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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	Z8
Core Size	8-Bit
Speed	8MHz
Connectivity	-
Peripherals	HLVD, POR, WDT
Number of I/O	32
Program Memory Size	16KB (16K x 8)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	237 x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	48-BSSOP (0.295", 7.50mm Width)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/zgp323heh4816g

List of Tables

Development Features

Table 2 lists the features of ZiLOG®'s ZGP323H members.

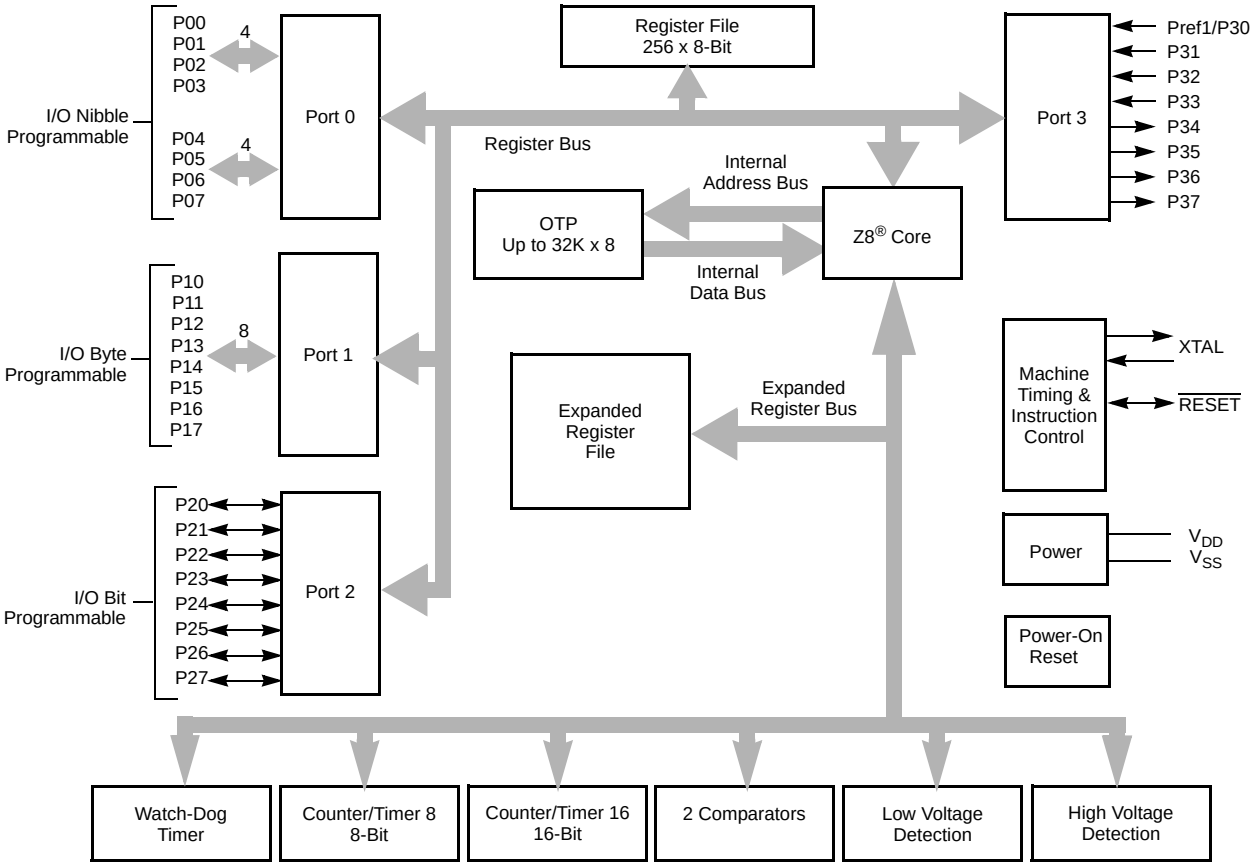
Table 2. Features

Device	OTP (KB)	RAM (Bytes)	I/O Lines	Voltage Range
ZGP323H OTP MCU Family	4, 8, 16, 32	237	32, 24 or 16	2.0V–5.5V

- Low power consumption–18mW (typical)
- T = Temperature
  S = Standard 0° to +70°C
  E = Extended -40° to +105°C
  A = Automotive -40° to +125°C
- Three standby modes:
  - STOP— (typical 1.8µA)
  - HALT— (typical 0.8mA)
  - Low voltage reset
- Special architecture to automate both generation and reception of complex pulses or signals:
  - One programmable 8-bit counter/timer with two capture registers and two load registers
  - One programmable 16-bit counter/timer with one 16-bit capture register pair and one 16-bit load register pair
  - Programmable input glitch filter for pulse reception
- Six priority interrupts
  - Three external
  - Two assigned to counter/timers
  - One low-voltage detection interrupt
- Low voltage detection and high voltage detection flags
- Programmable Watch-Dog Timer/Power-On Reset (WDT/POR) circuits
- Two independent comparators with programmable interrupt polarity
- Programmable EPROM options
  - Port 0: 0–3 pull-up transistors
  - Port 0: 4–7 pull-up transistors

Table 3. Power Connections

Connection	Circuit	Device
Power	V_{CC}	V_{DD}
Ground	GND	V_{SS}



Note: Refer to the specific package for available pins.

Figure 1. Functional Block Diagram

Table 9. GP323HS DC Characteristics (Continued)

			T_A=0°C to +70°C					
Symbol	**Parameter**	**V_{CC}**	**Min**	**Typ(7)**	**Max**	**Units**	**Conditions**	**Notes**
I_{OL}	Output Leakage	2.0-5.5	–1		1	µA	V_{IN} = 0V, V_{CC}	
I_{CC}	Supply Current	2.0V		1	3	mA	at 8.0 MHz	1, 2
		3.6V		5	10	mA	at 8.0 MHz	1, 2
		5.5V		10	15	mA	at 8.0 MHz	1, 2
I_{CC1}	Standby Current (HALT Mode)	2.0V		0.5	1.6	mA	V_{IN} = 0V, Clock at 8.0MHz	1, 2, 6
		3.6V		0.8	2.0	mA	V_{IN} = 0V, Clock at 8.0MHz	1, 2, 6
		5.5V		1.3	3.2	mA	V_{IN} = 0V, Clock at 8.0MHz	1, 2, 6
I_{CC2}	Standby Current (Stop Mode)	2.0V		1.6	8	µA	V_{IN} = 0 V, V_{CC} WDT not Running	3
		3.6V		1.8	10	µA	V_{IN} = 0 V, V_{CC} WDT not Running	3
		5.5V		1.9	12	µA	V_{IN} = 0 V, V_{CC} WDT not Running	3
		2.0V		5	20	µA	V_{IN} = 0 V, V_{CC} WDT is Running	3
		3.6V		8	30	µA	V_{IN} = 0 V, V_{CC} WDT is Running	3
		5.5V		15	45	µA	V_{IN} = 0 V, V_{CC} WDT is Running	3
I_{LV}	Standby Current (Low Voltage)			1.2	6	µA	Measured at 1.3V	4
V_{BO}	V_{CC} Low Voltage Protection			1.9	2.0	V	8MHz maximum Ext. CLK Freq.	
V_{LVD}	V_{CC} Low Voltage Detection			2.4		V		
V_{HVD}	Vcc High Voltage Detection			2.7		V		

Notes:
1. All outputs unloaded, inputs at rail.
2. CL1 = CL2 = 100 pF.
3. Oscillator stopped.
4. Oscillator stops when V_{CC} falls below V_{BO} limit.
5. It is strongly recommended to add a filter capacitor (minimum 0.1 µF), physically close to VCC and V_{SS} pins if operating voltage fluctuations are anticipated, such as those resulting from driving an Infrared LED.
6. Comparator and Timers are on. Interrupt disabled.
7. Typical values shown are at 25 degrees C.

Table 10. GP323HE DC Characteristics

			T_A= -40°C to +105°C					
Symbol	**Parameter**	**V_{CC}**	**Min**	**Typ(7)**	**Max**	**Units**	**Conditions**	**Notes**
V_{CC}	Supply Voltage		2.0		5.5	V	See Note 5	5
V_{CH}	Clock Input High Voltage	2.0-5.5	0.8 V_{CC}		V_{CC}+0.3	V	Driven by External Clock Generator	
V_{CL}	Clock Input Low Voltage	2.0-5.5	V_{SS}–0.3		0.4	V	Driven by External Clock Generator	
V_{IH}	Input High Voltage	2.0-5.5	0.7 V_{CC}		V_{CC}+0.3	V		
V_{IL}	Input Low Voltage	2.0-5.5	V_{SS}–0.3		0.2 V_{CC}	V		
V_{OH1}	Output High Voltage	2.0-5.5	V_{CC}–0.4			V	I_{OH} = –0.5mA	

Table 10. GP323HE DC Characteristics (Continued)

			T_A= -40°C to +105°C					
Symbol	**Parameter**	**V_{CC}**	**Min**	**Typ(7)**	**Max**	**Units**	**Conditions**	**Notes**
V_{OH2}	Output High Voltage (P36, P37, P00, P01)	2.0-5.5	V_{CC}–0.8			V	I_{OH} = –7mA	
V_{OL1}	Output Low Voltage	2.0-5.5			0.4	V	I_{OL} = 4.0mA	
V_{OL2}	Output Low Voltage (P00, P01, P36, P37)	2.0-5.5			0.8	V	I_{OL} = 10mA	
V_{OFFSET}	Comparator Input Offset Voltage	2.0-5.5			25	mV		
V_{REF}	Comparator Reference Voltage	2.0-5.5	0		V_{DD} -1.75	V		
I_{IL}	Input Leakage	2.0-5.5	–1		1	µA	V_{IN} = 0V, V_{CC} Pull-ups disabled	
R_{PU}	Pull-up Resistance	2.0V	200.0		700.0	KΩ	V_{IN} = 0V; Pullups selected by mask option	
		3.6V	50.0		300.0	KΩ		
		5.0V	25.0		175.0	KΩ		
I_{OL}	Output Leakage	2.0-5.5	–1		1	µA	V_{IN} = 0V, V_{CC}	
I_{CC}	Supply Current	2.0V		1	3	mA	at 8.0 MHz	1, 2
		3.6V		5	10	mA	at 8.0 MHz	1, 2
		5.5V		10	15	mA	at 8.0 MHz	1, 2
I_{CC1}	Standby Current (HALT Mode)	2.0V		0.5	1.6	mA	V_{IN} = 0V, Clock at 8.0MHz	1, 2, 6
		3.6V		0.8	2.0	mA	V_{IN} = 0V, Clock at 8.0MHz	1, 2, 6
		5.5V		1.3	3.2	mA	V_{IN} = 0V, Clock at 8.0MHz	1, 2, 6
I_{CC2}	Standby Current (Stop Mode)	2.0V		1.6	12	µA	V_{IN} = 0 V, V_{CC} WDT not Running	3
		3.6V		1.8	15	µA	V_{IN} = 0 V, V_{CC} WDT not Running	3
		5.5V		1.9	18	µA	V_{IN} = 0 V, V_{CC} WDT not Running	3
		2.0V		5	30	µA	V_{IN} = 0 V, V_{CC} WDT is Running	3
		3.6V		8	40	µA	V_{IN} = 0 V, V_{CC} WDT is Running	3
		5.5V		15	60	µA	V_{IN} = 0 V, V_{CC} WDT is Running	3
I_{LV}	Standby Current (Low Voltage)			1.2	6	µA	Measured at 1.3V	4
V_{BO}	V_{CC} Low Voltage Protection			1.9	2.15	V	8MHz maximum Ext. CLK Freq.	
V_{LVD}	V_{CC} Low Voltage Detection			2.4		V		
V_{HVD}	Vcc High Voltage Detection			2.7		V		

Notes:

1. All outputs unloaded, inputs at rail.
2. CL1 = CL2 = 100 pF.
3. Oscillator stopped.
4. Oscillator stops when V_{CC} falls below V_{BO} limit.
5. It is strongly recommended to add a filter capacitor (minimum 0.1 µF), physically close to VCC and V_{SS} pins if operating voltage fluctuations are anticipated, such as those resulting from driving an Infrared LED.
6. Comparator and Timers are on. Interrupt disabled.
7. Typical values shown are at 25 degrees C.

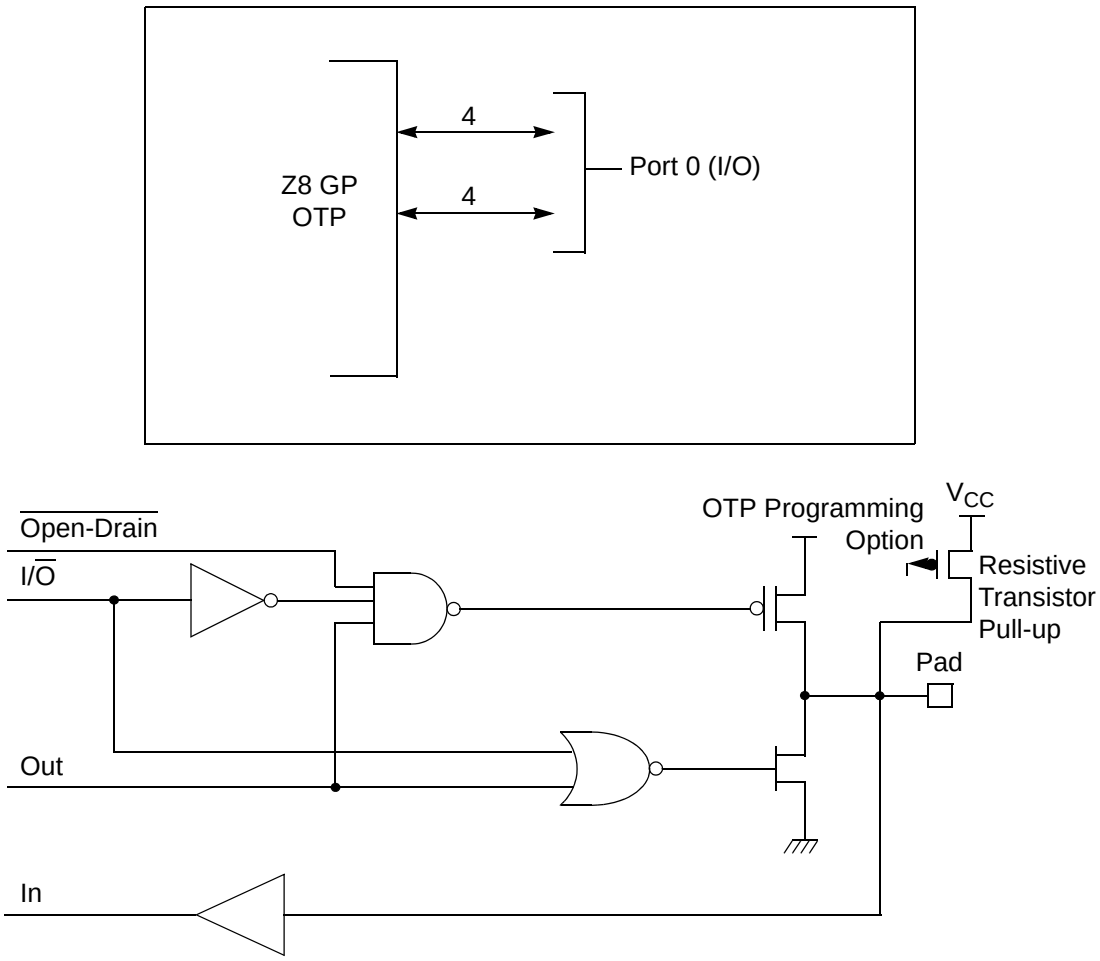


Figure 9. Port 0 Configuration

Port 1 (P17–P10)

Port 1 (see Figure 10) Port 1 can be configured for standard port input or output mode. After POR, Port 1 is configured as an input port. The output drivers are either push-pull or open-drain and are controlled by bit D1 in the PCON register.

Note: The Port 1 direction is reset to its default state following an SMR.

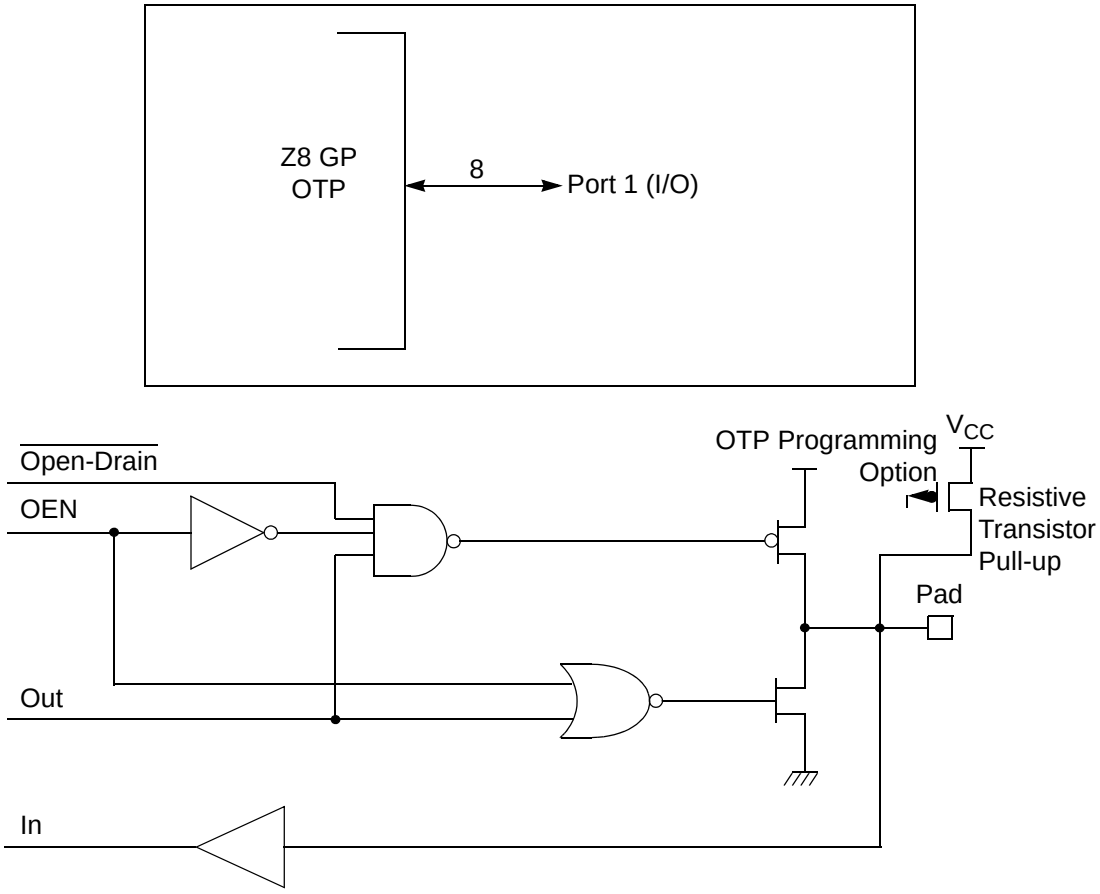


Figure 10. Port 1 Configuration

Port 2 (P27–P20)

Port 2 is an 8-bit, bidirectional, CMOS-compatible I/O port (see Figure 11). These eight I/O lines can be independently configured under software control as inputs or outputs. Port 2 is always available for I/O operation. A mask option is available to connect eight pull-up transistors on this port. Bits programmed as outputs are globally programmed as either push-pull or open-drain. The POR resets with the eight bits of Port 2 configured as inputs.

Port 2 also has an 8-bit input OR and AND gate, which can be used to wake up the part. P20 can be programmed to access the edge-detection circuitry in demodulation mode.

The counter/timers are mapped into ERF group D. Access is easily performed using the following:

```
LD                      RP, #0Dh                ; Select ERF D
for access to bank D
                                                ; (working
register group 0)
LD                      R0,#xx                  ; load CTR0
LD                      1, #xx                  ; load CTR1
LD                      R1, 2                   ; CTR2→CTR1

LD                      RP, #0Dh                ; Select ERF D
for access to bank D
                                                ; (working
register group 0)
LD                      RP, #7Dh                ; Select
expanded register bank D and working            ; register
group 7 of bank 0 for access.
LD                      71h, 2
; CTRL2→register 71h
LD                      R1, 2
; CTRL2→register 71h
```

Register File

The register file (bank 0) consists of 4 I/O port registers, 237 general-purpose registers, 16 control and status registers (R0–R3, R4–R239, and R240–R255, respectively), and two expanded registers groups in Banks D (see Table 15) and F. Instructions can access registers directly or indirectly through an 8-bit address field, thereby allowing a short, 4-bit register address to use the Register Pointer (Figure 17). In the 4-bit mode, the register file is divided into 16 working register groups, each occupying 16 continuous locations. The Register Pointer addresses the starting location of the active working register group.

Note: Working register group E0–EF can only be accessed through working registers and indirect addressing modes.

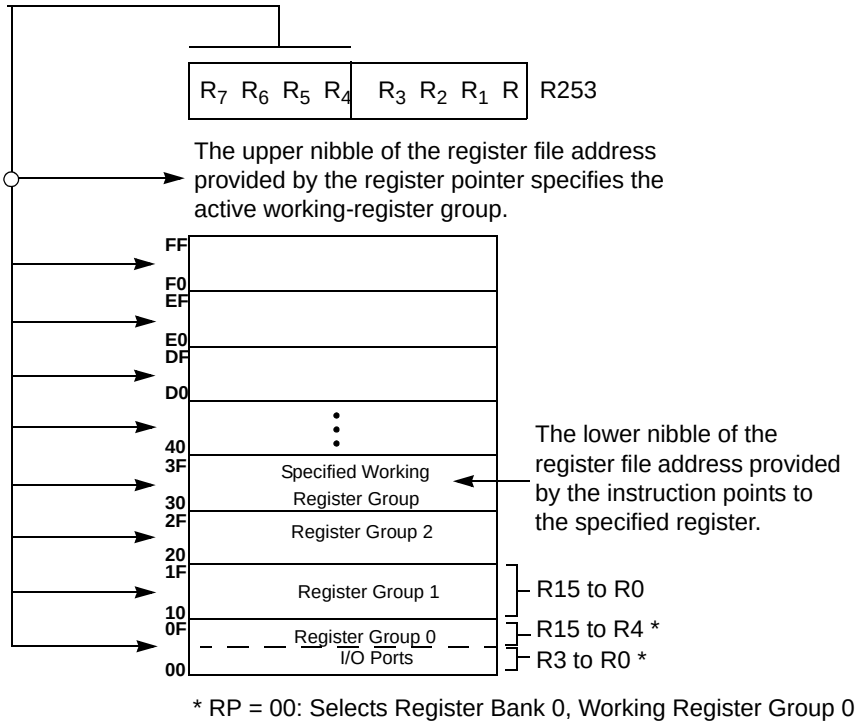


Figure 17. Register Pointer—Detail

Stack

The internal register file is used for the stack. An 8-bit Stack Pointer SPL (R255) is used for the internal stack that resides in the general-purpose registers (R4–R239). SPH (R254) can be used as a general-purpose register.

Table 15. CTR0(D)00H Counter/Timer8 Control Register (Continued)

Field	Bit Position		Value	Description
Counter_INT_Mask	------1-	R/W	0** 1	Disable Time-Out Interrupt Enable Time-Out Interrupt
P34_Out	-------0	R/W	0* 1	P34 as Port Output T8 Output on P34

Note:
***Indicates the value upon Power-On Reset.
****Indicates the value upon Power-On Reset. Not reset with a Stop Mode recovery.

T8 Enable

This field enables T8 when set (written) to 1.

Single/Modulo-N

When set to 0 (Modulo-N), the counter reloads the initial value when the terminal count is reached. When set to 1 (single-pass), the counter stops when the terminal count is reached.

Timeout

This bit is set when T8 times out (terminal count reached). To reset this bit, write a 1 to its location.

Caution: Writing a 1 is the only way to reset the Terminal Count status condition. Reset this bit before using/enabling the counter/timers.

The first clock of T8 might not have complete clock width and can occur any time when enabled.

Note: Take care when using the OR or AND commands to manipulate CTR0, bit 5 and CTR1, bits 0 and 1 (Demodulation Mode). These instructions use a Read-Modify-Write sequence in which the current status from the CTR0 and CTR1 registers is ORed or ANDed with the designated value and then written back into the registers.

T8 Clock

This bit defines the frequency of the input signal to T8.

When T8 is enabled, the output T8_OUT switches to the initial value (CTR1, D1). If the initial value (CTR1, D1) is 0, TC8L is loaded; otherwise, TC8H is loaded into the counter. In SINGLE-PASS Mode (CTR0, D6), T8 counts down to 0 and stops, T8_OUT toggles, the timeout status bit (CTR0, D5) is set, and a timeout interrupt can be generated if it is enabled (CTR0, D1). In Modulo-N Mode, upon reaching terminal count, T8_OUT is toggled, but no interrupt is generated. From that point, T8 loads a new count (if the T8_OUT level now is 0), TC8L is loaded; if it is 1, TC8H is loaded. T8 counts down to 0, toggles T8_OUT, and sets the timeout status bit (CTR0, D5), thereby generating an interrupt if enabled (CTR0, D1). One cycle is thus completed. T8 then loads from TC8H or TC8L according to the T8_OUT level and repeats the cycle. See Figure 20.

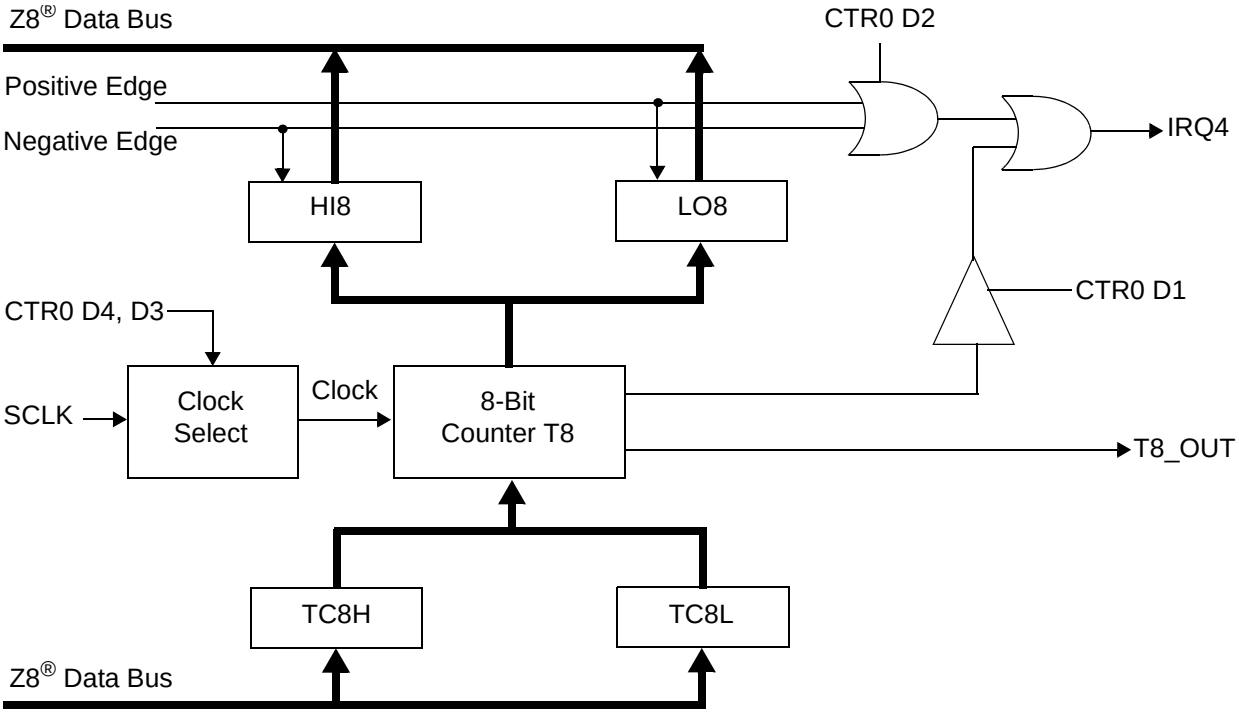


Figure 20. 8-Bit Counter/Timer Circuits

You can modify the values in TC8H or TC8L at any time. The new values take effect when they are loaded.

Caution: To ensure known operation do not write these registers at the time the values are to be loaded into the counter/timer. *An initial count of 1 is not allowed (a non-function occurs).* An initial count of 0 causes TC8 to count from 0 to FFH to FEH.

Note: The letter h denotes hexadecimal values.

Transition from 0 to FFh is not a timeout condition.

Caution: Using the same instructions for stopping the counter/timers and setting the status bits is not recommended.

Two successive commands are necessary. First, the counter/timers must be stopped. Second, the status bits must be reset. These commands are required because it takes one counter/timer clock interval for the initiated event to actually occur. See Figure 21 and Figure 22.

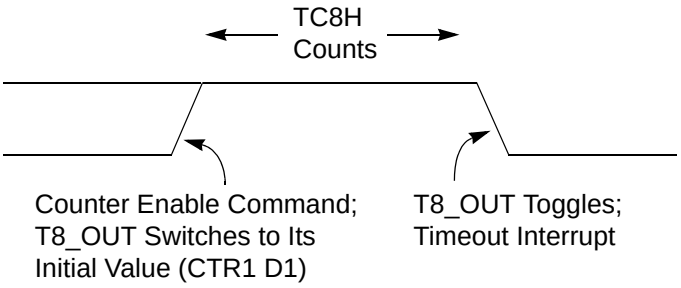


Figure 21. T8_OUT in Single-Pass Mode

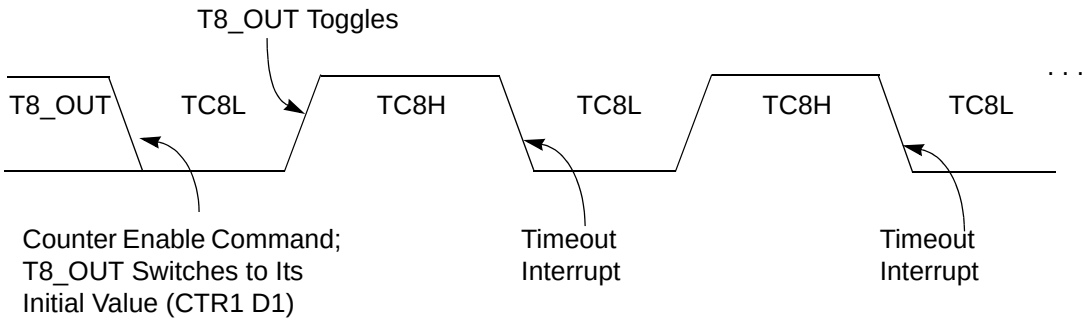


Figure 22. T8_OUT in Modulo-N Mode

T8 Demodulation Mode

The user must program TC8L and TC8H to FFH. After T8 is enabled, when the first edge (rising, falling, or both depending on CTR1, D5; D4) is detected, it starts to count down. When a subsequent edge (rising, falling, or both depending on CTR1, D5; D4) is detected during counting, the current value of T8 is complemented and put into one of the capture registers. If it is a positive edge, data is put

Caution: Do not load these registers at the time the values are to be loaded into the counter/timer to ensure known operation. An initial count of 1 is not allowed. An initial count of 0 causes T16 to count from 0 to FFFFH to FFFEH. Transition from 0 to FFFFH is not a timeout condition.

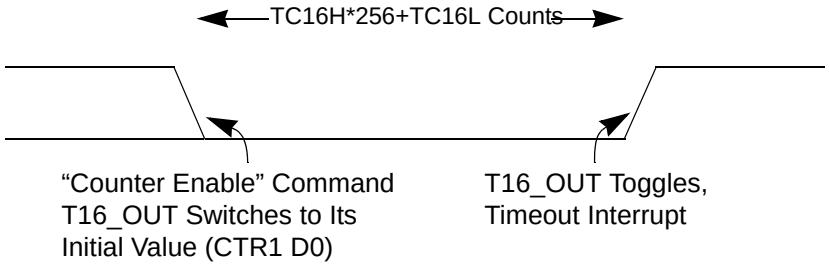


Figure 26. T16_OUT in Single-Pass Mode

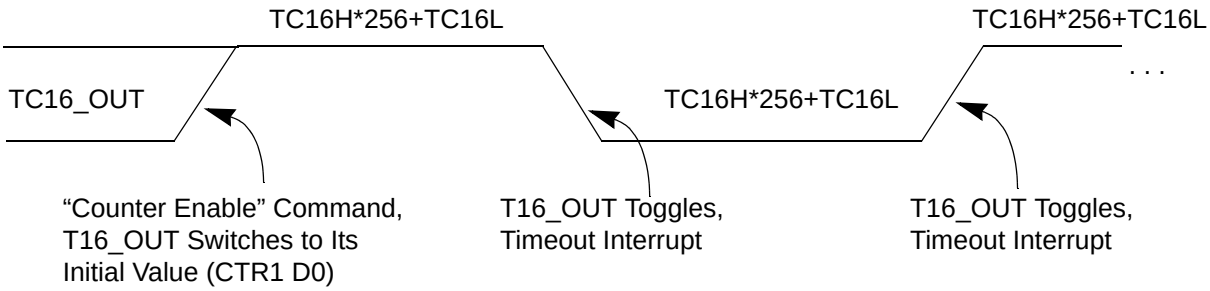


Figure 27. T16_OUT in Modulo-N Mode

T16 DEMODULATION Mode

The user must program TC16L and TC16H to FFH. After T16 is enabled, and the first edge (rising, falling, or both depending on CTR1 D5; D4) is detected, T16 captures HI16 and LO16, reloads, and begins counting.

If D6 of CTR2 Is 0

When a subsequent edge (rising, falling, or both depending on CTR1, D5; D4) is detected during counting, the current count in T16 is complemented and put into HI16 and LO16. When data is captured, one of the edge detect status bits (CTR1, D1; D0) is set, and an interrupt is generated if enabled (CTR2, D2). T16 is loaded with FFFFH and starts again.

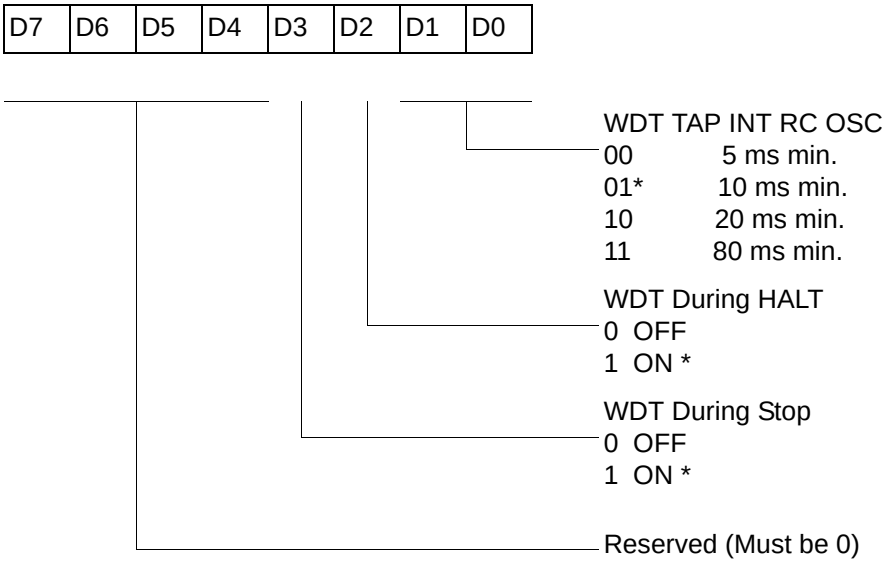
This T16 mode is generally used to measure space time, the length of time between bursts of carrier signal (marks).

Watch-Dog Timer Mode Register (WDTMR)

The Watch-Dog Timer (WDT) is a retriggerable one-shot timer that resets the Z8® CPU if it reaches its terminal count. The WDT must initially be enabled by executing the WDT instruction. On subsequent executions of the WDT instruction, the WDT is refreshed. The WDT circuit is driven by an on-board RC-oscillator. The WDT instruction affects the Zero (Z), Sign (S), and Overflow (V) flags.

The POR clock source the internal RC-oscillator. Bits 0 and 1 of the WDT register control a tap circuit that determines the minimum timeout period. Bit 2 determines whether the WDT is active during HALT, and Bit 3 determines WDT activity during Stop. Bits 4 through 7 are reserved (Figure 37). This register is accessible only during the first 60 processor cycles (120 XTAL clocks) from the execution of the first instruction after Power-On-Reset, Watch-Dog Reset, or a Stop-Mode Recovery (Figure 36). After this point, the register cannot be modified by any means (intentional or otherwise). The WDTMR cannot be read. The register is located in Bank F of the Expanded Register Group at address location `0Fh`. It is organized as shown in Figure 37.

WDTMR(0F)0Fh



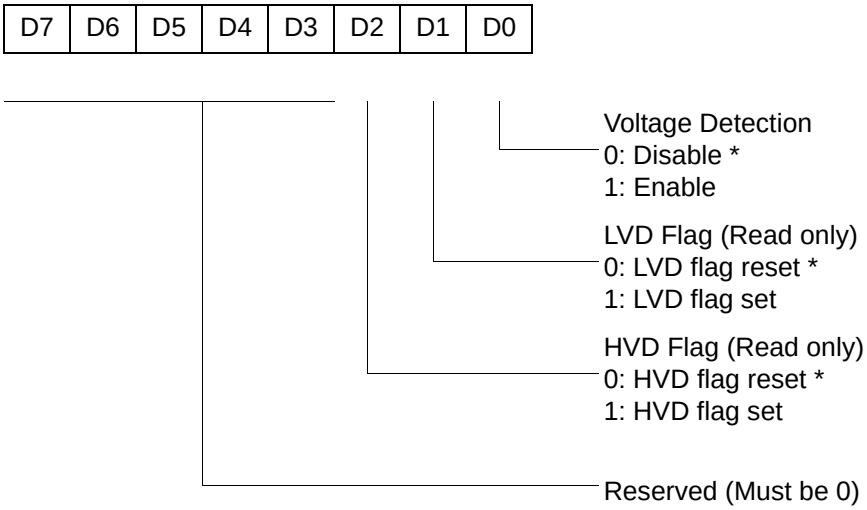
* Default setting after reset

Figure 37. Watch-Dog Timer Mode Register (Write Only)

WDT Time Select (D0, D1)

This bit selects the WDT time period. It is configured as indicated in Table 23.

LVD(0D)0CH



* Default setting after reset.

Figure 43. Voltage Detection Register

Note: Do not modify register P01M while checking a low-voltage condition. Switching noise of both ports 0 and 1 together might trigger the LVD flag.

Expanded Register File Control Registers (0F)

The expanded register file control registers (0F) are depicted in Figures 44 through Figure 57.

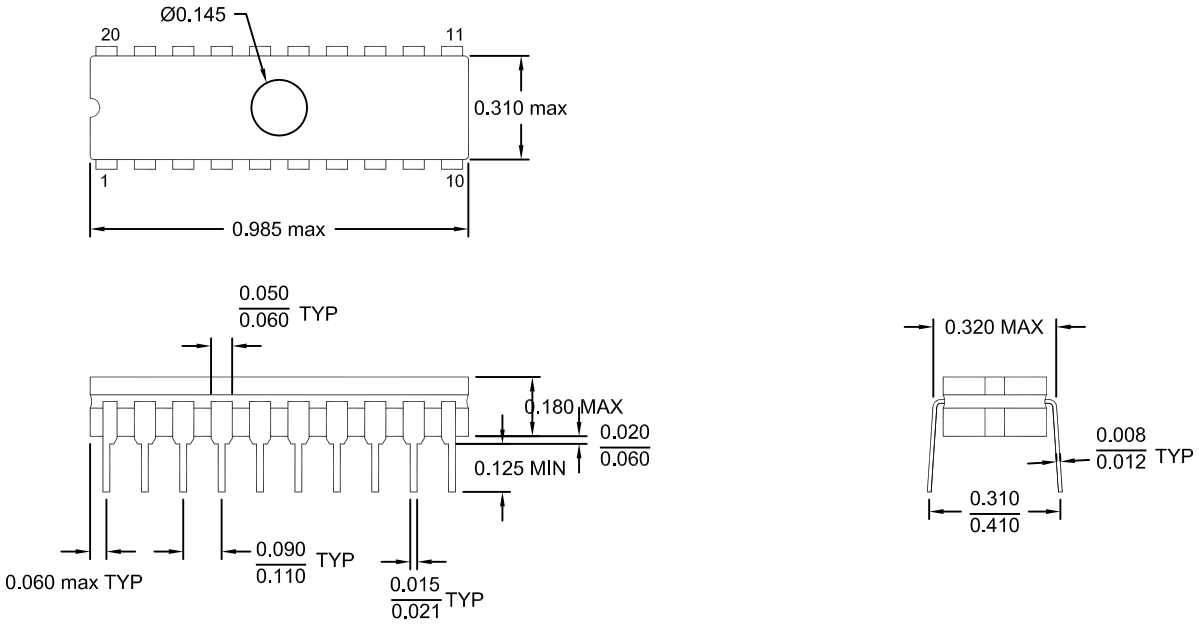
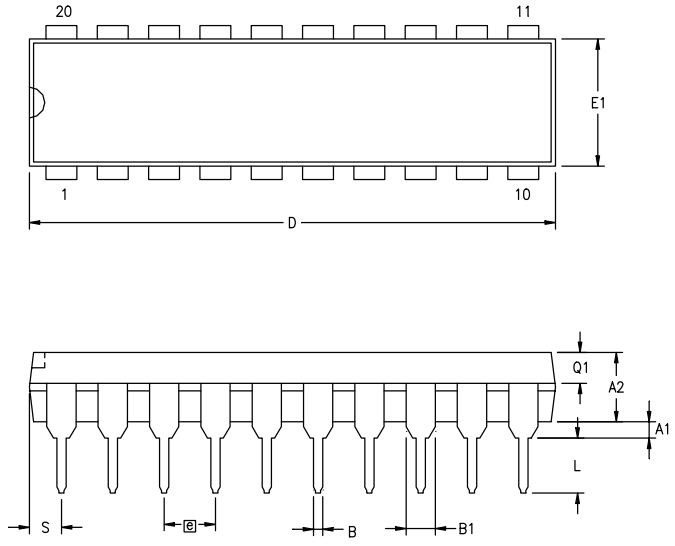


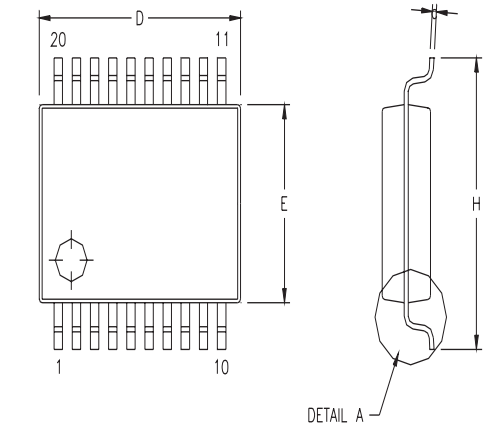
Figure 58. 20-Pin CDIP Package



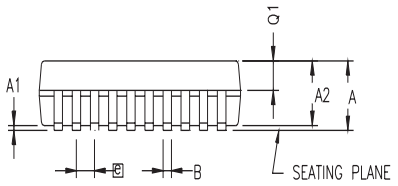
SYMBOL	MILLIMETER		INCH	
	MIN	MAX	MIN	MAX
A1	0.38	0.81	.015	.032
A2	3.25	3.68	.128	.145
B	0.41	0.51	.016	.020
B1	1.47	1.57	.058	.062
C	0.20	0.30	.008	.012
D	25.65	26.16	1.010	1.030
E	7.49	8.26	.295	.325
E1	6.10	6.65	.240	.262
e	2.54 BSC		.100 BSC	
eA	7.87	9.14	.310	.360
L	3.18	3.43	.125	.135
Q1	1.42	1.65	.056	.065
S	1.52	1.65	.060	.065

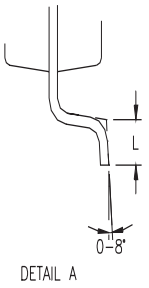
CONTROLLING DIMENSIONS : INCH

Figure 59. 20-Pin PDIP Package Diagram



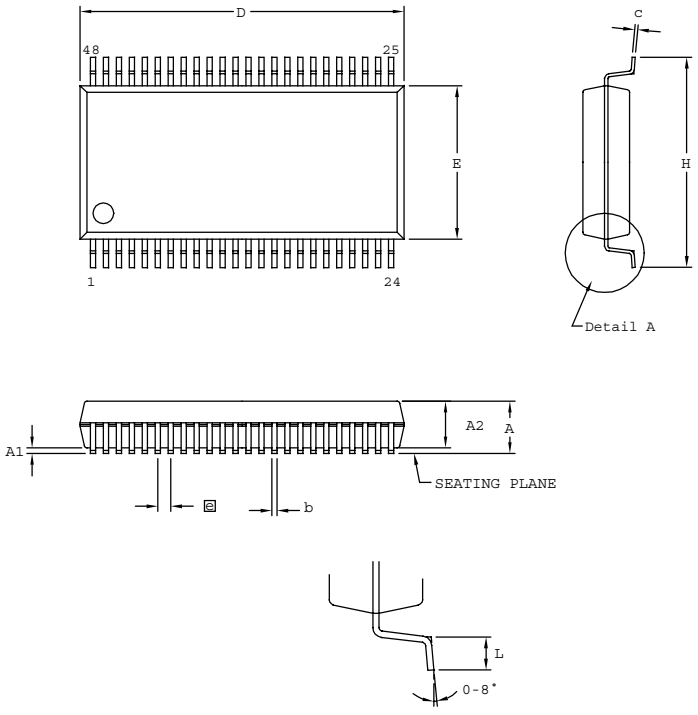
SYMBOL	MILLIMETER			INCH		
	MIN	NOM	MAX	MIN	NOM	MAX
A	1.73	1.85	1.98	0.068	0.073	0.078
A1	0.05	0.13	0.21	0.002	0.005	0.008
A2	1.68	1.73	1.83	0.066	0.068	0.072
B	0.25	0.30	0.38	0.010	0.012	0.015
C	0.13	0.15	0.22	0.005	0.006	0.009
D	7.07	7.20	7.33	0.278	0.283	0.289
E	5.20	5.30	5.38	0.205	0.209	0.212
e	0.65 BSC			0.0256 BSC		
H	7.65	7.80	7.90	0.301	0.307	0.311
L	0.56	0.75	0.94	0.022	0.030	0.037
Q1	0.74	0.78	0.82	0.029	0.031	0.032





CONTROLLING DIMENSIONS : MM
LEADS ARE COPLANAR WITHIN .004 INCH.

Figure 61. 20-Pin SSOP Package Diagram



SYMBOL	MILLIMETER		INCH	
	MIN	MAX	MIN	MAX
A	2.41	2.79	0.095	0.110
A1	0.23	0.38	0.009	0.015
A2	2.18	2.39	0.086	0.094
b	0.20	0.34	0.008	0.0135
c	0.13	0.25	0.005	0.010
D	15.75	16.00	0.620	0.630
E	7.39	7.59	0.291	0.299
e	0.635 BSC		0.025 BSC	
H	10.16	10.41	0.400	0.410
L	0.51	1.016	0.020	0.040

CONTROLLING DIMENSIONS : MM
LEADS ARE COPLANAR WITHIN .004 INCH

Figure 68. 48-Pin SSOP Package Design

Note: Check with ZiLOG on the actual bonding diagram and coordinate for chip-on-board assembly.