

Welcome to E-XFL.COM

What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

Product Status	Obsolete
Core Processor	Z8
Core Size	8-Bit
Speed	8MHz
Connectivity	-
Peripherals	HLVD, POR, WDT
Number of I/O	24
Program Memory Size	8KB (8K x 8)
Program Memory Type	ОТР
EEPROM Size	-
RAM Size	237 x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SOIC (0.295", 7.50mm Width)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/zgp323hes2808c

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

ZGP323H Product Specification



List of Tables

Table 1.	Revision History of this Document iii
Table 2.	Features
Table 3.	Power Connections 3
Table 4.	20-Pin PDIP/SOIC/SSOP/CDIP* Pin Identification
Table 5.	28-Pin PDIP/SOIC/SSOP/CDIP* Pin Identification
Table 6.	40- and 48-Pin Configuration 8
Table 7.	Absolute Maximum Ratings 10
Table 8.	Capacitance
Table 9.	GP323HS DC Characteristics 11
Table 10.	GP323HE DC Characteristics 12
Table 11.	GP323HA DC Characteristics 14
Table 12.	EPROM/OTP Characteristics 15
Table 13.	AC Characteristics 17
Table 14.	Port 3 Pin Function Summary 23
Table 15.	CTR1(0D)01H T8 and T16 Common Functions
Table 16.	Interrupt Types, Sources, and Vectors
Table 17.	IRQ Register
Table 18.	SMR2(F)0DH:Stop Mode Recovery Register 2* 58
Table 19.	Stop Mode Recovery Source 60
Table 20.	Watch-Dog Timer Time Select 63
Table 21.	EPROM Selectable Options 64



Development Features

Table 2 lists the features of ZiLOG[®]'s ZGP323H members.

Table 2. Features

Device	OTP (KB)	RAM (Bytes)	I/O Lines	Voltage Range
ZGP323H OTP MCU Family	4, 8, 16, 32	237	32, 24 or 16	2.0V–5.5V

- Low power consumption–18mW (typical)
- T = Temperature
 - S = Standard 0° to +70°C
 - $E = Extended -40^{\circ} to +105^{\circ}C$
 - A = Automotive -40° to $+125^{\circ}$ C
- Three standby modes:
 - STOP— (typical 1.8µA)
 - HALT— (typical 0.8mA)
 - Low voltage reset
- Special architecture to automate both generation and reception of complex pulses or signals:
 - One programmable 8-bit counter/timer with two capture registers and two load registers
 - One programmable 16-bit counter/timer with one 16-bit capture register pair and one 16-bit load register pair
 - Programmable input glitch filter for pulse reception
- Six priority interrupts
 - Three external
 - Two assigned to counter/timers
 - One low-voltage detection interrupt
- Low voltage detection and high voltage detection flags
- Programmable Watch-Dog Timer/Power-On Reset (WDT/POR) circuits
- Two independent comparators with programmable interrupt polarity
- Programmable EPROM options
 - Port 0: 0–3 pull-up transistors
 - Port 0: 4–7 pull-up transistors





P25 P26 P27 P04 P05 P07 V _{DD} XTAL2 XTAL1 P31 P32 P34	1 2 3 4 5 6 7 8 9 10 11 12 13 14	28-Pin PDIP SOIC SSOP CDIP*	28 27 26 25 24 23 22 21 20 19 18 17 16	 P24 P23 P22 P21 P20 P03 V_{SS} P02 P01 P00 Pref1/P30 P36 P35
P34 🗖	14		15	🖵 P35

Figure 4. 28-Pin PDIP/SOIC/SSOP/CDIP* Pin Configuration

Table 5. 28-Pin PDIP/SOIC/SSOP/CDIP* Pin Identification

Pin	Symbol	Direction	Description
1-3	P25-P27	Input/Output	Port 2, Bits 5,6,7
4-7	P04-P07	Input/Output	Port 0, Bits 4,5,6,7
8	V _{DD}		Power supply
9	XTAL2	Output	Crystal, oscillator clock
10	XTAL1	Input	Crystal, oscillator clock
11-13	P31-P33	Input	Port 3, Bits 1,2,3
14	P34	Output	Port 3, Bit 4
15	P35	Output	Port 3, Bit 5
16	P37	Output	Port 3, Bit 7
17	P36	Output	Port 3, Bit 6
18	Pref1/P30	Input	Analog ref input; connect to V _{CC} if not used
	Port 3 Bit 0		Input for Pref1/P30
19-21	P00-P02	Input/Output	Port 0, Bits 0,1,2
22	V _{SS}		Ground
23	P03	Input/Output	Port 0, Bit 3
24-28	P20-P24	Input/Output	Port 2, Bits 0-4



			T _A = -40°0	C to +105	°C			
Symbol	Parameter	V _{CC}	Min	Typ(7)	Max	Units	Conditions	Notes
V _{OH2}	Output High Voltage (P36, P37, P00, P01)	2.0-5.5	V _{CC} -0.8			V	I _{OH} = -7mA	
V _{OL1}	Output Low Voltage	2.0-5.5			0.4	V	$I_{OL} = 4.0 \text{mA}$	
V _{OL2}	Output Low Voltage (P00, P01, P36, P37)	2.0-5.5			0.8	V	I _{OL} = 10mA	
V _{OFFSET}	Comparator Input Offset Voltage	2.0-5.5			25	mV		
V _{REF}	Comparator Reference Voltage	2.0-5.5	0		V _{DD} -1.75	V		
IIL	Input Leakage	2.0-5.5	-1		1	μA	V _{IN} = 0V, V _{CC} Pull-ups disabled	
R _{PU}	Pull-up Resistance	2.0V	200.0		700.0	KΩ	V _{IN} = 0V; Pullups selected by mask	
		3.6V	50.0		300.0	KΩ	option	
		5.0V	25.0		175.0	KΩ	-	
I _{OL}	Output Leakage	2.0-5.5	-1		1	μA	$V_{IN} = 0V, V_{CC}$	
I _{CC}	Supply Current	2.0V		1	3	mA	at 8.0 MHz	1, 2
		3.6V		5	10	mA	at 8.0 MHz	1, 2
		5.5V		10	15	mA	at 8.0 MHz	1, 2
I _{CC1}	Standby Current	2.0V		0.5	1.6	mA	V _{IN} = 0V, Clock at 8.0MHz	1, 2, 6
	(HALT Mode)	3.6V		0.8	2.0	mA	V _{IN} = 0V, Clock at 8.0MHz	1, 2, 6
		5.5V		1.3	3.2	mA	V _{IN} = 0V, Clock at 8.0MHz	1, 2, 6
I _{CC2}	Standby Current (Stop	2.0V		1.6	12	μA	V _{IN} = 0 V, V _{CC} WDT not Running	3
	Mode)	3.6V		1.8	15	μA	V _{IN} = 0 V, V _{CC} WDT not Running	3
		5.5V		1.9	18	μA	$V_{IN} = 0 V, V_{CC} WDT not Running$	3
		2.0V		5	30	μA	$V_{IN} = 0 V, V_{CC} WDT$ is Running	3
		3.6V		8	40	μA	$V_{IN} = 0 V, V_{CC} WDT$ is Running	3
		5.5V		15	60	μA	$V_{IN} = 0 V, V_{CC} WDT$ is Running	3
I _{LV}	Standby Current (Low Voltage)			1.2	6	μA	Measured at 1.3V	4
V _{BO}	V _{CC} Low Voltage Protection			1.9	2.15	V	8MHz maximum Ext. CLK Freq.	
V_{LVD}	V _{CC} Low Voltage Detection			2.4		V		
V _{HVD}	Vcc High Voltage Detection			2.7		V		
-								

Table 10. GP323HE DC Characteristics (Continued)

Notes:

1. All outputs unloaded, inputs at rail.

2. CL1 = CL2 = 100 pF.

3. Oscillator stopped.

4. Oscillator stops when V_{CC} falls below V_{BO} limit.

 It is strongly recommended to add a filter capacitor (minimum 0.1 μF), physically close to VCC and V_{SS} pins if operating voltage fluctuations are anticipated, such as those resulting from driving an Infrared LED.

6. Comparator and Timers are on. Interrupt disabled.

7. Typical values shown are at 25 degrees C.



AC Characteristics



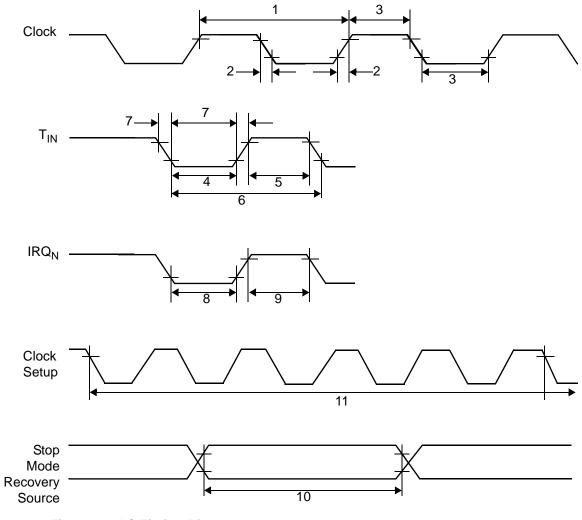


Figure 8. AC Timing Diagram



				–40°C to –40°C to	o +70°C (S) +105°C (E) +125°C (A) MHz			Watch-Dog Timer Mode Register
No	Symbol	Parameter	V _{CC}	Minimum	Maximum	Units	Notes	(D1, D0)
1	ТрС	Input Clock Period	2.0–5.5	121	DC	ns	1	
2	TrC,TfC	Clock Input Rise and Fall Times	2.0–5.5		25	ns	1	
3	TwC	Input Clock Width	2.0–5.5	37		ns	1	
4	TwTinL	Timer Input Low Width	2.0 5.5	100 70		ns	1	
5	TwTinH	Timer Input High Width	2.0–5.5	3ТрС			1	
6	TpTin	Timer Input Period	2.0–5.5	8TpC			1	
7	TrTin,TfTin	Timer Input Rise and Fall Timers	2.0–5.5		100	ns	1	
8	TwIL	Interrupt Request Low Time	2.0 5.5	100 70		ns	1, 2	
9	TwlH	Interrupt Request Input High Time	2.0–5.5	5TpC			1, 2	
10	Twsm	Stop-Mode Recovery Width	2.0–5.5	12		ns	3	
		Spec		5TpC			4	
11	Tost	Oscillator Start-Up Time	2.0–5.5		5TpC		4	
12	Twdt	Watch-Dog Timer Delay Time	2.0–5.5 2.0–5.5 2.0–5.5 2.0–5.5	5 10 20 80		ms ms ms ms		0, 0 0, 1 1, 0 1, 1
13	T _{POR}	Power-On Reset	2.0–5.5	2.5	10	ms		

Table 13. AC Characteristics

Notes:

1. Timing Reference uses 0.9 V_{CC} for a logic 1 and 0.1 V_{CC} for a logic 0. 2. Interrupt request through Port 3 (P33–P31).

3. SMR – D5 = 1.

4. SMR - D5 = 0.



CTR1(0D)01H" on page 35). Other edge detect and IRQ modes are described in Table 14.

Note: Comparators are powered down by entering Stop Mode. For P31–P33 to be used in a Stop Mode Recovery (SMR) source, these inputs must be placed into digital mode.

Pin	I/O	Counter/Timers	Comparator	Interrupt
Pref1/P30	IN		RF1	
P31	IN	IN	AN1	IRQ2
P32	IN		AN2	IRQ0
P33	IN		RF2	IRQ1
P34	OUT	Т8	AO1	
P35	OUT	T16		
P36	OUT	T8/16		
P37	OUT		AO2	
P20	I/O	IN		

Table 14. Port 3 Pin Function Summary

>

Port 3 also provides output for each of the counter/timers and the AND/OR Logic (see Figure 13). Control is performed by programming bits D5–D4 of CTR1, bit 0 of CTR0, and bit 0 of CTR2.





Figure 13. Port 3 Counter/Timer Output Configuration



Comparator Inputs

In analog mode, P31 and P32 have a comparator front end. The comparator reference is supplied to P33 and Pref1. In this mode, the P33 internal data latch and its corresponding IRQ1 are diverted to the SMR sources (excluding P31, P32, and P33) as indicated in Figure 12 on page 22. In digital mode, P33 is used as D3 of the Port 3 input register, which then generates IRQ1.



Note: Comparators are powered down by entering Stop Mode. For P31–P33 to be used in a Stop Mode Recovery source, these inputs must be placed into digital mode.

Comparator Outputs

These channels can be programmed to be output on P34 and P37 through the PCON register.

RESET (Input, Active Low)

Reset initializes the MCU and is accomplished either through Power-On, Watch-Dog Timer, Stop Mode Recovery, Low-Voltage detection, or external reset. During Power-On Reset and Watch-Dog Timer Reset, the internally generated reset drives the reset pin Low for the POR time. Any devices driving the external reset line must be open-drain to avoid damage from a possible conflict during reset conditions. Pull-up is provided internally.

When the Z8 GP asserts (Low) the $\overline{\text{RESET}}$ pin, the internal pull-up is disabled. The Z8 GP does not assert the $\overline{\text{RESET}}$ pin when under VBO.



Note: The external Reset does not initiate an exit from STOP mode.

Functional Description

This device incorporates special functions to enhance the Z8[®], functionality in consumer and battery-operated applications.

Program Memory

This device addresses up to 32KB of OTP memory. The first 12 Bytes are reserved for interrupt vectors. These locations contain the six 16-bit vectors that correspond to the six available interrupts.

RAM

This device features 256B of RAM. See Figure 14.

ZGP323H Product Specification



Leastion of C	0700	Not Accessible
Location of 3	2768 1	On-Chip
instruction		ROM
executed after RESET		
	12	Reset Start Address
	11	IRQ5
	10	IRQ5
	9	IRQ4
	8	IRQ4
	7	IRQ3
Interrupt Vector (Lower Byte)	6	IRQ3
	5	IRQ2
Interrupt Vecto	4 r	✓ IRQ2
(Upper Byte		IRQ1
	2	IRQ1
	1	IRQ0
	0	IRQ0



Expanded Register File

The register file has been expanded to allow for additional system control registers and for mapping of additional peripheral devices into the register address area. The Z8[®] register address space (R0 through R15) has been implemented as 16 banks, with 16 registers per bank. These register groups are known as the



The upper nibble of the register pointer (see Figure 16) selects which working register group, of 16 bytes in the register file, is accessed out of the possible 256. The lower nibble selects the expanded register file bank and, in the case of the Z8 GP family, banks 0, F, and D are implemented. A OH in the lower nibble allows the normal register file (bank 0) to be addressed. Any other value from 1H to FH exchanges the lower 16 registers to an expanded register bank.



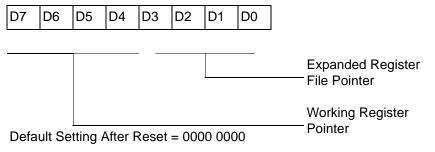


Figure 16. Register Pointer

Example: Z8 GP: (See Figure 15 on page 28)

R253 RP = 00h R0 = Port 0 R1 = Port 1 R2 = Port 2 R3 = Port 3

But if:

R253 RP = 0Dh R0 = CTR0 R1 = CTR1 R2 = CTR2R3 = Reserved



When T8 is enabled, the output T8_OUT switches to the initial value (CTR1, D1). If the initial value (CTR1, D1) is 0, TC8L is loaded; otherwise, TC8H is loaded into the counter. In SINGLE-PASS Mode (CTR0, D6), T8 counts down to 0 and stops, T8_OUT toggles, the timeout status bit (CTR0, D5) is set, and a timeout interrupt can be generated if it is enabled (CTR0, D1). In Modulo-N Mode, upon reaching terminal count, T8_OUT is toggled, but no interrupt is generated. From that point, T8 loads a new count (if the T8_OUT level now is 0), TC8L is loaded; if it is 1, TC8H is loaded. T8 counts down to 0, toggles T8_OUT, and sets the timeout status bit (CTR0, D5), thereby generating an interrupt if enabled (CTR0, D1). One cycle is thus completed. T8 then loads from TC8H or TC8L according to the T8_OUT level and repeats the cycle. See Figure 20.



Figure 20. 8-Bit Counter/Timer Circuits

You can modify the values in TC8H or TC8L at any time. The new values take effect when they are loaded.



Caution: To ensure known operation do not write these registers at the time the values are to be loaded into the counter/timer. *An initial count of 1 is not allowed (a non-function occurs).* An initial count of 0 causes TC8 to count from 0 to FFH to FEH.



into LO8; if it is a negative edge, data is put into HI8. From that point, one of the edge detect status bits (CTR1, D1; D0) is set, and an interrupt can be generated if enabled (CTR0, D2). Meanwhile, T8 is loaded with FFh and starts counting again. If T8 reaches 0, the timeout status bit (CTR0, D5) is set, and an interrupt can be generated if enabled (CTR0, D1). T8 then continues counting from FFH (see Figure 23 and Figure 24).



Figure 23. Demodulation Mode Count Capture Flowchart



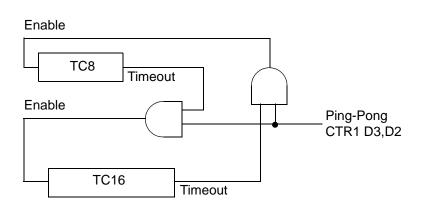


Figure 28. Ping-Pong Mode Diagram

Initiating PING-PONG Mode

First, make sure both counter/timers are not running. Set T8 into Single-Pass mode (CTR0, D6), set T16 into SINGLE-PASS mode (CTR2, D6), and set the Ping-Pong mode (CTR1, D2; D3). These instructions can be in random order. Finally, start PING-PONG mode by enabling either T8 (CTR0, D7) or T16 (CTR2, D7). See Figure 29.





The initial value of T8 or T16 must not be 1. Stopping the timer and restarting the timer reloads the initial value to avoid an unknown previous value.



ED
52

Name	Source	Vector Location	Comments
IRQ0	P32	0,1	External (P32), Rising, Falling Edge Triggered
IRQ1	P33	2,3	External (P33), Falling Edge Triggered
IRQ2	P31, T _{IN}	4,5	External (P31), Rising, Falling Edge Triggered
IRQ3	T16	6,7	Internal
IRQ4	T8	8,9	Internal
IRQ5	LVD	10,11	Internal

Table 19. Interrupt Types, Sources, and Vectors

When more than one interrupt is pending, priorities are resolved by a programmable priority encoder controlled by the Interrupt Priority Register. An interrupt machine cycle activates when an interrupt request is granted. As a result, all subsequent interrupts are disabled, and the Program Counter and Status Flags are saved. The cycle then branches to the program memory vector location reserved for that interrupt. All ZGP323H interrupts are vectored through locations in the program memory. This memory location and the next byte contain the 16-bit address of the interrupt service routine for that particular interrupt request. To accommodate polled interrupt systems, interrupt inputs are masked, and the Interrupt Request register is polled to determine which of the interrupt requests require service.

An interrupt resulting from AN1 is mapped into IRQ2, and an interrupt from AN2 is mapped into IRQ0. Interrupts IRQ2 and IRQ0 can be rising, falling, or both edge triggered. These interrupts are programmable by the user. The software can poll to identify the state of the pin.

Programming bits for the Interrupt Edge Select are located in the IRQ Register (R250), bits D7 and D6. The configuration is indicated in Table 20.

I	RQ	Interr	Interrupt Edge		
D7	D6	IRQ2 (P31)	IRQ0 (P32)		
0	0	F	F		
0	1	F	R		
1	0	R	F		
1	1	R/F	R/F		
Note	: F = Fa	Illing Edge; R = R	lising Edge		

Table 20. IRQ Register



Port 0 Output Mode (D2)

Bit 2 controls the output mode of port 0. A 1 in this location sets the output to push-pull, and a 0 sets the output to open-drain.

Stop-Mode Recovery Register (SMR)

This register selects the clock divide value and determines the mode of Stop Mode Recovery (Figure 33). All bits are write only except bit 7, which is read only. Bit 7 is a flag bit that is hardware set on the condition of Stop recovery and reset by a power-on cycle. Bit 6 controls whether a low level or a high level at the XORgate input (Figure 35 on page 59) is required from the recovery source. Bit 5 controls the reset delay after recovery. Bits D2, D3, and D4 of the SMR register specify the source of the Stop Mode Recovery signal. Bits D0 determines if SCLK/ TCLK are divided by 16 or not. The SMR is located in Bank F of the Expanded Register Group at address OBH.





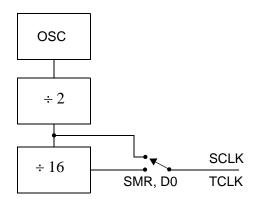


Figure 34. SCLK Circuit

Stop-Mode Recovery Source (D2, D3, and D4)

These three bits of the SMR specify the wake-up source of the Stop recovery (Figure 35 and Table 22).

Stop-Mode Recovery Register 2—SMR2(F)0DH

Table 21 lists and briefly describes the fields for this register.

Field	Bit Position		Value	Description
Reserved	7		0	Reserved (Must be 0)
Recovery Level	-6	W	0 [†]	Low
			1	High
Reserved	5		0	Reserved (Must be 0)
Source	432	W	000 [†]	A. POR Only
			001	B. NAND of P23–P20
			010	C. NAND of P27–P20
			011	D. NOR of P33–P31
			100	E. NAND of P33–P31
			101	F. NOR of P33–P31, P00, P07
			110	G. NAND of P33–P31, P00, P07
			111	H. NAND of P33–P31, P22–P20
Reserved	10		00	Reserved (Must be 0)

Notes:

* Port pins configured as outputs are ignored as a SMR recovery source. † Indicates the value upon Power-On Reset





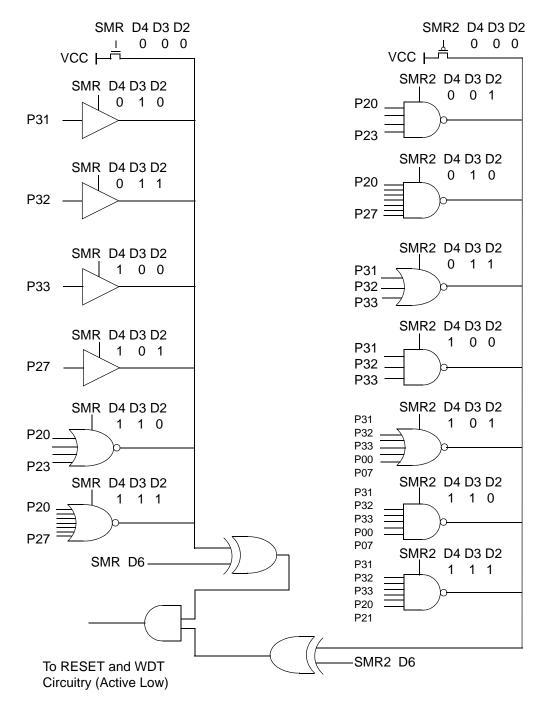


Figure 35. Stop Mode Recovery Source



CTR2(0D)02H

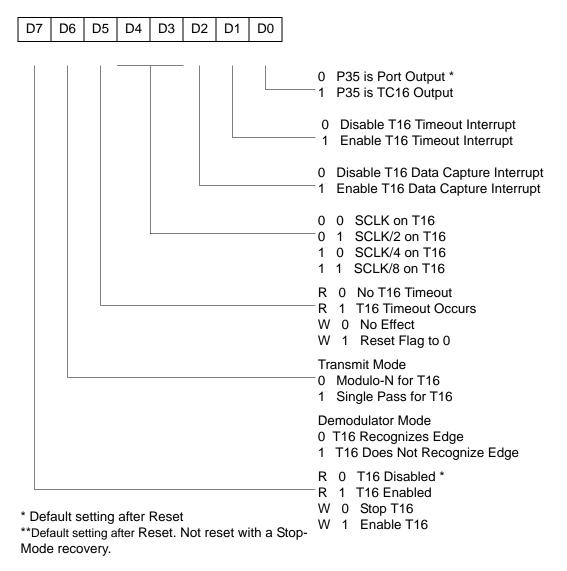
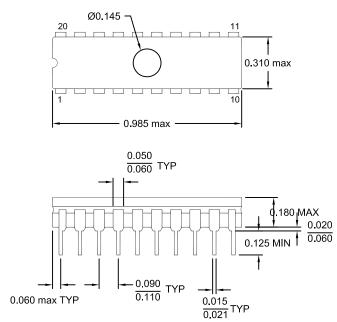


Figure 41. T16 Control Register ((0D) 2H: Read/Write Except Where Noted)







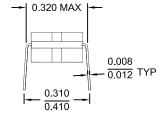
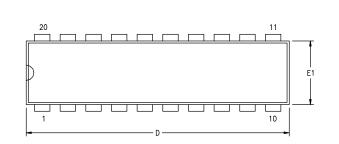


Figure 58. 20-Pin CDIP Package



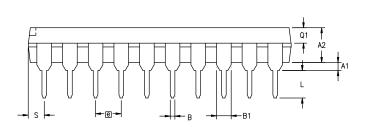
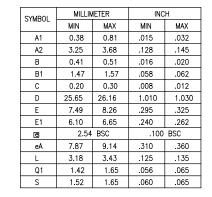
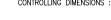


Figure 59. 20-Pin PDIP Package Diagram





CONTROLLING DIMENSIONS : INCH

