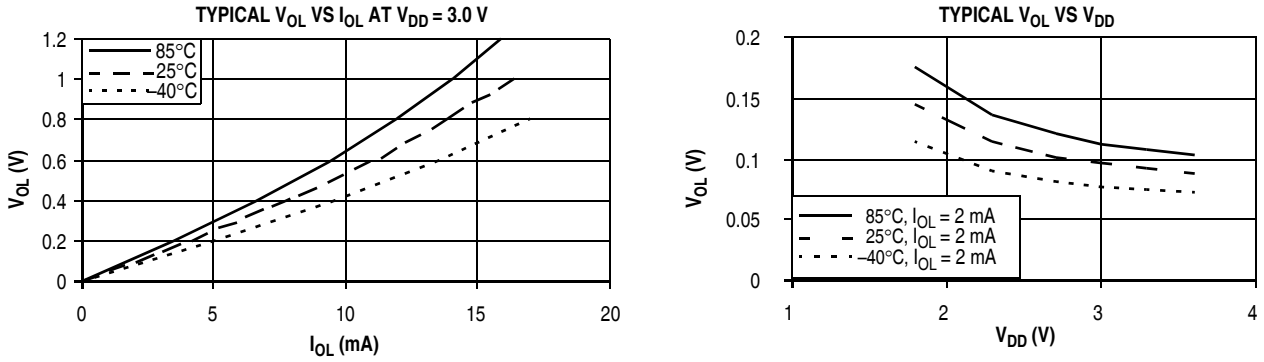


Figure 7. Typical Low-Side Driver (Sink) Characteristics — Low Drive (PTxDSn = 0)

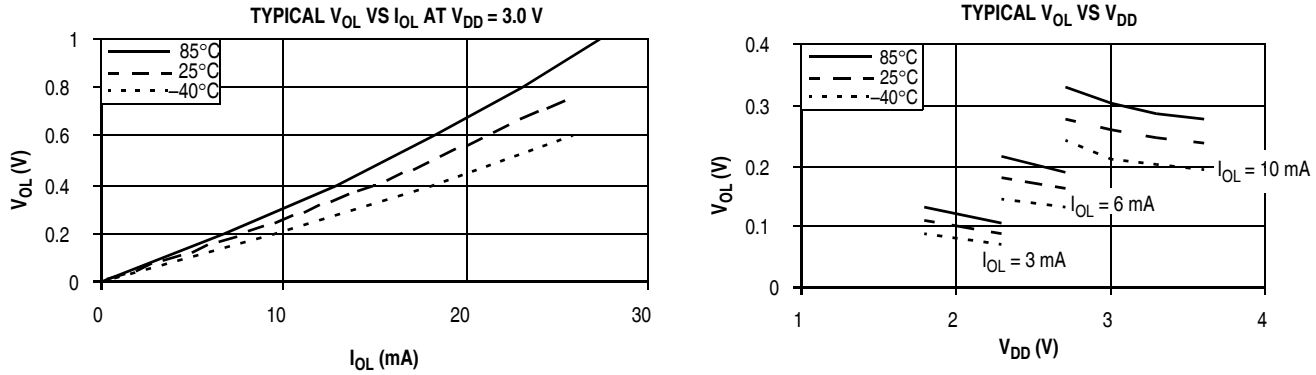


Figure 8. Typical Low-Side Driver (Sink) Characteristics — High Drive (PTxDSn = 1)

3.8 External Oscillator (XOSCVLP) Characteristics

Refer to Figure 12 and Figure 13 for crystal or resonator circuits.

Table 10. XOSCVLP Specifications (Temperature Range = –40 to 85°C Ambient)

Num	C	Characteristic	Symbol	Min.	Typical[1]	Max.	Unit
1	C	Oscillator crystal or resonator (EREFS = 1, ERCLKEN = 1) Low range (RANGE = 0) High range (RANGE = 1), high gain (HGO = 1), FBELP mode High range (RANGE = 1), low power (HGO = 0), FBELP mode	 f_{lo} f_{hi} f_{hi}	 32 1 1	 — — —	 38.4 16 8	 kHz MHz MHz
2	D	Load capacitors Low range (RANGE=0), low power (HGO = 0) Other oscillator settings	C_1,C_2	See Note [2] See Note [3]			
3	D	Feedback resistor Low range, low power (RANGE = 0, HGO = 0)[2] Low range, high gain (RANGE = 0, HGO = 1) High range (RANGE = 1, HGO = X)	R_F	 — — —	 — 10 1	 — — —	MΩ
4	D	Series resistor — Low range, low power (RANGE = 0, HGO = 0)[2] Low range, high gain (RANGE = 0, HGO = 1) High range, low power (RANGE = 1, HGO = 0) High range, high gain (RANGE = 1, HGO = 1) ≥ 8 MHz 4 MHz 1 MHz	R_S	 — — — — — —	 — 100 0 0 0 0	 — — — 0 10 20	kΩ
5	C	Crystal start-up time[4] Low range, low power Low range, high gain High range, low power High range, high gain	 t_{CSTL} t_{CSTH} 	 — — — —	 600 400 5 15	 — — — —	ms
6	D	Square wave input clock frequency (EREFS = 0, ERCLKEN = 1) FEE mode FBE or FBELP mode	f_{extal}	0.03125 0	— —	20 20	MHz MHz

1 Data in Typical column was characterized at 3.0 V, 25 °C or is typical recommended value.

2 Load capacitors (C_1,C_2), feedback resistor (R_F) and series resistor (R_S) are incorporated internally when RANGE = HGO = 0.

3 See crystal or resonator manufacturer's recommendation.

4 Proper PC board layout procedures must be followed to achieve specifications.

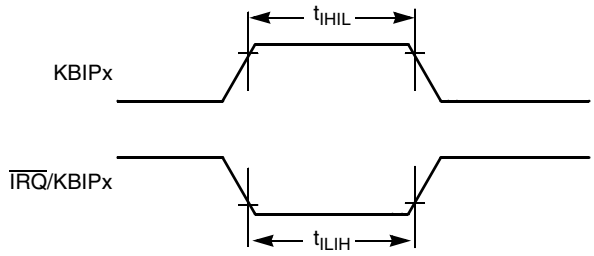


Figure 16. IRQ/KBIPx Timing

3.10.2 TPM Module Timing

Synchronizer circuits determine the shortest input pulses that can be recognized or the fastest clock that can be used as the optional external source to the timer counter. These synchronizers operate from the current bus rate clock.

Table 13. TPM Input Timing

No.	C	Function	Symbol	Min	Max	Unit
1	D	External clock frequency	f_{TCLK}	0	$f_{Bus}/4$	Hz
2	D	External clock period	t_{TCLK}	4	—	t_{cyc}
3	D	External clock high time	t_{clkh}	1.5	—	t_{cyc}
4	D	External clock low time	t_{clkl}	1.5	—	t_{cyc}
5	D	Input capture pulse width	t_{ICPW}	1.5	—	t_{cyc}

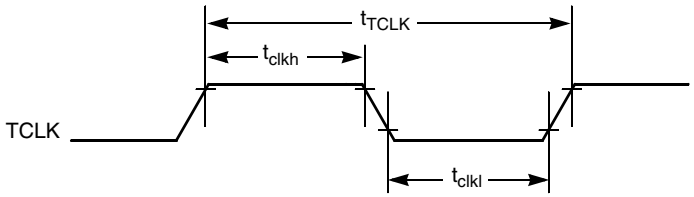


Figure 17. Timer External Clock

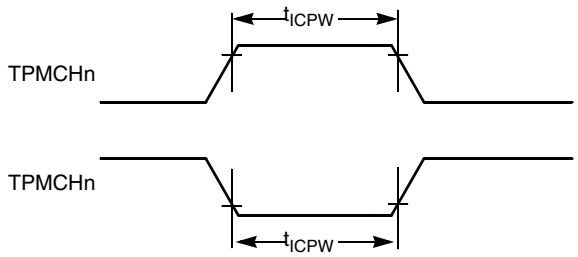


Figure 18. Timer Input Capture Pulse

3.10.3 SPI Timing

Table 14 and Figure 19 through Figure 22 describe the timing requirements for the SPI system.

Table 14. SPI Timing

No.	C	Function	Symbol	Min	Max	Unit
—	D	Operating frequency Master Slave	f_{op}	$f_{Bus}/2048$ 0	$f_{Bus}/2$ $f_{Bus}/4$	Hz
1	D	SPSCK period Master Slave	t_{SPSCK}	2 4	2048 —	t_{cyc} t_{cyc}
2	D	Enable lead time Master Slave	t_{Lead}	1/2 1	— —	t_{SPSCK} t_{cyc}
3	D	Enable lag time Master Slave	t_{Lag}	1/2 1	— —	t_{SPSCK} t_{cyc}
4	D	Clock (SPSCK) high or low time Master Slave	t_{WSPSCK}	$t_{cyc} - 30$ $t_{cyc} - 30$	1024 t_{cyc} —	ns ns
5	D	Data setup time (inputs) Master Slave	t_{SU}	15 15	— —	ns ns
6	D	Data hold time (inputs) Master Slave	t_{HI}	0 25	— —	ns ns
7	D	Slave access time	t_a	—	1	t_{cyc}
8	D	Slave MISO disable time	t_{dis}	—	1	t_{cyc}
9	D	Data valid (after SPSCK edge) Master Slave	t_v	— —	25 25	ns ns
10	D	Data hold time (outputs) Master Slave	t_{HO}	0 0	— —	ns ns
11	D	Rise time Input Output	t_{RI} t_{RO}	— —	$t_{cyc} - 25$ 25	ns ns
12	D	Fall time Input Output	t_{FI} t_{FO}	— —	$t_{cyc} - 25$ 25	ns ns

Table 17. ADC Characteristics (V_{REFH} = V_{DDA}, V_{REFL} = V_{SSA}) (continued)

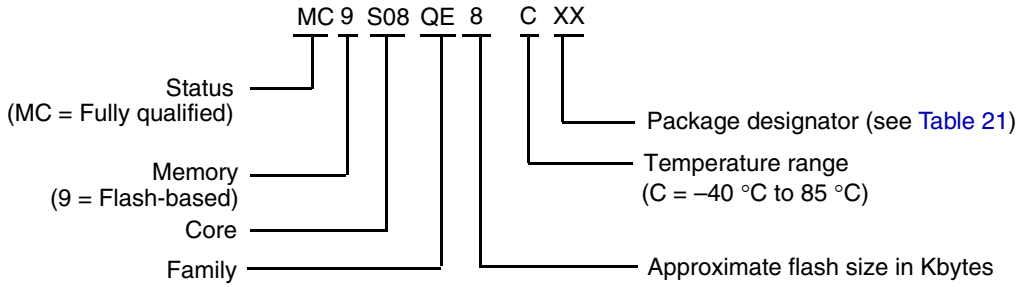
C	Characteristic	Conditions	Symbol	Min	Typ[1]	Max	Unit	Comment
D	Input leakage error	12-bit mode	E_{IL}	—	±2	—	LSB[2]	Pad leakage[4] * R_{AS}
		10-bit mode		—	±0.2	±4		
		8-bit mode		—	±0.1	±1.2		
Characteristics for devices with shared supply (16- and 20-pin packages only)								
T	Total unadjusted error	12-bit mode	E_{TUE}	Not recommended usage			LSB[2]	Includes quantization
P		10-bit mode		—	±1.5	±3.5		
P		8-bit mode		—	±0.7	±1.5		
T	Differential non-linearity	12-bit mode	DNL	Not recommended usage			LSB[2]	
P		10-bit mode[3]		—	±0.5	±1.0		
P		8-bit mode[3]		—	±0.3	±0.5		
T	Integral non-linearity	12-bit mode	INL	Not recommended usage			LSB[2]	
T		10-bit mode		—	±0.5	±1.0		
T		8-bit mode		—	±0.3	±0.5		
T	Zero-scale error	12-bit mode	E_{ZS}	Not recommended usage			LSB[2]	V_{ADIN} = V_{SSA}
P		10-bit mode		—	±1.5	±2.1		
P		8-bit mode		—	±0.5	±0.7		
T	Full-scale error	12-bit mode	E_{FS}	Not recommended usage			LSB[2]	V_{ADIN} = V_{DDA}
P		10-bit mode		—	±1	±1.5		
P		8-bit mode		—	±0.5	±0.5		
D	Quantization error	12-bit mode	E_Q	Not recommended usage			LSB[2]	
		10-bit mode		—	—	±0.5		
		8-bit mode		—	—	±0.5		
D	Input leakage error	12-bit mode	E_{IL}	Not recommended usage			LSB[2]	Pad leakage[4] * R_{AS}
		10-bit mode		—	±0.2	±4		
		8-bit mode		—	±0.1	±1.2		

1 Typical values assume V_{DDA} = 3.0 V, Temp = 25 °C, f_{ADCK} = 1.0 MHz unless otherwise stated. Typical values are for reference only and are not tested in production.

2 1 LSB = $(V_{REFH} - V_{REFL})/2^N$

3 Monotonicity and No-missing-codes guaranteed in 10-bit and 8-bit modes

4 Based on input pad leakage current. Refer to pad electricals.



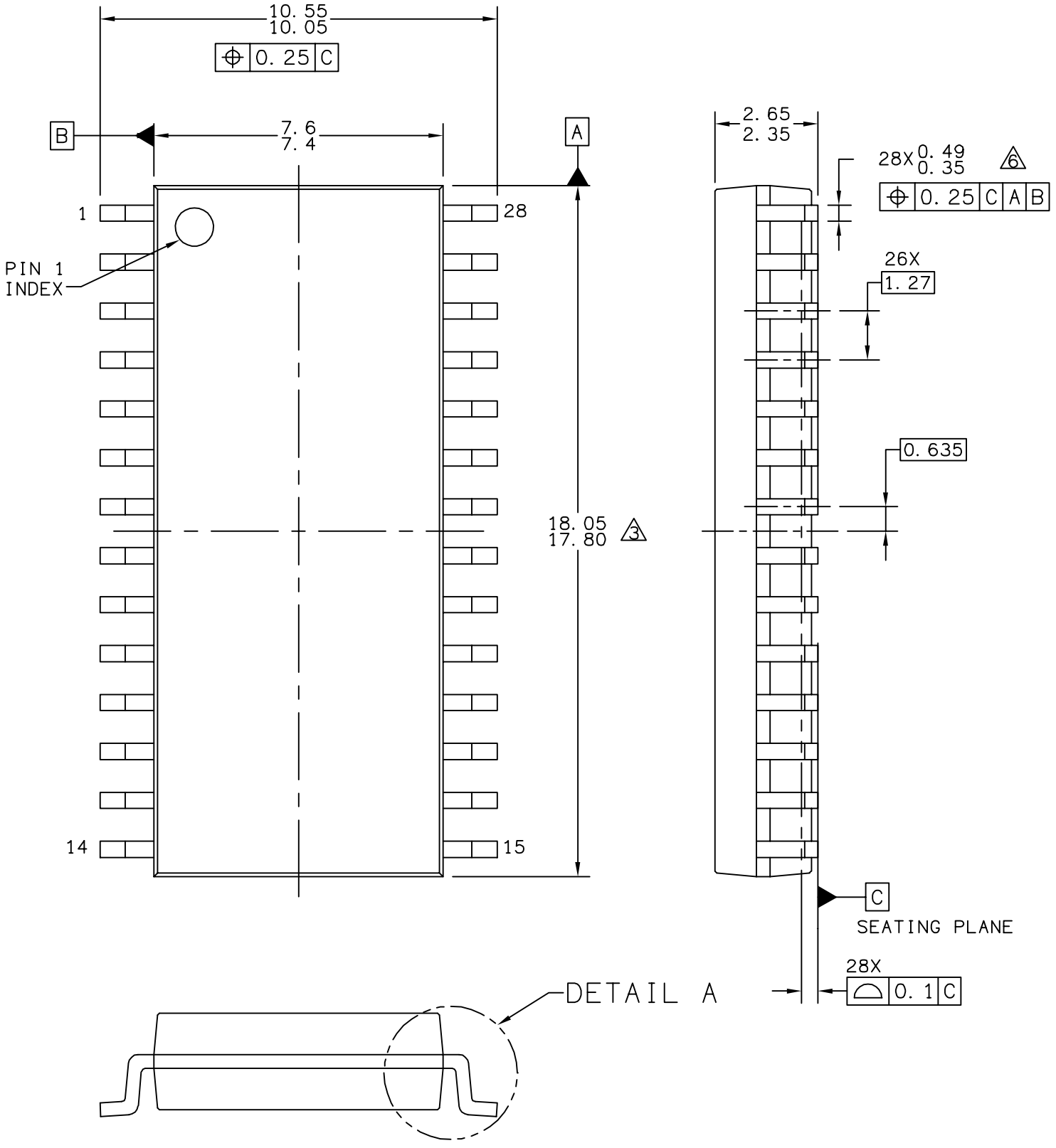
5 Package Information

Table 21. Package Descriptions

Pin Count	Package Type	Abbreviation	Designator	Case No.	Document No.
32	Quad Flat No-Leads	QFN	FM	2078	98ASA00071D
32	Low Quad Flat Package	LQFP	LC	873A	98ASH70029A
28	Small Outline Integrated Circuit	SOIC	WL	751F	98ASB42345B
20	Small Outline Integrated Circuit	SOIC	WJ	751D	98ASB42343B
16	Plastic Dual In-line Package	PDIP	PG	648	98ASB42431B
16	Thin Shrink Small Outline Package	TSSOP	TG	948F	98ASH70247A

5.1 Mechanical Drawings

The following pages are mechanical drawings for the packages described in Table 21.



MECHANICAL OUTLINE	PRINT VERSION NOT TO SCALE

TITLE: SOIC, WIDE BODY, 28 LEAD CASEOUTLINE	DOCUMENT NO: 98ASB42345B	REV: G
	CASE NUMBER: 751F-05	10 MAR 2005
	STANDARD: MS-013AE	

NOTES:

1. DIMENSIONS ARE IN MILLIMETERS.

2. DIMENSIONING AND TOLERANCING PER ASME Y14.5M–1994.

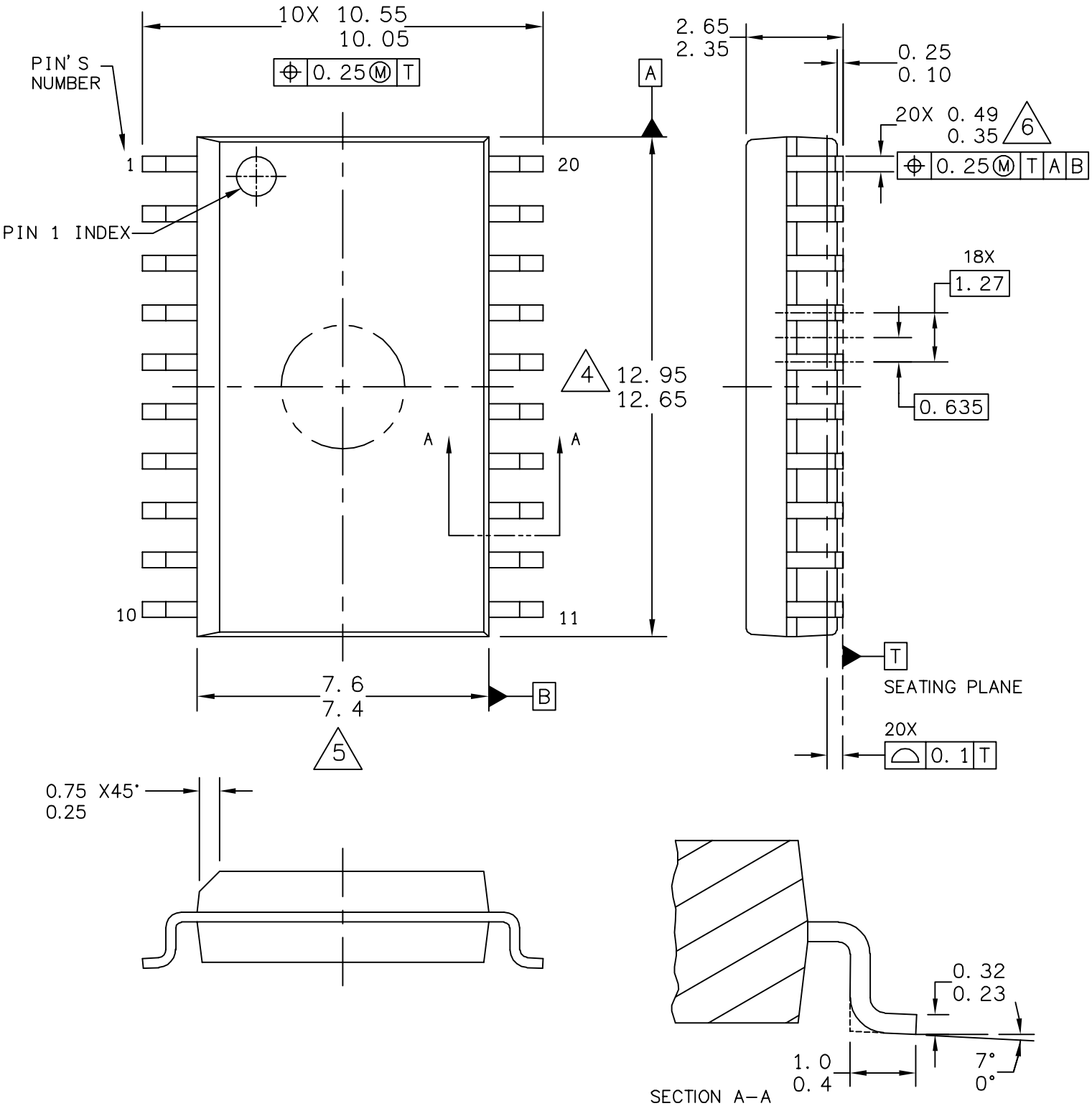
3. THIS DIMENSION DOES NOT INCLUDE MOLD PROTRUSION. MAXIMUM MOLD PROTRUSION 0.15 PER SIDE.

4. 751F–01 THRU –04 OBSOLETE. NEW STANDARD: 751F–05

5. THIS DIMENSION DOES NOT INCLUDE DAM BAR PROTRUSION ALLOWABLE DAM BAR PROTRUSION SHALL BE 0.13 TOTAL IN EXCESS OF THIS DIMENSION AT MAXIMUM MATERIAL CONDITION.

MECHANICAL OUTLINE	PRINT VERSION NOT TO SCALE

TITLE: SOIC, WIDE BODY, 28 LEAD CASEOUTLINE	DOCUMENT NO: 98ASB42345B	REV: G
	CASE NUMBER: 751F–05	10 MAR 2005
	STANDARD: MS–013AE	



MECHANICAL OUTLINE	PRINT VERSION NOT TO SCALE

TITLE:	DOCUMENT NO: 98ASB42343B	REV: J
20LD SOIC W/B, 1.27 PITCH CASE-OUTLINE	CASE NUMBER: 751D-07	23 MAR 2005
	STANDARD: JEDEC MS-013AC	

NOTES:

1. DIMENSIONS ARE IN MILLIMETERS.

2. DIMENSIONING AND TOLERANCING PER ASME Y14.5M–1994.

3. DATUMS A AND B TO BE DETERMINED AT THE PLANE WHERE THE BOTTOM OF THE LEADS EXIT THE PLASTIC BODY.

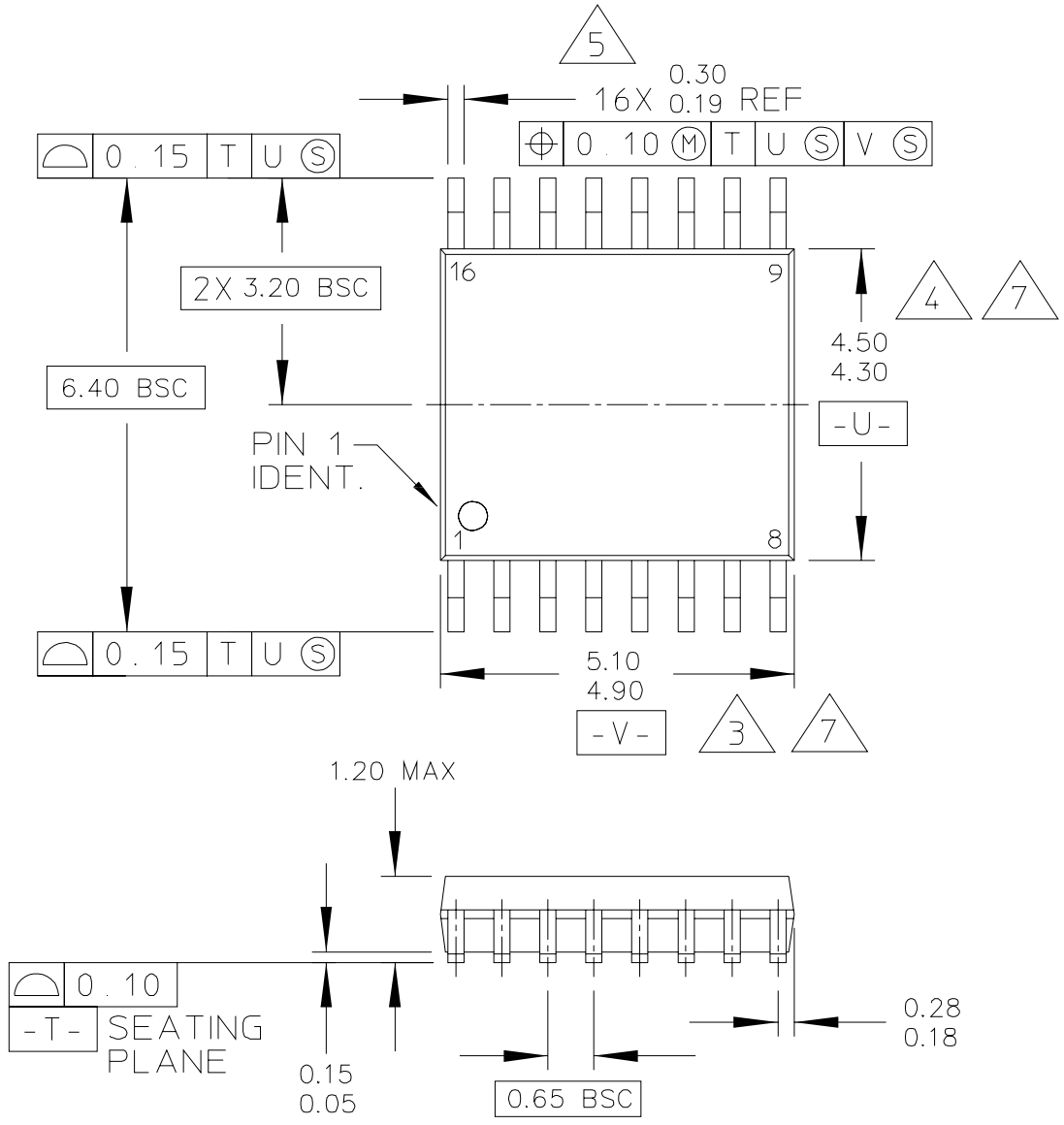
4. THIS DIMENSION DOES NOT INCLUDE MOLD FLASH, PROTRUSION OR GATE BURRS. MOLD FLASH, PROTRUSION OR GATE BURRS SHALL NOT EXCEED 0.15 MM PER SIDE. THIS DIMENSION IS DETERMINED AT THE PLANE WHERE THE BOTTOM OF THE LEADS EXIT THE PLASTIC BODY.

5. THIS DIMENSION DOES NOT INCLUDE INTER–LEAD FLASH OR PROTRUSIONS. INTER–LEAD FLASH AND PROTRUSIONS SHALL NOT EXCEED 0.25 MM PER SIDE. THIS DIMENSION IS DETERMINED AT THE PLANE WHERE THE BOTTOM OF THE LEADS EXIT THE PLASTIC BODY.

6. THIS DIMENSION DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL NOT CAUSE THE LEAD WIDTH TO EXCEED 0.62 mm.

MECHANICAL OUTLINE	PRINT VERSION NOT TO SCALE

TITLE:	DOCUMENT NO: 98ASB42343B	REV: J
20LD SOIC W/B, 1.27 PITCH, CASE OUTLINE	CASE NUMBER: 751D–07	23 MAR 2005
	STANDARD: JEDEC MS–013AC	



MECHANICAL OUTLINE	PRINT VERSION NOT TO SCALE

TITLE:	DOCUMENT NO: 98ASH70247A	REV: B
16 LD TSSOP, PITCH 0.65MM	CASE NUMBER: 948F-01	19 MAY 2005
	STANDARD: JEDEC	

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Rev. 8
4/2011