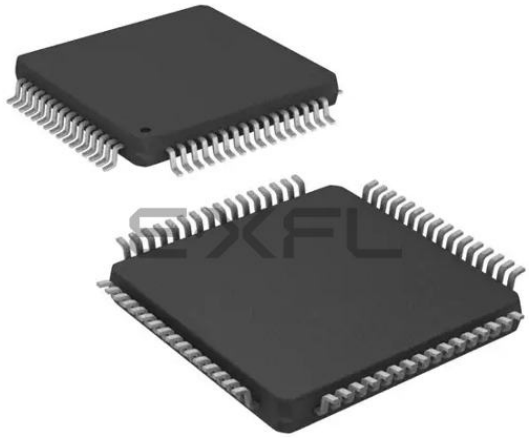

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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	ARM® Cortex®-M3
Core Size	32-Bit Single-Core
Speed	80MHz
Connectivity	EBI/EMI, I²C, IrDA, SmartCard, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, I²S, POR, PWM, WDT
Number of I/O	50
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 28x12b; D/A 2x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-TQFP
Supplier Device Package	64-TQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/sim3c146-b-gq

2. Typical Connection Diagrams

This section provides typical connection diagrams for SiM3C1xx devices.

2.1. Power

Figure 2.1 shows a typical connection diagram for the power pins of the SiM3C1xx devices when the internal regulator is in use.

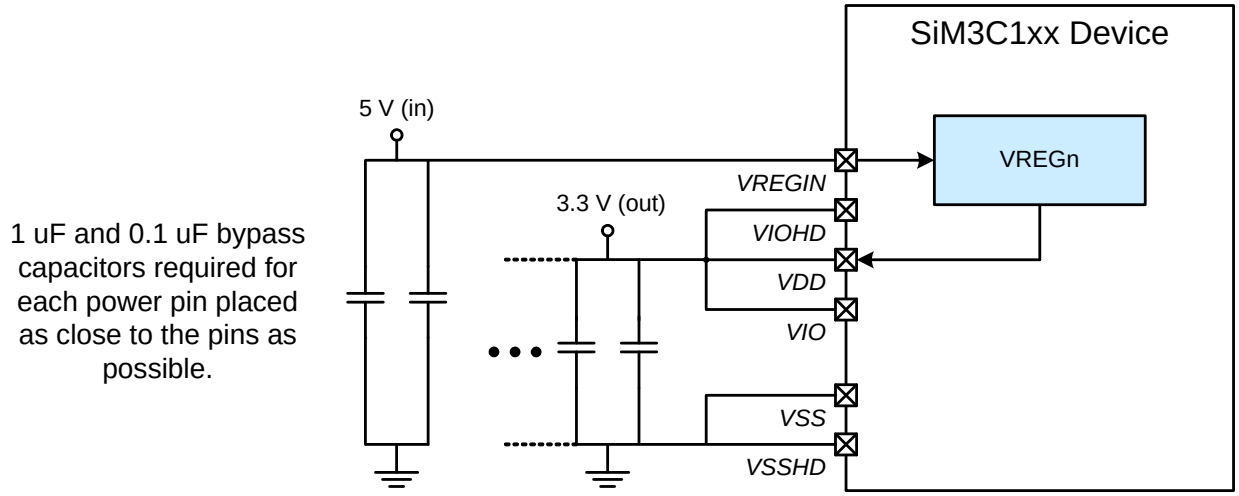


Figure 2.1. Connection Diagram with Voltage Regulator Used

Figure 2.2 shows a typical connection diagram for the power pins of the SiM3C1xx devices when the internal regulator is not used.

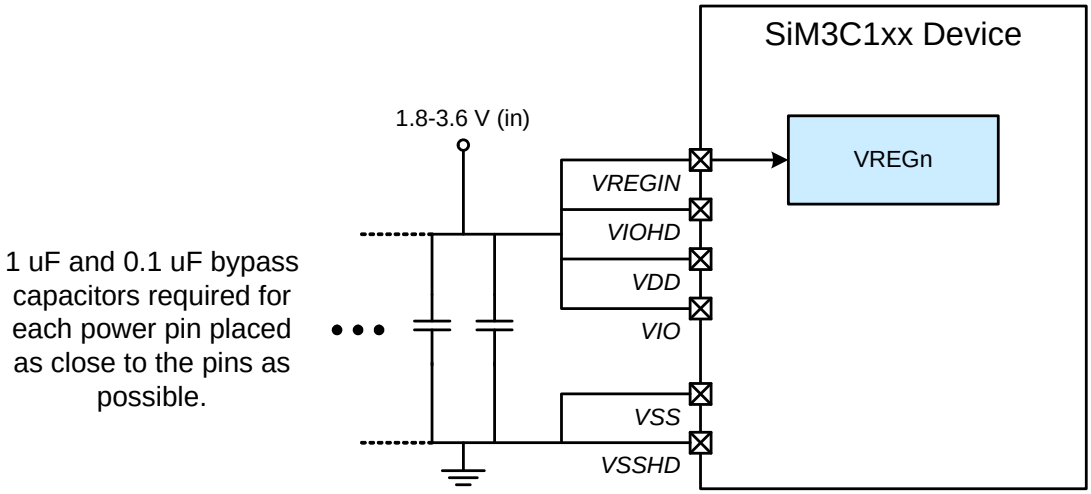


Figure 2.2. Connection Diagram with Voltage Regulator Not Used

Table 3.2. Power Consumption (Continued)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
External Oscillator (EXTOSC0)[8]	I_{EXTOSC}	FREQCN = 111	—	3.8	4.7	mA
		FREQCN = 110	—	840	950	µA
		FREQCN = 101	—	185	220	µA
		FREQCN = 100	—	65	80	µA
		FREQCN = 011	—	25	30	µA
		FREQCN = 010	—	10	15	µA
		FREQCN = 001	—	5	10	µA
		FREQCN = 000	—	3	8	µA
SARADC0, SARADC1	I_{SARADC}	Sampling at 1 Msps, highest power mode settings.	—	1.2	1.5	mA
		Sampling at 250 ksps, lowest power mode settings.	—	390	510	µA
Temperature Sensor	I_{TSENSE}		—	75	105	µA
Internal SAR Reference	I_{REFFS}	Normal Power Mode	—	680	750	µA
		Low Power Mode	—	160	190	µA
VREF0	I_{REFP}		—	75	100	µA
Comparator 0 (CMP0), Comparator 1 (CMP1)	I_{CMP}	CMPMD = 11	—	0.5	—	µA
		CMPMD = 10	—	3	—	µA
		CMPMD = 01	—	10	—	µA
		CMPMD = 00	—	25	—	µA
Capacitive Sensing (CAPSENSE0)	I_{CS}	Continuous Conversions	—	55	80	µA
IDAC0[7], IDAC1[7]	I_{IDAC}		—	75	90	µA
IVC0[7]	I_{IVC}	I_{IN} = 0	—	1.5	2.5	µA
Voltage Supply Monitor (VMON0)	I_{VMON}		—	15	25	µA

Notes:

1. Perhipheral currents drop to zero when peripheral clock and peripheral are disabled, unless otherwise noted.
2. Currents are additive. For example, where I_{DD} is specified and the mode is not mutually exclusive, enabling the functions increases supply current by the specified amount.
3. Includes all peripherals that cannot have clocks gated in the Clock Control module.
4. Includes supply current from internal regulator and PLL0OSC (>20 MHz) or LPOSC0 (<=20 MHz).
5. Flash execution numbers use 2 wait states for 80 MHz and 0 wait states at 20 MHz or less.
6. RAM execution numbers use 0 wait states for all frequencies.
7. IDAC output current and IVC input current not included.
8. Bias current only. Does not include dynamic current from oscillator running at speed.

4. Precision32™ SiM3C1xx System Overview

The SiM3C1xx Precision32™ devices are fully integrated, mixed-signal system-on-a-chip MCUs. Highlighted features are listed below. Refer to Table 5.1 for specific product feature selection and part ordering numbers.

- **Core:**
  - 32-bit ARM Cortex-M3 CPU.
  - 80 MHz maximum operating frequency.
  - Branch target cache and prefetch buffers to minimize wait states.
- **Memory:** 32–256 kB Flash; in-system programmable, 8–32 kB SRAM (including 4 kB retention SRAM, which preserves state in PM9 mode).
- **Power:**
  - Low drop-out (LDO) regulator for CPU core voltage.
  - Power-on reset circuit and brownout detectors.
  - 3.3 V output LDO for direct power from 5 V supplies.
  - External transistor regulator.
  - Power Management Unit (PMU).
- **I/O: Up to 65 total multifunction I/O pins:**
  - Up to six programmable high-power capable (5–300 mA with programmable current limiting, 1.8–5 V).
  - Up to twelve 5 V tolerant general purpose pins.
  - Two flexible peripheral crossbars for peripheral routing.
- **Clock Sources:**
  - Internal oscillator with PLL: 23–80 MHz with ± 1.5% accuracy in free-running mode.
  - Low-power internal oscillator: 20 MHz and 2.5 MHz modes.
  - Low-frequency internal oscillator: 16.4 kHz.
  - External RTC crystal oscillator: 32.768 kHz.
  - External oscillator: Crystal, RC, C, CMOS clock modes.
  - Programmable clock divider allows any oscillator source to be divided by binary factor from 1-128.
- **Data Peripherals:**
  - 16-Channel DMA Controller.
  - 128/192/256-bit Hardware AES Encryption.
  - 16/32-bit CRC.
- **Timers/Counters and PWM:**
  - 6-channel Enhanced Programmable Counter Array (EPCAn) supporting advanced PWM and capture/compare.
  - 2 x 2-channel Standard Programmable Counter Array (PCAn) supporting PWM and capture/compare.
  - 2 x 32-bit Timers - can be split into 4 x 16-bit Timers, support PWM and capture/compare.
  - Real Time Clock (RTCn).
  - Low Power Timer.
  - Watchdog Timer.
- **Communications Peripherals:**
  - External Memory Interface.
  - 2 x USARTs and 2 x UARTs with IrDA and ISO7816 SmartCard support.
  - 3 x SPIs.
  - 2 x I2C.
  - I^2S (receive and transmit).
- **Analog:**
  - 2 x 12-Bit Analog-to-Digital Converters (SARADC).
  - 2 x 10-Bit Digital-to-Analog Converter (IDAC).
  - 16-Channel Capacitance-to-Digital Converter (CAPSENSE).
  - 2 x Low-Current Comparators (CMP).
  - 1 x Current-to-Voltage Converter (IVC) module with two channels.
- **On-Chip Debugging**

With on-chip power-on reset, voltage supply monitor, watchdog timer, and clock oscillator, the SiM3C1xx devices are truly standalone system-on-a-chip solutions. The Flash memory is reprogrammable in-circuit, providing non-

4.1. Power

4.1.1. LDO and Voltage Regulator (VREG0)

The SiM3C1xx devices include two internal regulators: the core LDO Regulator and the Voltage Regulator (VREG0).

The LDO Regulator converts a 1.8–3.6 V supply to the core operating voltage of 1.8 V. This LDO consumes little power and provides flexibility in choosing a power supply for the system.

The Voltage Regulator regulates from 5.5 to 2.7 V and can serve as an input to the LDO. This allows the device to be powered from up to a 5.5 V supply without any external components other than bypass capacitors.

4.1.2. Voltage Supply Monitor (VMON0)

The SiM3C1xx devices include a voltage supply monitor which allows devices to function in known, safe operating condition without the need for external hardware. The supply monitor includes additional circuitry that can monitor the main supply voltage and the VREGIN input voltage divided by 4 (VREGIN / 4).

The supply monitor module includes the following features:

- Main supply “VDD Low” (VDD below the early warning threshold) notification.
- Holds the device in reset if the main VDD supply drops below the VDD Reset threshold.
- VREGIN divided by 4 (VREGIN / 4) supply “VREGIN Low” notification.

4.1.3. External Regulator (EXTVREG0)

The External Regulator provides all the circuitry needed for a high-power regulator except the power transistor (NPN or PNP) and current sensing resistor (if current limiting is enabled).

The External Regulator module has the following features:

- Interfaces with either an NPN or PNP external transistor that serves as the pass device for the high current regulator.
- Automatic current limiting.
- Automatic foldback limiting.
- Sources up to 1 A for use by external circuitry.
- Variable output voltage from 1.8–3.6 V in 100 mV steps.

4.1.4. Power Management Unit (PMU)

The Power Management Unit on the SiM3C1xx manages the power systems of the device. On power-up, the PMU ensures the core voltages are a proper value before core instruction execution begins. It also recognizes and manages the various wake sources for low-power modes of the device.

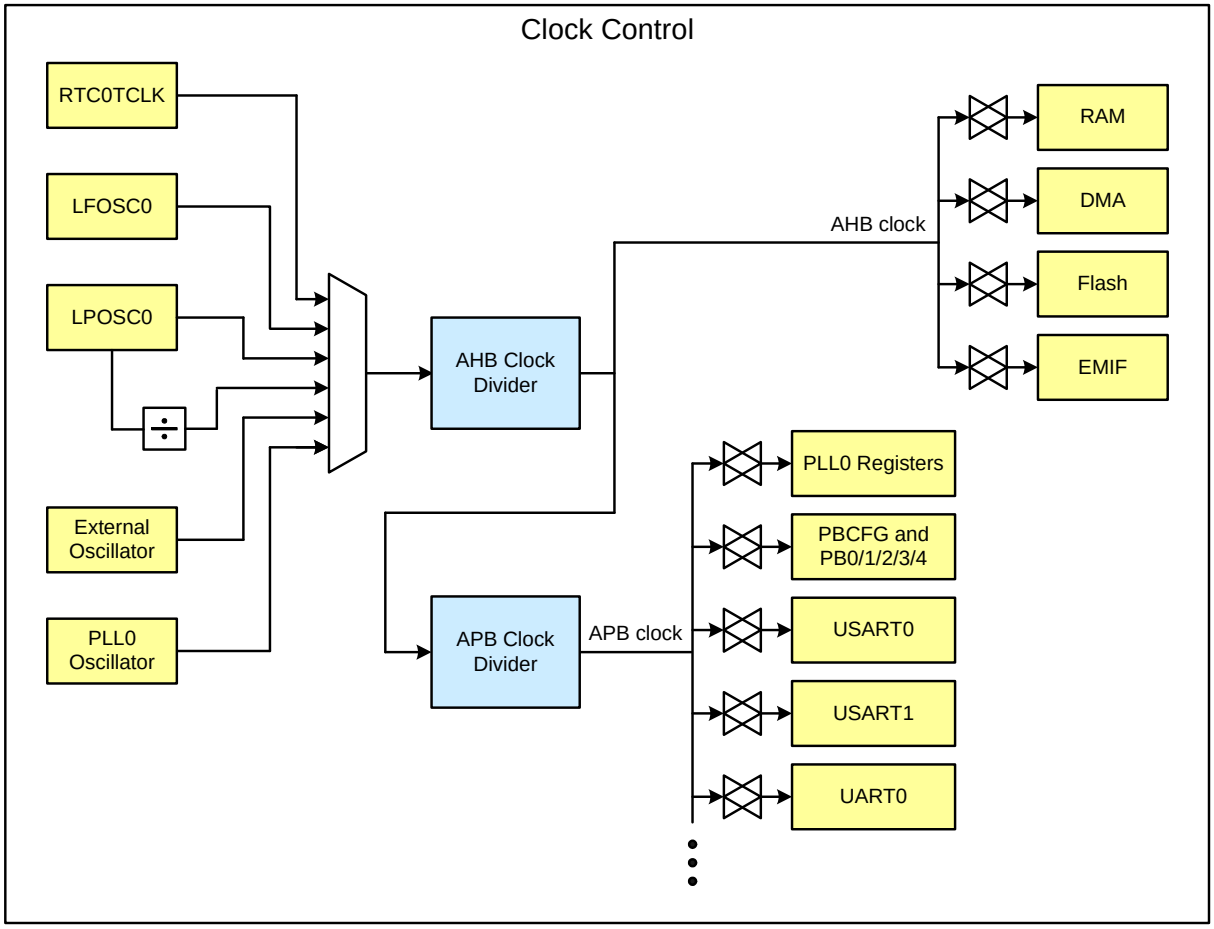
The PMU module includes the following features:

- Up to 16 pin wake inputs can wake the device from Power Mode 9.
- The Low Power Timer, RTC0 (alarms and oscillator fail), Comparator 0, and the $\overline{\text{RESET}}$ pin can also serve as wake sources for Power Mode 9.
- All PM9 wake sources (except for the $\overline{\text{RESET}}$ pin) can also reset the Low Power Timer or RTC0 modules.
- Disables the level shifters to pins and peripherals to further reduce power usage in PM9. These level shifters must be re-enabed by firmware after exiting PM9.
- Provides a PMU_Asleep signal to a pin as an indicator that the device is in PM9.

4.3. Clocking

The SiM3C1xx devices have two system clocks: AHB and APB. The AHB clock services memory peripherals and is derived from one of seven sources: the RTC0 timer clock (RTC0TCLK), the Low Frequency Oscillator, the Low Power Oscillator, the divided Low Power Oscillator, the External Oscillator, and the PLL0 Oscillator. In addition, a divider for the AHB clock provides flexible clock options for the device. The APB clock services data peripherals and is synchronized with the AHB clock. The APB clock can be equal to the AHB clock (if AHB is less than or equal to 50 MHz) or set to the AHB clock divided by two.

Clock Control allows the AHB and APB clocks to be turned off to unused peripherals to save system power. Any registers in a peripheral with disabled clocks will be unable to be accessed until the clocks are enabled. Most peripherals have clocks off by default after a power-on reset.



4.3.1. PLL (PLL0)

The PLL module consists of a dedicated Digitally-Controlled Oscillator (DCO) that can be used in Free-Running mode without a reference frequency, Frequency-Locked to a reference frequency, or Phase-Locked to a reference frequency. The reference frequency for Frequency-Lock and Phase-Lock modes can use one of multiple sources (including the external oscillator) to provide maximum flexibility for different application needs. Because the PLL module generates its own clock, the DCO can be locked to a particular reference frequency and then moved to Free-Running mode to reduce system power and noise.

The PLL module includes the following features:

- Five output ranges with output frequencies ranging from 23 to 80 MHz.
- Multiple reference frequency inputs.
- Three output modes: free-running DCO, frequency-locked, and phase-locked.
- Ability to sense the rising edge or falling edge of the reference source.
- DCO frequency LSB dithering to provide finer average output frequencies.
- Spectrum spreading to reduce generated system noise.
- Low jitter and fast lock times.
- Ability to suspend all output frequency updates (including dithering and spectrum spreading) using the STALL bit during jitter-sensitive operations.

4.3.2. Low Power Oscillator (LPOSC0)

The Low Power Oscillator is the default AHB oscillator on SiM3C1xx devices and enables or disables automatically, as needed.

The Low Power Oscillator has the following features:

- 20 MHz and divided 2.5 MHz frequencies available for the AHB clock.
- Automatically starts and stops as needed.

4.3.3. Low Frequency Oscillator (LFOSC0)

The low frequency oscillator (LFOSC0) provides a low power internal clock source running at approximately 16.4 kHz for the RTC0 timer and other peripherals on the device. No external components are required to use the low frequency oscillator

4.3.4. External Oscillators (EXTOSC0)

The EXTOSC0 external oscillator circuit may drive an external crystal, ceramic resonator, capacitor, or RC network. A CMOS clock may also provide a clock input. The external oscillator output may be selected as the AHB clock or used to clock other modules independent of the AHB clock selection.

The External Oscillator control has the following features:

- Support for external crystal, RC, C, or CMOS oscillators.
- Support external CMOS frequencies from 10 kHz to 50 MHz and external crystal frequencies from 10 kHz to 30 MHz.
- Various drive strengths for flexible crystal oscillator support.
- Internal frequency divide-by-two option available.

4.6. Communications Peripherals

4.6.1. External Memory Interface (EMIF0)

The External Memory Interface (EMIF0) allows external parallel asynchronous devices, like SRAMs and LCD controllers, to appear as part of the system memory map. The EMIF0 module includes the following features:

- Provides a memory mapped view of multiple external devices.
- Support for byte, half-word and word accesses regardless of external device data-width.
- Error indicator for certain invalid transfers.
- Minimum external timing allows for 3 clocks per write or 4 clocks per read.
- Output bus can be shared between non-muxed and muxed devices.
- Available extended address output allows for up to 24-bit address with 8-bit parallel devices.
- Support for 8-bit and 16-bit (muxed-mode only) devices with up to two chip-select signals.
- Support for internally muxed devices with dynamic address shifting.
- Fully programmable control signal waveforms.

4.6.2. USART (USART0, USART1)

The USART uses two signals (TX and RX) and a predetermined fixed baud rate to communicate with a single device. In addition to these signals, the USART0 module can optionally use a clock (UCLK) or hardware handshaking (RTS and CTS).

The USART module provides the following features:

- Independent transmitter and receiver configurations with separate 16-bit baud rate generators.
- Synchronous or asynchronous transmissions and receptions.
- Clock master or slave operation with programmable polarity and edge controls.
- Up to 5 Mbaud (synchronous or asynchronous, TX or RX, and master or slave) or 1 Mbaud Smartcard (TX or RX).
- Individual enables for generated clocks during start, stop, and idle states.
- Internal transmit and receive FIFOs with flush capability and support for byte, half-word, and word reads and writes.
- Data bit lengths from 5 to 9 bits.
- Programmable inter-packet transmit delays.
- Auto-baud detection with support for the LIN SYNC byte.
- Automatic parity generation (with enable).
- Automatic start and stop generation (with separate enables).
- Transmit and receive hardware flow-control.
- Independent inversion correction for TX, RX, RTS, and CTS signals.
- IrDA modulation and demodulation with programmable pulse widths.
- Smartcard ACK/NACK support.
- Parity error, frame error, overrun, and underrun detection.
- Multi-master and half-duplex support.
- Multiple loop-back modes supported.
- Multi-processor communications support.

4.6.3. UART (UART0, UART1)

The USART uses two signals (TX and RX) and a predetermined fixed baud rate to communicate with a single device.

The UART module provides the following features:

- Independent transmitter and receiver configurations with separate 16-bit baud-rate generators.
- Asynchronous transmissions and receptions.
- Up to 5 Mbaud (TX or RX) or 1 Mbaud Smartcard (TX or RX).

- Internal transmit and receive FIFOs with flush capability and support for byte, half-word, and word reads and writes.
- Data bit lengths from 5 to 9 bits.
- Programmable inter-packet transmit delays.
- Auto-baud detection with support for the LIN SYNC byte.
- Automatic parity generation (with enable).
- Automatic start and stop generation.
- Transmit and receive hardware flow-control.
- Independent inversion correction for TX, RX, RTS, and CTS signals.
- IrDA modulation and demodulation with programmable pulse widths.
- Smartcard ACK/NACK support.
- Parity error, frame error, overrun, and underrun detection.
- Multi-master and half-duplex support.
- Multiple loop-back modes supported.

4.6.4. SPI (SPI0, SPI1)

SPI is a 3- or 4-wire communication interface that includes a clock, input data, output data, and an optional select signal.

The SPI module includes the following features:

- Supports 3- or 4-wire master or slave modes.
- Supports up to 10 MHz clock in master mode and 5 MHz clock in slave mode.
- Support for all clock phase and slave select (NSS) polarity modes.
- 16-bit programmable clock rate.
- Programmable MSB-first or LSB-first shifting.
- 8-byte FIFO buffers for both transmit and receive data paths to support high speed transfers.
- Programmable FIFO threshold level to request data service for DMA transfers.
- Support for multiple masters on the same data lines.

4.6.5. I2C (I2C0, I2C1)

The I2C interface is a two-wire, bi-directional serial bus. The two clock and data signals operate in open-drain mode with external pull-ups to support automatic bus arbitration.

Reads and writes to the interface are byte oriented with the I2C interface autonomously controlling the serial transfer of the data. Data can be transferred at up to 1/8th of the APB clock as a master or slave, which can be faster than allowed by the I2C specification, depending on the clock source used. A method of extending the clock-low duration is available to accommodate devices with different speed capabilities on the same bus.

The I2C interface may operate as a master and/or slave, and may function on a bus with multiple masters. The I2C provides control of SDA (serial data), SCL (serial clock) generation and synchronization, arbitration logic, and start/stop control and generation.

The I2C module includes the following features:

- Standard (up to 100 kbps) and Fast (400 kbps) transfer speeds.
- Can operate down to APB clock divided by 32768 or up to APB clock divided by 8.
- Support for master, slave, and multi-master modes.
- Hardware synchronization and arbitration for multi-master mode.
- Clock low extending (clock stretching) to interface with faster masters.
- Hardware support for 7-bit slave and general call address recognition.
- Firmware support for 10-bit slave address decoding.
- Ability to disable all slave states.
- Programmable clock high and low period.
- Programmable data setup/hold times.

4.7.4. 16-Channel Capacitance-to-Digital Converter (CAPSENSE0)

The Capacitance Sensing module measures capacitance on external pins and converts it to a digital value. The CAPSENSE module has the following features:

- Multiple start-of-conversion sources (CSnTx).
- Option to convert to 12, 13, 14, or 16 bits.
- Automatic threshold comparison with programmable polarity (“less than or equal” or “greater than”).
- Four operation modes: single conversion, single scan, continuous single conversion, and continuous scan.
- Auto-accumulate mode that will take and average multiple samples together from a single start of conversion signal.
- Single bit retry options available to reduce the effect of noise during a conversion.
- Supports channel bonding to monitor multiple channels connected together with a single conversion.
- Scanning option allows the module to convert a single or series of channels and compare against the threshold while the AHB clock is stopped and the core is in a low power mode.

4.7.5. Low Current Comparators (CMP0, CMP1)

The Comparators take two analog input voltages and output the relationship between these voltages (less than or greater than) as a digital signal. The Low Power Comparator module includes the following features:

- Multiple sources for the positive and negative poles, including VDD, VREF, and 8 I/O pins.
- Two outputs are available: a digital synchronous latched output and a digital asynchronous raw output.
- Programmable hysteresis and response time.
- Falling or rising edge interrupt options on the comparator output.

4.7.6. Current-to-Voltage Converter (IVC0)

The IVC module provides inputs to the SARADCn modules so the input current can be measured. The IVC module has the following features:

- Two independent channels.
- Programmable input ranges (1–6 mA full-scale).

4.8. Reset Sources

Reset circuitry allows the controller to be easily placed in a predefined default condition. On entry to this reset state, the following occur:

- The core halts program execution.
- Module registers are initialized to their defined reset values unless the bits reset only with a power-on reset.
- External port pins are forced to a known state.
- Interrupts and timers are disabled.
- Clocks to all AHB peripherals are enabled.
- Clocks to all APB peripherals other than Watchdog Timer, EMIF0, and DMAXBAR are disabled.

All registers are reset to the predefined values noted in the register descriptions unless the bits only reset with a power-on reset. The contents of RAM are unaffected during a reset; any previously stored data is preserved as long as power is not lost.

The Port I/O latches are reset to 1 in open-drain mode. Weak pullups are enabled during and after the reset. For VDD Supply Monitor and power-on resets, the $\overline{\text{RESET}}$ pin is driven low until the device exits the reset state.

On exit from the reset state, the program counter (PC) is reset, and the system clock defaults to an internal oscillator. The Watchdog Timer is enabled with the Low Frequency Oscillator (LFO0) as its clock source. Program execution begins at location 0x00000000.

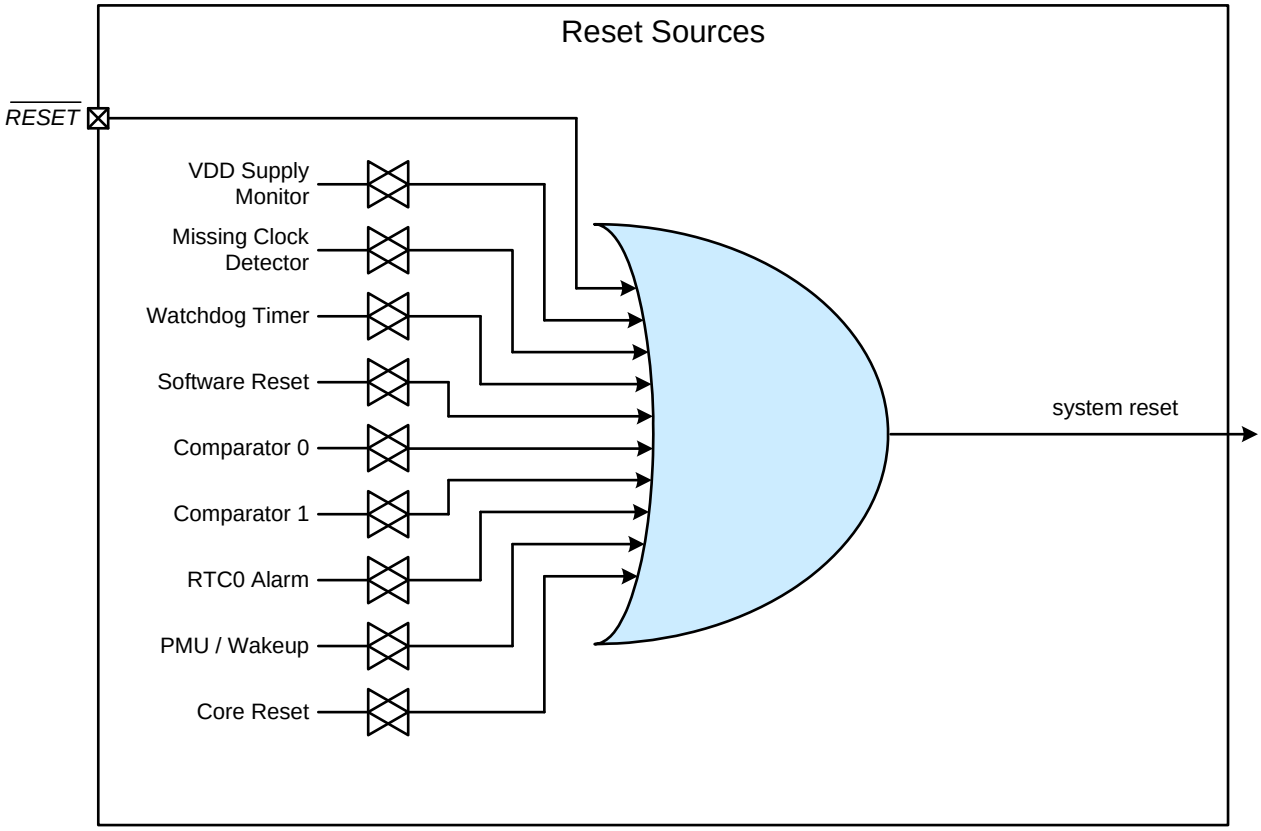


Table 5.1. Product Selection Guide

Ordering Part Number	Flash Memory (kB)	RAM (kB)	External Memory Interface (EMIF)	Maximum Number of EMIF Address/Data Pins	Digital Port I/Os (Total)	Digital Port I/Os with High Drive Capability	Number of SARADC0 Channels	Number of SARADC1 Channels	Number of CAPSENSE0 Channels	Number of Comparator 0/1 Inputs (+/-)	Number of PMU Pin Wake Sources	JTAG Debugging Interface	ETM Debugging Interface	Serial Wire Debugging Interface	Lead-free (RoHS Compliant)	Package
SiM3C167-B-GM	256	32	✓	24	65	6	16	16	16	8/8	16	✓	✓	✓	✓	LGA-92
SiM3C167-B-GQ	256	32	✓	24	65	6	16	16	16	8/8	16	✓	✓	✓	✓	TQFP-80
SiM3C166-B-GM	256	32	✓	16	50	4	13	15	15	6/6	15	✓		✓	✓	QFN-64
SiM3C166-B-GQ	256	32	✓	16	50	4	13	15	15	6/6	15	✓		✓	✓	TQFP-64
SiM3C164-B-GM	256	32			28	4	7	11	12	3/3	10			✓	✓	QFN-40
SiM3C157-B-GM	128	32	✓	24	65	6	16	16	16	8/8	16	✓	✓	✓	✓	LGA-92
SiM3C157-B-GQ	128	32	✓	24	65	6	16	16	16	8/8	16	✓	✓	✓	✓	TQFP-80
SiM3C156-B-GM	128	32	✓	16	50	4	13	15	15	6/6	15	✓		✓	✓	QFN-64
SiM3C156-B-GQ	128	32	✓	16	50	4	13	15	15	6/6	15	✓		✓	✓	TQFP-64
SiM3C154-B-GM	128	32			28	4	7	11	12	3/3	10			✓	✓	QFN-40
SiM3C146-B-GM	64	16	✓	16	50	4	13	15	15	6/6	15	✓		✓	✓	QFN-64
SiM3C146-B-GQ	64	16	✓	16	50	4	13	15	15	6/6	15	✓		✓	✓	TQFP-64
SiM3C144-B-GM	64	16			28	4	7	11	12	3/3	10			✓	✓	QFN-40
SiM3C136-B-GM	32	8	✓	16	50	4	13	15	15	6/6	15	✓		✓	✓	QFN-64
SiM3C136-B-GQ	32	8	✓	16	50	4	13	15	15	6/6	15	✓		✓	✓	TQFP-64
SiM3C134-B-GM	32	8			28	4	7	11	12	3/3	10			✓	✓	QFN-40

Table 6.1. Pin Definitions and alternate functions for SiM3C1x7 (Continued)

Pin Name	Type	Pin Numbers TQFP-80	Pin Numbers LGA-92	Crossbar Capability (see Port Config Section)	Port Match	External Memory Interface (m = muxed mode)	Port-Mapped Level Shifter	Output Toggle Logic	External Trigger Inputs	Analog or Additional Functions
PB2.6	Standard I/O	29	B13	XBR1	✓	AD11m/ A3		Yes	INT0.6 INT1.6	
PB2.7	Standard I/O	28	A17	XBR1	✓	AD10m/ A2		Yes	INT0.7 INT1.7	
PB2.8	Standard I/O	27	B12	XBR1	✓	AD9m/ A1		Yes		
PB2.9	Standard I/O	26	A16	XBR1	✓	AD8m/ A0		Yes		
PB2.10	Standard I/O	25	B11	XBR1	✓	AD7m/ D7		Yes		
PB2.11	Standard I/O	24	A15	XBR1	✓	AD6m/ D6		Yes		CMP0P.0 CMP1P.0
PB2.12	Standard I/O	23	A14	XBR1	✓	AD5m/ D5		Yes		CMP0N.0 CMP1N.0 RTC0TCLK_OUT
PB2.13	Standard I/O	22	A13	XBR1	✓	AD4m/ D4		Yes		CMP0P.1 CMP1P.1
PB2.14	Standard I/O	21	D2	XBR1	✓	AD3m/ D3		Yes		CMP0N.1 CMP1N.1
PB3.0	5 V Tolerant I/O	20	A12	XBR1	✓	AD2m/ D2				CMP0P.2 CMP1P.2
PB3.1	5 V Tolerant I/O	19	A11	XBR1	✓	AD1m/ D1				CMP0N.2 CMP1N.2
PB3.2	5 V Tolerant I/O	18	A10	XBR1	✓	AD0m/ D0			DAC0T0 DAC1T0 LPT0T0	CMP0P.3 CMP1P.3
PB3.3	5 V Tolerant I/O	17	B8	XBR1	✓	$\overline{WR}$			DAC0T1 DAC1T1 INT0.8 INT1.8	CMP0N.3 CMP1N.3

Table 6.2. Pin Definitions and alternate functions for SiM3C1x6 (Continued)

Pin Name	Type	Pin Numbers	Crossbar Capability (see Port Config Section)	Port Match	External Memory Interface (m = muxed mode)	Port-Mapped Level Shifter	Output Toggle Logic	External Trigger Inputs	Analog or Additional Functions
PB0.7	Standard I/O	50	XBR0	✓					RTC2
PB0.8	Standard I/O	49	XBR0	✓					ADC0.9 VREFGND
PB0.9	Standard I/O	48	XBR0	✓					ADC0.10 VREF
PB0.10	Standard I/O	47	XBR0	✓					ADC1.6 IDAC0
PB0.11	Standard I/O	46	XBR0	✓					IDAC1
PB0.12	Standard I/O	45	XBR0	✓					XTAL1
PB0.13	Standard I/O	44	XBR0	✓					XTAL2
PB0.14/TDO/ SWV	Standard I/O / JTAG / Serial Wire Viewer	43	XBR0	✓					ADC0.12 ADC1.12
PB0.15/TDI	Standard I/O / JTAG	42	XBR0	✓					ADC0.13 ADC1.13
PB1.0	Standard I/O	41	XBR0	✓					ADC0.14 ADC1.14
PB1.1	Standard I/O	40	XBR0	✓					ADC0.15 ADC1.15
PB1.2	Standard I/O	38	XBR0	✓					ADC1.11 CS0.8
PB1.3	Standard I/O	37	XBR0	✓					ADC1.10 CS0.9
PB1.4	Standard I/O	34	XBR0	✓					ADC1.8
PB1.5	Standard I/O	33	XBR0	✓					ADC1.7
PB1.6	Standard I/O	32	XBR0	✓				ADC0T15 WAKE.0	ADC1.5 CS0.10
PB1.7	Standard I/O	31	XBR0	✓	AD15m/ A7			ADC1T15 WAKE.1	ADC1.4 CS0.11

Table 6.3. Pin Definitions and Alternate Functions for SiM3C1x4 (Continued)

Pin Name	Type	Pin Numbers	Crossbar Capability (see Port Config Section)	Port Match	Output Toggle Logic	External Trigger Inputs	Analog or Additional Functions
PB3.1	5 V Tolerant I/O	9	XBR1	✓		DAC0T1 DAC1T1 LPT0T1 INT0.1 INT1.1 WAKE.13	CMP0N.1 CMP1N.1 EXREGSN
PB3.2	5 V Tolerant I/O	8	XBR1	✓		DAC0T2 DAC1T2 LPT0T2 INT0.2 INT1.3 WAKE.14	CMP0P.2 CMP1P.2 EXREGOUT
PB3.3	5 V Tolerant I/O	7	XBR1	✓		DAC0T3 DAC1T3 INT0.3 INT1.3 WAKE.15	CMP0N.2 CMP1N.2 EXREGBD
PB4.0	High Drive I/O	6					
PB4.1	High Drive I/O	5					
PB4.2	High Drive I/O	4					
PB4.3	High Drive I/O	1					

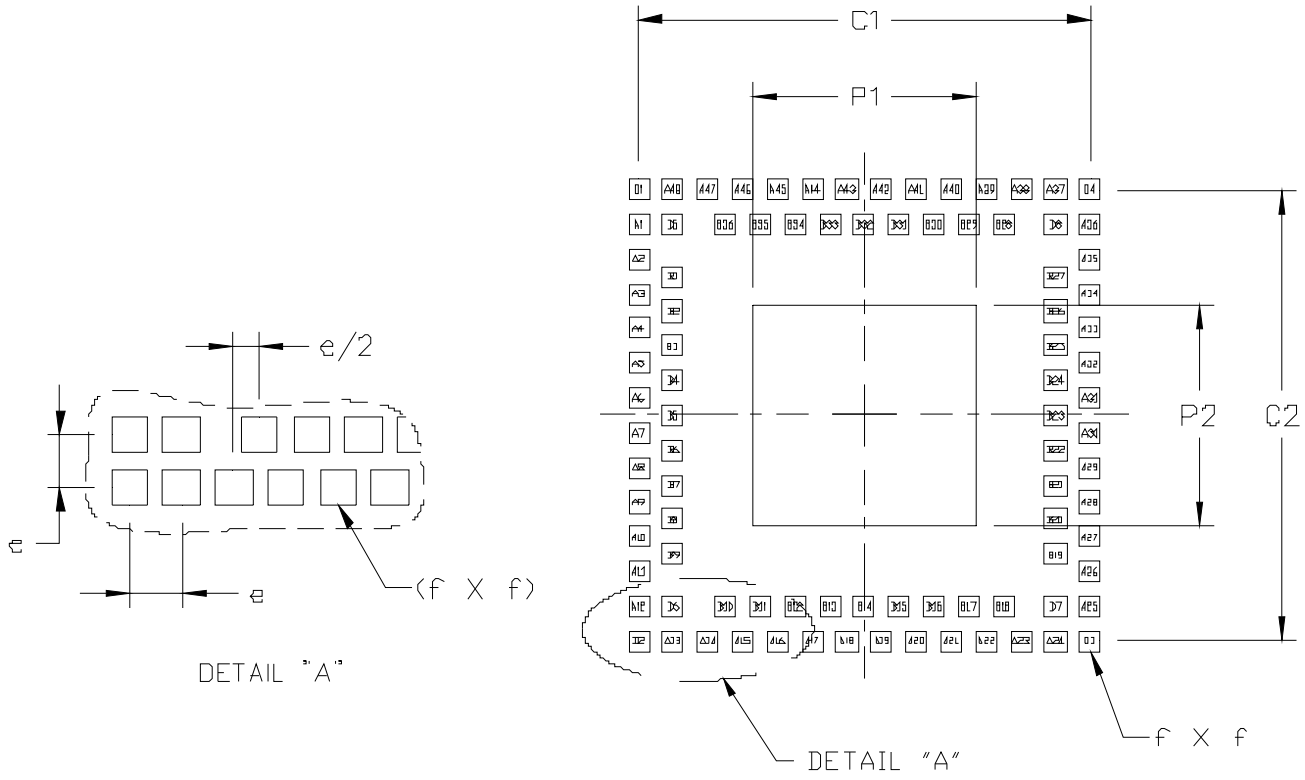


Figure 6.7. LGA-92 Landing Diagram

Table 6.5. LGA-92 Landing Diagram Dimensions

Dimension	Typical	Max
C1	6.50	—
C2	6.50	—
e	0.50	—
f	—	0.35
P1	—	3.20
P2	—	3.20

Notes:

1. All dimensions shown are in millimeters (mm) unless otherwise noted.
2. All feature sizes shown are at Maximum Material Condition (MMC) and a card fabrication tolerance of 0.05 mm is assumed.
3. Dimensioning and Tolerancing is per the ANSI Y14.5M-1994 specification.
4. This land pattern design is based on the IPC-7351 guidelines.

6.4.1. LGA-92 Solder Mask Design

All metal pads are to be non-solder mask defined (NSMD). Clearance between the solder mask and the metal pad is to be 60 µm minimum, all the way around the pad.

6.4.2. LGA-92 Stencil Design

1. A stainless steel, laser-cut and electro-polished stencil with trapezoidal walls should be used to assure good solder paste release.
2. The stencil thickness should be 0.125 mm (5 mils).
3. The ratio of stencil aperture to land pad size should be 1:1 for all perimeter pins.
4. A 2 x 2 array of 1.25 mm square openings on 1.60 mm pitch should be used for the center ground pad.

6.4.3. LGA-92 Card Assembly

1. A No-Clean, Type-3 solder paste is recommended.
2. The recommended card reflow profile is per the JEDEC/IPC J-STD-020 specification for Small Body Components.

6.7. TQFP-64 Package Specifications

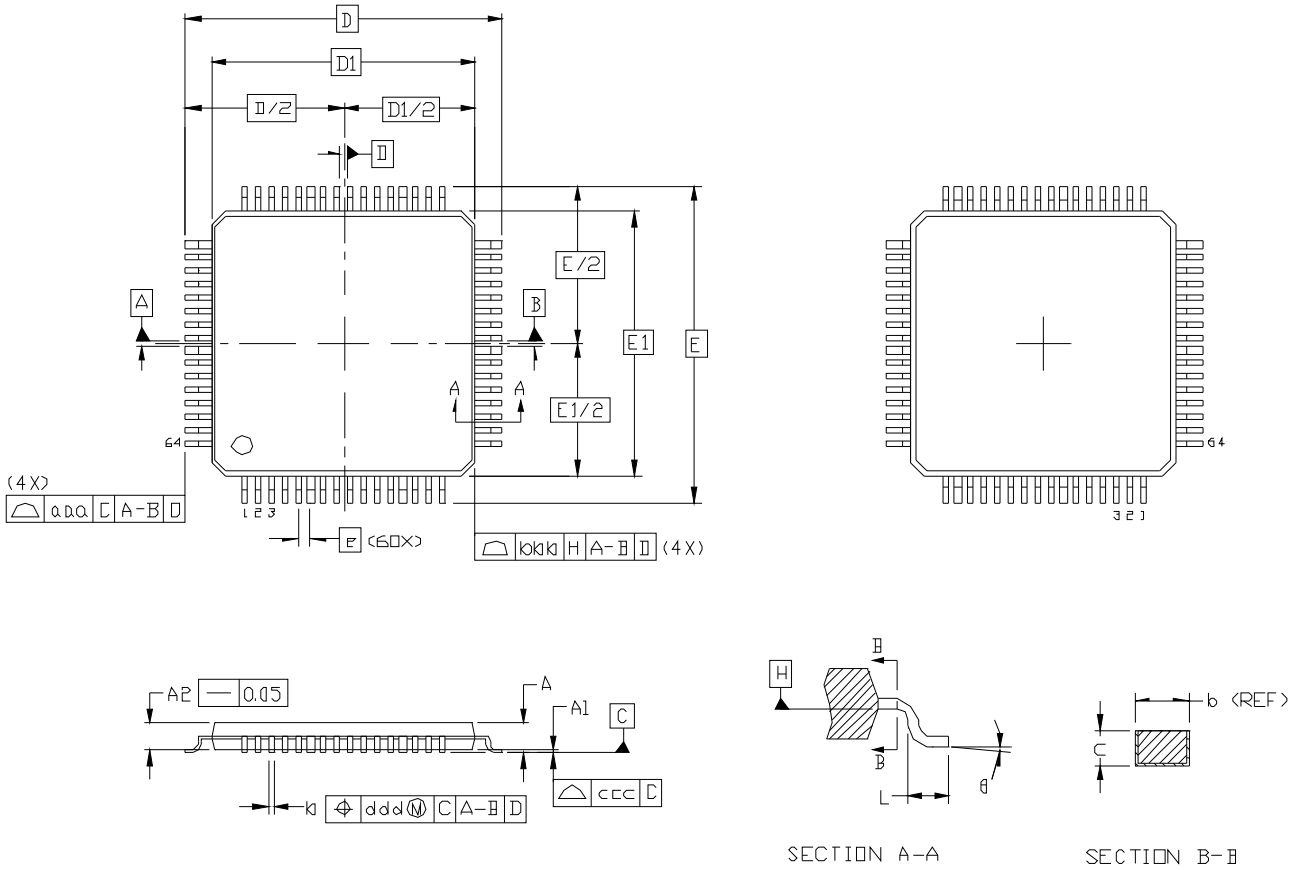


Figure 6.12. TQFP-64 Package Drawing

Table 6.10. TQFP-64 Package Dimensions

Dimension	Min	Nominal	Max
A	—	—	1.20
A1	0.05	—	0.15
A2	0.95	1.00	1.05
b	0.17	0.22	0.27
c	0.09	—	0.20
D	12.00 BSC		
D1	10.00 BSC		
e	0.50 BSC		
E	12.00 BSC		
E1	10.00 BSC		
L	0.45	0.60	0.75
Θ	0°	3.5°	7°

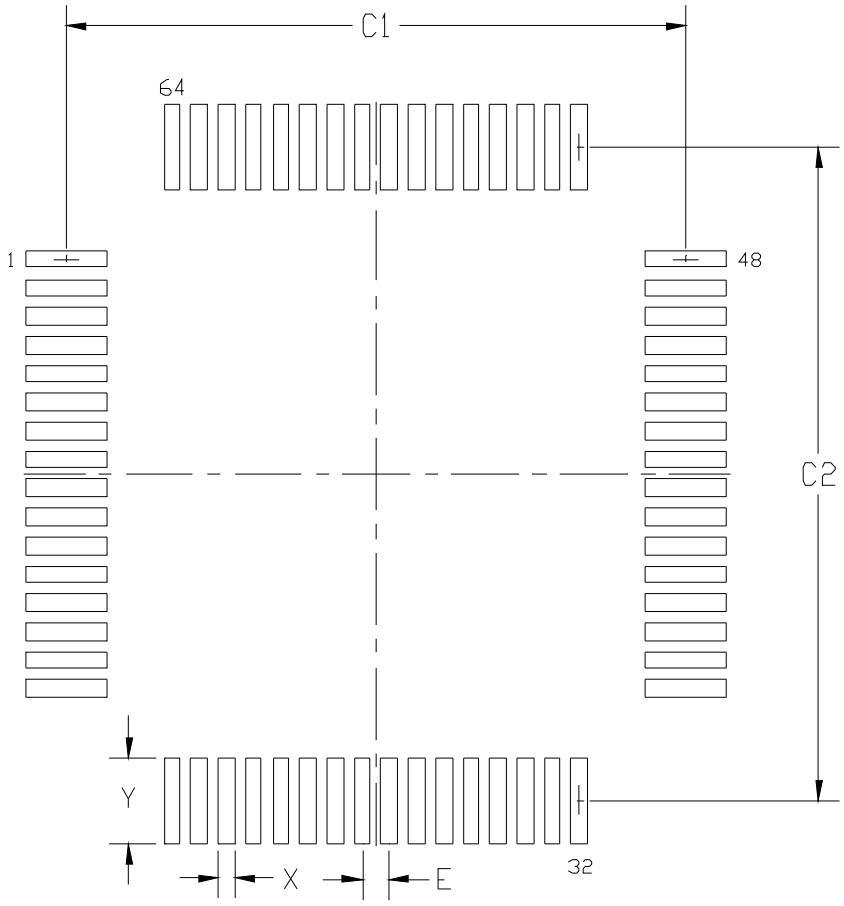


Figure 6.13. TQFP-64 Landing Diagram

Table 6.11. TQFP-64 Landing Diagram Dimensions

Dimension	Min	Max
C1	11.30	11.40
C2	11.30	11.40
E	0.50 BSC	
X	0.20	0.30
Y	1.40	1.50

Notes:
1. All dimensions shown are in millimeters (mm) unless otherwise noted.
2. This land pattern design is based on the IPC-7351 guidelines.

6.8. QFN-40 Package Specifications

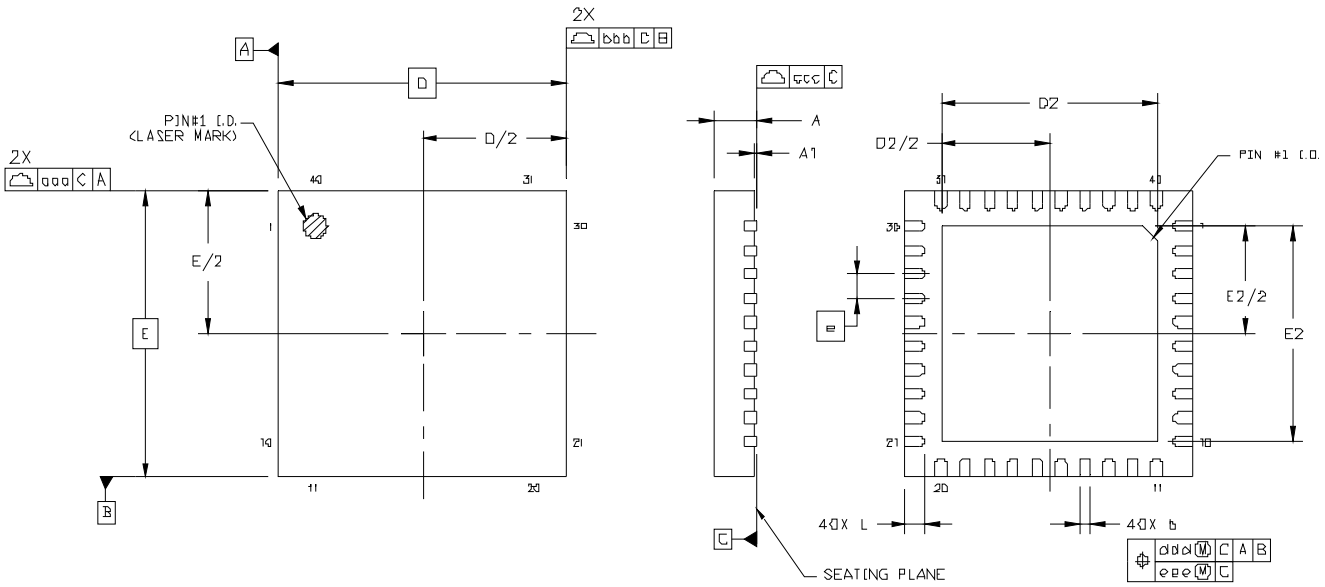


Figure 6.14. QFN-40 Package Drawing

Table 6.12. QFN-40 Package Dimensions

Dimension	Min	Nominal	Max
A	0.80	0.85	0.90
A1	0.00	0.02	0.05
b	0.18	0.25	0.30
D		6.00 BSC	
D2	4.35	4.50	4.65
e		0.50 BSC	
E		6.00 BSC	
E2	4.35	4.5	4.65
L	0.30	0.40	0.50
aaa		0.10	
bbb		0.10	
ccc		0.08	
ddd		0.10	
eee		0.05	

Notes:

1. All dimensions shown are in millimeters (mm) unless otherwise noted.
2. Dimensioning and Tolerancing per ANSI Y14.5M-1994.
3. This package outline conforms to JEDEC MO-220.
4. Recommended card reflow profile is per the JEDEC/IPC J-STD-020 specification for Small Body Components.

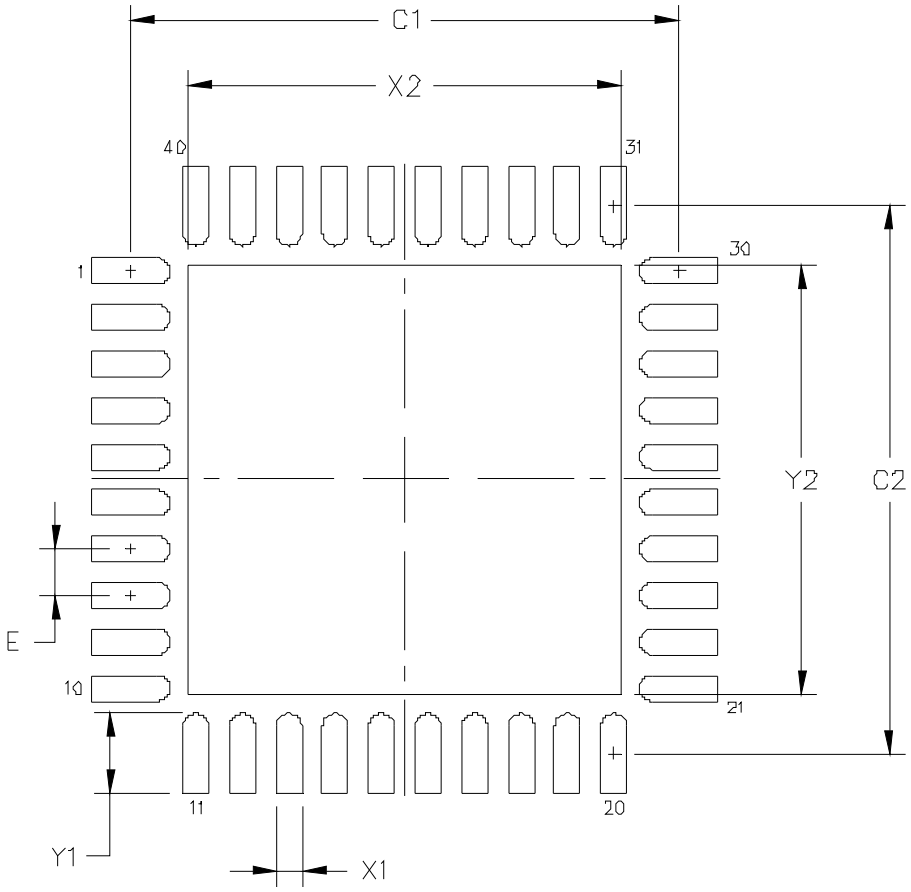


Figure 6.15. QFN-40 Landing Diagram

Table 6.13. QFN-40 Landing Diagram Dimensions

Dimension	mm
C1	5.90
C2	5.90
E	0.50
X1	0.30
Y1	0.85
X2	4.65
Y2	4.65

Notes:
1. All dimensions shown are in millimeters (mm).
2. This Land Pattern Design is based on the IPC-7351 guidelines.
3. All dimensions shown are at Maximum Material Condition (MMC). Least Material Condition (LMC) is calculated based on a Fabrication Allowance of 0.05 mm.