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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	Z8
Core Size	8-Bit
Speed	8MHz
Connectivity	-
Peripherals	HLVD, POR, WDT
Number of I/O	32
Program Memory Size	4KB (4K x 8)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	237 x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Through Hole
Package / Case	40-DIP (0.620", 15.75mm)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/zgp323hep4004c

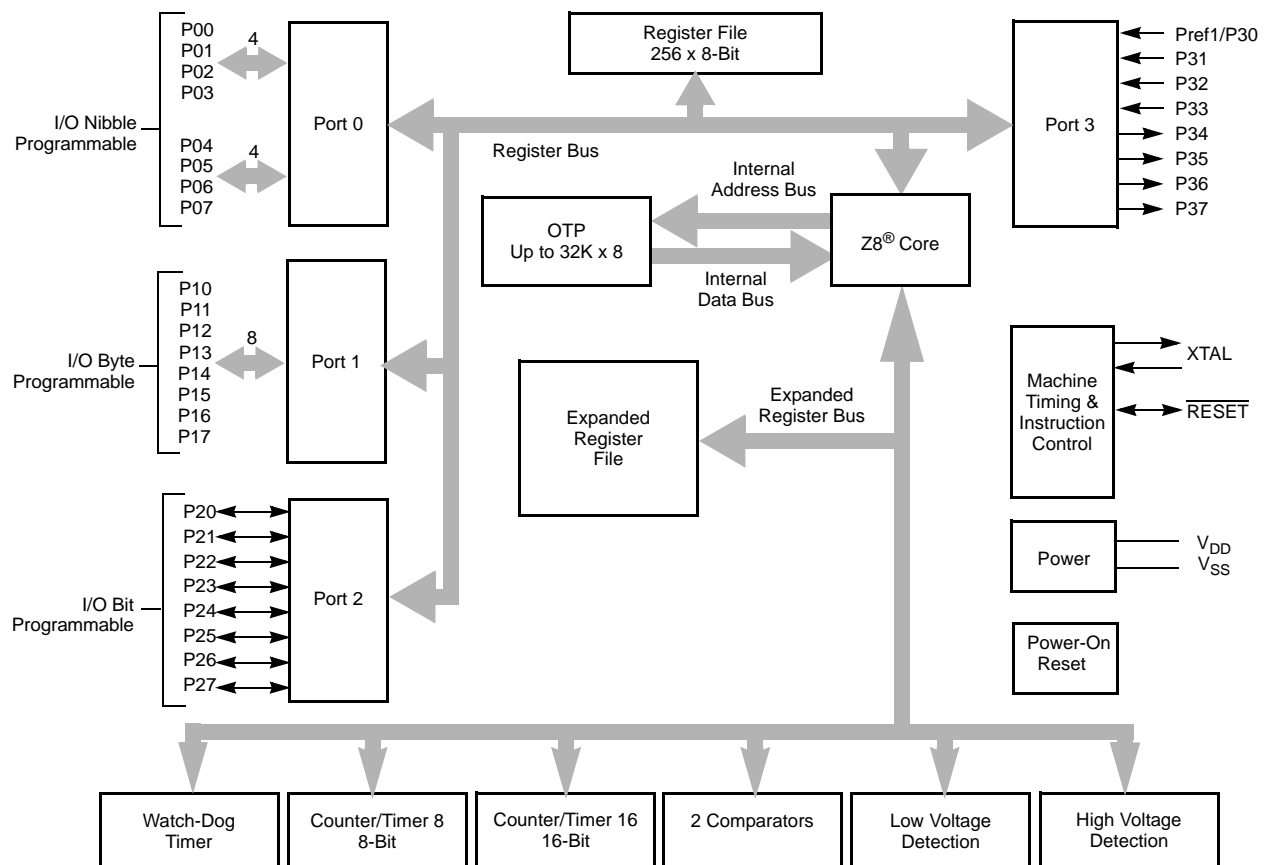


List of Figures

Figure 1. Functional Block Diagram	3
Figure 2. Counter/Timers Diagram	4
Figure 3. 20-Pin PDIP/SOIC/SSOP/CDIP* Pin Configuration	5
Figure 4. 28-Pin PDIP/SOIC/SSOP/CDIP* Pin Configuration	6
Figure 5. 40-Pin PDIP/CDIP* Pin Configuration	7
Figure 6. 48-Pin SSOP Pin Configuration	8
Figure 7. Test Load Diagram	10
Figure 8. AC Timing Diagram	16
Figure 9. Port 0 Configuration	19
Figure 10. Port 1 Configuration	20
Figure 11. Port 2 Configuration	21
Figure 12. Port 3 Configuration	22
Figure 13. Port 3 Counter/Timer Output Configuration	24
Figure 14. Program Memory Map (32K OTP)	26
Figure 15. Expanded Register File Architecture	28
Figure 16. Register Pointer	29
Figure 17. Register Pointer—Detail	31
Figure 18. Glitch Filter Circuitry	40
Figure 19. Transmit Mode Flowchart	41
Figure 20. 8-Bit Counter/Timer Circuits	42
Figure 21. T8_OUT in Single-Pass Mode	43
Figure 22. T8_OUT in Modulo-N Mode	43
Figure 23. Demodulation Mode Count Capture Flowchart	44
Figure 24. Demodulation Mode Flowchart	45
Figure 25. 16-Bit Counter/Timer Circuits	46
Figure 26. T16_OUT in Single-Pass Mode	47
Figure 27. T16_OUT in Modulo-N Mode	47
Figure 28. Ping-Pong Mode Diagram	49
Figure 29. Output Circuit	49
Figure 30. Interrupt Block Diagram	51
Figure 31. Oscillator Configuration	53
Figure 32. Port Configuration Register (PCON) (Write Only)	55
Figure 33. STOP Mode Recovery Register	57

Table 3. Power Connections

Connection	Circuit	Device
Power	V _{CC}	V _{DD}
Ground	GND	V _{SS}



Note: Refer to the specific package for available pins.

Figure 1. Functional Block Diagram

Table 11. GP323HA DC Characteristics

T_A = -40°C to +125°C								
Symbol	Parameter	V_{CC}	Min	Typ(7)	Max	Units	Conditions	Notes
V _{CC}	Supply Voltage		2.0		5.5	V	See Note 5	5
V _{CH}	Clock Input High Voltage	2.0-5.5	0.8 V _{CC}		V _{CC} +0.3	V	Driven by External Clock Generator	
V _{CL}	Clock Input Low Voltage	2.0-5.5	V _{SS} -0.3		0.4	V	Driven by External Clock Generator	
V _{IH}	Input High Voltage	2.0-5.5	0.7 V _{CC}		V _{CC} +0.3	V		
V _{IL}	Input Low Voltage	2.0-5.5	V _{SS} -0.3		0.2 V _{CC}	V		
V _{OH1}	Output High Voltage	2.0-5.5	V _{CC} -0.4			V	I _{OH} = -0.5mA	
V _{OH2}	Output High Voltage (P36, P37, P00, P01)	2.0-5.5	V _{CC} -0.8			V	I _{OH} = -7mA	
V _{OL1}	Output Low Voltage	2.0-5.5			0.4	V	I _{OL} = 4.0mA	
V _{OL2}	Output Low Voltage (P00, P01, P36, P37)	2.0-5.5			0.8	V	I _{OL} = 10mA	
V _{OFFSET}	Comparator Input Offset Voltage	2.0-5.5			25	mV		
V _{REF}	Comparator Reference Voltage	2.0-5.5	0		V _{DD} -1.75	V		
I _{IL}	Input Leakage	2.0-5.5	-1		1	μA	V _{IN} = 0V, V _{CC} Pull-ups disabled	
R _{PU}	Pull-up Resistance	2.0V	200		700	KΩ	V _{IN} = 0V; Pullups selected by mask option	
		3.6V	50		300	KΩ		
		5.0V	25		175	KΩ		
I _{OL}	Output Leakage	2.0-5.5	-1		1	μA	V _{IN} = 0V, V _{CC}	
I _{CC}	Supply Current	2.0V		1	3	mA	at 8.0 MHz	1, 2
		3.6V		5	10	mA	at 8.0 MHz	1, 2
		5.5V		10	15	mA	at 8.0 MHz	1, 2
I _{CC1}	Standby Current (HALT Mode)	2.0V		0.5	1.6	mA	V _{IN} = 0V, Clock at 8.0MHz	1, 2, 6
		3.6V		0.8	2.0	mA	V _{IN} = 0V, Clock at 8.0MHz	1, 2, 6
		5.5V		1.3	3.2	mA	V _{IN} = 0V, Clock at 8.0MHz	1, 2, 6
I _{CC2}	Standby Current (Stop Mode)	2.0V		1.6	15	μA	V _{IN} = 0 V, V _{CC} WDT not Running	3
		3.6V		1.8	20	μA	V _{IN} = 0 V, V _{CC} WDT not Running	3
		5.5V		1.9	25	μA	V _{IN} = 0 V, V _{CC} WDT not Running	3
		2.0V		5	30	μA	V _{IN} = 0 V, V _{CC} WDT is Running	3
		3.6V		8	40	μA	V _{IN} = 0 V, V _{CC} WDT is Running	3
		5.5V		15	60	μA	V _{IN} = 0 V, V _{CC} WDT is Running	3
I _{LV}	Standby Current (Low Voltage)			1.2	6	μA	Measured at 1.3V	4
V _{BO}	V _{CC} Low Voltage Protection			1.9	2.15	V	8MHz maximum Ext. CLK Freq.	
V _{LVD}	V _{CC} Low Voltage Detection			2.4		V		



AC Characteristics

Figure 8 and Table 13 describe the Alternating Current (AC) characteristics.

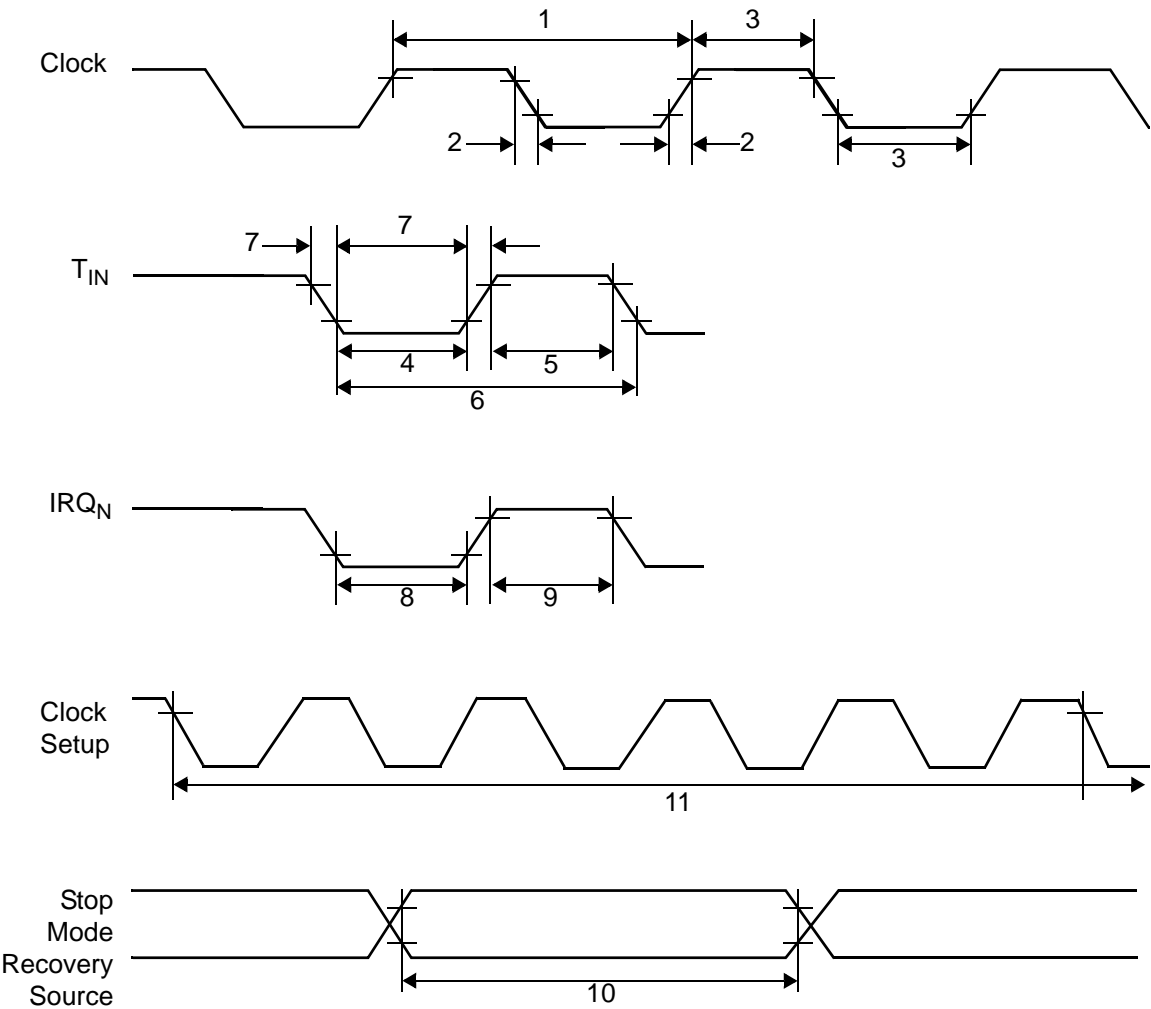


Figure 8. AC Timing Diagram



Table 13. AC Characteristics

				T _A =0°C to +70°C (S) –40°C to +105°C (E) –40°C to +125°C (A) 8.0MHz				Watch-Dog Timer Mode Register (D1, D0)
No	Symbol	Parameter	V _{CC}	Minimum	Maximum	Units	Notes	
1	TpC	Input Clock Period	2.0–5.5	121	DC	ns	1	
2	TrC,TfC	Clock Input Rise and Fall Times	2.0–5.5		25	ns	1	
3	TwC	Input Clock Width	2.0–5.5	37		ns	1	
4	TwTinL	Timer Input Low Width	2.0 5.5	100 70		ns	1	
5	TwTinH	Timer Input High Width	2.0–5.5	3TpC			1	
6	TpTin	Timer Input Period	2.0–5.5	8TpC			1	
7	TrTin,TfTin	Timer Input Rise and Fall Timers	2.0–5.5		100	ns	1	
8	TwIL	Interrupt Request Low Time	2.0 5.5	100 70		ns	1, 2	
9	TwIH	Interrupt Request Input High Time	2.0–5.5	5TpC			1, 2	
10	Twsm	Stop-Mode Recovery Width Spec	2.0–5.5	12 5TpC		ns	3 4	
11	Tost	Oscillator Start-Up Time	2.0–5.5		5TpC		4	
12	Twdt	Watch-Dog Timer Delay Time	2.0–5.5 2.0–5.5 2.0–5.5 2.0–5.5	5 10 20 80		ms ms ms ms	0, 0 0, 1 1, 0 1, 1	
13	T _{POR}	Power-On Reset	2.0–5.5	2.5	10	ms		

Notes:

1. Timing Reference uses 0.9 V_{CC} for a logic 1 and 0.1 V_{CC} for a logic 0.
2. Interrupt request through Port 3 (P33–P31).
3. SMR – D5 = 1.
4. SMR – D5 = 0.

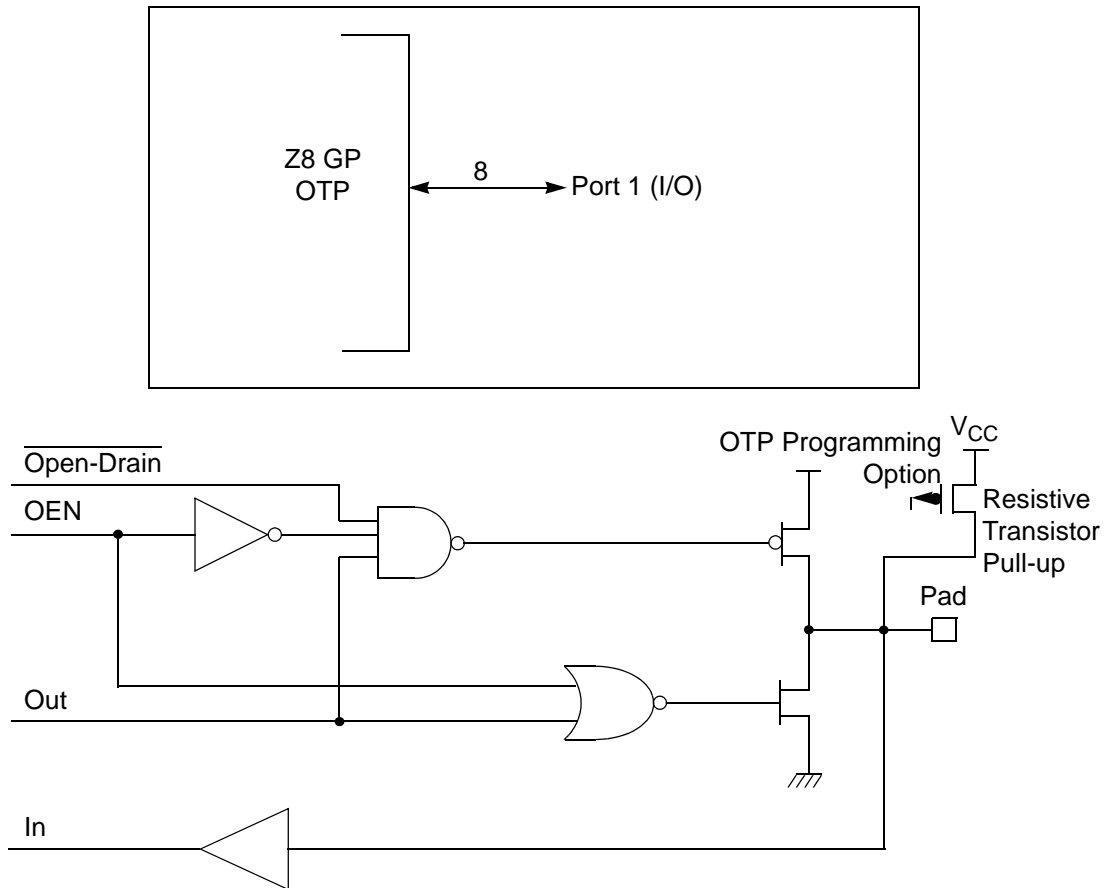


Figure 10. Port 1 Configuration

Port 2 (P27–P20)

Port 2 is an 8-bit, bidirectional, CMOS-compatible I/O port (see Figure 11). These eight I/O lines can be independently configured under software control as inputs or outputs. Port 2 is always available for I/O operation. A mask option is available to connect eight pull-up transistors on this port. Bits programmed as outputs are globally programmed as either push-pull or open-drain. The POR resets with the eight bits of Port 2 configured as inputs.

Port 2 also has an 8-bit input OR and AND gate, which can be used to wake up the part. P20 can be programmed to access the edge-detection circuitry in demodulation mode.



Comparator Inputs

In analog mode, P31 and P32 have a comparator front end. The comparator reference is supplied to P33 and Pref1. In this mode, the P33 internal data latch and its corresponding IRQ1 are diverted to the SMR sources (excluding P31, P32, and P33) as indicated in Figure 12 on page 22. In digital mode, P33 is used as D3 of the Port 3 input register, which then generates IRQ1.

- **Note:** Comparators are powered down by entering Stop Mode. For P31–P33 to be used in a Stop Mode Recovery source, these inputs must be placed into digital mode.

Comparator Outputs

These channels can be programmed to be output on P34 and P37 through the PCON register.

RESET (Input, Active Low)

Reset initializes the MCU and is accomplished either through Power-On, Watch-Dog Timer, Stop Mode Recovery, Low-Voltage detection, or external reset. During Power-On Reset and Watch-Dog Timer Reset, the internally generated reset drives the reset pin Low for the POR time. Any devices driving the external reset line must be open-drain to avoid damage from a possible conflict during reset conditions. Pull-up is provided internally.

When the Z8 GP asserts (Low) the RESET pin, the internal pull-up is disabled. The Z8 GP does not assert the RESET pin when under VBO.

- **Note:** The external Reset does not initiate an exit from STOP mode.

Functional Description

This device incorporates special functions to enhance the Z8[®] functionality in consumer and battery-operated applications.

Program Memory

This device addresses up to 32KB of OTP memory. The first 12 Bytes are reserved for interrupt vectors. These locations contain the six 16-bit vectors that correspond to the six available interrupts.

RAM

This device features 256B of RAM. See Figure 14.



Table 16. CTR1(0D)01H T8 and T16 Common Functions (Continued)

Field	Bit Position		Value	Description
Transmit_Submode/ Glitch_Filter	----32--	R/W		Transmit Mode
			00*	Normal Operation
			01	Ping-Pong Mode
			10	T16_Out = 0
			11	T16_Out = 1
				Demodulation Mode
			00*	No Filter
			01	4 SCLK Cycle
			10	8 SCLK Cycle
			11	Reserved
Initial_T8_Out/ Rising Edge	-----1-	R/W	0*	Transmit Mode
			1	T8_OUT is 0 Initially
		R	0*	T8_OUT is 1 Initially
			1	Demodulation Mode
		W	0	No Rising Edge
			1	Rising Edge Detected
			0	No Effect
			1	Reset Flag to 0
Initial_T16_Out/ Falling_Edge	-----0	R/W	0*	Transmit Mode
			1	T16_OUT is 0 Initially
		R	0*	T16_OUT is 1 Initially
			1	Demodulation Mode
		W	0	No Falling Edge
			1	Falling Edge Detected
			0	No Effect
			1	Reset Flag to 0

Note:

*Default at Power-On Reset

*Default at Power-On Reset. Not reset with Stop Mode recovery.

Mode

If the result is 0, the counter/timers are in TRANSMIT mode; otherwise, they are in DEMODULATION mode.

P36_Out/Demodulator_Input

In TRANSMIT Mode, this bit defines whether P36 is used as a normal output pin or the combined output of T8 and T16.

In DEMODULATION Mode, this bit defines whether the input signal to the Counter/Timers is from P20 or P31.

If the input signal is from Port 31, a capture event may also generate an IRQ2 interrupt. To prevent generating an IRQ2, either disable the IRQ2 interrupt by clearing its IMR bit D2 or use P20 as the input.

Table 18. CTR3 (D)03H: T8/T16 Control Register (Continued)

Field	Bit Position		Value	Description
Reserved	---43210	R	1	Always reads 11111
		W	x	No Effect

*Indicates the value upon Power-On Reset.

**Indicates the value upon Power-On Reset. Not reset with a Stop Mode recovery.

Counter/Timer Functional Blocks

Input Circuit

The edge detector monitors the input signal on P31 or P20. Based on CTR1 D5–D4, a pulse is generated at the Pos Edge or Neg Edge line when an edge is detected. Glitches in the input signal that have a width less than specified (CTR1 D3, D2) are filtered out (see Figure 18).

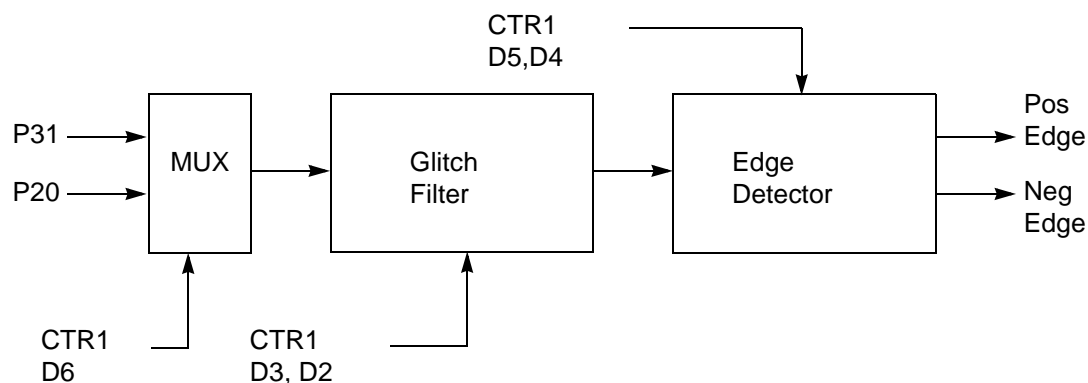


Figure 18. Glitch Filter Circuitry

T8 Transmit Mode

Before T8 is enabled, the output of T8 depends on CTR1, D1. If it is 0, T8_OUT is 1; if it is 1, T8_OUT is 0. See Figure 19.

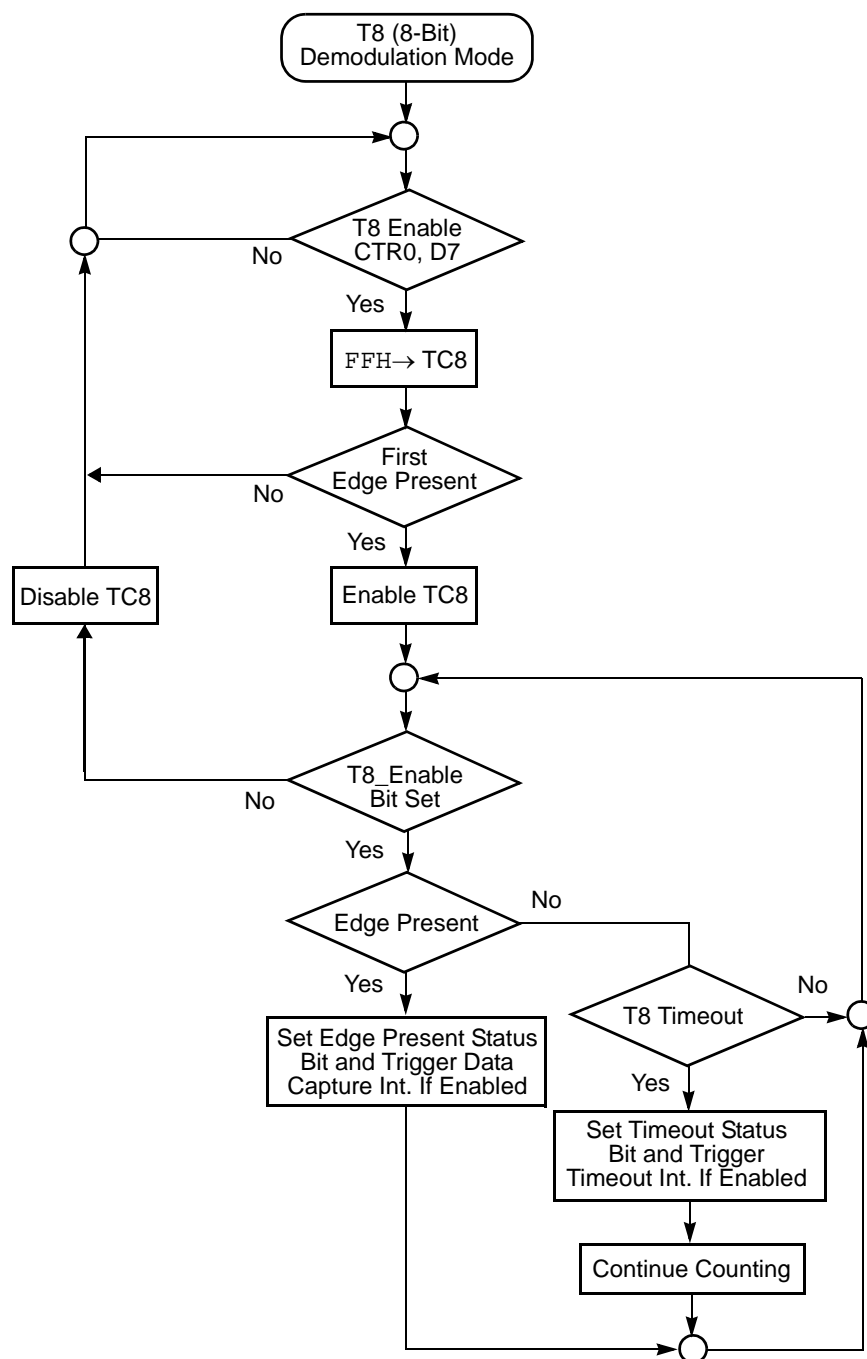


Figure 24. Demodulation Mode Flowchart



Caution:

Do not load these registers at the time the values are to be loaded into the counter/timer to ensure known operation. An initial count of 1 is not allowed. An initial count of 0 causes T16 to count from 0 to FFFFH to FFFE_H. Transition from 0 to FFFF_H is not a timeout condition.

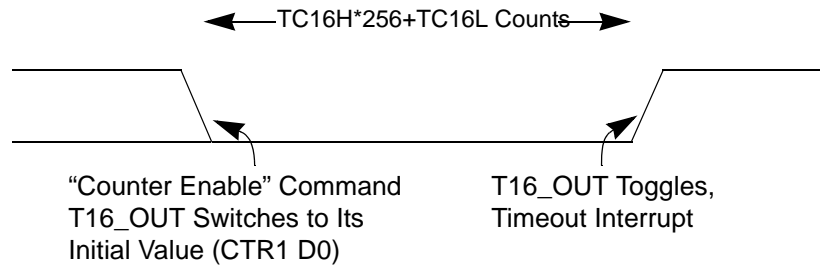


Figure 26. T16_OUT in Single-Pass Mode

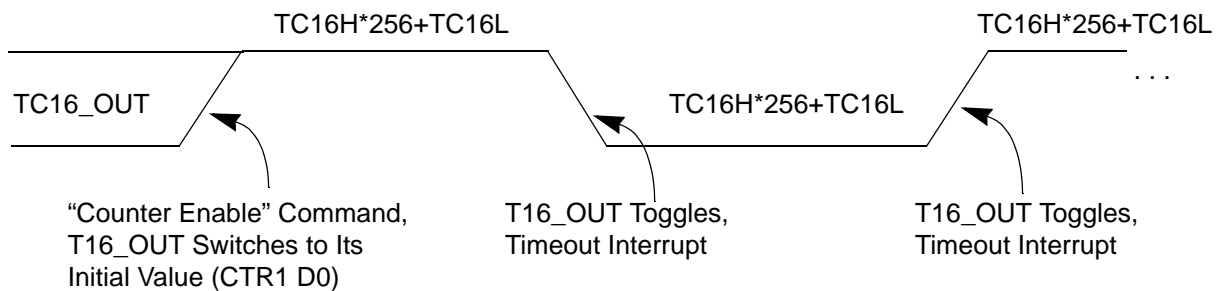


Figure 27. T16_OUT in Modulo-N Mode

T16 DEMODULATION Mode

The user must program TC16L and TC16H to FF_H. After T16 is enabled, and the first edge (rising, falling, or both depending on CTR1 D5; D4) is detected, T16 captures HI16 and LO16, reloads, and begins counting.

If D6 of CTR2 Is 0

When a subsequent edge (rising, falling, or both depending on CTR1, D5; D4) is detected during counting, the current count in T16 is complemented and put into HI16 and LO16. When data is captured, one of the edge detect status bits (CTR1, D1; D0) is set, and an interrupt is generated if enabled (CTR2, D2). T16 is loaded with FFFF_H and starts again.

This T16 mode is generally used to measure space time, the length of time between bursts of carrier signal (marks).

If D6 of CTR2 Is 1

T16 ignores the subsequent edges in the input signal and continues counting down. A timeout of T8 causes T16 to capture its current value and generate an interrupt if enabled (CTR2, D2). In this case, T16 does not reload and continues counting. If the D6 bit of CTR2 is toggled (by writing a 0 then a 1 to it), T16 captures and reloads on the next edge (rising, falling, or both depending on CTR1, D5; D4), continuing to ignore subsequent edges.

This T16 mode generally measures mark time, the length of an active carrier signal burst.

If T16 reaches 0, T16 continues counting from `FFFFh`. Meanwhile, a status bit (CTR2 D5) is set, and an interrupt timeout can be generated if enabled (CTR2 D1).

Ping-Pong Mode

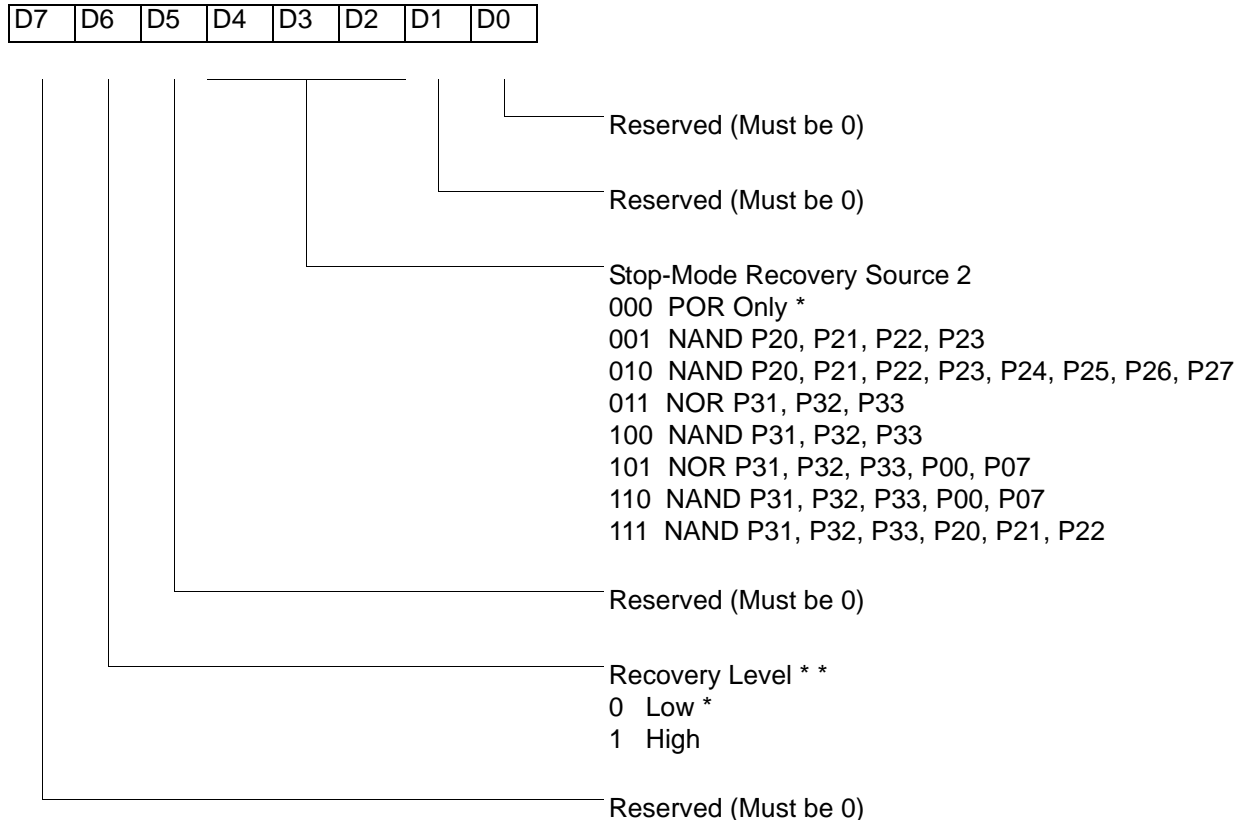
This operation mode is only valid in TRANSMIT Mode. T8 and T16 must be programmed in Single-Pass mode (CTR0, D6; CTR2, D6), and Ping-Pong mode must be programmed in CTR1, D3; D2. The user can begin the operation by enabling either T8 or T16 (CTR0, D7 or CTR2, D7). For example, if T8 is enabled, T8_OUT is set to this initial value (CTR1, D1). According to T8_OUT's level, TC8H or TC8L is loaded into T8. After the terminal count is reached, T8 is disabled, and T16 is enabled. T16_OUT then switches to its initial value (CTR1, D0), data from TC16H and TC16L is loaded, and T16 starts to count. After T16 reaches the terminal count, it stops, T8 is enabled again, repeating the entire cycle. Interrupts can be allowed when T8 or T16 reaches terminal control (CTR0, D1; CTR2, D1). To stop the ping-pong operation, write 00 to bits D3 and D2 of CTR1. See Figure 28.

- **Note:** Enabling ping-pong operation while the counter/timers are running might cause intermittent counter/timer function. Disable the counter/timers and reset the status flags before instituting this operation.

Stop Mode Recovery Register 2 (SMR2)

This register determines the mode of Stop Mode Recovery for SMR2 (Figure 36).

SMR2(0F)DH



Note: If used in conjunction with SMR, either of the two specified events causes a Stop-Mode Recovery.

* Default setting after reset

** At the XOR gate input

Figure 36. Stop Mode Recovery Register 2 ((0F)DH:D2–D4, D6 Write Only)

If SMR2 is used in conjunction with SMR, either of the specified events causes a Stop Mode Recovery.

► **Note:** Port pins configured as outputs are ignored as an SMR or SMR2 recovery source. For example, if the NAND or P23–P20 is selected as the recovery source and P20 is configured as an output, the remaining SMR pins (P23–P21) form the NAND equation.

WDTMR During STOP (D3)

This bit determines whether or not the WDT is active during STOP Mode. Because the XTAL clock is stopped during STOP Mode, the on-board RC has to be selected as the clock source to the WDT/POR counter. A 1 indicates active during Stop. The default is 1.

EPROM Selectable Options

There are seven EPROM Selectable Options to choose from based on ROM code requirements. These options are listed in Table 24.

Table 24. EPROM Selectable Options

Port 00–03 Pull-Ups	On/Off
Port 04–07 Pull-Ups	On/Off
Port 10–13 Pull-Ups	On/Off
Port 14–17 Pull-Ups	On/Off
Port 20–27 Pull-Ups	On/Off
EPROM Protection	On/Off
Watch-Dog Timer at Power-On Reset	On/Off

Voltage Brown-Out/Standby

An on-chip Voltage Comparator checks that the V_{DD} is at the required level for correct operation of the device. Reset is globally driven when V_{DD} falls below V_{BO} . A small drop in V_{DD} causes the XTAL1 and XTAL2 circuitry to stop the crystal or resonator clock. If the V_{DD} is allowed to stay above V_{RAM} , the RAM content is preserved. When the power level is returned to above V_{BO} , the device performs a POR and functions normally.

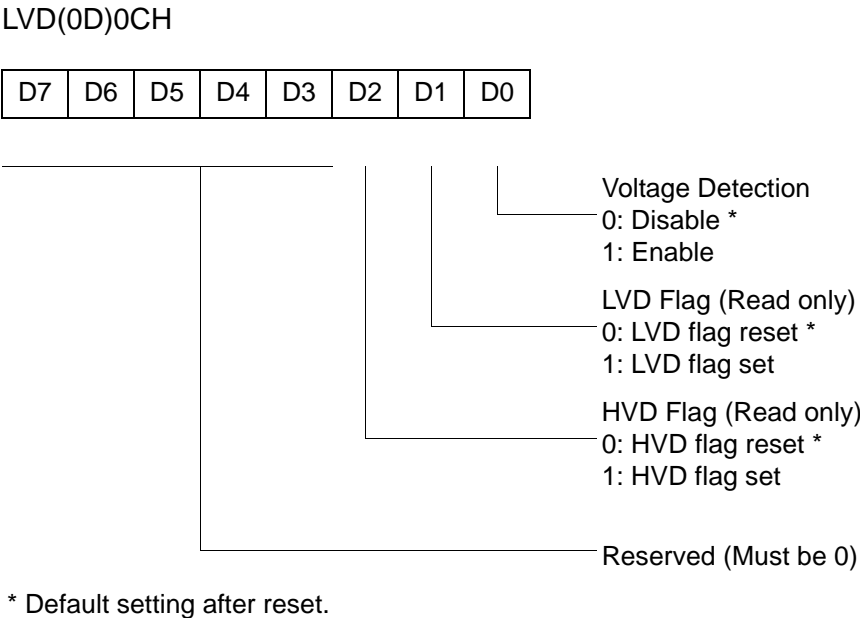


Figure 43. Voltage Detection Register

► **Note:** Do not modify register P01M while checking a low-voltage condition. Switching noise of both ports 0 and 1 together might trigger the LVD flag.

Expanded Register File Control Registers (0F)

The expanded register file control registers (0F) are depicted in Figures 44 through Figure 57.

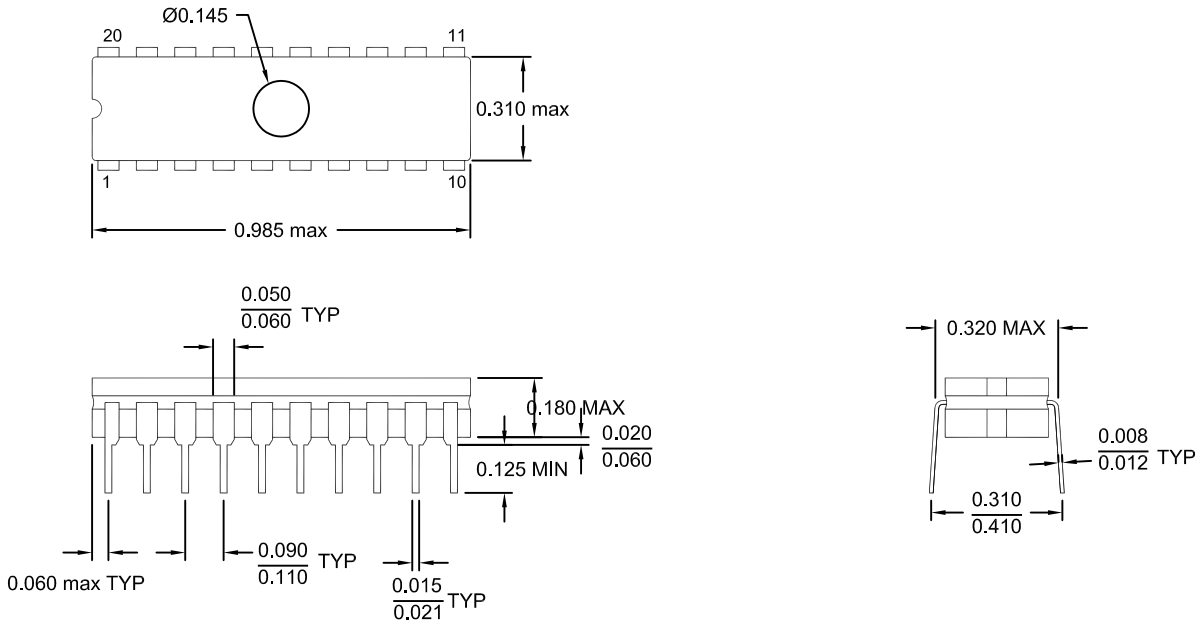


Figure 58. 20-Pin CDIP Package

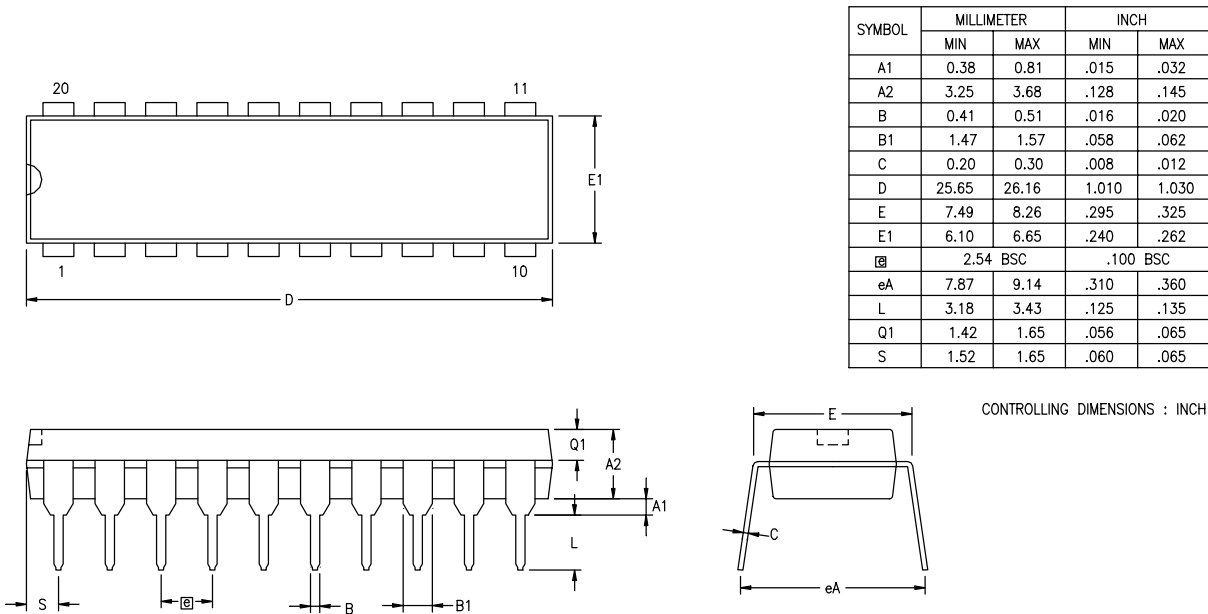


Figure 59. 20-Pin PDIP Package Diagram

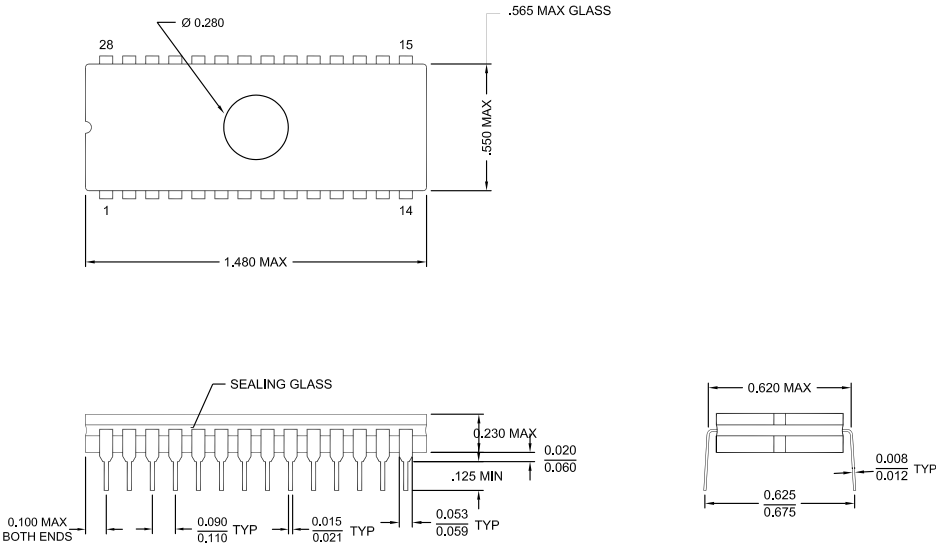


Figure 63. 28-Pin CDIP Package Diagram

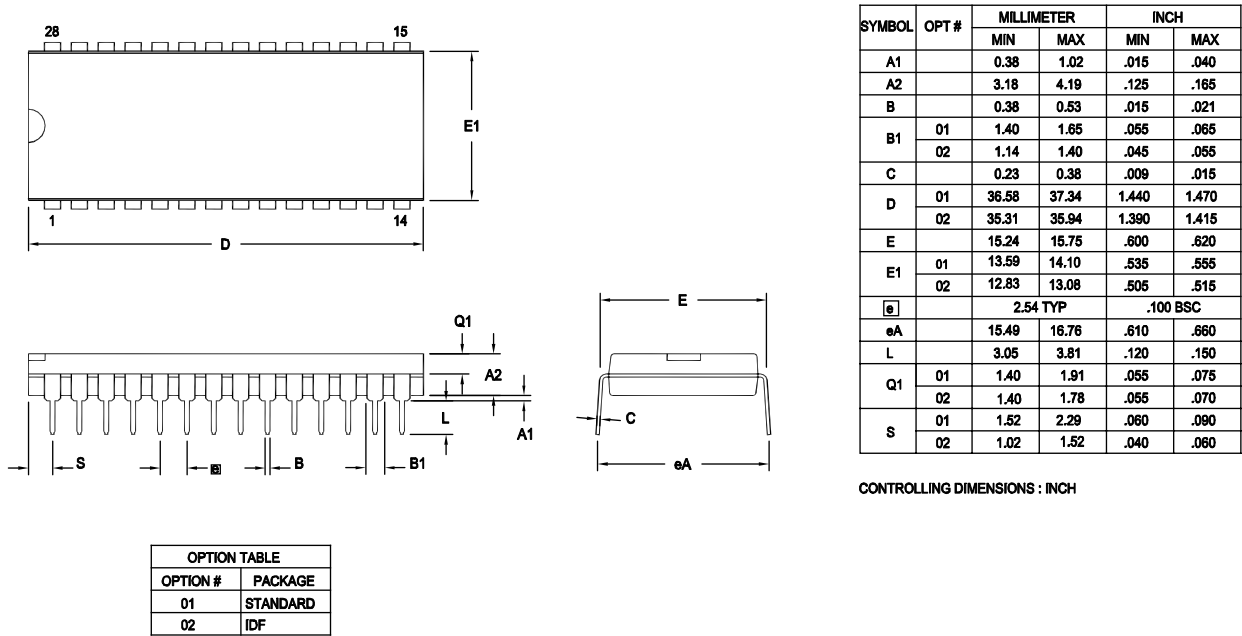


Figure 64. 28-Pin PDIP Package Diagram



Ordering Information

32KB Standard Temperature: 0° to +70°C

Part Number	Description	Part Number	Description
ZGP323HSH4832C	48-pin SSOP 32K OTP	ZGP323HSS2832C	28-pin SOIC 32K OTP
ZGP323HSP4032C	40-pin PDIP 32K OTP	ZGP323HSH2032C	20-pin SSOP 32K OTP
ZGP323HSK2832E	28-pin CDIP 32K OTP	ZGP323HSK2032E	20-pin CDIP 32K OTP
ZGP323HSK4032E	40-pin CDIP 32K OTP	ZGP323HSP2032C	20-pin PDIP 32K OTP
ZGP323HSH2832C	28-pin SSOP 32K OTP	ZGP323HSS2032C	20-pin SOIC 32K OTP
ZGP323HSP2832C	28-pin PDIP 32K OTP		

32KB Extended Temperature: -40° to +105°C

Part Number	Description	Part Number	Description
ZGP323HEH4832C	48-pin SSOP 32K OTP	ZGP323HES2832C	28-pin SOIC 32K OTP
ZGP323HEP4032C	40-pin PDIP 32K OTP	ZGP323HEH2032C	20-pin SSOP 32K OTP
ZGP323HEH2832C	28-pin SSOP 32K OTP	ZGP323HEP2032C	20-pin PDIP 32K OTP
ZGP323HEP2832C	28-pin PDIP 32K OTP	ZGP323HES2032C	20-pin SOIC 32K OTP

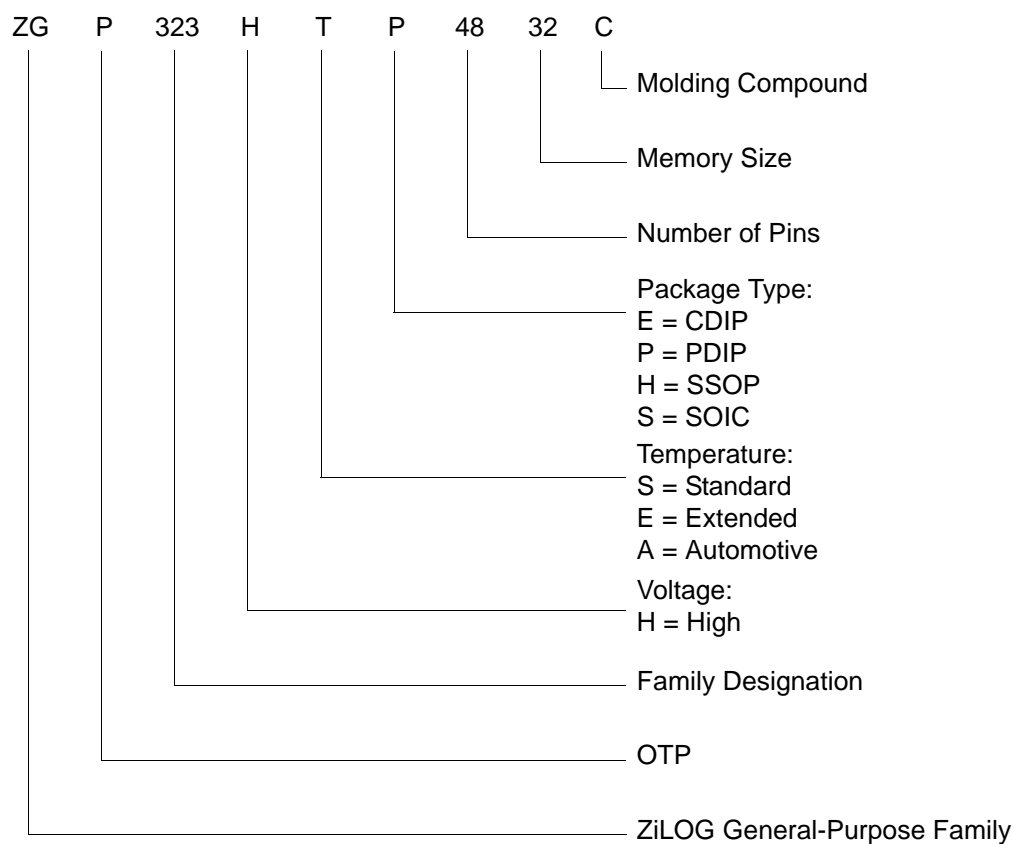
32KB Automotive Temperature: -40° to +125°C

Part Number	Description	Part Number	Description
ZGP323HAH4832C	48-pin SSOP 32K OTP	ZGP323HAS2832C	28-pin SOIC 32K OTP
ZGP323HAP4032C	40-pin PDIP 32K OTP	ZGP323HAH2032C	20-pin SSOP 32K OTP
ZGP323HAH2832C	28-pin SSOP 32K OTP	ZGP323HAP2032C	20-pin PDIP 32K OTP
ZGP323HAP2832C	28-pin PDIP 32K OTP	ZGP323HAS2032C	20-pin SOIC 32K OTP

Replace C with G for Lead-Free Packaging



Example



- pin 4
- E
- EPROM
 - selectable options 64
- expanded register file 26
- expanded register file architecture 28
- expanded register file control registers 71
 - flag 80
 - interrupt mask register 79
 - interrupt priority register 78
 - interrupt request register 79
 - port 0 and 1 mode register 77
 - port 2 configuration register 75
 - port 3 mode register 76
 - port configuration register 75
 - register pointer 80
 - stack pointer high register 81
 - stack pointer low register 81
 - stop-mode recovery register 73
 - stop-mode recovery register 2 74
 - T16 control register 69
 - T8 and T16 common control functions register 67
 - T8/T16 control register 70
 - TC8 control register 66
 - watch-dog timer register 75
- F
- features
 - standby modes 1
- functional description
 - counter/timer functional blocks 40
 - CTR(D)01h register 35
 - CTR0(D)00h register 33
 - CTR2(D)02h register 37
 - CTR3(D)03h register 39
 - expanded register file 26
 - expanded register file architecture 28
 - HI16(D)09h register 32
 - HI8(D)0Bh register 32
 - L08(D)0Ah register 32
 - L0I6(D)08h register 32
 - program memory map 26
 - RAM 25
 - register description 65
 - register file 30
 - register pointer 29
 - register pointer detail 31
 - SMR2(F)0D1h register 40
 - stack 31
 - TC16H(D)07h register 32
 - TC16L(D)06h register 33
 - TC8H(D)05h register 33
 - TC8L(D)04h register 33
- G
- glitch filter circuitry 40
- H
- halt instruction, counter/timer 54
- I
- input circuit 40
- interrupt block diagram, counter/timer 51
- interrupt types, sources and vectors 52
- L
- low-voltage detection register 65
- M
- memory, program 25
- modulo-N mode
 - T16_OUT 47
 - T8_OUT 43
- O
- oscillator configuration 53
- output circuit, counter/timer 49
- P
- package information
 - 20-pin DIP package diagram 82
 - 20-pin SSOP package diagram 84
 - 28-pin DIP package diagram 86
 - 28-pin SOIC package diagram 85
 - 28-pin SSOP package diagram 87
 - 40-pin DIP package diagram 87
 - 48-pin SSOP package diagram 89
- pin configuration
 - 20-pin DIP/SOIC/SSOP 5