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# **Understanding Embedded - CPLDs (Complex Programmable Logic Devices)**

Embedded - CPLDs, or Complex Programmable Logic Devices, are highly versatile digital logic devices used in electronic systems. These programmable components are designed to perform complex logical operations and can be customized for specific applications. Unlike fixed-function ICs, CPLDs offer the flexibility to reprogram their configuration, making them an ideal choice for various embedded systems. They consist of a set of logic gates and programmable interconnects, allowing designers to implement complex logic circuits without needing custom hardware.

# **Applications of Embedded - CPLDs**

Obsolete
In System Programmable
10 ns
4.75V ~ 5.25V
35
560
12000
216
0°C ~ 70°C (TA)
Surface Mount
356-LBGA
356-BGA (35x35)
https://www.e-xfl.com/product-detail/intel/epm9560abc356-10

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# General Description

The MAX 9000 family of in-system-programmable, high-density, high-performance EPLDs is based on Altera's third-generation MAX architecture. Fabricated on an advanced CMOS technology, the EEPROM-based MAX 9000 family provides 6,000 to 12,000 usable gates, pin-to-pin delays as fast as 10 ns, and counter speeds of up to 144 MHz. The -10 speed grade of the MAX 9000 family is compliant with the *PCI Local Bus Specification, Revision 2.2.* Table 3 shows the speed grades available for MAX 9000 devices.

Table 3. MAX 9000 Speed Grade Availability						
Device		Speed Grade				
	-10	-15	-20			
EPM9320		✓	✓			
EPM9320A	✓					
EPM9400		✓	✓			
EPM9480		✓	✓			
EPM9560		✓	✓			
EPM9560A	✓					

Table 4 shows the performance of MAX 9000 devices for typical functions.

Table 4. MAX 9000 Performance Note (1)						
Application	Macrocells Used	Macrocells Used Speed Grade I				
		-10	-15	-20		
16-bit loadable counter	16	144	118	100	MHz	
16-bit up/down counter	16	144	118	100	MHz	
16-bit prescaled counter	16	144	118	100	MHz	
16-bit address decode	1	5.6 (10)	7.9 (15)	10 (20)	ns	
16-to-1 multiplexer	1	7.7 (12.1)	10.9 (18)	16 (26)	ns	

#### Note:

(1) Internal logic array block (LAB) performance is shown. Numbers in parentheses show external delays from row input pin to row I/O pin.

The MAX 9000 architecture supports high-density integration of system-level logic functions. It easily integrates multiple programmable logic devices ranging from PALs, GALs, and 22V10s to field-programmable gate array (FPGA) devices and EPLDs.

The MAX 9000 family is supported by Altera's MAX+PLUS II development system, a single, integrated software package that offers schematic, text—including VHDL, Verilog HDL, and the Altera Hardware Description Language (AHDL)—and waveform design entry, compilation and logic synthesis, simulation and timing analysis, and device programming. The MAX+PLUS II software provides EDIF 2 0 0 and 3 0 0, LPM, and other interfaces for additional design entry and simulation support from other industry-standard PC- and UNIX-workstation-based EDA tools. The MAX+PLUS II software runs on Windows-based PCs as well as Sun SPARCstation, HP 9000 Series 700/800, and IBM RISC System/6000 workstations.



For more information on development tools, see the MAX+PLUS II Programmable Logic Development System & Software Data Sheet.

# Functional Description

MAX 9000 devices use a third-generation MAX architecture that yields both high performance and a high degree of utilization for most applications. The MAX 9000 architecture includes the following elements:

- Logic array blocks
- Macrocells
- Expander product terms (shareable and parallel)
- FastTrack Interconnect
- Dedicated inputs
- I/O cells

Figure 1 shows a block diagram of the MAX 9000 architecture.

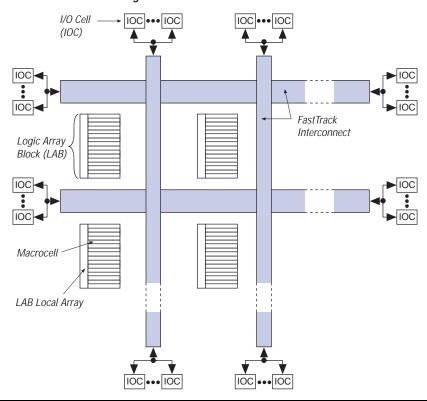


Figure 1. MAX 9000 Device Block Diagram

# Logic Array Blocks

The MAX 9000 architecture is based on linking high-performance, flexible logic array modules called logic array blocks (LABs). LABs consist of 16-macrocell arrays that are fed by the LAB local array, as shown in Figure 2 on page 7. Multiple LABs are linked together via the FastTrack Interconnect, a series of fast, continuous channels that run the entire length and width of the device. The I/O pins are supported by I/O cells (IOCs) located at the end of each row (horizontal) and column (vertical) path of the FastTrack Interconnect.

Each LAB is fed by 33 inputs from the row interconnect and 16 feedback signals from the macrocells within the LAB. All of these signals are available within the LAB in their true and inverted form. In addition, 16 shared expander product terms ("expanders") are available in their inverted form, for a total of 114 signals that feed each product term in the LAB. Each LAB is also fed by two low-skew global clocks and one global clear that can be used for register control signals in all 16 macrocells.

#### Macrocells

The MAX 9000 macrocell consists of three functional blocks: the product terms, the product-term select matrix, and the programmable register. The macrocell can be individually configured for both sequential and combinatorial logic operation. See Figure 3.

LAB Local Array Global Global 33 Row Clear Clocks FastTrack Parallel Interconnect 2 Expanders Inputs Macrocell Register Programmable (from Other Input Select Bypass Register Macrocells) To Row or Column FastTrack Clock/ Interconnect Product-(11) Enable ENA Select Select Matrix Clear Select 1 Local Array Feedback 16 Local 16 Shareable Feedbacks Expander Product

Figure 3. MAX 9000 Macrocell & Local Array

Combinatorial logic is implemented in the local array, which provides five product terms per macrocell. The product-term select matrix allocates these product terms for use as either primary logic inputs (to the OR and XOR gates) to implement combinatorial functions, or as secondary inputs to the macrocell's register clear, preset, clock, and clock enable control functions. Two kinds of expander product terms ("expanders") are available to supplement macrocell logic resources:

- Shareable expanders, which are inverted product terms that are fed back into the logic array
- Parallel expanders, which are product terms borrowed from adjacent macrocells

The MAX+PLUS II software automatically optimizes product-term allocation according to the logic requirements of the design.

# **Expander Product Terms**

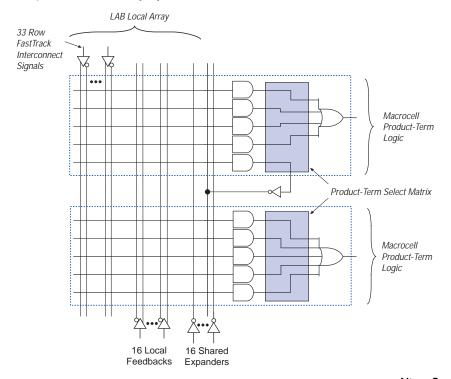
Although most logic functions can be implemented with the five product terms available in each macrocell, some logic functions are more complex and require additional product terms. Although another macrocell can supply the required logic resources, the MAX 9000 architecture also offers both shareable and parallel expander product terms that provide additional product terms directly to any macrocell in the same LAB. These expanders help ensure that logic is synthesized with the fewest possible logic resources to obtain the fastest possible speed.

### Shareable Expanders

Each LAB has 16 shareable expanders that can be viewed as a pool of uncommitted single product terms (one from each macrocell) with inverted outputs that feed back into the LAB local array. Each shareable expander can be used and shared by any or all macrocells in the LAB to build complex logic functions. A small delay ( $t_{LOCAL} + t_{SEXP}$ ) is incurred when shareable expanders are used. Figure 4 shows how shareable expanders can feed multiple macrocells.

Figure 4. MAX 9000 Shareable Expanders

Shareable expanders can be shared by any or all macrocells in the LAB.



The MAX+PLUS II Compiler automatically allocates as many as three sets of up to five parallel expanders to macrocells that require additional product terms. Each set of expanders incurs a small, incremental timing delay ( $t_{PEXP}$ ). For example, if a macrocell requires 14 product terms, the Compiler uses the five dedicated product terms within the macrocell and allocates two sets of parallel expanders; the first set includes five product terms and the second set includes four product terms, increasing the total delay by  $2 \times t_{PEXP}$ .

Two groups of eight macrocells within each LAB (e.g., macrocells 1 through 8 and 9 through 16) form two chains to lend or borrow parallel expanders. A macrocell borrows parallel expanders from lower-numbered macrocells. For example, macrocell 8 can borrow parallel expanders from macrocell 7, from macrocells 7 and 6, or from macrocells 7, 6, and 5. Within each group of 8, the lowest-numbered macrocell can only lend parallel expanders and the highest-numbered macrocell can only borrow them.

### FastTrack Interconnect

In the MAX 9000 architecture, connections between macrocells and device I/O pins are provided by the FastTrack Interconnect, a series of continuous horizontal and vertical routing channels that traverse the entire device. This device-wide routing structure provides predictable performance even in complex designs. In contrast, the segmented routing in FPGAs requires switch matrices to connect a variable number of routing paths, increasing the delays between logic resources and reducing performance. Figure 6 shows the interconnection of four adjacent LABs with row and column interconnects.

A row interconnect channel can be fed by the output of the macrocell through a 4-to-1 multiplexer that the macrocell shares with three column channels. If the multiplexer is used for a macrocell-to-row connection, the three column signals can access another row channel via an additional 3-to-1 multiplexer. Within any LAB, the multiplexers provide all 48 column channels with access to 32 row channels.

#### Row-to-I/O Cell Connections

Figure 8 illustrates the connections between row interconnect channels and IOCs. An input signal from an IOC can drive two separate row channels. When an IOC is used as an output, the signal is driven by a 10-to-1 multiplexer that selects the row channels. Each end of the row channel feeds up to eight IOCs on the periphery of the device.

Row FastTrack Interconnect

96

10

10

10C1

Property of the property of the

Figure 8. MAX 9000 Row-to-IOC Connections

### Column-to-I/O Cell Connections

Each end of a column channel has up to 10 IOCs (see Figure 9). An input signal from an IOC can drive two separate column channels. When an IOC is used as an output, the signal is driven by a 17-to-1 multiplexer that selects the column channels.

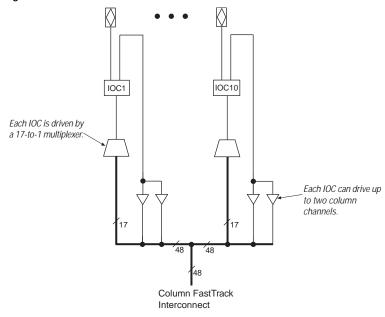


Figure 9. MAX 9000 Column-to-IOC Connections

# **Dedicated Inputs**

In addition to the general-purpose I/O pins, MAX 9000 devices have four dedicated input pins. These dedicated inputs provide low-skew, device-wide signal distribution to the LABs and IOCs in the device, and are typically used for global clock, clear, and output enable control signals. The global control signals can feed the macrocell or IOC clock and clear inputs, as well as the IOC output enable. The dedicated inputs can also be used as general-purpose data inputs because they can feed the row FastTrack Interconnect (see Figure 2 on page 7).

#### I/O Cells

Figure 10 shows the IOC block diagram. Signals enter the MAX 9000 device from either the I/O pins that provide general-purpose input capability or from the four dedicated inputs. The IOCs are located at the ends of the row and column interconnect channels.

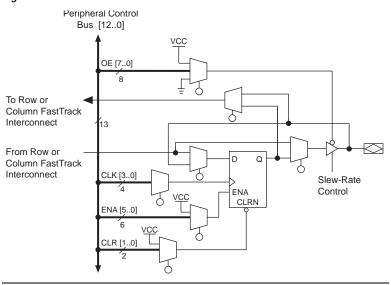


Figure 10. MAX 9000 IOC

I/O pins can be used as input, output, or bidirectional pins. Each IOC has an IOC register with a clock enable input. This register can be used either as an input register for external data that requires fast setup times, or as an output register for data that requires fast clock-to-output performance. The IOC register clock enable allows the global clock to be used for fast clock-to-output performance, while maintaining the flexibility required for selective clocking.

The clock, clock enable, clear, and output enable controls for the IOCs are provided by a network of I/O control signals. These signals can be supplied by either the dedicated input pins or internal logic. The IOC control-signal paths are designed to minimize the skew across the device. All control-signal sources are buffered onto high-speed drivers that drive the signals around the periphery of the device. This "peripheral bus" can be configured to provide up to eight output enable signals, up to four clock signals, up to six clock enable signals, and up to two clear signals. Table 6 on page 18 shows the sources that drive the peripheral bus and how the IOC control signals share the peripheral bus.

# **Programming Sequence**

During in-system programming, instructions, addresses, and data are shifted into the MAX 9000 device through the  $\mathtt{TDI}$  input pin. Data is shifted out through the  $\mathtt{TDO}$  output pin and compared against the expected data.

Programming a pattern into the device requires the following six ISP stages. A stand-alone verification of a programmed pattern involves only stages 1, 2, 5, and 6.

- Enter ISP. The enter ISP stage ensures that the I/O pins transition smoothly from user mode to ISP mode. The enter ISP stage requires 1 ms.
- Check ID. Before any program or verify process, the silicon ID is checked. The time required to read this silicon ID is relatively small compared to the overall programming time.
- Bulk Erase. Erasing the device in-system involves shifting in the instructions to erase the device and applying one erase pulse of 100 ms.
- Program. Programming the device in-system involves shifting in the address and data and then applying the programming pulse to program the EEPROM cells. This process is repeated for each EEPROM address.
- Verify. Verifying an Altera device in-system involves shifting in addresses, applying the read pulse to verify the EEPROM cells, and shifting out the data for comparison. This process is repeated for each EEPROM address.
- Exit ISP. An exit ISP stage ensures that the I/O pins transition smoothly from ISP mode to user mode. The exit ISP stage requires 1 ms.

# **Programming Times**

The time required to implement each of the six programming stages can be broken into the following two elements:

- A pulse time to erase, program, or read the EEPROM cells.
- A shifting time based on the test clock (TCK) frequency and the number of TCK cycles to shift instructions, address, and data into the device.

By combining the pulse and shift times for each of the programming stages, the program or verify time can be derived as a function of the TCK frequency, the number of devices, and specific target device(s). Because different ISP-capable devices have a different number of EEPROM cells, both the total fixed and total variable times are unique for a single device.

### Programming a Single MAX 9000 Device

The time required to program a single MAX 9000 device in-system can be calculated from the following formula:

$$t_{PROG} = t_{PPULSE} + \frac{Cycle_{PTCK}}{f_{TCK}}$$

where:  $t_{PROG} = t_{PPULSE}$  = Programming time  $t_{PPULSE} = t_{PPULSE}$  = Sum of the fixed times to erase, program, and

verify the EEPROM cells

Cycle<sub>PTCK</sub> = Number of TCK cycles to program a device

 $f_{TCK}$  = TCK frequency

The ISP times for a stand-alone verification of a single MAX 9000 device can be calculated from the following formula:

$$t_{VER} = t_{VPULSE} + \frac{Cycle_{VTCK}}{f_{TCK}}$$

where:  $t_{VER}$  = Verify time

 $t_{VPULSE}$  = Sum of the fixed times to verify the EEPROM cells

 $Cycle_{VTCK}$  = Number of TCK cycles to verify a device

The instruction register length for MAX 9000 devices is 10 bits. EPM9320A and EPM9560A devices support a 16-bit UESCODE register. Tables 11 and 12 show the boundary-scan register length and device IDCODE information for MAX 9000 devices.

Table 11. MAX 9000 Boundary-Scan Register Length					
Device Boundary-Scan Register Length					
EPM9320, EPM9320A	504				
EPM9400	552				
EPM9480	600				
EPM9560, EPM9560A	648				

Table 12. 32-Bit MAX 9000 Device IDCODE Note (1)						
Device	IDCODE (32 Bits)					
	Version (4 Bits)					
EPM9320A (3)	0000	1001 0011 0010 0000	00001101110	1		
EPM9400	0000	1001 0100 0000 0000	00001101110	1		
EPM9480	0000	1001 0100 1000 0000	00001101110	1		
EPM9560A (3)	0000	1001 0101 0110 0000	00001101110	1		

#### Notes:

- (1) The IDCODE's least significant bit (LSB) is always 1.
- (2) The most significant bit (MSB) is on the left.
- (3) Although the EPM9320A and EPM9560A devices support the IDCODE instruction, the EPM9320 and EPM9560 devices do not.

Figure 11 shows the timing requirements for the JTAG signals.

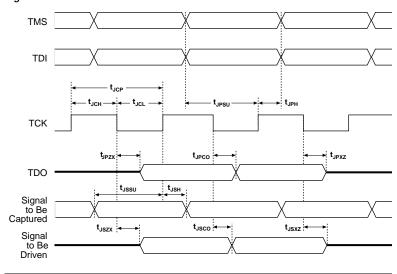


Figure 11. MAX 9000 JTAG Waveforms

Table 13 shows the JTAG timing parameters and values for MAX 9000 devices.

Table 1	Table 13. JTAG Timing Parameters & Values for MAX 9000 Devices						
Symbol	Parameter	Min	Max	Unit			
t <sub>JCP</sub>	TCK clock period	100		ns			
t <sub>JCH</sub>	TCK clock high time	50		ns			
t <sub>JCL</sub>	TCK clock low time	50		ns			
t <sub>JPSU</sub>	JTAG port setup time	20		ns			
t <sub>JPH</sub>	JTAG port hold time	45		ns			
t <sub>JPCO</sub>	JTAG port clock to output		25	ns			
t <sub>JPZX</sub>	JTAG port high impedance to valid output		25	ns			
t <sub>JPXZ</sub>	JTAG port valid output to high impedance		25	ns			
t <sub>JSSU</sub>	Capture register setup time	20		ns			
t <sub>JSH</sub>	Capture register hold time	45		ns			
t <sub>JSCO</sub>	Update register clock to output		25	ns			
t <sub>JSZX</sub>	Update register high impedance to valid output		25	ns			
t <sub>JSXZ</sub>	Update register valid output to high impedance		25	ns			



For detailed information on JTAG operation in MAX 9000 devices, refer to Application Note 39 (IEEE 1149.1 (JTAG) Boundary-Scan Testing in Altera Devices).

Table 24	Table 24. Interconnect Delays								
Symbol	mbol Parameter Conditions		Speed Grade					Unit	
				10	-1	15	-2	20	
			Min	Max	Min	Max	Min	Max	
t <sub>LOCAL</sub>	LAB local array delay			0.5		0.5		0.5	ns
t <sub>ROW</sub>	FastTrack row delay	(6)		0.9		1.4		2.0	ns
t <sub>COL</sub>	FastTrack column delay	(6)		0.9		1.7		3.0	ns
t <sub>DIN_D</sub>	Dedicated input data delay			4.0		4.5		5.0	ns
t <sub>DIN_CLK</sub>	Dedicated input clock delay			2.7		3.5		4.0	ns
t <sub>DIN_CLR</sub>	Dedicated input clear delay			4.5		5.0		5.5	ns
t <sub>DIN_IOC</sub>	Dedicated input I/O register clock delay			2.5		3.5		4.5	ns
t <sub>DIN_IO</sub>	Dedicated input I/O register control delay			5.5		6.0		6.5	ns

#### Notes to tables:

- These values are specified under the MAX 9000 device recommended operating conditions, shown in Table 15 on page 27.
- See Application Note 77 (Understanding MAX 9000 Timing) for more information on test conditions for t<sub>PD1</sub> and t<sub>PD2</sub> delays.
- (3) This parameter is a guideline that is sample-tested only. It is based on extensive device characterization. This parameter applies for both global and array clocking as well as both macrocell and I/O cell registers.
- (4) Measured with a 16-bit loadable, enabled, up/down counter programmed in each LAB.
- (5) The  $t_{LPA}$  parameter must be added to the  $t_{LOCAL}$  parameter for macrocells running in low-power mode.
- (6) The t<sub>ROW</sub>, t<sub>COL</sub>, and t<sub>IOC</sub> delays are worst-case values for typical applications. Post-compilation timing simulation or timing analysis is required to determine actual worst-case performance.

# Power Consumption

The supply power (P) versus frequency ( $f_{MAX}$ ) for MAX 9000 devices can be calculated with the following equation:

$$P = P_{INT} + P_{IO} = I_{CCINT} \times V_{CC} + P_{IO}$$

The  $P_{\rm IO}$  value, which depends on the device output load characteristics and switching frequency, can be calculated using the guidelines given in *Application Note 74 (Evaluating Power for Altera Devices)*. The  $I_{\rm CCINT}$  value depends on the switching frequency and the application logic.

The I<sub>CCINT</sub> value is calculated with the following equation:

$$I_{CCINT} = (A \times MC_{TON}) + [B \times (MC_{DEV} - MC_{TON})] + (C \times MC_{USED} \times f_{MAX} \times tog_{LC})$$

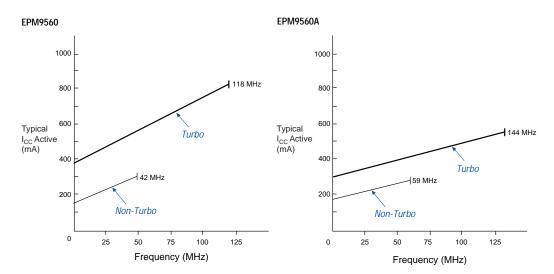


Figure 15. I<sub>CC</sub> vs. Frequency for MAX 9000 Devices (Part 2 of 2)

# Device Pin-Outs

Tables 26 through 29 show the dedicated pin names and numbers for each EPM9320, EPM9320A, EPM9400, EPM9480, EPM9560, and EPM9560A device package.

Table 26. EPM9320 & EPM9320A Dedicated Pin-Outs (Part 1 of 2)         Note (1)							
Pin Name	84-Pin PLCC (2)	208-Pin RQFP	280-Pin PGA (3)	356-Pin BGA			
DIN1 (GCLK1)	1	182	V10	AD13			
DIN2 (GCLK2)	84	183	U10	AF14			
DIN3 (GCLR)	13	153	V17	AD1			
DIN4 (GOE)	72	4	W2	AC24			
TCK	43	78	A9	A18			
TMS	55	49	D6	E23			
TDI	42	79	C11	A13			
TDO	30	108	A18	D3			

Pin Name	84-Pin PLCC (2)	208-Pin RQFP	280-Pin PGA (3)	356-Pin BGA
GND	6, 18, 24, 25, 48, 61, 67, 70	14, 20, 24, 31, 35, 41, 42, 43, 44, 46, 47, 66, 85, 102, 110, 113, 114, 115, 116, 118, 121, 122, 132, 133, 143, 152, 170, 189, 206	D4, D5, D16, E4, E5, E6, E15, E16, F5, F15, G5, G15, H5, H15, J5, J15, K5, K15, L5, L15, M5, M15, N5, N15, P4, P5, P15, P16, R4, R5, R15, R16, T4, T5, T16	A9, A22, A25, A26, B25, B26, D2, E1, E26, F2, G1, G25, G26, H2, J1, J25, J26 K2, L26, M26, N1, N25, P26, R2, T1, U2, U26, V1, V25, W25, Y26, AA2, AB1 AB26, AC26, AE1, AF1, AF2, AF4, AF7, AF20
VCCINT (5.0 V only)	14, 21, 28, 57, 64, 71	10, 19, 30, 45, 112, 128, 139, 148	D15, E8, E10, E12, E14, R7, R9, R11, R13, R14, T14	D26, F1, H1, K26, N26, P1 U1, W26, AE26, AF25, AF26
VCCIO (3.3 or 5.0 V)	15, 37, 60, 79	5, 25, 36, 55, 72, 91, 111, 127, 138, 159, 176, 195	D14, E7, E9, E11, E13, R6, R8, R10, R12, T13, T15	A1, A2, A21, B1, B10, B24 D1, H26, K1, M25, R1, V26 AA1, AC25, AF5, AF8, AF19
No Connect (N.C.)	29	6, 7, 8, 9, 11, 12, 13, 15, 16, 17, 18, 109, 140, 141, 142, 144, 145, 146, 147, 149, 150, 151	B6, K19, L2, L4, L18, L19, M1, M2, M3, M4, M16, M17, M18, M19, N1, N2, N3, N4, N16, N17, N18, N19, P1, P2, P3, P17, P18, P19, R1, R2, R3, R17, R18, R19, T1, T2, T3, T17, T18, T19, U1, U2, U3, U17, U18, U19, V1, V2, V19, W1	B4, B5, B6, B7, B8, B9, B11, B12, B13, B14, B15, B16, B18, B19, B20, B21, B22, B23, C4, C23, D4, D23, E4, E22, F4, F23, G4 H4, H23, J23, K4, L4, L23, N4, P4, P23, R3, R26, T2, T3, T4, T5, T22, T23, T24, T25, T26, U3, U4, U5, U22 U23, U24, U25, V2, V3, V4 V5, V22, V23, V24, W1, W2, W3, W4, W5, W22, W23, W24, Y1, Y2, Y3, Y4 Y5, Y22, Y23, Y24, Y25, A3, AA4, AA5, AA22, AA23, AA24, AA25, AA26, AB2, AB3, AB4, AB5, AB23, AB24, AB25, AC1, AC2, AC23, AD4, AD23, AE4, AE5, AE6, AE7, AE9 AE11, AE12, AE14, AE15, AE16, AE18, AE19, AE20, AE21, AE22, AE23
VPP <i>(4)</i>	56	48	C4	E25
Total User I/O Pins (5)	60	132	168	168

Table 28. EPM9480 Dedicated Pin-OutsNote (1)					
Pin Name	208-Pin RQFP	240-Pin RQFP			
DIN1 (GCLK1)	182	210			
DIN2 (GCLK2)	183	211			
DIN3 (GCLR)	153	187			
DIN4 (GOE)	4	234			
TCK	78	91			
TMS	49	68			
TDI	79	92			
TDO	108	114			
GND	14, 20, 24, 31, 35, 41, 42, 43, 44, 46, 47, 66, 85, 102, 110, 113, 114, 115, 116, 118, 121, 122, 132, 133, 143, 152, 170, 189, 206	5, 14, 25, 34, 45, 54, 65, 66, 81, 96, 110, 115, 126, 127, 146, 147, 166, 167, 186, 200, 216, 229			
VCCINT (5.0 V only)	10, 19, 30, 45, 112, 128, 139, 148	4, 24, 44, 64, 117, 137, 157, 177			
VCCIO (3.3 or 5.0 V)	5, 25, 36, 55, 72, 91, 111, 127, 138, 159, 176, 195	15, 35, 55, 73, 86, 101, 116, 136, 156, 176, 192, 205, 220, 235			
No Connect (N.C.)	6, 7, 8, 9, 109, 149, 150, 151	1, 2, 3, 178, 179, 180, 181, 182, 183, 184, 185, 236, 237, 238, 239, 240			
VPP (2)	48	67			
Total User I/O Pins (3)	146	175			

#### Notes:

- (1) All pins not listed are user I/O pins.
- (2) During in-system programming, each device's VPP pin must be connected to the 5.0-V power supply. During normal device operation, the VPP pin is pulled up internally and can be connected to the 5.0-V supply or left unconnected.
- (3) The user I/O pin count includes dedicated input pins and all I/O pins.

Pin Name	208-Pin RQFP	240-Pin RQFP	280-Pin PGA (2)	304-Pin RQFP (2)	356-Pin BGA
DIN1 (GCLK1)	182	210	V10	266	AD13
DIN2 (GCLK2)	183	211	U10	267	AF14
DIN3 (GCLR)	153	187	V17	237	AD1
DIN4 (GOE)	4	234	W2	296	AC24
TCK	78	91	A9	114	A18
TMS	49	68	D6	85	E23
TDI	79	92	C11	115	A13
TDO	108	114	A18	144	D3
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