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### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Not For New Designs
Core Processor	8051
Core Size	8-Bit
Speed	24MHz
Connectivity	EBI/EMI, I <sup>2</sup> C, UART/USART
Peripherals	Brown-out Detect/Reset, LVD, POR, PWM, WDT
Number of I/O	36
Program Memory Size	8KB (8K x 8)
Program Memory Type	FLASH
EEPROM Size	128 x 8
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	2.4V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-BQFP
Supplier Device Package	-
Purchase URL	<a href="https://www.e-xfl.com/product-detail/nuvoton-technology-corporation-america/n79e352afg">https://www.e-xfl.com/product-detail/nuvoton-technology-corporation-america/n79e352afg</a>



## 5. PIN DESCRIPTIONS

SYMBOL	Alternate Function 1	Alternate function 2	Type	DESCRIPTIONS
$\overline{EA}$			I	<b>EXTERNAL ACCESS ENABLE:</b> This pin forces the processor to execute out of external ROM. It should be kept high to access internal ROM. The ROM address and data will not be present on the bus if $\overline{EA}$ pin is high and the program counter is within internal ROM area. Otherwise they will be present on the bus.
$\overline{PSEN}$			O	<b>PROGRAM STORE ENABLE:</b> $\overline{PSEN}$ enables the external ROM data onto the Port 0 address/data bus during fetch and MOVC operations. When internal ROM access is performed, no $\overline{PSEN}$ strobe signal outputs from this pin.
ALE			O	<b>ADDRESS LATCH ENABLE:</b> ALE is used to enable the address latch that separates the address from the data on Port 0.
XTAL1	P5.1		I/O	<b>CRYSTAL1:</b> This is the crystal oscillator input. This pin may be driven by an external clock or configurable i/o pin, P5.1.
XTAL2	P5.0		I/O	<b>CRYSTAL2:</b> This is the crystal oscillator output. It is the inversion of XTAL1. Also a configurable i/o pin, P5.0.
VDD			P	<b>POWER SUPPLY:</b> Supply voltage for operation.
VSS			P	<b>GROUND:</b> Ground potential.
RST				<b>RESET:</b> A high on this pin for two machine cycles while the oscillator is running resets the device.
P0.0	KB0	AD0	I/O	<b>PORT0:</b> Support 4 mode output and 2 mode input. Multifunction pins for AD0-7 and KB0-7.
P0.1	KB1	AD1	I/O	
P0.2	KB2	AD2	I/O	
P0.3	KB3	AD3	I/O	
P0.4	KB4	AD4	I/O	
P0.5	KB5	AD5	I/O	
P0.6	KB6	AD6	I/O	
P0.7	KB7	AD7	I/O	
P1.0		T2	I/O	<b>PORT1:</b> Support 4 mode output and 2 mode input. Multifunction pins for SDA & SCL (I2C), T2, T2EX and PWM0-1.
P1.1		T2EX	I/O	
P1.2		SDA	I/O	
P1.3		SCL	I/O	
P1.4		PWM0	I/O	
P1.5		PWM1	I/O	
P1.6	ICPDAT		I/O	
P1.7	ICPCLK		I/O	

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		$\overline{INT0}$ . This bit is cleared by hardware when the service routine is vectored to only if the interrupt was edge triggered. Otherwise it follows the inverse of the pin.
0	IT0	Interrupt 0 Type Control: Set/cleared by software to specify falling edge/ low level triggered external inputs.

## TIMER MODE CONTROL

Bit:	7	6	5	4	3	2	1	0
	GATE	C/ $\overline{T}$	M1	M0	GATE	C/ $\overline{T}$	M1	M0
	TIMER1				TIMER0			

Mnemonic: TMOD

Address: 89h

BIT	NAME	FUNCTION
7	GATE	Gating control: When this bit is set, Timer/counter 1 is enabled only while the $\overline{INT1}$ pin is high and the TR1 control bit is set. When cleared, the $\overline{INT1}$ pin has no effect, and Timer 1 is enabled whenever TR1 control bit is set.
6	C/ $\overline{T}$	Timer or Counter Select: When clear, Timer 1 is incremented by the internal clock. When set, the timer counts falling edges on the T1 pin.
5	M1	Timer 1 mode select bit 1. See table below.
4	M0	Timer 1 mode select bit 0. See table below.
3	GATE	Gating control: When this bit is set, Timer/counter 0 is enabled only while the $\overline{INT0}$ pin is high and the TR0 control bit is set. When cleared, the $\overline{INT0}$ pin has no effect, and Timer 0 is enabled whenever TR0 control bit is set.
2	C/ $\overline{T}$	Timer or Counter Select: When clear, Timer 0 is incremented by the internal clock. When set, the timer counts falling edges on the T0 pin.
1	M1	Timer 0 mode select bit 1. See table below.
0	M0	Timer 0 mode select bit 0. See table below.

M1, M0: Mode Select bits:

M1	M0	MODE
0	0	Mode 0: 8-bit timer/counter TLx serves as 5-bit pre-scale.
0	1	Mode 1: 16-bit timer/counter, no pre-scale.
1	0	Mode 2: 8-bit timer/counter with auto-reload from THx.
1	1	Mode 3: (Timer 0) TL0 is an 8-bit timer/counter controlled by the standard Timer0 control bits. TH0 is an 8-bit timer only controlled by Timer1 control bits. (Timer 1) Timer/Counter 1 is stopped.

## TIMER 0 LSB

Bit:	7	6	5	4	3	2	1	0
	TL0.7	TL0.6	TL0.5	TL0.4	TL0.3	TL0.2	TL0.1	TL0.0

Mnemonic: TL0

Address: 8Ah

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2-1	-	Reserved.
0	CPTF0	External input capture 0 interrupt flag. It can be cleared by software.

## PORT 4

Bit:	7	6	5	4	3	2	1	0
	-	-	-	-	P4.3	P4.2	P4.1	P4.0

Mnemonic: P4

Address: A5h

BIT	NAME	FUNCTION
7~4	-	Reserved.
3~0	P4.3~0	Port 4 is a bi-directional I/O port with internal pull-ups. Port 4 can not use bit-addressable instruction (SETB or CLR).

## INTERRUPT ENABLE

Bit:	7	6	5	4	3	2	1	0
	EA	-	ET2	ES	ET1	EX1	ET0	EX0

Mnemonic: IE

Address: A8h

BIT	NAME	FUNCTION
7	EA	Global enable. Enable/Disable all interrupts.
6	-	Reserved.
5	ET2	Enable Timer 2 interrupt.
4	ES	Enable Serial Port 0 interrupt.
3	ET1	Enable Timer 1 interrupt.
2	EX1	Enable external interrupt 1.
1	ET0	Enable Timer 0 interrupt.
0	EX0	Enable external interrupt 0.

## SLAVE ADDRESS

Bit:	7	6	5	4	3	2	1	0
	SADDR.7	SADDR.6	SADDR.5	SADDR.4	SADDR.3	SADDR.2	SADDR.1	SADDR.0

Mnemonic: SADDR

Address: A9h

BIT	NAME	FUNCTION
7~0	SADDR	The SADDR should be programmed to the given or broadcast address for serial port 0 to which the slave processor is designated.

## PORT 3

Bit:	7	6	5	4	3	2	1	0
	P3.7	P3.6	P3.5	P3.4	P3.3	P3.2	P3.1	P3.0

Mnemonic: P3

Address: B0h

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I2CLK.7	I2CLK.6	I2CLK.5	I2CLK.4	I2CLK.3	I2CLK.2	I2CLK.1	I2CLK.0
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Mnemonic: I2CLK

Address: BEh

BIT	NAME	FUNCTION
7-0	I2CLK.[7:0]	The I2C clock rate bits.

## I2C TIMER COUNTER REGISTER

Bit:	7	6	5	4	3	2	1	0
	-	-	-	-	-	ENTI	DIV4	TIF

Mnemonic: I2TIMER

Address: BFh

BIT	NAME	FUNCTION
7~3	-	Reserved.
2	ENTI	Enable I2C 14-bits Timer Counter: 0: Disable 14-bits Timer Counter count. 1: Enable 14-bits Timer Counter count. After enable ENTI and ENSI, the 14-bit counter will be counted. When SI flag of I2C is set, the counter will stop to count and 14-bits Timer Counter will be cleared.
1	DIV4	I2C Timer Counter clock source divide function: 0: The 14-bits Timer Counter source clock is $F_{CPU}$ clock. 1: The 14-bits Timer Counter source clock is divided by 4.
0	TIF	The I2C Timer Counter count flag: 0: The 14-bits Timer Counter is not overflow. 1: The 14-bits Timer Counter is overflow. Before enable I2C Timer (both ENTI, ENSI = [1,1]) the SI must be cleared. If I2C interrupt is enabled. The I2C interrupt service routine will be executed. This bit is cleared by software.

## I2C CONTROL REGISTER

Bit:	7	6	5	4	3	2	1	0
	-	ENSI	STA	STO	SI	AA	-	-

Mnemonic: I2CON

Address: C0h

BIT	NAME	FUNCTION
7	-	Reserved.
6	ENSI	0: Disable I2C Serial Function. The SDA and SCL output are in a high impedance state. SDA and SCL input signals are ignored, I2C is not in the addressed slave mode or it is not addressable, and STO bit in I2CON is forced to "0". No other bits are affected. P1.3 (SCL) and P1.2 (SDA) may be used as open drain I/O ports. 1: Enable I2C Serial Function. The P1.2 and P1.3 port latches must be to logic 1.
5	STA	START flag: 0: The STA bit is reset, no START condition or repeated START condition will

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-	NVMADD R.6	NVMADD R.5	NVMADD R.4	NVMADD R.3	NVMADD R.2	NVMADD R.1	NVMADD R.0
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Mnemonic: NVMADDR

Address: C6h

BIT	NAME	FUNCTION
7	-	Reserved
6~0	NVMADDR.[6:0]	The NVM address: The register indicates NVM data memory address on On-Chip code memory space.

## TIMED ACCESS

Bit:	7	6	5	4	3	2	1	0
	TA.7	TA.6	TA.5	TA.4	TA.3	TA.2	TA.1	TA.0

Mnemonic: TA

Address: C7h

BIT	NAME	FUNCTION
7-0	TA.[7:0]	The Timed Access register: The Timed Access register controls the access to protected bits. To access protected bits, the user must first write AAH to the TA. This must be immediately followed by a write of 55H to TA. Now a window is opened in the protected bits for three machine cycles, during which the user can write to these bits.

## TIMER 2 CONTROL

Bit:	7	6	5	4	3	2	1	0
	TF2	EXF2	RCLK	TCLK	EXEN2	TR2	C / $\overline{T2}$	CP / $\overline{RL2}$

Mnemonic: T2CON

Address: C8h

BIT	NAME	FUNCTION
7	TF2	Timer 2 overflow flag: Timer 2 overflow flag: This bit is set when Timer 2 overflows. It is also set when the count is equal to the capture register in down count mode. It can be set only if RCLK and TCLK are both 0. It is cleared only by software. Software can also set or clear this bit.
6	EXF2	Timer 2 External Flag: A negative transition on the T2EX pin (P1.1) or timer 2 overflow will cause this flag to set based on the CP / $\overline{RL2}$ , EXEN2 and DCEN bits. If set by a negative transition, this flag must be cleared by software. Setting this bit in software or detection of a negative transition on T2EX pin will force a timer interrupt if enabled.
5	RCLK	Receive Clock Flag: This bit determines the serial port time-base when receiving data in serial modes 1 or 3. If it is 0, then timer 1 overflow is used for baud rate generation, otherwise timer 2 overflow is used. Setting this bit forces timer 2 in baud rate generator mode.



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		1: Set this bit to write NVM bytes and program counter will halt at this instruction. After write is finished, program counter will kept next instruction then executed.
5	EnNVM	To enable read NVM data memory area. 0: To disable the MOVX instruction to read NVM data memory. 1: To enable the MOVX instruction to read NVM data memory, the External RAM or AUX-RAM will be disabled.
4-0	-	Reserved

## NVM DATA

Bit:	7	6	5	4	3	2	1	0
	NVMDAT. 7	NVMDAT. 6	NVMDAT. 5	NVMDAT. 4	NVMDAT. 3	NVMDAT. 2	NVMDAT. 1	NVMDAT. 0

Mnemonic: NVMDATA

Address: CFh

BIT	NAME	FUNCTION
7~0	NVMDAT.[7:0]	The NVM data write register. The read NVM data is by MOVC instruction.

## PROGRAM STATUS WORD

Bit:	7	6	5	4	3	2	1	0
	CY	AC	F0	RS1	RS0	OV	F1	P

Mnemonic: PSW

Address: D0h

BIT	NAME	FUNCTION
7	CY	Carry flag: Set for an arithmetic operation which results in a carry being generated from the ALU. It is also used as the accumulator for the bit operations.
6	AC	Auxiliary carry: Set when the previous operation resulted in a carry from the high order nibble.
5	F0	User flag 0: The General purpose flag that can be set or cleared by the user.
4~3	RS1~RS0	Register bank select bits.
2	OV	Overflow flag: Set when a carry was generated from the seventh bit but not from the 8th bit as a result of the previous operation, or vice-versa.
1	F1	User Flag 1: The General purpose flag that can be set or cleared by the user software.
0	P	Parity flag: Set/cleared by hardware to indicate odd/even number of 1's in the accumulator.

RS.1-0: Register Bank Selection Bits:

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PCAPH	PBOH	-	PWDIH	-	-	PKBH	PI2H
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Mnemonic: IP1H

Address: F7h

BIT	NAME	FUNCTION
7	PCAPH	1: To set interrupt high priority of Input Capture 0 as highest priority level.
6	PBOH	1: To set interrupt high priority of Brownout is highest priority level.
5	-	Reserved.
4	PWDIH	1: To set interrupt high priority of Watchdog is highest priority level.
3~2	-	Reserved.
1	PKBH	1: To set interrupt high priority of Keypad is highest priority level.
0	PI2H	1: To set interrupt high priority of I2C is highest priority level.

## INTERRUPT PRIORITY 1

Bit:	7	6	5	4	3	2	1	0
	PCAP	PBO	-	PWDI	-	-	PKB	PI2

Mnemonic: IP1

Address: F8h

BIT	NAME	FUNCTION
7	PCAP	1: To set interrupt priority of Input Capture 0 as higher priority level.
6	PBO	1: To set interrupt priority of Brownout is higher priority level.
5	-	Reserved.
4	PWDI	1: To set interrupt priority of Watchdog is higher priority level.
3~2	-	Reserved.
1	PKB	1: To set interrupt priority of Keypad is higher priority level.
0	PI2	1: To set interrupt priority of I2C is higher priority level.



## 9. INSTRUCTION

The N79E352(R) executes all the instructions of the standard 8052 family. The operation of these instructions, their effect on the flag bits and the status bits is exactly the same. However, timing of these instructions is different. The reason for this is two fold. Firstly, in the N79E352(R), each machine cycle consists of 4 clock periods, while in the standard 8052 it consists of 12 clock periods. Also, in the N79E352(R) there is only one fetch per machine cycle i.e. 4 clocks per fetch, while in the standard 8052 there can be two fetches per machine cycle, which works out to 6 clocks per fetch.

The advantage the N79E352(R) has is that since there is only one fetch per machine cycle, the number of machine cycles in most cases is equal to the number of operands that the instruction has. In case of jumps and calls there will be an additional cycle that will be needed to calculate the new address. But overall the N79E352(R) reduces the number of dummy fetches and wasted cycles, thereby improving efficiency as compared to the standard 8052.

Table 9-1: Instructions that affect Flag settings

Instruction	Carry	Overflow	Auxiliary Carry	Instruction	Carry	Overflow	Auxiliary Carry
ADD	X	X	X	CLR C	0		
ADDC	X	X	X	CPL C	X		
SUBB	X	X	X	ANL C, bit	X		
MUL	0	X		ANL C, bit	X		
DIV	0	X		ORL C, bit	X		
DA A	X			ORL C, bit	X		
RRC A	X			MOV C, bit	X		
RLC A	X			CJNE	X		
SETB C	1						

A "X" indicates that the modification is as per the result of instruction.

# Preliminary N79E352/N79E352R Data Sheet



Instruction Timing for N79E352(R), continued

Instruction	HEX Op-Code	Bytes	N79E352(R) Machine Cycles	N79E352(R) Clock Cycles	8052 Clock Cycles	N79E352(R) vs. 8052 Speed Ratio
MOV R1, direct	A9	2	2	8	12	1.5
MOV R2, direct	AA	2	2	8	12	1.5
MOV R3, direct	AB	2	2	8	12	1.5
MOV R4, direct	AC	2	2	8	12	1.5
MOV R5, direct	AD	2	2	8	12	1.5
MOV R6, direct	AE	2	2	8	12	1.5
MOV R7, direct	AF	2	2	8	12	1.5
MOV R0, #data	78	2	2	8	12	1.5
MOV R1, #data	79	2	2	8	12	1.5
MOV R2, #data	7A	2	2	8	12	1.5
MOV R3, #data	7B	2	2	8	12	1.5
MOV R4, #data	7C	2	2	8	12	1.5
MOV R5, #data	7D	2	2	8	12	1.5
MOV R6, #data	7E	2	2	8	12	1.5
MOV R7, #data	7F	2	2	8	12	1.5
MOV @R0, A	F6	1	1	4	12	3
MOV @R1, A	F7	1	1	4	12	3
MOV @R0, direct	A6	2	2	8	12	1.5
MOV @R1, direct	A7	2	2	8	12	1.5
MOV @R0, #data	76	2	2	8	12	1.5
MOV @R1, #data	77	2	2	8	12	1.5
MOV direct, A	F5	2	2	8	12	1.5
MOV direct, R0	88	2	2	8	12	1.5
MOV direct, R1	89	2	2	8	12	1.5
MOV direct, R2	8A	2	2	8	12	1.5
MOV direct, R3	8B	2	2	8	12	1.5
MOV direct, R4	8C	2	2	8	12	1.5
MOV direct, R5	8D	2	2	8	12	1.5
MOV direct, R6	8E	2	2	8	12	1.5
MOV direct, R7	8F	2	2	8	12	1.5
MOV direct, @R0	86	2	2	8	12	1.5
MOV direct, @R1	87	2	2	8	12	1.5
MOV direct, direct	85	3	3	12	24	2
MOV direct, #data	75	3	3	12	24	2
MOV DPTR, #data 16	90	3	3	12	24	2
MOVC A, @A+DPTR	93	1	2	8	24	3

# Preliminary N79E352/N79E352R Data Sheet



Instruction Timing for N79E352(R), continued

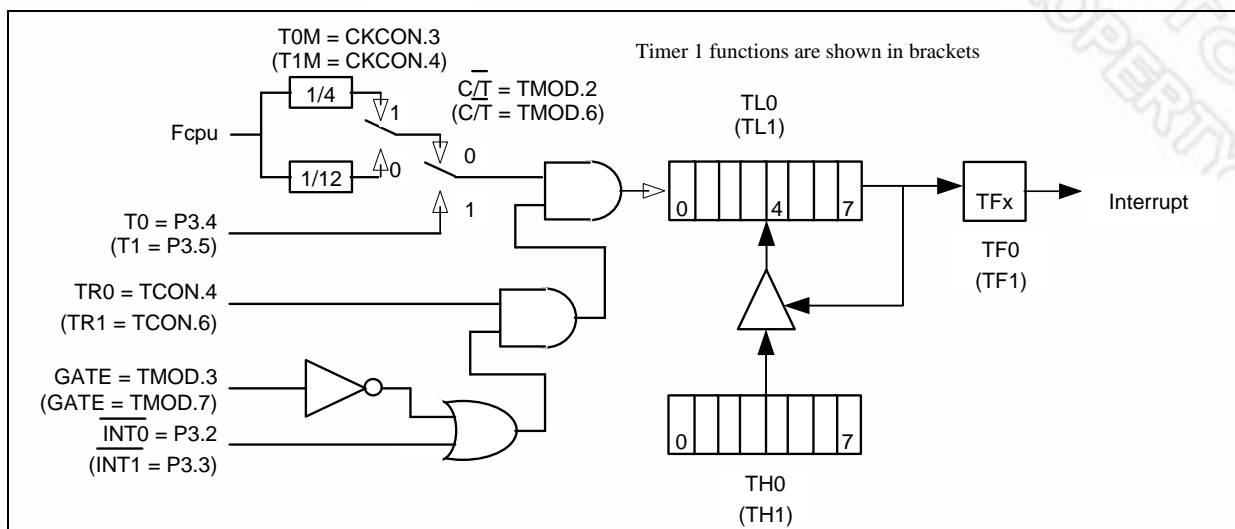
Instruction	HEX Op-Code	Bytes	N79E352(R) Machine Cycles	N79E352(R) Clock Cycles	8052 Clock Cycles	N79E352(R) vs. 8052 Speed Ratio
MOVX A, @R0	E2	1	2 - 9	8 - 36	24	3 - 0.66
MOVX A, @R1	E3	1	2 - 9	8 - 36	24	3 - 0.66
MOVX A, @DPTR	E0	1	2 - 9	8 - 36	24	3 - 0.66
MOVX @R0, A	F2	1	2 - 9	8 - 36	24	3 - 0.66
MOVX @R1, A	F3	1	2 - 9	8 - 36	24	3 - 0.66
MOVX @DPTR, A	F0	1	2 - 9	8 - 36	24	3 - 0.66
MOV C, bit	A2	2	2	8	12	1.5
MOV bit, C	92	2	2	8	24	3
ORL A, R0	48	1	1	4	12	3
ORL A, R1	49	1	1	4	12	3
ORL A, R2	4A	1	1	4	12	3
ORL A, R3	4B	1	1	4	12	3
ORL A, R4	4C	1	1	4	12	3
ORL A, R5	4D	1	1	4	12	3
ORL A, R6	4E	1	1	4	12	3
ORL A, R7	4F	1	1	4	12	3
ORL A, @R0	46	1	1	4	12	3
ORL A, @R1	47	1	1	4	12	3
ORL A, direct	45	2	2	8	12	1.5
ORL A, #data	44	2	2	8	12	1.5
ORL direct, A	42	2	2	8	12	1.5
ORL direct, #data	43	3	3	12	24	2
ORL C, bit	72	2	2	8	24	3
ORL C, /bit	A0	2	2	6	24	3
PUSH direct	C0	2	2	8	24	3
POP direct	D0	2	2	8	24	3
RET	22	1	2	8	24	3
RETI	32	1	2	8	24	3
RL A	23	1	1	4	12	3
RLC A	33	1	1	4	12	3
RR A	03	1	1	4	12	3
RRC A	13	1	1	4	12	3
SETB C	D3	1	1	4	12	3
SETB bit	D2	2	2	8	12	1.5
SWAP A	C4	1	1	4	12	3
SJMP rel	80	2	3	12	24	2
SUBB A, R0	98	1	1	4	12	3

## 12.2.2 Mode 1

Mode 1 is similar to Mode 0 except that the counting register forms a 16 bit counter, rather than a 13 bit counter. This means that all the bits of THx and TLx are used. Roll-over occurs when the timer moves from a count of FFFFh to 0000h. The timer overflow flag TFX of the relevant timer is set and if enabled an interrupt will occur. The selection of the time-base in the timer mode is similar to that in Mode 0. The gate function operates similarly to that in Mode 0.

## 12.2.3 Mode 2

In Mode 2, the timer/counter is in the Auto Reload Mode. In this mode, TLx acts as a 8 bit count register, while THx holds the reload value. When the TLx register overflows from FFh to 00h, the TFX bit in TCON is set and TLx is reloaded with the contents of THx, and the counting process continues from here. The reload operation leaves the contents of the THx register unchanged. Counting is enabled by the TRx bit and proper setting of  $\overline{\text{INTx}}$  pins. As in the other two modes 0 and 1 mode 2 allows counting of either clock cycles (clock/12 or clock/4) or pulses on pin Tn.



## 12.2.4 Mode 3

Mode 3 has different operating methods for the two timer/counters. For timer/counter 1, mode 3 simply freezes the counter. Timer/Counter 0, however, configures TL0 and TH0 as two separate 8 bit count registers in this mode. The logic for this mode is shown in the figure. TL0 uses the Timer/Counter 0 control bits  $\text{C}/\overline{\text{T}}$ , GATE, TR0,  $\overline{\text{INT0}}$  and TF0. The TL0 can be used to count clock cycles (clock/12 or clock/4) or 1-to-0 transitions on pin T0 as determined by  $\text{C}/\overline{\text{T}}$  (TMOD.2). TH0 is forced as a clock cycle counter (clock/12 or clock/4) and takes over the use of TR1 and TF1 from Timer/Counter 1. Mode 3 is used in cases where an extra 8 bit timer is needed. With Timer 0 in Mode 3, Timer 1 can still be used in Modes 0, 1 and 2., but its flexibility is somewhat limited. While its basic functionality is maintained, it no longer has control over its overflow flag TF1 and the enable bit TR1. Timer 1 can still be used as a timer/counter and retains the use of GATE and INT1 pin. In this condition it can be turned on and off by switching it out of and into its own Mode 3. It can also be used as a baud rate generator for the serial port.

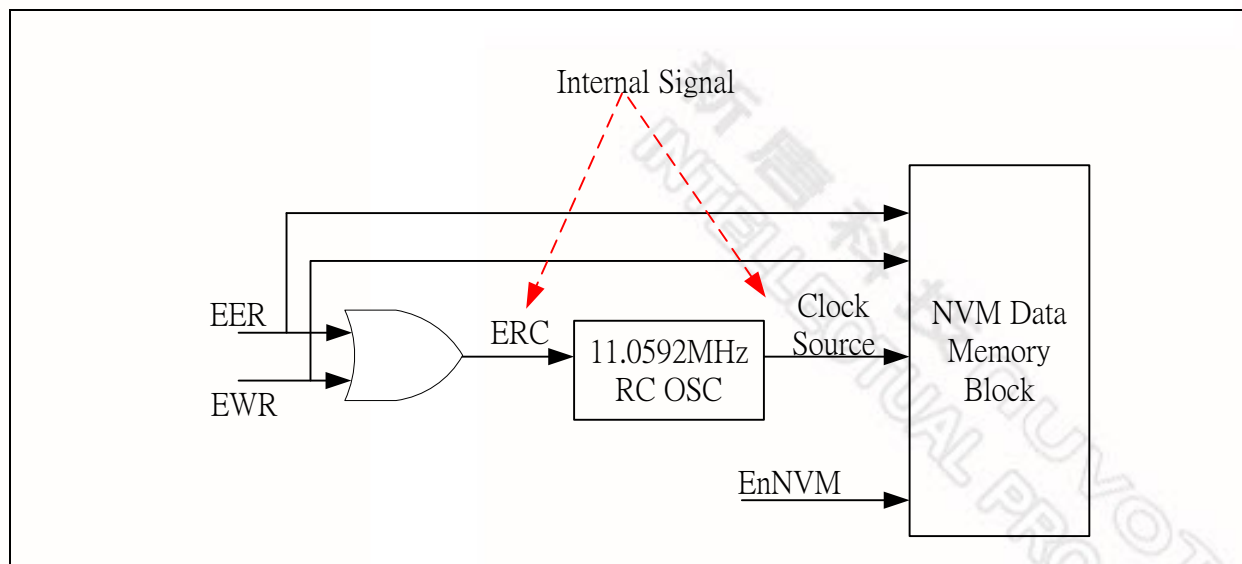


Figure 13-1: NVM control

Instructions	EnNVM = 0	EnNVM = 1	
		Addr within NVM address range	Addr out of NVM address range
MOVX A, @DPTR (Read)	Ext memory	NVM	Ext memory
MOVX A, @R0 (Read)	Ext memory	NVM	Ext memory <sup>[1]</sup>
MOVX A, @R1 (Read)	Ext memory	NVM	Ext memory <sup>[1]</sup>
MOVX @DPTR, A (Write)	Ext memory	Ext memory	Ext memory
MOVX @R0, A (Write)	Ext memory	Ext memory <sup>[1]</sup>	Ext memory <sup>[1]</sup>
MOVX @R1, A (Write)	Ext memory	Ext memory <sup>[1]</sup>	Ext memory <sup>[1]</sup>

Table 13-2: MOVX read/write access destination

Note: 1. Higher address bytes will come from SFR port 2 values.

For security purposes this NVM data flash provide an independent “Lock bit” located in Security bits, it is used to protect the customer’s data code in NVM. It may be enabled in CONFIG1.6 after the programmer finishes the programming and verifies sequence. Once this bit is set to logic 0, NVM Flash EPROM data can not be accessed again by hardware writer mode.

## 14. WATCHDOG TIMER

The Watchdog Timer is a free-running Timer which can be programmed by the user to serve as a system monitor, a time-base generator or an event timer. It is basically a set of dividers that divide the system clock. The divider output is selectable and determines the time-out interval. When the time-out occurs a flag is set, which can cause an interrupt if enabled, and a system reset can also be caused if it is enabled. The interrupt will occur if the individual interrupt enable and the global enable are set. The interrupt and reset functions are independent of each other and may be used separately or together depending on the user's software.

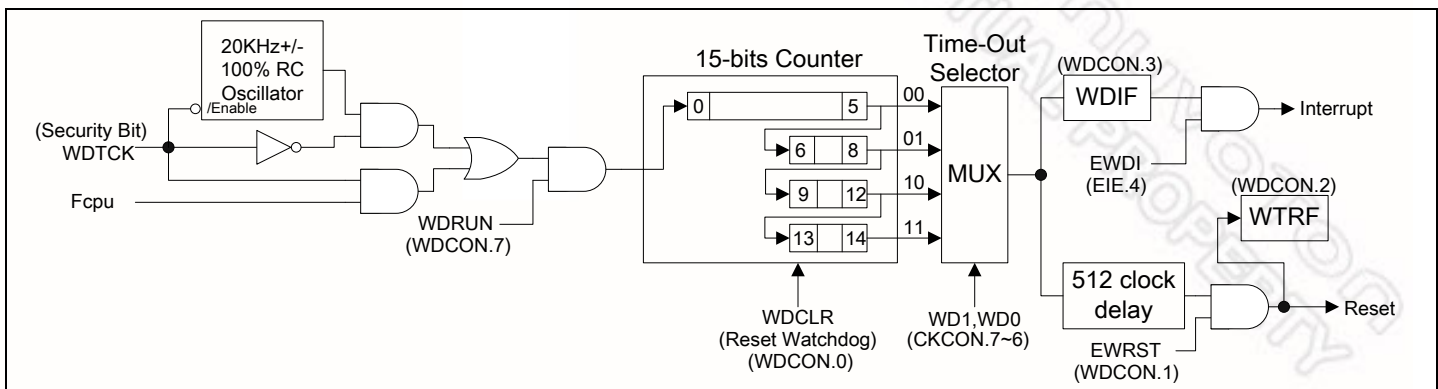


Figure 14-1: Watchdog Timer

The Watchdog Timer should first be restarted by using WDCLR. This ensures that the timer starts from a known state. The WDCLR bit is used to restart the Watchdog Timer. This bit is self clearing, i.e. after writing a 1 to this bit the software will automatically clear it. The Watchdog Timer will now count clock cycles. The time-out interval is selected by the two bits WD1 and WD0 (CKCON.7 and CKCON.6). When the selected time-out occurs, the Watchdog interrupt flag WDIF (WDCON.3) is set. After the time-out has occurred, the Watchdog Timer waits for an additional 512 clock cycles. If the Watchdog Reset EWRST (WDCON.1) is enabled, then 512 clocks after the time-out, if there is no WDCLR, a system reset due to Watchdog Timer will occur. This will last for two machine cycles, and the Watchdog Timer reset flag WTRF (WDCON.2) will be set. This indicates to the software that the Watchdog was the cause of the reset.

When used as a simple timer, the reset and interrupt functions are disabled. The timer will set the WDIF flag each time the timer completes the selected time interval. The WDIF flag is polled to detect a time-out and the WDCLR allows software to restart the timer. The Watchdog Timer can also be used as a very long timer. The interrupt feature is enabled in this case. Every time the time-out occurs an interrupt will occur if the global interrupt enable EA is set.

The main use of the Watchdog Timer is as a system monitor. This is important in real-time control applications. In case of some power glitches or electro-magnetic interference, the processor may begin to execute errant code. If this is left unchecked the entire system may crash. Using the watchdog timer interrupt during software development will allow the user to select ideal watchdog reset locations. The code is first written without the watchdog interrupt or reset. Then the Watchdog interrupt is enabled to identify code locations where interrupt occurs. The user can now insert instructions to reset the Watchdog Timer, which will allow the code to run without any Watchdog Timer interrupts. Now the Watchdog Timer reset is enabled and the Watchdog interrupt may be disabled. If any errant code is





If these conditions are met, then the stop bit goes to RB8, the 8 data bits go into SBUF and RI is set. Otherwise the received frame may be lost. After the middle of the stop bit, the receiver goes back to looking for a 1-to-0 transition on the RxD pin.

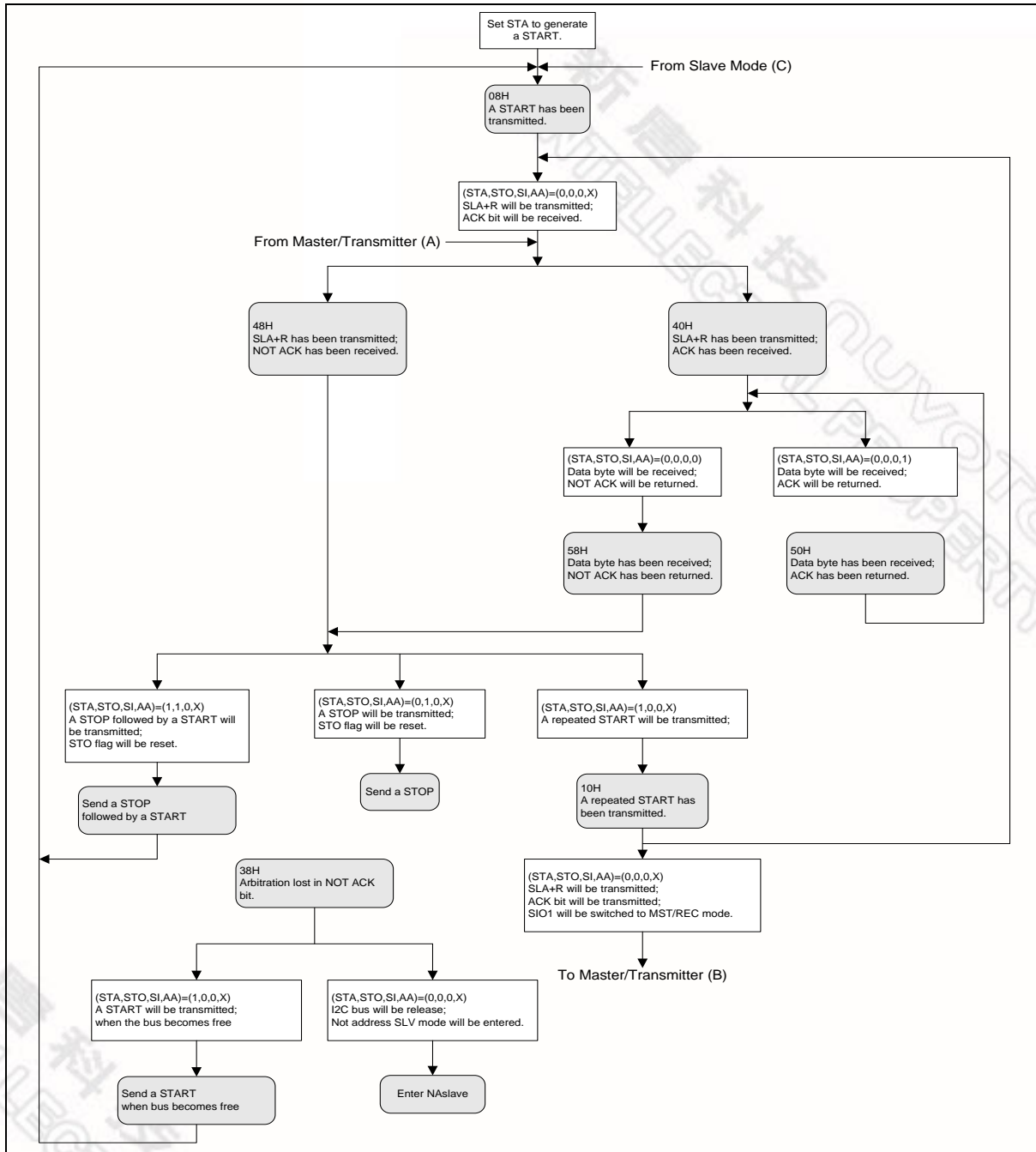


Figure 16-5: Master Receiver Mode

## 23. OSCILLATOR

N79E352(R) provides three oscillator input option. These are configured at CONFIG register (CONFIG0) that include On-Chip RC Oscillator Option, External Clock Input Option and Crystal Oscillator Input Option. The Crystal Oscillator Input frequency may be supported from 4MHz to 24MHz, and without capacitor or resistor.

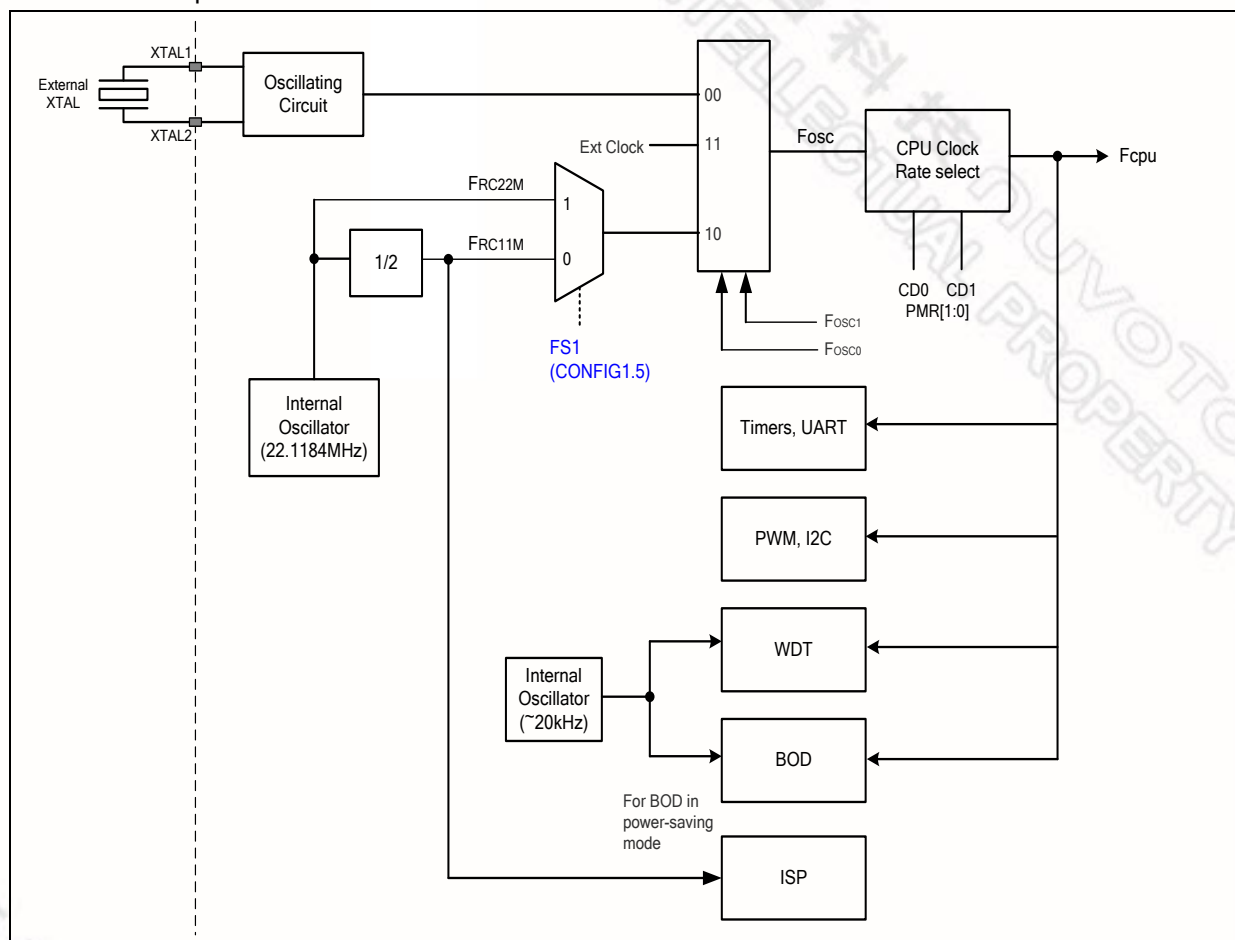


Figure 23-1: Oscillator

### 23.1 On-Chip RC Oscillator Option

The On-Chip RC Oscillator is fixed at 11.0592MHz or 22.1184MHz (selectable by FS1 config bit)  $\pm 2\%$  for N79E352R,  $\pm 25\%$  for N79E352 frequency to support clock source. When FOSC1, FOSC0 = 01b, the On-Chip RC Oscillator is enabled.

### 23.2 External Clock Input Option

The clock source pin (XTAL1) is from External Clock Input by FOSC1, FOSC0 = 11b, and frequency range is from 0Hz up to 24MHz.

The device supports a clock output function when either the on-chip RC oscillator or external clock input options are selected. This allows external devices to synchronize to the device. When enabled, via the ENCLK bit in the P5M1 register, the clock output appears on the XTAL2/CLKOUT pin whenever the on-chip oscillator is running, including in Idle Mode. The frequency of the clock output is 1/4 of the CPU clock rate. If the clock output is not needed in Idle Mode, it may be turned off prior to entering



0	Fosc0	CPU Oscillator Type select bit 0.
---	-------	-----------------------------------

Oscillator Configuration bits:

Fosc1	Fosc0	OSC source
0	0	4MHz ~ 24MHz crystal
0	1	Internal RC Oscillator (FS1 bit in CONFIG1.5 will determine either 11.0592MHz or 22.1184MHZ)
1	0	Reserved
1	1	External Oscillator in XTAL1; XALT2 is in Tri-state

## 26.2 CONFIG1

	7	6	5	4	3	2	1	0
	C7	C6	FS1	-	CBOV.1-0		C1	-
C7	: 8/4K Flash EPROM Code Lock Bit							
C6	: 512/256/128/64 byte Data Lock Bit							
FS1	: Internal RC 11.0592MHz/22.1184MHz Selection Bit							
CBOV.1-0	: Brownout Level Selection Bits							
C1	: Movc Inhibit Enable Bit							

Figure 25-2: Config1 register bits

### C7: 8K Flash EPROM Lock bit

This bit is used to protect the customer's program code. It may be set after the programmer finishes the programming and verifies sequence. Once this bit is set to logic 0, both the Flash EPROM data and CONFIG Registers can not be accessed again.

### C6: 128 byte Data Flash EPROM Lock bit

This bit is used to protect the customer's 128 bytes of data code. It may be set after the programmer finishes the programming and verifies sequence. Once this bit is set to logic 0, both the 128 bytes of Flash EPROM data and CONFIG Registers can not be accessed again.

Bit 7	Bit 6	Function Description
1	1	Both security of 8KB program code and 128 Bytes data area are not locked. They can be erased, programmed or read by Writer or JTAG mode.
0	1	The 8KB program code area is locked. It can not be read and written by Writer or JTAG mode. The 128 Bytes data area can be program or read. The bank erase is invalid.
1	0	Not supported.
0	0	Both security of 8KB program code and 128 Bytes data area are locked. They can not be read and written by Writer or JTAG mode.

### FS1: Internal Oscillator selection bit

This bit is used to select internal oscillator.

### 27.3.1 External Clock Characteristics

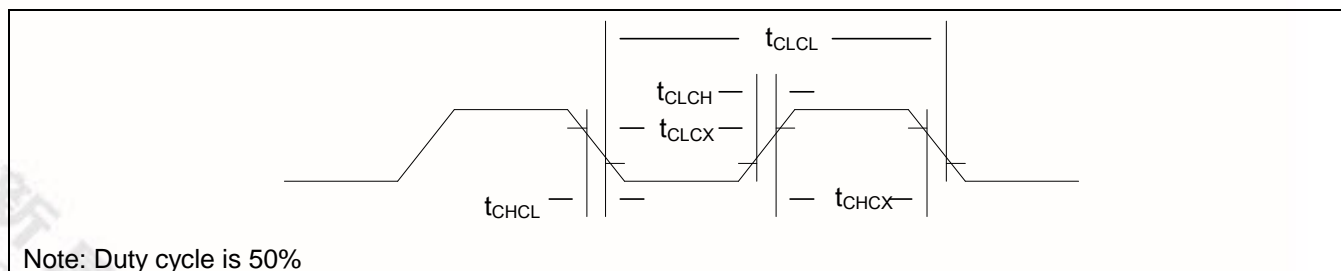
PARAMETER	SYMBOL	MIN.	TYP.	MAX.	UNITS	NOTES
Clock High Time	$t_{CHCX}$	22.6	-	-	nS	
Clock Low Time	$t_{CLCX}$	22.6	-	-	nS	
Clock Rise Time	$t_{CLCH}$	-	-	10	nS	
Clock Fall Time	$t_{CHCL}$	-	-	10	nS	

### 27.3.2 AC Specification

PARAMETER	SYMBOL	VARIABLE CLOCK MIN.	VARIABLE CLOCK MAX.	UNITS
Oscillator Frequency	$1/t_{CLCL}$	0	24	MHz

### 27.3.3 External clock Characteristics

PARAMETER	SYMBOL	MIN	TYP	MAX	UNITS	NOTES
Clock High Time	$t_{CHCX}$	12.5			ns	
Clock Low Time	$t_{CLCX}$	12.5			ns	
Clock Rise Time	$t_{CLCH}$			10	ns	
Clock Fall Time	$t_{CHCL}$			10	ns	



Note: Duty cycle is 50%

Figure 26-1 External clock characteristics

### 27.3.4 Serial Port Mode 0 Timing Characteristics

PARAMETER	SYMBOL	MIN	TYP	MAX	UNITS	NOTES
Serial Port Clock Cycle Time SM2=0 12 clocks per cycle SM2=1 4 clocks per cycle	$t_{XLXL}$		12 $t_{CLCL}$ 4 $t_{CLCL}$		ns	
Output Data Setup to Clock Rising Edge SM2=0 12 clocks per cycle SM2=1 4 clocks per cycle	$t_{QVXH}$		10 $t_{CLCL}$ 3 $t_{CLCL}$		ns	

Output Data Hold to Clock Rising Edge SM2=0 12 clocks per cycle SM2=1 4 clocks per cycle	$t_{XHGX}$		$2 t_{CLCL}$ $t_{CLCL}$	ns	
Input Data Hold after Clock Rising Edge SM2=0 12 clocks per cycle SM2=1 4 clocks per cycle	$t_{XHDX}$		$t_{CLCL}$ $t_{CLCL}$	ns	
Clock Rising Edge to Input Data Valid SM2=0 12 clocks per cycle SM2=1 4 clocks per cycle	$t_{XHDV}$		$11 t_{CLCL}$ $3 t_{CLCL}$	ns	

### 27.3.5 Program Memory Read Cycle

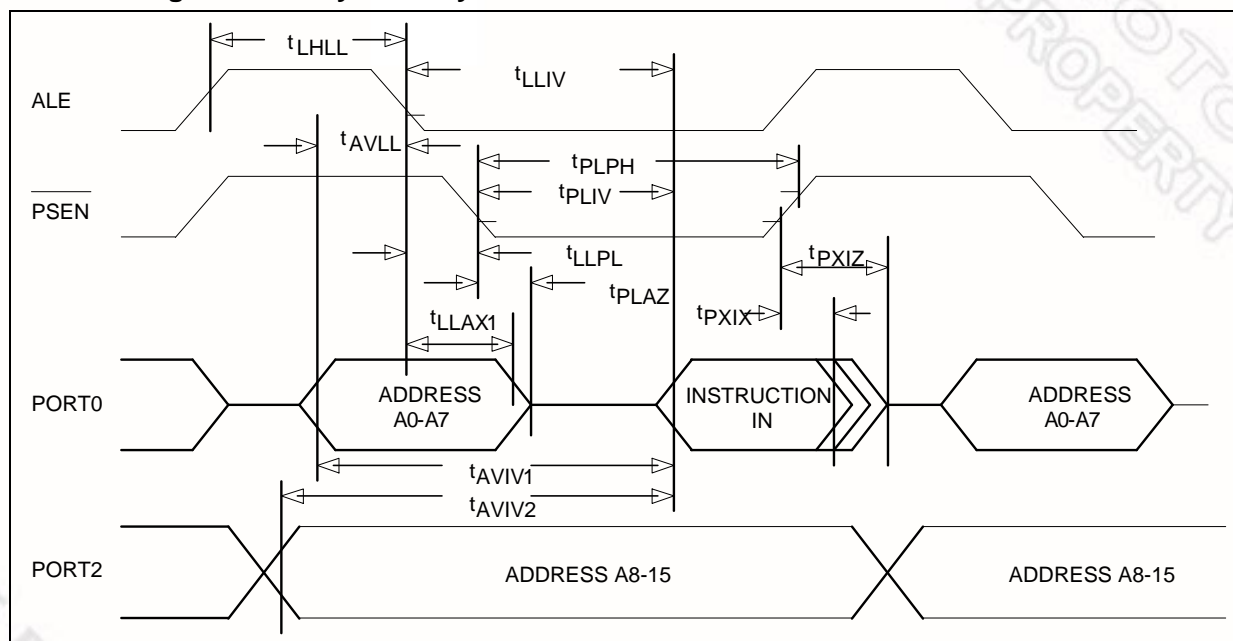


Figure 26-2 Program Memory Read Cycle



### 28.3 44-pin PQFP

