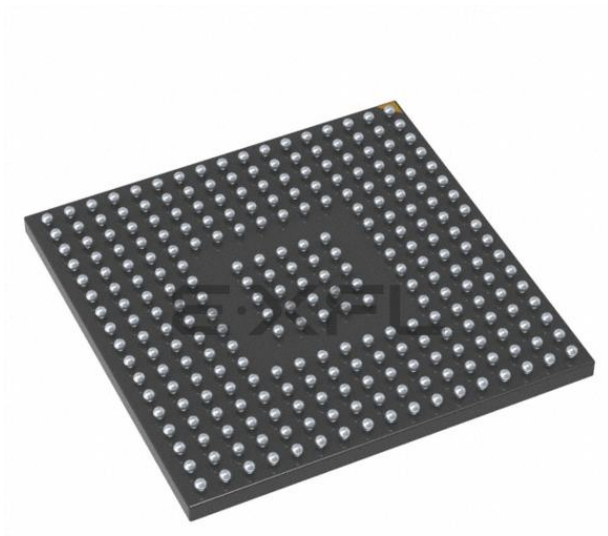




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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M7
Core Size	32-Bit Single-Core
Speed	216MHz
Connectivity	CANbus, EBI/EMI, Ethernet, I ² C, IrDA, LINbus, SAI, SD, SPDIF-Rx, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, I ² S, LCD, POR, PWM, WDT
Number of I/O	140
Program Memory Size	1MB (1M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	320K x 8
Voltage - Supply (Vcc/Vdd)	1.7V ~ 3.6V
Data Converters	A/D 24x12b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	201-UFBGA
Supplier Device Package	176+25UFBGA (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f746igk7

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Table 10. STM32F745xx and STM32F746xx pin and ball definition (continued)

Pin Number								Pin name (function after reset) ⁽¹⁾	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP100	TFBGA100	WLCSP143	LQFP144	UFBGA176	LQFP176	LQFP208	TFBGA216						
-	-	H11	20	L3	26	29	L3	PF8	I/O	FT	-	SPI5_MISO, SAI1_SCK_B, UART7_RTS, TIM13_CH1, QUADSPI_BK1_IO0, EVENTOUT	ADC3_IN6
-	-	G8	21	L2	27	30	L2	PF9	I/O	FT	-	SPI5_MOSI, SAI1_FS_B, UART7_CTS, TIM14_CH1, QUADSPI_BK1_IO1, EVENTOUT	ADC3_IN7
-	-	G9	22	L1	28	31	L1	PF10	I/O	FT	-	DCMI_D11, LCD_DE, EVENTOUT	ADC3_IN8
12	C1	J11	23	G1	29	32	G1	PH0- OSC_IN(PH0)	I/O	FT	-	EVENTOUT	OSC_IN ⁽⁴⁾
13	D1	H10	24	H1	30	33	H1	PH1- OSC_OUT(PH1)	I/O	FT	-	EVENTOUT	OSC_OUT ⁽⁴⁾
14	E1	H9	25	J1	31	34	J1	NRST	I/O	RS T	-	-	-
15	F1	H8	26	M2	32	35	M2	PC0	I/O	FT	(4)	SAI2_FS_B, OTG_HS_ULPI_STP, FMC_SDNWE, LCD_R5, EVENTOUT	ADC123_IN1 0
16	F2	K11	27	M3	33	36	M3	PC1	I/O	FT	(4)	TRACED0, SPI2_MOSI/I2S2_SD, SAI1_SD_A, ETH_MDC, EVENTOUT	ADC123_IN1 1, RTC_TAMP3, WKUP3
17	E2	J10	28	M4	34	37	M4	PC2	I/O	FT	(4)	SPI2_MISO, OTG_HS_ULPI_DIR, ETH_MII_TXD2, FMC_SDNE0, EVENTOUT	ADC123_IN1 2

Table 10. STM32F745xx and STM32F746xx pin and ball definition (continued)

Pin Number								Pin name (function after reset) ⁽¹⁾	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP100	TFBGA100	WLCSP143	LQFP144	UFBGA176	LQFP176	LQFP208	TFBGA216						
-	-	-	-	G4	44	47	J4	PH3	I/O	FT	-	QUADSPI_BK2_IO1, SAI2_MCK_B, ETH_MII_COL, FMC_SDNE0, LCD_R1, EVENTOUT	-
-	-	-	-	H4	45	48	H4	PH4	I/O	FT	-	I2C2_SCL, OTG_HS_ULPI_NXT, EVENTOUT	-
-	-	-	-	J4	46	49	J3	PH5	I/O	FT	-	I2C2_SDA, SPI5_NSS, FMC_SDNWE, EVENTOUT	-
25	K2	M11	37	R2	47	50	R2	PA3	I/O	FT	(4)	TIM2_CH4, TIM5_CH4, TIM9_CH2, USART2_RX, OTG_HS_ULPI_D0, ETH_MII_COL, LCD_B5, EVENTOUT	ADC123_IN3
26	J1	-	38	-	-	51	K6	VSS	S	-	-	-	-
-	E6	N11	-	L4	48	-	L5	BYPASS_REG	I	FT	-	-	-
27	K1	J8	39	K4	49	52	K5	VDD	S	-	-	-	-
28	G3	M10	40	N4	50	53	N4	PA4	I/O	TTa	(4)	SPI1_NSS/I2S1_WS, SPI3_NSS/I2S3_WS, USART2_CK, OTG_HS_SOF, DCMI_HSYNC, LCD_VSYNC, EVENTOUT	ADC12_IN4, DAC_OUT1
29	H3	M9	41	P4	51	54	P4	PA5	I/O	TTa	(4)	TIM2_CH1/TIM2_ETR, TIM8_CH1N, SPI1_SCK/I2S1_CK, OTG_HS_ULPI_CK, LCD_R4, EVENTOUT	ADC12_IN5, DAC_OUT2
30	J3	N10	42	P3	52	55	P3	PA6	I/O	FT	(4)	TIM1_BKIN, TIM3_CH1, TIM8_BKIN, SPI1_MISO, TIM13_CH1, DCMI_PIXCLK, LCD_G2, EVENTOUT	ADC12_IN6

Table 10. STM32F745xx and STM32F746xx pin and ball definition (continued)

Pin Number								Pin name (function after reset) ⁽¹⁾	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP100	TFBGA100	WLCSP143	LQFP144	UFBGA176	LQFP176	LQFP208	TFBGA216						
-	-	G2	93	H14	112	135	H14	PG8	I/O	FT	-	SPI6_NSS, SPDIFRX_IN2, USART6_RTS, ETH_PPS_OUT, FMC_SDCLK, EVENTOUT	-
-	-	D2	94	G12	113	136	G10	VSS	S	-	-	-	-
-	F6	G1	95	H13	114	137	G11	VDDUSB	S	-	-	-	-
63	F10	F2	96	H15	115	138	H15	PC6	I/O	FT	-	TIM3_CH1, TIM8_CH1, I2S2_MCK, USART6_TX, SDMMC1_D6, DCMI_D0, LCD_HSYNC, EVENTOUT	-
64	E10	F3	97	G15	116	139	G15	PC7	I/O	FT	-	TIM3_CH2, TIM8_CH2, I2S3_MCK, USART6_RX, SDMMC1_D7, DCMI_D1, LCD_G6, EVENTOUT	-
65	F9	E4	98	G14	117	140	G14	PC8	I/O	FT	-	TRACED1, TIM3_CH3, TIM8_CH3, UART5_RTS, USART6_CK, SDMMC1_D0, DCMI_D2, EVENTOUT	-
66	E9	E3	99	F14	118	141	F14	PC9	I/O	FT	-	MCO2, TIM3_CH4, TIM8_CH4, I2C3_SDA, I2S_CKIN, UART5_CTS, QUADSPI_BK1_IO0, SDMMC1_D1, DCMI_D3, EVENTOUT	-
67	D9	F1	100	F15	119	142	F15	PA8	I/O	FT	-	MCO1, TIM1_CH1, TIM8_BKIN2, I2C3_SCL, USART1_CK, OTG_FS_SOF, LCD_R6, EVENTOUT	-
68	C9	E2	101	E15	120	143	E15	PA9	I/O	FT	-	TIM1_CH2, I2C3_SMBA, SPI2_SCK/I2S2_CK, USART1_TX, DCMI_D0, EVENTOUT	OTG_FS_VB US



Table 12. STM32F745xx and STM32F746xx alternate function mapping

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
		SYS	TIM1/2	TIM3/4/5	TIM8/9/10/ 11/LPTIM 1/CEC	I2C1/2/3/ 4/CEC	SPI1/2/3/ 4/5/6	SPI3/ SAI1	SPI2/3/U SART1/2/ 3/UART5/ SPDIFRX	SAI2/US ART6/UA RT4/5/7/8 /SPDIFR X	CAN1/2/T IM12/13/ 14/QUAD SPI/LCD	SAI2/QU ADSPI/O TG2_HS/ OTG1_FS	ETH/ OTG1_FS	FMC/SD MMC1/O TG2_FS	DCMI	LCD	SYS
Port A	PA0	-	TIM2_C H1/TIM2 _ETR	TIM5_C H1	TIM8_ET R	-	-	-	USART2 _CTS	UART4_ TX	-	SAI2_SD_ B	ETH_MII_ CRS	-	-	-	EVEN TOUT
	PA1	-	TIM2_C H2	TIM5_C H2	-	-	-	-	USART2 _RTS	UART4_ RX	QUADSP I_BK1_IO 3	SAI2_MC K_B	ETH_MII_ RX_CLK/ ETH_RMI I_REF_C LK	-	-	LCD_R2	EVEN TOUT
	PA2	-	TIM2_C H3	TIM5_C H3	TIM9_CH 1	-	-	-	USART2 _TX	SAI2_SC K_B	-	-	ETH_MDI O	-	-	LCD_R1	EVEN TOUT
	PA3	-	TIM2_C H4	TIM5_C H4	TIM9_CH 2	-	-	-	USART2 _RX	-	-	OTG_HS_ ULPI_D0	ETH_MII_ COL	-	-	LCD_B5	EVEN TOUT
	PA4	-	-	-	-	-	SPI1_NS S/I2S1_ WS	SPI3_NS S/I2S3_ WS	USART2 _CK	-	-	-	-	OTG_HS_ _SOF	DCMI_H SYNC	LCD_VS YNC	EVEN TOUT
	PA5	-	TIM2_C H1/TIM2 _ETR	-	TIM8_CH 1N	-	SPI1_SC K/I2S1_ CK	-	-	-	-	OTG_HS_ ULPI_CK	-	-	-	LCD_R4	EVEN TOUT
	PA6	-	TIM1_B KIN	TIM3_C H1	TIM8_BKI N	-	SPI1_MI SO	-	-	-	TIM13_C H1	-	-	-	DCMI_PI XCLK	LCD_G2	EVEN TOUT
	PA7	-	TIM1_C H1N	TIM3_C H2	TIM8_CH 1N	-	SPI1_M OSI/I2S1 _SD	-	-	-	TIM14_C H1	-	ETH_MII_ RX_DV/E TH_RMII_ CRS_DV	FMC_SD NWE	-	-	EVEN TOUT
	PA8	MCO1	TIM1_C H1	-	TIM8_BKI N2	I2C3_SC L	-	-	USART1 _CK	-	-	OTG_FS_ SOF	-	-	-	LCD_R6	EVEN TOUT
	PA9	-	TIM1_C H2	-	-	I2C3_SM BA	SPI2_SC K/I2S2_ CK	-	USART1 _TX	-	-	-	-	-	DCMI_D 0	-	EVEN TOUT
	PA10	-	TIM1_C H3	-	-	-	-	-	USART1 _RX	-	-	OTG_FS_ ID	-	-	DCMI_D 1	-	EVEN TOUT
	PA11	-	TIM1_C H4	-	-	-	-	-	USART1 _CTS	-	CAN1_R X	OTG_FS_ DM	-	-	-	LCD_R4	EVEN TOUT

Table 12. STM32F745xx and STM32F746xx alternate function mapping (continued)

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
		SYS	TIM1/2	TIM3/4/5	TIM8/9/10/ 11/LPTIM 1/CEC	I2C1/2/3/ 4/CEC	SPI1/2/3/ 4/5/6	SPI3/ SAI1	SPI2/3/U SART1/2/ 3/UART5/ SPDIFRX	SAI2/US ART6/UA RT4/5/7/8 /SPDIFR X	CAN1/2/T IM12/13/ 14/QUAD SPI/LCD	SAI2/QU ADSPI/O TG2_HS/ OTG1_FS	ETH/ OTG1_FS	FMC/SD MMC1/O TG2_FS	DCMI	LCD	SYS
Port C	PC4	-	-	-	-	-	I2S1_M CK	-	-	SPDIFRX _IN2	-	-	ETH_MII_ RXD0/ET H_RMII_ RXD0	FMC_SD NE0	-	-	EVEN TOUT
	PC5	-	-	-	-	-	-	-	-	SPDIFRX _IN3	-	-	ETH_MII_ RXD1/ET H_RMII_ RXD1	FMC_SD CKE0	-	-	EVEN TOUT
	PC6	-	-	TIM3_C H1	TIM8_CH 1	-	I2S2_M CK	-	-	USART6 _TX	-	-	-	SDMMC 1_D6	DCMI_D 0	LCD_HS YNC	EVEN TOUT
	PC7	-	-	TIM3_C H2	TIM8_CH2	-	-	I2S3_M CK	-	USART6 _RX	-	-	-	SDMMC 1_D7	DCMI_D 1	LCD_G6	EVEN TOUT
	PC8	TRACE D1	-	TIM3_C H3	TIM8_CH3	-	-	-	UART5_ RTS	USART6 _CK	-	-	-	SDMMC 1_D0	DCMI_D 2	-	EVEN TOUT
	PC9	MCO2	-	TIM3_C H4	TIM8_CH4	I2C3_SD A	I2S_CK1 N	-	UART5_ CTS	-	QUADSP I_BK1_IO 0	-	-	SDMMC 1_D1	DCMI_D 3	-	EVEN TOUT
	PC10	-	-	-	-	-	-	SPI3_SC K/I2S3_ CK	USART3 _TX	UART4_T X	QUADSP I_BK1_IO 1	-	-	SDMMC 1_D2	DCMI_D 8	LCD_R2	EVEN TOUT
	PC11	-	-	-	-	-	-	SPI3_MI SO	USART3 _RX	UART4_ RX	QUADSP I_BK2_N CS	-	-	SDMMC 1_D3	DCMI_D 4	-	EVEN TOUT
	PC12	TRACE D3	-	-	-	-	-	SPI3_M OS/I2S3 _SD	USART3 _CK	UART5_T X	-	-	-	SDMMC 1_CK	DCMI_D 9	-	EVEN TOUT
	PC13	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVEN TOUT
	PC14	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVEN TOUT
	PC15	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVEN TOUT

Table 13. STM32F745xx and STM32F746xx register boundary addresses (continued)

Bus	Boundary address	Peripheral
	0x4008 0000 - 0x4FFF FFFF	Reserved
AHB1	0x4004 0000 - 0x4007 FFFF	USB OTG HS
	0x4002 BC00 - 0x4003 FFFF	Reserved
	0x4002 B000 - 0x4002 BBFF	Chrom-ART (DMA2D)
	0x4002 9400 - 0x4002 AFFF	Reserved
	0x4002 9000 - 0x4002 93FF	ETHERNET MAC
	0x4002 8C00 - 0x4002 8FFF	
	0x4002 8800 - 0x4002 8BFF	
	0x4002 8400 - 0x4002 87FF	
	0x4002 8000 - 0x4002 83FF	
	0x4002 6800 - 0x4002 7FFF	Reserved
	0x4002 6400 - 0x4002 67FF	DMA2
	0x4002 6000 - 0x4002 63FF	DMA1
	0x4002 5000 - 0x4002 5FFF	Reserved
	0x4002 4000 - 0x4002 4FFF	BKPSRAM
	0x4002 3C00 - 0x4002 3FFF	Flash interface register
	0x4002 3800 - 0x4002 3BFF	RCC
	0x4002 3400 - 0x4002 37FF	Reserved
	0x4002 3000 - 0x4002 33FF	CRC
	0x4002 2C00 - 0x4002 2FFF	Reserved
	0x4002 2800 - 0x4002 2BFF	GPIOK
	0x4002 2400 - 0x4002 27FF	GPIOJ
	0x4002 2000 - 0x4002 23FF	GPIOI
	0x4002 1C00 - 0x4002 1FFF	GPIOH
	0x4002 1800 - 0x4002 1BFF	GPIOG
	0x4002 1400 - 0x4002 17FF	GPIOF
	0x4002 1000 - 0x4002 13FF	GPIOE
	0x4002 0C00 - 0x4002 0FFF	GPIOD
	0x4002 0800 - 0x4002 0BFF	GPIOC
	0x4002 0400 - 0x4002 07FF	GPIOB
	0x4002 0000 - 0x4002 03FF	GPIOA

Table 22. reset and power control block characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{PVD}	Programmable voltage detector level selection	PLS[2:0]=000 (rising edge)	2.09	2.14	2.19	V
		PLS[2:0]=000 (falling edge)	1.98	2.04	2.08	V
		PLS[2:0]=001 (rising edge)	2.23	2.30	2.37	V
		PLS[2:0]=001 (falling edge)	2.13	2.19	2.25	V
		PLS[2:0]=010 (rising edge)	2.39	2.45	2.51	V
		PLS[2:0]=010 (falling edge)	2.29	2.35	2.39	V
		PLS[2:0]=011 (rising edge)	2.54	2.60	2.65	V
		PLS[2:0]=011 (falling edge)	2.44	2.51	2.56	V
		PLS[2:0]=100 (rising edge)	2.70	2.76	2.82	V
		PLS[2:0]=100 (falling edge)	2.59	2.66	2.71	V
		PLS[2:0]=101 (rising edge)	2.86	2.93	2.99	V
		PLS[2:0]=101 (falling edge)	2.65	2.84	2.92	V
		PLS[2:0]=110 (rising edge)	2.96	3.03	3.10	V
		PLS[2:0]=110 (falling edge)	2.85	2.93	2.99	V
		PLS[2:0]=111 (rising edge)	3.07	3.14	3.21	V
		PLS[2:0]=111 (falling edge)	2.95	3.03	3.09	V
$V_{PVDhyst}^{(1)}$	PVD hysteresis	-	-	100	-	mV
$V_{POR/PDR}$	Power-on/power-down reset threshold	Falling edge	1.60	1.68	1.76	V
		Rising edge	1.64	1.72	1.80	V
$V_{PDRhyst}^{(1)}$	PDR hysteresis	-	-	40	-	mV
V_{BOR1}	Brownout level 1 threshold	Falling edge	2.13	2.19	2.24	V
		Rising edge	2.23	2.29	2.33	V
V_{BOR2}	Brownout level 2 threshold	Falling edge	2.44	2.50	2.56	V
		Rising edge	2.53	2.59	2.63	V
V_{BOR3}	Brownout level 3 threshold	Falling edge	2.75	2.83	2.88	V
		Rising edge	2.85	2.92	2.97	V
$V_{BORhyst}^{(1)}$	BOR hysteresis	-	-	100	-	mV
$T_{RSTTEMPO}^{(1)(2)}$	POR reset temporization	-	0.5	1.5	3.0	ms
$I_{RUSH}^{(1)}$	InRush current on voltage regulator power-on (POR or wakeup from Standby)	-	-	160	250	mA
$E_{RUSH}^{(1)}$	InRush energy on voltage regulator power-on (POR or wakeup from Standby)	$V_{DD} = 1.7\text{ V}$, $T_A = 105\text{ }^{\circ}\text{C}$, $I_{RUSH} = 171\text{ mA}$ for $31\text{ }\mu\text{s}$	-	-	5.4	μC

Equation 2

Equation 2 allows to calculate the increment step (INCSTEP):

$$\text{INCSTEP} = \text{round}[(2^{15} - 1) \times \text{md} \times \text{PLLN}] / (100 \times 5 \times \text{MODEPER})$$

$f_{\text{VCO_OUT}}$ must be expressed in MHz.

With a modulation depth (md) = $\pm 2\%$ (4 % peak to peak), and PLLN = 240 (in MHz):

$$\text{INCSTEP} = \text{round}[(2^{15} - 1) \times 2 \times 240] / (100 \times 5 \times 250) = 126 \text{md}(\text{quantitized})\%$$

An amplitude quantization error may be generated because the linear modulation profile is obtained by taking the quantized values (rounded to the nearest integer) of MODPER and INCSTEP. As a result, the achieved modulation depth is quantized. The percentage quantized modulation depth is given by the following formula:

$$\text{md}_{\text{quantized}}\% = (\text{MODEPER} \times \text{INCSTEP} \times 100 \times 5) / ((2^{15} - 1) \times \text{PLLN})$$

As a result:

$$\text{md}_{\text{quantized}}\% = (250 \times 126 \times 100 \times 5) / ((2^{15} - 1) \times 240) = 2.002\%(\text{peak})$$

[Figure 36](#) and [Figure 37](#) show the main PLL output clock waveforms in center spread and down spread modes, where:

F0 is $f_{\text{PLL_OUT}}$ nominal.

T_{mode} is the modulation period.

md is the modulation depth.

Figure 36. PLL output clock waveforms in center spread mode

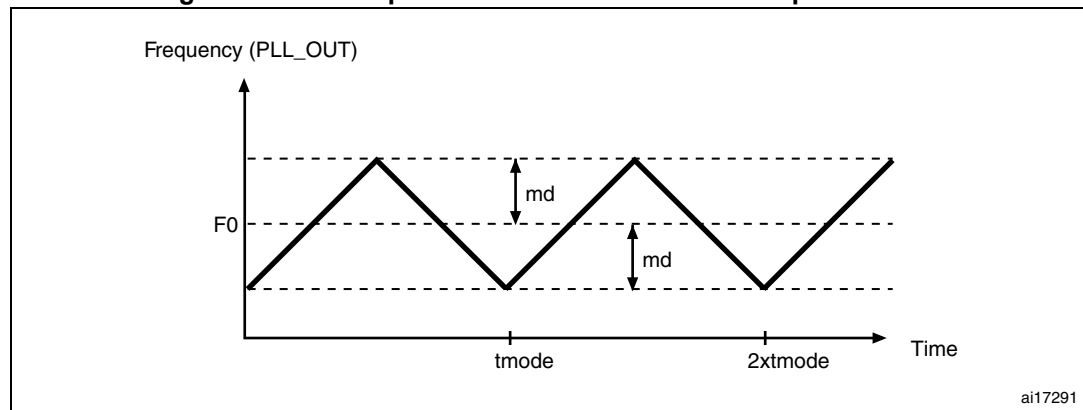


Table 56. I/O static characteristics (continued)

Symbol	Parameter		Conditions	Min	Typ	Max	Unit
V _{IH}	FT, TTa and NRST I/O input high level voltage ⁽⁵⁾		1.7 V≤V _{DD} ≤3.6 V	0.45V _{DD} +0.3 ⁽¹⁾	-	-	V
			0.7V _{DD} ⁽²⁾				
	BOOT I/O input high level voltage		1.75 V≤V _{DD} ≤3.6 V, −40 °C≤T _A ≤105 °C	0.17V _{DD} +0.7 ⁽¹⁾	-	-	
		1.7 V≤V _{DD} ≤3.6 V, 0 °C≤T _A ≤105 °C					
V _{HYS}	FT, TTa and NRST I/O input hysteresis		1.7 V≤V _{DD} ≤3.6 V	10%V _{DD} ⁽³⁾	-	-	V
	BOOT I/O input hysteresis		1.75 V≤V _{DD} ≤3.6 V, −40 °C≤T _A ≤105 °C	0.1	-	-	
			1.7 V≤V _{DD} ≤3.6 V, 0 °C≤T _A ≤105 °C				
I _{lkg}	I/O input leakage current ⁽⁴⁾		V _{SS} ≤V _{IN} ≤V _{DD}	-	-	±1	μA
	I/O FT input leakage current ⁽⁵⁾		V _{IN} = 5 V	-	-	3	
R _{PU}	Weak pull-up equivalent resistor ⁽⁶⁾	All pins except for PA10/PB12 (OTG_FS_ID ,OTG_HS_ID)	V _{IN} = V _{SS}	30	40	50	kΩ
		PA10/PB12 (OTG_FS_ID ,OTG_HS_ID)		7	10	14	
R _{PD}	Weak pull-down equivalent resistor ⁽⁷⁾	All pins except for PA10/PB12 (OTG_FS_ID ,OTG_HS_ID)	V _{IN} = V _{DD}	30	40	50	
		PA10/PB12 (OTG_FS_ID ,OTG_HS_ID)		7	10	14	
C _{IO} ⁽⁸⁾	I/O pin capacitance		-	-	5	-	pF

1. Guaranteed by design.

2. Tested in production.

3. With a minimum of 200 mV.

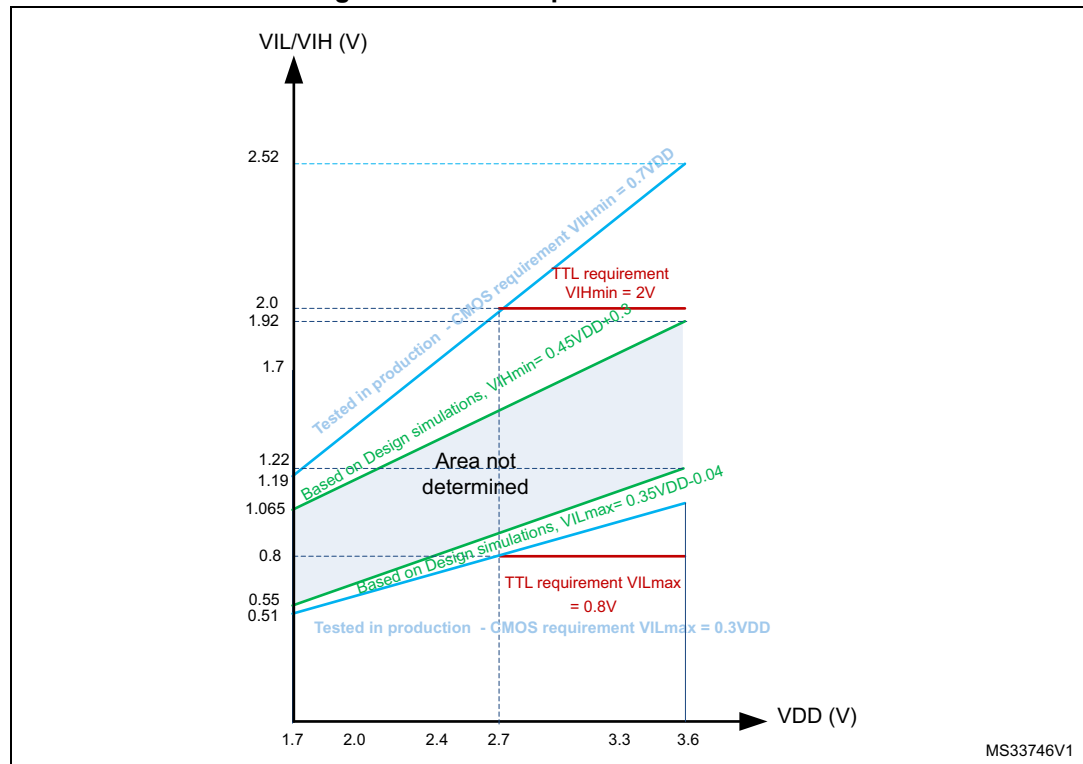
4. Leakage could be higher than the maximum value, if negative current is injected on adjacent pins, Refer to [Table 55: I/O current injection susceptibility](#)5. To sustain a voltage higher than $V_{DD} + 0.3\text{ V}$, the internal pull-up/pull-down resistors must be disabled. Leakage could be higher than the maximum value, if negative current is injected on adjacent pins. Refer to [Table 55: I/O current injection susceptibility](#)

6. Pull-up resistors are designed with a true resistance in series with a switchable PMOS. This PMOS contribution to the series resistance is minimum (~10% order).

7. Pull-down resistors are designed with a true resistance in series with a switchable NMOS. This NMOS contribution to the series resistance is minimum (~10% order).
8. Hysteresis voltage between Schmitt trigger switching levels. Guaranteed by characterization results.

All I/Os are CMOS and TTL compliant (no software configuration required). Their characteristics cover more than the strict CMOS-technology or TTL parameters. The coverage of these requirements for FT I/Os is shown in [Figure 38](#).

Figure 38. FT I/O input characteristics



Output driving current

The GPIOs (general purpose input/outputs) can sink or source up to ± 8 mA, and sink or source up to ± 20 mA (with a relaxed V_{OL}/V_{OH}) except PC13, PC14, PC15 and PI8 which can sink or source up to ± 3 mA. When using the PC13 to PC15 and PI8 GPIOs in output mode, the speed should not exceed 2 MHz with a maximum load of 30 pF.

In the user application, the number of I/O pins which can drive current must be limited to respect the absolute maximum rating specified in [Section 5.2](#). In particular:

- The sum of the currents sourced by all the I/Os on V_{DD} , plus the maximum Run consumption of the MCU sourced on V_{DD} , cannot exceed the absolute maximum rating ΣI_{VDD} (see [Table 15](#)).
- The sum of the currents sunk by all the I/Os on V_{SS} plus the maximum Run consumption of the MCU sunk on V_{SS} cannot exceed the absolute maximum rating ΣI_{VSS} (see [Table 15](#)).

Table 65. ADC static accuracy at $f_{\text{ADC}} = 36 \text{ MHz}$

Symbol	Parameter	Test conditions	Typ	Max ⁽¹⁾	Unit
ET	Total unadjusted error	$f_{\text{ADC}} = 36 \text{ MHz}$, $V_{\text{DDA}} = 2.4 \text{ to } 3.6 \text{ V}$, $V_{\text{REF}} = 1.7 \text{ to } 3.6 \text{ V}$ $V_{\text{DDA}} - V_{\text{REF}} < 1.2 \text{ V}$	± 4	± 7	LSB
EO	Offset error		± 2	± 3	
EG	Gain error		± 3	± 6	
ED	Differential linearity error		± 2	± 3	
EL	Integral linearity error		± 3	± 6	

1. Guaranteed by characterization results.

Table 66. ADC dynamic accuracy at $f_{\text{ADC}} = 18 \text{ MHz}$ - limited test conditions⁽¹⁾

Symbol	Parameter	Test conditions	Min	Typ	Max	Unit
ENOB	Effective number of bits	$f_{\text{ADC}} = 18 \text{ MHz}$ $V_{\text{DDA}} = V_{\text{REF+}} = 1.7 \text{ V}$ Input Frequency = 20 KHz Temperature = 25 °C	10.3	10.4	-	bits
SINAD	Signal-to-noise and distortion ratio		64	64.2	-	dB
SNR	Signal-to-noise ratio		64	65	-	
THD	Total harmonic distortion		- 67	- 72	-	

1. Guaranteed by characterization results.

Table 67. ADC dynamic accuracy at $f_{\text{ADC}} = 36 \text{ MHz}$ - limited test conditions⁽¹⁾

Symbol	Parameter	Test conditions	Min	Typ	Max	Unit
ENOB	Effective number of bits	$f_{\text{ADC}} = 36 \text{ MHz}$ $V_{\text{DDA}} = V_{\text{REF+}} = 3.3 \text{ V}$ Input Frequency = 20 KHz Temperature = 25 °C	10.6	10.8	-	bits
SINAD	Signal-to noise and distortion ratio		66	67	-	dB
SNR	Signal-to noise ratio		64	68	-	
THD	Total harmonic distortion		- 70	- 72	-	

1. Guaranteed by characterization results.

Note: ADC accuracy vs. negative injection current: injecting a negative current on any analog input pins should be avoided as this significantly reduces the accuracy of the conversion being performed on another analog input. It is recommended to add a Schottky diode (pin to ground) to analog pins which may potentially inject negative currents.

Any positive injection current within the limits specified for $I_{\text{INJ(PIN)}}$ and $\Sigma I_{\text{INJ(PIN)}}$ in [Section 5.3.17](#) does not affect the ADC accuracy.

5.3.27 FMC characteristics

Unless otherwise specified, the parameters given in [Table 88](#) to [Table 101](#) for the FMC interface are derived from tests performed under the ambient temperature, f_{HCLK} frequency and V_{DD} supply voltage conditions summarized in [Table 17](#), with the following configuration:

- Output speed is set to $OSPEEDRy[1:0] = 11$
- Measurement points are done at CMOS levels: $0.5V_{DD}$

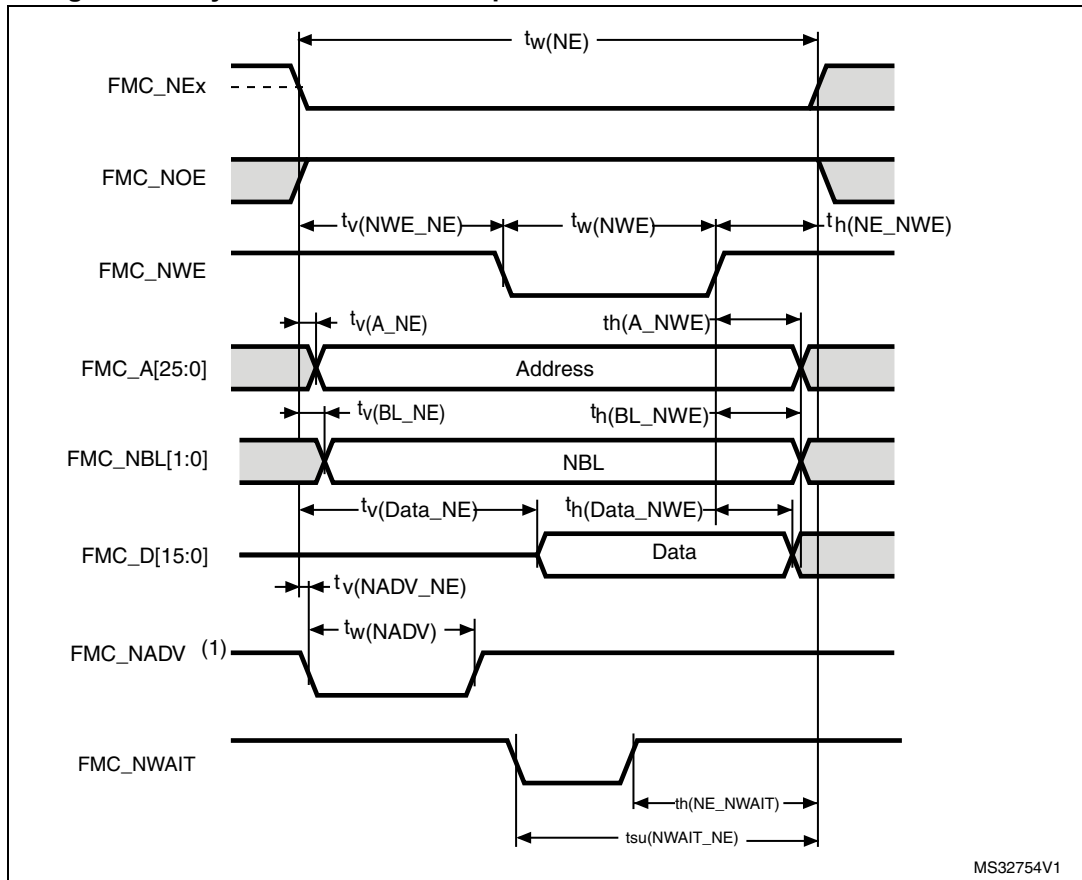
Refer to [Section 5.3.17: I/O port characteristics](#) for more details on the input/output characteristics.

Asynchronous waveforms and timings

[Figure 58](#) through [Figure 61](#) represent asynchronous waveforms and [Table 88](#) through [Table 95](#) provide the corresponding timings. The results shown in these tables are obtained with the following FMC configuration:

- AddressSetupTime = 0x1
- AddressHoldTime = 0x1
- DataSetupTime = 0x1 (except for asynchronous NWAIT mode , DataSetupTime = 0x5)
- BusTurnAroundDuration = 0x0
- Capacitive load CL = 30 pF

In all timing tables, the T_{HCLK} is the HCLK clock period

Figure 59. Asynchronous non-multiplexed SRAM/PSRAM/NOR write waveforms

1. Mode 2/B, C and D only. In Mode 1, FMC_NADV is not used.

Table 90. Asynchronous non-multiplexed SRAM/PSRAM/NOR write timings⁽¹⁾

Symbol	Parameter	Min	Max	Unit
$t_{w(NE)}$	FMC_NE low time	$3T_{HCLK}-0.5$	$3T_{HCLK}+1.5$	ns
$t_{v(NWE_NE)}$	FMC_NEx low to FMC_NWE low	$T_{HCLK}-0.5$	$T_{HCLK}+1$	
$t_{w(NWE)}$	FMC_NWE low time	$T_{HCLK}-0.5$	$T_{HCLK}+1$	
$t_{h(NE_NWE)}$	FMC_NWE high to FMC_NE high hold time	$T_{HCLK}-0.5$	-	
$t_{v(A_NE)}$	FMC_NEx low to FMC_A valid	-	0	
$t_{h(A_NWE)}$	Address hold time after FMC_NWE high	$T_{HCLK}-0.5$	-	
$t_{v(BL_NE)}$	FMC_NEx low to FMC_BL valid	-	0	
$t_{h(BL_NWE)}$	FMC_BL hold time after FMC_NWE high	$T_{HCLK}-0.5$	-	
$t_{v(Data_NE)}$	Data to FMC_NEx low to Data valid	-	$T_{HCLK}+3$	
$t_{h(Data_NWE)}$	Data hold time after FMC_NWE high	$T_{HCLK}+0.5$	-	
$t_{v(NADV_NE)}$	FMC_NEx low to FMC_NADV low	-	0	
$t_{w(NADV)}$	FMC_NADV low time	-	$T_{HCLK}+0.5$	

1. Guaranteed by characterization results.

Table 102. SDRAM read timings⁽¹⁾

Symbol	Parameter	Min	Max	Unit
$t_{w(SDCLK)}$	FMC_SDCLK period	$2T_{HCLK}-0.5$	$2T_{HCLK}+0.5$	ns
$t_{su(SDCLKH_Data)}$	Data input setup time	3.5	-	
$t_{h(SDCLKH_Data)}$	Data input hold time	1.5	-	
$t_{d(SDCLKL_Add)}$	Address valid time	-	4	
$t_{d(SDCLKL_SDNE)}$	Chip select valid time	-	0.5	
$t_{h(SDCLKL_SDNE)}$	Chip select hold time	0	-	
$t_{d(SDCLKL_SDNRAS)}$	SDNRAS valid time	-	0.5	
$t_{h(SDCLKL_SDNRAS)}$	SDNRAS hold time	0	-	
$t_{d(SDCLKL_SDNCAS)}$	SDNCAS valid time	-	0.5	
$t_{h(SDCLKL_SDNCAS)}$	SDNCAS hold time	0	-	

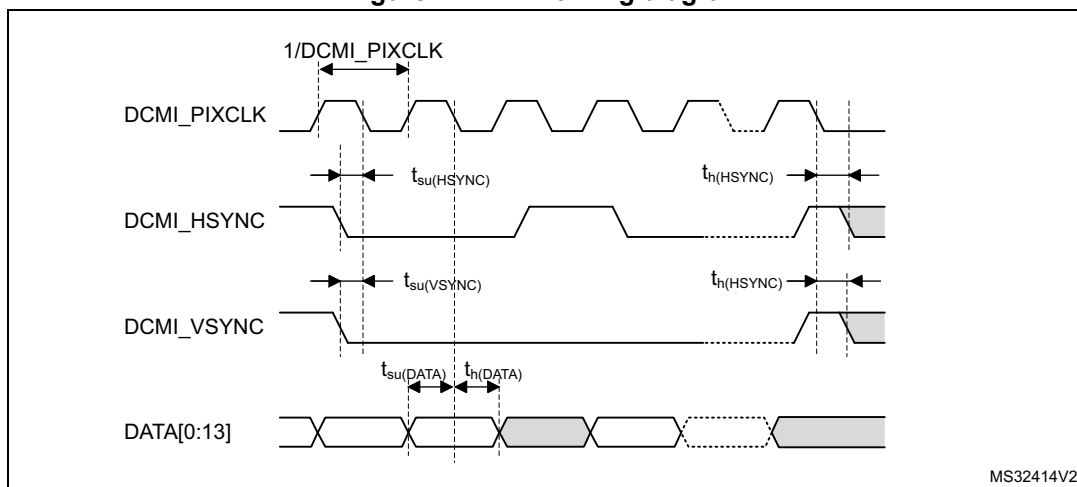
1. Guaranteed by characterization results.

Table 103. LPSPDR SDRAM read timings⁽¹⁾

Symbol	Parameter	Min	Max	Unit
$t_{w(SDCLK)}$	FMC_SDCLK period	$2T_{HCLK}-0.5$	$2T_{HCLK}+0.5$	ns
$t_{su(SDCLKH_Data)}$	Data input setup time	3	-	
$t_{h(SDCLKH_Data)}$	Data input hold time	1.5	-	
$t_{d(SDCLKL_Add)}$	Address valid time	-	3.5	
$t_{d(SDCLKL_SDNE)}$	Chip select valid time	-	0.5	
$t_{h(SDCLKL_SDNE)}$	Chip select hold time	0	-	
$t_{d(SDCLKL_SDNRAS)}$	SDNRAS valid time	-	0.5	
$t_{h(SDCLKL_SDNRAS)}$	SDNRAS hold time	0	-	
$t_{d(SDCLKL_SDNCAS)}$	SDNCAS valid time	-	0.5	
$t_{h(SDCLKL_SDNCAS)}$	SDNCAS hold time	0	-	

1. Guaranteed by characterization results.

Figure 74. DCMI timing diagram



5.3.30 LCD-TFT controller (LTDC) characteristics

Unless otherwise specified, the parameters given in [Table 109](#) for LCD-TFT are derived from tests performed under the ambient temperature, f_{HCLK} frequency and V_{DD} supply voltage summarized in [Table 17](#), with the following configuration:

- LCD_CLK polarity: high
- LCD_DE polarity : low
- LCD_VSYNC and LCD_HSYNC polarity: high
- Pixel formats: 24 bits

Table 109. LTDC characteristics ⁽¹⁾

Symbol	Parameter	Min	Max	Unit
f _{CLK}	LTDC clock output frequency	-	45	MHz
D _{CLK}	LTDC clock output duty cycle	45	55	%
t _w (CLKH) t _w (CLKL)	Clock High time, low time	tw(CLK)/2 – 0.5	tw(CLK)/2+0.5	ns
t _v (DATA)	Data output valid time	-	6	
t _h (DATA)	Data output hold time	2	-	
t _v (HSYNC)	HSYNC/VSYNC/DE output valid time	-	3	
t _v (VSYNC)				
t _v (DE)				
t _h (HSYNC)	HSYNC/VSYNC/DE output hold time	0.5	-	
t _h (VSYNC)				
t _h (DE)				

1. Guaranteed by characterization results.

Table 115. WLCSP143, 4.539x 5.849 mm, 0.4 mm pitch wafer level chip scale package mechanical data (continued)

Symbol	millimeters			inches ⁽¹⁾		
	Min	Typ	Max	Min	Typ	Max
A2	-	0.380	-	-	0.0150	-
A3 ⁽²⁾	-	0.025	-	-	0.0010	-
b ⁽³⁾	0.220	0.250	0.280	0.0087	0.0098	0.0110
D	4.504	4.539	4.574	0.1773	0.1787	0.1801
E	5.814	5.849	5.884	0.2289	0.2303	0.2317
e	-	0.400	-	-	0.0157	-
e1	-	4.000	-	-	0.1575	-
e2	-	4.800	-	-	0.1890	-
F	-	0.2695	-	-	0.0106	-
G	-	0.5245	-	-	0.0206	-
aaa	-	-	0.100	-	-	0.0039
bbb	-	-	0.100	-	-	0.0039
ccc	-	-	0.100	-	-	0.0039
ddd	-	-	0.050	-	-	0.0020
eee	-	-	0.050	-	-	0.0020

1. Values in inches are converted from mm and rounded to 4 decimal digits.

2. Back side coating.

3. Dimension is measured at the maximum bump diameter parallel to primary datum Z.

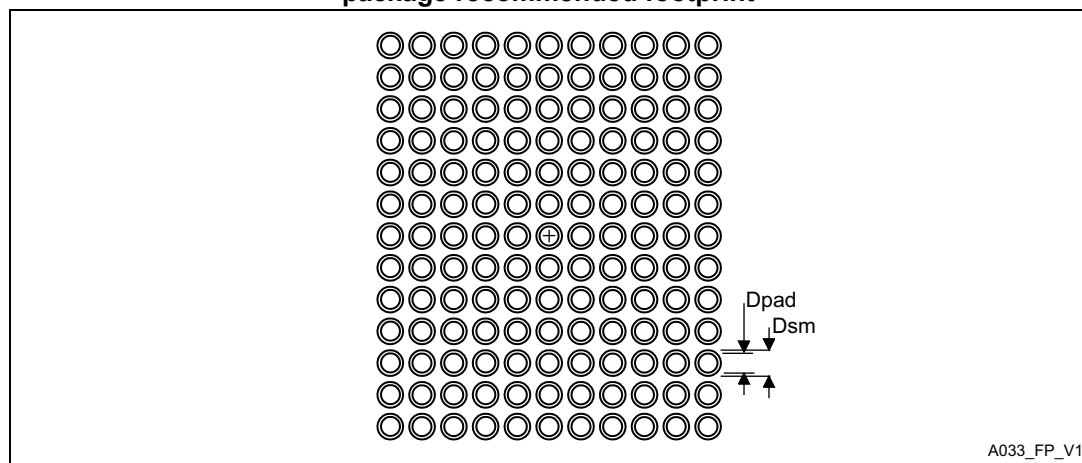
Figure 86. WLCSP143, 4.539x 5.849 mm, 0.4 mm pitch wafer level chip scale package recommended footprint

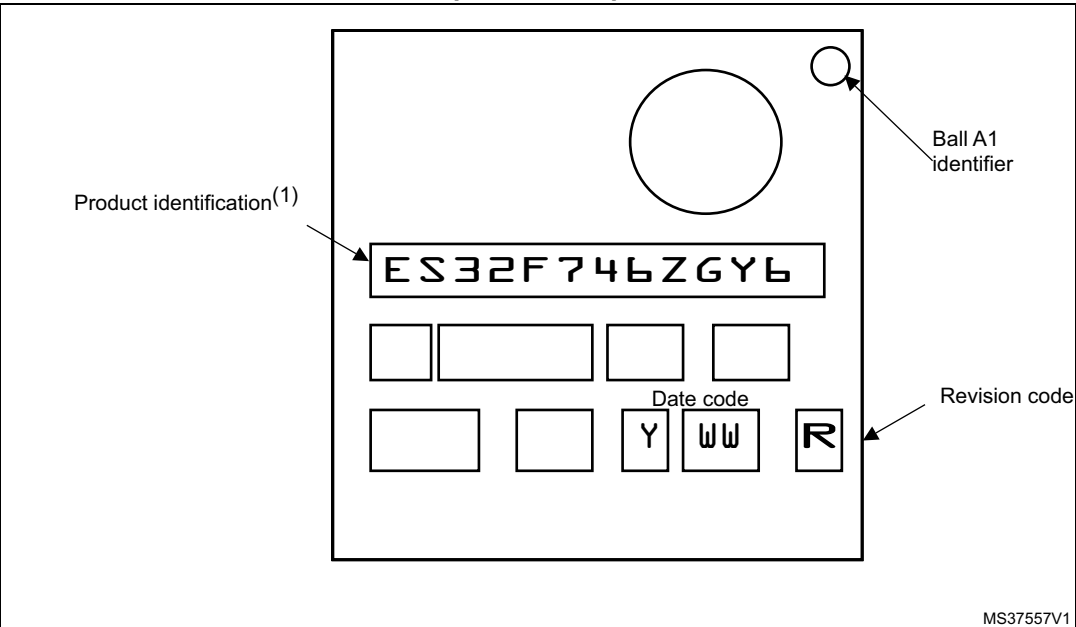
Table 116. WLCSP143 recommended PCB design rules

Dimension	Recommended values
Pitch	0.4
Dpad	0.225 mm
Dsm	0.290 mm typ. (depends on the soldermask registration tolerance)
Stencil opening	0.250 mm
Stencil thickness	0.100 mm

Marking of engineering samples

The following figure gives an example of topside marking orientation versus ball A1 identifier location.

Figure 87. WLCSP143, 0.4 mm pitch wafer level chip scale package top view example



1. Parts marked as “ES”, “E” or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering samples to run qualification activity.

Table 119. LQFP208, 28 x 28 mm, 208-pin low-profile quad flat package mechanical data (continued)

Symbol	millimeters			inches ⁽¹⁾		
	Min	Typ	Max	Min	Typ	Max
b	0.170	0.220	0.270	0.0067	0.0087	0.0106
c	0.090	-	0.200	0.0035	-	0.0079
D	29.800	30.000	30.200	1.1732	1.1811	1.1890
D1	27.800	28.000	28.200	1.0945	1.1024	1.1102
D3	-	25.500	-	-	1.0039	-
E	29.800	30.000	30.200	1.1732	1.1811	1.1890
E1	27.800	28.000	28.200	1.0945	1.1024	1.1102
E3	-	25.500	-	-	1.0039	-
e	-	0.500	-	-	0.0197	-
L	0.450	0.600	0.750	0.0177	0.0236	0.0295
L1	-	1.000	-	-	0.0394	-
k	0°	3.5°	7.0°	0°	3.5°	7.0°
ccc	-	-	0.080	-	-	0.0031

1. Values in inches are converted from mm and rounded to 4 decimal digits.

Revision history

Table 127. Document revision history

Date	Revision	Changes
26-May-2015	1	Initial release.
20-Oct-2015	2	Updated Table 53: ESD absolute maximum ratings adding packages. Updated note of Table 32: Typical and maximum current consumptions in Standby mode. Updated Figure 11: STM32F74xVx LQFP100 pinout replacing PB13 and PB14 by PE13 and PE14. Updated Table 51: EMS characteristics replacing 168 MHz by 216 MHz. Updated Section 2.9: Quad-SPI memory interface (QUADSPI) removing 'STM32F75xx'. Updated Section 2.22.2: General-purpose timers (TIMx) and Section 2.43: Embedded Trace Macrocell™ modifying STM32F756xx by STM32F74xxx. Updated Section 2.1: ARM® Cortex®-M7 with FPU modifying STM32F756xx family by STM32F745xx and STM32F746xx devices. Removed Table 86. Ethernet DC electrical characteristics. Updated all the notes removing 'not tested in production'. Updated Table 43: Main PLL characteristics, Table 44: PLLI2S characteristics and Table 45: PLLISAI characteristics fVCO_OUT output at min value '100' and VCO freq at 100 MHz. Updated Table 13: STM32F745xx and STM32F746xx register boundary addresses replacing cortex-M4 by Cortex-M7. Updated Table 87: Dynamics characteristics: Ethernet MAC signals for MII td (TXEN) and td (TXD) min value at 6.5 ns.