



Welcome to [E-XFL.COM](https://www.e-xfl.com)

### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Obsolete
Core Processor	ARM® Cortex®-M3
Core Size	32-Bit Single-Core
Speed	80MHz
Connectivity	EBI/EMI, I <sup>2</sup> C, IrDA, SmartCard, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, I <sup>2</sup> S, POR, PWM, WDT
Number of I/O	65
Program Memory Size	256KB (256K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 32x12b; D/A 2x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	80-TQFP
Supplier Device Package	80-TQFP (12x12)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/silicon-labs/sim3c167-b-gqr">https://www.e-xfl.com/product-detail/silicon-labs/sim3c167-b-gqr</a>

**Table 3.8. Internal Oscillators (Continued)**

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
<b>Low Power Oscillator (LPOSC0)</b>						
Oscillator Frequency	$f_{LPOSC}$	Full Temperature and Supply Range	19	20	21	MHz
		$T_A = 25\text{ }^{\circ}\text{C}$ , $V_{DD} = 3.3\text{ V}$	19.5	20	20.5	MHz
Divided Oscillator Frequency	$f_{LPOSCD}$	Full Temperature and Supply Range	2.375	2.5	2.625	MHz
Power Supply Sensitivity	$PSS_{LPOSC}$	$T_A = 25\text{ }^{\circ}\text{C}$	—	0.5	—	%/V
Temperature Sensitivity	$TS_{LPOSC}$	$V_{DD} = 3.3\text{ V}$	—	55	—	ppm/ $^{\circ}\text{C}$
<b>Low Frequency Oscillator (LFOSC0)</b>						
Oscillator Frequency	$f_{LFOSC}$	Full Temperature and Supply Range	13.4	16.4	19.7	kHz
		$T_A = 25\text{ }^{\circ}\text{C}$ , $V_{DD} = 3.3\text{ V}$	15.8	16.4	17.3	kHz
Power Supply Sensitivity	$PSS_{LFOSC}$	$T_A = 25\text{ }^{\circ}\text{C}$	—	2.4	—	%/V
Temperature Sensitivity	$TS_{LFOSC}$	$V_{DD} = 3.3\text{ V}$	—	0.2	—	%/ $^{\circ}\text{C}$
<b>RTC0 Oscillator (RTC0OSC)</b>						
Missing Clock Detector Trigger Frequency	$f_{RTCMCD}$		—	8	15	kHz
RTC Robust Duty Cycle Range	$DC_{RTC}$		25	—	55	%
<b>*Note:</b> PLL0OSC in free-running oscillator mode.						

**Table 3.9. External Oscillator**

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
External Input CMOS Clock Frequency*	$f_{CMOS}$		0	—	50	MHz
External Input CMOS Clock High Time	$t_{CMOSH}$		9	—	—	ns
External Input CMOS Clock Low Time	$t_{CMOSL}$		9	—	—	ns
External Crystal Clock Frequency	$f_{XTAL}$		0.01	—	30	MHz
<b>*Note:</b> Minimum of 10 kHz during debug operations.						

Table 3.17. Port I/O (Continued)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
P-Channel Source Current Limit ( $2.7\text{ V} \leq V_{IOHD} \leq 6\text{ V}$ , $V_{OH} = V_{IOHD} - 0.8\text{ V}$ ) See Figure 3.2	$I_{SRCL}$	Mode 0	—	0.8	—	mA
		Mode 1	—	1.25	—	
		Mode 2	—	1.75	—	
		Mode 3	—	2.5	—	
		Mode 4	—	3.5	—	
		Mode 5	—	4.75	—	
		Mode 6	—	7	—	
		Mode 7	—	9.5	—	
		Mode 8	—	14	—	
		Mode 9	—	18.75	—	
		Mode 10	—	28.25	—	
		Mode 11	—	37.5	—	
		Mode 12	—	56.25	—	
		Mode 13	—	75	—	
		Mode 14	—	112.5	—	
		Mode 15	—	150	—	
Total P-Channel Source Current on P4.0-P4.5 (DC)	$I_{SRCLT}$		—	—	400	mA
Pin Capacitance	$C_{IO}$		—	30	—	pF
Weak Pull-Up Current in Low Voltage Mode	$I_{PU}$	$V_{IOHD} = 1.8\text{ V}$	–6	–3.5	–2	$\mu\text{A}$
		$V_{IOHD} = 3.6\text{ V}$	–30	–20	–10	$\mu\text{A}$
Weak Pull-Up Current in High Voltage Mode	$I_{PU}$	$V_{IOHD} = 2.7\text{ V}$	–15	–10	–5	$\mu\text{A}$
		$V_{IOHD} = 6\text{ V}$	–30	–20	–10	$\mu\text{A}$
Input Leakage (Pullups off)	$I_{LK}$		–1	—	1	$\mu\text{A}$

**\*Note:**  $\overline{\text{RESET}}$  does not drive to logic high. Specifications for  $\overline{\text{RESET}}$   $V_{OL}$  adhere to the low drive setting.

**Table 3.19. Absolute Maximum Ratings (Continued)**

Parameter	Symbol	Test Condition	Min	Max	Unit
Voltage on I/O pins, Port Bank 3 I/O	$V_{IN}$	SiM3C1x7, PB3.0–PB3.7, $V_{IO} \geq 3.3$ V	$V_{SS}-0.3$	5.8	V
		SiM3C1x7, PB3.0–PB3.7, $V_{IO} < 3.3$ V	$V_{SS}-0.3$	$V_{IO}+2.5$	V
		SiM3C1x7, PB3.8 - PB3.11	$V_{SS}-0.3$	Lowest of $V_{IO}+2.5$ , $V_{REGIN}+0.3$ , or 5.8	V
		SiM3C1x6, PB3.0–PB3.5, $V_{IO} \geq 3.3$ V	$V_{SS}-0.3$	5.8	V
		SiM3C1x6, PB3.0–PB3.5, $V_{IO} < 3.3$ V	$V_{SS}-0.3$	$V_{IO}+2.5$	V
		SiM3C1x6, PB3.6–PB3.9	$V_{SS}-0.3$	Lowest of $V_{IO}+2.5$ , $V_{REGIN}+0.3$ , or 5.8	V
		SiM3C1x4, PB3.0–PB3.3	$V_{SS}-0.3$	Lowest of $V_{IO}+2.5$ , $V_{REGIN}+0.3$ , or 5.8	V
Total Current Sunk into Supply Pins	$I_{SUPP}$	$V_{DD}$ , $V_{REGIN}$ , $V_{IO}$ , $V_{IOHD}$	—	400	mA
Total Current Sourced out of Ground Pins	$I_{VSS}$	$V_{SS}$ , $V_{SSHD}$	400	—	mA
Current Sourced or Sunk by Any I/O Pin	$I_{PIO}$	PB0, PB1, PB2, PB3, and RESET	–100	100	mA
		PB4	–300	300	mA
Current Injected on Any I/O Pin	$I_{INJ}$	PB0, PB1, PB2, PB3, and RESET	–100	100	mA
		PB4	–300	300	mA
Total Injected Current on I/O Pins	$\Sigma I_{INJ}$	Sum of all I/O and RESET	–400	400	mA
<b>*Note:</b> VSS and VSSHD provide separate return current paths for device supplies, but are not isolated. They must always be connected to the same potential on board.					

## 4. Precision32™ SiM3C1xx System Overview

The SiM3C1xx Precision32™ devices are fully integrated, mixed-signal system-on-a-chip MCUs. Highlighted features are listed below. Refer to Table 5.1 for specific product feature selection and part ordering numbers.

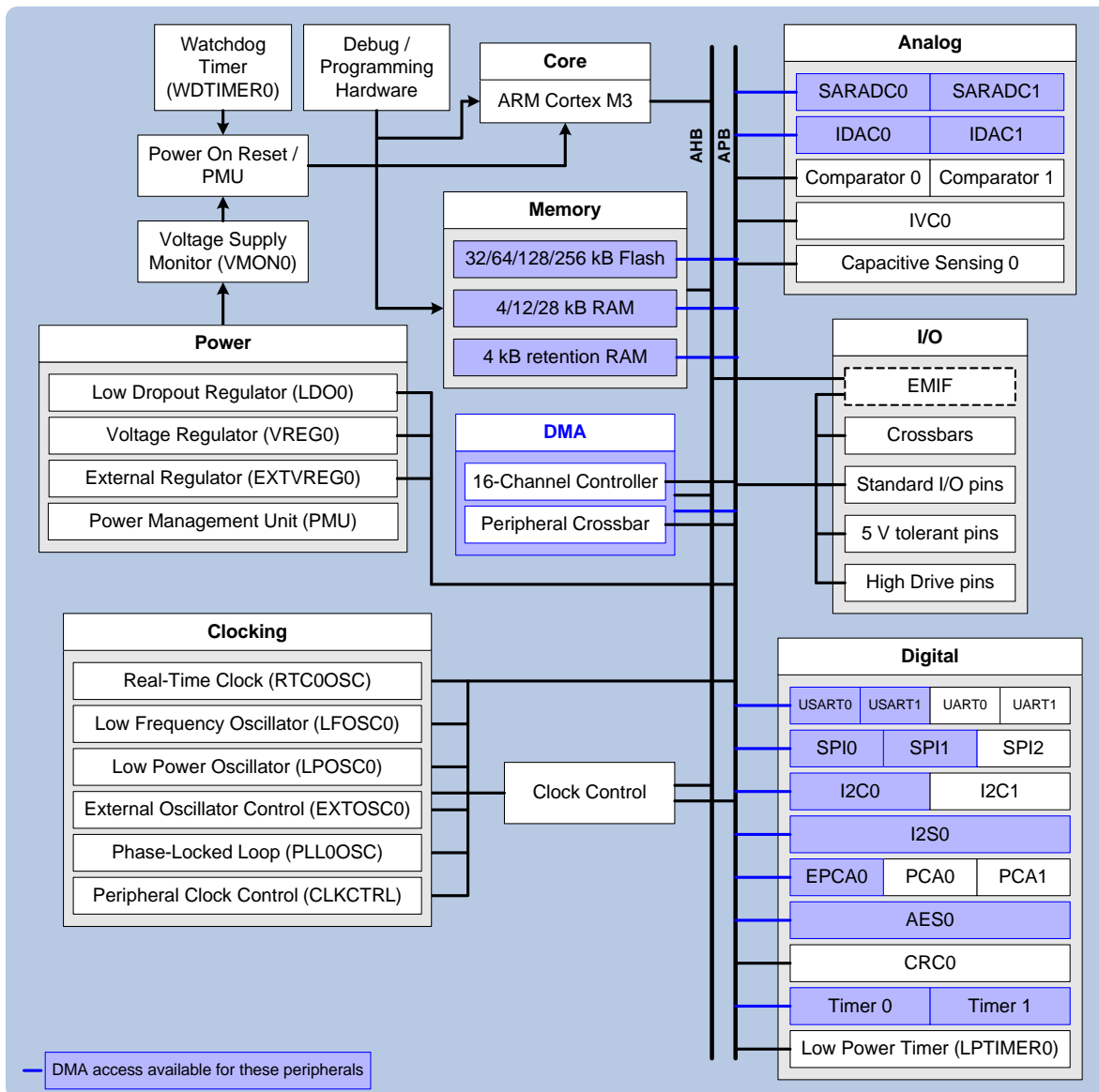
- **Core:**
  - 32-bit ARM Cortex-M3 CPU.
  - 80 MHz maximum operating frequency.
  - Branch target cache and prefetch buffers to minimize wait states.
- **Memory:** 32–256 kB Flash; in-system programmable, 8–32 kB SRAM (including 4 kB retention SRAM, which preserves state in PM9 mode).
- **Power:**
  - Low drop-out (LDO) regulator for CPU core voltage.
  - Power-on reset circuit and brownout detectors.
  - 3.3 V output LDO for direct power from 5 V supplies.
  - External transistor regulator.
  - Power Management Unit (PMU).
- **I/O: Up to 65 total multifunction I/O pins:**
  - Up to six programmable high-power capable (5–300 mA with programmable current limiting, 1.8–5 V).
  - Up to twelve 5 V tolerant general purpose pins.
  - Two flexible peripheral crossbars for peripheral routing.
- **Clock Sources:**
  - Internal oscillator with PLL: 23–80 MHz with  $\pm 1.5\%$  accuracy in free-running mode.
  - Low-power internal oscillator: 20 MHz and 2.5 MHz modes.
  - Low-frequency internal oscillator: 16.4 kHz.
  - External RTC crystal oscillator: 32.768 kHz.
  - External oscillator: Crystal, RC, C, CMOS clock modes.
  - Programmable clock divider allows any oscillator source to be divided by binary factor from 1-128.
- **Data Peripherals:**
  - 16-Channel DMA Controller.
  - 128/192/256-bit Hardware AES Encryption.
  - 16/32-bit CRC.
- **Timers/Counters and PWM:**
  - 6-channel Enhanced Programmable Counter Array (EPCAn) supporting advanced PWM and capture/compare.
  - 2 x 2-channel Standard Programmable Counter Array (PCAn) supporting PWM and capture/compare.
  - 2 x 32-bit Timers - can be split into 4 x 16-bit Timers, support PWM and capture/compare.
  - Real Time Clock (RTCn).
  - Low Power Timer.
  - Watchdog Timer.
- **Communications Peripherals:**
  - External Memory Interface.
  - 2 x USARTs and 2 x UARTs with IrDA and ISO7816 SmartCard support.
  - 3 x SPIs.
  - 2 x I2C.
  - I<sup>2</sup>S (receive and transmit).
- **Analog:**
  - 2 x 12-Bit Analog-to-Digital Converters (SARADC).
  - 2 x 10-Bit Digital-to-Analog Converter (IDAC).
  - 16-Channel Capacitance-to-Digital Converter (CAPSENSE).
  - 2 x Low-Current Comparators (CMP).
  - 1 x Current-to-Voltage Converter (IVC) module with two channels.
- **On-Chip Debugging**

With on-chip power-on reset, voltage supply monitor, watchdog timer, and clock oscillator, the SiM3C1xx devices are truly standalone system-on-a-chip solutions. The Flash memory is reprogrammable in-circuit, providing non-

volatile data storage and allowing field upgrades of the firmware. User firmware has complete control of all peripherals and may individually shut down and gate the clocks of any or all peripherals for power savings.

The on-chip debugging interface (SWJ-DP) allows non-intrusive (uses no on-chip resources), full speed, in-circuit debugging using the production MCU installed in the final application. This debug logic supports inspection and modification of memory and registers, setting breakpoints, single stepping, and run and halt commands. All analog and digital peripherals are fully functional while debugging.

Each device is specified for 1.8 to 3.6 V operation over the industrial temperature range (–40 to +85 °C). The Port I/O and **RESET** pins are powered from the IO supply voltage. The SiM3C1xx devices are available in 40-pin or 64-pin QFN, 64-pin or 80-pin TQFP, or 92-pin LGA packages. All package options are lead-free and RoHS compliant. See Table 5.1 for ordering information. A block diagram is included in Figure 4.1.



**Figure 4.1. Precision32™ SiM3C1xx Family Block Diagram**

## 4.1. Power

### 4.1.1. LDO and Voltage Regulator (VREG0)

The SiM3C1xx devices include two internal regulators: the core LDO Regulator and the Voltage Regulator (VREG0).

The LDO Regulator converts a 1.8–3.6 V supply to the core operating voltage of 1.8 V. This LDO consumes little power and provides flexibility in choosing a power supply for the system.

The Voltage Regulator regulates from 5.5 to 2.7 V and can serve as an input to the LDO. This allows the device to be powered from up to a 5.5 V supply without any external components other than bypass capacitors.

### 4.1.2. Voltage Supply Monitor (VMON0)

The SiM3C1xx devices include a voltage supply monitor which allows devices to function in known, safe operating condition without the need for external hardware. The supply monitor includes additional circuitry that can monitor the main supply voltage and the VREGIN input voltage divided by 4 ( $VREGIN / 4$ ).

The supply monitor module includes the following features:

- Main supply “VDD Low” (VDD below the early warning threshold) notification.
- Holds the device in reset if the main VDD supply drops below the VDD Reset threshold.
- VREGIN divided by 4 ( $VREGIN / 4$ ) supply “VREGIN Low” notification.

### 4.1.3. External Regulator (EXTVREG0)

The External Regulator provides all the circuitry needed for a high-power regulator except the power transistor (NPN or PNP) and current sensing resistor (if current limiting is enabled).

The External Regulator module has the following features:

- Interfaces with either an NPN or PNP external transistor that serves as the pass device for the high current regulator.
- Automatic current limiting.
- Automatic foldback limiting.
- Sources up to 1 A for use by external circuitry.
- Variable output voltage from 1.8–3.6 V in 100 mV steps.

### 4.1.4. Power Management Unit (PMU)

The Power Management Unit on the SiM3C1xx manages the power systems of the device. On power-up, the PMU ensures the core voltages are a proper value before core instruction execution begins. It also recognizes and manages the various wake sources for low-power modes of the device.

The PMU module includes the following features:

- Up to 16 pin wake inputs can wake the device from Power Mode 9.
- The Low Power Timer, RTC0 (alarms and oscillator fail), Comparator 0, and the  $\overline{RESET}$  pin can also serve as wake sources for Power Mode 9.
- All PM9 wake sources (except for the  $\overline{RESET}$  pin) can also reset the Low Power Timer or RTC0 modules.
- Disables the level shifters to pins and peripherals to further reduce power usage in PM9. These level shifters must be re-enabled by firmware after exiting PM9.
- Provides a PMU\_Asleep signal to a pin as an indicator that the device is in PM9.

## 4.2. I/O

### 4.2.1. General Features

The SiM3C1xx ports have the following features:

- Push-pull or open-drain output modes and analog or digital modes.
- Option for high or low output drive strength.
- Port Match allows the device to recognize a change on a port pin value.
- Internal pull-up resistors are enabled or disabled on a port-by-port basis.
- Two external interrupts with up to 16 inputs provide monitoring capability for external signals.
- Internal Pulse Generator Timer (PB2 only) to generate simple square waves.
- A subset of pins can also serve as inputs to the Port Mapped Level Shifters available on the High Drive Pins.

### 4.2.2. High Drive Pins (PB4)

The High Drive pins have the following additional features:

- Programmable safe state: high, low, or high impedance.
- Programmable drive strength and slew rates.
- Programmable hardware current limiting.
- Powered from a separate source (VIOHD, which can be up to 6 V) from the rest of the device.
- Supports various functions, including GPIO, UART1 pins, EPCA0 pins, or Port Mapped Level Shifting.

### 4.2.3. 5 V Tolerant Pins (PB3)

The 5 V tolerant pins can be connected to external circuitry operating at voltages above the device supply without needing extra components to shift the voltage level.

### 4.2.4. Crossbars

The SiM3C1xx devices have two Crossbars with the following features:

- Flexible peripheral assignment to port pins.
- Pins can be individually skipped to move peripherals as needed for design or layout considerations.

The Crossbars have a fixed priority for each I/O function and assign these functions to the port pins. When a digital resource is selected, the least-significant unassigned port pin is assigned to that resource. If a port pin is assigned, the Crossbars skip that pin when assigning the next selected resource. Additionally, the Crossbars will skip port pins whose associated bits in the PBSKIPEN registers are set. This provides some flexibility when designing a system: pins involved with sensitive analog measurements can be moved away from digital I/O and peripherals can be moved around the chip as needed to ease layout constraints.



## 4.6. Communications Peripherals

### 4.6.1. External Memory Interface (EMIF0)

The External Memory Interface (EMIF0) allows external parallel asynchronous devices, like SRAMs and LCD controllers, to appear as part of the system memory map. The EMIF0 module includes the following features:

- Provides a memory mapped view of multiple external devices.
- Support for byte, half-word and word accesses regardless of external device data-width.
- Error indicator for certain invalid transfers.
- Minimum external timing allows for 3 clocks per write or 4 clocks per read.
- Output bus can be shared between non-muxed and muxed devices.
- Available extended address output allows for up to 24-bit address with 8-bit parallel devices.
- Support for 8-bit and 16-bit (muxed-mode only) devices with up to two chip-select signals.
- Support for internally muxed devices with dynamic address shifting.
- Fully programmable control signal waveforms.

### 4.6.2. USART (USART0, USART1)

The USART uses two signals (TX and RX) and a predetermined fixed baud rate to communicate with a single device. In addition to these signals, the USART0 module can optionally use a clock (UCLK) or hardware handshaking (RTS and CTS).

The USART module provides the following features:

- Independent transmitter and receiver configurations with separate 16-bit baud rate generators.
- Synchronous or asynchronous transmissions and receptions.
- Clock master or slave operation with programmable polarity and edge controls.
- Up to 5 Mbaud (synchronous or asynchronous, TX or RX, and master or slave) or 1 Mbaud Smartcard (TX or RX).
- Individual enables for generated clocks during start, stop, and idle states.
- Internal transmit and receive FIFOs with flush capability and support for byte, half-word, and word reads and writes.
- Data bit lengths from 5 to 9 bits.
- Programmable inter-packet transmit delays.
- Auto-baud detection with support for the LIN SYNC byte.
- Automatic parity generation (with enable).
- Automatic start and stop generation (with separate enables).
- Transmit and receive hardware flow-control.
- Independent inversion correction for TX, RX, RTS, and CTS signals.
- IrDA modulation and demodulation with programmable pulse widths.
- Smartcard ACK/NACK support.
- Parity error, frame error, overrun, and underrun detection.
- Multi-master and half-duplex support.
- Multiple loop-back modes supported.
- Multi-processor communications support.

### 4.6.3. UART (UART0, UART1)

The USART uses two signals (TX and RX) and a predetermined fixed baud rate to communicate with a single device.

The UART module provides the following features:

- Independent transmitter and receiver configurations with separate 16-bit baud-rate generators.
- Asynchronous transmissions and receptions.
- Up to 5 Mbaud (TX or RX) or 1 Mbaud Smartcard (TX or RX).

## **4.7. Analog**

### **4.7.1. 12-Bit Analog-to-Digital Converters (SARADC0, SARADC1)**

The SARADC0 and SARADC1 modules on SiM3C1xx devices are Successive Approximation Register (SAR) Analog to Digital Converters (ADCs). The key features of the SARADC module are:

- Single-ended 12-bit and 10-bit modes.
- Supports an output update rate of 250 k samples per second in 12-bit mode or 1 M samples per second in 10-bit mode.
- Operation in low power modes at lower conversion speeds.
- Selectable asynchronous hardware conversion trigger with hardware channel select.
- Output data window comparator allows automatic range checking.
- Support for Burst Mode, which produces one set of accumulated data per conversion-start trigger with programmable power-on settling and tracking time.
- Conversion complete, multiple conversion complete, and FIFO overflow and underflow flags and interrupts supported.
- Flexible output data formatting.
- Sequencer allows up to 8 sources to be automatically scanned using one of four channel characteristic profiles without software intervention.
- Eight-word conversion data FIFO for DMA operations.
- Multiple SARADC modules can work together synchronously or by interleaving samples.
- Includes two internal references (1.65 V fast-settling, 1.2/2.4 V precision), support for an external reference, and support for an external signal ground.

### **4.7.2. Sample Sync Generator (SSG0)**

The SSG module includes a phase counter and a pulse generator. The phase counter is a 4-bit free-running counter clocked from the SARADC module clock. Counting-up from zero, the phase counter marks sixteen equally-spaced events for any number of SARADC modules. The ADCs can use this phase counter to start a conversion. The programmable pulse generator creates a 50% duty cycle pulse with a period of 16 phase counter ticks. Up to four programmable outputs available to external devices can be driven by the pulse generator with programmable polarity and a defined output setting when the pulse generator is stopped.

The Sample Sync Generator module has the following features:

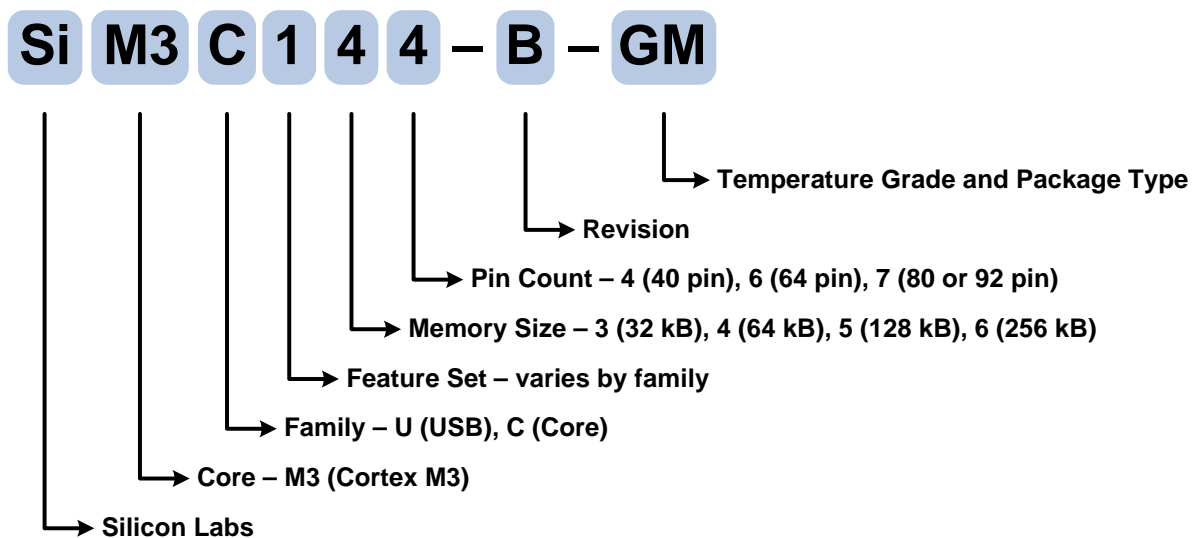
- Connects multiple modules together to perform synchronized actions.
- Outputs a clock synchronized to the internal sampling clock used by any number of SARADC modules to pins for use by external devices.
- Includes a phase counter, pulse generator, and up to four programmable outputs.

### **4.7.3. 10-Bit Digital-to-Analog Converter (IDAC0, IDAC1)**

The IDAC takes a digital value as an input and outputs a proportional constant current on a pin. The IDAC module includes the following features:

- 10-bit current DAC with support for four timer, up to seven external I/O, on demand, and SSG0 output update triggers.
- Ability to update on rising, falling, or both edges for any of the external I/O trigger sources (DACnTx).
- Supports an output update rate greater than 600 k samples per second.
- Support for three full-scale output modes: 0.5 mA, 1.0 mA and 2.0 mA.
- Four-word FIFO to aid with high-speed waveform generation or DMA interactions.
- Individual FIFO overrun, underrun, and went-empty interrupt status sources.
- Support for multiple data packing formats, including: single 10-bit sample per word, dual 10-bit samples per word, or four 8-bit samples per word.
- Support for left- and right-justified data.

## 5. Ordering Information



**Figure 5.1. SiM3C1xx Part Numbering**

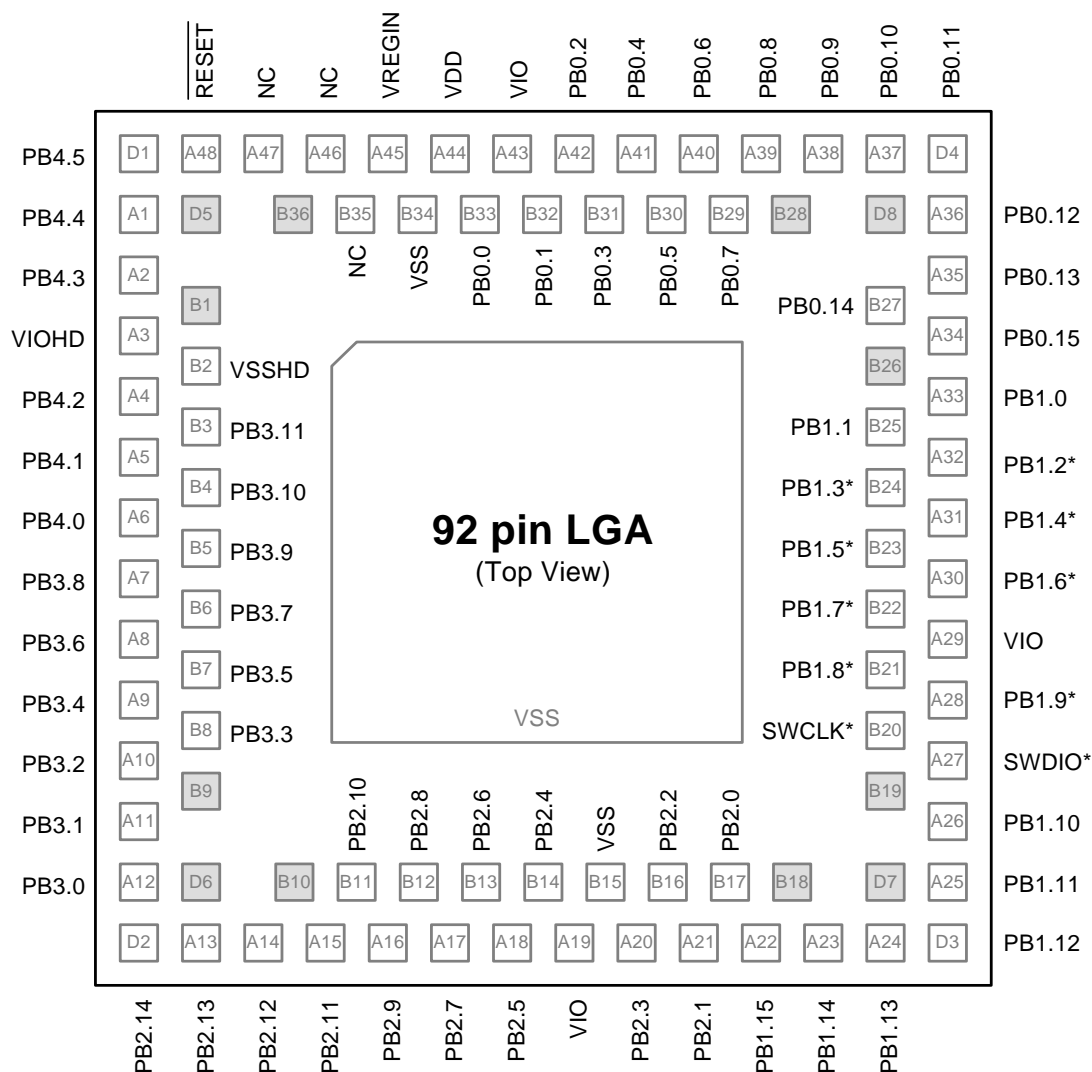
All devices in the SiM3C1xx family have the following features:

- **Core:** ARM Cortex-M3 with maximum operating frequency of 80 MHz.
- **Flash Program Memory:** 32-256 kB, in-system programmable.
- **RAM:** 8–32 kB SRAM, with 4 kB retention SRAM
- **I/O:** Up to 65 multifunction I/O pins, including high-drive and 5 V-tolerant pins.
- **Clock Sources:** Internal and external oscillator options.
- **16-Channel DMA Controller.**
- **128/192/256-bit AES.**
- **16/32-bit CRC.**
- **Timers:** 2 x 32-bit (4 x 16-bit).
- **Real-Time Clock.**
- **Low-Power Timer.**
- **PCA:** 1 x 6 channels (Enhanced), 2 x 2 channels (Standard). PWM, capture, and clock generation capabilities.
- **ADC:** 2 x 12-bit 250 ksps (10-bit 1 Msps) SAR.
- **DAC:** 2 x 10-bit IDAC.
- **Temperature Sensor.**
- **Internal VREF.**
- **16-channel Capacitive Sensing (CAPSENSE).**
- **Comparator:** 2 x low current.
- **Current to Voltage Converter (IVC).**
- **Serial Buses:** 2 x USART, 2 x UART, 3 x SPI, 2 x I2C, 1 x I<sup>2</sup>S.

The inclusion of some features varies across different members of the device family. The differences are detailed in Table 5.1.

**Table 5.1. Product Selection Guide**

Ordering Part Number	Flash Memory (kB)	RAM (kB)	External Memory Interface (EMIF)	Maximum Number of EMIF Address/Data Pins	Digital Port I/Os (Total)	Digital Port I/Os with High Drive Capability	Number of SARADC0 Channels	Number of SARADC1 Channels	Number of CAPSENSE0 Channels	Number of Comparator 0/1 Inputs (+/-)	Number of PMU Pin Wake Sources	JTAG Debugging Interface	ETM Debugging Interface	Serial Wire Debugging Interface	Lead-free (RoHS Compliant)	Package
SiM3C167-B-GM	256	32	✓	24	65	6	16	16	16	8/8	16	✓	✓	✓	✓	LGA-92
SiM3C167-B-GQ	256	32	✓	24	65	6	16	16	16	8/8	16	✓	✓	✓	✓	TQFP-80
SiM3C166-B-GM	256	32	✓	16	50	4	13	15	15	6/6	15	✓		✓	✓	QFN-64
SiM3C166-B-GQ	256	32	✓	16	50	4	13	15	15	6/6	15	✓		✓	✓	TQFP-64
SiM3C164-B-GM	256	32			28	4	7	11	12	3/3	10			✓	✓	QFN-40
SiM3C157-B-GM	128	32	✓	24	65	6	16	16	16	8/8	16	✓	✓	✓	✓	LGA-92
SiM3C157-B-GQ	128	32	✓	24	65	6	16	16	16	8/8	16	✓	✓	✓	✓	TQFP-80
SiM3C156-B-GM	128	32	✓	16	50	4	13	15	15	6/6	15	✓		✓	✓	QFN-64
SiM3C156-B-GQ	128	32	✓	16	50	4	13	15	15	6/6	15	✓		✓	✓	TQFP-64
SiM3C154-B-GM	128	32			28	4	7	11	12	3/3	10			✓	✓	QFN-40
SiM3C146-B-GM	64	16	✓	16	50	4	13	15	15	6/6	15	✓		✓	✓	QFN-64
SiM3C146-B-GQ	64	16	✓	16	50	4	13	15	15	6/6	15	✓		✓	✓	TQFP-64
SiM3C144-B-GM	64	16			28	4	7	11	12	3/3	10			✓	✓	QFN-40
SiM3C136-B-GM	32	8	✓	16	50	4	13	15	15	6/6	15	✓		✓	✓	QFN-64
SiM3C136-B-GQ	32	8	✓	16	50	4	13	15	15	6/6	15	✓		✓	✓	TQFP-64
SiM3C134-B-GM	32	8			28	4	7	11	12	3/3	10			✓	✓	QFN-40



\*Noted pins are listed in the pinout table and 80-pin TQFP package figure with additional names. These alternate functions are also present on the 92-pin LGA package and are identical to those on the 80-pin TQFP package.

**Figure 6.2. SiM3C1x7-GM Pinout**

**Table 6.1. Pin Definitions and alternate functions for SiM3C1x7 (Continued)**

Pin Name	Type	Pin Numbers TQFP-80	Pin Numbers LGA-92	Crossbar Capability (see Port Config Section)	Port Match	External Memory Interface (m = muxed mode)	Port-Mapped Level Shifter	Output Toggle Logic	External Trigger Inputs	Analog or Additional Functions
PB4.0	High Drive I/O	8	A6				LSO0			
PB4.1	High Drive I/O	7	A5				LSO1			
PB4.2	High Drive I/O	6	A4				LSO2			
PB4.3	High Drive I/O	3	A2				LSO3			
PB4.4	High Drive I/O	2	A1				LSO4			
PB4.5	High Drive I/O	1	D1				LSO5			
<b>Note:</b> All unnamed pins on the LGA-92 package are no-connect pins. They should be soldered to the PCB for mechanical stability, but have no internal connections to the device.										

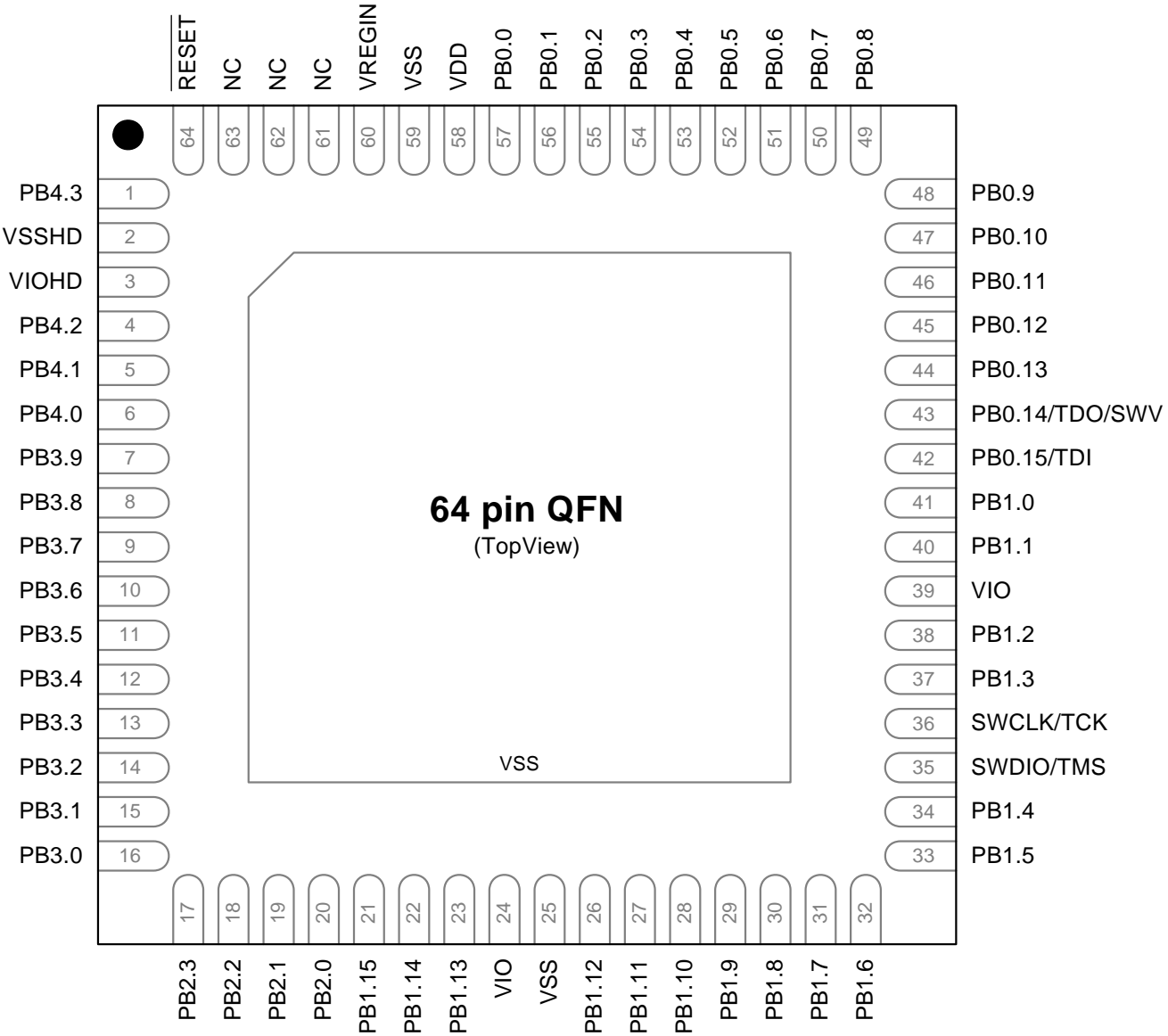


Figure 6.4. SiM3C1x6-GM Pinout

Table 6.2. Pin Definitions and alternate functions for SiM3C1x6

Pin Name	Type	Pin Numbers	Crossbar Capability (see Port Config Section)	Port Match	External Memory Interface (m = muxed mode)	Port-Mapped Level Shifter	Output Toggle Logic	External Trigger Inputs	Analog or Additional Functions
VSS	Ground	25 59							
VDD	Power (Core)	58							
VIO	Power (I/O)	24 39							
VREGIN	Power (Regulator)	60							
VSSHD	Ground (High Drive)	2							
VIOHD	Power (High Drive)	3							
$\overline{\text{RESET}}$	Active-low Reset	64							
SWCLK/TCK	Serial Wire / JTAG	36							
SWDIO/TMS	Serial Wire / JTAG	35							
PB0.0	Standard I/O	57	XBR0	✓					ADC0.2 CS0.1
PB0.1	Standard I/O	56	XBR0	✓					ADC0.3 CS0.2
PB0.2	Standard I/O	55	XBR0	✓					ADC0.4 CS0.3
PB0.3	Standard I/O	54	XBR0	✓					ADC0.5 CS0.4
PB0.4	Standard I/O	53	XBR0	✓					ADC0.6 CS0.5 IVC0.0
PB0.5	Standard I/O	52	XBR0	✓					ADC0.7 CS0.6 IVC0.1
PB0.6	Standard I/O	51	XBR0	✓					ADC0.8 CS0.7 RTC1



**Table 6.2. Pin Definitions and alternate functions for SiM3C1x6 (Continued)**

Pin Name	Type	Pin Numbers	Crossbar Capability (see Port Config Section)	Port Match	External Memory Interface (m = muxed mode)	Port-Mapped Level Shifter	Output Toggle Logic	External Trigger Inputs	Analog or Additional Functions
PB0.7	Standard I/O	50	XBR0	✓					RTC2
PB0.8	Standard I/O	49	XBR0	✓					ADC0.9 VREFGND
PB0.9	Standard I/O	48	XBR0	✓					ADC0.10 VREF
PB0.10	Standard I/O	47	XBR0	✓					ADC1.6 IDAC0
PB0.11	Standard I/O	46	XBR0	✓					IDAC1
PB0.12	Standard I/O	45	XBR0	✓					XTAL1
PB0.13	Standard I/O	44	XBR0	✓					XTAL2
PB0.14/TDO/ SWV	Standard I/O / JTAG / Serial Wire Viewer	43	XBR0	✓					ADC0.12 ADC1.12
PB0.15/TDI	Standard I/O / JTAG	42	XBR0	✓					ADC0.13 ADC1.13
PB1.0	Standard I/O	41	XBR0	✓					ADC0.14 ADC1.14
PB1.1	Standard I/O	40	XBR0	✓					ADC0.15 ADC1.15
PB1.2	Standard I/O	38	XBR0	✓					ADC1.11 CS0.8
PB1.3	Standard I/O	37	XBR0	✓					ADC1.10 CS0.9
PB1.4	Standard I/O	34	XBR0	✓					ADC1.8
PB1.5	Standard I/O	33	XBR0	✓					ADC1.7
PB1.6	Standard I/O	32	XBR0	✓				ADC0T15 WAKE.0	ADC1.5 CS0.10
PB1.7	Standard I/O	31	XBR0	✓	AD15m/ A7			ADC1T15 WAKE.1	ADC1.4 CS0.11

Table 6.3. Pin Definitions and Alternate Functions for SiM3C1x4 (Continued)

Pin Name	Type	Pin Numbers	Crossbar Capability (see Port Config Section)	Port Match	Output Toggle Logic	External Trigger Inputs	Analog or Additional Functions
PB3.1	5 V Tolerant I/O	9	XBR1	✓		DAC0T1 DAC1T1 LPT0T1 INT0.1 INT1.1 WAKE.13	CMP0N.1 CMP1N.1 EXREGSN
PB3.2	5 V Tolerant I/O	8	XBR1	✓		DAC0T2 DAC1T2 LPT0T2 INT0.2 INT1.3 WAKE.14	CMP0P.2 CMP1P.2 EXREGOUT
PB3.3	5 V Tolerant I/O	7	XBR1	✓		DAC0T3 DAC1T3 INT0.3 INT1.3 WAKE.15	CMP0N.2 CMP1N.2 EXREGBD
PB4.0	High Drive I/O	6					
PB4.1	High Drive I/O	5					
PB4.2	High Drive I/O	4					
PB4.3	High Drive I/O	1					

## 6.5. TQFP-80 Package Specifications

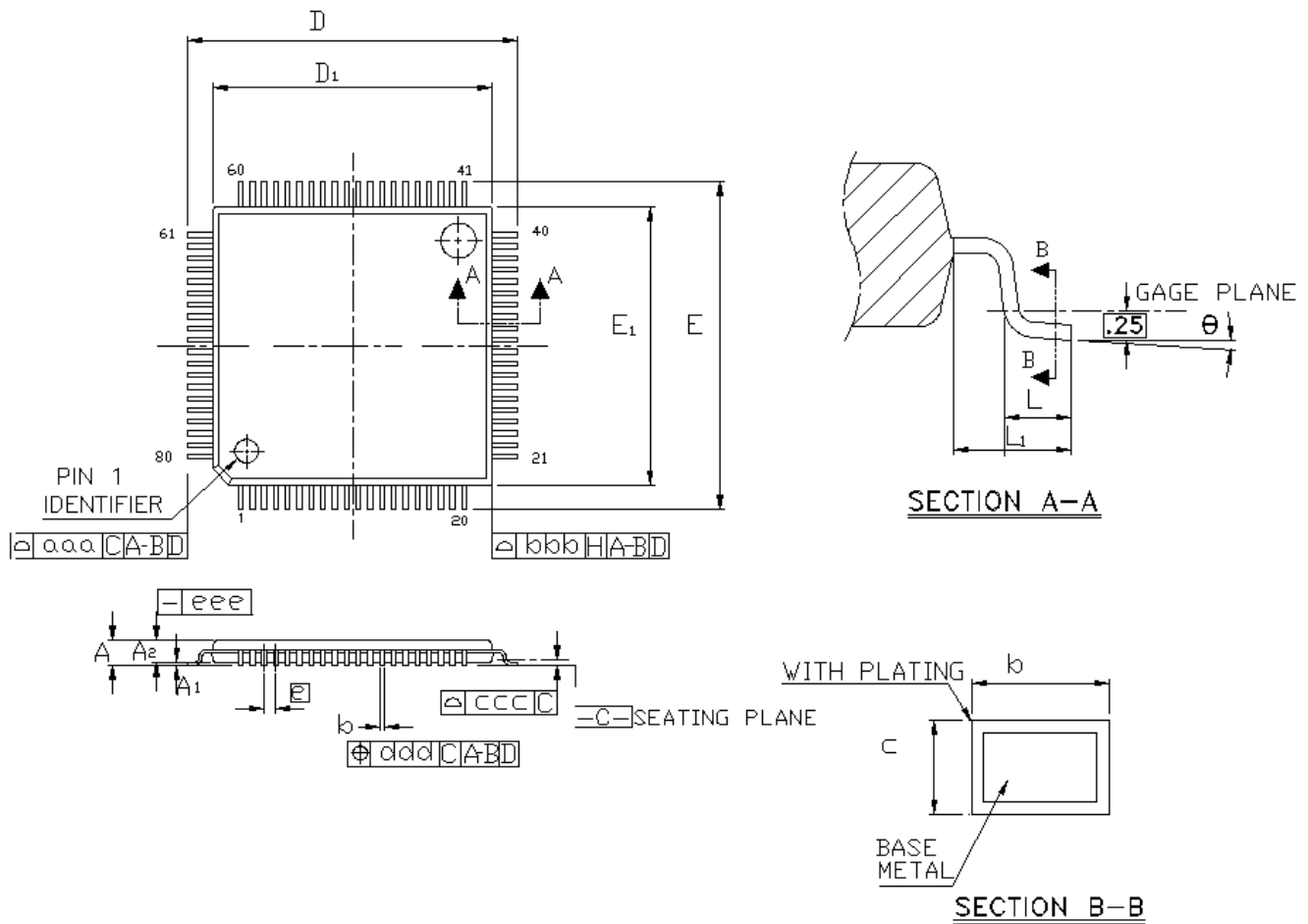
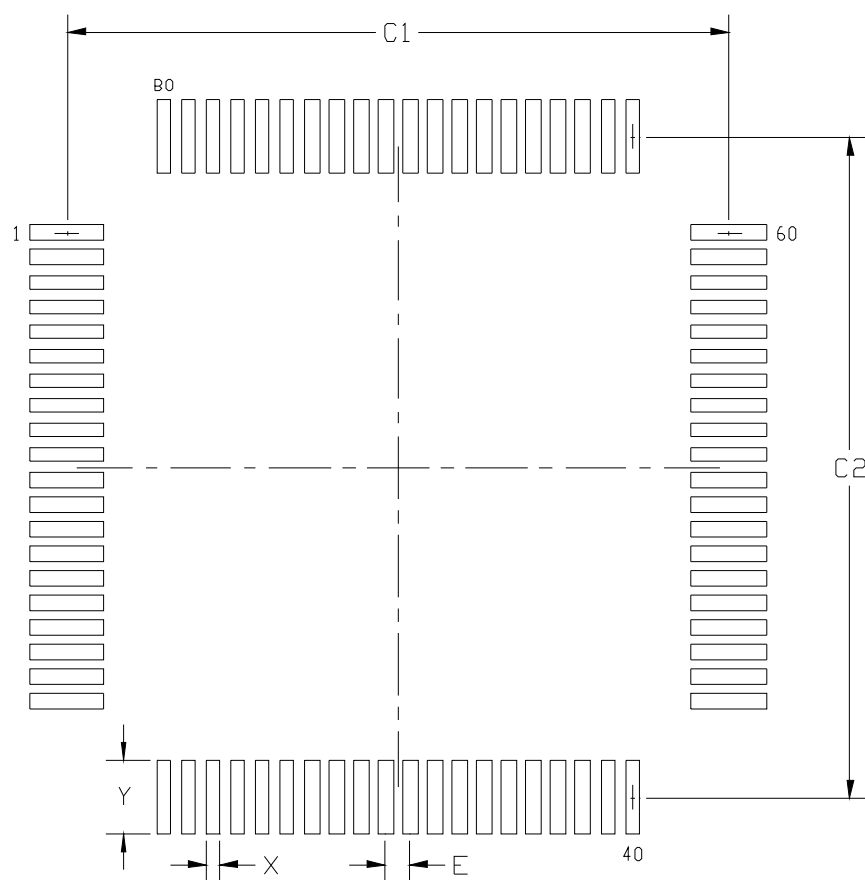


Figure 6.8. TQFP-80 Package Drawing

Table 6.6. TQFP-80 Package Dimensions

Dimension	Min	Nominal	Max
A	—	—	1.20
A1	0.05	—	0.15
A2	0.95	1.00	1.05
b	0.17	0.20	0.27
c	0.09	—	0.20
D	14.00 BSC		
D1	12.00 BSC		
e	0.50 BSC		
E	14.00 BSC		
E1	12.00 BSC		



**Figure 6.9. TQFP-80 Landing Diagram**

**Table 6.7. TQFP-80 Landing Diagram Dimensions**

Dimension	Min	Max
<b>C1</b>	13.30	13.40
<b>C2</b>	13.30	13.40
<b>E</b>	0.50 BSC	
<b>X</b>	0.20	0.30
<b>Y</b>	1.40	1.50
<b>Notes:</b>		
1. All dimensions shown are in millimeters (mm) unless otherwise noted.		
2. This land pattern design is based on the IPC-7351 guidelines.		

## DOCUMENT CHANGE LIST

### Revision 0.8 to Revision 1.0

- Added block diagram to front page; updated feature bullet lists.
- Electrical Specifications Tables Additions:
  - Voltage Regulator Current Sense Supply Current, Typ = 3  $\mu$ A (Table 3.2)
  - Power Mode 2 Wake Time, Min = 4 clocks, Max = 5 clocks (Table 3.3)
  - External Crystal Clock Frequency, Min = 0.01 MHz, Max = 30 MHz (Table 3.9)
  - Added /RESET pin characteristics (Table 3.17)
- Electrical Specifications Tables Removals:
  - Power Mode 3 Wake Time (Table 3.3)
- Electrical Specifications Tables Corrections/Adjustments:
  - IVC Supply Current, Max = 2.5  $\mu$ A (Table 3.2)
  - VREG0 Output Voltage Normal Mode, Min = 3.15 V (Table 3.5)
  - VREG0 Output Voltage Suspend Mode, Min = 3.15 V (Table 3.5)
  - External Regulator Internal Pull-Down, Typ = 5 k $\Omega$  (Table 3.6)
  - External Regulator Internal Pull-Up, Typ = 10 k $\Omega$  (Table 3.6)
  - Flash Memory Endurance, Typ = 100k write/erase cycles (Table 3.7)
  - Flash Memory Retention, Min = 10 Years, Typ = 100 Years (Table 3.7)
  - Low Power Oscillator Frequency, Min = 19.5 MHz, Max = 20.5 MHz (Table 3.8)
  - SAR Dynamic Performance : consolidated all specs. (Table 3.10)
  - IDAC Full Scale Output Current 1 mA Range, Min = 0.99 mA (Table 3.11)
  - IDAC Full Scale Output Current 0.5 mA Range, Min = 493  $\mu$ A (Table 3.11)
  - IVC Slope @ 1 mA, Min = 1.55 V/mA, Max = 1.75 V/mA (Table 3.13)
  - IVC Slope @ 2 mA, Min = 795 mV/mA, Max = 860 mV/mA (Table 3.13)
  - IVC Slope @ 3 mA, Min = 525 mV/mA, Max = 570 mV/mA (Table 3.13)
  - IVC Slope @ 4 mA, Min = 390 mV/mA, Max = 430 mV/mA (Table 3.13)
  - IVC Slope @ 5 mA, Min = 315 mV/mA (Table 3.13)
  - IVC Slope @ 6 mA, Min = 260 mV/mA (Table 3.13)
  - Temperature Sensor Slope Error, Type =  $\pm 120$   $\mu$ V/C (Table 3.15)
  - Comparator Input Offset Voltage, Min = -10 mV, Max = 10 mV (Table 3.16)
- "4. Precision32™ SiM3C1xx System Overview" :
  - Updated Power Modes discussion.
  - Refined and updated feature bullet lists.
- Updated and clarified RTC timer clock output. The RTC output is now referred to as "RTC0TCLK".
- "6. Pin Definitions and Packaging Information" : Renamed RTC0OSC\_OUT function to RTC0TCLK\_OUT for consistency.
- "7. Revision Specific Behavior" : Updated revision identification drawings to better match physical appearance of packages.