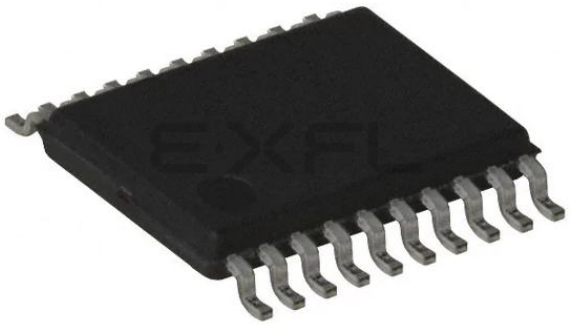

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Understanding Embedded - PLDs (Programmable Logic Devices)

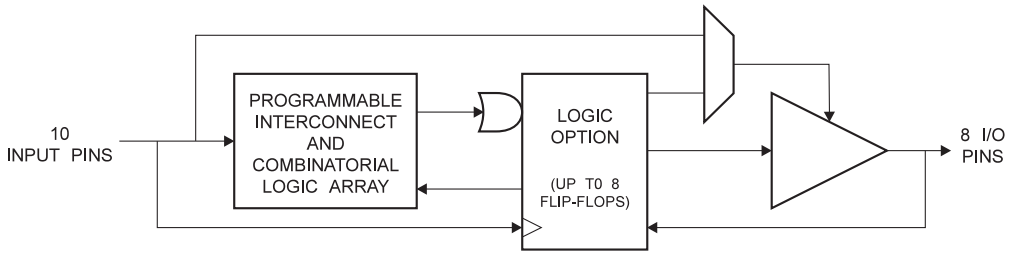
Embedded - PLDs, or Programmable Logic Devices, are a type of digital electronic component used to build reconfigurable digital circuits. Unlike fixed-function logic devices, PLDs can be programmed to perform specific functions by the user. This flexibility allows designers to customize the logic to meet the exact needs of their applications, making PLDs a crucial component in modern embedded systems.

Applications of Embedded - PLDs (Programmable Logic Devices)

The versatility of PLDs makes them suitable for a wide range of applications. In consumer electronics, PLDs are used to enhance the functionality and performance of

Details	
Product Status	Active
Programmable Type	EE PLD
Number of Macrocells	8
Voltage - Input	5V
Speed	15 ns
Mounting Type	Surface Mount
Package / Case	20-TSSOP (0.173", 4.40mm Width)
Supplier Device Package	20-TSSOP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/atf16v8cz-15xu

Figure 1-1. Block Diagram



2. Pin Configuration and Pinouts

Table 2-1. Pinouts - All Pinouts Top View

Pin Name	Function
CLK	Clock
I	Logic Inputs
I/O	Bi-directional Buffers
$\overline{OE}$	Output Enable
VCC	+5V Supply

Figure 2-1. TSSOP

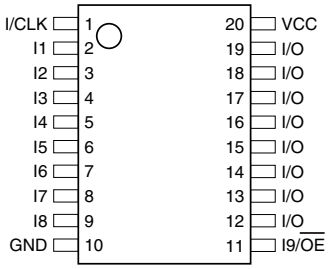


Figure 2-2. DIP/SOIC

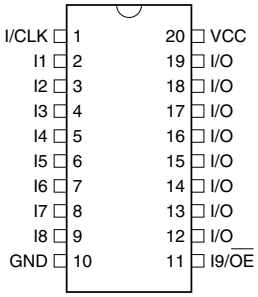
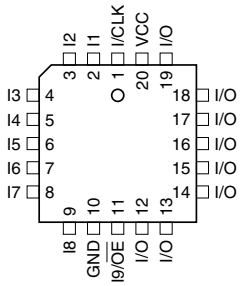


Figure 2-3. PLCC



3. Absolute Maximum Ratings*

Temperature Under Bias	-40°C to +85°C
Storage Temperature	-65°C to +150°C
Voltage on Any Pin with Respect to Ground	-2.0V to +7.0V[1]
Voltage on Input Pins with Respect to Ground During Programming	-2.0V to +14.0V[1]
Programming Voltage with Respect to Ground	-2.0V to +14.0V[1]

*NOTICE: Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Note: 1. Minimum voltage is -0.6V DC, which may undershoot to -2.0V for pulses of less than 20 ns. Maximum output pin voltage is V_{CC} + 0.75V DC, which may overshoot to 7.0V for pulses of less than 20 ns.

4. DC and AC Operating Conditions

	Commercial	Industrial
Operating Temperature (Ambient)	0°C - 70°C	-40°C - 85°C
V_{CC} Power Supply	5V ±5%	5V ±10%

4.1 DC Characteristics

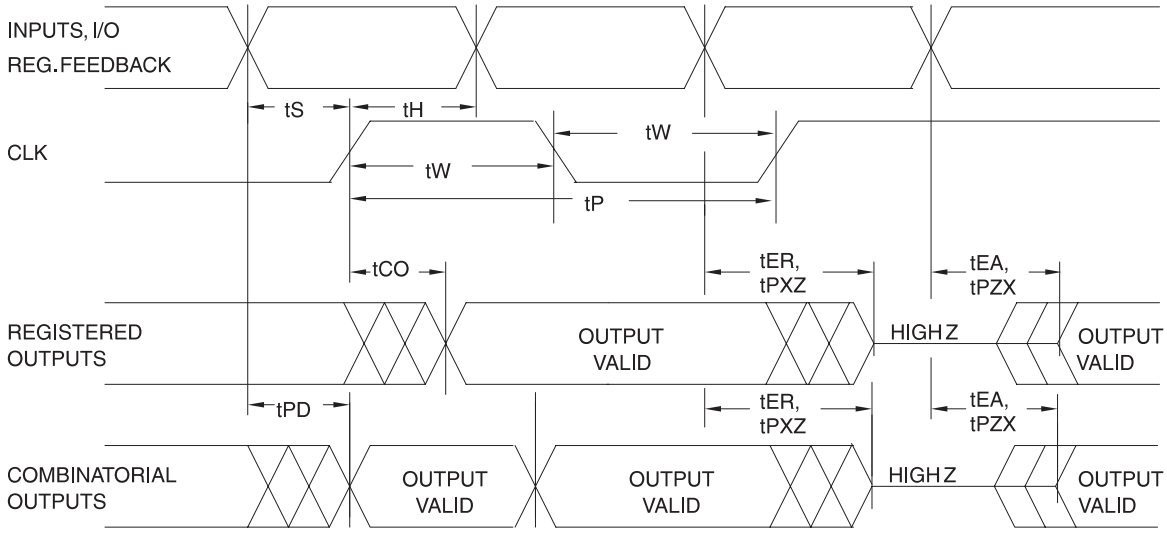
Symbol	Parameter	Condition		Min	Typ	Max	Units
I_{IL}	Input or I/O Low Leakage Current	$0 \le V_{IN} \le V_{IL}$(Max)				-10	µA
I_{IH}	Input or I/O High Leakage Current	$3.5 \le V_{IN} \le V_{CC}$				10	µA
I_{CC1}	Power Supply Current	15 MHz, V_{CC} = Max, V_{IN} = 0, V_{CC}, Outputs Open	Com			95	mA
			Ind.			105	mA
I_{CC}[1]	Power Supply Current, Standby Mode	0 MHz, V_{CC} = Max, V_{IN} = 0, V_{CC}, Outputs Open	Com.		5		µA
			Ind		5		µA
I_{OS}	Output Short Circuit Current	V_{OUT} = 0.5V; V_{CC}= 5V; TA = 25°C				-150	mA
V_{IL}	Input Low Voltage	Min < V_{CC} < Max		-0.5		0.8	V
V_{IH}	Input High Voltage			2.0		V_{CC}+1	V
V_{OL}	Output Low Voltage	V_{CC} = Min, All Outputs I_{OL} = -16 mA	Com, Ind.			0.5	V

4.1 DC Characteristics

Symbol	Parameter	Condition		Min	Typ	Max	Units
V_{OH}	Output High Voltage	V_{CC} = Min I_{OL} = -3.2 mA		2.4			V
I_{OL}	Output Low Current	V_{CC} = Min	Com.	24			mA
			Ind.	12			
I_{OH}	Output High Current	V_{CC} = Min	Com., Ind.	4			mA

Note: 1. All I_{CC} parameters measured with outputs open. Data is based on Atmel test patterns. Reading may vary with pattern.

4.2 AC Waveforms[1]



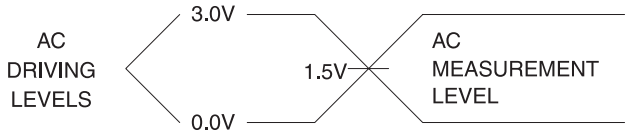
Note: 1. Timing measurement reference is 1.5V. Input AC driving levels are 0.0V and 3.0V, unless otherwise specified.

4.3 AC Characteristics

Symbol	Parameter	-12		-15		Units
		Min	Max	Min	Max	
t_{PD}	Input or Feedback to Non-registered Output	3	12	3	15	ns
t_{CF}	Clock to Feedback		6		8	ns
t_{CO}	Clock to Output	2	8	2	10	ns
t_S	Input or Feedback Setup Time	10		12		ns
t_H	Input Hold Time	0		0		ns
t_P	Clock Period	12		16		ns
t_W	Clock Width	6		8		ns
f_{MAX}	External Feedback $1/(t_S + t_{CO})$		55		45	MHz
	Internal Feedback $1/(t_S + t_{CF})$		62		50	MHz
	No Feedback $1/(t_P)$		83		62	MHz
t_{EA}	Input to Output Enable – Product Term	3	12	3	15	ns
t_{ER}	Input to Output Disable – Product Term	2	15	2	15	ns
t_{PZX}	$\overline{OE}$ pin to Output Enable	2	12	2	15	ns
t_{PXZ}	$\overline{OE}$ pin to Output Disable	1.5	12	1.5	15	ns

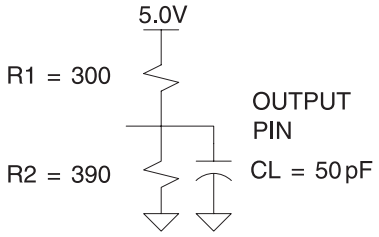
4.4 Input Test Waveforms

4.4.1 Input Test Waveforms and Measurement Levels



t_R, t_F < 1.5 ns (10% to 90%)

4.4.2 Output Test Loads



Note: Similar devices are tested with slightly different loads. These load differences may affect output signals' delay and slew rate. Atmel devices are tested with sufficient margins to meet compatible devices.

4.4.3 Pin Capacitance

Table 4-1. Pin Capacitance (f = 1 MHz, T = 25°C[1])

	Typ	Max	Units	Conditions
C_{IN}	5	8	pF	V_{IN} = 0V
C_{OUT}	6	8	pF	V_{OUT} = 0V

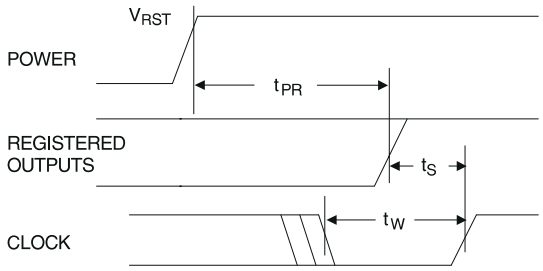
Note: 1. Typical values for nominal supply voltage. This parameter is only sampled and is not 100% tested.

4.5 Power-up Reset

The ATF16V8CZ's registers are designed to reset during power-up. At a point delayed slightly from V_{CC} crossing V_{RST}, all registers will be reset to the low state. As a result, the registered output state will always be high on power-up.

This feature is critical for state machine initialization. However, due to the asynchronous nature of reset and the uncertainty of how V_{CC} actually rises in the system, the following conditions are required:

1. The V_{CC} rise must be monotonic, from below 0.7V,
2. After reset occurs, all input and feedback setup times must be met before driving the clock term high, and
3. The signals from which the clock is derived must remain stable during t_{PR}.



Parameter	Description	Typ	Max	Units
t_{PR}	Power-up Reset Time	600	1,000	ns
V_{RST}	Power-up Reset Voltage	3.8	4.5	V

4.6 Preload of Registered Outputs

The ATF16V8CZ's registers are provided with circuitry to allow loading of each register with either a high or a low. This feature will simplify testing since any state can be forced into the registers to control test sequencing. A JEDEC file with preload is generated when a source file with vectors is compiled. Once downloaded, the JEDEC file preload sequence will be done automatically by approved programmers.

5. Security Fuse Usage

A single fuse is provided to prevent unauthorized copying of the ATF16V8CZ fuse patterns. Once programmed, fuse verify and preload are inhibited. However, the 64-bit User Signature remains accessible.

The security fuse should be programmed last, as its effect is immediate.

6. Input and I/O Pin-keeper Circuits

The ATF16V8CZ contains internal input and I/O pin-keeper circuits. These circuits allow each ATF16V8CZ pin to hold its previous value even when it is not being driven by an external source or by the device's output buffer. This helps insure that all logic array inputs are at known, valid logic levels. This reduces system power by preventing pins from floating to indeterminate levels. By using pin-keeper circuits rather than pull-up resistors, there is no DC current required to hold the pins in either logic state (high or low).

These pin-keeper circuits are implemented as weak feedback inverters, as shown in the Input Diagram below. These keeper circuits can easily be overdriven by standard TTL- or CMOS-compatible drivers. The typical overdrive current required is 40 µA.

Figure 6-1. Input Diagram

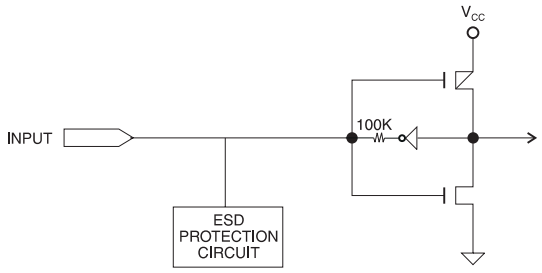
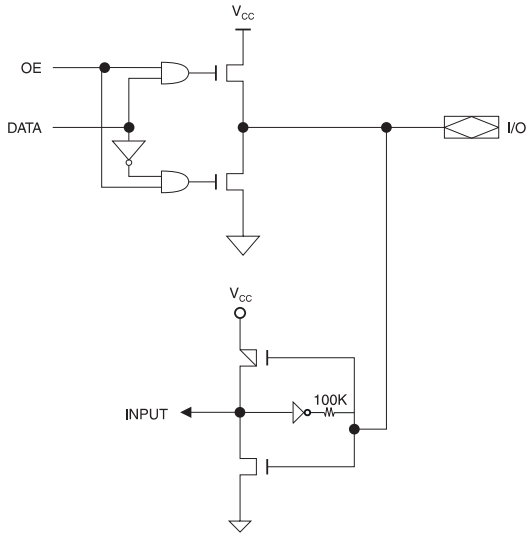


Figure 6-2. I/O Diagram



7. Functional Logic Diagram Description

The Logic Option and Functional Diagrams describe the ATF16V8CZ architecture. Eight configurable macrocells can be configured as a registered output, combinatorial I/O, combinatorial output, or dedicated input.

The ATF16V8CZ can be configured in one of three different modes. Each mode makes the ATF16V8CZ look like a different device. Most PLD compilers can choose the right mode automatically. The user can also force the selection by supplying the compiler with a mode selection. The determining factors would be the usage of register versus combinatorial outputs and dedicated outputs versus outputs with output enable control.

The ATF16V8CZ universal architecture can be programmed to emulate many 20-pin PAL devices. These architectural subsets can be found in each of the configuration modes described in the following pages. The user can download the listed subset device JEDEC programming file to the PLD programmer, and the ATF16V8CZ can be configured to act like the chosen device. Check with your programmer manufacturer for this capability.

Unused product terms are automatically disabled by the compiler to decrease power consumption. A security fuse, when programmed, protects the content of the ATF16V8CZ. Eight bytes (64 fuses) of User Signature are accessible to the user for purposes such as storing project name, part number, revision, or date. The User Signature is accessible regardless of the state of the security fuse.

Table 7-1. Compiler Mode Selection

	Registered	Complex	Simple	Auto Select
ABEL, Atmel-ABEL	P16C8R	P16V8C	P16V8AS	P16V8
CUPL	G16V8MS	G16V8MA	G16V8AS	G16V8A
LOG/iC	GAL16V8_R(1)	GAL16V8_C7(1)	GAL16V8_C8(1)	GAL16V8
OrCAD-PLD	“Registered”	“Complex”	“Simple”	GAL16V8A
PLDesigner	P16V8R	P16V8C	P16V8C	P16V8A
Tango-PLD	G16V8R	G16V8C	G16V8AS	G16V8

Notes: 1. Only applicable for version 3.4 or lower.

8. Macrocell Configuration

Software compilers support the three different OMC modes as different device types. These device types are listed in the table below. Most compilers have the ability to automatically select the device type, generally based on the register usage and output enable ($\overline{OE}$) usage. Register usage on the device forces the software to choose the registered mode. All combinatorial outputs with $\overline{OE}$ controlled by the product term will force the software to choose the complex mode. The software will choose the simple mode only when all outputs are dedicated combinatorial without $\overline{OE}$ control. The different device types listed in the table can be used to override the automatic device selection by the software. For further details, refer to the compiler software manuals.

When using compiler software to configure the device, the user must pay special attention to the following restrictions in each mode.

In **registered mode** pin 1 and pin 11 are permanently configured as clock and output enable, respectively. These pins cannot be configured as dedicated inputs in the registered mode.

In **complex mode** pin 1 and pin 11 become dedicated inputs and use the feedback paths of pin 19 and pin 12 respectively. Because of this feedback path usage, pin 19 and pin 12 do not have the feedback option in this mode.

In **simple mode** all feedback paths of the output pins are routed via the adjacent pins. In doing so, the two inner most pins (pins 15 and 16) will not have the feedback option as these pins are always configured as dedicated combinatorial output.

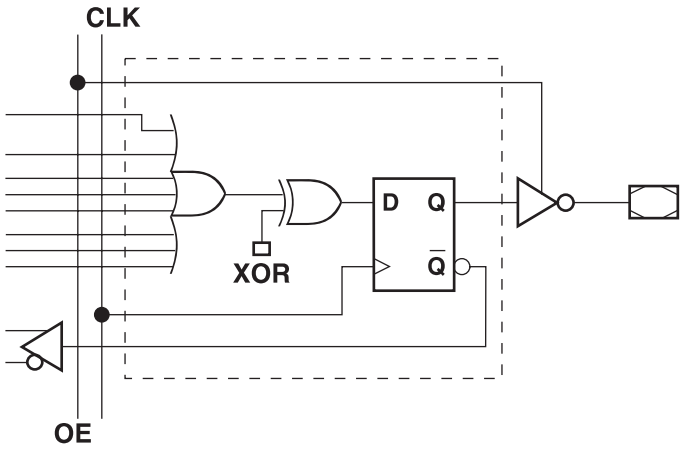
8.1 ATF16V8CZ Registered Mode

PAL Device Emulation/PAL Replacement. The registered mode is used if one or more registers are required. Each macrocell can be configured as either a registered or combinatorial output or I/O, or as an input. For a registered output or I/O, the output is enabled by the $\overline{OE}$ pin, and the register is clocked by the CLK pin. Eight product terms are allocated to the sum term. For a combinatorial output or I/O, the output enable is controlled by a product term, and seven product terms are allocated to the sum term. When the macrocell is configured as an input, the output enable is permanently disabled.

Any register usage will make the compiler select this mode. The following registered devices can be emulated using this mode:

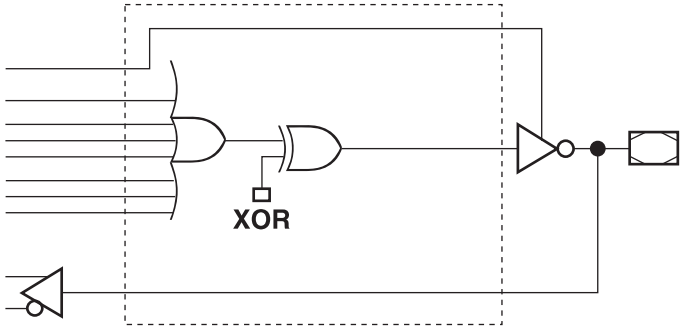
16R8	16RP8
16R6	16RP6
16R4	16RP4

Figure 8-1. Registered Configuration for Registered Mode[1][2]



Notes:
1. Pin 1 controls common CLK for the registered outputs.
   Pin 11 controls common $\overline{OE}$ for the registered outputs.
   Pin 1 and Pin 11 are permanently configured as CLK and $\overline{OE}$.
2. The development software configures all the architecture control bits and checks for proper pin usage automatically.

Figure 8-2. Combinatorial Configuration for Registered Mode[1][2]



Notes:
1. Pin 1 and Pin 11 are permanently configured as CLK and $\overline{OE}$.
2. The development software configures all the architecture control bits and checks for proper pin usage automatically.

Figure 8-3. Registered Mode Logic Diagram

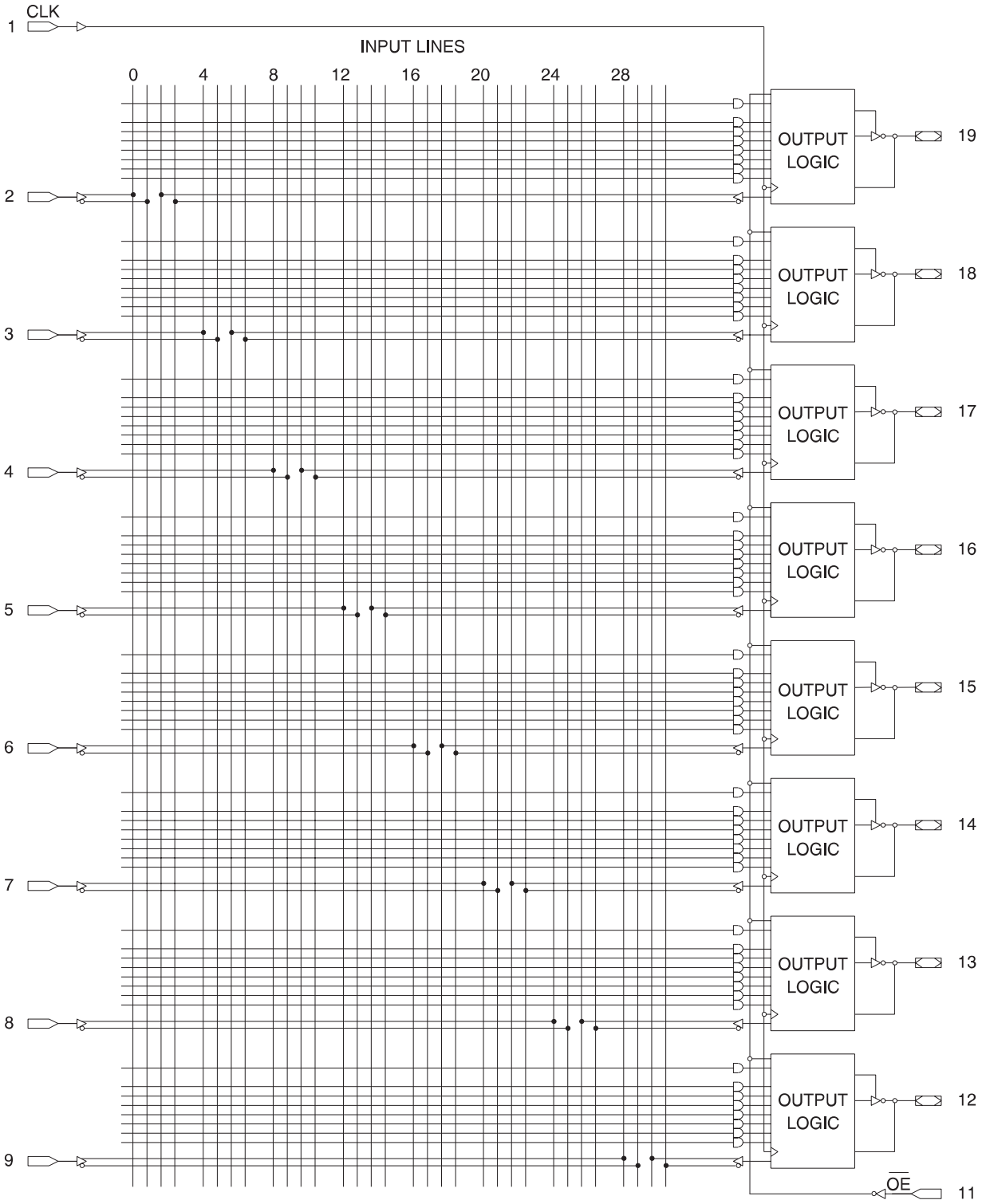
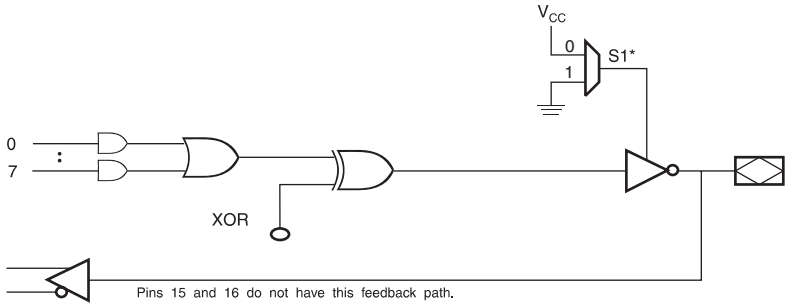


Figure 9-1. Simple Mode Option



* - Pins 15 and 16 are always enabled.

Figure 9-2. Complex Mode Logic Diagram

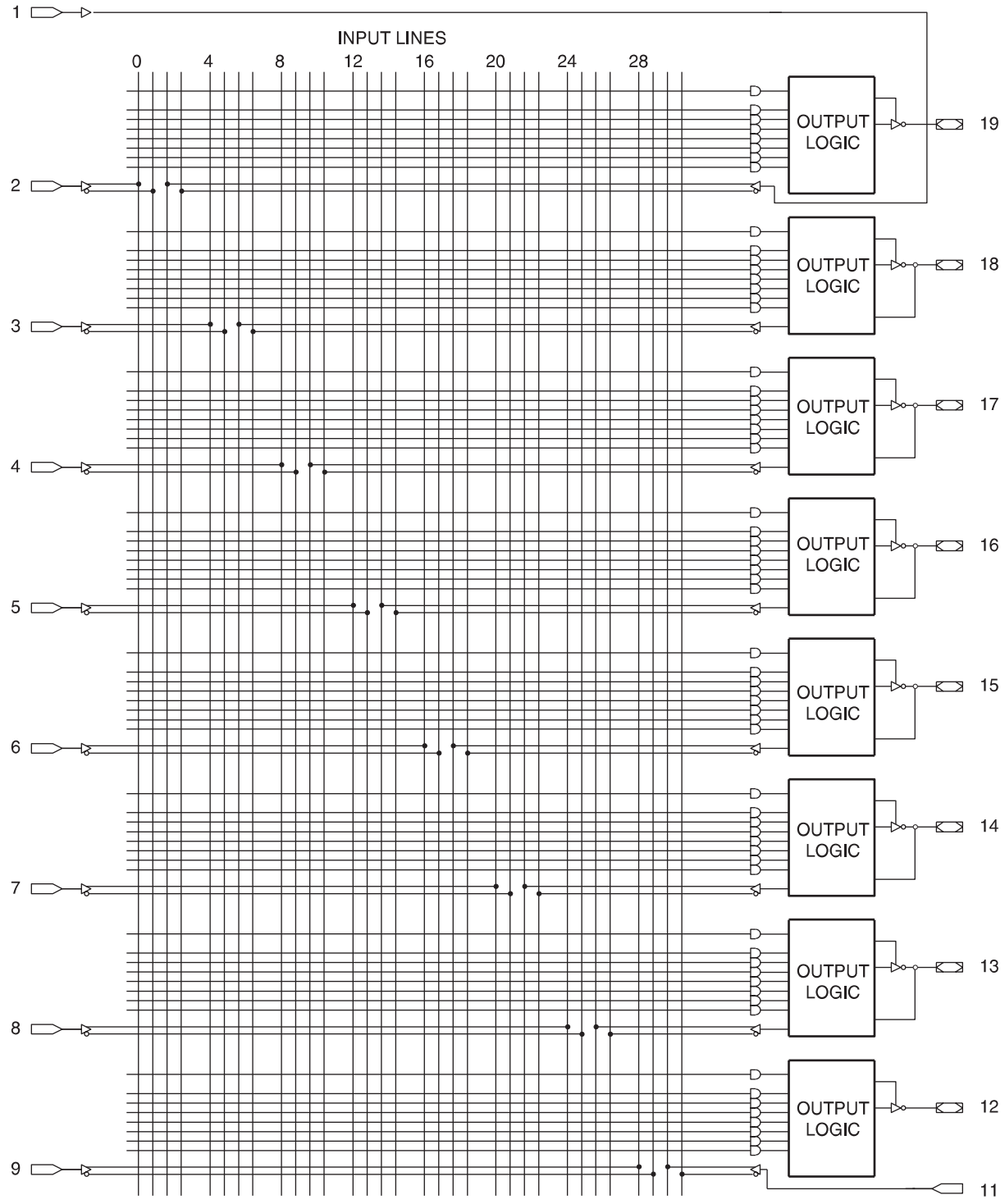
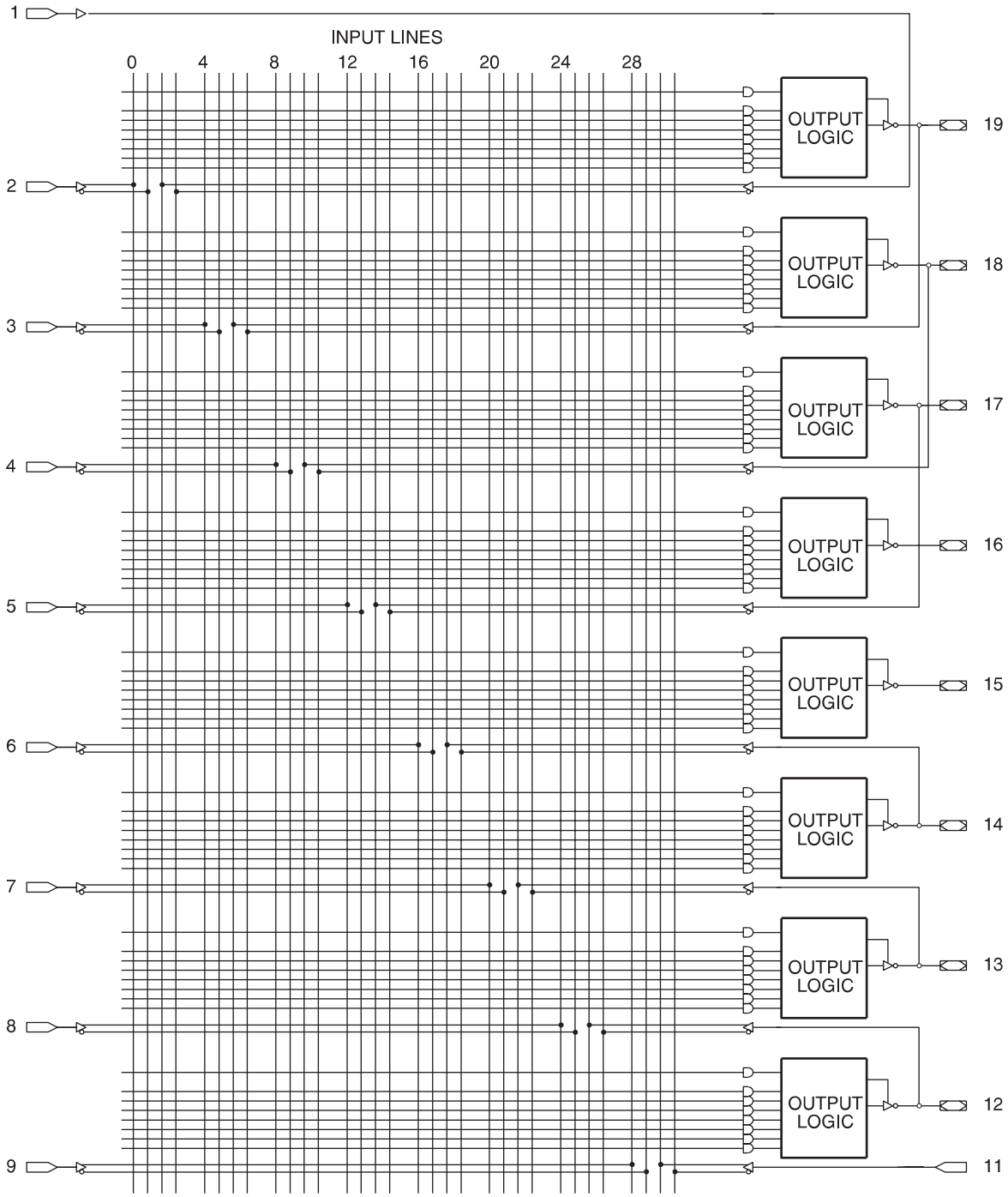
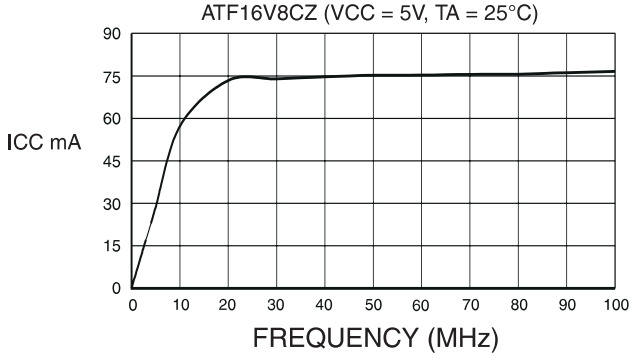


Figure 9-3. Simple Mode Logic Diagram

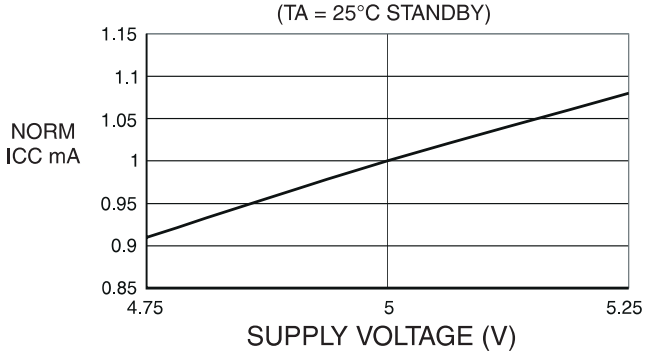


9.1 Test Characterization Data

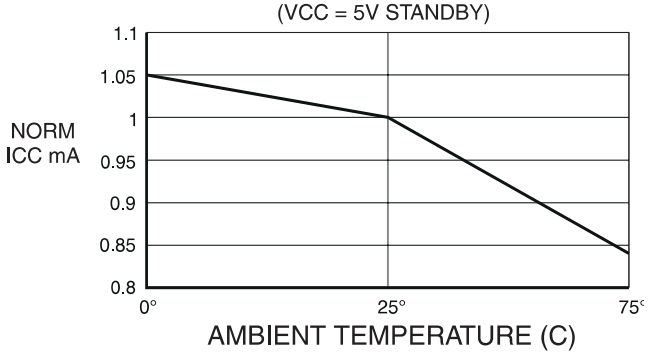
SUPPLY CURRENT
VS. INPUT FREQUENCY
ATF16V8CZ (VCC = 5V, TA = 25°C)



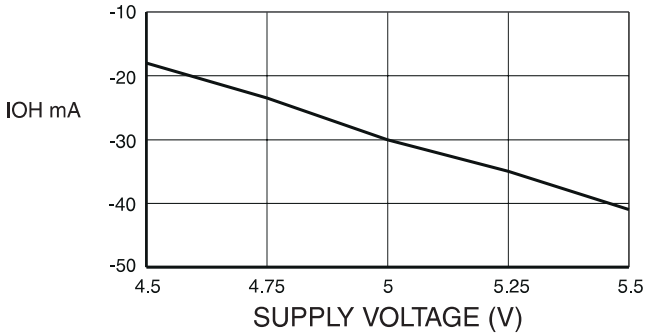
NORMALIZED SUPPLY CURRENT
VS. SUPPLY VOLTAGE
(TA = 25°C STANDBY)



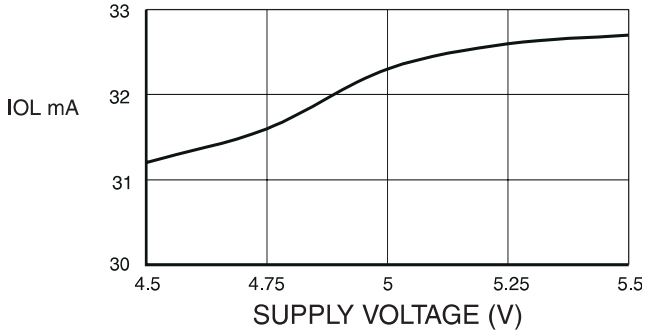
NORMALIZED SUPPLY CURRENT
VS. AMBIENT TEMPERATURE
(VCC = 5V STANDBY)



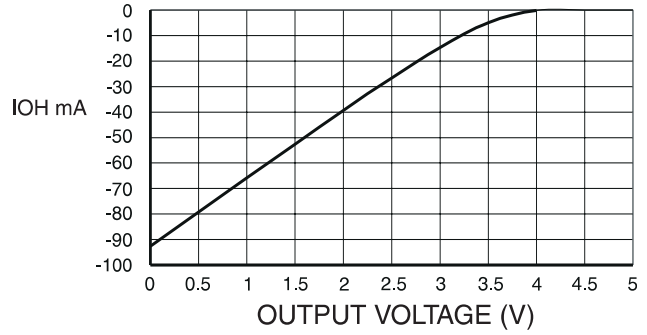
OUTPUT SOURCE CURRENT
VS. SUPPLY VOLTAGE (VOH = 2.4V, TA = 25°C)



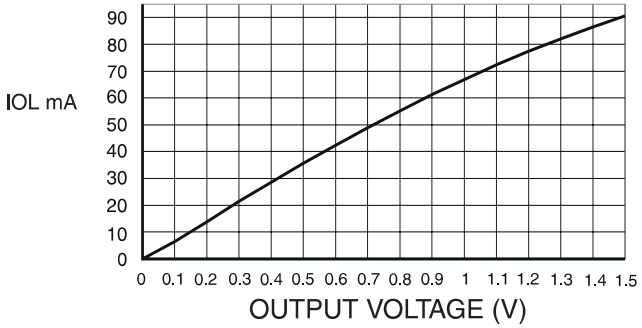
OUTPUT SINK CURRENT
VS. SUPPLY VOLTAGE (TA = 25°C, VOL = 0.45V)



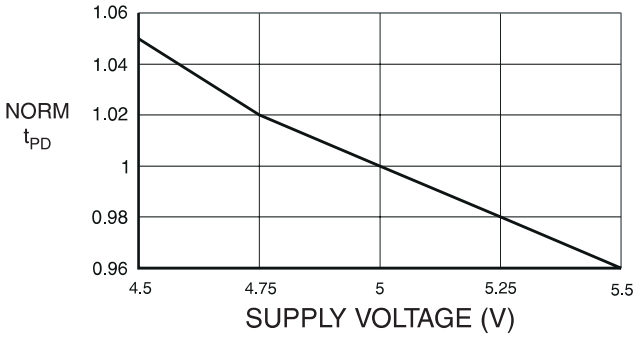
OUTPUT SOURCE CURRENT
VS. OUTPUT VOLTAGE (VOH = 2.4V, TA = 25°C)



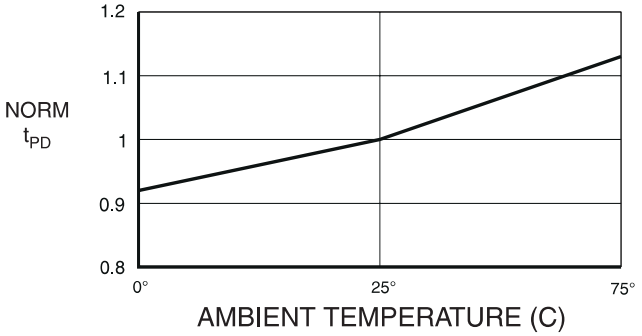
OUTPUT SINK CURRENT
VS. OUTPUT VOLTAGE (VCC = 5V, TA = 25°C)



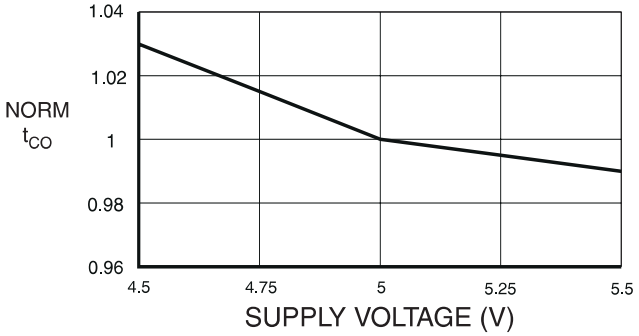
NORMALIZED t_{PD}
VS. SUPPLY VOLTAGE (TA = 25°C)



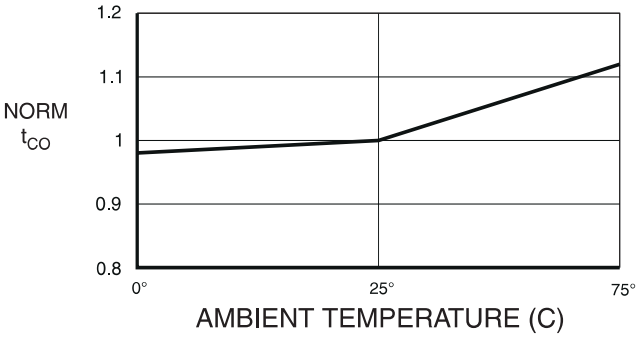
NORMALIZED t_{PD}
VS. AMBIENT TEMPERATURE (TA = 25°C)



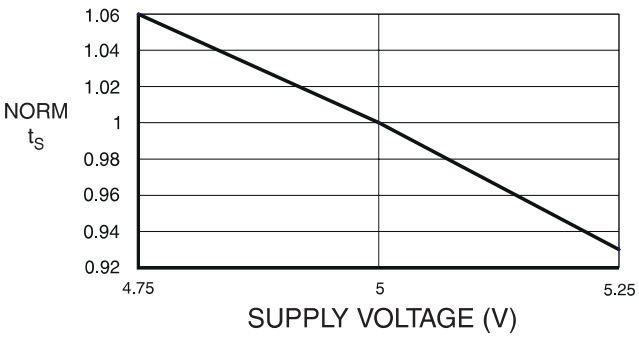
NORMALIZED t_{CO}
VS. SUPPLY VOLTAGE (TA = 25°C)



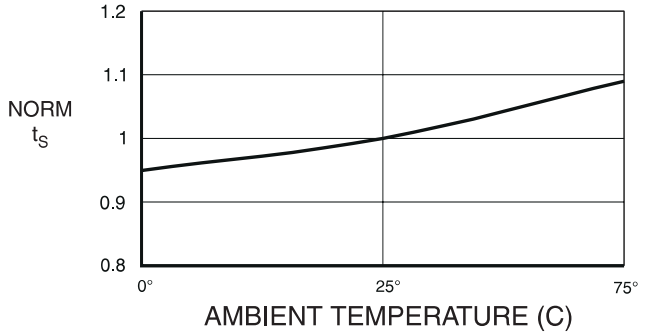
NORMALIZED t_{CO}
VS. AMBIENT TEMPERATURE (VCC = 5V)



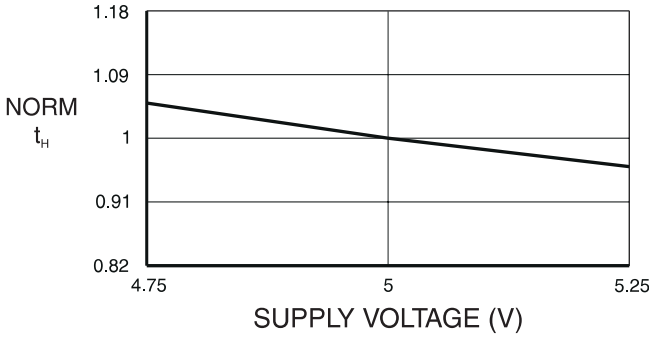
NORMALIZED t_S
VS. SUPPLY VOLTAGE (TA = 25C)



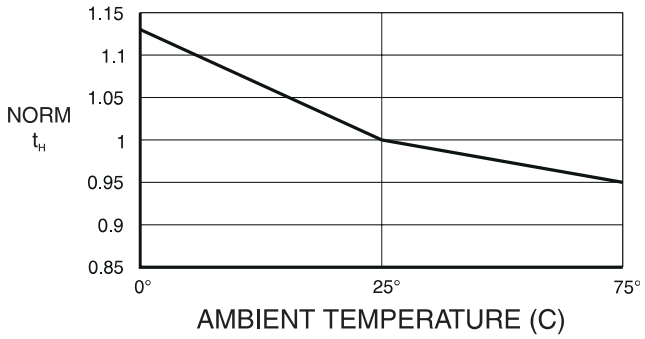
NORMALIZED t_S
VS. AMBIENT TEMPERATURE (TA = 25°C)



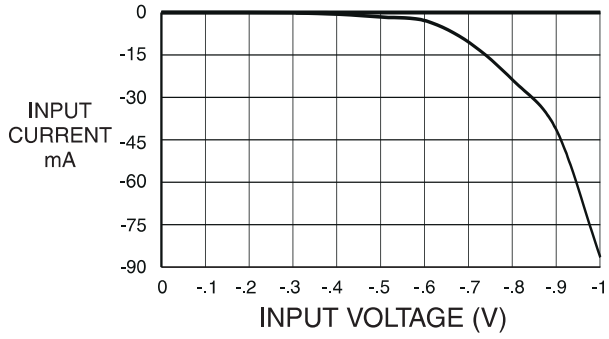
NORMALIZED t_H
VS. SUPPLY VOLTAGE (TA = 25°C)



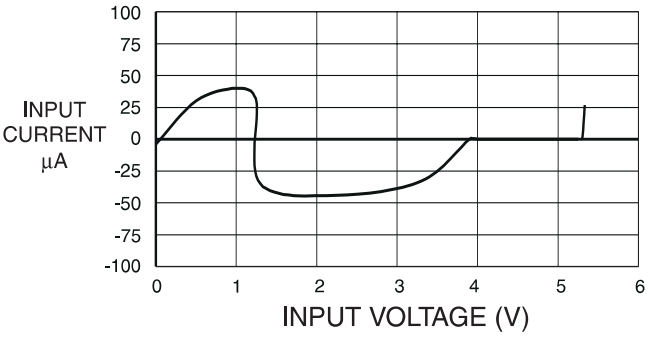
NORMALIZED t_H
VS. AMBIENT TEMPERATURE (VCC = 5V)



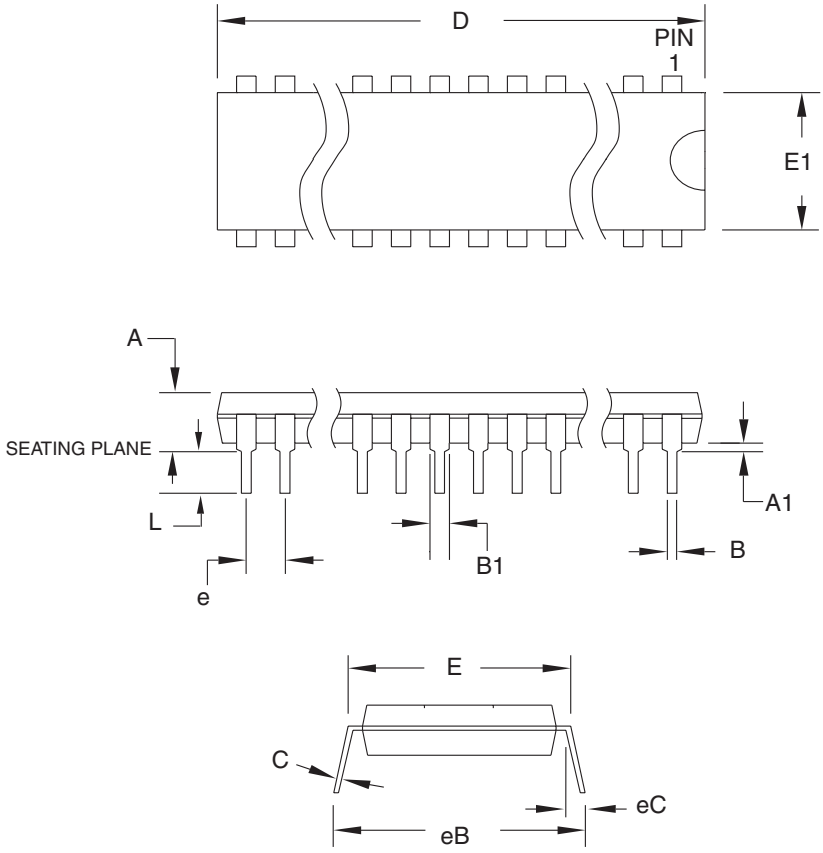
INPUT CLAMP CURRENT
VS. INPUT VOLTAGE (TA = 25°C, VCC = 5V)



INPUT CURRENT
VS. INPUT VOLTAGE (VCC = 5V, TA = 25°C)



11.2 20P3 – PDIP



COMMON DIMENSIONS
(Unit of Measure = mm)

SYMBOL	MIN	NOM	MAX	NOTE
A	–	–	5.334	
A1	0.381	–	–	
D	24.892	–	26.924	Note 2
E	7.620	–	8.255	
E1	6.096	–	7.112	Note 2
B	0.356	–	0.559	
B1	1.270	–	1.551	
L	2.921	–	3.810	
C	0.203	–	0.356	
eB	–	–	10.922	
eC	0.000	–	1.524	
e	2.540 TYP			

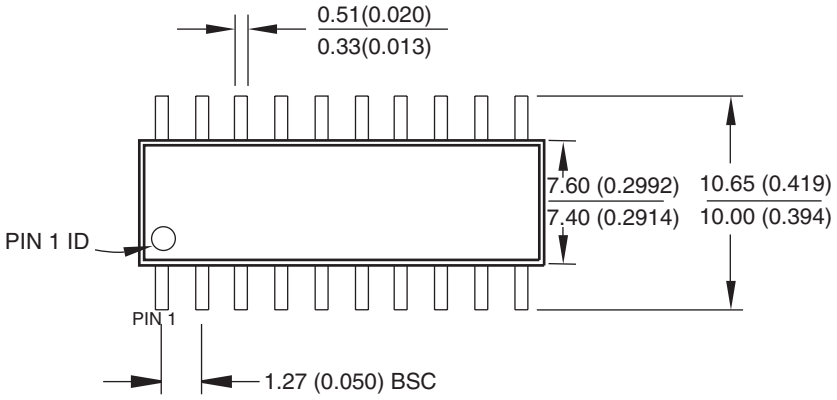
Notes: 1. This package conforms to JEDEC reference MS-001, Variation AD.
2. Dimensions D and E1 do not include mold Flash or Protrusion. Mold Flash or Protrusion shall not exceed 0.25 mm (0.010").

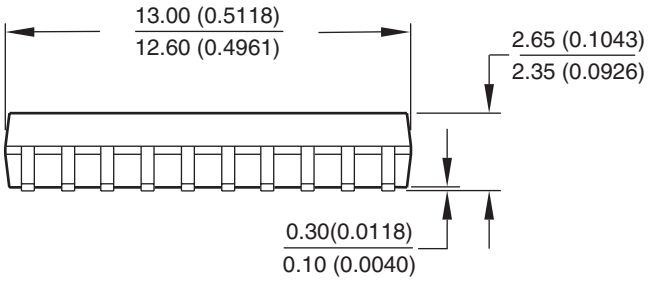
1/23/04

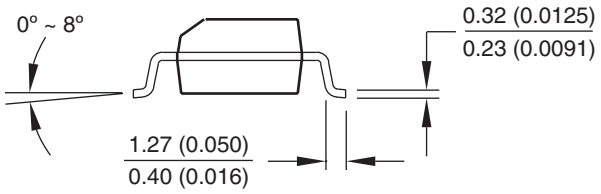
	TITLE	DRAWING NO.	REV.
2325 Orchard Parkway San Jose, CA 95131	**20P3**, 20-lead (0.300"/7.62 mm Wide) Plastic Dual Inline Package (PDIP)	20P3	D

11.3 20S – SOIC

Dimensions in Millimeters and (Inches).
Controlling dimension: Inches.
JEDEC Standard MS-013





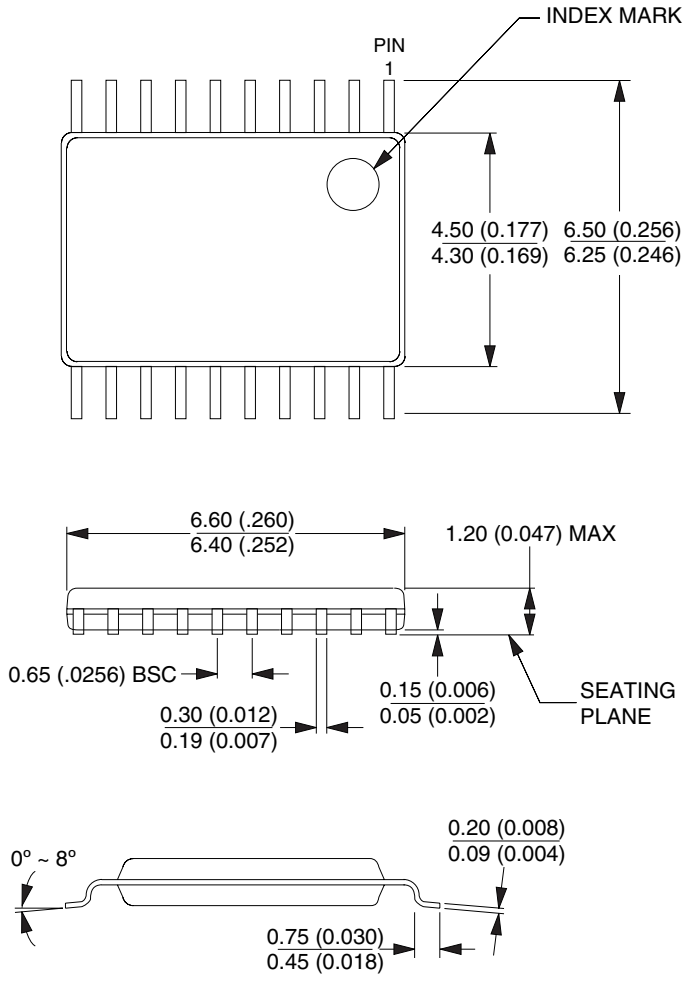


10/23/03

	TITLE	DRAWING NO.	REV.
2325 Orchard Parkway San Jose, CA 95131	**20S**, 20-lead, 0.300" Body, Plastic Gull Wing Small Outline (SOIC)	20S	B

11.4 20X – TSSOP

Dimensions in Millimeters and (Inches).
Controlling dimension: Millimeters.
JEDEC Standard MO-153 AC



10/23/03

	TITLE	DRAWING NO.	REV.
2325 Orchard Parkway San Jose, CA 95131	**20X**, (Formerly 20T), 20-lead, 4.4 mm Body Width, Plastic Thin Shrink Small Outline Package (TSSOP)	20X	C