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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	Z8
Core Size	8-Bit
Speed	8MHz
Connectivity	-
Peripherals	HLVD, POR, WDT
Number of I/O	16
Program Memory Size	8KB (8K x 8)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	237 x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Through Hole
Package / Case	20-DIP (0.300", 7.62mm)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/zgp323hap2008c



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Development Features

Table 2 lists the features of ZiLOG®'s ZGP323H members.

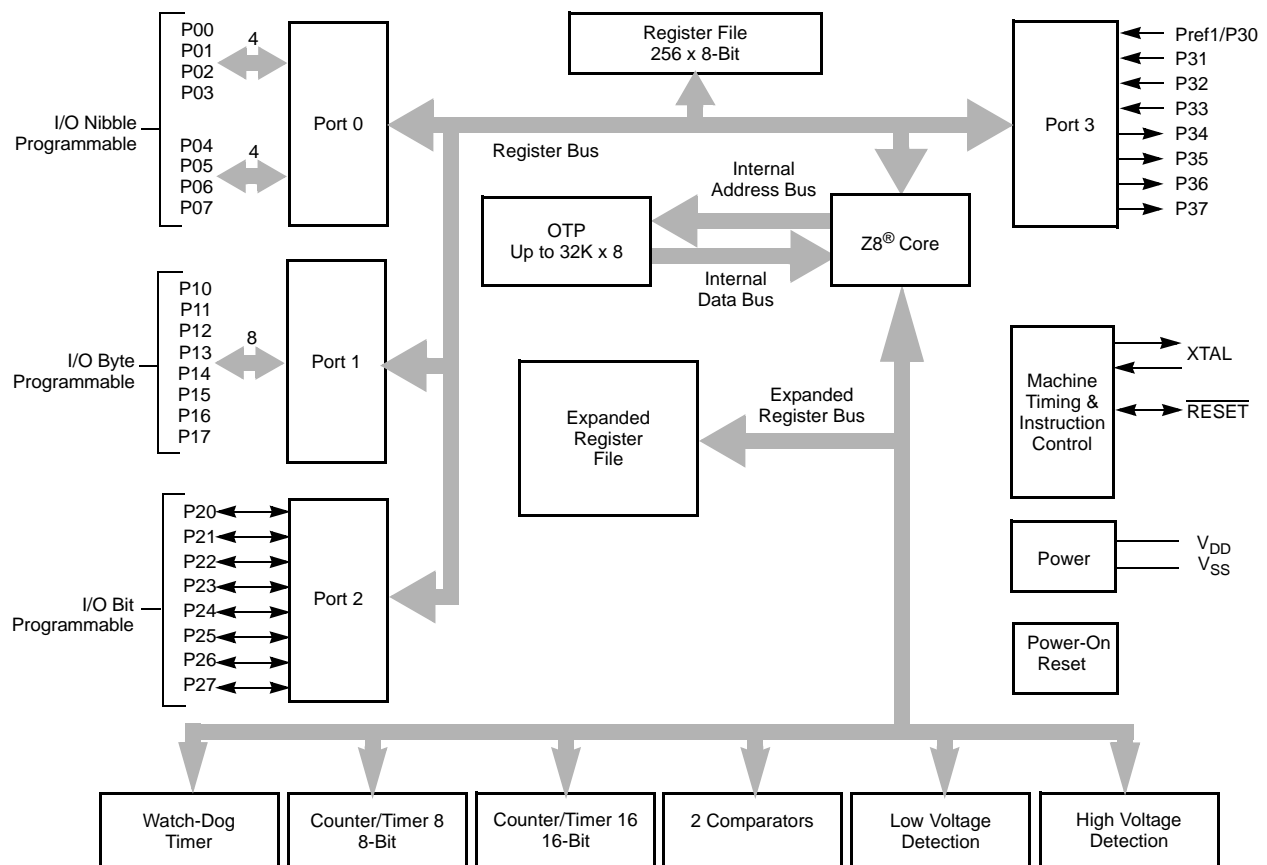
Table 2. Features

Device	OTP (KB)	RAM (Bytes)	I/O Lines	Voltage Range
ZGP323H OTP MCU Family	4, 8, 16, 32	237	32, 24 or 16	2.0V–5.5V

- Low power consumption—18mW (typical)
- T = Temperature
S = Standard 0° to +70°C
E = Extended -40° to +105°C
A = Automotive -40° to +125°C
- Three standby modes:
 - STOP— (typical 1.8µA)
 - HALT— (typical 0.8mA)
 - Low voltage reset
- Special architecture to automate both generation and reception of complex pulses or signals:
 - One programmable 8-bit counter/timer with two capture registers and two load registers
 - One programmable 16-bit counter/timer with one 16-bit capture register pair and one 16-bit load register pair
 - Programmable input glitch filter for pulse reception
- Six priority interrupts
 - Three external
 - Two assigned to counter/timers
 - One low-voltage detection interrupt
- Low voltage detection and high voltage detection flags
- Programmable Watch-Dog Timer/Power-On Reset (WDT/POR) circuits
- Two independent comparators with programmable interrupt polarity
- Programmable EPROM options
 - Port 0: 0–3 pull-up transistors
 - Port 0: 4–7 pull-up transistors

Table 3. Power Connections

Connection	Circuit	Device
Power	V _{CC}	V _{DD}
Ground	GND	V _{SS}



Note: Refer to the specific package for available pins.

Figure 1. Functional Block Diagram

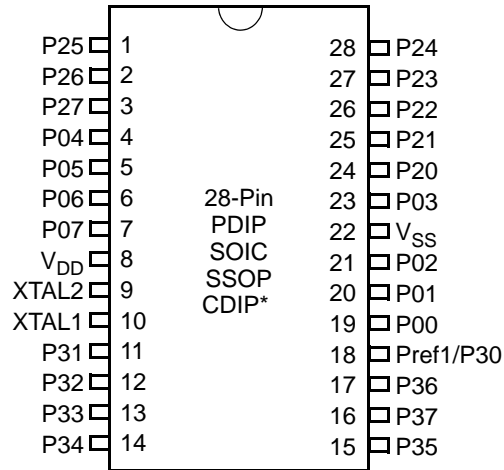


Figure 4. 28-Pin PDIP/SOIC/SSOP/CDIP* Pin Configuration

Table 5. 28-Pin PDIP/SOIC/SSOP/CDIP* Pin Identification

Pin	Symbol	Direction	Description
1-3	P25-P27	Input/Output	Port 2, Bits 5,6,7
4-7	P04-P07	Input/Output	Port 0, Bits 4,5,6,7
8	V _{DD}		Power supply
9	XTAL2	Output	Crystal, oscillator clock
10	XTAL1	Input	Crystal, oscillator clock
11-13	P31-P33	Input	Port 3, Bits 1,2,3
14	P34	Output	Port 3, Bit 4
15	P35	Output	Port 3, Bit 5
16	P37	Output	Port 3, Bit 7
17	P36	Output	Port 3, Bit 6
18	Pref1/P30 Port 3 Bit 0	Input	Analog ref input; connect to V _{CC} if not used Input for Pref1/P30
19-21	P00-P02	Input/Output	Port 0, Bits 0,1,2
22	V _{SS}		Ground
23	P03	Input/Output	Port 0, Bit 3
24-28	P20-P24	Input/Output	Port 2, Bits 0-4

Capacitance

Table 8 lists the capacitances.

Table 8. Capacitance

Parameter	Maximum
Input capacitance	12pF
Output capacitance	12pF
I/O capacitance	12pF
Note: $T_A = 25^\circ\text{C}$, $V_{CC} = \text{GND} = 0\text{V}$, $f = 1.0\text{MHz}$, unmeasured pins returned to GND	

DC Characteristics

Table 9. GP323HS DC Characteristics

Symbol	Parameter	V_{CC}	$T_A = 0^\circ\text{C to } +70^\circ\text{C}$			Units	Conditions	Notes
			Min	Typ(7)	Max			
V_{CC}	Supply Voltage		2.0		5.5	V	See Note 5	5
V_{CH}	Clock Input High Voltage	2.0-5.5	$0.8 V_{CC}$		$V_{CC}+0.3$	V	Driven by External Clock Generator	
V_{CL}	Clock Input Low Voltage	2.0-5.5	$V_{SS}-0.3$		0.4	V	Driven by External Clock Generator	
V_{IH}	Input High Voltage	2.0-5.5	$0.7 V_{CC}$		$V_{CC}+0.3$	V		
V_{IL}	Input Low Voltage	2.0-5.5	$V_{SS}-0.3$		$0.2 V_{CC}$	V		
V_{OH1}	Output High Voltage	2.0-5.5	$V_{CC}-0.4$			V	$I_{OH} = -0.5\text{mA}$	
V_{OH2}	Output High Voltage (P36, P37, P00, P01)	2.0-5.5	$V_{CC}-0.8$			V	$I_{OH} = -7\text{mA}$	
V_{OL1}	Output Low Voltage	2.0-5.5			0.4	V	$I_{OL} = 4.0\text{mA}$	
V_{OL2}	Output Low Voltage (P00, P01, P36, P37)	2.0-5.5			0.8	V	$I_{OL} = 10\text{mA}$	
V_{OFFSET}	Comparator Input Offset Voltage	2.0-5.5			25	mV		
V_{REF}	Comparator Reference Voltage	2.0-5.5	0		V_{CC} 1.75	V		
I_{IL}	Input Leakage	2.0-5.5	-1		1	μA	$V_{IN} = 0\text{V}$, V_{CC} Pull-ups disabled	
R_{PU}	Pull-up Resistance	2.0V	225		675	$\text{K}\Omega$	$V_{IN} = 0\text{V}$; Pullups selected by mask option	
		3.6V	75		275	$\text{K}\Omega$		
		5.0V	40		160	$\text{K}\Omega$		

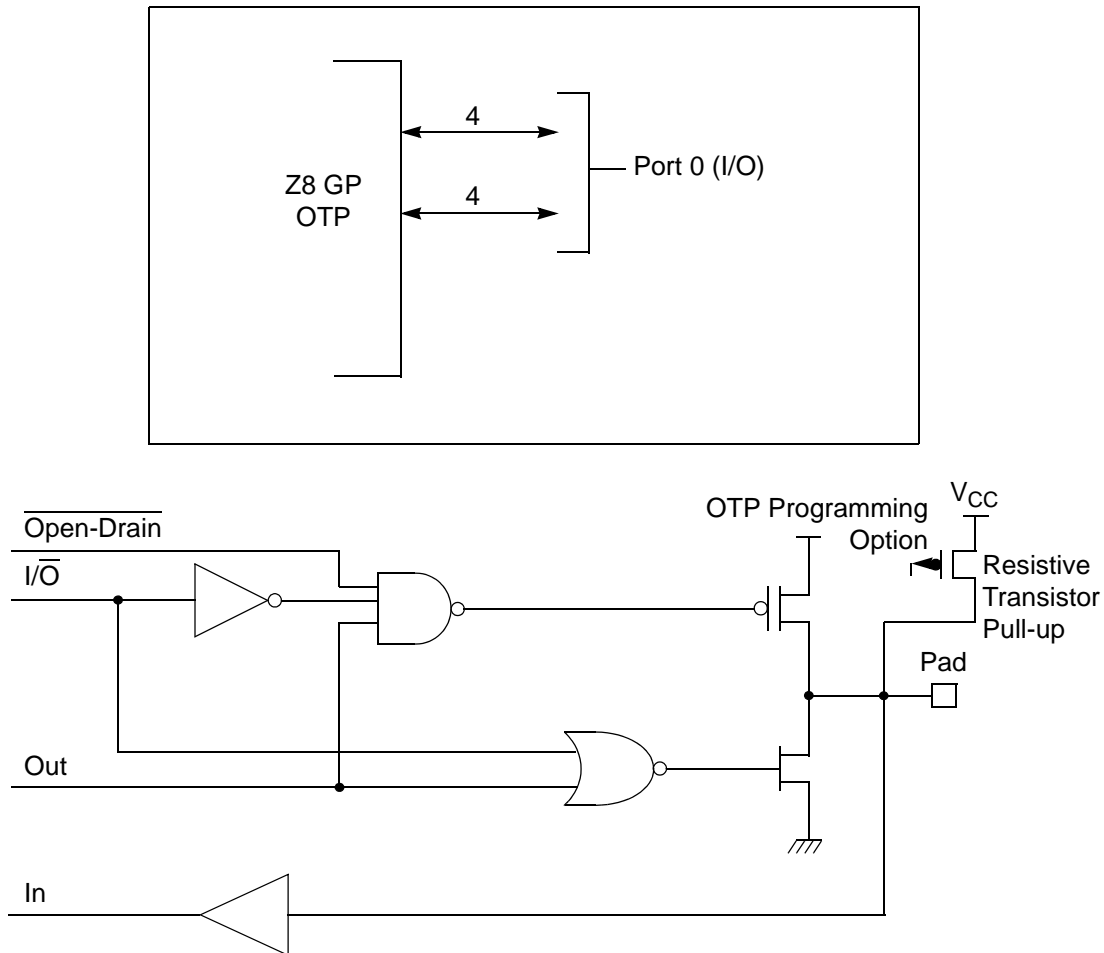


Figure 9. Port 0 Configuration

Port 1 (P17–P10)

Port 1 (see Figure 10) Port 1 can be configured for standard port input or output mode. After POR, Port 1 is configured as an input port. The output drivers are either push-pull or open-drain and are controlled by bit D1 in the PCON register.

► **Note:** The Port 1 direction is reset to its default state following an SMR.

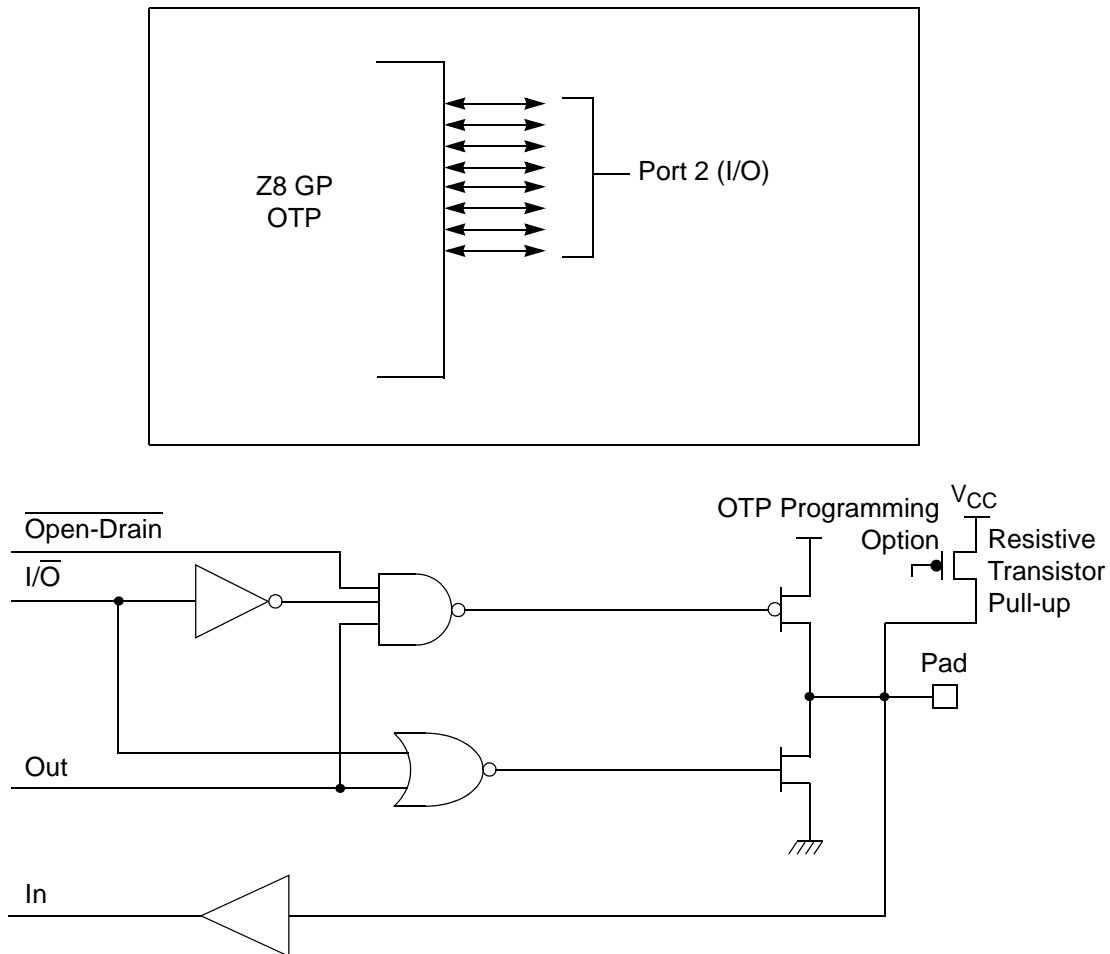


Figure 11. Port 2 Configuration

Port 3 (P37–P30)

Port 3 is a 8-bit, CMOS-compatible fixed I/O port (see Figure 12). Port 3 consists of four fixed input (P33–P30) and four fixed output (P37–P34), which can be configured under software control for interrupt and as output from the counter/timers. P30, P31, P32, and P33 are standard CMOS inputs; P34, P35, P36, and P37 are push-pull outputs.



CTR1(0D)01H" on page 35). Other edge detect and IRQ modes are described in Table 14.

- **Note:** Comparators are powered down by entering Stop Mode. For P31–P33 to be used in a Stop Mode Recovery (SMR) source, these inputs must be placed into digital mode.

Table 14. Port 3 Pin Function Summary

Pin	I/O	Counter/Timers	Comparator	Interrupt
Pref1/P30	IN		RF1	
P31	IN	IN	AN1	IRQ2
P32	IN		AN2	IRQ0
P33	IN		RF2	IRQ1
P34	OUT	T8	AO1	
P35	OUT	T16		
P36	OUT	T8/16		
P37	OUT		AO2	
P20	I/O	IN		

Port 3 also provides output for each of the counter/timers and the AND/OR Logic (see Figure 13). Control is performed by programming bits D5–D4 of CTR1, bit 0 of CTR0, and bit 0 of CTR2.



T8/T16_Logic/Edge _Detect

In TRANSMIT Mode, this field defines how the outputs of T8 and T16 are combined (AND, OR, NOR, NAND).

In DEMODULATION Mode, this field defines which edge should be detected by the edge detector.

Transmit_Submode/Glitch Filter

In Transmit Mode, this field defines whether T8 and T16 are in the PING-PONG mode or in independent normal operation mode. Setting this field to “NORMAL OPERATION Mode” terminates the “PING-PONG Mode” operation. When set to 10, T16 is immediately forced to a 0; a setting of 11 forces T16 to output a 1.

In DEMODULATION Mode, this field defines the width of the glitch that must be filtered out.

Initial_T8_Out/Rising_Edge

In TRANSMIT Mode, if 0, the output of T8 is set to 0 when it starts to count. If 1, the output of T8 is set to 1 when it starts to count. When the counter is not enabled and this bit is set to 1 or 0, T8_OUT is set to the opposite state of this bit. This ensures that when the clock is enabled, a transition occurs to the initial state set by CTR1, D1.

In DEMODULATION Mode, this bit is set to 1 when a rising edge is detected in the input signal. In order to reset the mode, a 1 should be written to this location.

Initial_T16 Out/Falling _Edge

In TRANSMIT Mode, if it is 0, the output of T16 is set to 0 when it starts to count. If it is 1, the output of T16 is set to 1 when it starts to count. This bit is effective only in Normal or PING-PONG Mode (CTR1, D3; D2). When the counter is not enabled and this bit is set, T16_OUT is set to the opposite state of this bit. This ensures that when the clock is enabled, a transition occurs to the initial state set by CTR1, D0.

In DEMODULATION Mode, this bit is set to 1 when a falling edge is detected in the input signal. In order to reset it, a 1 should be written to this location.

- **Note:** Modifying CTR1 (D1 or D0) while the counters are enabled causes unpredictable output from T8/16_OUT.

CTR2 Counter/Timer 16 Control Register—CTR2(D)02H

Table 17 lists and briefly describes the fields for this register.

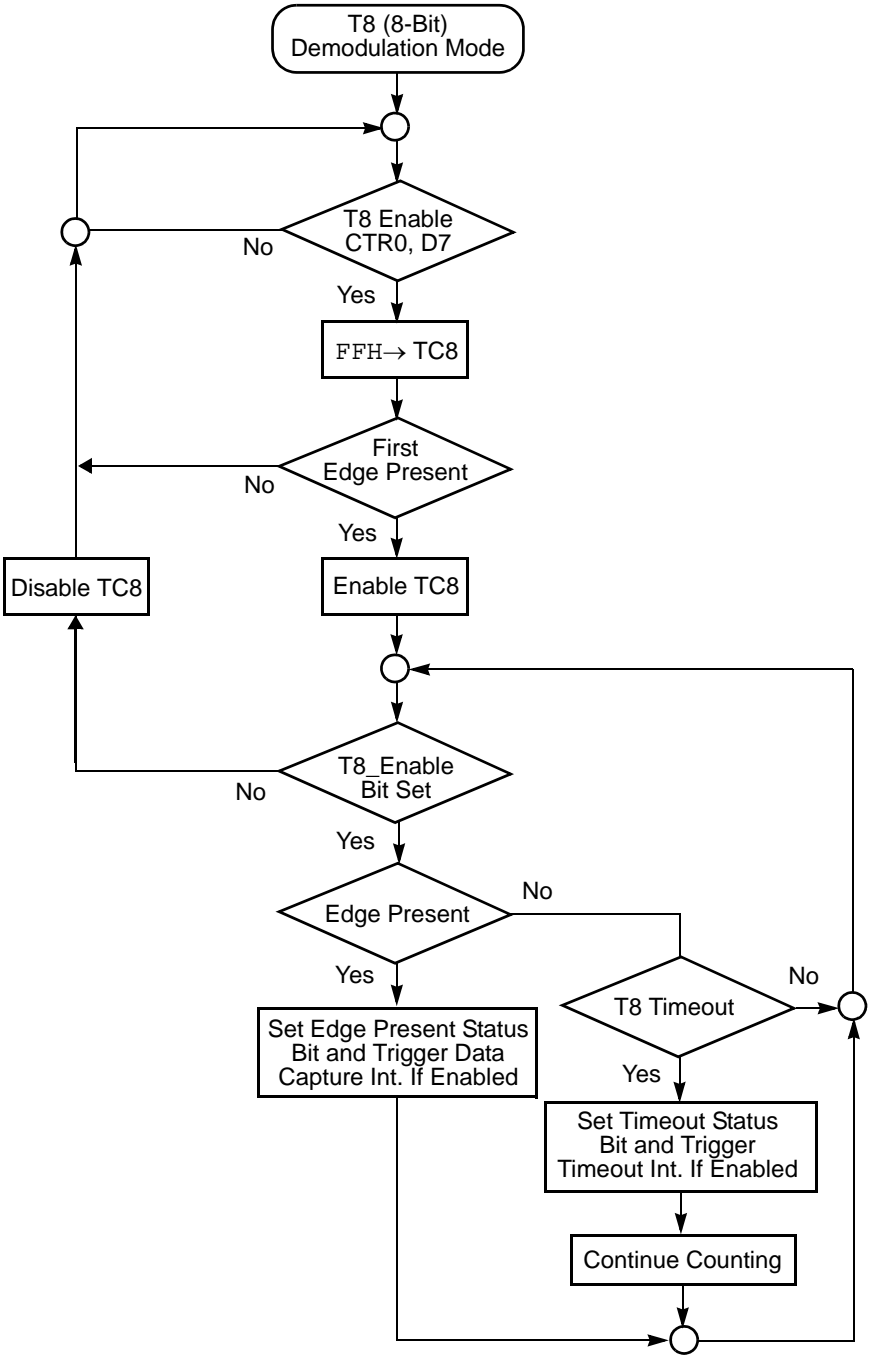


Figure 24. Demodulation Mode Flowchart



If D6 of CTR2 Is 1

T16 ignores the subsequent edges in the input signal and continues counting down. A timeout of T8 causes T16 to capture its current value and generate an interrupt if enabled (CTR2, D2). In this case, T16 does not reload and continues counting. If the D6 bit of CTR2 is toggled (by writing a 0 then a 1 to it), T16 captures and reloads on the next edge (rising, falling, or both depending on CTR1, D5; D4), continuing to ignore subsequent edges.

This T16 mode generally measures mark time, the length of an active carrier signal burst.

If T16 reaches 0, T16 continues counting from `FFFFh`. Meanwhile, a status bit (CTR2 D5) is set, and an interrupt timeout can be generated if enabled (CTR2 D1).

Ping-Pong Mode

This operation mode is only valid in TRANSMIT Mode. T8 and T16 must be programmed in Single-Pass mode (CTR0, D6; CTR2, D6), and Ping-Pong mode must be programmed in CTR1, D3; D2. The user can begin the operation by enabling either T8 or T16 (CTR0, D7 or CTR2, D7). For example, if T8 is enabled, T8_OUT is set to this initial value (CTR1, D1). According to T8_OUT's level, TC8H or TC8L is loaded into T8. After the terminal count is reached, T8 is disabled, and T16 is enabled. T16_OUT then switches to its initial value (CTR1, D0), data from TC16H and TC16L is loaded, and T16 starts to count. After T16 reaches the terminal count, it stops, T8 is enabled again, repeating the entire cycle. Interrupts can be allowed when T8 or T16 reaches terminal control (CTR0, D1; CTR2, D1). To stop the ping-pong operation, write 00 to bits D3 and D2 of CTR1. See Figure 28.

- **Note:** Enabling ping-pong operation while the counter/timers are running might cause intermittent counter/timer function. Disable the counter/timers and reset the status flags before instituting this operation.

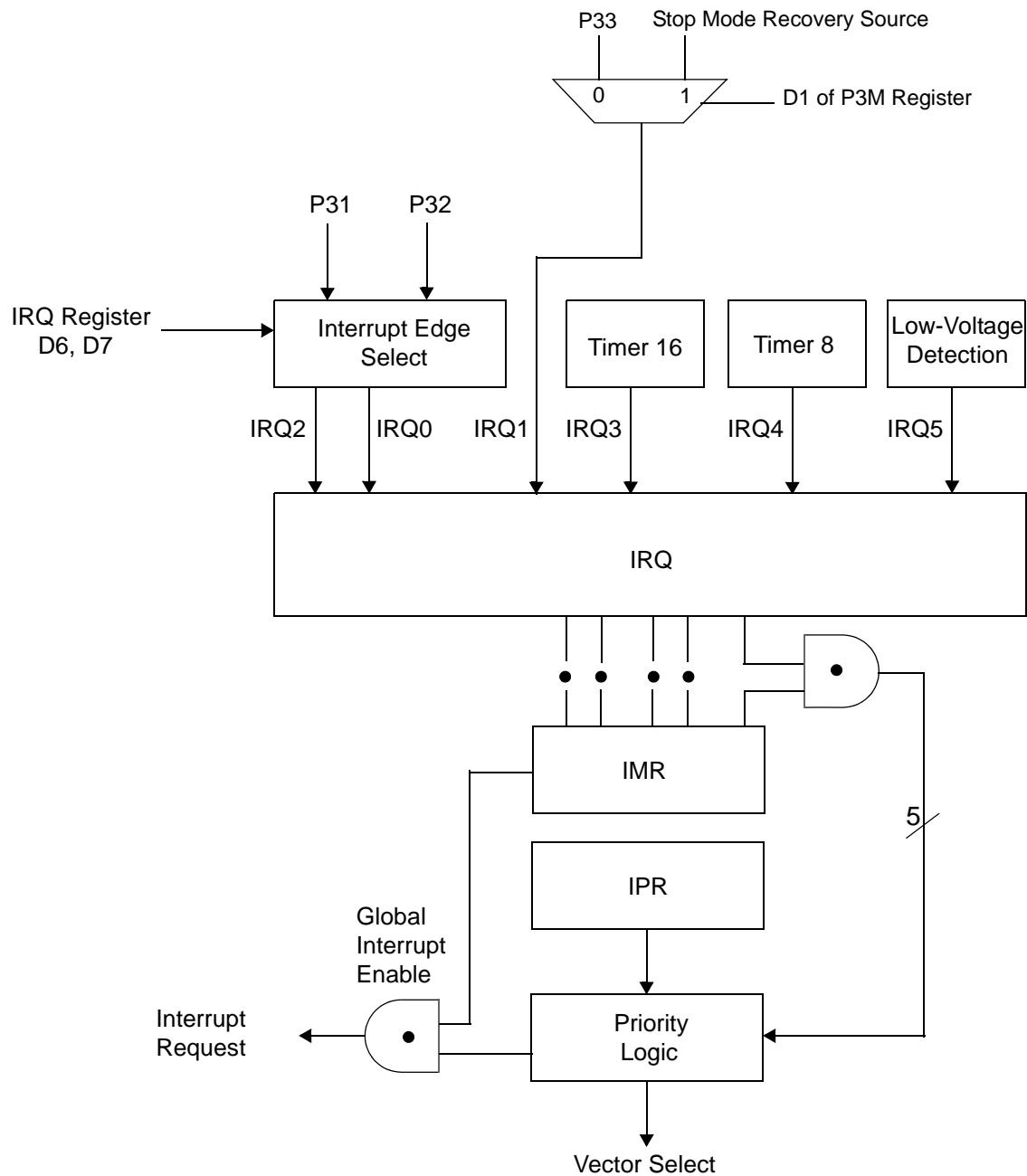
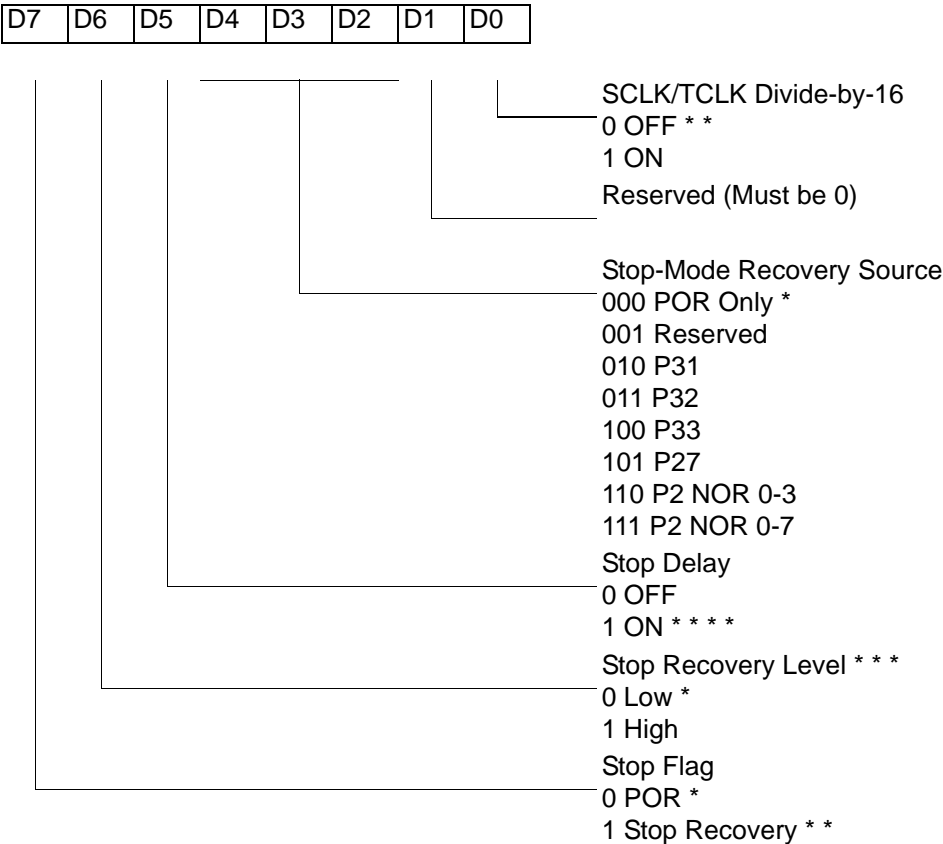


Figure 30. Interrupt Block Diagram



SMR(0F)0BH



* Default after Power On Reset or Watch-Dog Reset
* * Default setting after Reset and Stop Mode Recovery
* * * At the XOR gate input
* * * * Default setting after reset. Must be 1 if using a crystal or resonator clock source.

Figure 33. STOP Mode Recovery Register

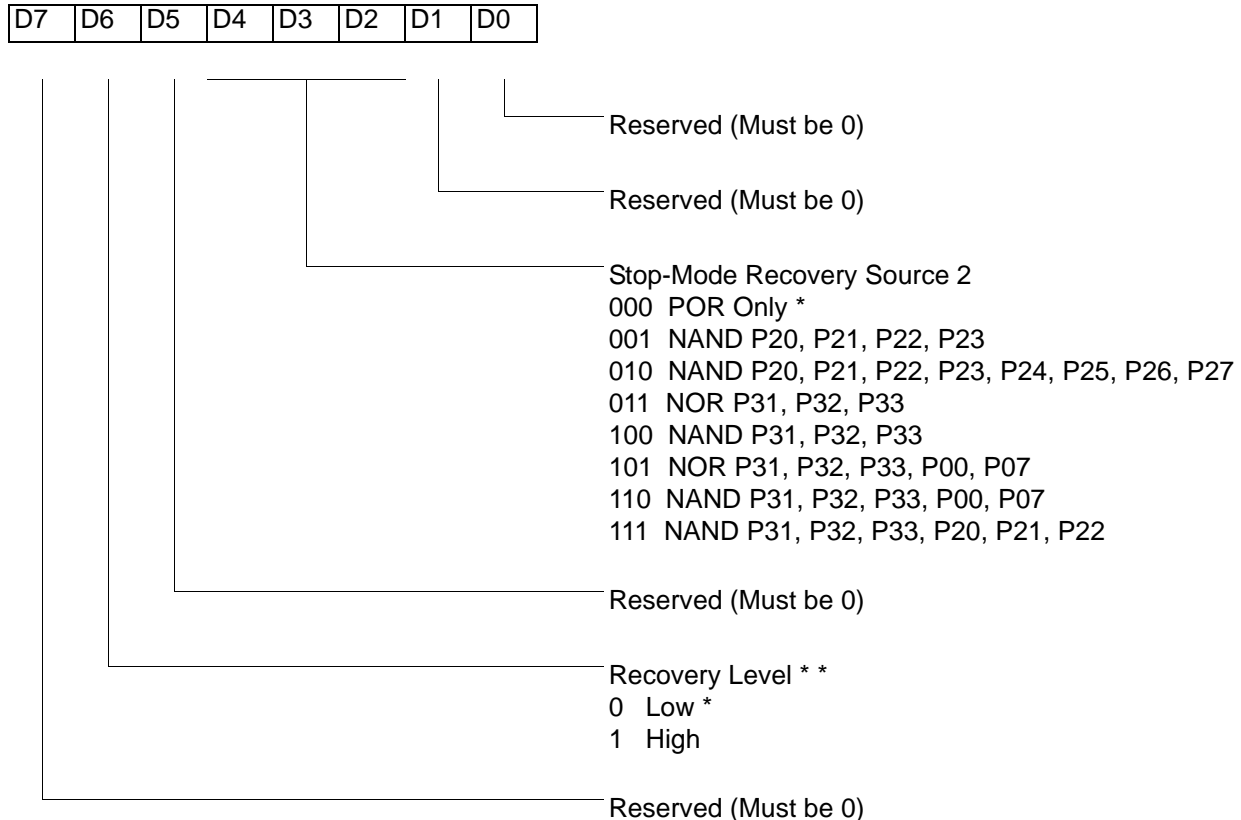
SCLK/TCLK Divide-by-16 Select (D0)

D0 of the SMR controls a divide-by-16 prescaler of SCLK/TCLK (Figure 34). This control selectively reduces device power consumption during normal processor execution (SCLK control) and/or Halt Mode (where TCLK sources interrupt logic). After Stop Mode Recovery, this bit is set to a 0.

Stop Mode Recovery Register 2 (SMR2)

This register determines the mode of Stop Mode Recovery for SMR2 (Figure 36).

SMR2(0F)DH



Note: If used in conjunction with SMR, either of the two specified events causes a Stop-Mode Recovery.

* Default setting after reset

** At the XOR gate input

Figure 36. Stop Mode Recovery Register 2 ((0F)DH:D2–D4, D6 Write Only)

If SMR2 is used in conjunction with SMR, either of the specified events causes a Stop Mode Recovery.

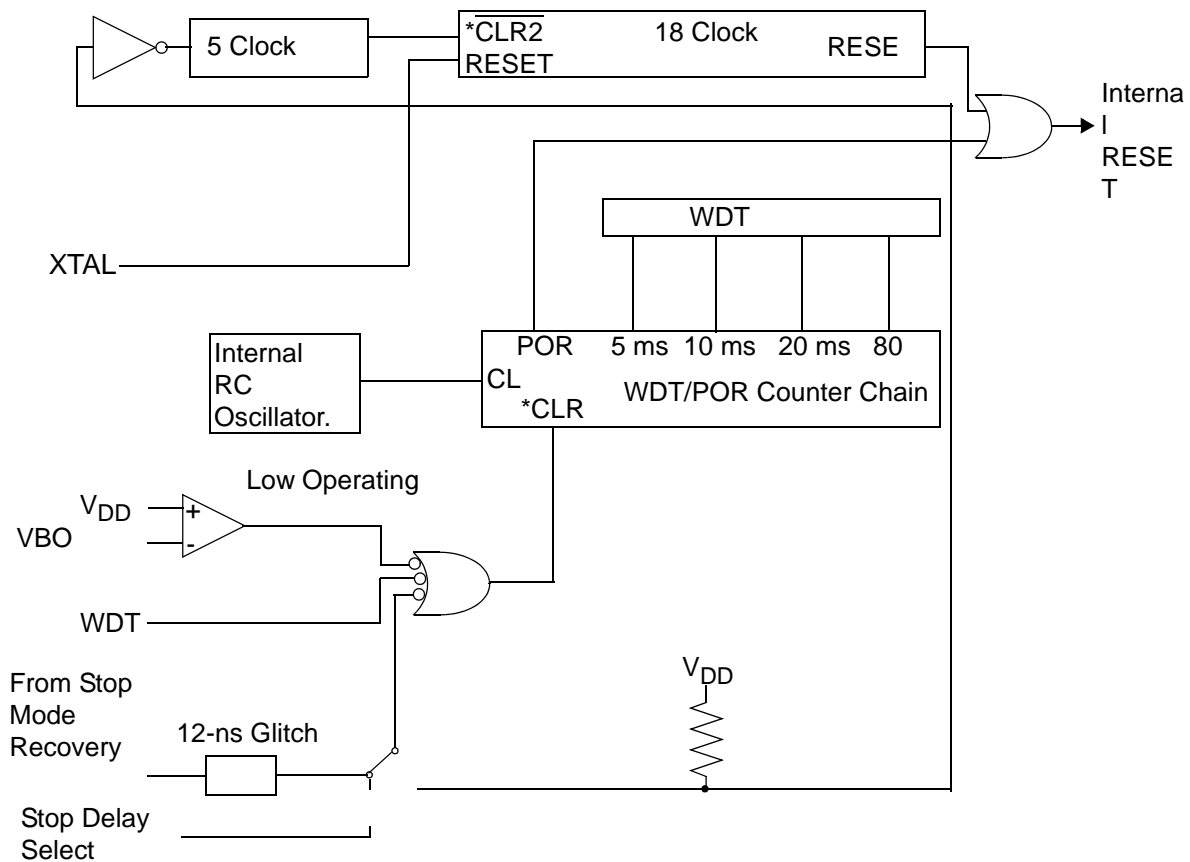
- **Note:** Port pins configured as outputs are ignored as an SMR or SMR2 recovery source. For example, if the NAND or P23–P20 is selected as the recovery source and P20 is configured as an output, the remaining SMR pins (P23–P21) form the NAND equation.

Table 23. Watch-Dog Timer Time Select

D1	D0	Timeout of Internal RC-Oscillator
0	0	5ms min.
0	1	10ms min.
1	0	20ms min.
1	1	80ms min.

WDTMR During Halt (D2)

This bit determines whether or not the WDT is active during HALT Mode. A 1 indicates active during HALT. The default is 1. See Figure 38.



* CLR1 and $\overline{\text{CLR2}}$ enable the WDT/POR and 18 Clock Reset timers respectively upon a Low-to-High transition.

Figure 38. Resets and WDT

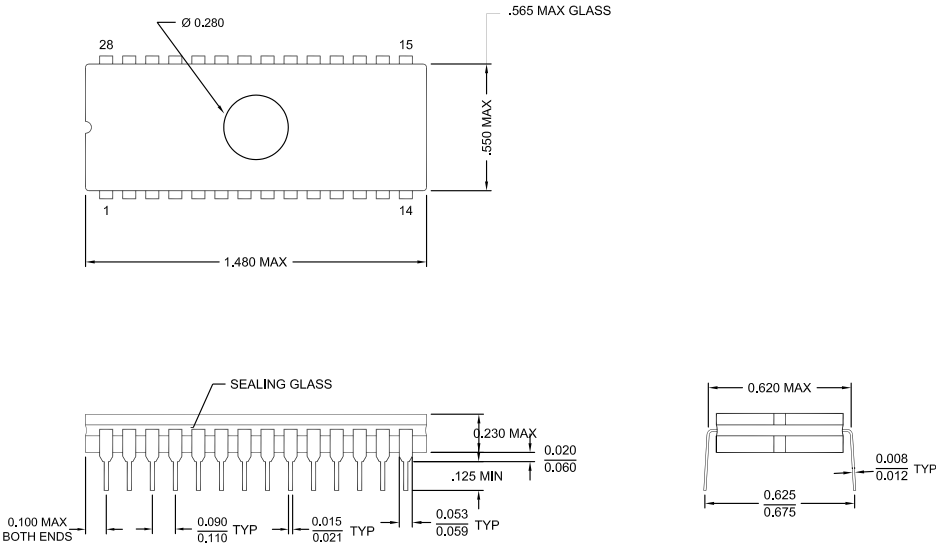
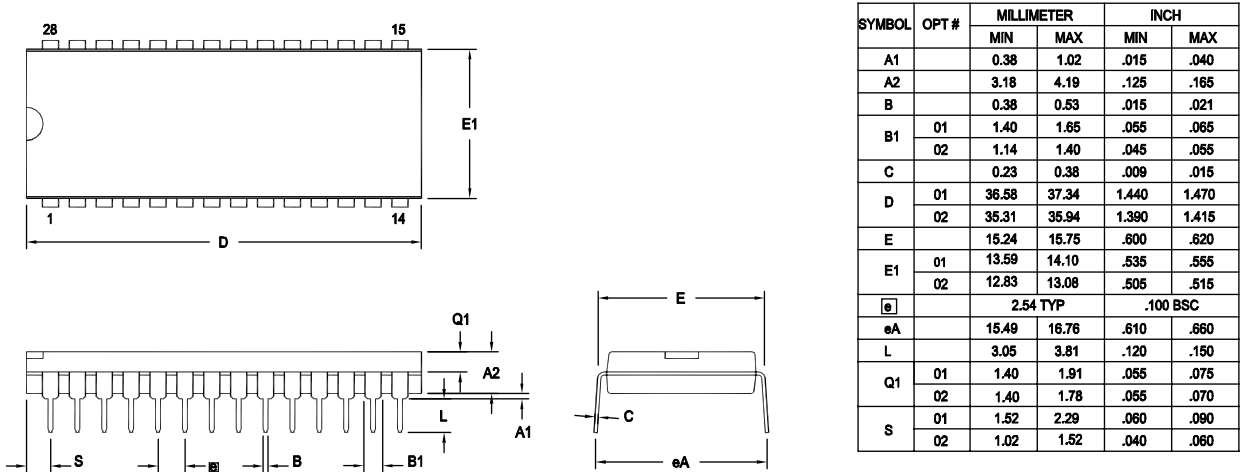


Figure 63. 28-Pin CDIP Package Diagram



CONTROLLING DIMENSIONS : INCH

OPTION TABLE	
OPTION #	PACKAGE
01	STANDARD
02	IDF

Note: ZILOG supplies both options for production. Component layout PCB design should cover bigger option 01.

Figure 64. 28-Pin PDIP Package Diagram

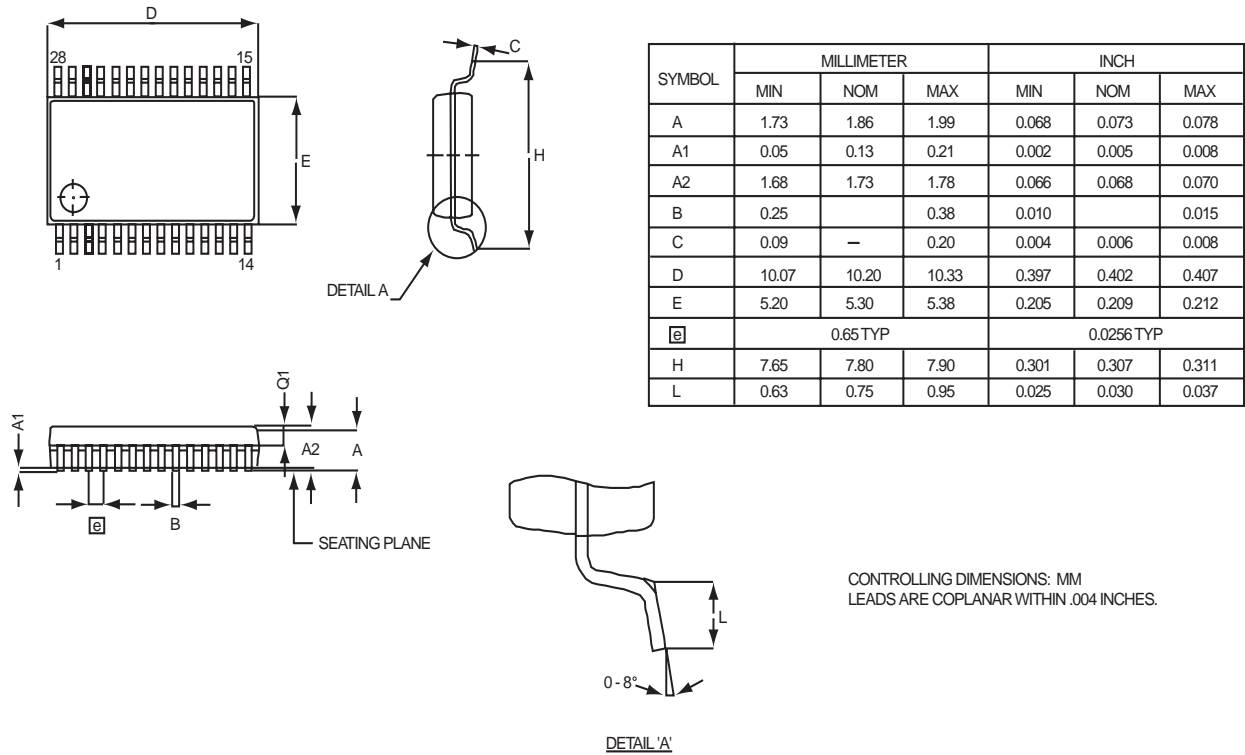


Figure 65. 28-Pin SSOP Package Diagram

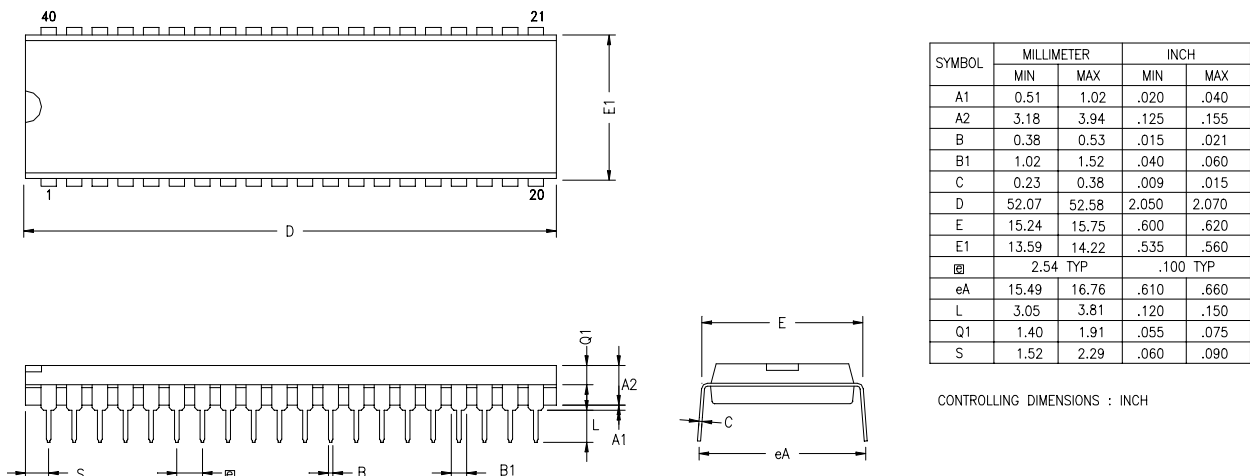
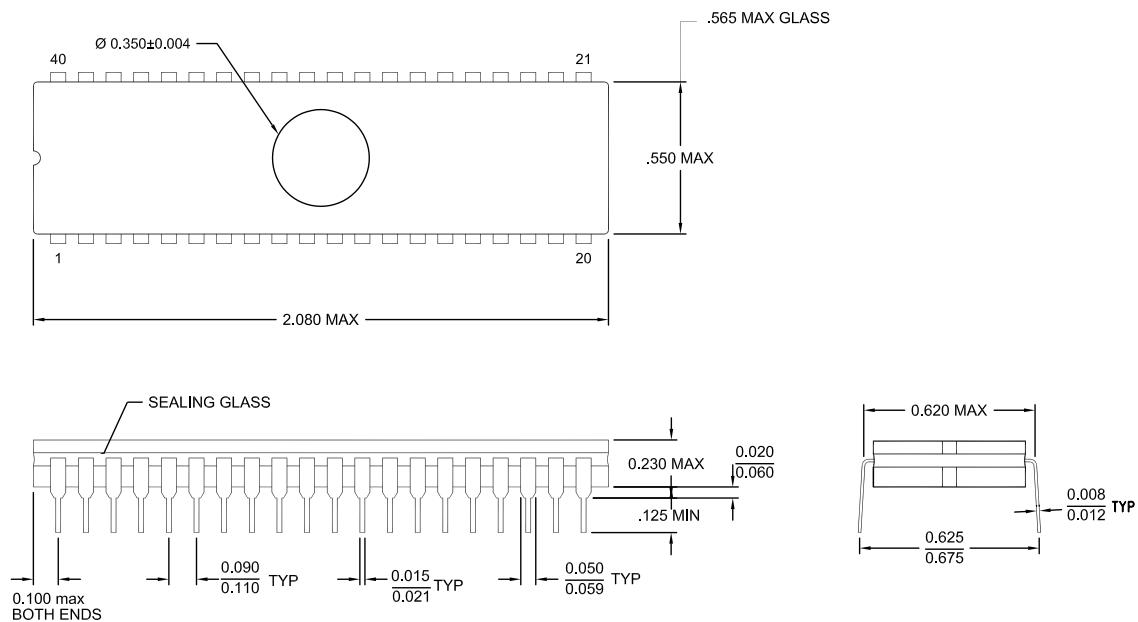


Figure 66. 40-Pin PDIP Package Diagram





16KB Standard Temperature: 0° to +70°C

Part Number	Description	Part Number	Description
ZGP323HSH4816C	48-pin SSOP 16K OTP	ZGP323HSS2816C	28-pin SOIC 16K OTP
ZGP323HSP4016C	40-pin PDIP 16K OTP	ZGP323HSH2016C	20-pin SSOP 16K OTP
ZGP323HSH2816C	28-pin SSOP 16K OTP	ZGP323HSP2016C	20-pin PDIP 16K OTP
ZGP323HSP2816C	28-pin PDIP 16K OTP	ZGP323HSS2016C	20-pin SOIC 16K OTP

16KB Extended Temperature: -40° to +105°C

Part Number	Description	Part Number	Description
ZGP323HEH4816C	48-pin SSOP 16K OTP	ZGP323HES2816C	28-pin SOIC 16K OTP
ZGP323HEP4016C	40-pin PDIP 16K OTP	ZGP323HEH2016C	20-pin SSOP 16K OTP
ZGP323HEH2816C	28-pin SSOP 16K OTP	ZGP323HEP2016C	20-pin PDIP 16K OTP
ZGP323HEP2816C	28-pin PDIP 16K OTP	ZGP323HES2016C	20-pin SOIC 16K OTP

16KB Automotive Temperature: -40° to +125°C

Part Number	Description	Part Number	Description
ZGP323HAH4816C	48-pin SSOP 16K OTP	ZGP323HAS2816C	28-pin SOIC 16K OTP
ZGP323HAP4016C	40-pin PDIP 16K OTP	ZGP323HAH2016C	20-pin SSOP 16K OTP
ZGP323HAH2816C	28-pin SSOP 16K OTP	ZGP323HAP2016C	20-pin PDIP 16K OTP
ZGP323HAP2816C	28-pin PDIP 16K OTP	ZGP323HAS2016C	20-pin SOIC 16K OTP

Replace C with G for Lead-Free Packaging