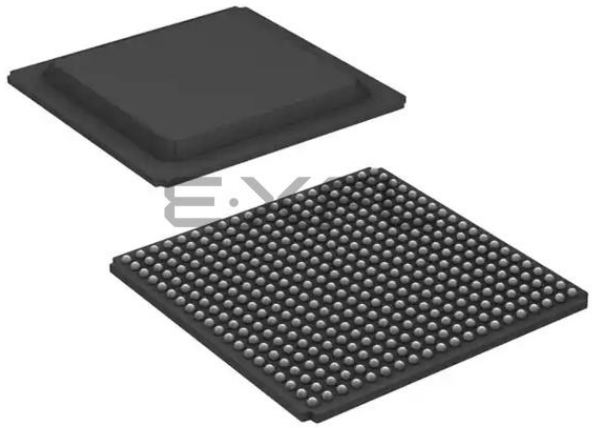


Welcome to E-XFL.COM

Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details	
Product Status	Active
Number of LABs/CLBs	8672
Number of Logic Elements/Cells	19512
Total RAM Bits	516096
Number of I/O	304
Number of Gates	1200000
Voltage - Supply	1.14V ~ 1.26V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 125°C (TJ)
Package / Case	400-BGA
Supplier Device Package	400-FBGA (21x21)
Purchase URL	https://www.e-xfl.com/product-detail/xilinx/xa3s1200e-4fgg400q

Key Feature Differences from Commercial XC Devices

- AEC-Q100 device qualification and full production part approval process (PPAP) documentation support available in both extended temperature I- and Q-Grades
- Guaranteed to meet full electrical specification over the T_J = –40°C to +125°C temperature range (Q-Grade)
- XA Spartan-3E devices are available in the -4 speed grade only.
- PCI-66 is not supported in the XA Spartan-3E FPGA product line.
- The readback feature is not supported in the XA Spartan-3E FPGA product line.
- XA Spartan-3E devices are available in Step 1 only.
- JTAG configuration frequency reduced from 30 MHz to 25 MHz.
- Platform Flash is not supported within the XA family.
- XA Spartan-3E devices are available in Pb-free packaging only.
- MultiBoot is not supported in XA versions of this product.
- The XA Spartan-3E device must be power cycled prior to reconfiguration.

Table 1: **Summary of XA Spartan-3E FPGA Attributes**

Device	System Gates	Equivalent Logic Cells	CLB Array (One CLB = Four Slices)				Distributed RAM bits(1)	Block RAM bits(1)	Dedicated Multipliers	DCMs	Maximum User I/O	Maximum Differential I/O Pairs
			Rows	Columns	Total CLBs	Total Slices						
XA3S100E	100K	2,160	22	16	240	960	15K	72K	4	2	108	40
XA3S250E	250K	5,508	34	26	612	2,448	38K	216K	12	4	172	68
XA3S500E	500K	10,476	46	34	1,164	4,656	73K	360K	20	4	190	77
XA3S1200E	1200K	19,512	60	46	2,168	8,672	136K	504K	28	8	304	124
XA3S1600E	1600K	33,192	76	58	3,688	14,752	231K	648K	36	8	376	156

Notes:

1. By convention, one Kb is equivalent to 1,024 bits.

Architectural Overview

The XA Spartan-3E family architecture consists of five fundamental programmable functional elements:

- **Configurable Logic Blocks (CLBs)** contain flexible Look-Up Tables (LUTs) that implement logic plus storage elements used as flip-flops or latches. CLBs perform a wide variety of logical functions as well as store data.
- **Input/Output Blocks (IOBs)** control the flow of data between the I/O pins and the internal logic of the device. Each IOB supports bidirectional data flow plus 3-state operation. Supports a variety of signal standards, including four high-performance differential standards. Double Data-Rate (DDR) registers are included.
- **Block RAM** provides data storage in the form of 18-Kbit dual-port blocks.
- **Multiplier Blocks** accept two 18-bit binary numbers as inputs and calculate the product.
- **Digital Clock Manager (DCM) Blocks** provide self-calibrating, fully digital solutions for distributing, delaying, multiplying, dividing, and phase-shifting clock signals.

These elements are organized as shown in Figure 1. A ring of IOBs surrounds a regular array of CLBs. Each device has two columns of block RAM except for the XA3S100E, which has one column. Each RAM column consists of several 18-Kbit RAM blocks. Each block RAM is associated with a dedicated multiplier. The DCMs are positioned in the center with two at the top and two at the bottom of the device. The XA3S100E has only one DCM at the top and bottom, while the XA3S1200E and XA3S1600E add two DCMs in the middle of the left and right sides.

The XA Spartan-3E family features a rich network of traces that interconnect all five functional elements, transmitting signals among them. Each functional element has an associated switch matrix that permits multiple connections to the routing.

Package Marking

Figure 2 provides a top marking example for XA Spartan-3E FPGAs in the quad-flat packages. Figure 3 shows the top marking for XA Spartan-3E FPGAs in BGA packages except the 132-ball chip-scale package (CPG132). The markings for the BGA packages are nearly identical to those for the quad-flat packages, except that the marking is rotated with respect to the ball A1 indicator. Figure 4 shows the top marking for XA Spartan-3E FPGAs in the CPG132 package.

Note: **No marking is shown for stepping.**

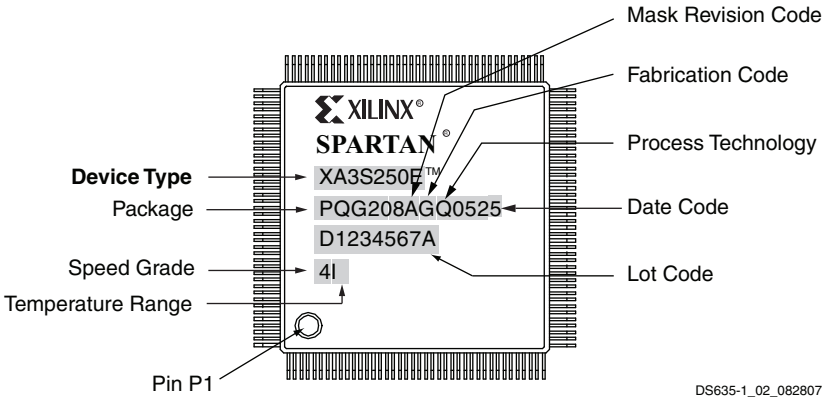


Figure 2: **XA Spartan-3E FPGA QFP Package Marking Example**

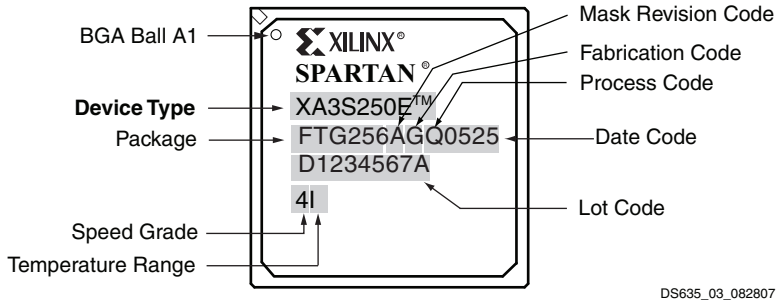


Figure 3: **XA Spartan-3E FPGA BGA Package Marking Example**

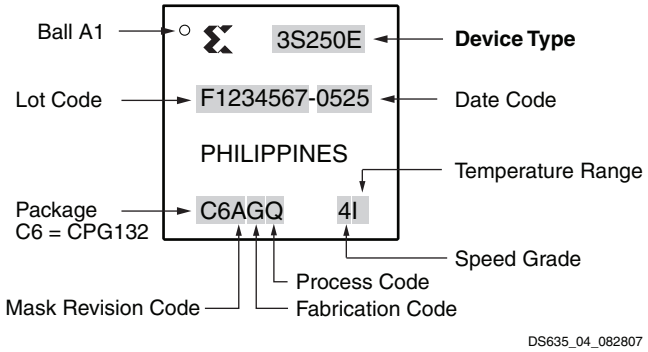
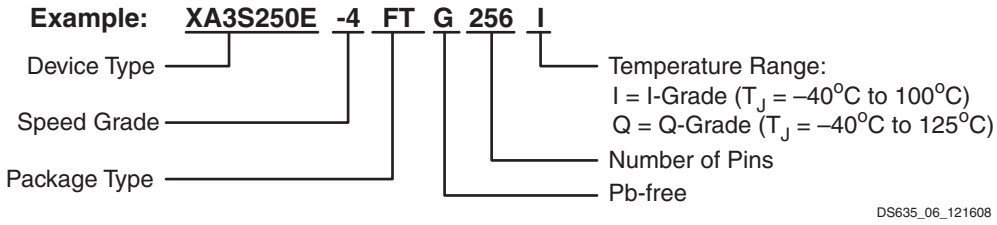


Figure 4: **XA Spartan-3E FPGA CPG132 Package Marking Example**

Ordering Information

XA Spartan-3E FPGAs are available in Pb-free packaging options for all device/package combinations. All devices are in Pb-free packages only, with a “G” character to the ordering code. All devices are available in either I-Grade or Q-Grade temperature ranges. Only the -4 speed grade is available for the XA Spartan-3E family. See Table 2 for valid device/package combinations.

Pb-Free Packaging



Device
XA3S100E
XA3S250E
XA3S500E
XA3S1200E
XA3S1600E

Speed Grade	
-4	Only

Package Type / Number of Pins	
VQG100	100-pin Very Thin Quad Flat Pack (VQFP)
CPG132	132-ball Chip-Scale Package (CSP)
TQG144	144-pin Thin Quad Flat Pack (TQFP)
PQG208	208-pin Plastic Quad Flat Pack (PQFP)
FTG256	256-ball Fine-Pitch Thin Ball Grid Array (FTBGA)
FGG400	400-ball Fine-Pitch Ball Grid Array (FBGA)
FGG484	484-ball Fine-Pitch Ball Grid Array (FBGA)

Temperature Range (T_J)	
I	I-Grade (–40°C to 100°C)
Q	Q-Grade (–40°C to 125°C)

DC Specifications

Table 6: **General Recommended Operating Conditions**

Symbol	Description		Min	Nominal	Max	Units
T_J	Junction temperature	I-Grade	–40	25	100	°C
		Q-Grade	–40	25	125	°C
V_{CCINT}	Internal supply voltage		1.140	1.200	1.260	V
V_{CCO}(1)	Output driver supply voltage		1.100	-	3.465	V
V_{CCAUX}	Auxiliary supply voltage		2.375	2.500	2.625	V
ΔV_{CCAUX}(2)	Voltage variance on V_{CCAUX} when using a DCM		-	-	10	mV/ms
V_{IN}(3,4,5,6)	Input voltage extremes to avoid turning on I/O protection diodes	I/O, Input-only, and Dual-Purpose pins(3)	–0.5	–	V_{CCO} + 0.5	V
		Dedicated pins(4)	–0.5	–	V_{CCAUX} + 0.5	V
T_{IN}	Input signal transition time(7)		–	–	500	ns

Notes:

1. This V_{CCO} range spans the lowest and highest operating voltages for all supported I/O standards. Table 9 lists the recommended V_{CCO} range specific to each of the single-ended I/O standards, and Table 11 lists that specific to the differential standards.
2. Only during DCM operation is it recommended that the rate of change of V_{CCAUX} not exceed 10 mV/ms.
3. Each of the User I/O and Dual-Purpose pins is associated with one of the four banks' V_{CCO} rails. Meeting the V_{IN} limit ensures that the internal diode junctions that exist between these pins and their associated V_{CCO} and GND rails do not turn on. See Absolute Maximum Ratings in DS312).
4. All Dedicated pins (PROG_B, DONE, TCK, TDI, TDO, and TMS) draw power from the V_{CCAUX} rail (2.5V). Meeting the V_{IN} max limit ensures that the internal diode junctions that exist between each of these pins and the V_{CCAUX} and GND rails do not turn on.
5. Input voltages outside the recommended range is permissible provided that the I_{IK} input clamp diode rating is met and no more than 100 pins exceed the range simultaneously. See Absolute Maximum Ratings in DS312).
6. See XAPP459, "Eliminating I/O Coupling Effects when Interfacing Large-Swing Single-Ended Signals to User I/O Pins."
7. Measured between 10% and 90% V_{CCO}. Follow Signal Integrity recommendations.

General DC Characteristics for I/O Pins

Table 7: **General DC Characteristics of User I/O, Dual-Purpose, and Dedicated Pins**

Symbol	Description	Test Conditions	Min	Typ	Max	Units
I_L	Leakage current at User I/O, Input-only, Dual-Purpose, and Dedicated pins	Driver is in a high-impedance state, V_{IN} = 0V or V_{CCO} max, sample-tested	–10	–	+10	µA
I_{RPU}(2)	Current through pull-up resistor at User I/O, Dual-Purpose, Input-only, and Dedicated pins	V_{IN} = 0V, V_{CCO} = 3.3V	–0.36	–	–1.24	mA
		V_{IN} = 0V, V_{CCO} = 2.5V	–0.22	–	–0.80	mA
		V_{IN} = 0V, V_{CCO} = 1.8V	–0.10	–	–0.42	mA
		V_{IN} = 0V, V_{CCO} = 1.5V	–0.06	–	–0.27	mA
		V_{IN} = 0V, V_{CCO} = 1.2V	–0.04	–	–0.22	mA
R_{PU}(2)	Equivalent pull-up resistor value at User I/O, Dual-Purpose, Input-only, and Dedicated pins (based on I_{RPU} per Note 2)	V_{IN} = 0V, V_{CCO} = 3.0V to 3.465V	2.4	–	10.8	kΩ
		V_{IN} = 0V, V_{CCO} = 2.3V to 2.7V	2.7	–	11.8	kΩ
		V_{IN} = 0V, V_{CCO} = 1.7V to 1.9V	4.3	–	20.2	kΩ
		V_{IN} = 0V, V_{CCO} =1.4V to 1.6V	5.0	–	25.9	kΩ
		V_{IN} = 0V, V_{CCO} = 1.14V to 1.26V	5.5	–	32.0	kΩ

Table 7: **General DC Characteristics of User I/O, Dual-Purpose, and Dedicated Pins *(Continued)***

Symbol	Description	Test Conditions	Min	Typ	Max	Units
I_{RPD}(2)	Current through pull-down resistor at User I/O, Dual-Purpose, Input-only, and Dedicated pins	$V_{IN} = V_{CCO}$	0.10	–	0.75	mA
R_{PD}(2)	Equivalent pull-down resistor value at User I/O, Dual-Purpose, Input-only, and Dedicated pins (based on I_{RPD} per Note 2)	$V_{IN} = V_{CCO}$ = 3.0V to 3.45V	4.0	–	34.5	kΩ
		$V_{IN} = V_{CCO}$ = 2.3V to 2.7V	3.0	–	27.0	kΩ
		$V_{IN} = V_{CCO}$ = 1.7V to 1.9V	2.3	–	19.0	kΩ
		$V_{IN} = V_{CCO}$ = 1.4V to 1.6V	1.8	–	16.0	kΩ
		$V_{IN} = V_{CCO}$ = 1.14V to 1.26V	1.5	–	12.6	kΩ
I_{REF}	V_{REF} current per pin	All V_{CCO} levels	–10	–	+10	µA
C_{IN}	Input capacitance	-	–	–	10	pF
R_{DT}	Resistance of optional differential termination circuit within a differential I/O pair. Not available on Input-only pairs.	V_{OCM} Min ≤ V_{ICM} ≤ V_{OCM} Max V_{OD} Min ≤ V_{ID} ≤ V_{OD} Max V_{CCO} = 2.5V	–	120	–	Ω

Notes:

1. The numbers in this table are based on the conditions set forth in Table 6.
2. This parameter is based on characterization. The pull-up resistance $R_{PU} = V_{CCO} / I_{RPU}$. The pull-down resistance $R_{PD} = V_{IN} / I_{RPD}$.

Table 8: **Quiescent Supply Current Characteristics**

Symbol	Description	Device	I-Grade Maximum	Q-Grade Maximum	Units
I_{CCINTQ}	Quiescent V_{CCINT} supply current	XA3S100E	36	58	mA
		XA3S250E	104	158	mA
		XA3S500E	145	300	mA
		XA3S1200E	324	500	mA
		XA3S1600E	457	750	mA
I_{CCOQ}	Quiescent V_{CCO} supply current	XA3S100E	1.5	2.0	mA
		XA3S250E	1.5	3.0	mA
		XA3S500E	1.5	3.0	mA
		XA3S1200E	2.5	4.0	mA
		XA3S1600E	2.5	4.0	mA

Table 8: **Quiescent Supply Current Characteristics *(Continued)***

Symbol	Description	Device	I-Grade Maximum	Q-Grade Maximum	Units
I_{CCAUXQ}	Quiescent V_{CCAUX} supply current	XA3S100E	13	22	mA
		XA3S250E	26	43	mA
		XA3S500E	34	63	mA
		XA3S1200E	59	100	mA
		XA3S1600E	86	150	mA

Notes:

1. The numbers in this table are based on the conditions set forth in Table 6.
2. Quiescent supply current is measured with all I/O drivers in a high-impedance state and with all pull-up/pull-down resistors at the I/O pads disabled. Typical values are characterized using typical devices at room temperature (T_J of 25°C at V_{CCINT} = 1.2 V, V_{CCO} = 3.3V, and V_{CCAUX} = 2.5V). The maximum limits are tested for each device at the respective maximum specified junction temperature and at maximum voltage limits with V_{CCINT} = 1.26V, V_{CCO} = 3.465V, and V_{CCAUX} = 2.625V. The FPGA is programmed with a "blank" configuration data file (i.e., a design with no functional elements instantiated). For conditions other than those described above, (e.g., a design including functional elements), measured quiescent current levels may be different than the values in the table. For more accurate estimates for a specific design, use the Xilinx XPower tools.
3. There are two recommended ways to estimate the total power consumption (quiescent plus dynamic) for a specific design: a) The Spartan-3E XPower Estimator provides quick, approximate, typical estimates, and does not require a netlist of the design. b) XPower Analyzer uses a netlist as input to provide maximum estimates as well as more accurate typical estimates.
4. The maximum numbers in this table indicate the minimum current each power rail requires in order for the FPGA to power-on successfully.

Single-Ended I/O Standards

Table 9: **Recommended Operating Conditions for User I/Os Using Single-Ended Standards**

IOSTANDARD Attribute	V_{CCO} for Drivers(2)			V_{REF}			V_{IL}	V_{IH}
	Min (V)	Nom (V)	Max (V)	Min (V)	Nom (V)	Max (V)	Max (V)	Min (V)
LVTTL	3.0	3.3	3.465	V_{REF} is not used for these I/O standards			0.8	2.0
LVCMOS33(4)	3.0	3.3	3.465				0.8	2.0
LVCMOS25(4,5)	2.3	2.5	2.7				0.7	1.7
LVCMOS18	1.65	1.8	1.95				0.4	0.8
LVCMOS15	1.4	1.5	1.6				0.4	0.8
LVCMOS12	1.1	1.2	1.3				0.4	0.7
PCI33_3	3.0	3.3	3.465				0.3 * V_{CCO}	0.5 * V_{CCO}
HSTL_I_18	1.7	1.8	1.9	0.8	0.9	1.1	V_{REF} - 0.1	V_{REF} + 0.1
HSTL_III_18	1.7	1.8	1.9	-	1.1	-	V_{REF} - 0.1	V_{REF} + 0.1
SSTL18_I	1.7	1.8	1.9	0.833	0.900	0.969	V_{REF} - 0.125	V_{REF} + 0.125
SSTL2_I	2.3	2.5	2.7	1.15	1.25	1.35	V_{REF} - 0.125	V_{REF} + 0.125

Notes:

1. Descriptions of the symbols used in this table are as follows:
   V_{CCO} – the supply voltage for output drivers
   V_{REF} – the reference voltage for setting the input switching threshold
   V_{IL} – the input voltage that indicates a Low logic level
   V_{IH} – the input voltage that indicates a High logic level
2. The V_{CCO} rails supply only output drivers, not input circuits.
3. For device operation, the maximum signal voltage (V_{IH} max) may be as high as V_{IN} max. See Table 72 in DS312.
4. There is approximately 100 mV of hysteresis on inputs using LVCMOS33 and LVCMOS25 I/O standards.
5. All Dedicated pins (PROG_B, DONE, TCK, TDI, TDO, and TMS) use the LVCMOS25 standard and draw power from the V_{CCAUX} rail (2.5V). The Dual-Purpose configuration pins use the LVCMOS standard before the User mode. When using these pins as part of a standard 2.5V configuration interface, apply 2.5V to the V_{CCO} lines of Banks 0, 1, and 2 at power-on as well as throughout configuration.
6. For information on PCI IP solutions, see www.xilinx.com/pci.

Differential I/O Standards

Table 11: **Recommended Operating Conditions for User I/Os Using Differential Signal Standards**

IOSTANDARD Attribute	V_{CCO} for Drivers(1)			V_{ID}			V_{ICM}		
	Min (V)	Nom (V)	Max (V)	Min (mV)	Nom (mV)	Max (mV)	Min (V)	Nom (V)	Max (V)
LVDS_25	2.375	2.50	2.625	100	350	600	0.30	1.25	2.20
BLVDS_25	2.375	2.50	2.625	100	350	600	0.30	1.25	2.20
MINI_LVDS_25	2.375	2.50	2.625	200	-	600	0.30	-	2.2
LVPECL_25(2)	Inputs Only			100	800	1000	0.5	1.2	2.0
RSDS_25	2.375	2.50	2.625	100	200	-	0.3	1.20	1.4
DIFF_HSTL_I_18	1.7	1.8	1.9	100	-	-	0.8	-	1.1
DIFF_HSTL_III_18	1.7	1.8	1.9	100	-	-	0.8	-	1.1
DIFF_SSTL18_I	1.7	1.8	1.9	100	-	-	0.7	-	1.1
DIFF_SSTL2_I	2.3	2.5	2.7	100	-	-	1.0	-	1.5

Notes:

1. The V_{CCO} rails supply only differential output drivers, not input circuits.
2. V_{REF} inputs are not used for any of the differential I/O standards.

Table 12: **DC Characteristics of User I/Os Using Differential Signal Standards**

IOSTANDARD Attribute	V_{OD}			ΔV_{OD}		V_{OCM}			ΔV_{OCM}		V_{OH}	V_{OL}
	Min (mV)	Typ (mV)	Max (mV)	Min (mV)	Max (mV)	Min (V)	Typ (V)	Max (V)	Min (mV)	Max (mV)	Min (V)	Max (V)
LVDS_25	250	350	450	–	–	1.125	–	1.375	–	–	–	–
BLVDS_25	250	350	450	–	–	–	1.20	–	–	–	–	–
MINI_LVDS_25	300	–	600	–	50	1.0	–	1.4	–	50	–	–
RSDS_25	100	–	400	–	–	1.1	–	1.4	–	–	–	–
DIFF_HSTL_I_18	–	–	–	–	–	–	–	–	–	–	V_{CCO} – 0.4	0.4
DIFF_HSTL_III_18	–	–	–	–	–	–	–	–	–	–	V_{CCO} – 0.4	0.4
DIFF_SSTL18_I	–	–	–	–	–	–	–	–	–	–	V_{TT} + 0.475	V_{TT} – 0.475
DIFF_SSTL2_I	–	–	–	–	–	–	–	–	–	–	V_{TT} + 0.61	V_{TT} – 0.61

Notes:

1. The numbers in this table are based on the conditions set forth in Table 6, and Table 11.
2. Output voltage measurements for all differential standards are made with a termination resistor (R_T) of 100Ω across the N and P pins of the differential signal pair. The exception is for BLVDS, shown in Figure 5 below.
3. At any given time, no more than two of the following differential output standards may be assigned to an I/O bank: LVDS_25, RSDS_25, MINI_LVDS_25

Table 14: **Pin-to-Pin Setup and Hold Times for the IOB Input Path (System Synchronous)**

Symbol	Description	Conditions	IFD_DELAY_VALUE=	Device	-4 Speed Grade	Units
					Min	
Setup Times						
T_{PSDCM}	When writing to the Input Flip-Flop (IFF), the time from the setup of data at the Input pin to the active transition at a Global Clock pin. The DCM is used. No Input Delay is programmed.	LVCMOS25(2), IFD_DELAY_VALUE = 0, with DCM(4)	0	**XA3S100E**	2.98	ns
				XA3S250E	2.59	ns
				XA3S500E	2.59	ns
				XA3S1200E	2.58	ns
				XA3S1600E	2.59	ns
T_{PSFD}	When writing to IFF, the time from the setup of data at the Input pin to an active transition at the Global Clock pin. The DCM is not used. The Input Delay is programmed.	LVCMOS25(2), IFD_DELAY_VALUE = default software setting	2	**XA3S100E**	3.58	ns
			3	**XA3S250E**	3.91	ns
			2	**XA3S500E**	4.02	ns
			5	**XA3S1200E**	5.52	ns
			4	**XA3S1600E**	4.46	ns
Hold Times						
T_{PHDCM}	When writing to IFF, the time from the active transition at the Global Clock pin to the point when data must be held at the Input pin. The DCM is used. No Input Delay is programmed.	LVCMOS25(3), IFD_DELAY_VALUE = 0, with DCM(4)	0	**XA3S100E**	–0.52	ns
				XA3S250E	0.14	ns
				XA3S500E	0.14	ns
				XA3S1200E	0.15	ns
				XA3S1600E	0.14	ns
T_{PHFD}	When writing to IFF, the time from the active transition at the Global Clock pin to the point when data must be held at the Input pin. The DCM is not used. The Input Delay is programmed.	LVCMOS25(3), IFD_DELAY_VALUE = default software setting	2	**XA3S100E**	–0.24	ns
			3	**XA3S250E**	–0.32	ns
			2	**XA3S500E**	–0.49	ns
			5	**XA3S1200E**	–0.63	ns
			4	**XA3S1600E**	–0.39	ns

Notes:

1. The numbers in this table are tested using the methodology presented in Table 19 and are based on the operating conditions set forth in Table 6 and Table 9.
2. This setup time requires adjustment whenever a signal standard other than LVCMOS25 is assigned to the Global Clock Input or the data Input. If this is true of the Global Clock Input, subtract the appropriate adjustment from Table 17. If this is true of the data Input, add the appropriate Input adjustment from the same table.
3. This hold time requires adjustment whenever a signal standard other than LVCMOS25 is assigned to the Global Clock Input or the data Input. If this is true of the Global Clock Input, add the appropriate Input adjustment from Table 17. If this is true of the data Input, subtract the appropriate Input adjustment from the same table. When the hold time is negative, it is possible to change the data before the clock's active edge.
4. DCM output jitter is included in all measurements.

Table 18: **Output Timing Adjustments for IOB**

Convert Output Time from LVCMOS25 with 12mA Drive and Fast Slew Rate to the Following Signal Standard (IOSTANDARD)			Add the Adjustment Below: -4 Speed Grade	Units
Single-Ended Standards				
LVTTL	Slow	2 mA	5.41	ns
		4 mA	2.41	ns
		6 mA	1.90	ns
		8 mA	0.67	ns
		12 mA	0.70	ns
		16 mA	0.43	ns
	Fast	2 mA	5.00	ns
		4 mA	1.96	ns
		6 mA	1.45	ns
		8 mA	0.34	ns
		12 mA	0.30	ns
		16 mA	0.30	ns
LVCMOS33	Slow	2 mA	5.29	ns
		4 mA	1.89	ns
		6 mA	1.04	ns
		8 mA	0.69	ns
		12 mA	0.42	ns
		16 mA	0.43	ns
	Fast	2 mA	4.87	ns
		4 mA	1.52	ns
		6 mA	0.39	ns
		8 mA	0.34	ns
		12 mA	0.30	ns
		16 mA	0.30	ns
LVCMOS25	Slow	2 mA	4.21	ns
		4 mA	2.26	ns
		6 mA	1.52	ns
		8 mA	1.08	ns
		12 mA	0.68	ns
	Fast	2 mA	3.67	ns
		4 mA	1.72	ns
		6 mA	0.46	ns
		8 mA	0.21	ns
		12 mA	0	ns

Table 18: **Output Timing Adjustments for IOB *(Continued)***

Convert Output Time from LVCMOS25 with 12mA Drive and Fast Slew Rate to the Following Signal Standard (IOSTANDARD)			Add the Adjustment Below: -4 Speed Grade	Units
LVCMOS18	Slow	2 mA	5.24	ns
		4 mA	3.21	ns
		6 mA	2.49	ns
		8 mA	1.90	ns
	Fast	2 mA	4.15	ns
		4 mA	2.13	ns
		6 mA	1.14	ns
		8 mA	0.75	ns
LVCMOS15	Slow	2 mA	4.68	ns
		4 mA	3.97	ns
		6 mA	3.11	ns
	Fast	2 mA	3.38	ns
		4 mA	2.70	ns
		6 mA	1.53	ns
LVCMOS12	Slow	2 mA	6.63	ns
	Fast	2 mA	4.44	ns
HSTL_I_18			0.34	ns
HSTL_III_18			0.55	ns
PCI33_3			0.46	ns
SSTL18_I			0.25	ns
SSTL2_I			–0.20	ns
Differential Standards				
LVDS_25			–0.55	ns
BLVDS_25			0.04	ns
MINI_LVDS_25			–0.56	ns
LVPECL_25			Input Only	ns
RSDS_25			–0.48	ns
DIFF_HSTL_I_18			0.42	ns
DIFF_HSTL_III_18			0.55	ns
DIFF_SSTL18_I			0.40	ns
DIFF_SSTL2_I			0.44	ns

Notes:

1. The numbers in this table are tested using the methodology presented in Table 19 and are based on the operating conditions set forth in Table 6, Table 9, and Table 11.
2. These adjustments are used to convert output- and three-state-path times originally specified for the LVCMOS25 standard with 12 mA drive and Fast slew rate to times that correspond to other signal standards. Do not adjust times that measure when outputs go into a high-impedance state.

Configurable Logic Block Timing

Table 20: **CLB (SLICEM) Timing**

Symbol	Description	-4 Speed Grade		Units
		Min	Max	
Clock-to-Output Times				
T_{CKO}	When reading from the FFX (FFY) Flip-Flop, the time from the active transition at the CLK input to data appearing at the XQ (YQ) output	-	0.60	ns
Setup Times				
T_{AS}	Time from the setup of data at the F or G input to the active transition at the CLK input of the CLB	0.52	-	ns
T_{DICK}	Time from the setup of data at the BX or BY input to the active transition at the CLK input of the CLB	1.81	-	ns
Hold Times				
T_{AH}	Time from the active transition at the CLK input to the point where data is last held at the F or G input	0	-	ns
T_{CKDI}	Time from the active transition at the CLK input to the point where data is last held at the BX or BY input	0	-	ns
Clock Timing				
T_{CH}	The High pulse width of the CLB's CLK signal	0.80	-	ns
T_{CL}	The Low pulse width of the CLK signal	0.80	-	ns
F_{TOG}	Toggle frequency (for export control)	0	572	MHz
Propagation Times				
T_{ILO}	The time it takes for data to travel from the CLB's F (G) input to the X (Y) output	-	0.76	ns
Set/Reset Pulse Width				
T_{RPW_CLB}	The minimum allowable pulse width, High or Low, to the CLB's SR input	1.80	-	ns

Notes:

1. The numbers in this table are based on the operating conditions set forth in Table 6.

Clock Buffer/Multiplexer Switching Characteristics

Table 23: **Clock Distribution Switching Characteristics**

Description	Symbol	Maximum	Units
		-4 Speed Grade	
Global clock buffer (BUFG, BUFGMUX, BUFGCE) I input to O-output delay	T_{GIO}	1.46	ns
Global clock multiplexer (BUFGMUX) select S-input setup to I0 and I1 inputs. Same as BUFGCE enable CE-input	T_{GSI}	0.63	ns
Frequency of signals distributed on global buffers (all sides)	F_{BUFG}	311	MHz

18 x 18 Embedded Multiplier Timing

Table 24: **18 x 18 Embedded Multiplier Timing**

Symbol	Description	-4 Speed Grade		Units
		Min	Max	
Combinatorial Delay				
T_{MULT}	Combinatorial multiplier propagation delay from the A and B inputs to the P outputs, assuming 18-bit inputs and a 36-bit product (AREG, BREG, and PREG registers unused)	-	4.88(1)	ns
Clock-to-Output Times				
T_{MSCKP_P}	Clock-to-output delay from the active transition of the CLK input to valid data appearing on the P outputs when using the PREG register(2)	-	1.10	ns
T_{MSCKP_A} T_{MSCKP_B}	Clock-to-output delay from the active transition of the CLK input to valid data appearing on the P outputs when using either the AREG or BREG register(3)	-	4.97	ns
Setup Times				
T_{MSDCK_P}	Data setup time at the A or B input before the active transition at the CLK when using only the PREG output register (AREG, BREG registers unused)(2)	3.98	-	ns
T_{MSDCK_A}	Data setup time at the A input before the active transition at the CLK when using the AREG input register(3)	0.23	-	ns
T_{MSDCK_B}	Data setup time at the B input before the active transition at the CLK when using the BREG input register(3)	0.39	-	ns
Hold Times				
T_{MSCKD_P}	Data hold time at the A or B input before the active transition at the CLK when using only the PREG output register (AREG, BREG registers unused)(2)	-0.97		
T_{MSCKD_A}	Data hold time at the A input before the active transition at the CLK when using the AREG input register(3)	0.04		
T_{MSCKD_B}	Data hold time at the B input before the active transition at the CLK when using the BREG input register(3)	0.05		

Table 24: **18 x 18 Embedded Multiplier Timing *(Continued)***

Symbol	Description	-4 Speed Grade		Units
		Min	Max	
Clock Frequency				
F_{MULT}	Internal operating frequency for a two-stage 18x18 multiplier using the AREG and BREG input registers and the PREG output register(1)	0	240	MHz

Notes:

1. Combinatorial delay is less and pipelined performance is higher when multiplying input data with less than 18 bits.
2. The PREG register is typically used in both single-stage and two-stage pipelined multiplier implementations.
3. Input registers AREG or BREG are typically used when inferring a two-stage multiplier.

Block RAM Timing

Table 25: **Block RAM Timing**

Symbol	Description	-4 Speed Grade		Units
		Min	Max	
Clock-to-Output Times				
T_{BCKO}	When reading from block RAM, the delay from the active transition at the CLK input to data appearing at the DOUT output	-	2.82	ns
Setup Times				
T_{BACK}	Setup time for the ADDR inputs before the active transition at the CLK input of the block RAM	0.38	-	ns
T_{BDCK}	Setup time for data at the DIN inputs before the active transition at the CLK input of the block RAM	0.23	-	ns
T_{BECK}	Setup time for the EN input before the active transition at the CLK input of the block RAM	0.77	-	ns
T_{BWCK}	Setup time for the WE input before the active transition at the CLK input of the block RAM	1.26	-	ns
Hold Times				
T_{BCKA}	Hold time on the ADDR inputs after the active transition at the CLK input	0.14	-	ns
T_{BCKD}	Hold time on the DIN inputs after the active transition at the CLK input	0.13	-	ns
T_{BCKE}	Hold time on the EN input after the active transition at the CLK input	0	-	ns
T_{BCKW}	Hold time on the WE input after the active transition at the CLK input	0	-	ns

Table 25: **Block RAM Timing *(Continued)***

Symbol	Description	-4 Speed Grade		Units
		Min	Max	
Clock Timing				
T_{BPWH}	High pulse width of the CLK signal	1.59	-	ns
T_{BPWL}	Low pulse width of the CLK signal	1.59	-	ns
Clock Frequency				
F_{BRAM}	Block RAM clock frequency. RAM read output value written back into RAM, for shift registers and circular buffers. Write-only or read-only performance is faster.	0	230	MHz

Notes:

1. The numbers in this table are based on the operating conditions set forth in Table 6.

Digital Clock Manager Timing

For specification purposes, the DCM consists of three key components: the Delay-Locked Loop (DLL), the Digital Frequency Synthesizer (DFS), and the Phase Shifter (PS).

Aspects of DLL operation play a role in all DCM applications. All such applications inevitably use the CLKIN and the CLKFB inputs connected to either the CLK0 or the CLK2X feedback, respectively. Thus, specifications in the DLL tables (Table 26 and Table 27) apply to any application that only employs the DLL component. When the DFS and/or the PS components are used together with the DLL, then the specifications listed in the DFS and PS tables (Table 28 through Table 31) supersede any corresponding ones in the DLL tables. DLL specifications that do not change with the addition of DFS or PS functions are presented in Table 26 and Table 27.

Period jitter and cycle-cycle jitter are two of many different ways of specifying clock jitter. Both specifications describe statistical variation from a mean value.

Period jitter is the worst-case deviation from the ideal clock period over a collection of millions of samples. In a histogram of period jitter, the mean value is the clock period.

Cycle-cycle jitter is the worst-case difference in clock period between adjacent clock cycles in the collection of clock periods sampled. In a histogram of cycle-cycle jitter, the mean value is zero.

Spread Spectrum

DCMs accept typical spread spectrum clocks as long as they meet the input requirements. The DLL will track the frequency changes created by the spread spectrum clock to drive the global clocks to the FPGA logic. See XAPP469, *Spread-Spectrum Clocking Reception for Displays* for details.

Table 29: **Switching Characteristics for the DFS**

Symbol	Description		Device	-4 Speed Grade		Units
				Min	Max	
Output Frequency Ranges						
CLKOUT_FREQ_FX	Frequency for the CLKFX and CLKFX180 outputs		All	5	311	MHz
Output Clock Jitter(2,3)						
CLKOUT_PER_JITT_FX	Period jitter at the CLKFX and CLKFX180 outputs		All	**Typ**	**Max**	
		CLKIN ≤20 MHz		See Note 4		ps
		CLKIN > 20 MHz		±[1% of CLKFX period + 100]	±[1% of CLKFX period + 200]	ps
Duty Cycle(5,6)						
CLKOUT_DUTY_CYCLE_FX	Duty cycle precision for the CLKFX and CLKFX180 outputs, including the BUFGMUX and clock tree duty-cycle distortion		All	-	±[1% of CLKFX period + 400]	ps
Phase Alignment(6)						
CLKOUT_PHASE_FX	Phase offset between the DFS CLKFX output and the DLL CLK0 output when both the DFS and DLL are used		All	-	±200	ps
CLKOUT_PHASE_FX180	Phase offset between the DFS CLKFX180 output and the DLL CLK0 output when both the DFS and DLL are used		All	-	±[1% of CLKFX period + 300]	ps
Lock Time						
LOCK_FX(2)	The time from deassertion at the DCM's Reset input to the rising transition at its LOCKED output. The DFS asserts LOCKED when the CLKFX and CLKFX180 signals are valid. If using both the DLL and the DFS, use the longer locking time.	5 MHz ≤ F_{CLKIN} ≤ 15 MHz	All	-	5	ms
		F_{CLKIN} > 15 MHz		-	450	µs

Notes:
1. The numbers in this table are based on the operating conditions set forth in Table 6 and Table 28.
2. For optimal jitter tolerance and faster lock time, use the CLKIN_PERIOD attribute.
3. Maximum output jitter is characterized within a reasonable noise environment (150 ps input period jitter, 40 SSOs and 25% CLB switching). Output jitter strongly depends on the environment, including the number of SSOs, the output drive strength, CLB utilization, CLB switching activities, switching frequency, power supply and PCB design. The actual maximum output jitter depends on the system application.
4. Use the Spartan-3A Jitter Calculator (www.xilinx.com/support/documentation/data_sheets/s3a_jitter_calc.zip) to estimate DFS output jitter. Use the Clocking Wizard to determine jitter for a specific design.
5. The CLKFX and CLKFX180 outputs always have an approximate 50% duty cycle.
6. Some duty-cycle and alignment specifications include 1% of the CLKFX output period or 0.01 UI. ***Example:*** The data sheet specifies a maximum jitter of "±[1% of CLKFX period + 300]". Assume the CLKFX output frequency is 100 MHz. The equivalent CLKFX period is 10 ns and 1% of 10 ns is 0.1 ns or 100 ps. According to the data sheet, the maximum jitter is ±[100 ps + 300 ps] = ±400 ps.

Phase Shifter

Table 30: **Recommended Operating Conditions for the PS in Variable Phase Mode**

Symbol	Description	-4 Speed Grade		Units
		Min	Max	
Operating Frequency Ranges				
PSCLK_FREQ (F_{PSCLK})	Frequency for the PSCLK input	1	167	MHz
Input Pulse Requirements				
PSCLK_PULSE	PSCLK pulse width as a percentage of the PSCLK period	40%	60%	-

Table 31: **Switching Characteristics for the PS in Variable Phase Mode**

Symbol	Description			Units
Phase Shifting Range				
MAX_STEPS(2)	Maximum allowed number of DCM_DELAY_STEP steps for a given CLKIN clock period, where T = CLKIN clock period in ns. If using CLKIN_DIVIDE_BY_2 = TRUE, double the clock effective clock period.	CLKIN < 60 MHz	±[INTEGER(10 • (T_{CLKIN} – 3 ns))]	steps
		CLKIN ≥ 60 MHz	±[INTEGER(15 • (T_{CLKIN} – 3 ns))]	steps
FINE_SHIFT_RANGE_MIN	Minimum guaranteed delay for variable phase shifting	±[MAX_STEPS • DCM_DELAY_STEP_MIN]		ns
FINE_SHIFT_RANGE_MAX	Maximum guaranteed delay for variable phase shifting	±[MAX_STEPS • DCM_DELAY_STEP_MAX]		ns

Notes:
1. The numbers in this table are based on the operating conditions set forth in Table 6 and Table 30.
2. The maximum variable phase shift range, MAX_STEPS, is only valid when the DCM is has no initial fixed phase shifting, i.e., the PHASE_SHIFT attribute is set to 0.
3. The DCM_DELAY_STEP values are provided at the bottom of Table 27.

Miscellaneous DCM Timing

Table 32: **Miscellaneous DCM Timing**

Symbol	Description	Min	Max	Units
DCM_RST_PW_MIN(1)	Minimum duration of a RST pulse width	3	-	CLKIN cycles
DCM_RST_PW_MAX(2)	Maximum duration of a RST pulse width	N/A	N/A	seconds
		N/A	N/A	seconds
DCM_CONFIG_LAG_TIME(3)	Maximum duration from V_{CCINT} applied to FPGA configuration successfully completed (DONE pin goes High) and clocks applied to DCM DLL	N/A	N/A	minutes
		N/A	N/A	minutes

Notes:
1. This limit only applies to applications that use the DCM DLL outputs (CLK0, CLK90, CLK180, CLK270, CLK2X, CLK2X180, and CLKDV). The DCM DFS outputs (CLKFX, CLKFX180) are unaffected.
2. This specification is equivalent to the Virtex-4 DCM_RESET specification. This specification does not apply for Spartan-3E FPGAs.
3. This specification is equivalent to the Virtex-4 TCONFIG specification. This specification does not apply for Spartan-3E FPGAs.

Master Serial and Slave Serial Mode Timing

Table 38: **Timing for the Master Serial and Slave Serial Configuration Modes**

Symbol	Description		Slave/ Master	-4 Speed Grade		Units
				Min	Max	
Clock-to-Output Times						
T_{CCO}	The time from the falling transition on the CCLK pin to data appearing at the DOUT pin		Both	1.5	10.0	ns
Setup Times						
T_{DCC}	The time from the setup of data at the DIN pin to the active edge of the CCLK pin		Both	11.0	-	ns
Hold Times						
T_{CCD}	The time from the active edge of the CCLK pin to the point when data is last held at the DIN pin		Both	0	-	ns
Clock Timing						
T_{CCH}	High pulse width at the CCLK input pin		Master	See Table 36		
			Slave	See Table 37		
T_{CCL}	Low pulse width at the CCLK input pin		Master	See Table 36		
			Slave	See Table 37		
F_{CCSER}	Frequency of the clock signal at the CCLK input pin	No bitstream compression	Slave	0	66(2)	MHz
		With bitstream compression		0	20	MHz

Notes:

1. The numbers in this table are based on the operating conditions set forth in Table 6.
2. For serial configuration with a daisy-chain of multiple FPGAs, the maximum limit is 25 MHz.

IEEE 1149.1/1553 JTAG Test Access Port Timing

Table 44: **Timing for the JTAG Test Access Port**

Symbol	Description	-4 Speed Grade		Units
		Min	Max	
Clock-to-Output Times				
T_{TCKTDO}	The time from the falling transition on the TCK pin to data appearing at the TDO pin	1.0	11.0	ns
Setup Times				
T_{TDITCK}	The time from the setup of data at the TDI pin to the rising transition at the TCK pin	7.0	-	ns
T_{TMSTCK}	The time from the setup of a logic level at the TMS pin to the rising transition at the TCK pin	7.0	-	ns
Hold Times				
T_{TCKTDI}	The time from the rising transition at the TCK pin to the point when data is last held at the TDI pin	0	-	ns
T_{TCKTMS}	The time from the rising transition at the TCK pin to the point when a logic level is last held at the TMS pin	0	-	ns
Clock Timing				
T_{CCH}	The High pulse width at the TCK pin	5	-	ns
T_{CCL}	The Low pulse width at the TCK pin	5	-	ns
F_{TCK}	Frequency of the TCK signal	-	25	MHz

Notes:

1. The numbers in this table are based on the operating conditions set forth in Table 6.

Revision History

The following table shows the revision history for this document.

Date	Version	Revision
08/31/07	1.0	Initial Xilinx release.
01/20/09	1.1	• Updated "Key Feature Differences from Commercial XC Devices." • Updated T_{ACC} requirement in Table 43. • Updated description of T_{DCC} and T_{CCD} in Table 42. • Removed Table 45: MultiBoot Trigger Timing.
09/09/09	2.0	• Added package sizes to Table 2, page 4. • Removed Genealogy Viewer Link from "Package Marking," page 5. • Updated data and notes for Table 6, page 8. • Updated test conditions for R_{PU} and maximum value for C_{IN} in Table 7, page 8. • Updated notes for Table 8, page 9. • Updated Max V_{CCO} for LVTTL and LVCMOS33, removed PCIX data, updated V_{IL} Max for LVCMOS18, LVCMOS15, and LVCMOS12, updated V_{IH} Min for LVCMOS12, and added note 6 in Table 9, page 11. • Removed PCIX data, revised note 2, and added note 4 in Table 10, page 12. • Updated figure description of Figure 5, page 14. • Added note 4 to Table 13, page 14. • Removed PC166_3 and PCIX adjustment values from Table 17, page 17. • Deleted Table 18 (duplicate of Table 17, page 17). Subsequent tables renumbered. • Removed PCIX data Table 18, page 18. • Removed PCIX data and removed V_{REF} values for DIFF_HSTL_I_18, DIFF_HSTL_III_18, DIFF_SSTL18_I, and DIFF_SSTL2_I from Table 19, page 19. • Updated T_{DICK} minimum setup time in Table 20, page 20. • Updated notes, references to notes, and revised the maximum clock-to-output times for T_{MSCKP_P} Table 24, page 22. • Added "Spread Spectrum," page 24. • Updated note 3 in Table 26, page 25. • Added note 4 Table 28, page 26. • Updated notes, references to notes, and CLKOUT_PER_JITT_FX data in Table 29, page 27. • Updated MAX_STEPS data in Table 31, page 28. • Updated ConfigRate Setting for T_{CCLK1} to indicate 1 is the default value in Table 34, page 30. • Updated ConfigRate Setting for F_{CCLK1} to indicate 1 is the default value in Table 35, page 30.

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